

Water-dielectric-breakdown relation for the design of large-area multimegavolt pulsed-power systems

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We have developed an empirical electrical-breakdown relation that can be used to design large-area water-insulated pulsed-power systems. Such systems often form an integral part of multiterawatt pulsed-power accelerators, and may be incorporated in future petawatt-class machines. We find that complete dielectric failure is likely to occur in water between a significantly field-enhanced anode and a less-enhanced cathode when $E_p \tau_{\text{eff}}^{0.330 \pm 0.026} = 0.135 \pm 0.009$. In this expression $E_p \equiv V_p/d$ is the peak value in time of the spatially averaged electric field between the anode and cathode (in MV/cm), V_p is the peak voltage across the electrodes, d is the distance between the anode and cathode, and τ_{eff} is the temporal width (in μs) of the voltage pulse at 63% of peak. This relation is based on 25 measurements for which $1 \leq V_p \leq 4.10$ MV, $1.25 \leq d \leq 22$ cm, and $0.011 \leq \tau_{\text{eff}} \leq 0.6$ μs . The normalized standard deviation of the differences between these measurements and the associated predictions of the relation is 12%.

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I. INTRODUCTION

Pulsed-power accelerators, such as the 55-TW Z accelerator at Sandia National Laboratories [1–10], often include one or more electrical components that use water as an insulating medium. Several applications (e.g., inertial confinement fusion, high-energy-density-physics studies, and equation-of-state research) have motivated the community to develop conceptual accelerator designs that could produce electrical powers as high as 1000 TW [11–23]; most of these designs also include water-insulated components. Optimizing the calculated performance of such components for both terawatt- and petawatt-class accelerators requires an estimate of the conditions under which the components are likely to suffer dielectric failure.

A number of useful water-dielectric-breakdown relations have been presented in the literature [24–33]. The relation developed by Eilbert and Lupton [26], which presently appears to be the most commonly used for the design of water-insulated systems, suggests that the probability of water breakdown in a uniform-electric-field system is $\sim 50\%$ when

$$E_p \tau_{\text{eff}}^{1/3} A^{0.058} = 0.230. \quad (1)$$

The quantity $E_p \equiv V_p/d$ is the peak value in time of the spatially averaged electric field between the anode and cathode (in MV/cm), V_p is the peak voltage across the electrodes, d is the distance between the anode and cathode, τ_{eff} is the temporal width (in μs) of the voltage pulse at 63% of peak voltage, and A is the electrode area (in cm^2).

Equation (1) is based on measurements performed by Smith and colleagues and reported in Refs. [24–26,31], and an additional measurement by Shipman [34] which is reported in [26]. These measurements were made at 7 different values of A , which range from 50 to 5520 cm^2 . For 6 of these, the peak voltage is ≤ 1.5 MV; for 3 of these, the voltage is < 0.5 MV.

Equation (1) is similar to uniform-field water-breakdown relations developed by the Atomic Weapons Research Establishment (AWRE) at Aldermaston, England [24,25,30,31]. The AWRE relation that is presented in Refs. [30,31] can be expressed as follows:

$$E_p \tau_{\text{eff}}^{1/3} A^{1/10} = 0.3. \quad (2)$$

Although Eqs. (1) and (2) have the same exponent for τ_{eff} , the exponents of A differ. Equation (2) is based on the same set of measurements as is Eq. (1), with the exception of the measurement by Shipman.

As is well known [31], Eqs. (1) and (2) must cease to be applicable at sufficiently large values of A . When τ_{eff} is held constant, these equations predict that as $A \rightarrow \infty$, the value of E_p required for complete dielectric failure approaches 0. Similarly when E_p is held constant, Eqs. (1) and (2) predict that as $A \rightarrow \infty$, the time required to achieve dielectric failure approaches 0.

Consequently, Eqs. (1) and (2) must cease to be applicable to the design of a pulsed-power accelerator when the area of its water-insulated system is sufficiently large. We consider here a possible example of such a situation. We estimate that a future 1000-TW accelerator might require

that the total area of the accelerator's intermediate-store capacitors be on the order of $5 \times 10^7 \text{ cm}^2$ [23]. Assuming that the effective pulse width of the voltage across such capacitors were to be $0.5 \mu\text{s}$, Eq. (1) predicts that the breakdown electric field would be 0.104 MV/cm . If the capacitors were to be designed to have a 20% safety factor, this would require that the field be limited to 0.083 MV/cm . Equation (2) predicts that breakdown would occur at 0.064 MV/cm ; applying a 20% safety factor would require that the field be limited to 0.051 MV/cm .

To determine whether the peak field in such a system of capacitors would, in fact, need to be as low as suggested by either Eq. (1) or (2), we develop in this article a water-breakdown relation that estimates, for a given pulse width, the *minimum* value of E_p that would be required to complete a dielectric breakdown. Thus we adopt the approach described in [31]; i.e., we develop an empirical *water-streamer transit-time* relation. The relation, which is developed in Sec. II, is based in part on ideas developed in Chapter 7c of Ref. [31], and uses data that became available after that chapter was written.

In Sec. III, we use Eq. (1) and the relation developed in Sec. II to develop a design criterion for large-area water-insulated systems. As we show in Sec. III, the criterion suggests that the large-area water-insulated system considered above could be operated at a much higher electric field than predicted by either Eq. (1) or (2). We discuss limitations of the design criterion, and present suggestions for future work, in Sec. IV.

In Appendix A, we demonstrate how the scaling suggested by Eq. (1) might be obtained from more fundamental considerations. In Appendix B, we evaluate one of the assumptions made in Sec. II.

II. WATER-BREAKDOWN RELATION FOR LARGE-AREA SYSTEMS

In this section we develop a dielectric-breakdown relation for large-area water-insulated pulsed-power systems. We begin by making the following simplifying assumptions.

(i) We assume that the *characteristic* time delay τ_{delay} between the application of a voltage to a water-insulated anode-cathode gap, and the completion of dielectric failure of that gap (assuming such a failure can occur), can be approximated as follows:

$$\tau_{\text{delay}} = \tau_{\text{stat}} + \tau_{\text{form}}. \quad (3)$$

In this expression τ_{stat} is the statistical component of the delay time; i.e., the *characteristic* time between the application of the voltage and the appearance of the free electrons and ions that initiate the formation of streamers in the water. We define τ_{form} to be the formative component: the time required for the streamers to propagate across the gap

and evolve sufficiently to produce complete dielectric failure.

Equation (3) is commonly assumed for modeling pulsed electrical breakdown of gas-filled spark gaps [35–40]; it is also assumed for millisecond-pulse water breakdown [28,29] and vacuum-insulator flashover [41].

(ii) We assume that the area of a water-insulated system of interest is sufficiently large that the appearance of free electrons and ions necessary to initiate a breakdown occurs *somewhere* in the system very early in the voltage pulse. Under this condition, the statistical time delay τ_{stat} can be neglected, and the breakdown time delay is dominated by its formative component:

$$\tau_{\text{delay}} \sim \tau_{\text{form}}. \quad (4)$$

(iii) We assume that breakdown dominated by the formative component can be studied experimentally with a point-plane electrode geometry [31].

(iv) We assume that when the point in a point-plane geometry is the anode, τ_{form} is less than it is when the point is the cathode. This assumption is motivated by measurements performed by VanDevender and Martin [27] and Woodworth and colleagues [42], who observe that streamers that initiate from the positive electrode travel significantly faster than negative streamers. Hence we limit the analysis in this article to point-plane measurements made with a positive enhancement.

(v) We assume that voltage pulses of interest have normalized time histories that, to a reasonable approximation, are mathematically similar. We also assume that the water is homogeneous and isotropic, and has similar dielectric properties for all systems of interest. In addition, we assume that statistical fluctuations in the formative time can be neglected. Under these conditions, positive-enhanced point-plane breakdown in water is described by at most three independent variables. We can choose these to be τ_{form} , E_p , and d .

{When τ_{delay} is dominated by its *statistical* component, i.e., when $\tau_{\text{stat}} \gg \tau_{\text{form}}$ and $\tau_{\text{delay}} \sim \tau_{\text{stat}}$, then as shown in Refs. [29,41], the resulting water-breakdown relation, when expressed in a form similar to that given by Eq. (1), has *identical exponents* for the variables τ_{eff} and A . Since the time exponent of Eq. (1) is much larger than the area exponent, this suggests that for the parameter regime over which Eq. (1) is valid, τ_{form} can no longer be neglected. We elaborate on this point in Appendix A. As discussed in the last paragraph of Sec. II A 1 of Ref. [41], when the *formative* component dominates, i.e., when $\tau_{\text{stat}} \ll \tau_{\text{form}}$ and $\tau_{\text{delay}} \sim \tau_{\text{form}}$, the resulting water-breakdown relation is, under a certain set of conditions, *independent* of A . This is the parameter regime we consider in this article; i.e., we assume that the water-streamer transit-time relation is independent of A .}

(vi) We assume that the dependence of the water-streamer relation on d is weak and can be neglected; i.e.,

we assume the relation depends only on τ_{form} and E_p . This assumption is also made by VanDevender and Martin in Ref. [27]. We evaluate this assumption in Appendix B.

When the above assumptions are valid, the peak field E_p required to achieve complete dielectric failure is a function only of the time over which the voltage pulse is applied to the gap. The effective width of the voltage pulse τ_{eff} in water-breakdown studies is usually quoted as the width at 63% of peak voltage [24–27,30,31,43–49]; we adopt this convention herein to be consistent with the previous work. When voltage pulses of interest have normalized time histories that are mathematically similar (as assumed above), then $\tau_{\text{eff}} \propto \tau_{\text{delay}} \sim \tau_{\text{form}}$.

Measurements performed with an *ideal* point-plane geometry, i.e., between an infinitely field-enhanced anode point and a flat cathode with infinite extent, are of course not possible. However, a number of measurements between a *significantly enhanced* anode electrode and a *less-enhanced* cathode have been described in the literature [27,42–46,50]; these are summarized in Table I.

Assuming that for these experiments the normalized shapes of the voltage pulses are sufficiently similar, we plot E_p as a function of τ_{eff} in Fig. 1. Assuming E_p is a

power-law function of τ_{eff} , we obtain from a regression analysis the following relation:

$$E_p \tau_{\text{eff}}^{0.330 \pm 0.026} = 0.135 \pm 0.009. \quad (5)$$

This relation is plotted in Fig. 1.

The uncertainties given in Eq. (5) are 1σ values. Hence the τ_{eff} exponent of Eq. (5) is within 3σ of the exponent of the *preliminary* relation developed by VanDevender and Martin [27] for positive-streamer breakdown; this relation can be expressed as

$$E_p \tau_{\text{eff}}^{0.4} = 0.11. \quad (6)$$

Sandia National Laboratories has successfully used Eq. (6) for the design of several of its accelerators, including PROTO II, PBFA I, and PBFA II.

Since 1977, the pulsed-power community has also used J. C. Martin's *preliminary* relation for positive-streamer breakdown [31]:

$$E_p \tau_{\text{eff}}^{0.5} = 0.1. \quad (7)$$

This relation is often used even though Martin warned of the lack of data supporting Eq. (7) for voltages >1 MV

TABLE I. Conditions under which complete dielectric breakdown of water is observed to occur. Each of these measurements was obtained with a significantly field-enhanced anode and a less-enhanced cathode, as described in Refs. [27,42–46,50]. The quantity V_p is the peak voltage in time across the anode-cathode gap, d is the length of the gap, $E_p \equiv V_p/d$, and τ_{eff} is the temporal width of the voltage pulse at 63% of peak. The last column assumes E_p is expressed in MV/cm, and τ_{eff} in μs .

Reference	V_p (MV)	d (cm)	E_p (MV/cm)	τ_{eff} (μs)	$E_p \tau_{\text{eff}}^{0.330}$
Corley and colleagues [44]	1.94	5.72	0.339	0.063	0.136
Corley and colleagues [44]	2.15	5.84	0.368	0.063	0.148
Corley and colleagues [44]	2.34	7.11	0.329	0.070	0.137
Corley and colleagues [44]	2.56	7.43	0.345	0.063	0.138
Puetz and colleagues [45,46]	2.07	7.63	0.271	0.077	0.116
Puetz and colleagues [45,46]	2.15	6.35	0.339	0.073	0.143
Puetz and colleagues [45,46]	2.32	7.63	0.304	0.094	0.139
Sazama and Kenyon [50]	4.0	22	0.182	0.6	0.154
VanDevender [43]	1.2	5.1	0.235	0.150	0.126
VanDevender [43]	1.4	5.1	0.275	0.130	0.140
VanDevender [43]	1.4	7.6	0.184	0.220	0.112
VanDevender [43]	1.7	7.6	0.224	0.190	0.129
VanDevender [43]	1.8	7.6	0.237	0.150	0.127
VanDevender [43]	1.2	5.1	0.235	0.240	0.147
VanDevender [43]	1.4	2.9	0.483	0.040	0.167
VanDevender [43]	1.5	3.2	0.469	0.043	0.166
VanDevender and Martin [27]			0.205	0.198	0.120
VanDevender and Martin [27]			0.228	0.157	0.124
VanDevender and Martin [27]			0.280	0.089	0.126
VanDevender and Martin [27]			0.295	0.113	0.144
VanDevender and Martin [27]			0.390	0.020	0.107
VanDevender and Martin [27]			0.412	0.028	0.127
VanDevender and Martin [27]			0.463	0.015	0.116
VanDevender and Martin [27]			0.695	0.011	0.155
Woodworth and colleagues [42]	4.10	15	0.273	0.136	0.142

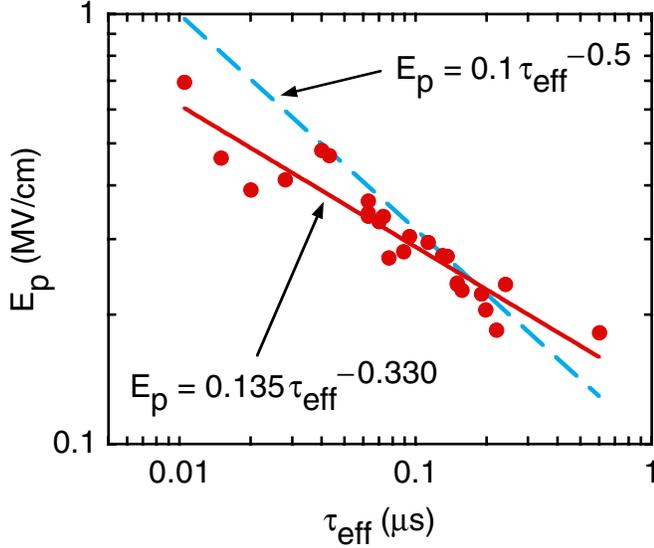


FIG. 1. (Color) The peak electric field required to achieve complete dielectric failure E_p as a function of the effective pulse width τ_{eff} . Each of the 25 measurements plotted here was obtained with a significantly field-enhanced anode and a less-enhanced cathode, as described in Refs. [27,42–46,50]. This data is summarized in Table I. We define E_p as V_p/d , where V_p is the peak voltage in time across the anode-cathode gap, and d is the length of the gap. We define τ_{eff} to be the width of the voltage pulse at 63% of peak. It appears that the data are more consistent with Eq. (5) than Eq. (7).

[30,31]. This relation is also plotted in Fig. 1. As suggested by the figure, Eq. (5) is more consistent with experiment than is Eq. (7).

Equation (7) can be obtained from Fig. 7c-1 of Ref. [31]. However, according to this figure, when $V_p > 1$ MV, positive and negative streamers have the same average velocity, which is *not* consistent with the measurements reported in Refs. [27,42]. We also note that Chapter 7c of Ref. [31] proposes a refinement of Eq. (7):

TABLE II. For each of the water-breakdown relations given as Eqs. (5)–(8), we present here the normalized standard deviation σ_n of the differences between the measurements listed in Table I and the associated predictions of the relation. For the first relation, we define σ_n as indicated by Eq. (9). We define σ_n for each of the other relations in a similar manner.

Water-breakdown relation	Normalized standard deviation σ_n of the differences between the measurements presented in Table I and the predictions of each relation
$E_p \tau_{\text{eff}}^{0.330} = 0.135$	12%
$E_p \tau_{\text{eff}}^{0.4} = 0.11$	14%
$E_p \tau_{\text{eff}}^{0.5} = 0.1$	20%
$E_p \tau_{\text{eff}}^{0.5} = 0.133$	36%

$$E_p \tau_{\text{eff}}^{0.5} = 0.133. \quad (8)$$

This expression is less consistent with the data in Table I than is Eq. (7).

In Table II we present, for each of the relations given by Eqs. (5)–(8), the normalized standard deviation of the differences between the data in Table I and the associated predictions of the relation. We define the normalized standard deviation σ_n for the first relation [Eq. (5)] as follows:

$$\sigma_n = \left[\frac{1}{25-1} \sum \left(\frac{E_p \tau_{\text{eff}}^{0.330} - 0.135}{0.135} \right)^2 \right]^{1/2}, \quad (9)$$

where the sum is over the 25 measurements listed in Table I. The normalized standard deviation for each of the other three relations is similarly defined.

III. DESIGN CRITERION FOR LARGE-AREA SYSTEMS

Comparing Eqs. (1) and (5), and assuming that the τ_{eff} exponents of these two relations are essentially the same, we find that Eq. (5) should be used instead of Eq. (1) whenever

$$A \geq 10^4 \text{ cm}^2. \quad (10)$$

As noted previously, the largest area of the data used by Eilbert and Lupton to develop Eq. (1) is 5520 cm² [24–26,31,34].

However, we caution that Eq. (10) may not be entirely meaningful. The water-streamer relation given in Chapter 7c of Ref. [31] for voltages < 0.5 MV differs significantly from the relation given for voltages > 1 MV, which suggests that water breakdown exhibits different behavior in these two voltage regimes. Equation (5) is based on voltages between 1 and 4.10 MV; however, much of the data used to develop Eq. (1) is less than 0.5 MV [24–26,31], so it is uncertain whether Eqs. (1) and (5) can be combined to obtain Eq. (10).

In the absence of additional measurements, we make the *tentative* assumption that Eqs. (1) and (5) are both valid for voltages in excess of 1 MV. Assuming also that a 20% safety factor should be applied to Eq. (5) when used to design a system with $A \geq 10^4$ cm², we obtain the following design criterion:

$$E_p \tau_{\text{eff}}^{0.330} \leq 0.108 \quad \text{when } A \geq 10^4 \text{ cm}^2. \quad (11)$$

Equation (11) is consistent with measurements conducted by Maxwell Labs on the transfer capacitor of the BLACKJACK-3 pulse generator, which demonstrate that breakdown does *not* occur in a water-insulated system when $E_p \tau_{\text{eff}}^{0.330} = 0.119$ and $A = 5.5 \times 10^4$ cm² [31,47]. Equation (11) is also consistent with *indirect* measurements (i.e., direct measurements supplemented with circuit modeling) conducted on the Z accelerator [48], which show that breakdown does *not* occur when

TABLE III. Conditions under which dielectric breakdown of water is observed *not* to occur. Each of these two observations was made on a large-area ($A \gtrsim 10^4 \text{ cm}^2$) water-insulated system with a nominally uniform electric field. The quantity V_p is the peak voltage in time across the anode-cathode gap, d is the length of the gap, $E_p \equiv V_p/d$, and τ_{eff} is the temporal width of the voltage pulse at 63% of peak. The last column assumes E_p is expressed in MV/cm, and τ_{eff} in μs . (The Maxwell-Lab data was taken on a transfer capacitor, with coaxial electrodes that have an outer radius of 60 cm and an inner radius of 48 cm [47]. The peak field E_p given here for this data is that at the outer conductor, which is the anode, and has been corrected for the coaxial geometry.) The observations summarized here are consistent with the design criterion given by Eq. (11).

Reference	A (cm^2)	V_p (MV)	d (cm)	E_p (MV/cm)	τ_{eff} (μs)	$E_p \tau_{\text{eff}}^{0.330}$
Measurements conducted by Maxwell Labs [31,47]	5.5×10^4	2.1	12	0.150	0.5	0.119
Stygar and colleagues [48]	5.3×10^5	3.6	14	0.257	0.083	0.113

$E_p \tau_{\text{eff}}^{0.330} = 0.113$ and $A = 5.3 \times 10^5 \text{ cm}^2$. These large-area observations are summarized in Table III.

Presently, effective pulse widths for water-insulated systems of most interest range between ~ 0.05 and $\sim 1 \mu\text{s}$. Hence, it is unfortunate that the literature only describes one point-plane measurement with $\tau_{\text{eff}} > 0.3 \mu\text{s}$, as indicated by Table I and Fig. 1. However, Table III suggests Eq. (5) is reasonably accurate when $\tau_{\text{eff}} = 0.5 \mu\text{s}$. According to assumption (ii) of Sec. II, and also Eq. (11), dielectric breakdown of a sufficiently large area follows the same relation as a point-plane system. If assumption (ii) and Eq. (11) are in fact valid, the BLACKJACK-3 data given in Table III suggests that when $\tau_{\text{eff}} = 0.5 \mu\text{s}$, point-plane breakdown occurs when $E_p \tau_{\text{eff}}^{0.330} > 0.119$, which is consistent with Eq. (5). We note that this data is *less* consistent with Eq. (7), which predicts that the BLACKJACK-3 transfer capacitor should fail at a field that is 6% below the capacitor's normal operating field of 0.150 MV/cm [31,47].

An additional measurement with $\tau_{\text{eff}} > 0.3 \mu\text{s}$ is presented in Table 7c-II of Ref. [31]. This measurement was performed at $A = 3000 \text{ cm}^2$ and $\tau_{\text{eff}} = 0.75 \mu\text{s}$. Under these conditions, breakdown was observed to occur when $E_p = 0.160 \text{ MV/cm}$. (The peak voltage was on the order of 1.85 MV [31].) Since the area of this measurement is less than 10^4 cm^2 , we use Eq. (1) to estimate that had this measurement been made at 10^4 cm^2 , the peak electric field E_p at breakdown would have been 0.149 MV/cm. Hence, this suggests that when $\tau_{\text{eff}} = 0.75 \mu\text{s}$, point-plane breakdown occurs when $E_p \tau_{\text{eff}}^{0.330} = 0.136$, in reasonable agreement with Eq. (5). This measurement is *less* consistent with Eq. (7), which predicts that under these conditions, the breakdown field E_p would be 0.115 MV/cm.

We revisit here the water-insulated system (with $A = 5 \times 10^7 \text{ cm}^2$) considered in Sec. I. According to Eq. (11), when $\tau_{\text{eff}} = 0.5 \mu\text{s}$, the peak electric field of such a system should be limited to 0.136 MV/cm. This is 64% higher than the 0.083 MV/cm limit suggested by Eq. (1), and 164% higher than the 0.051 MV/cm limit suggested by Eq. (2), assuming 20% safety factors are applied to both Eqs. (1) and (2). [As discussed above, a 20% safety factor

is applied to Eq. (5) to arrive at Eq. (11).] Consequently, if Eq. (11) is valid, large-area water-insulated systems of interest can be operated at significantly higher electric fields than suggested by either Eq. (1) or (2).

IV. DISCUSSION

A. Limitations of the design criterion

Equation (5) can be rewritten as

$$\frac{V_p}{0.135 \tau_{\text{eff}}^{0.670}} = \frac{d}{\tau_{\text{eff}}} \equiv v_{\text{ave}}, \quad (12)$$

where v_{ave} is the *average* streamer velocity across the anode-cathode gap. Assuming streamer propagation is driven by the electric field at the streamer tips, and that for frequencies of interest the dielectric constant of water is 80, then Eq. (5) [and hence Eq. (11)] are meaningful only when

$$\frac{V_p}{0.135 \tau_{\text{eff}}^{0.670}} < \frac{c}{\sqrt{80}} = 3354 \text{ cm}/\mu\text{s}, \quad (13)$$

where c is the speed of light in vacuum.

When Eq. (13) is not valid, the design criterion given by Eq. (11) should be replaced by one of the following form:

$$k \frac{d}{\tau_{\text{eff}}} > 3354 \text{ cm}/\mu\text{s}, \quad (14)$$

where k is a suitably defined constant. This constant would be defined so that Eq. (14) guarantees that streamers cannot physically cross the gap during the duration of the voltage pulse. The velocity on the right-hand-side of Eq. (14) is $0.11c$; we note that *peak* (i.e., not average) water-streamer-propagation velocities as high as $0.01c$ have been observed by Woodworth and colleagues [42].

Even when Eq. (13) is valid, we caution that Eq. (11) is only applicable for the first pulse applied to a water-insulated system during an accelerator shot, since Eq. (11) does not account for effects due to subsequent pulses (such as might be caused by reflections) on a system's dielectric strength. We also caution that Eq. (11) is not necessarily

applicable at an interface between water and a solid insulator.

B. Suggestions for future work

For the measurements listed in Table I, $1 \leq V_p \leq 4.10$ MV, $1.25 \leq d \leq 22$ cm, and $0.011 \leq \tau_{\text{eff}} \leq 0.6$ μ s. However, these measurements do not include all physically reasonable combinations of the variables V_p , d , and τ_{eff} within these ranges, but only a small subset. In addition, it is not clear how far Eq. (11) can be extrapolated beyond these ranges. Hence Eq. (11) is being proposed here only as a *tentative* design criterion; we suggest that additional experiments be conducted over a wider parameter regime to develop a *definitive* criterion. Such experiments would be similar to those described in Refs. [27,31,42–46,49,50].

Additional experiments performed with relatively uniform electric fields and large areas, such as the experiments described in Refs. [24,25,28,29,31–34,47,48], would also be of interest, to determine whether Eq. (11) is, in fact, a reasonable criterion.

In addition, we note that Eq. (11) is valid only when the shape of the voltage pulse in question is, to a reasonable approximation, mathematically similar to those used for the measurements presented in Table I. To generalize Eq. (11) for use with arbitrary pulse shapes, we propose that a relation of the following form be developed [41,49]:

$$\int_0^\tau E^\alpha(t)dt = \gamma, \quad (15)$$

where τ is the full width of the voltage pulse at its base, and α and γ are constants.

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APPENDIX A: DEVELOPING A DIELECTRIC-BREAKDOWN RELATION FROM EXPRESSIONS FOR τ_{stat} AND τ_{form}

In this appendix we discuss how a dielectric-breakdown relation of the form given by Eq. (1) can be obtained from expressions for τ_{stat} and τ_{form} .

According to Refs. [28,29,41], when the dielectric-breakdown time delay τ_{delay} of a system is dominated by τ_{stat} , the exponents of τ_{eff} and A in the corresponding breakdown relation, when expressed in the form given by Eq. (1), are identical. (This statement assumes that the relevant size variable of the system in question is the area A . For vacuum-insulator flashover, the relevant size variable is C , the insulator circumference [41].)

For water breakdown dominated by τ_{stat} , under the conditions studied in Ref. [28], it appears that

$$\tau_{\text{stat}} = \frac{\gamma_1}{E_p^{12.5}A}, \quad (A1)$$

where γ_1 is a constant. For water breakdown dominated by τ_{form} , under the conditions studied in Sec. II of the present article, we find that

$$\tau_{\text{form}} = \frac{\gamma_2}{E_p^{3.03}}, \quad (A2)$$

where γ_2 is a constant.

Combining Eqs. (3), (A1), and (A2), and assuming that the shapes of the voltage pulses for systems of interest are mathematically similar (so that when breakdown occurs, $\tau_{\text{eff}} \propto \tau_{\text{delay}}$), we find that in general

$$\tau_{\text{eff}} \propto \frac{\gamma_1}{E_p^{12.5}A} + \frac{\gamma_2}{E_p^{3.03}}. \quad (A3)$$

Hence,

$$\frac{E_p^{12.5}\tau_{\text{eff}}A}{1 + \gamma_3 E_p^{9.47}A} = \gamma_4, \quad (A4)$$

where γ_3 and γ_4 are constants. Making the following approximation,

$$(1 + \gamma_3 E_p^{9.47}A) \propto (E_p^{9.47}A)^\beta, \quad (A5)$$

where

$$0 \leq \beta \leq 1, \quad (A6)$$

we find that

$$E_p \tau_{\text{eff}}^{1/(12.5-9.47\beta)} A^{(1-\beta)/(12.5-9.47\beta)} = \gamma_5, \quad (\text{A7})$$

where γ_5 is a constant.

The case $\beta = 0$ corresponds to when τ_{stat} dominates; the case $\beta = 1$ when τ_{form} dominates. When $\beta = 0.95$ we obtain

$$E_p \tau_{\text{eff}}^{0.29} A^{0.014} = \gamma_5. \quad (\text{A8})$$

We have performed a multiple-regression analysis on the water-breakdown data presented in [24–26,31], and instead of Eq. (1), we obtain the following relation:

$$E_p \tau_{\text{eff}}^{0.316 \pm 0.021} A^{0.057 \pm 0.019} = 0.248 \pm 0.038. \quad (\text{A9})$$

The uncertainties presented in Eq. (A9) are 1σ values. Hence, to within $\sim 2\sigma$ (the usual standard for determining whether a discrepancy is significant [51]), Eqs. (A8) and (A9) are consistent. [However, we caution that such a comparison may not be meaningful. The data upon which Eq. (A1) is based was taken with voltages < 0.2 MV, and much of the data upon which Eq. (A9) is based was taken with voltages < 0.5 MV. The data upon which Eq. (A2) is based was taken with voltages between 1 and 4.10 MV. According to Chapter 7c of Ref. [31], the water-streamer relation for voltages < 0.5 MV differs significantly from the relation obtained for voltages > 1 MV, which suggests that water breakdown exhibits different behavior in these two voltage regimes. Hence, it is not clear we can combine Eqs. (A1) and (A2) to obtain Eq. (A8), as described above, nor that we can compare Eq. (A8) to Eq. (A9).]

When neither τ_{stat} nor τ_{form} dominates, a dielectric-breakdown relation may be more accurately expressed in a form similar to that given by Eq. (A4) than Eq. (A8), since an equation such as Eq. (A4) more accurately accounts for contributions from both τ_{stat} and τ_{form} to the delay time τ_{delay} .

APPENDIX B: DEPENDENCE OF THE WATER-BREAKDOWN RELATION ON THE ANODE-CATHODE GAP d

In Sec. II, we make the simplifying assumption that the water-streamer transit-time relation developed in this article is independent of the anode-cathode gap d . We evaluate this assumption below.

Table I lists 25 point-plane measurements; the gap d is available for 17 of these. When we assume E_p is a function of both τ_{eff} and d , and perform a multiple-regression analysis on these 17 measurements, we obtain instead of Eq. (5) the following relation:

$$E_p \tau_{\text{eff}}^{0.360 \pm 0.053} d^{0.030 \pm 0.077} = 0.137 \pm 0.038. \quad (\text{B1})$$

At the 95% confidence level, the exponent of d is between -0.136 and 0.196 . Hence, we presently do not have sufficient evidence to determine whether the exponent

of d differs significantly from 0. Consequently, it appears that, for the available data, we are justified in assuming that the dependence of the water-streamer transit-time relation on d can be neglected. Of course, as more data become available, this assumption should be reexamined.

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