

***Ab initio* phonon transport across grain boundaries in graphene using machine learning based on small dataset**

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Establishing the structure-property relationship for grain boundaries (GBs) is critical for developing next-generation functional materials but has been severely hampered due to its extremely large configurational space. Atomistic simulations with low computational cost and high predictive power are strongly desirable, but the conventional simulations using empirical interatomic potentials and density functional theory suffer from the lack of predictive power and high computational cost, respectively. A machine learning interatomic potential (MLIP) recently emerged but often requires extensive size of the training dataset, making it a less feasible approach. Here, we demonstrate that an MLIP trained with a rationally designed small training dataset can predict thermal transport across GBs in graphene with *ab initio* accuracy at an affordable computational cost. We employed a rational approach based on the structural unit model to find a small set of GBs that can represent the entire configurational space and thus can serve as a cost-effective training dataset for the MLIP. Only 5 GBs were found to be enough to represent the entire configurational space of graphene GBs. Using the atomistic Green's function approach and the MLIP, we revealed that the structure-thermal resistance relation in graphene does not follow the common understanding that large dislocation density causes larger thermal resistance. In fact, thermal resistance is nearly independent of dislocation density at room temperature and is higher when the dislocation density is small at sub-room temperature. We explain this intriguing behavior with the buckling near a GB causing a strong scattering of flexural phonon modes. In this paper, we show that a machine learning technique combined with conventional wisdom (e.g., structural unit model) can extend the recent success of *ab initio* thermal transport simulation, which has been mostly limited to single crystals, to complex yet practically important polycrystals with GBs.

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I. INTRODUCTION

Grain boundaries (GBs) are of interest in many applications because they are common defects and largely affect electrical, mechanical, and thermal properties. For two-dimensional (2D) materials such as graphene, experimental studies showed that GBs commonly exist in graphene sheets prepared by exfoliation [1–5], causing the fundamental physical properties of polycrystal samples to largely deviate from those of single crystals. Therefore, engineering GBs is an effective way to achieving desired electronic, thermal, and mechanical properties in many applications [6–14].

The physical properties are largely dependent on the local atomic structure of GB [5,6,15], and thus, it is important to establish the structure-property relationship on how a

GB structure affects the physical properties. However, establishing such a structure-property relationship has been challenging mainly for two reasons. The first is that GBs have extremely large configurational space. For example, three-dimensional (3D) materials have five degrees of freedom (misorientation angle noted as θ_M hereafter, line angle, and three degrees of freedom of crystalline grain orientation in 3D space) for GB structures, making the configurational space extremely large. The second is that the experimental characterization of an individual GB requires significant efforts, particularly for preparing samples with a geometrically well-defined GB. The samples with GBs have been prepared by bonding two wafers with a twist angle, but it often leaves a void at the interface [16]. Therefore, it is challenging to experimentally study enough GBs to draw a statistically conclusive finding on the structure-property relationship.

Atomistic simulation can be a useful tool for the study of GBs if it has high predictive power, but it also has major challenges. Atomistic simulations for thermal transport such as molecular dynamics (MD) [7,8,10,17–19] and the atomistic Green's function (AGF) [14,20] require an interatomic

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potential. A common approach for the interatomic potential has been empirical potentials that have a rigid functional form parametrized based on quantum mechanical calculation results and experimental data. Although the empirical potentials have been useful for promoting the understanding of physical phenomena from an atomistic level, they have clear limitations. For the physical properties that were not considered for the parametrization, empirical potentials do not provide an accurate prediction. Also, because of its rigid functional form, it is usually not flexible enough to describe a wide range of atomic configurations. On the contrary, *ab initio* calculation can be highly accurate and have a predictive power without adjustable parameters, as demonstrated by the recent studies. For example, the high thermal conductivity of boron arsenide was experimentally confirmed [21–23] after the prediction from *ab initio* simulation [24]. Also, the significant hydrodynamic phonon transport in graphitic materials was predicted using *ab initio* simulation first [25,26] and then experimentally confirmed [27,28]. However, *ab initio* simulation for thermal transport has been limited to the single-crystalline phase and point defect cases. For the thermal transport across GBs, *ab initio* simulation is not feasible due to its high computational cost, considering the size of GB atomic structures.

A recently emerging method is to use machine learning schemes to predict the interatomic interactions based on the dataset from *ab initio* simulations [29–40]. This so-called machine learning interatomic potential (MLIP) was motivated by the fact that the interatomic interaction is a function in a high-dimensional space where machine learning outperforms conventional regression methods. Recently developed MLIPs show that the MLIP can be as accurate as *ab initio* calculations, while its computational cost is several orders of magnitude cheaper than *ab initio* calculations [29–31,41]. The MLIP was proven for predicting the thermal transport in the crystalline phase [29,31,34] and partially disordered crystalline phase that has vacancies [29]. This confirms that the MLIP is accurate enough to correctly capture subtle anharmonicity, which is critical for phonon-phonon scattering and phonon-strain field scattering, and is also flexible enough to describe various atomic configurations including vacancies. However, extending the past success of MLIP to a spatially extended disorder case (e.g., GBs) has some challenges. Unlike vacancies, the GBs have extremely large atomic configurational space. Therefore, the training dataset should be carefully designed such that it can represent the entire configurational space. In addition, the size of the training dataset should be minimal since generating the training dataset from *ab initio* calculation can be prohibitively expensive, considering the typical size of GB structures.

In this paper, we develop MLIPs using the Gaussian regression, called the Gaussian approximation potential (GAP) [41,42], for studying phonon transport across graphene GBs. We use a systematic framework based on the structural unit model to select the complete and orthogonal training dataset. With the carefully chosen few GBs for the training dataset, we show that the GAP can produce similar results as *ab initio* calculations for a wide range of GBs, while its computational cost is six orders of magnitude cheaper than *ab initio* calculations. Using the GAP and AGF, we then report several important features of phonon transport across GBs

in graphene with its high predictive power. We distinguish the influence of the dislocation core and extended strain field on phonon scattering and reveal an intriguing scattering of flexural phonon modes by out-of-plane buckling in graphene GBs. We also briefly evaluate an empirical Tersoff potential (TSF) [43,44] that has been widely used in past studies by comparing it with GAP.

II. METHODS

A. Identifying a small set of GBs representing the entire configurational space of GBs

In this paper, we consider a total of 20 GBs that covers the full span of θ_M (0° to 60°), which includes a variety of disclination densities and different topological arrangements of disclinations. We focus on symmetric GBs with zero line angle because several parameters that are expected to affect phonon scattering such as GB formation energy, dislocation density, and out-of-plane roughness are nearly unchanged with the line angle in graphene [4]. The θ_M and coincidence site lattice Σ values of the 20 GBs are listed in Table I. The supercells containing each of the GBs were generated using an algorithm based on the centroidal Voronoi tessellation [4]. Then we appended the same supercell that is rotated by 180° , resulting in two GBs along opposite directions in a supercell. Such supercells are preferred for the subsequent relaxation process using MD simulation since they have translational symmetry along all directions including the direction perpendicular to the GB line. An example supercell is shown in Fig. S1 in the Supplemental Material [45]. We then relaxed the obtained supercell by running MD simulations at 300 K in the NVT ensemble over 100 ps using the LAMMPS package, with a time step of 0.5 fs and TSF potential. Those supercells were used for training a GAP based on TSF interatomic potential (GAPTSF), which was used for the validation of our methods. A separate set of 20 supercells was further relaxed by density functional theory (DFT) calculation to develop another GAP based on DFT (GAPDFT), which we used to study the phonon transport across GBs in graphene. For the DFT calculations, we used the energy minimization scheme in the VASP package using ultrasoft pseudopotentials with a plane-wave cutoff energy of 286 eV. The convergence criteria for energy and force were set to 10^{-8} eV and 10^{-6} eV/Å, respectively. The resulting supercells relaxed by TSF and DFT slightly differ, as shown in Table I.

A challenge in developing an MLIP for GBs is how to prepare a complete set of training data. Considering the typical period length of GBs and the area strained by a GB, a supercell that contains a GB can be often too large for *ab initio* calculation. Thus, for the training dataset, it is critical to select a small set of GBs that can represent the entire configurational space of GBs. In early studies developing an MLIP for general purpose, a fraction of the total database was chosen for the training dataset without much rationale, with the remaining as the testing dataset [29,41,42,46,47]. Recently, active learning schemes have been proposed to reduce the size of training dataset [48–50], making it possible to simulate the dynamic evolution of systems such as phase change in a large scale for a long time period. While the active learning scheme can

TABLE I. List of the 20 GBs with their structural properties. The 5 representative GBs chosen by the SOAP dissimilarity analysis are indicated with superscripts $\dagger$ and $\ddagger$ for the structures relaxed by TSF and DFT, respectively.

Index	ϑ_M (deg)	Coincidence site lattice Σ	Structures relaxed by TSF		Structures relaxed by DFT	
			GB period (Å)	Disclination density (Å ⁻¹)	GB period (Å)	Disclination density (Å ⁻¹)
1	6.01 †	91	23.7608	0.0842	23.3084	0.0858
2	7.34	61	19.4537	0.1028	19.0835	0.1048
3	9.43	37	15.1509	0.132	14.8627	0.1346
4	10.99	109	26.0123	0.1537	25.5172	0.1568
5	13.17 ‡	19	10.8593	0.1842	10.6527	0.1877
6	16.43	49	17.4449	0.2293	17.1116	0.2337
7	17.9 †	93	24.0326	0.2497	23.5727	0.2545
8	21.79 ‡	7	6.6012	0.3029	6.4725	0.309
9	26.01 ‡	79	22.1546	0.3611	21.7306	0.3681
10	27.8	39	15.5647	0.3855	15.2662	0.393
11	29.41	97	24.5397	0.4075	24.0737	0.4154
12	32.2	13	8.9919	0.4448	8.8178	0.4536
13	35.57	67	20.3977	0.3922	20.0072	0.3998
14	40.35 $^\dagger, \ddagger$	103	25.2933	0.3163	24.8106	0.3224
15	42.1	31	13.8792	0.2882	13.6149	0.2938
16	44.82 †	43	16.3393	0.2448	16.0284	0.2496
17	46.83	57	18.8093	0.2127	18.4503	0.2168
18	48.36 $^\dagger, \ddagger$	73	21.2859	0.1879	20.8804	0.1916
19	49.58	91	23.7631	0.1683	23.3122	0.1716
20	50.57	111	26.2369	0.1524	25.7374	0.1554

be used for general cases, using preexisting knowledge on the system of study, if it is available, can be more efficient. As an example, the active learning schemes need to scan the large configurational space of GBs until they find no additional GB structures required for the training dataset. Additionally, the active learning scheme is more suitable for MD simulation in which a training dataset is added based on the measured uncertainty at each time step. For phonon transport simulation, the lattice dynamics-based method (e.g., AGF) has several important advantages over MD simulations such as modal analysis and no statistical error.

We use the fact that most GBs have hierarchical structures with basic building blocks, as demonstrated in the previous studies that analyzed the GB structures with the structural unit model [51–53]. A basic idea is to identify those basic building blocks or unique local atomic environments (LAEs) from many GBs and find a small set of GBs that contain the complete set of the unique LAEs [54]. Then an MLIP trained with the data from the small set of GBs is expected to accurately capture the interatomic interactions of GBs in the entire configurational space.

We used the smooth overlap of atomic positions (SOAP) [55] descriptor to find the smallest GB dataset that contains all the representative LAEs in the 20 GBs. The SOAP descriptor places a Gaussian function on each atom to construct the density of neighbor atoms ρ_i , which is then expanded in a basis set of radial functions $g_n(r)$ and spherical harmonics $Y_{lm}(\mathbf{r})$ as

$$\rho_i(\mathbf{r}) = \sum_{nlm} c_{nlm}^{(i)} g_n(r) Y_{lm}(\mathbf{r}), \quad (1)$$

where $c_{nlm}^{(i)}$ are the expansion coefficients for atom i . The descriptor is formed from these coefficients by computing the power spectrum elements:

$$p_{nn'l}^{(i)} = \frac{1}{\sqrt{2l+1}} \sum_m c_{nlm}^{(i)} [c_{n'l'm}^{(i)}]^*. \quad (2)$$

The resulting descriptor has invariance under translation, rotation, and the permutation of atoms. For each GB, a SOAP descriptor for each atom i in the GB is calculated and represented as coefficients of basis functions $\mathbf{p}_i = \{p_1, p_2, \dots, p_N\}$. The length of the SOAP vector N is determined by a radial basis cutoff $n_{\max}$ and an angular basis (spherical harmonic) cutoff $l_{\max}$. We evaluate the dissimilarity of LAEs using SOAP descriptors which is defined as [54]

$$d_{ij} = \sqrt{\mathbf{p}_i \cdot \mathbf{p}_i + \mathbf{p}_j \cdot \mathbf{p}_j - 2\mathbf{p}_i \cdot \mathbf{p}_j}, \quad (3)$$

where $\mathbf{p}_i$ and $\mathbf{p}_j$ are the SOAP vectors for the two atoms i and j . We introduce a parameter ε , serving as a criteria for the unique LAE. If $d_{ij} > \varepsilon$, the $\mathbf{p}_i$ and $\mathbf{p}_j$ are different from each other, indicating that the two atoms i and j are surrounded by different LAEs. Otherwise, we determine $\mathbf{p}_i$ and $\mathbf{p}_j$ represent the same LAE. In this paper, we used 0.04 for the value of ε .

The 20 GBs covering the full span of θ_M contain a total of 5544 LAEs, and the dissimilarity analysis shows that there exists significant overlap among the 5544 LAEs; the total 5544 LAEs can be reduced to only 12 and 13 unique LAEs for the structures relaxed by TSF and DFT, respectively. The TSF and DFT produce slightly different structures after relaxation, and hence, the number of unique LAEs also differ. The analysis shows that the total 20 GBs covering the full span of θ_M can be composed using those 12 or 13 unique LAEs, confirming

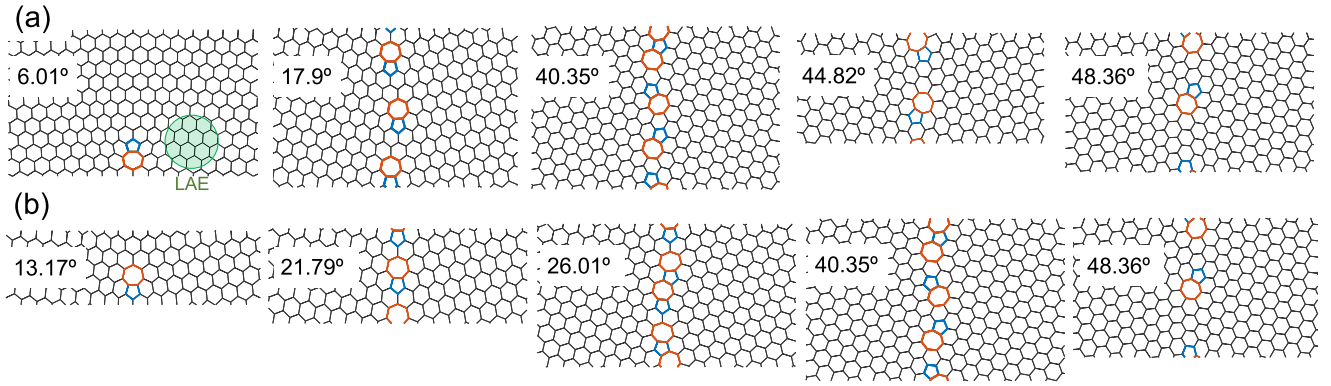


FIG. 1. Five representative grain boundaries (GBs) from (a) the Tersoff potential (TSF) and (b) density functional theory (DFT) showing distinct features such as density of disclinations and their topological arrangements. The angle in each figure shows the misorientation angle. The green circle shows the cutoff radius for defining the local atomic environment (LAE).

the idea that the extremely large configurational space of GBs in fact have a very small number of basic building blocks. We then identified five representative GBs, shown in Fig. 1, that contain all 12 or 13 unique LAEs. The selected GBs significantly differ from each other in terms of the topological arrangements and the density of disclinations. We used the 5 GBs to generate a training dataset for our GAP and train the GAP and performed the AGF simulation with the GAP to simulate the phonon transport across GBs, as discussed in the Methods sections.

B. Training the GAP

We trained two separate GAPs: GAPTSF for the validation of our methods using relatively cheap TSF potential and GAPDFT for studying of phonon transport across GBs with *ab initio* accuracy. For the training dataset, we performed MD simulations of the five representative GBs and obtained the snapshots of the atomic position, force, and energy. The MD simulations were performed at 300 K in the NVT ensemble with a time step of 0.5 fs. After initial time steps for thermal equilibration, we took one snapshot every 50 time steps to reduce the correlation between snapshots. The training datasets for both GAPTSF and GAPDFT include relaxed structures of the five selected GB structures and 50 snapshots for each

GB at 300 K. After obtaining the training dataset, we used the hyperparameters listed in Table II to train GAPTSF and GAPDFT.

C. AGF simulation

For the AGF simulation, the supercell needs to be sufficiently large so that the leads do not have strain from a GB. The supercell we used for the AGF calculation is 10 times longer in the direction perpendicular to GBs than those we used for SOAP dissimilarity analysis and training the GAP. Since the AGF simulation does not require translational symmetry along the heat flow direction, the supercells for the AGF calculation contain only 1 GB for each, unlike those for training the GAP that have 2 GBs. The comparison of supercells for GAP training and AGF simulation in terms of the size can be found in Table S1 in the Supplemental Material [45]. The second-order force constants were calculated using PHONOPY [56] and LAMMPS [57] with GAPTSF or GAPDFT. In the AGF simulation, we used a decimation technique [58,59] to approximate surface Green's functions, and we used a frequency broadening factor of 1 cm^{-1} for the continuous representation of discrete eigenfrequencies. We observed a good convergence of transmission functions with 20 transverse wave vectors for the GB with the largest width

TABLE II. List of hyperparameters for GAPTSF and GAPDFT.

Hyperparameter	Note	2-body	3-body	SOAP
r_{cut} (Å)	Cutoff radius of the descriptor	4.0	4.0	4.0
d (Å)	Transition width over which the magnitude of SOAP descriptor monotonically decrease to 0	–	–	1.0
δ (eV)	Weight of different descriptors	10.0	3.7	0.07
N_i	Number of representative atomic environments selected using the corresponding sparse method	50	200	650
Sparse method		Uniform	Uniform	CUR
n_{max}	Radial basis cutoff	–	–	12
l_{max}	Angular basis cutoff	–	–	12
σ_{energy} (eV/atom)	Expected error for atomic energy		0.001	
σ_{force} (eV/Å)	Expected error for force		0.0005	

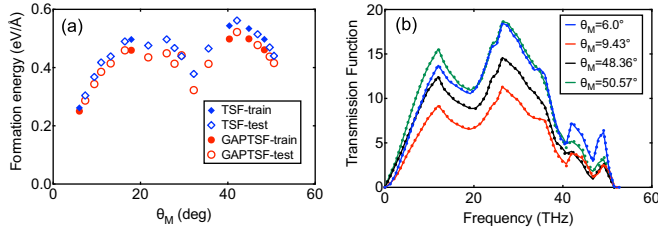


FIG. 2. Validation of the Gaussian approximation potential based on the Tersoff potential (GAPTSF) against the Tersoff potential (TSF) for (a) formation energy of grain boundaries (GBs) and (b) transmission function. The solid symbols in (a) represent GBs used for training GAPTSF. The solid lines and dots in (b) are from GAPTSF and TSF, respectively. In (b), the two GBs with $\theta_M = 6.0^\circ$ and 48.36° and the other two GBs with $\theta_M = 9.43^\circ$ and 50.57° are from the training and testing dataset, respectively.

($\theta_M = 50.57^\circ$). For the other GBs, the number of transverse wave vectors was determined such that the product of the number of transverse wave vectors and the width of the GB are the same for all GBs.

III. RESULTS AND DISCUSSIONS

We use GAPTSF to validate our simulation framework from selecting representative GBs to the AGF calculation. Unlike *ab initio* calculation, the TSF potential is computationally cheap enough to generate the data of interatomic force constants and transmission functions of all 20 GBs. Therefore, GAPTSF can be directly validated against the results from TSF for all 20 GBs. In Fig. 2, we compare GAPTSF and TSF for the GB formation energy and spectral phonon transmission function. GAPTSF and TSF agree well with each other for the prediction of the GB energy for both the training and testing GBs. The spectral phonon transmission functions, the properties of interest in this paper, are similar for all GBs. This confirms that the 5 GBs chosen from the LAE analysis are enough to represent all 20 GBs, and thus, the resulting GAP is highly accurate and reliable for a wide range of GBs.

With the success of GAPTSF, we proceeded to develop GAPDFT using the training dataset from DFT calculation. Like GAPTSF, GAPDFT also shows excellent accuracy. The root-mean-square of errors (RMSE) of energy and force are 0.0011 eV and 0.052 eV/Å, respectively, for the training set, and the RMSE of energy and force are 0.0019 eV and 0.066 eV/Å, respectively, for the testing set. In Fig. 3, we examine GAPDFT compared with DFT for the relaxed atomistic structures. The structures relaxed by GAPDFT are like those by DFT, particularly for the out-of-plane atomic displacements.

Figure 4 presents the GB formation energy from GAPDFT and DFT, showing good agreement between them for the entire range of θ_M . The overall trend of GB formation energy from GAPDFT follows the trend predicted by the Read-Shockley model [60]; the GB formation energy is linear to θ_M for low θ_M ($<15^\circ$) and high θ_M ($>45^\circ$), while the midrange θ_M show nonmonotonic behavior of GB formation energy with respect to θ_M .

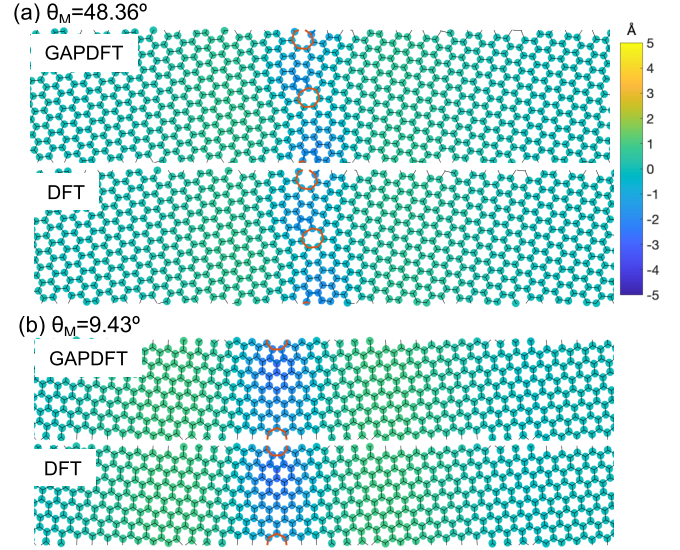


FIG. 3. Validation of the Gaussian approximation potential based on density functional theory (GAPDFT) against density functional theory (DFT) for relaxed structures projected onto the *a-b* plane. (a) $\theta_M = 48.36^\circ$ from the training dataset and (b) $\theta_M = 9.43^\circ$ from the test dataset. The color represents out-of-plane displacement in angstroms.

In Fig. 4(b) and 4(c), we separate the GB formation energy into the contribution from local dislocation cores (core energy, E_{core}) and surrounding strain field (strain energy, E_{strain}) [61,62] to better understand the GB formation energy and its effects on phonon transport. The core energy (E_{core}) and strain energy (E_{strain}) can be defined as

$$E_{\text{core}} = \frac{\sum_i^{N_{\text{core}}} E_i - \frac{N_{\text{core}}}{N_{\text{tot}}} E_{\text{bulk}}}{l_{\text{unit}}}, \quad (4)$$

$$E_{\text{strain}} = \frac{\sum_i^{N_{\text{strain}}} E_i - \frac{N_{\text{strain}}}{N_{\text{tot}}} E_{\text{bulk}}}{l_{\text{unit}}}, \quad (5)$$

where N_{core} and N_{strain} are the number of atoms forming dislocation cores (pentagons and heptagons) and hexagon lattices, respectively. The N_{tot} is the total number of atoms. The E_{bulk} and l_{unit} are the energy per atom in the perfect crystalline phase and the length of the GB. The core energy and strain energy from GAPDFT in Figs. 4(b) and 4(c) seem physically reasonable. The dislocation density linearly increases with θ_M , has a maximum value at mid- θ_M , and linearly decreases with θ_M (see Fig. S2 in the Supplemental Material [45]). Therefore, the core energy in Fig. 4(b) is maximum in the mid- θ_M range where the dislocation density is maximum. The strain energy is minimum in the same θ_M range where the lattice can open up to insert one additional lattice plane to form an edge dislocation, and thus, the strain is minimized [63]. One of the noteworthy advantages of MLIPs over DFT is that the MLIPs can predict the contribution of each atom to total energy, while DFT cannot in principle. Although partitioning the total energy into the contribution of each individual atom is somewhat arbitrary in the MLIP scheme, it provides qualitatively reasonable results compared with the DFT simulation,

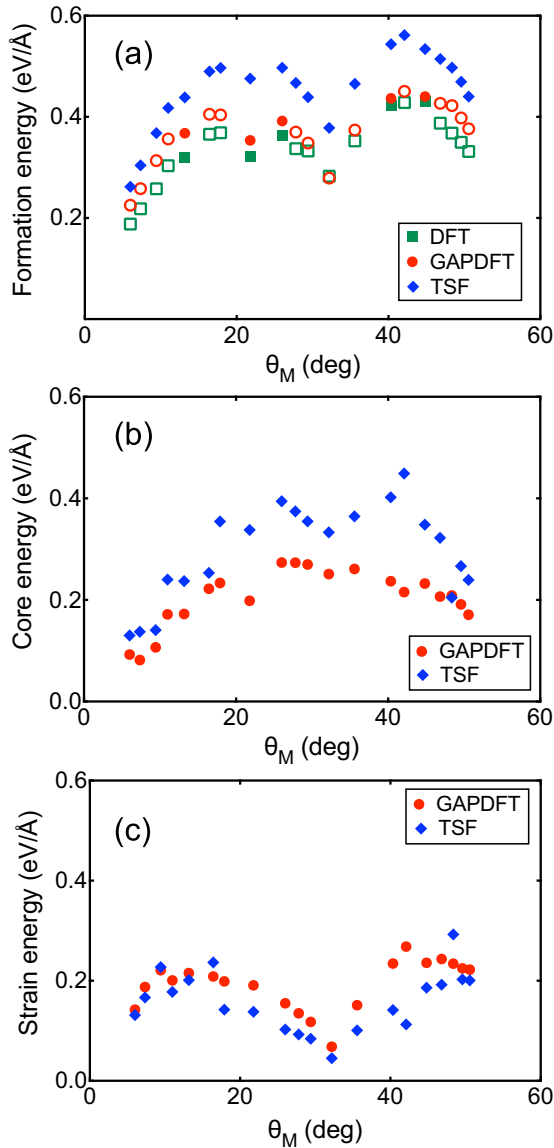


FIG. 4. Comparison of density functional theory (DFT), the Gaussian approximation potential based on density functional theory (GAPDFT), and the Tersoff potential (TSF) for (a) grain boundary (GB) formation energy, (b) core energy, and (c) strain energy. The solid symbols in (a) represent the GBs that were used for training GAPDFT.

as shown in the GB formation energy of the GBs that are not included in the training process.

In Fig. 5, we present the thermal resistance as a function of θ_M at various temperatures from the AGF and the Landauer formalism calculations. At high temperatures of 500 and 1500 K in Figs. 5(c) and 5(d), the thermal resistance has a concave shape with respect to θ_M , having a maximum resistance value at the mid- θ_M range. This behavior is like the case of Si and diamond at 1000 K that a previous study reports, using MD simulation with an empirical potential [8]. A common explanation for this behavior has been that the dislocation density is the maximum in the mid- θ_M , and thus, the phonon scattering by GBs is expected to be maximum in the mid- θ_M range. However, we observe different behav-

iors at low temperatures at 300 and 100 K. At 300 K in Fig. 5(b), the concave shape of thermal resistance becomes negligible, and the resistance is nearly independent of θ_M . As temperature further decreases to 100 K in Fig. 5(a), the thermal resistance shows a convex shape with respect to θ_M , having the lowest thermal resistance at mid- θ_M . The behavior of thermal resistance at 100 and 300 K is clearly opposite to the current understanding that the higher dislocation density leads to higher thermal resistance. For graphene GBs, the higher dislocation density does not necessarily lead to higher thermal resistance. At 100 K, the thermal resistance is even higher when the dislocation density is smaller.

A possible explanation for this intriguing behavior of thermal resistance as a function of θ_M at different temperatures is that the dislocation core and nearby strain field affect the phonon scattering by GBs to different extents at different temperatures. At low temperatures, heat is mostly carried by long-wavelength phonons which experience only weak scattering by dislocation cores since the wavelength is much longer than the characteristic size of the cores. The strain field can be a major contributor to the phonon scattering at low temperature due to its spatially extended characteristics. This is supported by the fact that the strain energy distribution in Fig. 4(c) and the thermal resistance at 100 K in Fig. 5(a) have a similar trend with respect to θ_M ; both thermal resistance and strain energy are minimum in mid- θ_M . At high temperatures where the short-wavelength phonons are the major heat carriers, the wavelengths become comparable with the size of dislocation cores which thus cause strong scattering due to their nature of large lattice distortion compared with the strain field. The thermal resistance at 500 and 1500 K in Fig. 5 follow a similar trend as the core energy in Fig. 4(b).

Observing the important role of the strain field for phonon scattering at low temperatures, we further investigate its detailed mechanisms. Figures 6(a) and 6(b) show the thermal conductance normalized by the ballistic thermal conductance of perfect graphene as a function of temperature. The normalization eliminates the specific heat effects from the conductance and thus shows how much the thermal conductance is suppressed by phonon scattering at a GB at various temperatures. The total 20 GBs can be clearly separated into two groups: one showing monotonously decreasing normalized thermal conductance as a function of temperature, shown in Fig. 6(a), and the other showing increasing at low temperature and then decreasing normalized thermal conductance with temperature, shown in Fig. 6(b). It is interesting to see that most GBs of the first group are from mid- θ_M , while the latter group is from small and large θ_M . To explain the different behavior of the two GB groups, we consider spectral transmissivity defined as the phonon transmission function across a GB normalized by the ballistic phonon transmission function across single-crystalline graphene. In Fig. 6(c), we present the spectral transmissivity for the two GBs with θ_M of 6.02° and 32.20° that represent each group. In the frequency range <15 THz which dominates the thermal transport below room temperature, the two GBs show a remarkable difference. While the spectral transmissivity is high and nearly constant for the GB with $\theta_M = 32.20^\circ$, the transmissivity for the GB with $\theta_M = 6.02^\circ$ is low and increases rapidly with frequency. It is noteworthy that the majority of phonon states

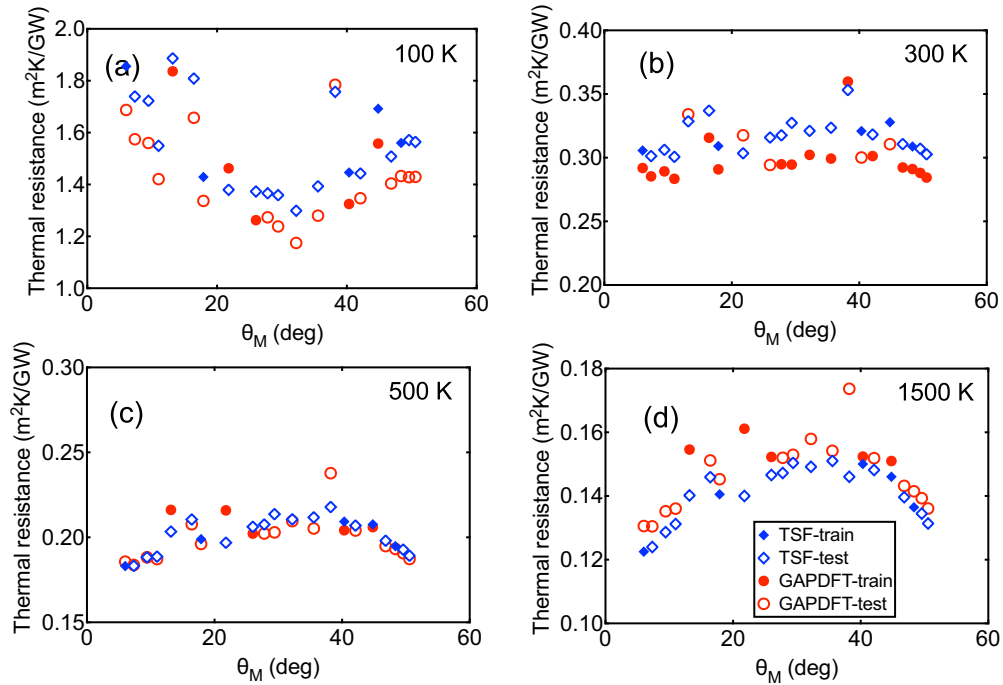


FIG. 5. Thermal resistance with varying misorientation angles at (a) 100 K, (b) 300 K, (c) 500 K, and (d) 1500 K.

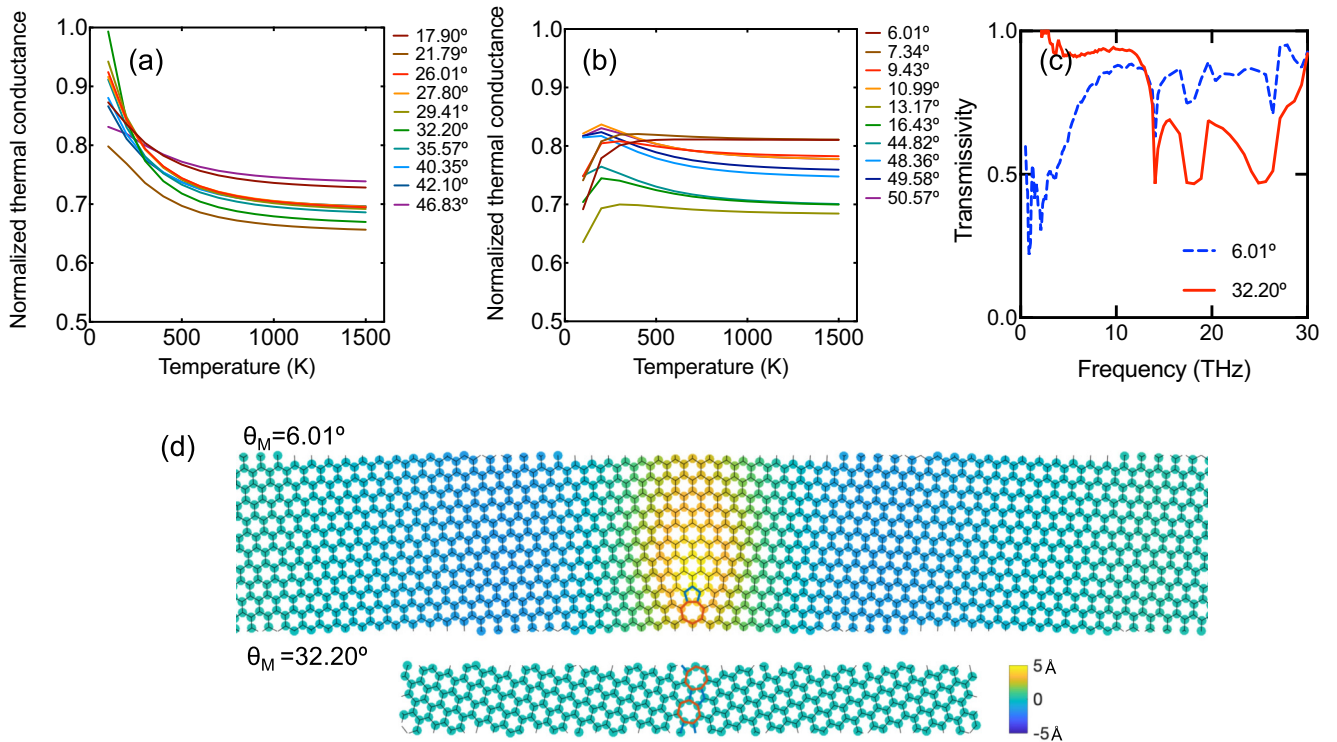


FIG. 6. Role of out-of-plane buckling for scattering of flexural phonon modes. Thermal conductance normalized by that of perfect crystalline graphene as a function of temperature for (a) grain boundaries (GBs) showing monotonously decreasing behavior and (b) GBs showing increasing behavior at low temperatures. The values in the legends represent misorientation angle. (c) Phonon transmissivity for two representative GBs showing a remarkable difference in low phonon frequency range <15 THz. (d) Comparison of the two representative GBs in terms of out-of-plane buckling. The color represents out-of-plane displacement of atoms, and the pentagon and heptagon are marked in blue and red, respectively.

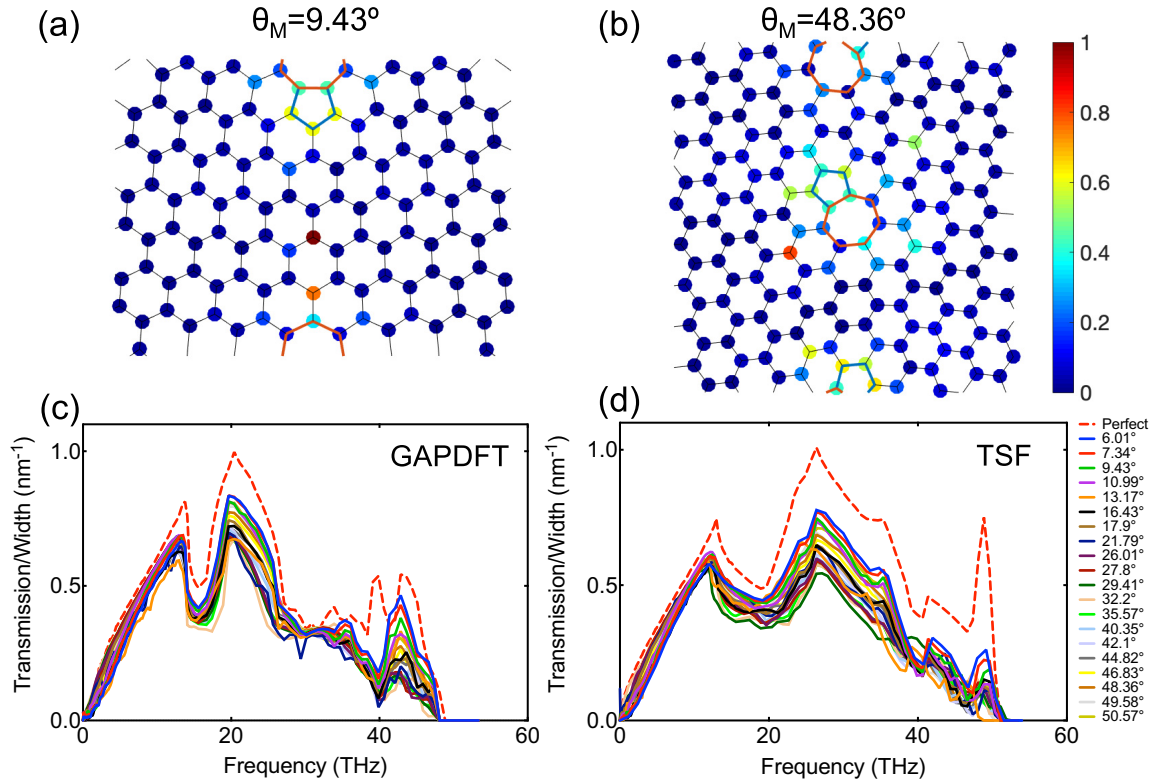


FIG. 7. Comparison of the Tersoff potential (TSF) and the Gaussian approximation potential based density functional theory (GAPDFT), showing inaccuracy of TSF for predicting force constants on dislocation cores and transmission function above midphonon frequency. (a) and (b) Normalized error of self-interatomic force constants, defined as $|\Delta\phi_{ii,TSF} - \Delta\phi_{ii,GAPDFT}|/\Delta\phi_{ii,GAPDFT}$, where $\Delta\phi_{ii}$ is the difference of self-interaction force constants in the grain boundary (GB) and perfect graphene. (c) and (d) Suppressed transmission function from perfect graphene for 20 GBs. The values in the legend are misorientation angles.

<15 THz are from the flexural acoustic phonon branch due to the quadratic phonon dispersion and large density of states.

The remarkably different scattering of flexural modes in the two GB groups originates from the structural difference, particularly buckling induced by a GB. This is consistent with the previous studies [64,65] that showed flexural modes are strongly scattered by buckling of the GB structure. Figure 6(d) shows that the two groups of GBs are very different in terms of out-of-plane buckling. The common disclinations in graphene, pentagon and heptagon, create compression and dilation stress at the tips of disclinations, respectively. When a GB has low or high θ_M , the pentagon and heptagon disclinations are far from each other due to the low density of dislocations, and thus, the out-of-plane buckling is induced to reduce the compressive and dilation strain. On the contrary, when a GB has mid- θ_M , the disclination cores are densely packed along the GB line with the pentagon and heptagon cores placed next to each other. In such a case, the compressive and dilation strain are canceled, and the out-of-plane buckling does not occur [60]. Therefore, at low temperatures where the thermal phonon wavelength is comparable with the characteristic length of buckling, the significant buckling in GBs with low and high θ_M causes strong scattering of the flexural phonon modes. As a result, the GBs with low and high θ_M exhibit higher thermal resistance at 100 K than those with mid- θ_M in Fig. 5(a), although they have lower dislocation density.

Lastly, it would be interesting to present a brief comparison of GAPDFT and TSF since the TSF has been widely used in past studies, while its accuracy for phonon transport across GBs has not been comprehensively examined. In Fig. 4, we compare GAPDFT and TSF for the GB formation, core, and strain energies. Figure 4(a) shows that the TSF overestimates the GB formation energy compared with GAPDFT. This is because the core energy from TSF is larger than that from GAPDFT in the mid- θ_M range where the density of dislocation core is maximum, as shown in Fig. 4(b). On the contrary, for strain energy in Fig. 4(c), the TSF and GAPDFT show similar predictions for the wide range of θ_M , although the strain energy from TSF is slightly smaller. The comparison of the core and strain energy from TSF and GAPDFT indicates that TSF is reasonably accurate in predicting the energy of strained hexagon structure, while it is poor in predicting the energy of severely distorted structures such as pentagons and heptagons.

The thermal resistances from TSF and GAPDFT in Fig. 5 are observed as similar, but the force constants and spectral transmission functions behind the thermal resistance values are noticeably different for TSF and GAPDFT. For the self-interaction force constant in the crystalline phase, the TSF overpredicts by 35% compared with GAPDFT (see Fig. S3 in the Supplemental Material [45]). The force constant prediction by TSF has a more pronounced error in the core region of GBs. In Figs. 7(a) and 7(b), we present the

error of TSF in predicting force constant change upon the introduction of GBs. We define the normalized error as $|\Delta\Phi_{ii,\text{TSF}} - \Delta\Phi_{ii,\text{GAPDFT}}|/\Delta\Phi_{ii,\text{GAPDFT}}$, where Φ_{ii} is a self-interaction force constant, and $\Delta\Phi_{ii}$ is the difference of a self-interatomic force constant from the perfect crystalline case (i.e., $\Phi_{ii,\text{GB}} - \Phi_{ii,\text{crystal}}$). The figure shows that the error in the core region is pronounced and reaches up to 50%, while the error is small for the surrounding hexagons. This agrees with the aforementioned observation that the TSF has significant error for dislocations, while it is reasonably accurate for strained hexagons. As a result, the spectral transmissions from GAPDFT and TSF in Fig. 7(c) and 7(d) show substantial difference >20 THz where dislocation cores are important for phonon scattering. Overall, the suppression of transmission functions from the perfect crystalline phase is noticeably larger in TSF than in GAPDFT, also supported by the overprediction of core energy by TSF in Fig. 4(b). However, <20 THz where the strain field is the dominant cause for phonon scattering, GAPDFT and TSF show similar suppression of the spectral transmission function.

IV. CONCLUSIONS

In summary, we demonstrated that MLIPs trained with the rationally designed minimal dataset can predict phonon transport across GBs with *ab initio* predictive power and accuracy, while the computational cost is affordable. Special attention was paid on reducing the required training dataset by employing the idea of the structural unit model that GBs have hierarchical structures and have only a few basic building blocks. Our approach shows that only 5 GBs are enough to represent the entire configurational space, and thus, the small training dataset using those 5 GBs is sufficient for an MLIP. Indeed, our test using TSF and GAPTSF shows that force constants and spectral transmission functions from the TSF and GAPTSF are similar for 20 GBs covering the entire configurational space.

GAPDFT trained with the dataset from DFT reveals several intriguing characteristics of phonon scattering by GBs with *ab initio* accuracy. Previous studies for 3D bulk materials suggested that thermal resistance increases with dislocation

density, but we showed that graphene does not follow the same trend. The thermal resistance at room temperature does not depend on the dislocation density and even decreases with increasing dislocation density. We explained this with the 2D structural characteristics of graphene: flexural phonon modes carrying the majority of heat and out-of-plane buckling induced by GBs. The heat-carrying flexural phonon modes are strongly scattered by the out-of-plane buckling which is pronounced for the GBs with low dislocation density. Thus, dislocation density alone cannot determine the scattering of phonons in polycrystalline graphene, but the surrounding strain field plays an important role.

We also briefly examined the accuracy of TSF for thermal transport across GBs by comparing it with GAPDFT. The overall thermal resistance values from both TSF and GAPDFT reasonably agree with each other, but the force constants and spectral transmission functions show a noticeable difference. TSF shows inaccuracy in predicting dislocation cores (pentagons and heptagons), while it is reasonably accurate for the strain field. As a result, the transmission functions from TSF agree with those from GAPDFT at low frequency where the strain field is important for phonon scattering, but they show noticeable error in the mid- to high-frequency range.

In this paper, we provide deep insight into the atomic-level mechanisms governing phonon transport across graphene GBs, particularly for the buckling effects on phonon transmission and thermal resistance. This understanding may help to explain phonon transport across GBs in other 2D materials and also to engineer their thermal properties using GBs. The present method for developing MLIPs with a minimal training dataset can be easily extended to 3D materials. It would help to predict and understand thermal transport in the polycrystalline phase of emerging materials for which a reliable interatomic potential has not yet been developed.

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