



Model for $1/f$ Flux Noise in SQUIDs and Qubits

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We propose a model for $1/f$ flux noise in superconducting devices (f is frequency). The noise is generated by the magnetic moments of electrons in defect states which they occupy for a wide distribution of times before escaping. A trapped electron occupies one of the two Kramers-degenerate ground states, between which the transition rate is negligible at low temperature. As a result, the magnetic moment orientation is locked. Simulations of the noise produced by randomly oriented defects with a density of $5 \times 10^{17} \text{ m}^{-2}$ yield $1/f$ noise magnitudes in good agreement with experiments.

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The phenomenon of $1/f$ noise, with spectral density $S(f)$ scaling inversely with frequency f , is common to virtually all devices. In this Letter, we are concerned with the origin of $1/f$ magnetic flux noise in dc SQUIDs (Superconducting QUantum Interference Devices) and superconducting flux qubits (quantum bits). In 1983, Koch *et al.* [1] identified two separate sources of $1/f$ noise in dc SQUIDs: critical-current noise and flux noise. The $1/f$ flux noise $S_{\Phi}^{1/2}$ (1 Hz) was within a factor of 3 of $10 \mu\Phi_0 \text{ Hz}^{-1/2}$ for Nb- or Pb-based SQUIDs at 4.2 K, even though the areas of the SQUID loops ranged over 6 orders of magnitude; here, Φ denotes magnetic flux and $\Phi_0 \equiv h/2e$ is the flux quantum. Subsequently, Wellstood *et al.* [2] reported values of $S_{\Phi}^{1/2}$ (1 Hz) of (4–10) $\mu\Phi_0 \text{ Hz}^{-1/2}$ at temperatures below 0.1 K in 12 Nb, Pb, and PbIn SQUIDs. Recently, Yoshihara *et al.* [3] measured the decoherence time in Al-based flux qubits at 20 mK and deduced that decoherence was induced by $1/f$ flux noise with $S_{\Phi}^{1/2}$ (1 Hz) $\approx 1 \mu\Phi_0 \text{ Hz}^{-1/2}$. The value of $S_{\Phi}^{1/2}$ (1 Hz) in the SQUIDs of Wellstood *et al.*, with areas up to $2 \times 10^5 \mu\text{m}^2$, is at most 1 order of magnitude higher than that in these qubits which have an area of about $3 \mu\text{m}^2$, 5 orders of magnitude less. These results, and those of Ref. [1], rule out the notion of a “global magnetic field noise”.

Critical-current fluctuations in Josephson junctions are understood to arise from the trapping and release of electrons in traps in the tunnel barrier [4–6]. In the case of high transition temperature (T_c) SQUIDs at 77 K, $1/f$ flux noise is ascribed to thermal activation of vortices among pinning sites. This noise can be eliminated by reducing the linewidth to below $(\Phi_0/B)^{1/2}$ [7]; B is the magnetic field in which the device is cooled. Given that the low- T_c devices are made of films with a much higher pinning energy, are operated at much lower temperatures, and may have linewidths orders of magnitude less than $(\Phi_0/B)^{1/2}$, vortex motion is not a viable mechanism for their $1/f$ flux noise. Thus, the origin of $1/f$ flux noise in low- T_c devices has remained an unsolved puzzle.

In this Letter, we propose a model for $1/f$ flux noise in low- T_c devices. Our basic assumption is that the noise is generated by unpaired electrons that hop on and off defect centers by thermal activation. The spin of an electron is locked in direction while the electron occupies a given trap; this direction varies randomly from trap to trap. The relevant trapping energies have a broad distribution on the scale of $k_B T$ [8], so that the characteristic times over which an electron resides on any one defect vary over many orders of magnitude. The uncorrelated changes of these spin directions yield a series of random telegraph signals that sum to a $1/f$ power spectrum [9]. There are many candidates for defect centers. In amorphous SiO_2 , these include E' center variants, the nonbridging oxygen hole center (NBOHC), and the superoxide radical [10]. In addition, the amorphous oxides of superconductors such as AlO_x and NbO_x contain large densities of defects of various sorts: for example, the concentration of OH defects in AlO_x can reach several percent [11,12].

One has first to understand how the direction of an electron spin can remain fixed for very long periods of time—longer than the inverse of the lowest frequency at which the $1/f$ noise is observed, say, 10^{-4} Hz. Our key assumption is that an electron randomly adopts a low-energy spin direction when it arrives at a defect, and that it remains *locked* in that orientation during its entire residence time. If the magnetic field \mathbf{B} is zero, Kramers' theorem [13] guarantees that the ground state is doubly degenerate, the two states having oppositely directed angular momenta [Fig. 1(a)]. It is well known that scattering mechanisms that take the electron from one member of the doublet to the other are extremely weak: the “Van Vleck cancellation” [14] implies that direct phonon scattering is forbidden. Higher order processes are allowed, but those that have been studied are strongly suppressed at low temperature; for example, the phonon Raman scattering rate [15] has a temperature dependence of T^{13} .

Of course, the magnetic field is not strictly zero; any particular defect experiences fluctuating dipole fields from neighboring defects of the order of 10^{-4} T (root mean

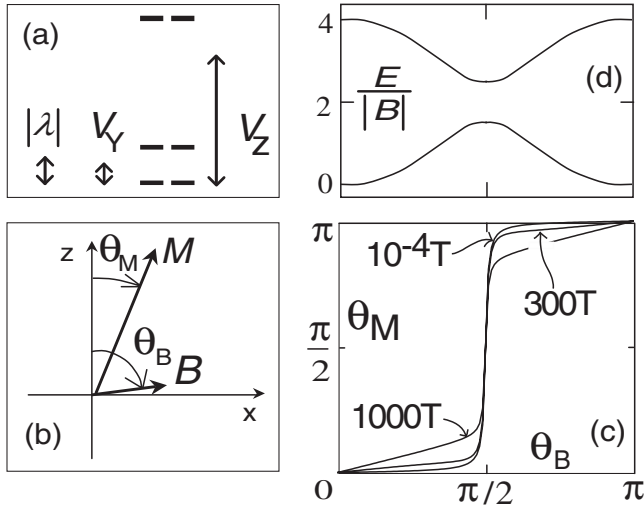


FIG. 1. (a) Properties of the p orbital defect model, Eq. (1). We take crystal-field parameters $V_x = 0$, $V_y = 400$ K, $V_z = 2000$ K, and spin-orbit coupling $\lambda = -600$ K. (a) The six energy levels of the model. The levels do not carry definite angular momentum quantum numbers, but occur in Kramers-degenerate pairs, no matter how strong the spin-orbit coupling. The mixing of the lowest four levels when $|\lambda|$ is comparable to the crystal-field parameters $V_{y,z}$ results in a locking of the magnetic moment direction; this locking is not present if $|\lambda| \gg V_{y,z}$ or if $|\lambda| \ll V_{y,z}$. (b) The idea of locking: even if the applied field B is at a large angle θ_B from the principal axis z of the crystal field, the resultant magnetization vector M lies at a small angle θ_M from z . (c) The calculated θ_M vs θ_B for $|B| = 10^{-4}$ T, 300 T, and 1000 T. For a defect with these parameters, locking is strong for any practical field; it remains strong up to near 1000 T, when the magnetic energy in Eq. (1) becomes comparable to the crystal-field and spin-orbit energies. M unlocks as θ_B passes through $\pi/2$, rotating rapidly to the opposite direction; however, if θ_B is large enough, this rapid rotation is prevented by Landau-Zener tunneling between the first and second energy levels. (d) The anticrossing of these levels near $\theta_B = \pi/2$; $E/|B|$ is in units of μ_B . The anticrossing gap scales with $|B|$, so that this Landau-Zener tunneling will occur readily at low fields.

square). The magnetic moment vector of the defect $\hat{M} = \mu_B(\hat{L} + 2\hat{S})$ can be locked as a result of spin-orbit coupling, making it stable with respect to these field fluctuations. The following model Hamiltonian [16] provides a good generic description of this locking effect:

$$\hat{H} = \sum_{i=x,y,z} V_i |p_i\rangle\langle p_i| + \lambda \hat{L} \cdot \hat{S} + \mu_B \mathbf{B} \cdot (\hat{L} + 2\hat{S}). \quad (1)$$

In this model, the unpaired electron occupies a p orbital; the $V_{x,y,z}$ are the matrix elements of the crystal-field potential (there will be a preferred coordinate system, varying randomly from defect to defect, for which the crystal-field tensor is diagonal, as shown). The spin-orbit coupling constant λ is observed to have a large range of possible magnitudes for different defects, in the range of [16] 10 K to 5000 K, but for defects involving atomic weights near that of silicon, $|\lambda| \approx 300$ K is typical [16]. The scale of the

crystal-field parameters $V_{x,y,z}$ is set by chemical energies, ranging up to [16] ≈ 2000 K. The orbital angular momentum of simple defects may be “quenched” [17], meaning that $\langle \hat{L} \rangle = 0$ and that the magnetic moment arises only from the (unlocked) spin angular momentum. Equation (1) exhibits this behavior if $|V_i - V_j| \gg |\lambda|$ ($i \neq j = x, y, z$). But, it seems quite reasonable that there is a substantial subpopulation of defects for which $|V_i - V_j| \approx |\lambda|$, and for these Figs. 1(b) and 1(c) show that the direction of $\mathbf{M} = \langle \Psi_0 | \hat{M} | \Psi_0 \rangle$ for the ground state $|\Psi_0\rangle$ is very stable with respect to variations in the direction of a 10^{-4} -T magnetic field, being locked to the principal axis of the crystal field. In defects for which $\lambda < 0$, L and S are parallel and M is large, while for the $\lambda > 0$ defects, M is near zero (i.e., the anisotropic Landé g factor is near zero) because L and S are antiparallel; thus, we expect the $\lambda < 0$ subpopulation to be most important for flux noise.

Given this picture of the underlying physical processes, we now calculate the flux noise coupled into a SQUID or qubit (henceforth succinctly referred to as “SQUID”) by a spatially random distribution of electron spins fluctuating in orientation. We assume that the defects are randomly distributed over the substrate, with uniform areal density n . We consider three regions (inset, Fig. 2): the hole of the SQUID (“hole noise”), the region outside the SQUID (“exterior noise”), and the loop itself (“loop noise”) [18]. For purposes of simulating the coupling between an electron magnetic moment and the SQUID, we represent the moment by a small test current loop. The SQUID loop lies in the plane $z = 1 \mu\text{m}$, has inner and outer dimensions of $2d$ and $2D$, and a thickness of $0.1 \mu\text{m}$. The current loop is in the plane $z = 0$ [“perpendicular (p) moment”] or in the x or y plane, centered at $z = 0$ [“in-plane (i) mo-

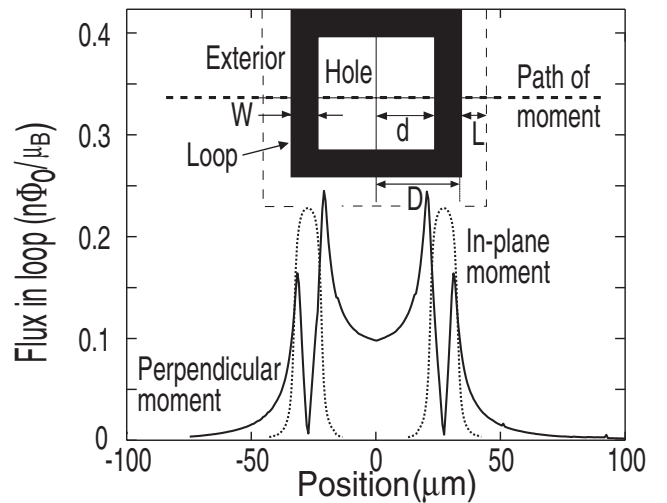


FIG. 2. Magnitude of the flux per Bohr magneton coupled to SQUID loop by a current loop moved along the line indicated. “In-plane” and “perpendicular” refer to the orientation of the magnetic moment. SQUID dimensions are $2D = 52 \mu\text{m}$ and $2d = 41.6 \mu\text{m}$. Inset shows configuration of SQUID loop.

ment²]. The test loop has an effective area $A = (0.1 \mu\text{m})^2$, a strip width $0.03 \mu\text{m}$, a thickness $0.1 \mu\text{m}$, and carries a current i chosen so that $Ai = \mu_B$, where $\mu_B = 9.27 \times 10^{-24} \text{ JT}^{-1}$ is the Bohr magneton (the scale of the magnetic moment of the defects). For the test loop at a specified location, we compute its mutual inductances M_p and M_i with the SQUID loop using the superconducting version of FastHenry [19]. The flux coupled into the SQUID for a single electron moment is given by $\Phi_s = M(x, y)i = M(x, y)\mu_B/A$. We calculate the quantity $\Phi_s/\mu_B = M(x, y)/A$ —the flux per Bohr magneton coupled into the SQUID loop.

In Fig. 2 we plot $|\Phi_s(x, y)|/\mu_B$ versus x for $y = 0$ for the magnetic moment perpendicular to the plane and in plane. For the perpendicular moment, $|\Phi_s(x, y)|/\mu_B$ has a local minimum at the center and increases towards either edge of the superconductor. When the moment is at the midpoint under (or over) the superconducting film, the coupled flux is zero as expected from symmetry. The flux coupled into the SQUID loop from an exterior moment also peaks at the edges of the superconductor. For the in-plane moment, $|\Phi_s(x, y)|/\mu_B$ peaks at the midpoints of the superconducting film and falls off rapidly as the moment moves away from the film. By symmetry, away from the superconducting region the flux would be zero if the moment and the SQUID loop were in the same plane. We showed that the results did not change when the area of the current loop was varied between $0.1A$ and $10A$.

To obtain the noise due to an ensemble of spins, we first integrate M_p and M_i over an element $dx dy$ in one quadrant. We cut off the integration at a distance $L = 100 \mu\text{m}$ beyond the outer edge of the SQUID, where M_p or M_i is 2 orders of magnitude less than at $(0, 0)$. For either case, the total mean square normalized flux noise coupled into the SQUID, summed over the hole, superconductor and exterior contributions, is given by $\langle(\delta\Phi_s)^2\rangle = 8n\mu_B^2 \int_0^{L+D} dx \int_0^x dy [M(x, y)/A]^2$. The total mean square noise is $\langle(\delta\Phi_{\text{st}})^2\rangle = [\langle(\delta\Phi_{\text{sp}})^2\rangle + \langle(\delta\Phi_{\text{si},x})^2\rangle + \langle(\delta\Phi_{\text{si},y})^2\rangle]/3$, the angular average of the quadrature sum of the noise from the three coordinate directions. To convert $\langle(\delta\Phi_{\text{st}})^2\rangle$ to a spectral density $S_\Phi(f) = \alpha/f$, where α is a constant, we introduce lower and upper cutoff frequencies, f_1 and f_2 , and set $\langle(\delta\Phi_{\text{st}})^2\rangle = \alpha \int_{f_1}^{f_2} df/f = \alpha \ln(f_2/f_1)$. Taking $f_1 = 10^{-4} \text{ Hz}$ and $f_2 = 10^9 \text{ Hz}$ (the results are only weakly sensitive to these values), we find $S_\Phi(f)/\Phi_0^2 \approx \langle(\delta\Phi_s/\Phi_0)^2\rangle/30f$.

We obtain noise levels in reasonable agreement with observations for $n = 5 \times 10^{17} \text{ m}^{-2}$. This value is 6 orders of magnitude higher than the value of about 10^{12} m^{-2} reported from measurements of two-level systems in Josephson junctions [11]. However, the two situations are physically very different. The thickness of the tunnel barrier is 2–3 nm, and the barrier is protected with a metallic layer immediately after its formation, before it is exposed to any contaminants. In contrast, the SiO_2 layer on a Si

wafer is typically 100 nm thick and, because of its exposure to processing chemicals and the atmosphere, is covered with contaminants that are likely to be highly disordered. For a 100-nm thickness, an areal density of $5 \times 10^{17} \text{ m}^{-2}$ corresponds to 1 defect in 10^4 atoms, which does not seem unreasonable. This areal density is also comparable with estimates of trap densities on silicon surfaces that have been exposed to atmospheric-like conditions [20]. Furthermore, room temperature scanning tunneling microscope experiments [21] on ultraclean silicon surfaces that were exposed to a low level of oxygen in an ultrahigh vacuum system revealed as many as eight near-surface two-level systems in an area of $4 \times 10^{-17} \text{ m}^2$ (i.e., a density of $2 \times 10^{17} \text{ m}^{-2}$) in a 10–500 Hz bandwidth, corresponding to $2 \times 10^{18} \text{ m}^{-2}$ over 13 decades of frequency. Thus, our required value of n does not seem beyond the realm of possibility. We note that the two SQUIDs with the lowest values of $1/f$ noise at 1 Hz and 4.2 K, $0.5 \mu\Phi_0 \text{ Hz}^{-1/2}$ [22] and $0.2 \mu\Phi_0 \text{ Hz}^{-1/2}$ [23], were passivated, and very likely had reduced levels of surface contamination.

We plot the normalized amplitude spectra of the flux noise in the SQUID at 1 Hz, $S_\Phi^{1/2}(1 \text{ Hz})/\Phi_0$, in Fig. 3. Figure 3(a) shows the contributions of the hole, loop, and exterior noises for the perpendicular moments, the loop noise for the in-plane moments, and the total noise versus the mean loop size $D + d$ for constant aspect ratio $2d/W$. All the contributions follow the same general trend, increasing by a factor of 4 when the loop area is increased by a factor of about 200. Figure 3(b) shows the same noise contributions versus $(D + d)$ for fixed W . As expected, the hole noise vanishes as the area of the hole vanishes. At values of $(D + d)$ greater than about $50 \mu\text{m}$, the slope tends asymptotically to 0.5. This result implies that $S_\Phi(1 \text{ Hz})$ scales with the linear dimension of the SQUID, that is, with the perimeter rather than the area. Thus, once the dimensions of the hole exceed the strip width, the noise is dominated by defects relatively close to or underneath (or on top of) the superconductor, and the contributions from the central region of the loop become unimportant. The total noise ranges from about 0.7 to $2.5 \mu\Phi_0 \text{ Hz}^{-1/2}$ over the range shown.

Figures 3(c) and 3(d) show the dependence of the $1/f$ noise generated by the perpendicular moments and one direction of in-plane moments versus the separation z_0 between the current and SQUID loops. For the cases of perpendicular moments and the in-plane moments under the superconductor, the noise is independent of z_0 for values below about $3 \mu\text{m}$. For the hole and exterior in-plane moments, as expected, the noise drops off as z_0 tends to zero; we neglect these contributions in calculating the total noise in Figs. 3(a) and 3(b). Thus, our choice of $z_0 = 1 \mu\text{m}$ in our simulations is well justified.

We briefly discuss the possibility that a similar model based on fluctuating nuclear spins in the superconductor or substrate could explain flux noise; we emphasize, however,

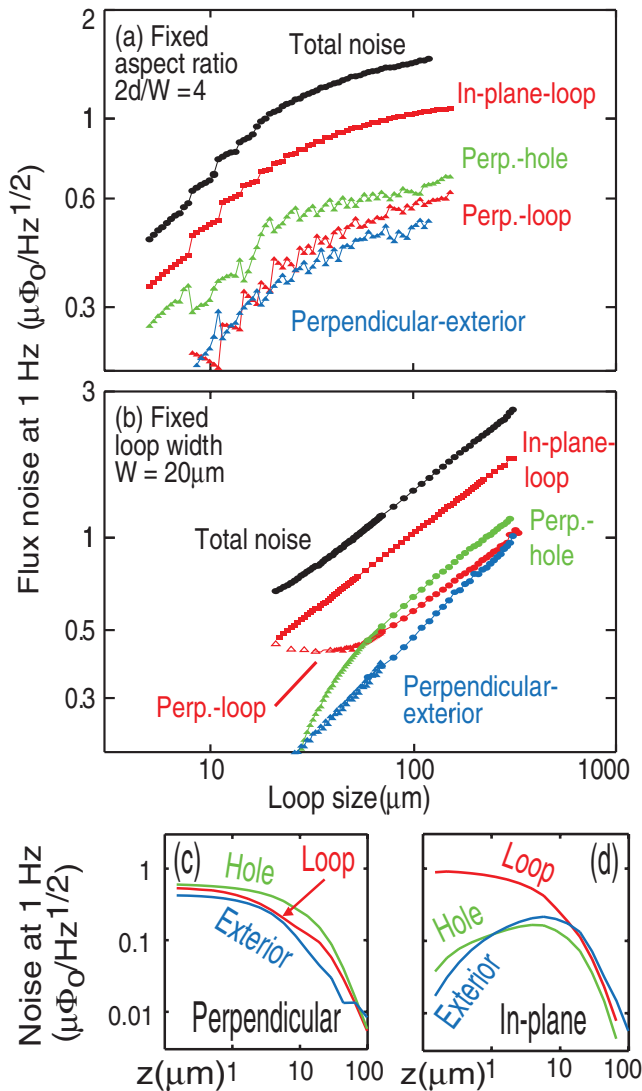


FIG. 3 (color). Computed flux noise vs loop size $D + d$ for (a) fixed loop aspect ratio $2d/W = 4$ and (b) fixed width $W = 20 \mu\text{m}$. The jagged behavior in (a) is due to the discrete mesh of FastHenry. The open triangles in (b) indicate that the accuracy of the calculations is limited. (c), (d) show the dependence of the $1/f$ noise vs the separation of the current and SQUID loops for the perpendicular and one in-plane magnetic moment orientation. Dimensions: $D = 30 \mu\text{m}$, $d = 20 \mu\text{m}$.

that we do not have a model in which nuclear fluctuations produce a $1/f$ power spectrum. As an example, we consider a 100-nm thick film of ^{27}Al (6×10^{28} nuclei/ m^3 , magnetic moment $0.0020\mu_B$). If we place all these nuclear spins in a 100-nm thick layer under the film (overestimating their effect), the spectral density of the noise would be a factor of 20 lower than for our assumed areal density of electrons. Furthermore, Wellstood *et al.* measured the $1/f$ noise in SQUIDs with loops made of both Nb (5.6×10^{28} nuclei/ m^3 , magnetic moment $0.0034\mu_B$) and ^{207}Pb (3.3×10^{28} nuclei/ m^3 , abundance 22%, magnetic moment $0.00032\mu_B$), and found that the noise powers at 0.1 K differed by no more than a factor of 4. Scaling the

parameters in our model predicts that the noise power for Nb would be higher than for Pb by a factor of 850. As an example for the substrate, we consider ^{29}Si (5×10^{28} nuclei/ m^3 , abundance 5%, magnetic moment $0.00030\mu_B$). Taking the results from the example in Fig. 3(c) and 3(d), we assume that the nuclei contribute to a depth of $10 \mu\text{m}$. The resulting noise power is lower than that for electrons by a factor of 200. Thus, nuclei are unlikely to be contributors to $1/f$ flux noise.

In conclusion, our picture unifies the concepts of charge, critical-current, and flux noise: all three noise sources originate in the random filling and emptying of charge traps; flux noise, in addition, involves the concept of spin locking and the random direction of the magnetic moment associated with the trapped carrier.

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