Solving the Characteristic Initial-Value Problem for Colliding Plane Gravitational and Electromagnetic Waves

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A method is presented for solving the characteristic initial-value problem for the collision and subsequent nonlinear interaction of plane gravitational or gravitational and electromagnetic waves in a Minkowski background. This method generalizes the monodromy-transform approach to fields with nonanalytic behavior on the characteristics inherent to waves with distinct wave fronts. The crux of the method is in a reformulation of the main nonlinear symmetry reduced field equations as linear integral equations whose solutions are determined by generalized ("dynamical") monodromy data which evolve from data specified on the initial characteristics (the wave fronts).

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Introduction.—The collision and subsequent nonlinear interaction between plane gravitational or gravitational and electromagnetic waves propagating with distinct wave fronts in a Minkowski background is a well formulated characteristic initial value problem. However, even the discovery of the integrability of the main field equations for this situation did not lead to a solution of this complex nonlinear problem. None of the existing solution generating methods have been found suitable for an effective construction of the solution in the wave interaction region starting from given characteristic initial data determined by the approaching waves.

The structure of the governing field equations for colliding plane waves, physical and geometrical interpretations, and various particular solutions and techniques, have been described in [1]. For colliding plane gravitational waves with aligned constant polarizations, the vacuum Einstein equations are reducible to the linear Euler-Poisson-Darboux equation. In this case, the corresponding characteristic initial value problem can be solved using the generalized version of Abel's transform [2].

However, when the polarizations of the approaching gravitational waves are not constant and aligned, or in the presence of electromagnetic waves, the governing equations are essentially nonlinear and are equivalent to the hyperbolic form of the Ernst equations. For this case, an appreciable number of particular solutions are known. These have been found using the "inverse" method in which a formal solution in the interaction region is first constructed and the corresponding characteristic initial data for the approaching waves are determined only subsequently. Recently, infinite hierarchies of exact vacuum and electrovacuum solutions with an arbitrary number of free parameters were found [3], and many of these are of the type appropriate for colliding plane waves. However, it is not a simple technical task to simplify these solutions for particular cases and to calculate the corresponding characteristic initial data.

For the analysis of the characteristic initial value problem for the vacuum hyperbolic Ernst equation, Hauser and Ernst [4] have generalized their group-theoretical approach (which had been developed earlier for stationary axisymmetric fields) and constructed a homogeneous Hilbert problem with corresponding matrix linear integral equations. Many aspects of this problem, including the existence and uniqueness of solutions and a detailed proof of the Geroch conjecture, were elaborated in [5].

However, a general scheme for the solution of various nonlinear initial and boundary value problems for integrable reductions of Einstein's equations had been developed in the framework of the monodromy transform approach [6–9]. In this approach, every solution can be characterized by a set of functions of an auxiliary (spectral) parameter. These functions are interpreted as the monodromy data on the spectral plane of the fundamental solution of an auxiliary overdetermined linear system associated with the (nonlinear) field equations. These monodromy data are nonevolving (i.e., coordinate independent) and, generally, can be chosen arbitrarily or specified in accordance with the properties of the solution being sought. In particular, these data can be determined (at least in principle) from the initial or boundary data. In this scheme, the solution of the initial or boundary value problem is determined by the solution of some linear singular integral equations whose kernel is constructed using these (specified) monodromy data.

Recently a further generalization of this approach was derived in [10], in which a new linear integral equation form of various hyperbolic integrable reductions of Einstein equations was constructed. The scalar kernels of these quasi-Fredholm equations are built now from a new kind of the monodromy data which we call "dynamical monodromy data." Unlike the previous method, these data evolve, and their evolution is prescribed by the characteristic initial conditions. These new integral equations are better adapted to the construction of an effective solution

of initial value problems because their coefficients carry more explicit information about the characteristic initial data and the corresponding analytical structures of the solutions desired.

In this paper, we present a new approach to the solution of the colliding plane wave problem and also describe a method that can be implemented in practice to derive explicit solutions. Our construction generalizes the monodromy transform approach whose formulation in the above-mentioned papers was applicable only for fields that are analytically dependent on some special set of geometrically defined space-time coordinates. (One of these coordinates determines the measure of an area on the twodimensional orbits of the space-time isometry group. The other is its harmonic conjugate.) However, for colliding plane waves propagating with distinct wave fronts on a Minkowski background, this analyticity is obviously violated on the wave fronts. Moreover, the physically accepted matching conditions imply regular behavior of the field components near the wave fronts in some appropriate null coordinates [1]. In terms of geometrically defined coordinates, this regularity leads to a specific *singular* behavior of the coefficients of the associated linear system on these hypersurfaces, where the first derivatives of the field components become infinite. In this case, some additional singularities appear on the spectral plane for auxiliary functions and the nonevolving monodromy data, which continue to exist, lose their most important property—their unambiguous characterization of the solutions.

The solution of these problems arises from our recent observation that one of two linear integral "evolution equation" forms of the field equations derived in [10] admits a generalization to the singular case. It is also important that the dynamical monodromy data can still be used in this case to characterize the solutions. In this paper we present the generalized linear quasi-Fredholm integral evolution equation, which covers the singular case and opens a direct way for the construction of solutions for colliding plane waves from given characteristic initial data. We also briefly discuss some applications.

Associated linear system with spectral parameter.—We base our construction on the Kinnersley-like linear system for a $N \times N$ matrix function $\Psi(\xi, \eta, w)$

$$
\begin{cases}\n\partial_{\xi} \Psi = \frac{\mathbf{U}(\xi, \eta)}{2i(w - \xi)} \Psi, & \text{rank} \mathbf{U} = 1, \quad \text{tr} \mathbf{U} = i, \\
\partial_{\eta} \Psi = \frac{\mathbf{V}(\xi, \eta)}{2i(w - \eta)} \Psi, & \text{rank} \mathbf{V} = 1, \quad \text{tr} \mathbf{V} = i,\n\end{cases}
$$

in which ξ , η are two real null coordinates arising as certain linear combinations of geometrically defined non-null coordinates, say α , β , mentioned in the introduction, and *w* is a free complex parameter. The integrability conditions of these equations, supplemented with the constraints on their matrix integral \overline{f}

$$
\begin{aligned} \Psi^{\dagger} W \Psi &= W_0(w), & \frac{\partial W}{\partial w} &= 4i\Omega \,, \\ W_0^{\dagger}(w) &= W_0(w), & \frac{\partial W}{\partial w} &= 4i\Omega \,, \end{aligned}
$$

with Hermitian conjugation \dagger defined as $\mathbf{W}_0^{\dagger}(w)$ $\mathbf{W}_0^T(\overline{w})$ and with a constant matrix Ω possessing the only nonzero components $\mathbf{\Omega}^{12} = 1$ and $\mathbf{\Omega}^{21} = -1$, are equivalent to the hyperbolic space-time symmetry reduction for $N = 2$ of the vacuum Einstein equations and for $N = 3$ of the Einstein-Maxwell equations [7,9].

For any solution of these conditions, the components of **U**, **V**, and **W** can be identified with certain metric components and the electromagnetic potential and their derivatives. Without loss of generality, we impose the normalization conditions at the point denoted by $(\xi_{\times}, \eta_{\times})$ at which the waves collide. These are $\Psi(\xi_{\times}, \eta_{\times}, w) =$ **I** and $W_0(w) = 4i(w - \beta_\times)\Omega + \text{diag}(4\alpha_\times^2, 4, 1)$, where $\alpha_{\times} = (\xi_{\times} - \eta_{\times})/2$ and $\beta_{\times} = (\xi_{\times} + \eta_{\times})/2$. A shift of origin and a rescaling of the coordinates ξ , η allow us to specify $\xi_{\times} = 1$ and $\eta_{\times} = -1$, so that $\alpha_{\times} = 1, \beta_{\times} = 0$.

The colliding plane wave problem.—For plane gravitational or gravitational and electromagnetic waves with distinct wave fronts which collide in a Minkowski background, it is well known [1] that the O'Brien-Singe matching conditions imposed at the wave fronts $u = 0$ and $v =$ 0 in some global null coordinates (u, v) , imply special relations between these (u, v) coordinates and geometrically defined (ξ, η) coordinates which are nonanalytical on the boundaries of the interaction region ($u \ge 0, v \ge 0$). In particular, we may have

$$
\xi = 1 - 2u^{n_+}, \quad \eta = -1 + 2v^{n_-},
$$

where $n_± \ge 2$ are specified as part of the initial data. Thus, the important specific of this characteristic initial value problem is that, in terms of geometrically defined coordinates (ξ, η) , the first derivatives of the field components should be discontinuous and even unbounded on the wave fronts and at the point of collision.

The analytical structure of Ψ *on the spectral plane.—* Everywhere below, Ψ denotes the fundamental solution of the associated linear system normalized at the point of collision. As in the regular case, the structure of the associated linear system implies that $\Psi(\xi, \eta, w)$ and its inverse possess four branch points on the spectral plane *w*, namely at $w = \xi$, $w = \eta$, $w = 1$, and $w = -1$. The order of these points and our choice of the cuts L_{\pm} joining them are indicated in Fig. 1. Near these singular points, and on the cuts L_{\pm} , the components of Ψ possess in general the local structure

$$
\Psi(\xi,\eta,w)=\tilde{\pmb{\psi}}_{\pm}(\xi,\eta,w)\otimes {\bf k}_{\pm}(w)+{\bf M}_{\pm}(\xi,\eta,w),
$$

where, as in the regular case, the coordinate independent components of the row vectors $\mathbf{k}_{\pm}(w)$ constitute the "projective vectors" of the monodromy data. Their

FIG. 1. Cuts in the spectral plane *w*.

components, as well as the components of the matrices $M_{\pm}(\xi, \eta, w)$, are regular on the cuts L_{\pm} with the corresponding index. In the analytical case we always have $\tilde{\psi}_{+}(\xi, \eta, w) = \sqrt{\frac{w-1}{w-\xi}}$ $\frac{w-1}{w-\xi}$ $\psi_+(\xi, \eta, w)$ and $\tilde{\psi}_{-}(\xi, \eta, w) = \sqrt{\frac{w+1}{w-\eta}} \psi_{-}(\xi, \eta, w)$ where the vectors ψ_+ and ψ_- are holomorphic on the cuts L_+ and L_- , respectively. In the general case, the components of the column vectors $\tilde{\psi}_{\pm}(\xi, \eta, w)$ also have branch points at the end points of the corresponding cuts L_{\pm} , but the character of their singularities at the points $w = 1$ and $w = -1$, respectively, is determined by the initial data.

The integral equations and the solution of the problem.—To set up the characteristic initial value problem, we introduce two matrix functions which are the normalized fundamental solutions of the linear ordinary differential equations—the restrictions of the associated linear system to the characteristics $\xi = 1$ and $\eta = -1$,

$$
\partial_{\xi} \Psi_{+} = \frac{\mathbf{U}(\xi, -1)}{2i(w - \xi)} \cdot \Psi_{+}, \qquad \Psi_{+}(1, w) = \mathbf{I},
$$

$$
\partial_{\eta} \Psi_{-} = \frac{\mathbf{V}(1, \eta)}{2i(w - \eta)} \cdot \Psi_{-}, \qquad \Psi_{-}(-1, w) = \mathbf{I},
$$

in which the coefficients are determined by the initial data for the fields on the corresponding characteristics. These matrices should be the characteristic initial data for the required solution for $\Psi(\xi, \eta, w)$:

$$
\Psi_{+}(\xi, w) \equiv \Psi(\xi, -1, w),
$$

$$
\Psi_{-}(\eta, w) \equiv \Psi(1, \eta, w).
$$

The analytical structures of Ψ_{\pm} on the spectral plane are very similar to those of Ψ . Namely, $\Psi_{\pm}(w = \infty) = I$, Ψ_+ is holomorphic outside L_+ and Ψ_- outside L_- , and their local structures on these cuts are given by

$$
L_{+}: \Psi_{+}(\xi, w) = \tilde{\psi}_{0+}(\xi, w) \otimes k_{+}(w) + M_{0+}(\xi, w),
$$

$$
L_{-}: \Psi_{-}(\eta, w) = \tilde{\psi}_{0-}(\eta, w) \otimes k_{-}(w) + M_{0-}(\eta, w),
$$

where $\mathbf{k}_{\pm}(w)$ are the same as for Ψ , and $\mathbf{M}_{0+}(\xi, w)$ and $M_{0-}(\eta, w)$ are regular on L_+ and L_- , respectively.

We now introduce, in analogy with the regular case [10], the evolution or "scattering" matrices $\chi_{\pm}(\xi, \eta, w)$, representing $\Psi(\xi, \eta, w)$ in two alternative forms

$$
\Psi(\xi, \eta, w) = \chi_+(\xi, \eta, w) \cdot \Psi_+(\xi, w),
$$

$$
\Psi(\xi, \eta, w) = \chi_-(\xi, \eta, w) \cdot \Psi_-(\eta, w).
$$

The crucial point is that the components of $\chi_+(\xi, \eta, w)$ are holomorphic on L_+ and possess a jump on L_- only, while the components of χ ₋ (ξ, η, w) are holomorphic on L_{-} and possess a jump on L_{+} . From the above it is clear also that these jumps are represented by highly degenerate matrices and that $\chi_{\pm}(\xi, \eta, w = \infty) = I$. These properties

permit us to represent χ_{\pm} as Cauchy integrals

$$
\chi_{+}(\xi,\eta,w) = \mathbf{I} + \frac{1}{\pi i} \int_{L_{-}} \frac{[\tilde{\Psi}_{-}]_{\zeta_{-}} \otimes \mathbf{m}_{-}(\xi,\zeta_{-})}{\zeta_{-} - w} d\zeta_{-},
$$

$$
\chi_{-}(\xi,\eta,w) = \mathbf{I} + \frac{1}{\pi i} \int_{L_{+}} \frac{[\tilde{\Psi}_{+}]_{\zeta_{-}} \otimes \mathbf{m}_{+}(\xi,\zeta_{+})}{\zeta_{+} - w} d\zeta_{+},
$$

where $\lceil \cdots \rceil$ is the jump (a half of the difference between the left and right limits) of a function on a cut and

$$
\mathbf{m}_{-}(\xi, w) = \mathbf{k}_{-}(w) \cdot \mathbf{\Psi}_{+}^{-1}(\xi, w),
$$

$$
\mathbf{m}_{+}(\eta, w) = \mathbf{k}_{+}(w) \cdot \mathbf{\Psi}_{-}^{-1}(\eta, w)
$$

represent a new (evolving) kind of monodromy data introduced for the regular case in [10] and called there the dynamical monodromy data. It is necessary to note here our conjecture of the convergency of the Cauchy integrals for χ_{\pm} at $w = -1$ and $w = 1$, respectively, which is confirmed for particular examples for any $n_+ \geq 2$.

The above alternative representations for Ψ should satisfy an obvious condition $\chi_+\Psi_+ \equiv \chi_-\Psi_-$. This condition considered on the cuts $L_±$ together with the constructed integral representations for χ_{\pm} leads to the linear integral equations (for brevity we omit here the parametric dependence of all objects upon ξ and η):

$$
\boldsymbol{\phi}_{+}(\tau_{+}) - \int_{L_{-}} S_{+}(\tau_{+}, \zeta_{-}) \boldsymbol{\phi}_{-}(\zeta_{-}) d\zeta_{-} = \boldsymbol{\phi}_{0+}(\tau_{+}),
$$

$$
\boldsymbol{\phi}_{-}(\tau_{-}) - \int_{L_{+}} S_{-}(\tau_{-}, \zeta_{+}) \boldsymbol{\phi}_{+}(\zeta_{+}) d\zeta_{+} = \boldsymbol{\phi}_{0-}(\tau_{-}),
$$

where $\tau_+, \zeta_+ \in L_+, \tau_-, \zeta_- \in L_-$ and the vector functions $\phi_+(\tau_+)$, $\phi_-(\tau_-)$ and their initial values $\phi_{0+}(\tau_+),$ $\phi_{0-}(\tau_{-})$ are the jumps $[\tilde{\psi}_{+}]_{\tau_{+}}, [\tilde{\psi}_{-}]_{\tau_{-}}$ and $[\tilde{\psi}_{0+}]_{\tau_{+}},$ $\left[\tilde{\psi}_{0-}\right]_{\tau_{-}}$, respectively. The scalar kernels are given by

$$
S_{+}(\xi, \tau_{+}, \zeta_{-}) = \frac{1}{i \pi (\zeta_{-} - \tau_{+})}
$$

$$
\times \langle \mathbf{m}_{-}(\xi, \zeta_{-}) \cdot \boldsymbol{\phi}_{0+}(\xi, \tau_{+}) \rangle,
$$

\n
$$
S_{-}(\eta, \tau_{-}, \zeta_{+}) = \frac{1}{i \pi (\zeta_{+} - \tau_{-})}
$$

\n
$$
\times \langle \mathbf{m}_{+}(\eta, \zeta_{+}) \cdot \boldsymbol{\phi}_{0-}(\eta, \tau_{-}) \rangle.
$$

The coefficients of these generalized "evolution equations" are also determined by the initial data, but they can be of a more complicated singular structure, than in the regular case, and they also can be easily decoupled into two independent equations for ϕ_+ and ϕ_- .

Our construction of solutions for colliding plane waves begins with the constants $n_± \ge 2$ which determine the degree of nonsmoothness of the fields on the wave fronts and the characteristic initial data for the fields in terms of the Ernst potentials $\mathscr{E}(u, v)$, $\Phi(u, v)$ which characterize every solution. These data, viz. $\mathscr{E}_+(u)$, $\Phi_+(u)$, $\mathscr{E}_-(v)$, and $\Phi_{-}(v)$, should be chosen to satisfy the normalization conditions $\mathscr{C}_{\pm}(0) = -1$, $\Phi_{\pm}(0) = 0$ and two wave front regularity conditions [1]: $|{\mathscr{C}}'_{\pm}(0)|^2 + 4|\Phi'_{\pm}(0)|^2 = 8(1 1/n_{\pm}$). With these data we have to solve the ordinary

differential equations for Ψ_{\pm} and the integral equations for ϕ_{\pm} . The Ernst potentials can be evaluated then as

$$
\mathscr{E} = \mathscr{E}_{+}(u) + \frac{2}{\pi} \int_{L_{-}} \langle \mathbf{e}_{1} \cdot \boldsymbol{\phi}_{-}(\zeta_{-}) \rangle \langle \mathbf{m}_{-}(\zeta_{-}) \cdot \mathbf{e}_{2} \rangle d\zeta_{-}
$$

\n
$$
= \mathscr{E}_{-}(v) + \frac{2}{\pi} \int_{L_{+}} \langle \mathbf{e}_{1} \cdot \boldsymbol{\phi}_{+}(\zeta_{+}) \rangle \langle \mathbf{m}_{+}(\zeta_{+}) \cdot \mathbf{e}_{2} \rangle d\zeta_{+},
$$

\n
$$
\Phi = \Phi_{+}(u) - \frac{2}{\pi} \int_{L_{-}} \langle \mathbf{e}_{1} \cdot \boldsymbol{\phi}_{-}(\zeta_{-}) \rangle \langle \mathbf{m}_{-}(\zeta_{-}) \cdot \mathbf{e}_{3} \rangle d\zeta_{-}
$$

\n
$$
= \Phi_{-}(v) - \frac{2}{\pi} \int_{L_{+}} \langle \mathbf{e}_{1} \cdot \boldsymbol{\phi}_{+}(\zeta_{+}) \rangle \langle \mathbf{m}_{+}(\zeta_{+}) \cdot \mathbf{e}_{3} \rangle d\zeta_{+},
$$

where $\mathbf{e}_1 = \{1, 0, 0\}, \mathbf{e}_2 = \{0, 1, 0\}, \text{ and } \mathbf{e}_3 = \{0, 0, 1\}.$

As a simple test, we consider $n_{+} = n_{-} = 2$ and choose

,

$$
\mathscr{E}_{+} = -1 + 2e^{i\delta}u - u^{2}
$$

$$
\mathscr{E}_{-} = -1 + 2v - v^{2},
$$

where δ is a real constant. For these vacuum data our calculations lead to the Nutku-Halil solution for the collision of impulsive gravitational waves with noncollinear polarizations. If $\delta = 0$, this reduces to the Khan-Penrose solution for the collision of waves with collinear polarizations. Similarly, the initial data (γ is a real constant)

$$
\mathscr{E}_{+} = -1, \qquad \Phi_{+} = u, \n\mathscr{E}_{-} = -1, \qquad \Phi_{-} = v e^{i\gamma}
$$

lead to another known solution for the collision of electromagnetic step waves with nonaligned polarizations [11]. If $\gamma = 0$, this reduces to the Bell-Szekeres solution for such waves with aligned polarizations.

We mention also a more complicated example with the initial data depending on two real parameters γ and δ

$$
\mathscr{E}_{+} = -1 + 2e^{i\delta}u - u^{2}, \qquad \Phi_{+} = 0,
$$

$$
\mathscr{E}_{-} = -1 + 2v \cos \gamma + 2(R(v) - 1)\cot^{2} \gamma,
$$

$$
\Phi_{-} = v \sin \gamma + (R(v) - 1)\cot \gamma,
$$

in which $R(v) = \sqrt{1 - v^2 \sin^2 \gamma}$. These data belong to a physically interesting family of colliding plane impulsive gravitational and step electromagnetic waves. For the collision of an impulsive gravitational wave with either a pure electromagnetic step wave or with a combined impulsive gravitational and step electromagnetic wave with collinear polarizations ($\delta = 0$) the solutions are known ([1] and [12], respectively). For $\delta \neq 0$, our method yields

$$
\mathcal{E} = \tilde{u}^2 - \frac{2v^2}{R(v) + 1} - \frac{2(\tilde{v} - e^{i\delta}u)Z(u, v)}{\tilde{u}\tilde{v} - uve^{i\delta}\cos\gamma},
$$

$$
\Phi = v \sin\gamma \left(-\frac{v \cos\gamma}{R(v) + 1} + \frac{\tilde{v} - ue^{i\delta}R(v)}{\tilde{u}\tilde{v} - uve^{i\delta}\cos\gamma} \right),
$$

 $\tilde{u} = \sqrt{1 - u^2}$, $\tilde{v} = \sqrt{1 - v^2}$, and $Z(u, v) = (\tilde{u}R(v) - \tilde{u})$ $v \cos \gamma$). This generalizes the solutions [1] and [12] to include nonaligned wave polarizations. It also generalizes the Nutku-Halil solution to include the presence of a step electromagnetic wave.

Further new solutions can be found in the same way for different choices of the initial data. However, it may be noted that for a large variety of initial data the solutions may be not expressible explicitly at all, or may lead to much more complicated expressions.

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