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A General Limitation on Monte Carlo Algorithms of Metropolis Type

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We prove that for any Monte Carlo algorithm of Metropolis type, the autocorrelation time of a suitable “energy”-like observable is bounded below by a multiple of the corresponding “specific heat.” This bound does not depend on whether the proposed moves are local or nonlocal; it depends only on the distance between the desired probability distribution π and the probability distribution $\pi^{(0)}$ for which the proposal matrix satisfies detailed balance. We show, with several examples, that this result is particularly powerful when applied to nonlocal algorithms.

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Forty years ago, Metropolis *et al.* [1] introduced a general method for constructing dynamic Monte Carlo algorithms (= Markov chains [2]) that satisfy detailed balance for a specified probability distribution π . In this Letter we would like to point out a general limitation on *all* algorithms of Metropolis type. We prove that the autocorrelation time of a suitable “energy”-like observable is bounded below by a multiple of the corresponding “specific heat.” This bound does not depend on whether the proposed moves are local or nonlocal; it depends only on the distance between the desired probability distribution π and the probability distribution $\pi^{(0)}$ for which the proposal matrix satisfies detailed balance.

Let us begin by recalling the general Metropolis *et al.* [1] method, as slightly generalized by Hastings [3]. We use the notation of a discrete (finite or countably infinite) state space S , but the same considerations apply with minor modifications to a general measurable state space. Let $P^{(0)} = \{p_{xy}^{(0)}\}$ be an arbitrary transition matrix on S . We call $P^{(0)}$ the *proposal matrix*, and use it to generate proposed moves $x \rightarrow y$ that will then be accepted or rejected with probabilities a_{xy} and $1 - a_{xy}$, respectively. If a proposed move is rejected, we make a “null transition” $x \rightarrow x$. The transition matrix $P = \{p_{xy}\}$ of the full algorithm is thus

$$p_{xy} = \begin{cases} p_{xy}^{(0)} a_{xy} & \text{for } x \neq y, \\ p_{xx}^{(0)} + \sum_{z \neq x} p_{xz}^{(0)} (1 - a_{xz}) & \text{for } x = y, \end{cases} \quad (1)$$

where of course we must have $0 \leq a_{xy} \leq 1$ for all x, y . It is easy to see that P satisfies detailed balance for π if and only if

$$\frac{a_{xy}}{a_{yx}} = \frac{\pi_y p_{yx}^{(0)}}{\pi_x p_{xy}^{(0)}} \quad (2)$$

for all pairs $x \neq y$. But this is easily arranged: Just set

$$a_{xy} = F \left(\frac{\pi_y p_{yx}^{(0)}}{\pi_x p_{xy}^{(0)}} \right), \quad (3)$$

where $F: [0, +\infty] \rightarrow [0, 1]$ is any function satisfying

$$\frac{F(z)}{F(1/z)} = z \quad \text{for all } z. \quad (4)$$

The choice suggested by Metropolis *et al.* [1] is

$$F_{\text{Metr}}(z) = \min(z, 1). \quad (5)$$

Other choices of F are possible, but it is easy to see that they must all satisfy the *inequality*

$$F(z) \leq \min(z, 1). \quad (6)$$

Of course, it is still necessary to check that P is irreducible (= ergodic); this is usually straightforward.

Note that if the proposal matrix $P^{(0)}$ happens to *already* satisfy detailed balance for π , then we have $\pi_y p_{yx}^{(0)}/\pi_x p_{xy}^{(0)}=1$, so that $a_{xy}=1$ (if we use the Metropolis choice of F) and $P=P^{(0)}$. On the other hand, no matter what $P^{(0)}$ is, we obtain a matrix P that satisfies detailed balance for π . So the Metropolis procedure can be thought of as a prescription for minimally modifying a given transition matrix $P^{(0)}$ so that it satisfies detailed balance for π .

Let us now assume that $P^{(0)}$ satisfies detailed balance for some probability measure $\pi^{(0)}$; in practice this is virtually always the case. We then define an energylike observable H by

$$H(x) = \begin{cases} -\log(\pi_x/\pi_x^{(0)}) & \text{if } \pi_x > 0, \\ +\infty & \text{if } \pi_x = 0. \end{cases} \quad (7)$$

The point is that H is the "energy" of the probability distribution π relative to $\pi^{(0)}$.

The heart of our argument is the following upper bound on the mean-square change in energy in a single

step of the Metropolis algorithm.

Proposition.—In the situation described above, we always have

$$\begin{aligned} \langle (\Delta H)^2 \rangle &\equiv \sum_{x,x'} \pi_x p_{xx'} [H(x') - H(x)]^2 \\ &\leq \frac{8}{e^2} f_+ \leq \frac{8}{e^2}, \end{aligned} \quad (8)$$

where

$$f_+ \equiv \sum_{\substack{x,x' \\ H(x') > H(x)}} \pi_x p_{xx'}^{(0)} \leq 1 \quad (9)$$

is the fraction (in equilibrium) of proposals that would strictly increase the energy.

Proof.—Since P satisfies detailed balance for π , the summand in (8) is symmetric under $x \leftrightarrow x'$. Therefore it suffices to consider the terms for which $H(x') > H(x)$, and to multiply the result by 2. [The terms having $H(x') = H(x)$ of course make no contribution to the sum.]

If $H(x') > H(x)$, we have $a_{xx'} \leq e^{-[H(x') - H(x)]}$ by (3) and (6). Therefore

$$\begin{aligned} \sum_{\substack{x,x' \\ H(x') > H(x)}} \pi_x p_{xx'} [H(x') - H(x)]^2 &= \sum_{\substack{x,x' \\ H(x') > H(x)}} \pi_x p_{xx'}^{(0)} a_{xx'} [H(x') - H(x)]^2 \\ &\leq \sum_{\substack{x,x' \\ H(x') > H(x)}} \pi_x p_{xx'}^{(0)} e^{-[H(x') - H(x)]} [H(x') - H(x)]^2 \leq \frac{4}{e^2} f_+ \end{aligned} \quad (10)$$

since $z^2 e^{-z} \leq 4/e^2$ for all $z \geq 0$.

The physical intuition behind this proof is simple: Proposed moves having a large energy change $\Delta H > 0$ have an exponentially small acceptance probability, so the mean-square energy increase $\langle (\Delta H)^2 \rangle$ in a single Metropolis step is at most of order 1. Proposed moves having an energy change $\Delta H < 0$ are connected to those with $\Delta H > 0$ by detailed balance: When proposed they are accepted, but if $|\Delta H|$ is large they are only rarely proposed. The result is that the mean-square energy change in either direction is at most of order 1.

Let us now recall the definitions of autocorrelation functions and autocorrelation times [4]: If A is a real-valued function defined on the state space S (i.e., a real-valued observable), we define its unnormalized autocorrelation function (in equilibrium) by

$$C_{AA}(t) \equiv \langle A_s A_{s+t} \rangle - \langle A \rangle_\pi^2 \quad (11a)$$

$$= \sum_{x,y} A(x) [\pi_x (P^{|t|})_{xy} - \pi_x \pi_y] A(y). \quad (11b)$$

The corresponding normalized autocorrelation function is

$$\rho_{AA}(t) \equiv C_{AA}(t)/C_{AA}(0). \quad (12)$$

The integrated and exponential autocorrelation times are then defined by

$$\tau_{\text{int},A} = \frac{1}{2} \sum_{t=-\infty}^{\infty} \rho_{AA}(t), \quad (13)$$

$$\tau_{\text{exp},A} = \limsup_{t \rightarrow \infty} \frac{|t|}{-\log |\rho_{AA}(t)|}, \quad (14)$$

$$\tau_{\text{exp}} = \sup_A \tau_{\text{exp},A}. \quad (15)$$

Some simple identities are worth noting:

$$C_{AA}(0) = \langle A^2 \rangle_\pi - \langle A \rangle_\pi^2, \quad (16a)$$

$$C_{AA}(1) = C_{AA}(0) - \frac{1}{2} \sum_{x,x'} \pi_x p_{xx'} [A(x') - A(x)]^2. \quad (16b)$$

Also, from detailed balance combined with the spectral theorem one can deduce the following inequalities:

$$\tau_{\text{int},A} \geq \frac{1}{2} \frac{1 + \rho_{AA}(1)}{1 - \rho_{AA}(1)}, \quad (17)$$

$$\tau_{\text{exp}} \geq \tau_{\text{exp},A} \geq -1/\log |\rho_{AA}(1)| \quad (18)$$

(see, e.g., [5], Appendix A).

With these preliminaries, the following theorem is an immediate consequence of the proposition.

Theorem.—Under the preceding hypotheses, we have

$$\tau_{\text{int},H} \geq \frac{e^2 \text{var}(H)}{4 f_+} - \frac{1}{2}, \quad (19a)$$

$$\tau_{\text{exp}} \geq -1/\log[1 - 4f_+/e^3 \text{var}(H)], \quad (19b)$$

where $\text{var}(H) \equiv \langle H^2 \rangle_\pi - \langle H \rangle_\pi^2$.

Proof.—From the proposition together with (16), we get

$$\rho_{HH}(1) \equiv \frac{C_{HH}(0)}{C_{HH}(1)} \geq 1 - \frac{4}{e^2 \text{var}(H)}. \quad (20)$$

Now use (17) and (18).

Again the physical intuition is simple: The mean-square energy change per Metropolis step is at most of order 1. On the other hand, in order to sample adequately the probability distribution π , the Markov chain must traverse an energy distribution of width $\sim \text{var}(H)^{1/2}$. This takes a time of order $[\text{var}(H)^{1/2}]^2 \sim \text{var}(H)$.

Single-site Metropolis algorithm.—Here $\pi^{(0)}$ is the *a priori* measure for the spins, and H is the full Hamiltonian. $P^{(0)}$ selects a spin at random and proposes to update it in some way that satisfies detailed balance for $\pi^{(0)}$. We have $\text{var}(H) = VC_h$, where V is the volume and C_h is the specific heat. So the theorem shows that

$$\tau_{\text{int},H}, \tau_{\text{exp},H} \gtrsim VC_h, \quad (21)$$

where time is measured here in hits of a single site; or equivalently $\tau \gtrsim C_h$ when time is measured in “sweeps.” This is a well-known result. However, it is a rather poor bound because the energy, being a *short*-distance observable, has a rather weak overlap with the slowest (*long*-wavelength) modes of this local dynamics. (A much stronger bound can be obtained by using the magnetization \mathcal{M} rather than the energy as the trial function: one gets $\tau_{\text{int},\mathcal{M}}, \tau_{\text{exp},\mathcal{M}} \gtrsim V\chi$, where χ is the susceptibility [4,6].)

The real power of the theorem comes when it is applied to *nonlocal* algorithms: It still yields $\tau \gtrsim VC_h$, but now the unit of time (a “hit” of $P^{(0)}$) is a nonlocal move which costs a CPU time $\gg 1$. As a result, several algorithms which *a priori* look promising must in fact perform rather poorly:

q-state Potts model with mixed ferromagnetic/antiferromagnetic interaction [7].—The purely ferromagnetic Potts model can be simulated very efficiently by the Swendsen-Wang (SW) algorithm [8,9] or its single-cluster (1CSW) variant [10,11], but these algorithms do not extend easily to the mixed ferromagnetic/antiferromagnetic case. One might therefore try using the SW or 1CSW algorithm for the ferromagnetic part of the Hamiltonian as a Metropolis proposal for the full theory. Thus, let $\pi^{(0)}$ (π) be the Gibbs measure for the ferromagnetic (full) theory, so that H is the antiferromagnetic part of the Hamiltonian. Let $P^{(0)}$ be *any* algorithm that satisfies detailed balance for $\pi^{(0)}$ (for example, SW or 1CSW); and let P be the corresponding Metropolis algorithm for π . One expects $\text{var}(H)$ to behave near criticality as $\sim J_{\text{af}}^2 VC_h$, where J_{af} is the antiferromagnetic coupling. So the theorem shows that

$$\tau_{\text{int},H}, \tau_{\text{exp},H} \gtrsim J_{\text{af}}^2 VC_h, \quad (22)$$

where time is measured here in hits of $P^{(0)}$. For SW (1CSW), each hit takes a CPU time of order $V(\chi)$. So the proposed algorithm must perform quite poorly, except when J_{af} is very small [12].

d=3 Heisenberg model with topological term [13].—The ferromagnetic Heisenberg model can be simulated very efficiently by the Wolff embedding algorithm [10,14] using either SW or 1CSW moves to update the induced Ising model [15]. The topological term seems difficult to incorporate into the cluster-algorithm framework, but one might try using the SW or 1CSW algorithm for the ferromagnetic two-body part of the Hamiltonian as a Metropolis proposal for the full theory. (The intuitive idea is that a 1CSW move is likely to make a modest change in the topological-charge field, so the acceptance rate should be reasonable.) Thus, let $\pi^{(0)}$ (π) be the Gibbs measure for the ferromagnetic (full) theory, so that H is the topological term. Let $P^{(0)}$ be *any* algorithm that satisfies detailed balance for $\pi^{(0)}$ (for example, SW or 1CSW); and let P be the corresponding Metropolis algorithm for π . One expects $\text{var}(H)$ to behave near criticality as $\sim J_{\text{top}}^2 VC_h$, where J_{top} is the topological coupling [16]; and it is known that $C_h \rightarrow \text{const} > 0$ at criticality (since $\alpha < 0$). So the theorem shows that

$$\tau_{\text{int},H}, \tau_{\text{exp},H} \gtrsim J_{\text{top}}^2 V, \quad (23)$$

where time is measured here in hits of $P^{(0)}$. For SW (1CSW), each hit takes a CPU time of order $V(\chi)$. So the proposed algorithm must perform quite poorly, except when J_{top} is very small.

Self-avoiding walk with nearest-neighbor interaction.—Fix an integer N , and let S be the space of all N -step self-avoiding walks on some specified lattice. Let $\pi^{(0)}$ be the probability measure that gives equal weight to each element of S . Then define the probability measure π by

$$\pi_\omega = Z(\epsilon)^{-1} e^{-\epsilon M(\omega)} \pi_\omega^{(0)}, \quad (24)$$

where $M(\omega)$ is the number of nonbonded nearest-neighbor contacts in the walk ω . Let $P^{(0)}$ be *any* algorithm that satisfies detailed balance for $\pi^{(0)}$ (e.g., the pivot algorithm [17,18]); and let P be the corresponding Metropolis algorithm for (24). Then the theorem shows that

$$\tau_{\text{int},M}, \tau_{\text{exp},M} \gtrsim \epsilon^2 \text{var}_\pi(M) / f, \quad (25)$$

where f is the fraction of proposals $p_{\omega\omega'}^{(0)}$ with $\omega' \neq \omega$ (e.g., the fraction of proposed pivot moves that preserve self-avoidance). And we expect $\text{var}_\pi(M) \approx NC(\epsilon)$, where the “specific heat per step” $C(\epsilon)$ is everywhere nonzero and diverges like $(\epsilon - \epsilon_\theta)^{-a_\theta}$ at the theta (tricritical) point.

For the pivot algorithm, the bound (25) is a rather weak result: In fact we expect that $\tau_{\text{int},M}, \tau_{\text{exp},M} \sim N/f$ even for $\epsilon=0$, because M is a “primarily local” observable [18]. But (25) does show that for $\epsilon \neq 0$ (and in particular for $\epsilon \rightarrow \epsilon_\theta$) the difficulties cannot be avoided by

using a different proposal $P^{(0)}$; they are inherent in the Metropolis method with this choice of $\pi^{(0)}$ [19].

We conclude by noting that the Metropolis *et al.* method is often applied indirectly: We define transition matrices P_1, \dots, P_n by the Metropolis method, and we then execute either $P = \sum_{i=1}^n \lambda_i P_i$ for some weights $\lambda_i \geq 0$ ("random updating") or else $P = P_1 \cdots P_n$ ("sequential updating"). The first case can easily be handled by our method. The second case is more subtle, because typically P does not satisfy detailed balance [20]; but the bound is almost certainly correct in order of magnitude, except in special situations like "successive overrelaxation" [21].

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