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## COMMENTS

### Nonlinear Crossover between Critical and Tricritical Behavior

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Recently *approximate* solutions to renormalization-group equations were used to calculate the double-power "tricritical" scaling equation of state. We show that this equation can be simply calculated using our *exact* renormalization-group trajectories. The equation of state is expressed *explicitly* in terms of nonlinear scaling fields.

In a recent Letter<sup>1</sup> it was suggested that the crossover or "double-power" scaling functions<sup>2</sup> germane to "tricritical"<sup>3-4</sup> and critical points may be constructed using iteration techniques proposed by Wilson, Nauenberg, and Nienhuis,<sup>5</sup> together with an appropriate mean-field approximation, by matching the Wilson-Fisher critical behavior with a Landau-like expression with fluctuation corrections.

For the problem treated in Ref. 1, approximate solutions of the corresponding recursion relations were derived. On the other hand, we had previously derived<sup>6</sup> the exact  $O(\epsilon)$  nonlinear solution of the renormalization group equations for the same problem.<sup>6-8</sup>

In this Comment we show (i) that our exact solutions are particularly convenient for a match-

ing procedure of the sort introduced in Ref. 1, so that there is no necessity to produce approximate solutions, and (ii) that the equation of state<sup>9</sup> can be expressed directly in terms of the nonlinear scaling fields calculated in Ref. 6, permitting a completely *explicit* expression (automatically in asymptotic Griffiths form) for the equation of state, in contrast to the *implicit* equation given in Ref. 1. Our results validate the approach of Ref. 1 and support its claimed potential utility for problems where exact trajectories may not be easily found.

As in Ref. 1 we begin with a Hamiltonian density of the form

$$\mathcal{H} = \frac{1}{2}(\nabla\vec{s})^2 - \vec{h}\cdot\vec{s} + \frac{1}{2}r\vec{s}^2 + \frac{1}{4}u\vec{s}^4 + \frac{1}{6}v\vec{s}^6 + \dots$$

in dimensions  $d \equiv 4 - \epsilon$ , where  $\vec{s}(\vec{x})$  is an  $n$ -com-

ponent vector spin field and  $\vec{h}$  is the ordering field. The differential equations for  $r$  and  $u$  [consistent to  $O(\epsilon)$ ] are<sup>6-7,10</sup>

$$\begin{aligned}\dot{r}_l &= 2r_l + 2(n+2)u_l/(1+r_l), \\ \dot{u}_l &= \epsilon u_l - 2(n+8)u_l^2/(1+r_l)^2,\end{aligned}\quad (1)$$

where the fluxions denote differentiation with respect to the renormalization parameter  $l$ . The approximate solutions of Ref. 1 were obtained to leading order in  $u(l)$  and  $\epsilon$  by assuming that  $|r_l| \lesssim 1$ . However, for  $r$  and  $u$  noncritical,  $|r_l| \rightarrow \infty$  and  $u_l \rightarrow \infty$  under the renormalization group action.<sup>11,12</sup> The approximation  $|r_l| \lesssim 1$  was avoided in Ref. 6, where it was necessary to assume only that the *critical* values of  $r$  and  $u$  are  $O(\epsilon)$ .

Reference 1 uses a modified homogeneity relation for the free energy,<sup>5,7,13,14</sup>

$$F(h, r, u) = e^{-d l} F(h_l, r_l, u_l) + n \int_0^l e^{-d l'} \ln(1+r_{l'}) dl', \quad (2)$$

where  $h_l \equiv h \exp[(1+d/2)l]$ . Reference 1 suggests that for large  $l$ , the first term be treated in the mean-field approximation (with fluctuation corrections). Because of their approximations, the limit  $l \rightarrow \infty$  cannot be taken. Instead, they use a value of  $l$  such that  $|r_l| \approx 1$ . *Using the exact solutions, we may take the  $l \rightarrow \infty$  limit.* We find that  $r_l \exp(-2l)$  and  $u_l \exp(-\epsilon l)$  have finite limits as  $l \rightarrow \infty$ . Using these limiting forms<sup>15</sup> we are able to calculate the magnetization equation of state [since the second term of (2) does not contribute to the equation of state, it will not be discussed further here<sup>16</sup>]. The general form of the equation of state obtained conforms to that suggested for the global behavior of competing fixed points.<sup>7</sup> From (2) we obtain an explicit expression for the renormalized mean-field approximation to the equation of state:

$$h = \lim_{l \rightarrow \infty} [r_l \exp(-2l)M + u_l \exp(-\epsilon l)M^3]. \quad (3)$$

To calculate  $r_l \exp(-2l)$  and  $u_l \exp(-\epsilon l)$ , we use the nonlinear scaling fields derived in Ref. 6, which are given in terms of variables

$$\begin{aligned}t_l &\equiv \frac{r_l}{1+r_l} + (n+2) \frac{r_l}{(1+r_l)^2}, \\ y_l &\equiv \frac{1}{2\epsilon(n+8)} \frac{u_l}{(1+r_l)^2}.\end{aligned}\quad (4)$$

The Wilson-Fisher fixed point is at  $t=0$ ,  $y=1$ , while the infinite Gaussian point is at  $t=1$ ,  $y=0$ .

The nonlinear scaling fields are<sup>6</sup>

$$\begin{aligned}(1+r_l)t_l/Y_l^{\Delta_n} &= \text{const } e^{2t}, \\ u_l/Y_l &= \text{const } e^{\epsilon t},\end{aligned}\quad (5)$$

where  $\Delta_n \equiv (n+2)/(n+8)$  and

$$Y_l \equiv (1 - y_l/\varphi_l) \exp(\epsilon t_l \Delta_n y_l/\varphi_l)$$

with

$$\varphi_l \equiv |1 - t_l|^{d/2} \exp\frac{1}{2}\epsilon t_l(1 - 2\Delta_n).$$

Thus

$$\begin{aligned}r_l \exp(-2l) &= \frac{(1+r)l}{Y^{\Delta_n}} \left[ \frac{r_l Y_l^{\Delta_n}}{(1+r_l)t_l} \right], \\ u_l \exp(-\epsilon l) &= \frac{u}{Y} Y_l,\end{aligned}\quad (6)$$

where henceforth we write  $r$ ,  $u$ ,  $t$ , and  $Y$  for  $r_0$ ,  $u_0$ ,  $t_0$ , and  $Y_0$ . For all noncritical Hamiltonians,  $|r_l| \rightarrow \infty$  (and  $t_l \rightarrow 1$ ) as  $l \rightarrow \infty$ . Thus, we need only calculate  $Y_l$  for large  $l$ . We expect  $Y_l$  to approach some invariant limit and therefore  $Y_\infty$  should be expressible in terms of the renormalization invariant<sup>6</sup>

$$I \equiv \frac{|t_l|^\epsilon Y_l^{2-\epsilon\Delta_n}}{|1+r_l|^d y_l^2} \xrightarrow{\text{large } l} \frac{Y_l^{2-\epsilon\Delta_n}}{|r_l|^d y_l^2}. \quad (7)$$

We see immediately that if  $Y_\infty$  is to be finite and nonzero, we must have  $|r_l|^d y_l^2$  invariant for large  $l$ . To the required order, we find  $Y_\infty = I^\nu / (I^\nu + 1)$ , where  $\nu^{-1} = 2 - \epsilon\Delta_n$ . Therefore we can write

$$\lim_{l \rightarrow \infty} r_l \exp(-2l) = \frac{(1+r)t}{Y^{\Delta_n}} Y_\infty^{\Delta_n}, \quad (8a)$$

$$\lim_{l \rightarrow \infty} u_l \exp(-\epsilon l) = (u/Y) Y_\infty. \quad (8b)$$

Combining (8) with (3) we obtain

$$h = M t (1+r) \left( \frac{Y_\infty}{Y} \right)^{\Delta_n} + M^3 u \frac{Y_\infty}{Y}. \quad (9)$$

In (9) the nonlinear crossover information is contained for *all* values of  $t$ , not just in the critical region ( $t \ll 1$ ). Since the behavior for *large*  $t$  of the equation of state should not be expected to be universal, we will use the forms of (9) valid for  $t \ll 1$  (retaining, of course, any singular term for  $t \rightarrow 0$ ). Consonant with the approximations already made, we will take the  $O(\epsilon^0)$  parts of (9), retaining  $\epsilon$  only in the exponents. On making the changes of scale  $h \rightarrow h[\epsilon(n+8)]^{-1/2}$  and  $M \rightarrow M[2\epsilon(n$

+8)]<sup>1/2</sup>, (9) becomes

$$h = Mt \left( \frac{|t|^{\epsilon\nu}}{y^\gamma + |t|^{\epsilon\nu}(1-y)} \right)^{\Delta_n} + M^3 y \frac{|t|^{\epsilon\nu}}{y^\gamma + |t|^{\epsilon\nu}(1-y)}, \quad (10)$$

where  $\gamma = 2\nu$ . Of course (10) represents only the lowest-order approximation to the equation of state. However, it can be shown<sup>11</sup> that even the higher-order corrections are functions of the nonlinear scaling fields given in (8). Thus although the details and accuracy of the equation of state are changed by the higher-order terms, the nonlinear crossover effects are the same.

Equation (10) explicitly exhibits the double-power structure of nonlinear crossover between the critical and "tricritical" behavior.<sup>2,7</sup> Various limiting behaviors of (10) are easily obtained:

(i)  $t \rightarrow 0$  with  $y$  held fixed.—The equation of state is

$$h = M \frac{t |t|^{\epsilon\nu\Delta_n}}{y^{\gamma\Delta_n}} + M^3 \frac{|t|^{\epsilon\nu}}{y^{\gamma-1}}. \quad (11a)$$

Thus, we immediately see that  $\gamma = 1 + \epsilon\Delta_n/2$  is the susceptibility exponent and that  $2\beta = 1 + \frac{1}{2}\epsilon(\Delta_n - 1)$  is the magnetization exponent. Dividing through by  $M^\delta = M^{3+\epsilon}$ , we see that (11a) is in the usual Griffiths asymptotic scaling form<sup>9,17</sup>:

$$\frac{h}{M^\delta} = \frac{\text{sgnt}}{y^{\gamma\Delta_n}} \left( \frac{|t|}{M^{1/\beta}} \right)^\gamma + \frac{1}{y^{\gamma-1}} \left( \frac{|t|}{M^{1/\beta}} \right)^{\gamma-2\beta}. \quad (11b)$$

(ii)  $y \rightarrow 0$  with  $y^\gamma |t|^{\epsilon\nu}$  fixed.— $Y_\infty$  is simply a constant, and we obtain the equation of state for the Gaussian model,

$$h = Y_\infty Mt + Y_\infty^{\Delta_n} M^3 |t|^{\epsilon/2}. \quad (12a)$$

Making additional scale changes in  $M$  and  $h$ , we write (12a) in scaling form:

$$\frac{h}{M^\delta} = \left( \frac{t}{M^{1/\beta}} \right)^\gamma + \left( \frac{t}{M^{1/\beta}} \right)^{\gamma-2\beta}, \quad (12b)$$

with  $\gamma = 1$  and  $2\beta = 1 - \epsilon/2$ .

The method employed here is general. For each Hamiltonian, we need to calculate the limits of the renormalized coupling constants for large  $l$ . If  $u_m$  is a coupling constant for a term involving  $m$  spins, we need  $\lim_{l \rightarrow \infty} u_m(l) \exp\{-[d+m(2-d)]l\}$ . This always is given by a simple nonlinear scaling field multiplying some function of the nonlinear renormalization invariants.

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tion and by the U. S. Air Force Office of Scientific Research.

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<sup>4</sup>T. S. Chang, G. F. Tuthill, and H. E. Stanley, Phys. Rev. B **9**, 4882 (1974).

<sup>5</sup>K. G. Wilson and J. Kogut, Phys. Rep. **12C**, 79 (1974); M. Nauenberg and B. Nienhuis, Phys. Rev. Lett. **33**, 1593 (1974); B. Nienhuis and M. Nauenberg, Phys. Rev. B **11**, 4152 (1975).

<sup>6</sup>J. F. Nicoll, T. S. Chang, and H. E. Stanley, Phys. Rev. Lett. **32**, 1446 (1974).

<sup>7</sup>J. F. Nicoll, T. S. Chang, and H. E. Stanley, Phys. Rev. B **12**, 458 (1975), and in *Magnetism and Magnetic Materials—1974*, AIP Conference Proceedings No. 24, edited by C. D. Graham, Jr., G. H. Lander, and J. J. Rhyne (American Institute of Physics, New York, 1975), p. 317.

<sup>8</sup>The exact  $O(\epsilon)$  nonlinear solutions of the renormalization-group equations describe the crossover between critical and Gaussian behavior for an isotropic  $n$ -vector model. The Gaussian fixed point may be considered as describing the tricritical behavior for  $d \geq 3$  (cf. Ref. 3). However, a strict perturbational analysis would require  $r$ ,  $u$ , and  $v$  to be of the same order with  $v > 0$ ; the feedback from the eight-spin term must also be considered (cf. Ref. 4). The conventional tricritical systems, with Hamiltonians like  $As^2 + Bs^4 + s^6$ , with  $B$  vanishing at the tricritical point, have mean-field (not Gaussian) behavior for  $d > 3$ . The Gaussian fixed point may also be viewed as a nonclassical tricritical fixed point for the type discussed recently in Ref. 7.

<sup>9a</sup>The critical equation of state (without double-power or crossover) was first given in E. Brézin, D. J. Wallace, and K. G. Wilson, Phys. Rev. Lett. **29**, 591 (1972), and Phys. Rev. B **7**, 232 (1973).

<sup>9b</sup>More detailed discussion can be found in E. Brézin, J. C. leGuillo, and J. Zinn-Justin, in "Phase Transitions and Critical Phenomena," edited by C. Domb and M. S. Green (Academic, London, to be published), Vol. 6.

<sup>10</sup>F. J. Wegner and A. Houghton, Phys. Rev. A **8**, 401 (1972); J. F. Nicoll, T. S. Chang, and H. E. Stanley, Phys. Rev. Lett. **33**, 540 (1974), and Phys. Rev. A (to be published).

<sup>11</sup>T. S. Chang, J. F. Nicoll, and H. E. Stanley, in "Proceedings of a Symposium on Physical Fields in Material Media," edited by A. C. Eringen (Pergamon, New York, to be published), and unpublished.

<sup>12</sup>For  $T < T_c$ , we have  $r_l \rightarrow -\infty$ , leading to apparent anomalies in (1) and (2). This difficulty is not just a breakdown of the particular equations, but rather a fail-

ure of perturbation theory itself at the point  $\nu_1 = -1$ . A nonperturbational view (cf. Ref. 11) shows that this anomaly is entirely artificial. Thus it is not surprising that it can be removed in several ways (one method is the "spin-shift" approach used in Ref. 1). Actually, we need only define some continuation of the trajectories through  $\nu_1 = -1$ ; the spin shift is not necessary. For the magnetization equation of state, the expression for  $T > T_c$  can be simply continued to  $T < T_c$ ; i.e., Eq. (10) holds for  $t > 0$  and for  $t < 0$  (cf. Ref. 9b, which illustrates this for the Brézin-Wallace-Wilson result). This corresponds to the fact that in field-theoretic calculations, the temperature can be treated as an  $s^2$  insertion rather than being incorporated into the propagator (cf. Ref. 9b).

<sup>13</sup>D. R. Nelson, Phys. Rev. B 11, 3504 (1975).

<sup>14</sup>As in Ref. 1, this form is only convenient for  $T > T_c$ . We use it illustratively for simplicity. As discussed in Refs. 11 and 12, the case  $T < T_c$  presents no real difficulty.

<sup>15</sup>These limits define the "dressed mass"  $m^2 \equiv \lim_{l \rightarrow \infty} \nu_l \times \exp(-2l)$  and renormalized four-spin coupling constant  $u_r \equiv \lim_{l \rightarrow \infty} u_l \exp(-\epsilon l)$ ; cf. J. Rudnick, Phys. Rev. B 11, 363 (1975).

<sup>16</sup>The exact solutions can, of course, be used in the second term of (2), and the result agrees with that given in Ref. 1.

<sup>17</sup>R. B. Griffiths, Phys. Rev. 158, 176 (1967). Note that expression (11b) is the nonlinear Griffiths-form "0-loop" contribution to the equation of state (cf. Ref. 9b).

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## ERRATUM

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EVIDENCE FOR GIANT  $M2$  STATES IN  $^{208}\text{Pb}$ .  
R. A. Lindgren, W. L. Bendel, L. W. Fagg, and  
E. C. Jones, Jr. [Phys. Rev. Lett. 35, 1423  
(1975)].

In Fig. 1 the units of  $d^2\sigma/d\theta dE$  should be  $\mu\text{b}/\text{sr}$   
MeV (not  $\text{nb}/\text{sr}$  MeV) on both vertical scales.