

Generalized Scaling and Model for Friction in Wall Turbulence

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We present a novel generalized scaling framework and predictive model for wall friction in turbulent flows. The scaling is derived from the dynamical equations, and total mean-flow kinetic energy and the velocity profile shape factor are used as surrogates for dynamical and boundary condition effects. Veracity of the present approach is assessed using data from the literature spanning unprecedented ranges of flow types, Reynolds numbers, accelerations, and history effects. Unlike previous models that solely apply to standard flows, the present framework reconciles nonstandard flows with standard flows and enables accurate estimates of wall friction in numerical simulations and experiments without resolving the viscous sublayer or using the law of the wall.

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Introduction.—Fluids flowing adjacent to solid surfaces experience a resisting force due to friction between the flow and the surface. This surface friction (also referred to as wall friction) depends on the character of the flow, namely, laminar, transitional or turbulent, which in turn depends on the flow Reynolds number Re (to be defined later). Most flows of practical relevance have high Reynolds numbers and are therefore, turbulent. In order to maintain a turbulent flow, energy needs to be supplied to overcome the work of wall friction; a reference frame wherein the wall moves upstream and fluid far away is stationary, is convenient to visualize the work of wall friction [1]. Therefore, wall friction dictates economics of flow processes such as the pumping power required to push fluids through pipe lines, consumption of aviation fuel by commercial airliners, and so on [2–5]. Hydrodynamically, rough walls cause more friction compared to smooth ones [6,7]. Thus, surfaces in most applications are polished or coated to be smooth to reduce operating costs. Even then, friction at these smooth walls contributes a major chunk of the financial burden passed on to the end users. Friction scaling and predictive models in smooth-wall turbulence have therefore been intensely studied for over a century [6,8–15], and are the focus of this Letter as well.

Smooth-wall turbulent flows may be classified as internal flows (fully developed pipe and channel flows) and external flows (boundary layers). Turbulent boundary layers (TBLs) are of three broad types: (a) no acceleration of the freestream, i.e., freestream velocity $U_\infty = \text{constant}$ due to the pressure-gradient force being zero (ZPG TBLs), (b) decelerating freestream, i.e., U_∞ is a decreasing function of the streamwise coordinate x due to adverse (opposing the flow) pressure gradient force (APG TBLs), and (c) accelerating freestream, i.e., U_∞ is an increasing function of x due to favorable (assisting the flow) pressure gradient force (FPG TBLs). For a very strong APG, the

boundary layer may start “approaching” separation so that, wall friction no longer remains dynamically relevant [2]. Our study therefore, comprises of internal flows, and all “attached” TBLs (Fig. 1) which also include, for the first time as far as we know, (i) a wide variety of non-self-similar TBLs, such as those over aircraft wings and turbine blades, and (ii) compressible (supersonic and

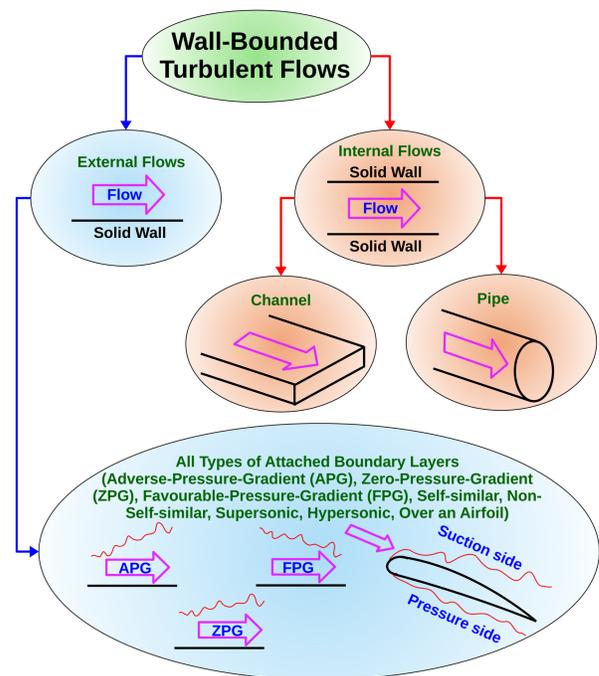


FIG. 1. Smooth-wall turbulent flows covered by this study. All flows are two dimensional in the mean. Internal flows are fully developed. External flows are different types of attached TBLs. Thick black lines indicate solid wall(s) and arrows indicate nominal flow direction. Thin red lines schematically indicate turbulent-nonturbulent interface, a measure of the thickness of TBLs.

hypersonic) TBLs with Van-Driest-transformed mean velocity profiles [16–19].

Drawbacks of existing scalings and models.—All friction scalings and models are mathematical descriptions of how a dimensionless measure f of friction varies with flow Reynolds number Re [9,11,14,15,20], where f and Re are defined by

$$f := \sqrt{\tau/\rho U_s^2} = U_\tau/U_s \quad \text{and} \quad Re := \delta U_s/\nu. \quad (1)$$

Here, ρ is the density of flowing fluid, τ is the shear stress between the flow and the wall, $U_\tau := \sqrt{\tau/\rho}$ is the friction velocity (throughout this Letter, $:=$ denotes a definition), δ is the outer length scale of the flow (boundary layer height or pipe radius or channel half-height), and ν is the kinematic viscosity of the fluid. The velocity scale U_s should (i) render τ (or U_τ) and δ dimensionless, and (ii) “scale” the data in a universal fashion in (f, Re) coordinates.

Despite the extensive research taken place so far, all f - Re relations in the literature suffer from two major shortcomings.

(1) From a fundamental point of view, these relations are not founded firmly in the governing dynamics of turbulent flows. Mostly, they are by-products of mean velocity scaling laws which themselves, are physically intuitive but still empirical. Specifically, it is a tradition to use U_∞ (freestream velocity for TBLs and center-line or bulk velocity for pipes and channels) as the velocity scale ($U_s = U_\infty$) in Eq. (1). However, this is simply because U_∞ is either specified as the outer velocity boundary condition (BC) in TBLs or is a practically useful measure of flow rate through pipe or channel. There is no “dynamical” basis for setting $U_s = U_\infty$; (2) From a practical point of view, the applicability of these relations is too restrictive, limited to only certain types of flows studied extensively using experiments and numerical simulations. These “standard” flows are ZPG TBLs, and fully-developed pipe and channel flows. Most practical flows of interest are, however, “nonstandard” and departures from the standard behavior are significant. These include self-similar and non-self-similar TBLs in strong APGs and FPGs, and compressible TBLs. For example, a TBL developing over an aircraft wing or turbine blade experiences strong PG that also varies in the streamwise direction much more rapidly compared to the intrinsic timescale of turbulence adjustments [21], and this mismatch renders these flows non-self-similar. Individual f - Re relations cannot be devised for such flows due to the diversity of flow situations that could arise. The generalized universal f - Re framework, which is the focus of this Letter, offers an elegant solution to this problem.

To highlight these issues, we consider friction data from several types of flows shown in Fig. 1. These data come from experiments and numerical simulation studies

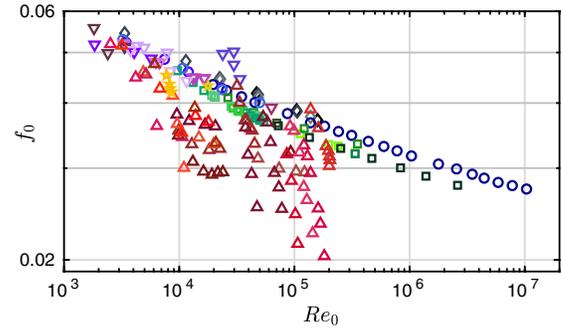


FIG. 2. Traditional scaling of friction ($f_0 := U_\tau/U_\infty$ and $Re_0 := \delta U_\infty/\nu$) in smooth-wall turbulent flows. Circles—pipes, squares—ZPG TBLs, diamonds—channels, triangles—APG TBLs (self-similar and non-self-similar), inverted triangles—FPG TBLs (self-similar and non-self-similar), and pentacles—compressible TBLs. Further details of symbols and datasets are in Supplemental Material Part IIC—Data Tables [22]. Data cover Reynolds number range $95 \leq Re_\tau \leq 528\,860$ (more than three decades in Re_τ) and dimensionless pressure gradient range $-1.5 \leq \beta \leq 35.9$ (from strong FPG to strong APG). Note that, $Re_\tau := \delta U_\tau/\nu$ is the friction Reynolds number and $\beta := \delta^*/\tau(dp/dx)$ is the Rotta-Clauser pressure gradient parameter [62,63]; δ^* is displacement thickness and dp/dx is mean streamwise pressure gradient.

published in the literature, and cover very wide ranges of Reynolds number and PG (Supplemental Material Part IIC—Data Tables [22]). Figure 2 plots friction data in the traditional scaling framework (f_0, Re_0) where $f_0 := U_\tau/U_\infty$ and $Re_0 := \delta U_\infty/\nu$, i.e., $U_s = U_\infty$ in Eq. (1). Different datasets show very different trends as well as varying degrees of scatter. Figure 2 clearly demonstrates the absence of any generalized scaling behavior in the (f_0, Re_0) framework, precluding any possibility of making useful predictions.

Physical basis for generalized scaling.—Fundamentally, the velocity field of every turbulent flow is a solution of the governing dynamical equations subject to certain initial and boundary conditions (ICs and BCs). For statistically stationary flows, only BCs are relevant; all flows considered here are statistically stationary. Friction at the wall is a consequence of the no-slip BC at the wall and is related to the gradient of mean velocity field in the vicinity of the wall. This region receives velocity contributions from turbulent motions or eddies that span a wide range of scales. The smallest eddies are dissipative and have sizes of the order of Kolmogorov length scale; the largest eddies are energetic and scale on δ [2,3]. Further, large eddies organize in the form of large-scale motions (LSMs) [64,65], and very-large-scale motions (VLSMs) in internal flows [66] or superstructures in external flows [67,68]. This rich spectral structure of a turbulence cascade is set up by nonlinearity of governing Navier-Stokes equations through vortex stretching mechanism [2]. Since friction at the wall receives contributions from this entire spectrum of scales [69–73], a meaningful “scaling” of friction must follow from the flow

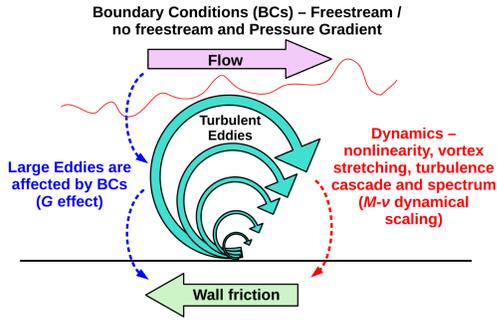


FIG. 3. Schematic depicting roles of dynamics and BCs towards setting up and modulating eddies of turbulence that contribute to friction experienced by the flow at the wall. Dynamics contributes M - ν scaling and effects of BCs are taken into account by Clauser's shape factor G , both together yielding generalized M - ν - G scaling.

dynamics that embodies this structure of turbulence. It is important to note that, BCs are not central to setting up the eddy cascade. They are, however, peripherally important since they modulate the strength of large eddies in a manner that differs from one type of flow to another [74,75]. Therefore, BCs could influence friction at the wall in an indirect fashion through their influence on the large eddies. With this physical insight, it is clear that the quest for a generalized scaling of friction, valid for all flows, must take into cognizance both, the dynamics and the BCs as illustrated schematically in Fig. 3. Note that, the traditional choice of velocity scale $U_s = U_\infty$ mentioned earlier, completely misses the dynamics since U_∞ is technically just the outer velocity BC.

Unified scaling in standard flows.—Our recent work [20] presents analysis of friction scaling in standard flows (ZPG TBLs, pipes and channels) along the lines discussed above. It shows how dynamics and BCs can be used to unify the scaling of friction in these flows. The analysis consists of two parts. First, the equation governing the evolution of streamwise mean-flow kinetic energy $U^2/2$ is considered in its wall-normally integrated form; this step bears striking resemblance to the approach of Renard and Deck [1] who decompose wall friction into contributions from physical phenomena across the complete TBL. The asymptotic form of this equation shows that the dynamics sets its own velocity scale for friction [20]. This new dynamical velocity scale is different from U_∞ , and is given by M/ν where $M = \int_0^\delta U^2 dz$ is proportional to total streamwise kinetic energy content of the mean flow. With $U_s = M/\nu$ in Eq. (1), dimensionless friction and the Reynolds number become

$$f'_1 := U_\tau \nu / M \quad \text{and} \quad \text{Re}'_1 := \delta M / \nu^2. \quad (2)$$

This nondimensionalization is referred to as M - ν scaling of friction and is founded firmly on the dynamics of wall-bounded turbulent shear flows. All standard flows are shown to obey the dynamical asymptotic friction scaling

law $f'_1 \sim \text{Re}'_1{}^{-1/2}$ in the limit of an infinite Reynolds number. For a given finite-Re standard flow, friction in M - ν scaling may be treated as a small perturbation from the asymptotic scaling law. Using asymptotic series expansions, a finite-Re model in the M - ν scaling framework is obtained [14,20]. This model combines contributions to friction from inviscid attached-eddy-type motions as well as small-scale, dissipative motions that are not captured by the attached-eddy model (Supplemental Material Part IB [22]). The model very well describes variation of f'_1 with Re'_1 for each individual standard flow type, but fails when all of them are taken together [20]. This happens because M - ν scaling does not account for any BC effects; at finite Reynolds numbers, BCs for different standard flows are different [20]. The second part of the analysis proposes that the shape of the mean velocity profile is a useful measure of the distinguishing effects of BCs. Empirical transformations are proposed [20] to obtain “effective” dimensionless friction f_1 and Reynolds number Re_1 where shape of mean velocity profile has been factored in. These transformations are

$$f_1 = f'_1 (G/G_{\text{ref}})^p \quad \text{and} \quad \text{Re}_1 = \text{Re}'_1 (G/G_{\text{ref}})^q, \quad (3)$$

where G is Clauser's shape factor [76], for the outer-scaled or defect velocity profile, defined as $G := U_\infty / U_\tau [(H-1)/H]$ wherein H is the conventional shape factor ($H := \delta^*/\theta$ where δ^* is displacement thickness and θ is momentum thickness), $G_{\text{ref}} = 6.8$ is the reference value of G corresponding to the ZPG TBL at high Reynolds number [20,76], and p and q are empirical (constant) exponents. Thus, $(G/G_{\text{ref}})^p$ and $(G/G_{\text{ref}})^q$ in Eq. (3) are empirical top ups, on the basic dynamical scaling of friction [Eq. (2)], accounting for BC effects. This scaling framework of coordinates (f_1, Re_1) is termed as M - ν - G scaling (Supplemental Material Part I [22]). The finite-Re friction model (M - ν - G scaling) unifying friction in standard flows [20] is

$$f_1 = \frac{A_1}{\ln \text{Re}_1} \text{Re}_1^{\left[B_0 + \frac{B_1}{\sqrt{\ln \text{Re}_1}} \right]}. \quad (4)$$

Model coefficients A_1 , B_0 , B_1 , and empirical (constant) transformation exponents p and q are determined by optimizing the fit of Eq. (4) to the data (Supplemental Material Part II-A [22]). Friction data from all standard flows are described very well, in a unified manner, by the M - ν - G scaling [Eq. (3)] and finite-Re model Eq. (4) [20].

Hypothesis of generalized scaling in all flows.—We now hypothesize that the M - ν - G scaling and friction model [Eq. (4)] are generally applicable to all flows. For this to happen, the following three conditions need to be satisfied: (i) M - ν scaling should apply to all flows, (ii) nonstandard flows can have strong PGs and mathematically, PG is a BC. Therefore, G , which accounts for BC effects in standard flows, should account for strong PG effects in nonstandard

flows, and (iii) nonstandard flows can have strong streamwise variations in PG giving rise to PG history or memory effects, and G should also account for these effects.

With reference to the first condition, we note that a cornerstone assumption for M - ν scaling in standard flows [20] is the turbulence kinetic energy (TKE) production term in the log-law-type overlap varying inversely with distance from the wall, i.e., $P_{+,overlap} \sim 1/z_+$; $z_+ := zU_\tau/\nu$ is the distance from the wall in viscous units. For nonstandard flows, the extent, slope and intercept of the log region vary with PG strength [77–81]. Alternatively, there are proposals arguing in favor of power-law-type overlap. If the type of overlap (log-law-type or power-law-type) is not specified, then the variation of production term may be generally written as $P_{+,overlap} \sim 1/z_+^m$ ($m > 0$); $m = 1$ corresponds to log-law-type overlap. Supplemental Material Part I [22] provides derivations of M - ν scaling for all possible overlaps $m = 1$, $0 < m < 1$ and $m > 1$. These derivations are new and account for the region below the overlap layer (viscous sublayer, buffer layer and mesolayer) in addition to overlap and wake layer regions. In all cases, the dynamics dictates the same M - ν scaling irrespective of the type of overlap and wall-normal extents of various flow regions. Therefore, the first condition mentioned above is satisfied for all flows. As to the second condition, it is known that G is a function of dimensionless PG in case of self-similar TBLs [62,82]. Therefore, one may readily expect G to capture strong PG effects, satisfying the second condition. Finally, flows with rapid variations of dimensionless PG are inevitably characterized by strong history effects wherein wall-normal distributions of turbulent stresses do not scale simply on local variables (self-similarity fails), but depend strongly on the upstream distribution of PG the flow has experienced [83]. This memory is due to large-scale structures such as LSMs and VLSMs or superstructures, that take longer time to adjust to the BCs compared to the timescale of the variation of PG BC itself [21]. As such, streamwise distributions of the Reynolds number, skin friction coefficient ($C_f := 2f_0^2$), conventional shape factor (H), etc. lag behind the streamwise variation of dimensionless PG [80,84,85]. However, careful scrutiny reveals that the streamwise variations of C_f and H follow each other very well albeit with opposite phases; H increases (decreases) with C_f decrease (increase). This is evident in several studies [Fig. 5(b) of Fernholz and Warnack [84], Figs. 3 and 4 of Warnack and Fernholz [85], Fig. 3 and Table 1 of Aubertine and Eaton [86], Fig. 6 of Bourassa and Thomas [80], Fig. 4 of Vinuesa *et al.* [87], Fig. 5 of Bobke *et al.* [83], Figs. 1(b) and 1(d) of Maciel *et al.* [63], Fig. 3 of Drózdź *et al.* [88]]. Since G is related to H and C_f [76], its variation is also in tune with that of H or C_f [Figs. 1(b), 1(d), and 1(e) of Maciel *et al.* [63]]. Most importantly, Figs. 2(a), 3, 6, and 7 of Bobke *et al.* [83] reveal that for matched local values of dimensionless PG and Reynolds number, the shapes of viscous-scaled mean velocity profiles differ (G values are

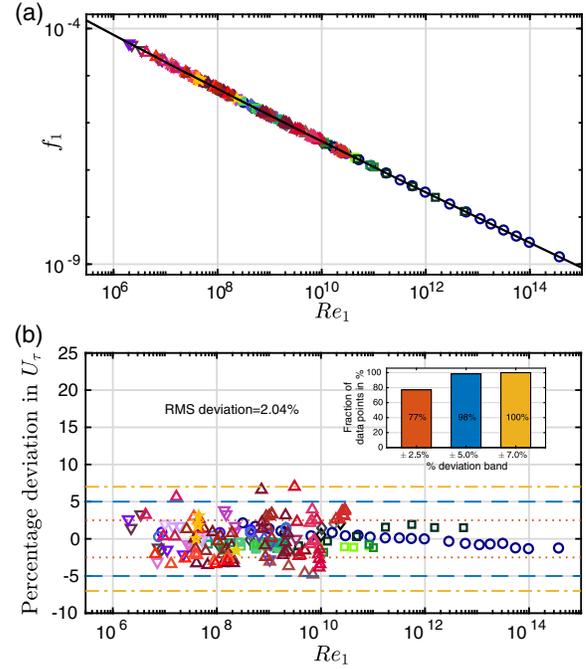


FIG. 4. (a) Generalized universal M - ν - G scaling of friction in smooth-wall turbulent flows. Solid line shows generalized finite-Re friction model Eq. (4) fitted to all data. (b) Percentage deviation of predicted U_τ from its actual value. Dotted, dashed, and dashed-dotted horizontal lines, respectively, indicate deviation bands of $\pm 2.5\%$, $\pm 5\%$, and $\pm 7\%$. Inset shows histogram of the fraction of data points contained in these bands. For symbols, see caption of Fig. 2.

different) depending on the PG history. Further, it has been suggested in the literature that H captures history effects in TBLs [63,88,89]. Taken together, the empirical evidence indeed suggests that G could capture PG history effects as well. This satisfies the third condition. In view of these facts, one may expect M - ν - G scaling Eq. (3) and friction model Eq. (4) to hold generally for all flows (Supplemental Material Part I [22]).

Hypothesis testing.—To test our hypothesis, we process and plot all data in M - ν - G scaling [Fig. 4(a)]. Friction model Eq. (4) fitted to the data is also plotted. Data processing is outlined in Supplemental Material Part IIA [22]. The model coefficients are $A_1 = 2.0699$, $B_0 = -0.4749$ and $B_1 = -0.2860$ [Eq. (4)], and empirical exponents are $p = 0.5392$ and $q = -0.5451$ [Eq. (3)]. Data in Fig. 4(a) tightly cluster around the fitted friction model [Eq. (4)] which can now be used to predict U_τ in any flow. Prediction involves solving implicit Eq. (4)— U_τ occurs on both sides due to the presence of G in f_1 and Re_1 [Eq. (3)]—using measured or computed velocity profile data (Supplemental Material Part IIB [22]); viscous sublayer data or law-of-the-wall assumptions are not required (Supplemental Material Part III [22]). Figure 4(b) plots, for all data points, the percentage deviation of the predicted value of U_τ from the actual value in measurements or

simulations. An impressive root-mean-squared (RMS) deviation of 2.04% is evident with a $\pm 5\%$ band covering almost all the deviations. Note that, 85 data points out of the total 192 correspond to standard flows and the remaining 107 correspond to nonstandard flows that involve strong PGs and/or PG history effects. Results are therefore not biased by standard flows. While dedicated models tailored to individual flows could achieve better prediction accuracy, results of Fig. 4 unequivocally confirm that our hypothesis stands scrutiny of the data, and our generalized M - ν - G scaling [Eq. (3)] and friction model [Eq. (4)] show high fidelity in handling wide variety of flows over very broad ranges of Reynolds number, PG and PG history effects.

Conclusion.—High-Re, nonstandard flows such as those over wings and fuselage of an aircraft or the nose and body of launch vehicles and missiles, are of great importance to practising designers and engineers. Standard flows, on the other hand, are mainly of interest to academicians as systematic tools for unveiling the behavior of wall turbulence. Strong PG and PG history effects make nonstandard flows hard to predict. The present results, for the first time, show that our generalized scaling and model for friction, founded firmly on the dynamics and BCs, and supported strongly by data from experiments and simulations, bring out an inherent universality of friction in all attached, smooth-wall turbulent flows. The results are very relevant to both modelers and experimentalists. For estimating wall friction, the viscous sublayer next to the wall needs to be resolved [90] which is computationally expensive or experimentally formidable [91] in high-Re flows. Alternatively, wall functions (based on the law of the wall) may be used if the first resolved (or measured) point is beyond the viscous sublayer [92,93]. For nonstandard flows, however, the law of the wall is not universal [78,93]. Our generalized friction model shows promising potential to accurately estimate wall friction in numerical simulations and experiments of high-Re, nonstandard flows without resolving the viscous sublayer or relying on the law of the wall.

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