

Improving Quantum Gate Fidelities by Using a Qubit to Measure Microwave Pulse Distortions

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(Received 2 November 2012; published 24 January 2013)

We present a new method for determining pulse imperfections and improving the single-gate fidelity in a superconducting qubit. By applying consecutive positive and negative π pulses, we amplify the qubit evolution due to microwave pulse distortions, which causes the qubit state to rotate around an axis perpendicular to the intended rotation axis. Measuring these rotations as a function of pulse period allows us to reconstruct the shape of the microwave pulse arriving at the sample. Using the extracted response to predistort the input signal, we are able to reduce the average error per gate by 37%, which enables us to reach an average single-qubit gate fidelity higher than 0.998.

DOI: 10.1103/PhysRevLett.110.040502

PACS numbers: 03.67.Lx, 03.67.Pp, 78.70.Gq, 85.25.Cp

A basic requirement for building a quantum information processor is the ability to perform fast and precise single- and two-qubit gate operations [1]. For qubits defined in superconducting circuits, much work has been done to improve the quality of both single-qubit [2–4] and two-qubit gate operations [5–11]. Still, gate fidelities need to improve further to reach error rates small enough for practically implementing fault-tolerant quantum computing with error-correcting protocols [12,13]. In most qubit architectures, many single-qubit operations are implemented by applying short microwave pulses resonant with the qubit transition frequency. The phase of the microwave pulse controls the rotation axis in the x - y plane of the Bloch sphere, whereas the pulse amplitude and duration set the rotation angle. A difficulty with this approach is that the single-qubit gate fidelity becomes highly susceptible to any impedance mismatch in the microwave line between the signal generator and the qubit, since such imperfections lead to pulse distortions.

Consider the microwave pulse shown in Fig. 1(a), which initially has a Gaussian-shaped envelope $A_I(t)$ with a well-defined phase. When passing from the generator to the device, the pulse gets distorted, which deforms the envelope in $A_I(t)$ and adds a quadrature component $A_Q(t)$. The pulse was intended to perform a rotation around the x axis of the Bloch sphere [see Fig. 1(b)], but the quadrature components present in the distorted pulse shape will change the rotation axis and generate an error in the final qubit state. The systematic errors due to the nonzero $A_Q(t)$ are particularly problematic for qubit control, since they will bring the qubit state out of the y - z plane expected from a pure rotation around the x axis. In the following, we will

focus exclusively on determining and eliminating these unwanted quadrature components.

In general, pulse distortions are described by the transfer function \mathcal{H} , which is the frequency-domain representation of the system's impulse response $h(t)$. If the transfer function is known, it is possible to correct pulse imperfections using digital signal processing techniques. By numerically applying the inverse \mathcal{H}^{-1} to the input signal x , the pulse is predistorted in precisely the right way to give the correct signal $\mathcal{H}[\mathcal{H}^{-1}[x]] = x$ at the device. The difficulty lies in obtaining \mathcal{H} . Since superconducting qubits operate at millikelvin temperatures inside a dilution refrigerator, it is generally not possible to probe the signal arriving at the qubit directly with conventional instruments such as a network analyzer or a sampling oscilloscope.

In this work, we take a different approach and use the qubit's response to various pulses as a probe for determining \mathcal{H} [14]. We have designed and implemented a pulse sequence consisting of pairs of positive and negative π pulses around the x axis; the reversing of the pulse direction amplifies the quadrature component of the signal and causes the qubit to slowly oscillate around the y axis.

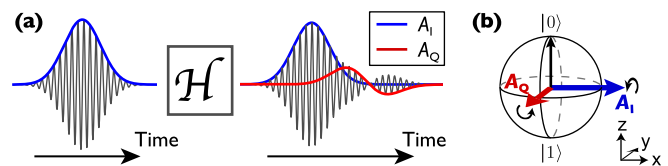


FIG. 1 (color online). (a) Distortion of a Gaussian-shaped microwave pulse. (b) Bloch sphere describing the qubit dynamics in the rotating frame.

By measuring the rotation frequency for different pulse periods, we are able to extract the time dependence of those quadrature components. From the obtained signal we construct the inverse transfer function \mathcal{H}^{-1} and use it to numerically predistort the input signal. The resulting pulse shapes give a significant reduction in the gate error rate, as determined in a randomized benchmarking experiment [15]. With optimized pulse shapes, we extract an average gate fidelity higher than 99.8%, which, to our knowledge, is the highest gate fidelity reported so far for a superconducting qubit.

We use a flux qubit [16], consisting of a superconducting loop interrupted by four Josephson junctions. Biased at the optimal operation point, the qubit's energy relaxation time is $T_1 = 12 \mu\text{s}$, and the dephasing time is $T_2^* = 2.5 \mu\text{s}$ (see Ref. [17] for a detailed device description). The device is embedded in a SQUID, which is used as a sensitive magnetometer for qubit readout [18]. We implement the readout by applying a short current pulse to the SQUID to determine its switching probability P_{sw} . When statically biasing the qubit loop at half a flux quantum $\Phi_0/2$ ($\Phi_0 = h/2e$), the Hamiltonian becomes $H = -\frac{\hbar}{2}[w_{\text{qb}}\hat{\sigma}_z + A(t)\hat{\sigma}_x]$, where $w_{\text{qb}}/2\pi = 5.4 \text{ GHz}$ is the qubit frequency and $A(t) = A_I(t)\cos(\omega t) + A_Q(t)\sin(\omega t)$ is the drive field. The drive is generated by applying an oscillatory flux $\Phi(t)$ to the qubit loop using an on-chip antenna, giving $A(t) = 2I_p\Phi(t)/\hbar$, with $I_p = 180 \text{ nA}$ being the loop's persistent current. When driving the qubit resonantly ($\omega = w_{\text{qb}}$) and going to the rotating frame, we get

$$H = -\frac{\hbar}{2}[A_I(t)\hat{\sigma}_x^{\text{rot}} + A_Q(t)\hat{\sigma}_y^{\text{rot}}], \quad (1)$$

which is the Hamiltonian depicted in the Bloch sphere in Fig. 1(b).

The microwave pulses are created by generating in-phase $[A_I(t)]$ and quadrature $[A_Q(t)]$ pulse envelopes using a Tektronix 5014 arbitrary waveform generator (AWG), and sending them to the internal in-phase and quadrature mixer of an Agilent 8267D microwave generator. We write the total transfer function from generator to qubit as $\mathcal{H} = \mathcal{H}_{\text{ext}}\mathcal{H}_{\text{int}}$, where \mathcal{H}_{ext} refers to imperfections in the electronics and coaxial cables outside the cryostat, and \mathcal{H}_{int} describe signal distortion occurring inside the cryostat, for example, from bonding wires or impedance mismatches on the chip. To ensure that the pulses we send to the cryostat are initially free from distortion, we determine \mathcal{H}_{ext} with a high-speed oscilloscope and use $\mathcal{H}_{\text{ext}}^{-1}$ to correct for imperfections in the AWG and in the in-phase quadrature mixers [19,20]. The setup allows us to create well-defined Gaussian-shaped microwave pulses with pulse widths as short as $t_{\text{pw}} = 2.5 \text{ ns}$ [21].

To extract information about \mathcal{H}_{int} , we drive the qubit with consecutive pairs of positive and negative π pulses in $A_I(t)$, separated by the pulse period T . The sequence is depicted in Fig. 2(a), together with Bloch spheres describing the qubit states at various points of the pulse sequence. Note that in

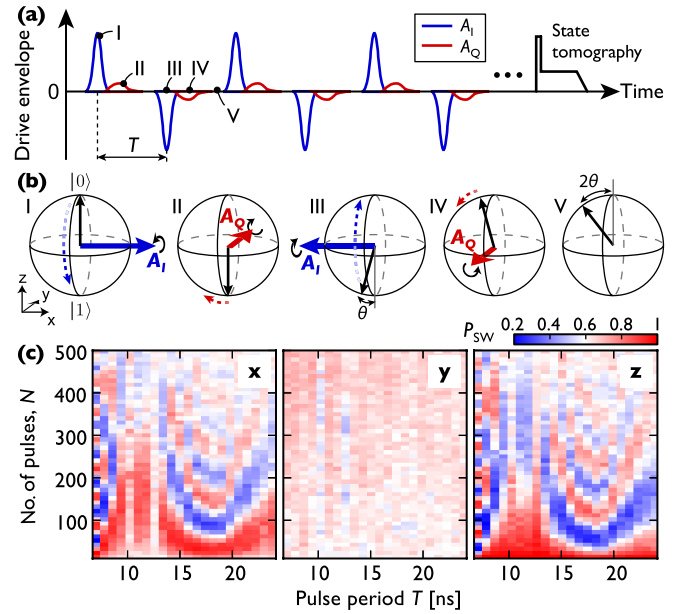


FIG. 2 (color online). (a) Pulse sequence used to probe quadrature components in the microwave pulses. (b) Bloch spheres depicting the evolution of the qubit during the pulse sequence in (a). The angle θ is the quadrature rotation acquired per π pulse. (c) Switching probability P_{sw} after the pulse sequence in (a), measured versus pulse period T and total number of pulses N , and projected onto the three axis x , y , and z .

Fig. 2(a), we show an example of the drive pulses that reach the qubit, including a small A_Q distortion after each pulse to better illustrate how the sequence works. The signal we create at the generator does not have any quadrature components. Starting with the qubit in the ground state, we apply a π pulse around x to take the qubit to $|1\rangle$ [step I in Figs. 2(a) and 2(b)]. Next, the A_Q part, due to the pulse distortion, induces a small rotation θ around y , bringing the qubit state slightly off the south pole (II). The negative π pulse then takes the qubit back towards the north pole (III), but since this pulse is inverted, the following A_Q part rotates the state even further away from $|0\rangle$ (IV). After the first two pulses, the qubit has acquired a rotation of 2θ around the y axis (V). The sequence is then repeated, and for each pair of subsequent π pulses the qubit rotates another 2θ .

Figure 2(c) shows the qubit state after the pulse sequence, measured versus the number of pulses and the pulse period T , and projected onto the three axes x , y , and z using additional $\pi/2$ pulses to do state tomography before reading out the qubit's polarization [22]. There are clear oscillations in the x and z components, verifying that the qubit indeed rotates around the y axis despite the pulses being applied to x . Note that the rotation frequency is relatively slow: it typically takes a few hundred π pulses to perform one full rotation around y . A striking feature of Fig. 2(c) is that the oscillation frequency varies with pulse period all the way up to $T = 25 \text{ ns}$, much longer than the pulse width $t_{\text{pw}} = 2.5 \text{ ns}$. This indicates that the quadrature distortions persist for a substantial time after the pulse should have ended.

To explain why the quadrature rotations depend on pulse period, we need to understand what happens when the π pulses start to overlap with the distortions of the previous π pulses. Let us start by assuming that the π pulses are instantaneous, and consider the qubit response to the static quadrature distortion shown in Fig. 3(a), where $A_Q(t)$ remains constant at $A_Q/2\pi = 0.4$ MHz for 30 ns after the π pulse in $A_I(t)$ at $t = 0$. Figure 3(b) shows the qubit quadrature rotation during the distortion, plotted for different values of the pulse period T . If T is 30 ns or longer [black circles in Fig. 3(b)], the qubit will continuously rotate in one direction during $A_Q(t)$, acquiring a total rotation per pulse of $\theta = \int_{t=0}^{t=30 \text{ ns}} A_Q(t) dt \approx 4.3$ deg. However, if the pulse period is only $T = 15$ ns [green squares in Fig. 3(b)], the second π pulse in A_I at $t = 15$ ns will reverse the direction of the A_Q -induced rotations of the first pulse. The rotation per pulse θ acquired with $T = 15$ ns ends up being zero, since the rotations during the second half of $A_Q(t)$ exactly cancel out the rotations during the first half. For $T = 10$ ns [blue diamonds in Fig. 3(b)], there are two extra π pulses in A_I occurring during the distortions of the first pulse, and we end up with $\theta = 1.4$ deg. Note that we only consider the rotation due

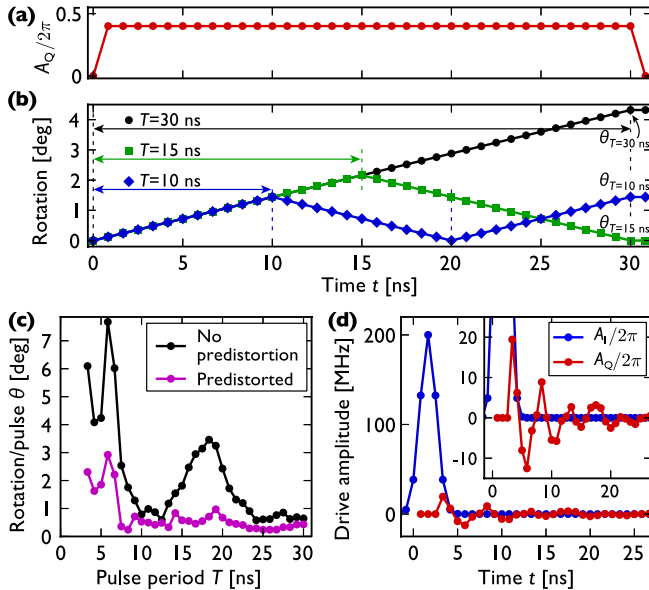


FIG. 3 (color online). (a) Constant quadrature distortion $A_Q(t)$ used to illustrate how the rotation angle depends on pulse period. (b) Qubit quadrature rotation for the quadrature distortion shown in (a), calculated with the pulse sequence from Fig. 2(a) and plotted for a few different pulse periods T . (c) Quadrature rotation θ acquired per π pulse. The black points are extracted from data similar to the measurement shown in Fig. 2(c). The gray (magenta) points are the results using a predistorted pulse shape, aimed at minimizing the quadrature distortion. (d) Quadrature component A_Q appearing at the sample when applying a 2.5 ns wide Gaussian pulse A_I at the input of the experimental setup.

to the distortion of the first π pulse; the total qubit rotation will be a sum of the rotations from all pulses.

Having understood why θ depends on pulse period T for a given $A_Q(t)$, we now ask if we can invert the problem: given a measurement of θ as a function of T such as the black trace in Fig. 3(c), can we extract the pulse distortions $A_Q(t)$? To simplify the problem, we discretize time in the smallest steps available with our AWG, $\Delta t = 1/(1.2 \text{ GS/s}) \approx 0.83$ ns, and write $A_Q(t)$ as a vector $\vec{Q} = [Q_1, Q_2, \dots, Q_N]$, with $Q_n = A_Q(n\Delta t)$. The rotations $\theta(T)$ in Fig. 3(a) are measured with the same time resolution, and in a similar fashion we write $\theta(T)$ as $\vec{\theta} = [\theta_1, \theta_2, \dots, \theta_N]$, $\theta_m = \theta(m\Delta t)$. Both vectors contain $N = 30 \text{ ns}/\Delta t = 36$ elements. We still assume the π pulses in A_I to be instantaneous, occurring with a period of $m = T/\Delta t$ in the discretized time.

As explained previously, the π pulses will act to periodically reverse the direction of the \vec{Q} -induced rotations, and the total rotation angle θ_m generated by \vec{Q} becomes a sum of forward and backward rotations, depending on the period of the π pulses:

$$\theta_m = \Delta t \left[\sum_{n=1}^m Q_n - \sum_{n=m+1}^{2m} Q_n + \sum_{n=2m+1}^{3m} Q_n - \dots \right]. \quad (2)$$

We can write Eq. (2) as a system of linear equations $\vec{\theta} = \Delta t \mathbf{M} \vec{Q}$, where \mathbf{M} is a matrix with elements being either 1 or -1 depending on the direction of rotation [21]. By inverting the matrix, we get the quadrature distortions directly from the measured rotations θ :

$$\vec{Q} = \mathbf{M}^{-1} \vec{\theta} / \Delta t. \quad (3)$$

In the experiment, the π pulses have a finite width $t_{\text{pw}} = 2.5$ ns, and the matrix \mathbf{M} needs to be modified slightly to account for the finite pulse duration [21]. In Fig. 3(d), we show the extracted quadrature response \vec{Q} , calculated using Eq. (3) and the rotation data θ from Fig. 3(c). For reference we also plot the shape and amplitude of the intended drive pulse A_I , digitized at $I_n = A_I(n\Delta t)$. The pulse has an amplitude of 200 MHz, giving a π rotation in $t_{\text{pw}} = 2.5$ ns. The extracted quadrature response \vec{Q} has considerably lower amplitude, but keeps oscillating for 25 ns after the main pulse ends.

Next, we use the measured response shown in Fig. 3(d) to determine the transfer function \mathcal{H}_{int} of the system [21]. With knowledge of \mathcal{H} , we can calculate the inverse \mathcal{H}^{-1} and use it to predistort the input signal, with the aim of reducing the quadrature distortions. The gray (magenta) trace in Fig. 3(c) shows the quadrature rotations θ for the same sequence of positive or negative pulses, but this time measured with a predistorted input signal. Compared to the black trace, θ has been significantly reduced for all values of the pulse period T , thus validating our method for extracting \mathcal{H} . We attribute the rotations still present after

predistortion to errors due to oversimplifications in the linear model in Eq. (3) used to extract \vec{Q} . It may be possible to get a better estimate for A_Q by calculating the qubit response using the full dynamics of the Hamiltonian in Eq. (1), but it would involve solving a system of 36 nonlinear equations, which computationally is much harder than inverting the matrix \mathbf{M} in Eq. (3).

Note that there may also be pulse distortions appearing in the in-phase component A_I . However, the consecutive positive and negative pulses in the sequence of Fig. 2(a) will cancel the effect of any errors in the rotations around x , which is also confirmed in the experiment [the y component in Fig. 2(c) shows no oscillations]. This cancellation allows us to exclusively target the A_Q distortions.

Having determined a way to reduce quadrature distortions and improve the microwave pulse shapes, we proceed to characterize the qubit gate fidelity in our system. A convenient way of testing single-qubit gates is to implement the randomized benchmarking protocol (RBM) [15], where a random sequence of π and $\pi/2$ pulses around the x and y axes are applied to the qubit. If the pulses are imperfect, the qubit will start to dephase as the pulse errors accumulate. Figure 4(a) shows examples of decay traces, where the three traces correspond to data measured with either full predistortion ($\mathcal{H} = \mathcal{H}_{\text{ext}} \mathcal{H}_{\text{int}}$), with predistortion only for the room-temperature electronics ($\mathcal{H} = \mathcal{H}_{\text{ext}}$), or with no predistortion at all. The pulses with full predistortion give a significantly slower decay than those without; when fitting to an exponential decay we find a decay constant of $N = 537 \pm 22$ pulses, giving an average error per pulse of $1/N = (0.186 \pm 0.008)\%$, which corresponds to a fidelity of 0.99814. The error rate achieved here is a few times lower than the theoretical threshold of 0.75% required for implementing fault-tolerant quantum computation with surface codes [13,23].

In Fig. 4(b) we plot the average error per gate versus pulse width t_{pw} , with the pulse period set to $T = 3t_{\text{pw}}$. The predistorted pulses perform better for all pulse widths, showing that the pulse shapes have improved and again confirming the

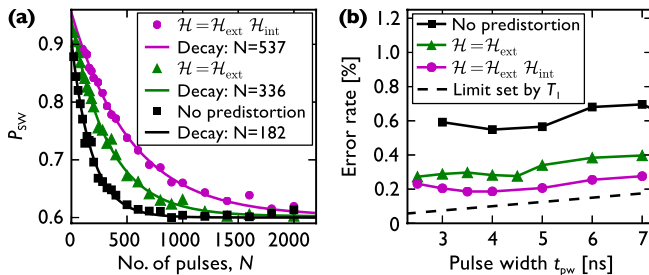


FIG. 4 (color online). (a) Qubit polarization as a function of the number of pulses in the RBM sequence, measured with and without predistortion. The pulses have width $t_{\text{pw}} = 3.5$ ns, separated by the period $T = 10.5$ ns. We use the same number of sequences and randomizations as in Refs. [3,15]. (b) Average error per pulse versus pulse width t_{pw} , measured with $T = 3t_{\text{pw}}$.

validity of our method for determining the transfer function \mathcal{H}_{int} . The general trend is that the gate error is reduced for shorter pulses; this decreases the total time $t_{\text{total}} = NT$ of the sequences, thereby reducing the errors due to loss of qubit coherence. The relevant coherence time during the RBM sequence is a combination of T_1 , T_2 , and the coherence time during driven evolution; for simplicity, we plot the expected error rate if the pulse errors were limited by $T_1 = 12 \mu\text{s}$ [dashed line in Fig. 4(b)]. This limit is a factor of 2 lower than our best results, indicating that the predistorted pulses still contain some pulse imperfections. We speculate that parts of the remaining errors are due to in-phase pulse distortions, which are not targeted with the method presented here. A similar scheme may be developed to investigate the in-phase errors independently. Another complication is that, in our system, T_1 is strongly reduced when driving the qubit continuously at Rabi frequencies above 100 MHz, probably due to local heating [24]. This may contribute to pulse errors for short pulses (where the drive amplitude $A \propto 1/t_{\text{pw}}$ becomes large). At high drive amplitudes the Bloch-Siegert shift will also start to introduce deviations from the rotating-wave approximation in Eq. (1).

To summarize, we have demonstrated a new technique of using a qubit to determine and correct microwave pulse imperfections, which for this sample allowed us to reduce the average error per gate by 37% and generate single-qubit rotations with an average gate fidelity better than 0.998. Even though there have been reports of superconducting qubits in 3D cavities with coherence times approaching $100 \mu\text{s}$ [25,26], we note that we obtain a higher gate fidelity in our system because we are able to create shorter pulses. By encoding the pulse imperfections into a slow rotation when applying many pulses, we are able to detect distortions on a nanosecond time scale without the need of a fast detector. This makes our method very general, and it can be applied to any quantum computing architecture where single-qubit gates are implemented by applying microwave pulses at the qubit frequency.

We thank X. Jin and P. Krantz for helpful discussions and K. Harrabi for assistance with device fabrication. This work was sponsored in part by the U.S. Government, the Laboratory for Physical Sciences, the U.S. Army Research Office (W911NF-12-1-0036), the National Science Foundation (PHY-1005373), the Funding Program for World-Leading Innovative R&D on Science and Technology (FIRST), NICT Commissioned Research, MEXT kakenhi “Quantum Cybernetics,” Project for Developing Innovation Systems of MEXT.

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