

Inertia and Chiral Edge Modes of a Skyrmion Magnetic Bubble

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The dynamics of a vortex in a thin-film ferromagnet resembles the motion of a charged massless particle in a uniform magnetic field. Similar dynamics is expected for other magnetic textures with a nonzero Skyrmion number. However, recent numerical simulations reveal that Skyrmion magnetic bubbles show significant deviations from this model. We show that a Skyrmion bubble possesses inertia and derive its mass from the standard theory of a thin-film ferromagnet. In addition to center-of-mass motion, other low energy modes are waves on the edge of the bubble traveling with different speeds in opposite directions.

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The dynamics of topological defects is a topic of long-standing interest in magnetism. The attention to it stems from rich basic physics as well as from its connection to technological applications [1]. The theory of magnetization dynamics in ferromagnets well below the critical temperature is based on the Landau-Lifshitz equation [2] for the unit vector of magnetization $\mathbf{m}(\mathbf{r}) = \mathbf{M}(\mathbf{r})/M$,

$$\dot{\mathbf{m}} = \gamma \mathbf{B} \times \mathbf{m} + \alpha \mathbf{m} \times \dot{\mathbf{m}}, \quad (1)$$

where γ is the gyromagnetic ratio, $\alpha \ll 1$ is a phenomenological damping constant [3], and the effective magnetic field is a functional derivative of the free energy, $\mathbf{B}(\mathbf{r}) = -\delta U/\delta \mathbf{M}(\mathbf{r})$. The latter includes local (e.g., exchange and anisotropy) as well as long-range (dipolar) interactions, thus making Eq. (1) a nonlinear and nonlocal partial differential equation with multiple length and time scales solvable in only a few simple cases. For example, translational motion of a rigid texture, $\mathbf{m} = \mathbf{m}[\mathbf{r} - \mathbf{R}(t)]$, is fully parametrized by the texture's "center-of-mass" \mathbf{R} . For steady motion, $\mathbf{R}(t) = \mathbf{V}t$, the velocity can be obtained from Thiele's equation [4] expressing the balance of gyrotopical, conservative, and viscous forces,

$$\mathbf{G} \times \dot{\mathbf{R}} + \mathbf{F} - D\dot{\mathbf{R}} = 0. \quad (2)$$

Here \mathbf{G} is a gyrocoupling vector, $\mathbf{F} = -\partial U/\partial \mathbf{R}$ is the net conservative force, and D is a dissipation tensor. A rigid texture moves like a massless particle with electric charge in a magnetic field and an external potential through a viscous medium. If $\mathbf{G} \neq 0$, the "Lorentz force" greatly exceeds the viscous drag. We thus ignore dissipation.

Although Eq. (2) was derived for steady motion, Thiele anticipated that it could serve as a good first approximation in more general situations. Indeed, his equation describes very well the dynamics of vortices in thin ferromagnetic films [5–9]. In this case, the gyrocoupling vector $\mathbf{G} = (0, 0, \mathcal{G})$ is proportional to a topological invariant known as the Skyrmion charge $q = (1/4\pi) \int dx dy \mathbf{m} \cdot (\partial_x \mathbf{m} \times \partial_y \mathbf{m})$, the film thickness t , and the density of angular momentum M/γ ; to wit, $\mathcal{G} = -4\pi q t M/\gamma$. A vortex has

$q = \pm 1/2$ and thus $\mathbf{G} \neq 0$. In a parabolic potential well, $U(X, Y) = \mathcal{K}(X^2 + Y^2)/2$, it moves in a circle at a frequency $\omega = \mathcal{K}/\mathcal{G}$.

Similar behavior is expected for other topologically non-trivial textures, e.g., magnetic bubbles in thin films with magnetization normal to the plane of the film [10–12]. A bubble is a circular domain with $m_z < 0$ surrounded by a domain with $m_z > 0$, or vice versa, Fig. 1(a) [13]. Recently discovered Skyrmion crystals [14,15], particularly those which are found in thin films [16,17], are periodic arrays of magnetic bubbles with the same Skyrmion charge $q = \pm 1$ [18]. Zang *et al.* [19] modeled Skyrmions in these structures as massless particles with Thiele's dynamics (2). However, numerical simulations of Moutafis *et al.* [20] showed that this approach does not reproduce the simulated motion of an isolated bubble. In a parabolic potential, the trajectory of the bubble's center was not a circle, but "roughly a pentagon"; see Fig. 1(c).

The main goal of this Letter is to derive the correct dynamical model of a Skyrmion magnetic bubble. We first introduce our model phenomenologically and then derive it from the standard theory of a thin-film ferromagnet. This allows us to characterize not only the center-of-mass motion of the bubble but also the dynamics of its shape within the same framework.

Phenomenology.—The puzzling trajectory of the bubble's center is readily reproduced if we endow a Skyrmion bubble with inertial mass \mathcal{M} ,

$$-\mathcal{M}\ddot{\mathbf{R}} + \mathcal{G} \times \dot{\mathbf{R}} - \mathcal{K}\mathbf{R} = 0. \quad (3)$$

The new equation of motion is of the second order in d/dt and has two circular modes with frequencies,

$$\omega_{\pm} = -\mathcal{G}/2\mathcal{M} \pm \sqrt{(\mathcal{G}/2\mathcal{M})^2 + \mathcal{K}/\mathcal{M}}. \quad (4)$$

A particle with zero initial velocity follows a hypocycloid. If $\omega_-/\omega_+ = -4$, the hypocycloid has five cusps and indeed resembles a pentagon, Fig. 1(d). We repeated the simulations of Moutafis *et al.* and found that the motion of

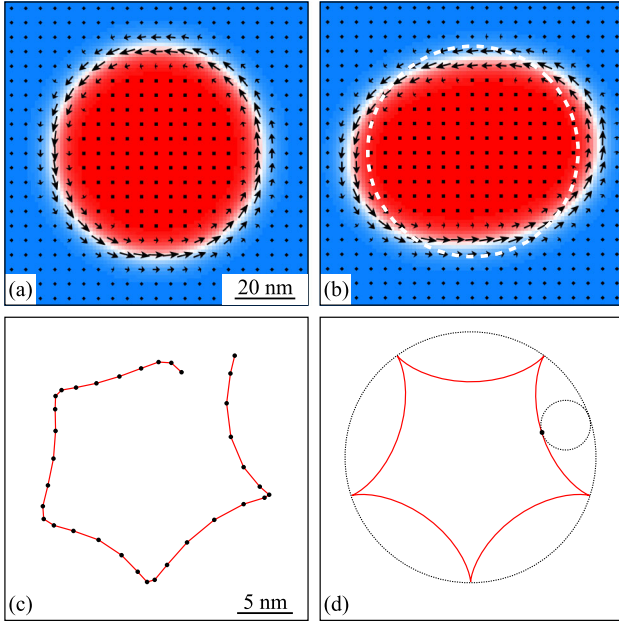


FIG. 1 (color online). A circular magnetic bubble with Skyrmion number $q = -1$. Out-of-plane magnetization is $M_z > 0$ (blue) outside the wall and $M_z < 0$ (red) inside; in-plane magnetization on the domain wall is shown by arrows. (a) Equilibrium. (b) Elliptic deformation. The dashed line marks the equilibrium position of the domain wall. (c) The trajectory of the bubble's center observed by Moutafis *et al.* Dots mark positions evenly spaced in time. (d) A 5-cusped hypocycloid with its directing and generating circles.

the bubble is described with good accuracy by a superposition of two underdamped modes with eigenfrequencies $\omega/2\pi = 0.97$ GHz and -4.27 GHz [21].

To understand the origin of inertia, we shift attention from the center of the bubble, where nothing is happening, to its boundary, a domain wall defined as a line $y(x)$, where $M_z(x, y) = 0$. A nearly circular domain wall is conveniently parametrized in polar coordinates (r, ϕ) ,

$$r(\phi) = \bar{r} + \sum_m r_m e^{im\phi}. \quad (5)$$

The Fourier amplitudes $r_m = r_m^*$ describe waves with wave numbers $k = m/\bar{r}$ traveling along the circular edge: r_0 is the breathing mode, $r_1 = (X - iY)/2$ encodes the location of the center of mass, r_2 parametrizes elliptical deformations, Fig. 1(b), and so on. On the domain wall, magnetization lies in the plane of the film, $\mathbf{m} = (\cos\psi, \sin\psi, 0)$. For a circular wall in equilibrium, \mathbf{m} points along the direction of the wall, $\psi = \phi \pm \pi/2$, Fig. 1(a). More generally,

$$\psi(\phi) = \phi \pm \pi/2 + \sum_m \psi_m e^{im\phi}. \quad (6)$$

The fields $r(\phi)$ and $\psi(\phi)$ are coupled to each other, and so are their harmonics r_m and ψ_m . Integrating out ψ_1 generates kinetic energy for the center of mass.

Theory.—We derive the dynamics of transverse fluctuations of a Bloch domain wall, first for a straight wall and

then for a circular one. To this end, we employ a method of collective coordinates generalizing Thiele's approach beyond steady motion [22]. The Lagrangian formalism allows us to easily integrate out the hidden degree of freedom—in-plane magnetization—in favor of the more evident transverse motion.

An evolving magnetic texture $\mathbf{m}(\mathbf{r}, t)$ can be parametrized by a (potentially infinite) set of collective coordinates $\boldsymbol{\xi}(t) = \{\xi_1(t), \xi_2(t), \dots\}$. Their equations of motion are similar to Thiele's equation (2),

$$G_{ij}\dot{\xi}_j + F_i - D_{ij}\dot{\xi}_j = 0, \quad (7)$$

with generalized forces $F_i = -\partial U/\partial \xi_i$, gyrotropic coefficients $G_{ij} = -G_{ji}$, and viscosity coefficients $D_{ij} = D_{ji}$. Equation (7) can be obtained from a Lagrangian $L = \mathbf{A} \cdot \dot{\boldsymbol{\xi}} - U(\boldsymbol{\xi})$, where $\mathbf{A}(\boldsymbol{\xi})$ is a gauge potential with curvature $\partial A_j/\partial \xi_i - \partial A_i/\partial \xi_j = G_{ij}$ [23]. The gauge term contributes to the action $S = \int L dt$ a time-independent piece $\int \mathbf{A} \cdot d\boldsymbol{\xi}$ known as Berry's geometric phase.

Straight domain wall.—We first consider the dynamics of a domain wall stretched along the x axis, $y(x, t) \approx 0$, $\psi(x, t) \approx 0$, from $x = 0$ to $x = \ell$. Its Lagrangian,

$$L[y, \psi] = \int_0^\ell dx g \dot{y} \dot{\psi} - U[y, \psi], \quad (8)$$

contains a gauge term with gyrotropic coupling $g = 2tM/\gamma$ [24,25]. The resulting equations of motion are $-g\dot{\psi} - \delta U/\delta y = 0$, $g\dot{y} - \delta U/\delta \psi = 0$ in the absence of dissipation. The in-plane magnetization is aligned with the wall in equilibrium, $\psi = y' \equiv \partial y/\partial x$; the cost of small misalignments is quadratic in $\psi - y'$, so

$$L[y, \psi] = \int_0^\ell dx [g\dot{y}\dot{\psi} - \kappa(\psi - y')^2/2] - U[y], \quad (9)$$

with the stiffness κ to be determined. The field ψ can be integrated out with the aid of its equation of motion, $g\dot{y} - \kappa(\psi - y') = 0$, to obtain a Lagrangian for transverse displacements,

$$L[y] = \int_0^\ell dx (\rho \dot{y}^2/2 + g\dot{y}y') - U[y], \quad (10)$$

where $\rho = g^2/\kappa$ is the Döring mass density [24,25].

Potential energy of a domain wall can be split into local and long-range contributions. The local term is proportional to the length of the wall and tension σ ,

$$U_l[y] = \int_0^\ell \sigma \sqrt{dx^2 + dy^2} \approx U_l[0] + \int_0^\ell dx \sigma y'^2/2, \quad (11)$$

where $U_l[0] = \sigma\ell$ is the energy of a straight wall. Thus,

$$L[y] = \int dx (\rho \dot{y}^2/2 + g\dot{y}y' - \sigma y'^2/2) - U_{nl}[y]. \quad (12)$$

Neglecting for the moment the nonlocal term $U_{nl}[y]$, we obtain a wave equation, $\rho \ddot{y} + 2g\dot{y}' - \sigma y'' = 0$, with waves traveling left and right at *different speeds*, cf. Eq. (4),

$$\omega = \rho^{-1} \left(-gk \pm \sqrt{g^2 k^2 + \sigma \rho k^2} \right). \quad (13)$$

In the limit $\sigma \ll g^2/\rho = \kappa$, the slow wave has velocity $v_1 \sim \sigma/2g$ that is insensitive to inertia; in-plane magnetization adiabatically aligns with the direction of the wall. The fast mode with velocity $v_2 \sim -2g/\rho$ involves oscillations of in-plane magnetization out of phase with those of the direction of the wall.

A minimal model of a thin-film ferromagnet with out-of-plane magnetization includes exchange coupling A and easy-axis anisotropy K strong enough to overcome the dipolar shape anisotropy: the “quality factor” $Q = 2K/\mu_0 M^2$ must exceed 1. In this model (see Supplemental Material [21]), a domain wall has the width $\lambda/\sqrt{Q-1}$, where $\lambda = \sqrt{2A/\mu_0 M^2}$ is the exchange length, and tension $\sigma = 2\mu_0 M^2 t \lambda \sqrt{Q-1}$. The coupling between the in-plane magnetization and the direction of the wall is $\kappa = \sigma/(Q-1)$. By using the material parameters characteristic of FePt with thickness $t = 32$ nm [20], we obtain $v_1 = 370$ m/s and $v_2 = -2100$ m/s in the local model.

The nonlocal part of the potential energy comes from long-range dipolar interactions. A domain wall in a thin ferromagnetic film produces a stray magnetic field whose energy can be written as a double line integral along the domain wall [26,27],

$$U_{nl}[\mathbf{r}] = -\frac{\sigma_d}{2} \int \frac{d\mathbf{r}_1 \cdot d\mathbf{r}_2}{|\mathbf{r}_1 - \mathbf{r}_2|}, \quad (14)$$

where $\sigma_d = \mu_0 M^2 t^2 / \pi$ is “dipolar tension.” This expression diverges at both short and long length scales and thus requires both short- and long-distance cutoffs (provided by the film thickness and the wall length). The local potential energy (11) may be absorbed into the nonlocal part (14) at the expense of renormalizing the short-distance cutoff. Expanding Eq. (14) to the second order in y yields the following result:

$$U_{nl}[y] = U_{nl}[0] + \ell \int_0^\infty \frac{dk}{2\pi} \sigma_d k^2 \ln(ka) |y_k|^2, \quad (15)$$

where $y_k = \ell^{-1/2} \int_0^\ell dx y(x) e^{-ikx}$, $U_{nl}[0] \sim -\sigma_d \ell \ln(\ell/a)$ is the energy of a straight domain wall, $a = (t/2)e^{C-1+\sigma/\sigma_d}$ is a short-distance length scale, and $C = 0.577 \dots$ is the Euler constant. The wave stiffness $\sigma_d k^2 \ln(ka)$ is negative for $k < 1/a$, which means that a straight domain wall is unstable against small deformations. This is the fingering instability occurring in systems with long-range interactions [26,28]. It can be prevented by placing the domain wall in a strip of finite width w . Repulsion from the edges, mediated by a stray magnetic field, increases the wave stiffness by a k -independent term $4\sigma_d/w^2$. The wave frequencies are

$$\omega = \rho^{-1} \left[-gk \pm \sqrt{g^2 k^2 + \sigma_d \rho (k^2 \ln|ka| + 4/w^2)} \right]. \quad (16)$$

The frequency spectrum (Fig. 2) has two significant changes from the local model (13): a gap opens up; the band bottom is shifted to $k_0 = e^{-1/2} a^{-1}$.

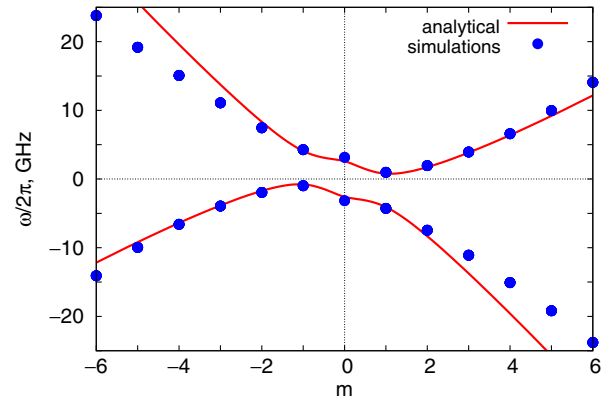


FIG. 2 (color online). The spectrum of spin waves $\omega/2\pi$ on a circular domain wall: numerical simulation (circles), model calculations for a straight wall (16) with $k = m/\bar{r}$ (line).

Magnetic bubble.—The dynamics of a circular domain wall is derived along similar lines. For a wall of given shape (5), the in-plane magnetization tends to align itself with the wall, $\psi_{\text{eq}}(\phi) = \phi \pm \pi/2 - \bar{r}^{-1} \partial r / \partial \phi$. The ψ -dependent terms in the Lagrangian density are thus $g\dot{r}\psi - \kappa(\psi - \psi_{\text{eq}})^2/2$. The Lagrangian of the Fourier modes (5) and (6) is

$$L[r, \psi] = 2\pi\bar{r} \sum_m \left(g\dot{r}_m \psi_m^* - \frac{\kappa |\psi_m + imr_m/\bar{r}|^2}{2} \right) - U[r]. \quad (17)$$

Integrating out ψ yields a Lagrangian for r containing both kinetic energy and a Berry-phase term,

$$L[r] = \sum_m (\pi\bar{r}\rho |\dot{r}_m|^2 - 4\pi m i g r_m^* \dot{r}_m) - U[r]. \quad (18)$$

We thus arrive at a Lagrangian for the center-of-mass mode $r_1 = (X - iY)/2$,

$$L(X, Y) = \mathcal{M}(\dot{X}^2 + \dot{Y}^2)/2 + \mathcal{G}\dot{X}Y - \mathcal{K}(X^2 + Y^2)/2. \quad (19)$$

It yields the anticipated inertial dynamics of a magnetic bubble (3). The gyrotropic constant, $\mathcal{G} = 2\pi g = 4\pi t M / \gamma = 2.29 \times 10^{-12}$ J s/m², depends only on the topology of the bubble (here the Skyrmion number $q = 1$) and on the area density of angular momentum tM/γ ; therefore, it can be taken at face value. The spring constant \mathcal{K} comes from magnetostatic repulsion between the domain wall and the edge of the disk; its calculated value, $\mathcal{K}_{\text{calc}} = 0.020$ J/m² for $\bar{r} = 37$ nm, should also be reliable. The weakest link in our theory is the mass term $\mathcal{M}_{\text{calc}} = \pi\bar{r}\rho = \pi\bar{r}g^2/\kappa = 5.4 \times 10^{-23}$ kg. It depends on the coupling κ between in-plane magnetization and the direction of the wall and thus requires an accurate model of the domain wall. Alternatively, the basic constant \mathcal{G} can be combined with the measured frequencies, $\omega_{\text{sim}}/2\pi = 0.97$ GHz and -4.27 GHz, to obtain $\mathcal{K}_{\text{sim}} = 0.018$ J/m² and $\mathcal{M}_{\text{sim}} = 1.11 \times 10^{-22}$ kg. As expected,

we find a good match between the calculated and simulated values of the spring constant \mathcal{K} , but the \mathcal{M} values differ by a factor of 2.

We have performed numerical simulations to measure the frequency spectrum of waves with higher azimuthal numbers m . We used the same geometry and material parameters as Moutafis *et al.*: a FePt disk of radius $R = 80$ nm, thickness $t = 32$ nm, magnetization $M = 10^6$ A/m, exchange constant $A = 10^{-11}$ J/m, easy-axis anisotropy $K = 1.3 \times 10^6$ J/m³, and gyromagnetic ratio $\gamma = 1.75 \times 10^{11}$ s A/kg. These give the quality factor $Q = 2.06$ and exchange length $\lambda = 4.0$ nm. We utilized micro-magnetic simulator OOMMF [29] in the two-dimensional regime with a unit cell of 1.25 nm. The equilibrium radius of the bubble was $\bar{r} = 37$ nm. The free motion of the m th harmonic of $\rho(\phi)$ was fitted by a sum of two underdamped components. The extracted frequencies are shown in Fig. 2. The theoretical curve is the straight-wall spectrum (16) with $k = m/\bar{r}$. We used the mass density extracted from the simulation of the $m = 1$ mode, $\rho = \mathcal{M}_{\text{sim}}/\pi\bar{r}$, and set the effective width w equal to the disk radius. The theory works quite well for the slow mode, less so for the fast one.

Discussion.—The widely used Thiele’s equation (2) predicts that magnetic textures with a Skyrmion number $q \neq 0$ behave as massless particles moving in a uniform magnetic field and an external potential. Although this approach works very well for magnetic vortices ($q = \pm 1/2$), it fails for Skyrmion magnetic bubbles ($q = \pm 1$). Here we have shown that a Skyrmion bubble behaves as a massive object and have explained the origin of its mass. A Skyrmion bubble possesses additional modes, which are best viewed as transverse fluctuations of its edge. These waves are chiral; i.e., they propagate with different speeds in opposite directions. The nonreciprocal wave propagation is expected in other geometries, e.g., striped and labyrinthine domains.

In a Skyrmion crystal, the discrete modes of a bubble turn into excitation branches. The slow and fast $m = 1$ modes give rise to the magnetophonon and cyclotron branches [30]; the cyclotron frequency $\omega = \mathcal{G}/\mathcal{M}$ is in the GHz range. The $m = 0$ breathing mode has been seen in numerical simulations [31]. The breathing mode and one of the $m = 1$ modes have been found in Cu₂OSeO₃ [32]. Branches with higher m may also be detectable.

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