


Study of the wall pressure variations on the stall inception of a thick cambered profile at high Reynolds number

Caroline Braud 

*Nantes Université, CNRS, Centrale Nantes, Laboratoire LHEEA, 44300 Nantes, France
and CSTB, Centre Scientifique et Technique du Bâtiment, 44300 Nantes, France*

Bérengère Podvin 

Université Paris-Saclay, CNRS, CentraleSupélec, Laboratoire EM2C, 91190 Gif-sur-Yvette, France

Julien Deparday 

IET, OST-Eastern Switzerland University of Applied Sciences, 8640 Rapperswil, Switzerland



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We present an experimental study of the aerodynamic forces on a thick and cambered airfoil at a high Reynolds number (Re) (3.6×10^6), which is of direct relevance for wind turbine design. Unlike thin airfoils at low chord-based Reynolds numbers, no consistent description currently exists for the stall process on such airfoils. We consider two chordwise rows of instantaneous wall pressure measurements, taken simultaneously at two spanwise locations over a range of angles of attack. We show that around maximum lift conditions, a strong asymmetry is observed in the statistics of the normal force on each chord. In this range of angles of attacks, the pressure fluctuations are largest in the adverse pressure gradient region, and the fluctuation peak along the chord is systematically located directly upstream of the mean steady separation point, indicating intermittent flow separation. Moreover, the fluctuations are characterized by bistability in both space and time: For each spanwise location, large excursions of the local wall pressure between two different levels can be observed in time (jumps), and these excursions are highly anticorrelated between the two spanwise locations (spatial switches). The characteristic timescale for the switches is found to be well correlated with the amplitudes of the fluctuations. Application of proper orthogonal decomposition (POD) analysis to each row of sensors confirms that the flow separation is an inherently local, three-dimensional, and unsteady process that occurs in a continuous manner when the angle of attack increases. The correlation between the dominant POD mode amplitudes is found to be a good indicator of bistability. For all angles of attack, most of the fluctuations can be captured with the two most energetic POD modes. This suggests that force fluctuations near the maximal lift could be modelled by a low-order approach for monitoring and control purposes.

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I. INTRODUCTION

Understanding the flow over airfoils is crucial for numerous applications such as aircraft or wind turbines. These systems evolve in the atmosphere, thus with strong interactions with the turbulence from atmospheric boundary layer flows [1]. Turbulence modifies the flow structure and dynamics over aerodynamic surfaces and leads to additional fatigue or loss of controllability. Many recent studies have demonstrated the importance of such phenomena on two-dimensional (2D) airfoils submitted to different turbulent inflows in controlled environments, i.e., wind tunnels [2–5]. Most of

the turbulent inflow effects inducing load variations occur for angles of attack close to the maximum lift value, at which, for example, wind turbines operate under optimal conditions or during the take-off or landing of an aircraft. Understanding the flow physics at these angles of attack, however, remains challenging, even in static conditions. The flow of an airfoil undergoing static stall and the resulting aerodynamic force are unsteady, and the dynamic features of static stall are qualitatively similar to those of the dynamic stall [6]. Understanding better static stall physics may help to improve further the dynamic stall phenomena which have been investigated by numerous studies (see, e.g., Refs. [7–10]).

The description of the flow physics on airfoils is generally based on a 2D scenario with three main regions of interest: (1) a boundary layer developing on the upper surface up to (2) the separation point where the flows starts to detach, which then interacts with (3) the wake at the trailing edge of the airfoil. Each of these regions is characterized by complex phenomena, which depend on many parameters and in particular the Reynolds number.

Due to the airfoil geometry and angle of attack, the flow over the airfoil is subject to a continuously varying spatial pressure gradient, and the boundary layer is therefore not in the equilibrium state that can be expected for instance for a fully developed turbulent boundary layer on a flat plate. The boundary layer state depends on the surface roughness, the turbulence intensity, and the Reynolds number, the effects of which are difficult to disentangle [4,11,12]. The flow can remain laminar within the entire recovery region at low chord-based Reynolds number (Re_c , Reynolds number based on the blade chord) (smaller than 3×10^4) if the surface roughness, the turbulence intensity, and the angles of attacks are low. With the increase of the Reynolds number, the transition to a turbulent boundary layer moves towards the leading edge, and can result in the formation of a laminar separation bubble. At Reynolds numbers larger than 10^5 , the length of the separation bubble is generally of the order of a few percentages of the airfoil chord and thus does not greatly alter the pressure from its normal attached distribution [13].

The airfoil performance is also greatly affected by the flow separation over the airfoil which depends on the state of the boundary layer, the adverse pressure gradient and the wake. The flow separation position moves along the chord, from which a shear layer is formed at the interface between the low-speed separated flow region and the free stream. Once the flow is separated, the shear layer vortices may influence wake vortex shedding characteristics. Wake vortices are formed in the near wake region and are shed alternately on the upper and lower surface of the airfoil. They are present at all angles of attack, as observed by Yarusevych *et al.* [14]. Yarusevych *et al.* [15] showed that universal scaling based on local length scales could be identified in both the separated shear layer and the wake. Furthermore, the wake can be influenced by the three-dimensionality of the flow field [16]. Despite a possible spanwise dependence of the flow dynamics, for load evaluation statistical invariance is generally assumed in the spanwise direction at all angles of attack, and measurements are only taken along a single chord.

When the flow is completely separated over the airfoil, the lift force decreases, which is often referred to as the stall phenomenon. Gault [17] found that the type of stall observed was highly dependent on the airfoil geometry and on the Reynolds number. For different thickness ratios ranging from 0 to 24% of the chord, and Reynolds numbers ranging from 0.7 to 25×10^6 , Gault was able to distinguish four types of stall. The leading-edge and the thin-airfoil stalls mostly happen on symmetric, thin airfoils and at low chord-based Reynolds numbers. It is abrupt and fast, occurring directly at the leading edge. The trailing-edge stall is a progressive displacement of the boundary layer flow separation from the trailing edge to the leading edge, as described, for instance, by Soulier *et al.* [18] using flow-field measurements. The last type of stall is a combined trailing-edge and leading-edge stall which was observed by Bak *et al.* [19] using a moderately thick airfoil and high chord-based Reynolds-number experiments, $Re_c = 1.3 \times 10^6$. Moderately thick airfoils are widely used for engineering systems operating in the atmosphere such as wind turbines blades, as they yield less load fluctuations near the maximum lift angle of attack when large inflow variations are encountered compared to thin airfoils. The flow physics have been widely investigated for symmetric shapes and at low chord-based Reynolds numbers (see, e.g., Refs. [13,15]), but fewer

TABLE I. Blade characteristics of experiments at high Reynolds numbers using thick profiles (Refs. [4,9,23,24,30]). “NC” denotes “not communicated” and “Scanned” denotes that it has been scanned from a 2-MW wind turbine blade.

| Reference | Airfoil name | Thickness | Re_c | Type of stall according to Gault [17] |
|---------------|--------------|--------------|--|---------------------------------------|
| Present study | Scanned | 20% <i>c</i> | 3.4×10^6 | TE |
| [29] | NACA0021 | 21% <i>c</i> | $5 \times 10^5 \leq Re_c \leq 7.9 \times 10^6$ | From TE to LE |
| [31] | NC | 18% <i>c</i> | 10^6 | TE |
| [32] | NACA64-418 | 18% <i>c</i> | 10^6 | TE |
| [33] | NACA63-418 | 18% <i>c</i> | 3.4×10^6 | TE |
| [34] | Scanned | 20% <i>c</i> | 4.7×10^6 | TE |

studies exist at high Reynolds numbers above 10^6 , and/or for (moderately) thick ($>20\%$ of the chord) and asymmetric shapes.

Understanding the flow physics and stall behavior at these high Reynolds numbers remains a challenge for both experimental and numerical approaches. Although transitional regimes $Re_c \simeq 2.5 \times 10^4 - 10^5$ have been studied in detail with direct numerical simulations (DNS) and large eddy simulations (LES) [20,21], the cost of such approaches still remains prohibitively high at these Reynolds numbers, despite efforts to relax LES resolution requirements [22]. The unsteady Reynolds averaged Navier-Stokes simulations (URANS) formalism then represents a viable alternative and has been successful to predict hysteresis [23,24], as well as 3D effects [25–27], but URANS prediction of separation near or at stall should be viewed with caution. Bifurcation analysis of the stall at high Reynolds numbers has provided useful insight but has been so far limited to a 2D approach [28].

Investigations at high Reynolds numbers also represent an experimental challenge. Small facilities rapidly experience disproportionate compressibility effects to reach high Reynolds numbers. Adequate wind tunnels for this purpose are generally either of very large size, such as those typically used in industry, or pressurised facilities that were specifically designed to increase the Reynolds number [29,30]. Experiments are thus more directed towards time-averaged, global force measurements rather than local and unsteady characterisations. Table I presents a summary of different studies performed at high Reynolds numbers for different airfoil thicknesses. Except in one case, all stalls are of the trailing-edge type. Furthermore, at high Reynolds numbers, near the maximum lift, the flow becomes three-dimensional and displays complex dynamics, while measurement tools remain limited to study these dynamics, especially for large-scale facilities. Manolesos *et al.* [31] and Ragni and Ferreira [32] have analyzed three-dimensional flow separation in wind tunnel experiments at chord-based Reynolds numbers of $O(10^6)$.

Flow visualizations provided evidence of a spanwise distribution of stall cells near the maximum lift value. For similar Reynolds numbers, Olsen *et al.* [33] have recently shown the high sensitivity of the lift curve close to the maximum lift to small differences in the experimental execution. Brunner *et al.* [29] have investigated the Reynolds number effect ranging from 5×10^5 to 7.9×10^6 of a moderately thick airfoil. Fundamental change of flow behavior was observed around $Re_c = 2 \times 10^6$: The stall gradually shifts from trailing-edge stall to leading-edge stall. In contrast, only trailing-edge stalls were found by Neunaber *et al.* [34] when investigating a 2D blade of similar thickness but of different shape. The blade was extracted from a 2-MW turbine at 80% of the rotor diameter (20% thick) and was studied at a chord-based Reynolds number of 4.7×10^6 . The same blade section has also been investigated in a lower Reynolds-number range [$O(10^5)$] [4]. Both Reynolds number ranges exhibit a trailing-edge stall, contrary to what was found for a different airfoil shape by Brunner *et al.* [29].

Moreover, Neunaber *et al.* [34] found that the normal forces measured at two different spanwise locations alternated between two quasi-steady states, thus pointing out to bistability in space and

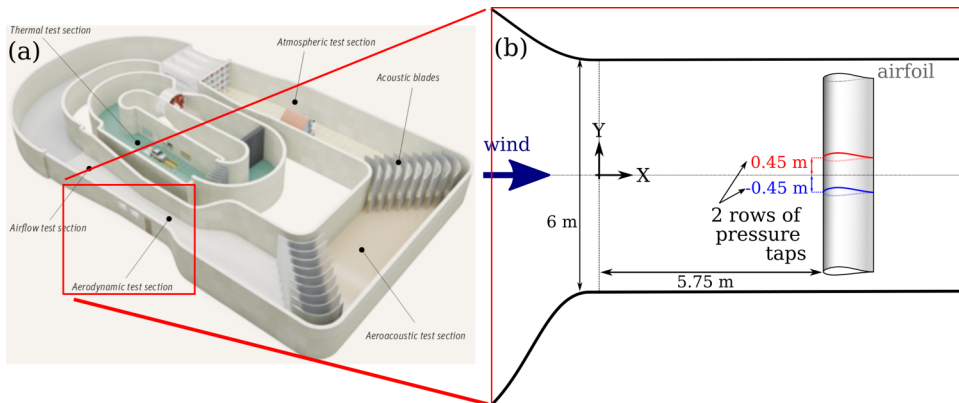


FIG. 1. (a) The CSTB wind tunnel and (b) schematics of the 2D blade installation in the aerodynamic test section with the two rows of 78 pressure taps each in the chordwise direction at two different spanwise locations (red and blue corresponds to respectively Y^+ and Y^- locations). (c) The inflow is measured 2.65 m upstream of the profile by a cobra probe. From Neunaber *et al.* [34].

time. This bistability was correlated with the unsteady displacement of the separation point. These recent findings highlight the fact that the stall process at high Reynolds number is a complex phenomenon, still not fully understood.

Using the same configuration as Neunaber *et al.* [34], the present paper focuses on investigating the flow bistability evolution with the increase of the angle of attack. Comparison of the two chords provides a check on the statistical bidimensionality of the flow, which is often assumed *a priori*. In addition, the spatial organization of the fluctuations is described using proper orthogonal decomposition (POD), which has proved to be a useful tool to extract coherent structures from pressure measurements in a variety of turbulent flows, for such phenomena as jet mixing layer instabilities [35], flow separation over a blunt flat plate [36], or flapping instability of a sail [37]. POD has also been applied to airfoils at moderate Reynolds numbers [$O(10^5)$]; Villegas and Diez [38] have investigated the relationship between vortex shedding and aerodynamic force fluctuations, while Ribeiro and Wolf [39] and Yang *et al.* [40] have focused on the generation mechanisms of airfoil tonal noise. In this study, the high Reynolds number considered is reached thanks to the large-scale test section of the Centre Scientifique et Technique du Bâtiment (CSTB) climatic wind tunnel, i.e., a test section of size 5 by 6 m. We first present in Sec. II the setup of experiments and we briefly review the POD method. We then give a general statistical description of the normal force in Sec. III. Section IV is focused on the spatiotemporal characteristics of the flow bistability. POD analysis of the wall pressure fluctuations is provided in Sec. V. The main spatiotemporal features of the pressure fluctuations, and their dependence on the angle of attack, are summarized in Sec. VI.

II. EXPERIMENTAL SETUP AND METHODS

A. The CSTB wind tunnel

Experiments have been performed in the aerodynamic test section of the CSTB wind tunnel [Fig. 1(a)]. The test section is 6 m wide and 5 m high and has a length of 12 m. The free stream wind can reach a speed of 70 ms^{-1} and is controlled to keep a constant and uniform velocity, taking into account the air density variations. The turbulence intensity is less than 1.5% in the empty test section.

B. Two-dimensional blade section

The 2D blade has a chord of 1.25 m and a span of 5 m, which is 1 m smaller than the test section, so that wall boundary layers of the test section (20 cm thick at maximum) do not interact with the blade. The resulting blockage is thus 8% at 24° , which compares well with other studies carried out at high Reynolds numbers [41]. The blockage effect is likely to have some influence on the effective angle of attack. Computations at zero incidence using correction laws provided in Ref. [42] yielded an effective angle of attack of 1° , although this result should be interpreted with caution near flow separation owing to the limitations of these estimation methods which are based on potential flow theory. The aspect ratio of the blade is 4, which is one of the largest ratio set in the literature at large Reynolds numbers (see, e.g., Ref. [41]). To prevent large end-plates from increasing the blockage, the extremities of the wing are set free. The blade is not spanning the entire test section so that tip vortices are formed on both sides of the model. It was verified that the tip vortices do not interact with the central part of the wing by using nylon tufts installed on the airfoil surface prior to the experiments.

The blade has been set at 5.75 m from the inlet on a lattice support structure that allows to set predefined angles of attack (AoA). To obtain a good yaw alignment of the blade with the inflow, a cross-line laser level is used to align a transverse line marked at 10% of the chord perpendicular to the build-in line on the wind tunnel floor which is parallel to the incoming wind direction. The yaw angle is therefore zero with an accuracy of $\pm 0.1^\circ$.

The blade profile comes from 3D scans of a commercial 2-MW wind turbine blade at 80% of its rotor diameter. It can be approximated by a NACA63-3-620 airfoil shape with a modified camber (4% instead of 2%). The maximum thickness is located at around 33% of the chord while the maximum camber is located at approximately 49% of the chord. Following Gault [17], we expect to find either trailing-edge stall or combined trailing-edge and leading-edge stall because of the thick and highly cambered profile shape.

C. Unsteady wall pressure measurements

The 2D blade section was equipped with two rows of 78 unsteady wall pressure taps each in the chordwise direction, located at two spanwise positions equally distributed from the midspan of the blade ($Y^- = -450$ mm and $Y^+ = +450$ mm) [Fig. 1(b)]. The chordwise spacing between the pressure taps is $0.026c$, where c is the chord of the airfoil. The pressure taps were connected to five multiplexed EPS pressure scanners of 32 channels each, using 1.5-m vinyl tubes with an internal diameter of 0.8 mm. Two ranges of the pressure sensors were used depending on their location, 0 to 7 kPa near the leading-edge suction peak and 0 to 2.5 kPa elsewhere, with a precision of $\pm 0.03\%$ of the full measurement range. The transfer function of the whole system (tubes plus sensor cavity) has been measured off-line at a sampling frequency of 1024 Hz following the methodology of Holmes and Lewis [43] and Whitmore *et al.* [44] and has been taken into account in the processing of the pressure data. The signal acquisition was performed using two National Instrument acquisition boards linked by real-time system integration for synchronization purposes. During the measurements, the sampling frequency was 200 Hz. Measurements were carried out at eight angles of attack between 6° to 24° . The measurement duration was 120 s for each angle of attack. The inflow velocity was $U_0 = 40.5$ ms $^{-1}$ which leads to a chord-based Reynolds number of $Re_c = 3.4 \times 10^6$.

In this study, the mean normal force coefficient C_N and the mean pressure coefficient $C_p = \Delta p/q_0$ (with Δp the differential pressure between wall pressure and the dynamic pressure q_0) were primarily investigated. The normal force coefficient indicates the normal force acting on the airfoil in the airfoil coordinate system and was obtained by integrating the pressure coefficient around the airfoil. As the lift force is calculated from the normal and tangential forces, and the latter are only partially retrievable from the pressure coefficient (the viscous part of the tangential force

was ignored using this measurement method), we focus on the normal force coefficient in this study.

D. Detection of the flow separation

For the analysis of the wall pressure variations presented in this paper, the region of the flow separation is a salient feature and must be correctly detected and therefore correctly defined. However, unlike the laminar case, turbulent separation is characterized by “a spectrum of states,” as first pointed out by Kline [45]. Sandborn and Kline [46] suggested that separation should be viewed as a transition process over a region of variable length and proposed a model with two distinct separation regions, corresponding to intermittent and steady separation. The model was validated by Sandborn and Liu [47] and extended by Simpson *et al.* [48], who introduced several new definitions, based on the amount of time reverse flow is observed at a particular location. In particular, the following regions were defined: (i) incipient detachment, for which reverse flow is observed 1% of the time, (ii) intermittent transitory detachment, corresponding to 20% of the time, and (iii) transitory detachment, corresponding to 50% of the time. Simpson *et al.* [48] found that transitory detachment coincided with a zero value for the time-averaged wall shear stress.

Sandborn and Liu [47] used Stratford’s criterion [49] theoretically developed using simplified turbulent equations to identify the steady separation point. An extension of this criterion was used in Refs. [34,50], where the separation point was defined as the first location where the pressure gradient becomes smaller than a given threshold. An advantage of this definition is that it can be applied to instantaneous pressure coefficients, making it possible to track the separation point in time. In addition to this separation point definition, we will use another definition for the intermittent separation region, based on the location of the pressure fluctuation peak. This region is located upstream of the steady separation point (SSP) as already pointed out in Refs. [45,47,48]. The location of the fluctuation peak maximum, which is defined only statistically, will be referred to throughout the paper as the *intermittent separation point (ISP)*.

E. Proper orthogonal decomposition

To obtain further insight into the organization of the fluctuations, we apply POD. POD [51] is a statistical technique that provides a spectral decomposition of the covariance of the fluctuations and makes it possible to represent the spatiotemporal pressure signal p as a superposition of spatial patterns $\Phi_n(x)$, the amplitude of which varies in time. The reader is referred to Ref. [52] for more details. Here we will consider the fluctuating pressure signal for each spanwise location and apply POD independently to Y^+ and Y^- . We checked that excluding the pressure side from the decomposition did not alter the shape of the modes and the domain of analysis was thus restricted to the suction side. Given N_T time measurements at times t_k of the pressure signal $p(x_i, t_k)$ taken at N different chord positions x_i , one builds the autocorrelation matrix M ,

$$M_{ij} = \frac{1}{N_T} \sum_{k=1}^{N_T} p(x_i, t_k) p(x_j, t_k),$$

from which one extracts N eigenvalues λ_n and N eigenvectors or empirical modes $\Phi_n(x)$. We note that the normalized eigenmodes Φ_n are defined within an arbitrary sign change. The λ_n can be ordered following $\lambda_1 \geq \lambda_2 \geq \dots \lambda_N$ and represent the contributions of each mode n to the total variance. In addition, the instantaneous pressure fluctuation at any location can then be reconstructed as

$$p(x_i, t_k) = \sum_{n=1}^N \lambda_n^{1/2} a_n(t_k) \Phi_n(x_i) \quad (1)$$

and the evolution of each normalized mode amplitude a_n can be considered independently.

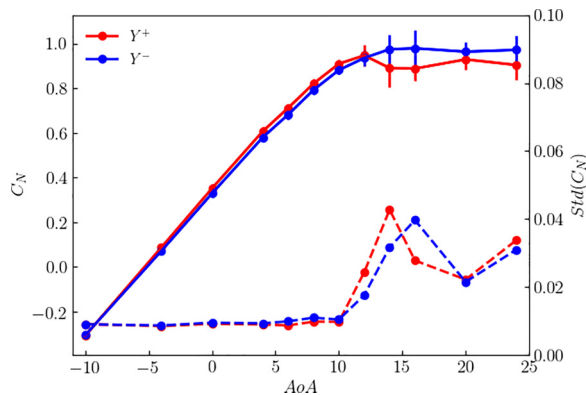


FIG. 2. Normal force coefficient C_N in solid lines and standard deviation of C_N in dashed lines from both spanwise locations, Y^+ and Y^- .

III. STATISTICAL DESCRIPTION

A. Normal force

The normal force obtained by integration of the chordwise pressure distribution at both spanwise locations, Y^+ and Y^- , shows a typical lift distribution of wind turbine blade sections (see Fig. 2). At low angles of attacks ($\leq 8^\circ$), the normal force increases linearly with the angle of attack. Then a transition occurs with a significant but progressive modification of the slope, becoming almost null above an angle of attack of 12° . This slope evolution corresponds to a boundary layer flow separation at the trailing edge, as is confirmed from the trailing-edge flattening of the mean pressure chordwise distribution (see Fig. 4). The evolution of the normal force for both rows of pressure Y^+ and Y^- is almost identical until the angle of attack 12° , which proves a good symmetry of the flow upstream and over the airfoil. At higher angles of attack, on the plateau of the maximum normal force, the row Y^+ (in red in Fig. 2) follows the same trend as Y^- but with values approximately 5% smaller.

The symmetry observed when the flow is fully attached breaks at higher angles of attack. The asymmetry coefficient $\Delta C^{rel} = 2[C_N(Y^+) - C_N(Y^-)]/[C_N(Y^+) + C_N(Y^-)]$ is represented in Fig. 3. The shaded area of the curve delimits the values obtained when segments corresponding to 25% of the signal length were used. The narrow gray area confirms that the presence of asymmetry is a

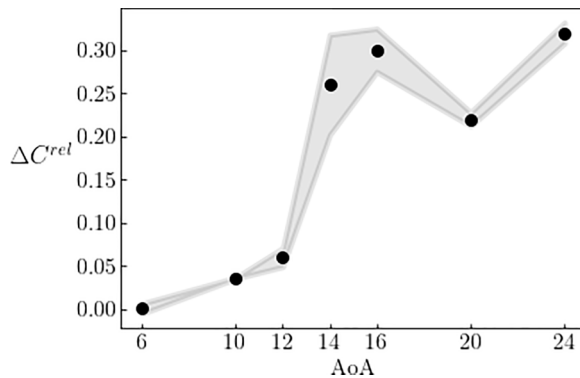


FIG. 3. Asymmetry coefficient $\Delta C^{rel} = 2[C_N(Y^+) - C_N(Y^-)]/[C_N(Y^+) + C_N(Y^-)]$ for the complete data set (solid points). Gray areas represent the results when only 25% of the data set length are used.

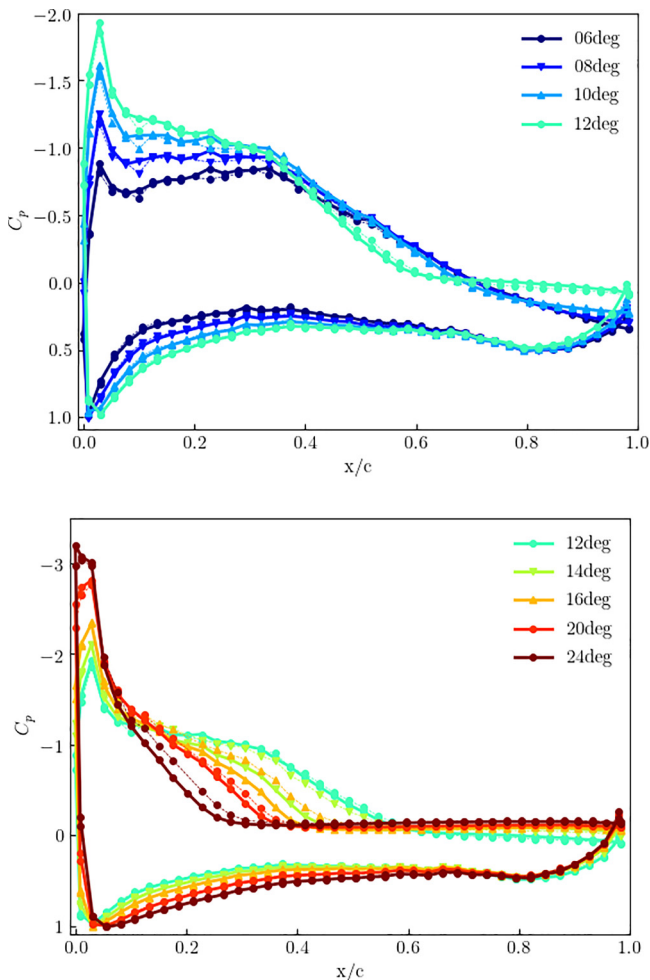


FIG. 4. Pressure coefficient (C_p) distribution in chordwise direction x/c for both spanwise locations (Y^+ in dotted lines and Y^- in solid lines) for different angles of attack: (a) from 6° to 12° and (b) from 12° to 24° . The markers indicate the pressure measurement locations.

robust feature of the flow. Two chords of measurements are naturally not enough to characterize in detail the structure of the flow in the spanwise direction; however, they give information about the loss of two-dimensionality of the flow statistics, which is usually taken for granted. We note that symmetry-breaking behavior has been observed in other symmetric geometries such as the wake of a sphere (Refs. [53,54] as well as for the flow behind an Ahmed body [55]).

The standard deviations, reported in dashed lines in Fig. 2, start to increase at 10° and then progressively increase with the angle of attack, with a maximum at 14° for Y^+ and at 16° for Y^- , followed by a small decrease at 20° . This indicates strong lift fluctuations at the maximum lift that will be analyzed further in the following sections.

B. Chordwise wall pressure distribution

We now examine the spatial distribution of the wall pressure along the chord. Figures 4 and 5 respectively represent the average and the standard deviation of the pressure coefficient for the different angles of attack. The dotted lines in Figs. 4 and 5 represent the other row of pressures, Y^+ .

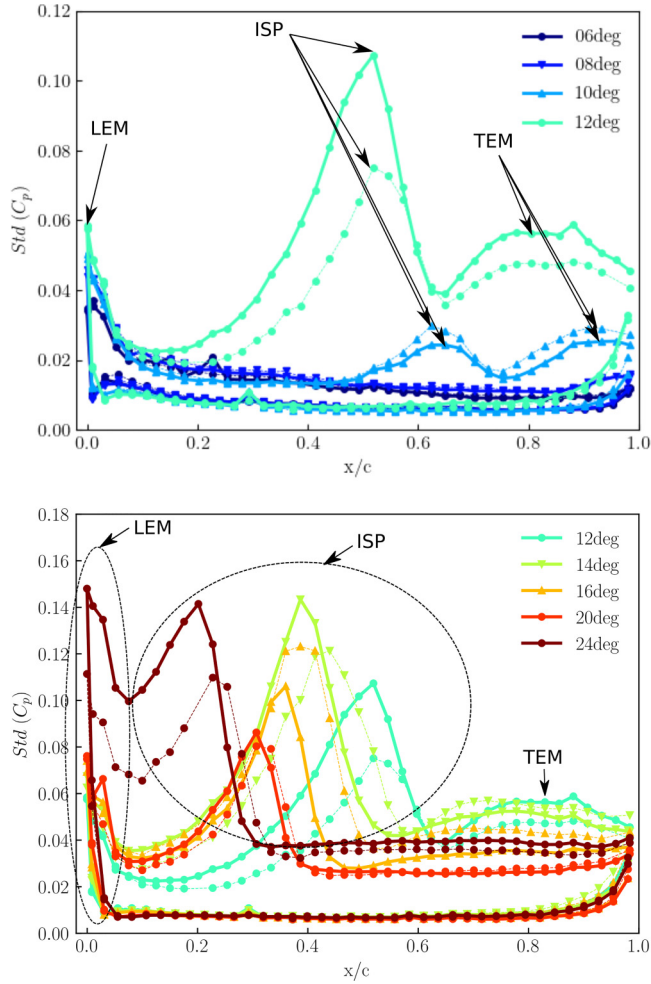


FIG. 5. Standard deviation of the wall pressure coefficient, $Std(C_p)$, along the chord x/c for both spanwise locations (Y^+ in dotted lines and Y^- in solid lines) for different angles of attack: (a) from 6° to 12° and (b) from 12° to 24° . The markers indicate the pressure measurement locations. Note the difference of the scale for the y axis between the low angles of attack (a) and high angles of attack (b) to highlight the apparitions of local maxima at 10° . Local maxima are respectively denoted LEM, leading-edge maximum; ISP, intermittent separation point; TEM, trailing-edge maximum.

We note that the asymmetry observed in C_N is also observable for C_P and $Std(C_P)$ quantities at the same angles of attack.

1. Chordwise wall pressure distribution

The pressure distributions for all angles of attack have similar features: a peak of suction at the leading edge, a zone of high suction in the first half of the chord, and then a decrease of the suction down to the trailing edge also called the recovery region. The peak of suction at the leading edge increases with the increase of the angle of attack, reaching -3 at an angle of attack of 24° . After the peak of pressure at the leading edge, the high suction zone loses intensity when the angle of attack increases, so that the recovery region starts closer to the leading edge. A progressive flattening of the mean pressure coefficient curve is observed in the trailing-edge region from 12° to 24° , which

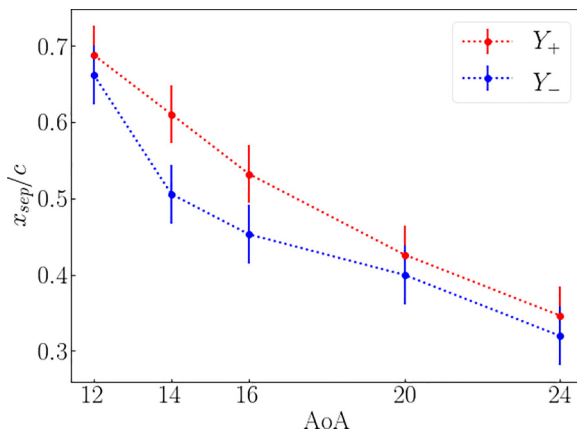


FIG. 6. Evolution of the separation point with the angle of attack for both spanwise locations. Error bars represent the accuracy in the evaluation of the separation point due to the pressure tap resolution.

indicates that the flow is progressively separating according to the criteria of Celik *et al.* [50] and Neunaber *et al.* [34] (see Sec. IID). Figure 6 shows that the separation point moves progressively at a nearly constant rate towards the leading edge as the angle of attack increases, with a marked asymmetry between the spanwise locations at 14° and 16° . At other angles of attack, the observed differences fall within the uncertainty due to the spacing between sensors.

2. Wall pressure fluctuations

Figure 5 shows that the increase in the force fluctuations shown in Fig. 2 is characterized by the emergence of three local maxima: one close to the leading edge [leading-edge maximum (LEM)], a sharp one which we defined in Sec. IID as the intermittent separation point (ISP), and a smaller one corresponding to the separation region extending to the trailing edge or trailing-edge maximum (TEM). The two last maxima [ISP and TEM in Fig. 5(a)] are already noticeable at 10° , which can be considered to represent a precursor state for flow separation over the airfoil.

a. LEM. The first maximum corresponds to the fluctuations of the suction peak at the leading edge and increases as the suction peak increases with the angle of attack.

b. ISP. The second maximum of fluctuations [ISP in Fig. 5(a)] first appears at approximately 65% of the chord at 10° . This peak (ISP) is related to the intermittent displacement of the separation point as sketched in Fig. 7 by a red arrow around the ISP point on the blade surface. The instantaneous signal associated to this peak will be described further in Sec. IV A. At 12° , when flow separation appears on the airfoil, the ISP moves at around 55% of the chord and increases with an amplitude five times higher than at 10° . When the angle of attack is further increased until 20° , the ISP decreases progressively in amplitude and moves towards the leading edge [see Fig. 5(b)]. At the highest angle of attack 24° , the second maxima of pressure fluctuations (ISP) is located at 20% of the chord and interacts with the LEM, with a significant increase of it. High-intensity fluctuations are thus generated, which seems to signal the onset of a new regime corresponding to fully separated flow, and which will not be studied here.

c. TEM. The third maximum in the trailing-edge region (TEM at around 80% of the chord) does not move but spreads out and progressively decreases in amplitude with the angle of attack until it totally disappears at 20° . The TEM is linked to the separated shear-layer whose distance from the airfoil oscillates, causing pressure variations as explained with Fig. 7. The centerline of the separated shear-layer is progressively moving away from the airfoil surface with the angle of attack which induces a decrease of the amplitude [56].

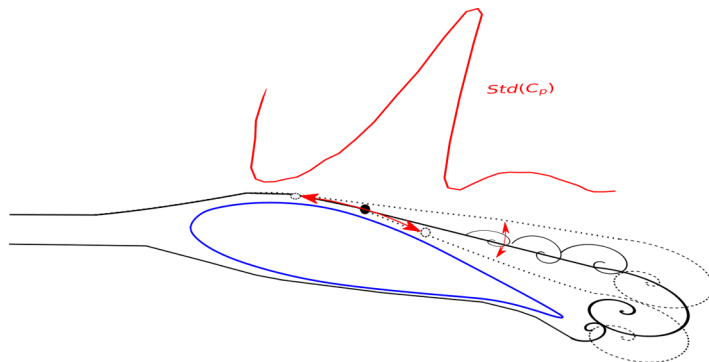


FIG. 7. Sketch of the flow physics corresponding to the spatial distribution of the pressure fluctuations. The red arrows along the blade surface show the intermittent flow separation associated with a large pressure standard deviation at the ISP, while the red arrows above the blade represent the fluctuations of the shear layer associated with the TEM.

3. Pressure gradient in the intermittent separation region

In the literature, the available quantity is generally limited to the average pressure around the chord at one blade span location. It is thus interesting to underline the link between the mean pressure and the fluctuating pressure that is related to the instability described in the present paper. Figure 8 displays on the same plot the pressure gradient (in black), the pressure standard deviation (in blue) and the mean pressure coefficient (in red) for the blade suction side. We will focus on the intermittent separation region away from the leading edge. At 10° , the mean pressure gradient takes high values in a large region at midchord spans from $x/c = 0.35$ to $x/c = 0.7$. The width of the region progressively shrinks with the increase of the angle of attack until 14° where a single peak is defined. As reported earlier, at 10° , the wall pressure standard deviation peak (in blue) displays two maxima: one in the central region corresponding to the large adverse pressure gradient and one close to the trailing edge. As the angle of attack increases, the trailing-edge maximum decreases and disappears for angles higher than 16° , while that in the pressure gradient region becomes important for 14° and 16° , i.e., where load fluctuations are maximal. A clear coincidence between the mean pressure gradient and standard deviation peaks can be observed for these angles. The strong connection between the two regions is still present at higher angles, as both peaks move toward and progressively merge with those at the leading edge. As detailed in Sec. II D, the steady separation point (SSP) is determined as the location where the pressure gradient falls below a certain threshold, while the ISP is defined at the peak of pressure fluctuations (see Fig. 6). These points are reported in Fig. 8. It is noticeable that for all angle of attacks over 12° , the ISP is located directly upstream of the SSP similarly as reported in Ref. [57].

In summary, it is shown that pressure fluctuations are significant in three regions: (i) the leading edge, (ii) the strong adverse pressure gradient region corresponding to the occurrence of intermittent separation, and (iii) the area where the flow is fully detached at the trailing edge. The pressure fluctuations are the highest around the maximal lift conditions, with a global fluctuation maximum in the ISP that coincides with the local pressure gradient maximum.

C. Coherence of the pressure fluctuations

The spatiotemporal evolution of the pressure fluctuations is represented at $\text{AoA} = 12^\circ$ in Figure 9 with the corresponding standard deviation. The local standard deviation minima (blue lines on the figure) are unambiguous criteria to delimit the region of strong pressure fluctuations that will be identified from now on as the intermittent separation region. The spatiotemporal map shows that at most instants, a strong spatial correlation is apparent in the intermittent separation region (and

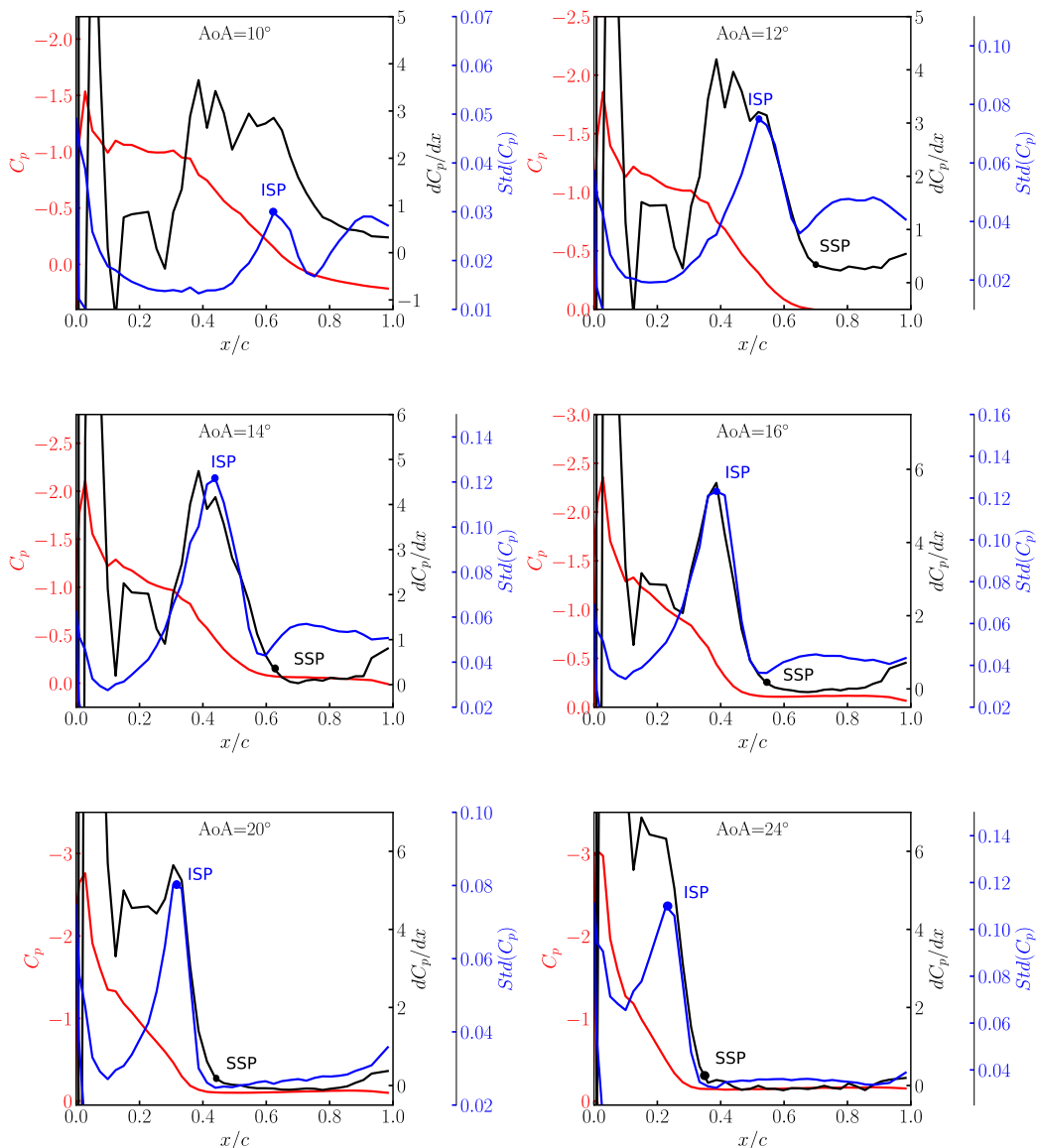


FIG. 8. Pressure coefficients C_p (in red), gradient of pressure dC_p/dx (in black), and standard deviation of the pressures $Std(C_p)$ (in blue) versus the chordwise direction, x/c , at the Y^- row for different angles of attack (from 10° to 24°). The ISP and the SSP locations are indicated in the figures.

to some lesser extent around the trailing edge). Some correlation in time is also noticeable in the intermittent separation region, in particular around the ISP. To characterize the organization of the fluctuations, we computed the coherence function of the pressure coefficient between the ISP and other chordwise location x/c . The coherence function is defined as

$$C_{x^{ISP}}(x, f) = \frac{S_{xx^{ISP}}(f)}{S_{xx}^{1/2}(f)S_{x^{ISP}x^{ISP}}^{1/2}(f)}, \quad (2)$$

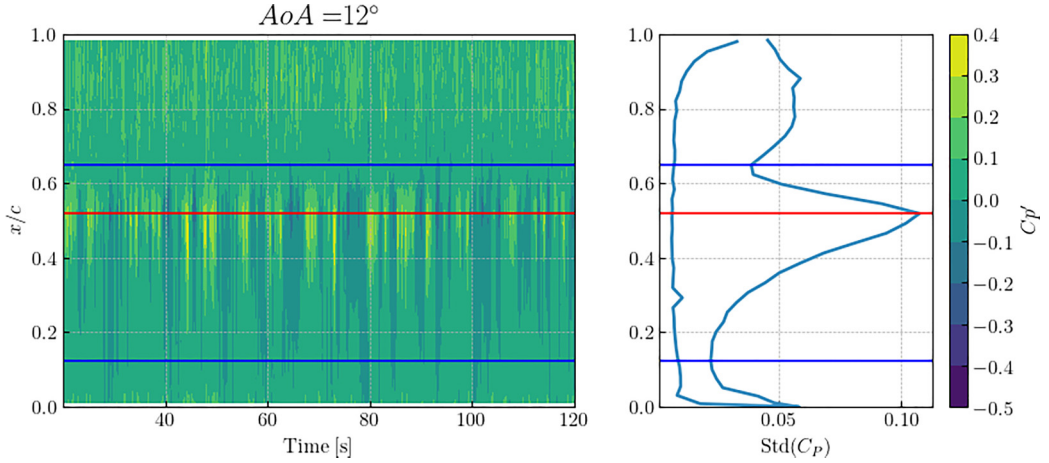


FIG. 9. Left: Spatiotemporal evolution of the wall pressure fluctuations at the spanwise location Y^+ (only suction side) and for $AoA = 12^\circ$. Right: Wall pressure standard deviation distribution for $AoA = 12^\circ$. For both plots, the red line represents the maximum location of the standard deviation peak in the recovery region and the blue lines correspond to the two local fluctuation minima delimiting the region of strong fluctuations.

where x is a location on the chord, x^{ISP} is the intermittent separation point (or maximum fluctuation location), $S_{xx^{ISP}}$ represents the cross-spectral density of the pressure signal at locations x , and x^{ISP} and S_{xx} represent the power spectral density at location x . High values of the coherence function represented in Fig. 10 can help identify spatial regions over which the pressure signals are well correlated. For clarity, the positions of the local maximum and local minima (respectively blue and red lines) are also reported in Fig. 10. At an angle of 10° , the main coherent region can be observed both upstream and downstream of the ISP. Its extent broadly coincides with the definition of the intermittent separation region as delimited by the blue lines. Some coherence is also present at the trailing edge, but its intensity gradually decreases and essentially disappears for $AoA \geq 16^\circ$. After separation, the main coherent region is relatively more important upstream of the maximum

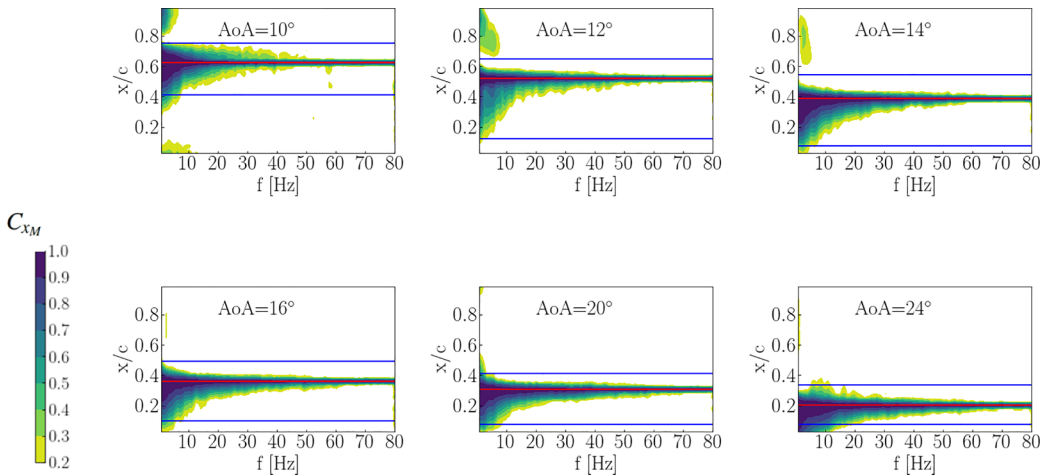


FIG. 10. Coherence $C_{xM}(x, f)$ between the pressure coefficient at location x on the suction side and the intermittent separation point x^{ISP} (indicated with a red line) on the chord $Y = Y^+$. The frequency is indicated in hertz. The blue lines correspond to local minima of the pressure fluctuations.

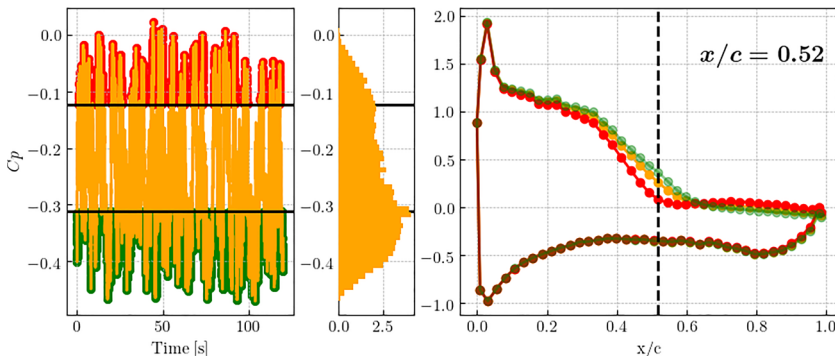


FIG. 11. Left: AoA = 12° ; instantaneous pressure signal (Y^+) at $x/c = 0.52$ at the intermittent separation point. Center: Histogram of the pressure signal. Right: Averaged pressure coefficient distribution based on full and conditional averages: high values (red), low values (green), and all values (orange).

location. Its size tends to decrease as the angle of attack increases. We note that no clearly identified frequency appears in the coherence plots, which seem dominated by a mixture of low frequencies (≤ 20 Hz).

IV. LOCAL PRESSURE FLUCTUATIONS

As seen in Figs. 2 and 3, it has been confirmed that the pressure variations and the separation points differ for the two rows of pressure Y^+ and Y^- at angles of attack between 12° and 20° . In Neunaber *et al.* [34], it was found that the highly unstable displacements of the separation point along each chord were anticorrelated and could be associated with a bistability phenomenon. The bistability was characterized in two ways: strong pressure *temporal jumps* on each chord, associated with *spatial switches* in intensity from one chord to another. The jumps and switches are investigated below using the instantaneous wall pressure signals at the ISP, which evolves with the angle of attack.

A. Jumps

In this section, we attempt to characterize the pressure jumps observed in the fluctuations, which is not straightforward given the temporal complexity of the signal (see Fig. 10). To do so, we consider the instantaneous pressure signal at the ISP on a single chord (we choose Y^+) at the angle of attack 12° , shown in Fig. 11 (left). The associated histogram [Fig. 11 (center)] shows a well-defined local maximum in the low-value range and a less clear one in the high-value range. These maxima (corresponding to the thick horizontal black lines in the figure) can be used as thresholds to delimit low-value and high-value regions (indicated respectively in green and red on the figure). A jump can then be defined as an excursion of the signal between the low-value and the high-value regions. In Fig. 11 (right), conditional averages of the pressure coefficient based on these two regions are compared with the average pressure coefficient distribution (in orange). At the ISP location, materialized by the dashed vertical line, low-value regions correspond to attached flow and high-value regions to separated flow.

To highlight this evolution, the instantaneous pressure signal is observed at a fixed point for different angles of attack (including the intermittent separation point). For instance, in Fig. 12(a), the chord location corresponds to the intermittent separation point at 12° , where the pressure variations are the highest compared to those at other angles of attack (10° , 14° , 16° , and 20°). The pressure signal at 12° jumps from one mean level measured for the angle of attack of 10° , where the flow is attached at this chord location, to another mean level measured for the higher angles of attack, where the flow is detached. Instead of oscillating around a mean value located between the

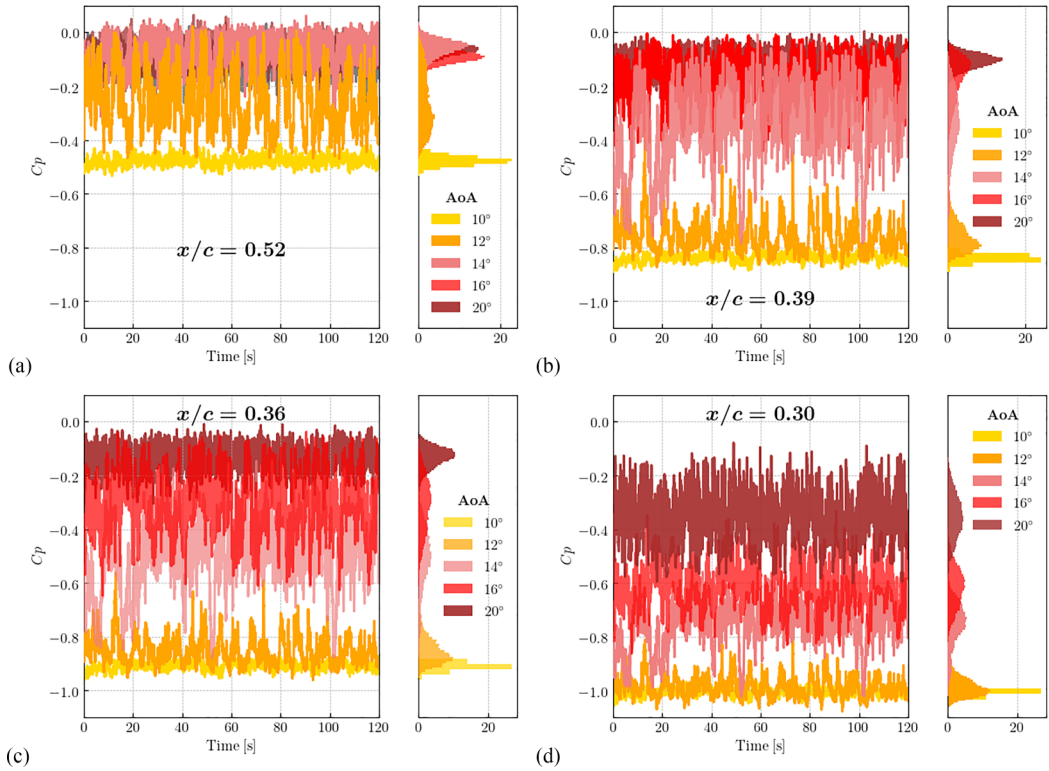


FIG. 12. Instantaneous pressure signals (Y^+) for different angle of attacks at four chordwise locations, $x/c = 0.52, 0.39, 0.36,$ and 0.30 , corresponding to the intermittent separation points at respectively $12^\circ, 14^\circ, 16^\circ,$ and 20° . The associated histograms are plotted on the right-hand side of each figure.

mean levels of 10° and 14° , with small amplitudes similar to those measured at the other angles of attack, the pressure signal at 12° has large variations, making large excursions into these two levels. The histogram plotted on the right side shows an elongated distribution with tails reaching both attached and separated pressure levels. The distribution has an almost bimodal shape with a negative skewness, which indicates that for this angle of attack, even if the flow is switching between attached and separated flow states, the preferred state is the attached flow.

For the other chord locations, from Figs. 12(b) to 12(d), the pressure difference increases significantly compared to Fig. 12(a) (see the difference between the brown curve and the yellow curve) and keeps increasing when the intermittent separation region moves toward the leading edge. In Fig. 12(b), corresponding to the intermittent separation point for an angle of attack of 14° , the wall pressure signal evolves from a negative (12°) to a positive (14°) skewness, so from a flow mostly attached to a flow mostly separated with no intermediate states within the 2° step of the angle of attack (note that on the other chord, the flow remains mostly attached at 14°). For Fig. 12(c), corresponding to the intermittent separation point for an angle of attack of 16° , the pressure signal at 14° displays a symmetric distribution representing an intermediate state between the mostly attached and mostly detached state. The pressure signal at 16° is flatter and reach both this intermediate state and the mostly detached state. For Fig. 12(d), where the intermittent separation point is defined for an angle of attack of 20° , no narrow and well defined detached state is easily defined, and the pressure signals for 14° and 16° show symmetric distributions, representing intermediate states. As a result, bistability cannot be easily identified anymore.

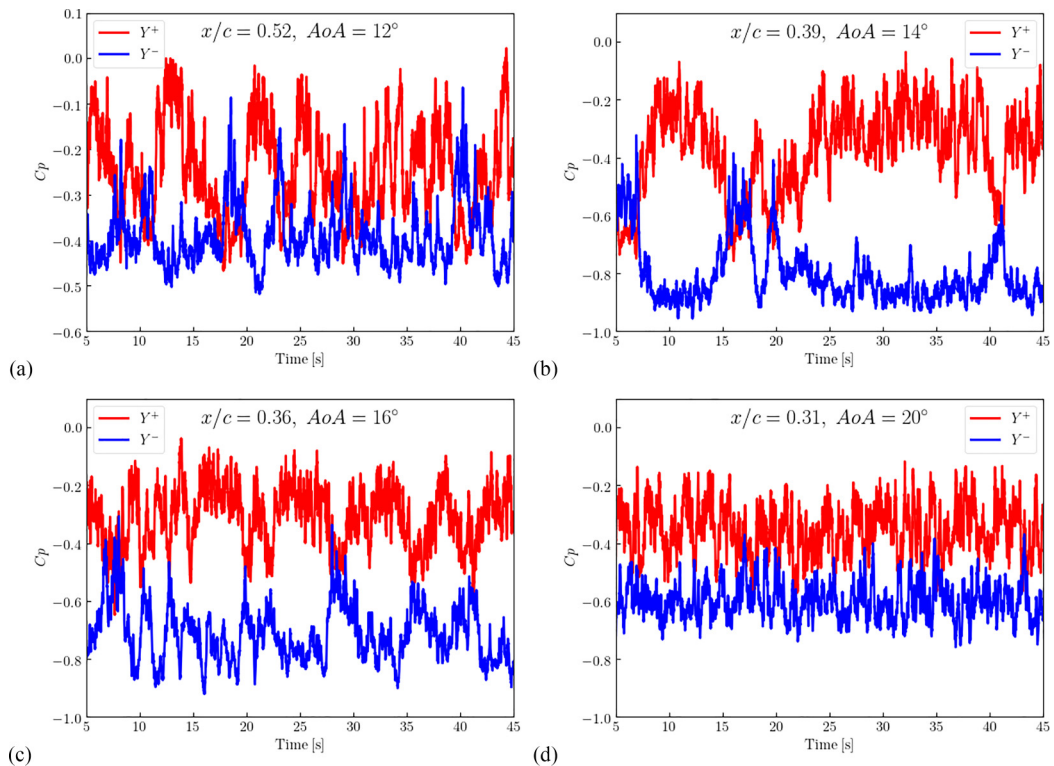


FIG. 13. Spatial pressure switch between Y^+ in red to Y^- in blue for different chordwise locations corresponding to the intermittent separation point of the considered angle of attack.

B. Switches

In this section, pressure signals at both locations Y^+ and Y^- are examined. A switch (see Fig. 13) is defined as a moment where a large pressure jump is observed on one side, Y^+ (or Y^-), while coinciding with a pressure jump of the opposite sign at the other spanwise location, Y^- (or Y^+). The switches between Y^+ and Y^- can be seen in the pressure signals measured at the intermittent separation point locations, which are shown in Fig. 13 for angles of attack ranging from 12° to 20° . The switches are clearly apparent for the angles of attack 12° [Fig. 13(a)] and 14° [Fig. 13(b)] and are correlated with sharp jumps from an attached to partially detached flow shown in Fig. 12. The switches are not as well identified at 20° [Fig. 13(d)], which is consistent with the less clear jumps and the appearance of intermediate states described in the previous section.

Figure 14 shows the temporal spectrum of the pressure signal at the intermittent separation point for different angles of attack after the onset of separation. No single timescale could be directly identified in the pressure signal to characterize the jumps and switches of the bistability phenomenon. We can see that it is consistent with the scenario of a gradual process involving a wide spectrum of timescales: At high frequencies, one observes an evolution from a f^{-2} behavior at 12° to a f^{-3} region between 16° and 20° . A sharper drop-off is observed at 24° . We note that Kiya *et al.* [58] found a scaling between -2 and -3 in the recovery region of the separated flow over a blunt flat plate, while a -3 spectrum for high frequencies was identified in several turbulent adverse pressure gradient flat-plate boundary layers [59] (see also Simpson *et al.* [57] for a review).

Despite the absence of a well-identified cyclic process, a characteristic timescale can still be extracted from the average time interval between such jumps. To do so, we considered the signals at the intermittent separation point on each chord and determined the times when one became higher

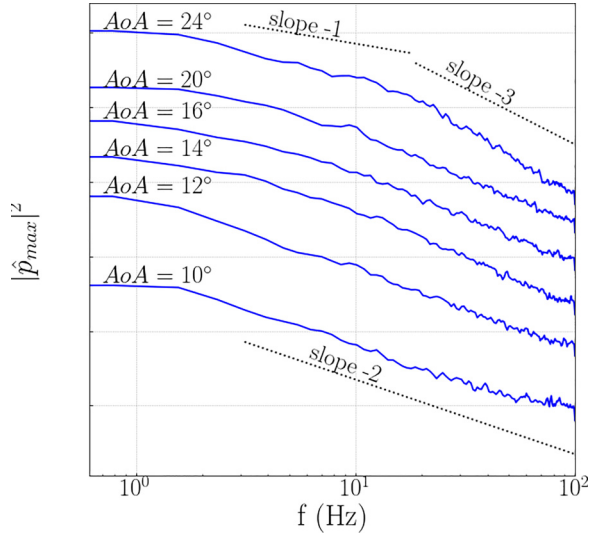


FIG. 14. Spectra of the pressure signal at the intermittent separation point for different angles of attack (the spectra have been rescaled for easier comparison).

than the other (similar results were obtained when the normal force on the chord was used instead of the local pressure signal). We defined the characteristic timescale T to be the average duration between these events. Events lasting less than a time threshold s were excluded, to exclude possible transients. Three different thresholds are represented in Fig. 15: $s = 0$ (all events were included), $s = 0.5$ s, and $s = 1$ s. No significant changes were observed for the last two cases, which provides some confidence in the robustness in the results. Sample time intervals are also shown in Fig. 15 as open symbols for a threshold of $s = 4$, and it can be seen that the variations of the distribution with the angle of attack are well captured by the characteristic timescale. In all cases where bistability is present, the timescale seems to evolve roughly like the variance of the pressure fluctuations. This means that large pressure variations corresponding to the difference between attached and

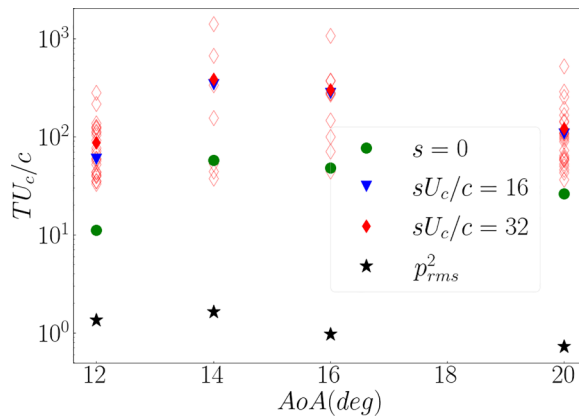


FIG. 15. Evolution of the bistability timescale with the angle of attack for different values of the time threshold s . The open symbols correspond to the different intervals measured for $sU_c/c = 32$. The variance of the pressure fluctuations p_{rms}^2 is also represented on the plot for comparison as star markers.

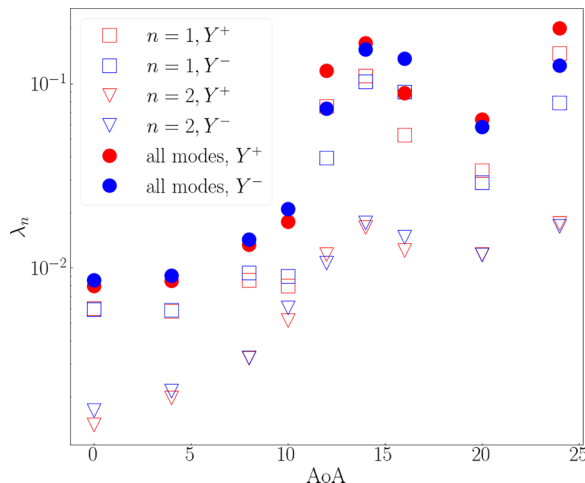


FIG. 16. Evolution with the angle of attack of the first two POD eigenvalues λ_1 (squares) and λ_2 (triangles), referring to the energy of the two first modes and of the total variance (solid circles), for each row of pressure Y^+ (in red) and Y^- (in blue).

separated flow states are less frequently observed than small pressure variations corresponding to the existence of intermediate states.

V. POD ANALYSIS

To complement the local description of the previous section, we provide a low-order characterization of the global dynamics based on POD. For each angle of attack, the decomposition was applied independently to each chordwise row of pressure taps, limited to the suction side. Only the fluctuating part of the signal was considered.

A. Eigenvalues and eigenmodes

Figure 16 shows the first two eigenvalues λ_1 (squares) and λ_2 (triangles) for both spanwise locations (Y^+ in red and Y^- in blue) as function of the angle of attack. The first two eigenvalues represent the two most energetic contributions to the total variance (full circles) (i.e., energy of the fluctuations). The total variance globally increases with the increasing angle of attack but with a drop at 20° . Before the flow separation, the two modes capture respectively 70% and 20% of the variance. After the start of the flow separation at an angle of attack of 12° , over 70% of the total variance is still captured by the first two modes, which suggests that the pressure dynamics could be successfully captured with a low-order representation. Generally speaking, eigenvalues tend to increase following the trend of the total variance, with one exception: Just before the start of the flow separation, at 10° , although the total variance increases sharply, the energy of the first mode actually decreases and becomes close to that of the second mode, which points out to a strong reorganization of the fluctuations. After flow separation, the energy of the first mode increases sharply again and a dissymmetry between the two chords, i.e., Y^+ and Y^- , is observed. The first mode at Y^+ appears to have more energy at 12° , while Y^- has more energy at 16° , which is consistent with what is observed in Fig. 5. Symmetry appears to be restored at 14° , when the fluctuation level is maximum, as well as at 20° . At 24° , the symmetry is broken again. This evolution confirms that strong, three-dimensional reorganizations of the flow take place as the angle of attack varies.

Figure 17 represents the modes Φ_n scaled with their average contribution $\lambda_n^{1/2}$. At low angles of attack ($\leq 8^\circ$), the shape of the modes remains similar with a small peak in the leading-edge

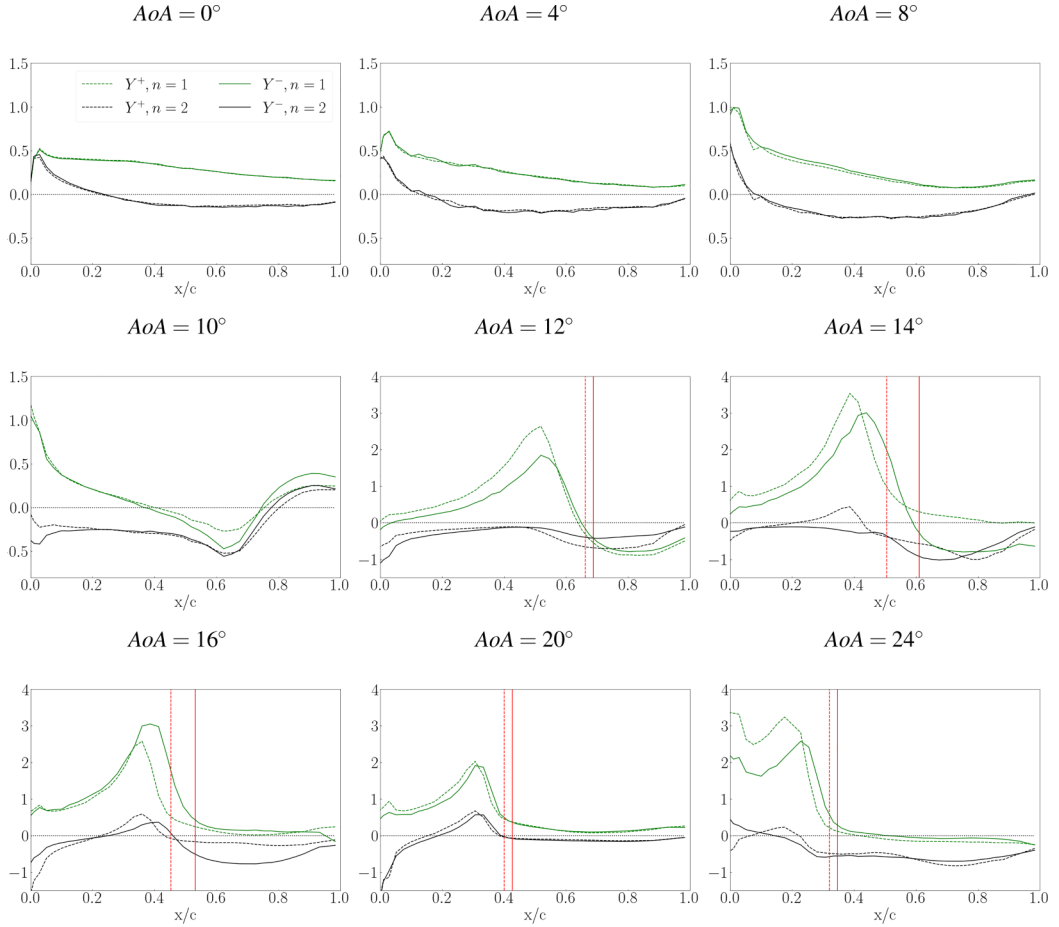


FIG. 17. First two POD modes of the pressure coefficient $\Phi_n \lambda_n^{1/2}$ on the suction side for Y^- (solid lines) and Y^+ (dashed lines). The red solid and dashed lines respectively correspond to the steady separation point at Y^+ and Y^- .

region and then a slow decrease along the chord. No significant differences are observed between the two spanwise locations, Y^+ and Y^- , which confirms that the flow is statistically 2D for low angles of attack. Just before flow separation at 10° , the first two modes look very similar over the aft region of the suction side. Both modes are characterized by a local maximum corresponding to the maximum variance location (the intermittent separation point). At 12° , the shapes of the modes change drastically and will remain more or less similar at higher angles. We can see that the sharp changes in POD energy levels displayed in Fig. 16 at 12° correspond to changes in the spatial structures of the modes. The vertical lines in the figure correspond to the steady separation criterion, applied to the time-averaged pressure coefficient, as defined in Sec. II D. One can see that the steady separation point constitute the downstream limit of the region of strong fluctuations similarly as observed in Sec. III B from the pressure gradient and fluctuation distribution. It follows closely the location of the dominant mode maximum which is by definition that of the intermittent separation point. We note that the separation region at Y_+ is located slightly farther upstream than that at Y_- , with largest discrepancies at 14° and 16° . This indicates again the loss of 2D statistical representation of the flow separation region. The shape of the modes remains essentially similar up to 24° , when the region of strong adverse pressure gradient merges with the leading edge.

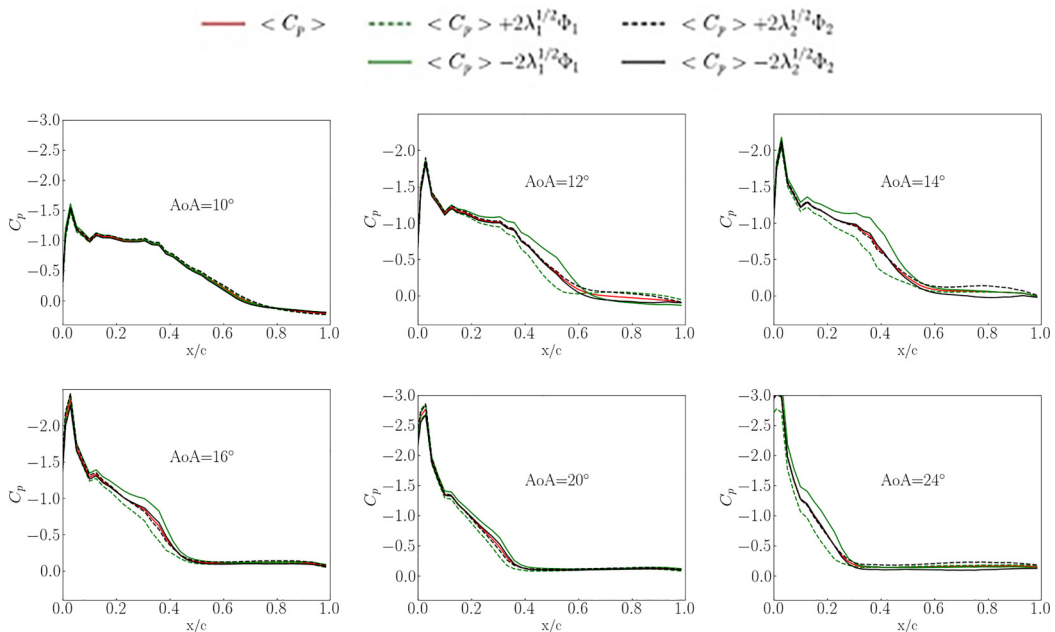


FIG. 18. POD-based reconstructions of the pressure coefficient on the suction side for different angles of attack using the two first modes (the modes represented are those determined at Y_+ ; the same trends were observed for those obtained at Y_-).

To determine the contribution of each mode to the spatial distribution of the pressure coefficient, we represented in Fig. 18 a POD-based reconstruction of the pressure coefficient using the first two modes and selected values of the mode amplitudes. We can see that when the amplitude of mode 1 is negative (respectively positive), the reconstructed pressure coefficient curve has a shorter plateau (respectively longer plateau) at zero in the trailing-edge region, and a more intense (respectively less intense) adverse pressure gradient region, thus corresponding to a separation closer to the trailing edge (respectively closer to the leading edge). As expected, no significant contribution from the modes is observed for low angles of attack smaller than (and including) 10° . At the angle of attack 12° , the reconstruction based on the dominant mode Φ_1 shows a modification of both the trailing-edge region (fluctuation of the local maximum) and the recovery region (displacement of the separation point). In contrast, the second mode only contributes to the fluctuations in the separated region close to the trailing edge, with a contribution level that is equivalent to that of mode 1. Since the fluctuations in the recovery region are mostly due to mode 1, and those at the trailing edge are about equally due to mode 1 and mode 2 (which are by construction uncorrelated), this means that the recovery region and the trailing-edge region are partially correlated. In contrast, Fig. 18 shows that at 14° , the fluctuations in the region of adverse pressure gradient, in the intermittent separation region, are completely decorrelated from those in the separated region over the trailing edge, as the fluctuations in the region of adverse pressure gradient is exclusively carried by mode 1 and the separated region by mode 2. Figure 18 shows at 16° that the intensity of the fluctuations over the trailing edge subsides, which is consistent with the displacement of the separated shear layer away from the airfoil. For the angle of attack of 20° , mode 1 creates less intense, but still significant, fluctuations in the adverse pressure gradient region, but both mode 1 and mode 2 are also associated with fluctuations at the leading edge at 20° . For the highest angle of attack 24° , mode 1 is again dominant over a region that extends from the leading edge to the separation point. Overall, these observations support the idea that the onset of flow separation is an inherently three-dimensional, continuously evolving process.

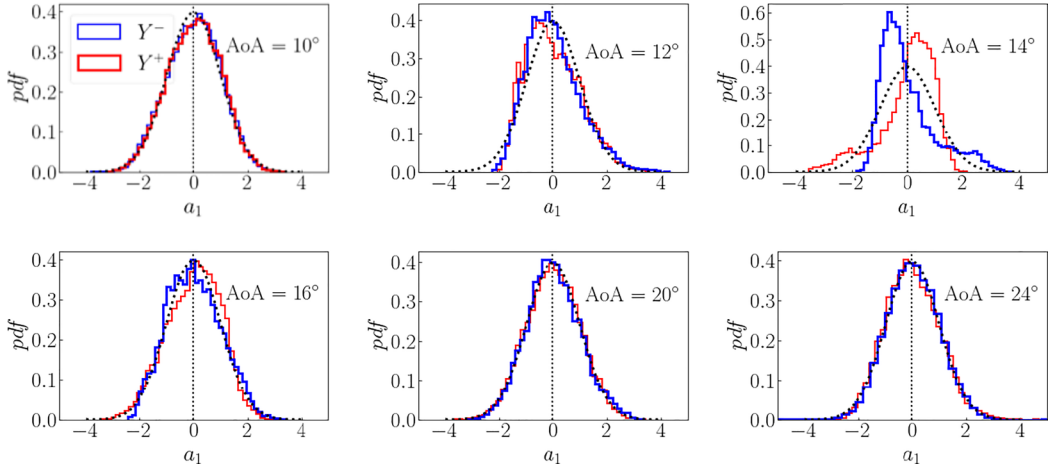


FIG. 19. Histogram of the first two POD amplitudes; the black dotted line indicates a reference Gaussian distribution.

To summarize, the pressure fluctuations on each chord are mostly captured by the first two POD modes. At angles larger than 10° , the first mode represents the variations of the pressure gradient and is dominant in the intermittent separation region. For low angles of attack (10° and 12°), both mode 1 and mode 2 contribute to the flow separation near the trailing edge, but at larger angles ($\text{AoA} \geq 14^\circ$), as the separation point moves towards the leading edge, mode 1 becomes decorrelated from the separated flow at the trailing edge.

B. POD characterization of the bistability

We now focus on the temporal amplitude of the dominant mode $a_1(t)$ for both chords. This amplitude is almost entirely correlated with the pressure signal at the ISP (with a correlation coefficient larger than 0.95). A distribution of the different values taken by the normalized amplitude $a_1(t)$ in time can be represented as a histogram (Fig. 19), which provides a description of the dominant mode dynamics. In particular, the mode (most frequent value) of the histogram a_{1c} corresponds to the most likely configuration of the flow, which may be different from zero (its time-averaged value) if the distribution is asymmetric. The following observations did not change when half the time period was used, as well as when we considered longer datasets obtained at 14° and 16° . At the angle of attack of 10° (and for lower angles as well, not shown), the distribution of the dominant POD amplitude is nearly symmetric and close to a Gaussian. Deviations from Gaussianity are observed at 12° . The distributions have the same asymmetry, with more frequent negative values, which means that the time-averaged separation point is on average located downstream of its most frequent position. This is illustrated in Fig. 20, which represents for each chord the mean pressure coefficient $\langle C_p \rangle$ and the reconstructed pressure based on the dominant fluctuation $\langle C_p \rangle + 2a_{1c}\phi_1$, where a_{1c} is the most likely value of the amplitude and the rescaling of 2 was chosen to make visualization easier. This means that the separation region makes large, infrequent excursions upstream on both chords.

At an angle of attack of 14° , corresponding to the maximum level of fluctuations, Fig. 19 shows that the deviation from Gaussianity is maximal. The remarkable observation here is that the distributions at Y^+ and Y^- are now antisymmetric, with a high negative (respectively positive) tail for Y^- (respectively Y^+). This means that the separation region at Y^- makes large, infrequent excursions towards the leading edge (like both chords at 12°), while the large, infrequent excursions at Y^+ are now directed towards the trailing edge. As can be seen in Fig. 20, this results in a persistent dissymmetry between the two chords, so that the separation point at Y^+ is located closer to the trailing edge with a more intense pressure gradient than that at Y^- . Figure 19 shows that the

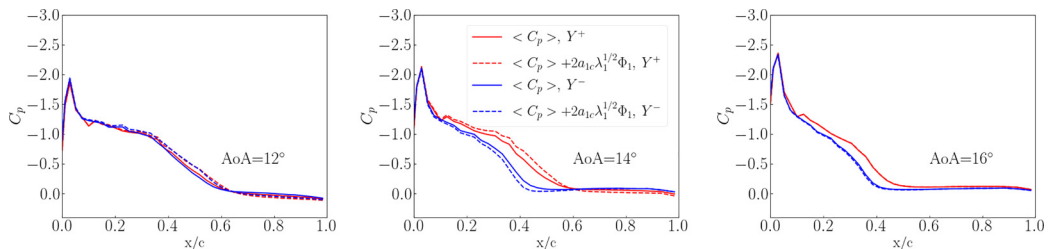


FIG. 20. POD-based reconstructions of the pressure coefficient on the suction side for different angles of attack using the dominant mode and the most frequent value of the amplitude (a rescaling factor of 2 has been applied to the fluctuation for easier visualization).

antisymmetry of the distributions is much weakened at 16° , while the time-averaged dissymmetry (see Fig. 20) is still significant. For angles of attack larger than 20° , the distribution of the amplitude of the two dominant POD modes appears to be Gaussian again.

We have established that the amplitude of the dominant POD mode captures the dynamics of the most important flow phenomenon for each angle of attack, namely the evolution of the separation point and the flow separation for higher angles of attack. A characterization of bistability can further be provided by the correlation of the dominant POD amplitudes.

Let a_n^+ ($-$) be the amplitude of mode n at the spanwise locations Y^+ (Y^-). Table II represents the correlation coefficient between the amplitudes of the first two POD modes $C(a_n^-, a_n^+)$ for different angles of attack. For the lowest angles ($\text{AoA} \leq 8^\circ$), a strong positive correlation is observed for the first two modes, indicating strong spatial coherence all over the suction side. At 10° , when the flow starts to detach, evidence of correlation disappears. At 12° , when the flow separation starts to move upstream, the amplitudes of the dominant mode become negatively correlated. The negative correlation is maximal (-0.7) for the angles of attack 14° and 16° and then disappears at 20° . At 24° , a positive correlation is observed with the dominant mode, which is now strongest over the leading edge. The correlation coefficient therefore varies (in absolute value) like the normal force standard deviation shown in Fig. 2. This means that in the bistability regime, $C(a_n^-, a_n^+)$ constitutes a good indicator of the local switch phenomenon described above. It also shows that local switches represent an essential part of the pressure dynamics over the complete airfoil section. Bistability therefore appears as a characteristic of early separation before complete flow separation over the airfoil.

Global timescales can be extracted from the autocorrelation and the cross-correlation of the POD amplitudes, shown in Fig. 21, which can be respectively connected with the local jumps and switches described above. Examination of the autocorrelation of a_1 [Fig. 21(a)] confirms that bistability is not a cyclical process as the cross-correlation falls to zero. The time delay at the first zero crossing T_0 gives a measure of the time during which the signal remains correlated with itself. It can be seen that this timescale is both on the order of and follows the variations of the local switch timescale T with the angle of attack. T_0 is on the order of 15 convective timescales for 10° and then increases significantly to about 40 for 12° and to a maximum of 150 at 14° . For higher angles, T_0 decreases to about 45 for 16° and to 15 for $\text{AoA} \geq 20^\circ$. A similar timescale is present in the cross-correlation of

TABLE II. Correlation coefficients between the amplitudes of the first two POD modes at the two spanwise locations Y^+ and Y^- . Coefficients larger than 0.3 in absolute value are indicated in bold.

| Angle of attack | 0 | 4 | 8 | 10 | 12 | 14 | 16 | 20 | 24 |
|-----------------|-------------|-------------|-------------|-------|--------------|--------------|--------------|--------|-------------|
| Mode 1 | 0.81 | 0.52 | 0.40 | 0.018 | -0.57 | -0.71 | -0.62 | -0.086 | 0.57 |
| Mode 2 | 0.15 | 0.38 | 0.47 | 0.27 | -0.28 | 0.056 | 0.10 | 0.15 | 0.30 |

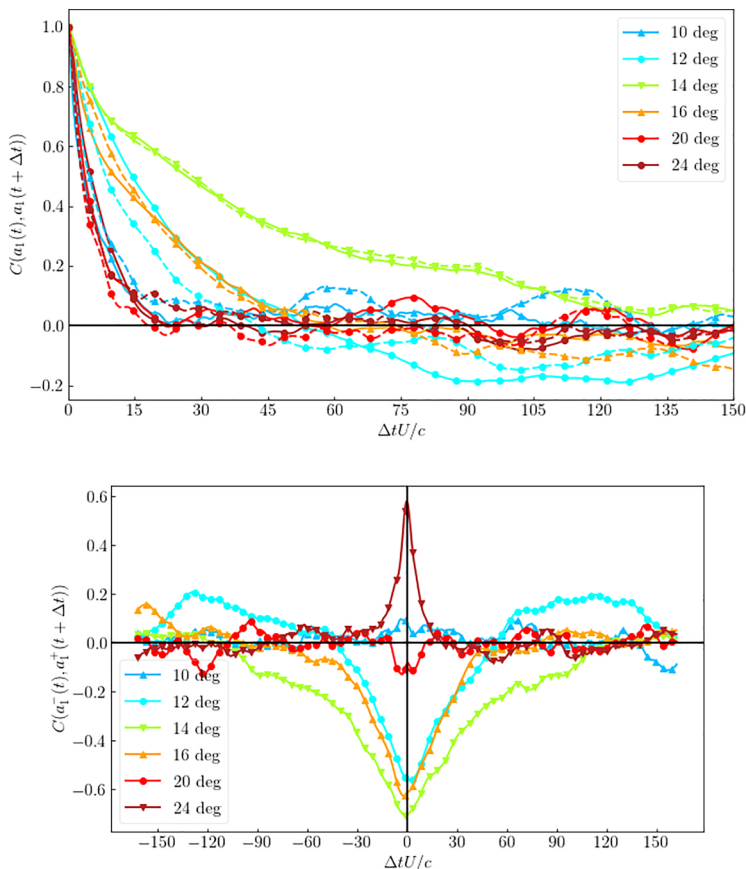


FIG. 21. Autocorrelation of the dominant (normalized) POD amplitude for different angles of attack. Cross-correlation of the dominant POD amplitude for different angles of attack.

the dominant POD amplitude in the $[12^\circ, 20^\circ]$ regime, which is represented in Fig. 21(b). We note that the modulus of the cross-correlation is close to its maximum value at zero time delay, which suggests that switches are essentially synchronized.

VI. CONCLUSIONS

We have investigated the behavior of wall pressure measurements over a moderately thick (20% of the chord) and cambered (4% of the chord) airfoil at a high chord-based Reynolds number, $Re_c = 3.6 \times 10^6$, and over a range of angles of attack including the maximum force. The airfoil was equipped with synchronized unsteady wall pressure sensors distributed along the chord at two spanwise locations, symmetrically from the midspan of the blade. At angles of attack where the normal force reaches its maximum, the load fluctuations are also the largest, which can cause additional fatigue and damage on wind turbines. Evidence of asymmetry between the chords was found in the time-averaged statistics in a range of angles of attack $[12^\circ, 20^\circ]$. In this asymmetric regime, the largest fluctuations were concentrated in the region of strong adverse pressure gradient. The location of the maximum of the fluctuations moved towards the leading edge with the increase of the angle of attack and was highly correlated with the location of the pressure distribution inflection point. The location of the maximum of the fluctuations therefore appeared as a relevant indicator of the intermittent separation region. We therefore called it the ISP.

This regime was also characterized by a bistability phenomenon: The wall pressure signals at the maximum of pressure fluctuation displayed a jumplike character between two characteristic levels, which were shown to correspond to intermittent flow separation and reattachment. In addition, the jumps on each chord were highly anticorrelated, with an anticorrelation maximum between the two fluctuation peak locations. The physical description of the bistability phenomenon can be given as follows: When the intermittent separation region on the chord Y^+ (respectively Y^-) moves downstream, thereby increasing the area of attached flow on that side, the intermittent separation region on the other chord Y^- (respectively Y^+) moves upstream, which yields a larger separated flow area. A characteristic timescale based on the switches measured at the ISP was proposed to characterize the bistability phenomenon. The average time between switches was found to evolve with the variance of the pressure fluctuations.

POD analysis provides additional insight into this description, as a large part of the fluctuation energy (over 70%) could be reconstructed with only two spatial modes. The amplitude of the dominant mode displays a very high correlation (larger than 0.9) with the intermittent separation point, which confirms the relevance of this location. Independent two-mode reconstructions of the instantaneous signal at the two spanwise locations are able to capture the highly intermittent flow separation and reattachment phenomena linked with pressure jumps at the intermittent separation point. The reconstructions also showed that as the angle of attack increases, the region of maximum fluctuations associated with the strong adverse pressure gradient became progressively decorrelated from the trailing edge and moves towards the leading edge, eventually merging with it. The evolution of the flow as it transitioned into bistability could be described by a single indicator based on the correlation coefficient between the dominant POD mode amplitudes on each chord. Overall, our results indicate that flow separation at high Reynolds numbers is an inherently local, three-dimensional, and unsteady process that occurs in a continuous manner and leads to high load fluctuations when the maximum of aerodynamic force is generated. However, as the characteristics of the flow separation can be represented with mainly two POD modes, our results also suggest that a low-order approach may offer a viable route to modeling and ultimately predicting and controlling this complex bistability phenomenon.

Data of the present paper are freely open for download on the AERIS platform [60].

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