Structural model for fluctuations in financial markets

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In this paper we provide a comprehensive analysis of a structural model for the dynamics of prices of assets traded in a market which takes the form of an interacting generalization of the geometric Brownian motion model. It is formally equivalent to a model describing the stochastic dynamics of a system of analog neurons, which is expected to exhibit glassy properties and thus many metastable states in a large portion of its parameter space. We perform a generating functional analysis, introducing a slow driving of the dynamics to mimic the effect of slowly varying macroeconomic conditions. Distributions of asset returns over various time separations are evaluated analytically and are found to be fat-tailed in a manner broadly in line with empirical observations. Our model also allows us to identify collective, interaction-mediated properties of pricing distributions and it predicts pricing distributions which are significantly broader than their noninteracting counterparts, if interactions between prices in the model contain a ferromagnetic bias. Using simulations, we are able to substantiate one of the main hypotheses underlying the original modeling, viz., that the phenomenon of volatility clustering can be rationalized in terms of an interplay between the dynamics within metastable states and the dynamics of occasional transitions between them.

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I. INTRODUCTION

Predicting and measuring the risk that the value of an investment portfolio will depreciate is a mainstay of financial mathematics. Integral to the success of these endeavors is identifying the various market risk (MR) factors and developing models for their evolution. These MRs include, among others, fluctuations in stock indices, changes in interest rates, foreign exchange parities, or commodity (e.g., gold, oil) prices.

In recognition of the importance of MRs, the Basel Committee for Banking Supervision (BCBS) stipulates that banks must explicitly reserve a portion of equity capital against MR. The Basel III accord [1] defines MR as the "the risk of losses arising from movements in market prices." It proposes two approaches to measure MRs, a so-called standardized approach and an internal models approach.

Within the standardized approach the market risk of a set of trading positions is defined by their exposure to a standardized set of risk factors and measured in terms of sensitivities of the market values of these positions to movements of the risk factors. To determine the capital to be held against MRs, the risks of various positions held by a bank are aggregated, using prescribed risk weights and prescribed correlations between risk factors.

Under the internal models approach, banks are permitted to design their own measurement model, which must adhere to strict guidelines. Guidelines cover a host of qualitative and quantitative standards. At a minimum, internal models must encompass the positions covered by the standard model, be regularly back-tested against historical market data to demonstrate their adequacy and accuracy, and be supplemented by a regular and rigorous regime of stress testing.

The collapse of the US based hedge fund Long-Term Capital Management (LTCM) in 1998, following the East Asian finan-

cial crisis of mid 1997 [2], is a poignant example of adverse MRs spreading across wide geographic regions. The crisis was instigated by a devaluation of Thailand's currency, the Thai baht. This move sent shock waves through the economies of East Asian countries, thereby triggering recessions. The economic downturns led to a sharp decline in the demand and price of oil. Russia, as a major oil producing country, was adversely hit and defaulted on its public debt. The culmination of all these interlinked shocks resulted in huge losses for LTCM and, in early 2000, its liquidation. It can fairly be argued that chains of events such as this call for a *more interconnected* approach to market risks than stipulated by the BCBS, even today.

The credit crunch of 2007–2009 provides further evidence to support the idea of interactions between risky market positions. While financial derivatives and globalization, which allow for greater portfolio diversification, may have helped mitigate MRs, adverse feedback loops between financial markets and the real economy may be responsible for propagating asset price shocks across borders and even commodity classes. A more thorough understanding of the dynamics of asset prices would thus be welcome.

A model of MRs should reproduce a set of stylized facts found from empirical analysis of time-series data of returns on investment [3–7], i.e., (i) return distributions are "fat-tailed," (ii) the variance of returns is time-dependent, and (iii) there are long-range correlations between variance of returns in time, a phenomenon referred to as "volatility clustering."

Over the years a variety of *descriptive* models have been developed for the returns in financial time series. These models do not attempt to advance theories of the mechanisms underlying price processes, but concentrate on capturing their statistics. Examples include autoregressive conditional heteroscedastic (ARCH) models and their various generalizations [8–11], and

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stochastic volatility models [12,13]. Other models assume that the statistics for return increments follow symmetric [3,14] or asymmetric [15] stable Paretian distributions. Most of these investigations are concerned with properties of univariate time series. Yet many issues in asset pricing and portfolio construction can only be meaningfully analyzed in a multivariate context, and multivariate generalizations of such ARCH-type models have indeed been proposed [16–18]. As an aside, we note that empirical properties of correlations between financial time series have also found considerable interest in the random matrix community; see, e.g., [19–21].

In an alternative *structural* model approach one attempts to model the *mechanisms* behind market dynamics. One possible formulation in this regard is to consider the collective results of actions performed by agents operating in the market. Models of this type include the Santa Fe Institute's artificial market model [22], the minority game [23–27], percolation models [28–30], Ising type models of interacting agents [31–33], or models in which a static equilibrium is destabilized by market imperfections (e.g., [34]), to name but a few. For a broader overview, we refer to the recent review of Sornette [35].

In [36] the authors take an intermediate approach and propose an interacting variant of the geometric Brownian motion model (henceforth referred to as the iGBM) as a structural model of asset price dynamics. They suggest that the structure of such a model should follow from very general considerations concerning market mechanisms, arguing in particular that the dynamical evolution of a market, when reduced (from a hypothetically complete description) to a description in terms of asset price dynamics, using, e.g., Mori-Zwanzig projection techniques [37], quite generally must exhibit "...interaction[s] between prices, which may be thought of as arising effectively through the collection of agents, each acting on the basis of his or her own, more or less rational perception of the underlying economy and market mechanisms" [36]. The Bouchaud-Cont model of market fluctuations and crashes [38] goes even farther by attempting to describe the macroscopic effects of interactions between agents in terms of an effective nonlinear Langevin equation for the evolution of a single global order parameter.

The iGBM proposed in [36] can be thought of as one of simplest interacting generalizations of the geometric Brownian motion model that can be constructed following the above line of reasoning. No assumptions on structural properties of markets are invested. The only assumptions used are (i) that there are effective (nonlinear) interactions between prices, and (ii) that there are mean-reverting forces, however weak, which ensure stability of the market in the long-time limit. The status of the second assumption is debated in economic circles. We will discuss it, along with a possible resolution within our model, in the concluding section. It is worth adding that the version of the iGBM actually analyzed in [36] adopts a sim*plification* in the sense that it assumes a Markovian interaction between asset prices, whereas according to the general line of reasoning outlined in that paper, one would generally have to expect the dynamics of a reduced model to be non-Markovian. The model analyzed in [36] must therefore be regarded as a Markovian approximation of a more comprehensive reduced description. In the present paper we will continue to use this Markovian approximation.

Using simulations, the authors demonstrate that such a simplified model is capable of reproducing the main stylized facts for asset returns [36]. Moreover, analytic investigations revealed that, in a significant portion of the space of model parameters, the system is "glassy" and is therefore expected to exhibit a large number of metastable states. The authors argue that it is above all the interplay between dynamics *within* metastable states and *occasional transitions between them*—whether spontaneous or induced by external stimuli—which accounts for a considerable *dynamically generated* heterogeneity of volatilities across assets as well as for the phenomenon of volatility clustering in time.

The purpose of the present paper is to provide a more thorough analysis of the iGBM proposed in [36]. Specifically, we perform a generating functional analysis of the model in the limit of large system size, keeping the Markovian approximation of the dynamics used by these authors. We introduce a slow driving of the dynamics to mimic the effect of slowly varying macroeconomic conditions, and investigate statistical properties of asset returns by recourse to a separation of timescales argument, assuming that the system equilibrates at given values of the slow variable describing macroeconomic conditions. This analysis allows one to compute distributions of asset returns on various timescales, and it also exposes interesting collective effects on the pricing of assets, which are driven by a combination of the macroeconomic driving and the effects of imitation as encoded in the couplings.

The remainder of this paper is organized as follows. In Sec. II we introduce the model. Section III provides a solution based on a generating functional analysis (GFA), with technical details of that analysis relegated to an appendix. Phase diagrams are provided in Sec. IV along with results of return distributions predicted by the model at various timescales. By looking at a variant of the model which has metastable states of a *known structure* embedded in its couplings, we are in a position to elucidate in some detail the relation between metastable states with a dynamics switching between them at longer timescales on one hand, and volatility clustering on the other hand. Finally, in Sec. V we provide a summary and a concluding discussion.

II. MODEL DEFINITIONS

In this section we describe the model for asset price dynamics as introduced in [36]. One considers a system consisting of N assets, labeled i = 1, ..., N. To each asset i, one associates a time-dependent price $S_i(t) > 0$. The geometric Brownian motion model postulates that the relative change of the price performs a random walk captured by the Langevin equation

$$\frac{1}{S_i(t)}\frac{d}{dt}S_i(t) = \mu_i + \sigma_i\xi_i(t),\tag{1}$$

where $\xi_i(t) \in \mathbb{R}$ denotes a Gaussian white noise with zero mean and unit variance. The factor $\sigma_i \ge 0$ measures the strength of the Gaussian fluctuations, and $\mu_i \ge 0$ characterizes the growth rate. Defining a normalized log-price $u_i(t) = \ln[S_i(t)/S_{i0}]$, in which S_{i_0} is a reference price (needed to nondimensionalize the argument of the logarithm) we obtain a new stochastic differential equation

$$\frac{d}{dt}u_i(t) = I_i + \sigma_i \xi_i(t), \qquad (2)$$

where $I_i = \mu_i - \sigma_i^2/2$ by an application of Ito's lemma. The iGBM model, at the level of the log-prices $u_i(t)$, is now constructed by introducing three extra terms into Eq. (2), to give us

$$\frac{d}{dt}u_i(t) = -\kappa_i u_i(t) + \sum_{j=1}^N J_{ij}g(u_j(t)) + \sigma_0 u_0(t)$$
$$+I_i + \sigma_i \xi_i(t). \tag{3}$$

The first additional term describes what might be thought of as an effect of fundamentalist traders in the market, creating a mean reversion effect with reversion coefficients $\kappa_i > 0$. The natural interpretation of the normalizing factors S_{i0} introduced above would in that case be that of "rational prices" of traded assets. The second additional term in Eq. (3) describes the interactions between log-prices of mutually dependent assets. We choose the interaction to be most sensitive in the vicinity of the rational prices, by taking g(u) to be a nonlinear, sigmoid function, describing the feedback mechanism. Possible choices for this function include the error function or hyperbolic tangent. The strength of this influence is given by $J_{ij} \in \mathbb{R}$. The sign of J_{ij} depends on the nature of mutual interactions. If, for example, assets *i* and *j* refer to firms with mutually beneficial economic relations, one would have $J_{ij} > 0$. Conversely if they refer to two competing firms, a negative shock on asset j, i.e., $g(u_i) < 0$, may positively affect asset *i*, implying $J_{ii} < 0$. Finally, the u_0 term is introduced to act as a global risk component mimicking slowly evolving economic conditions affecting prices of all traded assets. In the present paper we will model the u_0 term as a (slow) Ornstein-Uhlenbeck process,

$$\dot{u}_0(t) = -\gamma u_0(t) + \sqrt{2\gamma}\xi_0(t),$$
 (4)

where we take $\gamma \ll 1$ such that the above process becomes considerably slower than the microscopic asset dynamics described in Eq. (3).

For symmetrically coupled networks, the combined effect of mean reversion and the sigmoid nature of the feedback function is known to render such systems stable at long times [39].

As noted in [36], the model is formally equivalent to a model describing the stochastic evolution of a system of graded response neurons [39], with $u_i(t)$ playing the role of a postsynaptic potentials, and with g(u) describing the neuronal input-output relation, κ_i representing transmembrane conductances, and J_{ij} the synaptic efficacies. The I_i finally represent external (sensory) inputs, and the u_0 term—not typically included in the original neural modeling [39]—could describe the effects of neuromodulators.

Much is known about systems of this type [36,39–46]. For the purpose of the present paper, the most important feature is that iGBM type models as described by Eqs. (3) and (4) are—in a large part of their parameter space—expected to exhibit glassy phases [36,41,44,46] characterized by the existence of a very large number of long-lived metastable states [42,43]. The hypothesis investigated in [36] was that it would be the interplay between *dynamics within metastable states* and the dynamics of (occasional) *transitions between them*, which could be held responsible for the intermittent dynamics of financial markets.

For the purposes of the present analytic study we will keep a synthetic stochastic setting by taking J_{ii} to be of the form

$$J_{ij} = c_{ij} \tilde{J}_{ij}, \tag{5}$$

where $c_{ij} \in \{0,1\}$ are connectivity coefficients describing whether or not an interaction between the prices of assets *i* and *j* exists, and $\tilde{J}_{ij} \in \mathbb{R}$ describe the strengths of the interactions. We assume that $C = (c_{ij})$ is the adjacency matrix of an Erdös-Rényi random graph of mean degree *c*, but will specialize to the regime of sparse yet large connectivity by taking the limits $N \to \infty$ and $c \to \infty$, with $c/N \to 0$.

 \tilde{J}_{ij} are taken to be quenched random quantities with mean and variance scaling with the mean connectivity *c* to ensure the existence of the large system; i.e., we put

$$\tilde{J}_{ij} = \frac{J_0}{c} + \frac{J}{\sqrt{c}} x_{ij},\tag{6}$$

in which x_{ij} are zero mean and unit variance random variables chosen to be independent in pairs with $\overline{x_{ij}x_{ji}} = \alpha$. The parameter $\alpha \in [-1,1]$ thus describes the degree of correlations between \tilde{J}_{ij} and \tilde{J}_{ji} , with fully symmetric interactions given by $\alpha = 1$. It turns out that the collective properties of such a dilute system in the large mean connectivity limit are actually indistinguishable from those of a fully connected system.

III. MODEL SOLUTION

In this section we investigate the dynamics and stationary states for the model introduced in Sec. II. An analysis of the collective properties of the system in the noiseless limit $\sigma_0 = \sigma_i = 0$ was presented in [36], and used to identify parameter ranges, viz., the regions of small κ_i and sufficiently large *J*, where the system would exhibit a large number of metastable states. We will demonstrate in Sec. IV D below that our microscopic model described by Eq. (3) does indeed produce intermittent dynamics in this parameter range.

An exact and formal treatment of the *dynamics* is possible using a generating functional analysis (GFA) [47–50], to which we now turn. For systems of the type considered here the analysis closely follows [49].

A. Generating functional analysis

In what follows we present a solution of the model based on the generating functional formalism, which provides tools for the evaluation of correlation and response functions in terms of a characteristic functional of path probabilities. Performing the average over bond disorder in the sum over dynamical trajectories, details of which are found in Appendix A, one obtains a family of continuous-time effective single-site processes, each parametrized by a specific combination of single-node parameters $\vartheta \equiv (I, \kappa, \sigma)$,

$$\dot{u}_{\vartheta}(t) = -\kappa u_{\vartheta}(t) + I + J_0 m(t) + \sigma_0 u_0(t) + \alpha J^2 \int_0^t ds G(t,s) n_{\vartheta}(s) + \phi(t),$$
(7)

where $n_{\vartheta}(s) = g(u_{\vartheta}(s))$. The noise $\phi(t)$ in Eq. (7) is colored Gaussian noise, with

$$\langle \phi(t) \rangle = 0, \tag{8}$$

$$\langle \phi(t)\phi(s)\rangle = \sigma^2 \delta(t-s) + J^2 q(t,s). \tag{9}$$

The order parameters m(t) and q(t,s) appearing in the equation of motion (7) and in the specification (8), (9) of the noise statistics must be determined self-consistently to satisfy

$$m(t) = \langle \langle n_{\vartheta}(t) \rangle \rangle_{\vartheta}, \qquad (10)$$

$$q(t,s) = \langle \langle n_{\vartheta}(t)n_{\vartheta}(s) \rangle \rangle_{\vartheta}, \qquad (11)$$

$$G(t,s) = \left\langle \frac{\delta \langle n_{\vartheta}(t) \rangle}{\delta \phi(s)} \right\rangle_{\vartheta}.$$
 (12)

Here, the inner average $\langle \ldots \rangle$ refers to an average over colored noise ϕ for a given member of the single-site ensemble. The outer average $\langle \ldots \rangle_{\vartheta}$ refers to an average over the ensemble as characterized by the ϑ distribution. Further details for this calculation are provided in the Appendix. It should also be noted that this formalism is exact in the $N \to \infty$ limit.

We highlight the following: (i) there is a dependence of the single-site dynamics on the overall "magnetization" m(t); (ii) for *any* degree of symmetry of the interactions, $\alpha \neq 0$, the effective single-node dynamics is non-Markovian, with memory given by the response function G(t,s); (iii) the noise appearing in the single-site dynamics is colored, with correlations determined by the average temporal correlation q(t,s) of single nodes as described by Eq. (9).

We have thus reduced our system of equations describing the dynamics of prices of N interacting assets to an ensemble of dynamical evolution equations self-consistently coupled via a set of order parameters, which becomes exact in the thermodynamic limit. As is usually the case with the GFA, the resulting effective equation of motion is highly nontrivial and usually relies on sensible assumptions to be analyzed further.

B. Separation of timescales: Quasistationary regime

For sufficiently small values of γ in Eq. (4) one expects a separation of dynamical timescales to occur, entailing that the fast $u_{\vartheta}(t)$ processes become statistically stationary on timescales on which the slow $u_0(t)$ process can be treated as nonvarying. In what follows we shall thus analyze the $u_{\vartheta}(t)$ dynamics under the assumption that it is stationary at a given value u_0 of the slow process.

To assist our analysis further, we approximate Eq. (7) by neglecting fluctuations in the memory term, rewriting it as

$$\dot{u}_{\vartheta}(t) = -\kappa u_{\vartheta}(t) + I + J_0 m(t) + \sigma_0 u_0(t) + \alpha J^2 \int_0^t ds G(t,s) \langle n_{\vartheta}(s) \rangle + \phi(t), \qquad (13)$$

in which averages over the effective single-process dynamics at given ϑ appear in the retarded interaction. We are thereby discarding one source of noise in the dynamics, and so are likely to overestimate values of macroscopic order parameters. The important qualitative aspects of the collective properties of the system are, however, expected to remain intact as we shall verify through simulations later on.

Assuming stationarity and time translational invariance for a given u_0 , we introduce the integrated response

$$\chi = \int_0^t ds G(t,s), \tag{14}$$

and assume it to remain finite. This allows us to rewrite the effective dynamics in the stationary regime as

$$\dot{u}_{\vartheta}(t) = -\kappa u_{\vartheta}(t) + I + J_0 m + \sigma_0 u_0 + \alpha J^2 \chi m_{\vartheta} + \phi(t),$$
(15)

where $m_{\vartheta}(s) = \langle n_{\vartheta}(s) \rangle$ can be regarded as independent of *s* for *s* sufficiently close to *t* for the response function to be non-negligible.

Anticipating that the correlation q(t,s) might develop a time-persistent value q,

$$q(t,s) \to q$$
, as $|t-s| \to \infty$, (16)

we decompose the colored noise ϕ into a static (frozen) and an independent time-varying component

$$\phi(t) = J\sqrt{q}z + \eta(t), \tag{17}$$

in which $z \sim \mathcal{N}(0, 1)$, and the statistics of the time-varying part of the noise is given by

$$\langle \eta(t) \rangle = 0, \quad \langle \eta(t)\eta(s) \rangle = \sigma^2 \delta(t-s) + J^2 \mathcal{C}(t,s),$$
(18)

with

$$C(t,s) = q(t,s) - q \to 0$$
, as $|t - s| \to \infty$. (19)

The effective single-process dynamics within the stationary regime can then be rewritten in a more suggestive form as

$$\dot{u}_{\vartheta}(t) = -\kappa (u_{\vartheta}(t) - \overline{u}_{\vartheta}) + \eta(t), \qquad (20)$$

in which we have introduced the (long-term) average

$$\overline{u}_{\vartheta} = \frac{1}{\kappa} [I + J_0 m + J \sqrt{q} z + \alpha J^2 \chi m_{\vartheta} + \sigma_0 u_0].$$
(21)

We note that $m_{\vartheta} = \langle g(u_{\vartheta}(t)) \rangle$, where the average is over the stationary u_{ϑ} distribution that has \overline{u}_{ϑ} as its long-term mean; thus Eq. (21) is a self-consistency equation for the value of this long-term mean. Note also that ϑ now includes *z*, i.e., $\vartheta = (I, \kappa, \sigma, z)$. The solution to Eq. (20) is now easily written down as

$$u_{\vartheta}(t) = \overline{u}_{\vartheta} + [u_{\vartheta}(0) - \overline{u}_{\vartheta}]e^{-\kappa t} + \int_{0}^{t} e^{-\kappa(t-s)}\eta(s)ds, \quad (22)$$

implying that $u_{\vartheta}(t)$ is a Gaussian process with expectation

$$\langle u_{\vartheta}(t) \rangle = \overline{u}_{\vartheta} + [u_{\vartheta}(0) - \overline{u}_{\vartheta}]e^{-\kappa t}.$$
 (23)

For the auto-covariance

$$\mathcal{C}_{u_{\vartheta}}(t,t') = \langle [u_{\vartheta}(t) - \langle u_{\vartheta}(t) \rangle] [u_{\vartheta}(t') - \langle u_{\vartheta}(t') \rangle] \rangle$$

of the $u_{\vartheta}(t)$ in the large time limit we get a stationary law depending only on time differences, $C_{u_{\vartheta}}(t,t') = C_{u_{\vartheta}}(t-t')$ with

$$C_{u_{\vartheta}}(t-t') = \frac{1}{2\kappa} [\sigma^2 e^{-\kappa |t-t'|} + J^2 \hat{C}(0)], \qquad (24)$$

in which $\hat{C}(0)$ is the zero-frequency limit of the Fourier transform $\hat{C}(\omega) = \int_{-\infty}^{\infty} ds e^{-i\omega s} C(s)$. It is useful to specifically record the equal time limit of $C_{u_{\vartheta}}$,

$$\mathcal{C}_{u_{\vartheta}}(0) = \frac{1}{2\kappa} [\sigma^2 + J^2 \hat{\mathcal{C}}(0)] \equiv \sigma_{u_{\vartheta}}^2.$$
(25)

C. Self-consistency equations for the quasistationary regime

With full knowledge of the statistics of the $u_{\vartheta}(t)$ we can reformulate the self-consistent equations for the order parameters describing the stationary regime. They are (i) the stationary magnetization *m*, (ii) the time persistent part *q* of the node autocorrelations, (iii) the integrated response χ , and (iv) the zero-frequency limit $\hat{C}(0)$ of the Fourier transform of the (non-time-persistent) part $C(\tau)$ of the node autocorrelations in the stationary regime. To compute the latter, we also have to evaluate the average node autocorrelations $q(\tau)$.

To formulate the self-consistency equation for $m = \langle m_{\vartheta} \rangle_{\vartheta}$, we recall that $m_{\vartheta} = \langle g(u_{\vartheta}(t)) \rangle$ where the average is over the stationary u_{ϑ} distribution, and hence can be rewritten as

$$m_{\vartheta} = \langle g(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} x) \rangle_x \tag{26}$$

with $\sigma_{u_{\vartheta}}$ defined in Eq. (25), and $\langle \ldots \rangle_x$ denoting an average over a $\mathcal{N}(0,1)$ Gaussian *x*. By definition, an average over the distribution of the set of parameters ϑ then gives $m = \langle m_{\vartheta} \rangle_{\vartheta}$. Following the same logic for the two-point function $q(\tau)$, we obtain the following full set of self-consistency equations for the order parameters:

$$m = \langle \langle g(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} x) \rangle_{x} \rangle_{\vartheta}, \qquad (27)$$

$$q(\tau) = \langle \langle g(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} x) g(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} y) \rangle_{xy} \rangle_{\vartheta}, \qquad (28)$$

$$\chi = \langle \langle g'(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} x) \rangle_{x} \rangle_{\vartheta}, \qquad (29)$$

$$\hat{\mathcal{C}}(0) = \int_{-\infty}^{+\infty} d\tau [q(\tau) - q].$$
(30)

In Eq. (28) the average $\langle ... \rangle_{xy}$ is over *correlated* normal random variables $x, y \sim \mathcal{N}(0, 1)$ with correlation coefficient given by

$$\rho_{u_{\vartheta}}(\tau) = \frac{\mathcal{C}_{u_{\vartheta}}(\tau)}{\mathcal{C}_{u_{\vartheta}}(0)} = \frac{\sigma^2 e^{-\kappa |\tau|} + J^2 \hat{\mathcal{C}}(0)}{\sigma^2 + J^2 \hat{\mathcal{C}}(0)}.$$
 (31)

The u_0 -dependent order parameters of our system are now given by the solution of Eqs. (27)–(31) supplemented by the self-consistency equation (21) defining the \overline{u}_{ϑ} . An analytical characterization of the fixed points is not readily available and we have to resort to numerical analysis.

D. Analysis of the self-consistency equations

In this section, we present our analysis of the fixed point equations describing the stationary dynamics of the system. In particular, we will be taking the error function

$$g(x) = \operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x dy e^{-y^2}$$
 (32)

as the sigmoid function that governs the nonlinear feedback in the dynamics. This choice of feedback function has the advantage that it simplifies some of the Gaussian averages needed in the evaluation of Eqs. (27)–(30). To fully exploit this feature, we further assume that $I \sim \mathcal{N}(I_0, \sigma_I^2)$, so that one can combine the two Gaussians *z* and *I* in Eq. (21) into one. Likewise, we keep σ constant across the ensemble of effective single-node problems. These choices allow for some simplifications in evaluating the averages appearing in the original fixed point equations. For example, evaluating m_ϑ gives

$$m_{\vartheta} = \langle \operatorname{erf}(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}} x) \rangle_{x} = \operatorname{erf}\left(\frac{\overline{u}_{\vartheta}}{\sqrt{1 + 2\sigma_{u_{\vartheta}}^{2}}}\right), \quad (33)$$

with now

$$\overline{u}_{\vartheta} = \frac{1}{\kappa} \Big[J_0 m + I_0 + \sqrt{\sigma_I^2 + J^2 q} z + \alpha J^2 \chi m_{\vartheta} + \sigma_0 u_0 \Big].$$
(34)

The same simplifications can be made for the other order parameters, allowing us to rewrite the set of fixed point equations as

$$m = \left\langle \operatorname{erf}\left(\frac{\overline{u}_{\vartheta}}{\sqrt{1 + 2\sigma_{u_{\vartheta}}^{2}}}\right)\right\rangle_{\vartheta}, \qquad (35)$$

$$q(\tau) = \left\langle \left\langle \operatorname{erf}(\overline{u}_{\vartheta} + \sigma_{u_{\vartheta}}x)\operatorname{erf}\left(\frac{\overline{u}_{\vartheta} + \rho_{u_{\vartheta}}(\tau)\sigma_{u_{\vartheta}}x}{\sqrt{1 + 2[1 - \rho_{u_{\vartheta}}^{2}(\tau)]\sigma_{u_{\vartheta}}^{2}}}\right)\right\rangle_{x \ \vartheta}, \qquad (36)$$

$$\chi = \frac{1}{\sqrt{\sigma_I^2 + J^2 q}} \left\langle \operatorname{zerf}\left(\frac{\overline{u}_{\vartheta}}{\sqrt{1 + 2\sigma_{u_{\vartheta}}^2}}\right) \right\rangle_{\vartheta}, \qquad (37)$$

$$\hat{\mathcal{C}}(0) = \int_{-\infty}^{+\infty} d\tau [q(\tau) - q], \qquad (38)$$

where, given our current system specifications, the average $\langle \ldots \rangle_{\vartheta}$ now corresponds to an average over the Gaussian *z* and the κ distribution.

To further accelerate the numerics we follow [46] and avoid solving the self-consistency problem Eq. (34) for \overline{u}_{ϑ} for every member of the ϑ ensemble, by using monotonicity of the selfconsistent solution $\overline{u}_{\vartheta} = \overline{u}_{\vartheta}(z)$ of Eq. (34) to replace the *z* average by \overline{u}_{ϑ} integrations instead. To do so we require the Jacobian of the transformation, which from the *z* derivative of Eq. (34), one obtains as

$$\frac{dz}{d\overline{u}_{\vartheta}} = \frac{1}{\sqrt{\sigma_I^2 + J^2 q}} \left[\kappa - \frac{2\alpha J^2 \chi \exp\left(-\frac{\overline{u}_{\vartheta}^2}{1+2\sigma_{u_{\vartheta}}^2}\right)}{\sqrt{\pi \left(1 + 2\sigma_{u_{\vartheta}}^2\right)}} \right].$$
(39)

Following the reasoning in [46] we realize that for large values of $\alpha J^2 \chi / \kappa$ the \overline{u}_{ϑ} distribution will have a gap corresponding to a jump in the self-consistent solution of m_{ϑ} . The critical condition for a jump in the distribution is given by

$$\frac{2\alpha J^2 \chi}{\kappa \sqrt{\pi \left(1 + 2\sigma_{u_{\theta}}^2\right)}} = 1 \tag{40}$$

with $\overline{u}_{\vartheta}(z)$ jumping from the negative to the positive solutions of

$$\overline{u}_{\vartheta} = \frac{1}{\kappa} \alpha J^2 \chi \operatorname{erf}\left(\frac{\overline{u}_{\vartheta}}{\sqrt{1 + 2\sigma_{u_{\vartheta}}^2}}\right).$$
(41)

This concludes the analysis of the general theoretical framework. We now turn to results.

IV. RESULTS

In order to structure our presentation of results, it is useful to recall that—in the absence of symmetry breaking fields, i.e., for $I_i + \sigma_0 u_0 \equiv 0$ —the system described by Eq. (3) has a global \mathbb{Z}_2 symmetry $u_i \leftrightarrow -u_i$. Due to the presence of interactions, this symmetry can be spontaneously broken, giving rise to ferromagnetic or spin-glass like phases [41,44] at sufficiently low noise levels (and for sufficiently small values of the κ_i). If couplings are symmetric and if their ferromagnetic bias is sufficiently small, the system may in fact exhibit exponentially (in system size) many metastable states in the zero noise limit [42,43]. Recent work [51] has in fact demonstrated that a large number of stationary states of the noiseless dynamics continues to exist in a broad class of nonlinearly interacting systems when constraints such as symmetries of interactions are dropped.

In the absence of symmetry breaking fields, phases with spontaneously broken symmetries are usually separated by sharp phase boundaries from phases where these symmetries remain unbroken. In the context of modeling the evolution of interacting prices, however, a situation without any symmetry breaking fields in the evolution Eq. (3) would be a set of probability-measure zero for any nondegenerate distribution of μ_i and σ_i , irrespectively of the value u_0 of the macroeconomic risk factor, and would therefore have to be regarded as highly atypical. Transitions, if any, between phases of broken and unbroken symmetries would therefore typically appear to be rounded if described in terms of the order parameters m, q, and χ appearing in the theory. It would therefore not make too much sense to precisely locate phase boundaries which would not exist as sharp boundaries for virtually any realistic parameter setting. In such a situation the primary interest would be to locate regions in parameter space where we expect the existence of ferromagnetic or spin-glass like phases. We will endeavor to do this in Sec. IV A, taking properties of the phase structure that exists in the absence of symmetry breaking fields as a guidance.

Having identified interesting regions in parameter space, we will in Sec. IV B analyze distributions of log-returns for representative parameter values within these regions of interest, evaluating them for various timescales defined relative to the timescale γ^{-1} of the slow u_0 process that mimics the effect of macroeconomic conditions. In Sec. IV C we explore the phenomenon of collective pricing by investigating the distribution of equilibrium (log-)prices and in particular the effect that interactions between prices have on that distribution. In Sec. IV D, finally, we attempt to underpin our hypothesis concerning the relation between the existence of many longlived states in a system and the phenomenon of volatility clustering by setting up and simulating a system for which



FIG. 1. Magnetization as a function of u_0 , shown for three different values κ_0 of the mean of the kappa distribution. Here, we take $J_0 = J = 0.5$, with $\alpha = 0.5$, while $I_0 = 0$, $\sigma_I^2 = 0.1$, and $\sigma = 0.1$. From top to bottom the curves correspond to $\kappa_0 = 0.2, 0.7$, and 1.2, respectively.

we know—at least partially—the structure of some of its metastable states.

A. Phase structure

Here, we briefly discuss the phase structure of the model, with an eye mainly towards identifying regions in parameter space were we would expect phases with glassy properties characterized by a large number of metastable states. The authors of [36] went some way in that direction by analyzing macroscopic properties of attractors in the noiseless ($\sigma_i \equiv 0$) limit of the dynamics. In particular it was shown that the mean reversion constants κ_i , taken to be homogeneous across the system in [36], would play a role analogous to temperature.

Continuing on the assumption of Gaussian I_i made in Sec. III D, and assuming that σ_i are homogeneous across the network, $\sigma_i \equiv \sigma$, we have 7 parameters characterizing the system, viz., J_0 and J determining the mean and variance, and the parameter α quantifying the degree of asymmetry of the couplings, as well as the mean I_0 and variance σ_I^2 of the distribution of I_i , the strength σ of the noise in the dynamics, and κ_0 , the mean of the κ distributions that we will consider in this paper. Unless stated otherwise, results presented in the figures below were in fact obtained by choosing an exponential κ distribution for the mean reversion constants κ_i .

There can be no question of exploring this 7-dimensional parameter space completely. Fortunately we find that collective properties of the system are in the interesting region of parameter space fairly robust against parameter changes, so we will restrict ourselves to highlighting a few of the most important trends.

In Fig. 1 we show the behavior of the stationary macroscopic magnetization *m* as a function of the value u_0 of the slow process, using an unbiased I_i distribution with $I_0 = 0$, and $\sigma_I^2 = 0.1$. Note that parameters characterizing the distribution of couplings and the strength σ of the dynamic noise are chosen such that there is no spontaneous "ferromagnetic" order in the $u_0 \rightarrow 0$ limit. We also note that increasing the mean κ_0 of the κ distribution has an effect analogous to increasing the temperature, in that it reduces the degree of macroscopic (ferromagnetic) order.



FIG. 2. Magnetization *m* (blue full line), time-persistent correlation *q* (red dashed line), and integrated response χ (black dotted line) as functions of J_0 in the absence of any global symmetry breaking fields, i.e., for $I_0 = u_0 = 0$. Other parameters are $\sigma_I^2 = 0.1$, so there is a local random field, J = 0.5, $\alpha = 0.5$, $\kappa_0 = 0.2$, and $\sigma = 0.1$. The figure shows the appearance of a ferromagnetic phase as J_0 is increased beyond $J_0^c \simeq 0.75$. For $J_0 < J_0^c$ the system is in a frozen "spin-glass" like phase.

Figure 2 illustrates that in the absence of global symmetry breaking fields, the system exhibits a sharp second-order phase transition to ferromagnetic order as the value of the ferromagnetic bias J_0 in the coupling distributions is increased above a critical value J_0^c . For values of the other parameters as given, the system is in a frozen "spin-glass" like phase for $J_0 < J_0^c \simeq 0.75$. Transitions to ferromagnetic order could also be induced by reducing the noise level σ at sufficiently large ratios of J_0/J and for sufficiently low κ_0 . In a similar vein transitions into the spin-glass like phase could be induced by lowering the noise level at sufficiently small J_0/J ratio, again provided κ_0 is sufficiently small. Alternatively one could chose to lower κ_0 at sufficiently small value of σ to induce these transitions.

Figure 3 shows the phase boundary separating a spin-glass like phase at small values of J_0 from a ferromagnetic phase at larger values of J_0 as a function of κ_0 in the absence of global symmetry breaking fields. For such a phase boundary to exist the noise level σ has, of course, to be sufficiently low. It is



FIG. 3. Phase boundary separating a spin-glass like phase at small values of J_0 from a ferromagnetic phase at larger values of J_0 as a function of κ_0 in the absence of global symmetry breaking fields, i.e., for $I_0 = u_0 = 0$, but $\sigma_I^2 = 0.1$. Other parameters are J = 0.5, $\alpha = 0.5$, and $\sigma = 0.1$.

expected that a spin-glass like phase will continue to exist even in the presence of weak symmetry breaking fields, in analogy to what is known for the Sherrington-Kirkpatrick (SK) model [52].

B. Return distributions

We now look to compute distributions of log-returns across the ensemble of interacting assets. (In what follows, we will somewhat loosely refer to them as return distributions). To begin with, we consider the distribution of returns for an arbitrary member of the ϑ ensemble, and so we need to consider the statistics of differences,

$$\Delta u_{\vartheta} \equiv u_{\vartheta}(t) - u_{\vartheta}(t'), \tag{42}$$

omitting time arguments on the left-hand side for simplicity.

We will always consider late times such that $\gamma t \gg 1$ and $\gamma t' \gg 1$ in order to ensure the slow process is in equilibrium. Three timescales naturally arise following the above criteria:

(i) The quasistationary regime for which $\gamma |t - t'| \ll 1$. In this regime we regard the fast process as stationary at a given value of the slow process. This constitutes looking at times for which the macroscopic characterization of the system state remains constant.

(ii) An intermediate timescale defined by $\gamma |t - t'| = O(1)$. Explicitly, this involves looking at return distributions for stationary fast processes parametrized by $u_0(t)$ and $u_0(t')$, for which correlations between the two slow processes still exist.

(iii) The long timescale, which we define as $\gamma |t - t'| \gg 1$, so that even the slow process has decorrelated.

In any case, we will be interested in variations induced by both the ϑ distribution and for generality, the u_0 statistics too. It could, however, also be of interest to inspect return distributions conditioned on specific values of the slow process.

1. Quasistationary regime

Here, we look at the distribution of returns for the fast process in equilibrium for a given value u_0 of the slow process. This implies that we look at time differences such that u_{ϑ} obeys the equation of motion Eq. (15) for all times of interest. Naturally, we are interested in the limits $\kappa t, \kappa t' \gg 1$ which again allows us to define three distinct time scales of interest in the quasistationary regime itself. We will refer to these as

(i) short :
$$\kappa |t - t'| \ll 1$$
,
(ii) medium : $\kappa |t - t'| = O(1)$,
(iii) long : $\kappa |t - t'| \gg 1$.

We note that some initial regularization of the κ distributions (upper and lower cutoffs) may be needed to make the definition of these time windows and some of the arguments below well defined for all members of the ϑ ensemble; regularizations/cutoffs can then be removed at the end of each calculation in question. In order not to overburden the presentation, we will, however, not explicitly retrace and document these steps in what follows.

Using the solution given in Eq. (22), we see that

$$\Delta u_{\vartheta} = \int_0^t e^{-\kappa(t-s)} \eta(s) ds - \int_0^{t'} e^{-\kappa(t'-s')} \eta(s') ds'.$$
(43)

As η is a Gaussian noise, we find that the returns for a single member of the ensemble of effective single-site processes in the quasistationary regime are normally distributed, i.e.,

$$\Delta u_{\vartheta} \sim \mathcal{N}\left(0, \frac{\sigma^2}{\kappa} [1 - e^{-\kappa |t - t'|}]\right). \tag{44}$$

For the short timescale defined above, one may expand the exponential appearing in the variance, entailing that the κ dependence vanishes (at first order in the expansion),

$$\Delta u_{\vartheta} \sim \mathcal{N}(0, \sigma^2 | t - t' |). \tag{45}$$

At these very short time separations the return distribution thus exhibits simple diffusive broadening. If σ is taken to be constant across the ensemble, this result remains true across any portfolio of assets traded in the market.

At the long and intermediate timescales within the quasistationary regime there will of course be a κ dependence of individual returns. However, if we concern ourselves with the distribution $p(\Delta u)$ of returns across the ensemble of processes, we can obtain it by averaging the above over the ϑ distribution,

$$p(\Delta u) = \int d\vartheta P(\vartheta) p(\Delta u_{\vartheta}). \tag{46}$$

In general, this integral has to be done numerically. A simplification is possible for very large time separations within the quasistationary regime, for which the exponential correction in the variance in Eq. (44) can be neglected, and $\Delta u_{\vartheta} \sim \mathcal{N}(0, \frac{\sigma^2}{\kappa})$. Keeping σ constant across the ensemble, the only ϑ component to average over in this limit then is κ . An analytically closed form for the distribution of returns across the ensemble can then be obtained if we assume the κ to be Γ -distributed,

$$P(\kappa) = \frac{1}{\kappa_0 \Gamma(\nu)} \left(\frac{\kappa}{\kappa_0}\right)^{\nu-1} \exp(-\kappa/\kappa_0).$$
(47)

Here κ_0 is a scale parameter which also defines the mean of the κ distribution, while ν determines its actual shape. For this family of κ distributions we obtain

$$p(\Delta u) = \frac{\sqrt{\kappa_0}}{\sqrt{2\pi\sigma^2}} \frac{\Gamma(\nu + \frac{1}{2})}{\Gamma(\nu)} \left(1 + \frac{\kappa_0(\Delta u)^2}{2\sigma^2}\right)^{-(\nu + 1/2)}.$$
 (48)

Within this family of return distribution we observe power law tail behavior, $p(\Delta u) \sim (\Delta u)^{-\mu}$ for $|\Delta u| \gg 1$, with $\mu = 1 + 2\nu$. We note that the case $\nu = 1$ would correspond to an exponential κ distribution, which would be the distribution naturally selected by the maximum entropy principle for a strictly positive random variable with a prescribed mean, in which case the tail exponent would be $\mu = 3$. In Fig. 4 we compare this analytical asymptotic result with that of a full numerical evaluation of the distribution of returns across the ensemble for $\kappa_0 |t - t'| = 20$, observing excellent agreement between the two already for moderate time separations.

Although we are unable to evaluate the full distribution of returns across the ϑ ensemble for intermediate time separations, a quantity that we can evaluate in closed form for all time separations in the quasistationary regime is its variance $\langle (\Delta u)^2 \rangle = \langle \langle (\Delta u_\vartheta)^2 \rangle \rangle_\vartheta$, in which the inner average is the variance of the return distribution for a given member of the ϑ ensemble, specified in Eq. (44), and the outer average is over the ϑ distribution. With specifications as before, i.e., keeping σ



FIG. 4. Return distribution in the quasistationary regime evaluated for $\kappa_0 |t - t'| = 20$ (red dashed line) compared with the analytic prediction for its asymptotic behavior Eq. (48) (blue full line) for an exponential κ distribution with $\nu = 1$.

constant across the ensemble, the only ϑ component to average over is once more the κ distribution. For Γ -distributed κ as specified above we obtain

$$\langle (\Delta u)^2 \rangle = \frac{\sigma^2}{\kappa_0(\nu - 1)} \bigg[1 - \frac{1}{(1 + \kappa_0 |t - t'|)^{\nu - 1}} \bigg]$$
(49)

for $\nu \neq 1$. In the $\nu \rightarrow 1$ limit this specializes to

$$\langle (\Delta u)^2 \rangle \Big|_{\nu=1} = \frac{\sigma^2}{\kappa_0} \ln(1 + \kappa_0 |t - t'|).$$
 (50)

In the limit of very short time separations, this reproduces a diffusive broadening $\langle (\Delta u)^2 \rangle \sim \sigma^2 |t - t'|$ of the variance which is independent of properties of the κ distribution, as observed earlier.

It is worth pointing out that the return distributions in the quasistationary regime are independent of the global u_0 process, and in fact independent also of other parameters characterizing the interactions, as the u_0 -dependent means \overline{u}_{ϑ} , which do depend on the interaction parameters, cancel when taking differences.

2. Intermediate and long timescales

We now turn our attention to the case where the fast process is in equilibrium at two different values for u_0 . In particular, for a single member of the ensemble, evaluation of Eq. (42) gives

$$\Delta u_{\vartheta} = \overline{u}_{\vartheta}(t) - \overline{u}_{\vartheta}(t') + \int_{0}^{t} e^{-\kappa(t-s)} \eta(s) ds$$
$$- \int_{0}^{t'} e^{-\kappa(t'-s')} \eta(s') ds'.$$
(51)

In contrast to the quasistationary regime, the timedependent mean values \overline{u}_{ϑ} determined by the values of u_0 at two different times t and t' now explicitly appear in the returns. We also expect that on this timescale, the fast noise processes have decorrelated with one another. Therefore, the distribution of returns for a given member of the ensemble and for given values of $u_0(t)$ and $u_0(t')$ is now normal with a non-zero mean, and is given by

$$\Delta u_{\vartheta}\big|_{u_0(t),u_0(t')} \sim \mathcal{N}\big(\Delta \overline{u}_{\vartheta}(t,t'), \sigma^2_{u_{\vartheta}}(t) + \sigma^2_{u_{\vartheta}}(t')\big), \qquad (52)$$



FIG. 5. Distributions for long time log returns across the ensemble averaged over all market conditions. Again, power law tails are observed and we expect that upon suitable normalization the distributions across timescales should scale very well as is seen in microscopic simulations.

where

$$\Delta \overline{u}_{\vartheta}(t,t') = \overline{u}_{\vartheta}(t) - \overline{u}_{\vartheta}(t')$$

$$= \frac{1}{\kappa} [J_0(m_t - m_{t'}) + \sigma_0(u_0(t) - u_0(t'))$$

$$+ \alpha J^2(\chi_t m_{\vartheta,t} - \chi_{t'} m_{\vartheta,t'})].$$
(53)

Here we denote an order parameter A of interest by A_t to denote its value in equilibrium for a given value $u_0(t)$ of the slow process u_0 at time t. As before, we are interested in the return distribution across the whole ensemble, which is obtained by averaging over the ϑ distribution. In addition to this, we can either look at return distributions for a range of specific u_0 values, or we may choose to average over their distribution. Since the u_0 term mimics the state of global economic behavior, this average corresponds to return distributions across all market conditions. As the u_0 statistics are Gaussian, the joint distribution becomes easy to write down, allowing us to perform this average in a straightforward manner. Finally, the return distribution across the ensemble of processes, across all market conditions, is written down as

$$p(\Delta u) = \int d\vartheta du_0(t) du_0(t') P(\vartheta) p(u_0(t), u_0(t'))$$
$$\times p(\Delta u_\vartheta | u_0(t), u_0(t')). \tag{54}$$

This return distribution is shown in Fig. 5.

Differences between the intermediate and long timescales arise through differences in the joint distribution $p(u_0(t), u_0(t'))$ for the slow process. In the first case, the market conditions are still correlated while in the long time limit these correlations no longer persist. In both cases, we find that returns across the portfolio maintain their power law distributed tails.

C. Collective pricing

Here we explore the phenomenon of collective pricing mentioned at the beginning of this section. More specifically, we take a closer look at the role of \overline{u}_{ϑ} as defined in Eq. (21); we know that this quantity takes the role of the equilibrium value of the associated asset price under given macroeconomic conditions as parametrized by the value of the slow u_0 process. In order to identify the *collective* interaction-mediated properties of pricing distributions, we begin by looking at the noninteracting baseline. Without interactions in the system, the combined effect of mean reversion, drift, volatility, and the value u_0 of the slow process describing macroeconomic conditions is, according to Eq. (21), to produce a mean log-price

$$\overline{u}_{\vartheta} = \frac{1}{\kappa} [I + \sigma_0 u_0] \tag{55}$$

that depends linearly on *I* and on the value of the u_0 process. Recall that $I_i = \mu_i - \frac{1}{2}\sigma_i^2$, so *I* includes effects of drift and volatility.

Assuming a normal distribution for I as above, $I \sim \mathcal{N}(I_0, \sigma_I^2)$, we get a normally distributed family of mean prices at given mean reversion,

$$\overline{u}_{\kappa} \sim \mathcal{N}\left(\frac{I_0 + \sigma_0 u_0}{\kappa}, \frac{\sigma_I^2}{\kappa^2}\right),\tag{56}$$

which, upon averaging over κ which are Γ -distributed with $\nu > -1$ according to Eq. (47), gives

$$p(\overline{u}) = \frac{\nu \kappa_0}{\sqrt{2\pi\sigma_I^2}} \exp\left\{-\frac{1}{2\sigma_I^2}(I_0 + \sigma_0 u_0)^2\right\}$$
$$\times \beta^{-(1+\nu)/2} \exp\left\{\frac{\gamma^2}{4\beta}\right\} D_{-(1+\nu)}\left(\frac{\gamma}{\sqrt{\beta}}\right), \quad (57)$$

in which $D_{\nu}(z)$ is a parabolic cylinder function [53], and

$$\beta = \left(\frac{\kappa_0 \overline{u}}{\sigma_I}\right)^2, \quad \gamma = 1 - \frac{\kappa_0 \overline{u}}{\sigma_I^2} (I_0 + \sigma_0 u_0). \tag{58}$$

Note that $\gamma^2/\beta \to \text{constant as } |\overline{u}| \to \pm \infty$, so the tail behavior of the \overline{u} distribution is governed by the $\beta^{-(1+\nu)/2}$ term in the above expression, giving $p(\overline{u}) \sim \overline{u}^{-(1+\nu)}$ for $|\overline{u}| \gg 1$. Conversely, the singularities which the three terms in the second line of Eq. (57) exhibit as $\overline{u} \to 0$ (hence $\beta \to 0$) cancel, so that $p(\overline{u})$ remains finite in this limit.

Having analyzed the noninteracting case, we now return to Eq. (21), and more specifically to its version for normally distributed *I*, Eq. (34), to study the effects of interactions on the \overline{u}_{ϑ} . As indicated at the end of Sec. IIID the distribution of the solution \overline{u}_{ϑ} of Eq. (34) is obtained by transforming the normal density of *z*

$$p(\overline{u}_{\vartheta}) = P(z) \left| \frac{dz}{d\overline{u}_{\vartheta}} \right|$$
(59)

in which $P(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$, with $z = z(\overline{u}_{\vartheta})$ obtained by solving Eq. (34) for *z*, and the Jacobian $\frac{dz}{d\overline{u}_{\vartheta}}$ of the transformation for the error-function feedback (32)—given by Eq. (39). This allows us to obtain the distribution of equilibrium prices as induced by normal variable *z* for a fixed κ . The distribution $p(\overline{u})$ of equilibrium log-prices over the ensemble is obtained by averaging over the ϑ distribution as before; the average once more reduces to an average over the κ distribution, if σ is kept constant across the ensemble.



FIG. 6. Distribution of equilibrium log-prices \overline{u}_{ϑ} for the noninteracting system (first panel), compared to those of the corresponding interacting system (second panel), for selected values of the mean reversion κ and the slow process u_0 ; note the different scales. System parameters are $I_0 = 0$, $\sigma_I^2 = 0.1$, $\kappa_0 = 0.2$, and $\sigma = 0.1$; for the interacting system we chose $J_0 = J = 0.5$ and $\alpha = 0.5$. For the individual curves the parameters are ($\kappa = 0.5, u_0 = 0.1$) (blue narrow pair of distributions), ($\kappa = 0.2, u_0 = 0.1$) (black, nearly symmetric, broad pair of distributions).

We see in Fig. 6 that interactions lead to a considerable broadening for the equilibrium distributions when compared with their noninteracting counterparts. Also the degree of asymmetry of these distributions is significantly enhanced by the interactions. A highly nontrivial effect is the systematic suppression of equilibrium log-prices which would be characterized as typical in the noninteracting system. This effect is primarily induced by the ferromagnetic bias of the interaction, which could be induced by herding or imitation effects of agents acting in the market, or by economic fundamentals suggesting co-movement of asset prices. It can fairly be said that this mechanism creates an interaction-mediated mechanism of a market to push prices of assets to more extreme values, i.e., both to very high and to very low values. The effect appears to be stronger for members of the ensemble with small values of the mean reversion constant κ ; it weakens for those with a larger mean reversion constant.

We may also look at the global characteristics of pricing distribution across the entire ensemble. This is achieved by averaging over the κ distribution. For the parameter settings used, one can see in Fig. 7 that this smooths out the bimodal nature observed for the subensembles of assets with selected κ values shown in Fig. 6, but it shows once more a considerable broadening of the distribution and a significant enhancement of the degree of asymmetry when compared with the noninteracting counterpart.





FIG. 7. Equilibrium distribution of log-prices across the entire ensemble for $u_0 = 1$, both for the interacting system (full line) and for the noninteracting system (dashed line). Parameters are the same as in Fig 6.

D. Metastable states and volatility clustering

We finally return to one of the central hypotheses underlying our modeling, namely that the complexity of real market dynamics [4], including in particular the phenomenon of volatility clustering, could be rationalized in terms of the interplay of dynamics within (metastable) market states and the dynamics of occasional transitions between them, rather then being produced by phenomenological models [8–13] specifically designed to produce the volatility fluctuations observed in real markets.

In this respect we note that distinct market states have indeed been identified empirically, e.g., in [54], who analyzed stock market return time series using Markov switching techniques, in [55], who look at distributions of traded volumes conditioned on noise, or in [56–59], who analyzed correlations of asset returns in historical data. While [54] and [55] give rise to binary classifications of market behavior in terms of switching means or variances in return time series [54] or in terms of classifying a market as either in an equilibrium phase or in a nonequilibrium phase, the studies based on clustering correlation matrices [56–59] identify a richer spectrum of possibilities.

The assumption behind our modeling is that market states would indeed emerge naturally as attractors of the collective (nonlinear) dynamics of interacting prices. For the Gaussian couplings that we have been using in the present study, analogies with the SK spin-glass model suggest that we do in fact expect a very large number of such attractors to exist in a large region of parameter space, not too dissimilar in fact from the findings of [56,57]. However, while we have no way of *a priori* knowing the *structure* of these states, clustering correlation matrices of asset returns in the spirit of [56,57] could well be used as a way to reveal their existence in our model.

Here we take an alternative route, trying to make progress in elucidating the relation between metastable states and volatility clustering in a more direct manner. We propose to look at a version of the market in which we embed a small number of *known* random attractors in the system, in order to analyze whether there is a relation between system state—measured in terms of similarity with these known attractors—and the observed volatility of the dynamics. For simplicity we take the system to be fully connected, and introduce couplings with a



FIG. 8. Simulation of a market with of N = 50 traded assets, exhibiting the relation between volatility and metastable state structures. The upper panel shows overlaps of the system state with three random attractors embedded in the coupling matrix in a Hebbian form as explained in the main text, while the lower panel shows returns on the index as a function of time. The other system parameters are $\kappa_0 = 0.2$, $I_0 = 0$, $\sigma_I^2 = 0.5$, $\sigma = 0.1$, $J_0 = J = 0.5$, $\alpha = 0.5$, and $\gamma = 10^{-4}$.

Gaussian and a Hebbian coupling component as follows,

$$J_{ij} = J_{ij}^{(G)} + J_{ij}^{(H)}, (60)$$

with

$$J_{ij}^{(G)} = \frac{J_0}{N} + \frac{J}{\sqrt{N}} x_{ij}$$
(61)

and

$$J_{ij}^{(\mathrm{H})} = \frac{1}{N} \sum_{\mu=1}^{p} \xi_i^{\mu} \xi_j^{\mu}, \qquad (62)$$

in which the ξ_i^{μ} are i.i.d. random variables taking values $\xi_i^{\mu} = \pm 1$ with equal probability, and the x_{ij} are normally distributed $x_{ij} \sim \mathcal{N}(0,1)$ and independent in pairs with $\overline{x_{ij}x_{ji}} = \alpha$ as in the original setup.

Figure 8 presents results of a simulation of such a system of size N = 50, with p = 3 "patterns" embedded in the couplings, in which we simultaneously record the changes of the index, and the values of the overlaps

$$m_{\mu}(t) = \frac{1}{N} \sum_{i} \xi_{i}^{\mu} g(u_{it})$$
(63)

with the three random patterns $\{\xi_i^{\mu}\}$, for $\mu = 1, 2$, and 3 embedded in the system. There is indeed a pronounced correlation between the volatility of the index changes and the system state as measured by the three overlaps in the system, and we believe that we can take this as a clear qualitative, and indeed semiquantitative, indication that our hypothesis of a link

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between metastable states and volatility clustering is correct for the model class under consideration.

V. SUMMARY AND DISCUSSION

In this paper, we have provided a comprehensive analysis of the iGBM introduced in [36]. The line of reasoning leading to a model of interacting prices of this type is described in detail in that paper. Suffice it to mention here that the structure of the model follows from very general arguments concerning the description of market mechanisms and of agents acting in a market within reduced models based on the evolution of prices alone. This is not to suggest that choices were not made. They include the choice of Gaussian-distributed pair interactions and sigmoid-saturating nonlinear transfer functions. However, key properties underlying the intermittent nature of market dynamics observed in the present model are expected to be largely independent of these choices and will not require fine-tuning of parameters, as long as interactions were chosen in such a way as to exhibit a sufficient degree of both disorder and frustration, and as long as transfer functions were chosen which for large values of their argument grow slower than linearly with their argument (which is a prerequisite for the long-term stability of the system that was exploited in the analysis of quasistationary states in Sec. III).

In the present investigation we couple the dynamics of the system to a slow Ornstein-Uhlenbeck process, which we introduce to mimic the effect of slowly evolving macroeconomic conditions. The precise nature of this slow process is not crucial for the majority of our results, including in particular those related to statistics of return distributions in the quasistationary regime. At intermediate and long timescales, the time dependence of the correlation of the slow process will affect details of return distributions, though the fact that they are fat-tailed is independent of our choice, as are the properties of equilibrium log-price distributions discussed in Sec. IV C, where specific values of the slow process are only used parametrically.

We have performed a generating functional analysis of the dynamics, which maps the dynamics of the interacting system onto an ensemble of systems exhibiting a non-Markovian dynamics which is self-consistently coupled through a set of dynamic order parameters. Using a separation of timescales argument, which assumes that the fast internal dynamics of the interacting system equilibrates at given values of the slow Ornstein-Uhlenbeck process, we are able to analyze the stationary dynamics of the system. This then allows us to identify regions in parameter space where the system exhibits ferromagnetic or spin-glass like phases.

Our analysis of the stationary dynamics (at given values of the slow driving) allows us to evaluate the distribution of log-returns for the ensemble for various timescales, both in the quasistationary regime and at larger time separations. For a broad class of distributions of the mean reversion terms in the model, we find that distributions of log-returns across the ensemble are fat-tailed, exhibiting asymptotic power law behavior broadly in line with empirical facts [5]. We note, however, that our model, as it is currently set up, does not reproduce the fat tails at the single-asset level that were found empirically in [6]. We will discuss the origin of that shortcoming, and thus possible ways to improve the model in this respect, below. We are also able to evaluate the timedependent variance of the distribution of log-returns in the quasistationary regime, and find *diffusive* broadening in the limit of small time separations, with the broadening becoming subdiffusive at later times. These findings are broadly in line with empirical observations.

Interestingly, our model predicts the existence of equilibrium prices for assets, and we are able to explicitly trace the influence of interactions on the distribution of equilibrium prices across the ensemble. The two main effects of collective pricing, as predicted by the iGBM, are to considerably broaden the distribution of equilibrium prices in comparison with their noninteracting counterparts, as well as a significant enhancement of asymmetries characterizing such distributions for given (favorable or unfavorable) economic conditions as quantified by the value u_0 of the slow noise process. More specifically, we also observe a pronounced interaction-induced preference for very high or very low asset prices, which we think, deserves further study.

Note that distributions of log-returns and pricing distributions across the market are of *collective* origin, and so they can be expected to be to a certain extent independent of details of the model specifications. In particular, collective properties of the system will not depend on specific realizations of interasset couplings, though they may, and in general will, depend of properties of coupling *distributions*. This aspect could indeed provide an avenue to analyzing market data within the present modeling framework which does not require getting individual couplings correct. It is also the main aspect from which the current modeling approach may eventually derive some predictive power, and might, for instance, be used to provide tools to assess market risk at a systemic level. It goes without saying that further investigations using real data will be required to get there.

One of the principal motivations for constructing the iGBM was to explore whether some of the stylized facts of financial time series could be understood in terms of effective interactions between prices of assets traded in a market, given that effective interactions between asset prices are a necessary feature of any model that attempts to describe market dynamics in a reduced form as a dynamics of prices alone. We have gone some way to demonstrate that this is true at the level of return distributions. Another important phenomenon is that of volatility clustering which in fact finds a quite natural explanation in terms of interacting prices. Due to the interactions, the system is expected to exhibit a large number of (dynamic and static) attractors if there is a sufficient degree of disorder and frustration. In the presence of noise, many of these attractors will survive as long-lived states, and volatility clustering is expected to arise naturally through the interplay of the dynamics within long-lived states and the dynamics of occasional transitions between them. Such transitions can occur spontaneously or be triggered by news or slowly changing macroeconomic conditions. Different longlived states will be characterized by different values of their susceptibilities and so the presence of noise in the dynamics is expected to induce fluctuations with different degrees of volatility. Using simulations of a system with a partially known attractor structure, we have demonstrated in Sec. IVD above

that our hypothesis about a relation between metastable states and volatility clustering is correct at least for models of the type considered here.

In [36] the authors simulated the model using an external perturbation which they argued could represent the effect of the arrival of unexpected news (e.g., in the context of quarterly reporting). The process used in that paper is difficult to implement in analytically closed form, which was one of our reasons for adopting the slow Ornstein-Uhlenbeck process, which uniformly affects all prices in a market, as a mechanism to induce transitions between metastable states. We believe that it is the absence of a jump-process component of the noise in the version of the model investigated in the present paper which is ultimately responsible for the fact that the model does not exhibit fat-tailed return distributions at the level of single assets. This could easily be rectified in the model formulation, by adding, e.g., a Poisson jump process component to the noise, but it is likely to considerably complicate attempts at solving the model analytically. We believe it would be important to explore to what extent a model with a combination of continuous and discrete noise sources is amenable to analysis.

Our last remark refers to the presence of mean reverting forces in the iGBM, given that the existence of such forces is debated in economic circles. Within our modeling, the existence of mean reverting forces is responsible for ensuring long-term stability of the market. It would be easier to motivate the existence such forces if the $u_i(t)$ were introduced as logprices on a *co-moving frame* as $u_i(t) = \ln[S_i(t)/S_{i0}e^{(\mu_i - \frac{1}{2}\sigma_i^2)t}]$. This modification would in the first instance eliminate the drift I_i from the transformed equation (2), and it would suggest introducing an iGBM formally in the same manner as was done originally, albeit with the drift term I_i missing from the interacting version Eq. (3) as well. Within this modified interpretation of the $u_i(t)$, the mean reversion and the interactions would have to be interpreted as mean reversion and interactions relative to an expected trend rather than relative to some fixed log-price, which might be easier to justify in economic terms. Long-term stability of the model would be saved, albeit on a co-moving frame. As an additional benefit the random symmetry breaking field I_i would also disappear from the equations, which could simplify the ensuing analysis. As a downside though, such a model would likely be harder to calibrate against real market data, which should indeed be one of the next natural steps to undertake within the present project.

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APPENDIX: GENERATING FUNCTIONAL ANALYSIS

In this Appendix we use generating functional analysis (GFA) [47] to formally solve the model dynamics. We begin by introducing the generating functional in terms of source

fields, ℓ ,

$$Z[\ell|u_0] = \left\langle \exp\left\{-i \int dt \sum_i \ell_i(t) n_i(t)\right\} \right\rangle, \qquad (A1)$$

in which the $n_i(t) = g(u_i(t))$ are the variables in terms of which the interaction between log-prices is defined, and we condition on a realization u_0 of the path of the slow process representing the evolution of macroeconomic conditions. The angled brackets refer to the average over all paths, which are trajectories of microscopic states. Explicitly,

$$Z[\ell|u_0] = \int \mathcal{D}\boldsymbol{u} P[\boldsymbol{u}] \exp\left\{-i \int dt \sum_{i=1}^N \ell_i(t) n_i(t)\right\}, \quad (A2)$$

where $\mathcal{D}u$ is the flat measure over a set of paths $u = \{u_i(t)\}, i = 1, ..., N$ over some finite risk horizon $0 \le t \le T$, and P[u] denotes the probability of these paths. The generating functional can be used to compute expectation values and correlation functions as

$$\langle n_i(t) \rangle = i \left. \frac{\delta Z[\ell | u_0]}{\delta \ell_i(t)} \right|_{\ell \equiv 0},\tag{A3}$$

$$\langle n_j(s)n_i(t)\rangle = i^2 \frac{\delta Z[\ell|u_0]}{\delta \ell_j(s)\delta \ell_i(t)} \bigg|_{\ell=0}.$$
 (A4)

The evaluation of the generating functional follows standard reasoning; see, e.g., [47–50]. For stochastic processes described by a Langevin equation driven by Gaussian white noise, one uses δ functionals and their Fourier representations to enforce the equations of motion, which allows us to transform probabilities of noise trajectories into path probabilities. Assuming Ito discretization for the Langevin equation one can thus express the generating functional as

$$Z[\ell|u_0] = \int \mathcal{D}\{\boldsymbol{u}, \hat{\boldsymbol{u}}\} \exp\left\{-\int dt \sum_i \left[\frac{\sigma_i^2}{2} \hat{u}_i(t)^2 + i\hat{u}_i(t) \left(\dot{u}_i(t) + \kappa_i u_i(t) - I_i - \sum_j J_{ij} n_j(t) - \sigma_0 u_0(t)\right) - i\ell_i(t) n_i(t)\right]\right\}.$$
(A5)

We are interested in evaluating the generating functional for a typical realization of disorder. This is achieved by averaging Eq. (A5) over the bond disorder, i.e., over c_{ij} and x_{ij} in terms of which J_{ij} are expressed. This disorder average factors in pairs (i, j),

$$D = \prod_{i < j} \overline{\exp\left\{i \int dt [\hat{u}_i(t)J_{ij}n_j(t) + \hat{u}_j(t)J_{ji}n_i(t)]\right\}}^{c,x}.$$
 (A6)

Here, we use the overbar notation to represent an average over the disorder c and x.

Writing J_{ij} explicitly in terms of c_{ij} and x_{ij} according to Eqs. (5), (6), and performing the c_{ij} average in the the limit of

large N and finite mean connectivity c, we obtain

$$D = \prod_{i < j} \left\{ 1 + \frac{c}{N} \overline{\left[\exp\left\{ \left(\frac{J_0}{c} + \frac{J}{\sqrt{c}} x_{ij} \right) \int dt i \hat{u}_i(t) n_j(t) \right. \right. \right.} + \left(\frac{J_0}{c} + \frac{J}{\sqrt{c}} x_{ji} \right) \int dt i \hat{u}_j(t) n_i(t) \left. \right\} - 1 \right]^x} \right\}.$$
 (A7)

Using the fact that $c \gg 1$, we follow, e.g., [60], expanding the exponential to perform the *x* average, keeping only dominant terms in the expansion in terms of inverse powers of *c*, and then re-exponentiate to write

$$D \simeq \exp\left\{N\left[J_0 \int dt k(t)m(t) + \frac{J^2}{2} \int ds dt [Q(s,t)q(s,t) + \alpha G(s,t)G(t,s)]\right]\right\},$$
(A8)

where we have introduced the set of one-time and two-time order parameters

$$m(t) = \frac{1}{N} \sum_{i=1}^{N} n_i(t),$$

$$k(t) = \frac{1}{N} \sum_{i=1}^{N} i\hat{u}_i(t),$$

$$q(s,t) = \frac{1}{N} \sum_{i=1}^{N} n_i(s)n_i(t),$$

$$Q(s,t) = \frac{1}{N} \sum_{i=1}^{N} i\hat{u}_i(s)i\hat{u}_i(t),$$

$$G(t,s) = \frac{1}{N} \sum_{i=1}^{N} i\hat{u}_i(s)n_i(t).$$

One then enforces these definitions using Dirac δ -function identities and their Fourier representations, to transform the disorder-averaged generating functional into a functional integral, which to leading order in the system size N can be expressed in the following compact form,

$$\overline{Z[\ell|u_0]} = \int \mathcal{D}\{\dots\} \exp\{N[\Xi_1 + \Xi_2 + \Xi_3]\}.$$
 (A9)

Here, $\mathcal{D}\{\dots\}$ represents the functional measure over the set of macroscopic order parameter functions and their conjugates. The functionals Ξ_1 , Ξ_2 , and Ξ_3 , appearing in the exponential of Eq. (A9), are defined as

$$\Xi_1 = J_0 \int dt k(t) m(t) + \frac{J^2}{2} \int ds dt [Q(s,t)q(s,t) + \alpha G(s,t)G(t,s)], \qquad (A10)$$

$$\Xi_{2} = i \int dt [m(t)\hat{m}(t) + k(t)\hat{k}(t)] + i \int ds dt [q(s,t)\hat{q}(s,t) + Q(s,t)\hat{Q}(s,t) + G(t,s)\hat{G}(t,s)],$$
(A11)

$$\Xi_{3} = \frac{1}{N} \sum_{i} \ln \int \mathcal{D}\{u, \hat{u}\} \exp\left[-\mathcal{S}_{i} - i \int dt \ell_{i}(t) n(t)\right].$$
(A12)

Here S_i denotes the effective local dynamic action of process i,

$$S_{i} = \int dt \left\{ -\frac{\sigma_{i}^{2}}{2} [i\hat{u}(t)]^{2} + i\hat{u}(t) \left[\dot{u}(t) + \kappa_{i}u(t) - I_{i} -\sigma_{0}u_{0}(t) \right] + i\hat{m}(t)n(t) + i\hat{k}(t)i\hat{u}(t) \right\}$$
$$+i\int ds dt [\hat{q}(s,t)n(s)n(t) + \hat{Q}(s,t)i\hat{u}(s)i\hat{u}(t) + \hat{G}(t,s)n(t)i\hat{u}(s)].$$
(A13)

It depends on *i* only through the locally varying parameters $(I_i, \kappa_i, \sigma_i) \equiv \vartheta_i$.

One now evaluates Eq. (A9) using the saddle point technique, which requires the macroscopic order parameters of interest to satisfy the following fixed point equations:

$$m(t) = \frac{1}{N} \sum_{i} \langle n(t) \rangle_{(i)},$$

$$q(s,t) = \frac{1}{N} \sum_{i} \langle n(s)n(t) \rangle_{(i)},$$

$$G(t,s) = \frac{1}{N} \sum_{i} \langle n(t)i\hat{u}(s) \rangle_{(i)}, \quad t > s.$$
(A14)

All other order parameters are self-consistently zero due to causality. In Eq. (A14), we use $\langle ... \rangle_{(i)}$ to represent an average over the dynamics of effective single-site processes *i* which takes the form

$$\langle \dots \rangle_{(i)} = \frac{\int \mathcal{D}\{u, \hat{u}\}(\dots) \exp(-\mathcal{S}_i)}{\int \mathcal{D}\{u, \hat{u}\} \exp(-\mathcal{S}_i)}.$$
 (A15)

We note that due to causality the effective single-site action simplifies to

$$S_{i} = \int dt \left\{ -\frac{\sigma_{i}^{2}}{2} [i\hat{u}(t)]^{2} + i\hat{u}(t) \left[\dot{u}(t) + \kappa_{i}u(t) - I_{i} -J_{0}m(t) - \alpha J^{2} \int^{t} ds G(t,s)n(s) - \sigma_{0}u_{0}(t) \right] \right\}$$
$$-\frac{J^{2}}{2} \int ds dt q(s,t)i\hat{u}(s)i\hat{u}(t).$$
(A16)

By the law of large numbers the saddle point equations (A14) for the order parameters can be written as averages over

the distribution of the locally varying parameters $\vartheta \equiv (I, \kappa, \sigma)$,

$$\frac{1}{N}\sum_{i}\langle\ldots\rangle_{(i)}\to\langle\langle\ldots\rangle\rangle_{\vartheta},$$

as the large system limit $N \to \infty$ is taken. Here inner averages correspond to those over the dynamics of a single process with a particular parameter combination, while the outer average stands for an average over the ϑ distribution, i.e., $\langle \dots \rangle_{\vartheta} \equiv \int dI d\kappa d\sigma p(I,\kappa,\sigma)(\ldots)$.

One finally notes that the appearance of a contribution in the effective single-site action (A16) which is nonlocal in time and quadratic in the conjugate dynamical variables $\hat{u}(t)$ is a manifestation of the fact that the effective single-site processes are governed by *colored* noise, while the nonlocal contribution involving the response function G(t,s) expresses the effect that effective single-site dynamics is non-Markovian. The equation of motion for the effective single-site dynamics can be inferred from the effective single-site action (A16), giving

$$\dot{u}_{\vartheta}(t) = -\kappa u_{\vartheta}(t) + I + J_0 m(t) + \sigma_0 u_0(t) + \alpha J^2 \int_0^t ds G(t,s) n_{\vartheta}(s) + \phi(t), \quad (A17)$$

where we write $u(t) = u_{\vartheta}(t)$ when referring to the singlesite process with local parameters $\vartheta = (I, \kappa, \sigma)$, so $n_{\vartheta}(t) = g(u_{\vartheta}(t))$, and where the colored noise $\phi(t)$ and the dynamical order parameters appearing in Eq. (A17) must satisfy the self-consistency equations

$$\langle \phi(t) \rangle = 0, \tag{A18}$$

$$\langle \phi(t)\phi(s)\rangle = \sigma^2 \delta(t-s) + J^2 q(t,s),$$
 (A19)

and

$$m(t) = \langle \langle n_{\vartheta}(t) \rangle \rangle_{\vartheta}, \qquad (A20)$$

$$q(t,s) = \langle \langle n_{\vartheta}(t)n_{\vartheta}(s) \rangle \rangle_{\vartheta}, \qquad (A21)$$

$$G(t,s) = \left\langle \frac{\delta \langle n_{\vartheta}(t) \rangle}{\delta h(s)} \right\rangle_{\vartheta}, \quad t > s.$$
 (A22)

We have thus reduced the original system to one comprising an ensemble of effective single-site processes characterized by the ϑ distribution with colored noise and memory which are self-consistently determined in terms of dynamical order parameters.

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