

Almost-dispersionless pulse transport in long quasiuniform spring-mass chains: A different kind of Newton's cradle

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Almost-dispersionless pulse transfer between the extremal masses of a uniform harmonic spring-mass chain of arbitrary length can be induced by suitably modifying two masses and their spring's elastic constant at both extrema of the chain. It is shown that a deviation (or a pulse) imposed to the first mass gives rise to a wave packet that, after a time of the order of the chain length, almost perfectly reproduces the same deviation (pulse) at the opposite end, with an amplitude loss that is as small as 1.3% in the infinite-length limit; such a dynamics can continue back and forth again for several times before dispersion cleared the effect. The underlying coherence mechanism is that the initial condition excites a bunch of normal modes with almost equal frequency spacing. This constitutes a possible mechanism for efficient energy transfer, e.g., in nanofabricated structures.

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I. INTRODUCTION

Newton's cradle is a toy that seems to have a perfect behavior, explained in terms of the conservation of energy and momentum in the pairwise elastic collision of equal spheres. However, such a naïve theory only holds for two spheres: For many spheres the underlying physics is complicated and needs a detailed analysis of the collision mechanism. For instance, observation gives the impression that the internal spheres do not move, so one could imagine that gluing them together would not affect the cradle. This is in contrast with the conservation laws, for only a fraction of the momentum would be transferred from the first colliding sphere; in any case, why Newton's cradle works, as it indeed does, is a well-settled issue [1–3].

In this paper a different system is considered, namely a chain of N masses connected by elastic massless springs, such as that shown in Fig. 1, looking for the possibility that it behaved in an analogous way, by this meaning that an initial “pulse” located on the first mass travels along the chain and reaches the last mass yielding a mirror image of the initial configuration. This requirement is far from trivial. The simplest choice, namely a uniform chain with identical masses and identical springs, must be ruled out, since it is easily proven that it cannot coherently transfer a pulse between its ends [4]. Indeed, only if the frequencies of the normal modes involved in the dynamics had a greatest common divisor, i.e., they were integer multiples of a finite frequency $\delta\omega \equiv \pi/T$, then after a time $2T$ the system would be exactly back to the initial configuration and (provided the chain be mirror symmetric) at T the initial pulse would be found at the opposite end. The uniform chain does not possess the above requisite, because its frequencies $\omega_n \propto \sin(cn)$, with c constant and n integer,

cannot have a common divisor: An initial pulse would undergo dispersion giving rise to a seemingly chaotic dynamics.

In order to achieve dispersionless pulse transmission, most studies have been considering nonlinear chains: A uniform array with suitable anharmonic terms can indeed support the propagation of localized wave packets, sometimes dubbed *breathers* [4–6]. However, the goal of coherent transmission can be attained without invoking nonlinearity but rather allowing for a slight modification from uniformity. An optimal choice of the two masses and of the spring between them at both chain ends results in an almost-coherent dynamics, with the initial pulse traveling along the uniform bulk of the chain and reconstructing itself with high fidelity at the opposite end, thereafter bouncing back and forth many times, just as the Newton cradle does, with the difference that propagation along the chain takes a finite time, proportional to its length. The optimal masses and spring values depend on N , but, remarkably, the transmission quality is almost independent of N : Beyond $N \sim 60$ it even improves for increasing N . For $N \rightarrow \infty$ the optimized parameters can be studied analytically, showing that the amplitude loss on transmission tends to 1.28%, a result confirmed by a numerical approach, necessary for finite N . Among many experimental papers, Ref. [7] considers a setup, involving an ion chain which is kicked at one end, that is quite similar to the model studied here. In this experiment it appears that the chain is well isolated from the environment, so that friction can be assumed to be negligible.

The classical spring-mass chain can be realized in alternative ways, such as a sequence of bars or disks connected by torsion wires, or an electrical circuit with capacitors and inductances, where the role of the masses is played by the moments of inertia or by the inductances, respectively.

In Sec. II the spring-mass chain model is presented and described in terms of dimensionless parameters; the *transmission amplitude* is introduced as the relevant quality factor, which can be maximized to 100% in the analytically solvable cases with $N \leq 5$. A general analytical approach to the normal modes

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Since these physical parameters have to be positive, the possible values of the variables have constraints:

$$\begin{aligned} 0 < y < \sqrt{2}, \quad x > 0, \\ z \leq z_0 \equiv 2 - \frac{x^2}{2-y^2}. \end{aligned} \quad (10)$$

Note that if $x^2 > 2(2-y^2)$, then z has to be negative. When $z = z_0$ the chain-wall elastic constant K_{01} vanishes and the chain is *isolated* or *free*. In order that all elastic constants be equal, it is necessary that $y = 1$ and that $z = 2(1-x^2)$.

The chain has two different *uniform limits*, both with equal masses and equal internal elastic constants:

$$\begin{aligned} (x, y, z) &= (1, 1, 1) \quad \text{uniform free (uf),} \\ (x, y, z) &= (1, 1, 0) \quad \text{uniform bounded (ub),} \end{aligned}$$

namely, the chain without or with the spring connecting to the external walls, $K_{01} = 0$ or 1 ; in the first case the chain has to have a zero-frequency (Goldstone) mode.

Let $\mathbf{U} = \{U_{ni}\}$ be the orthogonal matrix that diagonalizes \mathbf{A} (and, of course, also $\mathbf{B} = 2 - \mathbf{A}$),

$$\sum_{ij} U_{ni} A_{ij} U_{mj} = \lambda_n \delta_{nm}. \quad (11)$$

Then, the diagonal form of the Hamiltonian (2) reads

$$\mathcal{H} = \frac{1}{2} \sum_{n=1}^N (p_n^2 + \omega_n^2 q_n^2), \quad (12)$$

with the eigenfrequencies

$$\omega_n = \sqrt{2 - \lambda_n} \quad (13)$$

and the normal-mode coordinates and momenta

$$q_n = \sum_{i=1}^N U_{ni} q_i, \quad p_n = \sum_{i=1}^N U_{ni} p_i. \quad (14)$$

For given initial conditions $\mathbf{q}(0) = \mathbf{x}$ and $\dot{\mathbf{q}}(0) = \mathbf{v}$, the chain dynamics is a superposition of the motions of the normal modes,

$$q_i(t) = \sum_{n=1}^N U_{ni} \left(x_n \cos \omega_n t + \frac{v_n}{\omega_n} \sin \omega_n t \right), \quad (15)$$

where x_n and v_n are the normal-mode initial values obtained as in Eq. (14).

B. Transmission amplitude

The goal is to start from a static configuration where only the first mass is displaced, $\mathbf{q}(0) = (x_1, 0, 0, \dots, 0)$, and to look for values of the chain parameters (9) such that the dynamics leads in a certain time t^* as close as possible to the mirror-symmetric configuration $\mathbf{q}(t^*) = (0, 0, 0, \dots, x_1)$. With these initial conditions Eq. (15) becomes

$$q_i(t) = x_1 \sum_{n=1}^N U_{ni} U_{n1} \cos \omega_n t. \quad (16)$$

Now, one can use an interesting property [10] arising from the mirror symmetry of the matrix \mathbf{A} : Assuming that the

eigenvalues $\{\lambda_1, \lambda_2, \dots, \lambda_N\}$ are chosen in decreasing order [11], it tells that $U_{nN} = (-)^{n-1} U_{n1} = U_{n1} \cos[\pi(n-1)]$. This gives, for the last mass in the array,

$$q_N(t) = x_1 \alpha_N(t), \quad (17)$$

where the *transmission amplitude*

$$\alpha_N(t) \equiv \sum_{n=1}^N \mathcal{P}_n \cos[\pi(n-1) - \omega_n t] \quad (18)$$

has been defined. The positive numbers

$$\mathcal{P}_n \equiv U_{n1}^2, \quad (19)$$

satisfying $\sum_n \mathcal{P}_n = 1$ by the orthogonality of \mathbf{U} , can be considered a probability distribution that can be dubbed the *mode density*, since they weigh the contribution to $\alpha_N(t)$ from each normal mode. The transmission amplitude has the form of the average over the mode density of time-dependent phase factors. The difference $\delta_N(t) = 1 - \alpha_N(t)$ will be dubbed the *transmission loss*. Zero loss corresponds to perfect transmission and can only occur at some time instant t^* if all phases are coherent, i.e., they are equal or differ by integer multiples of 2π . For instance, if the eigenfrequencies were equally spaced, say, $\omega_n = \delta\omega(n-1)$, one would have

$$\alpha_N(t) = \sum_{n=1}^N \mathcal{P}_n \cos[(n-1)(\pi - \delta\omega t)], \quad (20)$$

and at the time $t^* = \pi/\delta\omega$ (and odd multiples of it) there would be perfect response, $\alpha_N(t^*) = 1$, i.e., the starting elongation would be fully reproduced at the time t^* in the opposite end of the chain. Such ideal behavior is, however, almost impossible in any discrete array, as the frequencies are not equally spaced and the normal modes will not superpose coherently: This is the phenomenon of *dispersion*. Nevertheless, the parameters (x, y, z) can be tuned in such a way as to get $\alpha_N(t_N^*)$ quite close to 1 at some time t_N^* , as it will be shown in the following. In this regime the overall dynamics described by Eq. (16) appears as the formation of a localized wave packet that travels at constant velocity along the chain and gives rise to the elongation of the last mass; in the further evolution the wave packet comes back to the first mass, and so on, like in a Newton cradle.

One can also imagine a different initial situation, starting from the equilibrium configuration $\mathbf{q}(0) = \mathbf{0}$, but with a momentum given to the first mass, e.g., by an instantaneous collision, so that $\dot{\mathbf{q}}(0) = (v_1, 0, \dots, 0)$, which is the case experimentally studied in Ref. [7]. The dynamics is wanted to lead to $\dot{\mathbf{q}}(t^*) = (0, \dots, 0, v_1)$, meaning that the same momentum is present at the opposite end. In this case, Eq. (15) yields

$$\dot{q}_i(t) = v_1 \sum_{n=1}^N U_{ni} U_{n1} \cos \omega_n t, \quad (21)$$

and it follows that the relevant ratio $\dot{q}_N(t)/v_1 = \alpha_N(t)$ between the transmitted and the initial momentum is given by the same transmission amplitude (18).

If the chain is free, $K_{01} = 0$, then by momentum conservation the chain's center of mass uniformly translates with velocity $V = P_1/M$, with $M = \sum_i m_i$ and $P_1 = v_1 \sqrt{m_1}$;

if transmission is perfect, then the elastic energy is again zero at time t^* , so all spacings must be preserved, and the final configuration is shifted by $\delta Q = Vt^*$. In Eq. (15) this translation is accounted for by the zero-frequency mode.

Figure 1 shows a possible realization of a mass-spring cradle, involving two auxiliary masses that periodically transmit and receive momentum by hard-sphere collision with the chain extrema; the mass on the right is a distance δQ apart. In the case of $N=4$ masses transmission can be perfect, as shown in the next subsection. The following sections are devoted to the maximization of the transmission amplitude (18) by optimizing the values of the parameters (x, y, z) . These optimal values correspond to the extremal masses and springs that yield almost-perfect transmission also for large N .

C. Perfect transmission for small N

Within the model (8) the chain can yield ideal transmission if the masses are less than five. Indeed, for isolated chains ($K_{01} = 0$) with three or four masses the free parameters can be set such as to yield equally spaced frequencies [12]. The same result can be obtained for $N=5$ by allowing for a third free parameter, i.e., releasing the constraint $A_{22} = 0$, equivalent to the second of the relations (9). Longer chains can be made “perfect” by allowing for more parameters: Of course, such “engineered” chains are not uniform. Note that for perfect chains any initial configuration evolves to itself after the period $2\pi/\delta\omega$, where $\delta\omega$ is the frequency spacing; if the chain is mirror symmetric, then after a half period $\pi/\delta\omega$ the perfectly reflected configuration is attained.

For $N=3$ the three masses are $(m_1, 1, m_1)$ and the two spring constants are $(1, 1)$; there is only one adjustable parameter, m_1 . The interaction matrix is

$$\mathbf{B} = \begin{bmatrix} x^2 & -x & 0 \\ -x & 2 & -x \\ 0 & -x & x^2 \end{bmatrix}, \quad (22)$$

with $x = m_1^{-1/2}$ corresponding to the notation (9) with $y=1$. The eigenvalues of \mathbf{B} are solutions of

$$\det(\mu - \mathbf{B}) = \mu(\mu - x^2)(\mu - 2 - x^2) = 0, \quad (23)$$

so the eigenvalues are $\mu_1 = 0$, $\mu_2 = x^2$, $\mu_3 = 2 + x^2$, and the eigenfrequencies $\omega_n = \sqrt{\mu_n}$ are equally spaced if $\omega_3 = 2\omega_2$, i.e., $2 + x^2 = 4x^2$, that has the solution $x^2 = 2/3$. So three masses with two identical springs show perfect transmission when

$$m_1 = x^{-2} = \frac{3}{2}, \quad (24)$$

namely the mass sequence is $\propto (3, 2, 3)$. The frequency spacing is $\omega_1 = \sqrt{2/3}$ and the arrival time is $t_3 = \pi/\omega_1 = \sqrt{3/2}\pi \simeq 3.848$.

For $N=4$ the sequence of masses is (m_1, m_2, m_2, m_1) , connected by the spring constants $(K_{12}, 1, K_{12})$, so the interaction matrix is

$$\mathbf{B} = \begin{bmatrix} w & -x & 0 & 0 \\ -x & 2 & -y^2 & 0 \\ 0 & -y^2 & 2 & -x \\ 0 & 0 & -x & w \end{bmatrix}, \quad (25)$$

where $w \equiv x^2/(2-y^2)$; it is convenient to set $r \equiv 2-y^2$, so $x^2 = wr$. The secular equation, $0 = \det(\lambda - \mathbf{B})$, is easily worked out and reads

$$0 = [(\mu-w)(\mu-2) - x^2]^2 - (\mu-w)^2 y^4 \\ = \mu[\mu - (w+r)][\mu^2 - \mu(w+4-r) + 2w(2-r)]; \quad (26)$$

the eigenvalues of \mathbf{B} are given, in the increasing order $\mu_1 < \mu_2 < \mu_3 < \mu_4$, by

$$\begin{aligned} \mu_1 &= 0 & \mu_2 + \mu_4 &= w+4-r \\ \mu_3 &= w+r & \mu_2 \mu_4 &= 2w(2-r). \end{aligned} \quad (27)$$

In order that the frequencies $\omega_n = \sqrt{\mu_n}$ be equally spaced one has to require $\mu_n = (n-1)^2 \mu_2$, giving

$$\mu_4 + \mu_2 = \frac{5}{2} \mu_3, \quad \mu_4 \mu_2 = \frac{9}{16} \mu_3^2, \quad (28)$$

which in terms of the parameters r and w reduce to the linear system

$$3w + 7r = 8, \quad 2w + r = 2. \quad (29)$$

The solution is $r = 10/11$ and $w = 6/11$, hence $y^2 = 12/11$ and $x = \sqrt{60}/11$, so the 4-mass perfectly transmitting chain must have

$$m_1 = \frac{55}{36}, \quad m_2 = \frac{11}{12}, \quad K_{12} = \frac{5}{6}. \quad (30)$$

Basically, the mass sequence has to be $\propto (5, 3, 3, 5)$ and the spring sequence $\propto (5, 6, 5)$. The frequency spacing is $\omega_1 = \sqrt{w+r}/2 = 2/\sqrt{11}$, which entails the arrival time $t_4 = \pi/\omega_1 = \sqrt{11}\pi/2 \simeq 5.210$.

Also for $N=5$ a perfect solution is known:

$$m_1 = \frac{35}{18}, \quad m_2 = \frac{10}{9}, \quad K_{12} = \frac{7}{9}. \quad (31)$$

It is reported in Ref. [12] without proof (here given in Appendix A); the frequencies are $\omega_n = (n-1)/\sqrt{5}$ for $n = 1, \dots, 5$, and entail the arrival time $t_5 = \sqrt{5}\pi \simeq 7.025$. However, this solution does not belong to the constrained model (8) considered in this paper in order to deal with the quasiuniform matrix (7).

III. ANALYTIC APPROACH

A. Characteristic polynomial and phase shifts

The N th-degree characteristic polynomial associated with the $N \times N$ matrix \mathbf{A} [Eq. (7)] is given by

$$\chi_N(\lambda; x, y, z) \equiv \det[\lambda - \mathbf{A}(x, y, z)]; \quad (32)$$

by expanding it in the last column, one finds

$$\chi_N = [(\lambda-z)\lambda - x^2]\xi_{N-2} - (\lambda-z)y^2\xi_{N-3}, \quad (33)$$

where ξ_N is the characteristic polynomial of the matrix with only one nonuniform endpoint,

$$\xi_N(\lambda; x, z) = \begin{vmatrix} \lambda - z & -x & & & & \\ -x & \lambda & -y & & & \\ & -y & \lambda & -1 & & \\ & & \ddots & \ddots & \ddots & \\ & & & -1 & \lambda & -1 \\ & & & & -1 & \lambda \end{vmatrix}_N. \quad (34)$$

The same kind of expansion in the first column gives a similar relation,

$$\xi_N = [(\lambda-z)\lambda - x^2]\eta_{N-2} - (\lambda-z)y^2\eta_{N-3}, \quad (35)$$

in terms of the characteristic polynomials

$$\eta_N(\lambda) \equiv \chi_N(\lambda; 1, 1, 0) \quad (36)$$

of the fully uniform matrices $A_N(1, 1, 0)$, which correspond to the uniform-bounded chain. These polynomials are well known in the literature, as their roots can be obtained in a simple way: By column expansion one has the recursion relation

$$\eta_N = \lambda \eta_{N-1} - \eta_{N-2}, \quad (37)$$

which, using the initial conditions $\eta_0 = 1$ and $\eta_1 = \lambda$, can be solved in terms of Chebyshev polynomials of the second kind: Using, in the place of λ , the real variable $k \in [0, \pi]$ given by

$$\lambda \equiv 2 \cos k = e^{ik} + e^{-ik} \quad (38)$$

they can be synthetically expressed as

$$\eta_N(\lambda) = \frac{\sin(N+1)k}{\sin k} = \frac{\text{Im}\{e^{i(N+1)k}\}}{\sin k}. \quad (39)$$

Hence, for the uniform-bounded chain, that has the secular equation $\eta_N(\lambda) = 0$, the N eigenvalues correspond to the following values of k :

$$k_n^{(\text{ub})} = \frac{\pi n}{N+1}, \quad (n = 1, \dots, N). \quad (40)$$

Note that, keeping the notation (38), in terms of the pseudo wave vector k the system frequencies (13) read

$$\omega_k = \sqrt{2 - 2 \cos k} = 2 \sin \frac{k}{2}. \quad (41)$$

For $k \ll 1$ (i.e., $n \ll N$) they are almost linear in k and equally spaced in n , i.e., $\omega_k \simeq k \propto n$, meaning that wave packets with main components in the small- k zone travel with low dispersion along the chain. This corresponds to the continuum limit, namely the elastic string.

In order to work out Eq. (33) one first uses Eq. (35)

$$\begin{aligned} \chi_N &= (\lambda^2 - z\lambda - x^2)[(\lambda^2 - z\lambda - x^2)\eta_{N-4} - (\lambda-z)y^2\eta_{N-5}] \\ &\quad - (\lambda-z)y^2[(\lambda^2 - z\lambda - x^2)\eta_{N-5} - (\lambda-z)y^2\eta_{N-6}], \end{aligned}$$

and then by Eq. (39),

$$\sin k \chi_N(k) = \text{Im}\{e^{i(N+1)k} u_k^2\}, \quad (42)$$

where

$$u_k \equiv e^{-2ik} [(\lambda^2 - z\lambda - x^2) - (\lambda-z)y^2 e^{-ik}] \quad (43)$$

is a complex variable whose dependence on k can be made fully explicit using Eq. (38),

$$\begin{aligned} u_k &= 1 - z e^{-ik} + (2 - x^2 - y^2) e^{-2ik} \\ &\quad - z(1 - y^2) e^{-3ik} + (1 - y^2) e^{-4ik}. \end{aligned} \quad (44)$$

Equation (42) yields a compact expression of the secular equation, $\chi_N(k) = 0$. For instance, in the uniform-bounded case it is $u_k = 1$, so its solution (40) is immediate. Setting

$$u_k \equiv |u_k| e^{-i\varphi_k}, \quad (45)$$

the secular equation reads $\text{Im}\{e^{i[(N+1)k - 2\varphi_k]}\} = 0$, so that the eigenvalues $\lambda_n = 2 \cos k_n$ correspond to those values of $k = k_n$ such that $(N+1)k - 2\varphi_k = \pi n$ and are given as corrections to the uniform-bounded values, Eq. (40), due to the *phase shifts* φ_k ,

$$k_n = \frac{\pi n + 2\varphi_{k_n}}{N+1}, \quad (n = 1, \dots, N). \quad (46)$$

By the way, this determines the sign of the real quantity in braces in Eq. (42),

$$e^{i(N+1)k_n} u_{k_n}^2 = e^{i\pi n} |u_{k_n}|^2 = (-)^n |u_{k_n}|^2. \quad (47)$$

Note that there is a one-to-one correspondence between the N allowed values $\{k_n\}$ and the indices $n = 1, \dots, N$, so it is unambiguous to use the index k in the place of n , as mostly done in the following.

B. The mode density has to be peaked at $k = 0$

The mode density (19) is calculated in Appendix B, where it is shown that a compact expression can be worked out, namely:

$$\mathcal{P}_k = \frac{2x^2 y^2 \sin^2 k}{(N+1 - 2\varphi'_k) |u_k|^2}. \quad (48)$$

In the uniform-bounded limit, where $u_k \rightarrow 1$ and $\varphi_k \rightarrow 0$, this agrees with the known result.

After the discussion of Sec. II B, it is clear that a high transmission amplitude can be obtained only if the normal modes selected by \mathcal{P}_k , lie in a zone where the frequencies (41) are almost equally spaced. This happens in the “linear region” around $k = 0$, meaning that the parameters (x, y, z) have to be chosen such that \mathcal{P}_k be peaked around $k = 0$. Due to the sine function in Eq. (48), for $\mathcal{P}_{k=0}$ to be at least finite it must be $u_{k=0} = 0$, i.e.,

$$1 - z + (2 - x^2 - y^2) - z(1 - y^2) + (1 - y^2) = 0. \quad (49)$$

To satisfy this it is natural to keep x and y as free parameters, while fixing the value of z ,

$$z(x, y) \equiv 2 - \frac{x^2}{2 - y^2}. \quad (50)$$

(That the second of Eqs. (9) tells that this implies $K_{01} = 0$: The chain ends do not interact with the walls. In other words, it has been found that a requisite for coherent pulse propagation is that the spring-mass chain be isolated. From now on the condition (50) is assumed to hold.

As (44) shows that u_k is a polynomial in e^{-ik} , one can extract from u_k the factor $(1 - e^{-ik})$, obtaining

$$u_k = (1 - e^{-ik}) \tilde{u}_k \equiv 2 \sin \frac{k}{2} e^{-i(k-\pi)/2} \tilde{u}_k, \quad (51)$$

with

$$\tilde{u}_k \equiv 1 - (1-w)e^{-ik} - (1-w)(y^2 - 1)e^{-2ik} + (y^2 - 1)e^{-3ik}, \quad (52)$$

where the new parameter

$$w \equiv \frac{x^2}{2 - y^2}, \quad (53)$$

here introduced for brevity, will be useful in the following.

C. Phase shifts for the free chain

The case $x = y = 1$ with the choice (50) is to be understood as the uniform-free limit, since $z(1, 1) = 1$. This means that $\tilde{u}_k = 1$ and Eq. (51) tells that the phase shifts (45) are $\varphi_k = (k - \pi)/2$. From Eq. (46) the allowed values of k take the equally spaced values

$$k_n^{(\text{uf})} = \frac{\pi(n-1)}{N}, \quad (n = 1, \dots, N); \quad (54)$$

these include the Goldstone mode $k_1 = 0$ with frequency $\omega_1 = 0$, i.e., the translation mode expected for the isolated chain. As observed in the previous subsection, being $\omega_k \simeq k$ for $k \ll 1$, a situation close to that of perfect transmission, Eq. (20), would arise if the mode density selected only low- k modes: Indeed, in Eq. (18) the phases would be

$$\pi(n-1) - 2t \sin k_n \simeq \frac{\pi(n-1)}{N} (N-t). \quad (55)$$

Actually this is not the case, since in the uniform-free case the density (48) is peaked in zero, indeed, but consists in a too-broad distribution [13],

$$\mathcal{P}_k^{(\text{uf})} = \frac{2}{N} \cos^2 \frac{k}{2}; \quad (56)$$

the purpose is to vary the parameters x and y in such a way to deform this density and make it narrower; however, shrinking \mathcal{P}_k too much would definitely be disadvantageous, because the phase shifts change with x and y and the spacings between eigenvalues are deformed by Eq. (46). Therefore, one expects that an optimal compromise will maximize the transmission amplitude at some arrival time.

The phase ψ_k of

$$\tilde{u}_k = |\tilde{u}_k| e^{i\psi_k} \quad (57)$$

turns out to give the phase-shift correction to the uniform-free solution (54): Indeed, Eq. (51) gives $\psi_k \equiv (k - \pi)/2 - \varphi_k$, and Eq. (46) becomes

$$k_n = \frac{\pi(n-1) - 2\psi_{k_n}}{N}, \quad (n = 1, \dots, N). \quad (58)$$

The Goldstone mode $k_1 = 0$ is preserved, since $\tilde{u}_{k=0}$ is real and the corresponding phase shift vanishes, $\psi_{k_1} = 0$.

In the following it will appear to be useful to define, besides the variable w , Eq. (53), a further variable r ,

$$\begin{cases} r \equiv 2 - y^2 \\ w \equiv x^2/r \end{cases} \iff \begin{cases} y^2 = 2 - r \\ x^2 = r w \end{cases}, \quad (59)$$

so that w and r can be used in the place of x and y ; indeed, it will be proven later that the optimal values of both r and w decrease as a negative power of N . Note that the uniform limit corresponds to $r = w = 1$. In Appendix C the dependence of the mode density on w and r is worked out and made explicit in Eq. (C9). By means of it and using the frequencies (41) the transmission amplitude Eq. (18) is given by

$$\alpha_N(t) = \sum_{n=1}^N \mathcal{P}_{k_n} \cos \left[\pi(n-1) - 2t \sin \frac{k_n}{2} \right]. \quad (60)$$

where the discrete pseudo wave vectors $\{k_n\}$ are the solutions of Eq. (58). In the following sections these formulas are used

for setting up a numerical approach in order to calculate the optimal values of the parameters x^* and y^* which yield at some time t^* the maximum attainable transmission amplitude α^* . In addition the asymptotic behaviors in the limit of large N will be exactly derived.

IV. OPTIMIZING ONE MASS

In this section the simpler case when $y = 1$ (i.e., $r = 1$ and $w = x^2$) is considered, which, by Eqs. (9), corresponds to the mass-spring chain with all spring constants and all masses equal, except for the first and the last masses,

$$m_1 = m_N = \frac{1}{x^2}. \quad (61)$$

A. Mode density and phase shifts

Setting $r = 1$ and $w = x^2$ in Eq. (C9), the density becomes a pseudo-Lorentzian [13] peaked at $k = 0$,

$$\mathcal{P}_k = \frac{1}{N+2\psi'_k} \frac{\Delta(1+\Delta)}{\Delta^2 + \tan^2 \frac{k}{2}}, \quad (62)$$

with the parameter

$$\Delta \equiv \frac{x^2}{2-x^2} \quad (63)$$

characterizing the distribution width. A convenient expression for the phase shifts defined in Eq. (57) is found using Eq. (52),

$$\begin{aligned} \tilde{u}_k &\equiv |\tilde{u}_k| e^{i\psi_k} = 1 - (1-x^2)e^{-ik} \\ &= e^{-ik/2} [e^{ik/2} - (1-x^2)e^{-ik/2}] \\ &= e^{-ik/2} \left[x^2 \cos \frac{k}{2} + i(2-x^2) \sin \frac{k}{2} \right], \end{aligned} \quad (64)$$

so

$$\psi_k = \tan^{-1} \frac{\tan \frac{k}{2}}{\Delta} - \frac{k}{2}; \quad (65)$$

inserting in Eq. (58) the set $\{k_n\}$ corresponding to the normal modes is obtained. Note that ψ_k increases with k , which means that the k_n 's ($n > 1$) get a negative correction with respect to the free case and the frequency spacings decrease. Taking the derivative of ψ_k ,

$$2\psi'_k = (1-\Delta) \frac{\Delta - \tan^2 \frac{k}{2}}{\Delta^2 + \tan^2 \frac{k}{2}}, \quad (66)$$

the mode density can be written in fully explicit way,

$$\mathcal{P}_k = \frac{\Delta(1+\Delta)}{(N\Delta+1-\Delta)\Delta + (N-1+\Delta)\tan^2 \frac{k}{2}}. \quad (67)$$

Its exact normalization is a nontrivial outcome that can be numerically verified, while for $N \rightarrow \infty$ this agrees with an analytic result [14].

B. Frequency spacings and group velocity

From the expression of \mathcal{P}_k obtained above, the purpose of making \mathcal{P}_k narrower can be easily achieved by decreasing Δ , namely choosing m_1 larger than the other masses. However, as mentioned in Sec. III C, this also affects the phase shifts ψ_k and

the spacings between frequencies. In order to appreciate this effect, one is led to look at (an analog of) the group velocity (lattice spacings per time unit),

$$v_k = \frac{N}{\pi} \partial_n \omega = \frac{N}{\pi} \cos \frac{k}{2} \partial_n k, \quad (68)$$

which is indeed proportional to the spacing between subsequent values ω_n : The more constant is v_k , the more likely is that the initial pulse propagate coherently. In order to highlight the full dependence of v_k on k , note that from (58) one has $(N+2\psi'_k) \partial_n k = \pi$, so

$$v_k = \frac{N}{N+2\psi'_k} \cos \frac{k}{2}. \quad (69)$$

This expression suggests a strategy to improve the transmission, since one could make v_k flatter by a proper choice of a small Δ ; then, Eq. (66) can be expanded,

$$2\psi'_k = \frac{1-\Delta}{\Delta} - \frac{1-\Delta^2}{4\Delta^3} k^2 + O(k^4), \quad (70)$$

and also the group velocity

$$v_k = \frac{N}{t^*} \frac{1 - \frac{1}{8}k^2}{1 - \frac{1-\Delta^2}{4\Delta^3 t^*} k^2} + O(k^4). \quad (71)$$

Here

$$t^* \equiv N + \frac{1-\Delta}{\Delta} \quad (72)$$

represents the end-to-end arrival time: Indeed, an excitation traveling with the velocity $v_{k=0} = N/t^*$ would cover the distance of N lattice spacings in a time t^* ; in the uniform limit $v_0 = 1$ and $t^* = N$: The correction to this value is the *delay* and is positive since $\Delta < 1$. To make v_k flat, an obvious choice is to cancel all quadratic terms in k imposing for Δ the condition

$$\frac{1-\Delta^2}{4\Delta^3 t^*} = \frac{1}{8}. \quad (73)$$

This choice makes the group velocity almost constant in a rather wide k -interval, but such a criterion could work only if the involved modes, as weighted by \mathcal{P}_k , mainly lie in this flat region. The first panel of Fig. 2 ($N = 50$) shows that this is not the case: While v_k becomes particularly flat for the value that satisfies Eq. (73), $\Delta \simeq 0.30$, still the width of \mathcal{P}_k is too large and involves many modes with different group velocities. Therefore, a sharper distribution must perform better, in spite of the more deformed group velocity. Figure 2 illustrates the conflict between the two effects, shrinking of \mathcal{P}_k and deformation of v_k . What is to be learned here is that one would like to optimize two effects, which is hard when having only one free parameter: Two free parameters are expected to yield better results, as is shown in Sec. V. In any case, Eq. (73) yields the large- N behavior

$$\Delta \sim 2^{1/3} N^{-1/3}, \quad x \sim 2^{2/3} N^{-1/6}, \quad (74)$$

a scaling that turns out to be correct, though with different prefactors.

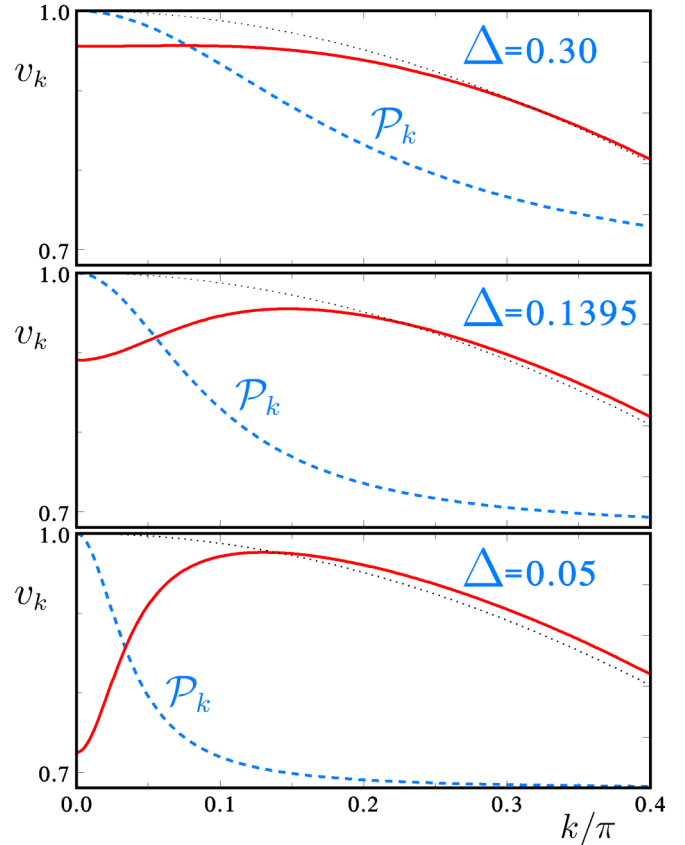


FIG. 2. The group velocity v_k (red solid line) and the mode density \mathcal{P}_k (blue dashed lines, arbitrary units) for a chain of 50 masses. The three panels correspond to $\Delta = 0.30, 0.1395$, and 0.05 . For the uniform chain ($\Delta = 1$) v_k (dotted line) is initially flat and small- k modes are almost coherent. Decreasing Δ selects low- k modes but also deforms v_k , destroying coherence. The middle panel shows the optimal compromise given in Table I.

C. Transmission amplitude for large N

The transmission amplitude at the time t is given by Eq. (18); using the frequencies (41), in the large- N limit one can write the sum as an integral,

$$\alpha_\infty(t) = \lim_{N \rightarrow \infty} \int_1^N dn \mathcal{P}_{k_n} \cos \left[\pi(n-1) - 2t \sin \frac{k_n}{2} \right], \quad (75)$$

with k_n given by Eq. (58), which implies

$$\pi dn = (N + 2\psi'_k) dk, \quad (76)$$

so that

$$\alpha_\infty(t) = \lim_{N \rightarrow \infty} \int_0^\pi \frac{dk}{\pi} \frac{\Delta(1+\Delta)}{\Delta^2 + \tan^2 \frac{k}{2}} \cos \left(Nk + 2\psi_k - 2t \sin \frac{k}{2} \right). \quad (77)$$

Writing the arrival time as $t = N + s$, where s is the *arrival delay*, and setting $k = 2q$,

$$\alpha_\infty(s) = \frac{2\Delta(1+\Delta)}{\pi} \int_0^{\pi/2} dq \frac{\cos\{2[t(q - \sin q) - sq + \psi_{2q}]\}}{\Delta^2 + \tan^2 q}. \quad (78)$$

TABLE I. Quasiuniform chain: Numerical optimization of the only extremal masses $m_1 = m_N$, considered in Sec. IV. For different N the reported quantities are the optimal parameter x^* that minimizes the transmission loss $\delta^*(x) \equiv 1 - \alpha^*(x)$, the corresponding time delay $s^* \equiv t^* - N$, mass m_1^* , and width parameter Δ^* . For comparison, the last column reports the transmission loss for the fully uniform chain, i.e., for $x = 1$. Note that for $N = 3$ the outcome agrees with the perfect transmission analytically found in Sec. IIC.

N	x^*	$\delta^*(x^*)$	$s^*(x^*)$	m_1^*	Δ^*	$\delta^*(1)$
3	0.8165	0.0000	0.85	1.500	0.5000	0.0292
4	0.7731	0.0041	1.08	1.673	0.4261	0.0608
5	0.7414	0.0083	1.28	1.819	0.3790	0.0900
6	0.7171	0.0123	1.44	1.945	0.3461	0.1161
7	0.6975	0.0160	1.58	2.056	0.3214	0.1395
8	0.6811	0.0193	1.71	2.156	0.3020	0.1606
9	0.6670	0.0223	1.83	2.248	0.2861	0.1796
10	0.6548	0.0251	1.94	2.333	0.2728	0.1969
12	0.6341	0.0299	2.13	2.487	0.2517	0.2274
14	0.6173	0.0341	2.31	2.625	0.2353	0.2535
16	0.6031	0.0377	2.46	2.750	0.2223	0.2762
18	0.5908	0.0409	2.61	2.865	0.2114	0.2962
20	0.5801	0.0437	2.74	2.972	0.2023	0.3141
25	0.5580	0.0496	3.04	3.212	0.1844	0.3516
30	0.5406	0.0544	3.30	3.421	0.1711	0.3817
35	0.5263	0.0583	3.54	3.610	0.1608	0.4067
40	0.5143	0.0617	3.75	3.781	0.1524	0.4280
45	0.5039	0.0646	3.94	3.938	0.1454	0.4464
50	0.4948	0.0671	4.12	4.085	0.1395	0.4626
60	0.4794	0.0714	4.45	4.352	0.1298	0.4898
70	0.4667	0.0749	4.75	4.590	0.1222	0.5122
80	0.4561	0.0778	5.01	4.808	0.1161	0.5310
90	0.4469	0.0804	5.26	5.008	0.1109	0.5471
100	0.4388	0.0826	5.49	5.194	0.1065	0.5612
150	0.4090	0.0906	6.45	5.977	0.09129	0.6121
200	0.3892	0.0958	7.21	6.602	0.08195	0.6452
250	0.3745	0.0996	7.86	7.130	0.07541	0.6692
300	0.3629	0.1026	8.42	7.593	0.07049	0.6877
350	0.3534	0.1049	8.93	8.008	0.06660	0.7027
400	0.3454	0.1069	9.39	8.385	0.06342	0.7151
450	0.3384	0.1086	9.81	8.731	0.06074	0.7256
500	0.3323	0.1100	10.20	9.054	0.05845	0.7348
600	0.3221	0.1124	10.92	9.639	0.05471	0.7499
700	0.3137	0.1144	11.56	10.164	0.05174	0.7621
800	0.3066	0.1160	12.14	10.640	0.04931	0.7722
900	0.3004	0.1174	12.67	11.079	0.04727	0.7807
1000	0.2951	0.1186	13.17	11.486	0.04551	0.7881
2000	0.2621	0.1255	16.91	14.559	0.03556	0.8311
3000	0.2446	0.1289	19.53	16.717	0.03083	0.8522
4000	0.2329	0.1310	21.63	18.436	0.02788	0.8656
5000	0.2242	0.1326	23.39	19.889	0.02579	0.8752
10000	0.1994	0.1368	29.80	25.158	0.02028	0.9008
20000	0.1773	0.1401	37.88	31.804	0.01597	0.9212
30000	0.1656	0.1417	43.55	36.465	0.01390	0.9311
40000	0.1578	0.1428	48.06	40.180	0.01260	0.9374
50000	0.1520	0.1435	51.87	43.311	0.01168	0.9419
100000	0.1350	0.1455	65.76	54.870	0.00920	0.9539
500000	0.1032	0.1486	113.3	93.895	0.00535	0.9730
$N \rightarrow \infty$	$0.9173 N^{-\frac{1}{6}}$	0.1531	$1.444 N^{\frac{1}{3}}$	$1.188 N^{\frac{1}{3}}$	$0.4207 N^{-\frac{1}{3}}$	1.0000

As by increasing N the distribution gets narrower and narrower ($\Delta \sim N^{-1/3}$), it is convenient to make the substitution $q = \Delta \xi$ to an integration variable ξ of the order of unity and then expand in Δ keeping all leading terms:

$$\begin{aligned} 2t(q - \sin q) &\simeq \frac{1}{3} t \Delta^3 \xi^3, \\ \psi_{2q} &= \tan^{-1} \frac{\tan q}{\Delta} - q \simeq \tan^{-1} \xi, \\ \frac{\Delta dq}{\Delta^2 + \tan^2 q} &\simeq \frac{d\xi}{1 + \xi^2}. \end{aligned} \quad (79)$$

It is then natural to define rescaled counterparts of the arrival time $t \simeq N$ and of the delay $s \sim N^{1/3}$,

$$\tau \equiv \frac{\Delta^3}{3} t, \quad \sigma \equiv 2\Delta s. \quad (80)$$

Optimizing Δ is now converted into optimizing τ , i.e., the coefficient of the asymptotic scaling law for Δ vs. $t \simeq N$. The final asymptotic expression is

$$\alpha_\infty(\tau, \sigma) = \frac{2}{\pi} \int_0^\infty d\xi \frac{\cos(\tau \xi^3 - \sigma \xi + 2 \tan^{-1} \xi)}{1 + \xi^2}. \quad (81)$$

Using the variable $\zeta = \tan^{-1} \xi$, such that $d\xi = (1 + \xi^2)d\zeta$, the integral becomes a summation of phase factors,

$$\alpha_\infty(\tau, \sigma) = \frac{2}{\pi} \int_0^{\pi/2} d\zeta \cos(\tau \tan^3 \zeta - \sigma \tan \zeta + 2\zeta), \quad (82)$$

and it is evident that the largest amplitude corresponds to the parameters that minimize the phase, namely the argument of the cosine. The same integral appeared in a different context in Ref. [15], where it was evaluated numerically: The maximum attainable amplitude amounts to

$$\alpha_\infty^* = 0.846902 \quad (83)$$

and corresponds to $\sigma^* = 1.2152$ and $\tau^* = 0.02483$. From Eq. (80) it follows that

$$\Delta^* \simeq 0.4208 N^{-1/3}, \quad s^* \simeq 1.444 N^{1/3}; \quad (84)$$

hence, by Eqs. (63) and (61), the variable x and the corresponding extremal mass m_1 scale as

$$\begin{aligned} x^* &\simeq \sqrt{2\Delta} \simeq 0.9173 N^{-1/6} \\ m_1^* &= \frac{1}{x^2} \simeq 1.188 N^{1/3}. \end{aligned} \quad (85)$$

D. Numerical results for finite N

The numerical results have been obtained by a code that, for given N and x , first evaluates and stores the set $\{k_n\}$ from Eqs. (58) and (65) by an iterative algorithm and then uses the density (67) to compute the amplitude $\alpha(s, x)$, Eq. (60), at different time delays $s \equiv t - N$ finding the maximal $\alpha^*[s^*(x), x]$; then an outer loop varies x until finding the best among these maxima, $\alpha^*[s^*(x^*), x^*]$, so identifying the optimal x^* and related delay $s^*(x^*)$. The outcomes for a choice of finite values of N are reported in Table I and illustrated in Figs. 3, 4, and 5. There, the optimal amplitude loss $\delta^* = 1 - \alpha^*$, which tends to zero in the case of perfect transmission, is reported

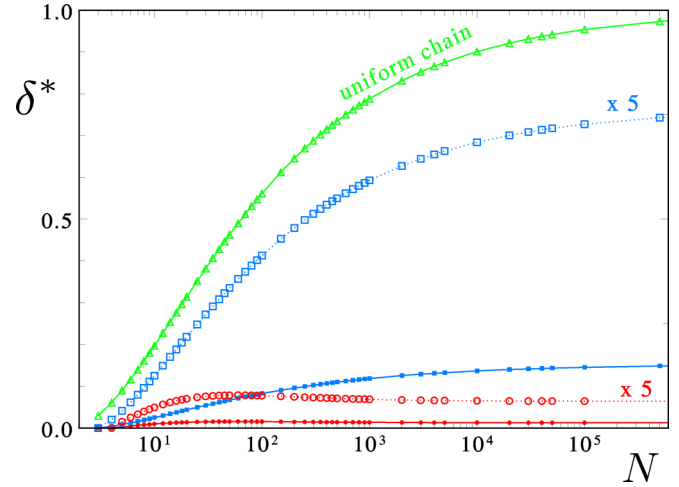


FIG. 3. Minimal transmission loss $\delta^* \equiv 1 - \alpha^*$ reported vs. N for the three cases: the uniform chain (green triangles), the chain with optimization of one mass m_1 (Sec. IV, blue squares), and that with optimization of two masses and their spring, m_1, m_2 , and K_{12} (Sec. V, red circles). The asymptotic limits are 1, 0.1531, and 0.01285, respectively. Open symbols are enlargements of the last two cases; the curves are splines. The fully uniform chain is evidently very dispersive, while the optimization of few parameters proves to enormously enhance the quality of transmission: Even in the limit of a (frictionless) infinite chain it is possible to efficiently transmit a pulse.

in the place of α^* : The loss increases with N and reaches the asymptotic value $\delta_\infty^* = 0.153098$ according to the above calculation. The last column of Table I is the amplitude loss for the fully uniform chain ($x = 1$), also shown in Fig. 3: It appears that the bare modulation of the extremal masses yields an enormous improvement for any N . For instance, in a 20-mass chain the loss can be reduced from 31% to 4.4%.

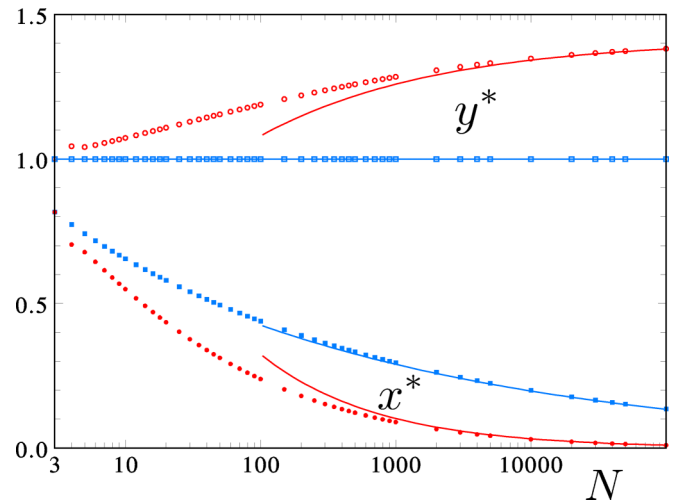


FIG. 4. Optimal parameters x^* and y^* , defined in Eqs. (9), reported vs. N in the case of Sec. IV, for which $y = 1$ is fixed (blue squares), and the case of Sec. V (red circles). The curves are the large- N asymptotics of Eqs. (85) and (101).

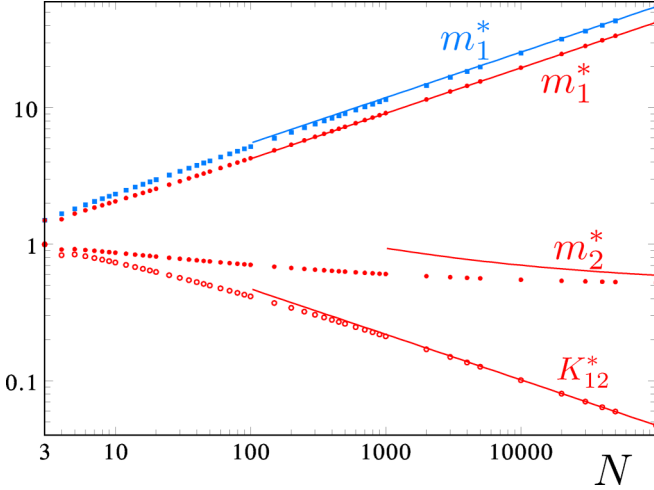


FIG. 5. Optimal mass- and spring parameters m_1^* , m_2^* , and K_{12}^* , defined in Eq. (1), are reported for the two cases, namely, the chain of Sec. IV, for which $m_2 = 1$ and $K_{12} = 1$ (blue squares) and that of Sec. V (red circles). The curves are the large- N asymptotics of Eqs. (85) and (102).

V. OPTIMIZING TWO MASSES AND THEIR SPRING

A. Transmission amplitude for large N

It will be justified at the end of this section that to attain maximal transmission, at least in the large- N limit, the denominator of the mode density (C9) must be quartic, namely of the type of Eq. (89) below. To satisfy this assumption one has to impose, between the parameters r and w , the following constraint:

$$r^2(2-w)^2 - 32(1-r)w = 0. \quad (86)$$

Looking for $w(r)$ satisfying Eq. (86), one finds

$$w = 2 \left(\frac{1 - \sqrt{1-r}}{1 + \sqrt{1-r}} \right)^2 = \frac{2}{r^2} (1 - \sqrt{1-r})^4, \quad (87)$$

the first expression being useful for the numerics, the second for expanding: For small r it gives $w = \frac{r^2}{8}(1+r+\dots)$ and the fact that $x^2 = rw \simeq r^3/8$ suggests that for large N the optimal values of r and $w(r)$ tend to zero. Accounting for the choice (86) one can simplify the denominator of the distribution (C9) and write it as

$$\mathcal{P}_k = \frac{1}{N+2\psi'_k} \times \frac{2(2-r)rw}{(2-r)^2 w^2 + 32(1-r)(w \tan^2 q + 2 \sin^2 q) \sin^2 q}, \quad (88)$$

where $w = w(r)$ as given as in Eq. (87) and $k = 2q$. This density can be expanded, taking into account Eq. (87), and the relevant terms are

$$\mathcal{P}_k \simeq \frac{1}{N} \frac{4r^3/8}{r^4/16 + 64q^4} \simeq \frac{\sqrt{2}}{N} \frac{\Delta^3}{\Delta^4 + q^4}, \quad (89)$$

where the half-width at half maximum is now defined as

$$\Delta \equiv \frac{r}{4\sqrt{2}}. \quad (90)$$

Proceeding as in Sec. IV C, the large- N transition amplitude can then be transformed into the integral

$$\alpha_\infty(t) = \frac{2\sqrt{2}\Delta^3}{\pi} \int_0^{\pi/2} dq \frac{\cos\{2[t(q - \sin q) - sq + \psi_{2q}]\}}{\Delta^4 + q^4}, \quad (91)$$

where again the arrival time is $t = N + s$, with the delay s . Note the qualitative difference represented by the quartic distribution. Expanding Eqs. (C1) gives $I_k \simeq kr$ and $R_k \simeq 2w - 2k^2$, so the asymptotic behavior of the phase shift (C2) is

$$\psi_{2q} \simeq \tan^{-1} \frac{2qr}{r^2/4 - 8q^2} \simeq \tan^{-1} \frac{\sqrt{2}\xi}{1 - \xi^2}, \quad (92)$$

which replaces the second of Eqs. (79) and here again $q = \Delta\xi$. Using the rescaled variables (80) gives

$$\alpha_\infty(t) = \frac{2\sqrt{2}}{\pi} \int_0^\infty d\xi \frac{\cos(\tau\xi^3 - \sigma\xi + 2 \tan^{-1} \frac{\sqrt{2}\xi}{1 - \xi^2})}{1 + \xi^4}. \quad (93)$$

It is again convenient, for the numerical evaluation, to perform the substitution $\xi = \tan \zeta$, so

$$\frac{2\xi}{1 - \xi^2} = \frac{2 \tan \zeta}{1 - \tan^2 \zeta} = \tan 2\zeta, \quad (94)$$

yielding

$$\alpha_\infty(\tau, \sigma) = \frac{2\sqrt{2}}{\pi} \int_0^{\pi/2} d\zeta \frac{1 + \tan^2 \zeta}{1 + \tan^4 \zeta} \cos \theta(\zeta) \quad (95)$$

$$\theta(\zeta) \equiv \tau \tan^3 \zeta - \sigma \tan \zeta + 2 \tan^{-1} \frac{\tan 2\zeta}{\sqrt{2}};$$

the same integral appears, though in a different context, in Ref. [8]. At variance with Eq. (82), this sum of phase factors $\cos(\theta(\zeta))$ is weighted by a prefactor that becomes small, $\sim (\tan \zeta)^{-2}$, in the region $\zeta \gtrsim \pi/4$ of large oscillations, so it is to be expected that larger values of α_∞ can be attained. In order to give an idea of the kind of integral one is dealing with, Fig. 6 reports the integrand of Eq. (95) for the values which eliminate first- and third-order terms of $\theta(\zeta)$, namely $\sigma = 2^{3/2}$ and $\tau = 2^{3/2}/3$, and for those values which yield the global maximum. The (algebraic) area below the curves is just $\alpha_\infty(\tau, \sigma)$. It is clear that the main point is in avoiding for as long as possible the onset of the rapid oscillations rather than setting the phase close to zero for small ζ . It turns out that for any fixed σ , $\alpha_\infty(\tau, \sigma)$ has a maximum, i.e., the loss $\delta_\infty(\tau, \sigma) = 1 - \alpha_\infty(\tau, \sigma)$ reported in Fig. 7 has a minimum at $\tau = \tau_m(\sigma)$. Repeating for different σ one can find that the overall minimum of $\delta_\infty[\sigma, \tau_m(\sigma)]$ is

$$\delta_\infty^* = 1 - \alpha_\infty^* = 0.012847, \quad (96)$$

corresponding to the asymptotic transmission amplitude

$$\alpha_\infty^* = 0.987153, \quad (97)$$

and occurs when

$$\sigma^* = 3.1645, \quad \tau^* \equiv \tau_m(\sigma^*) = 0.15545; \quad (98)$$

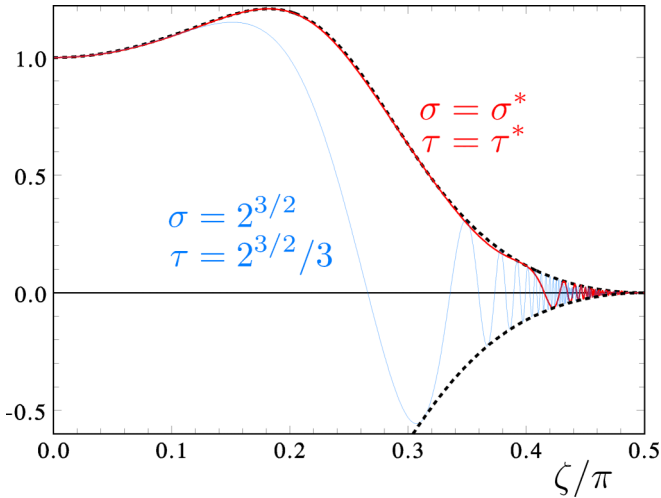


FIG. 6. Integrand of Eq. (95) for the parameter pair (τ, σ) that cancels the linear and cubic terms in the phase of Eq. (95) (blue, thin line) and that (red, thick line) which maximizes $\alpha_\infty(\sigma, \tau)$. The dashed curve is the weighting function.

as expected, using two adjustable parameters in the place of one strongly improved the transmission found in Sec. IVC. The scaling of Eq. (80) tells that asymptotically

$$\Delta^* \simeq 0.77548N^{-1/3}, \quad s^* \simeq 2.0403N^{1/3}. \quad (99)$$

The optimal values of the parameters r and w behave as

$$r^* \simeq 4.3868N^{-1/3}, \quad w^* \simeq 2.4055N^{-2/3}, \quad (100)$$

entailing that

$$x^* \simeq 3.2484N^{-1/2}, \quad y^* \simeq \sqrt{2} - 1.5510N^{-1/3}. \quad (101)$$

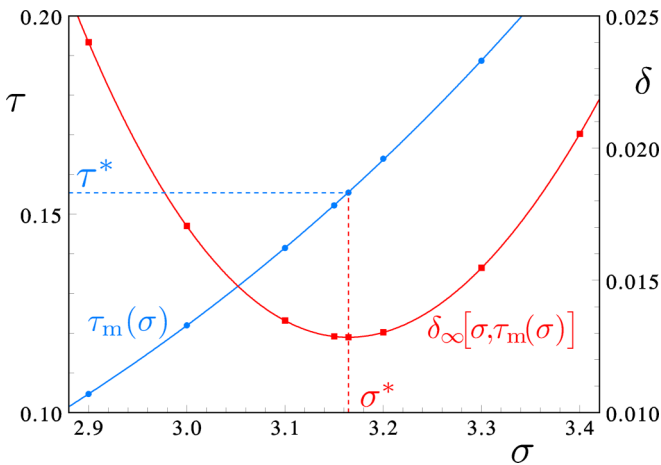


FIG. 7. Minimization of the asymptotic transmission loss $\delta_\infty(\sigma, \tau)$. First, for different σ 's one finds the values $\tau_m(\sigma)$ (blue line, left y axis) that minimize $\delta_\infty \equiv 1 - \alpha_\infty$ to the value $\delta_\infty[\sigma, \tau_m(\sigma)]$ (red line, right y axis); the latter has its global minimum for $\sigma = \sigma^*$.

For the optimal masses and spring, Eq. (9), one finds

$$\begin{aligned} m_1^* &= \frac{r}{(2-r)w} \simeq 0.9118N^{1/3} \\ m_2^* &= \frac{1}{2-r} \simeq \frac{1}{2} + 1.0967N^{-1/3} \\ K_{12}^* &= \frac{r}{2-r} \simeq 2.1934N^{-1/3}. \end{aligned} \quad (102)$$

Therefore, the best transmitting chain has a larger first mass, while the second is about one half the bulk ones, and the spring connecting them has to be weak, inversely proportional to m_1 . The above asymptotic behaviors are reported in Figs. 3–5.

Note that without the assumption (86) the density denominator would have a quadratic term and the dominant part, Eq. (89), would have the same form of the preceding section, leading to a similar asymptotic integral and to a much worse limit of the transmission amplitude: This justifies the elimination of the k^2 terms by means of the constraint (87), as also confirmed by the numerical results presented below.

B. Numerical results for finite N

The optimal values of r and w which maximize the transmission amplitude have been numerically evaluated for different values of N , as reported in Table II. Note that for each pair (r, w) the algorithm has first to evaluate the allowed k_n , which is done for each n by iterating Eq. (58) starting from the estimate $k_n = \pi(n-1)/N$ and using the expression (C2) for the shift ψ/k ; then, the maximum of $\alpha_n(t)$, Eq. (18), is found by scanning on the arrival delay $s = t - N$ and taking the maximal value $\alpha_n(N+s)$. By studying these values on the (r, w) plane (i.e., the numerical code contains three nested loops for s , w , and r , respectively) the optimized transmission maximum $\alpha^*(N+s^*)$ corresponding to the values r^* and w^* has been found. The numerical outcomes shown in Fig. 8 confirm the conjecture that w^* approaches, for large N , the value $w(r^*)$ which makes the mode density quartic. The corresponding transmission loss is reported in Fig. 3: At variance with the monotonic increase with N found in the preceding section, the transmission loss displays maximum $\delta^* \simeq 0.0157$ at about $N \simeq 60$, followed by a decrease towards the asymptotic value. The related parameters x^* and y^* , as well as those of the two masses and spring are shown in Figs. 4 and 5, respectively.

In Fig. 9 the shapes of the optimal mode density for $N = 20$ and $N = 100$ can be compared with the exact frequency spacings $\delta\omega_n = \omega_n - \omega_{n-1}$, explaining the basic mechanism of coherence: Lowering r shrinks the density involving smaller- k modes, but also deforms the frequency spacings, and there is a best compromise between the two effects. Note that $N\delta\omega_n/\pi$ corresponds to the “group velocity” (71), whose value for the uniform chain is reported as a dashed line.

VI. CONCLUSIONS

Highly efficient pulse transmission over a uniform discrete elastic system, modeled as a chain of N masses connected by springs, has been shown to be possible irrespective of N just by symmetrically modifying, at both chain ends, two masses and the spring between them. This result is far from trivial,

TABLE II. Quasiuniform chain: Numerical optimization of the two extremal masses, $m_1 = m_N$ and $m_2 = m_{N-1}$, and of the spring in between $K_{12} = K_{N-1,N}$, considered in Sec. V. For different N the reported quantities are the optimal parameters r^* and w^* which minimize the transmission loss $\delta^*(r, w) \equiv 1 - \alpha^*(r, w)$ and the associated time delay $s^* \equiv t^* - N$. The last three columns report the corresponding optimal masses and elastic constant, Eq. (102). Note that for $N = 3$ and $N = 4$ perfect transmission is found, in agreement with Sec. IIC.

N	r^*	w^*	$\delta^*(r^*, w^*)$	s^*	m_1^*	m_2^*	K_{12}^*
3	1.0000	0.6667	0.00000	0.85	1.500	1.0000	1.0000
4	0.9091	0.5455	0.00000	1.21	1.528	0.9167	0.8333
5	0.9151	0.5024	0.00304	1.40	1.679	0.9218	0.8435
6	0.9003	0.4610	0.00505	1.59	1.776	0.9093	0.8187
7	0.8853	0.4273	0.00664	1.77	1.859	0.8971	0.7942
8	0.8718	0.3996	0.00794	1.93	1.933	0.8863	0.7727
9	0.8595	0.3764	0.00902	2.08	2.002	0.8768	0.7536
10	0.8483	0.3565	0.00991	2.22	2.066	0.8683	0.7366
12	0.8285	0.3241	0.01130	2.47	2.182	0.8536	0.7073
14	0.8115	0.2986	0.01230	2.70	2.287	0.8414	0.6828
16	0.7965	0.2779	0.01305	2.91	2.382	0.8309	0.6619
18	0.7832	0.2606	0.01361	3.10	2.470	0.8218	0.6437
20	0.7713	0.2460	0.01405	3.28	2.552	0.8138	0.6277
25	0.7457	0.2173	0.01478	3.69	2.736	0.7973	0.5946
30	0.7248	0.1961	0.01519	4.04	2.898	0.7842	0.5684
35	0.7071	0.1797	0.01544	4.36	3.044	0.7735	0.5469
40	0.6917	0.1665	0.01559	4.65	3.176	0.7644	0.5288
45	0.6782	0.1555	0.01568	4.91	3.299	0.7566	0.5131
50	0.6661	0.1463	0.01572	5.16	3.413	0.7497	0.4994
60	0.6453	0.1316	0.01575	5.61	3.620	0.7382	0.4763
70	0.6277	0.1202	0.01572	6.02	3.805	0.7287	0.4574
80	0.6125	0.1111	0.01567	6.38	3.974	0.7207	0.4414
90	0.5992	0.1036	0.01561	6.72	4.130	0.7139	0.4277
100	0.5873	0.0972	0.01555	7.04	4.275	0.7079	0.4157
150	0.5421	0.0761	0.01524	8.36	4.883	0.6859	0.3718
200	0.5106	0.0639	0.01499	9.42	5.368	0.6714	0.3428
250	0.4866	0.0557	0.01479	10.31	5.778	0.6608	0.3215
300	0.4673	0.0497	0.01464	11.10	6.136	0.6525	0.3049
350	0.4513	0.0451	0.01451	11.80	6.457	0.6457	0.2914
400	0.4376	0.0415	0.01440	12.44	6.749	0.6400	0.2801
450	0.4257	0.0385	0.01431	13.03	7.018	0.6352	0.2704
500	0.4152	0.0361	0.01423	13.58	7.267	0.6310	0.2620
600	0.3973	0.0321	0.01410	14.57	7.720	0.6240	0.2479
700	0.3826	0.0291	0.01400	15.47	8.125	0.6183	0.2365
800	0.3700	0.0267	0.01392	16.28	8.493	0.6135	0.2270
900	0.3592	0.0248	0.01385	17.02	8.832	0.6095	0.2189
1000	0.3496	0.0232	0.01379	17.72	9.146	0.6059	0.2119
2000	0.2911	0.0148	0.01347	22.96	11.52	0.5852	0.1703
3000	0.2603	0.0114	0.01333	26.65	13.18	0.5748	0.1496
4000	0.2400	0.0094	0.01325	29.59	14.51	0.5682	0.1364
5000	0.2252	0.0081	0.01320	32.07	15.62	0.5634	0.1269
10000	0.1838	0.0051	0.01307	41.10	19.68	0.5506	0.1012
20000	0.1491	0.0032	0.01299	52.49	24.80	0.5403	0.0806
30000	0.1317	0.0025	0.01296	60.48	28.39	0.5352	0.0705
40000	0.1205	0.0021	0.01294	66.85	31.26	0.5321	0.0641
50000	0.1124	0.0018	0.01293	72.22	33.69	0.5298	0.0596
100000	0.0903	0.0011	0.01290	91.75	42.45	0.5236	0.0473
$N \rightarrow \infty$	$4.387 N^{-\frac{1}{3}}$	$2.406 N^{-\frac{2}{3}}$	0.01285	$2.040 N^{\frac{1}{3}}$	$0.9118 N^{\frac{1}{3}}$	$\frac{1}{2} + 2K_{12}$	$2.193 N^{-\frac{1}{3}}$

since the dynamics of such a chain is almost invariably affected by strong dispersion. The main point is in the analysis of the normal modes which are excited by the initial pulse: Their frequencies are made almost equally spaced, yielding coherent transmission, by suitably tuning two free parameters.

A pulse starting from an end of such an elastic chain can bounce back and forth several times before being “absorbed” by dispersion. This suggests the possibility of creating a mechanical toy similar but alternative to the Newton cradle, e.g., like that depicted in Fig. 1. Its behavior would be somewhat

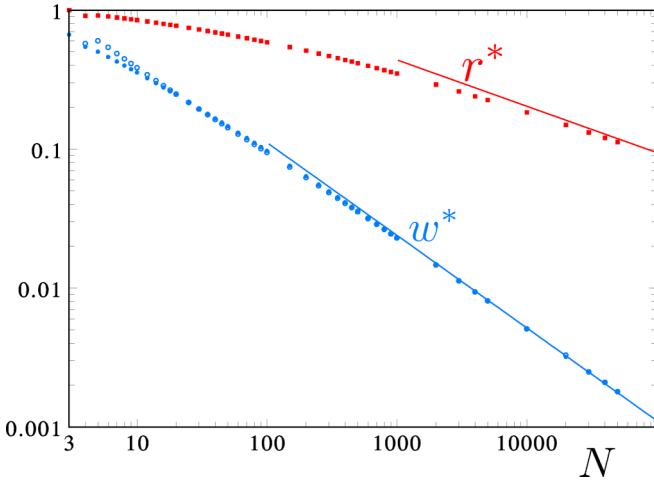


FIG. 8. Optimal parameters r^* (red squares) and w^* (blue circles) reported vs. N for the chain of Sec. V. The curves are the large- N asymptotics of Eq. (100). The open circles are the values of the function $w(r^*)$, Eq. (87): For $N \gtrsim 20$ they are almost indistinguishable from the optimal values w^* confirming that optimal transmission requires a quartic mode density.

bizarre due to the large duration of the bounces, of the order of $N\sqrt{m/K}$ (where m and K are the bulk masses and elastic constants), as it would work also for a long spring-mass chain.

The array of electric LC circuits depicted in Fig. 10 can also be described by the Hamiltonian (1), with capacitors and inductors replacing springs and masses, respectively, i.e., setting

$$K_{i,i+1} = C_{i,i+1}^{-1}, \quad m_i = L_i; \quad (103)$$

the role of the coordinate is played by the charge Q_i flowing in each loop yielding the current $I_i = \dot{Q}_i$. For instance, a current

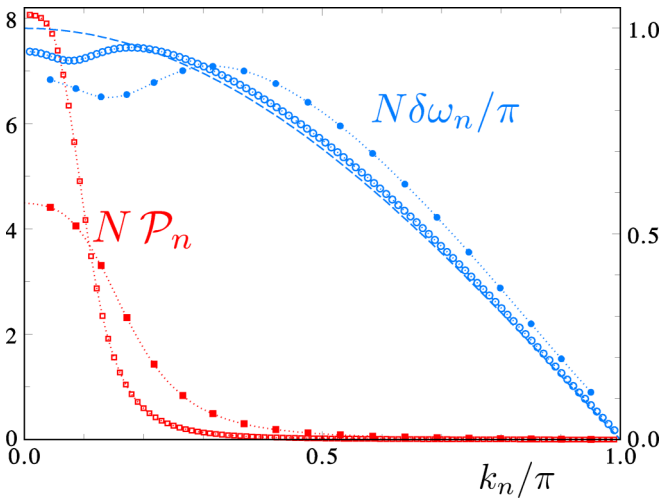


FIG. 9. Mode density \mathcal{P}_n (red squares, left y axis) and frequency spacing $\delta\omega_n = \omega_n - \omega_{n-1}$ (blue circles, right y axis) for $N = 20$ (filled symbols) and $N = 100$ (open symbols) in the optimized case with parameters (r^*, w^*) as in Table II. The dashed curve is the uniform-chain group velocity $v_k = \cos \frac{k}{2}$. Since the mode density has tiny tails, only modes with almost equally spaced frequencies are involved in the dynamics.

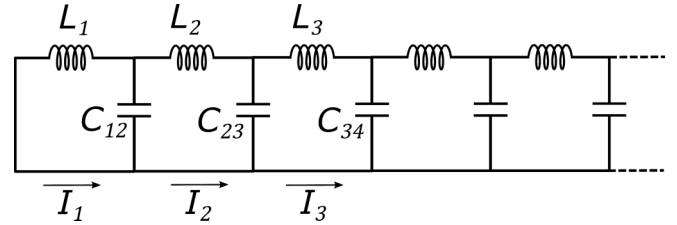


FIG. 10. The electric circuit equivalent to the spring-mass chain (1): Capacitances replace the elastic constants, $C_{i,i+1} \leftrightarrow K_{i,i+1}^{-1}$, and inductances replace the masses $L_i \leftrightarrow m_i$.

pulse given, e.g., by an external inductive coupling to L_1 , would travel back and forth through the electric array, provided the extremal inductances and capacitances are suitably tuned, while having the bulk uniform values L and C . The time scale is \sqrt{LC} and the end-to-end time travel is about N times larger.

Other, more useful, applications can exploit the capability of transferring a concentrated amount of energy between the chain ends; for instance, one can imagine a wall, constituted of an array of elastically coupled layers, that could efficiently transmit heat or sound. The same idea can be transferred to the nanoscale [16,17], for instance, to atomic chains [7] or multilayers. For instance, ballistic phonon transport could be engineered leading to different behavior, e.g., of the thermal conductance. Finally, it is a suggestive idea that the same simple mechanism be able to explain some features of energy transport in biological structures.

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APPENDIX A: PERFECT 5-MASS CHAIN

For $N = 5$ the interaction matrix (3) reads

$$\mathbf{B} = \begin{bmatrix} w & -x & 0 & 0 & 0 \\ -x & t & -y & 0 & 0 \\ 0 & -y & 2 & -y & 0 \\ 0 & 0 & -y & t & -x \\ 0 & 0 & 0 & -x & w \end{bmatrix}, \quad (A1)$$

where

$$w = \frac{K_{12}}{m_1}, \quad t = \frac{1 + K_{12}}{m_2}, \quad (A2)$$

$$x = \frac{K_{12}}{\sqrt{m_1 m_2}}, \quad y = \frac{1}{\sqrt{m_2}},$$

and one actually has three free parameters, since $w(t - y^2) = x^2$. This is more general than the model (8), which assumes $t = 2$. To proceed, it is convenient to set $r \equiv t - y^2$, so $x^2 = wr$. Calculated by expanding in the middle row or column, the determinant giving the secular equation is obtained in factorized form,

$$0 = \det(\mu - \mathbf{B}) = P(\mu) Q(\mu) \quad (A3)$$

with

$$\begin{aligned}
P(\mu) &= (\mu-w)(\mu-t) - x^2 \\
&= \mu^2 - (w+t)\mu + wy^2 \\
&\equiv (\mu - \mu_2)(\mu - \mu_4) \\
Q(\mu) &= (\mu-2)[(\mu-w)(\mu-t) - x^2] - 2(\mu-w)y^2 \\
&= \mu[\mu^2 - (w+t+2)\mu + wy^2 + 2(w+r)] \\
&\equiv \mu(\mu - \mu_3)(\mu - \mu_5); \tag{A4}
\end{aligned}$$

the eigenvalues $\{\mu_n, n = 1, \dots, 5\}$ are in increasing order, and to obtain equally spaced frequencies $\omega_n = \sqrt{\mu_n}$ one imposes $\mu_n = (n-1)^2 u$, which entails

$$\begin{cases} \mu_2 + \mu_4 = 10u = w + t \\ \mu_3 + \mu_5 = 20u = w + t + 2 \end{cases} \implies \begin{cases} u = \frac{1}{5} \\ w + t = 2 \end{cases}. \tag{A5}$$

and also

$$\begin{cases} \mu_2\mu_4 = 9u^2 = wy^2 \\ \mu_3\mu_5 = 64u^2 = wy^2 + 2(w+r) \end{cases} \implies \begin{cases} wy^2 = \frac{9}{25} \\ w + r = \frac{11}{10} \end{cases}. \tag{A6}$$

It is then straightforward to obtain

$$w = \frac{2}{5}, \quad t = \frac{8}{5}, \quad r = \frac{7}{10}, \quad x^2 = \frac{7}{25}, \quad y^2 = \frac{9}{10}, \tag{A7}$$

and the result (31) follows.

APPENDIX B: MODE DENSITY

The mode density (19) is given by the square components of the first column of the orthogonal diagonalizing matrix U_{ki} . For this quantity Parlett reports a very useful formula (Corollary 7.9.1 of Ref. [18]), namely

$$\mathcal{P}_k \equiv U_{k1}^2 = \frac{\chi_{2:N}(\lambda)}{\partial_\lambda \chi_N(\lambda)} = -\frac{2 \sin k \chi_{2:N}(k)}{\partial_k \chi_N(k)}, \tag{B1}$$

where $\chi_{2:N}(k)$ is the first minor of the determinant (32) and k is a root of the characteristic polynomial, $\chi_N(k) = 0$. The minor coincides with the part that multiplies $(\lambda-z)$ in Eq. (33),

$$\begin{aligned}
\chi_{2:N} &= \lambda \xi_{N-2} - y^2 \xi_{N-3} \\
&= \lambda[(\lambda^2 - z\lambda - x^2)\eta_{N-4} - (\lambda-z)y^2\eta_{N-5}] \\
&\quad - y^2[(\lambda^2 - z\lambda - x^2)\eta_{N-5} - (\lambda-z)y^2\eta_{N-6}]; \tag{B2}
\end{aligned}$$

in the second line Eqs. (35) has been used, and then from Eq. (39),

$$\begin{aligned}
\sin k \chi_{2:N} &= \text{Im}\{e^{i(N-3)k}(\lambda - y^2 e^{-ik}) \\
&\quad \times [(\lambda^2 - z\lambda - x^2) - (\lambda-z)y^2 e^{-ik}]\} \\
&= \text{Im}\{e^{iNk} a_k u_k\}, \tag{B3}
\end{aligned}$$

where

$$a_k \equiv e^{-ik}(\lambda - y^2 e^{-ik}). \tag{B4}$$

By deriving Eq. (42) with respect to k one has

$$\begin{aligned}
\partial_k [\chi_N(k) \sin k] &= \sin k \partial_k \chi_N(k) \\
&= \text{Im}\{e^{i(N+1)k} [i(N+1)u_k^2 + 2u_k u_k']\} \\
&= (N+1) \text{Re}\{e^{i(N+1)k} u_k^2\} + 2 \text{Im}\{e^{i(N+1)k} u_k u_k'\}; \tag{B5}
\end{aligned}$$

the secular equation entails that the argument of Re is real and Re can be omitted; then,

$$\begin{aligned}
\sin k \partial_k \chi_N(k) &= \left[N+1 + 2 \text{Im}\left\{ \frac{u_k'}{u_k} \right\} \right] e^{i(N+1)k} u_k^2 \\
&= [N+1 + 2 \text{Im}\{\partial_k \ln u_k\}] e^{i(N+1)k} u_k^2 \\
&= [N+1 + 2 \text{Im}\{\partial_k \ln |u_k| - i\phi_k'\}] e^{i(N+1)k} u_k^2 \\
&= (N+1 - 2\phi_k') e^{i(N+1)k} u_k^2. \tag{B6}
\end{aligned}$$

The Parlett formula (B1) becomes

$$\begin{aligned}
\mathcal{P}_k &= -\frac{2 \sin k}{N+1-2\phi_k'} \frac{\text{Im}\{e^{iNk} a_k u_k\}}{e^{i(N+1)k} u_k^2} \\
&= \frac{2 \sin k}{N+1-2\phi_k'} \frac{\text{Im}\{e^{ik} u_k a_k^*\}}{|u_k|^2}; \tag{B7}
\end{aligned}$$

comparing Eqs. (43) and (B4) one has

$$u_k e^{2ik} = (\lambda - z) a_k e^{ik} - x^2 \tag{B8}$$

and it follows

$$\begin{aligned}
\text{Im}\{e^{ik} u_k a_k^*\} &= \text{Im}\{(u_k e^{2ik})(a_k e^{ik})^*\} \\
&= \text{Im}\{(\lambda - z)|a_k|^2 - x^2(\lambda - y^2 e^{ik})\} \\
&= x^2 y^2 \sin k. \tag{B9}
\end{aligned}$$

This yields Eq. (48). Note that

$$\begin{aligned}
u_k^* u_k' &= u_k^* \partial_k (|u_k| e^{-i\phi_k}) \\
&= u_k^* e^{-i\phi_k} (\partial_k |u_k| - i|u_k| \phi_k') \\
&= |u_k| \partial_k |u_k| - i|u_k|^2 \phi_k' \tag{B10}
\end{aligned}$$

implies the identity

$$|u_k|^2 \phi_k' = -\text{Im}\{u_k^* u_k'\}, \tag{B11}$$

and the density can also be written in the alternative form

$$\mathcal{P}_k = \frac{2x^2 y^2 \sin^2 k}{(N+1)|u_k|^2 + 2\text{Im}\{u_k^* u_k'\}}. \tag{B12}$$

APPENDIX C: EXPLICIT EXPRESSION OF \mathcal{P}_k

From Eq. (52) one writes the real and imaginary parts of $\tilde{u}_k \equiv R_k + iI_k$,

$$\begin{aligned}
R_k &\equiv 1 - (1-w) \cos k - (1-w)(1-r) \cos 2k + (1-r) \cos 3k \\
I_k &\equiv (1-w) \sin k + (1-w)(1-r) \sin 2k - (1-r) \sin 3k \tag{C1}
\end{aligned}$$

and since [19]

$$\psi_k = \tan^{-1} \frac{I_k}{R_k} \tag{C2}$$

it follows that

$$|\tilde{u}_k|^2 \psi_k' = R_k I_k' - R_k' I_k. \tag{C3}$$

An expression analogous to Eq. (B11) holds for ψ_k' ,

$$\begin{aligned}
\tilde{u}_k^* \tilde{u}_k' &= \tilde{u}_k^* \partial_k (|\tilde{u}_k| e^{i\psi_k}) \\
&= \tilde{u}_k^* e^{i\psi_k} (\partial_k |\tilde{u}_k| + i|\tilde{u}_k| \psi_k') \\
&= |\tilde{u}_k| \partial_k |\tilde{u}_k| + i|\tilde{u}_k|^2 \psi_k', \tag{C4}
\end{aligned}$$

while Eq. (51) entails $|u_k|^2 = 4 \sin^2 \frac{k}{2} |\tilde{u}_k|^2$; eventually, the density (48) turns into

$$\mathcal{P}_k = \frac{2(2-r)rw \cos^2 \frac{k}{2}}{N+2\psi'_k |\tilde{u}_k|^2} = \frac{2(2-r)rw \cos^2 \frac{k}{2}}{N|\tilde{u}_k|^2+2\text{Im}\{\tilde{u}_k^* \tilde{u}'_k\}}. \quad (\text{C5})$$

Setting $k \equiv 2q$ and using the identities

$$\begin{aligned} \cos 3q &= \cos q(1 - 4 \sin^2 q), \\ \sin 3q &= \sin q(4 \cos^2 q - 1), \end{aligned} \quad (\text{C6})$$

one has

$$\begin{aligned} e^{3iq} \tilde{u}_k &= [e^{3iq} + (1-r)e^{-3iq}] - (1-w)[e^{iq} + (1-r)e^{-iq}] \\ &= [(2-r) \cos 3q + ir \sin 3q] - (1-w)[(2-r) \cos q + ir \sin q] \\ &= (2-r)(w - 4 \sin^2 q) \cos q - ir(2-w - 4 \cos^2 q) \sin q; \end{aligned} \quad (\text{C7})$$

from this one can work out the square modulus needed to calculate Eq. (C5),

$$\begin{aligned} |\tilde{u}_k|^2 &= (2-r)^2(w - 4 \sin^2 q)^2 \cos^2 q + r^2(2-w - 4 \cos^2 q)^2 \sin^2 q \\ &= (2-r)^2[w^2 - 8(w-2 \sin^2 q) \sin^2 q] \cos^2 q + r^2[(2-w)^2 - 8(2-w-2 \cos^2 q) \cos^2 q] \sin^2 q \\ &= [(2-r)^2 w^2 + r^2(2-w)^2 \tan^2 q - 32(1-r)(w-2 \sin^2 q) \sin^2 q] \cos^2 q. \end{aligned} \quad (\text{C8})$$

Eventually, from Eq. (C5),

$$\mathcal{P}_k = \frac{1}{1 + \delta_{k0}} \frac{1}{N+2\psi'_k} \frac{2(2-r)rw}{(2-r)^2 w^2 + r^2(2-w)^2 \tan^2 q - 32(1-r)(w-2 \sin^2 q) \sin^2 q}, \quad \left(q \equiv \frac{k}{2} \right). \quad (\text{C9})$$

The first term halves the value of \mathcal{P}_0 and is needed to restore the correct distribution. The reason for it can be more easily understood in the uniform limit $w = r = 1$, where one obtains the density (56), but with the correct value for $k = 0$ being $\mathcal{P}_0 = \frac{1}{N}$. Indeed, an accurate derivation of the free-chain limit $z \rightarrow 1^-$ gives for the lowest k -mode the shift $\psi_{k_1} \simeq -(1-z)/k_1$, and by Eq. (58) one has $k_1 \simeq \sqrt{2(1-z)/N} \rightarrow 0$; therefore, all shifts and their derivatives ψ'_k tend to zero, but with the exception of a finite limit for $2\psi'_{k_1} \simeq 2(1-z)/k_1^2 \rightarrow N$. Actually, one can analytically verify that with this caveat the distribution (56) is correctly normalized. It has been numerically checked that the more general distribution (C9) requires the the value at $k = 0$ to be halved in order to be exactly normalized.

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