Modulated phases in a three-dimensional Maier-Saupe model with competing interactions

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This work is dedicated to the study of the discrete version of the Maier-Saupe model in the presence of competing interactions. The competition between interactions favoring different orientational ordering produces a rich phase diagram including modulated phases. Using a mean-field approach and Monte Carlo simulations, we show that the proposed model exhibits isotropic and nematic phases and also a series of modulated phases that meet at a multicritical point, a Lifshitz point. Though the Monte Carlo and mean-field phase diagrams show some quantitative disagreements, the Monte Carlo simulations corroborate the general behavior found within the mean-field approximation.

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I. INTRODUCTION

Many condensed-matter systems, such as magnetic compounds, polymers, and liquid crystals, exhibit interesting phases with periodic structures [1]. Microscopically, this modular behavior can be understood as resulting from competing interactions favoring different orderings [2]. Perhaps the most simple and interesting example is the ANNNI (axial-nextnearest-neighbor-Ising) model, with competing interactions between first (ferromagnetic) and second (antiferromagnetic) neighbors along one specific direction [3]. The phase diagram, as a function of the temperature and the parameter regulating the degree of competition between different interactions, exhibits a paramagnetic and a ferromagnetic phase, as well as an infinite series of modulated phases [4]. All these phases meet at a special critical point called the Lifshitz point [5]. Because of its rich phase diagram, the ANNNI model has been widely studied using different analytical and numerical methods, and it also has experimental applications [6-8].

In the field of liquid crystals (LCs), there is also significant interest in modulated phases [9–11]. The constituent molecules of LCs have a rigid part, which is responsible for the alignment of the molecules along a direction (described by a director, an angle in the range $[0,\pi]$), and a more flexible part, which induces the fluidity. The different phases in this state of matter depend on the preferential ordering of the molecules, which in turn depends on the temperature. Their characterizations are given by the underlying translational and rotational symmetries and are usually classified as nematic, smectic, or cholesteric (also known as the chiral or helical phase). The uniaxial nematic phases are well established in the phase diagram of a large number of LCs [12–18] as well as the biaxial nematic phases and its stability [19–21].

In general, statistical formulations defined on lattices describe satisfactorily many physical characteristics of thermotropic LCs, and their mean-field formulations can describe nematic phases and the related phase transitions [13–16]. The simplest and most important model is the Maier-Saupe model, which has been successful not only in explaining the orientational properties but also hosts an order-disorder transition, i.e., a transition between nematic and isotropic phases [17].

In this work, we consider a generalization of the Maier-Saupe model on a 3D lattice, which includes competing interactions along one specific direction, similar to the ANNNI model. We show that this frustrated Maier-Saupe model hosts a series of modulated phases that may be related to the cholesteric phase observed in some in LCs [22,23]. Here, as a first step to start exploring frustration effects in LCs, instead of describing the molecules by continuously varying vector degrees of freedom, we consider a discrete version first. Similar to the standard discrete version of the Maier-Saupe model, the "molecules" are discrete spins that can only take three different orientations. This simiplification makes the model equivalent to the 3D three-state ANNN-potts model. As far as we are aware, even though there has been numerous works reported on the standard 3D three-state potts model with nearest-neighbor interactions [24,25], as well as a 2D ANNN-potts model [26], no research has been done on this type of system in 3D. Thus, from either the view of understanding the rich phases in LCs or the more general perspective of enriching our knowledge of potts models, such a study is desirable. In fact, even though this discrete version of Maier-Saupe model with competitions cannot fully describe the complexity of the cholesteric phase, our results still show that this model produces modulated structures, with periodicity that depends on the parameter regulating the competing interactions and the temperature.

The paper is organized as follows: In Sec. II, we introduce the Maier-Saupe model with competing interactions. Section III is dedicated to an analytical calculation of the order parameter and the free energy by means of a variational mean-field approach, which is solved numerically to obtain the phase diagram. Monte Carlo (MC) simulations aimed at an unbiased determination of the phase boundaries are discussed in Sec. IV, and final remarks are given in Sec. V.

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II. STATEMENT OF THE PROBLEM

To describe a LC statistically, it is appropriate to define an order parameter in terms of a unitary director \mathbf{n} that corresponds the preferential ordering of the molecules. Due to the quadrupole symmetry, the LCs are indistinguishable under $\mathbf{n} \to -\mathbf{n}$ transformation and a natural order parameter that takes it into account is given by the second-order tensor,

$$T^{\mu\nu} = an^{\mu}n^{\nu} + b\delta_{\mu\nu},\tag{1}$$

where a and b are arbitrary constants and n^{μ} are components of the director \mathbf{n} , with $\mu, \nu = \{x, y, z\}$. The trace of the tensor T does not contain any orientational information, and a convenient order parameter to describe a nematic LC, where the molecules have axial symmetry, can be defined by eliminating the trace part as

$$S^{\mu\nu} \equiv T^{\mu\nu} - \frac{\delta_{\mu\nu}}{3} \text{Tr}\{T\} = \frac{a}{3} (3n^{\mu}n^{\nu} - \delta_{\mu\nu}).$$
 (2)

In a lattice model, we can use the expectation value of the elements of such a tensor order parameter at an arbitrary site *i*,

$$M^{\mu\nu} = \langle S_i^{\mu\nu} \rangle = \langle \frac{1}{2} (3n_i^{\mu} n_i^{\nu} - \delta_{\mu\nu}) \rangle, \tag{3}$$

where n_i^{μ} are the components of the vector that defines the preferred orientation of the molecule located on site *i*. In the nematic phase, the order parameter must be nonzero and in the isotropic phase it should vanish. In this way, we choose a=3/2 such that $M^{\mu\nu}=1$ in the perfectly ordered phase.

The weak first-order transition between uniaxial nematic and anisotropic phases is well understood from theoretical as well as experimental investigations [27–30]. The transition is well described by the mean-field Maier-Saupe theory, and, following this approach, we will here implement competing interactions in the Maier-Saupe model (also known as the Lebwohl-Lasher model [31]). In analogy with the ANNNI model, we consider interactions between first neighbors along the x and y axes and competing interactions along the z axis, and introduce the following Hamiltonian:

$$\mathcal{H} = -J_1 \sum_{\mu,\nu} \sum_{x,y,z} \left(S_{xyz}^{\mu\nu} S_{x+1yz}^{\mu\nu} + S_{xyz}^{\mu\nu} S_{xy+1z}^{\mu\nu} + S_{xyz}^{\mu\nu} S_{xyz+1}^{\mu\nu} \right) - J_2 \sum_{\mu\nu} \sum_{xyz} S_{xyz}^{\mu\nu} S_{xyz+2}^{\mu\nu}.$$
(4)

To achieve the desired competition, the couplings between first neighbors, J_1 , and second neighbors, J_2 , should have opposite signs. The lattice sites will be labeled by a suffix xyz, where $1 \le x, y, z \le N$; i.e., the total number of sites is N^3 . The reason for introducing the spatially anisotropic coupling is that, once a layered structure has formed, there is no reason for the effective couplings in the simplified lattice model to be isotropic, and the analogy with the ANNNI model suggests that the frustration only in the interaction between the layers (our z direction) should be the simplest way to achieve the modulated phases. The anisotropic interaction still also allows for isotropic (disordered) and nematic phases.

A convenient explicit form for $S_{xyz}^{\mu,\nu}$ is given by

$$S_{xyz}^{\mu\nu} = \frac{1}{2} \left(3n_{xyz}^{\mu} n_{xyz}^{\nu} - \delta_{\mu\nu} \right), \tag{5}$$

and we will proceed using it to calculate the partition function associated with the Hamiltonian Eq. (4). The partition function is

$$\mathcal{Z} = \sum_{\{\mathbf{n}\}} e^{-\beta \mathcal{H}},\tag{6}$$

where the sum is over all allowed directions of the vectors \mathbf{n}_i allowed and $\beta = 1/(k_BT)$, with T the temperature and k_B Boltzmann's constant (which we set to 1 henceforth). A considerable simplification, which we will adopt here, is to consider a discrete version of the director as proposed by Zwanzig [32], where the site directors can be oriented only along three perpendicular directions,

$$\mathbf{n}_i = \begin{cases} (0,0,1), \\ (0,1,0), \\ (1,0,0). \end{cases} \tag{7}$$

This approach works very well in the mean-field Maier-Saupe model, where the fluctuations are not so relevant for the main features of the phase diagram, and, despite the discrete simplification, the usual Maier-Saupe model (without competition) shows qualitatively the physical behavior of LCs [33]. Because of the symmetries, the model is also equivalent to a three-state frustrated Potts model [24,25], an extension of the standard ANNNI model. While a generalized S=1 ANNII model (i.e., with three states per lattice site) has been previously studied [34], the symmetries of this model are different. To our knowledge, the Potts version of the ANNNI model has not been studied previously.

When we turn on the competing interactions, the calculation of the partition function is a formidable task even with the discrete approximation. In the next section, we will first employ a variational (mean-field) approach to obtain an approximate analytical expression for the order parameter and the free energy and obtain the phase diagram numerically. In Sec. IV, we apply MC simulations and extract a phase diagram and this is in good general agreement with the mean-field version.

III. VARIATIONAL APPROACH

Let F be the free energy of the system. To implement the Bogoliubov variational method, we need to find the free energy F_0 corresponding to a trial Hamiltonian \mathcal{H}_0 , satisfying the inequality

$$F \leqslant F_0 + \langle \mathcal{H} - \mathcal{H}_0 \rangle_0 \equiv \Phi. \tag{8}$$

The notation $\langle \rangle_0$ represents an average with respect to the partition function of the Hamiltonian \mathcal{H}_0 , that can be parameterized as

$$\mathcal{H}_0 = -\sum_{xyz} \sum_{\mu\nu} h_z^{\mu\nu} S_{xyz}^{\mu\nu}.$$
 (9)

Here, $h_z^{\mu\nu}$ is a symmetric tensor that should be considered as a variational parameter to minimize the free energy Φ in Eq. (8). As shown below, from this approach it is possible to obtain self-consistent analytical equations for the order parameter.

We start by calculating the partition function \mathcal{Z}_0 ,

$$\mathcal{Z}_{0} = \sum_{\{\mathbf{n}_{xy1}\}} \exp\left[\beta \sum_{\mu\nu} \left(S_{111}^{\mu\nu} + \cdots S_{NN1}^{\mu\nu}\right) h_{1}^{\mu\nu}\right] \times \cdots \sum_{\{\mathbf{n}_{xyN}\}} \exp\left[\beta \sum_{\mu\nu} \left(S_{1,1,N}^{\mu\nu} + \cdots S_{NNN}^{\mu\nu}\right) h_{N}^{\mu\nu}\right] \\
= \prod_{z=1}^{N} \left\{\sum_{\mathbf{n}_{xyz}} \exp\left[\beta \sum_{\mu\nu} S_{xyz}^{\mu\nu} h_{z}^{\mu\nu}\right]\right\}^{N^{2}}.$$
(10)

From this, taking into account that the director \mathbf{n}_{xyz} can assume six different values in accordance with Eq. (7), we obtain

$$Z_{0} = \prod_{z=1}^{N} \left\{ 2 \exp\left[-\frac{\beta}{2} \sum_{\mu} h_{z}^{\mu\mu} \right] \sum_{\nu} \exp\left(\frac{3}{2} \beta h_{z}^{\nu\nu} \right) \right\}^{N^{2}}$$
 (11)

and, consequently,

$$F_0 = -\frac{N^2}{\beta} \sum_{z=1}^{N} \left\{ \ln 2 - \frac{\beta}{2} \sum_{\nu} h_z^{\nu\nu} + \ln \left[\sum_{\nu} \exp\left(\frac{3}{2}\beta h_z^{\nu\nu}\right) \right] \right\}.$$
 (12)

In this case, the problem reduces to the calculation of $\langle \mathcal{H} - \mathcal{H}_0 \rangle$

$$\langle H - H_0 \rangle_0 = -J_1 \sum_{\mu\nu} \sum_{xyz} \left(\left\langle S_{xyz}^{\mu\nu} S_{x+1yz}^{\mu\nu} \right\rangle_0 + \left\langle S_{xyz}^{\mu\nu} S_{xy+1z}^{\mu\nu} \right\rangle_0 + \left\langle S_{xyz}^{\mu\nu} S_{xyz+1}^{\mu\nu} \right\rangle_0 \right) - J_2 \sum_{\mu\nu} \sum_{xyx} \left\langle S_{xyz}^{\mu\nu} S_{xyz+2}^{\mu\nu} \right\rangle_0 + \sum_{\mu\nu} \sum_{xyz} h_z^{\mu\nu} \left\langle S_{xyz}^{\mu\nu} S_{xyz}^{\mu\nu} \right\rangle_0. \tag{13}$$

We need to determine the averages of the right side of Eq. (13). It is straightforward to show that $\langle S_{xyz}^{\mu\nu} S_{xyz+1}^{\mu\nu} \rangle_0 = \langle S_{xyz}^{\mu\nu} \rangle_0 \langle S_{xyz+1}^{\mu\nu} \rangle_0$ and then it is sufficient to calculate $\langle S_{xyz}^{\mu\nu} \rangle_0$:

$$\left\langle S_{xyz}^{\mu\nu} \right\rangle_{0} = \frac{\sum_{\mathbf{n}_{xyz}} S_{xyz}^{\mu\nu} \exp\left(\beta \sum_{\mu\nu} h_{z}^{\mu\nu} S_{xyz}^{\mu\nu}\right)}{\sum_{\mathbf{n}_{xyz}} \exp\left(\beta \sum_{\mu\nu} h_{z}^{\mu\nu} S_{xyz}^{\mu\nu}\right)} = -\frac{\delta_{\mu\nu}}{2} + \frac{3}{2} \frac{\exp\left(\frac{3}{2} h_{z}^{\mu\nu}\right) \delta_{\mu\nu}}{\sum_{\gamma} \exp\left(\frac{3}{2} \beta h_{z}^{\gamma\gamma}\right)}. \tag{14}$$

From this expression we see that $\langle S_{xyz}^{\mu\nu}\rangle_0 = \langle S_{x+1yz}^{\mu\nu}\rangle_0 = \langle S_{xy+1z}^{\mu\nu}\rangle_0$. Since $\langle S_{xyz+a}^{\mu\nu}\rangle_0$, with a=0,1, or 2, there is no dependence on the x and y variables, and we therefore we sum over these in the free-energy expression as follows:

$$\frac{\Phi}{N^2} = -\frac{1}{\beta} \sum_{z=1}^{N} \left\{ \ln 2 - \frac{\beta}{2} \sum_{\mu} h_z^{\mu\mu} + \ln \left[\sum_{\mu} \exp\left(\frac{3}{2}\beta h_z^{\mu\mu}\right) \right] \right\} - J_1 \sum_{z=1}^{N} \sum_{\mu} \left[2(M_z^{\mu\mu})^2 + M_z^{\mu\mu} M_{z+1}^{\mu\mu} \right] - J_2 \sum_{z} \sum_{\mu} M_z^{\mu\mu} M_{z+2}^{\mu\mu} + \sum_{z} \sum_{\mu} h_z^{\mu\mu} M_z^{\mu\mu}, \tag{15}$$

with $M_z^{\mu\nu} \equiv \langle S_{x,y,z}^{\mu\nu} \rangle_0$.

The equation defining the adjustable parameter $h_z^{\mu\nu}$ is obtained by free-energy minimization,

$$h_z^{\mu\nu} = 4J_1 M_z^{\mu\nu} + J_1 (M_{z+1}^{\mu\nu} + M_{z-1}^{\mu\nu}) + J_2 (M_{z+2}^{\mu\nu} + M_{z-2}^{\mu\nu}),$$
(16)

since $M_z^{\mu\nu}$ is a function of $h_z^{\mu\nu}$, Eq. (14). According to Eq. (14), M is traceless, consequently, $\sum_{\mu} h_z^{\mu\mu} = 0$, and we use the standard parametrization,

$$M_z = \begin{pmatrix} -\frac{1}{2}(Q_z + \eta_z) & 0 & 0\\ 0 & -\frac{1}{2}(Q_z - \eta_z) & 0\\ 0 & 0 & Q_z \end{pmatrix}$$
(17)

and

$$h_z = \begin{pmatrix} -\frac{1}{2}(H_z + \varphi_z) & 0 & 0\\ 0 & -\frac{1}{2}(H_z - \varphi_z) & 0\\ 0 & 0 & H_z \end{pmatrix}. \tag{18}$$

We then obtain the self-consistent equations for the order parameters:

$$Q_z = \frac{1 - \exp\left(-\frac{9}{4}\beta H_z\right) \cosh\left(\frac{3}{4}\beta\varphi_z\right)}{1 + 2\exp\left(-\frac{9}{4}\beta H_z\right) \cosh\left(\frac{3}{4}\beta\varphi_z\right)}$$
(19)

and

$$\eta_z = \frac{3e^{-\frac{9}{4}\beta H_z}\sinh\left(\frac{3}{4}\beta\varphi_z\right)}{1 + 2\exp\left(-\frac{9}{4}\beta H_z\right)\cosh\left(\frac{3}{4}\beta\varphi_z\right)},\tag{20}$$

with

$$H_z = 4J_1Q_z + J_1(Q_{z+1} + Q_{z-1}) + J_2(Q_{z+2} + Q_{z-2})$$
 (21)

$$\varphi_z = 4J_1\eta_z + J_1(\eta_{z+1} + \eta_{z-1}) + J_2(\eta_{z+2} + \eta_{z-2}). \tag{22}$$

To study competing interactions we consider $J_1 > 0$ and $J_2 < 0$, where we defined the coupling ratio regulating the competing interactions (competition parameter), $p = -J_2/J_1$, whence p is positive. So, from Eqs. (19) and (20), the free

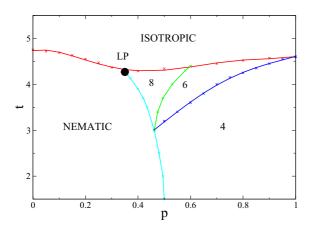


FIG. 1. Phase diagram of the Maier-Saupe model with competing interactions, with $J_1 > 0$, $J_2 < 0$, and $p = -J_2/J_1$, obtained by numerically minimizing the free energy with different imposed periodicities of the order parameter. We have identified isotropic, nematic, and modulated (with 4, 6, and 8 periodicity) phases. The nematic and modulated phases meet the isotropic phase at the Lifshitz point located at $p \approx 0.35$ and $t \approx 4.27$.

energy, Φ , is given in terms of the parameters Q_z and η_z by

$$\frac{\Phi}{N^2 J_1} = -t \sum_{z=1}^{N} \left\{ \ln 2 + \ln \left[e^{-\frac{3}{4iJ_1} (H_z + \varphi_z)} + e^{-\frac{3}{4iJ_1} (H_z - \varphi_z)} + e^{\frac{3}{2i} \frac{H_z}{J_1}} \right] \right\}
+ \frac{3}{2} \sum_{z=1}^{N} \left(2Q_z^2 + Q_z Q_{z-1} - pQ_z Q_{z-2} \right)
+ \frac{1}{2} \sum_{z=1}^{N} \left(2\eta_z^2 + \eta_z \eta_{z-1} - p\eta_z \eta_{z-2} \right), \tag{23}$$

with $t \equiv 1/(\beta J_1)$.

From Eqs. (19), (20), and (23) it is possible to obtain the thermodynamic phases as a function of the temperature and the competition parameter. To do so, at each point (t, p), we take an initial guess about the periodicity as our initial condition (here the periodicity is defined as the number of layers after which the system repeats itself. Take a simple case as an example, if molecules have only two states, + or -, and along the z axis, if molecules are aligned with the pattern ++--++---, then we say that the periodicity of this system is 4). However, eventually the initial condition converges to a final configuration based on the iterative equations, Eqs. (19)–(22), irrespective of the initial guess. For some cases, the final configuration may vary depending on different initial conditions. In such cases, we compare their energies based on Eq. (23) to find the ground state.

To evaluate Eqs. (19) and (20), we used the iterative method (fixed points) for lattices sufficiently large to accommodate the periodicity of each phase studied (using periodic boundary conditions). Although the competing interactions can be expected to give rise to an infinite series of modulated phases, as in magnetic systems [35–38], the phase diagram displayed in Fig. 1 has been constructed by analyzing the free energies only of the isotropic (disordered), nematic (ordered), and

modulated phases with periodicity 4, 6, and 8. For our purposes this is enough, since we are not aiming at describing in detail the transitions that occur between different modulated phases. The results already point to the existence of a Lifshitz point. We see that, beyond the isotropic-nematic transition, the model exhibits a transition between the nematic and modulated as well as between the isotropic and modulated phases. Considering m(z) as the order parameter in each layer, we note that the period-4 state is special, in that the structure of the modulated order in a unit cell (along the z axis), m(1), m(2), m(3), m(4), is such that m(1) = m(2) and m(3) = m(4), while for the larger periodicities m(z) shows a smooth variation. Therefore, the period-4 phase should be considered a different "bilayer" phase separate from the series of modulated phases. We will confirm this picture with MC simulations.

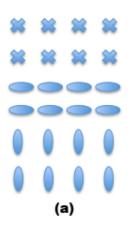
IV. MONTE CARLO SIMULATIONS

For the purpose of MC simulations, we now write the effective Hamiltonian in Eq. (4) as

$$H = -J \sum_{(i,j)} (\mathbf{n}_i \cdot \mathbf{n}_j)^2 + pJ \sum_{((k,k'))} (\mathbf{n}_k \cdot \mathbf{n}_{k'})^2 + \frac{JN(3-p)}{3},$$
(24)

where \mathbf{n}_i is an orientational degree of freedom that can be along the directions (0,0,1) or (0,1,0) or (1,0,0), according to the three possible orientations of the liquid crystal molecule. The first term stands for the ferromagnetic interactions between the nearest neighbors along the x, y, and z directions, while the second term represents the interactions between the second-nearest neighbors only along the z axis. The third term is a constant, consistent with the original Maier-Saupe model (without frustration), and N is the total number of molecules; for a system with linear size L, $N = L^3$. Compared to the Hamiltonian defined for the mean-field calculations by Eq. (4), the coupling strengths in these two Hamiltonians differ by a factor $J = (9/4)J_1$, which we will adjust for later when comparing the phase diagrams. In the following, we set J = 1and the parameter p will be the ratio of the two competing couplings.

Similar to the study of the 3D ANNNI model [39], when analyzing Eq. (24) at T=0 it is expected that the groundstate energy corresponds to a nematic phase when p < 0.5, while for p > 0.5, the ground state corresponds to a modulated phase, which has the bilayer structure, as seen in Fig. 2, which are example configurations of the bilayer structure. Figure 2(a) shows a stack of three bilayers with three different molecule orientations, while Fig. 2(b) shows an alternating structure of bilayers with two different orientations. There is a large ground-state degeneracy, as any bilayer structure maintains the same lowest energy as long as two adjacent bilayers have perpendicular orientations. Therefore, at T=0 it is clear that $p_c = 1/2$ is the transition point separating the nematic phase from the bilayer-structured phase. However, for T > 0, it is not clear which state the system will stay in, as the entropy plays an important role at finite temperatures. To draw a complete phase diagram, we applied MC simulation to this system. In



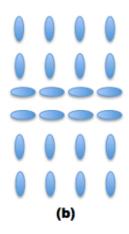


FIG. 2. Bilayer structure of liquid crystal molecules. (a) and (b) are two examples of the bilayer structure: (a) shows a stack of three bilayers with three different molecule orientations; (b) shows an alternating structure of bilayers with two different orientations.

this section, we will discuss the simulation method as well as the main numerical results obtained.

In our MC simulations, we primarily consider an $8 \times 8 \times 8$ cubic lattice. We used a rather small size here, as this model is very difficult to equilibrate and the simulation rapidly becomes much harder for larger sizes (as is well known for frustrated systems). Nevertheless, for the purpose of obtaining a semiquantitative view of the phase transitions of the system, we will argue that the system size is sufficient. We have also done some calculations with a $12 \times 12 \times 12$ lattice and will discuss the finite-size effects based on comparing the two sizes. For each value of p, the ratio of the two competing interactions, we simulated the system at different temperatures within the range $T \in [2.5, 0.5]$, in steps of $\Delta T = 0.01$. We studied coupling ratio $p \in [0,1]$ in steps of 0.1. At each T, we start from random initial configurations. To equilibrate the system, 10⁶ MC sweeps of N random local updates were performed according to the Metropolis algorithm. The final results came from a binaverage of 20 bins with each bin containing the average of 10⁵ measurements.

Figure 3 shows the behavior of the energy versus the temperature. As discussed previously, at low temperatures the system stays in the nematic phase for p < 0.5 and the energy density (per site) then approaches to E = (2p - 6)/3 when $T \rightarrow 0$, while for p > 0.5 the system is in a modulated phase with bilayer structure, where the energy density approaches E = -(9 + 2p)/6. This behavior confirms that p = 0.5 is the transition point at T = 0.

The simplest order parameter that describes the isotropicnematic transition is given by

$$m = \left\langle \frac{1}{N} \sum_{i} \frac{(3\cos^2 \theta_i - 1)}{2} \right\rangle,\tag{25}$$

where θ_i is the angle between the central axis of the *i*th molecule and the global director **n**. Because of symmetry, we can simply choose a reference director to be along z direction. This order parameter m easily differentiates between the nematic ($m \neq 0$) and the isotropic (m = 0) phases. The transition between these two phases is known to be first

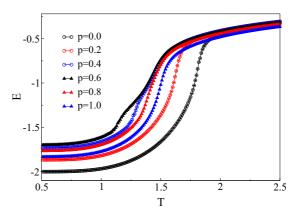


FIG. 3. Temperature dependence of energy density at various coupling ratios p for system size L=8. As expected, at low temperatures, for system with p<0.5 energy approaches to E=(2p-6)/3, while for p>0.5 it approaches E=-(9+2p)/6. The apparent anomalies seen for p=0.4 at around T=1.4 and p=0.6 around T=1.1 comes from the second phase transition taking place for this range of p.

order in the standard (p=0) Maier-Saupe model. The order parameter defined in Eq. (25) is not good for describing a modulated phase in MC simulations, however, because in modulated phases with different orientation of the directors in different planes, it can acquire any value between $0 \le m \le 1$, depending on the values of p and t, and it cannot differentiate the modulated phase from either the isotropic phase or the nematic phase.

To circumvent this problem, we define a layer order parameter, m_z , with $z \in [0, L-1]$, in each xy plane along the z direction:

$$m_z = \left\langle \frac{1}{L^2} \sum_{i}^{L^2} \frac{(3\cos^2\theta_i - 1)}{2} \right\rangle_{xy \text{ plane}}.$$
 (26)

If there is no preferential ordering within the layers, then for finite but reasonably large system size, m_z is close to zero in all layers; thus, $m \approx 0$ and $m_z \approx 0$ defines an isotropic phase. If $m \approx 1$ and $m_z \approx 1$, and furthermore m_z has the same value for all z, it signals a nematic phase. However, if $0 < m, m_z \le 1$, and at the same time m_z varies in different layers, then we identify the behavior as that of a modulated phase. Within the class of modulated phases, we here find two kinds: one is the bilayer-structured phase already discussed and illustrated with the configurations shown in Fig. 2; in this phase, m < 1 and $m_z \approx 1$. The other kind of modulated phase has no bilayer structure and we refer to it as a single-layer modulated phase. In this case, the molecules align more chaotically and m_7 varies from layer to layer with $0 < m, m_z < 1$. We associate this disorder in the z direction with incommensurate ordering that cannot be realized on the small lattices considered here. In addition, in this regime the behavior is clearly impacted by the discreteness of the director in our model.

Figure 4 shows the behavior of order parameter at various p values for system size L=8. From high to low temperatures, systems with p<0.5 transition from the high-T isotropic phase to the low-T nematic phase, while for $p\geqslant0.5$ the systems change from the high-T isotropic phase to the

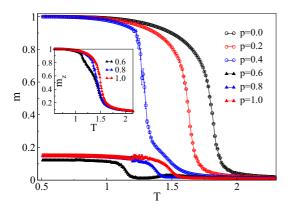


FIG. 4. Temperature dependence of order parameter at various ratios p for system size L = 8. The inset shows the layer order parameter averaged over the layers for $p \ge 0.5$.

low-T bilayer-structured phase. The inset shows the layer order parameter for three cases with p > 0.5. The order parameter 0 < m < 1, while $m_z \approx 1$ clearly reveals the fact that in each layer the molecules align, but overall the layers align randomly along the z axis. However, in the course of the evolution from the isotropic to the nematic phase for p < 0.5, as well as that from isotropic to bilayer structure for p > 0.5, we observe that, for a certain range of p, there is another phase that the system has to go through, which is the single-layer-structured modulated phase. For if examined carefully, there are obvious abnormal behaviors of the order parameter for p = 0.4 and p = 0.6, in addition, we can also see features beyond the statistical noise in the energy behavior at around T = 1.3 and T = 1.1, respectively, for the two p values. We believe that these anomalies arise from a second phase transition in the system. For p = 0.4, the system first undergoes the transition from the isotropic phase to the single-layer modulated phase, and at lower temperature it goes through the second phase transition, which is from the single-layer-structured phase to the nematic phase. For p = 0.6, the system goes through the first isotropic to single-layer transition, followed by the second transition from the single-layer-structured to the bilayer-structured phase. As mentioned above, this single-layer-structured phase has m_z varying along each different layer (i.e., the director is aligned differently in adjacent layers); however, it does not exhibit any aligned structure in the z direction, in analogy with the configurations shown in Fig. 2 in the case of the bilayer phase. In the following, we will provide more evidence for the two phase transitions and construct the phase diagram.

Figure 5 shows the behavior of specific heat C_v versus temperature for several coupling ratios p < 0.5 (p = 0.0, 0.36, 0.38). Specific heat is defined as

$$C_v = N\beta^2 (\langle E^2 \rangle - \langle E \rangle^2), \quad \beta = \frac{1}{T}.$$
 (27)

For 0.0 , we observe only a single peak, indicating that the system changes from the isotropic phase directly to the nematic phase. However, a second peak starts to show up for <math>p = 0.36 and becomes obvious for p = 0.38, indicating that dual phase transitions appear for $p \ge 0.36$, where the systems go through the isotropic—single-layer transition, followed

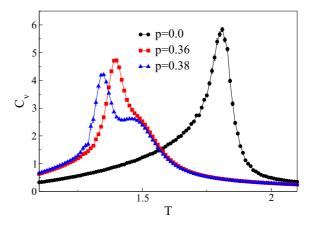


FIG. 5. Temperature dependence of the specific heat for p = 0.0, 0.36, and 0.38. There is only one peak for p = 0, indicating the isotropic-nematic phase transition, however, a second peak emerges for p = 0.36 and becomes obvious for p = 0.38, indicating that dual phase transitions occur at these p values.

by the single-layer—nematic phase transition. The crossover between the single to dual transitions takes place close to p=0.36 (within ± 0.01 from this point). Similarly, Fig. 6 shows the behavior of the specific heat for several ratios p>0.5 (p=0.75, 0.8, 0.9). For $p\geqslant 0.9$, there is only one peak, indicating that the systems change from the isotropic phase directly into the bilayer-structured phase. However, for $0.5 the specific heat again exhibits two peaks, indicating that systems go through the dual isotropic—single-layer—bilayer phase transitions. The crossover here occurs at <math>p\approx 0.8$.

Not only does the specific heat show evidence for dual phase transitions, but there are also corresponding anomalies in the behavior of the order-parameter fluctuations. In analogy with the susceptibility in a magnetic system, we define a "susceptibility" χ for our model as

$$\chi = N\beta(\langle m^2 \rangle - \langle m \rangle^2), \tag{28}$$

and this quantity should diverge at any of the ordering transitions discussed. Figure 7 shows the behavior of the susceptibility versus temperature at p = 0.6 for both L = 8

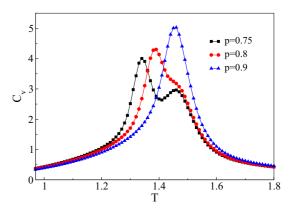


FIG. 6. Temperature dependence of the specific heat for p = 0.75, 0.8, and 0.9. There are two peaks for p = 0.75 and p = 0.8, while only one peak for p = 0.9, indicating that the dual phase transition disappears between p = 0.8 and p = 0.9.

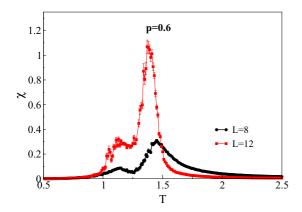


FIG. 7. Temperature dependence of χ at p=0.6 for L=8 and L=12. The peak near $T\approx 1.44$ indicates the isotropic—single-layer phase transition, while the anomaly at around T=1.14 corresponds to the transition from single-layer-structure to bilayer-structure. Comparing the results for the two cases, we can see the finite-size-effect playing some role in the L=8 systems, but we believe that the overall effects on the phase boundaries are minor.

and L=12. In both cases, two well-separated peaks can be seen, indicating the two phase transitions take place with both lattices. Moreover, comparing the results for the two cases, we can see that the peaks become higher and narrower with increasing size, as expected for peaks diverging in the thermodynamic limit, and the peak positions shift by only about 5%. While the finite-size-effect is, thus, playing some role in the L=8 systems, we believe that the overall effects on the phase boundaries are minor.

We finally, in Fig. 8, present the phase diagram drawn based on our MC simulations. By fitting the specific heat results to high-order polynomials in the peak regions, we can locate the transition temperature T_c for various values of p. We estimate error bars by fitting multiple times through the bootstrapping method. As discussed above, the system has four different phases: isotropic phase, nematic phase, single-layer-structured

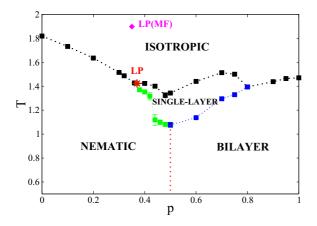


FIG. 8. Phase diagram of the discrete Maier-Saupe model with competing interactions, obtained on the basis of MC simulations with $8 \times 8 \times 8$ lattices. The red star point indicates the Lifshitz point (LP) based on our MC results, while the magenta diamond shows the LP based on mean-field results in Fig. 1 adjusted by the factor 9/4 relating the two versions of the Hamiltonian.

modulated phase as well as bilayer-structured modulated phase. For a certain range of p (0.36 < p < 0.8), the system goes through two phase transitions as the temperature is lowered, as it has to go through the single-layer-structured modulated phase as an intermediate state before reaching the nematic state or the bilayer-structured state at low temperature. The red star in the phase diagram represents the Lifshitz point (LP), located at $p \approx 0.36$, $T \approx 1.42$. Recall that the mean-field calculations found LP at $p_{\rm MF} \approx 0.35$ and $t_{\rm MF} \approx 4.27$, since the coupling strengths in the two Hamiltonians differs by a factor of 9/4, converting t used there to the the temperature defined in the MC simulation, we obtain $T_{\rm MF} = (4/9)t_{\rm MF} \approx 1.90$. The magenta diamond in the MC phase diagram shows the LP based on mean-field calculation for comparison.

According to the phase diagram of the 3D ANNNI model from MC simulation, it is known that the paramagnetic-ferromagnetic phase transition is continuous, while both the paramodulated and ferromodulated transitions are first order [40]. For our model, which is equivalent to the 3D three-state ANNN-Potts model, the isotropic-nematic phase transition is first order (just as the case in the standard 3D three-state Potts model). For the nemetic-modulated and isotropic-modulated phase transitions, we are not certain but we think they are most likely first-order phase transitions as well. Potentially, if we have data from more system sizes, we can test this conclusion through finite-size analysis.

Compared to the phase diagram from the mean-field calculations (Fig. 1), the MC phase diagram shows no clear signs of modulation in the modulated phase (in the case of the single-layer structure as well as the double-layer structure). Instead, the interlayer orientation always appears random and we cannot detect any meaningful correlations. Most likely, this is an indication of incommensurate ordering pitch that cannot be realized on the small lattices considered here and with the discreteness of the director. Nevertheless, the regime marked as phase with periodicity 4 in the mean-field phase diagram represents exactly the bilayer structure in Fig. 2(b). In this sense, despite some quantitative difference, in general the two phase diagrams are very consistent with each other.

V. FINAL CONSIDERATIONS

In this work, we have investigated the phase diagram of an extended version of the discrete Maier-Saupe model with competing interactions between nearest and second-nearest neighbors in one direction. The model also corresponds to a three-state Potts version of the ANNNI model. Initially, we carried out the studies by means of mean-field calculations. Even with a variational mean-field approach, the competing interactions produce a phase diagram with modulated structures. By applying numerical methods to find the order parameter, we obtained the transition lines between isotropicnematic, isotropic-modulated, and nematic-modulated phases. To compare with the mean-field results we also employed MC simulations. In this case, the order parameter in Eq. (25) is not able to distinguish the modulated phase of the isotropic and nematic phases, thus we introduced a modified layer-order parameter to distinguish the phases in more detail. With the MC results, we were then able to identify four phases of the system and construct the full phase diagram. In addition to a

nematic-isotropic transition, which are present in the absence of competing interactions, the model shows both transitions between isotropic-modulated and nematic-modulated phases. Although one cannot expect the mean-field phase diagram to be quantitatively correct, the MC simulations still corroborate the general pattern of the mean-field phase diagram, and even quantitatively the Lifshits point appears almost at the same coupling ratio as in the mean-field phase diagram, and at a temperature only about 25% lower.

We stress that, even with the discretized version of the Maier-Saupe model considered here, its phase diagram shows an interesting rich structure. To make definite statements about the relevance of our results to LCs, the model should be extended to continuous degrees of freedom; classical Heisenberg spins taking continuous values over a unit sphere. We regard our study of the discrete model as a first step on the path to future studies of frustrated models of LCs. Most likely the modulated phases we have found here will survive with continuous degrees of freedom, though details such as the phase boundaries and the pitch of the modulation with the

frustration parameter and the temperature may shift. We also expect that such a more refined model might be able to capture elements of more complex liquid crystalline phase transitions, such as the isotropic-smectic C* and isotropic-cholesteric transitions. In this last case, it should be pointed out that it is necessary to further generalize the Hamiltonian Eq. (4), including odd-chirality terms, which are important to take into account the striking feature of handedness observed in the cholesteric phase.

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