

Orientational glass in mixtures of elliptic and circular particles: Structural heterogeneities, rotational dynamics, and rheology

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Using molecular dynamics simulation with an angle-dependent Lennard-Jones potential, we study orientational glass with quadrupolar symmetry in mixtures of elliptic particles and circular impurities in two dimensions. With a mild aspect ratio ($=1.23$) and a mild size ratio ($=1.2$), we realize a plastic crystal at relatively high temperature T . With further lowering T , we find a structural phase transition for very small impurity concentration c and pinned disordered orientations for not small c . The ellipses are anchored by the impurities in the planar alignment. With increasing c , the orientation domains composed of isosceles triangles gradually become smaller, resulting in orientational glass with crystal order. In our simulation, the impurity distribution becomes heterogeneous during quenching from liquid, which then produces rotational dynamic heterogeneities. We also examine rheology in orientational glass to predict a shape memory effect and a superelasticity effect, where a large fraction of the strain is due to collective orientation changes.

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I. INTRODUCTION

Certain anisotropic molecules such as KCN, N_2 , and ortho-H form a cubic crystal without orientational order [1–3]. Solids in such a rotator phase are often called plastic solids [4]. As the temperature T is further lowered, they undergo orientational phase transitions, where the crystal structure changes from a cubic to noncubic one [1,5]. In mixtures of anisotropic particles such as KCN diluted with KBr, N_2 diluted with Ar, and ortho-H diluted with para-H, the so-called orientational glass is realized with increasing the impurity concentration c [1–3], where the quadrupolar, orientational degrees of freedom are randomly frozen [6]. In such mixtures, a specific-heat peak [1,7] and a decrease in one of the shear moduli [1,8] have been observed above the transition for not large c . The latter indicates a strong orientation-strain coupling [9–12]. To explain these behaviors, molecular dynamics (MD) simulation was also performed on mixed cyanides [13]. It is also remarkable that one-component systems of globular molecules such as ethanol, cyclohexanol, and C_{60} have rotator phases and are orientationally arrested at lower T with weak specific-heat singularities [14–16].

However, not enough attention has yet been paid to the physics of orientational glass. In contrast, numerous investigations have been made of translational glass, where positional disorder is frozen [3]. In previous MD simulations on diatomic systems [17] and more complex molecular systems [18], the correlations between the translational and rotational degrees of freedom have been examined in glassy states. Glassy dynamics was also found in monodisperse hard ellipsoids with slight anisotropy [19]. Moreover, in double glass [20], these two kinds of degrees of freedom have been predicted to freeze at the same temperature.

Recently we performed MD simulation on mixtures of spheroidal particles and spherical impurities in three dimensions to examine the formation of orientational glass [21]. In this paper, we aim to investigate its complex dynamics in more detail in mixtures of elliptic particle and circular impurities in crystal in two dimensions. We assume a mild aspect ratio ($=1.23$) of the ellipses to avoid liquid crystal mesophases and a mild size ratio ($=1.2$) between the two species to suppress

positional disorder. We vary T and c to examine the changeover between multivariant domain states for small c and highly frustrated states of orientational glass for not small c . We shall find that mesoscopic orientational order and strains exist in glassy states. Previously, for binary mixtures of circular particles, the changeover between polycrystal and translational glass was studied with varying c [22]. In translational glass, mesoscopic crystalline order still remains and was visualized [22,23]. In double glass, the simultaneous appearance of these two mesoscopic heterogeneities has been detected [24].

If the molecules forming a crystal are anisotropic, there arises a direct coupling between the orientations and the lattice deformations [9–12]. In fact, an effective interaction mediated by acoustic phonons was derived among anisotropic particles in crystal such as $(CN)^-$ in KCN [9–11], leading to acoustic softening in the rotator phase [1,8]. The orientational phase transitions for small c thus belong to type I instabilities in Cowley's classification of elastic instabilities [25,26], where acoustic modes become soft in particular wave vector directions. In this paper we predict a shape memory effect and a superelasticity effect in orientational glass at low T , where favored oriented domains increase and disfavored ones decrease upon stretching. These effects are well known for shape memory alloys such as TiNi [27–29]. Molecular dynamics simulation was also performed to reproduce superelasticity for a model alloy [30]. It is worth noting that mesoscopic strain heterogeneities were observed in TiNi glass, which were on a scale of 20 nm at a slightly off-stoichiometric composition [29].

As another ingredient, we shall find a tendency of impurity clustering depending on the molecular interactions [21]. In our simulation, it took place during quenching from a high-temperature liquid to low-temperature solid. The impurity clustering gives rise to significant heterogeneities in orientational order and rotational dynamics. For example, a small fraction of the elliptic particles remain not strongly anchored to the impurities such that they undergo flip rotations even at very low T . Though such effects have rarely been discussed in the literature, they should be relevant in many real experiments.

We point out that our system is similar to liquid crystal gels (gels containing rodlike molecules) [31,32]. In such soft matter, there arises a strong orientation-strain coupling, which makes the isotropic-nematic transition analogous to the orientation transition in solids. Irregularities in the cross-linkage play the role of random quenched disorder, leading to mesoscopic nematic polydomains [33]. Application of stress or electric field induces polydomain-monodomain transitions [34]. We also note that dilute magnetic alloys, called spin glass, have glassy phases characterized by frozen-in local magnetic moments which point in random directions [2,3,6]. However, in research, the spin-lattice coupling and the impurity clustering (resulting in correlated quenched disorder) have not yet been well examined.

The problem of orientational glass is thus closely related to many important problems in solids and soft matter. On the basis of a simple microscopic model, we organize this paper as follows. In Sec. II we will present the background of our simulation. In Sec. III we will display orientational configurations for various c at low T . In Sec. IV we will examine the rotational dynamics. In Sec. V we will treat rheology of orientational glass.

II. SIMULATION BACKGROUND

We use an angle-dependent potential [21], which is similar to but much simpler than the Gay-Berne potential [35] for rodlike molecules forming mesophases.

A. Model of anisotropic particles

We consider a binary mixture in two dimensions, where the first species consists of anisotropic particles with number N_1 and the second species consists of circular ones with number N_2 . The total number is $N = N_1 + N_2$. The concentration of the second species is

$$c = N_2/N. \quad (2.1)$$

For small c , the circular particles are impurities. The particle positions are written as \mathbf{r}_i , where $i = 1, \dots, N_1$ for the anisotropic particles ($i \in 1$) and $i = N_1 + 1, \dots, N$ for the isotropic particles ($i \in 2$). The orientations of the anisotropic particles are expressed by

$$\mathbf{n}_i = (\cos \theta_i, \sin \theta_i), \quad (2.2)$$

where θ_i are their angles with respect to the x axis. The particle sizes are characterized by two lengths, σ_1 and σ_2 . The pair potential U_{ij} between particles $i \in \alpha$ and $j \in \beta$ ($\alpha, \beta = 1, 2$) depends on the distance $r_{ij} = |\mathbf{r}_i - \mathbf{r}_j|$ and the angles θ_i ($i \in 1$) and θ_j ($j \in 1$). For $r_{ij} < r_c$, it is a modified Lennard-Jones potential,

$$U_{ij} = 4\epsilon \left[(1 + A_{ij}) \frac{\sigma_{\alpha\beta}^{12}}{r_{ij}^{12}} - \frac{\sigma_{\alpha\beta}^6}{r_{ij}^6} \right] - C_{ij}. \quad (2.3)$$

For $r_{ij} > r_c = 3\sigma_1$, it is zero. Here ϵ is the characteristic interaction energy and

$$\sigma_{\alpha\beta} = (\sigma_\alpha + \sigma_\beta)/2. \quad (2.4)$$

The C_{ij} ensures the continuity of U_{ij} at $r_{ij} = r_c$, so it is equal to the first term at $r = r_c$ in the right-hand side of Eq. (2.3). The

angle factor A_{ij} depends on the angles between the relative direction $\hat{\mathbf{r}}_{ij} = r_{ij}^{-1}(\mathbf{r}_i - \mathbf{r}_j)$ and the particle orientations. We assume the following form:

$$A_{ij} = \chi \delta_{\alpha 1} (\mathbf{n}_i \cdot \hat{\mathbf{r}}_{ij})^2 + \chi \delta_{\beta 1} (\mathbf{n}_j \cdot \hat{\mathbf{r}}_{ij})^2, \quad (2.5)$$

where $\delta_{\alpha\beta}$ is the Kronecker delta and χ represents the strength of anisotropic repulsion for $\chi > 0$. Our potential is invariant with respect to turnovers $\theta_i \rightarrow \theta_i \pm \pi$ or inversions $\mathbf{n}_i \rightarrow -\mathbf{n}_i$. It leads to quadrupolar orientational glass with impurities [2,3,6,21]. On the other hand, if U_{ij} contained a term like $(\mathbf{n}_i \cdot \mathbf{n}_j)v(r_{ij})$, it would not be invariant with respect to these transformations, resulting in spin glass with impurities [2,3].

The total kinetic energy of our system is given by

$$K = \frac{1}{2} \sum_{1 \leq i \leq N} m_\alpha |\dot{\mathbf{r}}_i|^2 + \frac{1}{2} \sum_{1 \leq i \leq N_1} I_1 |\dot{\theta}_i|^2, \quad (2.6)$$

where $\dot{\mathbf{r}}_i = d\mathbf{r}_i/dt$, $\dot{\theta}_i = d\theta_i/dt$, m_1 and m_2 are the masses, and I_1 is the moment of inertia of the anisotropic particles. The total potential energy is $U = \sum_{i < j} U_{ij}$, and the total energy is $H = K + U$. The Newton equations for $\mathbf{r}_i(t)$ and $\theta_i(t)$ are written as

$$m_\alpha \ddot{\mathbf{r}}_i = \frac{d}{dt} \frac{\partial}{\partial \dot{\mathbf{r}}_i} K = - \frac{\partial}{\partial \mathbf{r}_i} U, \quad (2.7)$$

$$I_1 \ddot{\theta}_i = \frac{d}{dt} \frac{\partial}{\partial \dot{\theta}_i} K = - \frac{\partial}{\partial \theta_i} U, \quad (2.8)$$

where $\ddot{\mathbf{r}}_i = d^2\mathbf{r}_i/dt^2$ ($i \in 1$ and 2) and $\ddot{\theta}_i = d^2\theta_i/dt^2$ ($i \in 1$). In our time integration, θ_i are unbounded, changing continuously in the range $[-\infty, \infty]$.

We regard the anisotropic particles as ellipses with short and long diameters a_s and a_ℓ . To determine them, we minimize U_{ij} in Eq. (2.3) with respect to r_{ij} to obtain $r_{ij} = 2^{1/6}(1 + A_{ij})^{1/6}\sigma_1$. For $\chi > 0$, this distance is minimum at $A_{ij} = 0$ for the perpendicular orientations ($\mathbf{n}_i, \mathbf{n}_j \perp \hat{\mathbf{r}}_{ij}$) and is maximum at $A_{ij} = 2\chi$ for the parallel orientations ($\mathbf{n}_i, \mathbf{n}_j \parallel \hat{\mathbf{r}}_{ij}$). Thus, we set

$$a_s = 2^{1/6}\sigma_1, \quad a_\ell = (1 + 2\chi)^{1/6}a_s. \quad (2.9)$$

If these elliptic diameters are assumed, we obtain

$$I_1 = (a_s^2 + a_\ell^2)m_1/4. \quad (2.10)$$

B. Simulation method

We integrated Eqs. (2.7) and (2.8) using the leap-frog method under the periodic boundary condition for $N = N_1 + N_2 = 4096$. We set

$$\chi = 1.2, \quad \sigma_2/\sigma_1 = 1.2. \quad (2.11)$$

The aspect ratio is $a_\ell/a_s = 1.23$ from Eq. (2.9). We measure space in units of σ_1 and time in units of

$$\tau_0 = \sigma_1 \sqrt{m_1/\epsilon}. \quad (2.12)$$

We also set $m_1 = m_2$. The temperature T is measured in units of ϵ/k_B with k_B being the Boltzmann constant.

To prepare the initial states in each simulation run, we started with a liquid state at $T = 2$, lowered T to 0.5 below the melting temperature (~ 1), waited for a time interval of 10^5 , and changed T to the final temperature, where we attached

a Nosé-Hoover thermostat [36] to all the particles. After this preparation, we used three simulation methods. First, retaining the thermostat, we took data in the NVT ensemble (Sec. III). Second, we switched off the thermostat, waited for another time interval of 10^5 , and calculated the time correlation functions in the NVE ensemble (Sec. IV). In these simulations at fixed V , the cell volume V was given by

$$\frac{\pi}{4}a_s a_\ell (1-c) + \frac{\pi}{4}a_s^2 (\sigma_2/\sigma_1)^2 c = 0.95 \frac{V}{N}. \quad (2.13)$$

Then the cell length was $L = V^{1/2} \sim 70$ for small c . Third, to apply uniaxial stress, we varied the cell lengths in the x and y axes assuming a rectangular cell, where we used the method of Parrinello and Rahman [37] (Sec. V).

III. NVT SIMULATION OF ORIENTATIONAL GLASS ON A HEXAGONAL LATTICE

In Figs. 1–4 we give results in the NVT ensemble. Under Eqs. (2.11) and (2.13), the melting temperature T_m was about 1.0, above which liquid was realized. Below T_m , a hexagonal crystal without orientational order appeared. For $T \lesssim 0.4$, an orientational phase transition took place for small $c \lesssim 0.1$, while orientational glass emerged for not small $c \gtrsim 0.2$. Previously, many authors [38] examined the phase transition between orientationally disordered and ordered crystal phases for monodisperse hard rods with mild aspect ratios.

A. Order parameter amplitude and specific heat

In Fig. 1 we plot the average orientation amplitude $\langle S \rangle$ defined in Appendix A and the constant-volume specific heat $C_V = (\partial \langle H \rangle / \partial T)_{NV}$ vs T for four concentrations. The former represents the overall strength of the orientational order, while the latter is the fluctuation amplitude of the energy H in the NVT ensemble,

$$C_V = \langle (H - \langle H \rangle)^2 \rangle / k_B T^2. \quad (3.1)$$

Hereafter, $\langle \dots \rangle$ denotes the average over time and over several runs. For $c = 0$, $\langle S \rangle$ grows nearly discontinuously at $T = 0.18$ in a narrow temperature window with a width

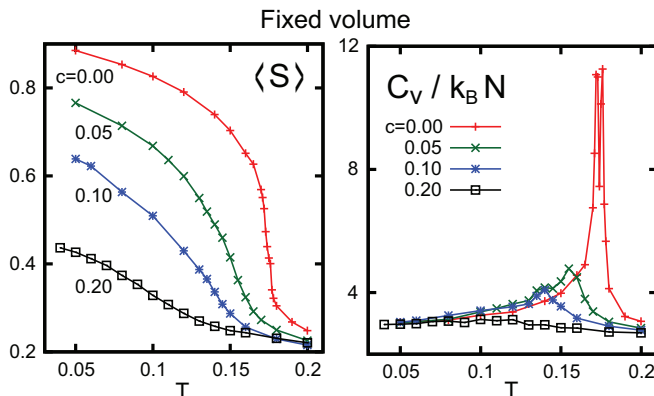


FIG. 1. (Color online) Average orientation amplitude $\langle S \rangle$ in Eq. (A4) (left) and specific heat C_V in Eq. (3.1) divided by $k_B N$ (right) vs T for $c = 0.0, 0.05, 0.1$, and 0.2 , which are calculated in the NVT ensemble. The peak of C_V decreases with increasing c .

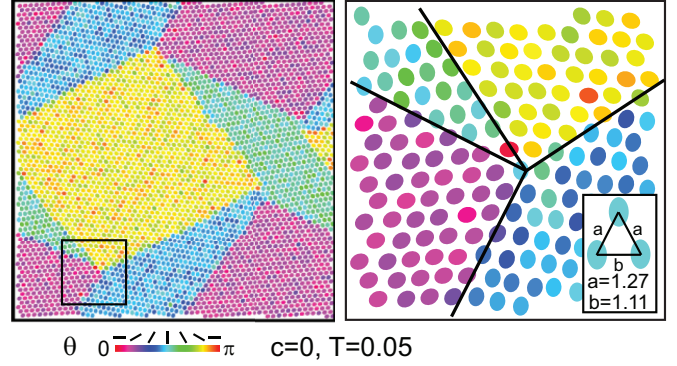


FIG. 2. (Color online) Left: Domain pattern composed of three martensitic variants for $c = 0$ at $T = 0.05$. Right: Elliptic particles around a junction of four domains in the box region in the left. The angles among the four lines are nearly equal to $\pi/2$ (for yellow square), $\pi/6$, $\pi/2$, and $5\pi/6$, being multiples of $\pi/6$. Each variant is composed of isosceles triangles with long side length $a = 1.27\sigma_1$ and short one $b = 1.11\sigma_1$ (inset). Colors represent $[\theta_i]_\pi$ according to the color bar.

about 0.02, where the disordered and ordered phases coexist. However, its T dependence becomes gradual for $c > 0$. The C_V exhibits a peak at the orientational transition, and its peak height decreases with increasing c . This peak stems from the enhanced orientation fluctuations near the transition.

In the same situation with the same N , we also performed simulation in the NpT ensemble with an isotropic applied stress in two dimensions (not shown in this paper), where we allowed the cell to take a rectangular shape. There, the transition was first-order with discontinuous changes in volume and entropy [39] as in three-dimensional KCN [3,5,7,9,11]. We also found a sharp peak in the isobaric specific heat C_p at the transition. For $c \gtrsim 0.1$, the impurities pin the domain growth and the NVT and NpT simulations provide essentially the same low- T behavior.

In previous experiments on $(\text{KCN})_{1-c}(\text{KBr})_c$, C_p exhibited peaks as a function of T at structural phase transitions for small c , but it varied continuously without peaks for large c [1,7]. In addition, the peak height for small c was of order $5k_B$ per molecule. These features are common to those of our specific heat results.

B. Structural phase transition for $c = 0$ and fragmentation of domains for $c > 0$

In the one-component case $c = 0$, the ellipses undergo a first-order structural (martensitic) phase transition from a hexagonal lattice to a deformed hexagonal lattice formed by isosceles triangles. The transition temperature is about 0.18 under Eq. (3.1) as indicated by Fig. 1. In Fig. 2 we show a typical orientational pattern of oriented domains for $c = 0$ below the transition at fixed V . Depicted are the angles,

$$[\theta_i]_\pi = \theta_i - k\pi, \quad (3.2)$$

in the range $[0, \pi]$ with k being an integer, where θ_i and $\theta_i \pm \pi$ are not differentiated. There appear three kinds of domains, which are called martensitic variants, with the same volume fraction $1/3$. Here n_i are aligned along one of the

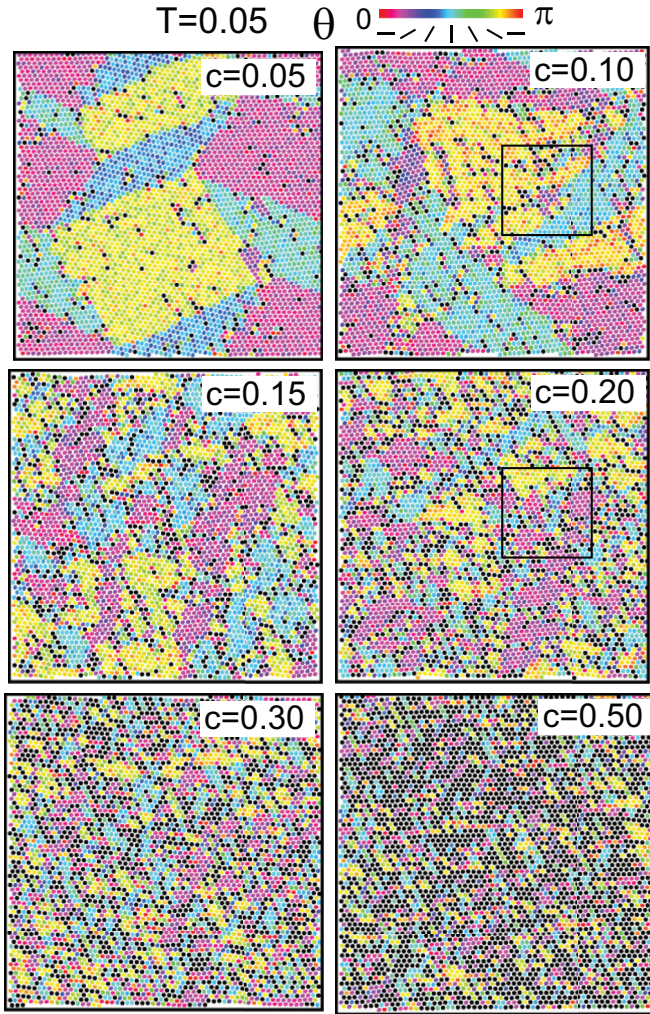


FIG. 3. (Color online) Frozen patterns of the angles θ_i of the ellipses at $T = 0.05$ for $c = 0.05, 0.1, 0.15, 0.2, 0.3,$ and 0.5 . Colors of the ellipses represent $[\theta_i]_\pi$ according to the color bar, and black points (\bullet) represent impurities. With increasing impurity concentration c , the domains become smaller, resulting in orientational glass.

underlying crystal axes, so each variant is composed of isosceles triangles elongated along its orientated direction. The domains are separated by sharp interfaces, where the surface tension is about $0.2\epsilon/\sigma_1^2$. As a unique feature, the junctions, at which domain boundaries intersect, have angles $\pi n/6$ ($n = 1, 2, \dots$) approximately. Similar unique domain patterns were experimentally observed on hexagonal planes after structural phase transitions [40]. They were also reproduced in 2D phase-field simulations [26,41].

Next, we examine how the domain structure is influenced by impurities. In Fig. 3 we present snapshots of $[\theta_i]_\pi$ at $T = 0.05$ for $c = 0.05, 0.1, 0.15, 0.2, 0.3,$ and 0.5 . At this low T , the thermal fluctuations are very small and the patterns of $[\theta_i]_\pi$ are nearly frozen in time even on a time scale of 10^5 , though flip rotations are still activated (see the bottom panels of Fig. 5). We note that the distribution of $[\theta_i]_\pi$ is peaked at the three angles along the crystal directions (even for $c = 0.5$; see Fig. 15). Remarkably, the domains gradually become

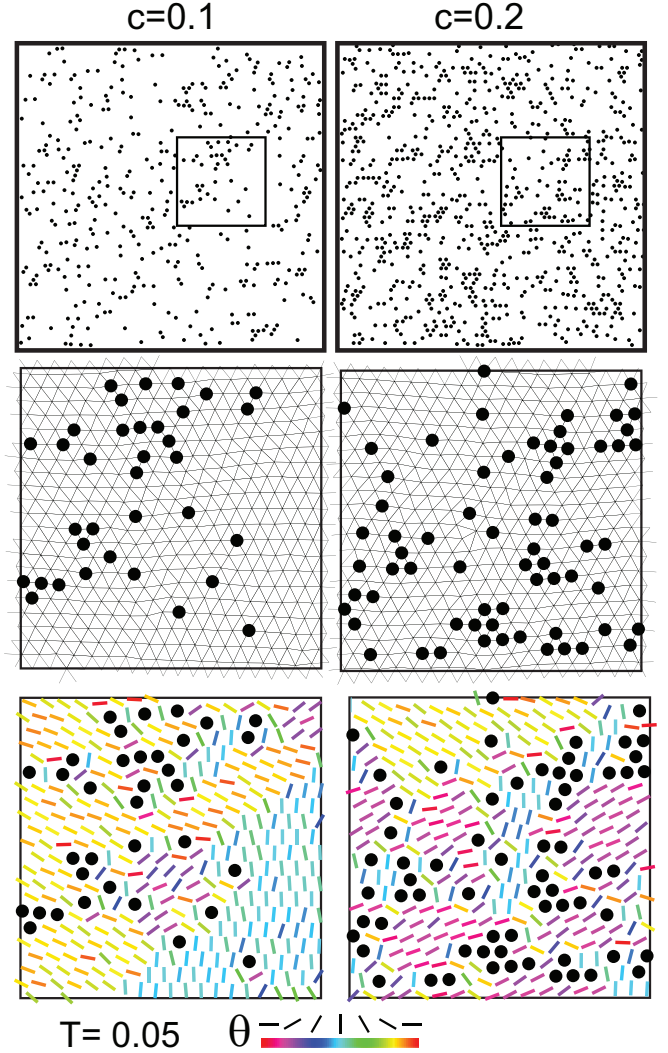


FIG. 4. (Color online) Top: Impurity distribution with significant clustering for $c = 0.1$ (left) and 0.2 (right) at $T = 0.05$. The data of these snapshots are common to those of $c = 0.1$ and 0.2 in Fig. 3. Middle: Delaunay diagrams in the box regions in the top panels (common to those in Fig. 3), mostly composed of isosceles triangles. Impurities are also shown (\bullet). Bottom: Expanded snapshots of ellipses around impurities in the same regions, exhibiting planar anchoring with $[\theta_i]_\pi$ according to the color bar.

finely divided with increasing c . For $c \gtrsim 0.2$, the orientational disorder is much enhanced, resulting in orientational glass.

To estimate the typical domain size, we calculated the structure factor of $\cos(2\theta_j)$,

$$S_2(q) = \frac{1}{N_1} \left\langle \left| \sum_{j \in 1} \cos(2\theta_j) \exp[i\mathbf{q} \cdot \mathbf{r}_j] \right|^2 \right\rangle. \quad (3.3)$$

Here we may fit $S_2(q)$ to the Ornstein-Zernike form $\text{const}(q^2 + \kappa^2)^{-1}$ to obtain $\kappa^{-1} = 5.2, 1.6, 0.9, 0.7,$ and 0.4 for $c = 0.15, 0.2, 0.3, 0.4,$ and 0.5 , respectively. The typical domain size is given by $2\pi/\kappa$. Though our cell length L is not very large, the finite-size effect is negligible for not very small c . For $c = 0$, the domain size becomes of order L at fixed V , and hysteresis behavior at the transition at fixed p [39] depends on L .

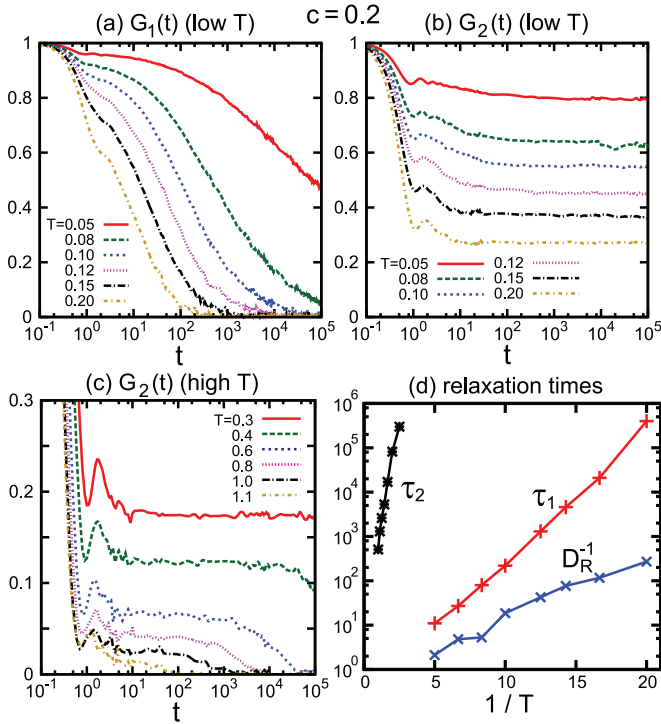


FIG. 5. (Color online) Orientational relaxations for $c = 0.2$ at various T . (a) $G_1(t)$ and (b) $G_2(t)$ at low $T = 0.05, 0.08, 0.10, 0.12, 0.15,$ and 0.20 . (c) $G_2(t)$ at relatively high $T = 0.3, 0.4, 0.6, 0.8, 1.0,$ and 1.1 . (d) Relaxation times τ_1 from $G_1(t)$ at low T in Eq. (4.3), τ_2 from $G_2(t)$ at high T in Eq. (4.4), and the inverse rotational diffusion constant D_R^{-1} in Eq. (4.12).

C. Impurity clustering and planar anchoring

The top panels of Fig. 4 display the overall impurity distributions for $c = 0.1$ and 0.2 at $T = 0.05$. We can see significant impurity clustering, which took place mostly during liquid states in the quenching process. In the present model, association of the impurities lowers the total potential energy by -0.4ϵ at $T = 0.4$ and -0.8ϵ at $T = 0.05$ per impurity [21].

In the middle plates of Fig. 4, the Delaunay triangulation is given for the particle configurations in the box regions in the upper panels, which are the dual graphs of the Voronoi diagrams. They are mostly composed of isosceles triangles in the inset of Fig. 2. With impurities of size ratio 1.2, the hexagonal lattice is locally elongated, where the number of triangles surrounding each particle (the coordination number) k is mostly 6. However, in Figs. 3 and 4, particles appear with $k = 5$ and some with $k = 7$. They are both two ellipses for $c = 0.1$, while they are both seven (including two impurities with $k = 7$) for $c = 0.2$. See Fig. 11(b) for such defects.

In the bottom panels of Fig. 4, we present expanded snapshots of anisotropic particles around impurities. The alignments are mostly perpendicular to the surface normals of the impurities, analogously to the planar anchoring of liquid crystal molecules near colloid surfaces [42]. We can also see interfaces between different domains.

To examine the degree of clustering of the impurities, let us group them into clusters. We assume that two impurities i and j belong to the same cluster if their distance is shorter

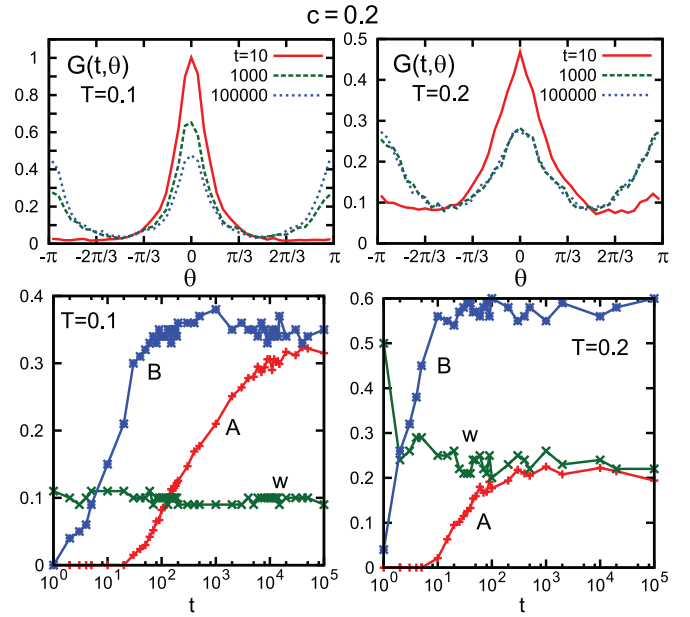


FIG. 6. (Color online) Top: Time-dependent angle distribution $G(t, \theta)$ in Eq. (4.5) for $c = 0.2$ at $t = 10, 10^3,$ and 10^5 . Here $T = 0.1$ and $\tau_1 = 220$ (left), and $T = 0.2$ and $\tau_1 = 220$ (right). Bottom: Parameters $A, B,$ and w in the approximate expression (4.8) for $T = 0.1$ and 0.2 as functions of t .

than 1.6. Then we calculate the numbers $N_1(\ell)$ of the ℓ clusters consisting of ℓ impurities, where $\sum_{\ell \geq 1} \ell N_1(\ell) = N_2$. The average cluster size is given by

$$\ell_1 = \sum_{\ell} \ell^2 N_1(\ell) / N_2. \quad (3.4)$$

In Fig. 3, we have $\ell_1 = 1.37, 2.04, 3.02, 4.79, 10.7,$ and 984 for $c = 0.05, 0.1, 0.15, 0.2, 0.3,$ and 0.5 , respectively. For $c = 0.5$, a cluster of the system size ~ 1400 appears.

IV. NVE SIMULATION OF ROTATIONAL DYNAMICS

In Figs. 5–11, we give simulation results in the *NVE* ensemble, where the average translational and rotational kinetic energies were kept at $k_B T$ and $k_B T/2$, respectively, per particle. Varying T , we examine the rotational dynamics at $c = 0.2$. For $0.3 \lesssim T \lesssim 0.7$, we realize the rotator phase, where nonflip rotations (with angle changes not close to $\pm\pi$) are gradually arrested with lowering T . For $T \lesssim 0.3$, quadrupolar glass is realized, where only flip rotations can be activated heterogeneously.

A. Rotational time-correlation functions

The rotational dynamics has been extensively investigated for anisotropic particles in glassy states [17–21]. We consider the rotational time-correlation functions $G_1(t)$ and $G_2(t)$ for the ellipses defined by

$$G_\ell(t) = \frac{1}{N_1} \sum_{j \in \ell} \langle \cos[\ell \Delta \theta_j(t_0, t_0 + t)] \rangle, \quad (4.1)$$

where $\ell = 1, 2$. We write the angle change of ellipse i as

$$\Delta\theta_i(t_0, t_1) = \theta_i(t_1) - \theta_i(t_0). \quad (4.2)$$

In Fig. 5 we show $G_1(t)$ and $G_2(t)$ for $c = 0.2$ at various temperatures. For low $T \leq 0.2$, the relaxation of $G_1(t)$ is slowed with lowering T in (a), while $G_2(t)$ tends to a plateau $f_2(T)$ for $t \gtrsim 10^2$ after considerable initial relaxations in (b). For higher $T \geq 0.4$, $G_2(t)$ decays at long times in (c). Relaxation times vs $1/T$ are plotted in (d), where τ_1 of $G_1(t)$ is determined by

$$G_1(\tau_1) = e^{-1}. \quad (4.3)$$

At long times, $G_2(t)$ relaxes only for $T \geq 0.4$, and its relaxation time τ_2 is determined by its fitting to the stretched exponential form:

$$G_2(t) \cong f_2 \exp[-(t/\tau_2)^\beta]. \quad (4.4)$$

In our case, we find $\beta \cong 1$. In the Arrhenius form, we obtain $\ln(\tau_1) = 0.68/T - 1.2$ for $T \lesssim 0.2$ and $\ln(\tau_2) = 4.2/T + 2.5$ for $T \gtrsim 0.4$. Note that these two temperature ranges are separated.

The difference between $G_1(t)$ and $G_2(t)$ can be understood if we consider the distribution of the angle changes,

$$G(t, \theta) = \frac{1}{N_1} \sum_{i \in 1} \langle \delta([\Delta\theta_i(t_0, t + t_0)]_{2\pi} - \theta) \rangle, \quad (4.5)$$

where $-\pi \leq \theta < \pi$. For any $\Delta\theta_i$, we set

$$[\Delta\theta_i]_{2\pi} = \Delta\theta_i - 2k\pi, \quad (4.6)$$

in the range $[-\pi, \pi]$ with an integer k . This $G(t, \theta)$ tends to $\delta(\theta)$ as $t \rightarrow 0$ and broadens gradually for $t > 0$. The $G_\ell(t)$ in Eq. (4.1) can be written as

$$G_\ell(t) = \int_{-\pi}^{\pi} d\theta G(t, \theta) \cos(\ell\theta). \quad (4.7)$$

In the top panels of Fig. 6, we plot time evolution of $G(t, \theta)$ for $c = 0.2$ at $T = 0.1$ and 0.2 . Salient features are as follows. (1) The width of the peak at $\theta = 0$, written as \sqrt{w} , soon tends to be independent of t . For $t \gg 1$, w represents the vibrational amplitude of the ellipses [see Eq. (4.10)]. We obtain $w = 0.09, 0.17, \text{ and } 0.22$ at $T = 0.1, 0.15, \text{ and } 0.2$, respectively. (2) For $t \gtrsim \tau_1$, $G(t, \theta)$ exhibits secondary peaks at $\theta = \pm\pi$ due to the flip motions $\theta_i \rightarrow \theta_i \pm \pi$. Their peak widths are nearly equal to that of the main peak at $\theta = 0$. (3) The midpoint values $G(t, \pm\pi/2)$ become appreciable at long times.

We may thus approximate $G(t, \theta)$ as a superposition of a constant and Gaussian functions as

$$G(t, \theta) \cong \frac{B}{2\pi} + \frac{1-A-B}{\sqrt{2\pi}w} e^{-\theta^2/2w} + \frac{A}{\sqrt{2\pi}w} [e^{-(\theta-\pi)^2/2w} + e^{-(\theta+\pi)^2/2w}], \quad (4.8)$$

where A is the turnover probability of an ellipse and $B/2\pi$ is the homogeneous part. We fit the calculated $G(t, \theta)$ to the above form to obtain $w(t)$, $A(t)$, and $B(t)$ vs t for $T = 0.1$ and 0.2 in the bottom panels of Fig. 6. Here $w(t)$ and $B(t)$ are nearly constant for $t \gg 1$, while $A(t)$ tends to saturate for $t \gtrsim 10^5$ at $T = 0.1$ and for $t \gtrsim 10^3$ at $T = 0.2$. Also w remains so small such that the Gaussian functions in Eq. (4.8) are negligible at

the midpoints $\theta = \pm\pi/2$ compared to $B/2\pi$. The plateau f_2 of $G_2(t)$ in Fig. 5(b) is expressed as

$$f_2 \cong (1-B) \exp(-2w). \quad (4.9)$$

Substitution of the calculated values of B and w into the above expression yields $f_2 = 0.54, 0.37, \text{ and } 0.26$ for $T = 0.1, 0.15, \text{ and } 0.2$, respectively, in excellent agreement with f_2 in Fig. 5(b). On the other hand, at higher $T \gtrsim 0.4$, the system is in the plastic solid phase and $G(t, \theta)$ tends to be homogeneous ($=1/2\pi$) very slowly for $t \gg \tau_2$, leading to the long-time decay of $G_2(t)$ in Fig. 5(c).

We comment on the meaning of w in Eq. (4.8). Let $\bar{\theta}_i$ be the time average of θ_i over many vibrations, where we neglect flip rotations. Then we have $\Delta\theta_i(t_0, t_1) = \delta\theta_i(t_1) - \delta\theta_i(t_0)$ in Eq. (4.2), where $\delta\theta_i = \theta_i - \bar{\theta}_i$ is the deviation from the equilibrium angle $\bar{\theta}_i$. With increasing $t = t_1 - t_0$, $\delta\theta_i(t_1)$ and $\delta\theta_i(t_0)$ should become uncorrelated to give $\sum_i \delta\theta_i(t_1)\delta\theta_i(t_0)/N_1 = 0$ so that

$$w = 2\langle \delta\theta^2 \rangle = 2 \sum_{i \in 1} |\delta\theta_i|^2 / N_1, \quad (4.10)$$

where $\langle \delta\theta^2 \rangle$ is the variance of $\delta\theta_i$ over all the ellipses.

B. Angular mean-square displacement

In the literature [17,18], the rotational diffusion has been discussed in terms of the angular mean-square displacement. In our case, it is defined for the ellipses as

$$M_\theta(t) = \langle (\Delta\theta)^2 \rangle = \frac{1}{N_1} \sum_{i \in 1} [(\Delta\theta_i(t_0, t_0 + t))]^2, \quad (4.11)$$

which exhibits the ballistic behavior ($\propto t^2$) for $t \lesssim 1$ and the diffusion behavior for $t \gg 1$ as

$$M_\theta(t) \cong 2D_R t. \quad (4.12)$$

See Fig. 5(d), where $\ln(D_R^{-1}) = 0.33/T - 0.68$ in the Arrhenius form. These behaviors are analogous to those of the

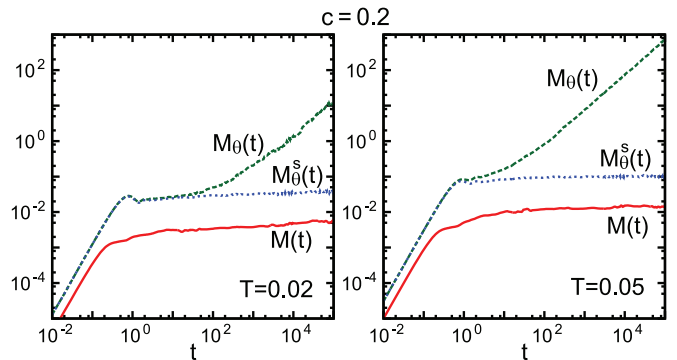


FIG. 7. (Color online) $M_\theta(t)$ in Eq. (4.11), $M(t)$ in Eq. (4.13), and $M_\theta^s(t)$ in Eq. (4.14) for $c = 0.2$ at $T = 0.02$ (left) and $T = 0.05$ (right). These are the averages of $\langle (\Delta\theta_i)^2 \rangle$, $|\Delta r_i|^2$, and $\sin^2(\Delta\theta_i)$, respectively. At these low T , $M(t)$ and $M_\theta^s(t)$ tend to plateaus, but $M_\theta(t)$ exhibits linear growth at long times due to flip rotations. Then D_R is 0.75×10^{-4} at $T = 0.02$ and 3.5×10^{-3} at $T = 0.05$. Transient plateau behavior can also be seen in $M_\theta(t)$ at $T = 0.02$.

positional mean-square displacement,

$$M(t) = \langle |\Delta \mathbf{r}|^2 \rangle = \frac{1}{N_1} \sum_{i \in 1} \langle |\Delta \mathbf{r}_i(t_0, t_0 + t)|^2 \rangle, \quad (4.13)$$

where $\Delta \mathbf{r}_i(t_0, t_0 + t) = \mathbf{r}_i(t_0 + t) - \mathbf{r}_i(t_0)$ is the displacement vector of ellipse i in time interval $[t_0, t_0 + t]$. In Fig. 7 we plot $M_\theta(t)$ and $M(t)$ vs t at low $T = 0.02$ and 0.05 for $c = 0.2$. Here $M(t)$ saturates at a plateau, but $M_\theta(t)$ still exhibits the diffusion behavior. As Fig. 6 suggests, this difference originates from flip rotations without positional changes. To confirm this, we also plot the mean-square displacement of $\sin(\Delta\theta_i)$ written as

$$M_\theta^s(t) = \frac{1}{N_1} \sum_{i \in 1} |\sin[\Delta\theta_i(t_0, t_0 + t)]|^2 / N_1, \quad (4.14)$$

which is insensitive to flip rotations. As ought to be the case, $M_\theta^s(t)$ coincides with $M_\theta(t)$ at short times but tends to a plateau at long times. We also notice that $M_\theta(t)$ exhibits a plateau in the range $1 \lesssim t \lesssim 100$ at $T = 0.02$.

C. Flip rotations in orientational glass

The rotational activity of the anisotropic particles sensitively depends on the surrounding particle configurations. In Fig. 8 we show typical time evolution of the angle changes. Rotationally inactive ellipses are those anchored to impurities and those within orientationally ordered domains, while rotationally active ones are those in disordered regions

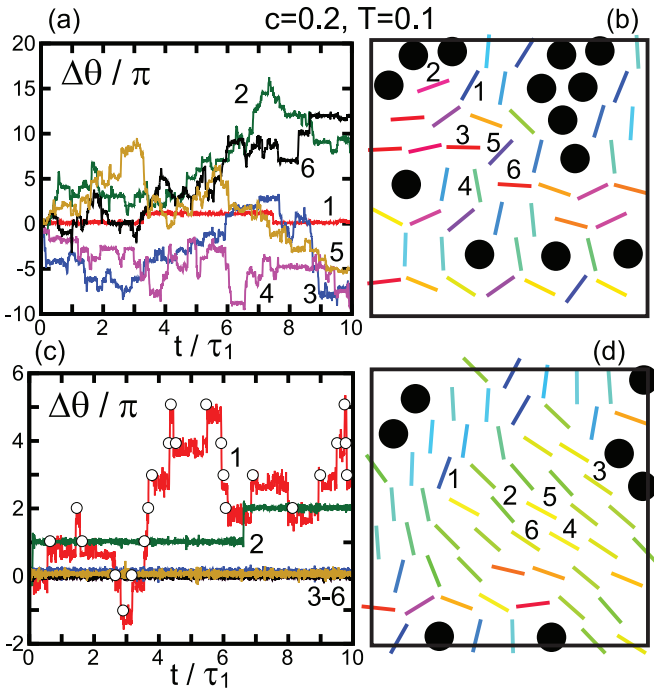


FIG. 8. (Color online) Time evolution of angle changes $\Delta\theta_i(t_0, t_0 + t)$ in Eq. (4.2) (left) for $c = 0.2$ and $T = 0.1$, where $\tau_1 = 220$. Selected ellipses are numbered 1, ..., 6 and impurities are written as large circles (\bullet) (right). (a) Rotationally active ellipses not anchored by impurities. Ellipse 2 is active though it is rather close to impurities. (c) Inactive ones in an orientationally ordered domain (3–6) and relatively active ones in an interfacial region (1 and 2). On the curve of ellipse 1, the flip times are marked (\circ) (see Appendix B).

not anchored to impurities and those in interfacial regions between different domains.

As will be shown in Appendix B, we may numerically determine flip events. That is, within any time interval $[t_0, t_0 + t_f]$, each ellipse i flips at successive times $t_0 + t_{i1}, t_0 + t_{i2}, \dots, t_0 + t_{ini}$ with $t_{i1} > 0$ and $t_{ini} < t_f$, where n_i is the flip number of ellipse i . The fraction of the ellipses with n flips is expressed as

$$\phi_n^f = \left\langle \sum_{i \in 1} \delta_{n, n_i} \right\rangle / N_1, \quad (4.15)$$

where $\sum_n \phi_n^f = 1$. We do not write the t_f dependence of n_i and ϕ_n^f explicitly. We divide the ellipses into groups $\mathcal{F}_0, \mathcal{F}_1, \dots, \mathcal{F}_{n_{\max}}$, where those in \mathcal{F}_n have undergone n flips in the time interval $[t_0, t_0 + t_f]$. We introduce the maximum flip number n_{\max} among all the ellipses. For large n and t_f , we should have the scaling relation,

$$\phi_n^f = \Phi_f(n/t_f)/t_f, \quad (4.16)$$

where $\Phi_f(x)$ is a scaling function. In particular, n_{\max} is proportional to t_f as

$$n_{\max} = A_{\max} t_f. \quad (4.17)$$

The coefficient A_{\max} is about 0.11 at $T = 0.1$ and 0.022 at $T = 0.05$.

We then introduce the angular mean-square displacement within the group \mathcal{F}_n as

$$\langle \Delta\theta^2 \rangle_n(t) = \frac{1}{N_1 \phi_n^f} \left\langle \sum_{i \in \mathcal{F}_n} [\Delta\theta_i(t_0, t_0 + t)]^2 \right\rangle, \quad (4.18)$$

which is a function of t for each given t_f . The total angular mean-square displacement is expressed as

$$M_\theta(t) = \sum_{1 \leq n \leq n_{\max}} \phi_n^f \langle \Delta\theta^2 \rangle_n(t). \quad (4.19)$$

For sufficiently large t and n , the ellipses in the group \mathcal{F}_n should have undergone nt/t_f flips on the average. Then, in the diffusion regime, we should have

$$\langle \Delta\theta^2 \rangle_n \cong \pi^2 nt/t_f. \quad (4.20)$$

Here the angle changes $\Delta\theta_i(t_0, t_0 + t)$ at jumps are π or $-\pi$, and their distribution should be nearly Gaussian.

In Fig. 9 we show numerical results which are the averages over six runs. We plot $t_f \phi_n^f = \Phi_f(x)$ in (a) and $n \phi_n^f = x \Phi_f(x)$ in (b) as functions of $x = n/t_f$ ($n \geq 1$) for $c = 0.2$ and $T = 0.1$ by setting $t_f/\tau_1 = 1, 5, 10$, and 20 (where $\tau_1 = 220$). These curves are nearly independent of t_f , which confirms the scaling form (4.16). However, the ellipses without flips still remain, whose fraction is $\phi_0^f = 0.17$ even for $t_f = 20\tau_1$. From Fig. 9(b), for large n , ϕ_n^f may be fitted to

$$\phi_n^f \cong A_f \left(\frac{1}{n} - \frac{1}{n_{\max}} \right), \quad (4.21)$$

where $A_f \cong 0.20$ and $n_{\max} \cong 500$ at $T = 0.1$. The A_f is independent of t_f . In panel (c) we also confirm Eq. (4.20). From Eqs. (4.12), (4.17), and (4.19)–(4.21), we obtain

$$D_R \cong \frac{1}{4} \pi^2 A_f A_{\max}, \quad (4.22)$$

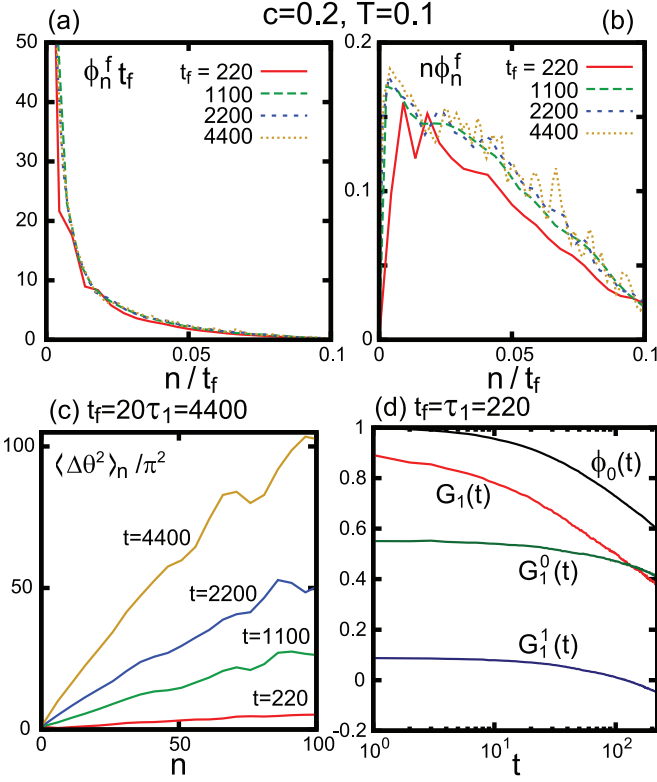


FIG. 9. (Color online) (a) $t_f \phi_n^f$ and (b) $n \phi_n^f$ vs n/t_f for $t_f/\tau_1 = 1, 5, 10$, and 20 with $\tau_1 = 220$. (c) $\langle \Delta \theta^2 \rangle_n(t)/\pi^2$ vs n at $t/t_f = 1, 5, 10$, and 20 . Here $c = 0.2$ and $T = 0.1$. See Eqs. (4.15) and (4.18) for ϕ_n^f and $\langle \Delta \theta^2 \rangle_n(t)$. (d) $G_1(t)$ in Eq. (4.1), $G_1^i(t)$ ($n = 0, 1$) with $t_f = \tau_1$ in Eq. (4.23), and $\phi_0(t)$ in Eq. (4.24).

which yields $D_R \sim 0.056 \sim 13/\tau_1$ at $T = 0.1$ in good agreement with the result from the slope of $M_\theta(t)$. At $T = 0.05$, we again find Eq. (4.21) with $A_f \cong 0.048$, $n_{\max} \cong 2800$, and $\phi_0^f \cong 0.58$ for $t_f = 10^5$. From Eq. (4.22) these lead to $D_R = 0.0033 \sim 1500/\tau_1$, while the right panel of Fig. 7 yields $D_R = 0.0035$. The rotational diffusion constant D_R is thus determined by the rotationally active ellipses with $n_i \sim n_{\max}$.

In contrast, the main contribution to $G_1(t)$ in Eq. (4.1) is from the ellipses which have undergone no flip in time interval $[t_0, t_0 + t]$. This is the reason why τ_1 behaves very differently from D_R^{-1} in Fig. 5(d). To show this, we set $t_f = \tau_1$. We then consider the following partial sums,

$$G_1^n(t) = \frac{1}{N_1} \left\langle \sum_{i \in 1, n_i=n} \cos[\Delta \theta_i(t_0, t_0 + t)] \right\rangle. \quad (4.23)$$

In Fig. 9(d) we compare $G_1^0(t)$ (no-flip contribution) and $G_1^1(t)$ (single-flip contribution) with $G_1(t)$. Here $G_1^0(\tau_1) = 0.41 = 1.11/e$ and $G_1^1(\tau_1) = -0.05$, so $G_1(\tau_1) = 1/e$ mostly consists of the no-flip contribution. We also display the fraction of the ellipses with no flip in time interval $[t_0, t_0 + t]$, denoted by $\phi_0(t)$. Treating ϕ_0^f in Eq. (4.15) as a function of t_f , we have

$$\phi_0(t) = [\phi_0^f]_{t_f=t}. \quad (4.24)$$

In Fig. 9(d) we find $\phi_0(\tau_1) = 0.60$. If $\phi_0(t)$ is shifted by 0.1 downward, it nearly coincides with $G_1(t)$.

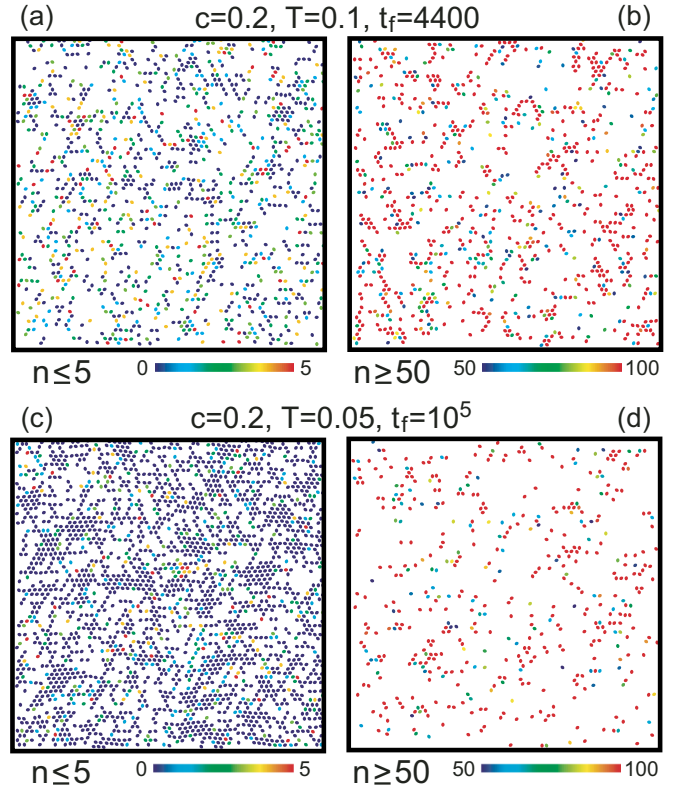


FIG. 10. (Color online) Top: Snapshots of ellipses at $T = 0.1$ with $n_i \leq 5$ (a) and $n_i \geq 50$ (b). Bottom: Snapshots of ellipses at $T = 0.05$ with $n_i \leq 5$ (c) and with $n_i \geq 50$ (d). Depicted ellipse fractions are (a) 0.36, (b) 0.27, (c) 0.72, and (d) 0.15. These rotationally inactive and active ellipses exhibit heterogeneities closely correlated with the impurity clustering (see the top right panel in Fig. 4).

In Fig. 10 we show snapshots of the ellipses with $n \leq 5$ (left) and $n \geq 50$ (right) for $T = 0.1$ and $t_f = 4400$ (top) and for 0.05 and $t_f = 10^5$ (bottom). The distributions of these rotationally inactive and active ellipses are highly heterogeneous. This marked feature is due to the significant impurity clustering in the top right panel in Fig. 4. With lowering T , the flip rotations become increasingly infrequent. In fact, the fraction of the ellipses with $n \geq 50$ are 0.36, 0.15, and 0.005 for $(T, t_f) = (0.1, 4400)$, $(0.05, 10^5)$, and $(0.02, 10^5)$, respectively.

D. Nonflip rotations in plastic solids at relatively high temperature

So far we have studied the rotational dynamics in orientational glass. We should also examine the crossover from plastic solid to orientational glass at higher T . In this high T regime, the long-time decay of $G_2(t)$ first saturates at the plateau in Eq. (4.9) and slowly decays to zero on the time scale of τ_2 as in Fig. 5(c). Some ellipses are attached to impurities on very long time scales, and the homogenization of $G(t, \theta)$ takes a very long time.

In Fig. 11 we hence display large nonflip rotations and long-distance displacements between two times t_0 and $t_0 + t$ with $t = 10^5$ for $c = 0.2$ and $T = 0.4$. Here the particle positions

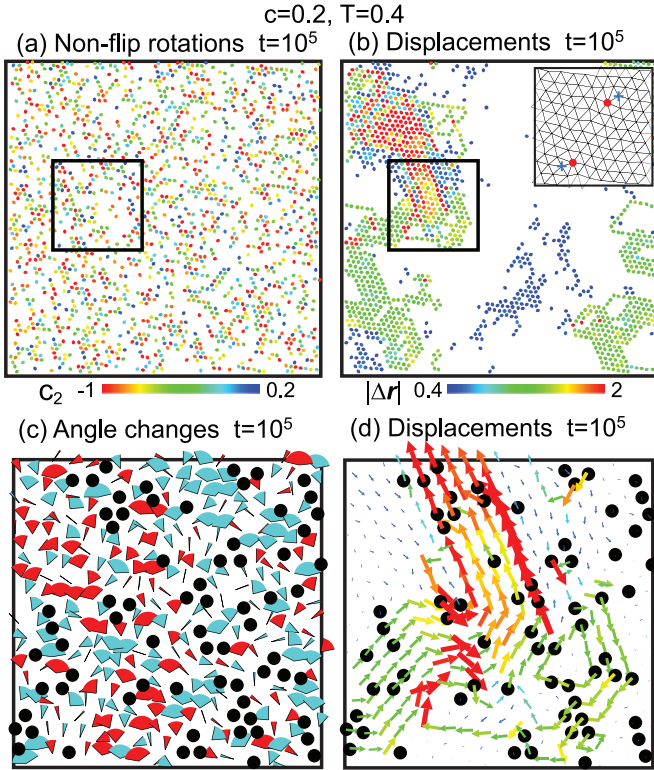


FIG. 11. (Color online) Nonflip rotations and displacements between two times t_0 and $t_0 + t$ with $t = 10^5$ for $c = 0.2$ and $T = 0.4$, where orientational glass is approached from plastic solid. (a) Particles with $c_{2i} = \cos[2\Delta\theta_i] < 0.2$ forming clusters and (b) those with large displacements $\Delta r_i > 0.4$ caused by defect motions. Depicted particle numbers are $0.50N_1$ (a) and $0.35N$ (b). Colors represent c_{2i} and Δr_i according to the color bars. Expanded snapshot of defects is also given (inset). (c) Expanded snapshot of the ellipses in the box region in (a), where each ellipse i is written as a circular sector with two arcs parallel to $\mathbf{n}_i(t_0)$ and $\mathbf{n}_i(t_0 + t)$. They are shown in blue for clockwise rotation ($\Delta\theta_i < 0$) and in red for counterclockwise rotation ($\Delta\theta_i > 0$). Impurities are also depicted (\bullet). (d) Expanded snapshot of the particles with large displacements in the box region in (b), where red (green) arrows represent displacements by two (one) lattice constants.

depicted are those $\mathbf{r}_i(t_0)$ at the initial time t_0 . The flip numbers of the ellipses in this time interval are huge, ranging from 10^3 to 10^4 . In panel (a) we pick up the ellipses with $c_{2i}(t) < 0.2$, where we define

$$c_{2i}(t) = \cos[2\Delta\theta_i(t_0, t_0 + t)]. \quad (4.25)$$

Because c_{2i} is invariant with respect to turnovers $\theta_i \rightarrow \theta_i \pm \pi$, it deviates from unity significantly due to nonflip rotations. The condition $c_{2i}(t) < 0.2$ means $0.22\pi < [\Delta\theta_i(t_0, t_0 + t)]_\pi < 0.78\pi$ in terms of $[\Delta\theta_i]_\pi$ in Eq. (3.2). In panel (b), we mark the particles with $\Delta r_i(t) = |\mathbf{r}_i(t_0 + t) - \mathbf{r}_i(t_0)| > 0.4$. These displacements are induced by intermittent motions of a few pointlike defects. As in the inset of Fig. 11(b), they are composed of two particles with their coordination numbers equal to five and seven (see the explanation of the middle panels in Fig. 4 also). These defects have been observed in a number of simulations and experiments in two dimensions [43]. The lengths of the large displacements are then mostly a

or $2a$ with a being the lattice constant, so they do not affect the hexagonal crystal structure. In panel (c), an expanded snapshot of the box region in panel (a) is presented, where each ellipse i is written as a circular sector with two arcs parallel to $\mathbf{n}_i(t_0)$ and $\mathbf{n}_i(t_0 + t)$. In panel (d), an expanded snapshot of the box region in panel (b) is presented with displacement vectors in arrows.

In Fig. 11(a) we can see marked clustering of many ellipses with significant nonflip rotations, which is strongly correlated with the heterogeneous impurity distribution. In Fig. 11(c), we further notice the presence of considerable thermal motions superimposed. Also in regions without defects [in the upper middle part from Fig. 11(b)], we may also write expanded figures, but they are similar to Fig. 11(c). Let $N_{cl}(\ell)$ be the numbers of the ℓ clusters consisting of ℓ ellipses with $c_{2i} < 0.2$, where two ellipses i and j belong to the same cluster for $r_{ij} < 1.6$. As in Eq. (3.4), the average cluster size may be defined as

$$\ell_{cl} = \sum_{\ell} \ell^2 N_{im}(\ell) / N_1. \quad (4.26)$$

Then we find $\ell_{cl} = 48$ for the snapshot in Fig. 11(a).

V. RHEOLOGY IN ORIENTATIONAL GLASS

In Figs. 12–15, we imposed a Parrinello-Rahman barostat [37] together with a Nosé-Hoover thermostat [36] under the periodic boundary condition. In our system, small crystalline domains are elongated along the orientations of the ellipses and their orientation changes can induce a macroscopic strain. We predict a shape memory effect and a superelasticity effect in orientational glass, where soft elasticity appears without dislocations.

A. Shape memory effect

We stretched the system along the y axis keeping the cell shape rectangular under the isothermal condition at $T = 0.05$. We mention similar simulations of stretching in Refs. [30,44]. In the following figures, the x and y axes are in the horizontal and vertical directions, respectively. One crystal axis of the crystal was made parallel to the x axis. Then one variant is elongated along the y axis, and the other two are elongated in the directions making an angle of $2\pi/3$ with respect to the y axis.

We controlled the space average of the yy component of the stress. Its value is written as

$$\sigma = \langle \sigma_{yy} \rangle_s, \quad (5.1)$$

where $\langle \cdot \cdot \rangle_s$ denotes the space average. The system was assumed to be stress-free along the x axis. Thus,

$$\langle \sigma_{xx} \rangle_s = 0, \quad (5.2)$$

which is possible owing to the attractive part of the potential [44]. From the symmetry of the geometry, we also have $\langle \sigma_{xy} \rangle_s = 0$. In our simulation, we started with a stress-free state with $\sigma = 0$ in a square cell with length L_0 . With applied stress, the cell lengths along the x and y axes were changed to L_x and L_y . The average strain along the y axis is given by

$$\varepsilon = L_y / L_0 - 1. \quad (5.3)$$

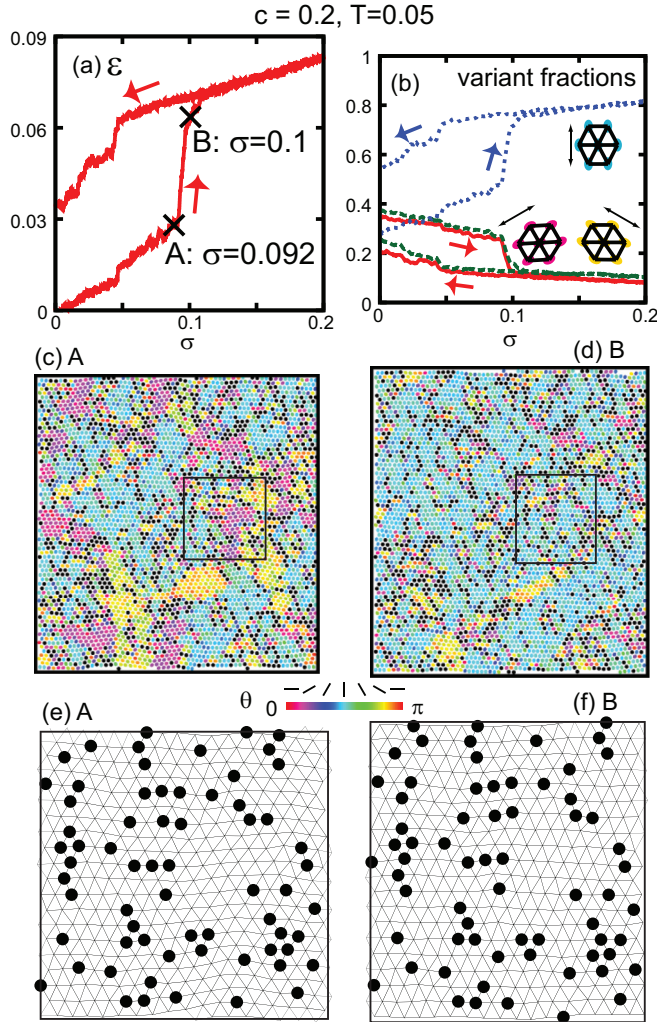


FIG. 12. (Color online) Shape memory effect for $c = 0.2$ and $T = 0.05$. (a) Strain ϵ vs applied stress σ . Between points A ($\sigma = 0.092$) and B ($\sigma = 0.10$), the domains elongated along the y axis increase yielding soft elasticity. The favored domains remain dominant on the return path. After this cycle, the residual strain vanishes upon heating to $T = 0.1$. (b) Fractions of the three kinds of domains (variants) during the cycle, which are elongated along the three crystal axes. (c) and (d) $[\theta_i]_{\pi}$ are written at points A and B in (a). (e) and (f) Delaunay diagrams of the box regions in (c) and (d) are given.

The effective Young modulus is defined by

$$E_e = (d\epsilon/d\sigma)_T^{-1}. \quad (5.4)$$

Here E_e nonlinearly depends on σ , but we may define the effective shear modulus μ_e using the linear elasticity relation $E_e = 4K\mu_e/(K + \mu_e)$, where K is the bulk modulus related to the volume $V = L_x L_y$ by $2\sigma/K = V/L_0^2 - 1$. In our system, $K \gg E_e/4$ holds so that

$$\mu_e = E_e/(4 - E_e/K) \cong E_e/4. \quad (5.5)$$

Hereafter we measure σ and E_e in units of ϵ/σ_1^2 .

In Fig. 12(a) we increased σ slowly as $d\sigma/dt = 4 \times 10^{-6}$ from 0 up to 0.2 and then decreased σ back to 0 as $d\sigma/dt = -4 \times 10^{-6}$. The stretching pass is divided into four parts:

(1) $0 < \sigma < 0.04$, (2) $0.04 < \sigma < 0.09$, (3) $0.09 < \sigma < 0.12$, and (4) $0.12 < \sigma < 0.20$, while the return path is divided into two parts: (5) $0.20 > \sigma > 0.05$ and (6) $0.05 > \sigma > 0$. The effective Young modulus E_e is very small in the range (3). In fact, we have $E_e \cong 0.25$ between two points A ($\sigma = 0.092$) and B ($\sigma = 0.10$) in Fig. 12(a), while $E_e \cong 4$ in the range (1) and $E_e \cong 8$ in the ranges (4) and (5). In addition, there appears a remnant strain (~ 0.03) at the final point $\sigma = 0$. Furthermore, if T was raised above 0.1 in this final state, an orientationally disordered state was realized and a square shape of the cell was restored. In this sense, we realize a shape-memory effect in our system.

In Fig. 12(b) we show the volume fractions of the three kinds of domains (variants). See the discussion below Eq. (5.9) as to how they can be determined. We can see that the favored domains elongated along the y axis increase and the disfavored ones decrease upon stretching. However, the favored domains do not much decrease in the return path, giving rise to the remnant strain. We also show the snapshot of the orientations at point A in (c) and that at point B in (d), between which the fractions of the favored variant are considerably different. In this stress cycle, a history-dependent loop is realized, where the impurities pin the orientation domains in quasistationary states under very slow variations of σ . In (e) and (f), we give Delaunay diagrams of the box regions in (c) and (d), where local strain variations can be seen without defects.

In Fig. 13 we show the orientational and positional changes between two points A and B in Fig. 12, which exhibit conspicuous large-scale heterogeneities. Displayed are (a) ellipses with large nonflip rotations with

$$c_{2i}(A, B) = \cos[2\theta_i(A) - 2\theta_i(B)] < 0.2 \quad (5.6)$$

and (b) particles with large nonaffine displacement

$$|\tilde{\Delta}\mathbf{r}_i(A, B)| > 0.4. \quad (5.7)$$

Here we write the angles and positions at A as $\theta_i(A)$ and $\mathbf{r}_i(A) = (x_i(A), y_i(A))$ and those at B as $\theta_i(B)$ and $\mathbf{r}_i(B) = (x_i(B), y_i(B))$. The x and y components of $\tilde{\Delta}\mathbf{r}_i(A, B)$ in Eq. (5.7) are defined by

$$\begin{aligned} \tilde{\Delta}x_i(A, B) &= x_i(B) - x_i(A)L_x(B)/L_x(A), \\ \tilde{\Delta}y_i(A, B) &= y_i(B) - y_i(A)L_y(B)/L_y(A), \end{aligned} \quad (5.8)$$

where $L_\mu(A)$ and $L_\mu(B)$ are the cell lengths at A and B ($\mu = x, y$). For affine deformations, $\tilde{\Delta}\mathbf{r}_i(A, B)$ vanishes.

As in Fig. 11(c), Fig. 13(c) displays the ellipses in the box region in panel (a) written as circular sectors, whose arcs are parallel to $\mathbf{n}_i(A)$ and $\mathbf{n}_i(B)$ [in blue for $\theta_i(A) < \theta_i(B)$ and in red for $\theta_i(A) > \theta_i(B)$]. The rotations are more collective with weaker thermal fluctuations than in Fig. 11(c). In panel (d), the particles with large nonaffine displacement (5.8) are written as arrows, which also indicates collective motions upon stretching. In both panels (c) and (d), the heterogeneities are strongly correlated with the inhomogeneous impurity distribution. The simulation time between A and B is 2000, so the flip numbers $n_i(A, B)$ between A and B are small. In fact, the ellipse number without flips $n_i(A, B) = 0$ is $0.75N_1$, while that with $n_i(A, B) \geq 5$ is $0.04N_1$ with $n_{\max}(A, B) = 10$.

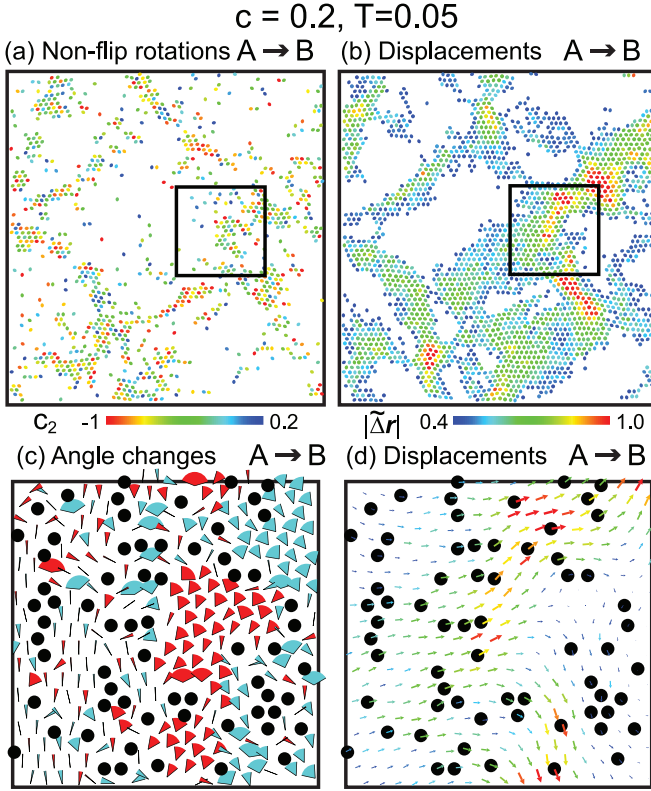


FIG. 13. (Color online) (a) Ellipses with large nonflip rotation $c_{2i} < 0.2$ and (b) particles with large nonaffine displacement $|\tilde{\Delta}r_i| > 0.4$ between two points A and B in Fig. 12, where soft elasticity is realized. Colors are given according to the color bars. (c) Expanded snapshot of the ellipses in the box region in (a), where each ellipse i is written as a circular sector with two arcs parallel to $\mathbf{n}_i(t_0)$ and $\mathbf{n}_i(t_0 + t)$ written in blue for clockwise rotation and in red for counterclockwise rotation. (d) Expanded snapshot of the particles with large nonaffine displacement in the box region in (b).

B. Superelasticity and angle distribution

We also find that the shape memory effect becomes weaker with increasing c , where the domain size is decreased. In Fig. 14 the hysteresis loop diminishes for $c = 0.3$ and vanishes for $c = 0.5$.

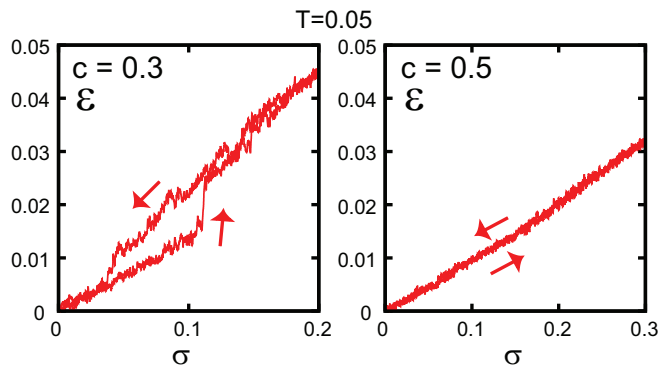


FIG. 14. (Color online) Stress-strain curve for $c = 0.3$ (left) and $c = 0.5$ (right). For $c = 0.3$ the loop is closed at positive σ and there remains no remnant strain (superelasticity). For $c = 0.5$ there is no hysteresis, and the curve is linear in the range $0 \leq \sigma \leq 0.3$.

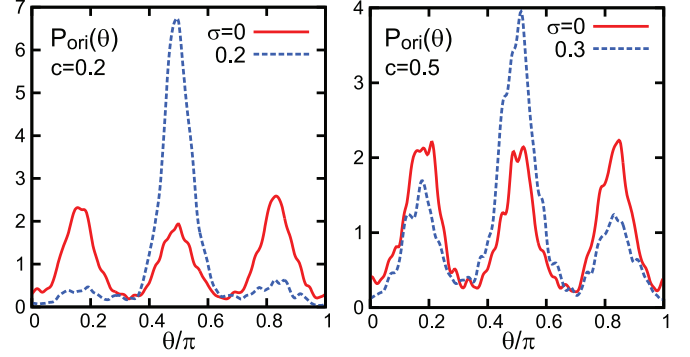


FIG. 15. (Color online) Orientational distribution $P_{\text{ori}}(\theta)$ in Eq. (5.9) for $c = 0.2$ (left) and 0.5 (right) for the initial point $\sigma = 0$ and the point with maximum σ (0.2 or 0.3) in the stress cycle. It has three peaks with equal heights for $\sigma = 0$ and the peak at $\theta \cong \pi/2$ is increased at the maximum σ .

for $c = 0.5$. We recognize that mesoscopic orientational order is responsible for the singular mechanical response. However, a unique feature arises for $c = 0.3$, though the loop is smaller; that is, the loop is closed at $\sigma \sim 0.03$ on the return path and the initial and final points coincide, resulting in no remnant strain at $\sigma = 0$. It is worth noting that this stress-strain behavior, called superelasticity, has been observed in metallic alloys as a stress-induced martensitic phase transition [27–29]. In TiNi, this superelasticity effect appears at higher temperatures than the shape memory effect. For a model alloy system, Ding *et al.* [30] numerically studied the superelasticity effect.

Furthermore, in Fig. 15 we plot the angle distribution,

$$P_{\text{ori}}(\theta) = \sum_{i \in 1} \delta([\theta]_{\pi} - \theta) / N_1, \quad (5.9)$$

at $T = 0.05$. Each curve was the result of a single run. This distribution has three peaks for both $c = 0.2$ and 0.5 in the directions of the three crystal axes and the peak at $\theta \cong \pi/2$ increases after stretching. This behavior is consistent with Fig. 12(b). Here we divide the ellipses into the three groups with $n/3 \leq [\theta]_{\pi}/\pi < (n+1)/3$ ($n = 0, 1, 2$) and calculate their volume fractions during stretching.

C. Orientational strain

On the stress-strain curve, we consider two points between which the curve is nearly linear. From Eq. (5.4) the stress change $\Delta\sigma$ and the strain change $\Delta\epsilon$ are related in terms of the effective Young modulus E_e by

$$\Delta\epsilon = E_e^{-1} \Delta\sigma. \quad (5.10)$$

Generally, in the presence of a (proper) coupling between strain and orientation, $\Delta\epsilon$ consists of three parts as

$$\Delta\epsilon = \Delta\epsilon_{\text{el}} + \Delta\epsilon_{\text{pl}} + \Delta\epsilon_{\text{ori}}. \quad (5.11)$$

First, the elastic part $\Delta\epsilon_{\text{el}}$ is approximately related to $\Delta\sigma$ by the linear elasticity relation,

$$\Delta\epsilon_{\text{el}} = E_0^{-1} \Delta\sigma. \quad (5.12)$$

where E_0 is the (bare) Young modulus in a single variant state being of order 20 in our case. Second, the plastic part $\Delta\epsilon_{\text{pl}}$

TABLE I. Stress change $\Delta\sigma$, strain change $\Delta\varepsilon$, Young modulus E_e , change of fraction of the favored variant $\Delta\phi_{va}$, fraction of orientational strain change γ_{ori} , and ratio E_e/γ_{el} for $c = 0.2$ and $T = 0.05$, which are calculated between two points on the stress-strain curves. The last quantity should be equal to E_0 from Eq. (5.12).

c	σ	$\Delta\sigma$	$\Delta\varepsilon$	E_e	$\Delta\phi_{va}$	γ_{ori}	E_e/γ_{el}
0.2	$0 \rightarrow 0.04$	0.04	0.010	4	0.05	0.75	16
0.2	$0.092 \rightarrow 0.1$	0.008	0.032	0.25	0.21	0.98	15
0.2	$0.12 \rightarrow 0.2$	0.08	0.011	8	0.04	0.55	18
0.3	$0 \rightarrow 0.1$	0.1	0.014	7	0.06	0.64	18
0.3	$0.11 \rightarrow 0.12$	0.11	0.010	1	0.06	0.94	18
0.3	$0.12 \rightarrow 0.2$	0.08	0.018	4	0.09	0.72	16
0.5	$0 \rightarrow 0.15$	0.15	0.014	11	0.04	0.43	19
0.5	$0.15 \rightarrow 0.3$	0.15	0.018	8	0.07	0.56	18

is due to plastic deformations. In the present example, there is no defect generation up to a large applied stress σ_y , where $\sigma_y \sim 0.5$ for $c = 0.2$. Thus,

$$\Delta\varepsilon_{pl} = 0 \quad (5.13)$$

in the absence of positional defects. Third, the orientational part $\Delta\varepsilon_{ori}$ is related to the change of the volume fraction of the favored variant $\Delta\phi_{va}$ as

$$\Delta\varepsilon_{ori} = A_0 \Delta\phi_{va}, \quad (5.14)$$

where we may calculate $\Delta\phi_{va}$ from the angle distribution $P_{ori}(\theta)$ in Eq. (5.9). We may also determine the coefficient A_0 if we apply the relation (5.14) between the initial point $(\sigma, \varepsilon) = (0, 0)$ and the final point $(\sigma, \varepsilon) = (0, 0.03)$ on the stress-strain loop in Fig. 12(a); that is, using $\Delta\phi_{va} = 0.2$ between these two points, we find $A_0 = 0.15$ for $c = 0.2$.

It is convenient to define the ratios,

$$\gamma_{el} = \Delta\varepsilon_{el}/\Delta\varepsilon, \quad \gamma_{ori} = \Delta\varepsilon_{ori}/\Delta\varepsilon. \quad (5.15)$$

In this paper we have $\gamma_{el} + \gamma_{ori} = 1$ from $\Delta\varepsilon_{pl} = 0$. From Eq. (5.10) we obtain

$$E_e = E_0(1 - \gamma_{ori}) = E_0\gamma_{el}. \quad (5.16)$$

In Table I we give examples of the quantities, $\Delta\sigma$, $\Delta\varepsilon$, E_e , $\Delta\phi_{va}$, γ_{ori} , and E_e/γ_{el} for $c = 0.2, 0.3$, and 0.5 at $T = 0.05$. We set $A_0 = 0.15$ for these three concentrations, though it has been obtained for $c = 0.2$. From Eq. (5.14) the last quantity E_e/γ_{el} should be equal to E_0 and is indeed calculated to be around 18.

VI. SUMMARY AND REMARKS

We have presented an angle-dependent Lennard-Jones potential for binary mixtures and performed MD simulation in two dimensions varying the concentration c and the temperature T . The aspect ratio is 1.23, and the size ratio is 1.2. Then, the crystal order is realized in all the examples treated. We have visualized heterogeneous and collective rotational dynamics and have predicted nonlinear strain effects. Our main results are as follows.

(1) In Sec. III, we have presented results of NVT simulation. First, the orientation amplitude $\langle S \rangle$ and the constant-volume specific heat C_V have been presented as functions of T

around the orientational transition in Fig. 1. Second, frozen orientational configurations at $T = 0.05$ have been displayed for $c = 0$ in Fig. 2 and for six concentrations in Fig. 3, where the domains are fragmented with increasing c . In our system, the circular impurities exhibit significant clustering and disturb the the orientations of the ellipses, as in Fig. 4.

(2) In Sec. IV, the rotational dynamics has been found to be very complex. In Fig. 5 $G_1(t)$ decays due to the thermally activated flip rotations even at low T , while $G_2(t)$ tends to a plateau at low T and decays to zero only in plastic solids due to the nonflip ones. At low T , the distribution of angle changes $G(t, \theta)$ evolves as in Fig. 6 and may be approximated as a sum of a constant and Gaussian functions.

(3) The distribution of the flip numbers n_i in appropriate time intervals has been found to be extremely broad as in Fig. 9. The rotational diffusion constant D_R from the angular mean-square displacement is determined by rapidly flipping ellipses, while $G_1(t)$ is determined by those without flips as in Fig. 9(d), leading to $D_R\tau_1 \gg 1$. The flip activity is closely correlated with the impurity distribution and is very heterogeneous as in Fig. 10.

(4) In Sec. V we have examined rheology of orientational glass at $T = 0.05$. For $c = 0.2$, we have found a shape memory effect due to the orientation-strain coupling in Fig. 12, where the stress-strain loop ends at zero stress with a remnant strain. When soft elasticity appears, the angle changes and the nonaffine displacements are highly heterogeneous and collective as in Fig. 13. For $c = 0.3$, we have found a superelasticity effect in Fig. 14, where the loop is closed at a nonvanishing stress. The angle distribution $P_{ori}(\theta)$ has three peaks and is changed by applied stress as in Fig. 15, from which we may calculate the orientational strain from Eq. (5.14).

We further make critical remarks, as follows.

(1) In this paper, the aspect ratio is rather close to unity. We should examine the glass transitions for various aspect ratios and molecular shapes. For large anisotropy, liquid crystal phases should appear [38], where the impurity effect has not yet been well understood. Mixtures of two species of anisotropic particles should also be studied.

(2) In analyzing the rheology, we have varied the applied stress at a fixed temperature. On the other hand, a nonlinear shear effect was observed in experiments of zero-field cooling and field cooling at static strain in $(\text{KBr})_{47}(\text{KCN})_{53}$ [45] and in $\text{Ti}_{48.5}\text{Ni}_{51.5}$ [46]. We will soon report on this thermal effect using our model.

(3) The impurity clustering leads to the broad flip-number distribution $\phi_n^f \propto n^{-1} - n_{\max}^{-1}$ in Fig. 9. This suggests that it strongly influences the underlying phase transition dynamics in various glassy systems. In particular, it has been neglected in spin glass theories [2,3]. It should also be relevant in the formation of nanopolar domains in ferroelectric glass [47].

(4) In real systems, the quadrupolar behavior can be expected only when the constituent molecules carry small dipole moments and exhibit no head-to-tail order at low T [1]. Experimentally, the dipolar freezing in mixtures of KCN-KBr (slowing of reorientational motions of CN^-) was found to occur at low T in a quadrupolar glass state [48]. On the other hand, for molecules with large dipole moments, an applied electric field can be important [49] and a ferroelectric transition can even occur.

(5) As mentioned in Sec. I, one-component systems of globular molecules become orientational glass [14–16]. However, to understand this phenomenon, we cannot use the physical picture for mixtures in this paper.

(6) In our recent paper [24], we have examined the effect of small impurities, to which host anisotropic particles are homeotropically anchored [42]. We stress that there can be a variety of angle-dependent molecular interactions, giving rise to a wide range of rotational and translational glass transitions.

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APPENDIX A: ORIENTATIONAL ORDER PARAMETER

Here we introduce an orientation tensor $\vec{Q}_i = \{Q_{i\mu\nu}\}$ ($\mu, \nu = x, y$) for each anisotropic particle $i \in 1$ by

$$\vec{Q}_i = \frac{1}{1 + n_b^i} \left(\mathbf{n}_i \mathbf{n}_i + \sum_{j \in \text{bonded}} \mathbf{n}_j \mathbf{n}_j \right) - \frac{1}{2} \vec{I}, \quad (\text{A1})$$

where $\vec{I} = \{\delta_{\mu\nu}\}$ is the unit tensor. In the summation over j , we pick up the ellipses in the region $|r_{ij}| < 1.6$ ($i, j \in 1$). The n_b^i is the number of these bonded ellipses. Thus, this tensor is a coarse-grained orientational order parameter as in liquid crystal systems. If a hexagonal lattice is formed, the nearest neighbor particles are included in this definition, so $n_b^i \sim 6$. This 2×2 tensor is traceless and symmetric, so it may be expressed as

$$Q_{i\mu\nu} = \sqrt{S_i} (d_{i\mu} d_{i\nu} - \delta_{\mu\nu}/2) \quad (\text{A2})$$

in terms of an amplitude S_i and a unit vector (director) $\mathbf{d}_i = (d_{ix}, d_{iy})$. For each i , S_i may be expressed as

$$S_i = 2 \sum_{\mu, \nu} Q_{i\mu\nu}^2, \quad (\text{A3})$$

which increases up to unity in ordered regions at low T and is about 0.1 in disordered crystals due to the thermal fluctuations. The degree of overall orientational order is represented by the average,

$$\langle S \rangle = \frac{1}{N_1} \sum_{i \in 1} S_i = \frac{2}{N_1} \sum_{i \in 1} \sum_{\mu, \nu} Q_{i\mu\nu}^2. \quad (\text{A4})$$

See Fig. 1 for a plot of $\langle S \rangle$ vs T .

APPENDIX B: FLIP TIMES AND NUMBERS

Here we determine a series of flip times, $t_0 + t_{i1} < t_0 + t_{i2} < t_0 + t_{i3} < \dots$, for each ellipse i in time interval $[t_0, t_0 + t_f]$. (1) The first flip time $t_0 + t_{i1}$ is determined in terms of $\Delta\theta_i(t) = \Delta\theta_i(t_0, t + t_0)$ by

$$|\Delta\theta_i(t_{i1})| = 2\pi/3. \quad (\text{B1})$$

For $t > t_{i1}$ we introduce a shifted angle change,

$$\Delta\theta_{i1}(t) = \Delta\theta_i(t) \pm \pi, \quad (\text{B2})$$

where $+\pi$ or $-\pi$ is chosen such that $|\Delta\theta_{i1}(t_{i1} + 0)| < \pi/2$. (2) The second flip time $t_0 + t_{i2}$ is determined by

$$|\Delta\theta_{i1}(t_{i2})| = 2\pi/3. \quad (\text{B3})$$

For $t > t_{i2}$, we again shift the angle change as

$$\Delta\theta_{i2}(t) = \Delta\theta_{i1}(t) \pm \pi, \quad (\text{B4})$$

where $|\Delta\theta_{i2}(t_{i2} + 0)| < \pi/2$. (3) Repeating these procedures yields the successive flip times; see Fig. 8. Within any time interval $[t_0, t_0 + t_f]$, each ellipse flips at times $t_0 + t_{i1}, t_0 + t_{i2}, \dots, t_0 + t_{in_i}$ ($t_{i1} > 0$ and $t_{in_i} < t_f$), with n_i being the flip number of ellipse i .

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