Magnetic particle hyperthermia: Power losses under circularly polarized field in anisotropic nanoparticles

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The deterministic Landau-Lifshitz-Gilbert equation has been used to investigate the nonlinear dynamics of magnetization and the specific power loss in magnetic nanoparticles with uniaxial anisotropy driven by a rotating magnetic field, generalizing the results obtained for the isotropic case found by P. F. de Châtel, I. Nándori, J. Hakl, S. Mészáros, and K. Vad [J. Phys. Condens. Matter 21, 124202 (2009)]. As opposed to many applications of magnetization reversal in single-domain ferromagnetic particles, where losses must be minimized, in this paper, we study the mechanisms of dissipation used in cancer therapy by hyperthermia, which requires the enhancement of energy losses. We show that for circularly polarized field, the energy loss per cycle is decreased by the anisotropy compared to the isotropic case when only dynamical effects are taken into account. Thus, in this case, in the low-frequency limit, a better heating efficiency can be achieved for isotropic nanoparticles. The possible role of thermal fluctuations is also discussed. Results obtained are compared to experimental data.

DOI: 10.1103/PhysRevE.86.061404 PACS number(s): 82.70.-y, 87.50.-a, 87.85.Rs, 75.75.Jn

I. INTRODUCTION

The nonlinear dynamics of the magnetization in singledomain ferromagnetic nanoparticle systems has been the subject of intense study and is to date a challenging issue. Examples are ferromagnetic resonance, switching of magnetization, data storage based on magnetic devices, spintronics, etc. The applications that are strongly related to the present work are ferrofluids, magnetic resonance imaging (MRI), and other biomedical applications; see, e.g., Refs. [1–7]. While in most cases the energy loss per cycle has to be minimized, in cancer therapy by hyperthermia the goal is to enhance the heating efficiency of magnetic nanoparticles driven by an external magnetic field, preferably inside the malignant tumors. The common practice is to use a linearly polarized external magnetic field alternating at a frequency of the order of 10⁵ Hz. Indeed, in the case of the linearly polarized applied field, the optimization of energy loss with respect to the amplitude and frequency of the external field has been studied in detail [4,8,9]. It is natural to ask what is the dependence of the specific absorption rate on the nature of polarization, i.e., whether a better heating efficiency can be achieved by a circularly polarized applied field [5-7,10]. The study of dynamical effects of a circularly polarized field has received considerable attention [11–15]. Power losses for isotropic nanoparticles under a rotating field have also been investigated in the presence (see, e.g., Refs. [5,6]) or absence (see, e.g., Ref. [10]) of thermal effects, but no systematic analysis has been performed in order to investigate the effect of anisotropy on the energy absorption of nanoparticles in the low-frequency limit suitable for hyperthermia.

The relaxation and the energy loss of a single isotropic magnetic nanoparticle has been considered under a circularly polarized applied field in Ref. [10] when no thermal effects were included. In the low-frequency limit, the energy loss per cycle was found to be larger in the case of the linearly polarized applied field as compared to the circularly polarized one. Thermal effects for an isotropic system were studied in detail in Ref. [5]. In the limit of low frequency, the linearly

polarized field was found to produce more heat power for higher temperatures, too. However, recent experimental results [7] show a different picture; the linearly and the circularly polarized external field produced an equal heat power, at least for low frequencies. Since the immobility and the aggregation of particles into chains is a known feature of ferrofluids when the sample becomes very anisotropic, it is a natural question to ask whether the anisotropy can be responsible for the discrepancy between the theory and the experiment.

The goal of this paper is twofold. On the one hand, we consider the role of anisotropy in the possible enhancement of heat power of magnetic nanoparticles (in the absence of thermal effects) by generalizing the results obtained for the isotropic case found in Ref. [10]. On the other hand, we study whether the anisotropy can be used to explain the experimental results of Ref. [7]. The possible role of thermal fluctuations is also discussed.

The paper is organized as follows. In Sec. II, the deterministic Landau-Lifshitz-Gilbert equation has been given in the case of uniaxial anisotropy suitable for the description of magnetization dynamics for single magnetic nanoparticles (in the temperature range far from the Curie temperature). The specific power loss and energy loss is studied in the case of the circularly polarized applied field in Sec. III. Known results of the isotropic case are briefly summarized and compared to the findings of the present work done for nanoparticles with uniaxial anisotropy. In Sec. IV, we study the linearly polarized applied field in the limit of large anisotropy, and in Sec. V the possible modification of the findings by thermal fluctuations is discussed. Finally, Sec. VI stands for the summary.

II. LANDAU-LIFSHITZ-GILBERT EQUATION

In order to study the energy losses under repeated magnetization reversal, one can distinguish two different processes related to the mobility of magnetic particles in ferrofluids. Either the magnetic moment rotates within the particle (Néel regime [16]) or the particle rotates as a whole (Brown

regime). Another way to classify various types of relaxation mechanisms is related to the temperature. For example, if one considers relaxation far from the Curie temperature, then the magnetization process in a single-domain particle can be well described by means of the Landau-Lifshitz equation [17], which is mathematically equivalent to Gilbert's equation [18], with the appropriate definition of its coefficient [19,20]. This is referred as the Landau-Lifshitz-Gilbert (LLG) equation. For a complete description of relaxations close to the Curie temperature, thermal effects should be incorporated. However, in some cases (such as a rotating applied field) the LLG equation provides us reliable results on energy losses, even at higher temperatures.

In this work the focus is on the relaxation based on the dynamical effect obtained by the LLG equation for anisotropic nanoparticles. We argue that at least for small and relatively large anisotropy, findings of the present work can be used to study energy losses in a temperature range relevant for hyperthermia. An important feature of the LLG equation is that the magnetization vector's magnitude does not change under the influence of the external field. Thus, it is convenient to rewrite it in terms of the unit vector $\mathbf{M} = \mathbf{m}/m_S$, where m_S is the saturation magnetization. Then the LLG equation reads as

$$\frac{d}{dt}\mathbf{M} = -\gamma'[\mathbf{M} \times \mathbf{H}_{\text{eff}}] + \alpha'[[\mathbf{M} \times \mathbf{H}_{\text{eff}}] \times \mathbf{M}], \quad (1)$$

with the coefficients $\gamma' = \mu_0 \gamma_0/(1+\alpha^2)$ and $\alpha' = \mu_0^2 \gamma_0^2 \eta m_S/(1+\alpha^2)$, where μ_0 is the permeability of free space, γ_0 is the gyromagnetic ratio, and η is the dimensionful and $\alpha = \mu_0 \gamma_0 \eta m_S$ the dimensionless damping constant. Let us introduce an effective gyromagnetic ratio $\gamma = \gamma_0/(1+\alpha^2)$. Then the parameters of the LLG Eq. (1) can be rewritten as $\gamma' = \mu_0 \gamma$ and $\alpha' = \mu_0 \gamma \alpha$. It is important to note that the effective gyromagnetic ratio γ used in this paper is positive as opposed to the negative parameter of Ref. [10]. The cross denotes the vector product and the effective magnetic field acting on the magnetization **M** is defined as

$$\mathbf{H}_{\text{eff}} = \mathbf{H}_{\text{ext}} + \mathbf{H}_{\text{aniso}},\tag{2}$$

with the alternating or circulating applied (external) field \mathbf{H}_{ext} and the anisotropy field $\mathbf{H}_{\text{aniso}}$. Let us note that in this work all considerations have been done in the absence of a static field.

III. CIRCULARLY POLARIZED APPLIED FIELD

In this section we discuss the solution of the LLG equation [Eq. (1)] obtained for an immobile single-domain (isotropic and anisotropic) magnetic particle under circularly polarized, i.e., rotating applied (external) magnetic field. The applied field is assumed to rotate in the xy plane with an angular frequency ω

$$\mathbf{H}_{\text{ext}} = \frac{\omega_L}{\gamma'} (\cos(\omega t), \sin(\omega t), 0), \tag{3}$$

where $\omega_L = \gamma' |\mathbf{H}|$ is the Larmor frequency. (The angular velocity vector is perpendicular the the xy plane.) For the sake of simplicity we consider particles with uniaxial anisotropy, where the easy axis of the magnetization is chosen to be the z

axis, i.e., the anisotropy field is defined as

$$\mathbf{H}_{\text{aniso}} = \frac{\omega_L}{\gamma'} (0, 0, \lambda_{\text{eff}} M_z), \tag{4}$$

where M_z is the z component of the magnetization vector and the parameter $\lambda_{\rm eff}$ describes the strength of the anisotropy. With this particular choice of the anisotropy field, the arrangement used in the paper is identical to that investigated in Refs. [11, 12]. For a more detailed analysis, specifically when the effect of thermal fluctuations is also taken into account, the easy axis of magnetization has to be chosen arbitrarily (for linearly polarized case see, e.g., Ref. [22]), but this is out of the scope of the present work.

It is convenient to use a coordinate system in which the steady-state solution of the LLG equation [Eq. (1)] has the simplest form: a time-independent magnetization vector [10–12]. The transformation is done by an appropriate rotation [10]:

$$\underline{\underline{O_1}} = \begin{pmatrix} +\cos(\omega t) & +\sin(\omega t) & 0\\ -\sin(\omega t) & +\cos(\omega t) & 0\\ 0 & 0 & 1 \end{pmatrix}, \tag{5}$$

which transforms the LLG equation into a coordinate system, which rotates around the z axis with the applied magnetic field. The transformed z axis then points in the direction of the angular velocity vector ω . Denoting the Cartesian coordinates of the transformed magnetization

$$(u_x, u_y, u_z) = \underline{\underline{O_1}} \mathbf{M}, \tag{6}$$

the LLG equation [Eq. (1)] can be written as

$$\frac{du_x}{dt} = \omega u_y + \alpha_N u_y^2 + \alpha_N u_z^2
- \omega_L \lambda_{\text{eff}} u_y u_z - \alpha_N \lambda_{\text{eff}} u_x u_z^2,
\frac{du_y}{dt} = -\omega u_x - \omega_L u_z - \alpha_N u_x u_y
+ \omega_L \lambda_{\text{eff}} u_x u_z - \alpha_N \lambda_{\text{eff}} u_y u_z^2,
\frac{du_z}{dt} = \omega_L u_y - \alpha_N u_x u_z + \alpha_N \lambda_{\text{eff}} \left(1 - u_z^2\right) u_z,$$
(7)

where $\alpha_N = \alpha' | \mathbf{H} |$ is introduced. Let us note that $\lambda_{\rm eff}$ is dimensionless but α_N , ω , and ω_L are of dimension 1/s. However, by introducing a dimensionless time $\tilde{t} = t/t_0$, all the frequency parameters can be rewritten as dimensionless quantities such as $\tilde{\alpha}_N = \alpha_N t_0$, etc. For the sake of simplicity, we keep the original notation (without the tilde superscript), but the time and consequently the frequencies are considered as dimensionless parameters. Since the LLG equation retains the magnitude of the magnetization vector, only two of the Cartesian components are independent (\mathbf{u} is a unit vector in the rotating frame). In order to describe the orientation of the magnetization, let us introduce angles following the definition of Ref. [11]:

$$u_x = \sin \theta \cos \phi,$$

$$u_y = -\sin \theta \sin \phi,$$

$$u_z = \cos \theta.$$
(8)

Thus, in the rotating frame the LLG equation obtained for the three Cartesian coordinates [Eq. (7)] reduces to a set of differential equations for the two angles

$$\frac{d\theta}{dt} = \omega_L \sin\phi + \alpha_N \cos\theta \cos\phi - \alpha_N \lambda_{\text{eff}} \sin\theta \cos\theta,$$

$$\frac{d\phi}{dt} = \omega_L \cos\phi \frac{\cos\theta}{\sin\theta} + w - \alpha_N \frac{\sin\phi}{\sin\theta} - \omega_L \lambda_{\text{eff}} \cos\theta.$$
(9)

Let us note that the differential equations for θ and ϕ in Eq. (9) are identical to Eqs. (2) and (3) of Ref. [11] in the case of vanishing static field $(h_{\rm az}=0)$, if one makes the following identifications: $\omega_L \equiv h_{a\perp}/(1+\alpha^2)$, $\alpha_N \equiv \alpha h_{a\perp}/(1+\alpha^2)$, and $\lambda_{\rm eff} \equiv \kappa_{\rm eff}/h_{a\perp}$.

A. Isotropic case

In this subsection we briefly summarize the results obtained for the isotropic case in Ref. [10]. Numerical solutions of Eq. (9) derived for the isotropic case ($\lambda_{eff}=0$) with various initial conditions are plotted in Fig. 1 (for a set of parameters given in the figure caption). Two fixed points, a repulsive (circle) one and an attractive one, appear in the phase diagram. Both can be determined by the analytical solution of the algebraic fixed point equation derived from Eq. (7) in the case of vanishing anisotropy, i.e., for $\lambda_{eff}=0$. The solution for the attractive fixed point is [see Eq. (25) in Ref. [10]]

$$u_{x0} = \sqrt{\frac{\alpha_N^2 - \omega_L^2 - \omega^2 + \sqrt{4\alpha_N^2 \omega_L^2 + (\alpha_N^2 - \omega_L^2 - \omega^2)^2}}{2\alpha_N^2}},$$

$$u_{y0} = -\frac{\alpha_N^2 + \omega_L^2 + \omega^2 - \sqrt{4\alpha_N^2 \omega_L^2 + (\alpha_N^2 - \omega_L^2 - \omega^2)^2}}{2\omega\alpha_N},$$

$$u_{z0} = -\sqrt{1 - u_{x0}^2 - u_{y0}^2}$$
(10)

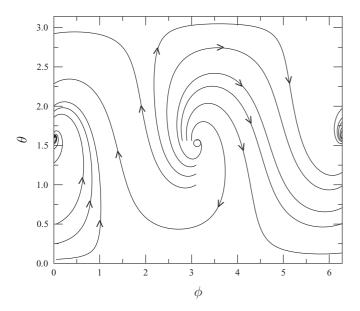


FIG. 1. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] for the isotropic case ($\lambda_{\rm eff}=0$) with the parameters $\alpha_N=0.1,\,\omega=0.01,\,\omega_L=0.2$. The circle indicates the repulsive fixed point at $\phi=3.12,\,\theta=1.53$. The attractive fixed point is at $\phi=0.02,\,\theta=1.61$.

(in the case of the repulsive fixed point u_{x0} and u_{z0} having been multiplied by -1). The attractive fixed point of the LLG equation in the rotating frame corresponds to the stable steady-state solution obtained in the laboratory frame [Eq. (24) in [10]]:

$$M_{x}(t) = u_{x0}\cos(\omega t) - u_{y0}\sin(\omega t),$$

$$M_{y}(t) = u_{x0}\sin(\omega t) + u_{y0}\cos(\omega t),$$

$$M_{z}(t) = u_{z0}.$$
(11)

The steady-state solution enables us to calculate the energy loss for a single particle. The energy dissipated in a single cycle can be calculated as [based on Eq. (11)]

$$E = \mu_0 m_S \int_0^{\frac{2\pi}{\omega}} dt \left(\mathbf{H} \frac{d\mathbf{M}}{dt} \right) = \mu_0 2\pi m_S H(-u_{y0}) \quad (12)$$

[see also Eq. (32) in [10]], which has the form in the low-frequency limit, $\omega \ll \alpha_N$,

$$E = 2\pi \mu_0 m_S H \left[\frac{\alpha_N \omega}{\omega_L^2 + \alpha_N^2} - \frac{\alpha_N \omega_L^2 \omega^3}{\left(\omega_L^2 + \alpha_N^2\right)^3} + \mathcal{O}(\omega^5) \right]. \quad (13)$$

Let us note that in Ref. [10] the energy loss per cycle of isotropic nanoparticles obtained by oscillating and rotating external fields have been analyzed in the absence of thermal effects; see, e.g., Fig. 2 in Ref. [10]. It was shown that in the low-frequency limit the energy loss per cycle was found to be larger in the linearly polarized case. In order to consider the role of thermal fluctuations in the case of isotropic samples, let us compare the findings of Ref. [5] (where thermal effects were included) to the findings of Ref. [10]. Dashed lines on Fig. 6 of Ref. [5] correspond to the limit $T \to 0$ and agree to the findings plotted in Fig. 2(a) of Ref. [10] qualitatively. The important result is that in the limit of low frequency, the linearly polarized field was found to produce more heat power both for T = 0 and for $T \neq 0$.

B. Anisotropic case

In order to study the role of anisotropy, let us follow the strategy applied in the isotropic case. Namely, we calculate the energy loss per cycle by determining the attractive fixed point solution of Eq. (7) for nonvanishing anisotropy ($\lambda_{eff} \neq 0$), which reads

$$0 = \omega u_y + \alpha_N u_y^2 + \alpha_N u_z^2 - \omega_L \lambda_{\text{eff}} u_y u_z - \alpha_N \lambda_{\text{eff}} u_x u_z^2,$$

$$0 = -\omega u_x - \omega_L u_z - \alpha_N u_x u_y + \omega_L \lambda_{\text{eff}} u_x u_z - \alpha_N \lambda_{\text{eff}} u_y u_z^2,$$

$$0 = \omega_L u_y - \alpha_N u_x u_z + \alpha_N \lambda_{\text{eff}} (1 - u_z^2) u_z,$$
(14)

which can be reduced for the following equation for u_z :

$$0 = \frac{1 - u_z^2}{u_z^2} \left[\left(u_z - \frac{r \,\omega_L}{\lambda_{\text{eff}}} \right)^2 + \left(u_z \frac{r \,\alpha_N}{\lambda_{\text{eff}}} \right)^2 \right] - \frac{1}{\lambda_{\text{eff}}^2}, \quad (15)$$

with $r = \omega/(\omega_L^2 + \alpha_N^2)$. Let us note that Eq. (15) is identical to Eq. (3.8) of Ref. [12] (with zero static field $\tilde{H} = 0$ and with $\rho = 1$) if the following identifications are used: $\tilde{h} \equiv 1/\lambda_{\rm eff}$, $\kappa \equiv r\omega_L/\lambda_{\rm eff}$, and $\lambda \equiv \alpha_N/\omega_L$. The switching of the nanoparticle magnetic moments and the dynamical effects under the action of rotating field have been studied in Ref. [12] with great details and further considered in Refs. [14,15];

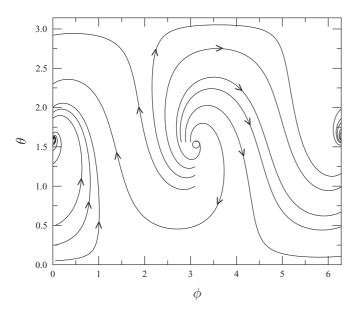


FIG. 2. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] in the limit of low frequency and small anisotropy for the parameters $\alpha_N = 0.1$, $\omega = 0.01$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 0.05$. It is similar but not identical to Fig. 1.

however, energy losses were not calculated, which is the goal of the present work.

Equation (15) can be solved analytically, which is used to calculate all the Cartesian coordinates of the attractive fixed point (or fixed points) in the rotating frame. If u_{y0} (y axis component of the attractive fixed point) is known, the energy loss per cycle can be evaluated similarly to the isotropic case. For biomedical applications such as hyperthermia, the low-frequency limit is relevant. Therefore, let us first consider the low-frequency $\omega \ll \alpha_N$ and small anisotropy $\lambda_{\rm eff} \ll 1$ limit, where one finds a single attractive fixed point with

$$u_{y0} \approx -\frac{\alpha_N \omega}{\omega_L^2 + \alpha_N^2} + \frac{\alpha_N \omega_L^2 \omega^3}{\left(\omega_L^2 + \alpha_N^2\right)^3} (1 + 2\lambda_{\text{eff}}).$$
 (16)

Inserting Eq. (16) into the expression of the energy loss per cycle [Eq. (12)], one finds

$$E \approx 2\pi \mu_0 m_S H \left[\frac{\alpha_N \omega}{\omega_L^2 + \alpha_N^2} - \frac{\alpha_N \omega_L^2 \omega^3}{\left(\omega_L^2 + \alpha_N^2\right)^3} (1 + 2\lambda_{\text{eff}}) \right], \tag{17}$$

which shows that in the low-frequency limit, the small anisotropy does not modify the energy loss per cycle obtained for the isotropic case. At higher frequencies, in the case of small anisotropy, a decrease is observed in the energy dissipated in a single cycle compared to the isotropic case. This analytic result is supported by the numerical integration of Eq. (9) (low frequency, small anisotropy; see Fig. 2), which is very similar to the isotropic case; see Fig. 1. Figures 1 and 2 are similar but not identical. Trajectories of the two figures, far from the fixed points, differ from each other (but the deviation is small). However, for low frequency and small anisotropy, the attractive and the repulsive fixed points of Figs. 1 and 2 coincide. The stability analysis done in Ref. [12] also confirms the existence of a single attractive fixed

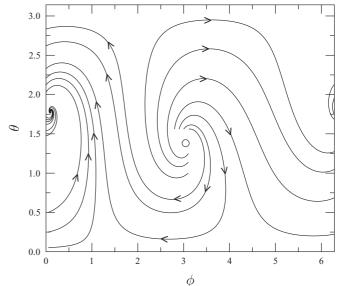


FIG. 3. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] (medium frequency and small anisotropy) for the parameters $\alpha_N = 0.1$, $\omega = 0.05$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 0.05$. According to numerical results, the attractive fixed point is at $\phi = 0.097995$, $\theta = 1.77908$, which gives $u_{y0} = -0.0957$.

point in this regime of the parameter space. The difference between the positions of the attractive fixed point obtained for the isotropic and anisotropic cases is more recognizable at higher angular frequencies. For example, according to the approximate expression Eq. (16), the attractive fixed point of Fig. 3 is at $u_{y0} = -0.0956$; numerical results give $u_{y0} = -0.0957$ and the corresponding isotropic case [see, Eq. (10)] gives $u_{y0} = -0.0961$. Thus, the energy loss per cycle (which is related to $-u_{y0}$) is decreased for the set of parameters used in Fig. 3 compared to the isotropic case (for the same ω , ω_L , and α_N).

Let us consider the low-frequency, large-anisotropy limit. In this case, one finds two attractive fixed points; see Fig. 4. The attractive fixed points are situated above (up) and below (down) the equator. In the strong anisotropy limit, their ϕ -components are the same and their θ components are symmetric to the equator; thus, their Cartesian components are $u_{x0}^{\rm up} = u_{x0}^{\rm down}$, $|u_{z0}^{\rm up}| = |u_{z0}^{\rm down}|$, and $u_{y0}^{\rm up} = u_{y0}^{\rm down}$. Therefore, both attractive fixed points have the same y components in the rotating frame, which reads as

$$u_{y0} \approx -\frac{\alpha_N \omega}{\omega_L^2 + \alpha_N^2} \frac{1}{\lambda_{\text{eff}}^2}.$$
 (18)

Inserting Eq. (18) into the expression of energy loss per cycle [Eq. (12)], one finds

$$E \approx 2\pi \mu_0 m_S H \left[\frac{\alpha_N \omega}{\omega_L^2 + \alpha_N^2} \frac{1}{\lambda_{\text{eff}}^2} \right], \tag{19}$$

which vanishes for $\lambda_{\rm eff} \to \infty$. In the limit of extremely large anisotropy, there is no room for energy dissipation, since the magnetization is aligned to the easy axis independent of the applied field. Indeed, for $\lambda_{\rm eff} \to \infty$, the xy-plane components tend to zero: $u_{x0} \to 0$, $u_{y0} \to 0$, and $u_z \to \pm 1$. In the $(\phi - \theta)$ plane, the attractive fixed points should tend to the "poles";

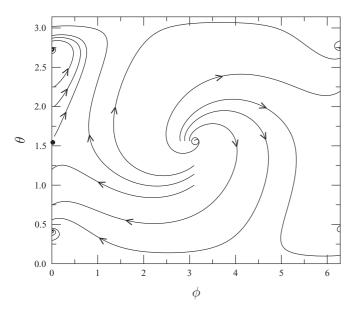


FIG. 4. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] in the limit of low frequency and large anisotropy for the parameters $\alpha_N = 0.1$, $\omega = 0.01$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 2.5$. Two attractive fixed points appear in the figure. The repulsive fixed point and the saddle point are indicated by a circle and a solid circle, respectively.

i.e., $\phi = 0$ and $\theta = 0,\pi$. If the anisotropy is decreased, they "move away" from the poles and tend to the equator; see Fig. 5. A critical value for the anisotropy parameter can be identified where one of the attractive fixed points [the one that corresponds to small θ , i.e., which lies above the equator, Eq. (8)] vanishes. The other attractive fixed point remains always below the equator. The phase diagram obtained in

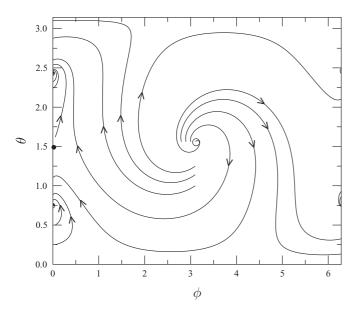


FIG. 5. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] (low frequency, large anisotropy) for the parameters $\alpha_N = 0.1$, $\omega = 0.01$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 1.5$. The attractive fixed points are closer to the equator as compared to Fig. 4, where the anisotropy was larger.

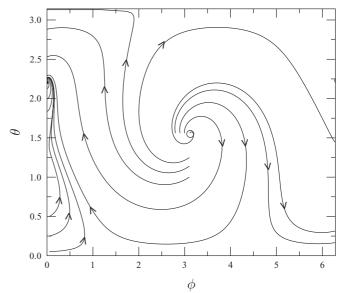


FIG. 6. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] in the limit of low frequency, slightly below the critical value of anisotropy. The parameters are $\alpha_N = 0.1$, $\omega = 0.01$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 1.175$. There is only a single attractive fixed point below the equator (large θ). The other attractive fixed point (above the equator, small θ) of the large anisotropic case and also the saddle point vanish in this regime of the parameter space.

the low-frequency limit, slightly below the critical value of anisotropy, is plotted in Fig. 6.

Let us consider the energy loss as a function of the anisotropy parameter. In Fig. 7, the energy loss is plotted versus λ_{eff} (for a set of parameters given in the figure), which shows that in the case of a rotating field the energy loss is a monotonic function of the anisotropy parameter. Thus,

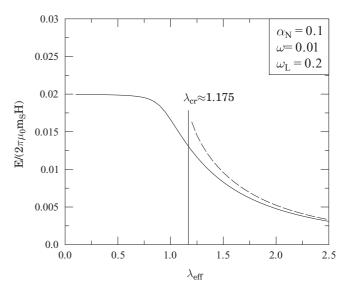


FIG. 7. The energy loss is plotted vs. the anisotropy λ_{eff} . There are two scaling regimes: one is at small and the other is at large anisotropy, which are separated by the critical value λ_{cr} . The solid line corresponds to energy loss obtained at the stable fixed point below the equator, and the dashed line represents energy loss at the fixed point above the equator, which is stable only for $\lambda_{eff} > \lambda_{cr}$.

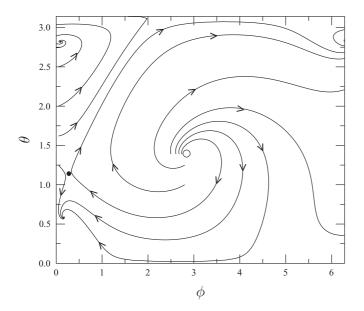


FIG. 8. Phase portrait in the rotating frame obtained by solving the LLG equation [Eq. (9)] in the limit of high frequency and large anisotropy for the parameters $\alpha_N = 0.1$, $\omega = 0.15$, $\omega_L = 0.2$, and $\lambda_{\rm eff} = 2.5$. There are two attractive fixed points in the figure similar to the low-frequency case (Fig. 4). Here, the attractive fixed points have different y components; thus, the corresponding energy losses also differ from each other.

according to our results, the anisotropy (where the easy axis is perpendicular to the rotating external field) cannot be used to increase the heating efficiency of magnetic nanoparticles in the low-frequency limit.

For the sake of completeness, let us consider the high-frequency limit, although it is out of the scope of the present work (irrelevant in case of cancer therapy by hyperthermia); hence, we do not study this in detail. The phase diagram obtained in the high-frequency and large-anisotropy limit is shown in Fig. 8 and can be compared to the one obtained for low frequencies (with the same anisotropy); see Fig. 4. The similarity between the high- and low-frequency cases is that two attractive fixed points appear. However, in the high-frequency case they have different coordinates in the $(\phi-\theta)$ plane. Thus, the energy losses correspond to the attractive fixed points differ from each other.

In summary, we conclude that the uniaxial anisotropy (where the easy axis is perpendicular to the rotating external field) either does not modify the energy loss per cycle (in the case of small anisotropy) or the energy dissipated is decreased as compared to the isotropic case.

IV. LINEARLY POLARIZED APPLIED FIELD IN THE LIMIT OF LARGE ANISOTROPY

One of the goals of this paper is to investigate the role of anisotropy in the possible enhancement of heat efficiency of magnetic nanoparticles driven by a rotating magnetic field. On the one hand, in the previous section it was obtained that in the case of circularly polarized applied field if the uniaxial anisotropy (perpendicular to the rotating external field) has been taken into account, the energy loss per cycle either remains unchanged (small anisotropy) or decreases (large

anisotropy). On the other hand, in Ref. [10] it was shown that for isotropic nanoparticles the linearly polarized external field provides us a larger heat power in the limit of low frequency. Furthermore, the latter statement was shown by Ref. [5] to be reliable in the presence of thermal effect, too. Thus, the circularly polarized applied field cannot be used to achieve a better heating efficiency by nanoparticle systems (neither for isotropic nor for anisotropic nanoparticles with uniaxial anisotropy) if the effect of thermal fluctuations is negligible. The role of thermal effects is discussed in Sec. V, where it is argued that the possible modification of the above finding by thermal fluctuations can only be expected in the case of moderate anisotropy. Thus, the results of the present work indicate that the heating efficiency cannot be increased by the rotating field, at least for small and very large anisotropy in the limit of low frequencies (independently whether thermal effect are included or not). This finding does not require any further analysis of the linearly polarized applied field.

However, the study of energy loss in the case of the linearly polarized applied field for anisotropic nanoparticles enables us to consider whether the large anisotropy can be used to explain the experimental results of Ref. [7]. Let us note the formation of chains by nanoparticles is a known feature of ferrofluids and the chains of particles represents a very large anisotropy [21]. Therefore, in this section we discuss the solution of the LLG equations [Eq. (1)] obtained for a single-domain magnetic nanoparticle under linearly polarized, i.e., alternating applied (external) magnetic field in the limit of large anisotropy. The applied field is assumed to oscillate along the x axis with an angular frequency ω ,

$$\mathbf{H}_{\text{ext}} = \frac{\omega_L}{\gamma'} (\cos(\omega t), 0, 0), \tag{20}$$

where $\omega_L = \gamma' |\mathbf{H}|$ is the Larmor frequency. Similar to the circularly polarized case, here we consider particles with uniaxial anisotropy. The easy axis of the magnetization is chosen to be the x axis (similar results can be obtained if it is chosen to be perpendicular to the x axis),

$$\mathbf{H}_{\text{aniso}} = \frac{\omega_L}{\gamma'} \ (\lambda_{\text{eff}} M_x, 0, 0), \tag{21}$$

where M_x is the x component of the magnetization vector and the parameter $\lambda_{\rm eff}$ describes the strength of the anisotropy. Note that in the case of alternating applied field, it is convenient to study the original LLG equation [Eq. (1)] instead of the rotated one [Eq. (7)]. The LLG equation for the Cartesian coordinates of the magnetization reads as

$$\frac{dM_x}{dt} = \alpha_N [\lambda_{\text{eff}} M_x + \cos(\omega t)] (1 - M_x^2),$$

$$\frac{dM_y}{dt} = -(\omega_L M_z + \alpha_N M_x M_y) [\cos(\omega t) + \lambda_{\text{eff}} M_x],$$

$$\frac{dM_z}{dt} = (\omega_L M_y + \alpha_N M_x M_z) [\cos(\omega t) + \lambda_{\text{eff}} M_x],$$
(22)

which has in general no analytic solution. In the limit of extremely large anisotropy $[\cos(\omega t) \ll \lambda_{\rm eff} M_x]$, however, the time-dependence of M_x can be determined as

$$M_x(t) = \pm \frac{\exp(\alpha_N \lambda_{\text{eff}} t)}{\sqrt{\exp(2\alpha_N \lambda_{\text{eff}} t) - C}},$$
 (23)

with $C = 1 - 1/M_{x0}^2$. If $t \to \infty$, the solution of Eq. (23) tends to ± 1 and the energy loss per cycle vanishes.

We conclude that in the case of a very large anisotropy the heat power of a magnetic nanoparticle driven by a linearly polarized applied field vanishes. The same was observed in the case of the circularly polarized external field. Thus, it is a natural requirement to obtain a comparable heat power given by the linearly and the circularly polarized applied fields if the anisotropy is large enough, which can explain the experimental results of Ref. [7]. Indeed, if the ferrofluid was not prepared appropriately, the nanoparticles can form chains and, consequently, the anisotropy could become large and the energy loss tends to zero rapidly.

V. THERMAL EFFECTS

In this work we studied the influence of anisotropy on the energy losses in the framework of the deterministic LLG equation in the absence of thermal fluctuations for rotating applied field. In this subsection, we discuss briefly how thermal effects (see, e.g., Refs. [22–24]) can possibly modify the results obtained by considering purely dynamical effects based on the LLG equation. Let us follow Refs. [12,14,15]. In case of a rotating field, the steady-state solutions of the dynamical problem are independent of the initial conditions of the individual particles. Therefore, the average magnetization can be easily determined by these (stable) steady states.

In the case of two steady-state magnetizations (up and down states), due to thermal effects, a nonzero probability of a transition from one stable state to another appears. This type of relaxation mechanism is missing in the present work due to the lack of thermal effects. We showed that large anisotropy is needed in order to have more than one stable state. It was also shown that if the anisotropy is not large enough, only a single fixed point appears in the phase portrait; thus, one has to consider only a single stable state. In this case, the modification caused by thermal effects is less important. Thus, thermal effects can only modify the determination of energy losses (in the case of a rotating applied field, for low frequencies relevant to hyperthermia) if the anisotropy is large enough but not too large (otherwise the barrier between one state to an other becomes too large).

Furthermore, let us compare Refs. [5,10] in order to consider the role of thermal effects in the case of isotropic samples. In these articles, energy losses were investigated both for alternating and for rotating applied field. Thermal effects were included in Ref. [5], while these are absent in Ref. [10]. For example, the dashed lines on Fig. 6 of Ref. [5] correspond to the limit $T \to 0$ and agree to the findings plotted in Fig. 2(a) of Ref. [10] qualitatively. Let us turn the attention of the reader to the logarithmic scale used in Fig. 2(a) of Ref. [10]. The modification caused by thermal effects (solid lines in Fig. 6) are less important for the rotating case but very significant for the alternating case in the limit of low frequencies. Nevertheless,

for low frequencies, the linearly polarized field was found to produce more heat power for both T=0 and $T\neq 0$.

According to Refs. [12,14,15], for small and for very large anisotropy the thermal effects are less important. It was shown in Ref. [5] that for isotropic samples, even for $T \neq 0$, the energy absorption per cycle for a nanoparticle was larger in the case of a linearly polarized applied field. Thus, if anisotropy (at least if it is small or very large) does not increase the energy losses obtained in the case of a rotating external field (which is one of the findings of the present work), a better heating efficiency can be achieved for isotropic nanoparticles using a linearly polarized field. This indicates that possible modification caused by thermal effects can only be expected in the case of moderate anisotropy. Therefore, the study of the present work is relevant for applications in hyperthermia, at least for small and very large anisotropy.

VI. SUMMARY

The nonlinear dynamics of magnetization and the energy loss of a single magnetic nanoparticle with uniaxial anisotropy have been considered under a circularly polarized applied field in the absence of thermal fluctuations. The easy axis of magnetization has been chosen to be perpendicular to the rotating applied field. We solved the deterministic Landau-Lifshitz-Gilbert equation in order to determine the energy loss per cycle in the case of the rotating applied field and the findings were compared to those of the isotropic case in Ref. [10]. Comparison between the linearly and circularly polarized applied fields has also been performed, and the results were analyzed in terms of the experimental data [7].

Our goal was twofold: (i) to study whether anisotropy can be used to achieve a better heating efficiency in the case of a rotating external field, and (ii) to use anisotropy to resolve the discrepancy between theory [10] and experiment [7]. We showed that for a circularly polarized field, the energy loss per cycle is decreased by anisotropy, compared to the isotropic case. Thus, in the low-frequency limit, more heat power can be achieved by alternating applied field for isotropic nanoparticles, at least the rotating applied field produces lower energy absorption for small and very large anisotropy. It was also shown that in the limit of extremely large anisotropy, the experimental results of Ref. [7] can be explained. The possible role of thermal fluctuations discussed here indicates the necessity of the extension of the present study for the case of moderate anisotropy when thermal effects are taken into account appropriately.

ACKNOWLEDGMENTS

This research was supported by the TÁMOP 4.2.1./B-09/1/KONV-2010-0007 project. Fruitful discussions with P. F. de Châtel, J. Hakl, Zs. Jánosfalvi, S. Nagy, and K. Vad are warmly acknowledged.

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