

Compaction dynamics of a magnetized powder

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We have investigated experimentally the influence of a magnetic interaction between the grains on the compaction dynamics of a granular pile submitted to a series of taps. The granular material used to perform this study is a mixture of metallic and glass grains. The packing is immersed in homogeneous external magnetic field. The magnetic field induces an interaction between the metallic grains that constitutes the tunable cohesion. The compaction characteristic time and the asymptotic packing fraction have been measured as a function of the Bond number which is the ratio between the cohesive magnetic force and the grain weight. These measurements have been performed for different fractions of metallic beads in the pile. When the pile is only made of metallic grains, the characteristic compaction time increases as the square root of the Bond number. While the asymptotic packing fraction decreases as the inverse of the Bond number. For mixtures, when the fraction of magnetized grains in the pile is increased, the characteristic time increases while the asymptotic packing fraction decreases. A simple mesoscopic model based on the formation of granular chains along the magnetic field direction is proposed to explain the observed macroscopic properties of the packings.

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I. INTRODUCTION

Over the last decade, the compaction of granular materials has been the subject of numerous studies in the physics community [1–5]. The majority of these studies are focused on cohesiveless granular materials. However, a better fundamental knowledge of cohesive powder properties is required for their manipulation, in particular within the recent development of nanopowder technology. Indeed, cohesive forces are known to strongly affect the flow and the static properties of fine powders, since they induce the formation of large aggregates [6].

The compaction process is commonly used in the industry to measure the static and the flow properties of a powder. The sample of powder is poured in a graduated glass tube and the initial volume of the powder is measured. Afterward, the sample is submitted to 500 calibrated taps. After this compaction process, the final volume is measured. By comparing the initial powder volume with the final volume, the flowability of a powder is estimated. This empirical protocol has been defined in 1965 [7] and is still used nowadays [8] despite the lack of precision and the weakness of the interpretations. A better fundamental understanding of the compaction process is necessary to increase the quality of this measurement in particular when cohesive powder is considered.

The compaction dynamics of cohesiveless granular material submitted to a series of taps has been studied experimentally, theoretically and numerically [9–17]. Different laws have been proposed for the evolution of the volume fraction η as a function of the number n of taps. Among others, one has proposed the inverse logarithmic law [9]

$$\eta(n) = \eta_{\infty} - \frac{\Delta\eta}{1 + B \ln\left(1 + \frac{n}{\tau}\right)}, \quad (1)$$

where the parameters η_{∞} and $\Delta\eta$ are, respectively, the asymptotic volume fraction and the maximum variation in

the volume fraction. The dimensionless parameter B depends on the acceleration during each tap and τ is the characteristic relaxation time for the grain reorganization process.

The difference between a powder and a granular assembly is the increase in the importance of cohesion forces in respect to the gravitation because the grains are much smaller in powder than in granular assembly. It is difficult to imagine a model powder for which it is possible to tune the size or shape of the grains independently to the cohesion. In order to study the influence of the cohesive forces on the properties of granular assemblies, several methods can be used. For example, one may change the size of the particles [18]. However, controlling the size and the shape of particles is a difficult task in particular for small cohesive objects. Liquid bridges can also be used to increase the interparticle forces [19] and, under certain conditions, to lubricate contacts [20] in addition to cohesive forces.

The idea of our study is the use the magnetic force to measure the impact of the cohesion on the compaction properties of a granular assembly. The interparticle force can be tuned continuously by varying the strength of the external magnetic field \vec{B} . This technique has previously been used to study the influence of the cohesion on the packing fraction [21,22] and on the avalanche angle [23] of granular assemblies. The choice of the size of grains (beads) is important: not too small to avoid “natural” cohesion, not too large to avoid the use of high magnetic field and to remain in powder conditions.

The influence of the magnetic field can be sum up as following. Each ferromagnetic particle becomes a magnetic dipole characterized by a magnetic moment $\vec{\mu}$. We assume that the magnetic moments $\vec{\mu}$ are parallel to the applied magnetic field \vec{B} . This is an approximation when we consider many interacting particles. The potential energy U_{ij} between two magnetic dipoles i and j separated by a distance r_{ij} (see Fig. 1) is given by

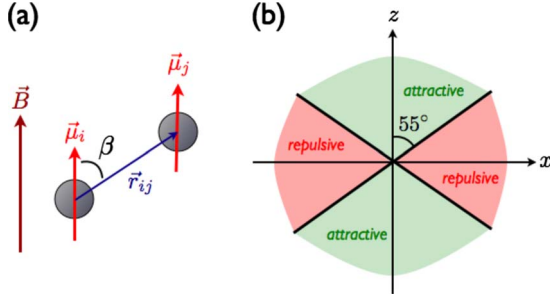


FIG. 1. (Color online) (a) Interactions between two ferromagnetic particles in a magnetic field \vec{B} . The $\vec{\mu}$ vector denotes the magnetic dipole induced by the magnetic field \vec{B} , \vec{r}_{ij} denotes the vector between the dipoles. (b) The magnetization of two ferromagnetic particles in a vertical magnetic field induces repulsive interaction when \vec{r}_{ij} is perpendicular to \vec{B} and attractive interaction when \vec{r}_{ij} is parallel to \vec{B} .

$$U_{ij} = \frac{\mu_0 \mu_i \mu_j}{4\pi} \frac{1 - 3 \cos^2 \beta}{r_{ij}^3}, \quad (2)$$

where β denotes the angle between the vector \vec{r}_{ij} and the magnetic field \vec{B} . As illustrated in Fig. 1, the potential is attractive when $\beta < 55^\circ$ and repulsive when $55^\circ < \beta < 90^\circ$. These interactions between the particles change significantly the internal structure of the packing and the force network. Moreover, due to the directional nature of the force acting between dipoles, anisotropic particle aggregates form along the field direction.

In this paper, we study the influence of the magnetic interaction between the grains on the compaction dynamics. The size of the grains has been chosen such as the cohesion is weak regards their weights and small enough to be considered as a powder. First, a granular material made of metallic beads has been used. Afterward, mixtures of glass and metallic beads have been considered. The compaction characteristic time τ and the asymptotic packing fraction η_∞ have been measured for different magnetic field strength and for different fraction ϕ of metallic beads in the mixture. At the end of the paper, a simple mesoscopic model is proposed in order to describe the properties of a magnetic packing.

II. EXPERIMENTAL SETUP

A sketch of our experimental setup is illustrated in Fig. 2. A glass tube of internal diameter $D=21$ mm is placed into a vertical magnetic coil where a constant current can be injected. The magnetic field is thus parallel to the gravity field. The strength of the magnetic field can be fixed between 0 and 150 G. We checked that the variation in the magnetic field along the vertical axis of the coil does not exceed 10%. The average diameter of both metallic and glass grains is $d=100$ μm with a polydispersity of about 50%.

In order to obtain a reproducible and spatially homogeneous initial packing fraction, the following initialization protocol has been used. A narrower and bottomless glass tube (external diameter slightly below 21 mm) is inserted into the main vessel. Afterward, the small tube is filled with

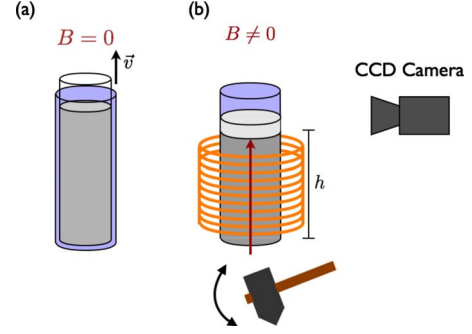


FIG. 2. (Color online) Sketch of the experimental setup. (a) An initialization protocol is used to obtain a reproducible and homogeneous initial packing fraction η_0 . A smaller bottomless tube is inserted into the main glass cylinder. This tube is filled with the granular material and is removed at constant speed v . (b) After the initialization process, the magnetic field B is set. An electromagnetic hammer produces periodic taps on the bottom of the system. A CCD camera take a picture of the top of the pile after each tap. In order to keep the granular/air interface flat, a light cylinder is placed on the top of the pile.

the granular material. The small tube is then removed upward at a low and constant velocity $v=1$ mm/s. The current in the coil is set after the initialization protocol in order to obtain a constant initial packing fraction η_0 . A light disk is gently placed on the top of the pile in order to keep it flat during the compaction process. The system used to produce the taps under the tube is an electromagnetic hammer as described in [13,24]. During one tap, the system undergoes a short peak of acceleration (the width of the peak is 0.25 ms and the maximum intensity is 15 g) and some damped oscillations during 2 ms. To obtain a compaction curve, two thousand taps are produced. Successive taps are separated by one second. So as the packing relaxes after each tap.

The packing fraction of the pile is measured by image analysis from a CCD camera. The average position h of the upper interface of the packing is measured after each tap and gives the packing fraction η by using the known value for the volumic mass ρ of the beads and the total mass m of grains. One has $\eta = \frac{4m}{\rho h D^2 \pi}$. The part of the pile situated above the coil is typically less than 10% of the total height of the pile.

To obtain a relationship between the magnetic field strength and the intergrain interactions, a reference magnetic field B_{ref} has been measured. This reference magnetic field gives the balance between the magnetic force acting on two contacting grains aligned with the magnetic field and the weight of one grain. Then, we can compute the Bond number, Bo , which is the ratio between the cohesive force F_c and the grain weight, mg . If we assume that the intergrains force is proportional to the square of the magnetic field [22], we obtain $\text{Bo} = B^2 / B_{\text{ref}}^2$. The reference magnetic field for the metallic beads is $B_{\text{ref}} = 50$ G.

III. PURE CASE: ONLY METALLIC GRAINS

A. Observations

To perform the compaction experiments, the pile is initialized with the method explained previously. The magnetic

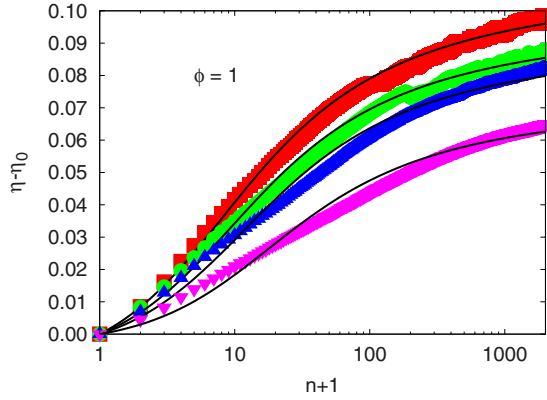


FIG. 3. (Color online) Typical compaction curves corresponding to different Bond numbers Bo . From the top curve to the bottom one, we have: $Bo=0.0$, $Bo=0.4$, $Bo=1.0$ and $Bo=5.8$. The fraction of metallic grains is $\phi=1$. The experimental data are fitted with the logarithmic law Eq. (1).

field is set after the initialization of the pile in order to obtain always the same initial packing fraction η_0 . The Fig. 3 presents four typical compaction curves obtained with different values of the magnetic field strength. The corresponding Bond numbers are $Bo=0$, $Bo=0.4$, $Bo=1.0$, and $Bo=5.8$. The continuous curves are the fits with the logarithmic law Eq. (1). The parameter B is fixed to 1 in order to minimize the number of free fitting parameters. Indeed, the parameters B and τ are known to be strongly anticorrelated.

The evolution of the characteristic time τ obtained from the fits as a function of the Bond number is presented in Fig. 4. The strong increase of τ observed for a low Bond number shows that the compaction dynamics is strongly influenced by the interactions between the grains. The cohesion induced by the magnetic field slows down the compaction process. We have observed previously this effect with fine cohesive powder [24]. The evolution τ as a function of the Bond number, Bo is well fitted by a square-root law [see Fig. 4(a)]. Therefore, τ increases linearly with the magnetic field strength B . In the cohesionless case ($Bo=0$ and $B=0$), some fluctuations are observed in the compaction curve after 80

taps (see Fig. 3). These fluctuations are related to a convective process inside the packing. When the Bond number increases, this convective process takes place later. Moreover, for high Bond numbers ($Bo > 1$), i.e., when the cohesion between the grains is higher than the weight of one grain, this convection process disappears.

Figure 4(b) presents the asymptotic packing fraction η_∞ as a function of the Bond number Bo . The fraction η_∞ decreases when the magnetic interaction between the grains strengthens. This behavior has been observed in a previous work [21] for the packing fraction η_0 of a metallic grains pile created in a vertical magnetic field. One should note that the asymptotic packing fraction obtained in the cohesionless case is far lower than the random close packing limit $\eta_{RCP} \sim 0.64$. The low value of the packing fractions obtained in our experiment is due to the roughness of the metallic grains.

B. Modeling

In order to estimate the compaction characteristic time τ , numerous theoretical models [17,25] have been developed. The great majority of them consider particles which are moving in “cages” constituted of neighboring particles. As shown recently [25] in numerical simulations, the probability that a particle escapes a cage is related to τ . The escape probability is a complex function of both packing fraction η and some energy barrier E_b related to the work for separating two grains. Roughly, one has a scaling $\tau \sim E_b$ [25]. If one considers that the energy barrier is herein linked to the work for separating two magnetic dipoles, one obtains the scaling $\tau \sim Bo$ which is not observed in Fig. 4. As a consequence, the assumption of caging dynamics does not hold in our system.

Theoretical and numerical works have been done to predict the packing fraction η of an assembly of particles. Thermodynamic approaches [26] and statistical methods [27] have been developed. For identical spherical grains, an average over all possible Voronoi cells around particles allows to estimate the random loose packing fraction in 2d. A similar approach [28] allows to estimate the packing fraction of bidisperse two-dimensional grains. Herein, the situation is more complex because the attractive and repulsive interactions

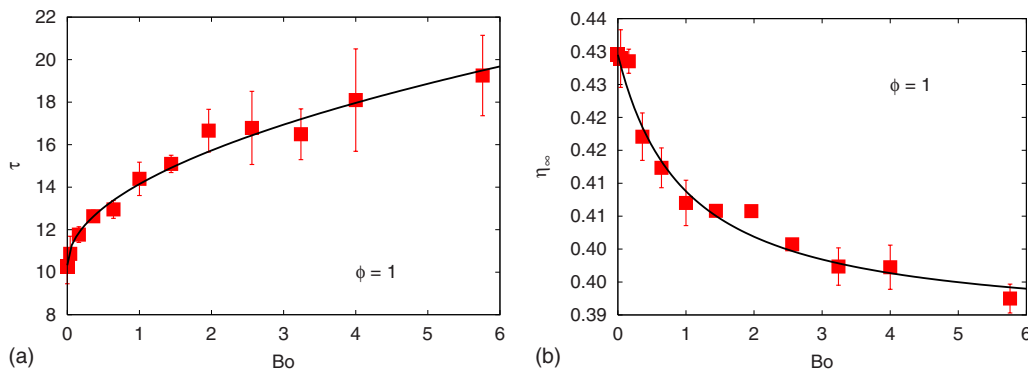


FIG. 4. (Color online) (a) Evolution of the characteristic time τ as a function of the Bond number Bo . The fraction of metallic grains is $\phi=1$. Each point corresponds to an average over three experiments. The continuous line is a fit with a square root law $\tau = \tau_0 + a\sqrt{Bo}$. The only fitting parameters is $a=3.8 \pm 0.2$. The value of the characteristic time when $Bo=0$ is $\tau_0=10.3$. (b) Decrease of the asymptotic packing fraction η_∞ with the Bond number Bo . The fraction of metallic grains is $\phi=1$. Each point corresponds to an average over three experiments. Error bars are indicated. The continuous line is a fit by Eq. (5). The only fitting parameter is $\eta_{\infty,Bo=0} = 0.388 \pm 0.001$.

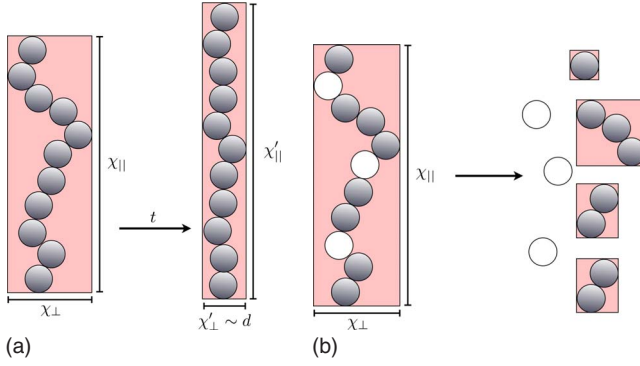


FIG. 5. (Color online) (a) An aggregate composed by several metallic beads before and after the compaction process. The disordered nature of the chain formation defines two typical length $\chi_{||}$ and χ_{\perp} which are related to each other (see text). (b) When the fraction $\phi < 1$, the chains of magnetized grains are divided due to the presence of glass beads.

should be taken into account. Note that vertical chains are favored by the magnetic field.

Let us propose a simple model to explain the scaling for both compaction parameters τ and η_{∞} . Due to the orientational nature of the interaction, the magnetic field induces the formation of vertical chains inside the packing. The vertical length of a chain $\chi_{||} \sim \text{Bo}$ is the key physical ingredient for describing the local grains organization in the packing [see Fig. 5(a)]. The geometry of a chain looks like a disordered aggregate [similarly to one-dimensional (1D) random walk] rather than a linear needle. The “thickness” χ_{\perp} of random aggregates is given by $\chi_{\perp} \sim \sqrt{\chi_{||}} \sim \sqrt{\text{Bo}}$ as for 1D random walk [29]. The packing of such random objects involves a loose packing fraction η_0 . For increasing the packing fraction η , the structure of the disordered chains should change in order to align the grains. Indeed, the space occupied by a chain is strongly decreased. Even if the height of the chain may increase, several chains can arrange in the space occupied by a single chain before the compaction process. The characteristic time needed to align chains along the magnetic field, being the characteristic time τ for the packing reorganization, is proportional to χ_{\perp} , giving the right scaling $\tau \sim \sqrt{\text{Bo}}$ obtained in Fig. 4. Adding the appropriate limit conditions, one writes

$$\tau = \tau_0 + a\sqrt{\text{Bo}}. \quad (3)$$

The experimental data are well fitted by the above square root law (see Fig. 4) with the only one fitting parameter $a = 3.8 \pm 0.1$.

If one consider that the packing is an assembly of cells illustrated in Fig. 5 (top), the packing fraction η of the pile is the ratio between the volume of the grains in the cell V_{grains} and the volume of the cell V_{cell} . One obtain

$$\eta = \frac{4N\pi d^3}{3\chi_{||}\chi_{\perp}^2}, \quad (4)$$

where N is the number of grains in the chain and d is the grains diameter. Since $N \sim \text{Bo}$, $\chi_{\perp} \sim \sqrt{\text{Bo}}$, and $\chi_{||} \sim \text{Bo}$, we

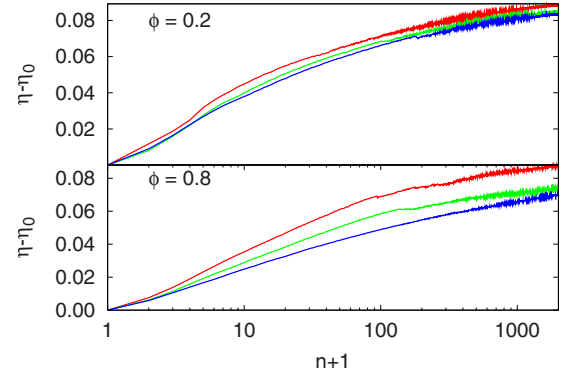


FIG. 6. (Color online) Typical compaction curves corresponding to different values of the Bond numbers Bo and of the fraction ϕ of metallic grains in the pile. From the top curve to the bottom one, we have for both fractions $\phi = 0.2$ and $\phi = 0.8$: $\text{Bo} = 0.25$, $\text{Bo} = 1$, and $\text{Bo} = 5.8$.

get the scaling $\eta \sim \text{Bo}^{-1}$. Adding the limit conditions, one writes

$$\eta_{\infty} = \eta_{\infty, \text{Bo}=\infty} + \frac{\eta_{\infty, \text{Bo}=0} - \eta_{\infty, \text{Bo}=\infty}}{1 + \text{Bo}}. \quad (5)$$

The decrease in η_{∞} with Bo is well fitted by this relation [see Fig. 4(b)]. The only fitting parameter is the asymptotic packing fraction obtained for infinite Bond number $\eta_{\infty, \text{Bo}=\infty} = 0.388 \pm 0.001$.

In summary, we have derived a simple model for describing the compaction dynamics of a magnetized packing. It appears that the packing fractions as well as compaction dynamics are understood when considering the mesoscopic level. Indeed, both size and shape of particle aggregates play a major role in such a system.

IV. MIXTURE CASES

A. Observations

The Fig. 6 presents typical compaction curves for two values of the fraction ϕ of metallic grains in the pile. For both fractions $\phi = 0.2$ and $\phi = 0.8$, three curves corresponding to different Bond number Bo are presented. Of course, When the fraction ϕ of metallic grains increases, the influence of the magnetic interaction on the compaction dynamics is enhanced. The influence of the fraction ϕ on the compaction dynamics is analyzed qualitatively through the characteristic time τ and the asymptotic packing fraction η_{∞} . We should note that the segregation can influence the compaction process. This effect is not analyzed qualitatively in our study and could be the subject of future works.

The characteristic compaction time τ and the asymptotic packing fraction η_{∞} have been measured for mixtures of glass and metallic beads. Eight volume fractions ϕ of metallic beads in the mixture have been considered. Moreover, the measurements have been repeated for different values of the Bond number Bo .

The Fig. 7 presents the evolution of the characteristic time τ as a function of the fraction ϕ of metallic beads in the

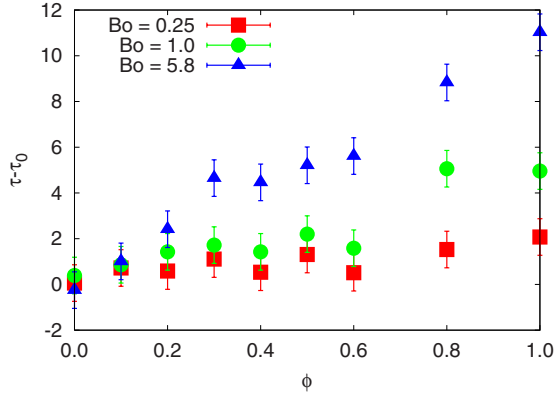


FIG. 7. (Color online) Evolution of the characteristic time τ as a function of the fraction of metallic beads in the mixture for different values of the Bond number Bo . The characteristic time τ_0 obtained when $Bo=0$ has been subtracted. Each point corresponds to an average over three experiments. Error bars are indicated.

mixture for three values of the Bond number Bo . For each value of ϕ , the characteristic time τ_0 obtained when $Bo=0$ has been subtracted. As expected, the compaction characteristic time τ increases with the fraction ϕ of metallic grains in the pile. Indeed, the cohesion inside the packing is expected to strengthen when the fraction of magnetized beads increases. This effect is amplified when the Bond number Bo increases.

The evolution of the asymptotic packing fraction η_∞ as a function of the fraction ϕ of metallic beads in the mixture for different values of the Bond number Bo is presented in Fig. 8. The asymptotic packing fraction $\eta_{\infty,0}$ obtained when $Bo=0$ has been subtracted for each value of ϕ . The packing fraction is found to decrease with the fraction ϕ of metallic beads. However, when $Bo > 1$, a local maximum is observed for $\phi \sim 0.2$. The signification of this maximum will be discussed below.

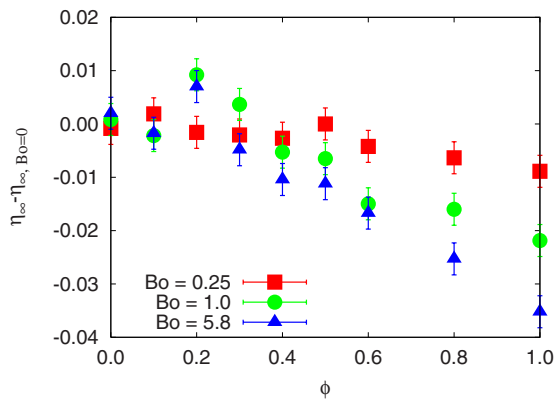


FIG. 8. (Color online) Evolution of the asymptotic packing fraction η_∞ as a function of the fraction of metallic beads in the mixture for different values of the Bond number Bo . The asymptotic packing fraction $\eta_{\infty,0}$ obtained when $Bo=0$ has been subtracted. Each point corresponds to an average over three experiments. Error bars are indicated.

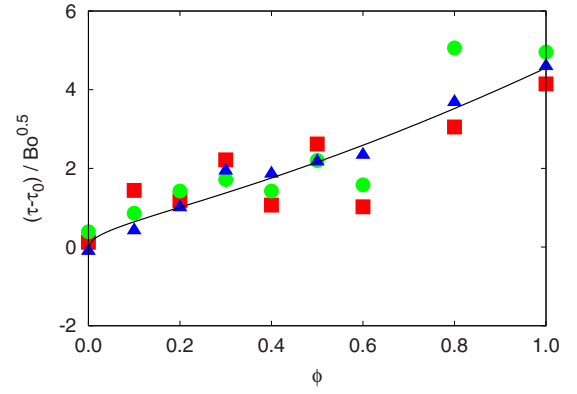


FIG. 9. (Color online) Scaling of the data presented in Fig. 7. The plain squares, circles and triangles correspond respectively to $Bo=0.25$, $Bo=1$ and $Bo=5.8$. The data collapse on a same trends and are well fitted by the Eq. (7).

B. Modeling

The previous model (Sec. III B) can be generalized to mixtures. The presence of glass beads in the packing decreases the length of the magnetic chains inside the packing [see Fig. 5(b)]. The decrease in the chain length as a function of the fraction ϕ can be evaluated simply. If we consider a reservoir of metallic and glass balls with a fraction ϕ of metallic balls, the probability to pick randomly a metallic ball is ϕ . The probability to obtain n successive metallic balls is ϕ^n . In our system, when $\phi=1$, the chains have a finite size. If N_{\max} is the maximum chain size, the average size $\langle N \rangle$ is

$$\langle N \rangle = \sum_{i=1}^{N_{\max}} i \phi^i. \quad (6)$$

Therefore, both Eqs. (3) and (5) can be generalized in the case of magnetic and nonmagnetic grains mixing. Indeed, in the case of mixtures, the characteristic size $\chi_{||}$ is proportional to $\sum_{i=1}^{N_{\max}} i \phi^i / Bo$. Then, we obtain

$$\tau = \tau_0 + a \sqrt{\frac{\sum_{i=1}^{N_{\max}} i \phi^i}{\sum_{i=1}^{N_{\max}} i} Bo} \quad (7)$$

and

$$\eta_\infty = \eta_{\infty, Bo=\infty} + \frac{\eta_{\infty, Bo=0} - \eta_{\infty, Bo=\infty}}{1 + \frac{\sum_{i=1}^{N_{\max}} i \phi^i}{\sum_{i=1}^{N_{\max}} i} Bo}. \quad (8)$$

The division by the arithmetic series $\sum_{i=1}^{N_{\max}} i$ has been used to recover the Eqs. (3) and (5) when $\phi=1$. Both series could be evaluated analytically.

The Fig. 9 shows the scaling $(\tau - \tau_0) / \sqrt{Bo}$ as a function of ϕ . The points corresponding to different values of the Bond numbers Bo collapse on a same trends. This collapse confirms the relation $\tau \sim \sqrt{Bo}$. Moreover, the data are well fitted by the Eq. (7) with $a = 4.55 \pm 0.7$ and $N_{\max} = 3 \pm 1$ as free fitting parameters.

The deviation between the experimental values of η_∞ and the prediction of the model $\eta_{\infty, \text{model}}$ obtained from the Eq. (8)

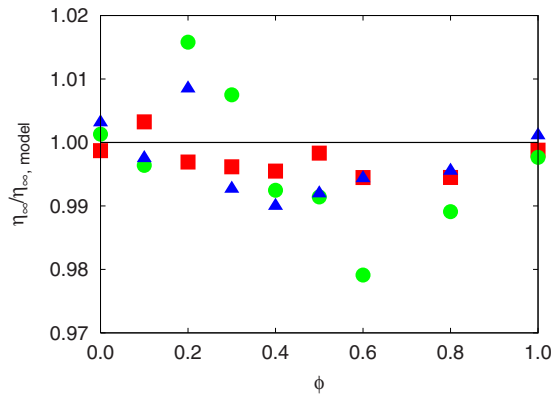


FIG. 10. (Color online) Deviation between the experimental values of η_∞ and the prediction of the model [Eq. (8)]. The plain squares, circles and triangles correspond respectively to $Bo=0.25$, $Bo=1$, and $Bo=5.8$.

is presented in Fig. 10. The ratio $\eta_\infty/\eta_{\infty,\text{model}}$ is close to unity except for the fractions ϕ of metallic grains situated between 0.1 and 0.3 where a local maximum of η_∞ is observed. Within this range, the metallic grains are mainly in contact with glass grains if the mixture is homogenous. However, during the compaction process, some clusters of metallic grains could be created in the packing. The existence of this segregation process could explain this increase in the asymptotic packing fraction.

In summary, the simple model proposed in the pure case has been generalized to the mixture case. We expect that the magnetic chains are divided due to the presence of glass beads in the packing.

V. CONCLUSIONS

The characteristic compaction time τ and the asymptotic packing fraction η_∞ have been measured for mixtures of glass and metallic beads in a magnetic field. When the pile is made of metallic grains, the characteristic compaction time τ increases as \sqrt{Bo} and the asymptotic packing fraction η_∞ is proportional to Bo^{-1} . We have derived a simple mesoscopic models that explains these scalings. This model has been generalized to mixtures.

These fundamental results should be useful to interpret the measurements made with cohesive powders used in the industry. Indeed, the tapping measurement is a very common tool to characterize the physical properties of powders.

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