

Renormalization of oscillator lattices with disorder

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A real-space renormalization transformation is constructed for lattices of nonidentical oscillators with dynamics of the general form $d\phi_k/dt = \omega_k + g \sum_l f_{lk}(\phi_l, \phi_k)$. The transformation acts on ensembles of such lattices. Critical properties corresponding to a second-order phase transition toward macroscopic synchronization are deduced. The analysis is potentially exact but relies in part on unproven assumptions. Numerically, second-order phase transitions with the predicted properties are observed as g increases in two structurally different two-dimensional oscillator models. One model has smooth coupling $f_{lk}(\phi_l, \phi_k) = \varphi(\phi_l - \phi_k)$, where $\varphi(x)$ is nonodd. The other model is pulse coupled, with $f_{lk}(\phi_l, \phi_k) = \delta(\phi_l) \varphi(\phi_k)$. Lower bounds for the critical dimensions for different types of coupling are obtained. For nonodd coupling, macroscopic synchronization cannot be ruled out for any dimension $D \geq 1$, whereas in the case of odd coupling, the well-known result that it can be ruled out for $D < 3$ is regained.

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I. INTRODUCTION

The study of synchronization in large oscillator networks has been a thriving field of research ever since the classic work by Winfree [1] in 1967. Even so, there are still basic questions that await satisfactory answers. One such question is when and how macroscopic synchronization occurs in lattices of nonidentical oscillators. This is the subject of the present paper.

Part of the charm of the study of synchronization is that the applications are very diverse [2–4]. Rhythmic activities in living organisms are, in many cases, generated by the collective oscillation of a large synchronized assembly of pacemaker cells. Examples include the beating of the heart [5], locomotion [6], the circadian rhythm [7], and the peristalsis of the small intestine [8]. There is also growing evidence that large-scale synchronization among neurons is crucial in the interpretation of sensory data and in conscious perception [9]. Epileptic seizures correspond to an abnormal degree of synchronization [10]. On a larger scale, synchronization can be seen in groups of organisms. Swarms of fireflies may flash in unison [11], the chirping of crickets in a field waxes and wanes in partial synchrony [12], an audience may spontaneously start to clap in unison [13], and females living together synchronize their menstrual cycles [14]. It has also been realized that synchronization is an essential concept in the dynamics of spatially extended animal populations [15]. Examples from outside biology include synchronization in power grids [4], lasers [16], oscillatory chemical reactions [17], and arrays of Josephson junctions [18].

In most applications, there will inevitably be some variation among the oscillators, for instance in the *natural frequency* with which they oscillate when isolated. In this situation, macroscopic synchronization means that the order parameter r becomes nonzero, where

$$r = \lim_{N \rightarrow \infty} M/N. \quad (1)$$

Here, M is the size of the largest group of oscillators that attain the same mean frequency and N is the total number of oscillators. If the network has spatial structure, the M syn-

chronized oscillators typically form a percolating cluster [19,20]. The mean frequency Ω_k of oscillator k is defined as

$$\Omega_k = \lim_{t \rightarrow \infty} \dot{\phi}_k(t)/t, \quad (2)$$

where ϕ_k is the phase of k . The existence of the above limits has to be assumed [21].

In theoretical work, the description of each oscillator must be simple to enable the study of large networks. Kuramoto [22] introduced the so-called phase reduction technique and showed that in the limits of small coupling between oscillators and small variation in natural frequencies, the phase ϕ_k is sufficient to describe the state of each oscillator k , and the network dynamics is given by

$$\frac{d\phi_k}{dt} = \omega_k + g \sum_{l=1}^N \varphi_{lk}(\phi_l - \phi_k). \quad (3)$$

The constant ω_k is the natural frequency, g is the coupling strength, and $\varphi_{lk}(x)$ is a one-periodic function. Another situation where a phase description is sufficient is in the limits of short, pulselike interactions and strong dissipation. The quick reduction in phase-space volumes then ensures that after one perturbation from a nearby oscillator l , oscillator k returns close to its limit cycle before the next perturbation, and we may write

$$\frac{d\phi_k}{dt} = \omega_k + g \sum_{l=1}^N \delta[\text{mod}(\phi_l, 1)] \varphi_{lk}(\phi_k), \quad (4)$$

where $\delta(x)$ is the Dirac delta function. This is often a good description in biological applications, where the interactions, for instance, may consist of electric discharges or light flashes. If we define ϕ_k as a cyclic variable, $\phi_k \in [0, 1)$, we can replace $\delta[\text{mod}(\phi_l, 1)]$, with $\delta(\phi_l)$. The one-periodic function $\varphi_{lk}(x)$ is often called the *phase response curve*.

Transitions to macroscopic synchronization are similar to phase transitions in equilibrium systems. The two main methods to analyze phase transitions are to make a mean-field description or to use a renormalization group. So far,

most attempts to gain understanding of macroscopic synchronization among nonidentical oscillators have assumed that the oscillators are coupled all-to-all. This is the mean-field description. To use a renormalization group, on the other hand, is the natural way to gain understanding of phase transitions in lattices.

This is the method used in this study. A real-space renormalization scheme is developed that is potentially exact. It is tested numerically on two structurally different models. At its present stage of development, however, the scheme has to be called heuristic since it relies in part on unproven assumptions.

Before describing the approach, let me review very briefly the current state of knowledge about transitions to macroscopic synchronization in mean-field and lattice models.

II. REVIEW OF RELATED WORK

A. Mean-field models

As a special case of Eq. (3), Kuramoto [22] introduced the mean-field model

$$\frac{d\phi_k}{dt} = \omega_k + \frac{g}{N} \sum_{l=1}^N \sin[2\pi(\phi_l - \phi_k)] \quad (5)$$

because of its analytical tractability. Instead of r , Kuramoto [22] studied the order parameter

$$R = \lim_{t \rightarrow \infty} \lim_{N \rightarrow \infty} \left| \sum_{k=1}^N e^{2\pi i \phi_k(t)} \right|, \quad (6)$$

and found that there is a critical coupling strength g_c such that

$$R = 0, \quad g < g_c,$$

$$R \propto (g - g_c)^{1/2}, \quad g \geq g_c. \quad (7)$$

If each ω_k is chosen independently from a density function \mathcal{D}_ω that is unimodal and symmetric about its mean μ , the critical coupling is given by $g_c = 2/\pi \mathcal{D}_\omega(\mu)$.

Since the original work by Kuramoto [22], the analysis of model (5) has been refined [23]. Also, it turns out that the exponent 1/2 in Eq. (7) changes to 1 as soon as non-odd harmonics are added to the coupling function $\varphi_{lk}(x) = \sin(2\pi x)$ [24].

Note that the order parameter R measures the degree of *phase synchronization*, whereas r [Eq. (1)] measures the degree of *frequency synchronization*. A nonzero R implies a nonzero r , but the opposite is not true. In a mean-field model, r and R typically becomes nonzero at the same critical coupling g_c . In a lattice model, waves in the phase field may be expected [1–4,22,25,26] even if the frequencies are synchronized so that $r > 0$ but $R = 0$.

Ariaratnam and Strogatz [27] studied Winfree’s original model,

$$\frac{d\phi_k}{dt} = \omega_k + \frac{g}{N} \sum_{l=1}^N \theta(\phi_l) \varphi(\phi_k), \quad (8)$$

in the special case $\theta(x) = 1 + \cos(2\pi x)$ and $\varphi(x) = -\sin(2\pi x)$. This model is similar to model (4), with the smooth one-periodic influence function $\theta(x)$ replacing the delta pulse. The authors were able to obtain the phase diagram in the plane spanned by g and γ , where \mathcal{D}_ω is uniform with support $[1 - \gamma, 1 + \gamma]$. Apart from the phases with $r = R = 0$ and $r = R = 1$, there is a phase of partial synchrony with $r < 1$ and $R < 1$ and also phases with partial or complete oscillator death ($d\phi_k/dt = 0$).

Tsubo *et al.* [28] studied a similar model, but let the disorder reside in the phase response curves $\varphi_{lk}(x)$, whereas the natural frequencies were identical. With $\varphi_{lk}(x) = \cos(\pi a_k) - \cos(2\pi x - \pi a_k)$, where a_k is a random number from a uniform distribution with support $[a_{\min}, a_{\max}]$, they found a discontinuous transition to macroscopic synchronization in the phase plane spanned by a_{\min} and a_{\max} , in contrast to the continuous transition in the Kuramoto model, as expressed in Eq. (7).

B. Lattice models

The analysis of oscillator lattices is harder than that of mean-field models, and less progress has been made. For cubic lattices with dimension D and dynamics of form (3) with $\varphi_{lk}(x) = \varphi(x)$ and odd coupling, $\varphi(-x) \equiv -\varphi(x)$, Daido [29] ruled out states with $r > 0$ for $D \leq 2$. Daido obtained this result using renormalizationlike arguments. With similar methods, Strogatz and Mirollo [30] were able to prove that whenever \mathcal{D}_ω has nonzero variance, states with $r = 1$ are ruled out for *any* finite D . In addition, states with $0 < r < 1$ cannot have synchronized clusters which contain macroscopic cubes (with volume $V = aN$, where $0 < a < 1$). Thus, for odd coupling, macroscopic synchronization may occur only if $D \geq 3$ and can only be partial with spongelike synchronized clusters. Whether such states actually exist is still an open question. The numerical evidence is inconclusive in my view [19,29,31,32].

Kopell and Ermentrout [33] were the first to point out that non-odd coupling facilitates synchronization. For an oscillator chain ($D = 1$) of form (3) with $\varphi_{lk}(x) = \varphi(x)$, I studied the case when \mathcal{D}_ω has finite support $[\omega_{\min}, \omega_{\max}]$. For models with $\varphi(0) = 0$ and $\varphi'(0) > 0$, there is then a critical coupling g_c at which a discontinuous transition from $r = 0$ to $r = 1$ takes place [34]. I found that $g_c = (\omega_{\max} - \omega_{\min})/|d(\hat{x})|$, where the denominator $|d(\hat{x})|$ is a measure of the “nonoddity” of $\varphi(x)$, vanishing for odd coupling such as $\varphi(x) = \sin(2\pi x)$. A similar result was provided for a model of form (4), which can be seen as inherently nonodd due to the sequential interaction of two oscillators via pulses [35].

Since macroscopic synchronization is possible for $D = 1$ for nonodd coupling, it is expected to be possible for all $D > 1$. However, no proofs have been obtained, to my best knowledge. For $D = 2$, me and my co-workers [20] offered numerical evidence for a continuous, second-order phase transition to $r > 0$ in a model of form (4).

In equilibrium systems, there is typically an upper critical dimension, above which a lattice model shows mean-field critical behavior. Hong and co-workers [32] have re-examined the lattice version of the Kuramoto model [Eq. (5)] and claim that $D=4$ is the upper critical dimension, above which critical exponents take mean-field values and macroscopic frequency and phase synchronizations appear at the same critical coupling. However, the results by Strogatz and Mirollo [30] indicate that the upper critical dimension is infinity for this model since they ruled out states with $r=1$ for any finite D and any \mathcal{D}_ω with nonzero variance, whereas such states exist in the mean-field model [Eq. (5)] when \mathcal{D}_ω has nonzero variance but finite support. It is conceivable that the phase-transition structure of oscillator networks is richer than in equilibrium systems and cannot be fully captured by the concepts used there.

Lattice models of oscillator networks are closely related to spatial continuum models. This is the natural way to describe the oscillatory Belousov-Zhabotinsky reaction [36] and the smooth muscle tissue in the intestine [8]. It may also be an adequate model of a large piece of oscillatory cardiac muscle even though it consists of discrete cells. The preferable mathematical description is given by the Ginzburg-Landau equation (GLE) [3,22], where the state at each point in space is given by a complex number, encoding both the phase and amplitude of oscillation. The GLE corresponds to a lattice of *identical* oscillators. Using a field-theoretic renormalization group, Risler and co-workers [37] performed a thorough analysis of synchronization transitions in the GLE with noise. The noise is assumed to be uncorrelated in space and time. In contrast, random natural frequencies correspond to “noise” that is uncorrelated in space but quenched in time. This makes the problem much more difficult in the continuum formulation. In particular, discontinuities arise in the phase field whenever frequency synchronization is not perfect ($r < 1$).

III. MODELS AND METHODS

In the analysis, models of the following form are considered:

$$\frac{d\phi_k}{dt} = \omega_k + g \sum_{l \in n_k} f_{lk}(\phi_l, \phi_k), \quad k = 1, \dots, N. \quad (9)$$

Here, $\phi_k \in \mathbb{R}$ is the phase of oscillator k , ω_k is its natural frequency, g is the coupling strength, and n_k is the set of k 's nearest neighbors. The analysis is restricted to cubic lattices of dimension D . The coupling functions f_{lk} are assumed to be one-periodic in each argument. With this restriction, the phases ϕ_k are allowed to grow linearly to be able to count the number of cycles, that is, the largest integer smaller than $\phi_k(t) - \phi_k(0)$. Since no further assumptions are made, the results are expected to apply (at least) to all models of this form. All the coupling functions in the models referred to above have the form given in Eq. (9).

Let us define the ensemble

$$\mathcal{E} = \mathcal{E}(g, \mathcal{D}_\omega, \mathcal{D}_f, \mathcal{D}_{\phi(0)}, D, N) \quad (10)$$

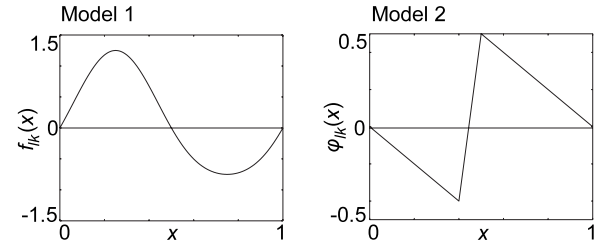


FIG. 1. Coupling functions in the two test models. Model 1 is of form (3) with $\varphi_{lk}(x)$ given by Eq. (12). Model 2 has form (4) with $\varphi_{lk}(x)$ given by Eq. (13)

of realizations of system (9), where ω_k are independent random numbers from the density function \mathcal{D}_ω , each f_{lk} is chosen from \mathcal{D}_f , and the initial condition $\phi(0) = [\phi_1(0), \dots, \phi_N(0)]$ is chosen from $\mathcal{D}_{\phi(0)}$. Quenched disorder is introduced by \mathcal{D}_ω and \mathcal{D}_f .

To give the coupling strength g a clear meaning, \mathcal{D}_f should be chosen so that

$$\left\langle \int_0^1 \int_0^1 |f_{lk}(\phi_l, \phi_k)| d\phi_l d\phi_k \right\rangle_{\mathcal{D}_f} = 1 \quad (11)$$

or so that it fulfils a similar condition. Alternatively, one may drop g as an argument of \mathcal{E} .

To test the theoretical predictions, numerical simulations of two specific models with $D=2$ are performed. The first model has form (3) with

$$\varphi_{lk}(x) = \sin(2\pi x) + \frac{1}{4} \sin^2(2\pi x) \quad (12)$$

(Fig. 1). This model will be referred to as model 1. The density function \mathcal{D}_ω is uniform with support $[1.0, 1.5]$ and $\mathcal{D}_{\phi(0)}$ is uniform in the interval $[0, 1]$. Forward Euler integration is used, with $\Delta t=0.05$. The motivation for this model is that it is similar to the Kuramoto model but has a nonodd term to allow macroscopic synchronization for $D=2$ (see below).

The second model has form (4) with

$$\varphi_{lk}(x) = \begin{cases} -x, & x \leq 0.4 \\ 9x - 4, & 0.4 < x < 0.5 \\ 1 - x, & 0.5 \leq x < 1 \end{cases} \quad (13)$$

(Fig. 1). This model will be referred to as model 2. $\mathcal{D}_{\omega-1}$ is uniform with support $[1.0, 1.5]$ and $\mathcal{D}_{\phi(0)}$ is uniform in the interval $[0, 1]$. The same integration method as in Refs. [20,34] is used. The piecewise linear phase response curve expressed by Eq. (13) has the same bipolar characteristics as the curve $\varphi(x) = -\sin(2\pi x)$ used by Ariaratnam and Strogatz [27]. This type of response to external perturbation is found in many biological applications [2].

The details are arbitrary, but these models are chosen since they have been studied previously, model (12) for $D=1$ in Ref. [34] and model (13) for $D=1$ in Ref. [35] and in the case $D=2$ in Refs. [20,25].

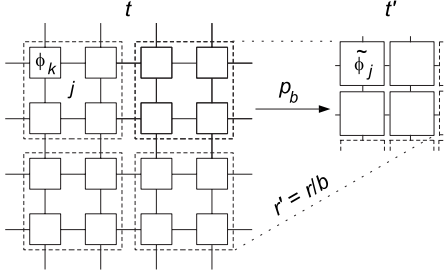


FIG. 2. A block-oscillator transformation Eq. (14) with scale factor $b=2$ and implicit change in length scale $r'=r/b$.

Unless otherwise stated, simulations of model 1 are carried out with lattice size 300×300 , whereas for model 2 the lattice size 500×500 is used. The larger lattice size is needed to resolve phase 2 in model 2 (see below). Periodic boundary conditions are used, unless otherwise stated. In and around critical regions, a transient time of $t=100\,000$ – $200\,000$ is used before measurements are done. For g well below critical values, shorter transient times are used. Mean frequencies Ω_k are approximated by taking the mean of $d\phi_k/dt$ during a time interval $\Delta t=1000$ after the initial transient [21].

To identify frequency clusters, the lattice is scanned. An oscillator k is considered to belong to the same cluster as a previously scanned neighbor oscillator l if $|\Omega_l - \Omega_k| < 0.001$. If two such neighbor oscillators l and l' are preliminarily judged to belong to different clusters C and C' , but both fulfill the above inequality, C and C' are identified as two parts of the same cluster.

IV. THEORETICAL APPROACH

The first step in the renormalization scheme is to define a block-oscillator transformation $p_b: \mathbb{R}^{b^d+1} \rightarrow \mathbb{R}^2$ (Fig. 2),

$$[\tilde{\phi}_j(t'), t'] = p_b[\{\phi_k(t)\}_{k \in j}, t]. \quad (14)$$

We get a coarse-grained version of the lattice and interpret the phase $\tilde{\phi}_j$ as the state of block oscillator j . Applying p_b to all j , we may define the scale transformation $P_b: \mathbb{R}^{N+1} \rightarrow \mathbb{R}^{N/b^d+1}$ as

$$[\tilde{\phi}(t'), t'] = P_b[\phi(t), t], \quad (15)$$

with $\phi = (\phi_1, \dots, \phi_N)$ and $\tilde{\phi} = (\tilde{\phi}_1, \dots, \tilde{\phi}_{N/b^d})$.

Let us discuss these transformations in a bit more detail. To be able to interpret P_b as a scale transformation, note that it must fulfill the group property

$$P_{b_1} P_{b_2} = P_{b_1 b_2}. \quad (16)$$

Regarding p_b , I restrict the interest to linear transformations of the form

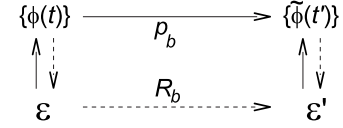


FIG. 3. Relation between the renormalization transformation R_b and the block-oscillator transformation p_b . An ensemble \mathcal{E} produces an infinite set $\{\phi(t)\}$ of time series $\phi(t)$. Only if such a set $\{\phi(t)\}$ inversely determines \mathcal{E} (dashed vertical arrows), is \mathcal{E}' uniquely determined by $\{\tilde{\phi}(t')\}$. Thus R_b does only exist in this case.

$$\begin{pmatrix} \tilde{\phi}_j \\ t' \end{pmatrix} = M(b, D) \begin{pmatrix} \phi_{k_1} \\ \vdots \\ \phi_{k_{b^d}} \\ t \end{pmatrix}, \quad (17)$$

where $\phi_{k_1}, \dots, \phi_{k_{b^d}}$ is some list of the phases in block j , and $M(b, D)$ is a $2 \times (b^d + 1)$ matrix with

$$M(b, D) = \begin{pmatrix} A & \dots & A & B \\ 0 & \dots & 0 & C \end{pmatrix}.$$

(Here, A , B , and C are functions of b and D .) Linear transformations with $M_{1,1} = \dots = M_{1,b^d} = A$ are considered since $\tilde{\phi}_j$ is intended to be a kind of arithmetic mean of the phases ϕ_k in block j , where all ϕ_k are treated in the same way. Such a choice of $\tilde{\phi}_j$ is justified if the phases are interpreted to be linear variables, instead of cyclic ones. There is no reason to let the transformed time t' depend on the phases, and therefore I set $M_{2,1} = \dots = M_{2,b^d} = 0$.

Next, let $\langle H[\phi(t)] \rangle_{\mathcal{E}}$ be the ensemble mean of $H[\phi(t)]$, where H is a functional of the time series $\phi(t)$. We then seek an ensemble

$$\mathcal{E}' = \mathcal{E}(g', \mathcal{D}_{f'}, \mathcal{D}_{\omega'}, \mathcal{D}_{\phi'(0)}, D, N/b^d) \quad (18)$$

[cf. Eq. (10)] such that

$$\langle H[\phi'(t')] \rangle_{\mathcal{E}'} = \langle H[\tilde{\phi}(t')] \rangle_{\mathcal{E}} \quad (19)$$

for any functional H . In words, all statistical quantities produced by the desired ensemble \mathcal{E}' should be the same as those given by the transformed phases $\{\tilde{\phi}(t')\}$, which in turn are determined by \mathcal{E} . The relation

$$\mathcal{E}' = R_b \mathcal{E} \quad (20)$$

defines the renormalization transformation R_b , assuming that \mathcal{E}' exists (Fig. 3).

Naively, instead of working at the ensemble level, we could have looked for an evolution equation for the transformed phases $\tilde{\phi}$. If we would have been successful, we could have written $d\tilde{\phi}_j/dt' = \omega'_j + g' \sum_{i \in n_j} f'_{ij}(\tilde{\phi}_i, \tilde{\phi}_j)$ or, in compressed form, $d\tilde{\phi}_j/dt' = \omega'_j + h'(\tilde{\phi})$. However, since p_b is not invertible, we have to express the interaction in the original phases, i.e., $h' = h'(\phi)$, and we do not get an evolution equation of the transformed phases in closed form such as Eq. (9).

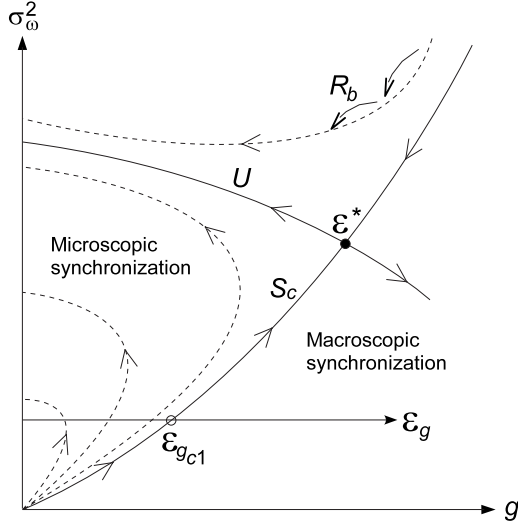


FIG. 4. Projection of $\{\mathcal{E}\}$ to the plane spanned by coupling strength g and the variance σ_ω^2 of natural frequencies. The transformation p_b [Eq. (14)] is chosen so that a critical fixed point \mathcal{E}^* with finite g^* and $(\sigma_\omega^2)^*$ may appear. The flow under R_b is intended to be such that ensembles on the critical line S_c are attracted to \mathcal{E}^* , and that σ_ω^2 is invariant at $g=0$. Numerically, two ensemble families \mathcal{E}_g are studied, models 1 and 2. Each of these seemingly becomes critical at some coupling $g=g_{c1}$.

Let us write

$$\begin{aligned} d\phi_k/dt &= \omega_k + h_k(\phi) \\ d\phi'_k/dt' &= \omega'_k + h'_k(\phi') \end{aligned} \quad (21)$$

for the original and transformed ensembles \mathcal{E} and \mathcal{E}' , respectively. In the following, I also adopt the notation $E[x]=\langle x \rangle_{\mathcal{E}}$ and let $\text{var}[x]$ and $\text{cov}[x,y]$ be the ensemble variance and covariance, respectively.

To be able to extract information about critical behavior from R_b , the transformation p_b has to be chosen so that there may appear a nontrivial fixed-point ensemble

$$\mathcal{E}^* = R_b \mathcal{E}^* \quad (22)$$

in the limit $N \rightarrow \infty$ (Fig. 4). In this paper I look for, and assume the existence of, a fixed point \mathcal{E}^* for which the variance of natural frequencies and the variance of the interaction exist, that is

$$\begin{aligned} 0 < (\sigma_\omega^2)^* < \infty \\ 0 < \text{var}^*[h_k] < \infty. \end{aligned} \quad (23)$$

A finite $\text{var}^*[h_k]$ implies a finite fixed-point coupling strength g^* [38].

Further, \mathcal{E}^* should attract an ensemble $\mathcal{E}_{g_{c1}}$ belonging to a family \mathcal{E}_g that passes a transition to macroscopic synchronization at the critical coupling $g=g_{c1}$. The behavior of \mathcal{E}_{g_c} will then be the same as that of \mathcal{E}^* at large scales and after long times.

With this in mind, p_b is chosen to fulfill three conditions, in addition to Eqs. (16) and (17). Before stating these conditions, let me introduce a few quantities.

First, let $m(t)$ and m_∞ be the mean attained frequencies:

$$\begin{aligned} m(t) &= \langle d\phi_k/dt \rangle_{\mathcal{E}}, \\ m_\infty &= \lim_{t \rightarrow \infty} m(t). \end{aligned} \quad (24)$$

The limit $\lim_{t \rightarrow \infty} m(t)$ exists at the presumed fixed point \mathcal{E}^* according to assumption (23). In fact, it follows from Eqs. (21) and (23) that the two first moments of the distribution of attained mean frequencies Ω_k exist at \mathcal{E}^* [21,39]:

$$\begin{aligned} E^*[\Omega_k] &= (m_\infty)^* < \infty, \\ 0 < \text{var}^*[\Omega_k] < \infty. \end{aligned} \quad (25)$$

Further, let κ be the mean wave number. Since the phases are allowed to be linear variables, the wave nature of the phase landscape in a given lattice \mathcal{L} may only be manifest if a suitable integer q_k is added or subtracted to each ϕ_k . Writing $Q=(q_1, \dots, q_N)$ and $\phi^{(Q)} = \phi + Q$, I define

$$\kappa = \lim_{l \rightarrow \infty} \min [\langle | \phi_k^{(Q)} - \phi_{l+n_k}^{(Q)} | \rangle_{\mathcal{L}}]_Q. \quad (26)$$

In other words, Q should be chosen so that the mean phase difference between neighbor oscillators is minimized, and this phase difference is κ . The lattice mean $\langle \dots \rangle_{\mathcal{L}}$ is expected to become equivalent to an ensemble mean $\langle \dots \rangle_{\mathcal{E}}$ in the limit $N \rightarrow \infty$. (Otherwise an ensemble mean can be added in the definition.)

Let \tilde{m} and $\tilde{\kappa}$ be the corresponding mean frequency and wave number in the transformed lattice. The three conditions that guide the choice of p_b , apart from Eqs. (16) and (17), are then as follows:

- (1) There is a (nonempty) set of ensembles Σ_1 , such that if $\mathcal{E} \in \Sigma_1$, then $\tilde{m}_\infty = m_\infty$ for any b .
- (2) There is a set of ensembles $\Sigma_2 \subseteq \Sigma_1$, such that if $\mathcal{E} \in \Sigma_2$, then $\tilde{\kappa} = \kappa$ for any b .
- (3) There is a set of ensembles \mathcal{E} with no coupling ($g=0$) such that if σ_ω^2 is finite and nonzero, then $\sigma_\omega'^2 = \sigma_\omega^2$ is finite and nonzero for any b .

It is clear that the two first conditions are necessary. The critical fixed point \mathcal{E}^* I hope to construct belongs to Σ_2 .

To see why condition (3) is necessary, look at Fig. 4. Assume first that the condition is broken and that $\lim_{b \rightarrow \infty} \sigma_\omega'^2 = 0$ for all ensembles with no coupling. Then the unstable manifold U of \mathcal{E}^* bends down to the origin. If S_c would still be a stable manifold of \mathcal{E}^* , closed flow lines would appear, which is impossible since correlation lengths are always reduced a factor b each time R_b is applied. Thus the flow along the critical line S_c changes direction, and the critical properties at g_{c1} are no longer given by those of \mathcal{E}^* . In other words, \mathcal{E}^* becomes irrelevant.

Assume instead that $\lim_{b \rightarrow \infty} \sigma_\omega'^2 = \infty$ at $g=0$ for all ensembles with no coupling. I will give a plausibility argument why this is not consistent with the existence of a fixed point \mathcal{E}^* of the desired kind. From Eqs. (17) and (21),

$d\tilde{\phi}_j/dt' = (A/C)\sum_{k \in j} \omega_k + (A/C)\sum_{k \in j} h_k + B/C$. Since $g=0$ corresponds to $h_k \equiv 0$, we have $d\tilde{\phi}_j/dt' = (\tilde{\omega}_j)_{g=0} + (A/C)\sum_{k \in j} h_k$. Here, $(\tilde{\omega}_j)_{g=0}$ is the transformed natural frequency of block j in the ensemble obtained when g is replaced by 0 in the original ensemble $\mathcal{E}(g, \dots)$. Taking the ensemble variance and applying the equation to the presumed fixed point $\mathcal{E}^*(g^*, \dots)$, we may write $\text{var}^*[d\tilde{\phi}_j/dt'] = (\sigma_{\omega'}^2)_{g=0} + R$, where I do not specify the rest term R for clarity. The left-hand side of this equation must be finite for any b since $\text{var}[d\tilde{\phi}_j/dt'] = \text{var}[d\phi_k/dt]$ at a fixed point and $\text{var}^*[d\phi_k/dt]$ exists [39]. This condition would be hard to fulfill if $(\sigma_{\omega'}^2)_{g=0} \rightarrow \infty$ as $b \rightarrow \infty$. Then the term R must sensitively balance this divergence.

Straightforward algebra shows that the only block-oscillator transformation p_b of form (17) that has the group property Eq. (16) and satisfies conditions 1–3 is the one with

$$\begin{aligned}
 A &= b^{-D-1}, \\
 B &= (b^{-D/2-1} - b^{-1})m_\infty, \\
 C &= b^{-D/2-1},
 \end{aligned} \quad (27)$$

or, explicitly,

$$\begin{cases} \tilde{\phi}_j(t') &= b^{-D-1} \sum_{k \in j} \phi_k(t) - b^{-1}(1 - b^{-D/2})m_\infty t \\ t' &= b^{-D/2-1}t. \end{cases} \quad (28)$$

(In fact, I only demonstrate that this transformation satisfies condition 2 in a restricted sense, to be described below.)

Note that if we are interested in critical ensembles for which σ_ω^2 does not exist, the three conditions, and hence transformation (28), should be modified. This point was discussed by Daido [29]. This in turn affects the critical properties and the critical dimension. I do not deal with these cases explicitly in this paper.

Instead of proving the uniqueness of transformation (28), let us examine to what extent it fulfills conditions 1–3.

Regarding condition 1, we get

$$\tilde{m}_\infty = m_\infty \quad (29)$$

for any b and any \mathcal{E} by direct evaluation of $\lim_{t \rightarrow \infty} \langle d\tilde{\phi}_j/dt' \rangle_{\mathcal{E}}$ using Eq. (28).

Condition 2 is fulfilled in the following restricted sense. If we may choose Q [Eq. (26)] such that a plane wave moving along a principal axis appears in the phase field $\phi^{(Q)}(\mathbf{r})$, then its wave number will remain the same in the transformed field $\tilde{\phi}^{(Q)}(\mathbf{r}')$. Assume that i and j are two neighbor block-oscillators along the relevant principal axis (Fig. 5). Then, dropping the superscript (Q) for brevity,

$$\tilde{\phi}_j - \tilde{\phi}_i = b^{-D-1} \sum_{k=1}^{b^D} (\phi_{k_j} - \phi_{k_i}), \quad (30)$$

where k_i and k_j are the oscillators at corresponding positions in block i and j , respectively. The distance between these is b , and thus $\langle \phi_{k_j} - \phi_{k_i} \rangle_{\mathcal{L}} = b \langle \phi_l - \phi_k \rangle_{\mathcal{L}}$, where k and l are neigh-

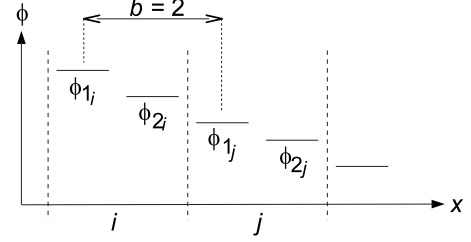


FIG. 5. Illustration for the argument why condition 3 is fulfilled for the block-oscillator transformation p_b [Eq. (28)]. A wave is moving in the positive x direction in the case $D=1$. Two neighbor block-oscillators i and j with size $b=2$ are indicated. Corresponding individual oscillators in the two blocks are paired as (ϕ_{1i}, ϕ_{1j}) and (ϕ_{2i}, ϕ_{2j}) . The oscillators in each pair are placed at distance $b=2$ from each other.

bor oscillators along the principal axis. Consequently, taking the lattice mean of Eq. (30), we get $\langle \tilde{\phi}_j - \tilde{\phi}_i \rangle_{\mathcal{L}} = \langle \phi_l - \phi_k \rangle_{\mathcal{L}}$.

Turning to condition 3, let us use Eqs. (28) and (29) to write

$$\frac{d\tilde{\phi}_j}{dt'} - \tilde{m}_\infty = b^{-D/2} \sum_{k \in j} \left(\frac{d\phi_k}{dt} - m_\infty \right). \quad (31)$$

At $g=0$ we have $d\tilde{\phi}_j/dt' = \tilde{\omega}_j$ and $d\phi_k/dt = \omega_k$. Also, $\tilde{m}_\infty = m_\infty = \tilde{\mu} = \mu$ by Eq. (29) so that $\tilde{\omega}_j - \tilde{\mu} = b^{-D/2} \sum_{k \in j} (\omega_k - \mu)$. Thus $\sigma_{\tilde{\omega}}^2 = \sigma_\omega^2$ for all b . Condition 3 is then fulfilled since $\mathcal{D}_{\omega'} = \mathcal{D}_{\tilde{\omega}}$ at $g=0$. In the limit $b \rightarrow \infty$, $\mathcal{D}_{\omega'}$ becomes a Gaussian by the central limit theorem, with the same mean and variance as \mathcal{D}_ω .

Transformation (28) is the only block-oscillator transformation of form (17) that enables a nontrivial fixed point \mathcal{E}^* of the desired kind. There may be acceptable transformations that do not have form (17). This is not essential. Fixed-point properties derived from any p_b that gives rise to a fixed point \mathcal{E}^* of the desired kind have to reflect critical properties of model (9) if the corresponding family of ensembles \mathcal{E}_g pass through the critical surface S_c as coupling strength g is varied (Fig. 4).

To gain some information about R_b , let us try to express

$$d\tilde{\phi}_j/dt' = \tilde{\omega}_j + \tilde{h}_j(\phi), \quad (32)$$

where $\tilde{\omega}_j$ is a constant that can be interpreted as the natural frequency of block-oscillator j in the transformed lattice, and $\tilde{h}_j(\phi)$ can be seen as the interaction term. To allow such an interpretation, $\tilde{h}_j(\phi)$ has to be zero when block j is decoupled from the rest of the lattice. Let

$$m_j = \lim_{t \rightarrow \infty} b^{-D} \sum_{k \in j} [d\phi_k/dt]^{x^<}, \quad (33)$$

where $x^<$ is the value of x when block-oscillator j is decoupled from the surroundings. Further, let an underlined variable denote an initial condition mean,

$$\underline{x} = \langle x \rangle_{\mathcal{D}_{\phi(0)}}. \quad (34)$$

In a sense, m_j is then the natural frequency of block-oscillator j in the original lattice. Using Eqs. (9) and (28), we may express

$$\begin{aligned} \frac{d\tilde{\phi}_j}{dt'} &= m_\infty + b^{D/2}(m_j - m_\infty) \\ &+ b^{-D/2} \sum_{k \in j} \left\{ g \left[\sum_{l \in n_k} f_{lk}(\phi_l, \phi_k) \right] - (m_j - \omega_k) \right\}. \end{aligned} \quad (35)$$

Let us interpret

$$\tilde{\omega}_j = m_\infty + b^{D/2}(m_j - m_\infty), \quad (36)$$

and

$$\begin{aligned} \tilde{h}_j(\phi) &= b^{-D/2} \sum_{k \in j} \left\{ g \left[\sum_{l \in n_k} f_{lk}(\phi_l, \phi_k) \right] - (m_j - \omega_k) \right\} \\ &= b^{-D/2} \sum_{k \in j} g \sum_{l \in n_k} [f_{lk}(\phi_l, \phi_k) - \underline{f}_{lk}^{\leftarrow}] \\ &= b^{-D/2} \sum_{k \in j} (h_k(\phi) - \underline{h}_k^{\leftarrow}). \end{aligned} \quad (37)$$

Here, $\underline{f}_{lk}^{\leftarrow}$ is the initial condition mean of the coupling function $f_{lk}(\phi_l, \phi_k)$ as $t \rightarrow \infty$ and block j is decoupled, and $\underline{h}_k^{\leftarrow} = g \sum_{l \in n_k} \underline{f}_{lk}^{\leftarrow}$. The interaction \tilde{h}_j in Eq. (37) is not strictly zero when j is decoupled from other blocks. However, the initial condition mean \tilde{h}_j is zero, in the limit $t \rightarrow \infty$. Thus, these identifications can be used to deduce *asymptotic* critical behavior of *initial condition averaged* variables but nothing else.

I formulate the following conjecture:

$$\mathcal{D}_{\omega'} = \mathcal{D}_{\tilde{\omega}},$$

$$\langle H[\underline{h}_k^{\leftarrow}(\phi')] \rangle_{\mathcal{E}'} = \langle H[\tilde{h}_j(\phi)] \rangle_{\mathcal{E}} \quad (38)$$

for any functional H as $t \rightarrow \infty$. A number of critical properties follow from Eqs. (19), (28), and (38), and the fixed point condition $\mathcal{E}' = \mathcal{E} = \mathcal{E}^*$.

V. RESULTS

A. Phase diagrams

I want to compare each theoretical prediction with numerical results from the two test models, model 1 [Eq. (12)] and model 2 [Eq. (13)], in the case $D=2$. To do so, it has to be demonstrated that there are critical points in these models, and the critical coupling strengths g_{c1} have to be identified.

Previously, two critical couplings g_{c1} and g_{c2} were found in model 2 [20]. The system seemingly becomes critical at $g=g_{c1}$ and almost perfect synchronization settles at $g=g_{c2}$. There are still isolated oscillators that never fire for $g > g_{c2}$, and thus they are not synchronized to the rest of the lattice [25]. The two critical couplings separate three phases, *phase 1* ($0 \leq g < g_{c1}$), *phase 2* ($g_{c1} < g < g_{c2}$), and *phase 3* ($g > g_{c2}$). These conclusions were reached by looking at the distribution of cluster sizes. At $g=g_{c1}$, this distribution seems

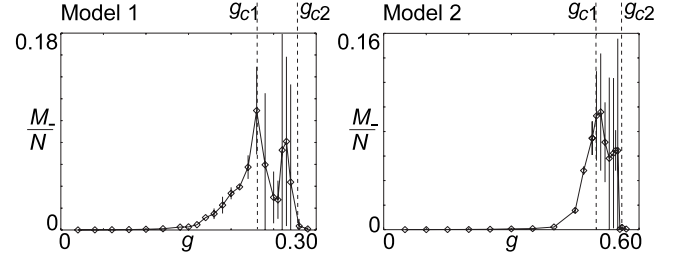


FIG. 6. The portion M_-/N of the lattice occupied by the *next* largest frequency cluster as a function of coupling strength g . The maximum of M_-/N corresponds to g_{c1} and it drops almost to zero at g_{c2} . For model 1 it is found that $g_{c1} \approx 0.23$ and $g_{c2} \approx 0.28$, and for model 2 $g_{c1} \approx 0.50$ and $g_{c2} \approx 0.56$. Average and standard deviation of 7 realizations of models 1 and 3 realizations of Model 2 are shown for each g .

to obey a power law. This is true in phase 2 also if the macroscopic cluster is disregarded. By estimating g_{c1} and g_{c2} for different values of N , it was argued that the three phases are not a finite size effect but persist as $N \rightarrow \infty$.

Simulations with model 1 suggest that it behaves qualitatively in the same way. Instead of showing cluster size distributions, we look in Fig. 6 at the quantity M_-/N , where M_- is the size of the *next* largest cluster. M_-/N is expected to peak at g_{c1} . Above g_{c1} the largest, percolating cluster grows in size as g increases further, whereas the other clusters become smaller. At g_{c2} , M_-/N should drop close to zero. In this way, it is estimated that $g_{c1} \approx 0.23$ and $g_{c2} \approx 0.28$ for model 1, whereas $g_{c1} \approx 0.50$ and $g_{c2} \approx 0.56$ for model 2 (Fig. 6). Figure 7 shows frequency landscapes $\Omega(\mathbf{r})$ in each of the three phases [21].

For both models, phase 2 is rather narrow but clearly distinguishable. To establish the existence of phase 2 even more clearly, complementary simulations were made for wider and narrower \mathcal{D}_ω (Fig. 8).

The hypothesis that will be tested is that the curve $g_{c1}(\sigma_\omega^2)$ is identical to the critical curve S_c , which is also the stable manifold of a critical fixed point \mathcal{E}^* (Fig. 4). Thus I identify $g_c = g_{c1}$. It is a delicate question whether the entire phase 2 is critical. In Ref. [20] I hypothesized that this is so, based on the cluster size distribution and the temporal instability of clusters, even after very long times. The large sample-to-sample fluctuations seen in Fig. 6 further strengthen this idea. The matter is discussed further below.

To test whether phase 3 exists even if \mathcal{D}_ω has tails, model 1 is simulated with Gaussian natural frequencies, with mean $\mu=0$ and variance $\sigma_\omega^2=1/48$, i.e.,

$$\mathcal{D}_\omega = \mathcal{N}(0, 1/48). \quad (39)$$

The variance is chosen to be equal to the variance of the original, uniform \mathcal{D}_ω . I estimate $g_{c1}=0.23$ and $g_{c2}=0.28$. Phase 3 is entered even if the oscillators with the most extreme natural frequencies do not synchronize to the rest of the lattice. Model 2 is simulated with the Rayleigh density function

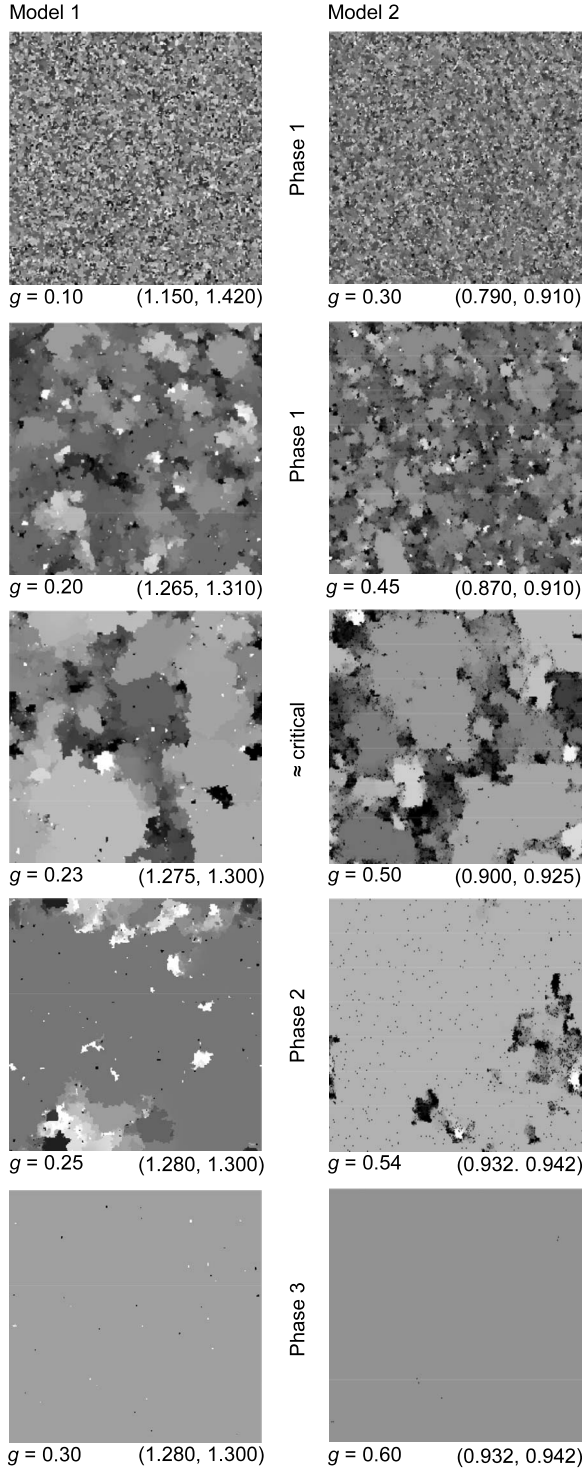


FIG. 7. Frequency landscapes $\Omega(\mathbf{r})$. Frequency is coded according to the bracket $(\omega_{\min}, \omega_{\max})$. An oscillator k is colored black if Ω_k is less than ω_{\min} and white if it is higher than ω_{\max} .

$$\begin{cases} \mathcal{D}_{\omega^{-1}} = 4\pi(\omega^{-1} - 1)e^{-2\pi(\omega^{-1} - 1)^2}, & \omega^{-1} \geq 1 \\ \mathcal{D}_{\omega^{-1}} = 0, & \omega^{-1} < 1. \end{cases} \quad (40)$$

In this model, it is found that $g_{c1} \approx 0.55$ and $g_{c2} \approx 0.75$. Phase 3 is entered even if the slowest oscillators do not synchronize to the rest of the lattice.

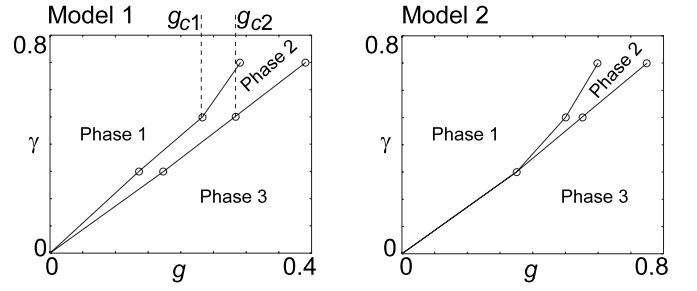


FIG. 8. Phase diagrams. The same quantity M_-/N as in Fig. 6 is used to identify g_{c1} and g_{c2} . For model 1, \mathcal{D}_ω is uniform with support $[1, 1 + \gamma]$. For model 2, $\mathcal{D}_{\omega^{-1}}$ is uniform with the same support. Phase 1 is subcritical with microscopic frequency clusters only. In phase 2, there is one macroscopic cluster. In phase 3, almost all oscillators synchronize their frequencies. All three phases seem to persist even if \mathcal{D}_ω has tails (see text). For model 2, it is impossible to resolve phase 2 in the data obtained with $\gamma=0.3$. I cannot decide whether phase 2 extends down to the origin, or if there is a triple point.

I hypothesize that the transition to phase 3 is discontinuous since the distribution of cluster sizes seems to collapse discontinuously at g_{c2} . However, more detailed studies are needed to establish the nature of this transition and to be able to define phase 3 precisely.

B. Frequency correlations

We have $E[\Omega'_k] = m'_\infty = m_\infty = E[\Omega_k]$ from Eqs. (19) and (29) and

$$\text{var}[\Omega'_k] = \text{var}[\Omega_k] + b^{-D} \sum_{k, k' \in j, k' \neq k} \text{cov}[\Omega_k, \Omega_{k'}] \quad (41)$$

from Eq. (31) [21]. At a fixed point \mathcal{E}^* , the sum has to be zero for *any* b if $\text{var}^*[\Omega_k] < \infty$, which is the case treated here [Eq. (25)]. Therefore we must have $\text{cov}^*[\Omega_k, \Omega_{k'}] = 0$ for all $k \neq k'$. Introducing the pair-correlation function

$$\Gamma_\Omega(r) = \text{cov}[\Omega_k, \Omega_{k'}]_{|k'-k|=r} / \text{var}[\Omega_k], \quad (42)$$

it is concluded that

$$\Gamma_\Omega^*(r) \equiv 0, \quad r \geq 1. \quad (43)$$

Note that even if $\Gamma_\Omega^*(r) \equiv 0$, the Ω_k s do not have to be *independent* at a critical fixed point. Rather, clusters of oscillators which run at the same frequency are expected (Fig. 7).

Figure 9 shows the correlation length $\hat{\xi}_\Omega$ defined by the relation

$$\Gamma_\Omega(\hat{\xi}_\Omega) = e^{-1}. \quad (44)$$

(Note that this is not the standard way to define a correlation length, thus the hat symbol. Normally it is defined as the rate of exponential fall-off at large r , cf. Eq. (82). The quantity $\hat{\xi}_\Omega$ is used here since it turned out to be more stable, given the fluctuations of $\Gamma_\Omega(r)$.) In model 1, $\hat{\xi}_\Omega$ drops significantly just above the estimated value of g_{c1} , with comparably small sample variations. In phase 2, $\hat{\xi}_\Omega$ seemingly increases again

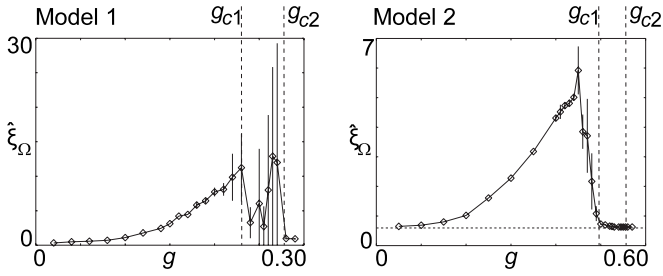


FIG. 9. The frequency correlation length $\hat{\xi}_\Omega$ [Eq. (44)]. According to Eq. (43), $\hat{\xi}_\Omega$ is expected to drop to zero at $g=g_{c1}$. The same number of realizations as in Fig. 6 are used. Since linear interpolation is used, zero correlation between neighbors gives $\hat{\xi}_\Omega=1-e^{-1}$ (dotted horizontal line).

even if large variations make such a conclusion uncertain. In model 2, $\hat{\xi}_\Omega$ falls steeply toward zero just below g_{c1} and stay very close to zero for $g>g_{c1}$ with very small variations.

Thus, model 2 supports the theory better than model 1 does. However, the drop of $\hat{\xi}_\Omega$ in model 1 may occur exactly at g_{c1} , given the uncertainty in its estimation due to the large sample variations of the cluster sizes (Fig. 6).

No indications of negative correlations have been observed.

C. Frequency distribution

Consider the density function \mathcal{D}_Ω of attained frequencies Ω_k [21]. I do not attempt to deduce $(\mathcal{D}_\Omega)^*$ but discuss some of its basic properties.

We have already concluded that assumption (23) implies that $E^*[\Omega_k]$ and $\text{var}^*[\Omega_k]$ both exist. Put differently, if the critical properties of models 1 and 2 are to be the same as those deduced for the fixed point \mathcal{E}^* , then $E[\Omega_k]$ and $\text{var}[\Omega_k]$ should exist at $g=g_{c1}$. Infinite $\text{var}[\Omega_k]$ at $g=g_{c1}$ and finite $\text{var}^*[\Omega_k]$ make necessary negative frequency correlations [Eqs. (41) and (42)] along the critical line S_c (Fig. 4), which have not been observed in simulations.

At $g=g_{c1}$, the order parameter r [Eq. (1)] becomes non-zero, that is, a finite portion of the oscillators attain identical frequencies so that an infinitely high spike develops in \mathcal{D}_Ω as g approaches g_{c1} from below:

$$\lim_{g \rightarrow (g_{c1})_-} \max[\mathcal{D}_\Omega] = \infty. \quad (45)$$

Let us use Eq. (31) to write

$$\tilde{\Omega}_j = E[\Omega_k] + b^{-D/2} \sum_{k \in j} (\Omega_k - E[\Omega_k]). \quad (46)$$

At a critical fixed point, the emerging spike should not move when p_b is applied so that

$$(\Omega_{\text{peak}})^* = E^*[\Omega_k], \quad (47)$$

where $\mathcal{D}_\Omega(\Omega_{\text{peak}}) = \max[\mathcal{D}_\Omega]$.

Equation (46) can be used to renormalize a frequency landscape numerically, just like an Ising lattice can be renormalized by assigning the direction of the block spin according to the majority rule. Ideally,

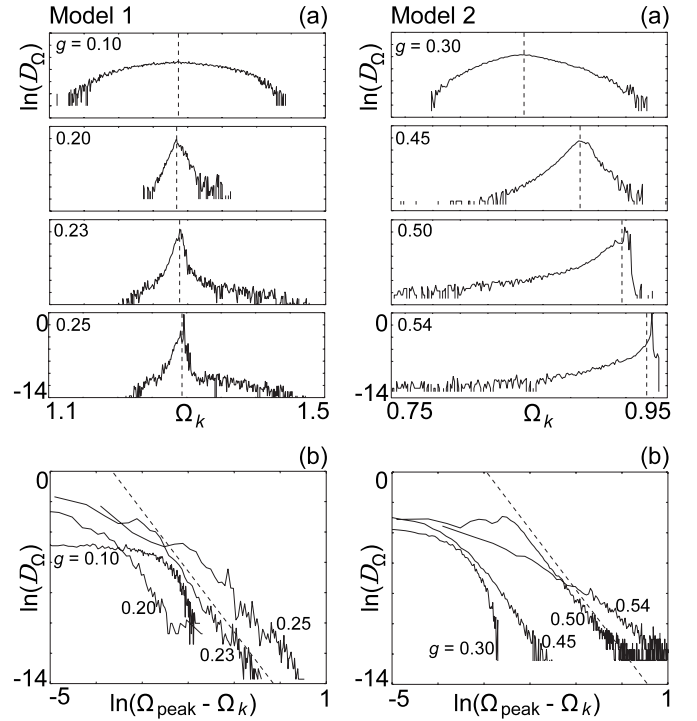


FIG. 10. Density functions \mathcal{D}_Ω of attained frequencies Ω_k in models 1 and 2. The vertical dashed lines in panels (a) show the mean frequency $E[\Omega_k]$. Panels (b) show the low-frequency tails. The dashed lines correspond to a relation $\mathcal{D}_\Omega(\Omega_k) \propto (\Omega_{\text{peak}} - \Omega_k)^{-4}$. The critical coupling strengths are $g_{c1}=0.23$ for Model 1 and $g_{c1}=0.50$ for Model 2.

$$\lim_{b \rightarrow \infty} (\mathcal{D}_\Omega)_{g_{c1}} = (\mathcal{D}_\Omega)^*, \quad (48)$$

but there are numerical problems (apart from the dynamical instability). First, small frequency gradients in a presumed cluster are magnified by Eq. (46). Second, a block oscillator containing a cluster border will not be part of the renormalized cluster, which distorts the renormalization of cluster sizes for small and medium sized clusters, such as those obtained in a simulation. Basically, the problem is that the frequencies are continuous variables, whereas spins are discrete.

Figure 10 shows numerical estimations of \mathcal{D}_Ω for model 1 and model 2. Panels (a) show that $\Omega_{\text{peak}} \approx E[\Omega_k]$, at least for $g \leq g_{c1}$, indicating that Eq. (47) is fulfilled. This is true even if \mathcal{D}_Ω is not symmetric about its mean. However, in model 2 for $g > g_{c1}$, it is clear that $(\Omega_{\text{peak}}) > E[\Omega_k]$.

Panels (b) in Fig. 10 show the low-frequency tails for each model at different values of g . Just below and at $g = g_{c1}$ it seems that

$$\mathcal{D}_\Omega(\Omega_k) \propto (\Omega_{\text{peak}} - \Omega_k)^{-\chi} \quad (49)$$

with $\chi \approx 4$ (dashed lines), suggesting that the requirement that $\text{var}[\Omega_k]$ exists at $g=g_{c1}$ is indeed fulfilled. Regarding the high-frequency tails, in model 1 they seem to fall off quicker than a power law for the largest frequencies for all g . In model 2, there seems to be no tails close to and above g_{c1} .

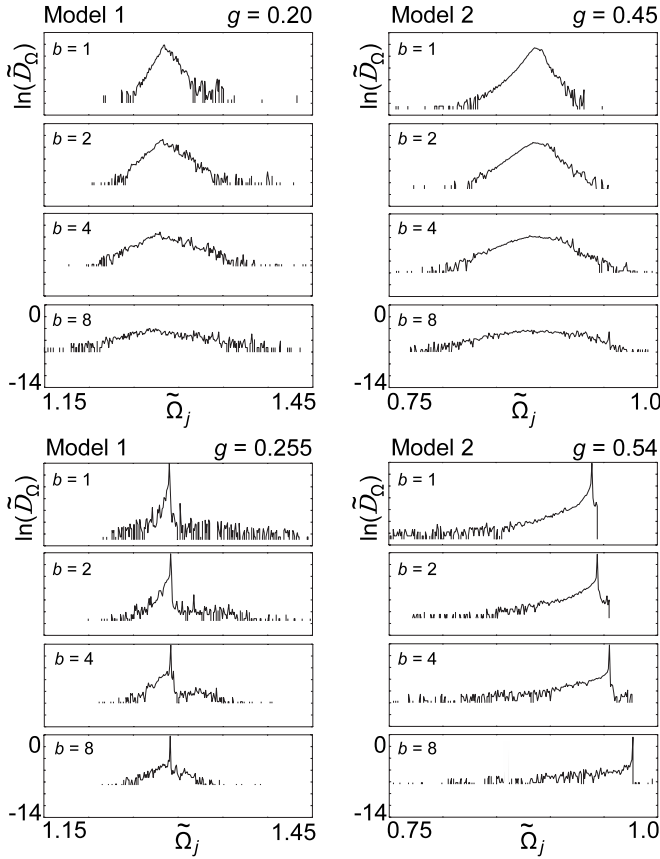


FIG. 11. Density functions \tilde{D}_ω of attained renormalized frequencies $\tilde{\Omega}_j$. Equation (46) is used for the numerical renormalization with different scale factors b . In phase 1 ($g=0.20$ for model 1 and $g=0.45$ for model 2), \tilde{D}_ω approaches a normal distribution corresponding to a trivial fixed point at $g=0$. This does not seem to be the case in phase 2 ($g=0.255$ for model 1 and $g=0.54$ for model 2).

Figure 11 shows numerical renormalizations in phases 1 and 2 using Eq. (46). The outcomes are qualitatively different, indicating that different fixed points are approached in the two cases. We have not been able to obtain convergence toward the presumed critical fixed-point density function \mathcal{D}_Ω^* using a system close to $g=g_{c1}$. Instead, the outcome is similar to that shown in phase 1 although the normal distribution is approached more slowly (as b increases). The reason may be that, numerically, some positive correlations are still remaining (Fig. 9).

The frequency correlation function $\Gamma_\Omega(r)$ drops close to zero in phase 2, but it seems that it never becomes negative. This means that $\text{var}[\tilde{\Omega}_j] \geq \text{var}[\Omega_k]$. Thus the flow under R_b cannot go toward perfect synchronization ($r=1$), for which $\text{var}[\Omega_k]=0$, but it can reach states where the lattice is synchronized except for isolated oscillators with opposing frequencies. Such states are indeed seen at coupling strengths slightly larger than g_{c2} (Fig. 7). If there is a nontrivial fixed point corresponding to such a state, then the outlier oscillators must have a fractal spatial distribution. Otherwise they will “eat” the synchronized part of the lattice, and $r \rightarrow 0$ as $b \rightarrow \infty$. This effect is seen in Fig. 11 as a (slightly) decreasing height of the spike and an elevated baseline of outlier oscillators as b increases.

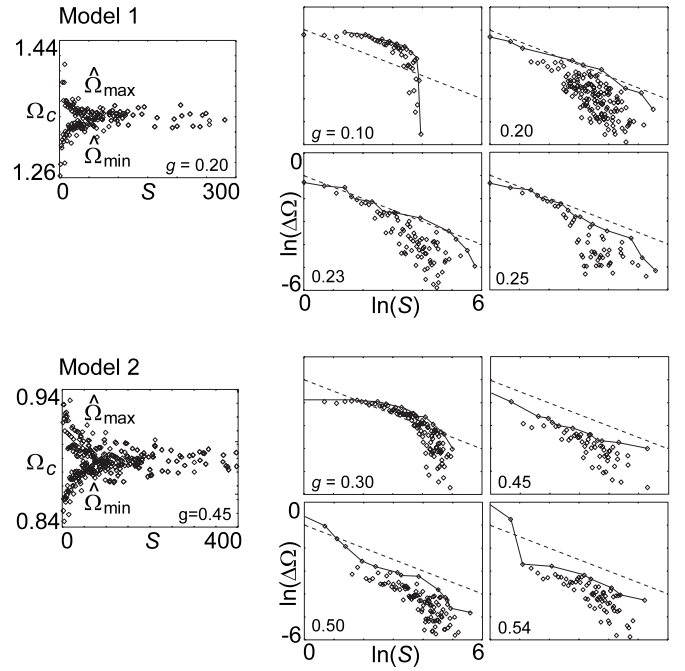


FIG. 12. $\hat{\Omega}_{\max}$ and $\hat{\Omega}_{\min}$ are the minimum and maximum frequencies of clusters of size S found numerically. Let us write $\Delta\Omega = \hat{\Omega}_{\max} - \hat{\Omega}_{\min}$. Lower bounds on $\Delta\Omega_{\max}(S)$ are shown, assuming $d\Delta\Omega_{\max}/dS < 0, \forall S$ (piecewise linear, continuous curves). Dashed lines: predictions by Eq. (51) for a critical ensemble. Data from 10 realizations of $\{\omega_k\}$ for each g .

D. Cluster frequencies

Assume that the frequency of a cluster C with spatial size $S \geq 1$ is bounded by the inequality

$$|\Omega_C - m_\infty| < \Delta\Omega_{\max}(S), \quad (50)$$

where $\Omega_k = \Omega_C$ whenever $k \in C$ [21]. For $t \geq 1$, choose $b \ll S$ and apply p_b . We get $\tilde{S} = b^{-D}S$, and $\Omega_{\tilde{C}} - m_\infty = b^{D/2}(\Omega_C - m_\infty)$ from Eq. (31). Consequently, $\Delta\Omega'_{\max}(b^{-D}S) = b^{D/2}\Delta\Omega_{\max}(S)$, and at a fixed point we get

$$\Delta\Omega'_{\max}(S) \propto S^{-1/2}. \quad (51)$$

Thus, the cluster frequencies vary less and less as their sizes increase.

Figure 12 shows comparisons between the theoretical prediction in Eq. (51) and numerical data. The numerical difference $\hat{\Omega}_{\max} - \hat{\Omega}_{\min}$ as a function of S is studied rather than the differences $\hat{\Omega}_{\max} - \hat{m}_\infty$ or $\hat{m}_\infty - \hat{\Omega}_{\min}$, where \hat{m}_∞ is a numerical estimation of m_∞ . The reason is that I want to estimate as few quantities as possible. Especially for large S , the latter differences are very sensitive to the choice of \hat{m}_∞ . Note however, that if these differences are used, data are obtained that support Eq. (51) to the same extent as the data shown in Fig. 12 does. Around g_{c1} and in phase 2, the agreement with theory is reasonable, given the fluctuations in the data. This gives further support to the idea that the entire phase 2 is critical. For model 2, the large values of $\Delta\Omega$ for $g=0.50$ and 0.54 for $S=1$ and $S=2$ are due to the existence of isolated oscillators which are transiently suppressed, with $\Omega_k \approx 0$ [20,25].

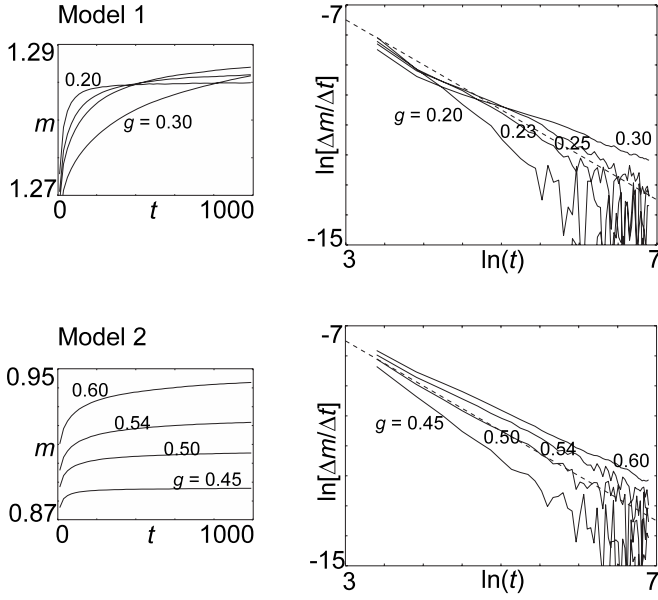


FIG. 13. Transient of mean frequency $m(t)$. Lattice size 2000×2000 . The dashed lines correspond to the prediction by Eq. (52) for a critical ensemble. Good data quality enables use of dm/dt , so that no asymptotic values have to be estimated (cf. Fig. 14).

E. Frequency transient

From Eq. (28) we get $\tilde{m}(t') = E[d\tilde{\phi}_j/dt'] = b^{D/2}m(t) - (b^{D/2} - 1)m_\infty$. At a fixed point we have $m^*(b^{D/2-1}t) - m_\infty^* = b^{D/2}(m^*(t) - m_\infty^*)$ with solution

$$m^*(t) - m_\infty^* \propto t^{-D/(D+2)}. \quad (52)$$

Close to the critical couplings $g_{c1} \approx 0.23$ (model 1) and $g_{c1} \approx 0.50$ (model 2), the agreement with Eq. (52) is excellent in the data shown in Fig. 13. In the double-logarithmic plots, there is a tendency to a gradual increase of the slope as g increases, suggesting that the scaling expressed in Eq. (52) only applies at g_{c1} , and not in the entire phase 2. This in turn suggests that phase 2 is *not* critical, at least that it is not attracted to the critical fixed point \mathcal{E}^* described in this paper.

F. Mean frequency for finite N

Taking the ensemble mean of Eq. (36) gives $E[\tilde{\omega}_j] - m_\infty = b^{D/2}(E[\tilde{m}_j] - m_\infty)$. We may write $m_\infty = m_\infty(N)$ and then have $E[\tilde{m}_j] = m_\infty(b^D)$. If we first let the size of the whole lattice go to infinity and then set $b^D = N$, we get

$$m_\infty(N) - m_\infty(\infty) = N^{-1/2}\{E[\tilde{\omega}_j] - m_\infty(\infty)\}. \quad (53)$$

Taking the ensemble mean of Eq. (32) in the limits $N \rightarrow \infty$ and $t \rightarrow \infty$, we get $\tilde{m}_\infty(\infty) = E[\tilde{\omega}_j] + E[\tilde{h}_j]$. Using Eq. (29), we may therefore write

$$m_\infty(\infty) - m_\infty(N) = N^{-1/2}E[\tilde{h}_j]. \quad (54)$$

At a critical fixed point \mathcal{E}^* , $E^*[\tilde{h}_j] = E^*[h_k]$ for all b (or N) and therefore $m_\infty(N) - m_\infty(\infty) \propto N^{-1/2}$ for all N . At a critical ensemble attracted to \mathcal{E}^* , we have $E^*[\tilde{h}_j] \rightarrow E^*[h_k]$ as $b \rightarrow \infty$ so that

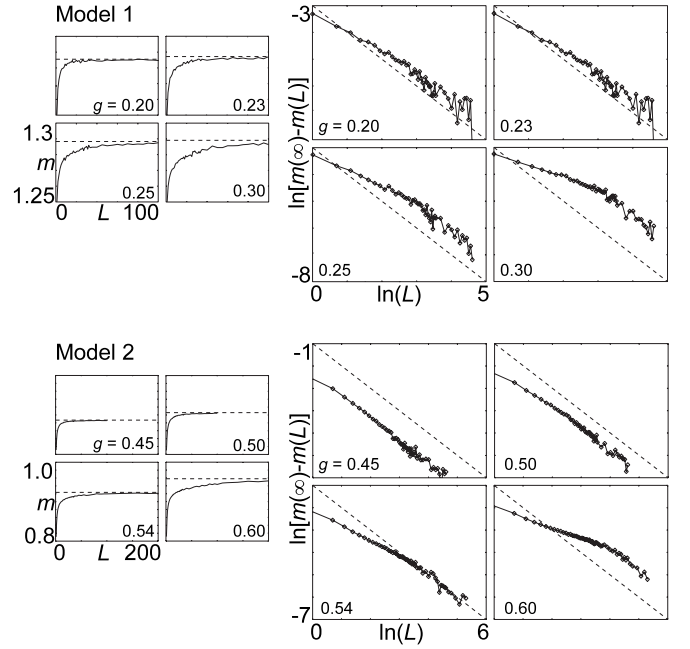


FIG. 14. Mean frequency $m(t)$ at time $t=1000$ versus $L=\sqrt{N}$. Averages of up to $400\,000/N$ realizations. Estimated values of $m(\infty)$ (dashed horizontal lines) provide good agreement with Eq. (55) for all g (dashed diagonal lines).

$$m_\infty(N) - m_\infty(\infty) \propto N^{-1/2}, \quad N \gg 1. \quad (55)$$

For odd coupling [Eq. (59)], we have $E[\tilde{h}_j] = E[h_k] = 0$ and $m_\infty(N) = E[\omega_k]$ for all N . This corresponds to zero constant of proportionality in Eq. (55).

For subcritical ensembles it is expected that $\lim_{b \rightarrow \infty} E[\tilde{h}_j] = 0$, and for supercritical ensembles that $\lim_{b \rightarrow \infty} E[\tilde{h}_j] = \infty$. In both cases, Eq. (55) cannot be expected to hold as $N \rightarrow \infty$.

Nevertheless, the data in Fig. 14 is consistent with Eq. (55) for all shown g . However, crossover to another scaling for larger $L = \sqrt{N}$ cannot be excluded. For both models, the asymptotic behavior is reached for larger L for higher values of g . Due to poor data quality (cf. Fig. 13), estimated values of $m(\infty)$ have to be relied upon, chosen to get curves in the double-logarithmic plots that are as straight as possible for large L . Another possible source of error is that I had to compute the mean frequencies at a rather small time $t=1000$ due to limited computational resources. However, tests with smaller and larger t indicate that this is not crucial.

G. Correlations of interactions

Let us turn to the renormalization of the interactions h_k . It turns out to be useful to decompose h_k into the coupling functions f_{lk} and to define the asymmetry function

$$d_m(x, y) \equiv f_{lk}(y, x) + f_{kl}(x, y), \quad (56)$$

where m is the edge connecting oscillators $l \in j$ and $k \in j$. Let n be a directed edge across δj (Fig. 15), and let us write $f_n = f_{lk}$, where $l \notin j$ and $k \in j$. We then have

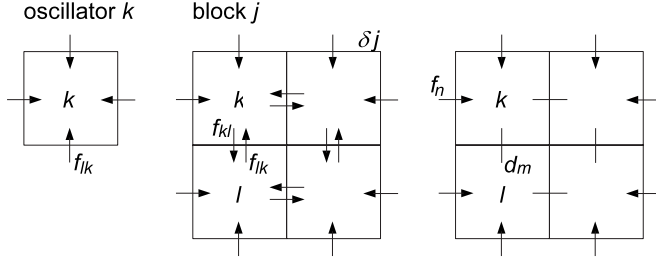


FIG. 15. The interaction h_k is a sum of the $2D$ coupling functions f_{lk} . In the same way, the interaction \tilde{h}_j of block j can be decomposed into a sum of $2Db^{D-1}$ border terms f_n and $Db^D(1-b^{-1})$ interior terms $d_m=f_{lk}+f_{kl}$.

$$\tilde{h}_j = b^{-D/2} g \left[\sum_n f_n + \sum_m (d_m - \underline{d}_m^<) \right], \quad (57)$$

where $d_m^<(x,y) = f_{lk}^<(x,y) + f_{kl}^<(y,x)$. To make the following expressions more compact, let

$$\Delta d_m = d_m - \underline{d}_m^< \quad (58)$$

be the mean increase of d_m as block j is connected to its neighbor block oscillators. For odd coupling, i.e.,

$$f_{lk}(y,x) \equiv -f_{kl}(x,y), \quad \forall lk, \quad (59)$$

we have $d_m \equiv \underline{d}_m^< \equiv 0$. An example is the Kuramoto model $f_{lk}(x,y) = \sin[2\pi(x-y)]$.

Information about critical behavior can be gained by comparing moments of the original and renormalized interactions: $E[h_k]$, $E[h_k^2]$, and so on. A comparison between $E[h_k]$ and $E[\tilde{h}_j]$ just leads us back to Eq. (54). Below, I focus instead on $\text{var}[h_k]$ and $\text{var}[\tilde{h}_j]$, from which information can be gained of two-point correlations of the interaction. At this point we make use of assumption (23). We may then write

$$\text{var}[\tilde{h}_j] = b^{-D} \sum_{k,k' \in j} \text{cov}[h_k - \underline{h}_k^<, h_{k'} - \underline{h}_{k'}^<], \quad (60)$$

or, upon decomposition,

$$\begin{aligned} \text{var}[\tilde{h}_j] &= b^{-D} g^2 \sum_{n,n'} \text{cov}[f_n, f_{n'}] + b^{-D} g^2 \sum_{n,m} \text{cov}[f_n, \Delta d_m] \\ &+ b^{-D} g^2 \sum_{m,m'} \text{cov}[\Delta d_m, \Delta d_{m'}] = S_1 + S_2 + S_3. \end{aligned} \quad (61)$$

In the following, three correlation functions will be used:

$$\begin{aligned} \Gamma_{f_l}(r) &= \lim_{t \rightarrow \infty} \frac{\text{cov}[f_{lk}, f_{l'k'}]_{|l'k' - lk| = r}}{\text{var}[f_{lk}]}, \\ \Gamma_{f \Delta d}(r) &= \lim_{t \rightarrow \infty} \frac{\text{cov}[f_n, \Delta d_m]_{|n-m| = r}}{\text{cov}[f_n, \Delta d_m]_{|n-m| = 1}}, \\ \Gamma_{\Delta d}(r) &= \lim_{t \rightarrow \infty} \frac{\text{cov}[\Delta d_m, \Delta d_{m'}]_{|m-m'| = r}}{\text{var}[\Delta d_m]}. \end{aligned} \quad (62)$$

Note that f_{lk} has a direction of influence $l \rightarrow k$ and that d_m is vertical or horizontal. Correlations between different types of

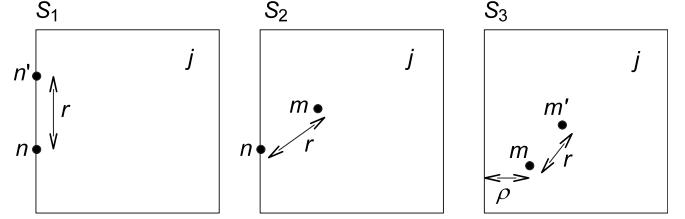


FIG. 16. Pairs of interactions and distances in a block-oscillator j , used in the expressions for S_1 , S_2 , and S_3 in Eqs. (61), (64), (67), and (70).

pairs should therefore be separated, and summed up to yield the covariances in Eq. (61). Numerically, only parallel pairs are considered.

A necessary fixed-point condition is $\text{var}^*[\tilde{h}_j] = \text{var}^*[h_k]$ for any b as $t \rightarrow \infty$, or, in particular, at a nontrivial fixed point,

$$\lim_{b \rightarrow \infty} \lim_{t \rightarrow \infty} \text{var}^*[\tilde{h}_j] = \text{const} > 0. \quad (63)$$

We may write

$$S_1 \propto b^{-D} \int_1^b N_1(r) \Gamma_{f_l}(r) dr, \quad (64)$$

where

$$N_1(r) = \mathcal{O}(b^{D-1} r^{D-2}) \quad (65)$$

is the number of pairs nn' at distance r (Fig. 16). It follows that

$$\lim_{b \rightarrow \infty} S_1 = \text{const} > 0 \Leftrightarrow \Gamma_{f_l}(r) \propto r^{2-D}. \quad (66)$$

Similarly,

$$S_2 \propto b^{-D} \int_1^b N_2(r) \Gamma_{f \Delta d}(r) dr, \quad (67)$$

where

$$N_2(r) = \mathcal{O}(b^{D-1} r^{D-1}) \quad (68)$$

is the number of pairs nm at distance r (Fig. 16). Therefore it is expected that

$$\lim_{b \rightarrow \infty} S_2 = \text{const} > 0 \Leftrightarrow \Gamma_{f \Delta d}(r) \propto r^{1-D}. \quad (69)$$

Turning to S_3 , we may write

$$\text{cov}[\Delta d_m, \Delta d_{m'}] = \psi(\rho) \Gamma_{\Delta d}(r), \quad (70)$$

where ρ is the smallest distance from any of the two edges m or m' to δj and r is the distance between m and m' (Fig. 16). The function

$$\psi(\rho) = \text{var}[\Delta d_m] \quad (71)$$

measures how the lattice that surrounds block j , in the mean, changes d_m at distance ρ from δj so that we have

$$\psi(1) > 0$$

$$\lim_{\rho \rightarrow \infty} \psi(\rho) = 0. \quad (72)$$

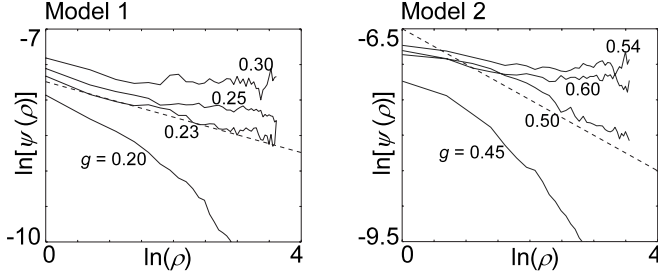


FIG. 17. $\psi(\rho) = \text{var}[\Delta d_m]$ as a function of the distance ρ from δj to the edge m (Fig. 16). For both models, it seems that $\psi(\rho) \propto \rho^{-\alpha}$ at g_{c1} . For model 1, $\alpha \approx 1/4$, and for model 2, $\alpha \approx 1/2$. Lattice size: 140×140 . Block size: 70×70 . Transient time: $t=5000$. For each of 10 realizations of $\{\omega_k\}$, 20 initial conditions $\phi(0)$ were used.

We may then write

$$S_3 \propto b^{-D} \int_1^{b/2} \psi(\rho) \int_1^{b-2\rho} N_3(\rho, r) \Gamma_{\Delta d}(r) dr d\rho. \quad (73)$$

Here,

$$N_3(\rho, r) = \mathcal{O}(\rho^{D-1} r^{D-1}) \quad (74)$$

is the number of pairs mm' for given ρ . In a critical fixed-point ensemble, it is expected that

$$\psi^*(\rho) \propto \rho^{-\alpha}, \quad (75)$$

and therefore we get

$$\lim_{b \rightarrow \infty} S_3 = \text{const} > 0 \Leftrightarrow \Gamma_{\Delta d}^*(r) \propto r^{\alpha-D}, \quad (76)$$

provided $\alpha \neq 1$.

I have not been able to deduce the value of α from first principles. Figure 17 shows numerical estimations of $\psi(r)$ for model 1 and model 2. It seems that $\alpha=1/4$ for model 1 and $\alpha=1/2$ for model 2, and thus that it is a nonuniversal model dependent critical exponent. Scaling form (75) seems to apply only at $g=g_{c1}$, suggesting that phase 2 is not critical.

It can be argued that since d_m and Δd_m are linear combinations of f_{lk} and f_{lk}^* , Γ_f , Γ_d , $\Gamma_{f\Delta d}$, and $\Gamma_{\Delta d}$ should have the same functional form for $r \gg 1$. Then,

$$\Gamma_f^* \propto \Gamma_d^* \propto r^{-\beta}, \quad (77)$$

with

$$\begin{aligned} \beta &= D-2, & \text{odd } f_{lk} \text{ (case 1),} \\ \beta &= D-1, & \text{other } f_{lk}, \alpha \geq 1 \text{ (case 2),} \\ \beta &= D-\alpha, & \text{other } f_{lk}, \alpha < 1 \text{ (case 3).} \end{aligned} \quad (78)$$

The terms S_1 , S_2 , and S_3 are responsible for criticality in the three cases, respectively. In case 1,

$$\begin{aligned} S_1^* &= \text{const} > 0, \\ S_{2,3}^* &= 0. \end{aligned} \quad (79)$$

[In fact, $S_{2,3}=0$ for all ensembles since $d_m(x) \equiv 0$.] In case 2,

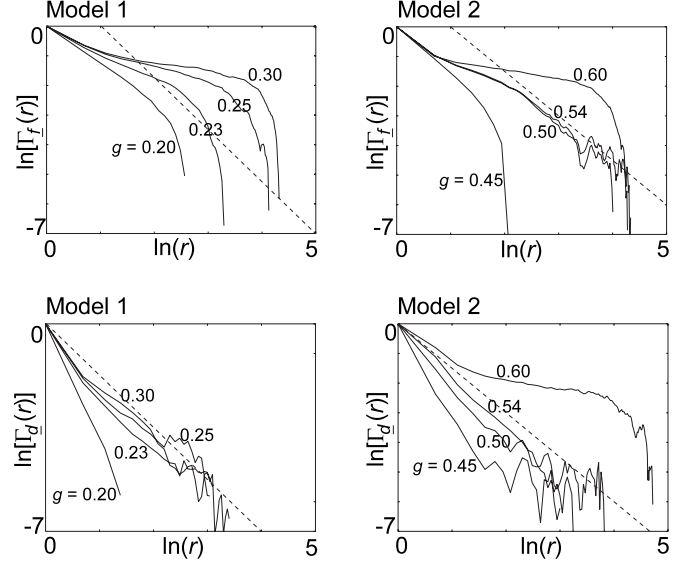


FIG. 18. Pair correlations of f (left) and d (right). According to Eq. (78) and the estimations of α in Fig. 17, it is expected that $\beta = -7/4$ for model 1, and $\beta = -3/2$ for model 2 in critical ensembles (dashed lines). Ten $\phi(0)$ were used for each g to estimate the initial condition mean. In model 2, a time average of each f_{lk} was calculated during $\Delta t=100$, due to its pulselike nature. The choice of Δt did not affect the results.

$$\lim_{b \rightarrow \infty} S_2^* = \text{const} > 0,$$

$$\lim_{b \rightarrow \infty} S_{1,3}^* = 0, \quad (80)$$

and in case 3,

$$\lim_{b \rightarrow \infty} S_3^* = \text{const} > 0,$$

$$\lim_{b \rightarrow \infty} S_{1,2}^* = 0. \quad (81)$$

In cases 1 and 2, critical behavior is ruled out below $D=3$ and $D=2$, respectively, since correlations must decay with r . In case 1, the result $D_c \geq 2$ by Daido [29] is regained.

The numerical results in Fig. 17 suggest that $\alpha < 1$ for both models 1 and 2, and thus that the term S_3 is responsible for criticality in both models. However, since the estimated values of α differ, it is possible that there are other nonodd models with $\alpha \geq 1$, in which case S_2 becomes the crucial term.

Figure 18 shows numerical estimations of $\Gamma_f(r)$ and $\Gamma_d(r)$. Looking at $\Gamma_d(r)$, the data is consistent with the combined theoretical and numerical predictions [Eq. (78) and Fig. 17] in both models 1 and 2. Looking at $\Gamma_f(r)$, the data are consistent with theory only in model 2.

The reason for this discrepancy between numerical data and theory in model 1 is likely to be found in the fact that $\Gamma_f(r)$ is less well behaved than $\Gamma_d(r)$ for finite lattice sizes. The phase fields $\phi(x, y)$ become more and more well ordered as g increases, containing just a few foci or spirals as phase 3 is approached (at the present lattice size) [25]. Therefore the phase waves tend to move in opposite directions at opposite ends of the lattice, giving rise to negative correlations

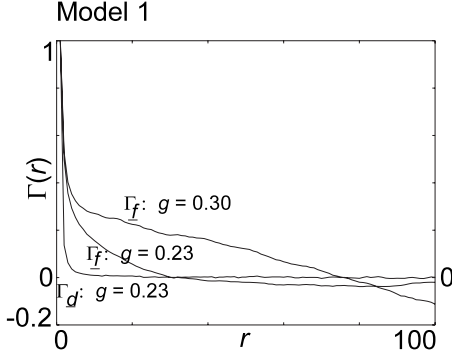


FIG. 19. Illustration of the fact that numerical estimations of $\Gamma_f(r)$ are less well behaved than those of $\Gamma_d(r)$. For a given finite lattice size, $\Gamma_f(r)$ becomes more ill-behaved when g increases (see text). In model 2, a time average of each f_{lk} was calculated during $\Delta t=100$. (cf. Figure 18).

of f at large distances. This dependence on the wave direction of the correlations is eliminated by the definition of d [Eq. (56)].

This problem is illustrated for model 1 in Fig. 19. Close to criticality, for $g=0.23$, $\Gamma_d(r)$ converges nicely toward zero as r increases, whereas $\Gamma_f(r)$ drops significantly below zero, and then fluctuate, at least up to $r=150$. (This is the maximum r considered, since the lattice size is 300×300 .) This effect is more prominent for larger g as seen in the estimation of $\Gamma_f(r)$ for $g=0.30$. The zero crossings of $\Gamma_f(r)$ is the reason why the curves drop sharply in the double-logarithmic plots in Fig. 18.

H. Correlation length

Let us analyze Γ_f close to a critical fixed point in a subcritical ensemble and make the standard ansatz

$$\Gamma_f(r) = cr^{-\beta} e^{-r/\xi(\Delta g)}, \quad (82)$$

where

$$\Delta g = (g - g^*)/g^*. \quad (83)$$

As discussed below, subcriticality is expected only for $g < g^*$. It is therefore assumed that $\Delta g \leq 0$. We may write $\text{var}[f_{lk}] = F(g)$. Assuming that $dF/dg \neq 0$ at $g = g^*$, we have

$$\Delta g \propto \text{var}^*[f_{lk}] - \text{var}[f_{lk}] \quad (84)$$

for small enough Δg . Consider the case of odd coupling. From expression (64) for S_1 we get

$$\Delta g' \propto b^{-1} \int_1^b r^{D-2} [\Gamma_f^*(r) - \Gamma_f(r)] dr. \quad (85)$$

Taylor expanding the exponential part of Γ_f gives $\Delta g' \propto b \xi^{-1}$. Using $\xi' = \xi/b$, specifying $\xi = \xi_f$, it is seen that the correlation length of the initial condition mean of the coupling f_{lk} diverges according to

$$\xi_f \propto \Delta g^{-1}, \quad (86)$$

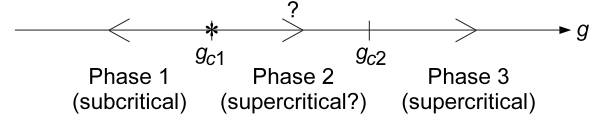


FIG. 20. Hypothetical flow under R_b in a one-dimensional projection of $\{\mathcal{E}\}$. The critical coupling strength g_{c1} is supposed to belong to the stable manifold S_c of the critical fixed point \mathcal{E}^* (cf. Fig. 2). It is speculated that the flow does not pass g_{c2} , i.e., that phase 2 is invariant. See text for explanation.

for small enough $|\Delta g|$ if $\Delta g < 0$. A similar calculation gives the same result in the cases of nonodd coupling, using the expressions for S_2 and S_3 .

Indeed, simulations suggest that ξ_f diverges at $g = g_{c1}$, but unfortunately I have not been able to obtain good enough data to test relation (86). The fluctuations in the estimated ξ_f are too large close to g_{c1} . [I used up to three realizations of $\{\omega_k\}$ for each g , and for each $\{\omega_k\}$, ten $\phi(0)$ were used to estimate the initial condition mean.] It was not possible to use data from estimations of Γ_d either since it drops close to zero for too small r to be able to resolve its functional form.

I. Direction of the renormalization flow

In Fig. 17 the exponent α is estimated in the relation $\psi(\rho) \propto \rho^{-\alpha}$ [Eqs. (71) and (75)] that is expected to hold in a critical ensemble. Let us call these estimations α_1 and α_2 for models 1 and 2, respectively. In phases 2 and 3, $\psi(\rho)$ clearly falls off slower than this. Figure 18 shows that in phases 2 and 3, Γ_f and Γ_d falls off as $r^{-(D-\alpha_1)}$ (model 1), $r^{-(D-\alpha_2)}$ (model 2), or possibly slower. Taken together, these observations suggest that condition (76) is violated in phases 2 and 3, and that $\lim_{b \rightarrow \infty} S_3 = \infty$. This in turn means that $\lim_{b \rightarrow \infty} \text{var}[\tilde{h}_j] = \lim_{b \rightarrow \infty} \text{var}[h'_j] = \infty$, and that the renormalization flow goes in the direction of increasing g for $g > g_{c1}$ (Fig. 20). That the flow goes toward $g=0$ for $g < g_c$ becomes clear from a similar argument. I have mentioned the possibility that the entire phase 2 is critical and that it is attracted to the critical fixed point \mathcal{E}^* . Some numerical results favor such an interpretation (see Figs. 9, 12–14, and 18 and also Ref. [20]). However, based on the combined numerical and theoretical argument given above, I hypothesize that this is not so.

Referring to the discussion in Sec. V C, it seems that the renormalization flow in phase 2 cannot approach states with $r=1$. Therefore it is probable that phase 2 is invariant under R_b . There may be a second, attractive fixed point with $\text{var}[\Omega_k] = \infty$ somewhere along the line separating phases 2 and 3, possibly at infinity where $g \rightarrow \infty$ or $\sigma_\omega^2 \rightarrow \infty$.

Correlation functions seem to decay as a power law or slower for all $g > g_{c1}$. In fact, Eqs. (64), (67), and (70) predict that finite correlation lengths are excluded for $g > g_{c1}$ since whenever Γ_f has an exponential factor, $\lim_{b \rightarrow \infty} S_{1-3} = 0$. This corresponds to a renormalization flow toward $g=0$ ($\text{var}[\tilde{h}_j] = 0$), which can be expected only for $g < g_{c1}$. Therefore, phases 2 and 3 must be considered *supercritical*.

VI. DISCUSSION

In this paper, I present a real-space renormalization transformation for oscillator lattices with quenched disorder. The

transformation acts on ensembles of lattices and predicts the behavior of ensemble averaged quantities. It is assumed that the variance of the natural and attained frequencies exists, but it should be possible to generalize the theory. A bold hypothesis is that *if* a system of form (9) is critical for some parameter values, then the critical behavior is given by the critical fixed point \mathcal{E}^* described in this paper. At its present stage, the theory cannot be used to decide *whether* a given system possesses a critical phase transition. However, lower bounds on critical dimensions for different classes of systems are given.

In this respect, the crucial difference between odd and nonodd coupling stands out clearly in the analysis. For non-odd coupling, macroscopic synchronization cannot be ruled out for any dimension $D \geq 1$, whereas for odd coupling it is necessary that $D \geq 3$. Perfectly odd coupling must be regarded as a nongeneric special case, except for particular problems that can be mapped onto Kuramoto-type models, such as Josephson-junction arrays [18].

The merits of the approach are that it is simple, that it applies to a broad class of systems, that several predictions about critical behavior can be extracted, and that it is potentially exact. Most of the predictions have been tested numerically with two structurally different two-dimensional models. The agreement with theory ranges from acceptable to very good. The drawback of the approach is that the theory must be considered heuristic at its present stage. Its full potential and its mathematical foundation should be clarified.

My experience is that it is computationally demanding to get good numerical data to compare with theory. Large oscillator lattices [$\mathcal{O}(10^5)$ oscillators] and long simulation times [$\mathcal{O}(10^5)$ periods of oscillation] are typically needed to see critical behavior. Further, to get good ensemble averages, it seems that $\mathcal{O}(10)$ realizations of the initial condition are needed for each of $\mathcal{O}(10)$ to $\mathcal{O}(100)$ realizations of natural periods. In other words, $\mathcal{O}(100)$ to $\mathcal{O}(1000)$ realizations are needed for lattice sizes and integration times of the above order of magnitude. This is probably the reason why almost no clear-cut numerical results regarding the existence or non-existence of phase transitions in oscillator lattices have been presented in the past (Sec. II B). The data presented in this paper should be seen as an initial overview of the behavior of some relevant quantities. A more detailed study of each quantity is needed. In particular, the number of realizations of natural periods has to be increased.

To put the theory to further test, it goes without saying that simulations of oscillator lattices with dimensions other than $D=2$ are called for. Perhaps the quantities used in this paper can be used to find an answer to the long-standing question whether there is a transition to macroscopic synchronization in the three-dimensional Kuramoto model.

It is worth noting that the relevance of the second critical coupling g_{c2} is established in this study. It was first described in Ref. [20], but there a density function \mathcal{D}_ω of natural fre-

quencies with finite support was used. Here, I find that it is present even if \mathcal{D}_ω has tails. It is therefore a more generic transition than that to $R=1$ in the globally coupled Kuramoto or Winfree models [27], appearing when \mathcal{D}_ω has no tails. The nature of the transition at g_{c2} is a subject for future work, and the question whether there is an additional nontrivial fixed point associated with this transition is left unanswered.

Theory and numerics taken together indicate that the renormalization flow goes toward increasing g for $g > g_{c1}$ (Fig. 20). I judge that both phases 2 and 3 are supercritical, and Sec. II gives a technical argument why this is so. Here, a qualitative argument is presented why an oscillator lattice cannot be subcritical above g_{c1} , that is, why correlation functions cannot have exponential tails, corresponding to finite correlation lengths.

Correlation lengths relate to the typical distance a perturbation or fluctuation spreads. Let us compare with the Ising model, which is subcritical both above and below the critical temperature T_c . In the ordered phase below T_c , most spins are aligned. Let us introduce a perturbation in the form of a spin with opposite direction. Such a spin increases the probability that a neighbor spin will also flip. The perturbation tends to spread. However, the lower the temperature, the smaller the probability that the neighbor will flip, according to the Boltzmann distribution. Thus, a typical perturbation spreads shorter distances, and the correlation length drops.

The situation is quite different in the ordered phase of an oscillator lattice, where I am thinking mainly of states with partial frequency synchronization ($0 < r < 1$). A perturbation in such a lattice corresponds to an oscillator k that runs at a different frequency. This perturbation spreads to the rest of the lattice via the coupling functions, which will not vary with the entrained frequency. Assume for simplicity that the coupling has the form $g\varphi_{lk}(\phi_l - \phi_k)$. The peak magnitude of this perturbation can only increase with g , since the argument takes on all values in the range $[0, 1)$ because Ω_l and Ω_k are assumed to be different. Thus, if the correlation lengths are infinite at a critical coupling g_{c1} , they should stay infinite even if $g > g_{c1}$.

In conclusion, I hope that this study will inspire further theoretical and numerical work on macroscopic synchronization in oscillator lattices. Unfortunately, the understanding of these systems has fallen way behind the understanding of globally coupled oscillator networks. A better understanding of oscillator lattices should also promote the understanding of transitions to macroscopic synchronization in complex networks since the topology of these often can be seen as lying in between the topologies of the lattice and the fully connected network.

ACKNOWLEDGMENT

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- [38] If we let $g \rightarrow \infty$, then almost all $h_k \rightarrow \infty$ and $\text{var}[h_k]$ will not exist. Those $h_k = g \sum_{l \in n_k} f_{lk}(\phi_l, \phi_k)$ that might still be finite are those for which the phases in the f_{lk} s are fine tuned so that the sum vanishes.
- [39] Taking the ensemble variance of both sides of Eq. (21) at the fixed point, we get $\text{var}^*[d\phi_k/dt] = (\sigma_\omega^2)^* + \text{var}^*[h_k] + 2 \text{cov}^*[\omega_k, h_k]$. Because of the statistical inequality $|\text{cov}[X, Y]| \leq \sqrt{\text{var}[X]\text{var}[Y]}$ we see that $\text{var}^*[d\phi_k/dt]$ exists since $(\sigma_\omega^2)^*$ and $\text{var}^*[h_k]$ do so by assumption [Eq. (23)]. It follows that $E^*[d\phi_k/dt]$ also exists. These statements hold for any t . We may express $\Omega_k = \langle d\phi_k/dt \rangle_t$. It is straightforward to show that $E^*[\Omega_k] = \langle E^*[d\phi_k/dt] \rangle_t$ and that $\text{var}^*[\Omega_k] \leq \max\{\text{var}^*[d\phi_k/dt]\}_t$. Finally, we must have $\text{var}^*[\Omega_k] > 0$ at a critical fixed point corresponding to a transition to *partial* synchronization [21].