

Reciprocity relations between ordinary temperature and the Frieden-Soffer Fisher temperature

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Frieden and Soffer conjectured some years ago [Phys. Rev. E **52**, 2274 (1995)] the existence of a “Fisher temperature” T_F that would play, with regards to Fisher’s information measure I , the same role that the ordinary temperature T plays in relation to Shannon’s logarithmic measure. Here we exhibit the existence of reciprocity relations between T_F and T and provide an interpretation with reference to the meaning of T_F for the canonical ensemble.

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I. WHY A FISHER TEMPERATURE?

Frieden and Soffer conjectured some years ago [1,2] the existence of a “Fisher temperature” T_F that would play, with regards to Fisher’s information measure I , the same role that the ordinary temperature T plays in relation to Shannon’s logarithmic measure S [3,4]. In a series of more recent publications, this conjecture was amply validated by showing that the Legendre transform structure of thermodynamics can be replicated without changes if one substitutes I for the Shannon entropy S [5–8], which yields then a “Fisher thermodynamics.”

This Fisher thermodynamics is exactly equivalent to the conventional one, except that instead of the Shannon-Boltzmann-Gibbs (SBG) entropy S one uses Fisher’s I [5–8]. A question still lingers, though: we have a SBG pair (S, T) and a Fisher pair (I, T_F) . What is the relation between T and T_F ?

In other words, in parallel to $(1/T)=dS/dU$ (U is the mean energy) [9], we have $(1/T_F)=dI/dU$ [5–8]. We need a thermometer to measure T_F , and this is best achieved by finding a relationship between the two temperatures. In this Brief Report we purport to provide a first answer with respects to the relation between T and T_F .

II. BRIEF FISHER CONSIDERATIONS

Estimation theory [2] provides one with a powerful result with reference to a system that is specified by a physical parameter θ . Let \mathbf{x} be a stochastic variable and $p_\theta(\mathbf{x})$ the probability density for this variable, which depends on the parameter θ . If an observer (i) makes a measurement of \mathbf{x} and wishes to best infer θ from this measurement, calling the resulting estimate $\tilde{\theta}=\tilde{\theta}(\mathbf{x})$ and (ii) wonders how well θ can be determined, then estimation theory asserts [2] that the best possible estimator $\tilde{\theta}(\mathbf{x})$, after a very large number of \mathbf{x} samples is examined, suffers a mean-square error e^2 from θ , which obeys a relationship involving Fisher’s I —namely, $Ie^2=1$ —where the Fisher information measure (FIM) I is of the form

$$I = \left\langle \left(\frac{\partial \ln p_\theta}{\partial \theta} \right)^2 \right\rangle. \quad (1)$$

The FIM is additive [2]. If we have n independent parameters θ_i , Eq. (1) becomes a sum of n terms of the form given

above [2]. The “best” estimator is called the *efficient* estimator. Any other estimator must have a larger mean-square error. The only proviso to the above result is that all estimators be unbiased—i.e., satisfy $\langle \tilde{\theta}(\mathbf{x}) \rangle = \theta$. Thus, Fisher’s information measure has a lower bound, in the sense that, no matter what parameter of the system we choose to measure, I has to be larger or equal than the inverse of the mean-square error associated with the concomitant experiment. This result, i.e.,

$$Ie^2 \geq 1, \quad (2)$$

is referred to as the Cramer-Rao bound and constitutes a very powerful statistical result [2].

III. FORMALISM

We start by defining the well-known density operator that describes a system at equilibrium [3,4]:

$$\hat{\rho} = \frac{1}{Z} \exp \left(- \sum_{i=1}^M \chi_i \hat{A}_i \right). \quad (3)$$

The χ_i are Lagrangian multipliers associated to the M observables \hat{A}_i , whose expectation values are given by

$$\langle \hat{A}_i \rangle = \text{Tr} \hat{\rho} \hat{A}_i \quad (i = 1, \dots, M), \quad (4)$$

where the partition function Z has the form $Z(\chi_i) = \text{Tr}[\exp(-\sum_{i=1}^M \chi_i \hat{A}_i)]$ [10]. In our present considerations we assume that these multipliers *have already been determined*.

Following Mandelbrot [11–13] we (i) *associate* the above Lagrange multipliers to parameters to be estimated via *Fisher considerations* involving a FIM that depends upon $\hat{\rho}$ and (ii) write down this FIM as a sum of M terms, each one associated to the estimation of the parameter χ_i , i.e.,

$$I = \sum_{i=1}^M \Gamma_i \left\langle \left(\frac{\partial \ln \hat{\rho}}{\partial \chi_i} \right)^2 \right\rangle, \quad (5)$$

where the Γ_i are suitable constants related to the (conventional) wish of having a dimensionless I , as discussed in [14,15]. After replacing Eq. (3) into Eq. (5) we then find that I is intimately connected to our observables’ fluctuations, as pointed out long ago by Mandelbrot [11,16]:

$$I = \sum_{i=1}^M \Gamma_i \langle (\hat{A}_i - \langle \hat{A}_i \rangle)^2 \rangle. \quad (6)$$

If we wish to have a dimensionless I , Γ_i has the dimension of $[1/\text{dim}(\hat{A}_i)^2]$. Now, it is well known (and straightforwardly verified) that the statistical fluctuations of an observable obey the relation [11,16]

$$\langle (\hat{A}_i - \langle \hat{A}_i \rangle)^2 \rangle = - \frac{\partial \langle \hat{A}_i \rangle}{\partial \chi_i} \quad (7)$$

(the χ_i have dimension of $[1/\text{dim}(\hat{A}_i)]$), which allows us to recast the Fisher measure in the fashion

$$I = - \sum_{i=1}^M \Gamma_i \frac{\partial \langle \hat{A}_i \rangle}{\partial \chi_i}. \quad (8)$$

IV. EXTREMIZATION OF I SUBJECT TO CONSTRAINTS

As stated above, the thermodynamics Legendre structure can be neatly re-obtained if one extremizes FIM subject to constraints instead of doing this using the Boltzmann entropy [5–8]. We deal then with the same mean values $\langle \hat{A}_i \rangle$ used above, but, of course, different Lagrange multipliers will ensue. Let us call these new Fisher multipliers γ_i and borrow from the well-known thermodynamic relation that links information measure, Lagrange multipliers (here the Fisher ones), and expectation values [3,5]:

$$\gamma_i = \frac{\partial I}{\partial \langle \hat{A}_i \rangle}. \quad (9)$$

It is now clear that, introducing the above result into Eq. (8), we get an expression for the Fisher multipliers γ_i in terms of the Shannon ones (χ_i):

$$\gamma_i = - \sum_{j=1}^M \Gamma_j \frac{\partial}{\partial \langle \hat{A}_j \rangle} \frac{\partial \langle \hat{A}_j \rangle}{\partial \chi_j}; \quad \text{dim}(\gamma_i) = \text{dim}(1/\hat{A}_i), \quad (10)$$

a relation which could be used to determine them. It might seem at this point natural to ask what happens if we consider a canonical distribution in which the Lagrange multipliers are the γ_i instead of the χ_i . We discuss this question below for classical systems within the strictures of the canonical ensemble.

V. EQUIPARTITION THEOREM

In classical statistical mechanics there exists a useful general result concerning the energy E of a system expressed as a function of $2N$ generalized coordinates ξ_i (for instance, N coordinates r_i and N momenta p_i). Thus, $E = E(\xi_1, \dots, \xi_{2N})$. The result holds in the case of the following (frequent) occurrence.

(i) The energy splits additively into the form $E = \epsilon_i(\xi_i) + E'(\xi_1, \dots, \xi_{i-1}, \xi_{i+1}, \dots, \xi_{2N})$, where $\epsilon_i(\xi_i)$ involves only the

variable ξ_i and the remaining part E' does not depend on ξ_i .

(ii) The function $\epsilon_i(\xi_i)$ is quadratic in ξ_i .

In these circumstances $\langle \epsilon_i \rangle = kT/2$, with k Boltzmann's constant and T the temperature. This is the equipartition theorem [9]. The mean value of each independent quadratic term in the energy E equals $kT/2$, where $\beta = 1/kT$ is the (Shannon-Boltzmann-Gibbs) Lagrange multiplier associated with the the mean-energy constraint $\langle E \rangle = \int d\tau f E$. Its demonstration assumes that the thermal equilibrium Boltzmann-Gibbs equilibrium probability distribution

$$f = \frac{1}{Z} e^{-\beta E}, \quad (11)$$

with $d\tau$ the phase-space volume element. Setting $\Gamma = 1/k^2 T_0^2$, with T_0 an arbitrary but fixed reference temperature, yields a dimensionless Fisher information measure (8) for the canonical ensemble:

$$I = - \frac{1}{k^2 T_0^2} \frac{\partial \langle E \rangle}{\partial \beta}. \quad (12)$$

VI. RECIPROCITY

Since we assume equipartition, we immediately find [9]

$$\langle E \rangle = N\beta^{-1}, \quad (13)$$

implying

$$\frac{\partial \langle E \rangle}{\partial \beta} = -N\beta^{-2} = -\frac{\langle E \rangle^2}{N}, \quad (14)$$

entailing that, according to Eq. (10), the Fisher multiplier (defined as $\gamma = 1/kT_F$) is

$$\gamma = \frac{1}{kT_F} = - \frac{1}{k^2 T_0^2} \frac{\partial}{\partial \langle E \rangle} \frac{\partial \langle E \rangle}{\partial \beta} = \frac{2}{k^2 T_0^2 \beta}. \quad (15)$$

Since the multipliers are inverse temperatures, we obtain the interesting relationship

$$T_F = \frac{T_0^2}{2T}, \quad (16)$$

our main result here, which, on reflection, should not surprise anyone since it is a well-known fact that whenever I grows, Shannon's S decreases and vice versa [2]. Note that the Fisher information (12) adopts now the following appearance:

$$I = \frac{\langle E \rangle^2}{Nk^2 T_0^2}, \quad \frac{\partial I}{\partial \langle E \rangle} = \frac{2}{k^2 T_0^2 \beta}, \quad (17)$$

where we have used equipartition ($\langle E \rangle = N/\beta$), leading to

$$\frac{1}{\beta} = \frac{k^2 T_0^2}{2} \frac{\partial I}{\partial \langle E \rangle}, \quad \langle E \rangle \equiv \langle E \rangle_\beta. \quad (18)$$

With reference to Eq. (15), let us introduce now the Fisher result $\gamma = 2/(k^2 T_0^2 \beta)$ as the multiplier entering the canonical probability distribution f in Eq. (11) and repeat the preceding

discussion, starting with the relation that takes now the place of Eq. (13), here

$$\langle E \rangle_\gamma = N\gamma^{-1}. \quad (19)$$

One has

$$\frac{\partial \langle E \rangle_\gamma}{\partial \gamma} = -N\gamma^{-2} = -\frac{\langle E \rangle_\gamma^2}{N}. \quad (20)$$

We ask ourselves what is now the new Fisher multiplier γ_2 . The answer is, using Eqs. (19) and (15),

$$\gamma_2 = -\frac{1}{k^2 T_0^2} \frac{\partial}{\partial \langle E \rangle_\gamma} \frac{\partial \langle E \rangle_\gamma}{\partial \gamma} = \frac{2}{k^2 T_0^2} \frac{\langle E \rangle_\gamma}{N} = \gamma \beta \frac{\langle E \rangle_\gamma}{N}, \quad (21)$$

i.e.,

$$\gamma_2 = \beta, \quad (22)$$

which is indeed consistent with Eq. (18). Here we encounter reciprocity. The ‘‘Fisher multiplier’’ γ_2 is the inverse

Boltzmann-Gibbs-Shannon temperature that verifies [cf. Eq. (17)]

$$\frac{1}{kT} = \beta = \frac{\partial I(\gamma)}{\partial \langle E \rangle_\gamma},$$

$$\frac{1}{kT_F} = \gamma = \frac{\partial I(\beta)}{\partial \langle E \rangle_\beta}, \quad (23)$$

in self-explanatory notation. Equation (17) can be written in either the ‘‘ β ’’ language or in the ‘‘ γ ’’ one, indistinctly.

VII. CONCLUDING REMARKS

We have in this Brief Report provided two results that we deem important for the Fisher practitioners: namely, (a) $T_F = T_0^2/2T$, with T_0 an arbitrary but fixed reference Boltzmann temperature, and (b) the reciprocity relations given by Eq. (23).

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