

Statistical ensemble of scale-free random graphs

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A thorough discussion of the statistical ensemble of scale-free connected random tree graphs is presented. Methods borrowed from field theory are used to define the ensemble and to study analytically its properties. The ensemble is characterized by two global parameters, the fractal and the spectral dimensions, which are explicitly calculated. It is discussed in detail how the geometry of the graphs varies when the weights of the nodes are modified. The stability of the scale-free regime is also considered: when it breaks down, either a scale is spontaneously generated or else, a “singular” node appears and the graphs become crumpled. A new computer algorithm to generate these random graphs is proposed. Possible generalizations are also discussed. In particular, more general ensembles are defined along the same lines and the computer algorithm is extended to arbitrary (degenerate) scale-free random graphs.

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I. INTRODUCTION

Random graphs are entities one encounters in many fields of research. Every time one has some objects or agents in mutual interaction, one can consider these objects or agents as the nodes (vertices) of a graph and represent, pictorially, the existence of the interaction by an abstract link (edge) connecting two nodes. Hence, an epidemic can be regarded as a graph: the nodes are the infected people and the links connect those who have been infected with their infectors. Likewise, the science citation index can be represented by a graph. Of course, the world-wide-web is a graph. There are many more such examples. Usually the graph structure is fairly random.

Consider a random graph. Let n denote the degree of a node and P_n the corresponding bulk probability distribution. When $P_n \sim n^{-\beta}$ for $n \gg 1$, it is common to call the graphs *scale free*. This class of graphs is not described by the classical theory of random graphs [1], where P_n is Poissonian. The subject became popular recently, when data on large graphs—in particular on the web network structure [2]—became available.

Scale-free graphs are naturally generated by stochastic processes, where the graph size is growing and the addition of links is preferential: the probability to attach a link to a node is, roughly speaking, proportional to the node degree. Several models of growing networks have been proposed [4–11]. The prototype is the model worked out in a classic paper by Simon [3]. This model does not really deal with graphs, but can easily be converted into a (directed) graph model, as observed in [11].

In studying random graphs one can adopt two complementary approaches:

(1) The *diachronic* approach, where one focuses on the time evolution of the graph. The main advantage of this approach is that one stays close, in spirit at least, to the dynamics operating in nature. Furthermore, one can discuss processes, like aging, which are intimately related to the time

evolution. To our knowledge, this approach is the one commonly used in works on scale-free graphs.

(2) The *synchronic* approach, where one considers the statistical ensemble of graphs at a fixed large time. Introducing a statistical ensemble enables one to use the conceptual tools of statistical mechanics. The dynamics of processes producing scale-free networks is presumably much more complicated than that of the proposed simple models. The resulting randomness is better implemented in the synchronic than in the diachronic approach. Generating graphs with an *a priori*-given connectivity distribution seems also easier. This is the approach adopted in this work.

Introducing a statistical ensemble of graphs means *ipso facto* that the graphs are weighted. In our model, each graph is given a weight proportional to the product of weights attached to individual nodes and depending on node degrees. The latter weights are chosen so as to generate the scale-free behavior in the ensemble. Thus, in a sense, the graphs—the microstates of the ensemble—are given an “internal energy.” Our general results characterize, of course, the “typical” graphs only, i.e., those contributing most significantly to the ensemble averages. The “typicality” of graphs results from the usual interplay of energy and entropy (see also Fig. 1). This can be considered as a virtue or as a flaw of the approach, depending on the goal one is pursuing.

A rather general graph ensemble is defined in Sec. II. For definiteness, we consider undirected graphs only. We use techniques borrowed from field theory, which enable one to formulate the problem and to find a number of results in a rather elegant fashion. The ensemble is defined for a given set of input weights. We rapidly focus on scale-free *connected tree* graphs, i.e., connected graphs without cycles. This is the case we have fully under control and where many results can be obtained analytically, so that a maximum clarity is achieved and our approach is exposed the best. We discuss the condition that guarantees that an *a priori*-given connectivity distribution is found in the “output,” i.e., when the weights of graphs and their entropy are taken into account. In Sec. III, we show that the ensemble can be in a

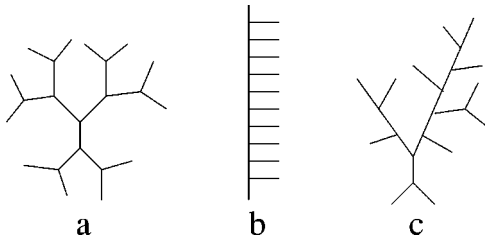


FIG. 1. Three graphs with the same number of identical nodes and therefore, in our model, with the same weight. A Cayley tree (a) has always a diameter $\sim \log N$, where $N = \# \text{nodes}$. A comblike tree (b) has a diameter $\sim N$. The generic trees, like (c), are devoid of any symmetry and can be drawn in a variety of manners, i.e., have large entropy. Such trees made up with nodes of degree one and three have the Hausdorff dimension $d_H = 2$ (cf [12]) and therefore, their diameter is typically $\sim \sqrt{N}$.

variety of phases. For each of these phases, we calculate two important scaling exponents: the fractal and the spectral dimensions. In Sec. IV, we discuss what happens when the input weights are modified. We show that the scale-free regime is unstable. Generically, the ensemble develops two responses: either a scale is spontaneously generated or else a “singular” node appears, which is connected to almost all other nodes (the “one-takes-it-all” scenario) [14].

A graph model can be used as an event generator in Monte Carlo studies of the statistical properties of graphs themselves or of the “matter” (e.g., Ising spins, complex spins, etc.) living on the nodes [13]. Our discussion will also lead to the formulation of a simple computer algorithm for generating random graphs. Readers more interested in this aspect of this work than in the more formal discussion to follow can jump directly to Sec. V, where our algorithm is formulated, after reading the beginning of Sec. II to get acquainted with our notation. In Sec. VI, we present a sample of curves representing the connectivity distributions calculated for finite systems using our code, compared to the analogous curves generated from the growing network recipe of Refs. [4,8,7] and we briefly discuss some finite size effects.

In Sec. VII, we summarize our results and we discuss the problems related to the generalization of the present approach to models more complicated than the connected tree model discussed at length in the previous sections. We also list some open questions. In this paper, when necessary, we make use of some results, found in a different context, scattered in earlier publications we have coauthored [15–18]. We believe that it is useful to adapt these results to the present context, putting them in another perspective and making them accessible to a different community.

II. MINIFIELD THEORY AND GRAPH ENSEMBLES

Our starting idea is to use a toy field theory in zero dimensions—we call it a minifield theory—and to identify the Feynman diagrams of this theory with the graphs of our ensemble. The weights attached to the graphs are the amplitudes calculated using the standard Feynman rules, the model

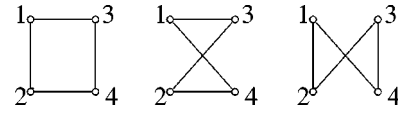


FIG. 2. The labeled connected Feynman diagrams representing the contributions to the right-hand side (r.h.s.) of (2). With each one of these graphs is associated the weight $2[p_2\lambda]^4/3$.

being, of course, formulated in such a manner that these weights are positive.

Let us define the minifield theory [17] by the following formal integral:

$$Z = (2\pi\kappa\lambda)^{-1/2} \int d\phi \exp \frac{1}{\kappa} \left[-\phi^2/2\lambda + \sum_{n>0} p_n \phi^n \right]. \quad (1)$$

By assumption, the real constants p_n are non-negative. Hence, strictly speaking, the integral does not exist. However, expanding the exponential and performing the integrations over ϕ one obtains an unambiguously defined series. The terms of this series can be represented, as usual in field theory, by Feynman diagrams. The convergence of the series is, in general, uncertain and requires some consideration. When the series converges, its sum, also denoted by Z , can be regarded as the partition function of a graph ensemble.

The content of the above paragraph will appear obvious to the practitioners of field theory, but may appear fortuitous to some readers working on networks, but not totally familiar with the former. We have no space to explain the point at length. Hopefully, a simple example may be of some help. Consider the following contribution to Z :

$$Z_{\text{ex.}} = (2\pi\kappa\lambda)^{-1/2} \int d\phi e^{-(1/2\kappa\lambda)\phi^2} \frac{1}{4!} [p_2\phi^2/\kappa]^4. \quad (2)$$

We need to calculate the eighth moment of a Gaussian. We shall do it in a fancy way. For book-keeping purposes, we distinguish by a label the four “interaction terms” that are being multiplied above,

$$[\phi^2]^4 \rightarrow \phi(1)^2 \phi(2)^2 \phi(3)^2 \phi(4)^2, \quad (3)$$

and we represent each label by a point in a plane. We observe that every moment of a Gaussian is fully determined by its second moment, which in our case equals $\kappa\lambda$. We replace all binomials appearing in the integrand, $\phi(i)\phi(j) \rightarrow \kappa\lambda$ and we join with a line the points representing the labels i and j . The latter results in a specific graph, a Feynman diagram. The moment to be calculated is obtained by summing over all possible matchings of four pairs of labels. All the *connected* graphs corresponding to our example are shown in Fig. 2. One checks easily that to each of these diagrams correspond 16 distinct matchings of the same four pairs of labels. Thus, the contribution to the right-hand side (r.h.s.) of Eq. (2) of each of these Feynman diagrams is $\lambda^4 [p_2 2!]^4 / 4!$. The full result is obtained by taking into account the disconnected diagrams, too. In some diagrams, a line connects a point to itself ($i=j$), these are the so-called “tadpoles.” We shall not list all these diagrams here.

The point is that the Feynman diagrams of the minifield theory are the graphs familiar to people working on networks, except that there is a specific weight attached to each such a graph. The graphs are not necessarily connected, except if one imposes an appropriate extra constraint, defining a graph subensemble.

We assume that p_1 , which plays the role of an external current, is strictly positive. Hence, in our minifield theory, there exist graphs with nodes that are “external,” i.e., of unit degree.

The weight w associated with a Feynman diagram that is “nondegenerate”—i.e., does not have tadpoles and multiple connections between nodes—and whose nodes are labeled, is

$$w = \kappa^{L-N} \frac{\lambda^L}{N!} \prod_{j=1}^N [p_{n_j} n_j!], \quad (4)$$

where N and L denote the total number of nodes and links, respectively. When tadpoles and/or multiple connections are present, one has to multiply the r.h.s. by the usual symmetry factors. In graph theory, some authors accept the existence of degeneracies in the definition of what they mean by a graph. In most texts, the degeneracies are excluded. The class of graph models we propose is fairly general, but not the most general. Indeed, by construction, the weight of a graph is given in Eq. (4) by a product of weights associated with individual nodes. A possible generalization will be proposed later on.

As is well known from field theory, $W = \kappa \ln Z$ generates the connected graphs. Only tree graphs survive in the “semi-classical” limit $\kappa \rightarrow 0$. From here on, we focus on the statistical ensemble of *connected tree graphs*. We shall return to more general graphs in the last section.

In this paper, we are interested in models where the radius of convergence of the series in the exponent on the r.h.s. of Eq. (1) is finite. It is not a loss of generality to set this radius to unity. It is evident from Eq. (4) that this can always be achieved by a multiplicative renormalization of λ and κ .

The partition function of connected tree graphs W^{trees} is given by the stationary value of the action at $\phi = \Phi$, Φ being defined implicitly by the saddle-point equation

$$\Phi = \lambda \sum_{n>0} t_n \Phi^{n-1}, \quad (5)$$

where we have introduced a shorthand notation $t_n = n p_n$. One easily checks that

$$\Phi = \partial W^{\text{trees}} / \partial t_1. \quad (6)$$

Hence, Φ generates tree graphs with one marked external node. Equation (5), with its nice graphical representation [12,19]—see Fig. 3—has a long history and is recurrently rediscovered in the literature.

It is easy to see that Φ is singular. Indeed, Eq. (5) can only be satisfied if λ is smaller than some critical value $\lambda_c = \lambda_c(t_1, t_2, \dots)$. Equation (5) can be rewritten as

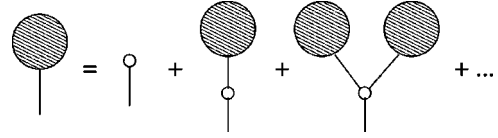


FIG. 3. The graphical representation of Eq. (5). With every node in the figure—the open circles—is associated the factor λt_n . We use the shorthand notation $t_n = n p_n$.

$$\lambda^{-1} = F(\Phi) \equiv \sum_{n>0} t_n \Phi^{n-2}, \quad (7)$$

and by definition

$$\lambda_c^{-1} = F(\Phi_0), \quad (8)$$

where $\Phi = \Phi_0$ is the point in the interval $[0,1]$ where $F(\Phi)$ takes its minimal value. The critical behavior of the theory is found from the behavior of $F(\Phi)$ in the vicinity of Φ_0 .

One observes that both the r.h.s. of Eq. (7) and its second derivative are positive for $\Phi > 0$. Moreover, λ_c is finite (because $t_1 > 0$). The concavity property of $F(\Phi)$ implies that one has, in general, the choice between only three possibilities (cf Refs. [15,17,12]):

- (A) $\Phi_0 < 1$ and $F'(\Phi_0) = 0$.
- (B) $\Phi_0 = 1$ and $F'(1) = 0$.
- (C) $\Phi_0 = 1$ and $F'(1) < 0$.

These three cases will be discussed in detail later on.

It is customary to introduce a susceptibility critical exponent γ controlling the most singular part of the second derivative of the partition function. Since Φ is the first derivative of the partition function, we write

$$\Phi \sim (\lambda_c - \lambda)^{1-\gamma}. \quad (9)$$

The exponent γ is finite in all cases of interest for us, as will be shown in the following sections, where it will be calculated.

A factor λ is associated with every link of a tree graph and has the physical significance of the fugacity of links. Since $L = N - 1$, it can also be regarded as the fugacity of nodes. Hence,

$$W^{\text{trees}} = \sum_N W_N^{\text{trees}} \lambda^N \sim (\lambda_c - \lambda)^{2-\gamma}. \quad (10)$$

Taking the inverse Laplace transform, one obtains for tree graphs the canonical partition function,

$$W_N^{\text{trees}} \sim N^{\gamma-3} \lambda_c^{-N} \quad N \gg 1. \quad (11)$$

Hence, the ensemble of random trees behaves like a standard statistical mechanical ensemble. In particular, the number of trees with N nodes is exponentially bounded in N and the canonical ensemble has an extensive entropy.

We have not yet introduced the constraints associated with the absence of a scale. The quantity of experimental interest is P_n , the bulk connectivity distribution. It is P_n that should exhibit a power-like fall at large n . The relevant ques-

tion is how to choose the series of the bare couplings p_n in order to get a given scale-free P_n . The rest of this section is devoted to this problem. For tree graphs, the solution can be found mapping the model of graphs on another one, known in the literature as the balls-in-boxes model [16].

In Sec. 2.7.7 of Ref. [20] a series solution of Eq. (5) is given as

$$\Phi = \sum_N \Phi_N \lambda^N, \quad (12)$$

with

$$\Phi_N = \frac{1}{N} \sum_{\{v_j\}} \frac{N!}{v_1! v_2! \dots v_N!} t_1^{v_1} \dots t_N^{v_N}, \quad (13)$$

and v_j being positive integers satisfying the constraints

$$\sum_j v_j = N \quad \sum_j j v_j = 2N - 1. \quad (14)$$

Equation (13) can be further rewritten as

$$N \Phi_N = \Omega(N, 2N - 1), \quad (15)$$

with

$$\Omega(N, M) = \sum_{\{n_j\}} t_{n_1} \dots t_{n_N} \delta\left(\sum_{j=1}^N n_j - M\right). \quad (16)$$

The summation is now on all sets of N positive integers. The r.h.s. is the partition function of a system of M balls distributed at random and with weights t_n among N boxes, empty boxes being forbidden. This model of weighted partitions is precisely the balls-in-boxes model [21].

The effective box occupation distribution is $t_n \Omega(N - 1, M - n) / \Omega(N, M)$. Using the integral representation of the (discrete) δ -function, one easily finds an integral representation of $\Omega(N, M)$, which can be used to calculate it by the saddle-point method in the limit $N \rightarrow \infty$, $\rho = M/N = \text{const}$. The effective box occupation distribution follows. Of course, the tree-graph model corresponds to $\rho = 2$. We shall not repeat this calculation here, referring the reader to Ref. [16] for details and quoting the result for $\rho = 2 \leq \langle n \rangle_t \equiv \sum_n n t_n / \sum_n t_n$,

$$P_n \sim t_n \Phi_0^n \quad (17)$$

up to an obvious normalization factor. Here, Φ_0 is to be found from $F'(\Phi_0) = 0$. This last condition can be rewritten as

$$\sum_n n t_n \Phi_0^n / \sum_n t_n \Phi_0^n = 2. \quad (18)$$

The left-hand side (l.h.s.) is an increasing function of Φ_0 . Consequently $\langle n \rangle_t = 2$ corresponds to $\Phi_0 = 1$ and, therefore, to case (B) introduced earlier. Hence, for tree graphs and in the limit $N \rightarrow \infty$,

$$P_n \sim t_n \quad \text{iff} \quad \langle n \rangle_t = 2. \quad (19)$$

This result can be understood intuitively. The shape of the two distributions P_n and t_n differs because of the constraint $s_N \equiv (1/N) \sum_j n_j = 2$. But for $N \rightarrow \infty$, the constraint is satisfied “for free” when $\langle n \rangle_t = 2$ and $\beta > 2$ by virtue of Khintchin’s law of large numbers.

The condition (19) solves our problem: the input couplings p_n of the tree-graph model should be set to $p_n = P_n/n$ in order to get the scale-free connectivity distribution P_n in the bulk. The distribution P_n must, of course, satisfy the constraint $\sum_n n P_n = 2$, otherwise it would not refer to trees [22].

III. GEOMETRY OF SCALE-FREE TREE GRAPHS

In this section, we discuss the geometry of graphs belonging to the statistical ensemble of scale-free trees. Hence, according to the results of the preceding section, we assume that $t_n \sim n^{-\beta}$ for $n \rightarrow \infty$ and that $\langle n \rangle_t = 2$. We have already stated in the preceding section that this situation corresponds to case (B): $\Phi_0 = 1$ and $F'(1) = 0$.

It follows from general arguments that $F(\Phi)$ has a branch point at $\Phi = 1$. The order of the singularity is determined by the shape of the tail of t_n . For noninteger β one finds (cf [15]) that [23]

$$F(\Phi) = \text{polynomial in } (1 - \Phi) + (1 - \Phi)^{\beta-1} + \text{higher-order terms.} \quad (20)$$

The concavity of $F(\Phi)$ implies $\beta > 2$. The linear term in the polynomial is absent.

When $2 < \beta < 3$, inverting Eq. (21) one finds the singular part of Φ ,

$$\Phi_{\text{sing}} \sim (\lambda_c - \lambda)^{1/(\beta-1)}, \quad (21)$$

so that $\gamma = (\beta - 2) / (\beta - 1)$.

When $\beta > 3$ the inversion yields

$$\Phi_{\text{sing}} \sim (\lambda_c - \lambda)^{1/2}. \quad (22)$$

Therefore, $\gamma = 1/2$.

We now consider two scaling exponents that have a direct geometrical interpretation in terms of the average “dimension” of the ensemble graphs.

One can define a two-point correlation function $C(x, \lambda)$ equal, up to normalization, to the average number of pairs of nodes separated by a distance x . Using a graphical representation analogous to that of Fig. 3, one finds [12]

$$C(x, \lambda) \sim \left[\lambda \frac{\partial}{\partial \Phi} (\Phi F(\Phi)) \right]^x. \quad (23)$$

The fractal dimension d_H of the tree can be defined by

$$x^{-1} \ln C(x, \lambda) = -\text{const} (\lambda_c - \lambda)^{1/d_H} \quad \text{for } x \rightarrow \infty, \quad (24)$$

where it is assumed that $|\lambda_c - \lambda| \ll 1$. Notice, that $(\lambda_c - \lambda)^{-1}$ is a measure of the average size of a graph [24]. One finds finally

$$d_H = \frac{1}{\gamma}. \quad (25)$$

Another definition of dimension is obtained by considering a diffusion process on the graph; as is well known, diffusion can be mapped to a random walk. If we consider a walker departing from a certain point at time $T=0$, then the return probability to the start of the walk is, for small T , proportional to $T^{-d_s/2}$ where d_s is the spectral dimension: the dimension of the graph as seen by a random walker moving on the graph.

It was shown in [18,25] that the spectral dimension d_s is for $\gamma \geq 0$ given by

$$d_s = \frac{2}{1 + \gamma}. \quad (26)$$

Combining Eqs. (26) and (26), one obtains the nice relation

$$d_s = \frac{2d_H}{1 + d_H}. \quad (27)$$

For $\beta > 3$, one finds $d_H = 2$ and $d_s = 4/3$. These are the generic values for a tree graph [12,25], which would be found also if there were only a finite number of nonvanishing couplings t_n . The typical graph is a fully developed tree, with many branching branches.

For $2 < \beta < 3$ one obtains

$$d_H = (\beta - 1)/(\beta - 2), \quad (28)$$

$$d_s = 2(\beta - 1)/(2\beta - 3). \quad (29)$$

As $\beta \rightarrow 2$, the trees become increasingly crumpled, they look like a set of linked hedgehogs. As β approaches 2 the average distance between a pair of nodes starts growing very slowly with N . For example, when $\beta = 2.1$, this distance is $\sim N^{1/d_H} = N^{1/6}$. The increase is not logarithmic, as is sometimes claimed, but powerlike. Of course, in practice, this does not make much difference, when the power is small.

The upshot of the above discussion is that a scale-free large-degree behavior $P_n \sim n^{-\beta}$, $\beta > 2$, is associated with a variety of distinct graph geometries. It is quite remarkable, that at least for the tree graphs of the discussed ensemble, one can give a complete catalogue of expected geometries.

IV. INSTABILITY OF A SCALE-FREE REGIME

The logical next step of the discussion is to examine what happens when the shape of t_n is so distorted that the constraint $\langle n \rangle_t = 2$ is broken. We continue assuming that $t_n \sim n^{-\beta}$ at large n .

Consider, first, the case $\langle n \rangle_t < 2$. This condition is equivalent to $F'(1) < 0$. We recover case (C) of Sec. II. Since the linear term in the polynomial on the r.h.s. of Eq. (21) is now present, inverting Eq. (21) one gets

$$\Phi_{\text{sing}} \sim (\lambda_c - \lambda)^{\beta-1}, \quad (30)$$

with $\beta > 2$. An explicit calculation using Eq. (24) yields $d_H = \infty$. We also expect $d_s = 2$. A typical tree graph looks like a set of linked hedgehogs. Moreover, as explained below, a different feature shows up: a ‘‘singular’’ node with a fixed degree of $O(N)$, a hedgehog even more spiky than the others.

To see this, it is instructive to understand how the constraint $s_N = 2$ is satisfied. Notice that if we omit from s_N a few terms, say n_{j_1}, \dots, n_{j_p} , the resulting sum will fluctuate around $\langle n \rangle_t$. Hence, for $N \rightarrow \infty$,

$$s_N - \frac{1}{N}(n_{j_1} + \dots + n_{j_p}) = \langle n \rangle_t. \quad (31)$$

But, since $s_N = 2$, it is clear that at least some of the contributions to the sum on the l.h.s. must be of order $O(N)$. Since the probability distribution falls like a power, it is most probable that there is only one such contribution. Thus, one expects the appearance of a characteristic ‘‘singular’’ node with degree $n = (2 - \langle n \rangle_t)N$. Other nodes have degree distribution $\sim t_n$:

$$P_n = \frac{t_n}{\sum_k t_k} + \frac{1}{N} \delta[n - (2 - \langle n \rangle_t)N]. \quad (32)$$

The normalization factor in front of δ is determined by the tree condition $\sum_n n P_n = 2$.

The other possible case is $\langle n \rangle_t > 2$. This condition is equivalent to $F'(1) > 0$, which by virtue of the concavity of $F(\Phi)$ implies that $\Phi_0 < 1$. This is case (A) of Sec. II. Hence, P_n equals t_n times an exponentially falling factor. A scale in the node-order distribution is spontaneously generated. The dramatic fluctuations of node degrees are absent.

Expanding $F(\Phi)$ in the neighborhood of $\Phi = \Phi_0$, where its derivative is bound to vanish and inverting the resulting expansion in order to find the most singular part of Φ , one gets

$$\Phi_{\text{sing}} \sim (\lambda_c - \lambda)^{1/2}. \quad (33)$$

Hence, $\gamma = 1/2$ and one again obtains the generic values $d_H = 2$ and $d_s = 4/3$.

The above two scenarios are the only alternatives to the scale-free behavior of the discussed statistical ensemble of tree graphs.

One can show that the transitions between different phases of the model are continuous and that the degree of their softness varies when the couplings t_n change. There is no phase transition between the generic phase (A) and the scale-free regime (B) with $\beta > 3$.

V. COMPUTER ALGORITHM

In the synchronic approach, the construction of graphs does not mimic any real physical process. The emphasis is on the flexibility and on the efficiency in producing a sample

of graphs to work with. We use the following notation: $R(n) = p_n/p_{n-1}$.

We propose an algorithm working for a given fixed N and L . It rewires links, generating Feynman diagrams of the minifield theory, proceeding as follows [26]:

- (a) Pick a random oriented link $\vec{i}j$.
- (b) Pick a random target node k .
- (c) Apply the Metropolis test: rewire the link $\vec{i}j$ to $\vec{i}k$ with probability

$$\text{Prob}(\text{rewiring}) = (n_k + 1)R(n_k + 1)/n_j R(n_j). \quad (34)$$

These Feynman diagrams are properly weighted. The algorithm is probing all possible connections within a set of distinguishable nodes. For nondegenerate diagrams, the Metropolis condition immediately follows from the detailed balance equations together with the weight (4) given to microstates. For general diagrams, the symmetry factors, related to the presence of tadpoles and multiple connection between nodes, also come out correctly. This is again a consequence of the detailed balance: if two nodes are connected by m links, the transition to a state where the nodes are connected by $m - 1$ links can be done in m ways. The inverse operation has only one realization. When $p_n = 1/n!$ the Metropolis test is always positive and the nondegenerate labeled diagrams produced by the algorithm are equiprobable, as they should be. We have checked the validity of the general argument on a variety of examples.

In order to produce connected tree graphs, one starts from a connected tree configuration, e.g., a polyline with free ends and one adds, before the Metropolis test, a check insuring that $k \neq i, j$ and $n_i = 1$. It is easy to convince oneself that with this constraint the tree is never broken into parts. As explained in Sec. II, the scale-free connectivity distribution in the bulk is obtained setting $p_n \sim P_n/n$.

Notice that, with a constraint added before the Metropolis test, the algorithm explores a well-defined subensemble of graphs. However, because the detailed balance is satisfied, this subensemble is in equilibrium, or, more precisely fluctuates around equilibrium (see also the remark on that matter in the last section). Thus, within the subensemble in question the algorithm tends to sample ‘‘typical’’ graphs.

VI. NUMERICAL EXAMPLES AND FINITE-SIZE EFFECTS

Since we propose an algorithm for generating random graphs, it may be of interest to the reader to see how our results compare to those obtained with an algorithm already existing on the market. As an example to compare with, we take the Growing Network model of Ref. [7], which is a slight generalization of the algorithm proposed originally in Ref. [4] and that also generates connected trees. The asymptotic analytic solution for P_n is given by Eq. (12) in the second paper of Ref. [7] (see also [8]):

$$P_n = (\beta - 1) \frac{\Gamma(2\beta - 3)\Gamma(n + \beta - 3)}{\Gamma(\beta - 2)\Gamma(n + 2\beta - 3)}. \quad (35)$$

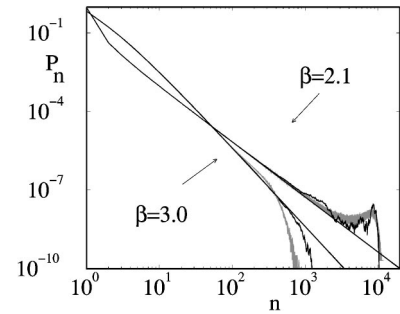


FIG. 4. Comparison of the connectivity distribution produced by our Monte Carlo algorithm (black) and that of Ref. [7] (gray) for $N = 2^{14}$ and $\beta = 2.1$ and 3.0 , respectively. The points are joined by a line to guide the eye. The almost straight lines correspond to the asymptotic P_n given in Eq. (35).

We use this P_n as input in our code. A sample result is shown in Fig. 4, where we compare the results of the calculation using the two algorithms, respectively. The calculated points are practically indistinguishable and follow the input distribution, except for those n where finite-size effects cut and distort the distribution.

Indeed, when N is finite, the distribution of node degrees cannot extend to infinity, there is an upper cutoff on $n: n < n_{\max}$. The cutoff can be estimated by imposing the condition that the expected number of nodes found above n_{\max} is at most equal to unity. Then

$$N \sum_{n_{\max}}^{\infty} n^{-\beta} = \text{const.} \quad (36)$$

The value of the constant on the r.h.s. depends on the detailed shape of P_n . Equation (36) leads to the scaling law

$$n_{\max} \sim N^{1/(\beta-1)}, \quad (37)$$

analogous to the result of [7,9], where instead of N appears the time. Beyond n_{\max} , the node-distribution function falls very abruptly and can be neglected for all practical purposes. Notice, that n_{\max} may be much smaller than N . As noticed in Ref. [9], this explains why large scale-free graphs with β significantly larger than three are not observed in nature.

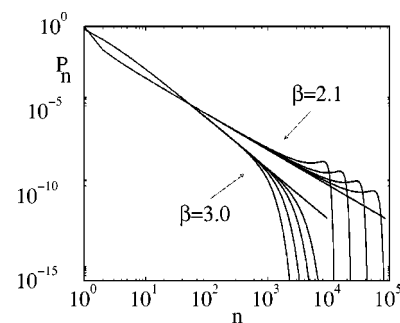


FIG. 5. The connectivity distribution calculated for our ensemble of tree graphs, at finite $N = 2^k$, $k = 14, 15, 16, 17$, and for $\beta = 2.1$ and 3.0 . The almost straight lines correspond to the asymptotic P_n given in Eq. (35). The figure illustrates the finite-size cutoff of the order distribution discussed in the text.

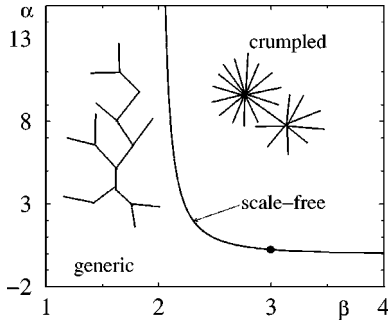


FIG. 6. Phase diagram for the simple two-parameter model presented in Sec. VII: $t_1=1$, $t_n=(1/\alpha)n^{-\beta}$, $n>1$. The part of the continuous line on the right of the black dot corresponds to the scale-free graphs belonging to the generic phase.

In Fig. 5 we show the evolution of P_n with N . In order to obtain a very precise result we use, instead of the Monte Carlo, an analytic recursion formula satisfied by the equivalent partition function given by Eq. (16) of Sec. II (see Ref. [21] in that section). When the abscissa in Fig. 5 is rescaled, for different N and using Eq. (37), the curves corresponding to the same β are cut at the same place.

VII. SUMMARY AND DISCUSSION

A. Connected tree graphs: A tentative summary

Let us summarize what has been achieved so far. We have started by introducing a fairly general ensemble of random graphs, but we have rapidly focused our attention on the sub-ensemble of connected tree graphs. We have found the conditions insuring that the latter are scale free. We have discussed in detail the geometry of the connected tree graphs. We have also constructed a computer algorithm generating these graphs with an arbitrary bulk connectivity distribution P_n . Since our analytic discussion may sound somewhat formal for some readers, let us illustrate it with a simple, but very instructive example.

Consider a two-parameter family of input weights $t_n = np_n$: $t_1=1$ and $t_n=(1/\alpha)n^{-\beta}$, $n>1$. The condition insuring that the trees are scale free was found in Sec. II and is $\langle n \rangle_t = \sum_n n t_n / \sum_n t_n = 2$. In the example in question, it is equivalent to the following relation between the parameters α and β :

$$\alpha = 1 + \zeta(\beta - 1) - 2\zeta(\beta), \quad (38)$$

where $\zeta(\beta)$ is the Riemann Zeta function. The phase diagram [15] is shown in Fig. 6: the line is calculated from Eq. (38).

As one moves along this line in the direction of decreasing β , the geometry remains generic down to $\beta=3$ and becomes progressively more and more crumpled below that point. In particular, the fractal dimension increases from the initial value 2 to ∞ [see Eq. (28)]. This behavior is easily understood. When β is moved towards 2 the convergence of the series deteriorates. The only way to keep the average $\langle n \rangle_t$ constant, viz. equal to two, is to reduce the normalization of the tail. This means, however, that the relative weight of

nodes with unit degree gets larger. Eventually, the number of ‘‘external’’ nodes increases with N much faster than the number of large-degree nodes. The latter are usually connected to the former, building hedgehoglike structures.

Off the line (38) one falls into one of the alternative phases discussed in Sec. IV: either a scale is generated spontaneously and P_n falls exponentially, or else there appears a ‘‘singular’’ node with huge connectivity $n_{\text{sing}} = N(2 - \langle n \rangle_t)$. In the former case, the graphs have a typical extension $\sim \sqrt{N}$, while in the latter case, they are crumpled and have infinite fractal dimension. Because of the constant presence of the ‘‘singular’’ vertex, the diameter of the graph grows slower than any power of N for $N \rightarrow \infty$.

Notice that the condition $\beta > 2$ appears often in our discussion. Indeed, at least in the framework adopted in this paper, a scale-free graph with a different exponent cannot exist. Actually, the arguments used towards the end of Sec. IV can also be used when $\langle n \rangle_t = \infty$ and one predicts an exponentially falling P_n at the ‘‘output.’’

We have considered the stability of scale-free graphs with respect to possible deformations of the sequence of weights. Indeed, in nature, a random graph does not exist in isolation. It is an open system, subject to interactions with, loosely speaking, a heat bath. It is, thus, interesting to know what is expected to happen when this interaction becomes strong.

Our results reflect the behavior of ‘‘typical’’ graphs. But very ‘‘atypical’’ values of global parameters, for example, of the spectral dimension, can be found when a specific large graph is analyzed [27]. Our algorithm makes it possible to measure the degree of this ‘‘atypicality.’’ a numerical simulation enables one to estimate the probability of a given fluctuation of the global parameter.

B. More general graph models

1. Weighted connections

Our graph model has been constructed in such a way that the weight of a graph is a product of weights associated with individual nodes. A possible generalization could consist in replacing the starting graph generating function defined in Eq. (1) by

$$Z \sim \int d^q \phi \exp \left[\frac{1}{\kappa} \left(-\phi A \phi + \sum_{n=1}^q p_n \phi_n^n \right) \right], \quad (39)$$

where A is a positive definite matrix of rank q and $\phi = (\phi_1, \dots, \phi_q)$. The series expansion of the r.h.s. generates graphs with nodes of degree $1, 2, \dots, q$ and a weight $\propto A_{mn}^{-1}$ attached to every link connecting a pair of nodes of degree m and n . The limit $q \rightarrow \infty$ should be handled with care. In a study of tree graphs, the limit $\kappa \rightarrow 0$ should be taken first. The investigation of this model goes, however, beyond the scope of the present paper [28].

2. Matter on graphs

Another generalization would consist in putting ‘‘matter’’ fields on graphs. Ising spins on ‘‘small-world’’ graphs [29] were already discussed in Ref. [30]. Ising spins living on the

nodes of quenched Feynman diagrams generated by ϕ^3 or ϕ^4 interactions were studied by many people (see, for example, [31] and the long list of references therein), in particular, with the aim to determine the critical behavior of the spin system. It would be very interesting to extend these studies to scale-free graphs as defined in the present paper and to see, for example, what is the effect of changing β and therefore also the fractal dimension of the graphs.

3. Graphs with cycles

The most important generalization consists in extending the study to graphs with cycles. Introduction of a fixed number of cycles does not seem to be a big deal in the present context (see, however, Ref. [17]). For example, when $N \rightarrow \infty$ the Hausdorff dimension is expected to be insensitive to the presence of a fixed number of cycles. On the other hand, the case where the ratio L/N is kept fixed at some arbitrary value when $N \rightarrow \infty$ is very challenging.

There are conceptual problems related to the over-extensive nature of the ensemble. It is not difficult to count the number of nondegenerate graphs (\mathcal{N}) with given N and L . It is sufficient to consider the number of distinct adjacency matrices $C_{ij}=1$ or 0, for i,j connected or not, respectively:

$$\mathcal{N}(N,L) = \binom{1/2N(N-1)}{L}. \quad (40)$$

In general, the r.h.s. behaves like $\exp(\text{const } N \log N)$ when $N \rightarrow \infty$, L/N fixed. A similar result is easily obtained for degenerate graphs. The entropy is not extensive. This is easy to understand. It is impossible to divide an arbitrary graph into two parts separated by a ‘‘boundary’’ of negligible measure. Any two nodes can interact. Hence, it is not certain, in general, that the bulk distribution P_n calculated in the ensemble coincides with that obtained from a single, sufficiently large graph. Tree graphs are a notable exception: in the ‘‘semiclassical limit’’ $\kappa \rightarrow 0$, the entropy becomes extensive.

Our algorithm, in its most general version, generates all possible Feynman diagrams and can, in principle, be used to simulate arbitrary graphs. The problem is to find the constraints on the couplings p_n insuring that the bulk connectivity distribution has a desired form.

The presence of the factor $(n_k+1)/n_j$ in Eq. (34) means that the rewired nodes are sampled independently of their degree (without this factor, nodes belonging to a large number of links would be rewired preferentially). If no extra check is performed before the Metropolis one, the algorithm does not know about the underlying graph structure. It plays with node degrees and nodes as it would play with balls and boxes in the balls-in-boxes model with occupation weights p_n . Hence, a scale-free P_n is obtained setting $p_n \sim P_n$ (and $L = \frac{1}{2}N\langle n \rangle$). The graphs produced that way are degenerate—there are tadpoles and multiple connections between nodes. They are, in general, not connected—it is very difficult to avoid producing disconnected graphs—but for $\beta \leq 3$, most of nodes belong to the giant component. The conditions of its appearance are well understood [32,19]. The connectivity

distribution within the giant component has the same scale-free behavior at not too small n .

Our present experience is that the algorithm has no difficulty equilibrating the ensemble. The algorithm defines a Markov process. We do not have any proof that the next-to-largest eigenvalue of the transition matrix is separated from unity by a gap remaining finite when $N \rightarrow \infty$, but it seems very likely that it is, since we do not expect any collective effects to occur.

A different algorithm, generating graphs with an arbitrary connectivity, is proposed and used in Refs. [19,32]. In this algorithm a graph is generated in two steps. First, a list of N degrees, n_1, n_2, \dots, n_N , is sampled out of the distribution P_n . In a sense, one creates first N nodes with attached links having the other end free. Then, in the second step, one connects together, at random, the free ends of links. The produced graph is, in general, not connected and degenerate. The ensemble is defined by repeating this procedure over and over. In the limit $N \rightarrow \infty$, the connectivity distribution is identical to P_n for *individual graphs*. Notice that L is not fixed.

Our approach, rooted in field theory, is different. We start with microstates weighted so that the connectivity distribution becomes scale free after *averaging over the ensemble*. But, as already mentioned, the scale-free connectivity within individual graphs is, strictly speaking, not guaranteed, except for the ensemble of trees: averaging within a single graph of infinite size is, in general, not equivalent to averaging over the ensemble of graphs. This is perhaps a flaw, but on the whole, the virtues of the two approaches seem complementary. We hope to develop this point elsewhere.

In order to construct nondegenerate graphs, it suffices to verify, before performing the Metropolis check, that the proposed rewiring does not produce tadpoles and/or multiple connections. We have a code doing that efficiently. The real problem, which we have not solved yet, is to find for nondegenerate graphs, the set of couplings p_n producing the desired scale-free bulk distribution P_n . Setting $p_n = P_n$ gives for, say $\beta = 3$, results that are encouraging, although the cut-off n_{\max} is smaller than in the degenerate case. However, when β is decreased things worsen. No doubt the problem deserves more theoretical and numerical work.

We are tempted to conjecture that the degeneracy does not matter for large-scale features of graphs. The absence of any natural scale suggests that the graphs are self-similar. If so, one can decimate nodes as follows: pick a node at random and shrink to a single point all its immediate neighbors. If the graph is really self-similar, decimating nodes should not alter its large-scale features. But such a decimation will necessarily produce degenerate graphs. For the moment, this conjecture is a speculation. However, our experience with simulating random surfaces suggests that this possibility should not be disregarded: degenerate randomly triangulated surfaces—those whose duals have ‘‘tadpoles’’ and ‘‘self-energy’’ insertions—turn out to fall into the same universality class as the nondegenerate surfaces, but are much easier to simulate.

Finally, let us note that it is straightforward to produce an algorithm analogous to the one proposed in this paper but constructing directed graphs.

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