Simulating \mathbb{Z}_2 lattice gauge theory on a quantum computer

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The utility of quantum computers for simulating lattice gauge theories is currently limited by the noisiness of the physical hardware. Various quantum error mitigation strategies exist to reduce the statistical and systematic uncertainties in quantum simulations via improved algorithms and analysis strategies. We perform quantum simulations of \mathbb{Z}_2 gauge theory with matter to study the efficacy and interplay of different error mitigation methods: readout error mitigation, randomized compiling, rescaling, and dynamical decoupling. We compute Minkowski correlation functions in this confining gauge theory and extract the mass of the lightest spin-1 state from fits to their time dependence. Quantum error mitigation extends the range of times over which our correlation functions are accurate by a factor of 6 and is therefore essential for obtaining reliable masses.

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I. INTRODUCTION

Nucleons and other hadrons are ubiquitous in particleand nuclear-physics experiments. Predicting their properties theoretically requires a nonperturbative description of bound states in quantum chromodynamics (QCD). Nonperturbative QCD uncertainties are now the dominant theoretical uncertainties in a wide range of new physics searches in areas ranging from quark and lepton flavor physics to neutron star physics to neutrino physics [1-4]. Lattice QCD has become a highly successful tool that enables nonperturbative calculations of QCD observables such as hadron masses and matrix elements with systematically improvable uncertainties that are essential to the success of many ongoing and future experiments [5–9]. However, lattice QCD calculations on classical computers exclusively rely on Monte Carlo algorithms to compute the high-dimensional path integrals required for precise calculations of hadron properties. Monte Carlo algorithms are very efficient for path integrals whose integrands are positive definite, but the presence of sign problems-integrands with sign or complex-phase fluctuations-leads to computational resource requirements that grow exponentially with system size [10]. Many systems of interest cannot presently be studied with lattice QCD using classical computers because of challenges arising from sign problems, including all systems involving nonequilibrium real-time evolution. Although there has been progress in developing novel classical lattice gauge theory (LGT) algorithms [11–14], simulations of the dynamics of four-dimensional LGTs relevant for studying hadronization of quarks and gluons, heavy-ion collisions, and phase transitions in the early universe remain unfeasible.

Quantum computers offer the possibility to simulate realtime dynamics of LGTs without sign problems by using Hamiltonian time evolution of quantum states instead of Monte Carlo evaluations of path integrals [15]. As with the evolution of LGT on classical computers, however, realizing this potential will require a sustained effort over many years to understand and address theoretical issues, develop and test efficient algorithms, and identify and control systematic uncertainties. Therefore, even though large-scale fault-tolerant quantum computers capable of realistic four-dimensional LGT simulations will not be realized for many years, it is timely to begin exploring the possibilities and tackling the challenges associated with quantum simulations of LGTs.

Extracting accurate physical results from noisy intermediate-scale quantum (NISQ) hardware requires quantifying and reducing systematic uncertainties. Substantial effort has been dedicated to developing and testing strategies for quantum error mitigation (QEM) in quantum simulations for chemistry, physics, and mathematics [16–38]. In LGT calculations, the use [39–48] and systematic study [49–64] of QEM techniques has primarily focused on using zero noise extrapolation, random compilation, and readout error mitigation. Because many approaches for digitization of LGTs (see Sec VI.b of Ref. [65] for a review) have been proposed, it will be illuminating to compare their

performance on currently accessible systems to understand which approaches should be pursued for large-scale quantum simulations.

Quantum electrodynamics (QED) in 1 + 1d, also called the Schwinger model [66], demonstrates both chiral symmetry breaking and confinement. Therefore, the Schwinger model and its approximations provide relatively simple yet nontrivial test cases for quantum simulation methods, and have been the focus of much activity. State-preparation techniques using adiabatic [67,68] and variational [69-71] methods as well as thermal-pure-quantum states [72] have been tested. Ground state properties have been calculated at finite temperature [70,73] and density [71,72], including topological terms [68,74,75]. Additional work has studied nonequilibrium dynamics [73,76] and the role of dynamical quantum phase transitions [77,78]. Error mitigation [59] and correction [64,79] strategies have been developed for the Schwinger model, and practical resource estimates have been derived for some digitization schemes [80].

In this paper, we simulate $1 + 1d \mathbb{Z}_2$ gauge theory with a single massive fermion, which is the simplest discrete subgroup approximation of the Schwinger model, [74,81–83]¹ as well as a model of condensed matter Luttinger liquid systems with interesting phenomena that has attracted recent interest [83,86–92]. We compute real-time (Minkowski) two-point correlation functions and extract the energy of the lowest-lying spin-1 state from their time dependence. In the infinite-volume continuum limit, this energy corresponds to the mass of the lightest spin-1 fermion-antifermion bound state in the theory. In realistic four-dimensional LGT studies, a set of analogous quantities can be matched to experimentally measured particle masses to set the scale of the lattice spacing in physical units and fix the quark masses. This scale setting is a necessary step before calculations of other spectral quantities can be used to predict other particle masses as well as some nonequilibrium observables. Strategies for determining the lattice spacing in quantum simulations have been proposed in Refs. [93–95].

The remainder of this paper is organized as follows. We first discuss in Sec. II the Hamiltonian time evolution in \mathbb{Z}_2 gauge theory and its implementation via quantum circuits in Sec. II. Section III discusses the study of QEM strategies for these circuits. We apply the QEM strategies in Sec. IV to compute the real-time evolution of fermion-antifermion bound states and determine the mass gap from these results. The performance and interplay of various QEM techniques is detailed for simulations using multiple IBM quantum computers. Finally, we conclude with a discussion of the results and future work in Sec. V.

II. THEORY

In this paper, we use the Kogut-Susskind lattice Hamiltonian for $1 + 1d \mathbb{Z}_2$ gauge theory with two-component



FIG. 1. Pictorial representation of the $N_s = 4$ one-dimensional lattice used in this work. The lattice is represented using seven qubits: two represent electron components of the staggered fermion e_n (green), two represent the analogous positron components p_n (red), and three represent \mathbb{Z}_2 -valued photon fields for which operators are labeled by adjacent pairs of lattice sites, e.g., $\sigma_{n,n+1}$ (orange).

staggered fermionic matter and open boundary conditions (OBCs) [96,97].² A convenient feature of this model is that both the fermionic and bosonic degrees of freedom have the same local Hilbert space dimension as qubits. This allows for a straightforward mapping to qubit-based quantum computers. Further simplifications are possible in 1 + 1d to reduce the quantum resources required, e.g., integrating out the non-dynamical gauge fields or using the block structure of the symmetry sectors. We do not employ such optimizations here, however, since they do not persist in higher dimensions [98].

Our simulations were performed on the IBM quantum computers ibmq_manila, ibm_nairobi, ibmq_jakarta, and ibmq_quito. Typical specifications for these machines during our running period are provided in the files accompanying this paper, while their physical qubit layouts are shown in Fig. 2.

A. Hamiltonian

The Hamiltonian governing \mathbb{Z}_2 gauge theory on a lattice of length N_s with OBCs is

$$H = \sum_{n=1}^{N_s - 1} \left[\frac{1}{2a_s} \sigma_{n,n+1}^x + \frac{a_s \eta}{2} (\bar{\psi}_n \sigma_{n,n+1}^z \psi_{n+1} + \text{H.c.}) \right] + a_s m_0 \sum_{n=1}^{N_s} (-1)^n \bar{\psi}_n \psi_n, \qquad (1)$$

where m_0 and η are the bare fermion mass and the gauge coupling, respectively, ψ_n is a fermion field on lattice site *n*,

²Open boundary conditions minimize the complexity of our circuits on the available IBM hardware topology (see Sec. II 2).



FIG. 2. Qubit layout and connectivity for (a) ibm_nairobi and ibmq_jakarta, (b) ibmq_manila, and (c) ibmq_quito.

¹Other proposed schemes for rendering the photon-field Hilbert space finite dimensional include truncating the compact QED variables [67], quantum link models [84], and quantum cellular automatons [85].

 $\bar{\psi}_n$ is the corresponding antifermion field, the Pauli matrices $\sigma_{n,n+1}^x$ and $\sigma_{n,n+1}^z$ act on the two-component state of the \mathbb{Z}_2 gauge field, and a_s is the spatial lattice spacing. The three terms in *H* represent the gauge kinetic term, the fermion hopping term, and the fermion mass term, respectively. For the remainder of the paper, we will set $a_s = 1$ such that all dimensionful quantities are in lattice-spacing units.

In the Kogut-Susskind fermion formulation, a single twocomponent spinor $\psi(x)$ is described by two one-component staggered fields ψ_n on neighboring sites. Here we denote the components on even sites by p_n (for positron) and the components on odd sites by e_n (for electron). The field content of an N_s -site lattice with OBCs is $N_s/2$ electron sites, $N_s/2$ positron sites, and $N_s - 1$ gauge-field links, where N_s must be even. A depiction for the case of $N_s = 4$ is provided in Fig. 1.

After a Jordan-Wigner transformation [99] to convert the fermionic degrees of freedom to bosonic ones, H becomes

$$H = \frac{1}{2} \sum_{n=0}^{N_s - 1} \sigma_{n,n+1}^x - \frac{m_0}{2} \sum_{n=0}^{N_s - 1} (-1)^n Z_n + \frac{\eta}{4} \sum_{n=0}^{N_s - 2} (X_n X_{n+1} + Y_n Y_{n+1}) \sigma_{n,n+1}^z.$$
(2)

The operators X_n , Y_n , and Z_n denote Pauli matrices acting on the electron and positron qubit states. This form of the Hamiltonian is used in the quantum simulations below.

B. Circuits

For \mathbb{Z}_2 LGT with Kogut-Susskind fermions, the state of each fermion component and gauge field can be encoded in a single qubit. Hence, a lattice with N_s sites (or, equivalently, $N_x = N_s/2$ spatial points) can be encoded in $N_q = 2N_s - 1 = 4N_x - 1$ qubits. Here we simulate two-site and four-site systems using three and seven qubits, respectively. As hardware constraints will be important, we show various compilations for the operators which are optimized for different quantum computers shown in Fig. 2.

We approximate the time evolution operator $U(t) = e^{-itH}$ via second-order Trotterization [100–102] as

$$U(t) \approx \mathcal{U}(t/\varepsilon)^{N_t},$$
 (3)

where N_t is an integer and $\epsilon \equiv t/N_t$. Performing simulations of real-time evolution on a quantum computer requires encoding $\mathcal{U}(t/\varepsilon)$ as a quantum circuit. To simplify the circuit encoding, we first express the Hamiltonian as a sum of three commuting operators.

$$H_{1} = \frac{1}{2} \sum_{n=0}^{N_{s}-1} \sigma_{n,n+1}^{x} - \frac{m_{0}}{2} \sum_{n=0}^{N_{s}-1} (-1)^{n} Z_{n},$$

$$H_{2} = \frac{\eta}{2} \sum_{n=\text{even}}^{N_{s}-2} (X_{n} X_{n+1} + Y_{n} Y_{n+1}) \sigma_{n,n+1}^{z}, \qquad (4)$$

$$H_{3} = \frac{\eta}{2} \sum_{n=\text{odd}}^{N_{s}-2} (X_{n} X_{n+1} + Y_{n} Y_{n+1}) \sigma_{n,n+1}^{z},$$

each of which is easily diagonalizable. Operator H_1 comprises the gauge-kinetic and fermion-mass terms, while H_2 and H_3 are the even- and odd-site fermion-hopping terms, respectively. In terms of the H_i , the Hamiltonian in Eq. (2) is given by

$$H = \sum_{i=1}^{3} H_i,\tag{5}$$

and the Trotterized time-evolution operator in Eq. (3) is

$$\mathcal{U}(t/\varepsilon) = \prod_{i=1}^{3} \mathcal{U}_i(t/\varepsilon), \tag{6}$$

where

$$\mathcal{U}_i(t) \equiv e^{-itH_i}.$$
 (7)

For the simulations described in this paper, we time evolve the quantum system using the circuits shown in Fig. 3. Operator \mathcal{U}_1 requires only single-qubit gates, and we employ the simple circuit implementation shown in the left panel. Operators \mathcal{U}_2 and \mathcal{U}_3 require entangling gates because the hopping term couples neighboring fermion and gauge degrees of freedom. They can be represented by the same quantum circuit, however, since H_2 and H_3 differ only by the lattice sites upon which they act. We employ the two equivalent circuit representations of the hopping-term operator in our simulations, $\mathcal{U}_{fh,1}$ and $\mathcal{U}_{fh,2}$. These are shown in the upperand lower-right panels, respectively. Because the locations of the entangling CNOT gates differ between $U_{fh,1}$ and $U_{fh,2}$, combining both circuit variations allows us to more efficiently use the available quantum hardware without the need for costly SWAP gates.

For circuit $\mathcal{U}_{fh,1}$, in which the fermion and antifermion are coupled via a central gauge field, the physical qubit layout matches the 1*d* lattice picture in Fig. 1. This straightforward implementation has been employed in recent quantum simulations of the lattice Schwinger model and its approximations, e.g., [68,71,73], and it is well-suited to quantum hardware with linear topology. Many NISQ-era computers, however, have nonlinear qubit layouts [103–106]. On these devices, the number of lattice sites that can be simulated using the hopping-term circuit layout $\mathcal{U}_{fh,1}$ is limited by the longest linear graph, and the resulting efficiency loss can be substantial. For example, on the machines ibmq_jakarta and ibm_nairobi [see Fig. 2(a)], with the standard qubit layout $\mathcal{U}_{fh,1}$ only three out of seven qubits would be usable, thereby wasting over 60% of the available resources.

To address this limitation, we employed circuit identities to derive from the standard circuit $U_{fh,1}$ a new circuit $U_{fh,2}$ in which the gauge and antifermion fields are coupled via a central fermion. Using both fermion hopping-term circuits together allows us to employ all seven quibits on ibmq_jakarta and ibm_nairobi in our quantum simulations. Further, these two circuits form a basis for efficient 1+1d \mathbb{Z}_2 simulations using all qubits on any quantum device with heavy-polygon topology.³ To illustrate how $U_{fh,1}$ and $U_{fh,2}$ can be effectively combined, Fig. 4 shows an example circuit mapping of 1+1d \mathbb{Z}_2 LGT with five spatial points onto a 22-qubit heavy-square device. This is the maximum possible

³An *N*-sided heavy polygon has qubits on both the *N* edges and the *N* vertices.



FIG. 3. The quantum circuit U_1 implementing the gauge kinetic term and the fermion mass term is shown in the left panel. In the right panel, two equivalent quantum circuits implementing the fermion hopping term appearing in U_2 and U_3 are shown. These two circuits have different qubit connectivities and are used in conjunction to provide efficient mappings between logical and physical qubits as described in the main text.

efficiency since simulating this system with N_x spatial points requires $4N_x - 1$ qubits as discussed above.

C. Simulation prescription

Correlation functions describing the real-time evolution of a quantum state of interest $|\phi\rangle \equiv \phi^{\dagger}|0\rangle$ and subsequent interaction with a Hermitian⁴ operator *O* are generically of the form

$$C(t) = \langle \phi | U^{\dagger}(t) O U(t) | \phi \rangle = \langle 0 | \phi U^{\dagger}(t) O U(t) \phi^{\dagger} | 0 \rangle.$$
 (8)

By inserting complete sets of energy eigenstates, it is straightforward to show that C(t) has the spectral representation

$$C(t) = \sum_{n,m} \langle \phi | E_m \rangle \langle E_n | \phi \rangle \langle m | O | n \rangle e^{-i(E_n - E_m)t}.$$
 (9)

Measurements of $|C(t)|^2$ from quantum simulations can be fit to this oscillatory form in order to extract energy differences $E_n - E_m$.

Because we do not explicitly project to the gauge-invariant sector of Hilbert space during time evolution, our simulations must start with gauge-invariant initial states to construct gauge-invariant correlation functions. Here we choose our

⁴Computing the expectation value of non-Hermitian operators is possible but requires multiple circuits and ancilla qubits as in e.g. the Hadamard test (see Sec. 2.4.3 of Ref [107]).



FIG. 4. Example mapping of $1+1d \mathbb{Z}_2$ which tessellates heavysquare qubit connectivity layouts relevant for ibm_nairobi and ibmq_jakarta. Solid (dashed) lines indicate $U_{fh,1}$ ($U_{fh,2}$) gates are used to implement fermion hopping terms involving a given pair of lattice sites and grayed qubits denote ones unnecessary for even numbers of lattice sites. This is the fewest number of idle qubits possible for this graph.

initial state to be a linear superposition of two gauge-invariant states: the noninteracting vacuum state $|\Omega\rangle$ and a state $|P\rangle$ that is expected to have significant overlap with excited states such as electron-positron bound states. Explicitly, the states $|\Omega(N_s)\rangle$ and $|P(N_s)\rangle$ are defined for lattices of size N_s as

$$\begin{split} |\Omega(N_s)\rangle &= \left(\prod_{n=\text{even}}^{N_2-2} H_{n,n+1} X_{n+1}\right) |0\rangle^{\otimes 2N_s-1}, \\ |P(N_s)\rangle &= X_m \sigma_{m,m+1} X_{n+1} |\Omega(N_s)\rangle, \end{split}$$
(10)

where *H* is the Hadamard gate and $m = N_s/2 - 1$ is the center lattice site. The superposition of these two states,

$$\phi(N_s)\rangle = \frac{1}{\sqrt{2}}(|\Omega(N_s)\rangle + |P(N_s)\rangle), \qquad (11)$$

is used as the initial state in our simulations. The circuit to build this state from the computational $|0....0\rangle$ state for $N_s = 4$ is given in Fig. 5.

In this paper, we compute correlation functions involving this state and the operator

$$O = \psi_n^{\dagger} \sigma_{n,n+1}^z \psi_{n+1} + \psi_n^{\dagger} \sigma_{n,n+1}^z \psi_{n+1}^{\dagger} + \text{H.c.}$$
(12)

This operator takes a simple form in the qubit spin basis,

$$O = X_n \sigma_{n,n+1}^z X_{n+1}, \tag{13}$$

which allows it to be included efficiently in quantum simulations. Further, using Eqs. (10) shows that diagonal matrix elements of O vanish for these states,

$$\langle \Omega(N_s) | O | \Omega(N_s) \rangle = 0 = \langle P(N_s) | O | P(N_s) \rangle, \qquad (14)$$



FIG. 5. Quantum circuit implementing initial-state preparation as $|\psi e.g., \rangle = U_{sp}|0...0\rangle$.

while off-diagonal matrix elements are unity:

$$\langle \Omega(N_s)|O|P(N_s)\rangle = 1 = \langle \Omega(N_s)|O|P(N_s)\rangle.$$
 (15)

Thus, the value of C(t = 0) can be computed exactly:

$$C(0) = \langle \phi(N_s) | O | \phi(N_s) \rangle = 1.$$
(16)

Correlation functions C(t) defined using this state as in Eq. (8) have time dependence generically given by Eq. (9), and in the limit of large *t* their Fourier transformations should be sharply peaked about values corresponding to some energy differences. If $|\Omega\rangle$ and $|P\rangle$ each overlap predominantly with a single energy eigenstate with energy E_{Ω} and E_P , respectively, then the time-dependence of C(t) reduces to the simple form

$$\langle \phi | U^{\dagger}(t) O U(t) | \phi \rangle \approx \cos[(E_P - E_{\Omega})t] \langle \Omega | O | P \rangle$$
$$+ \frac{1}{2} \langle \Omega | O | \Omega \rangle + \frac{1}{2} \langle P | O | P \rangle$$
$$= \cos[(E_P - E_{\Omega})t]. \tag{17}$$

This means that C(t) can be expressed as

$$C(t) = \langle \phi(N_s) | U^{\dagger}(t) O U(t) | \phi(N_s) \rangle$$

= cos(Mt) + ..., (18)

where *M* is the energy difference between the eigenstates dominantly overlapping with $|P(N_s)\rangle$ and $|\Omega(N_s)\rangle$ and the ... denotes contributions from other states that can lead to different *t* dependencies than a single-cosine form. Fits of quantum simulation results to Eq. (18) can be used to study the validity of this approximation. If the single-state contribution $\cos(Mt)$ provides a good fit to correlation function results, then the fit parameter *M* can be expected to describe the energy gap between an electron-positron bound state and the vacuum, which corresponds to the mass of the particle associated with this state in the continuum and infinite-volume limits. This accuracy of this method can be directly tested by comparing fitted results for *M* with exact spectral results, which can be numerically computed on classical computers for small N_s .

Finally, we employ the Trotterized approximation to C(t) in our simulations, which is defined as

.

$$\mathcal{C}(t/\varepsilon) = \langle \phi(N_s) | \mathcal{U}^{\mathsf{T}}(t/\varepsilon)^{N_t} O \mathcal{U}(t/\varepsilon)^{N_t} | \phi(N_s) \rangle, \qquad (19)$$

where $\mathcal{U}(t/\varepsilon)$ is defined in Eq. (3).

III. ERROR MITIGATION OF A QUANTUM SIMULATION

Many QEM strategies have been studied for reducing the systematic uncertainties associated with errors in NISQ-era quantum simulations. A primary goal of this paper is to study the interplay between different QEM methods and the reliability of quantum simulation results using combinations of state-of-the-art methods. This section briefly introduces the QEM methods that we found to provide significant improvements in these calculations: randomized compiling (RC), readout error mitigation, rescaling, and dynamic decoupling.

These QEM strategies introduce additional correlations between quantum simulation results, and it is important to accurately determine and include these correlations in analyses of quantum simulation results. Throughout this paper we

TABLE I. Details of the simulations performed in this paper. The different dynamic decoupling (DD) schemes are described below in Sec. III 4.

m_0	N_s	Machine	Date	Time ^a	DD	Qubits ^b
1	2	ibmq_jakarta	1/3/23	20:59 ^c	None	(5,6,3)
1	2	ibmq_jakarta	1/4/23	18:41 [°]	XY4	(5,6,3)
1	2	ibm_nairobi	9/10/22	13:28	None	(5,4,6)
1	2	ibm_nairobi	9/10/22	11:53	XY4	(5,4,6)
1	4	ibmq_jakarta	9/21/22	15:23	None	(0,2,1,3,5,4,6)
1	4	ibmq_jakarta	9/21/22	19:39	XY4	(0,2,1,3,5,4,6)
1	4	ibm_nairobi	1/5/23	08:57 [°]	None	(0,2,1,3,5,4,6)
1	4	ibm_nairobi	1/5/23	09:30 ^c	XY4	(0,2,1,3,5,4,6)
2	2	ibmq_jakarta	8/27/22	22:04	None	(5,6,3)
2	2	ibmq_jakarta	9/22/22	21:44	XY4	(5,6,3)
2	2	ibm_nairobi	1/4/23	21:41 [°]	None	(5,4,6)
2	2	ibm_nairobi	1/5/23	22:51 [°]	XY4	(5,4,6)
2	4	ibmq_jakarta	1/4/23	20:36 [°]	None	(0,2,1,3,5,4,6)
2	4	ibmq_jakarta	1/4/23	21:01 ^c	XY4	(0,2,1,3,5,4,6)
2	4	ibm_nairobi	9/12/22	11:26	None	(0,2,1,3,5,4,6)
2	4	ibm_nairobi	9/14/22	11:22	XY4	(0,2,1,3,5,4,6)
1	2	ibmq_manila	8/4/22	10:25	XY4	(3,1,4)
1	2	ibmq_manila	8/4/22	09:06	CMPG	(3,1,4)
1	2	ibmq_manila	8/4/22	10:26	EDD	(3,1,4)
1	2	ibmq_manila	8/4/22	16:57	XY4	(1,0,2)
1	2	ibmq_manila	8/4/22	14:58	CMPG	(1,0,2)
1	2	ibmq_manila	8/4/22	16:56	EDD	(1,0,2)
1	2	ibmq_quito	7/27/22	13:38	XY4	(3,2,4)
1	2	ibmq_quito	7/27/22	13:26	CMPG	(3,2,4)
1	2	ibmq_quito	7/27/22	13:39	EDD	(3,2,4)
1	2	ibmq_quito	7/27/22	12:05	XY4	(1,0,2)
1	2	ibmq_quito	7/27/22	11:46	CMPG	(1,0,2)
1	2	ibmq_quito	7/27/22	12:08	EDD	(1,0,2)

^aCentral Daylight Time.

^bLayouts found in Fig. 2.

^cRandom compilation not used

use bootstrap resampling [108–110] to determine all statistical uncertainties and correlations between observables, in particular, using correlated resampling of quantities arising through QEM that appear in multiple observables computed using the same quantum computer.

We performed quantum simulations of C(t) using the parameter choices $m_0 \in \{1, 2\}$ and $N_s \in \{2, 4\}$ in the Hamiltonian in Eq. (2) with $\eta = 1$ in all cases. Each simulation was performed for $N_t = 20$ Trotter steps with $\varepsilon = 0.3$. For each N_t , $N_{\rm rc} = 30$ randomly compiled circuits were run with $N_{\rm meas} = 2000$ measurements collected for each. These production simulations were carried out on ibm_nairobiand ibmq_jakartawhile additional testing simulations were also investigated on ibmq_manilaand ibmq_quito. The full details of the simulations are listed in Table I. For each simulation, we performed $N_{\text{meas}} = N_{\text{shots}}N_{\text{rc}} = 6 \times 10^4$ measurements of each quantum circuit and used $N_{\text{boot}} = 10^4$ random bootstrap samples of this ensemble of measurements. Bootstrap covariance matrices were determined for all correlated observables and the associated uncertainties were propagated to fitted quantities in a correlated way using the gvar and lsqfit packages [111–115].

A. Randomized compiling

Randomized compiling transforms coherent systematic uncertainties associated with the imperfect fidelity of quantum gates into stochastic systematic uncertainties that can be quantified with a Markovian noise model [116–122]. It has seen great success in other (1 + 1)d LGT applications [45,46,48,63,123]. At present, it must be implemented by hand, but it is expected to become a standard part of transpilation through parametric compilation [124–130]. RC utilizes multiple gates that are equivalent in the absence of noise but that differ in the presence of gate errors. Therefore, the averages of the results often have smaller errors than any individual circuit and the variance of the results provides a partial measure of the size of systematic uncertainties arising from gate errors.

A strategy for implementing RC is Pauli twirling, in which a gate Λ is replaced by a gate including additional sets of Pauli gates { σ_i } and { σ'_i }, where *i* indexes the qubits acted on by Λ that are chosen to satisfy [120,121]

$$\left[\bigotimes_{i} \sigma_{i}\right] \Lambda \left[\bigotimes_{j} \sigma_{j}'\right] = \Lambda.$$
(20)

Any solution to Eq. (20) provides a valid gate that is equivalent to Λ on an ideal quantum computer and can be used for RC. For any choice of $\{\sigma_i\}$, the $\{\sigma'_i\}$ required to produce such a solution is simply obtained by multiplying both sides of Eq. (20) by the inverses of the gates appearing and is given by

$$\left[\bigotimes_{j} \sigma_{j}^{\prime}\right] = \Lambda^{\dagger} \left[\bigotimes_{i} \sigma_{i}\right] \Lambda.$$
 (21)

For complicated gates such as the fermion hopping term above, 64 solutions to Eq. (21) can be produced in this manner, while for the CNOT there are 16. To better handle circuit scheduling constraints on cloud computing platforms, a random set of $N_{\rm RC}$ solutions can be chosen at compile time, with solutions chosen independently for each instance of Λ appearing in a quantum circuit. The optimal value of $N_{\rm twirl}$ depends on both Λ and the hardware is run and can be determined empirically by increasing $N_{\rm twirl}$ until the effects of RC saturate or are offset by a prohibitively larger number of simulations.

Pauli twirling removes correlations between repeated Λ , but any internal correlations persist. Thus, as the correlation between native gates decreases with hardware and implementation improvements, resources devoted to Pauli twirling can be reduced by only implementing them for larger gates like U_{fh} . On present systems, we investigate pauli twirling at the level of U_{fh} and at the level of the CNOTs within it. A mild but statistically significant preference to twirling the CNOTs was observed, which will be used for the remainder of this paper.

B. Readout error mitigation

The measurement operation on quantum computers is quite noisy. There are many causes for these errors, such as classical bit-flips, amplitude dampening, and cross talk [131–137]. It is important to mitigate these errors as they will bias the observed value of an operator measured on a quantum computer.

While many methods to correct these errors exist [138–143], we use regularized response matrix inversion [144–148]. For a single qubit, if we prepare the system in the state $|0\rangle$ there is a probability p_0 that we measure the qubit in the state $|0\rangle$ and a probability $1 - p_0$ that we measure it in the $|1\rangle$ state. We can then use these and the analogous probabilities for an initial $|1\rangle$ state to construct a calibration matrix:

$$M = \begin{pmatrix} p_0 & 1 - p_0 \\ 1 - p_1 & p_1 \end{pmatrix}.$$
 (22)

By acting on the vector of measured qubit state results with M^{-1} , one can mitigate the readout error and return a corrected output closer to the underlying distribution. Assuming that readout errors are uncorrelated, we can construct a tensor product $M^{\otimes N}$ and correct the readouts individually rather than the exponentially time consuming task of measuring all possible elements of the full readout correction matrix. QISKIT RUNTIME has readout mitigation built in [149].

The size of readout mitigation effects will depend on the observable under study, which is taken to be C(t) below. The calibration matrix may introduce correlations between any simulations that are transformed using the same estimated process. The absolute shift in the correlation function due to readout mitigation is defined as

$$\mathcal{A}(t) = |\mathcal{C}_{\rm RO}(t) - \mathcal{C}_{\rm raw}(t)|, \qquad (23)$$

where $C_{RO}(t)$ is the readout mitigated observable and $C_{raw}(t)$ is the observable calculated using the unmitigated data. The relative shift is defined as

$$\mathcal{R}(t) = \frac{\mathcal{A}(t)}{|\mathcal{C}_{\text{raw}}(t)|}.$$
(24)

Figure 6 shows the relative shift of the observable as a function of the observable magnitude for the simulations performed on ibm_nairobi. The relative independence of \mathcal{R} on C_{raw} indicates that the absolute size \mathcal{A} of readout mitigation effects is correlated with, and, in particular, approximately proportional to, C_{raw} . This is not unexpected, as errors on physical hardware are commonly asymmetric [150]. Similar patterns were observed on ibmq_jakarta and together we can conclude the relative shift is approximately constant with circuit depth, as seen in Fig. 7.

Separate simulations with the same or different numbers of Trotter steps may become correlated because of the calibration matrix. The correlations between randomly compiled circuits were observed to be $\lesssim 5\%$. Including these correlations has a noticeable effect when averaging these circuits, as seen in Fig. 8.

Figure 9 shows the correlations introduced by readout mitigation between different time steps for the same parameters as Fig. 8. It is unsurprising that observables involving different numbers of Trotter steps are less significantly correlated than those with the same number because the wave function is not as similar.



FIG. 6. Relative shifts \mathcal{R} in the Trotterized correlation function C_{raw} (aggregated across t/ε) defined in Eq. (24) due to readout mitigation for ibm_nairobi and ibmq_jakarta. The data points are aggregated across all possible randomized compiling circuits that did not use dynamic decoupling. Each data point was measured with $N_{\text{meas}} = 2000$.

C. Rescaling

Measured observables will include an exponential decay with respect to the circuit depth [151]. It is possible to counteract this signal damping using rescaling [62,152,153]. This method rescales the measurements of one set of circuits using information from a related set of circuits. The first set is the randomly compiled quantum simulation circuits C(t)of interest. The second set uses the same circuits except all non-Clifford gates are removed, which is denoted r(t). The first set of circuits has an unknown output that the quantum simulation is designed to determine. On the other hand, the second set containing only Clifford gates can be efficiently simulated classically [154]. Such classical algorithms can be extended further to some cases where some non-Clifford gates are allowed [155,156]. This allows for comparison between the exact answer and the noisy result, which can be used to mitigate some errors.

On a quantum computer, assuming only a depolarizing noise channel, the noisy estimate $\tilde{r}(t)$ of the classically computable observable r(t) is

$$\widetilde{r}(t) = (1 - \varepsilon)r(t) + \frac{\varepsilon}{2^n} \langle \operatorname{Tr}[U_r(t)] \rangle, \qquad (25)$$

where $U_r(t)$ is an operator satisfying $r(t) = \langle U_r(t) \rangle$ for expectation values taken in the state $|\phi(N_s)\rangle$ and ε is the strength of the depolarizing noise. Since $U_r(t)$ in our case is traceless and Hermitian because it is a tensor product of Pauli matrices, the result simplifies to $\tilde{r}(t) = (1 - \varepsilon)r(t)$. Since r(t) is easily computable, we can determine $(1 - \varepsilon)$ from a measurement of $\tilde{r}(t)$. Then we can correct for the same depolarizing noise in our correlation function of interest by rescaling the analogous noisy estimator $\tilde{C}(t)$ by $(1 - \varepsilon)^{-1}$ [62,152,153]. The resulting

rescaled correlation function is given by

$$C_{\text{rescaled}}(t) = \frac{\widetilde{C}(t)}{1-\varepsilon} = \frac{\widetilde{C}(t)r(t)}{\widetilde{r}(t)}.$$
 (26)

This method is less feasible for long depth circuits because $\tilde{r}(t)$ can be vanishingly small. A pictorial representation is shown in Fig. 10. The efficacy of rescaling is found to significantly depend on whether or not dynamical decoupling (DD) is included and is discussed further in the next section.

D. Dynamical decoupling

DD is a method to reduce errors arising from spectator qubits that are acted on trivially by a given gate. When a qubit is idling, a set of single-qubit operations are interleaved using basis transformations so environmental contamination or spurious signals from other qubits become decoupled. As a result, the coherence time of the quantum circuit becomes extended. See Ref. [157] for a review of the method. There exist many methods for DD [25,157–161] and extensive studies on different DD sequences have been done [25,162–164]. It is well known the effectiveness of a given DD sequence is problem- [165–168] and hardware-dependent [25,162].

The time-dependent evolution can be described using a total Hamiltonian H that depends on the Hamiltonian of the ideal system H_S , the Hamiltonian of the environment H_E , and the interaction between the system and the environment H_{SE} as

$$H = H_S + H_E + H_{SE}.$$
 (27)

We can view H_{SE} as an error term in the desired errormitigated Hamiltonian and cancel them out to some degree using time-dependent inversion pulses in long periods of



FIG. 7. Effects of readout correction for various depth circuits corresponding to t/ε Trotter steps. The top (bottom) figure corresponds to the $N_s = 2$ ($N_s = 4$) lattice volume, and the different colored points in each plot correspond to the different bare fermion masses indicated. Note that simulations for different masses were performed using different machines in both cases (ibm_nairobifor parameters { $N_s = 2, m_0 = 1$ } and { $N_s = 4, m_0 = 2$ } and ibmq_jakartafor the other combinations), and the central values and uncertainties of the results will therefore differ.

system-environment interaction. These pulses can be incorporated into a circuit via a transpiler pass, as described below, and are available within QISKIT.

When a circuit is prepared to be run on a quantum computer, it is first transformed into a logically equivalent circuit in terms of the basis gates supported by the quantum computer through a process called transpiling. The DD transpiler pass [169] analyzes a transpiled circuit for idle periods and inserts delay instructions. Although this will be effective in keeping a system in phase during single-qubit gates, CNOTs have longer gate times (ten or more times that of a single-qubit gate) and require a DD pulse sequence to decouple the idle qubits. Research on CNOT-induced idle periods and the best strategies for DD implementation is detailed in Ref. [170].

In this paper, we studied three different DD sequences: Carr-Purcell-Meiboom-Gill (CPMG) [158,159], XY4 [160], and Eulerian Dynamical Decoupling (EDD) [161], which are described below. These pulse sequences are shown in Fig. 11, where τ is the length of idle time on the qubit minus the single qubit gate operation times.

One of the earliest described decoupling sequences was proposed by Carr sand Purcell in 1954 [158] and elaborated on by Meiboom & Gill four years later [159]. Called CPMG, this sequence gives first-order protection to environmental



FIG. 8. Comparison of the absolute shifts from readout mitigation using calibration matrices computed with and without taking into account correlations between different circuit measurements.

coupling. It involves two X pulses, symmetrically placed on a spectator like in Fig. 11. While CPMG has been shown to perform better than a system without DD [25], it makes assumptions about the pulses being ideal. In addition, CPMG can only decouple states close to the equator of the Bloch sphere (such as the $|+\rangle$ and $|-\rangle$ states). To protect all states universally, more than just X pulses are needed.

Following previous work on DD sequences, Maudsley brought forward a sequence with universal first-order protection of states in the ideal pulse limit [160] by introducing a Y rotation to the CPMG sequence as seen in Fig. 11. This additional direction of rotation cancels out the final undesirable H_{SE} terms. It is important to note that to properly implement XY4, the total delay time *t* must be bounded by the number of single qubit gates. If the total CNOT time is less than the time it takes to implement four single qubit gates, then XY4 cannot be implemented. For IBM devices, this issue does not arise because CNOT times are ten or more times that of single



FIG. 9. Correlation matrices (that is, normalized covariance matrices) for circuits with different numbers of Trotter steps for the representative case of simulations with $m_0 = 1$ and $N_s = 2$.



FIG. 10. Pictorial representation of how rescaling circuits restore the signal. A noisy measurement (black dashed line) of an observable with a known *t*-independent expectation value (black solid line) is used to rescale a noisy measurement of an observable (yellow dashed line), resulting in the rescaled observable (yellow solid line).

qubit gates. However, other factors such as pulse alignment can place restrictions on the allowed f_t . Like CPMG, XY4's efficacy is based on an ideal pulse model and may not accurately describe some noise sources arising on real quantum computers.

EDD is a class of sequences proposed by Viola and Knill [161] that provides universal first-order protection and takes into account imperfect pulses as well. The name of this procedure is derived from the Eulerian cycles on a Cayley graph of the discrete group (in our case, rotational gates from which a sequence is constructed), a formalism which is elaborated on in Ref. [162]. The explicit sequence of gates we used is described in Ref. [25] and shown in Fig. 11.

Environmental couplings can introduce both oscillatory effects and exponential damping to the underlying signal as discussed above. DD can mitigate these oscillatory and exponential damping effects. It is easiest to see these effects on the simple observables r(t) used for rescaling. With an ideal quantum computer, the expected value of r(t) for our studies should be 1, regardless of the circuit depth. We show the effects of including DD on the rescaling circuit in Fig. 12. If only Pauli or depolarizing noise channels are affecting the quantum system, then this circuit should decay exponentially with depth. However, we observe that without DD, environmental effects introduce oscillatory terms which invalidate Eq. (25).

To quantify the efficacy of the different DD sequences, we ran simulations of the rescaling circuit on ibmq_quito and ibmq_manila with CPMG, XY4, and EDD protocols. To avoid overoptimizing our choice of DD sequence, these studies used a different initial state than the one used in our final results, corresponding to $|\psi\rangle = \frac{1}{\sqrt{2}}(|0\rangle|+\rangle|0\rangle + |1\rangle|-\rangle|1\rangle$). The results were then fit to the ansatz

$$f(x) = Ae^{-Bx}\cos(Cx) + D,$$
(28)

which is inspired by studies in Ref. [157]. The inclusion of the oscillatory term is often seen when superposition states are prepared [171]. When comparing the fits with and without DD, we expect to see that the coefficients B and C should decrease when DD sequences are included into the

TABLE II. Best-fit parameters and associated goodness of fit for fits of rescaling circuit results to Eq. (28) using the three dynamical decoupling sequences described in the main text. Calculations were performed using ibmq_manilaand ibmq_quito.

Machine	Qubits	Sequence	В	С	$\frac{\chi^2}{dof}$
ibmq_quito	(1,0,2)	CPMG	0.1137(72)	0.070(43)	0.87
ibmq_quito	(1,0,2)	XY4	0.117(72)	0.069(58)	2.2
ibmq_quito	(1,0,2)	EDD	0.116(10)	0.116(76)	1.6
ibmq_quito	(3,2,4)	CPMG	0.0870(37)	-0.068(18)	0.97
ibmq_quito	(3,2,4)	XY4	0.0836(49)	0.0006(81)	1.4
ibmq_quito	(3,2,4)	EDD	0.0725(31)	-0.075(18)	2.2
ibmq_manila	(1,0,2)	CPMG	0.1493(60)	0.076(23)	0.53
ibmq_manila	(1,0,2)	XY4	0.1321(46)	0.095(14)	0.42
ibmq_manila	(1,0,2)	EDD	0.1418(54)	0.087(15)	0.60
ibmq_manila	(3,1,4)	CPMG	0.1163(97)	0.1939(68)	1.4
ibmq_manila	(3,1,4)	XY4	0.1079(84)	0.0001(31)	1.9
ibmq_manila	(3,1,4)	EDD	0.0793(60)	0.00007(62)	3.2

quantum simulation. We find fit coefficients for the example case shown in Fig. 12 and in this and all other cases it is indeed observed that DD lowers the fitted values of *B* and *C*. For the example shown in Fig. 12, we find that B = 0.1356(58) and C = 0.3664(68) without DD and B = 0.1016(18) and C = -0.0919(54) when DD is included. Similar trends are observed with the other simulations.

The rescaling circuits were also fit to Eq. (28) and the resulting *B* values are shown in Figs. 13 and 14 and Table II. The results show that XY4 and EDD generally perform better for this study than CPMG since they have a smaller value of *B*. There is a slight preference for EDD over XY4, however, there are physical hardware constraints that limit the ability to implement EDD due to its large number of gates. Thus, XY4 was used for all further simulations.

IV. NUMERICAL RESULTS

Quantum simulation results with and without QEM are shown for one set of simulation parameters in Fig. 15. Exact results can be obtained classically for the lattice sizes studied in this paper and are shown for comparison. It is clear that with only RC and readout error mitigation, quantum simulation results deviate significantly from their expected values for all $t/\varepsilon > 1$. This demonstrates that RC is able to transform some but far from all systematic uncertainties into statistical uncertainties. The inclusion of DD without rescaling improves agreement between quantum simulation results and expectations for small circuit depths, but there are still statistically significant discrepancies visible for $t/\varepsilon \gtrsim 2$. In particular, the amplitude of the signal decays with increasing t/ε , while the expected result describes a fixed-amplitude oscillation.

This decay is effectively counteracted for some values of t/ε by including rescaling alone; however, at other values of t/ε , rescaling leads to overcorrections or drives the simulation results further away from the expected result. The overcorrection could arise from the fact that the rescaling circuit and the time evolution circuit are not exactly the same length and the small mismatch leads to an accumulation of error as the simulation circuit depth increases. In addition, RC using only



FIG. 11. The dynamical decoupling sequences studied in this paper. The notation $\frac{\tau}{N}$ indicates a delay on the qubit equal to $\frac{\tau}{N}$.

Pauli matrices does not exactly map the coherent error to a depolarizing channel. This mapping is only true if the full Clifford group is used. Given this, the rescaling procedure defined in Eq. (28) is not exactly correct. Rescaling will typically fail if the observable used for rescaling has any oscillatory components.

The simultaneous inclusion of DD and rescaling leads to significant improvements over the use of either technique alone. The quantum simulation results for $t/\varepsilon \leq 10$ agree with theoretical expectations within 5% precision. Even for larger t/ε , results obtained with DD and rescaling are much closer to theoretical expectations than unmitigated results. These results show that the amplitude of the fully mitigated results still leaves the expected physical range for large t/ε but suggest that the frequency of observed oscillations approximately matches the expected frequency. Similar behavior can be observed in fully mitigated quantum simulation results for

each set of parameters m_0 and N_s considered here, as shown in Fig. 16.

To quantify the accuracy of our simulation results with and without QEM, we perform fits of C(t) to the spectral representation discussed in Sec. II 3. The simplest ansatz is the single-cosine form shown in Eq. (18), which assumes that the initial state can be approximated as a superposition of two energy eigenstates. The largest correction to this form arising from Trotterization is that physical times t are equal to $a_t N_t$, where the renormalized Trotterization scale a_t is only equal to the Trotter step size t/ε for a noninteracting theory and otherwise is a function $a_t(\varepsilon, m_0, \eta, N_s)$ that must be determined for a given set of parameters by matching a dimensionful observable to a known value through scale setting. Taking $t = a_t N_t$ in Eq. (18) allows us to express the single-state fit ansatz as

$$\mathcal{C}(t) \approx \cos(a_t M N_t) e^{Bt}, \qquad (29)$$





FIG. 12. Effects on the rescaling circuit for $m_0 = 1$ and 3 qubits with and without using dynamical decoupling. The rescaling circuits r(t) (or in the notation of Sec. III 3 our noisy estimators $\tilde{r}(t)$) for both cases are shown as a function of the number of Trotter steps (top) along with the resulting (noisy estimator $\tilde{C}(t)$ of the) unrescaled correlation function C(t) (bottom) including readout mitigation but not rescaling.

where e^{Bt} factor introduces a nuisance parameter B to account for residual effects of depolarizing noise that are not



FIG. 13. Comparison of noisy estimates of the rescaling circuits and correlation functions using the three DD sequences described in the main text for an $N_s = 2$ lattice representing $[e_0, \sigma_{0,1}, p_1]$ using qubits [3, 2, 4] on ibmq_quito.



(b) evolution circuit observable

FIG. 14. Comparison of noisy estimates of the rescaling circuits and correlation functions using the three DD sequences described in the main text for an $N_s = 2$ lattice representing $[e_0, \sigma_{0,1}, p_1]$ using qubits [3, 2, 4] on ibmq_manila.

completely removed by rescaling. This shows that $a_t M$ is the dimensionless Fourier conjugate variable to the number of Trotter steps N_t . Correlated χ^2 -minimization fits to this functional form are used to extract $a_t M$. The ansatz is then fit to all possible ranges of fit data with six or more consecutive Trotter steps. We then use Bayesian model averaging from Ref. [172] to determine the time-dependent mass and associated systematic and statistical uncertainties. If these results described a physically relevant LGT, we could match observables like $a_t M$ to their experimental values to determine a_t and therefore make unambiguous predictions for other energies in physical units. For the 1+1 dimensional model at hand, $a_t M$ provides a proof-of-principle demonstration of the calculation of an observable that could be used for scale setting and is the final result of this paper.

Results for $a_t M$ obtained from fitting our quantum simulation results at each m_0 and N_s studied are shown in Table III. The theoretically expected exact results $(a_t M)_{\text{expected}}$ com-

TABLE III. Mass gap determined by fitting quantum simulation results to the single-state ansatz described in the main text.

Ns	m_0	ε	$a_t M$	$(a_t M)_{\text{exact}}$	
2	1.0	0.3	0.89(13)	0.9473	
4	1.0	0.3	1.02(18)	0.9386	
2	2.0	0.3	1.619(53)	1.5204	
4	2.0	0.3	1.591(27)	1.5168	

puted classically are shown for comparison in the same table, and 1σ agreement between quantum simulation results and these expectations is found in the $a_s m_0 = 1$ cases. However, significant discrepancies are found in the $a_s m_0 = 2$ cases. These discrepancies may arise from couplings to other excited states whose exact energies are close to the ones extracted from fits to our quantum simulations. It is noteworthy that applying QEM methods and, in particular, the combination of rescaling and DD, is found to be necessary for achieving a good fit to Eq. (29). Performing analogous fits to results without either of these techniques leads to less accurate estimates of the mass gap with larger uncertainties.

The effect of QEM can also be studied in Fourier space by calculating the discrete Fourier transform (DFT):

$$f(a_t\omega) \propto \sum_{t/\varepsilon=0}^{N_t} C(t) \cos(a_t\omega t/\varepsilon).$$
 (30)

The squared magnitude $|f(a_t\omega)|^2$ for the $m_0 = 2$ and $N_s = 4$ (seven-qubit lattice) correlation functions with and without DD and rescaling are shown in Fig. 17. In a noiseless simulation, a clear peak around $a_t \omega \approx (a_t M)_{\text{expected}}$ should be visible that would approach a δ function as $N_t \to \infty$. While the simulation without DD and rescaling shows an apparent peak close to this value, it is statistically not significant at 1.3 σ . Including DD and rescaling leads to a drastic decrease in relative uncertainty in frequency space and the peak close to $(a_t M)_{\text{expected}}$ is clearly visible at 6.4 σ . The frequencies $a_t \omega$ associated with these peaks in the Fourier spectrum correspond to energy gaps (relative to the vacuum) for states that have significant overlap with the state studied here. As expected from the success of single-cosine fits to correlation functions in the time domain, the location of the statistically significant peak visible in mitigated results is consistent with the fitted values of $a_t M$ in Table III and with $(a_t M)_{\text{exact}}$. We provide graphical depiction in Fig. 18. The remaining spurious oscillations in the simulation including all error mitigation techniques could arise from correlations between different frequency DFTs and possible ringing artifacts due to the finite number of Trotter steps.

To measure the efficacy of QEM, we use a figure of merit that quantifies how much longer a mitigated circuit can be simulated over an unmitigated one. This definition uses the relative deviation $\delta_{\lambda}^{\mathcal{M}}(t)$ of a simulation with parameters $\lambda = \{m_0, N_s, \epsilon, \text{device}\}$ at a time t/ε from the noiseless exact value with a mitigation strategy \mathcal{M} :

$$\delta_{\lambda}^{\mathcal{M}}(t) = \sqrt{\frac{\sum_{t_i=0}^{t} \left[\mathcal{C}_{\text{exact}}(t_i) - \mathcal{C}_{\mathcal{M}}(t_i)\right]^2}{\sum_{t_i=0}^{t} \mathcal{C}_{\text{exact}}(t_i)^2}}.$$
 (31)

We then define $t_{\lambda}^{\mathcal{M}}(\Delta)$ as the first Trotter step t/ε such that $\delta_{\lambda}^{\mathcal{M}}(t)$ is larger than a threshold Δ . An improvement factor from mitigation can then be defined as

$$T_{\lambda}(\Delta) = \frac{t_{\lambda}^{\mathcal{M}}(\Delta)}{t_{\lambda}^{\mathbf{0}}(\Delta)},$$
(32)

where $\mathcal{M} = \mathbf{0}$ corresponds to the unmitigated or only randomly compiled cases that we use as baselines. This is similar to the relative error mitigation metric proposed in



FIG. 15. Effects of rescaling and/or DD on correlation-function results. The results labeled "No QEM" include readout mitagation and randomized compiling but neither rescaling nor DD. Errors show statistical uncertainties determined using bootstrap methods as described in the main text. The parameters for this simulation are $m_0 = 1$ and $N_s = 2$. Data points outside of the range ± 2 are not shown.

Refs. [173,174]. For three of our parameter sets, we have $\mathcal{M} = \mathbf{0}$ results available for comparison. We find that $1 \leq T_{\lambda}(\Delta) \leq 20$ for $0 \leq \Delta \leq 1$ with *T* monotonically increasing with Δ —here $\Delta \leq 0.2$ trivially shows no signs of improvement because $t_{\lambda}^{\mathcal{M}}(\Delta)$ is equal to 1 for all \mathcal{M} , while the maximum value of T_{λ} achieved corresponds to the number

of Trotter steps N_t . Finally, to compute a single value, we average over a wide range of reasonable choices $\Delta = d/25$ with $d \in \{1, ..., 25\}$ as

$$\bar{T} = \frac{1}{N_{\Delta}N_{\lambda}} \sum_{\Delta,\lambda} T_{\lambda}(\Delta).$$
(33)



FIG. 16. Fully mitigated results (including rescaling and DD) for $m_0 = 1$ and $N_s = 2$ on ibm_nairobi (top left), $m_0 = 1$ and $N_s = 4$ on ibm_jakarta (bottom left), $m_0 = 2$ and $N_s = 2$ on ibm_jakarta (top right), and $m_0 = 2$ and $N_s = 4$ on ibm_nairobi (bottom right) simulations. Points that are overly noisy, unreliable, or outside the plot range are not shown.



FIG. 17. Fourier transform of the $m_0 = 2$ and $N_s = 4$ correlationfunction results. The yellow dash-dotted line is from the simulation only applying readout mitigation and randomized compiling, while the black solid line is from the simulation including dynamic decoupling and rescaling. The apparent oscillatory behavior of the amplitude could arise from correlations among neighboring points and ringing artifacts. The blue line indicates the exact mass gap of the Trotterized Hamiltonian.

This leads to $\overline{T} = 5.92(12)$, which indicates that QEM enables about six times more Trotter steps to be computed with a given level of precision.

V. CONCLUSIONS

Quantum simulations offer promising methods for computing the nonequilibrium responses of strongly coupled quantum systems to applied currents. In high-energy physics, such responses can be used to predict observables ranging from transport coefficients to scattering cross sections [65]. Predictions for these nonequilibrium observables require calculations of Minkowski correlation functions including the time-evolution operator U(t). In this paper, we computed



a simple two-point Minkowski correlation function in $1 + 1d \mathbb{Z}_2$ gauge theory to study how such observables might be determined using quantum simulations. After combining several QEM strategies, we obtained an accurate description of the time dependence of the correlation function and thereby the energy of the lowest-lying spin-1 state. These QEM strategies were essential for extracting accurate predictions from the NISQ-era quantum hardware used here.

During our studies, we found interesting synergies between various QEM techniques. RC allows some hardware-level stochastic systematic errors to be converted to quantifiable statistical uncertainties, but quantum simulation results using only this technique still differ significantly from exact results. Rescaling can be used to remove exponential signal decay with respect to circuit depth but requires a noise model that correctly describes the remaining systematics. We find that a simple noise model including only a depolarizing channel does not adequately describe our simulation results when only RC and readout error correction are employed. However, this simple noise model satisfactorily describes our results when dynamic decoupling is included. Leveraging all of these error mitigation strategies together, we extend the range of simulation times over which accurate results are achieved by a factor of 6 in comparison to results using only RC and readout error correction.

Extending these simulations to realistic LGTs in four dimensions will require further theoretical and algorithmic developments. The simplicity of $1 + 1d \mathbb{Z}_2$ gauge theory allowed us to construct initial states that predominantly overlap with a small number of energy eigenstates. Constructing such initial states will be increasingly difficult to achieve for more complex theories and in higher dimensions, and a variety of methods for efficient initial-state preparation are under active investigation [52,67–73,175–199]

Trotterization errors were not found to be numerically significant for the range of times used in this analysis, but these issues are also likely to be more challenging in more complex simulations. One promising avenue for addressing these errors is the construction of improved Hamiltonians [46,176] along the lines of the Symanzik improvement program used in classical LGT simulations [200]. Finally, it is anticipated that the efficacy of particular error mitigation strategies will change dramatically for larger gauge groups and non-Abelian gauge theories where the gauge and fermion registers themselves require multiple qubits. For these cases, additional OEM methods such as those discussed in Refs. [54,64] may be important to include. Although NISQ-era quantum computers are not large enough for phenomenologically relevant lattice-QCD simulations, it is crucial to develop QEM strategies and identify best practices for Hamiltonian simulations of lattice gauge theories so the community is ready to efficiently and effectively utilize large-scale quantum computers when they become available.

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FIG. 18. The mass gap in lattice units, $a_t M$, determined using quantum simulation results is shown as a function of the bare mass $a_s m_0$ as points with error bars. Solid lines indicate exact results for the Trotterized Hamiltonian.

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