

Saturation of rogue wave amplification over steep shoals

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Shoaling surface gravity waves induce rogue wave formation. Though commonly reduced to water waves passing over a step, nonequilibrium physics allows finite slopes to be considered in this problem. Using nonhomogeneous spectral analysis of a spatially varying energy density ratio, we describe the dependence of the amplification as a function of the slope steepness. Increasing the slope increases the amplification of rogue wave probability until this amplification saturates at steep slopes. In contrast, the increase of the down slope of a subsequent de-shoal zone leads to a monotonic decrease in the rogue wave probability, thus featuring a strong asymmetry between shoaling and de-shoaling zones. Due to the saturation of the rogue wave amplification at steep slopes, our model is applicable beyond its range of validity up to a step, thus elucidating why previous models based on a step could describe the physics of steep finite slopes. We also explain why the rogue wave probability increases over a shoal while it is lower in shallower water.

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I. INTRODUCTION

Rogue waves have been observed in a variety of fields of physics [1], such as astrophysics [2,3], optics [4,5], and condensed matter physics [6,7]. In the ocean, they present a threat to ocean vessels and offshore operations [8,9]. In the latter case, most studies have focused on deep water, where both Benjamin and Feir [10] instability and quasideterminism theory [11] apply. The study of wave statistics evolving from deep toward shallow water regimes have become a recent trend. On the other hand, no standard distribution reproduces observations over a wide range of depths and sea states [12,13]. For sea states in equilibrium (without shoaling), it may be possible to describe both deep and shallow regimes with second-order models of enhanced empirical parameter space (steepness, bandwidth, depth) [14,15], albeit such methods lack first principles of the physical problem. For seas out of equilibrium, experiments in shallower regimes have shown that inhomogeneities in the wave field due to shoaling contribute to rogue wave formation and amplification [16–18]. Paradoxically, rogue waves are less likely to occur in shallow waters as compared to deep waters [19,20]. Furthermore, spatial statistics for seas in both equilibrium and out-of-equilibrium are not captured by available theories [21,22].

Recently, successful theories of rogue wave shoaling have arisen. For an abrupt bathymetry change, Li *et al.* [23,24] propose a solution in terms of the transmission coefficients and the interaction of bound waves influenced by the step. On the other hand, Majda *et al.* [25] and Moore *et al.* [26]

dealt with a step transition implementing a truncated KdV model. However, the homogeneity of surface waves is often assumed [27], whereas the relaxation of this condition is expected to play a role in rogue wave formation over a shoal [28]. Indeed, we recently provided a third framework [29] by taking nonhomogeneity into account. These three frameworks are complementary, because they rely on different physical approaches, respectively: Fluid dynamics analysis of wave harmonics, the statistical mechanics of water waves, and the lifting of long-held implicit assumptions regarding the homogeneity of ocean waves. Nonetheless, the generality of the third framework may have the advantage of being applicable to any out-of-equilibrium water wave problem besides nonuniform bathymetry, such as opposing currents [30] or reflection [31].

Although the influence of the slope steepness on rogue wave enhancement over a shoal has been demonstrated in numerical simulations [32–34], none of the three approaches described above consider the effect of the slope steepness $\nabla h(x) \equiv \partial h(x)/\partial x$ explicitly. Therefore, the current work addresses analytically the problem of how the slope affects the amplification of extreme events when irregular waves travel over a shoal. We show that the slope mainly decreases the spatial energy density and thus increases the nonhomogeneous correction Γ introduced in Mendes *et al.* [29], increasing the rogue wave probability. Also, this slope effect saturates beyond a critical steepness. We thus provide a physical interpretation to the observation of this saturation by Zheng *et al.* [33]. Our theory explains why the physics of steep finite slopes can be well described by the three above theories. Furthermore, the slope effect saturates for mild slopes in shallow waters, explaining why it is important in intermediate depths, while dying out not only in deep water but paradoxically also in shallow waters.

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II. THEORETICAL CONSIDERATIONS

Rather than a deterministic approach based on the hydrodynamic description of the rogue wave evolution over a shoal, the model of Mendes *et al.* [29] uses a statistical approach focused on the integral properties of the wave system [35], namely the energy density. It considers the perturbation induced by the shoal on the surface elevation and thus on the energy partition, which in turn affects the statistics of water waves. This perturbation is spatially inhomogeneous and thereby redistributes the wave energy density throughout the bathymetry change. To derive the corresponding correction Γ to the distribution capturing the energetic spatial evolution, we consider the velocity potential $\Phi(x, z, t)$ and surface elevation $\zeta(x, t)$, written in generalized form of an expansion of trigonometric functions with coefficients $(\Omega_{m,i}, \tilde{\Omega}_{m,i})$:

$$\begin{aligned}\Phi(x, z, t) &= \sum_{m,i} \frac{\Omega_{m,i}(k_i h)}{m k_i} \cosh(m\varphi) \sin(m\phi), \\ \zeta(x, t) &= \sum_{m,i} \tilde{\Omega}_{m,i}(k_i h) \cos(m\phi),\end{aligned}\quad (1)$$

with the auxiliary variables $\varphi = k_i(z + h)$ and $\phi = k_i(x - c_{m,i}t + \theta_i)$, where $c_{m,i} = c_m(k_i)$ is the phase velocity of the i th spectral component and m th order in wave steepness and h the water depth. For unidirectional waves of first-order in steepness we extract $\Omega_1 = a\omega / \sinh kh$ as well as $\tilde{\Omega}_1 = a$ from linear theory [36], leading to the energy density [37]:

$$\mathcal{E} = \frac{1}{2} \rho g \sum_i a_i^2, \quad (2)$$

where ρ is the density, g is the gravitational acceleration, and a is the wave amplitude. A spectral energy \mathcal{E} is preferred to match the definition of power in signal processing [38,39], such that we define $\mathcal{E} = \rho g \mathcal{E}$. Due to the spatial inhomogeneity in \mathcal{E} and the ensemble average $\mathbb{E}[\zeta^2]$, an initially Rayleigh distribution over a flat bottom becomes $\mathcal{R}_{\alpha,\Gamma}(H > \alpha H_s) = e^{-2\alpha^2/\Gamma}$, where the nonhomogeneous correction Γ is [29]

$$\Gamma(x) = \frac{\mathbb{E}[\zeta^2(x, t)](x)}{\mathcal{E}(x)} \approx \frac{\langle \zeta^2(x, t) \rangle_t(x)}{\mathcal{E}(x)}. \quad (3)$$

Second-order waves have energy density ratio [29]:

$$\check{\mathcal{E}}(x) \equiv \frac{2\mathcal{E}(x)}{a^2} = 1 + \frac{\pi^2 \varepsilon^2(x) \mathfrak{S}^2}{32} [\tilde{\chi}_1(x) + \chi_1(x)], \quad (4)$$

where $\varepsilon = H_s/\lambda$ the significant steepness of irregular waves with the significant wave height H_s (the average height of the 1/3 tallest waves), zero-crossing wavelength λ , and with coefficients dependent on the peak wave number $k_p = 2\pi/\lambda_p$:

$$\tilde{\chi}_1 = \left[\frac{3 - \tanh^2(k_p h)}{\tanh^3(k_p h)} \right]^2, \quad \chi_1 = \frac{9 \cosh(2k_p h)}{\sinh^6(k_p h)}. \quad (5)$$

Moreover, $1 \leq \mathfrak{S} \leq 2$ denotes the slowly varying vertical asymmetry between crests and wave heights ($a = \mathfrak{S}H/2$), which for rogue waves reads [13,29]:

$$\mathfrak{S}_{(\alpha=2)} \approx \frac{2\eta_s}{1 + \eta_s} \left(1 + \frac{\eta_s}{6} \right), \quad \eta_s = \left(\frac{\langle Z_c \rangle}{\langle Z_t \rangle} \right)_{H > H_s}, \quad (6)$$

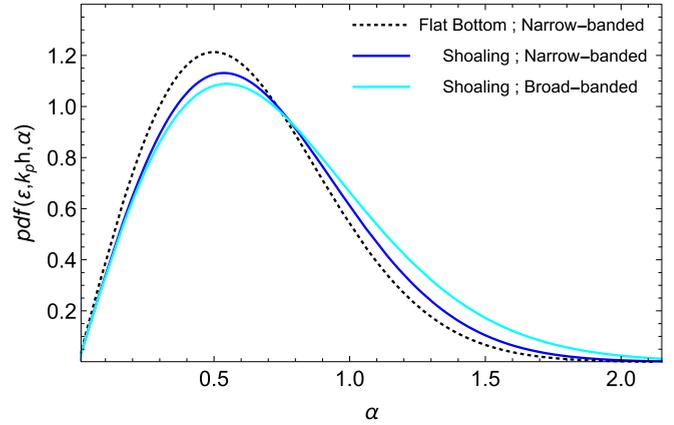


FIG. 1. Probability density due to energy density inhomogeneities caused by a shoal as compared to the Rayleigh distribution (dotted) for wave heights. Shoaling featured steepness $\varepsilon = 1/20$ while broad-banded waves have $\mathfrak{S}(\alpha = 2) = 1.20$ and narrow-banded $\mathfrak{S}(\alpha = 2) = 1.05$ instead.

given the mean crest $\langle Z_c \rangle$ and mean trough $\langle Z_t \rangle$. In the limit $\varepsilon \rightarrow 0$ we recover $\check{\mathcal{E}} = 1$ for linear waves. The physics of second-order waves leads to [40]:

$$\Gamma \equiv \Gamma(\varepsilon(x), k_p h(x), \mathfrak{S}(x)) = \frac{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{S}^2}{16} \tilde{\chi}_1}{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{S}^2}{32} (\tilde{\chi}_1 + \chi_1)}. \quad (7)$$

From the point of view of the energy density, both a homogeneous energy density of steep waves ($\varepsilon \sim 1/10$) over a flat bottom and a nonhomogeneous energy density of very small waves ($\varepsilon \ll 1/100$) over a shoal induce a Rayleigh distribution for wave heights [41]. Otherwise, the disparity in the growth of $\mathbb{E}[\zeta^2(x, t)]$ and \mathcal{E} will lead to a redistribution of the likelihood of wave heights (see Fig. 1), boosting the chances of encountering waves with $\alpha \geq 0.8$ and decreasing the chances for ordinary sized waves $0 < \alpha < 0.8$. Due to the vertical asymmetry \mathfrak{S} between wave crests and troughs, the repartitioning of probability is further enhanced as the wave spectrum is broadened and waves become more nonlinear and asymmetric. In practice, the impact of the energy repartitioning is negligible on the bulk ($0 < \alpha < 0.5$) of the exceedance probability but significant for large and rogue waves ($\alpha \gtrsim 1$).

III. ANALYTICAL SLOPE EFFECT

While our previous work focused on steep slopes, we now investigate the effect of an arbitrary finite slope. In shallow depths ($H_s = h_0$) [42], a constant slope ∇h implies an evolution of $h(x)$ and an associated slope-induced set-down ($\langle \zeta \rangle < 0$) or set-up ($\langle \zeta \rangle > 0$) effect (see Fig. 2) that affects the energy (and hence the rogue wave probability) [37] [43] on top of the effect previously investigated in Mendes *et al.* [29]:

$$\begin{aligned}\mathcal{E}_p + \mathcal{E}_k &= \frac{1}{2\lambda} \int_0^\lambda \{[\zeta(x, t) + h(x) + \langle \zeta \rangle]^2 - h^2(x)\} dx \\ &+ \frac{1}{2\lambda g} \int_0^\lambda \int_{-h(x)}^\zeta \left[\left(\frac{\partial \Phi}{\partial x} \right)^2 + \left(\frac{\partial \Phi}{\partial z} \right)^2 \right] dz dx,\end{aligned}\quad (8)$$

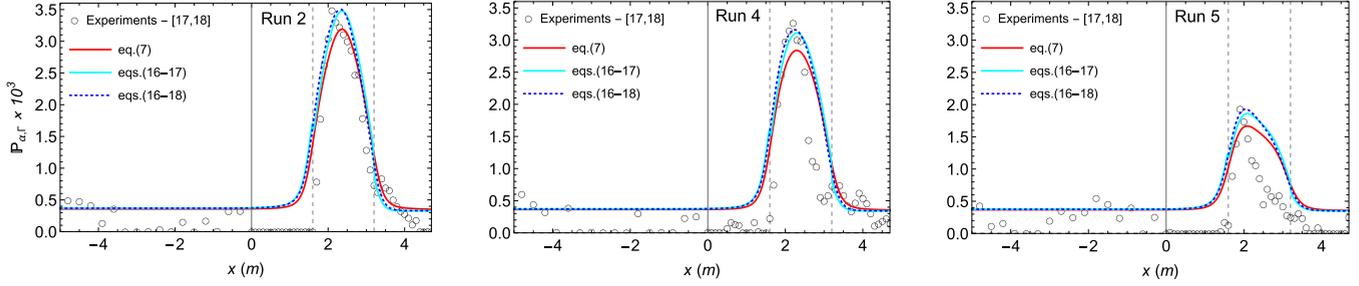


FIG. 4. Exceedance probability evolution over a bar from Eq. (17) versus data (hollow circles) [17]. The probability evolution has been computed from Eq. (7) as in Mendes *et al.* [29] (solid red) and the slope-dependent counterpart in Eq. (16) without (cyan) and with (dotted blue) smoothing of the bar geometry ($\vartheta = 3$) from Eq. (18). Note that the experiments of Trulsen *et al.* [18] lie within all assumptions leading to Eq. (16).

the down slope is increased because the term $\check{\mathcal{E}}_{p2}$ increases monotonically.

Previous theories disregarding the slope were restricted to the range $|\nabla h| \geq 1/20$. In contrast, the validity of our derivation is only limited by the assumption $L|\nabla h|/\lambda \lesssim 1$ in Eq. (10), which is why the energy ratio correction diverges $|\check{\mathcal{E}}_{p2}| \rightarrow \infty$ for $\pi|\nabla h|/k_p h_0 \gg 1$. Thus, the shoal case of our model is valid for $0 < |\nabla h| \lesssim k_p h_0/\pi$. Nonetheless, this range covers realistic conditions in the ocean, where shoaling geometries with the highest slope steepness do not exceed $|\nabla h| \approx 1$ [53,54]. While only $<1\%$ of slopes over ocean cross sections exceed $|\nabla h| \approx 1$, the typical mean slopes are $<1/10$ [55].

We compute the slope effect on $\Gamma_{\nabla h}$ for experiments of Raustøl [17] and Trulsen *et al.* [18], plotted in Fig. 4. For this purpose, the evolution of exceedance probability $\mathbb{P}_\alpha \equiv \mathbb{P}(H > \alpha H_s)$ over a shoal is described as [29]:

$$\ln\left(\frac{\mathbb{P}_{\alpha, \Gamma, \nabla h}}{\mathbb{P}_\alpha}\right) = 2\alpha^2 \left(1 - \frac{1}{\mathfrak{S}^2 \Gamma_{\nabla h}}\right). \quad (17)$$

At the peak locations and in the deshoaling zones (Fig. 4), we improve (cyan curve) the agreement with experimental data as compared with the model disregarding the slope (red curve), although the discrepancy in exceedance probability between models displayed in all panels of Fig. 4 does not exceed 8% at the location of maximum amplification of the exceedance probability. This surprisingly good fidelity of the model disregarding slope is due to the saturation evidenced in Eq. (16). Indeed, the experimental slope $\nabla h \approx -0.26$ happened to be close to saturation at $(\nabla h)_{(s)} = -(9/5) \cdot (1/2\pi) \approx -0.29$. Although our model implementing the exact slope effect is more accurate than the steep slope approximation of Mendes *et al.* [29], the experiments demonstrate that as long as the shoaling slope is near saturation the simpler model of Mendes *et al.* [29] is already very accurate. This provides a physical interpretation for the success of theories based on a step [24,26,29] in describing steep slope configurations.

However, we also checked the applicability of our model to real ocean slopes which vary smoothly and continuously, whereas the bar in the considered experiment features sharp edges. To that purpose, we numerically smoothed the edges

of the bar employing logistic functions with parameter ϑ :

$$\frac{\nabla h(x)}{|\nabla h|} = \frac{1}{1 + e^{-\vartheta(x-L)}} \left[1 + \frac{1}{1 + e^{-\vartheta(x-2L)}}\right] - 1. \quad (18)$$

Therefore, we investigated the effect of using the smoothed slope function on the exceedance probability evolution. We verified that the amplification of the exceedance probability displayed in Fig. 4 with smoothed shoal edges (dotted curve) marginally deviates from the exact ∇h (cyan curve) for $\vartheta \gtrsim 3$ corresponding to a bell-shaped bar (see Fig. 5) and is indiscernible from the sharp edges when $\vartheta \geq 10$. This insensitivity to curvature ensures the applicability to real shapes in the ocean.

Finding the excursion of the slope function in the region of $\Gamma_{\nabla h}(\nabla h \rightarrow 0) = 1$ would require the analytical evolution $\varepsilon(\nabla h)$, which is unavailable [56–60]. Therefore, we perform a parameterization. A residue $B(k_p h, \nabla h)$ relevant only for very mild slopes is introduced:

$$\check{\mathcal{E}}_{p2}(k_p h) \approx \frac{\pi \nabla h}{k_p h_0} \left[1 + \frac{\pi \nabla h}{k_p h_0}\right] \frac{6\pi^2 \varepsilon^2}{5\mathfrak{S}^4 (k_p h)^2} + B(k_p h, \nabla h), \quad (19)$$

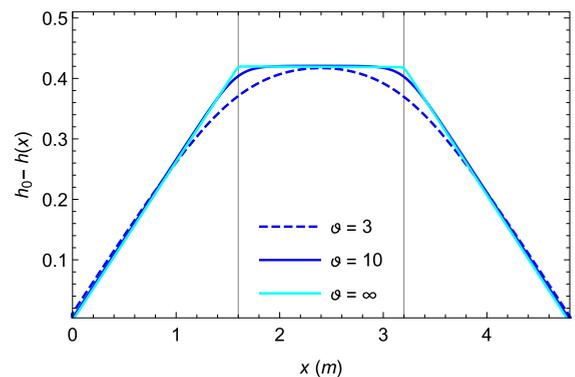


FIG. 5. Bathymetry smoothing of the bar in Trulsen *et al.* [18] generated from the integral of the slope function $\nabla h(x)$ with finite parameter ϑ as compared to the experimental bathymetry with $\vartheta = \infty$.

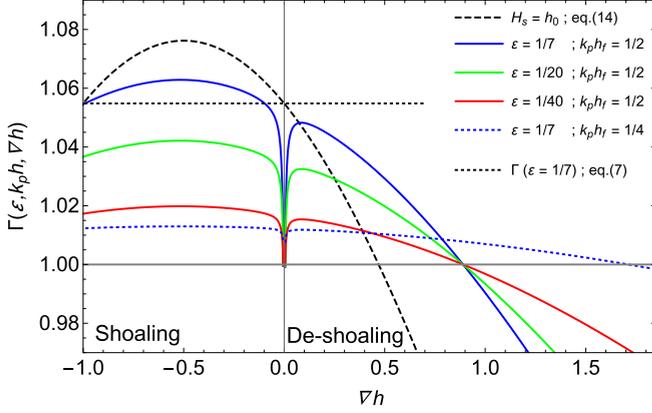


FIG. 6. Computation of $\Gamma_{\nabla h}$ from Eqs. (29) (solid), Eq. (14) (dashed), and Mendes *et al.* [29] (dotted), for an initial depth $k_p h_0 = \pi$.

noting that $\lim_{\nabla h \rightarrow 0} \check{\mathcal{E}}_{p2} = \lim_{\nabla h \rightarrow 0} B$ and

$$\lim_{\nabla h \rightarrow 0} \Gamma_{\nabla h} = \frac{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{G}^2}{16} \check{\chi}_1}{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{G}^2}{32} (\check{\chi}_1 + \chi_1) + B(k_p h, \nabla h = 0)} = 1. \quad (20)$$

Denoting $|\nabla h|_- \ll 1/20$ and $|\nabla h|_+ > k_p h_0$ as the slopes minimizing and maximizing the slope effect on the exceedance probability, Eq. (20) imposes:

$$B(|\nabla h|_-) = \frac{\pi^2 \varepsilon^2 \mathfrak{G}^2}{32} (\check{\chi}_1 - \chi_1) > 0. \quad (21)$$

The flat bottom boundary condition also requires [61]:

$$\lim_{\nabla h \rightarrow |\nabla h|_-} \frac{\partial \Gamma_{\nabla h}}{\partial |\nabla h|} > 0 \quad \therefore \quad \lim_{\nabla h \rightarrow |\nabla h|_-} \frac{\partial B}{\partial |\nabla h|} < 0, \quad (22)$$

imposing the form $B(k_p h, \nabla h) = B_0(k_p h) |\nabla h|^{-n}$ [62]. Causality and neglecting reflection effects on Γ lead to:

$$\lim_{k_p h \rightarrow k_p h_0} \Gamma(\varepsilon, |\nabla h|_+) = \lim_{k_p h \rightarrow k_p h_0} \Gamma(\varepsilon, |\nabla h|_-). \quad (23)$$

$$\Gamma(k_p h, \varepsilon, \nabla h) = \frac{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{G}^2}{16} \check{\chi}_1}{1 + \frac{\pi^2 \varepsilon^2 \mathfrak{G}^2}{32} (\check{\chi}_1 + \chi_1) + \frac{5\varepsilon^2}{(k_p h)^2} \left\{ \frac{\pi \nabla h}{k_p h_0} \left[1 + \frac{\pi \nabla h}{k_p h_0} \right] + \frac{\pi^2}{125(k_p h_0)^2 |\nabla h|} \right\}}. \quad (29)$$

The canceling effect of $B(k_p h, \nabla h)$ on the preshoal flat bottom Γ clearly appears around $\nabla h = 0$ in Fig. 6. However, when $k_p h \rightarrow 0$ the trigonometric coefficients $(\chi_1, \check{\chi}_1) \rightarrow \infty$ grow much faster than $\check{\mathcal{E}}_{p2}$, and Γ no longer depends on ∇h . This slow dependence on the slope in shallow waters (see the blue dotted curve in Fig. 6) has been observed in Doeleman [64], which carrying experiments at $k_p h_0 \approx 0.38$ found the evolution of the kurtosis for a step ($|\nabla h| = \infty$) and a slope of $|\nabla h| = 0.05$ to be identical. Our model explains this phenomenon with the proximity of the slope to the saturation point $|\nabla h|_{(s)} = k_p h_0 / 2\pi \approx 0.06$.

Experiments with wide ranges of slopes, i.e., with length $L \sim \lambda$ and water depth $\pi/10 \lesssim k_p h \lesssim \pi/2$, are not available to date because mild slopes usually require lengths exceeding wave tank dimensions or wave frequencies must be too high

Applying the general form of $B(k_p h, \nabla h)$ to Eqs. (19) and (23) results in:

$$\frac{6\pi^3 \varepsilon_0^2 |\nabla h|_+}{5\mathfrak{G}^4 (k_p h_0)^3} \left[1 \pm \frac{\pi |\nabla h|_+}{k_p h_0} \right] = \pm B(k_p h_0, |\nabla h|_-), \quad (24)$$

with \pm denoting de-shoaling and shoaling, respectively. To leading order in $|\nabla h|_+ |\nabla h|_- \sim 10^{-2}$ we obtain:

$$B(k_p h_0, \nabla h) \approx \frac{6\pi^2}{25\mathfrak{G}^4} \frac{\pi^2 \varepsilon_0^2}{2000(k_p h_0)^4} \frac{|\nabla h|_-^{n-2}}{|\nabla h|^n}. \quad (25)$$

By definition, $|\nabla h|_-$ corresponds to the limit in Eq. (20). Having $6\pi^2/25\mathfrak{G}^4 \approx 1$ [13,29], we equate Eqs. (21) and (25):

$$|\nabla h|_- \approx \frac{\varepsilon_0}{\varepsilon} \frac{1}{\sqrt{90(k_p h_0)^4 (\check{\chi}_1 - \chi_1)}}, \quad (26)$$

so that $|\nabla h|_- \approx 1/90$ for $k_p h \in [0.5, 1.5]$, experimentally observed in Katsardi *et al.* [63]. At the depth corresponding to the maximum amplification ($k_p h \approx 1/2$), Eq. (21) results in $B(|\nabla h|_-) \approx 5\pi^2 \varepsilon^2$. Since the slope effect loses importance for $|\nabla h| > 1/20$, the growth becomes $(\partial B / \partial |\nabla h|)_{|\nabla h|_-} > -120\pi^2 \varepsilon^2$. Then, the derivative of Eq. (25) imposes $n \approx \pi^2/12 \sim 1$:

$$B(k_p h, \nabla h) \approx \frac{\pi^2}{25(k_p h_0)^2} \frac{\varepsilon^2}{(k_p h)^2 |\nabla h|}. \quad (27)$$

The intermediate depth energy ratio reads:

$$\check{\mathcal{E}}_{p2} \approx \frac{5\varepsilon^2}{(k_p h)^2} \left\{ \frac{\pi \nabla h}{k_p h_0} \left[1 + \frac{\pi \nabla h}{k_p h_0} \right] + \frac{\pi^2}{125(k_p h_0)^2 |\nabla h|} \right\}. \quad (28)$$

Plugging Eq. (28) into Eq. (16) results in (Fig. 6),

for the given dimensions. Hence, in the absence of experiments with broad ranges for slopes, steepness, and water depth, we assess our theory against the numerical results of Zheng *et al.* [33], describing how the probability of the envelope [65] is affected by increasing the slope steepness. In Fig. 13 of Zheng *et al.* [33] the shoal increased the exceedance probability for rogue waves as soon as $|\nabla h| = 1/80$, with a saturation of this effect for slopes steeper than $|\nabla h| \gtrsim 1/10$ (the details of physical variables of the performed simulations C1–C8 are found on Table II in Zheng *et al.* [33]). We apply the same conditions to the slope-dependent nonhomogeneous correction of Eqs. (7), (16), (29), and (17) and compare the maximum amplification ($\varepsilon = 1/16$) of the exceedance probability (Fig. 7). Our model reproduces well the exceedance probability for rogue waves ($\alpha > 2$) and its saturation for

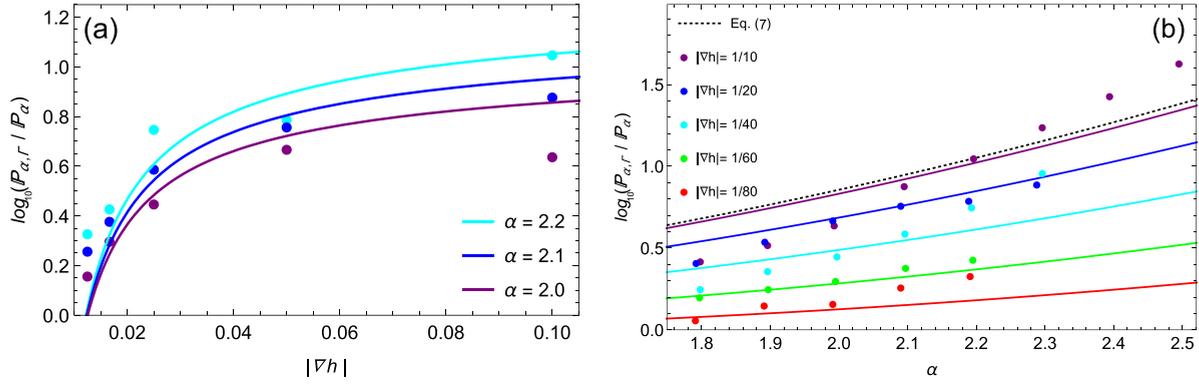


FIG. 7. Ratio of exceedance probabilities (relative to the Rayleigh distribution) as a function of (a) slope ∇h and (b) normalized heights $\alpha = H/H_s$ reported from Zheng *et al.* [33]. Dots display numerical data at $k_p h = 0.7$ while our model of Eq. (7) is shown in dotted line and Eq. (29) in solid lines.

steep slopes [Fig. 7(a)] or for large waves $\alpha \geq 1.75$ with fixed slope as shown in Fig. 7(b). Furthermore, we recover our previous model [29] for the steepest slopes [see dotted line in Fig. 7(b)].

IV. DISCUSSION

The slope effect on the exceedance probability can be interpreted as a second redistribution of the wave statistics, on top of that induced by the depth change. In the presence of a strong departure from a zero-mean water level due to a set-down/set-up the potential energy density is affected by a slope-induced correction $\tilde{\mathcal{E}}_{p2}$. In the case of a shoal, such energy disturbance decreases the total potential energy as compared to linear homogeneous waves, thereby increasing the effect of the energy redistribution ($\Gamma_{\nabla h} > \Gamma$). Similarly, a set-up induced by wave-breaking would cause the total potential energy to increase, and so we would observe the opposite effect by decreasing the exceedance probability because of $\Gamma_{\nabla h} < \Gamma$. This means that the depth change has the leading order in amplifying the exceedance probability over a shoal when the slope steepness does not vanish ($|\nabla h| \rightarrow 0$), while the slope modulates the energy redistribution due to this depth change.

The saturation of the slope effect can be understood as a combination of the effect of lowering the mean water level as a function of the slope and of the pace of the depth transition itself. The secondary term in brackets of Eq. (14) is equivalent to $\langle h(x)/h_0 \rangle$. A continuous steep slope $|\nabla h| \rightarrow \infty$ implies $\langle h(x)/h_0 \rangle \rightarrow 0$ over the wave relaxation region following the start of the shoal. Indeed, over this region the mean depth converges to the shallower depth. In the meantime, a very steep slope will quickly increase the set-down. Nevertheless, the fast increase in the set-down is balanced by the fast decrease in mean depth, therefore creating the observed saturation of their product, namely $\tilde{\mathcal{E}}_{p2}$. In other words, the response of the set-down to the steep slope transition past the saturation point is slower than the depth transition itself and has no time to develop. Conversely, in the de-shoaling zone the faster increase of the set-up due to steeper slopes is not balanced by the depth transition, as the mean depth will increase rather than decrease.

Our framework poses a clear unifying picture for wave statistics and energetics transitioning from deep to shallow waters: (i) Waves in deep water will not have their energy affected by the slope and tend to follow Gaussian statistics; (ii) in intermediate water the wave energy density will be redistributed due to depth effects on the steepness, vertical asymmetry, and mean water level, ultimately increasing rogue wave likelihoods; and (iii) in shallow water the effects on steepness and vertical asymmetry still exist, but the quick divergence of the superharmonics halts the energy redistribution while the set-up inverts the latter. Therefore, in the absence of any ocean process besides shoaling, we unify within a single physical mechanism the seemingly contradictory results of Longuet-Higgins [41] in deep water, Trulsen *et al.* [18] in intermediate water and Glukhovskii [19] in shallow water.

V. CONCLUSIONS

We have for the first time obtained an analytical dependence of the wave height exceedance probability on ∇h . It widely extends the approach developed for steps and unifies the theories for wave statistics in deep, intermediate, and shallow waters within a dynamical evolution. The unified framework is laid out as bathymetry effects on the energy partition between waves of different heights, and therefore the probability distribution, by considering the specific effects of the slope beyond the sole bathymetry change. Models that do not take finite slopes into account are nonetheless capable of reproducing well the wave statistics of steep slopes [24,26,29]. We explain this equivalency between a step and steep slopes with the saturation effect as evidenced from Eq. (16). When slopes become too steep and we reach saturation, the success of these models can be interpreted as the result of the slope effect being fully encoded in the change of both steepness and depth. Although our model does not cover the limiting case of a step *per se*, both steep and mild bathymetric profiles in the ocean are well covered by the model range of validity. Furthermore, our range of validity is consistent with small reflection effect due to a nondiverging surf similarity. Qualitatively, our theory points to three major consequences. First, making a mild slope steeper increases the probability of large wave heights in

shoaling zones and decreases it in de-shoaling zones following a shoal. Second, in very shallow water the slope effect already saturates even for mild slopes, while in intermediate waters the saturation point is harder to attain. Third, we reconcile the transient increase of rogue wave probability over a shoal with lower probabilities in shallow water. We have quantitatively validated our model against the numerical results of Zheng *et al.* [33] and the experiments of Raustøl [17] for the exceedance probability of wave heights, obtaining good agreement. Finally, the unification of

rogue wave formation mechanisms within the present framework should be possible, provided future work addresses the out-of-equilibrium ocean processes driving non-Gaussian statistics over a flat bottom, such as opposing currents and crossing seas.

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- [43] While the total energy \mathcal{E} changes over a shoal in part because of changes in c_g , in the absence of wave breaking the energy flux is constant $\nabla(\mathcal{E} \cdot c_g) = 0$. The radiation stress will continue to increase during the shoaling [67], thus producing a decrease in the mean water level from $\langle \zeta \rangle = 0$ to $\langle \zeta \rangle < 0$. If the waves break past the breaker line, then we have a positive set-up $\langle \zeta \rangle > 0$. However, Brevik [68] describes how other ocean processes can induce different types of set-down, such as wave group or current-induced. Although the wave group set-down over a flat bottom is accompanied by a small return flow [67,69], the shoal-induced set-down induces a small forward flow [70,71], and the conservation of mass near the beach or at the end of a wave tank works to cancel out this forward flow at the shoaling zone [71,72].
- [44] Because $\int_0^\lambda (x \nabla k_p / k_p)^2 dx / \lambda$ is equivalent to the integral $\int_0^\lambda (x \nabla \lambda / \lambda)^2 dx / \lambda = (\nabla \lambda)^2 / 3$.
- [45] The surface elevation can be decomposed into two parts $\zeta^*(x, t) = \zeta(x, t) + \zeta_s(x, t)$, where $\zeta(x, t)$ denotes the zero-mean oscillatory motion and $\zeta_s(x, t)$ the slope-induced set-down. However, Longuet-Higgins and Stewart [67] and subsequent literature did not derive the set-down $\zeta_s(x, t)$ explicitly. The periodicity of the type of solutions for $\zeta(x, t)$ in Eq. (1) shows that its form must be $\zeta_s(x, t) \sim \langle \zeta \rangle \cos^{2n}(m\phi)$ to fulfill $\langle \zeta^*(x, t) \rangle = \langle \zeta_s(x, t) \rangle = \langle \zeta \rangle$, with $n \in \mathbb{N}$. It is straightforward to show in the generalized case that $\int_0^\lambda 2\zeta(x, t)\zeta_s(x, t)dx = \int_0^\lambda 2\zeta(x, t)\langle \zeta \rangle dx = 0$. As long as $\nabla^2 h = 0$ we have $\int_0^\lambda \zeta(x, t)h(x)dx = 0$. Hence, our implicit choice $\zeta^*(x, t, n=0) = \zeta(x, t) + \langle \zeta \rangle$ in Eq. (8) does not lead to any loss of generality.
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