Lattice Boltzmann method with moment-based boundary conditions for rarefied flow in the slip regime

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A lattice Boltzmann method with moment-based boundary conditions is used to compute flow in the slip regime. Navier-Maxwell slip conditions and Burnett-order stress conditions that are consistent with the discrete velocity Boltzmann equation are imposed locally on stationary and moving boundaries. Micro-Couette and micro-lid-driven cavity flows are studied numerically at Knudsen and Mach numbers of the order $O(10^{-1})$. The Couette results for velocity and the deviatoric stress at second order in Knudsen number are in excellent agreement with analytical solutions, and the cavity results are in excellent agreement with existing data. The algorithm is shown to compute nonequilibrium effects in the pressure that are in very good agreement with DSMC simulations of the Boltzmann equation but not captured by the Navier-Stokes equations.

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I. INTRODUCTION

The study of flows in microdevices has received much attention in recent years [1–4]. In microdevices the Knudsen number Kn (the ratio between the mean-free path of particles and a characteristic macroscopic length scale) and the Mach number Ma (the ratio of the flow speed to the speed of sound) are typically of the order $O(10^{-1})$. This is known as the slip flow regime, and it exhibits phenomena that is not captured by the Navier-Stokes equations. This includes narrow [O(Kn) wide] slip boundary layers in the macroscopic velocity, known as Knudsen layers [2] and nonequilibrium effects in the pressure tensor [5]. To fully capture the flow one can solve the Boltzmann equation

$$\frac{\partial f}{\partial t} + \mathbf{c} \cdot \nabla f = -\frac{1}{\tau} (f - f^{(e)}), \qquad (1)$$

where $f = f(\mathbf{x}, \mathbf{c}, t)$ is the particle velocity distribution function with velocity \mathbf{c} at position \mathbf{x} and time t. The right-hand side is the BGK collision term, which assumes the relaxation of f to the Maxwell-Boltzmann equilibrium $f^{(e)}$ over the collisional timescale τ .

Solving Eq. (1) is challenging due to its high dimensionality. Simpler, lower dimensional, macroscopic equations of motion are thought to be good approximate descriptions of slip flow outside of the boundary layers as long as appropriate boundary conditions are used [6]. The three nondimensional numbers that characterize the macroscopic flow are the Reynolds, Mach, and Knudsen numbers, which are connected by von Kármán's relation and defined to be

$$\operatorname{Re} = \frac{\rho u H}{\mu}, \quad \operatorname{Ma} = \frac{u}{a}, \quad \operatorname{Kn} = \sqrt{\frac{\pi \gamma}{2} \frac{\operatorname{Ma}}{\operatorname{Re}}}, \quad (2)$$

where *u* is the characteristic flow velocity, ρ is the density of the fluid, *H* is the macroscopic length scale, and μ is the dynamic viscosity. The speed of sound in the fluid is $a = \sqrt{\gamma RT}$ where γ is the ratio of specific heats for an ideal monatomic gas (taken to be 5/3) and *R* and *T* are the gas constant and absolute temperature. Later we will use the ideal equation of state for pressure, $p = \rho RT$. The Navier-Stokes equations with Navier-Maxwell slip boundary conditions are often solved in favor of the Boltzmann equation [7]. Here, provided the velocity in the bulk flow is accurately captured, one sacrifices capturing the narrow boundary layer in favor of ease of analysis or computation.

The Navier-Stokes equations can be recovered from an asymptotic expansion of (1) to first order in Kn \ll 1. Thus by modeling the slip flow regime using the Navier-Stokes equations one is ignoring physical contributions to nonconserved hydrodynamic moments at higher order in Kn, as well as the Knudsen velocity boundary layer. These contributions can be seen and understood by taking moments in the hydrodynamic reference frame, that is, with respect to the peculiar velocity. Defining the peculiar velocity $\xi = \mathbf{c} - \mathbf{u}$, one can obtain from (1) the evolution of the pressure tensor $\mathbf{P} = \int \xi \xi f d\xi$ [8]

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$$\partial_t P_{\alpha\beta} + \partial_\gamma (u_\gamma \partial_\gamma P_{\alpha\beta} + Q_{\alpha\beta\gamma}) + P_{\alpha\gamma} \frac{\partial u_\beta}{\partial x_\gamma} + P_{\gamma\beta} \frac{\partial u_\alpha}{\partial x_\gamma} = -\frac{1}{\tau} (P_{\alpha\beta} - P_{\alpha\beta}^{(e)}), \qquad (3)$$

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where $\mathbf{Q} = \int \boldsymbol{\xi} \boldsymbol{\xi} \boldsymbol{\xi} f d\boldsymbol{\xi}$. This level of detail can be appreciable for moderate Knudsen numbers (as discussed below) but cannot be predicted by the Navier-Stokes model.

The importance of flows in microdevices with moving boundaries has seen the development of numerical methods for macroscopic equations in the slip flow regime and also numerical solvers for the Boltzmann equation [9–13]. Of particular interest here, Mizzi et al. [5] computed solutions to the Navier-Stokes-Fourier equations in micro-lid-driven cavity flow and compared them with their DSMC results for the Boltzmann equation. Importantly, they found that while the Navier-Stokes-Fourier model could predict the velocity field well outside of kinetic boundary layers, it could not compute accurate solutions to other aspects of flow in the slip regime. In particular, and in agreement with Jiang et al. [14], they showed that the nonequilibrium effects of the Knudsen number were strong near the moving wall and in the vicinity of the corners, with the Navier-Stokes and DSMC solvers predicting considerably different pressures. Mizzi et al. [5] argued for alternative solution methods to be developed. We show in this article that the lattice Boltzmann equation with moment-based boundary conditions can accurately capture the pressure distribution in the slip flow regime where the Navier-Stokes-Fourier equations could not.

The lattice Boltzmann method (LBM) may be considered an intermediate approach to computing slip flow. Its discrete particle velocity set restricts it to capturing only the first few moments of the Boltzmann equation (1), and, for standard integer lattices at least, it cannot capture kinetic effects in the velocity field [15]. However, the LBM will capture the bulk flow with a high degree of accuracy when supplemented with appropriate slip boundary conditions [16,17]. Furthermore, and despite being primary used as a Navier-Stokes solver, it can compute the pressure tensor, viz., the deviatoric stress, from kinetic theory with an isothermal equation of state, even with a small number of degrees of freedom [18]. The application of the LBM to the slip flow regime has received significant attention [16,17,19-25], but most studies used "kinetic-style" boundary conditions that are prone to inaccuracies in the slip at the boundaries; see Verhaeghe et al. [17] and Reis and Dellar [16] for an overview. A tworelaxation-time collision operator can be used to remove or minimise such artifacts, allowing for a far more robust scheme [26,27], yet the timescale of the relaxation of the third order moment required to minismize the error is too long to capture the deviatoric stress at appreciable Knudsen numbers [28]. Alternatively, a novel technique for implementing boundary conditions in the LBM was proposed by Bennett [29] and used to impose the Navier-Maxwell conditions precisely for slip flow in microchannels by Reis and Dellar [16]. This methodology does not produce any artificial slip and can be used with any lattice Boltzmann collision operator [30–32]. It can also be used to impose boundary conditions that are consistent with the deviatoric stress and has been shown to predict non-Navier-Stokes behavior [28,33], but until now this has not been used to compute the slip-flow regime. Here we show that the LBM with consistent moment-based boundary conditions can accurately compute flow in the slip regime, including subtle effects in the pressure that the Navier-Stokes-Fourier systems cannot capture.



FIG. 1. The nine particle velocities and the D2Q9 lattice.

The remainder of the article is organized as follows. In Sec. II we discuss the lattice Boltzmann framework for the slip flow regime, and we explain the boundary conditions and their implementation in Sec. III. Numerical results for micro-Couette and mico-lid-driven cavity flows are shown in Secs. IV and V, respectively, and concluding remarks are made in Sec. VI.

II. THE LATTICE BOLTZMANN METHODOLOGY

The discrete velocity Boltzmann equation with a BGK collision operator with relaxation time τ is

$$\frac{\partial f_i}{\partial t} + \mathbf{c}_i \cdot \nabla f_i = -\frac{1}{\tau} \big(f_i - f_i^{(0)} \big), \tag{4}$$

where f_i represents the particle distribution function with discrete particle velocity \mathbf{c}_i . Here the truncated discrete velocity set $\{\mathbf{c}_i | i = 0, ..., 8\}$ forms the integer D2Q9 lattice shown in Fig. 1. The prescribed equilibria, $f_i^{(0)}$, are [34,35]

$$f_i^{(0)}(\mathbf{x},t) = \omega_i \rho \left(1 + 3\mathbf{c}_i \cdot \mathbf{u} + \frac{9}{2} (\mathbf{c}_i \cdot \mathbf{u})^2 - \frac{3}{2} \mathbf{u}^2 \right), \quad (5)$$

with lattice weights

a

$$p_i = \begin{cases} 4/9, & \text{if } i = 0, \\ 1/9, & \text{if } i = 1, \dots, 4, \\ 1/36, & \text{if } i = 5, \dots, 8. \end{cases}$$
(6)

Macroscopic observables are obtained by taking discrete velocity moments of f_i . The first three moments are the hydro-dynamic mass, momentum, and momentum flux, respectively:

$$\rho = \sum_{i} f_{i}, \quad \rho \mathbf{u} = \sum_{i} f_{i} \mathbf{c}_{i}, \quad \mathbf{\Pi} = \sum_{i} f_{i} \mathbf{c}_{i} \mathbf{c}_{i}, \quad (7)$$

and mass and momentum are conserved by collisions:

$$\rho = \sum_{i} f_i^{(0)}, \quad \rho \mathbf{u} = \sum_{i} f_i^{(0)} \mathbf{c}_i. \tag{8}$$

The remaining moments are nonhydrodynamic moments (or "ghost moments") and are given by

$$Q_{xxy} = \sum_{i} f_{i}c_{iy}c_{ix}^{2}, \quad Q_{xyy} = \sum_{i} f_{i}c_{ix}c_{iy}^{2},$$

$$S_{xxyy} = \sum_{i} f_{i}c_{ix}^{2}c_{iy}^{2}.$$
 (9)

Taking the first three moments of the discrete Boltzmann equation (4) yields exact conservation laws for mass and momentum and a partial differential equation for the evolution of the flux of momentum,

$$\partial_t \rho + \boldsymbol{\nabla} \cdot \rho \mathbf{u} = 0, \tag{10}$$

$$\partial_t \rho \mathbf{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Pi} = 0, \tag{11}$$

$$\partial_t \mathbf{\Pi} + \nabla \cdot \mathbf{Q} = -\frac{1}{\tau} (\mathbf{\Pi} - \mathbf{\Pi}^{(0)}),$$
 (12)

where $\mathbf{\Pi}^{(0)} = \sum_{i} f_{i}^{(0)} \mathbf{c}_{i} \mathbf{c}_{i}$ is the equilibrium momentum flux tensor and, from Eq. (5), is known to be

$$\mathbf{\Pi}^{(0)} = \frac{\rho}{3}\mathbf{I} + \rho \mathbf{u}\mathbf{u}.$$
 (13)

We identify the pressure as $p = \rho/3 = \rho RT$, i.e., an ideal equation of state. The right-hand side of equation (12) includes the deviatoric stress $\mathbf{\Gamma} = \mathbf{\Pi}^0 - \mathbf{\Pi}$, which one usually approximates to first order in relaxation time τ (or Knudsen number) using a Chapman-Enskog analysis. Instead, the stress can be obtained by taking moments with respect to the discrete peculiar velocity $\boldsymbol{\xi}_i = \mathbf{c}_i - \mathbf{u}$. The pressure tensor $\mathbf{P} = \sum_i f_i \boldsymbol{\xi}_i \boldsymbol{\xi}_i$ in discrete kinetic theory evolves according to the same PDE found in classical kinetic theory, i.e., Eq. (3), although without enough degrees of freedom to specify \mathbf{Q} completely [8,18,36]. Following Dellar [18], the deviatoric stress with the D2Q9 lattice isothermal equation of state, $p = \rho RT = \rho/3$, is $\mathbf{\Gamma} = \rho/3\mathbf{I} - \mathbf{P}$ and is governed by

$$\Gamma_{\alpha\beta} + \tau (\partial_t \Gamma_{\alpha\beta} + u_\gamma \partial_\gamma \Gamma_{\alpha\beta} + \Gamma_{\alpha\gamma} \partial_\gamma u_\beta + \Gamma_{\beta\gamma} \partial_\gamma u_\alpha) = \mu (\partial_\beta u_\alpha + \partial_\alpha u_\beta),$$
(14)

where $\mu = \rho \tau/3$ is the dynamic viscosity. It has been assumed that the third-order moment remains close to its equilibrium, which is $O(Ma^3)$, and thus has been neglected (and we note that the equilibrium part of **Q** is zero in continuous kinetic theory) [18]. It is noted again that this is an isothermal LBM.

Clearly, the stress embedded in the D2Q9 discrete velocity model includes contributions beyond what is captured by the Navier-Stokes equations. The Navier-Stokes relation would be recovered only if the terms multiplied by τ on the lefthand side of Eq. (14) vanish. Instead, the stress includes nonequilibrium effects from the Boltzmann equation. While these contributions may be negligible for very small Knudsen numbers, they can be appreciable in the slip flow regime or when τ is not small [16,28].

B. From discrete Boltzmann to lattice Boltzmann

To solve Eq. (4) numerically we integrate both sides along a characteristic for time, Δt , to obtain

$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) - f_i(\mathbf{x}, t) = -\frac{1}{\tau} \int_0^{\Delta t} \left(f_i - f_i^{(0)} \right) ds.$$
(15)

The integral on the right side is approximated using the trapezoidal rule to give a fully discrete and implicit system of algebraic equations:

$$f_{i}(\mathbf{x} + \mathbf{c}_{i}\Delta t, t + \Delta t) - f_{i}(\mathbf{x}, t)$$

$$= -\frac{\Delta t}{2\tau} \Big[f_{i}(\mathbf{x} + \mathbf{c}_{i}\Delta t, t + \Delta t) - f_{i}^{(0)}(\mathbf{x} + \mathbf{c}_{i}\Delta t, t + \Delta t) \Big]$$

$$- \frac{\Delta t}{2\tau} \Big[f_{i}(\mathbf{x}, t) - f_{i}^{(0)}(\mathbf{x}, t) \Big] + O(\Delta t^{3}).$$
(16)

This second-order implicit system is converted into an explicit algorithm using the He *et al.* [37] variable change

$$\bar{f}_i(\mathbf{x},t) = f_i(\mathbf{x},t) + \frac{\Delta t}{2\tau} \Big[f_i(\mathbf{x},t) - f_i^{(0)}(\mathbf{x},t) \Big], \qquad (17)$$

to obtain the second order in space and time lattice Boltzmann equation (LBE) for f_i :

$$\bar{f}_{i}(\mathbf{x} + \mathbf{c}_{i}\Delta t, t + \Delta t) - \bar{f}_{i}(\mathbf{x}, t)$$

$$= -\frac{\Delta t}{(\tau + \Delta t/2)} \left[\bar{f}_{i}(\mathbf{x}, t) - f_{i}^{(0)}(\mathbf{x}, t) \right] + O(\Delta t^{3}). \quad (18)$$

Recall that the grid spacing and time step are connected by the lattice speed $c = (\Delta x / \Delta t) \gg 1$.

Density, momentum, and momentum flux are computed from f_i using the variable change (17),

$$\rho = \sum_{i} f_{i} = \sum_{i} \bar{f}_{i}, \quad \rho \mathbf{u} = \sum_{i} \bar{f}_{i} \mathbf{c}_{i} = \sum_{i} f_{i} \mathbf{c}_{i}, \quad (19)$$
$$\overline{\mathbf{\Pi}} = \sum_{i} \bar{f}_{i} \mathbf{c}_{i} \mathbf{c}_{i} = \sum_{i} f_{i} + \sum_{i} \frac{\Delta t}{2\tau} \left(f_{i} - f_{i}^{(0)} \right)$$
$$= \frac{(2\tau + \Delta t)}{2\tau} \mathbf{\Pi} - \frac{\Delta t}{2\tau} \mathbf{\Pi}^{(0)}. \quad (20)$$

Thus, the deviatoric stress is given in terms of barred quantities as

$$\boldsymbol{\Gamma} = \boldsymbol{\Pi}^0 - \boldsymbol{\Pi} = \frac{2\tau(\boldsymbol{\Pi}^{(0)} - \boldsymbol{\Pi})}{(2\tau + \Delta t)}.$$
(21)

III. HYDRODYNAMIC BOUNDARY CONDITIONS FOR THE SLIP FLOW REGIME

Modeling microflows at small Knudsen numbers with macroscopic conservation laws can capture phenomena outside of the velocity boundary layers provided suitable boundary conditions are used. We consider flat walls that may move tangentially only. In the slip flow regime, the tangential velocity at a wall can be modeled with the Navier-Maxwell condition, which says the amount of slippage is proportional to the shear at the wall [6],

$$u_x = U_m - \sigma K n H \frac{\partial u_x}{\partial y} \bigg|_{\text{wall}}.$$
 (22)

Here we have taken the liberty to let the subscripts *x* and *y* denote the tangential and normal directions at a flat wall, respectively. In Eq. (22) U_m is the velocity of the wall and σ is the (streamwise momentum) accommodation coefficient. In what follows we use $\sigma = 1$. The coefficient Kn*H*, where *H* is the characteristic macroscopic length scale, defines the mean-free path. The kinematic condition states that $u_y = 0$.

In Sec. II A we saw that the stress embedded in the LBM is given by Eq. (14). At a boundary we assume there is no dependence on time or tangential coordinate, $\partial_t = \partial_x = 0$. Noting

TABLE I. Moment combinations for unknown f_i at the north boundary.

Moments	Combination of unknowns at north boundary	
$\overline{\rho, \rho u_y, \Pi_{yy}}$ $\rho u_x, \Pi_{xy}, Q_{xyy}$	$egin{array}{llllllllllllllllllllllllllllllllllll$	
$\mathbf{\Pi}_{xx}, Q_{xxy}, S_{xxyy}$	$f_7 + f_8$	

that the normal velocity is zero by the kinematic condition, the components of stress at a boundary are

$$\Gamma_{xx} + 2\tau \Gamma_{xy} \frac{\partial u_x}{\partial y} = 0, \qquad (23)$$

$$\Gamma_{yy} = 0, \qquad (24)$$

$$\Gamma_{xy} - \mu \frac{\partial u_x}{\partial y} = 0.$$
 (25)

Equations (24) and (25) represent the shear stress and the normal component of the stress at a boundary, respectively, and they are the same as in the Navier-Stokes equations. Equation (23) shows the tangential component of the stress at a boundary. This would be zero in the Navier-Stokes equation, but at $O(\tau^2)$ it is proportional to the square of the shear. Thus special consideration of the tangential stress at the boundary is needed in lattice Boltzmann computations.

A. Moment-based boundary conditions for the lattice Boltzmann equation

The moment-based approach for implementing boundary conditions for the LBE is a general methodology that imposes constraints directly and precisely upon moments of the LBE and then translates them into conditions for the unknown distribution functions at a boundary [29]. The unknowns are the incoming f_i (or $\bar{f_i}$), i.e., the f_i with velocity \mathbf{c}_i pointing into the fluid domain, and clearly one should have as many boundary moment conditions as there are unknown f_i , and these moments need to be linearly independent at a boundary. For the D2Q9 lattice with boundaries aligned with grid points three conditions are needed for three unknowns.

We proceed by illustrating the method using a horizontal boundary at the north of the domain. Here the functions \bar{f}_4 , \bar{f}_7 , and \bar{f}_8 are unknown and need to be supplied to the algorithm (see Fig. 1). These unknowns appear in the moments in one of three linear combinations, as shown in Table I. Thus one must impose a condition on one moment from each row of Table I and then solve for the unknown f_i [noting the definitions given in Eqs. (7) and (9)]. For the second-order discretization (18), the conditions need to be expressed in terms of "barred" quantities using the transformation (17). Considering we are computing solutions to hydrodynamic flow equations we choose to impose hydrodynamic constraints. For the slip flow regime considered here we have conditions for the two components of momentum,

$$\rho u_y = 0, \quad \rho u_x = \rho U_m - \rho \sigma \operatorname{Kn} H \frac{\partial u_x}{\partial y} \Big|_{\text{wall}}, \quad (26)$$



FIG. 2. Numerical and analytical solutions for the velocity in micro-Couette flow with Kn = 0.05 and Ma = 0.09.

and also the tangential component of the momentum flux (and hence stress)—the only hydrodynamic moment in the final row of Table I.

Equation (23) for the tangential stress can be rewritten using Eq. (25) as

$$\Gamma_{xx} = -\frac{2\tau}{\mu} \Gamma_{xy}^2, \tag{27}$$

and since $\Gamma_{xx} = \Pi_{xx}^{(0)} - \Pi_{xx}$, we have the boundary condition for the momentum flux moment of the LBE:

$$\Pi_{xx} = \frac{\rho}{3} + \rho u_x^2 + \frac{2\tau}{\mu} \Gamma_{xy}^2.$$
 (28)

This condition, together with the two in Eq. (26), gives our three linear independent moment constraints at the boundary. Using the transformation (17), these are easily converted into



FIG. 3. Velocity profiles of mico-Couette flow at Kn = 0.01, 0.05, 0.1, 0.2 with Ma = 0.09.



FIG. 4. Numerical and analytical solutions for the deviatoric stress $\Gamma_{xx}(0.5, y)$ in micro-Couette flow with Kn = 0.05 and Ma = 0.09. Numerical results for the consistent Burnett-order (23) and inconsistent Navier-Stokes ($\Gamma_{xx} = 0$) order stress boundary conditions are shown.

conditions on "barred" moments:

$$\rho \overline{u}_{y} = 0,$$

$$\rho \overline{u}_{x} = \rho U_{m} + \frac{2\tau \rho \sigma \operatorname{Kn} H}{\mu (2\tau + 1)} \overline{\Pi}_{xy},$$
(29)
$$\overline{\Pi}_{xx} = \frac{\rho}{3} + \rho u_{x}^{2} + \frac{4\tau^{2}}{\mu (2\tau + 1)} \overline{\Pi}_{xy}^{2},$$

where we have used Eqs. (21) and (25) to write the shear derivative in terms of locally available moments (noting that $\Pi_{xy}^{(0)} = \rho u_x u_y = 0$ at the boundary). The moments ρ and $\overline{\Pi}_{xy}$ in the boundary conditions above can be written in terms of imposed conditions and known (incoming) distribution functions:

$$\rho = \rho u_y + \bar{f}_0 + \bar{f}_1 + \bar{f}_3 + 2(\bar{f}_2 + \bar{f}_5 + \bar{f}_6)$$

= $\bar{f}_0 + \bar{f}_1 + \bar{f}_3 + 2(\bar{f}_2 + \bar{f}_5 + \bar{f}_6),$
 $\overline{\Pi}_{xy} = -\rho u_x + \bar{f}_1 - \bar{f}_2 + 2\bar{f}_5 - 2\bar{f}_6,$



FIG. 5. Schematic diagram of lid-driven cavity flow.



FIG. 6. Horizontal velocity profiles $u_x(x, 0.5)$ at different Knudsen numbers when Ma = 0.09.

Simply solving the linear system (29) for the three unknowns yields

$$\bar{f}_4 = -\overline{\Pi}_{xx} + \bar{f}_1 + \bar{f}_3 + \bar{f}_2 + 2(\bar{f}_5 + \bar{f}_6),
\bar{f}_7 = \frac{1}{2}(\overline{\Pi}_{xx} - \rho u_x) - \bar{f}_3 - \bar{f}_6,
\bar{f}_8 = \frac{1}{2}(\rho u_x + \overline{\Pi}_{xx}) - \bar{f}_1 - \bar{f}_5.$$
(30)

We note that most previous applications of moment-based boundary conditions [16,29,30,38–40] impose a Navier-Stokes stress condition, $\Gamma_{xx} = 0$ at a boundary, but this has been shown to be inconsistent with the underlying moment system [28,33].

IV. MICRO-COUETTE FLOW

We use the LBE to compute solutions to planar micro-Couette flow with the Navier-Maxwell slip condition (22) and Burnett stress condition (23) imposed on the top and bottom boundaries using the moment-based approach described in Sec. III A. The top wall moves horizontally with velocity U_m



FIG. 7. Vertical velocity profiles $u_y(0.5, y)$ at different Knudsen numbers when Ma = 0.09.



FIG. 8. Streamlines in micro-lid-driven cavity flow when Ma = 0.09 and Kn = 0.1 (left) and Kn = 0.001.

while the parallel bottom wall, which is a distance *H* away, is stationary. The domain is periodic in the flow direction. Four different values of the Knudsen number are used: Kn = 0.01, 0.05, 0.1, and 0.2; and our results are compared with the analytical solution of the Navier-Stokes equations with the aforementioned boundary conditions, assuming the flow is steady ($\partial_t = 0$), incompressible ($\rho = \text{const}$), and unidirectional [u = u(y)]:

$$u(y) = \frac{U_m}{(1+2\mathrm{Kn})} \left[\left(\frac{y}{H}\right) + \mathrm{Kn} \right].$$
(31)

In the plots that follow the velocity has been scaled with the wall moving velocity, U_m , and the normal coordinate with the channel height, H.

Figure 2 plots the numerical and analytical solution for the velocity when Kn = 0.05. For clarity of visualization, a 1×17 grid is used in the plot, but errors smaller than $O(10^{-10})$ were observed on just three grid points. Figure 3 plots the velocity profiles at different Kn and shows the increasing slip at the boundaries as we increase the Knudsen number. In all cases the LBM results are grid independent and agree well with the benchmark data [22,23,25] and, moreover, with the analytical solution.

Figure 4 plots the computed and analytical solution of the tangential component of the deviatoric stress down the center of the channel, $\Gamma_{xx}(0.5, y)$, when Kn = 0.05 and Ma = 0.09. The analytical solution is

$$\Gamma_{xx} = -2\tau \mu \left[\frac{U_m}{H(1+2\mathrm{Kn})} \right]^2, \qquad (32)$$

where we have used Eq. (14) noting that the flow is steady $(\partial_t = 0)$ and unidirectional [u = u(y)], and the flow velocity is given by Eq. (31). The computed solution with the Navier-Stokes stress condition $\Gamma_{xx} = 0$ that has often been used with the moment-based approach [16,30,31,38,39,41] is also shown. The resolution is the same as above, and the results are grid independent. The figure illustrates the excellent agreement between the numerical and analytical solutions for Γ_{xx} using the Navier-Maxwell slip (22) and stress moment-based boundary conditions (23). We remark that when the

Navier-Stokes condition is used, the stress is constrained to be zero at the boundaries, and this is in contradiction the the underling PDE moment system, and hence the spurious numerical boundary layers observed in Fig. 4.

V. MICRO-LID-DRIVEN CAVITY FLOW

The methodology is applied to two-dimensional micro-liddriven cavity flow, with the top wall of a square box of side Lmoving horizontally with constant velocity U_m while the other boundaries are stationary; see Fig. 5. The Navier-Maxwell slip condition (22) and the Burnett stress condition (23) are applied to all boundaries. A grid of size 65×65 was used in the simulations shown here with no discernible differences in the velocity field on finer grids, and second-order convergence has been observed from 17×17 grids. In the plots that follow the velocity has been scaled with the moving wall velocity, U_m , and the coordinates with the channel height, L.

Figures 6 and 7 show the effect of the Knudsen number on the behavior of the velocity when the Mach number is fixed at Ma = 0.09. The wall slippage increases with Kn, and the respective turning points are smaller in magnitude, in agreement with existing results [9,11,22,25].

We plot in Fig. 8 the streamlines when Kn = 0.1 and 0.001; the latter being used to highlight vanishingly small slip lengths. The secondary vortices in the corners that appear for the case of no slip are not detected when there is significant wall slip (increasing Knudsen number), and the location of the primary vortex travels towards the center of the cavity as we increase Kn, in agreement with the results of Ogata and Kawaguchi [9]. For more quantitative measures, Table II shows the maximum value of the primary stream function, Ψ_{max} , and its location. Our data show that Ψ_{max} decreases when the Knudsen number increases with fixed Ma [meaning that Re is decreasing by von Kármán's relation, Eq. (2)], and the location of the maximum stream function creeps downwards with higher Kn and thus more slip.

Finally, the normalized pressure $P = p/p_0$ along the surface of the cavity when Kn = 0.05 is shown in Fig. 9 and when Kn = 0.1 in Fig. 10. In these figures the coordinate

TABLE II. The maximum value of the streamfunction and its location for various Kn when Ma = 0.09.

Kn	$\Psi_{ m max}$	(x, y)
0.001	0.1047	(0.60, 0.73)
0.01	0.0951	(0.50, 0.77)
0.05	0.0789	(0.50, 0.74)
0.10	0.0681	(0.50, 0.71)
0.20	0.0635	(0.49, 0.63)

S refers to the distance along the perimeter of the cavity in the clockwise direction from the origin (0,0), denoted by A in Fig. 5. A 129×129 grid was used, and no discernible difference was observed on finer grids. The influence of the Knudsen number and rarefaction on the pressure distribution is seen and in agreement with Jian et al. [14]. Moreover, our results are in very good quantitative agreement with the hard sphere DSMC results of Mizzi et al. [5]. The computed solutions of the Navier-Stokes-Fourier equations with slip conditions of [5] are also shown in Figs. 9 and 10. It is noteworthy that the solutions based on the Navier-Stokes-Fourier model, which has the normal pressure tensor $-p\mathbf{I}$, overpredicts the pressure greatly, whereas the LBM with the prescribed boundary conditions has a pressure evolution equation that agrees with kinetic theory and computes solutions in agreement with the DSMC results.

VI. CONCLUSION

The lattice Boltzmann method (LBM) has been used to compute near-continuum flow. Navier-Maxwell slip velocity conditions and Burnett-order deviatoric stress conditions were imposed on moving and stationary boundaries to capture Knudsen phenomena using a moment-based approach. Although the LBM does not compute Knudsen boundary layers, it can predict the slip flow regime outside of these





FIG. 10. Nondimensional pressure distribution $P = p/p_0$ along the cavity walls when Kn = 0.1 and Ma = 0.09. The Mizzi *et al.* [5] DSMC (line) and Navier-Stokes-Fourier (dashed) results are also shown.

boundary layers very well. This has previously been shown for pressure-driven microchannel flows using the moment-based approach by Reis and Dellar [16] and extended here to more complicated flows and boundaries. The influence of the Knudsen number on the behavior of the micro-lid-driven cavity has been examined, with the cross-channel velocity profiles flattening and the primary vortex creeping towards the cavity center as Kn increases.

Furthermore, the D2Q9 lattice Boltzmann can compute subtle kinetic phenomena in its non-conserved hydrodynamic moments, even though it does not capture Knudsen boundary layers. The pressure tensor embedded in the moments of the LBM approximates that of the BGK Boltzmann equation when the Mach number is small but fixed and the flow is isothermal with the equation of state $p = \rho RT$ [18,28,33]. Spurious numerical boundary layers in computations of the stress can appear in simple flows if constraints inconsistent with the pressure tensor are imposed, but these can be removed using the moment-based method. We remark that all results presented here converged under mesh refinement with fixed nondimensional numbers.

We have shown that the LBM can predict near-wall nonequilibrium phenomena in the pressure. Where simulations of the Navier-Stokes-Fourier equations over predict the pressure considerably, the LBM computations are in very good agreement with the DSMC results of Mizzi *et al.* [5]. While the model considered here does not include temperature, extending the methodology to thermal flows is a prospect for future work, and following Krastins *et al.* [32], the extension to other lattices in three dimensions is relatively straightforward.

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FIG. 9. Nondimensional pressure distribution $P = p/p_0$ along the cavity walls when Kn = 0.05 and Ma = 0.09. The Mizzi *et al.* [5] DSMC (line) and Navier-Stokes-Fourier (dashed) results are also shown.

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