Vesicle budding induced by binding of curvature-inducing proteins

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Vesicle budding induced by protein binding that generates an isotropic spontaneous curvature is studied using a mean-field theory. Many spherical buds are formed via protein binding. As the binding chemical potential increases, the proteins first bind to the buds and then to the remainder of the vesicle. For a high spontaneous curvature and/or high bending rigidity of the bound membrane, it is found that a first-order transition occurs between a small number of large buds and a large number of small buds. These two states coexist around the transition point. The proposed scheme is simple and easily applicable to many interaction types, so we investigate the effects of interprotein interactions, the protein-insertion-induced changes in area, the variation of the saddlesplay modulus, and the area-difference-elasticity energy. The differences in the preferred curvatures for curvature sensing and generation are also clarified.

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I. INTRODUCTION

In living cells, biomembranes have various shapes depending on their functions. Spherical vesicles, which are involved in endocytosis, exocytosis, and vesicle transports, are formed through membrane budding. Many types of proteins are known to be involved in such budding $[1-6]$. For example, clathrins assemble on a membrane and form a spherical bud with \approx 100-nm diameter; the clathrin-coated bud is then pinched off by dynamin and other proteins [\[5–9\]](#page-11-0).

To understand the bud-formation mechanism, many experiments have been conducted *in vitro* using giant liposomes. Buds can be induced by the area difference elasticity (ADE) in single-phase liposomes $[10-14]$, and by the separation of liquid-ordered and liquid-disordered phases in threecomponent liposomes [\[15–17\]](#page-11-0). Moreover, budding induced by polymer anchoring [\[18\]](#page-11-0) and binding of proteins such as clathrin [\[19\]](#page-11-0) and annexins [\[20\]](#page-11-0) has been observed. A contrasting mechanism involves bin-amphiphysin-rvs (BAR) superfamily proteins, which bend the membrane in one direction along its axis than in the other direction; thus, their binding generates cylindrical membrane tubes rather than spherical buds $[1-3,21,22]$. These curvature-inducing proteins also sense the local membrane curvature and exhibit preferred binding to membranes with their preferred curvatures. To investigate this curvature sensing, a liposome with a narrow membrane tube pulled by optical tweezers and a micropipette [\[23–26\]](#page-11-0) and different sizes of liposomes [\[27\]](#page-11-0) have been employed for various types of proteins.

Vesicle shape transformation has been numerically investigated using various types of coarse-grained membrane models. Budding has been simulated using dynamically triangulated membranes [\[28–](#page-11-0)[32\]](#page-12-0), meshless membranes [\[33\]](#page-12-0), dissipative particle dynamics [\[34,35\]](#page-12-0), phase-field models

[\[36\]](#page-12-0), and so on. Spontaneous tubule formation has been simulated by taking the membrane anisotropic spontaneous curvature into account [\[33,37–39\]](#page-12-0). However, in contrast with experiments, the simulated vesicle size is limited by the computational costs. In simulations, the vesicle-to-bud size ratio is typically less than 10, which is far less than that in the experiments on budding induced by protein binding, i.e., \approx 100.

In previous theoretical analyses of the budding [\[40–43\]](#page-12-0), a single bud in a flat membrane was typically considered; that is, the remaining vesicle area was regarded as a membrane reservoir. However, to understand the global vesicle shape in thermal equilibrium, the entire vesicle must be considered.

This study examines changes in vesicle shape in response to increased binding chemical potential using a mean-field theory. The entire vesicle is treated explicitly using a simplified geometry. Hence, the binding dependence on the membrane properties and various interactions between membrane and proteins and between proteins are clarified.

Protein binding to an arbitrarily shaped vesicle is described in Sec. II. The budding of a vesicle with a constant membrane area is examined in Sec. [III,](#page-2-0) with the effects of the saddlesplay-modulus difference and interprotein interactions being presented in Secs. [III B 2](#page-6-0) and [III B 3,](#page-7-0) respectively. The effects of the area changes due to the protein insertion and the ADE energy are examined in Secs. [IV](#page-8-0) and [V,](#page-8-0) respectively. Finally, the discussion and summary are presented in Secs. [VI](#page-10-0) and [VII,](#page-10-0) respectively.

II. LOCAL PROTEIN BINDING

Binding of proteins or other molecules to a membrane is considered because this binding modifies the membrane bending rigidity and spontaneous curvature. First, the case where the membrane area is unchanged by the binding is considered; that is, the proteins adsorb on the membrane surface, or the hydrophobic segments of the protein inserted into the membrane are so small that the area change is negligible. The

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free energy F of a vesicle consists of the bending energy $F_{\rm cv}$, binding energy, interprotein interaction energy, and mixing entropy:

$$
F = F_{\rm cv} + \int dA \left\{ -\frac{\mu}{a_{\rm p}} \phi + b\phi^2 \right\} \tag{1}
$$

+
$$
\frac{k_{\rm B}T}{a_{\rm p}} [\phi \ln (\phi) + (1 - \phi) \ln (1 - \phi)] \right\},
$$

$$
F_{\rm cv} = 4\pi \bar{\kappa}_d (1 - g) + \int dA \left\{ 2\kappa_d H^2 (1 - \phi) + 2\kappa_p (H - H_0)^2 \phi + (\bar{\kappa}_p - \bar{\kappa}_d) C_1 C_2 \phi \right\}, \tag{2}
$$

where *A* is the membrane area, ϕ is the local protein density $(\phi = 1$ at the maximum coverage), μ is the chemical potential of the protein binding, $k_B T$ is the thermal energy, C_1 and C_2 are the principal curvatures, and *H* is the mean curvature of each position $[H = (C_1 + C_2)/2]$. Here, subscript p indicates the bound-membrane quantities and a_p is the area covered by one protein (the maximum number of the bound proteins is A/a_p). The remaining terms are defined in the discussion below.

The membrane is in a fluid phase and $F_{\rm cv}$ is the second-order expansion to the curvature [\[44,45\]](#page-12-0). The bare (protein-unbound) membrane has bending rigidity κ_d with zero spontaneous curvature. The bound proteins are considered to be laterally isotropic (i.e., they have no preferred bending direction); hence, the bound membrane has a bending rigidity κ_p and finite spontaneous mean curvature H_0 , which is the half of the spontaneous curvature C_0 because $H_0 = C_0/2$. Here, H_0 is used instead of C_0 because $1/H_0$ is the radius of the spherical membrane to minimize the bending energy of the protein-bound membrane [the second term in the integral of Eq. (2) for $F_{\rm cv}$]. The first term of Eq. (2) represents the integral over the Gaussian curvature C_1C_2 with the saddlesplay modulus \bar{k}_d (also called the Gaussian modulus) [\[46\]](#page-12-0) of the bare membrane, where *g* is the genus of the vesicle. This type of bending energy for protein binding has been used in Refs. [\[32,47\]](#page-12-0), as well as for a cylindrical membrane with protein rods of anisotropic spontaneous curvature [\[48\]](#page-12-0).

In this study, $\kappa_d = 20k_BT$ and $\bar{\kappa}_d/\kappa_d = -1$ are used because they are typical values of lipid membranes. Since $\bar{\kappa}_p$ for the bound membrane is unknown, two cases are considered: $\bar{\kappa}_p = -\kappa_p$ and $\bar{\kappa}_p = \bar{\kappa}_d$. In the former case, the proteins have the same ratio to the bending rigidity as for the bare membrane. In the latter, the proteins do not change the saddle-splay modulus of the membrane. The former condition is considered in this work, unless otherwise specified (the latter condition is examined in Sec. [III B 2\)](#page-6-0).

The first term in the integral of Eq. (1) represents the protein binding energy. Under higher μ , more proteins bind to the membrane. The last two terms of Eq. (1) represent the pairwise interprotein interactions and the mixing entropy of the bound proteins, respectively. Proteins have repulsive or attractive interactions at $b > 0$ and $b < 0$, respectively. In addition to the direct interprotein interactions, the proteins interact with each other via membrane interactions (bending deformation, height mismatch, and Casimir-like interactions) [\[47,49–52\]](#page-12-0). Here, we consider only weak curvature-

FIG. 1. Schematic of the membrane. (a) Binding and unbinding of proteins to the membrane. (b) Budded vesicle. The buds and the large remaining vesicle have spherical shapes with radii of *R*bud and R_L , respectively. (c) Prolate vesicle approximated by cylinder combined with two hemispheres with radius R_{pro} and cylinder length L_{pro} .

independent interactions so that proteins are uniformly distributed in each component. Note that membrane-mediated interactions between soft objects such as proteins can be much weaker than hard objects [\[53\]](#page-12-0).

The interprotein interaction via the spontaneous curvature is also considered in this work. If proteins have large hydrophobic domains above the membrane, as depicted on the right side of Fig. $1(a)$, a repulsive interaction yields a positive spontaneous curvature [\[23\]](#page-11-0). Opposite (negative) curvature can be induced by an attractive interaction. In this study, linear dependence on the protein density is considered as a leadingorder approximation; i.e., H_0 is replaced by $H'_0 = H_0 + H_1 \phi$ in Eq. (2). The effect of this condition on a constant-area vesicle is discussed in Sec. [III B 3.](#page-7-0) For the other conditions, only constant spontaneous curvature $(H_1 = 0)$ is considered, for simplicity.

In thermal equilibrium, the protein density ϕ is locally determined for the given curvatures. When the interprotein interactions are negligible ($b = 0$ and $H_1 = 0$), ϕ is obtained from $\partial F/\partial \phi|_H = 0$ for a spherical membrane (*H* = *C*₁ = *C*₂) as a sigmoid function:

$$
\phi = \frac{1}{1 + \exp\left[\frac{a_p}{k_B T} (2\kappa_{\text{dif}} H^2 - 4\kappa_p H_0 H + \sigma_p)\right]},\tag{3}
$$

where $\kappa_{\text{dif}} = \kappa_{\text{p}} - \kappa_{\text{d}} + (\bar{\kappa}_{\text{p}} - \bar{\kappa}_{\text{d}})/2$ and $\sigma_{\text{p}} = -\mu/a_{\text{p}} + \sigma$ $2\kappa_{\rm p}H_0^2$. For $\kappa_{\rm dif} = 0$ and $H = 0$, this expression corresponds to Eq. (5) in Ref. $[54]$ and Eq. (4) in Ref. $[47]$, respectively. For a membrane with arbitrary curvature, the first energy term in the parentheses in Eq. (3) is replaced by $2(\kappa_p - \kappa_d)H^2 + (\bar{\kappa}_p - \bar{\kappa}_d)C_1C_2$. When interprotein interactions exist, ϕ is obtained by iteratively solving Eq. (3), while adding $2b\phi - 8\kappa_p (H - H_0)H_1\phi + 6\kappa_p H_1^2\phi^2$ within the parentheses. For a flat membrane $(H = 0)$ with $\phi = 0.5$ (i.e., the proteins bind to half of the membrane area),

$$
\mu = \left[\left(2H_0^2 + 4H_0H_1 + \frac{3}{2}H_1^2 \right) \kappa_p + b \right] a_p. \tag{4}
$$

Figure [2](#page-2-0) shows that the protein binding depends on the local membrane curvature. For a high curvature of H_0 or high rigidity of κ_p , the density ϕ changes steeply from 0 to 1 with a small increase in *H* [see Figs. $2(a)$ and $2(c)$]. Here, ϕ exhibits a maximum at $H = (\kappa_p / \kappa_{\text{dif}})H_0$ (given by $d\phi / dH =$ 0). This curvature dependence is called curvature sensing. In contrast, the free-energy minimum given by $dF/dH = 0$ is

FIG. 2. Protein density ϕ as a function of the local mean curvature *H* for a spherical membrane $(H = C_1 = C_2)$. The binding chemical potential μ is varied for $\kappa_p/\kappa_d = 3$ at (a) $H_0^2 a_p = 0.04$ and (b) $H_0^2 a_p = 0.01$. (c) The bending rigidity κ_p of the bound membrane is varied for $\mu = 0$ and $H_0^2 a_p = 0.01$.

 $H = [\kappa_p \phi / (\kappa_{\text{dif}} \phi + \kappa_d)] H_0$, because the membrane must bend together. Therefore, the curvature generated by the protein binding is lower than the preferred curvature for the curvature sensing, even for $\phi = 1$. For a cylindrical membrane, the preferred curvatures for the curvature sensing and generation are $H = [\kappa_{\rm p}/(\kappa_{\rm p} - \kappa_{\rm d})]H_0$ and $H = {\kappa_{\rm p}\phi/[(\kappa_{\rm p} - \kappa_{\rm d})\phi + \kappa_{\rm d}]}H_0$, respectively.

To close this section, two variants of the bending energy for protein binding are discussed. When proteins adhere to the membrane surface, as depicted on the left of Fig. $1(a)$, and the membrane composition beneath the proteins is unchanged by the binding, the bending energy can be expressed as

$$
F_{\rm cv} = 4\pi \bar{\kappa}_d (1 - g) + \int dA \left\{ 2\kappa_d H^2 + \left[2\kappa_{\rm pa} (H - H_{0a})^2 + \bar{\kappa}_{\rm pa} C_1 C_2 \right] \phi \right\}.
$$
 (5)

This bending energy is identical to Eq. [\(2\)](#page-1-0) with $\kappa_p = \kappa_{pa} + \kappa_d$, $\bar{\kappa}_{\rm p} = \bar{\kappa}_{\rm pa} + \bar{\kappa}_{\rm d}, H_0 = [\kappa_{\rm pa}/(\kappa_{\rm pa} + \kappa_{\rm d})]H_{0{\rm a}}$, and $\sigma_{\rm p} = -\mu/a_{\rm p} + \kappa$ $2\kappa_{pa}H_{0a}^2$. κ_{pa} is the bending rigidity of protein itself, while κ_p is the rigidity including the membrane beneath the protein. For a spherical membrane, the preferred curvatures for the curvature sensing and generation are $H = [\kappa_{pa}/(\kappa_{pa} + \bar{\kappa}_{pa}/2)]H_{0a}$ and $H = {\kappa_{pa} \phi / [(\kappa_{pa} + \bar{\kappa}_{pa}/2)\phi + \kappa_d]} H_{0a}$, respectively. This type of $F_{\rm cv}$ with $\bar{\kappa}_{\rm pa} = 0$ was used in Refs. [\[25,26,](#page-11-0)[43\]](#page-12-0).

In some previous studies $[24,54-57]$ $[24,54-57]$, the binding-induced modification of the bending rigidity was not accounted for,

and the following bending energy was used:

$$
F_{\rm cv} = \int dA \, \{ 2\kappa_{\rm d}(H - \phi H_0)^2 \}.
$$
 (6)

This corresponds to the condition of $\kappa_p = \kappa_d$, $\bar{\kappa}_p = \bar{\kappa}_d$, $b =$ $2\kappa_d H_0^2$, and $\sigma_p = -\mu/a_p$ in the present model. The preferred curvatures for the curvature sensing and generation are $H =$ ∞ and $H = \phi H_0$, respectively. In their model, neighboring proteins interact via the bending energy through $b = 2\kappa_d H_0^2$. Thus, this term has often been neglected [\[58,59\]](#page-12-0). Since the linear and quadratic terms of ϕ represent membrane-protein and interprotein interactions, respectively, they should be separately treated. As discussed above, the present model is generic and involves these two bending-energy models as the specific parameter sets.

III. BUDDED VESICLE WITH CONSTANT AREA

A. Free energy

We investigate budding of a vesicle induced by protein binding in thermal equilibrium. The vesicle has a spherical topology $(g = 0)$ with no pores. For this theoretical analysis, the vesicle is assumed to form n_{bud} buds, each with radius *R*bud. The remainder of the vesicle is assumed to form a spherical shape with a radius of R_L , as depicted in Fig. [1\(b\),](#page-1-0) with $R_L > R_{\text{bud}}$. The proteins have a positive spontaneous curvature $(H_0 > 0)$ such that they bind to the buds more than the remaining vesicle. In the absence of the proteins, the vesicle forms a prolate shape, which is approximated as shown in Fig. $1(c)$.

In this section, we consider that the membrane maintains a constant surface area, i.e., the protein binding does not change the membrane area [corresponding to the left protein in Fig. $1(a)$]. The protein densities at the large spherical component of the vesicle and at the buds are ϕ_L and ϕ_{bud} , respectively. The proteins are assumed to be homogeneously distributed in each region. The total membrane area $A = 4\pi R_0^2$ is kept constant; thus, the total bud area is given by

$$
\frac{A_{\text{bud}}}{4\pi} = n_{\text{bud}} R_{\text{bud}}^2 = R_0^2 (1 - r^2),\tag{7}
$$

where $r = R_L/R_0$. The volume *V* of the vesicle is fixed:

$$
V = \frac{4\pi}{3} (R_{\rm L}^3 + n_{\rm bud} R_{\rm bud}{}^3).
$$
 (8)

Using Eqs. (7) and (8) , the bud curvature can be expressed as

$$
\frac{R_0}{R_{\text{bud}}} = \frac{1 - r^2}{V^* - r^3},\tag{9}
$$

where $V^* = V/(4\pi R_0^3/3)$ is the reduced volume. The free energy *F* of the vesicle is given by

$$
F = F_{\rm L} + F_{\rm bud}, \tag{10}
$$
\n
$$
\frac{F_{\rm L}}{4\pi} = \bar{\kappa}_{\rm d} + 2(\kappa_{\rm dif}\phi_{\rm L} + \kappa_{\rm d}) - 4\kappa_{\rm p}H_0R_0r\phi_{\rm L}
$$
\n
$$
+ R_0^2r^2(\sigma_{\rm p}\phi_{\rm L} + b\phi_{\rm L}^2) + \frac{k_{\rm B}TR_0^2r^2}{a_{\rm p}}[\phi_{\rm L}\ln(\phi_{\rm L}) + (1 - \phi_{\rm L})\ln(1 - \phi_{\rm L})], \tag{11}
$$

$$
\frac{F_{\text{bud}}}{4\pi} = n_{\text{bud}} \Big\{ 2[(\kappa_{\text{p}} - \kappa_{\text{d}}) \phi_{\text{bud}} \n+ (\bar{\kappa}_{\text{p}} - \bar{\kappa}_{\text{d}}) (\phi_{\text{bud}} - s_{\text{neck}} \phi_{\text{L}}) + \kappa_{\text{d}}] \n- 4\kappa_{\text{p}} H_0 R_{\text{bud}} \phi_{\text{bud}} + R_{\text{bud}}^2 (\sigma_{\text{p}} \phi_{\text{bud}} + b \phi_{\text{bud}}^2) \n+ \frac{k_{\text{B}} T R_{\text{bud}}^2}{a_{\text{p}}} [\phi_{\text{bud}} \ln (\phi_{\text{bud}}) \n+ (1 - \phi_{\text{bud}}) \ln (1 - \phi_{\text{bud}})] \Big\} \qquad (12) \n= (1 - r^2) \Big\{ 2[(\kappa_{\text{p}} - \kappa_{\text{d}}) \phi_{\text{bud}} \n+ (\bar{\kappa}_{\text{p}} - \bar{\kappa}_{\text{d}}) (\phi_{\text{bud}} - s_{\text{neck}} \phi_{\text{L}}) + \kappa_{\text{d}}] \Big[\frac{1 - r^2}{V^* - r^3} \Big]^2 \n- 4\kappa_{\text{p}} H_0 R_0 \phi_{\text{bud}} \frac{1 - r^2}{V^* - r^3} + R_0^2 (\sigma_{\text{p}} \phi_{\text{bud}} + b \phi_{\text{bud}}^2) \n+ \frac{k_{\text{B}} T R_0^2}{a_{\text{p}}} [\phi_{\text{bud}} \ln (\phi_{\text{bud}})
$$

 $+(1 - \phi_{\text{bud}}) \ln (1 - \phi_{\text{bud}})]$ (13)

where $F_{\rm L}$ and $F_{\rm bud}$ are the free energies for the large spherical region and buds, respectively. In Eq. (13) , n_{bud} is treated as a real number. This is a reasonable assumption for $n_{\text{bud}} \gg 1$. For $n_{\text{bud}} < 10$, we treated n_{bud} as an integer, so that *r* is geometrically determined for each *n*bud, and *F*bud is calculated using Eq. (12) .

The neck region connecting a bud and the main spherical component (or connecting buds) has a saddle shape, with $H \simeq 0$. Since these necks have low curvature and small area, the influence of the integral of the mean curvature is negligible. However, it is necessary to examine the Gaussian curvature. The second term of Eq. (12) represents the integral of the Gaussian curvature of the bud and neck regions, where $s_{\text{neck}}\phi_L$ is the protein density of the neck region. At $s_{\text{neck}} = 1$, the necks have the same protein density as the main spherical component. This is reasonable because both regions have $H \simeq 0$. However, the necks have high principal curvatures ($\approx \pm 0.1$ nm⁻¹), which likely prevent large proteins from binding to them; that is, $s_{\text{neck}} = 0$. In general, $s_{\text{neck}} \in [0, 1]$. Here, $s_{\text{neck}} = 0$ is used, unless otherwise specified. The neck exerts a very small influence, as discussed in Sec. [III B 2.](#page-6-0)

The free energy *F* is a function of three variables: r , ϕ _L, and ϕ_{bud} . In the case of no interprotein interactions ($b = 0$ and $H_1 = 0$, *F* is expressed as a function of one variable, i.e., *r*, using Eq. [\(3\)](#page-1-0). Hence, the free-energy minimum is numerically determined by $dF/dr = \partial F/\partial r = 0$ [note that $\partial F/\partial \phi = 0$ for ϕ satisfying Eq. [\(3\)](#page-1-0)]. When the interprotein interactions exist, Eq. [\(3\)](#page-1-0) is iteratively solved. In this study, the iterations were repeated until the difference in ϕ was less than 10⁻⁸. Typically, fewer than 10 iterations were performed at $b \neq 0$ and $H_1R_0 \lesssim 100$.

The surface tension σ_d and the osmotic pressure Π can be imposed as a Lagrange multiplier to maintain the area and volume, respectively: $\tilde{F} = F_L + F_{\text{bud}} + \sigma_d A - \Pi V$. Then, σ_d and Π are determined from $\partial \vec{F}/\partial R_L|_{R_{\text{bud}},n_{\text{bud}}}=0$ and $\partial \breve{F}/\partial R_{\text{bud}}|_{R_{\text{L}},n_{\text{bud}}}=0$:

$$
\Pi = \frac{1}{R_{\rm L} - R_{\rm bud}} \left\{ 4\kappa_{\rm p} H_0 \frac{R_{\rm L} \phi_{\rm bud} - R_{\rm bud} \phi_{\rm L}}{R_{\rm L} R_{\rm bud}} + 2\sigma_{\rm p} (\phi_{\rm L} - \phi_{\rm bud}) + 2b (\phi_{\rm L}^2 - \phi_{\rm bud}^2) + \frac{2k_{\rm B} T}{a_{\rm p}} [\phi_{\rm L} \ln (\phi_{\rm L}) - (1 - \phi_{\rm L}) \ln (1 - \phi_{\rm L}) - \phi_{\rm bud} \ln (\phi_{\rm bud}) + (1 - \phi_{\rm bud}) \ln (1 - \phi_{\rm bud}) \right\}, \quad (14)
$$

$$
\sigma_{\rm d} = \frac{\Pi R_{\rm L}}{2} + \frac{2\kappa_{\rm p} H_0 \phi_{\rm L}}{R_{\rm L}} - \sigma_{\rm p} \phi_{\rm L} - b \phi_{\rm L}^2 - \frac{k_{\rm B} T}{a_{\rm p}} [\phi_{\rm L} \ln (\phi_{\rm L}) + (1 - \phi_{\rm L}) \ln (1 - \phi_{\rm L})] \qquad (15)
$$

$$
= \frac{\Pi R_{\rm bud}}{2} + \frac{2\kappa_{\rm p} H_0 \phi_{\rm bud}}{R_{\rm bud}} - \sigma_{\rm p} \phi_{\rm bud} - b \phi_{\rm bud}^2 - \frac{k_{\rm B} T}{a_{\rm p}} [\phi_{\rm bud} \ln (\phi_{\rm bud}) + (1 - \phi_{\rm bud}) \ln (1 - \phi_{\rm bud})]. \qquad (16)
$$

The first terms of Eqs. (15) and (16) represent the Laplace tension.

A prolate vesicle is modeled with a simple geometry using a combination of one cylinder and two hemispheres, as shown in Fig. $1(c)$. The surface area and volume of the vesicle are $A = 4\pi R_{\text{pro}}^2 + 2\pi R_{\text{pro}} L_{\text{pro}}$ and $V = (4\pi/3)R_{\text{pro}}^3 +$ $\pi R_{\text{pro}}^2 L_{\text{pro}}$, respectively; thus, the reduced volume is $V^* =$ $(1 + 3L_{\text{pro}}/4R_{\text{pro}})/(1 + L_{\text{pro}}/2R_{\text{pro}})^{3/2}$. The free energy is given by

$$
\frac{F_{\text{pro}}}{4\pi} = \bar{\kappa}_{\text{d}} + 2(\kappa_{\text{dif}}\phi_{\text{sp}} + \kappa_{\text{d}}) - 4\kappa_{\text{p}}H_{0}R_{\text{pro}}\phi_{\text{sp}} \n+ R_{\text{pro}}^{2}(\sigma_{\text{p}}\phi_{\text{sp}} + b\phi_{\text{sp}}^{2}) \n+ \frac{k_{\text{B}}TR_{\text{pro}}^{2}}{a_{\text{p}}}[\phi_{\text{sp}}\ln(\phi_{\text{sp}}) + (1 - \phi_{\text{sp}})\ln(1 - \phi_{\text{sp}})] \n+ \frac{L_{\text{pro}}}{2} \left\{ \frac{1}{2R_{\text{pro}}}[(\kappa_{\text{p}} - \kappa_{\text{d}}) \phi_{\text{cy}} + \kappa_{\text{d}})] - 2\kappa_{\text{p}}H_{0}\phi_{\text{cy}} \n+ R_{\text{pro}}(\sigma_{\text{p}}\phi_{\text{cy}} + b\phi_{\text{cy}}^{2}) \n+ \frac{k_{\text{B}}TR_{\text{pro}}}{a_{\text{p}}} [\phi_{\text{cy}}\ln(\phi_{\text{cy}}) + (1 - \phi_{\text{cy}})\ln(1 - \phi_{\text{cy}})] \right\}, (17)
$$

where ϕ_{cy} and ϕ_{sp} are the protein densities in the cylindrical and spherical regions, respectively. The expression well approximates the energy of the prolate vesicle. We determine the thermal equilibrium state (i.e., the lowest free energy *F*) by comparing *F* of budded vesicles and prolate.

comparing *F* of budded vesicles and prolate.
In this study, we consider the vesicle at $V^* > 1/\sqrt{2} \approx$ 0.707, in which a vesicle with one bud can exist ($R_{\text{bud}} = R_{\text{L}}$ at *V*. *V*/*(v*), in which a vesicle with one bud can exist ($R_{\text{bud}} = R_{\text{L}}$ at $V^* = 1/\sqrt{2}$). In this range, the prolate vesicle is the most stable state in the absence of the protein. We use $a_p = 100$ nm² and $R_0 = 10 \mu m$ for the area of proteins and the radius of giant liposomes, unless otherwise specified, i.e., $a_p/R_0^2 = 10^{-6}$.

FIG. 3. Chemical potential μ dependence of the protein densities in the vesicle and buds, ϕ_L and ϕ_{bud} , respectively, for (a) $H_0R_0 = 200$, (b) $H_0R_0 = 150$, and (c) $H_0R_0 = 100$ at $\kappa_p/\kappa_d = 3$, $V^* = 0.9$, and $b = H_1 = 0$. The solid lines represent thermal equilibrium states. The dashed lines represent the metastable and free-energy-barrier states.

B. Results

1. No interprotein interactions

First, we describe protein binding in the absence of the interprotein interactions ($b = 0$ and $H_1 = 0$). As μ increases, ϕ_{bud} increases, and, subsequently, ϕ_L increases, as shown in Fig. 3. At low H_0 , ϕ_{bud} continuously changes from 0 to 1 [see Fig. $3(c)$]. In contrast, at high H_0 , ϕ_{bud} exhibits a first-order transition. As the double minima of the free energy are shown in Fig. 4(a), metastable states exist around the transition point [see also the van der Waals loop depicted by the dashed lines in Figs. $3(a)$ and $3(b)$]. On the other hand, ϕ_L always exhibits a continuous change. Accompanied by the discrete change in ϕ_{bud} , n_{bud} and R_{bud} also discretely change, as shown in Figs. $4(b)$ and [5.](#page-5-0) Hence, around the transition point, the vesicles of small ϕ_{bud} for buds with large R_{bud} coexist with those having large ϕ_{bud} with small R_{bud} . At large μ , R_{bud} reaches the radius of curvature for the curvature generation R_{min} at $\phi_{\text{bud}} = 1$. Therefore, with increasing H_0 , the radius decreases as $R_{\text{bud}} \sim 1/H_0$, and the bud number increases as $n_{\text{bud}} \sim H_0^2$. The free-energy barrier between a small number

FIG. 4. Free-energy profiles for (a) the protein density in the buds ϕ_{bud} and (b) the bud curvature $R_{\text{min}}/R_{\text{bud}}$ at $H_0R_0 =$ 150, $\kappa_p/\kappa_d = 3$, $V^* = 0.9$, and $b = H_1 = 0$, where $R_{\text{min}} = (\kappa_{\text{dif}} +$ κ_d)/ κ_p *H*⁰ is the radius of the minimum bud curvature energy at $\phi_{\text{bud}} = 1$. From top to bottom, $\mu/k_B T = -1.7, -1.5,$ and -1.3 . The inset in panel (b) shows an enlarged plot at small $R_{\text{min}}/R_{\text{bud}}$, in which circles represent F at integer n_{bud} . The free-energy minimum is obtained at $R_{\text{min}}/R_{\text{bud}} = 0.0279$ ($n_{\text{bud}} = 3$), $R_{\text{min}}/R_{\text{bud}} = 0.891$ ($n_{\text{bud}} =$ 2737), and $R_{\text{min}}/R_{\text{bud}} = 0.919$ ($n_{\text{bud}} = 2908$) for $\mu/k_BT = -1.7$, -1.5 , and -1.3 , respectively.

of buds and many buds can be very high: $\Delta F \simeq 10^5 k_d$ and $5 \times 10^5 k_d$ for $H_0 R_0 = 150$ and 200, respectively, at $\kappa_p / \kappa_d =$ 3 and $V^* = 0.9$ (see Fig. 4 for $H_0R_0 = 150$). Although a free-energy barrier can exist for the single-bud formation depending on conditions $[40-43,60]$, this is much greater than the single-bud barrier, since more than 1000 buds are formed. Thus, the metastable states presented in this study can remain even on much longer timescales than the single-bud-formation period.

After the buds are almost covered by the proteins, the surface tension σ_d increases linearly. Furthermore, osmotic pressure Π increases first linearly and then saturates [see Figs. $5(c)$ and $5(d)$]. The vesicle ruptures when σ_d overcomes the lysis tension. This threshold is typically $1-25$ mN/m, depending on the membrane composition and conditions [\[61–63\]](#page-12-0). Since $\sigma_d = 10^7 k_B T / R_0^2$ corresponds to 0.4 mN/m,

FIG. 5. Chemical potential μ dependence of (a) the bud number n_{bud} , (b) the bud curvature $R_{\text{min}}/R_{\text{bud}}$, (c) the surface tension σ_d , and (d) the osmotic pressure Π for $H_0R_0 = 100$, 150, and 200 at $\kappa_p/\kappa_d =$ 3, $V^* = 0.9$, and $b = H_1 = 0$. The curvature radius of the minimum bud curvature energy is $R_{\text{min}} = (\kappa_{\text{dif}} + \kappa_d)/\kappa_p H_0$ at $\phi_{\text{bud}} = 1$.

the lipid membranes are not yet ruptured in the range shown in Fig. $5(c)$. However, protein binding (for transmembrane proteins in particular) may reduce the lysis tension and induce rupturing at a lower tension.

The dependencies on H_0 and κ_p/κ_d are clearly captured by the phase diagrams shown in Fig. 6. With increasing *H*0, the middle points $\phi_{\text{bud}} = 0.5$ and $\phi_{\text{L}} = 0.5$ shift to smaller and larger values, respectively. At $H_0R_0 \gtrsim 120$, the firstorder transition appears for $\kappa_p/\kappa_d = 3$ [see Fig. 6(a)]. With further increases in H_0 , the coexistence region widens. At a greater value of κ_p/κ_d , protein binding occurs at lower and higher values of μ for the buds and remaining region,

FIG. 6. Phase diagrams at $V^* = 0.9$ and $b = H_1 = 0$. (a) H_0 vs μ for $\kappa_p/\kappa_d = 3$. κ_p/κ_d vs μ for (b) $H_0R_0 = 200$ and (c) $H_0R_0 = 100$. Two states with small and large bud numbers coexist in the region between the two solid lines. The upper and lower dashed lines represent the states with $\phi_{\rm L} = 0.5$ and $\phi_{\rm bud} = 0.5$, respectively. The solid gray lines are given by Eq. [\(4\)](#page-1-0) and well overlay the data for $\phi_L = 0.5$.

respectively, and the first-order transition starts at lower H_0 [see Figs. $6(b)$ and $6(c)$]. For $H_0R_0 \gg 1$, the large spherical component of the vesicle can be approximated as a flat membrane; thus, μ for ϕ _L = 0.5 is well represented by Eq. [\(4\)](#page-1-0) for $H = 0$ (see the overlay of dashed lines and solid gray lines in Fig. 6). More precisely, the effect of the nonzero curvature is estimated as $-4\kappa_pH_0a_p/R_0$ from the second energy term in Eq. [\(3\)](#page-1-0); thus, the deviation is proportional to κ_p and *H*₀ and is less than 0.1 in Fig. 6. Moreover, the sigmoidal shapes of ϕ _L shown in Fig. [3](#page-4-0) are well represented by

$$
\phi_{\rm L} = \frac{1}{1 + \exp\left(-\frac{\mu - \mu_{\rm half}}{k_{\rm B}T}\right)}.\tag{18}
$$

The deviation from Eq. (18) is less than 10^{-5} for the data shown in Fig. [3.](#page-4-0) In contrast, the shape of ϕ_{bud} can be largely modified.

Figure [7](#page-6-0) shows the dependence on the reduced volume V^* . For smaller V^* , n_{bud} increases to hold the excess area,

FIG. 7. Dependence on reduced volume V^* at $\kappa_p/\kappa_d = 3$ and $b = H_1 = 0$. (a) Number n_{bud} of the buds for $V^* = 0.75$, 0.85, and 0.95 at $H_0R_0 = 150$. Inset shows magnified graph for small n_{bud} . (b) Chemical potential μ for the transition points for $H_0R_0 = 100$, 150, and 200. The solid lines represent the transition from the prolate to budded vesicle, having a single bud for $H_0R_0 = 100$ and 150, and many buds for $H_0R_0 = 200$. The dashed lines represent the shape transition from low ϕ_{bud} with small n_{bud} to high ϕ_{bud} with large n_{bud} at $H_0R_0 = 150$.

although no other notable differences are obtained for the vesicles with many buds. The chemical potential μ necessary for the transition to form many buds remains unchanged [see the dashed line in Fig. $7(b)$]. In contrast, μ required for the transition between the prolate to a single bud increases with increasing V^* [see the lower two solid lines in Fig. $7(b)$ and the inset of Fig. 7(a)]. For $H_0R_0 = 200$, the prolate vesicle transforms into many buds without forming a small number of buds, so that μ for the transition is independent of V^* [see the upper solid line in Fig. $7(b)$].

Figure 8 shows the dependence of ϕ_{bud} on the area ratio $a_{\rm p}/R_0^2$. The maximum number of bound proteins is $4\pi R_0^2/a_{\rm p}$. For smaller a_p (or a larger vesicle), buds develop more gently with increasing μ , since more proteins bind to the vesicle and generate greater mixing entropy. In contrast, ϕ_L is shifted to $2\kappa_{\rm p}H_0^2a_{\rm p}$, and the sigmoid function of μ is maintained (data not shown).

Finally, we examine the validity of the chosen vesicle shapes. First, the formation of a spherical bud on a prolate vesicle is considered. We calculated the free energy of a prolate vesicle with a single bud for the conditions used in Fig. 7 and confirmed the energy is always higher than the spherical vesicle with a single bud or many buds. Next, two sizes of the buds are allowed at $H_0R_0 = 150$ (the other condition is the same in Figs. [3–](#page-4-0)[5\)](#page-5-0). At the first-order transition point, the large

FIG. 8. Dependence of ϕ_{bud} on the area ratio a_{p}/R_0^2 at $H_0R_0 =$ 150, $\kappa_{p}/\kappa_{d} = 3$, $V^{*} = 0.9$, and $b = H_{1} = 0$. From top to bottom, $a_p/R_0^2 = 2 \times 10^{-6}$, 10^{-6} , and 5×10^{-7} . The dashed lines represent metastable and free-energy-barrier states.

buds of $R_{\text{min}}/R_{\text{bud}} = 0.0365$ and $n_{\text{bud}} = 5$ and the small buds of $R_{\text{min}}/R_{\text{bud}} = 0.891$ and $n_{\text{bud}} = 2733$ coexist. This large size of buds with a number of 2, 3, or 4 and many small buds are prepared as initial states, and then we performed the energy minimization for $-1.8 \le \mu/k_B T \le -1.2$. These two bud radii relax into the same value (the small or large sizes depending on the relaxation method and condition). Thus, the assumption that the buds have the same radius is reasonable.

2. Gaussian curvature

In this section, we examine the effects of the quantities related to the integral of the Gaussian curvature. First, the effects of the modulation of the saddle-splay modulus \bar{k} are discussed. When the protein does not modify $\bar{\kappa}$ ($\bar{\kappa}_p = \bar{\kappa}_d$), the coexistence region is reduced at $\mu < 0$ and begins at higher *H*₀, as shown in Fig. 9. Note that the phase diagrams shown in Fig. [6](#page-5-0) can represent the data for $\bar{\kappa}_p = \bar{\kappa}_d$ through rescaling with $\kappa'_{p} = (\kappa_{p} + \kappa_{d})/2$, $H'_{0} = (\kappa_{p}/\kappa'_{p})H_{0}$, and

FIG. 9. Effects of $\bar{\kappa}_p$ on the phase diagram for at $\kappa_p/\kappa_d = 5$, $V^* =$ 0.9, and $b = H_1 = 0$. Data for $\bar{\kappa}_p = \bar{\kappa}_d$ and $\bar{\kappa}_p = -\kappa_p$ are shown. Two states with a small and large number of buds coexist in the region between the two solid lines. The middle and lower dashed lines represent the states with $\phi_{\text{bud}} = 0.5$ at $\bar{\kappa}_{\text{p}} = \bar{\kappa}_{\text{d}}$ and $\bar{\kappa}_{\text{p}} = -\kappa_{\text{p}}$, respectively. The upper dashed lines for $\phi_L = 0.5$ and the upper boundary of the coexistence region overlay for two cases ($\bar{\kappa}_{\rm p} = \bar{\kappa}_{\rm d}$ and $\bar{\kappa}_{\rm p} = -\kappa_{\rm p}$).

FIG. 10. Effects of the relative coverage ratio s_{neck} of the neck region at $\kappa_p/\kappa_d = 3$, $V^* = 0.9$, and $b = H_1 = 0$. (a), (b) Enlarged graphs of the boundaries of the coexistence region for $s_{\text{neck}} = 0$ and 1 at $H_0R_0 = 150$. The dashed lines ($s_{\text{neck}} = 0$) correspond to the data shown in Fig. [3\(b\).](#page-4-0) Differences in (c) ϕ_{bud} and (d) ϕ_{bud} for $s_{\text{neck}} =$ 0 and 1 at $H_0R_0 = 100$, 150, and 200. The dashed lines in panels (c) and (d) represent free-energy-barrier states. Here, Eq. [\(13\)](#page-3-0) is used even for $n_{\text{bud}} < 10$.

 $\mu' = \mu + 2\kappa_p H_0^2 a_p (\kappa_p/\kappa_p' - 1)$. Thus, the phase behavior is qualitatively unchanged by the choice of the \bar{k} dependence.

Next, the dependence on protein binding in the bud-neck region is considered. When the necks have the same protein density as the large spherical component $(s_{neck} = 1)$, the boundary of the coexistence region slightly shifts to the right, as shown in Figs. $10(a)$ – $10(c)$, and ϕ_L slightly decreases around the inflection point (ϕ _L = 0.5), as shown in Fig. 10(d). Therefore, the effects of s_{neck} are so small as to be negligible.

3. Effects of interprotein interactions

Next, we consider the interprotein interactions. When *b* is negative or positive, protein binding is more or less promoted at large ϕ , such that the coexistence region widens or shrinks, respectively [see Figs. $11(a)$ and 12]. Note that the membrane can be separated into regions with large and small ϕ within the buds or the main spherical component at $b < -2k_BT/a_p$, in which F_{L} and F_{bud} can have double minima. However, because

FIG. 11. Dependence on protein pairwise interactions at $\kappa_p/\kappa_d =$ 3 and $V^* = 0.9$. (a) $ba_p/k_B T = -1$ and 2 at $H_0R_0 = 200$ and $H_1 =$ 0. (b) $H_1R_0 = 0$ and 100 at $H_0R_0 = 50$ and $b = 0$. The solid lines represent thermal equilibrium states. The two left and two right lines correspond to ϕ_{bud} and ϕ_{L} , respectively. The dashed lines represent metastable and free-energy-barrier states.

FIG. 12. Phase diagrams of *b* vs μ for (a) $H_0R_0 = 200$ and (b) $H_0R_0 = 120$ at $V^* = 0.9$, $\kappa_p/\kappa_d = 3$, and $H_1 = 0$. Two states with a small and large number of buds coexist in the region between the two solid lines. The dashed lines represent the states with $\phi_{\text{bud}} = 0.5$ or ϕ _L = 0.5. The solid gray lines are given by Eq. [\(4\)](#page-1-0) and well overlay the data for $\phi_{\rm L} = 0.5$.

FIG. 13. Phase diagram of H_1 vs μ for (a) $ba_p/k_BT = 1$ and (b) $b = 0$ at $H_0 R_0 = 50$, $\kappa_p / \kappa_d = 3$, and $V^* = 0.9$. Two states with a small and large number of buds coexist in the region between the two solid lines. The upper and lower dashed lines represent the states with $\phi_{\rm L} = 0.5$ and $\phi_{\rm bud} = 0.5$, respectively. The solid gray lines are given by Eq. [\(4\)](#page-1-0) and well overlay the data for $\phi_{\rm L} = 0.5$.

a homogeneous distribution is assumed for each component, such a phase-separation condition is not considered in this study.

For a nonzero value of H_1 , the spontaneous curvature increases from H_0 to $H_0 + H_1$ as ϕ increases from 0 to 1; thus, the coexistence region can appear with increasing H_1 [see Figs. [11\(b\)](#page-7-0) and 13].

The chemical potential μ for ϕ _L = 0.5 continues to satisfy Eq. [\(4\)](#page-1-0), as shown in Figs. [12](#page-7-0) and 13. However, the sigmoidal shape of ϕ _L is modified, because *b* and H_1 have greater influence at larger ϕ (see Fig. [11\)](#page-7-0). Therefore, when a significant deviation of ϕ _L from the sigmoid function of Eq. [\(18\)](#page-5-0) is observed, the interprotein interactions should be considered.

IV. AREA CHANGE DUE TO PROTEIN INSERTION

In this section, the changes in the membrane area induced by protein binding are considered. When the proteins have a transmembrane domain, as depicted on the right side of Fig. $1(a)$, the membrane area is increased by the protein insertion. Here, the area ratio of the transmembrane domain $\alpha \in [0, 0.6]$ is considered. Generally, lipid molecules are required to stabilize the membrane proteins, such that lipids remain between the proteins even under the most densely packed conditions. Although the vesicle area is changed by this behavior, the lipid membrane area remains at the initial value of $A_{lp} = 4\pi R_0^2$. Thus,

$$
R_0^2 = R_{\rm L}^2 (1 - \alpha \phi_{\rm L}) + \frac{A_{\rm bud}}{4\pi} (1 - \alpha \phi_{\rm bud}).
$$
 (19)

The vesicle volume is also fixed. Hence, Eqs. [\(7\)](#page-2-0) and [\(9\)](#page-2-0) are modified as

$$
\frac{A_{\text{bud}}}{4\pi} = \frac{R_0^2 [1 - r^2 (1 - \alpha \phi_{\text{L}})]}{1 - \alpha \phi_{\text{bud}}},
$$
(20)

$$
\frac{R_0}{R_{\text{bud}}} = \frac{1 - r^2 (1 - \alpha \phi_{\text{L}})}{(1 - \alpha \phi_{\text{bud}})(V_{\text{int}}^* - r^3)},
$$
(21)

where V_{int}^* is the reduced volume of the initial vesicle (no protein binding).

The free energy is given by

$$
\frac{F_{\rm L}}{4\pi} = \bar{\kappa}_{\rm d} + 2(\kappa_{\rm dif}\phi_{\rm L} + \kappa_{\rm d}) - 4\kappa_{\rm p}H_0R_0r\phi_{\rm L} \n+ R_0^2r^2(\sigma_{\rm p}\phi_{\rm L} + b\phi_{\rm L}^2) \n+ \frac{(1 - \alpha\phi_{\rm L})k_{\rm B}TR_0^2r^2}{(1 - \alpha)a_{\rm p}}[\phi_{\rm L}\ln(\phi_{\rm L}) \n+ (1 - \phi_{\rm L})\ln(1 - \phi_{\rm L})],
$$
\n(22)

$$
\frac{F_{\text{bud}}}{4\pi} = n_{\text{bud}} \left\{ 2(\kappa_{\text{dif}} \phi_{\text{bud}} + \kappa_{\text{d}}) - 4\kappa_{\text{p}} H_0 R_{\text{bud}} \phi_{\text{bud}} + R_{\text{bud}}^2 (\sigma_{\text{p}} \phi_{\text{bud}} + b\phi_{\text{bud}}^2) + \frac{(1 - \alpha \phi_{\text{bud}}) k_{\text{B}} T R_{\text{bud}}^2}{(1 - \alpha) a_{\text{p}}} [\phi_{\text{bud}} \ln (\phi_{\text{bud}}) + (1 - \phi_{\text{bud}}) \ln (1 - \phi_{\text{bud}})] \right\}
$$
(23)

$$
= 2(\kappa_{\text{dif}}\phi_{\text{bud}} + \kappa_{\text{d}}) \frac{\left[1 - r^2(1 - \alpha\phi_{\text{L}})\right]^3}{(1 - \alpha\phi_{\text{bud}})^3(V^* - r^3)^2} - 4\kappa_{\text{p}}H_0R_0\phi_{\text{bud}} \frac{\left[1 - r^2(1 - \alpha\phi_{\text{L}})\right]^2}{(1 - \alpha\phi_{\text{bud}})^2(V^* - r^3)} + \frac{R_0^2[1 - r^2(1 - \alpha\phi_{\text{L}})]}{1 - \alpha\phi_{\text{bud}}}\left(\sigma_{\text{p}}\phi_{\text{bud}} + b\phi_{\text{bud}}^2\right) + \frac{\left[1 - r^2(1 - \alpha\phi_{\text{L}})\right]k_{\text{B}}TR_0^2}{(1 - \alpha)a_{\text{p}}}\left[\phi_{\text{bud}}\ln\left(\phi_{\text{bud}}\right) + (1 - \phi_{\text{bud}})\ln\left(1 - \phi_{\text{bud}}\right)\right].
$$

The coefficients of the entropy terms are modified by the factors $(1 - \alpha \phi_L)/(1 - \alpha)$ and $(1 - \alpha \phi_{bud})/(1 - \alpha)$ to count the number of binding sites under the area change.

Figures [14](#page-9-0) and [15](#page-9-0) show the dependencies of various properties on α . With increasing α , the coexistence region shrinks [see Figs. $14(a)$ and [15\]](#page-9-0). Furthermore, V^* decreases with increasing ϕ _L at $\alpha > 0$, since the surface area is increased by the protein insertion [see Fig. [14\(c\)\]](#page-9-0). Accordingly, the sigmoidal shape of ϕ _L is slightly modified [see Fig. [14\(b\)\]](#page-9-0).

V. EFFECTS OF AREA-DIFFERENCE ELASTICITY

In this section, the effects of the area-difference elasticity (ADE) energy on the vesicle budding are considered. In lipid membranes, the flip-flop (traverse motion between monolayers) of lipids is very slow; the relaxation time of the phospholipids is several hours to days [\[64\]](#page-12-0). In contrast, amphiphilic molecules with small hydrophilic head groups such as cholesterols and diacylglycerols exhibit much faster

FIG. 14. Dependence of (a) ϕ_{bud} , (b) ϕ_{bud} , and (c) V^* on proteininsertion area ratio α at $H_0R_0 = 150$, $\kappa_p/\kappa_d = 3$, initial reduced volume $V_{\text{int}}^* = 0.9$, and $b = H_1 = 0$. The green, red, and blue lines represent the data for $\alpha = 0, 0.2,$ and 0.4, respectively. The dashed lines in panel (a) represent metastable states.

flip-flop (less than a minute) $[65–67]$. In living cells, proteins transport lipids in addition; flippases or floppases pump specific lipids in one direction (flip or flop, respectively) using ATP hydrolysis, yielding an asymmetric lipid distribution, whereas scramblases translocate lipids in both directions and relax the bilayer into a thermal-equilibrium lipid distribution [\[65\]](#page-12-0). Thus, the number of lipids in each monolayer can be fixed on timescales of typical *in vitro* experiments, although it can relax with the addition of cholesterols [\[68,69\]](#page-12-0), ultralong-chain fatty acids [\[70\]](#page-12-0), and scramblases. Hence, the area difference $\Delta A_0 = (N_{\text{out}} - N_{\text{in}})a_0$ preferred by lipids can be different from the area difference ΔA of the vesicle, where *N*out and *N*in are the numbers of lipids in the outer and inner monolayers, respectively, and a_0 is the area per lipid. In the ADE model $[10,11,71]$ $[10,11,71]$, the energy of this mismatch $\Delta A - \Delta A_0$ is taken into account by a harmonic potential:

$$
F_{\text{ade}} = \frac{\pi k_{\text{ade}}}{2Ah^2} (\Delta A - \Delta A_0)^2 = \frac{k_{\text{ade}}}{2} (m - m_0)^2, \quad (25)
$$

FIG. 15. Phase diagram of α vs μ for (a) $H_0R_0 = 150$ and (b) $H_0R_0 = 100$ at $\kappa_p/\kappa_d = 3$, $V^* = 0.9$, and $b = H_1 = 0$. Two states with a small and large number of buds coexist in the region between the two solid lines. The upper and lower dashed lines represent the states with $\phi_{\rm L} = 0.5$ and $\phi_{\rm bud} = 0.5$, respectively.

with the averaged curvature $m = (1/2R_0) \oint (C_1 + C_2) dA$. For typical lipid membranes, $k_{\text{ade}} \simeq \kappa$ has been reported [\[13\]](#page-11-0) $(q = \pi k_{\text{ade}}/\kappa)$ in the notation in Ref. [\[13\]](#page-11-0)).

The area differences of the budded and prolate vesicles are given by

$$
\frac{m_{\rm ves}}{4\pi} = r + n_{\rm bud} \frac{R_{\rm bud}}{R_0},\tag{26}
$$

$$
\frac{m_{\text{pro}}}{4\pi} = \frac{R_{\text{pro}}}{R_0} + \frac{L_{\text{pro}}}{4R_0},\tag{27}
$$

respectively. Here, the case of no flip-flop and $m_0 = m_{\text{pro}}$ is considered; that is, the initial prolate vesicle has no ADE penalty. This corresponds to an experimental condition on a timescale spanning minutes to a few hours, in the absence of sterols and proteins promoting flip-flop or forming membrane pores.

Figures [16](#page-10-0) and [17](#page-10-0) show the effects of the ADE energy. Here, μ becomes slightly larger to overcome the ADE energy, but the amount is less than $k_B T$. The influence on ϕ_L is negligibly small (data not shown). Thus, the effects can only be detected if the other parameters are well determined. Otherwise, the ADE energy can be neglected.

In the above analysis, it is assumed that the bound proteins do not change the preferred area difference m_0 between the two monolayers. However, some proteins may modify $m₀$ through the domain insertion into the membrane. When protein binding significantly increases $m₀$, the buds form at smaller μ and the phase boundaries shown in Fig. [17](#page-10-0) are likely shifted downward.

FIG. 16. Effects of the ADE energy on ϕ_{bud} at $H_0R_0 = 150$, $\kappa_{\rm p}/\kappa_{\rm d} = 3$, $V_{\rm int}^* = 0.9$, and $b = H_1 = 0$, The red and blue colors represent the data with and without the ADE energy, respectively.

VI. DISCUSSION

In this section, we discuss the experimental conditions for vesicle budding. Note that μ can be controlled by the buffer protein concentration ρ . For a dilute solution, it is given by $\mu = \mu_0 + k_B T \ln(\rho)$. Through screening of electrostatic interactions, μ also depends on the ion concentration.

Some proteins have large hydrophilic domains that can generate a repulsive interaction between them $(b > 0)$, and protein-density-dependent spontaneous curvature $(H_1 > 0)$.

FIG. 17. Effects of the ADE energy on phase diagrams at V^* = 0.9 and $b = H_1 = 0$. (a) Phase diagram of H_0R_0 vs μ for $\kappa_p/\kappa_d = 3$. (b) Phase diagram of κ_p/κ_d vs μ for $H_0R_0 = 150$. Two states with a small and large number of buds coexist in the region between the two solid lines. The dashed lines represent the states with $\phi_{\text{bud}} = 0.5$. The upper (red) and lower (blue) lines represent the data with and without the ADE energy, respectively.

The dependence of the spontaneous curvature on the length of the disordered hydrophilic domains has been investigated experimentally [\[27,](#page-11-0)[72\]](#page-12-0). The induced spontaneous curvature can be analytically represented using the conformational entropy of the chains [\[73–75\]](#page-12-0) and the excluded volume [\[57\]](#page-12-0). Although a linear dependence on the protein density was considered in this work, it can easily be extended to include a nonlinear dependence for a specific protein.

Many proteins have hydrophobic segments to insert the membrane. G-protein-coupled receptors and ion channels have wide transmembrane domains, some of which have been reported to sense and generate membrane curvature [\[26](#page-11-0)[,76\]](#page-12-0). For these proteins, the area change α due to protein binding should be considered. However, when the area change is small $(\alpha \ll 1)$, it can be neglected, because the α dependence is not sensitive. For example, the diameters of α HL are 10 nm and 1.2 nm at the head and transmembrane regions, respectively $(α \simeq 0.01)$ [\[77\]](#page-12-0). Thus, the αHL binding can be approximated as $\alpha = 0$. The area change due to shallow insertion of domains such as amphipathic α helix is also likely negligible. Some transmembrane proteins require the help of other proteins for membrane insertion. In the experiments of such proteins, the total number of proteins is rather fixed in the membrane. To investigate them, the present model can be modified to control the total number of proteins instead of the chemical potential.

Protein assembly can be induced by the interprotein attraction, as seen in the clathrin binding [\[9,19,](#page-11-0)[43,60\]](#page-12-0). To model this behavior, the line tension of the phase boundary should be incorporated into the model, and a constant protein density is used in the assembled domains. Moreover, the bound proteins may exhibit a conformational change or form a complex of several proteins through membrane-protein interactions, as depicted on the right side of Fig. $1(a)$. When different binding conformations coexist in significant amounts on the membrane in thermal equilibrium, multiple bound states can be considered. The present model is easily extended to this scenario, although many more parameters (the free-energy parameters for each state) must be determined.

Under some experimental conditions, the buds may be pinched off and form separated vesicles. Moreover, the membrane rupture may be caused by the high surface tension induced by protein binding. These dynamics can be taken into account by setting a threshold of the surface tension or the bud radius, which depends on the membrane composition and proteins.

VII. SUMMARY

We have studied vesicle budding using mean-field theory. First, we presented a formula for protein binding with an arbitrary curvature and clarified the preferred curvatures for curvature sensing and generation. The generation curvature is lower than the sensing curvature because the proteins are required to bend the membrane. Then, we presented the free energy of the budded vesicle, in which the protein binding can modify the spontaneous curvature, bending rigidity, saddle-splay modulus of the membrane. Moreover, interprotein interactions are included as direct interaction and protein-density-dependent spontaneous curvature. Furthermore, the changes in the membrane area due to the protein insertion and ADE energy are taken into account.

With increasing binding chemical potential μ , a prolate vesicle transforms into a budded vesicle. Subsequently, the number of buds increases and the bud radius is saturated to that for the curvature generation. The surface tension σ_d increases linearly to μ after bud formation. Furthermore, when high spontaneous curvature H_0 and/or large bending rigidity κ_p are induced by the protein binding, a first-order shape transition occurs between a vesicle with a small number of large buds and that with a large number of small buds. These two states coexist in a wider μ range for higher H_0 or larger κ_{p} . The attractive interaction between bound proteins and the spontaneous-curvature increase due to the protein contact promote budding and generate a wider coexistence region. In contrast, the area increase due to protein insertion reduces the coexistence region. When the preferred area difference between two monolayers is fixed at the initial prolate, the budding requires a slightly larger μ owing to the ADE energy.

In this study, we approximated that the budded vesicle consists of spheres. With the help of this simple geometry, the free-energy minimum could be determined so easily that additional terms could be considered. Hence, the effects of protein-membrane and interprotein interactions were examined. However, the proposed model can be extended to more complicated geometries. Under low σ_d , a flat membrane

can exhibit a separated-corrugated (SC) phase, in which the bound proteins form hexagonally ordered bowl-shaped domains, even in the absence of direct interprotein attractive interactions [\[47\]](#page-12-0). Hence, this SC phase may appear on a vesicle before budding or on a vesicle with a few buds. These bowl-shaped domains should be modeled into a simplified geometry to account for the SC phase.

Moreover, the present strategy can be used to examine other types of interactions, as discussed in Sec. [VI](#page-10-0) and extended to include other geometries. For example, BAR superfamily proteins can induce cylindrical membrane tubes from liposomes $[1-3,21,22]$. Recently, the formation of a nematic order coupled with the bending energy was investigated for a membrane with fixed shapes using a mean-field theory [\[78\]](#page-12-0). The stable shape of these membrane tubes that protrude from a vesicle is an interesting problem for further study. As discussed above, the model presented herein is a useful tool for investigating many problems related to vesicle deformation and can be further extended in various directions.

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