Size-stretched exponential relaxation in a model with arrested states

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We study the effect of a rapid quench to zero temperature in a model with competing interactions, evolving through conserved spin dynamics. In a certain regime of model parameters, we find that the model belongs to the broader class of kinetically constrained models, however, the dynamics is different from that of a glass. The system shows stretched exponential relaxation with the unusual feature that the relaxation time diverges as a power of the system size. Explicitly, we find that the spatial correlation function decays as $\exp(-2r/\sqrt{L})$ as a function of spatial separation r in a system with L sites in the steady state, while the temporal autocorrelation function follows $\exp[-(t/\tau_L)^{1/2}]$, where t is the time and τ_L proportional to L. In the coarsening regime, after time t_w , there are two growing length scales, namely $\mathcal{L}(t_w) \sim t_w^{1/2}$ and $\mathcal{R}(t_w) \sim t_w^{1/4}$; the spatial correlation function decays as $\exp[-r/\mathcal{R}(t_w)]$. Interestingly, the stretched exponential form of the autocorrelation function of a single typical sample in the steady state differs markedly from that averaged over an ensemble of initial conditions resulting from different quenches; the latter shows a slow power-law decay at large times.

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I. INTRODUCTION

Systems which are cooled rapidly often reach arrested states in which the kinetics is strongly constrained. Such systems then often show anomalously slow dynamics, manifested through slow decays of time-dependent correlation functions. A variety of forms is possible for such decays, but a form which is often encountered is that of a stretched exponential relaxation (SER)

$$\phi(t) \sim \exp(-t/\tau)^{\beta},\tag{1}$$

where $\phi(t)$ is an autocorrelation function over a time stretch t, the time τ sets the scale for the decay, and the stretching exponent β satisfies $0 < \beta < 1$. First observed in capacitor discharges by Kohlrausch [1] and subsequently by Williams and Watts in the context of dielectric relaxation [2], this form of decay has been found in a host of systems, some with quenched disorder and others without; representative systems are discussed in Sec. II.

Our focus in this paper is on the decay of the spin autocorrelation function $\phi(t)$ in a particular type of arrested state that arises in a one-dimensional (1D) Ising model with competing first- and second-neighbor interactions and conserved dynamics [3]. Competing interactions arise in magnetic rare earths through the Ruderman-Kittel-Kasuya-Yosida (RKKY) interaction [4]. Such interactions can also be realized in artificial spin chains [5] where one can experimentally reach the regime of interest in this paper (that is, a weak antiferromagnetic second-neighbor interaction). Competing interactions between close-by Ising spins in one dimension also arise in quite a different context, namely stacking dynamics in polytypes, where Ising pseudospins +1 and -1 are associated with cyclic and anticyclic *ABC* stackings, respectively [6]. The kinetics of stacking transitions such as 3C-6H [7,8] involves conservation laws in related competing-interaction spin models [9].

On quenching instantaneously from infinite temperature T to T = 0, the model considered in Ref. [3] is known to show a number of distinct types of arrested states, depending on the ratio of the coupling constants. The arrested state of interest to us here is one in which $\phi(t)$ follows Eq. (1) but with the exceptional feature that the relaxation time τ depends strongly on the system size L,

$$\tau = \tau_L \sim L^z. \tag{2}$$

We refer to relaxation characterized by Eqs. (1) and (2) as *size-stretched exponential relaxation* (SSER), to emphasize that the stretching depends on system size. As discussed in Sec. II, within the class of stretched exponential decays, SSER is uncommon and so far, to the best of our knowledge, only one other class of systems with this property has been identified.

It is interesting to ask about the qualitative physical features that give rise to SSER in the arrested state under study here. During the quench to T = 0, the system is able to anneal out most localized high-energy excitations, but a dilute gas of mobile excitations (domain walls) remains, whose number N varies sublinearly $\sim L^{\alpha}$ ($\alpha < 1$) and stays constant in time owing to a conservation law. The subsequent time evolution of the state involves microscopic moves which conserve energy and are consequently constrained by the local configurations of spins in the close vicinity. Thus the evolution rules fall within the class of kinetically constrained models (KCMs) [10–12] discussed in the next section. However, unlike KCMs studied earlier, these rules produce an SSER, as embodied in

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Eqs. (1) and (2), as a consequence of the number of excitations growing subextensively.

The main results of this work are as follows: (i) We show that the spatial correlation function in the steady state decays exponentially with a length scale varying as \sqrt{L} . (ii) For a rapid quench to zero temperature, the coarsening length scale $\mathcal{L}(t_w)$ at waiting time t_w varies as $t_w^{1/2}$. But there is also a second length scale $\mathcal{R}(t_w)$ which grows as $t_w^{1/4}$, and governs the decay of the two-point correlation function. (iii) The autocorrelation function in the steady state reached on starting with a typical initial condition shows a stretched exponential relaxation with the stretching exponent $\beta = 1/2$; the unusual feature is that the relaxation time depends on system size (SSER). When averaged over initial conditions, the autocorrelation function shows distinctly different behavior, namely SSER followed by a power-law decay.

The rest of the paper is organized as follows: A brief overview of stretched exponential decays in various systems is given in Sec. II. In Sec. III, we define the model along with the dynamical rules and also recall different types of arrested states which ensue on quenching the system to T = 0depending on parameter values. We discuss some aspects of the arrested state of interest in Sec. IV, while in Sec. V, we present quantitative results for statics and dynamics, including the coarsening regime. In Sec. VI, we obtain analytic results by relating our system to the simple exclusion process [13,14], and finally conclude in Sec. VII with a discussion of our results.

II. EARLIER WORK ON STRETCHED EXPONENTIAL DECAYS

In this section, we give a brief overview of different classes of models which show a stretched exponential decay of correlations [Eq. (1)] with a view to providing a context for our results.

A well-known mechanism that produces a stretched exponential decay involves averaging over different regions of the system, with individual exponential relaxations running in parallel. A suitable distribution of relaxation times can then lead to a stretched exponential form for the overall relaxation function [15,16]. In fact, as discussed in Sec. III B below, this mechanism also leads to SER in one of the possible arrested states (not the one of primary interest in this paper) in the model under study here. The dynamic heterogeneity picture of glassy materials, as discussed below, invokes and supports this mechanism for glassy relaxation [17]. In a variant, Palmer et al. [18] proposed a general mechanism where an individual region has an exponential relaxation, which, however, is hierarchically constrained. Trap models [19–24] consider the diffusion of excitations which reach randomly distributed static traps, in which case the long-time behavior is controlled by particle motion in large trap-free regions. Stretched exponential relaxation also arises in continuoustime random walks with a broad distribution of pausing times [15,25].

In the ordered phase of the 2D Ising model, the autocorrelation function exhibits SER arising from the relaxation of rare, long-lived droplets of the minority phase [26,27]. Rare clusters also dominate the $T \rightarrow 0$ dynamics of a 1D Ising ferromagnet with quenched disorder in the coupling, again leading to SER [28].

SER is one of the hallmarks of glassy dynamics [10,17]. Different theories, ranging from microscopic theories such as the mode-coupling theory (MCT) [29–31], to phenomenological theories such as the free volume theory [32] the Adam-Gibbs-DiMarzio theory [33,34], as well as the random first-order transition theory [35–37] have put forward mechanisms for such relaxations. Within these theories, the stretching exponent is related to the length scale of dynamic heterogeneity in the former, whereas it is related to the length scale of spatially correlated domains in the the latter class of theories.

A class of simple models, known as kinetically constrained models (KCMs) [10], have been proposed to understand some properties of a glassy system. A variety of KCMs have been studied in the last several decades [11,12,38,39], with the constraint in the dynamics being included in different forms, for instance, dynamics with local constraints such as the magnetization-conserving Kawasaki dynamics. In models with an infinite number of conservation laws, the configuration space divides up into an exponentially large number of sectors with different forms of slow relaxation, including sectors which exhibit stretched exponential decays [40]. Although these models show some glasslike features, the precise mechanism for SER in glassy systems remains unclear.

An interesting subclass of KCMs of particular relevance to the current work invokes the action triggered at a site by the arrival of diffusing entities, whose total number is conserved. Thus Glarum [41] and Bordewijk [42] argue that an SER with $\beta = 1/2$ describes relaxation of a molecule, caused by diffusing defects of the liquid structure reaching it. In another context, Skinner [39] studied a model of polymer dynamics, which was mapped onto a 1D Ising model. At low T, only energy-conserving moves are allowed, implying a conserved number of domain walls (DWs), resulting in local spin relaxation following an SER with $\beta = 1/2$. This form of SER was established rigorously by Spohn [43] who derived upper and lower bounds on τ in Eq. (1) in a model with a conserved number of DWs, while a generalized model was considered in Ref. [44]. In the arrested state studied in this paper, we will show that similar DW dynamics holds, but the result is an SSER with $\beta = 1/2$ and $\tau_L \sim L$.

We close this section by alluding to the only other example of SSER that we are aware of. Systems of particles with mutual exclusion driven by a fluctuating surface are known to exhibit fluctuation-dominated phase ordering (FDPO). The autocorrelation function of particle occupancies exhibits SSER. This result is supported by an analytic calculation of $\phi(t)$ for a related coarse-grained depth model [45] which exhibits SSER with $\beta = 1/4$ and $\tau_L \sim L^2$.

III. MODEL AND ARRESTED STATES

A. Hamiltonian and dynamics

We study the relaxation dynamics to, and in, an arrested state in a simple 1D model with competing interactions, namely the axial next-nearest-neighbor Ising (ANNNI) model [6,46]. We consider the ANNNI model on a 1D lattice with

periodic boundary conditions described by the Hamiltonian

$$\mathcal{H} = -J_1 \sum_{i=1}^{L} S_i S_{i+1} + J_2 \sum_{i=1}^{L} S_i S_{i+2}, \qquad (3)$$

where J_1 and J_2 are the coupling constants corresponding to the nearest- and the next-nearest-neighbor interactions, respectively, $S_i = \pm 1$ is an Ising spin variable at the *i*th site, and *L* is the size of the system. If the next-nearest-neighbor interaction is antiferromagnetic ($J_2 > 0$), it competes with the nearest-neighbor interaction J_1 , which could be either ferromagnetic or antiferromagnetic. In this study, we assume that $J_1 > 0$ and define $j = J_2/J_1$. The time evolution of the system proceeds through double-spin-flip (DSF) dynamics, wherein only pairs of adjacent parallel spins are flipped: $\uparrow \uparrow \leftrightarrow \downarrow \downarrow$.

Let us define the sublattice magnetizations as

$$M_{\text{even}} = \sum_{j=1}^{L/2} S_{2j}, \quad M_{\text{odd}} = \sum_{j=1}^{L/2} S_{2j-1}.$$
 (4)

The staggered magnetization, defined as the difference of the sublattice magnetizations, $\mathcal{M} \equiv M_{\text{even}} - M_{\text{odd}}$, evidently remains conserved as every DSF move changes both M_{even} and M_{odd} equally.

Under a transformation which flips every spin on the even sublattice, the nearest-neighbor coupling J_1 reverses its sign but J_2 does not. The DSF dynamics then maps into spinexchange or Kawaski dynamics $\uparrow \downarrow \leftrightarrow \downarrow \uparrow$. In other words, the DSF dynamics with the ferromagnetic nearest-neighbor interaction and antiferromagnetic next-nearest-neighbor interaction becomes equivalent to the Kawasaki dynamics with both the nearest-neighbor and next-nearest-neighbor interactions being antiferromagnetic. The two descriptions are thus equivalent; we use DSF throughout in this paper. It is simple to transcribe results to the Kawsaki dynamics description. For instance, single-point correlation functions such as spin autocorrelation functions remain unchanged, as do correlation functions between two sites on the same sublattice.

B. Arrested states

Consider performing an instantaneous quench to temperature T = 0 from an infinite-temperature random state. The T = 0 condition only allows those DSF moves which lead to a negative- or zero-energy change, as computed using the Hamiltonian, Eq. (3). Initially the system enters a coarsening regime in which both negative-energy change and zero-energy change moves occur, and the overall energy decreases as a result. Ultimately, this ceases when the system reaches the steady state (here, the arrested state), where only the zeroenergy change moves operate. The set of allowed DSF moves depends on the ratio of couplings j. There are five different regions along the j axis, each corresponding to a type of arrested state [3]. The local environment which affects the orientation of a pair of adjacent parallel spins consists of the nearest and next-nearest neighbors of these two spins. Since each spin can be either up or down, there is a total of 16 possible distinct local environments for a given pair of spins; these are listed in Ref. [3].

Each of the five arrested states has different characteristics. In particular, the arrested state which occurs when j > 1,

FIG. 1. An arbitrary spin configuration. The domains with even number of spins (E) ultimately get annihilated in the DSF dynamics whereas those with odd number of spins (O) cannot be annihilated. The curly lines depict domain walls, and an example of an E domain (eight blue spins, underlined with dots) and an O domain (three green spins with a solid underline) are shown.

called the inhomogeneous quiescent and active (IQA) state, was studied in detail in Ref. [3]. In this state, active and quiescent regions of varying lengths alternate in space. Each active region relaxes exponentially, with different relaxation times for each. This leads to an SER for the autocorrelation function $\sim \exp[-(t/\tau)^{\frac{1}{3}}]$ [3].

In this paper, we concentrate on a different arrested state which arises when $0 \le j < 0.5$. This state has an interesting structure, with large ferromagnetically ordered domains separated by mobile domain walls, whose number is conserved. This state with conserved mobile domain walls also shows a stretched exponential relaxation with the autocorrelation function decaying as $\sim \exp[-A(t/\tau_L)^{1/2}]$ but the mechanism behind this decay is quite different from that in the IQA state. Notably, while τ in the IQA state is *L* independent, in this state τ_L grows with system size $\sim L$, implying that the relaxation follows SSER. This is one of the main results of this paper. We now turn to a discussion of the properties and dynamics in this phase.

IV. DOMAIN WALL DESCRIPTION

Consider a quench from a completely disordered state to T = 0, in the coupling-constant range $0 \le j < 0.5$. The allowed moves are shown in Table I, where energy-lowering moves have been shown separately from equal-energy moves. The former lead to the approach to steady state, while the latter operate even in the arrested steady state, where they lead to nontrivial decays of spin autocorrelation functions.

Domain walls (DWs) separate successive parallel-spin segments and hence lie between every pair of adjacent parallel spin segments (Fig. 1). It is interesting to follow the fate of DWs under the DSF dynamics. Table I shows that (a) zero-energy moves correspond to a single DW moving by a distance 2a in each step, where a denotes the lattice spacing, (b) if two DWs are a distance 2a apart, a DSF move which flips the intervening pair of spins leads to the annihilation of both DWs and a concomitant lowering of the energy, and (c) if two DWs are a distance 3a apart, they cannot approach any closer.

Now consider two successive DWs as shown schematically in Fig. 1. Two cases arise. (i) If the separation between DWs is an even multiple of a, then they get annihilated at a long time. (ii) If the DWs are separated by an odd multiple of a, then it is not possible to annihilate these DWs, as shown in more detail in Sec. V B.

In view of (i) and (ii) above, we deduce that a succession of annihilations leads to the steady state with N domains, each containing an odd number of parallel spins; further, the minimum size of each domain is three. The question

TABLE I. Allowed moves (those that do not raise the energy) in the double-spin-flip dynamics for a quench to T = 0 from a high-temperature random initial configuration when $0 \le j < 0.5$.

Nature of the MC moves					ΔE
Energy lowering moves	(a)	$\uparrow \downarrow \uparrow \uparrow \downarrow \uparrow$	\rightarrow	$\uparrow \downarrow \; \downarrow \downarrow \; \downarrow \uparrow$	-4
	(b)	$\overline{\downarrow} \overline{\downarrow} \uparrow \uparrow \overline{\downarrow} \overline{\downarrow}$	\longrightarrow	$\overline{\downarrow} \overline{\downarrow} \downarrow \downarrow \downarrow \overline{\downarrow} \overline{\downarrow}$	-8(0.5 - j)
	(c)	$\overline{\uparrow} \overline{\uparrow} \uparrow \uparrow \overline{\downarrow} \overline{\uparrow}$	\rightarrow	$\overline{\uparrow} \overline{\uparrow} \downarrow \downarrow \overline{\downarrow} \overline{\uparrow}$	-4j
	(d)	$\overline{\uparrow} \overline{\downarrow} \uparrow \uparrow \overline{\downarrow} \overline{\downarrow}$	\rightarrow	$\overline{\uparrow} \overline{\downarrow} \downarrow \downarrow \overline{\downarrow} \overline{\downarrow}$	-4(1-j)
Zero-energy cost moves	(e)	$\overline{\uparrow} \overline{\uparrow} \uparrow \uparrow \overline{\downarrow} \overline{\downarrow}$	\longleftrightarrow	$\overline{\uparrow} \overline{\uparrow} \downarrow \downarrow \overline{\downarrow} \overline{\downarrow}$	0
	(f)	$\underline{\overline{\uparrow}} \underline{\overline{\downarrow}} \uparrow \uparrow \underline{\overline{\uparrow}} \underline{\overline{\downarrow}}$	\longleftrightarrow	$\underline{\overline{\uparrow}} \overline{\underline{\downarrow}} \downarrow \downarrow \underline{\overline{\uparrow}} \overline{\underline{\downarrow}}$	0

then arises: What is the typical value of N in the steady state of a system of size L? We observe that N is equal to the sublattice magnetization $\mathcal{M} \equiv M_{\text{even}} - M_{\text{odd}}$, defined in Sec. III, as each domain contributes unity to \mathcal{M} . Since \mathcal{M} is conserved by DSF dynamics its value can be deduced from the initial configuration. Since the initial state is purely random, \mathcal{M} has a binomial distribution from -L to L with zero mean and standard deviation \sqrt{L} for a system of size L. Therefore, the typical number of domains N in steady state is $\sim \mathcal{O}(\sqrt{L})$. On the other hand, if we start with a carefully designed random initial state with $\mathcal{M} = 0$, the system reaches a state with all spins either up or down and the dynamical rules in this regime at T = 0 forbid any dynamics in this state. We show the evolution of such a state in Appendix B.

Thus we arrive at the following simple description of the steady state. A conserved number N of DWs separate N domains, each with an odd number ≥ 3 of parallel spins. Each DW performs a random walk with a step length of 2a with the 'hard-core' constraint that the closest distance of approach of two successive walkers is 3a. The total number $\Omega(N, L)$ of allowed configurations with N walkers in a system of size L can be found by considering the distribution of L spins in N boxes, ensuring an odd number, at least 3, in each box. The result is $\Omega(N, L) = (2L/N) \binom{(L-N-2)/2}{(N-1)}$.

We now invoke the condition of detailed balance to show that in the steady state, every allowed configuration C is equally likely, and is given by $P_{ss}(C) = 1/\Omega(N, L)$. Since all allowed zero-energy moves occur at the same rate (Table I), we have $W(C \rightarrow C') = W(C' \rightarrow C)$, where $W(C \rightarrow C')$ is the rate from configuration C to C'. This implies $P_{ss}(C)W(C \rightarrow$ $C') = P_{ss}(C')W(C' \rightarrow C)$, which proves the assertion above.

Figure 2 illustrates features of the steady state and the approach to it. Figure 2(a) shows the time evolution of the system in the steady state on a large scale. The zoomedin version in Fig. 2(b) and successive collisions of two walkers (domain walls) shown in Fig. 2(c) illustrate the 3a hard-core constraint which operates between successive walkers. Figure 2(d) shows the evolution of the system during the approach to steady state, when annihilations of successive even-separation DWs occur. Finally, Fig. 2(e) shows the time evolution when DWs follow the rules of the simple exclusion process (SEP) [13,14]. We will argue below that our system resembles the SEP, which can then be used to deduce the time dependence of correlation functions at long times.

V. RESULTS

We now present the results of numerical simulations which quantitatively characterize the state with mobile domain walls. We begin with one of two initial configurations:

 (C_1) A configuration with spins at every site chosen at random, but subject to the constraint that the sublattice magnetization is \mathcal{M} , with \mathcal{M} even. The number of DWs in such a configuration is typically much larger than \mathcal{M} .

 (C_2) A configuration with an even number \mathcal{M} of domain walls placed at random, but subject to the constraint that every domain has an odd number *n* of spins with $n \ge 3$. As shown in Sec. IV, every configuration of this type occurs with equal probability in steady state.

Configurations of type C_1 are used for studies of coarsening, while configurations of type C_2 are appropriate for studies



FIG. 2. In all the subfigures, the vertical axis denotes increasing time and the horizontal axis denotes increasing site index. (a) A typical timeline of the arrested state, where black pixels are downspins, and gray pixels are up-spins. (b) A zoomed-in version of the timeline. (c) A timeline showing the hard-core interaction between walkers, where yellow pixels are the domain walls, and purple pixels are domains. (d) The system is still coarsening. Some annihilations of the domain walls are circled, where yellow pixels are the domain walls, and purple pixels are domains. (e) A typical timeline of the SEP-mappable Ising system, where black pixels are down-spins, and gray pixels are up-spins.



FIG. 3. Spin-spin spatial correlation functions in the steady state follow $\exp(-2r/\sqrt{L})$. (a) $C_{\rm SS}(r)$ vs r in linear scale. (b) Scaling collapse. $C_{\rm SS}(r)$ vs r/\sqrt{L} . Inset in (b): $C_{\rm SS}(r)$ vs r/\sqrt{L} in semilog scale. Each point is an average over 5000 histories.

of dynamics within steady state. At large enough times, an evolution starting with a C_1 configuration leads to a steady state configuration of type C_2 , as verified also by numerical simulations. In the simulations discussed below, we chose $\mathcal{M} = \sqrt{L}$, typical of a purely random state.

A. Static correlation function in steady state

As discussed above, we begin with a configuration of type C_2 with $\mathcal{M} = \sqrt{L}$. The correlation function in the steady state is defined as

$$C_{\rm SS}(r) = \frac{1}{L} \sum_{i=1}^{L} \langle S_i S_{i+r} \rangle, \qquad (5)$$

where $\langle \cdots \rangle$ denotes a steady state ensemble average. $C_{\rm SS}(r)$ is plotted in Fig. 3(a) for different system sizes *L*. Due to the presence of the \sqrt{L} -sized domains in the steady state, we expect $C_{\rm SS}(r)$ to decay exponentially with a length scale \sqrt{L} . Indeed, as shown in Fig. 3(b), plotting $C_{\rm SS}(r)$ as a function of r/\sqrt{L} leads to an excellent scaling collapse to a single master curve. The inset in Fig. 3(b) shows a straight line for the same plot on a semilog scale; this confirms the exponential behavior. As we show in Sec. VI, by relating the large-distance, long-time properties in the steady state of our model to that of a simple exclusion process (SEP), we find

$$C_{\rm SS}(r) = \exp\left(-\frac{2r}{\sqrt{L}}\right).$$
 (6)

Our simulation data support this analytical prediction.

Note in passing that our system displays long-range order (LRO) defined by

$$m_0^2 \equiv \lim_{r \to \infty} \lim_{L \to \infty} \langle S_i S_{i+r} \rangle.$$
(7)

Although ordered regions are not of order system size L as is customary, the fact that they are of order \sqrt{L} suffices to ensure that $m_0^2 = 1$.

B. Correlation function in coarsening regime

We next look at the coarsening following a sudden quench to T = 0 starting at t = 0 with a random initial configuration of type C_1 . Domain walls separated by ordered regions with an even number of spins diffuse until they are two lattice spacings apart, at which point they annihilate. Finally, the



FIG. 4. Spin-spin spatial correlation functions in the coarsening regime follow $\exp(-\Gamma r/t_w^{1/4})$. (a) $C(r, t_w)$ vs r in linear scale. (b) Scaling collapse. $C(r, t_w)$ vs $r/t_w^{1/4}$. Inset in (b): $C(r, t_w)$ vs $r/t_w^{1/4}$ in semilog scale. Each point is an average over 1000 histories in a system with L = 4096.

system approaches the steady state [see Fig. 2(d)] with $\mathcal{M} \sim \sqrt{L}$ domain walls.

In the coarsening regime, there are two length scales of relevance, each growing with a different power of the waiting time t_w . The first is $\mathcal{L}(t_w)$, the length scale below which the system has achieved a quasiequilibrium. Here, $\mathcal{L}(t_w)$ is the typical separation between two even-sized domains, and considering the diffusive nature of the process which leads to the annihilation of even domains, we have $\mathcal{L}(t_w) \sim t_w^{1/2}$. Now each such equilibrated stretch holds a large number of DWs separating odd-sized domains. The second length scale of relevance is $\mathcal{R}(t_w)$, the mean separation of these DWs, which scales as $\sqrt{\mathcal{L}(t_w)}$ and determines the decay of the two-point correlation function. Evidently we have $\mathcal{R}(t_w) \sim t_w^{1/4}$, so we expect the correlation function in the coarsening regime to follow

$$C(r, t_w) = \exp\left(-\frac{\Gamma r}{t_w^{1/4}}\right),\tag{8}$$

where Γ is a constant. Figure 4(a) shows the correlation function $C(r, t_w)$ as a function of r after a quench from the random configuration to T = 0 for four different values of t_w for a system with L = 4096. Figure 4(b) shows that when $C(r, t_w)$ is plotted as a function of $r/t_w^{1/4}$, a very good data collapse is obtained at large values of t_w , confirming the scaling prediction, Eq. (8). The inset of Fig. 4(b) shows the same plot in semilog scale, clearly showing a better collapse for larger values of t_w . We provide a detailed description of the coarsening dynamics in Appendix A.

C. Autocorrelation function in steady state

The spin-spin autocorrelation function $\phi(t)$ in the steady state is defined as

$$\phi(t) \equiv \frac{1}{L} \sum_{i} \langle S_i(t_0) S_i(t_0 + t) \rangle - \langle S_i(t_0) \rangle^2, \qquad (9)$$

where $\langle \cdots \rangle$ represents an average over t_0 . As already discussed, in the steady state, there are $\mathcal{M} = (\sqrt{L})$ domains and an equal number of DWs, with a hard-core repulsion between successive DWs [see Fig. 2(c)]. Each DW performs a random walk through the energy-conserving moves alone as listed



FIG. 5. Spin-spin autocorrelation functions in the steady state follow $\exp[-A(t/L)^{1/2}]$. (a) $\phi(t)$ vs t in linear scale in the steady state with exactly \sqrt{L} domain walls. (b) Scaling collapse. $\phi(t)$ vs $(t/L)^{1/2}$ for the same set of data presented in (a). The line is a fit of Eq. (10) that yields A = 4.6. Inset: $\phi(t)$ vs $(t/L)^{\frac{1}{2}}$ in semilog scale. Each point is an average over at least 5000 histories and in some cases it is substantially larger, for instance, 10^5 for the smallest L. (c) Evolution of $\phi(t)$ as a function of $(t/L)^{1/2}$ with a different number of DWs as quoted in the legend and L = 2048. (d) The coefficient A in Eq. (10) increases linearly with the number of DWs. Symbols are results obtained from fitting Eq. (10) with simulation data of a system of size L = 2048 and the line is a fit $A(x) = \kappa x$ with $\kappa = 0.11$.

in Table I. This feature leads to the conservation of \mathcal{M} , a dynamical constraint in the steady state.

From simulation, we find that $\phi(t)$ shows stretched exponential relaxation in the steady state,

$$\phi(t) = \exp\left[-A\left(\frac{t}{L}\right)^{\frac{1}{2}}\right],\tag{10}$$

where A is a constant. We plot $\phi(t)$ as function of t for different system sizes L in Fig. 5(a). We obtain excellent data collapse when we plot $\phi(t)$ as a function of $(t/L)^{1/2}$ as shown in Fig. 5(b). The inset shows the same data on a semilog scale where it is expected to be a straight line at large $(t/L)^{1/2}$. The coefficient A in Eq. (10) depends on the number N of DWs present in the system; our simulations show that A varies linearly with N [Fig. 5(d)]. Since the DSF dynamics does not annihilate DWs in the steady state, N is determined by the sublattice magnetization \mathcal{M} of the random initial state. For convenience of simulation, we generate steady state configurations with precisely $N = \sqrt{L}$ DWs and take an average over these configurations, which is equivalent to averaging over t_0 . From a fit of Eq. (10) with the simulation data we obtain $A \simeq 4.6$.

D. Ensemble average of autocorrelation function

Consider performing successive quenches from the $T = \infty$ state, and averaging the autocorrelation function over the

ensemble of steady states reached, which in general have different numbers N of DWs. Since the number of DWs in a steady state is conserved, it follows that an average over this ensemble and an average over t_0 for a particular value of N need not be the same. In fact, as we show below, there are significant differences, especially at large times.

We define the ensemble average of the autocorrelation function q(t) in steady state,

$$q(t) = \overline{\phi(t)} = \frac{1}{L} \sum_{i} \langle S_i(t_0) S_i(t_0 + t) \rangle - \langle S_i(t_0) \rangle^2, \quad (11)$$

where $\overline{\mathcal{O}}$ defines the ensemble average of \mathcal{O} . Starting from a random initial condition, the number of DWs in steady state has a distribution, given as

$$P(N) = \sqrt{\frac{2}{\pi L}} \exp\left[-\frac{N^2}{2L}\right],$$
 (12)

where $N (\ge 0)$ is the number of DWs. We saw in Sec. V C that the coefficient A in Eq. (10) increases linearly with the number of DWs, whose typical number is of the order of \sqrt{L} , as can be seen from Eq. (12). Therefore, we write $A = A_0 N / \sqrt{L}$, where A_0 is the typical value of A. Averaging over N, we obtain q(t)as

$$q(t) = \sqrt{\frac{2}{\pi L}} \int_0^\infty \exp\left[-\frac{N^2}{2L}\right] \exp\left[-\frac{A_0 N t^{1/2}}{L}\right]$$
$$= \exp\left[\frac{A_0^2 t}{2L}\right] \operatorname{erfc}\left(A_0 \sqrt{\frac{t}{2L}}\right). \tag{13}$$

At short times $t \ll L$, Eq. (13) reduces to $q(t) \approx [1 - A_0\sqrt{2/\pi}(t/L)^{1/2}]$, which is consistent with Eq. (10). On the other hand, at long times $t \gg L$, we may use the asymptotic form $\operatorname{erfc}(x) \sim \exp(-x^2)/\sqrt{\pi}x$ to obtain $q(t) \approx \sqrt{2/\pi A_0^2}(t/L)^{-1/2}$. Figure 6 shows the very good agreement of Eq. (13) with simulation results for q(t). For comparison, the figure also shows the decay of $\phi(t)$ for a single typical configuration with L = 2048 and \sqrt{L} number of DWs. We see that there is a significant difference at long times: While $\phi(t)$ exhibits SSER throughout, q(t) shows a slow power-law decay at long times t. This difference arises as at large t, there is always a fraction of members of the ensemble (those with $A_0N/L^2 \ll t$) which would have decayed very little, and would contribute strongly to q(t).

VI. RELATION TO THE SIMPLE EXCLUSION PROCESS

From the coarse-grained point of view, in the steady state the system consists of $\mathcal{M} = \sqrt{L}$ domains separated by diffusing DWs with a no-crossing constraint. We expect that microscopic details, such as the odd number of spins in each domain, the domain walls moving in steps of two lattice spacings, and the minimum possible distance between the walls being three lattice spacings should not matter for largeseparation or long-time properties.

The DW dynamics should then be well approximated by the simple exclusion process (SEP) that describes a system of identical particles with hard-core repulsion moving on a



FIG. 6. Simulation data for the autocorrelation function q(t) averaged over the ensemble of initial states, plotted for different *L* as noted in the figure. Equation (13) gives the form of a master curve when q(t) is plotted as a function of t/2L. The figure shows that the numerical data agrees well with the plot of Eq. (13) with $A_0 = 4.6$. Also plotted in the figure is the autocorrelation function $\phi(t)$ starting with a single, typical configuration with L = 2048 and \sqrt{L} DWs. Notice that q(t) decays much slower than $\phi(t)$ at long times. Each point is an average over at least 5000 histories.

lattice [13,14]. Each particle attempts to move to its nearestneighbor sites with equal probability; the move is implemented if the site in question is not already occupied. The dynamics in our arrested system in steady state resembles that of an Ising spin chain with a number \sqrt{L} of alternating domains, evolving with the rule that a single spin can flip only if the two neighboring spins are mutually antiparallel. Such spins are necessarily at the boundaries of the domains. The spin system is related to the SEP through the relation $\eta_{i+1/2}(t) = \frac{1}{4} [S_i(t) - S_{i+1}(t)]^2$, where $\eta_{i+1/2} = 1$ if there is a DW (which represents a particle in the SEP) between sites i and i + 1, and 0 otherwise. A particular snapshot of the simulation of this system is presented in Fig. 2(e). As expected, with increasing system size, the details of the original arrested steady state become irrelevant and the behaviors of the original and the new system converge. Thus, we consider a system that has \sqrt{L} DWs which perform random walks but cannot cross each other-a SEP with a subextensive number of particles.

A similar system was considered in Refs. [39,43,44], but with the important difference that the number of DWs was proportional to *L*. In that case, the autocorrelation function follows $\phi(t) \sim \exp[-(t/\tau)^{1/2}]$ where upper and lower bounds derived in Ref. [43] imply that τ remains finite in the limit $L \to \infty$. For the system of interest in this work, the density of domain walls, $\rho = 1/\sqrt{L} \to 0$ as $L \to \infty$, which leads to τ being proportional *L*, while the exponent β of the SER as well as the linear dependence of *A* in Eq. (10) on the number of DWs remain the same.

We now turn to the analytic derivations of the spatial correlation and temporal autocorrelation functions in the steady state, using the independent interval approximation (IIA) [47,48]. Spatial correlation function. The spatial correlation function $C_{SS}(r)$ can be written as

$$C_{\rm SS}(r) = \sum_{n=0}^{\infty} (-1)^n p_n(r), \qquad (14)$$

where $p_n(r)$ is the probability that a segment of length *r* has exactly *n* domain walls. If domains are drawn independently from a common distribution P(l), the correlation function in Laplace space, $\tilde{C}(s) = \int_0^\infty C_{\rm SS}(r)e^{-sr}dr$, can be written as

$$\tilde{C}(s) = \frac{1}{s} - \frac{2}{\langle l \rangle s^2} \frac{1 - \tilde{P}(s)}{1 + \tilde{P}(s)},$$
(15)

where $\tilde{P}(s)$ is the Laplace transform of P(l) and $\langle l \rangle$ is the average domain size. For large *L*, the probability that a domain is of length *l* is given by $P(l) = (1 - \rho)^l \rho$, where $\rho = \sqrt{L}/L = 1/\sqrt{L}$ is the density of the domain walls. For large *l*, we have $P(l) \approx \rho e^{-\rho l}$, which gives us $\langle l \rangle = \sqrt{L}$ and $\tilde{P}(s) = \frac{\rho}{s+\rho}$. Using these relations in Eq. (15), we get

$$\tilde{C}(s) = \frac{1}{s + \frac{2}{\sqrt{L}}}.$$
(16)

Inverting the Laplace transform gives us (6).

Autocorrelation function. We now argue that the temporal autocorrelation function $\phi(t)$ can be found similarly by focusing on the time segments between successive returns of a DW, noting that each sign change of the spin is associated with such a return of the DW. Thus, in analogy with Eq. (14), we write

$$\phi(t) = \sum_{n=0}^{\infty} (-1)^n p_n(t), \qquad (17)$$

where $p_n(t)$ now stands for the probability that there are *n* returns to the origin in a time stretch *t*. The probability that a random-walking DW first returns to its starting point at time *t* follows $P_{\text{return}}(t) \sim t^{-3/2}$ [49], assuming that the DW performs an unhindered random walk. This would be expected to hold up to a time t_{coll} , which is of order the typical collision time between successive walkers. Since the mean spacing between walkers is \sqrt{L} , we expect t_{coll} to be proportional to *L*.

Since successive returns to the origin for a free random walk are independent events, within the time $t_{coll} \sim L$, we use the IIA to make further progress. Note that the mean return time τ within t_{coll} is $\tau = 2\sqrt{L}$ and that the Laplace transform of $P_{return}(t)$ is $\tilde{P}(s) \sim 1 + \Gamma(-\frac{1}{2})\sqrt{s}$. We now use Eq. (15), replacing $\tilde{C}(s)$ by $\tilde{\phi}(s)$ [the Laplace transform of $\phi(t)$] and $\langle l \rangle$ by τ . We obtain the small-*s* behavior of $\tilde{\phi}(s)$ as

$$\tilde{\phi}(s) \approx \frac{1}{s} - \frac{2\sqrt{\pi}}{\tau} s^{-3/2}.$$
(18)

Performing the inverse Laplace transform, we find

$$\phi(t) \approx 1 - 2\left(\frac{t}{L}\right)^{1/2},\tag{19}$$

which, for small values of t/L, coincides with the size-stretched exponential form Eq. (10).

VII. CONCLUSION

We have studied the relaxation properties of a system in an arrested state in which the dynamics involves a conserved number of interacting, diffusing excitations. The key point which underlies the unusual behavior of the system is that the number of excitations grows subextensively with the system size. This ultimately leads to the feature of SSER in the autocorrelation function in the steady state, namely stretched exponential decay with a relaxation time that diverges with growing system size. It also leads to an unusual feature in the coarsening dynamics describing the approach to the steady state, namely the existence of two length scales, each growing with a different power of the time. Further, the characteristic time-dependent behavior of a single typical sample differs markedly from the average behavior over an ensemble of initial conditions.

We demonstrated these properties in the ANNNI model with double-spin-flip dynamics that conserves the staggered magnetization. For a range of parameters, a rapid quench from a disordered state towards zero temperature leads to an arrested steady state with a conserved number of domain walls separating domains with an odd number of parallel spins. In the steady state, the dynamics is governed by energyconserving moves, under which domain walls diffuse but respect a no-crossing constraint. In a system of size L, we showed that the spatial correlation function decays exponentially with a length scale that varies as \sqrt{L} and the system exhibits long-range order. The autocorrelation function in the steady state displays a stretched exponential relaxation with the stretching exponent $\beta = 1/2$. The noteworthy feature is that the relaxation time depends on L. The form of relaxation of a single typical sample in steady state differs markedly from that averaged over an ensemble of initial conditions resulting from different quenches. The latter shows a slow power-law decay at large times, reflecting the propensity of systems with a low value of N to relax very slowly.

In the coarsening regime, the size of odd-spin domains grows as $t_w^{1/4}$, whereas the typical separation between evensized domains grows as $t_w^{1/2}$. This pattern of growth continues indefinitely in an infinite system, but in a finite system of size L, as $t_w \to \infty$, the number of even-sized domains vanishes, while the number of odd-sized domains approaches \sqrt{L} , characteristic of the steady state.

For large-distance long-time properties in the steady state, our system resembles an Ising system where the dynamics involves only energy-conserving moves [39,43,44], insofar as domain walls move diffusively in the steady state and respect a no-crossing constraint in both systems. But the analogy cannot be extended too far. For instance, in the coarsening regime, the occurrence of two distinct diverging length scales in our system (in contrast to the single diverging length in the Ising model) can be traced ultimately to the competing interactions of the ANNNI model along with the conservation law implied by double-spin-flip dynamics.

The dynamics in the arrested steady state studied in this paper is constrained since we consider dynamic evolution at T = 0 and allow only energy-conserving moves. In this sense, our system belongs to the class of kinetically constrained models (KCMs) that have been studied earlier in the context

of glass. As in several KCMs, our system too shows stretched exponential relaxation. But there are a couple of distinctive features: First, the relaxation time diverges as a power of the system size, corresponding to SSER, and second, the average over the ensemble of initial conditions yields a form of relaxation which is quite different from that of a single sample. It would be interesting to identify such features in other KCMs as well.

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APPENDIX A: DETAILS OF THE COARSENING DYNAMICS

Below we discuss key characteristics of the approach to the steady state, based on a detailed consideration of domain dynamics. As discussed in Sec. IV, domains with an even number of spins (denoted E) get annihilated at long times, and in steady state we are left only with domains with \uparrow and \downarrow spins are denoted as E_{\uparrow} and E_{\downarrow} and odd domains with \uparrow and \downarrow spins as O_{\uparrow} and O_{\downarrow} , respectively. The time evolution starting from an arbitrary initial configuration is shown in Fig. 7(a), where black and red refer to O_{\uparrow} and O_{\downarrow} , respectively, and green and blue refer to E_{\uparrow} and E_{\downarrow} , respectively.

We now turn to a discussion of domain dynamics.

(i) The number of *E* domains $\mathcal{N}_E(t_w)$ decreases as $t_w^{-1/2}$, as shown in Fig. 7(b) for four different system sizes. $\mathcal{N}_E(t_w)$ is expected to be proportional to system size *L* and therefore $\mathcal{N}_E(t_w)/L$ should follow a master curve as shown in Fig. 7(c).

(ii) The length scale $\mathcal{L}(t_w)$, defined as the separation between two successive *E* domains, varies as $t_w^{1/2}$ as shown in Fig. 7(d).

(iii) During coarsening, the system has equilibrated within the length scale $\mathcal{L}(t_w)$, which typically contains several *O* domains. In equilibrium, there are typically \sqrt{L} number of odd domains in a system of size *L*. Therefore, we expect the number of *O* domains during coarsening to vary as $\sqrt{\mathcal{L}(t_w)}$. Thus, their average number $\mathcal{N}_O(t_w)$ decreases as $t_w^{-1/4}$, as shown in Fig. 7(e), and the average *O* domain length $\xi(t_w)$ increases as $t_w^{1/4}$, as shown in Fig. 7(f).

(iv) The decrease of $\mathcal{N}_O(t_w)$ shows that some O domains get annihilated during coarsening. To understand how this happens, consider a particular configuration $O_{\downarrow}E_{\uparrow}O_{\downarrow}$. The number of spins in E_{\uparrow} decreases through a succession of double spin flips until it reduces to width two, following which E_{\uparrow} is annihilated. The two O_{\downarrow} domains then join and create a single E_{\downarrow} domain as highlighted in the region A in Fig. 7(a).

(v) There are two separate mechanisms by which *E* domains get annihilated: (a) Consider a configuration $O_{\downarrow}E_{\uparrow}E_{\downarrow}$. When E_{\uparrow} is annihilated, the entire domain becomes O_{\downarrow} as highlighted in the region B in Fig. 7(a). (b) If there are successive *E* domains, such as $E_{\downarrow}E_{\uparrow}E_{\downarrow}$, annihilation of E_{\uparrow} creates an



FIG. 7. Details of coarsening, following even- and odd-spin clusters. (a) Time evolution (upward) towards the steady state, starting from a random configuration. Black and red colors mark odd domains with spins \uparrow and \downarrow , denoted as O_{\uparrow} and O_{\downarrow} , respectively. Green and blue colors show even domains with \uparrow and \downarrow , denoted as E_{\uparrow} and E_{\downarrow} , respectively. The highlighted regions, A, B, and C, show three mechanisms discussed in points (iv), (v), and (vi) in the main text. (b) The number of even domains $\mathcal{N}_E(t_w)$ decreases as $t_w^{-1/2}$, the line being a fit with a function $f(x) \sim x^{-1/2}$. (c) During coarsening in a system of length L, $\mathcal{N}_E(t_w)$ is expected to be proportional to L. $\mathcal{N}_E(t_w)/L$ for different L follows a master curve. (d) $\mathcal{L}(t_w)$ grows as $t_w^{1/2}$, the line being a fit. (e) Number of odd domains $\mathcal{N}_O(t_w)$ decreases as $t_w^{-1/4}$. (f) Length of odd domains increases as $t_w^{1/4}$. (g) The fit shows that $P(\xi) \sim \exp(-\xi^{1/2})$ and thus the plot of $\ln[P(\xi)]$ as a function of $\xi^{1/2}$ becomes linear. (h) Scaling collapse of the distribution of odd domain sizes confirm that odd domain length increases as $t_w^{1/4}$.

 E_{\downarrow} domain. We find this second mechanism becomes rarer as coarsening proceeds.

(vi) Consider a configuration where an *E* domain is surrounded by several *O* domains on either side, for instance, $O_{\downarrow}O_{\uparrow}O_{\downarrow}E_{\uparrow}O_{\downarrow}O_{\uparrow}O_{\downarrow}$. Through the mechanism (iv) above, O domains will continue getting annihilated until the configuration meets an E domain on one side and an Odomain on the other side. In this case, annihilation of the central E domain creates a broad E domain that becomes narrower with time and eventually gets annihilated creating



FIG. 8. Time evolution of the configuration for a quench to T = 0 starting from a random initial state with $M_{\text{even}} = M_{\text{odd}}$. The color black refers to \downarrow and yellow to \uparrow with system size L = 1024 and $M_{\text{even}} = 32$.

another broad E domain:

$$\begin{aligned} O_{\uparrow}O_{\downarrow}O_{\uparrow}O_{\downarrow}E_{\uparrow}O_{\downarrow}O_{\uparrow}O_{\downarrow}E_{\uparrow} \Rightarrow O_{\uparrow}O_{\downarrow}O_{\uparrow}E_{\downarrow}O_{\uparrow}O_{\downarrow}E_{\uparrow} \\ \Rightarrow O_{\uparrow}O_{\downarrow}E_{\uparrow}O_{\downarrow}E_{\uparrow} \Rightarrow O_{\uparrow}E_{\downarrow}E_{\uparrow} \\ \Rightarrow O_{\uparrow}. \end{aligned}$$

Such a process is highlighted by region C in Fig. 7(a).

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(vii) To understand the t_w dependence of the typical O domain length $\xi(t_w)$, we follow the distribution $P(\xi(t_w))$. We find that $P(\xi(t_w)) \sim \exp(-\xi^{1/2})$ as shown in Fig. 7(g). Considering $\xi \sim t_w^{\alpha}$, we have

$$P(\xi(t_w)) \sim \frac{1}{t_w^{\alpha}} e^{-(\xi/t_w^{\alpha})^{1/2}}.$$
 (A1)

Plotting $t_w^{\alpha} P(\xi(t_w))$ as a function of ξ/t_w^{α} , we obtain excellent data collapse for $\alpha = 1/4$ for different t_w as shown in Fig. 7(h). This confirms our earlier expectation that $\xi \sim t_w^{1/4}$.

APPENDIX B: TIME EVOLUTION OF THE SYSTEM WHEN INITIAL STATE IS PREPARED WITH ZERO SUBLATTICE MAGNETIZATION M

As discussed in Sec. IV, the number of domain walls N equals the sublattice magnetization \mathcal{M} . This implies that when a system with an initial state that has $\mathcal{M} = 0$ is quenched to T = 0, it evolves to a steady state with zero domain walls, that is, a state with all spins \uparrow or \downarrow . To test this result, we have prepared random initial states with $M_{\text{even}} = M_{\text{odd}}$ with different values of M_{even} for a range of system sizes L. A typical time evolution for a quench to T = 0 from such an initial sate is shown in Fig. 8, where black refers to \downarrow and yellow refers to \uparrow . We find that the system goes to a state with all spins either \uparrow or \downarrow .

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