Neutrino mixing from finite modular groups

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We study the lepton flavor models, whose flavor symmetries are finite subgroups of the modular group such as S_3 and A_4 . In our models, couplings are also nontrivial representations of these groups and modular functions of the modulus. We study the possibilities that these models realize realistic values of neutrino masses and lepton mixing angles.

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I. INTRODUCTION

One of the unsolved but important mysteries in particle physics is the mystery about the flavor structure of the quarks and leptons, such as the generation number, mass hierarchy, and mixing angles. Such a mystery would provide us with hints to explore physics beyond the standard model. Indeed, several types of scenarios have been proposed to understand quark and lepton masses and mixing angles as well as *CP* phases.

One of interesting ideas is to impose non-Abelian discrete flavor symmetries. Many models have been proposed imposing non-Abelain discrete flavor symmetries, e.g., S_3 , A_4 , S_4 and other various finite groups. (See for review [1–4].) In particular, the lepton sector has been intensively studied, because at least two of three lepton mixing angles are large compared with the quark mixing angles, and their experimental results have been improved precisely. Recently, *CP* symmetry and its violation were also studied [5–7].

Superstring theory is a promising candidate for the unified theory of all interactions including gravity and matter fields such as quarks and leptons as well as Higgs fields. It is shown that superstring theory on certain compactifications leads to non-Abelian discrete flavor symmetries. For example, heterotic string theory on orbifolds can lead to D_4 , $\Delta(54)$, etc. [8]. (See also [9,10].)¹ In addition, type II magnetized and intersecting D-brane models can lead to similar flavor symmetries [12–16].

On the other hand, string theory on tori and orbifolds has the modular symmetry. For example, modular symmetries were studied in heterotic orbifold models [17-19] and magnetized D-brane models [20-22]. In general, modular transformations act nontrivially on string modes and interchange massless modes such as quarks and leptons to each other. In this sense, modular symmetry is a non-Abelain discrete flavor symmetry. Furthermore, it is interesting that the modular symmetry includes S_3 , A_4 , S_4 , A_5 as its congruence subgroups, $\Gamma(N)$. However, there is a difference between the modular symmetry and the usual flavor symmetries.² Coupling constants such as Yukawa couplings also transform nontrivially under the modular symmetry [17,20–22], while coupling constants are invariant under the usual flavor symmetries, although flavon fields, which develop their vacuum expectation values (VEVs), transform nontrivially under flavor symmetries. Moreover, Yukawa couplings as well as higher order coupling constants are modular functions of moduli [20,23–25].

By use of the above aspects, an interesting ansatz was proposed in Ref. [26], where $\Gamma(3) \simeq A_4$ was used and leptons were assigned to triplets and singlets of A_4 . Also coupling constants were assigned to A_4 triplet and singlets, which are modular functions. Then, neutrino masses and mixing angles were analyzed. Such an ansatz would be interesting in order to bridge a gap between underlying theory such as superstring theory and low-energy physics like neutrino phenomena. Our purpose in this paper is to study systematically the above approach. We study the A_4 model following Ref. [26]. Also, we extend our analysis to S_3 models.

This paper is organized as follows. In Sec. II, we give a briel review on modular symmetry. In Sec. III, using experimental values, we write the neutrino mass matrix, which is convenient to our analyses. In Sec. IV, we study systematically the A_4 model following Ref. [26]. In Sec. V,

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¹In Ref. [11], relations between enhanced gauge symmetries and non-Abelian discrete flavor symmetries were studied.

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²See for their difference and relation [22].

we construct S_3 models in a way similar to the A_4 model and study them systematically. Section VI is our conclusion and discussions. In Appendix, we briefly review modular functions and show modular functions corresponding to the A_4 triplet and the S_3 doublet.

II. MODULAR TRANSFORMATION AND ITS SUBGROUP SYMMETRIES

In this section, we give a brief review on the modular symmetry and its congruence subgroups.

Toroidal compactification is one of simple compactifications. The two-dimensional torus T^2 is obtained as $T^2 = \mathbb{R}^2 / \Lambda$. Here, Λ is the two-dimensional lattice, which is spanned by two lattice vectors, $\alpha_1 = 2\pi R$ and $\alpha_2 = 2\pi R \tau$. We use the complex coordinate, where *R* is a real parameter, and τ is a complex modulus parameter.

The choice of the basis vectors has some ambiguity. The same lattice can be spanned by other bases,

$$\begin{pmatrix} \alpha'_2 \\ \alpha'_1 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} \alpha_2 \\ \alpha_1 \end{pmatrix},$$
(1)

where a, b, c, d are integer with satisfying ad - bc = 1. That is the SL(2, Z) transformation.

The modular parameter $\tau = \alpha_2/\alpha_1$ transforms as

$$\tau \to \tau' = \frac{a\tau + b}{c\tau + d},$$
 (2)

under (1). Both lattice bases (α_1, α_2) and (α'_1, α'_2) , and both modular parameters, τ and τ' , lead to the same lattice Λ and the same T^2 . The modular transformation is generated by the *S* and *T* transformations,

$$S: \tau \to -\frac{1}{\tau}, \tag{3}$$

$$T: \tau \to \tau + 1. \tag{4}$$

In addition, these satisfy the following algebraic relations,

$$S^2 = 1,$$
 $(ST)^3 = 1.$ (5)

On top of that, when we impose $T^N = 1$, the so-called congruence subgroups $\Gamma(N)$ can be realized. The congruence subgroups $\Gamma(N)$ are isomorphic to (even) permutation groups, e.g., $\Gamma(2) \simeq S_3$, $\Gamma(3) \simeq A_4$, $\Gamma(4) \simeq S_4$, and $\Gamma(5) \simeq A_5$. (For subgroups of the modular group, e.g., see Ref. [27].)

String theory on T^2 as well as orbifolds T^2/Z_N has the modular symmetry. Furthermore, four-dimensional lowenergy effective field theory on the compactification $T^2 \times X_4$ as well as $(T^2/Z_N) \times X_4$ also has the modular symmetry, where X_4 is a four-dimensional compact space. A set of chiral superfields $\phi^{(I)}$ transform under the modular transformation (2) as a multiplet [28],

$$\phi^{(I)} \to (c\tau + d)^{-k_I} \rho^{(I)}(\gamma) \phi^{(I)}, \tag{6}$$

where $-k_I$ is the so-called modular weight and $\rho^{(I)}$ denotes a representation matrix. Modular invariant kinetic terms expanded around a VEV of the modulus τ are written by

$$\frac{|\partial_{\mu}\tau|^2}{\langle\tau-\bar{\tau}\rangle^2} + \sum_{I} \frac{|\partial_{\mu}\phi^{(I)}|^2}{\langle\tau-\bar{\tau}\rangle^{k_I}}.$$
(7)

Also, the superpotential should be invariant under the modular symmetry. That is, the superpotential should have vanishing modular weight in global supersymmetric models. Indeed, Yukawa coupling constants as well as higher-order couplings constants are modular functions of τ [20,23–25]. In the framework of supergravity theory, the superpotential must be invariant up to the Kähler transformation [28]. That implies that the superpotential of supergravity models with the above kinetic term should have modular weight one. In Secs. IV and V, we consider the global supersymmetric models, and require that the superpotential has vanishing modular weight, although it is straightforward to arrange modular weights of chiral superfields for supergravity models.

The Dedekind eta-function $\eta(\tau)$ is one of famous modular functions, which is written by

$$\eta(\tau) = q^{1/24} \prod_{n=1}^{\infty} (1 - q^n), \tag{8}$$

where $q = e^{2\pi i \tau}$. The $\eta(\tau)$ function behaves under *S* and *T* transformations as

$$\eta(-1/\tau) = \sqrt{-i\tau}\eta(\tau), \qquad \eta(\tau+1) = e^{i\pi/12}\eta(\tau).$$
(9)

The former transformation implies that the $\eta(\tau)$ function has the modular weight 1/2.

The modular functions (Y_1, Y_2, Y_3) with weight 2, which behave as an A_4 triplet, are obtained as

$$\begin{split} Y_{1}(\tau) &= \frac{i}{2\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} \right. \\ &+ \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} - \frac{27\eta'(3\tau)}{\eta(3\tau)} \right), \\ Y_{2}(\tau) &= \frac{-i}{\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \omega^{2} \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} + \omega \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} \right), \\ Y_{3}(\tau) &= \frac{-i}{\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \omega \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} + \omega^{2} \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} \right), \end{split}$$

$$(10)$$

in Ref. [26], where $\omega = e^{2\pi i/3}$. (See Appendix)

We can obtain the modular functions with weight 2, which behave as an S_3 doublet,

$$Y_{1}(\tau) = \frac{i}{4\pi} \left(\frac{\eta'(\tau/2)}{\eta(\tau/2)} + \frac{\eta'((\tau+1)/2)}{\eta((\tau+1)/2)} - \frac{8\eta'(2\tau)}{\eta(2\tau)} \right),$$

$$Y_{2}(\tau) = \frac{\sqrt{3}i}{4\pi} \left(\frac{\eta'(\tau/2)}{\eta(\tau/2)} - \frac{\eta'((\tau+1)/2)}{\eta((\tau+1)/2)} \right),$$
(11)

by a similar technique. (See Appendix)

We use the following expansions:

$$Y_1(\tau) = \frac{1}{8} + 3q + 3q^2 + 12q^3 + 3q^4 \cdots,$$

$$Y_2(\tau) = \sqrt{3}q^{1/2}(1 + 4q + 6q^2 + 8q^3 \cdots).$$
 (12)

In Sec. V, we fit Y_2/Y_1 to experimental data. That is, we use the following expansion:

$$\frac{1}{Y_1} = \frac{1}{8} \cdot \frac{1}{1 + 24q + \cdots}.$$
 (13)

Such an expansion would be valid for $|24q| \lesssim 0.1$, i.e.

$$\mathrm{Im}(\tau) \gtrsim 0.65. \tag{14}$$

III. NEUTRINO MASS MATRIX

Before studying the A_4 and S_3 models, here using experimental values of neutrino oscillations we write the neutrino mass matrix, which is convenient to our analyses in Secs. IV and V.

A. Experimental values

Flavor eigenstates of neutrino $(\nu_e, \nu_\mu, \nu_\tau)$ are linear combinations of mass eigenstates (ν_1, ν_2, ν_3) . Their mixing matrix *U*, i.e. the so-called PMNS matrix can be written by

$$U = \begin{pmatrix} U_{e1} & U_{e2} & U_{e3} \\ U_{\mu 1} & U_{\mu 2} & U_{\mu 3} \\ U_{\tau 1} & U_{\tau 2} & U_{\tau 3} \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_{23} & s_{23} \\ 0 & -s_{23} & c_{23} \end{pmatrix} \begin{pmatrix} c_{13} & 0 & s_{13}e^{-i\delta_{CP}} \\ 0 & 1 & 0 \\ -s_{13}e^{i\delta_{CP}} & 0 & c_{13} \end{pmatrix}$$
$$\times \begin{pmatrix} c_{12} & s_{12} & 0 \\ -s_{12} & c_{12} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i\alpha_2/2} & 0 \\ 0 & 0 & e^{i\alpha_3/2} \end{pmatrix}, \quad (15)$$

where $c_{ij} = \cos \theta_{ij}$ and $s_{ij} = \sin \theta_{ij}$ for mixing angles θ_{ij} , δ_{CP} is the Dirac *CP* phase, and α_i are Majorana *CP* phases. The mass-squared differences are defined by

$$\delta m^2 = m_2^2 - m_1^2, \tag{16}$$

$$\Delta m^2 = m_3^2 - \frac{m_1^2 + m_2^2}{2}, \qquad (17)$$

where m_i is the mass eigenvalue of ν_i . We also define the ratio between the mass-squared differences as

$$r = \frac{\delta m^2}{|\Delta m^2|}.$$
 (18)

Experimental values with normal ordering (NO) and inverted ordering (IO) are shown in Table I.

B. General setup of our models

In Secs. IV and V, we consider the models, where the charged lepton mass matrix is diagonal, following [26]. In such models, the neutrino mass matrix m_{ν} is written as

$$m_{\nu} = U^* \operatorname{diag}(m_1, m_2, m_3) U^{\dagger},$$
 (19)

by use of the PMNS matrix. By using three column vectors $U = (\vec{U}_1, \vec{U}_2, \vec{U}_3)$, the matrix m_{ν} can be decomposed into

$$m_{\nu} = m_{\nu}^{(1)} + e^{-i\alpha_2}m_{\nu}^{(2)} + e^{-i\alpha_3}m_{\nu}^{(3)},$$
 (20)

where

е

$$m_{\nu}^{(1)} \equiv m_1(\vec{U}_1^* \cdot \vec{U}_1^{\dagger}), \qquad e^{-i\alpha_2} m_{\nu}^{(2)} \equiv m_2(\vec{U}_2^* \cdot \vec{U}_2^{\dagger}),$$

$$^{-i\alpha_3} m_{\nu}^{(3)} \equiv m_3(\vec{U}_3^* \cdot \vec{U}_3^{\dagger}). \tag{21}$$

The matrices $m_{\nu}^{(i)}$ are symmetric matrices and do not depend on Majorana phases α_i in this definition. The overall sizes of $m_{\nu}^{(i)}$ are of $\mathcal{O}(m_i)$.

In the case of NO ($m_1 \simeq m_2 \ll m_3$), m_ν can be approximated by

TABLE I. The best-fit values and 1σ ranges in experiments with NO and IO from Ref. [29].

Parameter	Normal ordering	Inverted ordering	
$\delta m^2 / 10^{-5} \text{ eV}^2$	$7.37^{+0.17}_{-0.16}$	$7.37^{+0.17}_{-0.16}$	
$\Delta m^2 / 10^{-3} \text{ eV}^2$	$2.525\substack{+0.042\\-0.030}$	$2.505\substack{+0.034\\-0.032}$	
$\sin^2 \theta_{12} / 10^{-1}$	$2.97_{-0.16}^{+0.17}$	$2.97\substack{+0.17 \\ -0.16}$	
$\sin^2 \theta_{13} / 10^{-2}$	$2.15\substack{+0.07 \\ -0.07}$	$2.16\substack{+0.08 \\ -0.07}$	
$\sin^2 \theta_{23} / 10^{-1}$	$4.25_{-0.15}^{+0.21}$	$5.89^{+0.16}_{-0.22} \oplus 4.33^{+0.15}_{-0.16}$	
δ_{CP}/π	$1.38\substack{+0.23\\-0.20}$	$1.31\substack{+0.31 \\ -0.19}$	
r	$2.92^{+0.10}_{-0.11} imes 10^{-2}$	$2.94^{+0.11}_{-0.10} imes 10^{-2}$	

$$m_{\nu} \simeq m_{\nu}^{(3)} = m_{3} \begin{pmatrix} s_{13}^{2} e^{2i\delta_{CP}} & c_{13}s_{13}s_{23}e^{i\delta_{CP}} & c_{13}s_{13}c_{23}e^{i\delta_{CP}} \\ & c_{13}^{2}s_{23}^{2} & c_{13}^{2}c_{23}s_{23} \\ & & c_{13}^{2}c_{23}^{2} \end{pmatrix}, \quad (22)$$

up to the phase. Here, we have omitted to write explicitly some elements, because $m_{\nu}^{(3)}$ is the symmetric matrix. These matrix elements have the following relations:

$$(m_{\nu})_{11}(m_{\nu})_{22} = (m_{\nu})_{12}^{2}, \qquad (m_{\nu})_{11}(m_{\nu})_{33} = (m_{\nu})_{13}^{2}, (m_{\nu})_{22}(m_{\nu})_{33} = (m_{\nu})_{23}^{2}, \qquad \frac{(m_{\nu})_{22}}{(m_{\nu})_{33}} = t_{23}^{2}, \frac{(m_{\nu})_{11}}{(m_{\nu})_{22} + (m_{\nu})_{33}} = t_{13}^{2}e^{2i\delta_{CP}},$$
(23)

where $t_{ij} = \tan \theta_{ij}$. Thus, realistic models should be consistent with these rules (23).

In the case of IO $(m_3 \ll m_1 \simeq m_2)$, the mass matrix m_{ν} can be approximated by

$$m_{\nu} \simeq m_{\nu}^{(1)} + e^{-i\alpha_2} m_{\nu}^{(2)}.$$
 (24)

Since α_2 has not been determined by experiments, there is one more parameter in IO than in NO.

IV. A₄ MODEL

In this section, we consider the model in Ref. [26] systematically. This model is the supersymmetric model, although we can construct a similar nonsupersymmetric model. This model has the flavor symmetry $\Gamma(3) \simeq A_4$.

We concentrate on the lepton sector. Table II shows the A_4 representations and k_I of lepton and Higgs superfields, L_i , e_{Ri}^c and $H_{u.d.}$ Recall that $-k_I$ is the modular weight. The superfield ϕ is a flavon field and the A_4 triplet. We arrange k_I such that the charged lepton masses are not modular functions of τ and the flavon field does not appear in the Weinberg operator. For example, we take $k_{\phi} = 3$, $k_{H_{u.d}} = 0$, $k_L = 1$ and $k_{ei} = -4$ [26]. Then, the superpotential terms of the charged lepton sector can be written by

$$W_{e} = \beta_{1} e_{R_{1}}^{c} H_{d}(L\phi)_{1} + \beta_{2} e_{R_{2}}^{c} H_{d}(L\phi)_{1'} + \beta_{3} e_{R_{3}}^{c} H_{d}(L\phi)_{1''},$$
(25)

where the β_i are constant coefficients.

We assume that the flavon multiplet develops the VEV along the direction, $\langle \phi \rangle = (u, 0, 0)$. Such a VEV as well as the VEV v_d of the neutral component of H_d leads to the diagonal charged lepton mass matrix,

TABLE II. A_4 representations and k_I in the A_4 model.

	$SU(2)_L \times U(1)_Y$	A_4	k_I
$e_{R_1}^c$	(1, +1)	1	k_{e1}
$e_{R_2}^c$	(1, +1)	1″	k_{e2}
$e_{R_3}^{c}$	(1, +1)	1′	k_{e3}
L	(2, -1/2)	3	k_L
H_u	(2, +1/2)	1	k_{H_u}
H_d	(2, -1/2)	1	k_{H_d}
ϕ	(1, 0)	3	k _φ ຶ

$$m_e = uv_d \begin{pmatrix} \beta_1 & & \\ & \beta_2 & \\ & & \beta_3 \end{pmatrix}.$$
(26)

By choosing proper values of couplings β_i , we can realize the experimental values of the charged lepton masses, $m_{e,\mu,\tau}$.

On the other hand, we can write the Weinberg operator in the superpotential

$$W_{\nu} = \frac{1}{\Lambda} (H_u H_u LLY(\tau))_1.$$
⁽²⁷⁾

Since $k_L = 1$ and $k_{H_u} = 0$, the couplings $Y = (Y_1, Y_2, Y_3)$ must be a modular form with modular weight 2 and an A_4 triplet.³ We use the modular functions (10). Then, we obtain the mass matrix of neutrinos written by

$$m_{\nu}^{\text{model}} = \frac{v_{\mu}^2}{\Lambda} \begin{pmatrix} 2Y_1 & -Y_3 & -Y_2 \\ -Y_3 & 2Y_2 & -Y_1 \\ -Y_2 & -Y_1 & 2Y_3 \end{pmatrix}, \quad (28)$$

where v_{μ} denotes the VEV of the neutral component of H_{μ} .

Note that the charged lepton mass matrix is diagonal. Thus, mixing angles as well as the CP phases originated from the neutrino mass matrix. In the following subsections, we perform numerical analyses by using the mass matrix (28).

A. Normal ordering in A_4 model

Here, we study the NO case. In the case of NO, there are constraints (24) for the realistic mass matrix. By using the equations in the second line of (24), we obtain

$$t_{13}^2 e^{2i\delta_{CP}} = \frac{Y_1}{Y_2 + Y_3} = \left[4\left(1 + \frac{Y_2}{Y_3}\right)\frac{Y_2}{Y_3}\right]^{-1} = \frac{1}{4t_{23}^2(1 + t_{23}^2)}.$$
(29)

³Although three more couplings 1 + 1' + 1'' can be included in (27) generally, we only consider triplet coupling artificially according to [26].





FIG. 1. Plot of Re F_1 with 3σ deviation of s_{ij} and δ_{CP} .

This is the theoretical prediction in this model. By putting experimental values with $\pm 3\sigma$, the left- and right-hand sides of (29) become

$$|t_{13}^2 e^{2i\delta_{CP}}| \sim 0.02, \qquad \frac{1}{4t_{23}^2(1+t_{23}^2)} \sim 0.2, \quad (30)$$

respectively. The theoretical prediction (29) is inconsistent with experimental data (30). Thus, this model does not reproduce the experimental results for NO.

B. Inverted ordering in A₄ model

Here, we study the IO case. The mass matrix in this model m_{ν}^{model} (28) obeys the following relations:

$$F_1(\alpha_2; s_{ij}, \delta_{CP}) \equiv (m_{\nu}^{\text{model}})_{11} + 2(m_{\nu}^{\text{model}})_{23} = 0, \quad (31)$$

$$F_2(\alpha_2; s_{ij}, \delta_{CP}) \equiv (m_{\nu}^{\text{model}})_{22} + 2(m_{\nu}^{\text{model}})_{13} = 0, \quad (32)$$

$$F_3(\alpha_2; s_{ij}, \delta_{CP}) \equiv (m_{\nu}^{\text{model}})_{33} + 2(m_{\nu}^{\text{model}})_{12} = 0.$$
(33)

Figure 1 shows a plot of Re F_1 . The shaded region shows the 3σ deviation of s_{ij} and δ_{CP} . Figure 2 shows plots of Re F_i , i = 2, 3. Since a realistic model must satisfy $F_i = 0$ at the same α_2 , this model does not reproduce the experimental results within the 3σ range for IO.

 TABLE III.
 S_3 representations and k_I in the S_3 models.

	$SU(2)_L \times U(1)_Y$	S_3	k _I
$e_{R_{a}}^{c}$	(1,+1)	1	-3
$e_{R_{b}}^{c}$	(1, +1)	1	-4
$e_{R_{o}}^{c}$	(1, +1)	1′	-4
$L^{(1)}$	(2, -1/2)	1	1
$L^{(2)}$	(2, -1/2)	2	1
H_u	(2, +1/2)	1	0
H_d	(2, -1/2)	1	0
$\phi^{(1)}$	(1, 0)	1	2
$\phi^{(2)}$	(1, 0)	2	3

V. S₃ MODEL

In this section, we construct the models with the flavor symmetry $\Gamma(2) \simeq S_3$ in a way similar to the A_4 model, and study them systematically.

Table III shows the S_3 representations and k_I of lepton and Higgs superfields. The $\phi^{(1)}$ and $\phi^{(2)}$ fields are flavon fields, and $\phi^{(1)}$ and $\phi^{(2)}$ are S_3 singlet and doublet, respectively. In order to distinguish e_{R_a} and e_{R_b} , we assign k_I different from each other. For such a purpose, we can impose an additional symmetry, e.g., Z_2 . We assign k_I such that we can realize the diagonal charged lepton mass matrix similar to the A_4 model. Indeed, the superpotential terms in the charged lepton sector can be written by

$$W_{e} = \beta_{a} e_{R_{a}}^{c} H_{d} (L^{(1)} \phi^{(1)})_{1} + \beta_{b} e_{R_{b}}^{c} H_{d} (L^{(2)} \phi^{(2)})_{1} - \beta_{c} e_{R}^{c} H_{d} (L^{(2)} \phi^{(2)})_{1'},$$
(34)

where the β_i are constant coefficients. We assume that the flavon fields develop their VEVs as

$$\langle \phi^{(1)} \rangle = u_1, \qquad \langle \phi^{(2)} \rangle = (u_2, 0).$$
 (35)

Then, we can realize the diagonal charged lepton mass matrix when the neutral component of H_d develops its VEV. Similar to the A_4 model, we can realize the experimental values of the charged lepton masses, $m_{e,\mu,\tau}$ by



FIG. 2. Plots of Re F_2 (left) and Re F_3 (right) with 3σ deviation of s_{ij} and δ_{CP} .

TABLE IV. Three S_3 models.

Model	$L^{(1)}$	$L^{(2)}$	$m_{ u}^{ m model}$
1	L_3	(L_1, L_2)	$\begin{pmatrix} dY_2 & dY_1 & aY_1 \\ dY_1 & -dY_2 & aY_2 \\ aY & aY & 0 \end{pmatrix} + \begin{pmatrix} cY & 0 & 0 \\ 0 & cY & 0 \\ 0 & 0 & bY \end{pmatrix}$
2	L_2	(L_1, L_3)	$\begin{pmatrix} dY_1 & dY_2 & 0 \\ dY_2 & aY_1 & dY_1 \\ aY_1 & 0 & aY_2 \\ W & W & W \end{pmatrix} + \begin{pmatrix} cY & 0 & 0 \\ 0 & bY & 0 \\ 0 & 0 & W \end{pmatrix}$
3	L_1	(L_2, L_3)	$\begin{pmatrix} dY_1 & dY_2 & -dY_2 \end{pmatrix} + \begin{pmatrix} 0 & 0 & cY \end{pmatrix} \\ \begin{pmatrix} 0 & aY_1 & aY_2 \\ aY_1 & -dY_2 & dY_1 \\ aY_2 & dY_1 & dY_2 \end{pmatrix} + \begin{pmatrix} bY & 0 & 0 \\ 0 & cY & 0 \\ 0 & 0 & cY \end{pmatrix}$

choosing proper values of couplings β_a . Note that the assignment of generations to e_{R_i} , i = a, b, c is not fixed yet.

Modular invariant Weinberg operators in the superpotential can be written by

$$\mathcal{L}_{\text{eff}}^{\nu} = \frac{1}{\Lambda} [dHH(L^{(2)}L^{(2)})_2 Y^{(2)} + aHH(L^{(1)}L^{(2)})_2 Y^{(2)} + bHH(L^{(1)}L^{(1)})_1 Y^{(1)} + cHH(L^{(2)}L^{(2)})_1 Y^{(1)}], \quad (36)$$

where $a, b, c, d \in \mathbb{C}$ are constant coefficients. $Y^{(1)}$ and $Y^{(2)}$ are modular forms with modular weight 2, and $Y^{(1)}$ and $Y^{(2)}$ are S_3 singlet and doublet,⁴ respectively. Note that since $\mathbf{1}'$ in $\mathbf{2} \times \mathbf{2} = \mathbf{1} + \mathbf{1}' + \mathbf{2}$ is antisymmetric, $(L^{(2)}L^{(2)})_{\mathbf{1}'} = 0$. We denote $Y^{(1)} = Y$ and $Y^{(2)} = (Y_1, Y_2)$. There are 6 ways to assign 3 generations of lepton L_i to S_3 singlet $L^{(1)}$ and doublet $L^{(2)}$. The replacement of $L^{(2)} = (L_i, L_j) \rightarrow$ (L_j, L_i) corresponds to the replacement of $Y_1 \leftrightarrow Y_2$ and less affects analysis. Therefore, we study 3 models shown in table (IV). The fifth column shows the neutrino mass matrix in each model. Since parameters *b* and *c* always appear in *bY* and *cY*, respectively, we rewrite $B \equiv bY$ and $C \equiv cY$.

A. Normal ordering in S_3 models

Here, we study the NO case in the three S_3 models. In the model 1, the neutrino mass matrix is written by

$$m_{\nu}^{\text{model}} = \begin{pmatrix} C + dY_2 & dY_1 & aY_1 \\ dY_1 & C - dY_2 & aY_2 \\ aY_1 & aY_2 & B \end{pmatrix}.$$
 (37)

Since the charged lepton mass matrix is diagonal, the PMNS matrix is determined only by the neutrino mass matrix. The consistency conditions (24) are written by

$$\begin{aligned} (C+dY_2)(C-dY_2) &= (dY_1)^2, \qquad B(C+dY_2) = (aY_1)^2, \\ B(C-dY_2) &= (aY_2)^2, \end{aligned}$$
(38)

$$\frac{C - dY_2}{B} = t_{23}^2, \qquad \frac{C + dY_2}{B + (C - dY_2)} = e^{2i\delta_{CP}}t_{13}^2.$$
(39)

We obtain $dY_2 = C/2$ from (38), and then

$$t_{23}^2 = \frac{C}{2B}, \qquad e^{2i\delta_{CP}}t_{13}^2 = \frac{3}{1 + \frac{2B}{C}}$$
 (40)

from (39). Thus, a prediction of this model is

$$e^{2i\delta_{CP}}t_{13}^2 = 3s_{23}^2. \tag{41}$$

Experimental values lead to $t_{13}^2 = \mathcal{O}(10^{-2})$ and $3s_{23}^2 = \mathcal{O}(1)$. Hence this model is inconsistent with experiments. Note that since this result (41) does not depend on Y_i , we obtain the same result by replacing $Y_1 \leftrightarrow Y_2$, that is, $L^{(2)} = (L_1, L_2) \rightarrow (L_2, L_1)$.

In the models 2 and 3, we can analyze in the same way as in the model 1. A prediction of the model 2 is

$$e^{2i\delta_{CP}}t_{13}^2 = 3c_{23}^2,\tag{42}$$

and a prediction of the model 3 is

$$t_{23}^2 = 3. (43)$$

Both of these predictions are inconsistent with experiments. Hence, these models are not realistic.

B. Inverted ordering in S₃ models

Here, we study the IO case in the three S_3 models.

1. Model 1

In the model 1, the mass matrix is written by

$$m_{\nu}^{\text{model}} = \begin{pmatrix} C + dY_2 & dY_1 & aY_1 \\ dY_1 & C - dY_2 & aY_2 \\ aY_1 & aY_2 & B \end{pmatrix}.$$
(44)

From this matrix, we find

$$\frac{(m_{\nu}^{\text{model}})_{11} - (m_{\nu}^{\text{model}})_{22}}{2(m_{\nu}^{\text{model}})_{12}} = \frac{(m_{\nu}^{\text{model}})_{23}}{(m_{\nu}^{\text{model}})_{13}} = \frac{Y_2}{Y_1}, \quad (45)$$

and hence

$$F^{\text{model}} \equiv 2(m_{\nu}^{\text{model}})_{12}(m_{\nu}^{\text{model}})_{23} - (m_{\nu}^{\text{model}})_{13}[(m_{\nu}^{\text{model}})_{11} - (m_{\nu}^{\text{model}})_{22}] = 0.$$
(46)

This is a prediction of this model.

⁴There are two independent modular forms with weight 2 and $\Gamma(2)$ [26,30]. Thus, there is only one independent modular form doublet $Y^{(2)}$ in (36).

First, we define a function

$$F_1(\alpha_2; s_{ij}, \delta_{CP}) = 2(m_\nu)_{12}(m_\nu)_{23} - (m_\nu)_{13}[(m_\nu)_{11} - (m_\nu)_{22}],$$
(47)

with m_{ν} in (24), and search a set of the values of $(\alpha_2, s_{ij}, \delta_{CP})$ satisfying $F_1 = 0$ within the 3σ experimental range. Here, we treat α_2 as a free parameter. Figure 3 shows a plot of the F_1 on a complex plane. The blue curve is an one-parametric plot of the $F_1(\alpha_2)$ with $\alpha_2 \in [0, 2\pi)$ and the best-fit values of s_{ij} and δ_{CP} . The blue shaded region is a two-parametric plot of the $F_1(\alpha_2; \delta_{CP})$ with $\alpha \in [0, 2\pi)$, $\delta_{CP} \in (3\sigma$ -range), and the best-fit values of s_{ij} . The origin $F_1 = 0$ is the point consistent with the model prediction (46), and this point corresponds to $\alpha_2/\pi \simeq 0.26$ and $\delta_{CP}/\pi \simeq 0.89$.

Second, we solve $m_{\nu}^{\text{model}} = m_{\nu}$ with numerical matrix m_{ν} . Since there are six complex model parameters and six complex equations, we can solve these equations. An approximate solution is

$$a = 0.874 - 0.162i, \qquad B = 0.469 - 0.246i,$$

$$C = 0.607 - 0.235i, \qquad d = -0.473 - 0.269i,$$

$$Y_1 = 0.163 + 0.330i, \qquad Y_2 = -0.468 + 0.218i. \quad (48)$$

At this stage, numerically expressed mass matrix m_{ν} has degenerate eigenvalues $m_1^2 = m_2^2$, and therefore m_{ν} does not reproduce the mixing angle s_{12}^2 and mass-squared differences.

We can resolve the degeneracy $m_1^2 = m_2^2$ by changing parameters slightly. That is, we modify the parameter $B \rightarrow B + \epsilon_B$ to reproduce the s_{12}^2 and mass-squared differences by resolving the degeneracy. When the $\epsilon_B = 0.030 + 0.026i$, observables are given by



FIG. 3. F_1 in the model 1.

$$s_{12}^2 = 2.79 \times 10^{-1}, \quad s_{13}^2 = 2.37 \times 10^{-2}, \quad s_{23}^2 = 5.95 \times 10^{-1},$$

$$r = 2.91 \times 10^{-2}, \quad \sin \delta_{CP} = -0.58,$$
(49)

and Majorana phases are given by

$$\alpha_2/\pi = 0.39, \qquad \alpha_3/\pi = 0.70.$$
 (50)

These observables are consistent with experimental results up to 3σ , and the values of Majorana phases are predictions of the model 1.

Finally, we fit the values of Y_1 and Y_2 in (48) with the modular functions in (11). Since the overall coefficient of $Y_i(\tau)$ is not fixed in (A23), we fit the value of Y_2/Y_1 by

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 1.403 \times e^{0.507\pi i}.$$
 (51)

Such a ratio can be obtained for $\tau = 0.505 + 0.781i$. This value is sufficiently large compared with Eq. (14).

When we change the generation assignment as $L^{(2)} = (L_1, L_2) \rightarrow (L_2, L_1)$, Y_1 and Y_2 are replaced each other. Thus, we fit the values of Y_1 and Y_2 by

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 0.713 \times e^{-0.507\pi i},$$
 (52)

and we get the solution $\tau = -0.507 + 0.960i$.

2. Model 2

In the model 2, we can analyze with the same way as in the model 1.

The model 2 predicts

$$F^{\text{model}} \equiv 2(m_{\nu}^{\text{model}})_{13}(m_{\nu}^{\text{model}})_{23} - (m_{\nu}^{\text{model}})_{12}[(m_{\nu}^{\text{model}})_{11} - (m_{\nu}^{\text{model}})_{33}] = 0.$$
(53)

We define

$$F_{2}(\alpha_{2};s_{ij},\delta_{CP}) = 2(m_{\nu})_{13}(m_{\nu})_{23} - (m_{\nu})_{12}[(m_{\nu})_{11} - (m_{\nu})_{33}],$$
(54)

and this is shown in Fig. 4 similar to the model 1. The condition $F_2 = 0$ is satisfied at $\alpha_2/\pi \simeq 0.16$ and $\delta_{CP}/\pi \simeq 1.67$.

An approximate solution of $m_{\nu}^{\text{model}} = m_{\nu}$ is

$$a = 0.872 - 0.277i, \qquad B = 0.346 - 0.106i,$$

$$C = 0.748 - 0.182i, \qquad d = -0.361 - 0.098i,$$

$$Y_1 = -0.037 - 0.271i, \qquad Y_2 = -0.523 + 0.036i. \quad (55)$$

We can tune $B \rightarrow B + \epsilon_B$ with $\epsilon_B = 0.033 + 0.049i$, and we obtain



FIG. 4. F_2 in the model 2.

$$s_{12}^2 = 2.94 \times 10^{-1}, \quad s_{13}^2 = 2.30 \times 10^{-2}, \quad s_{23}^2 = 5.81 \times 10^{-1},$$

 $r = 2.93 \times 10^{-2}, \quad \sin \delta_{CP} = 0.79,$ (56)

and

$$\alpha_2/\pi = 0.01, \qquad \alpha_3/\pi = 0.42.$$
 (57)

These observables are consistent with experimental results up to 3σ except for the δ_{CP} . The value of δ_{CP} is out of 3σ deviation. The values of Majorana phases are predictions of the model 2. In this model, we can also tune *a* or *d* instead of *B*.

Finally, we fit the values of Y_i by

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 1.917 \times e^{-0.479\pi i}.$$
(58)

By solving this equation, we obtain the solution $\tau = -0.487 + 0.714i$. When we change the generation assignment as $L^{(2)} = (L_1, L_3) \rightarrow (L_3, L_1)$, we find

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 0.521 \times e^{0.479\pi i},\tag{59}$$

and we obtain the solution $\tau = 0.480 + 1.052i$,

3. Model 3

The model 3 predicts

$$F^{\text{model}} \equiv 2(m_{\nu}^{\text{model}})_{13}(m_{\nu}^{\text{model}})_{23} - (m_{\nu}^{\text{model}})_{12}[(m_{\nu}^{\text{model}})_{33} - (m_{\nu}^{\text{model}})_{22}] = 0.$$
(60)

We define



FIG. 5. F_3 in the model 3.

$$F_{3}(\alpha_{2};s_{ij},\delta_{CP}) = 2(m_{\nu})_{13}(m_{\nu})_{23} - (m_{\nu})_{12}[(m_{\nu})_{33} - (m_{\nu})_{22}],$$
(61)

and this is shown in Fig. 5 similar to the model 1. The condition $F_2 = 0$ is satisfied at $\alpha_2/\pi \simeq 0.14$ and $\delta_{CP}/\pi \simeq 1.53$.

An approximate solution of $m_{\nu}^{\text{model}} = m_{\nu}$ is

$$a = 0.000 + 0.188i, \qquad B = 0.952 - 0.121i,$$

$$C = 0.458 - 0.143i, \qquad d = 0.395 - 0.037i,$$

$$Y_1 = -1.203 + 0.255i, \qquad Y_2 = 0.289 - 0.061i. \qquad (62)$$

We can tune $B \rightarrow B + \epsilon_B$ with $\epsilon_B = 0.001 + 0.081i$, and we obtain

$$s_{12}^2 = 3.02 \times 10^{-1}, \quad s_{13}^2 = 2.16 \times 10^{-2}, \quad s_{23}^2 = 5.89 \times 10^{-1},$$

 $r = 2.89 \times 10^{-2}, \quad \sin \delta_{CP} = 0.84,$ (63)

and

$$\alpha_2/\pi = -0.03, \qquad \alpha_3/\pi = -0.54.$$
 (64)

These observables are consistent with experimental results up to 1σ except for the δ_{CP} . The value of δ_{CP} is out of 3σ deviation. The values of Majorana phases are predictions of the model 3. In this model, we can also tune *C* or *d* instead of *B*.

Finally, we fit the values of Y_i by

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 0.240 \times e^{-1.000\pi i}.$$
(65)

By solving this equation, we obtain the solution $\tau = 1.000 + 1.289i$. When we change the generation assignment as $L^{(2)} = (L_2, L_3) \rightarrow (L_3, L_2)$, we get

$$\frac{Y_2(\tau)}{Y_1(\tau)} \simeq 4.163 \times e^{1.000\pi i},$$
(66)

This equation has no solution.

VI. CONCLUSION

We have studied neutrino mixing in the models with A_4 and S₃ discrete flavor symmetries. In our models, couplings are also nontrivial representations under the discrete flavor symmetries, and they are modular functions. In the A_4 model, following [26], we assigned the three generations of leptons to the triplet of A_4 , and we restricted coupling constant to be a triplet. In this case, the form of the neutrino mass matrix is strongly restricted as (28), and there are no realistic solution. In the S_3 models, we assigned the three generations of leptons to a singlet and a doublet of S_3 . In these cases, there are five model parameters except for an overall coefficient in Table IV. It may be easier to fit the experimental data by increasing the number of parameters. However, neutrino mass matrices in our models have restricted forms, and are written by modular functions. Thus, it is nontrivial to realize the experimental values by many parameters. Indeed, there are no solution in the case of normal ordering. In the case of inverted ordering, we can reconstruct experimental results except for the δ_{CP} within the 3σ -range in all three models. Additionally, we can fit the mass matrix by using modular functions in all three models. Also, we have predictions on the Majorana CP phases.

It would be interesting to study more general form of couplings including three singlets 1 + 1' + 1'' in A_4 models, or other assignments of leptons in A_4 and S_3 models such that the charged lepton mass matrix is not diagonal and depend on modular functions of τ . Also, it would be interesting to extend our analyses to other congruence subgroups, e.g., $\Gamma(4) \simeq S_4$ and $\Gamma(5) \simeq A_5$.

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APPENDIX: MODULAR FUNCITONS

Here, following [26], we derive modular functions with modular weight 2, which behave as an A_4 triplet and an S_3 doublet.

Suppose that the function $f_i(\tau)$ has modular weight k_i . That is, it transforms under the modular transformation (2),

$$f_i(\tau) \to (c\tau + d)^{k_i} f_i(\tau).$$
 (A1)

Then, it is found that

$$\frac{d}{d\tau} \sum_{i} \log f_{i}(\tau) \rightarrow (c\tau + d)^{2} \frac{d}{d\tau} \sum_{i} \log f_{i}(\tau) + c(c\tau + d) \sum_{i} k_{i}.$$
 (A2)

Thus, $\frac{d}{d\tau} \sum_{i} \log f_i(\tau)$ is a modular function with the weight 2 if

$$\sum_{i} k_i = 0. \tag{A3}$$

We find the following transformation behaviors under T,

$$\begin{split} \eta(3\tau) &\to e^{i\pi/4} \eta(3\tau), \\ \eta(\tau/3) &\to \eta((\tau+1)/3), \\ \eta((\tau+1)/3) &\to \eta((\tau+2)/3), \\ \eta((\tau+2)/3) &\to e^{i\pi/12} \eta(\tau/3), \end{split}$$
(A4)

and the following transformations under S,

$$\eta(3\tau) \rightarrow \sqrt{\frac{-i\tau}{3}}\eta(\tau/3),$$

$$\eta(\tau/3) \rightarrow \sqrt{-i3\tau}\eta(3\tau),$$

$$\eta((\tau+1)/3) \rightarrow e^{-i\pi/12}\sqrt{-i\tau}\eta((\tau+2)/3),$$

$$\eta((\tau+2)/3) \rightarrow e^{i\pi/12}\sqrt{-i\tau}\eta((\tau+1)/3).$$
 (A5)

Using them, we can construct the modular functions with weight 2 by

$$Y(\alpha, \beta, \gamma, \delta | \tau) = \frac{d}{d\tau} (\alpha \log \eta(\tau/3) + \beta \log \eta((\tau+1)/3) + \gamma \log \eta((\tau+2)/3) + \delta \log \eta(3\tau)), \quad (A6)$$

with $\alpha + \beta + \gamma + \delta = 0$ because of Eq. (A3). These functions transform under *S* and *T* as

$$S: Y(\alpha, \beta, \gamma, \delta | \tau) \to \tau^2 Y(\delta, \gamma, \beta, \alpha | \tau),$$
$$T: Y(\alpha, \beta, \gamma, \delta | \tau) \to Y(\gamma, \alpha, \beta, \delta | \tau).$$
(A7)

Now let us construct an A_4 triplet by the modular functions $Y(\alpha, \beta, \gamma, \delta | \tau)$. We use the (3×3) matrix presentations of *S* and *T* as

$$\rho(S) = \frac{1}{3} \begin{pmatrix} -1 & 2 & 2\\ 2 & -1 & 2\\ 2 & 2 & -1 \end{pmatrix}, \quad \rho(T) = \begin{pmatrix} 1 & 0 & 0\\ 0 & \omega & 0\\ 0 & 0 & \omega^2 \end{pmatrix}, \quad (A8)$$

where $\omega = e^{2\pi i/3}$. They satisfy

$$(\rho(S))^2 = \mathbb{I}, \qquad (\rho(S)\rho(T))^3 = \mathbb{I}, \qquad (\rho(T))^3 = \mathbb{I},$$
 (A9)

that is, $\Gamma(3) \simeq A_4$. Using these matrices and $Y(\alpha, \beta, \gamma, \delta | \tau)$, we search an A_4 triplet, which satisfy,

$$\begin{pmatrix} Y_1(-1/\tau) \\ Y_2(-1/\tau) \\ Y_3(-1/\tau) \end{pmatrix} = \tau^2 \rho(S) \begin{pmatrix} Y_1(\tau) \\ Y_2(\tau) \\ Y_3(\tau) \end{pmatrix},$$
$$\begin{pmatrix} Y_1(\tau+1) \\ Y_2(\tau+1) \\ Y_3(\tau+1) \end{pmatrix} = \rho(T) \begin{pmatrix} Y_1(\tau) \\ Y_2(\tau) \\ Y_3(\tau) \end{pmatrix}.$$
(A10)

Their solutions are written by

$$\begin{split} Y_1(\tau) &= 3cY(1,1,1,-3|\tau), \quad Y_2(\tau) = -6cY(1,\omega^2,\omega,0|\tau), \\ Y_3(\tau) &= -6cY(1,\omega,\omega^2,0|\tau), \end{split} \tag{A11}$$

up to the constant c. They are explicitly written by use of eta-function as

$$\begin{split} Y_{1}(\tau) &= \frac{i}{2\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} \right. \\ &+ \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} - \frac{27\eta'(3\tau)}{\eta(3\tau)} \right), \\ Y_{2}(\tau) &= \frac{-i}{\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \omega^{2} \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} + \omega \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} \right), \\ Y_{3}(\tau) &= \frac{-i}{\pi} \left(\frac{\eta'(\tau/3)}{\eta(\tau/3)} + \omega \frac{\eta'((\tau+1)/3)}{\eta((\tau+1)/3)} + \omega^{2} \frac{\eta'((\tau+2)/3)}{\eta((\tau+2)/3)} \right), \end{split}$$
(A12)

where we set $c = i/(2\pi)$. They can be expanded as

$$Y_{1}(\tau) = 1 + 12q + 36q^{2} + 12q^{3} + \cdots,$$

$$Y_{2}(\tau) = -6q^{1/3}(1 + 7q + 8q^{2} + \cdots),$$

$$Y_{3}(\tau) = -18q^{2/3}(1 + 2q + 5q^{2} + \cdots).$$
 (A13)

Similarly, we can construct the modular functions, which behave as an S_3 doublet. Under *T*, we find the following transformation behaviors,

$$\begin{split} \eta(2\tau) &\to e^{i\pi/6} \eta(2\tau), \\ \eta(\tau/2) &\to \eta((\tau+1)/2), \end{split} \tag{A14}$$

$$\eta((\tau+1)/2) \to e^{i\pi/12}\eta(\tau/2).$$
 (A15)

Also, S transformation is represented by

$$\eta(2\tau) \to \sqrt{\frac{-i\tau}{2}} \eta(\tau/2),$$

$$\eta(\tau/2) \to \sqrt{-i3\tau} \eta(2\tau),$$
 (A16)

$$\eta((\tau+1)/2) \to e^{-i\pi/12} \sqrt{-i\tau} \eta((\tau+1)/2).$$
 (A17)

Then, we consider

$$Y(\alpha, \beta, \gamma | \tau) = \frac{d}{d\tau} (\alpha \log \eta(\tau/2) + \beta \log \eta((\tau+1)/2) + \gamma \log \eta(2\tau)).$$
(A18)

These functions are the modular functions with the weight 2 if $\alpha + \beta + \gamma = 0$. They transform under *S* and *T* as

$$S: Y(\alpha, \beta, \gamma | \tau) \to \tau^2 Y(\gamma, \beta, \alpha | \tau),$$

$$T: Y(\alpha, \beta, \gamma | \tau) \to Y(\gamma, \alpha, \beta | \tau).$$
 (A19)

Using $Y(\alpha, \beta, \gamma | \tau)$, we construct the S_3 doublet. For example, we use the (2×2) matrix representations of *S* and *T* as

$$\rho(S) = \frac{1}{2} \begin{pmatrix} -1 & -\sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix}, \qquad \rho(T) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (A20)$$

They satisfy

$$(\rho(S))^2 = \mathbb{I}, \quad (\rho(S)\rho(T))^3 = \mathbb{I}, \quad (\rho(T))^2 = \mathbb{I}, \quad (A21)$$

that is, $\Gamma(3) \simeq S_3$. Using these matrices and $Y(\alpha, \beta, \gamma | \tau)$, we search an S_3 doublet, which satisfy,

$$\begin{pmatrix} Y_1(-1/\tau) \\ Y_2(-1/\tau) \end{pmatrix} = \tau^2 \rho(S) \begin{pmatrix} Y_1(\tau) \\ Y_2(\tau) \end{pmatrix},$$

$$\begin{pmatrix} Y_1(\tau+1) \\ Y_2(\tau+1) \end{pmatrix} = \rho(T) \begin{pmatrix} Y_1(\tau) \\ Y_2(\tau) \end{pmatrix}.$$
(A22)

Their solutions are written by

$$Y_1(\tau) = cY(1, 1, -2|\tau),$$

$$Y_2(\tau) = \sqrt{3}cY(1, -1, 0|\tau),$$
(A23)

up to the constant c. They are explicitly written by use of eta-function as

$$Y_{1}(\tau) = \frac{i}{4\pi} \left(\frac{\eta'(\tau/2)}{\eta(\tau/2)} + \frac{\eta'((\tau+1)/2)}{\eta((\tau+1)/2)} - \frac{8\eta'(2\tau)}{\eta(2\tau)} \right),$$

$$Y_{2}(\tau) = \frac{\sqrt{3}i}{4\pi} \left(\frac{\eta'(\tau/2)}{\eta(\tau/2)} - \frac{\eta'((\tau+1)/2)}{\eta((\tau+1)/2)} \right),$$
 (A24)

where we set $c = i/(2\pi)$. Moreover, they can be expanded as

$$Y_1(\tau) = \frac{1}{8} + 3q + 3q^2 + 12q^3 + 3q^4 \cdots,$$

$$Y_2(\tau) = \sqrt{3}q^{1/2}(1 + 4q + 6q^2 + 8q^3 \cdots).$$
 (A25)

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