Generalized plane waves in Poincaré gauge theory of gravity

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A family of exact vacuum solutions, representing generalized plane waves propagating on the (anti-)de Sitter background, is constructed in the framework of Poincaré gauge theory. The wave dynamics is defined by the general Lagrangian that includes all parity even and parity odd invariants up to the second order in the gauge field strength. The structure of the solution shows that the wave metric significantly depends on the spacetime torsion.

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I. INTRODUCTION

The gauge principle, which was originally formulated by Weyl in the context of electrodynamics [\[1\],](#page-11-0) now belongs to the key concepts which underlie the modern understanding of dynamical structure of fundamental physical interactions. Development of Weyl's idea, most notably in the works of Yang, Mills and Utiyama [\[2,3\]](#page-11-1), resulted in the construction of the general gauge-theoretic framework for arbitrary non-Abelian groups of internal symmetries. Sciama and Kibble extended this formalism to the space-time symmetries, and proposed a theory of gravity [\[4,5\]](#page-11-2) based on the Poincaré group—a semidirect product of the group of spacetime translations times the Lorentz group. The importance of the Poincaré group in particle physics strongly supports the Poincaré gauge theory (PGT) as the most appropriate framework for description of the gravitational phenomena.

The "translational" gauge field potentials (corresponding to the subgroup of the spacetime translations) can be consistently identified with the spacetime coframe field, whereas the "rotational" gauge field potentials (corresponding to the local Lorentz subgroup) can be interpreted as the spacetime connection. This introduces the Riemann–Cartan geometry on the spacetime manifold, since one naturally recovers the torsion and the curvature as the Poincaré gauge field strengths [6–[16\]](#page-11-3) ("translational" and "rotational" one, respectively). The gravitational dynamics in PGT is determined by a Lagrangian that is assumed to be the function of the field strengths, the curvature and the torsion, and the dynamical setup is completed by including a suitable matter Lagrangian.

In the past, investigations of PGT were mostly focused on the class of models with quadratic parity symmetric Lagrangians of the Yang-Mills type, expecting that the results obtained for such a class should be sufficient to reveal essential dynamical features of the more complex general theory, for an overview see [\[17\]](#page-12-0). Recently, however, there has been a growing interest for the extended class of models with a general Lagrangian that includes both parity even and parity odd quadratic terms, see for instance [\[18](#page-12-1)–23]. An important difference between these two classes of PGT models is manifest in their particle spectra. Generically, the particle spectrum of the parity conserving PGT model consists of the massless graviton and eighteen massive torsion modes. The conditions for the absence of ghosts and tachyons impose serious restrictions on the propagation of these modes [24–[29\].](#page-12-2) In contrast, a recent analysis of the general PGT [\[30\]](#page-12-3) shows that the propagation of torsion modes is much less restricted. This is a new and physically interesting dynamical effect of the parity odd sector.

Based on the experience stemming from general relativity (GR), it is well known that exact solutions play an important role in understanding gravitational dynamics. An important class of these solutions consists of the gravitational waves [31–[35\],](#page-12-4) one of the best known families of exact solutions in GR. For many years, investigation of gravitational waves has been an interesting subject also in the framework of PGT [\[36](#page-12-5)–45], as well as in the metricaffine gravity theory which is obtained in the gaugetheoretic approach when the Poincaré group is extended to the general affine symmetry group [\[46](#page-12-6)–54]. Noticing that dynamical effects of the parity odd sector of PGT are not sufficiently well known, recently one of us [\[55\]](#page-13-0) has studied exact plane wave solutions with torsion in vacuum, propagating on the flat background, for the case of the vanishing cosmological constant Λ. In another recent work [\[56\]](#page-13-1) complementary results have been obtained, when the

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generalized pp waves with torsion were derived as exact vacuum solutions of the parity even PGT, but for the case of a nontrivial $\Lambda \neq 0$. In the present paper, we merge and extend these investigations by constructing the generalized plane waves with torsion as vacuum solutions of the general quadratic PGT with nonvanishing cosmological constant. The resulting structure offers a deeper insight into the dynamical role of the parity odd sector of PGT.

The paper is organized as follows. In the next Sec. [II](#page-1-0) we present a condensed introduction to the Poincaré gauge gravity theory, giving the basic definitions and describing the main structures; more details can be found in [6–[9\].](#page-11-3) In Sec. [III](#page-2-0) we start with representing an (anti)-de Sitter spacetime as a gravitational wave and use the properties of the plane-fronted electromagnetic and gravitational waves discussed in [\[57\]](#page-13-2) to formulate an ansatz for the gravitational wave in the Poincaré gauge gravity. The properties of the resulting curvature and torsion 2-forms are studied. In Sec. [IV](#page-5-0) the set of differential equations for the wave variables is derived. It is worthwhile to note that the functions which describe the wave's profile satisfy a system of linear equations, even though the original field equations of the Poincaré gauge theory are highly nonlinear. Solutions of this system are constructed, and their properties are discussed. We demonstrate the consistency of the results obtained with the particle spectrum of the general Poincaré gauge gravity model. Finally, the conclusions are outlined in Sec. [V.](#page-10-0)

Our basic notation and conventions are consistent with [\[7\]](#page-11-4). In particular, Greek indices $\alpha, \beta, \ldots = 0, \ldots, 3$, denote the anholonomic components (for example, of a coframe ϑ^{α}), while the Latin indices i, j, ... = 0, ..., 3, label the holonomic components $(dx^i, e.g.)$. The anholonomic vector frame basis e_{α} is dual to the coframe basis in the sense that e_{α}] $\theta^{\beta} = \delta_{\alpha}^{\beta}$, where β denotes the interior product. The volume 4-form is denoted *n* and the *n*-basis in the space of volume 4-form is denoted η , and the η -basis in the space of exterior forms is constructed with the help of the interior products as $\eta_{\alpha_1...\alpha_n} := e_{\alpha_n} \cdot \cdot \cdot e_{\alpha_1} \cdot \cdot \cdot \cdot$, 4. They are related to the θ -basis via the Hodge dual operator $*$, for example, $\eta_{\alpha\beta} = ^{\ast}(\vartheta_{\alpha} \wedge \vartheta_{\beta})$. The Minkowski metric $\rho_{\alpha\beta} = \text{diag}(\pm 1, -1, -1, -1)$. All the objects related to $g_{\alpha\beta} = \text{diag}(+1,-1,-1,-1)$. All the objects related to the parity-odd sector (coupling constants irreducible pieces the parity-odd sector (coupling constants, irreducible pieces of the curvature, gravitational wave potentials, etc) are marked by an overline, to distinguish them from the corresponding parity-even objects.

II. BASICS OF POINCARÉ GAUGE GRAVITY

The gravitational field is described by the coframe $\theta^{\alpha} =$ $e_i^{\alpha} dx^{\alpha}$ and connection $\Gamma_{\alpha}^{\beta} = \Gamma_{i\alpha}^{\beta} dx^i$ 1-forms. The trans-
lational and rotational field strengths read lational and rotational field strengths read

$$
T^{\alpha} = D\theta^{\alpha} = d\theta^{\alpha} + \Gamma_{\beta}{}^{\alpha} \wedge \theta^{\beta}, \qquad (2.1)
$$

$$
R_{\alpha}{}^{\beta} = d\Gamma_{\alpha}{}^{\beta} + \Gamma_{\gamma}{}^{\beta} \wedge \Gamma_{\alpha}{}^{\gamma}.
$$
 (2.2)

As usual, the covariant differential is denoted D.

The gravitational Lagrangian 4-form is (in general) an arbitrary function of the geometrical variables:

$$
V = V(\vartheta^{\alpha}, T^{\alpha}, R_{\alpha}{}^{\beta}). \tag{2.3}
$$

Its variation with respect to the gravitational (translational and Lorentz) potentials yields the field equations

$$
\mathcal{E}_{\alpha} := \frac{\delta V}{\delta \theta^{\alpha}} = -DH_{\alpha} + E_{\alpha} = 0, \tag{2.4}
$$

$$
\mathcal{C}^{\alpha}{}_{\beta} := \frac{\delta V}{\delta \Gamma_{\alpha}{}^{\beta}} = -DH^{\alpha}{}_{\beta} + E^{\alpha}{}_{\beta} = 0. \tag{2.5}
$$

Here, the Poincaré gauge field momenta 2-forms are introduced by

$$
H_{\alpha} := -\frac{\partial V}{\partial T^{\alpha}}, \qquad H^{\alpha}{}_{\beta} := -\frac{\partial V}{\partial R_{\alpha}{}^{\beta}}, \tag{2.6}
$$

and the 3–forms of the canonical energy–momentum and spin for the gravitational gauge fields are constructed as

$$
E_{\alpha} := \frac{\partial V}{\partial \theta^{\alpha}} = e_{\alpha} V + (e_{\alpha} I T^{\beta}) \wedge H_{\beta}
$$

$$
+ (e_{\alpha} I R_{\beta}^{\gamma}) \wedge H^{\beta}_{\gamma}, \qquad (2.7)
$$

$$
E^{\alpha}{}_{\beta} := \frac{\partial V}{\partial \Gamma_{\alpha}{}^{\beta}} = -\vartheta^{[\alpha} \wedge H_{\beta]}.
$$
 (2.8)

The field equations [\(2.4\)](#page-1-1) and [\(2.5\)](#page-1-2) are written here for the vacuum case. In the presence of matter, the right-hand sides of [\(2.4\)](#page-1-1) and [\(2.5\)](#page-1-2) contain the canonical energymomentum and the canonical spin currents of the physical sources, respectively.

A. Quadratic Poincaré gravity models

The torsion 2-form can be decomposed into the 3 irreducible parts, whereas the curvature 2-form has 6 irreducible pieces. Their definition is presented in the Appendix.

The general quadratic model is described by the Lagrangian 4-form that contains all possible quadratic invariants of the torsion and the curvature:

$$
V = \frac{1}{2\kappa c} \left\{ (a_0 \eta_{\alpha\beta} + \bar{a}_0 \vartheta_{\alpha} \wedge \vartheta_{\beta}) \wedge R^{\alpha\beta} - 2\lambda_0 \eta \right\}
$$

$$
- T^{\alpha} \wedge \sum_{I=1}^{3} \left[a_I \sqrt[t]{(I)} T_{\alpha} \right] + \bar{a}_I \sqrt[I]{T_{\alpha}} \right\}
$$

$$
- \frac{1}{2\rho} R^{\alpha\beta} \wedge \sum_{I=1}^{6} \left[b_I \sqrt[t]{(I)} R_{\alpha\beta} \right] + \bar{b}_I \sqrt[I]{R_{\alpha\beta}} \right]. \tag{2.9}
$$

The Lagrangian has a clear structure: the first line is linear in the curvature, the second line collects torsion quadratic

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terms, whereas the third line contains the curvature quadratic invariants. Furthermore, each line is composed of the parity even pieces (first terms on each line), and the parity odd parts (last terms on each line). The dimensionless constant $\bar{a}_0 = \frac{1}{5}$ is inverse to the so-called Barbero-
Immirzi parameter \bar{f} and the linear part of the Lagrangian Immirzi parameter ξ , and the linear part of the Lagrangian —the first line in [\(2.9\)](#page-1-3)—describes what is known in the literature as the Einstein-Cartan-Holst model. A special case $a_0 = 0$ and $\bar{a}_0 = 0$ describes the purely quadratic model without the Hilbert-Einstein linear term in the Lagrangian. In the Einstein-Cartan model, one puts $a_0 = 1$ and $\bar{a}_0 = 0$.

Besides that, the general PGT model contains a set of the coupling constants which determine the structure of quadratic part of the Lagrangian: ρ , a_1 , a_2 , a_3 and \bar{a}_1 , \bar{a}_2 , \bar{a}_3 , $b_1, ..., b_6$ and $\bar{b}_1, ..., \bar{b}_6$. The overbar denotes the constants responsible for the parity odd interaction. We have the dimension $\begin{bmatrix} \frac{1}{p} \end{bmatrix} = [\hbar]$, whereas a_I , \bar{a}_I , b_I and \bar{b}_I are dimensionless. Moreover, not all of these constants are independent: we take $\bar{a}_2 = \bar{a}_3$, $\bar{b}_2 = \bar{b}_4$ and $\bar{b}_3 = \bar{b}_6$ because some of terms in (2.9) are the same in view of (A14)–(A16) of terms in (2.9) are the same in view of $(A14)–(A16)$ $(A14)–(A16)$.

For the Lagrangian (2.9) from (2.6) – (2.8) we derive the gauge gravitational field momenta

$$
H_a = \frac{1}{\kappa c} h_a,\tag{2.10}
$$

$$
H^{\alpha}{}_{\beta} = -\frac{1}{2\kappa c} \left(a_0 \eta^{\alpha}{}_{\beta} + \bar{a}_0 \vartheta^{\alpha} \wedge \vartheta_{\beta} \right) + \frac{1}{\rho} h^{\alpha}{}_{\beta}, \qquad (2.11)
$$

and the canonical energy-momentum and spin currents of the gravitational field

$$
E_{\alpha} = \frac{1}{2\kappa c} (a_0 \eta_{\alpha\beta\gamma} \wedge R^{\beta\gamma} + 2\bar{a}_0 R_{\alpha}{}^{\beta} \wedge \vartheta_{\beta}
$$

$$
- 2\lambda_0 \eta_{\alpha} + q_{\alpha}^{(T)}) + \frac{1}{\rho} q_{\alpha}^{(R)}, \qquad (2.12)
$$

$$
E^{\alpha}{}_{\beta} = \frac{1}{2} (H^{\alpha} \wedge \vartheta_{\beta} - H_{\beta} \wedge \vartheta^{\alpha}). \tag{2.13}
$$

For convenience, we introduced here the 2-forms which are linear functions of the torsion and the curvature, respectively, by

$$
h_{\alpha} = \sum_{I=1}^{3} \left[a_{I} {}^{*}({}^{(I)}T_{\alpha}) + \bar{a}_{I} {}^{(I)}T_{\alpha} \right], \tag{2.14}
$$

$$
h^{\alpha}{}_{\beta} = \sum_{I=1}^{6} \left[b_{I} {}^{*}({}^{(I)}R^{\alpha}{}_{\beta}) + \bar{b}_{I} {}^{(I)}R^{\alpha}{}_{\beta} \right], \qquad (2.15)
$$

and the 3-forms which are quadratic in the torsion and in the curvature, respectively:

$$
q_{\alpha}^{(T)} = \frac{1}{2} \left[(e_{\alpha} \rfloor T^{\beta}) \wedge h_{\beta} - T^{\beta} \wedge e_{\alpha} \rfloor h_{\beta} \right], \quad (2.16)
$$

$$
q_{\alpha}^{(R)} = \frac{1}{2} \left[(e_{\alpha} \rfloor R_{\beta}{}^{\gamma}) \wedge h^{\beta}{}_{\gamma} - R_{\beta}{}^{\gamma} \wedge e_{\alpha} \rfloor h^{\beta}{}_{\gamma} \right]. \tag{2.17}
$$

By construction, [\(2.14\)](#page-2-1) has the dimension of a length, $[h_{\alpha}] = [\ell]$, whereas the 2-form [\(2.15\)](#page-2-2) is obviously dimensionless, $[h^{\alpha}_{\beta}] = 1$. Similarly, we find for [\(2.16\)](#page-2-3) the dimension of length $[q_\alpha^{(T)}] = [\ell]$, and the dimension of the inverse length, $[q_\alpha^{(R)}] = [1/\ell]$ for [\(2.17\).](#page-2-4)

The resulting *vacuum* Poincaré gravity field equations (2.4) and (2.5) then read:

$$
\frac{a_0}{2} \eta_{\alpha\beta\gamma} \wedge R^{\beta\gamma} + \bar{a}_0 R_{\alpha}{}^{\beta} \wedge \vartheta_{\beta} - \lambda_0 \eta_{\alpha} + q_{\alpha}^{(T)} + \ell_{\rho}^2 q_{\alpha}^{(R)} - Dh_{\alpha} = 0,
$$
\n(2.18)

$$
a_0 \eta^{\alpha}{}_{\beta\gamma} \wedge T^{\gamma} + \bar{a}_0 (T^{\alpha} \wedge \vartheta_{\beta} - T_{\beta} \wedge \vartheta^{\alpha})
$$

+
$$
h^{\alpha} \wedge \vartheta_{\beta} - h_{\beta} \wedge \vartheta^{\alpha} - 2\ell^2_{\rho} Dh^{\alpha}{}_{\beta} = 0. \quad (2.19)
$$

The contribution of the curvature square terms in the Lagrangian [\(2.9\)](#page-1-3) to the gravitational field dynamics in the Eqs. [\(2.18\)](#page-2-5) and [\(2.19\)](#page-2-6) is characterized by the parameter

$$
\ell_{\rho}^2 = \frac{\kappa c}{\rho}.\tag{2.20}
$$

Since $\begin{bmatrix} 1 \\ p \end{bmatrix} = [h]$, this new coupling parameter has the dimension of the area $\begin{bmatrix} 1/2 \\ p/2 \end{bmatrix} = [h^2]$ dimension of the area, $[\ell_\rho^2] = [\ell^2]$.

III. GRAVITATIONAL WAVES IN POINCARÉ GAUGE GRAVITY

Gravitational waves are of fundamental importance in physics, and recently the purely theoretical research in this area was finally supported by the first experimental evidence [\[58](#page-13-3)–60]. A general overview of the history of this fascinating subject can be found in [\[61](#page-13-4)–63].

A. (Anti)-de Sitter spacetime as a wave

Let us now discuss the four-dimensional manifold which can be viewed as an "(anti)-de Sitter spacetime in the wave disguise". As before [\[55\]](#page-13-0), we use the same local coordinates which are divided into two groups: $x^{i} = (x^{a}, x^{A})$, where $x^a = (x^0 = \sigma, x^1 = \rho)$ and $x^A = (x^2, x^3)$. Hereafter the indices from the beginning of the Latin alphabet label the coordinates σ and ρ parametrizing the wave rays, $a, b, c... = 0, 1$, whereas the capital Latin indices, $A, B, C... = 2, 3$, refer to coordinates x^A on the wave front.

The coframe 1-form is chosen as a direct generalization of the ansatz used in [\[55,57\]](#page-13-0):

$$
\hat{\theta}^{\hat{0}} = \frac{q}{2p} [(\hat{U} + 1)d\sigma + d\rho],\tag{3.1}
$$

$$
\hat{\vartheta}^{\hat{1}} = \frac{q}{2p} [(\hat{U} - 1)d\sigma + d\rho],\tag{3.2}
$$

$$
\hat{\vartheta}^{\hat{A}} = \frac{1}{p} dx^A, \qquad A = 2, 3. \tag{3.3}
$$

Here the three functions are given by the following expressions:

$$
\hat{U} = -\frac{\lambda}{4}\rho^2,\tag{3.4}
$$

$$
p = 1 + \frac{\lambda}{4} \delta_{AB} x^A x^B, \qquad (3.5)
$$

$$
q = 1 - \frac{\lambda}{4} \delta_{AB} x^A x^B. \tag{3.6}
$$

The constant parameter λ is an arbitrary real number (which can be positive, negative or zero). As a result, the line element reads

$$
ds^2 = \frac{1}{p^2} \{ q^2 (d\sigma d\rho + \hat{U} d\sigma^2) - \delta_{AB} dx^A dx^B \}. \tag{3.7}
$$

The key object for the description of the wave configurations is the wave 1-form. On the basis of the earlier results [\[55\]](#page-13-0), we introduce a wave 1-form k as

$$
k := d\sigma = \frac{p}{q} (\hat{\vartheta}^{\hat{0}} - \hat{\vartheta}^{\hat{1}}).
$$
 (3.8)

By construction, we have $k \wedge {}^*k = 0$. As before, the wave covector is $k = e \, | \, k$ Its (anholonomic) components are covector is $k_a = e_a | k$. Its (anholonomic) components are thus $k_{\alpha} = \frac{p}{q}(1, -1, 0, 0)$ and $k^{\alpha} = \frac{p}{q}(1, 1, 0, 0)$. Hence, this is a null vector field, $k_{\alpha}k^{\alpha} = 0$.

The corresponding Riemannian connection $\hat{\Gamma}_{\beta}^{\alpha}$ is determined from

$$
d\hat{\vartheta}^{\alpha} + \hat{\Gamma}_{\beta}^{\alpha} \wedge \hat{\vartheta}^{\beta} = 0, \qquad (3.9)
$$

and it reads explicitly (recall that $a, b, ... = 0, 1$ and $A, B, \ldots = 2, 3$

$$
\hat{\Gamma}_{\hat{0}}{}^{\hat{1}} = \hat{\Gamma}_{\hat{1}}{}^{\hat{0}} = -\frac{\lambda \rho}{2} k,\tag{3.10}
$$

$$
\hat{\Gamma}_B{}^a = \frac{p}{q} \hat{\partial}^a e_B \rfloor d \left(\frac{q}{p} \right),\tag{3.11}
$$

$$
\hat{\Gamma}_B^A = \frac{1}{p} (\hat{\vartheta}_B e^A \rfloor dp - \hat{\vartheta}^A e_B \rfloor dp). \tag{3.12}
$$

Substituting [\(3.4\)](#page-3-0)–[\(3.6\)](#page-3-1), we straightforwardly find the curvature:

$$
\hat{R}_{\beta}{}^{\alpha} = \lambda \hat{\vartheta}_{\beta} \wedge \hat{\vartheta}^{\alpha}.
$$
 (3.13)

Thus, the coframe and connection $(\hat{\theta}^{\alpha}, \hat{\Gamma}_{\beta}^{\alpha})$, described by
(3.1) (3.3) and (3.10) (3.12) represent the geometry of a (3.1) – (3.3) and (3.10) – (3.12) , represent the geometry of a torsionless [\(3.9\)](#page-3-5) spacetime of constant curvature [\(3.13\)](#page-3-6). Depending on the sign of λ , we have either a de Sitter or an anti-de Sitter space.

We mark the corresponding geometrical quantities by the hat over the symbols. This geometry will be used as a starting point for the construction of the plane wave solutions in the Poincaré gauge gravity with nontrivial cosmological constant.

It is worthwhile to note that the wave vector field k is a null geodesic in this geometry:

$$
k \wedge {}^*k = 0, \qquad k \wedge {}^*{\hat{D}}k^{\alpha} = 0.
$$
 (3.14)

B. Generalized plane wave ansatz

We will construct new gravitational wave solutions in Poincaré gauge gravity theory by making use of the ansatz for the coframe and for the local Lorentz connection

$$
\vartheta^{\alpha} = \hat{\vartheta}^{\alpha} + \frac{U}{2} \frac{q}{p} k^{\alpha} k, \tag{3.15}
$$

$$
\Gamma_{\alpha}{}^{\beta} = \hat{\Gamma}_{\alpha}{}^{\beta} + \frac{q}{p} (k_{\alpha} W^{\beta} - k^{\beta} W_{\alpha}) k. \tag{3.16}
$$

Here the function $U = U(\sigma, x^A)$ determines the wave profile. The ansatz for the local Lorentz connection is postulated as a direct analogue of the construction used earlier in [\[55\]](#page-13-0), and the vector variable $W^{\alpha} = W^{\alpha}(\sigma, x^A)$ satisfies the same orthogonality property, $k_{\alpha}W^{\alpha} = 0$, which is guaranteed by the choice

$$
W^{\alpha} = \begin{cases} W^a = 0, & a = 0, 1, \\ W^A = W^A(\sigma, x^B), & A = 2, 3. \end{cases}
$$
 (3.17)

Consequently, the generalized ansatz for the Poincaré gauge potentials—coframe [\(3.15\)](#page-3-7) and connection [\(3.16\)](#page-3-8) —is described by the three variables $U = U(\sigma, x^B)$ and $W^A = W^A(\sigma, x^B)$. These should be determined from the gravitational field equations.

The ansatz (3.15) and (3.16) can be viewed as a non-Riemannian extension of the Kerr-Schild-Kundt construction developed recently [64–[67\]](#page-13-5) in general relativity and in modified gravity models. The original Kerr-Schild construction [\[34\]](#page-12-7) in GR is underlain by the existence of preferred null directions. In our approach, the metric defined by the coframe [\(3.15\)](#page-3-7) can be written in a typical Kerr-Schild form

$$
g_{ij} = \hat{g}_{ij} + \frac{q}{p} U k_i k_j, \qquad (3.18)
$$

where \hat{g}_{ij} is the spacetime metric of the (anti)-de Sitter line element [\(3.7\)](#page-3-9), and $k_i = \partial_i |k = \partial_i | d\sigma = (1, 0, 0, 0)$ is the null vector with respect to both \hat{g}_{ij} and g_{ij} . On the other hand, the orthogonality property of the vector W^{α} that defines the radiation piece of the connection [\(3.17\)](#page-3-10), $k_\alpha W^\alpha = 0$, ensures typical radiation structure of the Riemann-Cartan field strengths, the torsion and the curvature.

The line element for this ansatz has the same form [\(3.7\)](#page-3-9), with a replacement

$$
\hat{U} \to \hat{U} + \frac{p}{q}U.\tag{3.19}
$$

It is important to stress that the wave 1-form k is still defined by [\(3.8\),](#page-3-11) which however can be recast into

$$
k = d\sigma = \frac{p}{q}(\theta^{\hat{0}} - \theta^{\hat{1}}).
$$
 (3.20)

Consequently, the anholonomic components of the wave covector $k_{\alpha} = e_{\alpha}$] k still have the values $k_{\alpha} = \frac{p}{q}(1,-1,0,0)$ and $k^{\alpha} = \frac{p}{q}(1, 1, 0, 0)$. As before, this is a null vector field, $k_{\alpha}k^{\alpha} = 0$.

One may wonder why does the factor $\frac{q}{p}$ appear in the ansatz (3.15) and (3.16) . After all, it is always possible to absorb it by redefining U and W^A . However, it is convenient to keep this factor explicitly by noticing that the combination $\frac{q}{p}k^{\alpha} = (1, 1, 0, 0)$ has the constant values. It becomes clear then that the following differential relations are valid:

$$
dk = 0, \qquad d\left(\frac{q}{p}k_{\alpha}\right) = 0. \tag{3.21}
$$

Moreover, although Dk_{α} no longer vanishes, we find

$$
k \wedge D\left(\frac{q}{p}k_{\alpha}\right) = k \wedge \hat{D}\left(\frac{q}{p}k_{\alpha}\right) = 0. \qquad (3.22)
$$

Taking this into account, we straightforwardly compute the torsion 2-form

$$
T^{\alpha} = -k \wedge \frac{q}{p} k^{\alpha} \Theta, \qquad (3.23)
$$

where we introduced the 1-form

$$
\Theta = \frac{1}{2}\underline{d}U + W_a \vartheta^{\alpha},\tag{3.24}
$$

with the differential $\underline{d} := \vartheta^A e_A \underline{d} = dx^A \partial_A$ that acts in the transversal 2-space spanned by $x^A = (x^2, x^3)$.

The structure of the torsion is qualitatively the same as in the case of the vanishing parameter λ , see [\[55\]](#page-13-0). The structure of curvature is more nontrivial, though. A direct computation yields a 2-form

$$
R_{\alpha}{}^{\beta} = \lambda \vartheta_{\alpha} \wedge \vartheta^{\beta} - k \wedge \frac{q}{p} (k_{\alpha} \Omega^{\beta} - k^{\beta} \Omega_{\alpha}), \qquad (3.25)
$$

where we introduced the vector-valued 1-form with the components

$$
\Omega^{\alpha} = \begin{cases} \Omega^{a} = 0, & a = 0, 1, \\ \Omega^{A} = \hat{D}W^{A} + \frac{\lambda}{2}U\vartheta^{A}, & A = 2, 3. \end{cases}
$$
 (3.26)

The transversal covariant derivative is defined by

$$
\hat{D}W^A = \underline{d}W^A + \hat{\Gamma}_B{}^A W^B. \tag{3.27}
$$

Note that the Riemannian de Sitter connection [\(3.12\)](#page-3-4) appears here (more exactly, the corresponding components of the Riemann-Cartan connection [\(3.16\)](#page-3-8) coincide with the Riemannian components: $\Gamma_B^A = \hat{\Gamma}_B^A$).
Let us describe the geometry of the

Let us describe the geometry of the transversal 2-space spanned by $x^A = (x^2, x^3)$ explicitly. The volume 2-form reads $\underline{\eta} = \frac{1}{2} \eta_{AB} \theta^A \wedge \theta^B = \frac{1}{p^2} dx^2 \wedge dx^3$, where $\eta_{AB} =$ $-\eta_{BA}$ is the 2-dimensional Levi-Civita tensor (with $\eta_{23} = 1$). Obviously this is a non-flat space. The corresponding Riemannian connection [\(3.12\)](#page-3-4) yields a nontrivial curvature $\hat{R}_B^A = \lambda \theta_B \wedge \theta^A$ of a 2-dimensional de Sitter space. The volume 4-form of the spacetime manifold reads space. The volume 4-form of the spacetime manifold reads $\eta = \theta^{\hat{0}} \wedge \theta^{\hat{1}} \wedge \theta^{\hat{2}} \wedge \theta^{\hat{3}} = \frac{q^2}{2p^2} k \wedge d\rho \wedge \underline{\eta}$. For the wave 1form we find the remarkable relation

$$
*k = -k \wedge \underline{\eta}.\tag{3.28}
$$

We will denote the geometrical objects on the transversal 2-space by underlining them; for example, a 1-form $\phi = \phi_A \theta^A$. The Hodge duality on this space is defined as usual via ${}^{\pm}\theta_A = \eta_A = e_A \cdot \eta = \eta_{AB} \theta^B$. With the help of [\(3.28\)](#page-4-0), we can verify

$$
*(k \wedge \underline{\phi}) = k \wedge \underline{\ast}\underline{\phi}.
$$
 (3.29)

The new 1-forms (3.24) and (3.26) have the obvious transversality properties:

$$
k \wedge {}^* \Theta = 0
$$
, $k \wedge {}^* \Omega^{\alpha} = 0$, $k_{\alpha} \Omega^{\alpha} = 0$. (3.30)

In accordance with (3.17) and (3.26) , we have explicitly:

$$
\Theta = \vartheta^A \bigg(\frac{1}{2} \hat{D}_A U - \delta_{AB} W^B \bigg), \tag{3.31}
$$

$$
\Omega^A = \vartheta^B \bigg(\hat{D}_B W^A + \frac{\lambda}{2} U \delta^A_B \bigg). \tag{3.32}
$$

Here we denoted $\hat{D}_A = e_A \hat{D}$. Applying the transversal differential to [\(3.24\)](#page-4-1), and making use of [\(3.26\),](#page-4-2) we find

$$
\underline{d}\Theta = \Omega_a \wedge \vartheta^{\alpha}.\tag{3.33}
$$

In essence, this is equivalent to the Bianchi identity DT^{α} = $R_\beta^{\ \alpha} \wedge \vartheta^{\beta}$ which is immediately checked by applying the covariant differential D to [\(3.23\)](#page-4-3) and using [\(3.25\)](#page-4-4). Note that it is crucial to use [\(3.21\)](#page-4-5).

A further refinement of the generalized wave ansatz will be considered in Sec. [IV C](#page-7-0).

C. Irreducible decomposition of gravitational field strengths

Irreducible parts of the torsion and the curvature are as follows. The second (trace) and third (axial trace) irreducible part of the torsion are trivial, $^{(2)}T^{\alpha} = 0$ and $^{(3)}T^{\alpha} = 0$, and the first (pure tensor) piece is nontrivial. and the first (pure tensor) piece is nontrivial:

$$
^{(1)}T^{\alpha} = T^{\alpha} = -k \wedge \frac{q}{p}k^{\alpha}\Theta.
$$
 (3.34)

At the same time, the curvature pieces ⁽³⁾ $R^{\alpha\beta} = {}^{(5)}R^{\alpha\beta} = 0$, whereas whereas

$$
^{(6)}R^{\alpha\beta} = \lambda\vartheta^{\alpha} \wedge \vartheta^{\beta}, \qquad (3.35)
$$

and for $I = 1, 2, 4$:

$$
^{(I)}R^{\alpha\beta} = 2k \wedge {}^{(I)}\Omega^{[\alpha}k^{\beta]} \frac{q}{p}.
$$
 (3.36)

Here $^{(1)}\Omega^{\alpha} + ^{(2)}\Omega^{\alpha} + ^{(4)}\Omega^{\alpha} = \Omega^{\alpha}$, and explicitly we have

$$
{}^{(1)}\Omega^{\alpha} = \frac{1}{2} \left(\Omega^{\alpha} - \vartheta^{\alpha} e_{\beta} \right) \Omega^{\beta} + \vartheta^{\beta} e^{\alpha} \right] \Omega_{\beta}), \quad (3.37)
$$

$$
^{(2)}\Omega^{\alpha} = \frac{1}{2} (\Omega^{\alpha} - \partial^{\beta} e^{\alpha}) \Omega_{\beta}), \tag{3.38}
$$

$$
^{(4)}\Omega^{\alpha} = \frac{1}{2} \vartheta^{\alpha} e_{\beta} \rfloor \Omega^{\beta}.
$$
 (3.39)

The transversal components of these objects are constructed in terms of the irreducible pieces of the 2×2 matrix $\hat{D}_B W^A$: symmetric traceless part, skew-symmetric part and the trace, respectively. Using [\(3.32\),](#page-4-6) we derive ${}^{(I)}\Omega^A = {}^{(I)}\Omega^A{}_B \vartheta^B$, with

$$
{}^{(1)}\Omega^A{}_B = \frac{1}{2} (\hat{D}_B W^A + \hat{D}^A W_B - \delta^A_B \hat{D}_C W^C), \tag{3.40}
$$

$$
^{(2)}\Omega^A{}_B = \frac{1}{2} (\hat{D}_B W^A - \hat{D}^A W_B), \tag{3.41}
$$

$$
^{(4)}\Omega^{A}{}_{B} = \frac{1}{2} \delta^{A}_{B} (\hat{D}_{C} W^{C} + \lambda U). \tag{3.42}
$$

One can demonstrate the following properties of these 1-forms:

$$
\vartheta_{\alpha} \wedge {}^{(1)}\Omega^{\alpha} = 0, \qquad \vartheta_{\alpha} \wedge {}^{(2)}\Omega^{\alpha} = \vartheta_{\alpha} \wedge \Omega^{\alpha}, \qquad (3.43)
$$

$$
\vartheta_{\alpha} \wedge {}^{(4)}\Omega^{\alpha} = 0, \qquad e_{\alpha} \rfloor {}^{(1)}\Omega^{\alpha} = -e_{\alpha} \rfloor \Omega^{\alpha}, \qquad (3.44)
$$

$$
e_{\alpha} \rfloor^{(2)} \Omega^{\alpha} = 0, \qquad e_{\alpha} \rfloor^{(4)} \Omega^{\alpha} = 2e_{\alpha} \rfloor \Omega^{\alpha}, \quad (3.45)
$$

$$
k_{\alpha}^{(1)}\Omega^{\alpha} = -\frac{1}{2}ke_{\alpha}\rfloor\Omega^{\alpha}, \qquad k_{\alpha}^{(2)}\Omega^{\alpha} = 0, \qquad (3.46)
$$

$$
k_{\alpha}^{(4)}\Omega^{\alpha} = \frac{1}{2}k e_{\alpha}\rfloor \Omega^{\alpha}, \qquad k \wedge^{*(2)}\Omega^{\alpha} = 0, \qquad (3.47)
$$

$$
k \wedge {}^{*(1)}\Omega^{\alpha} = -k \wedge {}^{*(4)}\Omega^{\alpha} = -\frac{1}{2}k^{\alpha}\vartheta_{\beta} \wedge {}^{*\Omega^{\beta}}.
$$
 (3.48)

IV. FIELD EQUATIONS

Let us now turn to the quadratic Poincaré gauge model with the general Lagrangian (2.9) , and allow for a nontrivial cosmological constant λ_0 .

Substituting the torsion [\(3.34\)](#page-5-1) and the curvature [\(3.35\)](#page-5-2), [\(3.36\)](#page-5-3), into [\(2.14\)](#page-2-1) and [\(2.15\),](#page-2-2) we find

$$
h^{\alpha} = -k^{\alpha} Z \frac{q}{p},\tag{4.1}
$$

$$
h^{\alpha\beta} = \lambda b_6 \eta^{\alpha\beta} + \lambda \bar{b}_6 \vartheta^{\alpha} \wedge \vartheta^{\beta} - 2k^{[\alpha} Z^{\beta]} \frac{q}{p}, \qquad (4.2)
$$

where we introduced the 2-forms

$$
Z = a_1^*(k \wedge \Theta) + \bar{a}_1 k \wedge \Theta, \tag{4.3}
$$

$$
Z^{\alpha} = \sum_{I=1,2,4} [b_I^*(k \wedge {}^{(I)}\Omega^{\alpha}) + \bar{b}_I k \wedge {}^{(I)}\Omega^{\alpha}]. \quad (4.4)
$$

Making use of (3.30) and (3.43) – (3.48) we can show that

$$
k \wedge h^{\alpha} = 0
$$
, $k \wedge {}^{*}h^{\alpha} = 0$, $k_{\alpha}h^{\alpha} = 0$. (4.5)

As a result, substituting [\(4.2\)](#page-5-6) into [\(2.16\)](#page-2-3) and [\(2.17\)](#page-2-4), we find $q_\alpha^{(T)}=0$ and

$$
q_a^{(R)} = 2\lambda \frac{q}{p} k_\alpha \{ -(b_4 + b_6)^* k e_\beta \} \Omega^\beta
$$

$$
+ (\bar{b}_2 - \bar{b}_6) k \wedge \vartheta_\beta \wedge \Omega^\beta \}. \tag{4.6}
$$

With an account of the properties (4.5) , one can check that

$$
Dh_a = -\hat{D}\left(k_a Z \frac{q}{p}\right),\tag{4.7}
$$

$$
Dh_{\alpha\beta} = -\hat{D}\left(2k_{\left[\alpha}Z_{\beta\right]}\frac{q}{p}\right) + \lambda b_6 \eta_{\alpha\beta\mu} \wedge T^{\mu} + \lambda \bar{b}_6 (T_\alpha \wedge \vartheta_\beta - T_\beta \wedge \vartheta_\alpha).
$$
 (4.8)

The transversal nature of Θ and Ω^A leads to a further simplification. In particular, using (3.29) , we recast (4.3) and [\(4.4\)](#page-5-9) into

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$$
Z = k \wedge \Xi, \qquad Z^A = k \wedge \Xi^A, \tag{4.9}
$$

where we have introduced the 1-forms

$$
\Xi = a_1^* \Theta + \bar{a}_1 \Theta, \tag{4.10}
$$

$$
\Xi^A = \sum_{I=1,2,4} [b_I \, ^{\ast (I)} \Omega^A + \bar{b}_I{}^{(I)} \Omega^A]. \tag{4.11}
$$

A. Wave equations

After all these preparations, we are in a position to write down the gravitational field equations for the quadratic Poincaré gauge model [\(2.9\)](#page-1-3). Substituting the gravitational wave ansatz (3.15) – (3.16) into (2.18) , we derive the first equation

$$
(3a_0\lambda - \lambda_0)\eta_a + \frac{q}{p}k_a * k(e_\beta \rfloor \Omega^\beta)[a_0 - 2\lambda \ell^2_\rho (b_4 + b_6)]
$$

+
$$
\frac{q}{p}k_a k \wedge \{\vartheta_\beta \wedge \Omega^\beta [\bar{a}_0 + 2\lambda \ell^2_\rho (\bar{b}_2 - \bar{b}_6)] - \underline{d}\Xi\} = 0.
$$

(4.12)

Contracting this with k^{α} , we find the value of the constant parameter in the wave ansatz:

$$
\lambda = \frac{\lambda_0}{3a_0},\tag{4.13}
$$

and with an account of [\(3.28\)](#page-4-0) and [\(4.10\)](#page-6-0) we recast [\(4.12\)](#page-6-1) into

$$
[a_0 - 2\lambda \ell_\rho^2 (b_4 + b_6)] \vartheta_A \wedge {}^* \Omega^A + a_1 \underline{d} {}^* \Theta - [\bar{a}_0 + \bar{a}_1 + 2\lambda \ell_\rho^2 (\bar{b}_2 - \bar{b}_6)] \vartheta_A \wedge \Omega^A = 0. \tag{4.14}
$$

The first two terms describe the parity-even model, whereas the last term accounts for the parity-odd sector.

Similarly, by gravitational wave ansatz (3.15) – (3.16) in (2.19) , we obtain the second equation

$$
k_a \frac{q}{p} k \wedge \{ (a_0 + a_1 - 2\lambda \ell_\rho^2 b_6) \vartheta_B \wedge {}^* \Theta + (\bar{a}_0 + \bar{a}_1 - 2\lambda \ell_\rho^2 \bar{b}_6) \vartheta_B \wedge \Theta - 2\ell_\rho^2 \hat{D} \Xi_B \} = 0.
$$
 (4.15)

Note here that the $[ab]$ and $[AB]$ components in [\(2.19\)](#page-2-6) are satisfied identically, and only the mixed $[aB]$ components give rise to the result [\(4.15\)](#page-6-2).

Equation [\(4.14\)](#page-6-3) and the expression inside the curly bracket in [\(4.15\)](#page-6-2) are both 2-forms on the 2-dimensional transversal space spanned by $x^4 = (x^2, x^3)$, and thus [\(4.14\)](#page-6-3) and [\(4.15\)](#page-6-2) describe a system of three partial differential equations for the three variables $U = U(\sigma, x^B)$ and $W^A = W^A(\sigma, x^B)$. Substituting [\(3.31\)](#page-4-9) and [\(3.32\),](#page-4-6) we recast [\(4.14\)](#page-6-3) and [\(4.15\)](#page-6-2) into the final tensorial form

$$
A_0(\hat{D}_A W^A + \lambda U) + a_1 \left(\hat{D}_A W^A - \frac{1}{2} \hat{\Delta} U\right) - \bar{A}_0 \eta^{AB} \hat{D}_A \underline{W}_B = 0, \tag{4.16}
$$

$$
-A_1 \left(\underline{W}_A - \frac{1}{2} \hat{D}_A U \right) + \bar{A}_1 \eta_{AB} \left(W^B - \frac{1}{2} \hat{D}^B U \right) + \ell_\rho^2 (\bar{b}_1 - \bar{b}_2) [\hat{D}_A (\eta^{BC} \hat{D}_B \underline{W}_C) + \eta_{AB} \hat{D}^B (\hat{D}_C W^C + \lambda U)]
$$

$$
+ \ell_\rho^2 (b_1 + b_4) \left[-\hat{\Delta} \left(\underline{W}_A - \frac{1}{2} \hat{D}_A U \right) + \lambda \left(\underline{W}_A - \frac{1}{2} \hat{D}_A U \right) - \hat{D}_A (\hat{D}_B W^B + \lambda U) + \hat{D}_A \left(\hat{D}_B W^B - \frac{1}{2} \hat{\Delta} U \right) \right] = 0. \quad (4.17)
$$

The 2-dimensional transversal space has the (anti)-de Sitter geometry and the corresponding covariant Laplacian reads

$$
\hat{\Delta} = \delta^{AB} \hat{D}_A \hat{D}_B = p^2 \underline{\Delta}, \qquad (4.18)
$$

where $\Delta = \delta^{AB} \partial_A \partial_B$ is the usual Laplace operator.

Note that $\bar{b}_4 = \bar{b}_2$. Here we denoted $\underline{W}_A = \delta_{AB} W^B$ and
 $A = s^{AB} \hat{D}$ and introduced the convenient ebbrewistings $\underline{\hat{D}}^A = \delta^{AB} \hat{D}_B$, and introduced the convenient abbreviations for the combinations of the coupling constants,

$$
A_0 = a_0 - 2\lambda \mathcal{C}_\rho^2 (b_4 + b_6), \tag{4.19}
$$

$$
\bar{A}_0 = \bar{a}_0 + \bar{a}_1 + 2\lambda \ell_\rho^2 (\bar{b}_2 - \bar{b}_6), \tag{4.20}
$$

$$
A_1 = a_0 + a_1 + 2\lambda \ell_\rho^2 (b_1 - b_6), \tag{4.21}
$$

$$
\bar{A}_1 = \bar{a}_0 + \bar{a}_1 + 2\lambda \ell_\rho^2 (\bar{b}_1 - \bar{b}_6). \tag{4.22}
$$

The transversal covariant derivatives do not commute,

$$
(\hat{D}_A \hat{D}_B - \hat{D}_B \hat{D}_A)W^C = \hat{R}_{ABD}{}^C W^D = 2\lambda \delta^C_{[A} \underline{W}_{B]},\qquad(4.23)
$$

and we used this fact when deriving [\(4.16\)](#page-6-4) and [\(4.17\)](#page-6-5). Direct consequences of [\(4.23\)](#page-6-6) are:

$$
\eta^{BC}\hat{D}_B\hat{D}_C\underline{W}_A = \lambda \eta_{AB}W^B, \qquad (4.24)
$$

$$
(\hat{\Delta}\hat{D}_A - \hat{D}_A\hat{\Delta})U = \lambda \hat{D}_A U.
$$
 (4.25)

It is worthwhile to notice that the derivatives of W^A appear in (4.16) – (4.17) only in combinations

$$
\Omega \coloneqq e_{\alpha} \rfloor \Omega^{\alpha} = \hat{D}_A W^A + \lambda U, \tag{4.26}
$$

$$
\Phi \coloneqq \frac{A}{2} \Delta \Theta = \hat{D}_A W^A - \frac{1}{2} \hat{\Delta} U,\tag{4.27}
$$

$$
\bar{\Phi} \coloneqq \Delta \underline{d} \Theta = -\eta^{AB} \hat{D}_A \underline{W}_B, \tag{4.28}
$$

which have a clear geometrical meaning in terms of the curvature and the torsion.

The system (4.16) – (4.17) always admits a nontrivial solution for arbitrary quadratic Poincaré gauge model with any choices of the coupling constants. There are some interesting special cases.

B. Torsionless gravitational waves

The torsion [\(3.23\)](#page-4-3) vanishes when $\Theta = 0$ which is realized, see (3.24) and (3.31) , for

$$
W^A = \frac{1}{2} \delta^{AB} \hat{D}_B U. \tag{4.29}
$$

Substituting this into [\(4.16\)](#page-6-4), we find

$$
A_0\{\hat{\Delta}U + 2\lambda U\} = 0,\t(4.30)
$$

whereas [\(4.17\)](#page-6-5) reduces to

$$
\ell^2_{\rho}(\bar{b}_1 - \bar{b}_2) \eta_{AB} \hat{\underline{D}}^B \{\hat{\Delta}U + 2\lambda U\}
$$

$$
-\ell^2_{\rho} (b_1 + b_4) \hat{D}_A \{\hat{\Delta}U + 2\lambda U\} = 0. \qquad (4.31)
$$

Accordingly, we conclude that the well-known torsionless wave solution of GR with the function U satisfying

$$
p^2 \underline{\Delta} U + 2\lambda U = 0 \tag{4.32}
$$

is an exact solution of the generic quadratic Poincaré gauge gravity model. This is consistent with our earlier results on the torsion-free solutions in Poincaré gauge theory [\[16\]](#page-12-8).

Moreover, the torsionless wave (4.29) – (4.30) represents a general solution for the purely torsion quadratic class of Poincaré models, since this is the only configuration admitted by the system [\(4.16\)](#page-6-4)–[\(4.17\)](#page-6-5) for $b_I = \bar{b}_I = 0$.

C. Torsion gravitational waves

The torsion-free ansatz [\(3.9\)](#page-3-5) can be generalized to

$$
W^{A} = \frac{1}{2} \delta^{AB} \hat{D}_{B} (U + V) + \frac{1}{2} \eta^{AB} \hat{D}_{B} \bar{V}, \qquad (4.33)
$$

with $V \neq 0$. The two scalar functions $V = V(\sigma, x^A)$ and $\bar{V} = \bar{V}(\sigma, x^A)$ define the non-Riemannian piece of the connection, stemming from torsion:

$$
\Theta = -\frac{1}{2} \left(\underline{d}V + \underline{d}\,\overline{V} \right)
$$

=
$$
-\frac{1}{2} \vartheta^A (\hat{D}_A V - \eta_{AB} \underline{\hat{D}}^B \overline{V}).
$$
 (4.34)

For the above choice, the metric and torsion contributions to the connection are described in a rather symmetric way, in terms of the three potentials (U, V, \overline{V}) . In particular, we find for [\(4.26\)](#page-7-3)–[\(4.28\)](#page-7-4):

$$
\Omega = \frac{1}{2} (\hat{\Delta} V + \hat{\Delta} U + 2\lambda U), \tag{4.35}
$$

$$
\Phi = \frac{1}{2}\hat{\Delta}V, \qquad \bar{\Phi} = \frac{1}{2}\hat{\Delta}\bar{V}. \tag{4.36}
$$

Substituting (4.33) into (4.16) and (4.17) , we derive

$$
A_0\Omega + a_1\Phi + \bar{A}_0\bar{\Phi} = 0,\tag{4.37}
$$

$$
\hat{D}_A \left\{ -\frac{1}{2} A_1 V - \frac{1}{2} \bar{A}_1 \bar{V} - \ell_\rho^2 (b_1 + b_4) \Omega - \ell_\rho^2 (\bar{b}_1 - \bar{b}_2) \bar{\Phi} \right\} \n+ \eta_{AB} \hat{D}^B \left\{ -\frac{1}{2} A_1 V + \frac{1}{2} \bar{A}_1 \bar{V} - \ell_\rho^2 (b_1 + b_4) \bar{\Phi} + \ell_\rho^2 (\bar{b}_1 - \bar{b}_2) \Omega \right\} = 0.
$$
\n(4.38)

One needs to pay attention to the noncommutativity of the covariant derivatives and use (4.23) – (4.25) .

As a result, we obtain the system of the three linear second order differential equations for the three functions U, V, \bar{V} :

$$
A_0(\hat{\Delta}V + \hat{\Delta}U + 2\lambda U) + a_1 \hat{\Delta}V + \bar{A}_0 \hat{\Delta}\bar{V} = 0,
$$
\n(4.39)

$$
-\ell_{\rho}^{2}(b_{1}+b_{4})(\hat{\Delta}V+\hat{\Delta}U+2\lambda U)-A_{1}V-\ell_{\rho}^{2}(\bar{b}_{1}-\bar{b}_{2})\hat{\Delta}\bar{V}-\bar{A}_{1}\bar{V}=0, \qquad (4.40)
$$

$$
\ell_{\rho}^{2}(\bar{b}_{1} - \bar{b}_{2})(\hat{\Delta}V + \hat{\Delta}U + 2\lambda U) + \bar{A}_{1}V - \ell_{\rho}^{2}(b_{1} + b_{2})\hat{\Delta}\bar{V} - A_{1}\bar{V} = 0.
$$
\n(4.41)

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D. Solution for potentials

Before starting the analysis of solutions, one can notice that the system (4.40) and (4.41) is actually not equivalent to the original equation [\(4.38\)](#page-7-9). Indeed, by taking the covariant divergence (applying \hat{D}^A) and by taking the covariant curl (applying $\eta^{AB} \hat{D}_B$) of [\(4.38\),](#page-7-9) we derive the pair of equations where on the right-hand sides of [\(4.40\)](#page-7-7) and [\(4.41\)](#page-7-8) one finds not zeros but arbitrary functions, say, $\alpha(\sigma, x^A)$ and $\beta(\sigma, x^A)$, which are *harmonic*, in the sense that they both satisfy equations $\hat{\Delta} \alpha = \hat{\Delta} \beta = 0$. However, one then immediately notices that with the help of redefinitions

$$
V \to V + v, \qquad \hat{\Delta}v = 0, \tag{4.42}
$$

$$
\bar{V} \to \bar{V} + \bar{v}, \qquad \hat{\Delta}\,\bar{v} = 0, \tag{4.43}
$$

we can always remove these nontrivial right-hand sides and come to the system [\(4.40\)](#page-7-7) and [\(4.41\)](#page-7-8).

In other words, a solution of the system (4.39) – (4.41) admits the gauge transformation [\(4.42\)](#page-8-0)–[\(4.43\)](#page-8-1), under which the potentials V and \overline{V} can be shifted by arbitrary harmonic functions. Such gauge transformed potentials are of course still solutions of the Poincaré gauge field equations [\(4.37\)](#page-7-11) and [\(4.38\).](#page-7-9) What is important, however, the curvature and the torsion remain invariant under the redefinition (4.42) – (4.43) of potentials: (4.35) and (4.36) obviously are not affected by the arbitrary harmonic functions.

Now, as a first step, we substitute $(\hat{\Delta}V + \hat{\Delta}U + 2\lambda U)$ from (4.39) into (4.40) and (4.41) . The resulting system reads

$$
\mathcal{E}_{\rho}^{2} \hat{\Delta} \{ a_{1} (b_{1} + b_{4}) V + [-A_{0} (\bar{b}_{1} - \bar{b}_{2}) + \bar{A}_{0} (b_{1} + b_{4})] \bar{V} \} - A_{0} A_{1} V - A_{0} \bar{A}_{1} \bar{V} = 0,
$$
\n(4.44)

$$
\mathcal{E}_{\rho}^{2} \hat{\Delta} \{ a_{1} (\bar{b}_{1} - \bar{b}_{2}) V + [A_{0} (b_{1} + b_{2}) + \bar{A}_{0} (\bar{b}_{1} - \bar{b}_{2})] \bar{V} \} - A_{0} \bar{A}_{1} V + A_{0} A_{1} \bar{V} = 0.
$$
 (4.45)

After solving this system, we can use the potentials V and \overline{V} to substitute them into [\(4.39\)](#page-7-10) which then becomes an inhomogeneous differential equation for the metric potential U:

$$
A_0(\hat{\Delta}U + 2\lambda U) = -(a_1 + A_0)\hat{\Delta}V - \bar{A}_0\hat{\Delta}\bar{V}.
$$
 (4.46)

For the parity-even models with $\bar{a}_I = 0$, $\bar{b}_I = 0$, hence $\bar{a}_2 = 0$ and $\bar{a}_3 = 0$, the system (4.44) (4.45) reduces to the $\bar{A}_0 = 0$ and $\bar{A}_1 = 0$, the system [\(4.44\)](#page-8-2)–[\(4.45\)](#page-8-3) reduces to the two uncoupled equations

$$
a_1(b_1 + b_4)\ell_\rho^2 \hat{\Delta} V - A_0 A_1 V = 0, \qquad (4.47)
$$

$$
(b_1 + b_2) \mathcal{C}_{\rho}^2 \hat{\Delta} \bar{V} + A_1 \bar{V} = 0, \qquad (4.48)
$$

recovering the result of [\[56\]](#page-13-1).

To analyze the system [\(4.44\)](#page-8-2)–[\(4.45\)](#page-8-3), let us rewrite it in matrix form

$$
\hat{\Delta}V - MV = 0, \qquad M := \frac{A_0}{\ell \rho^2} F, \qquad (4.49)
$$

where we combined the potentials into a single object, a "2 vector" $V = \begin{pmatrix} V \\ V \end{pmatrix}$, and the 2 × 2 matrix $F = K^{-1}N$ is constructed from constructed from

$$
K = \begin{pmatrix} \frac{a_1(b_1 + b_4)}{a_1(\bar{b}_1 - \bar{b}_2)} & \bar{A}_0(b_1 + b_4) - A_0(\bar{b}_1 - \bar{b}_2) \\ \frac{a_1(\bar{b}_1 - \bar{b}_2)}{a_1(b_1 + b_2)} + \bar{A}_0(\bar{b}_1 - \bar{b}_2) \end{pmatrix},
$$

\n
$$
N = \begin{pmatrix} \frac{A_1}{\bar{A}_1} & \bar{A}_1 \\ \frac{A_1}{\bar{A}_1} & -A_1 \end{pmatrix}.
$$
 (4.50)

One immediately notices the simple structure of the matrix N which is manifest in the properties

$$
N^{2} = (A_{1}^{2} + \bar{A}_{1}^{2}) \left(\frac{1}{0} \frac{1}{1}\right), \quad \det N = -(A_{1}^{2} + \bar{A}_{1}^{2}).
$$
 (4.51)

One can solve the matrix differential equation [\(4.49\)](#page-8-4) by diagonalizing this system. To achieve this, one needs to find the eigenvalues of the matrix M and to construct the corresponding eigenvectors. Let m^2 be an eigenvalue of the matrix M . It is determined from the corresponding characteristic equation det $(M - m^2) = 0$ which has the meaning of the dispersion relation for the mass:

$$
\ell_{\rho}^4 m^4 \det K + \ell_{\rho}^2 m^2 A_0 \text{tr}(NK) - A_0^2 (A_1^2 + \bar{A}_1^2) = 0. \quad (4.52)
$$

The coefficients of the quadratic equation [\(4.52\)](#page-8-5) are constructed from the coupling constants of the gauge gravity model. From [\(4.50\)](#page-8-6) we have explicitly:

$$
\det K = a_1 A_0 [(b_1 + b_4)(b_1 + b_2) + (\bar{b}_1 - \bar{b}_2)^2], \quad (4.53)
$$

$$
tr(NK) = (a_1A_1 + \bar{A}_0\bar{A}_1)(b_1 + b_4) - A_0A_1(b_1 + b_2) + (a_1\bar{A}_1 - A_0\bar{A}_1 - \bar{A}_0A_1)(\bar{b}_1 - \bar{b}_2).
$$
 (4.54)

For the parity-even models with $\bar{a}_I = 0$, $\bar{b}_I = 0$, hence $\bar{a}_I = 0$ and $\bar{a}_I = 0$ the dispersion equation (4.52) reduces $\bar{A}_0 = 0$ and $\bar{A}_1 = 0$, the dispersion equation [\(4.52\)](#page-8-5) reduces to

$$
[\ell_{\rho}^{2} m^{2} a_{1} (b_{1} + b_{4}) - A_{0} A_{1}]
$$

$$
\times [\ell_{\rho}^{2} m^{2} A_{0} (b_{1} + b_{2}) + A_{0} A_{1}] = 0, \qquad (4.55)
$$

and hence we recover the result [\(4.47\)](#page-8-7)–[\(4.48\)](#page-8-8).

General case with parity-odd terms in the Lagrangian is more complicated. No obvious simplification of [\(4.52\)](#page-8-5) is visible.

Having found the eigenvalues m_1^2 and m_2^2 of the mass matrix M as the two roots of the quadratic equation [\(4.49\)](#page-8-4), one can construct the matrix P that transforms M to its diagonal form. For $M_{12} \neq 0$, the latter reads

$$
P = \begin{pmatrix} -M_{12} & -M_{12} \\ M_{11} - m_1^2 & M_{11} - m_2^2 \end{pmatrix}.
$$
 (4.56)

Multiplying Eq. [\(4.49\)](#page-8-4) by P^{-1} , one then obtains

$$
\hat{\Delta}V' - M'V' = 0,\t(4.57)
$$

where

$$
M' := P^{-1}MP = \begin{pmatrix} m_1^2 & 0 \\ 0 & m_2^2 \end{pmatrix}, \tag{4.58}
$$

and V' is the eigenvector of M, corresponding to the eigenvalues m_1^2 and m_2^2 :

$$
\mathcal{V}' = \begin{pmatrix} \mathcal{V}'_1 \\ \mathcal{V}'_2 \end{pmatrix} = P^{-1} \mathcal{V}
$$

=
$$
\frac{1}{\det P} \begin{pmatrix} (M_{11} - m_2^2) V + M_{12} \bar{V} \\ -(M_{11} - m_1^2) V - M_{12} \bar{V} \end{pmatrix}.
$$
 (4.59)

Recalling $\hat{\Delta} = p^2 \Delta$, we thus recast the system of the field equations [\(4.44\)](#page-8-2) and [\(4.45\)](#page-8-3) into a diagonal form

$$
p^2 \underline{\Delta} \mathcal{V}'_n - m_n^2 \mathcal{V}'_n = 0, \qquad (4.60)
$$

with $n = 1, 2$. The solutions for \mathcal{V}'_n are given in terms of the hypergeometric functions. $F_n(a, b, c, z)$ see [56]. Similar hypergeometric functions ${}_{2}F_{1}(a, b, c, z)$, see [\[56\].](#page-13-1) Similar construction exists in the case $M_{21} \neq 0$.

Now, we can return to (4.46) to find the solution for U. Each solution for \mathcal{V}'_n defines the corresponding solution

$$
\mathcal{V} = P\mathcal{V}' \tag{4.61}
$$

of [\(4.49\)](#page-8-4). Inserting these solutions for V and \bar{V} on the righthand side of [\(4.46\),](#page-8-9) this equation becomes an inhomogeneous differential equation for U. Its general solution is given as a general solution of the homogeneous equation plus a particular solution of the inhomogeneous equation, $U = U_h + U_p$. Note that U_h coincides with the general vacuum solution of GR, see (4.32) . The solution for U obtained by choosing $U_h = 0$ has a very interesting interpretation. Indeed, in that case U reduces just to the particular solution U_p , the form of which is completely determined by the torsion potentials (V, \bar{V}) . A similar mechanism was found also in the parity even sector [\[56\]](#page-13-1). Clearly, there are many other solutions for U_h , and consequently, for U. In each of them, the influence of torsion on the metric is quite clear.

E. Masses of the torsion modes

In order to get a deeper understanding of the role of the torsion in our gravitational wave solution, it is important to examine the mass spectrum of the associated torsion modes. Having found the matrix $F = K^{-1}N$ with the help of [\(4.50\)](#page-8-6), the solutions of the characteristic equation [\(4.52\)](#page-8-5) can be conveniently represented in terms of the matrix $f =$ $(\det K)F$ as

$$
m_{\pm}^{2} = \frac{A_{0}}{2\ell^{2} \det K} (\text{tr} f \pm \sqrt{(\text{tr} f)^{2} - 4 \det f}). \quad (4.62)
$$

This is an exact formula for the mass eigenvalues $m₊²$ associated to the gravitational wave. It is worthwhile to notice that tr $f = -\text{tr}(NK)$, and det $f = (\text{det }N)(\text{det }K)$.

The particle spectrum of PGT has been calculated only with respect to the Minkowski background [\[24](#page-12-2)–29], and never for the (anti)-de Sitter spacetime. Accordingly, we can compare the result [\(4.62\)](#page-9-0) with those existing in the literature only for the values of m^2_{\pm} in the limit of the vanishing cosmological constant. In the limit of $\lambda \to 0$ we vanishing cosmological constant. In the limit of $\lambda \to 0$, we have

$$
\text{tr}f = -[a_1(a_0 + a_1) + (\bar{a}_0 + \bar{a}_1)^2](b_1 + b_4) + a_0(a_0 + a_1)(b_1 + b_2) + 2a_0(\bar{a}_0 + \bar{a}_1)(\bar{b}_1 - \bar{b}_2),
$$

$$
\det f = -a_0 a_1 [(a_0 + a_1)^2 + (\bar{a}_0 + \bar{a}_1)^2]
$$

$$
\times [(b_1 + b_2)(b_1 + b_4) + (\bar{b}_1 - \bar{b}_2)^2],
$$

$$
\det K = a_0 a_1 [(b_1 + b_2)(b_1 + b_4) + (\bar{b}_1 - \bar{b}_2)^2].
$$
 (4.63)

As a first test, we apply the formula [\(4.62\)](#page-9-0) to the parity even sector of PGT. One can straightforwardly see that the corresponding values of m^2 coincide with the masses of the spin 2^{\pm} torsion modes, known from the literature [24] spin-2^{\pm} torsion modes, known from the literature [\[24\]](#page-12-2); compare also with [\[56\].](#page-13-1) This is consistent with [\(4.55\)](#page-8-10).

A more complete verification can be done by comparing [\(4.62\)](#page-9-0) with the recent work of Karananas [\[30\]](#page-12-3), which presently offers the only existing calculation of the complete mass spectrum for the most general PGT with both parity even and parity odd sectors included. A comparison of the Lagrangian (5) of Ref. [\[30\]](#page-12-3) with our expression [\(2.9\)](#page-1-3) is straightforward, although one should be careful since the paper [\[30\]](#page-12-3) contains numerous misprints. As a result, we establish the following relations between our and Karananas' coupling constants (we use the notation t_0 instead of Karananas' λ to distinguish it from our cosmological term):

$$
a_0 = 2\kappa ct_0, \qquad \bar{a}_0 = 0, \tag{4.64}
$$

$$
a_1 = 2\kappa c(-t_1 - t_0), \tag{4.65}
$$

$$
a_2 = 4\kappa c(-t_3 + t_0), \tag{4.66}
$$

$$
a_3 = \kappa c(-t_2 + t_0), \tag{4.67}
$$

$$
\bar{a}_1 = 4\kappa ct_5, \tag{4.68}
$$

$$
\bar{a}_2 = \bar{a}_3 = 2\kappa c t_4. \tag{4.69}
$$

$$
b_1 = 4\rho(-r_1 + r_3), \tag{4.70}
$$

$$
b_2 = 4\rho(-r_3), \tag{4.71}
$$

$$
b_3 = 4\rho(-r_2 + r_3), \tag{4.72}
$$

$$
b_4 = 4\rho(-r_1 + r_3 - r_4), \tag{4.73}
$$

$$
b_5 = 4\rho(-r_3 - r_5), \tag{4.74}
$$

$$
b_6 = 4\rho(-r_1 + r_3 - 3r_4), \tag{4.75}
$$

$$
\bar{b}_1 = \rho(-r_7 + 3r_8),\tag{4.76}
$$

$$
\bar{b}_2 = \bar{b}_4 = \rho(-r_7 - r_8), \tag{4.77}
$$

$$
\bar{b}_3 = \bar{b}_6 = \rho (4r_6 - r_7 - r_8), \tag{4.78}
$$

$$
\bar{b}_5 = \rho(3r_7 - r_8). \tag{4.79}
$$

Substituting the expressions for a_I , b_I and \bar{a}_I , \bar{b}_I into [\(4.63\)](#page-9-1), one finds that the resulting values of m_{\pm}^2 in [\(4.62\)](#page-9-0) exactly
reproduce the result (A 3.5) of Karananas' paper [30] (after reproduce the result (A.3.5) of Karananas' paper [\[30\]](#page-12-3) (after correcting a number of his misprints), which displays the spin- 2^{\pm} torsion modes.

Thus, we conclude that the massive spin- 2^{\pm} torsion modes turn out to be an essential ingredient of our gravitational wave, in the sense that these massive torsion modes determine the structure of the wave profile encoded in the functions V, \bar{V} and U. This is a remarkable result if one recalls that the particle spectrum of PGT is derived from the linearized equations of motion, whereas our gravitational waves are exact solutions of the full nonlinear field equations.

V. DISCUSSION AND CONCLUSION

In this paper, we have found a family of the exact vacuum solutions of the most general PGT model with all possible parity even and parity odd linear and quadratic invariants in the Lagrangian [\(2.9\)](#page-1-3), and with a nontrivial cosmological constant $\lambda_0 \neq 0$. This family represents generalized plane waves with torsion, propagating on the (anti)-de Sitter background. The present paper extends the results obtained recently in [\[55,56\].](#page-13-0)

The underlying construction can be understood as a generalization of the Kerr-Schild-Kundt ansatz from the Riemannian to the Riemann-Cartan geometry of PGT. An essentially new element in this extended formalism is the

ansatz for the local Lorentz connection $\Gamma_{\alpha}{}^{\beta}$, the radiation piece of which is constructed in terms of the null covector field k. The generalized plane wave ansatz (3.15) – (3.16) ensures that the torsion 2-form T^{α} and the radiation piece of the curvature 2-form $S^{\alpha\beta} := R^{\alpha\beta} - \lambda \vartheta^{\alpha} \wedge \vartheta^{\beta}$ satisfy the radiation conditions

$$
k \wedge {}^*T^{\alpha} = 0, \qquad k \wedge {}^*S^{\alpha\beta} = 0, \qquad (5.1)
$$

$$
k \wedge T^{\alpha} = 0, \qquad k \wedge S^{\alpha \beta} = 0, \tag{5.2}
$$

$$
T^{\alpha} \wedge {}^{*}T^{\beta} = 0, \qquad S^{\alpha\beta} \wedge {}^{*}S^{\rho\sigma} = 0. \qquad (5.3)
$$

These relations represent an extension of the well-known Lichnerowicz criterion for identifying gravitational waves [\[68\]](#page-13-6) (see also [\[32\]\)](#page-12-9), based on analogy with the electromagnetic waves, to the framework of the PGT.

In the limit of vanishing torsion, the generalized plane waves with torsion reduce to the family of the Riemannian pp waves on the (anti)-de Sitter background. The pp waves are classified as solutions of Petrov type N, since the corresponding Weyl tensor satisfies the special algebraic condition $k^{\alpha}C_{\alpha\beta\mu\nu} = 0$, see [\[34,35\].](#page-12-7) This criterion can be naturally extended to a Riemann-Cartan geometry of PGT as

$$
k^{\alpha(1)}R_{\alpha\beta\mu\nu} = 0, \qquad (5.4)
$$

where $^{(1)}R_{\alpha\beta\mu\nu}$ is the first irreducible part of the curvature tensor, see [\[55,56\]](#page-13-0). The validity of [\(5.4\)](#page-10-1) for the generalized plane waves with torsion confirms that they are also of type N.

The spacetime torsion is an essential ingredient of the generalized gravitational wave solution; its dynamical characteristics are described by the two potentials V and \bar{V} , satisfying the matrix equation [\(4.49\)](#page-8-4). The mass matrix M is of particular importance for the physical interpretation of the torsion. We demonstrate that, in the limit of $\lambda \to 0$, the eigenvalues of M coincide with the values of the mass square the spin- 2^{\pm} torsion modes, identified in the work of Karananas [\[30\]](#page-12-3). Generically, wave front profile of a generalized plane wave with torsion is thus determined by two spin-2 massive torsion modes and the massless graviton, produced by the third, coframe potential U (which enters the spacetime metric).

It is interesting to note that there exist particular solutions for which the metric potential is completely determined by the torsion. For such solutions, the motion of a spinless test particle is effectively determined by the spacetime torsion.

The results obtained in this work were checked with the help of the computer algebra systems Reduce and Mathematica.

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APPENDIX: IRREDUCIBLE DECOMPOSITION OF THE TORSION AND CURVATURE

The torsion 2-form can be decomposed into the three irreducible pieces, $T^{\alpha} = {^{(1)}}T^{\alpha} + {^{(2)}}T^{\alpha} + {^{(3)}}T^{\alpha}$, where

$$
^{(2)}T^{\alpha} = \frac{1}{3} \vartheta^{\alpha} \wedge (e_{\nu} \rfloor T^{\nu}), \tag{A1}
$$

$$
^{(3)}T^{\alpha} = \frac{1}{3}e^{\alpha} \rfloor (T^{\nu} \wedge \vartheta_{\nu}), \tag{A2}
$$

$$
^{(1)}T^{\alpha} = T^{\alpha} - {^{(2)}}T^{\alpha} - {^{(3)}}T^{\alpha}.
$$
 (A3)

The Riemann-Cartan curvature 2-form is decomposed $R^{\alpha\beta} = \sum_{l=1}^{6} {^{(l)}}R^{\alpha\beta}$ into the 6 irreducible parts

$$
^{(2)}R^{\alpha\beta} = -{}^{*}(\vartheta^{[\alpha} \wedge \bar{\Psi}^{\beta]}), \tag{A4}
$$

$$
^{(3)}R^{\alpha\beta} = -\frac{1}{12} * (\bar{X}\vartheta^{\alpha} \wedge \vartheta^{\beta}), \tag{A5}
$$

$$
^{(4)}R^{\alpha\beta} = -\vartheta^{[\alpha} \wedge \Psi^{\beta]}, \qquad (A6)
$$

$$
^{(5)}R^{\alpha\beta} = -\frac{1}{2}\vartheta^{[\alpha} \wedge e^{\beta]} \rfloor (\vartheta^{\gamma} \wedge X_{\gamma}), \tag{A7}
$$

$$
^{(6)}R^{\alpha\beta} = -\frac{1}{12}X\vartheta^{\alpha} \wedge \vartheta^{\beta}, \qquad (A8)
$$

$$
{}^{(1)}R^{\alpha\beta} = R^{\alpha\beta} - \sum_{I=2}^{6} {}^{(I)}R^{\alpha\beta}, \tag{A9}
$$

where

 $($

$$
X^{\alpha} := e_{\beta} \rfloor R^{\alpha \beta}, \qquad X := e_{\alpha} \rfloor X^{\alpha}, \qquad (A10)
$$

$$
\bar{X}^{\alpha} := {}^{*}(R^{\beta\alpha} \wedge \vartheta_{\beta}), \qquad \bar{X} := e_{\alpha} \rfloor \bar{X}^{\alpha}, \qquad (A11)
$$

and

$$
\Psi_{\alpha} := X_{\alpha} - \frac{1}{4} \vartheta_{\alpha} X - \frac{1}{2} e_{\alpha} \rfloor (\vartheta^{\beta} \wedge X_{\beta}), \qquad (A12)
$$

$$
\bar{\Psi}_{\alpha} := \bar{X}_{\alpha} - \frac{1}{4} \vartheta_{\alpha} \bar{X} - \frac{1}{2} e_{\alpha} \rfloor (\vartheta^{\beta} \wedge \bar{X}_{\beta}). \tag{A13}
$$

Directly from the definitions $(A1)$ – $(A3)$ and $(A4)$ – $(A9)$, one can prove the relations

$$
T^{\alpha} \wedge {}^{(2)}T_{\alpha} = T^{\alpha} \wedge {}^{(3)}T_{\alpha} = {}^{(2)}T^{\alpha} \wedge {}^{(3)}T_{\alpha}, \qquad (A14)
$$

$$
R^{\alpha\beta} \wedge {}^{(2)}R_{\alpha\beta} = R^{\alpha\beta} \wedge {}^{(4)}R_{\alpha\beta} = {}^{(2)}R^{\alpha\beta} \wedge {}^{(4)}R_{\alpha\beta}, \quad (A15)
$$

$$
R^{\alpha\beta} \wedge {}^{(3)}R_{\alpha\beta} = R^{\alpha\beta} \wedge {}^{(6)}R_{\alpha\beta} = {}^{(3)}R^{\alpha\beta} \wedge {}^{(6)}R_{\alpha\beta}, \quad (A16)
$$

whereas $T^{\alpha} \wedge {}^{(1)}T_{\alpha} = {}^{(1)}T^{\alpha} \wedge {}^{(1)}T_{\alpha}$ and $R^{\alpha\beta} \wedge {}^{(1)}R_{\alpha\beta} = {}^{(1)}R^{\alpha\beta} \wedge {}^{(1)}R_{\alpha\beta}$ and $R^{\alpha\beta} \wedge {}^{(5)}R_{\alpha\beta} = {}^{(5)}R^{\alpha\beta} \wedge {}^{(5)}R_{\alpha\beta}$. $R^{\alpha\beta} \wedge {}^{(1)}R_{\alpha\beta}$ and $R^{\alpha\beta} \wedge {}^{(5)}R_{\alpha\beta} = {}^{(5)}R^{\alpha\beta} \wedge {}^{(5)}R_{\alpha\beta}$.

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