

Lagrangian formulation of relativistic Israel-Stewart hydrodynamics

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We rederive relativistic hydrodynamics as a Lagrangian effective theory using the doubled coordinates technique, allowing us to include dissipative terms. We include Navier-Stokes shear and bulk terms, as well as Israel-Stewart relaxation time terms, within this formalism. We show how the inclusion of shear dissipation forces the inclusion of the Israel-Stewart term into the theory, thereby providing an additional justification for the form of this term.

DOI: [10.1103/PhysRevD.94.065042](https://doi.org/10.1103/PhysRevD.94.065042)**I. INTRODUCTION**

Hydrodynamics, and its relativistic incarnation, is a topic of very active theoretical and phenomenological development [1]. Phenomenologically, it seems to provide a good description of physics in heavy ion collisions, making numerical hydrodynamic solvers an indispensable tool in this field. These phenomenological applications are, however, hampered by the fact that a rigorous link between hydrodynamics and “microscopic theory” (in this case, quantum chromodynamics close to deconfinement temperature) is still missing. In fact, a general link between hydrodynamics and *any* microscopic theory, including models where hydrodynamic behavior appears most naturally as an infrared limit [2], is a surprisingly nontrivial problem.

There are several aspects to this: Extending Navier-Stokes hydrodynamics to the relativistic limit will give problems with causality [3–5], due to the presence of arbitrarily high speed dissipative modes. These can be removed by promoting all elements of the energy-momentum tensor to degrees of freedom, and giving them a Maxwell-Cattaneo type equation of motion [3,4] characterized by a “relaxation time” transport coefficient.

Phenomenologically this works, and also avoids unphysical instabilities in the linearized expansion [6–8] (such instabilities would affect the hydrostatic limit, making local entropy nondecrease problematic), but, if one regards the microscopic origin of hydrodynamics as a “gradient expansion” in terms of bulk quantities, it is not immediately clear why additional degrees of freedom need to arise at second order, nor what the relationship between relaxation time τ_π and the usual microscopic “dimensionless small parameter” (the Knudsen number) of the theory is. One expects τ_π to scale as the sound wave attenuation length, but this is not universally true; in any case the extra degrees of freedom are determined by initial conditions, and there is no limitation to their size [9,10]. The existence of this extra small parameter can also be understood from the form of the microscopic spectral function [11], but this turns out to be highly dependent on the exact microscopic theory we are

dealing with. Some works [12] consider it a second independent small parameter (“inverse Reynolds number”) to the gradient “Knudsen number” expansion.

In general, extending these approaches into a consistent general systematic small parameter expansion, with possibly additional higher-order tensor degrees of freedom, hundreds of higher order gradient terms, and the requirement of overall hydrostatic stability entropy nondecrease seems only feasible for a select number of highly symmetric theories and boundary conditions [13–15].

Microscopic fluctuation terms, most likely highly relevant in the low viscosity limit [16–19] are even more mysterious. So far, they have been studied systematically only at linear order [20,21], but evidence exists [22,23] they cannot at all be captured in a perturbative expansion.

A recent attempt to investigate this problem is to rewrite hydrodynamics as a field theory [24–30], with the fields representing the Lagrangian coordinates of the fluid’s volume elements. This picture allows the use of effective field theory techniques [31] to investigate links between microscopic and macroscopic theories without explicitly writing down the microscopic dynamics. In this approach, hydrodynamics can be thought of as an example of an effective field theory with a cutoff, since we do track macroscopic degrees of freedom, but only conserved currents (energy-momentum, conserved charges) averaged over each fluid cell. Thus, long wavelength and microscopic variables can be reformulated in the sense of effective field theory (EFT) as, respectively, infrared and ultraviolet degrees of freedom [18,31], the latter relevant at a microscopic scale l_{UV} (either a small distance or a high wave number/momentum). In the case of hydrodynamics the Knudsen number provides a natural expansion parameter, combining the mean free path l_{mfp} and the gradients into a dimensionless parameter. Effective Lagrangian terms are calculated or corrected with systematic expansion of higher order derivatives $(l_{UV} \cdot \vec{\nabla})^n$ and the fundamental symmetries of the system.

The big apparent limitation of such an approach is that leading corrections in hydrodynamics are dissipative, and

standard Lagrangian theory cannot deal with them. However, methods have been developed to overcome this problem [32–35]. Provided these can be developed consistently for all orders in the EFT, the problems highlighted in the preceding paragraph are all solvable systematically. EFT techniques will automatically separate physical from nonphysical terms, and fluctuations can be included without any approximations by promoting the least action trajectory into a functional integral [19,22,23]. This works in this direction using the “doubled coordinate approach” outlined in Appendix A [27,28] (in this work, a variable with a subscript \pm is doubled; without the subscript it is standard nondissipative). As this work will show, the appearance of extra degrees of freedom at second order, and the relationship between the relaxation time and the microscopic scale, also looks natural within the Lagrangian formalism once the existence of semiclassical Lagrangian and “vacuum stability” (the existence of an action extremum) are taken into account. We show that, as hypothesized in [27], the extra degrees of freedom appear already in the Navier-Stokes limit, but in a way that cannot give a stable hydrostatic vacuum. The extra degrees of freedom in Israel-Stewart hydrodynamics [3,4] are then required to stabilize the theory.

More specifically, we shall show that the form of the Lagrangian for viscous hydrodynamics has to be

$$\mathcal{L} = \mathcal{L}_{\text{ideal}}(B) + \mathcal{L}_{\text{bulk}}(B_{\pm}, u_{\pm}^{\mu}) + \mathcal{L}_{\text{shear}}(B_{\pm}, u_{\pm}^{\mu}, B_{IJ\pm}). \quad (1)$$

The term $\mathcal{L}_{\text{ideal}}(B)$ is the one studied in [22,24,25], corresponds to a conserved local quantity (the microscopic entropy; an infinite number of nonlocal conserved vortices are also present [24]), and generates Euler’s equations. $\mathcal{L}_{\text{bulk}}$ does not require extra degrees of freedom but needs to generate dissipative terms, something done here using the doubling of degrees of freedom (DoFs) described in the Appendix. Shear viscosity requires, as well as doubling, new terms (B_{IJ}) which do not correspond to a conserved quantity and break volume-preserving diffeomorphisms, and yet are necessary to define the shear viscosity. Mathematically, they represent the dissipation of macroscopic energy by microscopic degrees of freedom, above the cutoff.

As we will show, extra degrees of freedom appear in $\mathcal{L}_{\text{shear}}$ “implicitly,” without touching the equations of motion. As long known [32], actions based on such Lagrangians are unstable, without global minimum (Fig. 1 top panel). *This can be understood as the fundamental reason for the instability of the Navier-Stokes equations.* Furthermore, as we shall show, the only way to stabilize this system (have a Lagrangian of the form Fig. 1 bottom panel) is to modify $\mathcal{L}_{\text{shear,bulk}}$ into a term of the form \mathcal{L}_{IS} , with additional degrees of freedom X_{IJ} (corresponding to shear stress terms $\Pi_{\mu\nu}$ in the comoving frame, now promoted to independent

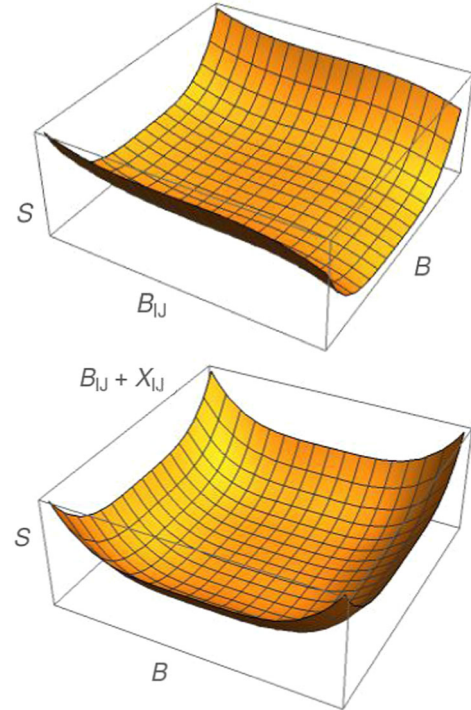


FIG. 1. The qualitative form of the action S in terms of the b B and B_{IJ} degrees of freedom for Navier-Stokes (top panel) and Israel-Stewart hydrodynamics (bottom panel) close to the hydrostatic ($\phi^I \approx x^I$) limit. The first exhibits a saddle point, and the other is positive definite.

degrees of freedom), which gives rise to Israel-Stewart type dynamics. The Lagrangian of this new dynamics is therefore of the form

$$\mathcal{L} = \mathcal{L}_{\text{ideal}}(B_{\pm}) + \mathcal{L}_{\text{IS}}(B_{\pm}, u_{\pm}^{\mu}, X_{IJ\pm}, B_{IJ\pm}). \quad (2)$$

II. A REVIEW OF IDEAL HYDRODYNAMICS

In this section, we give a review of the understanding of Lagrangian hydrodynamics as a field theory, developed in [19,22–24].

Let us consider an uncharged fluid element. In the Lagrangian formulation of hydrodynamics it can be characterized by three scalar fields $\phi^I(\vec{x}, t)$ as degrees of freedom (d.o.f.), where ϕ^I is simply the Lagrangian coordinate of the comoving volume, and \vec{x} the Eulerian (lab) spacetime coordinate. At thermostatic equilibrium these coordinates coincide so $\langle \phi^I \rangle = x^I$, with $I = \{1, 2, 3\}$, and it identifies the physical coordinate in flat 3 + 1 dimensions with metric $g_{\mu\nu} = \text{diag}(-1, 1, 1, 1)$ ¹ [22].

¹Greek letters are used here to specify spacetime coordinates, while latin letters specify comoving coordinates. The Einstein summation convention, with, respectively, four-dimensional (4D) Minkowski and three-dimensional (3D) Euclidean metrics, is used unless specified.

In this formalism the dynamics of fluids, as opposed to other continuous media, can be built up by imposing symmetries on the Lagrangian. Translation symmetry ($\phi^I \rightarrow \phi^I + a^I$ with $a^I = \text{const}$) forces the Lagrangian to depend on derivatives of ϕ^I . Rotation symmetry (isotropy, $\phi^I \rightarrow R^I_J \phi^J$), $R^I_J \in SO(3)$, is straightforwardly implemented by requiring the Lagrangian to be a function of B_{IJ} . Volume preserving deformation symmetry [$\phi^I \rightarrow \xi^I(\phi^J)$, where ξ^I is a different set of coordinates with the same volume element, i.e., $\det(\partial \xi^I / \partial \phi^J) = 1$] implies the Lagrangian depends solely on B . (In the hydrostatic limit each such symmetry gives the ‘‘Goldstone bosons’’ of the sound waves [25].)

In summary, an ideal fluid is described as

$$\mathcal{L} = T_0^4 F(B), \quad B \equiv \det |B^{IJ}| = \det |\partial_\mu \phi^I \partial^\mu \phi^J|, \quad (3)$$

where T_0 is a microscopic scale whose necessity is clear since $\partial \phi^I$ is dimensionless. The role of this microscopic scale (which also absorbs a microscopic degeneracy, such as N_c^2 in gauge theories) is extensively discussed in [19,23] and will be discussed later in this work.

It is straightforward to derive the stress energy tensor from Eq. (3) via the usual Noether current

$$T_{\mu\nu} = \sum_I \frac{\partial \mathcal{L}}{\partial (\partial^\mu \phi^I)} (\partial_\nu \phi^I) - g_{\mu\nu} \mathcal{L}, \quad (4)$$

and we get

$$T_{\mu\nu} = T_0^4 \left(2B \frac{dF}{dB} B_{IJ}^{-1} A_{\mu\nu}^{IJ} - F g_{\mu\nu} \right), \quad (5)$$

where B_{IJ}^{-1} is the inverse of the matrix defined as

$$B^{IJ} \equiv \partial_\mu \phi^I \partial^\mu \phi^J, \quad A_{\mu\nu}^{IJ} \equiv \partial_\mu \phi^I \partial_\nu \phi^J, \quad (6)$$

and the average value is $\Delta^{\mu\nu} \equiv \langle B_{IJ}^{-1} A^{IJ} \rangle = u^\mu u^\nu + g^{\mu\nu}$ [23]. The tensor can be written in the usual hydrodynamic form

$$T^{\mu\nu} = e u^\mu u^\nu + p \Delta^{\mu\nu}, \quad (7)$$

provided the fluid energy density and pressure are, respectively,

$$e T_0^{-4} = -F(B), \quad p T_0^{-4} = F(B) - 2B \frac{dF}{dB}, \quad (8)$$

and the velocity is defined, via $u^\mu \partial_\mu \phi^I = 0 \forall I$, $u_\mu u^\mu = -1$, as

$$u^\mu = \frac{1}{6\sqrt{B}} \epsilon^{\mu\alpha\beta\gamma} \epsilon_{IJK} \partial_\alpha \phi^I \partial_\beta \phi^J \partial_\gamma \phi^K. \quad (9)$$

Using the Gibbs-Duhem relation, relating entropy s to pressure P , energy density ρ [Eq. (8)], and temperature T

$$s = \left. \frac{dP}{dT} \right|_V = \frac{P + e}{T}, \quad (10)$$

we obtain the thermodynamic parameters

$$s = T_0^3 \sqrt{B}, \quad T = -T_0 \frac{\sqrt{B} dF/dB}{g}, \quad (11)$$

where to define temperature one needs to separate the microscopic degeneracy g from T_0 [23] because of the heat capacity’s explicit dependence on g .

This entropy is the only locally conserved quantity (there are infinite numbers of nonlocal conserved vorticity charges [36] corresponding to the Noether charges of diffeomorphisms [24]), giving rise to the conserved current used in [27]

$$K^\mu = \sqrt{B} u^\mu. \quad (12)$$

One can understand the above by *defining* u^μ to be parallel to entropy flow (the so-called Landau frame [36]), since the Euler-Lagrange equations applied to the Lagrangian in Eq. (3) will just yield $\partial_\mu K^\mu = 0$. The symmetry of this Lagrangian against deformation and rotation will then yield the fact that u^μ is always perpendicular to the gradients of ϕ^I .

This way one can always construct K^μ and u^μ out of ϕ^I via a projector

$$P_K^{\mu\nu} = \frac{1}{3!} \epsilon^{\mu\alpha\beta\gamma} \epsilon_{IJK} \partial_\alpha \phi^I \partial_\beta \phi^J. \quad (13)$$

This definition is in accordance with Eq. (12) since clearly

$$K^\mu \equiv P_K^{\mu\nu} \partial_\nu \phi^K. \quad (14)$$

III. NAVIER-STOKES HYDRODYNAMICS

The natural first order term within the Lagrangian is first order, i.e., contains exactly one gradient. Such terms, however, are, as shown in [25], nondynamical since they can always be reabsorbed into field redefinitions. Physically, this should not surprise us since we know that first order terms in the Navier-Stokes equations are dissipative, and hence cannot be represented by ‘‘normal’’ Lagrangian terms. Such terms are, however, amenable to be included via the doubled degrees of freedom formalism [28,32–34] described in Appendix A. In this approach, the two degrees of freedom (represented here by ϕ_\pm according to the formalism introduced within [27]) can be taken as representing the ‘‘system’’ and ‘‘unobserved environment,’’

with the two distinguished by advanced and retarded boundary conditions [28].

Coarse graining usually implies that the dynamics of the theory is a function of currents of conserved quantities, since these are the slowest to equilibrate. These are related to symmetries by Noether's theorem, as well as their derivatives. Since in the last section, we found that the only conserved local charge is the entropy. We construct two independent vectors by doubling the DoFs of Eq. (12), and we get two currents degenerated and independent,

$$K^{i\mu} = \frac{1}{3!} \epsilon^{\mu\alpha_1\alpha_2\alpha_3} \epsilon_{IJK} \partial_{\alpha_1} \phi^{\sigma_1 I} \partial_{\alpha_2} \phi^{\sigma_2 J} \partial_{\alpha_3} \phi^{\sigma_3 K}, \quad (15)$$

where $(\sigma_1\sigma_2\sigma_3) = \{(- - -), (+ + +)\}$, for $i = \{0, 3\}$. The current vectors are still conserved by $\partial_\mu K^{i\mu} = 0$, where further combinations are, in fact, forbidden by conservation laws [27]. K^μ can be understood as a generalization of the entropy current with doubled fields ($i = \{0, 3\}$) with the two new projectors constructed using the properties of Eqs. (13) and (14),

$$P_K^{i\mu\nu} \partial^\lambda \phi^K = \frac{1}{3} (K^{i\mu} \Delta^{\nu\lambda} - K^{i\nu} \Delta^{\mu\lambda}), \quad (16)$$

$$P_K^{i\mu\nu} \partial^\lambda \partial_\nu \phi^K = \frac{1}{3} \partial^\lambda K^{i\mu}. \quad (17)$$

We use the closed time path (CTP) formalism to obtain the Lagrangian and extend the hydrodynamics formulation to first order terms. Following the correction to Noether's theorem described in [34] and the procedure of [27] [Eq. (A3) in Appendix A], we see that the stress-energy tensor in CTP can be obtained by varying just one field by the Noether current

$$\phi^+(x) \rightarrow \phi^+(x + a(x)), \quad \phi^-(x) \rightarrow \phi^-(x). \quad (18)$$

Note that in the physical limit (p.l.), the $\phi^{+K} = \phi^{-K}$ involve $K^{i\mu} = K^\mu$ which also defines $K^{3\mu} \equiv P_K^{3\mu\alpha} \partial_\alpha \phi^{+K}$ and $P_K^{0\mu\alpha} \equiv 0$. As we deal with only variations in $\delta_\phi^+ K^{i\mu} = iP_K^{i\mu\alpha} \partial_\alpha \delta \phi^{+K}$, the other one, $\delta_\phi^- K^{i\mu} = 0$, after a shift of the metric $x \rightarrow x + a(x)$, we get $\delta_x^+ \phi^{+K} = a^\mu \partial_\mu \phi^{+K}$. By inspection it gives

$$\delta_x^+ K^{i\mu} = iP_K^{i\mu\alpha} (\partial_\alpha a_\lambda \partial^\lambda \phi^{+K} + a_\lambda \partial^\lambda \partial_\alpha \phi^{+K}). \quad (19)$$

For the displacement $a(x)$, one can identify a equation of motion for $T_{\mu\nu}$ with a nonvanishing divergence which, however, depends on second-order gradients [27].

Without dissipative terms, + and - Lagrangians are symmetric; hence the results of the previous section merely get doubled [27]. The Lagrangian of Eq. (3), written in terms of $K^{i\mu}$, is then promoted to

$$\mathcal{L}_{\text{CTP}}^{(0)} = T_o^4 F(K_\gamma^3 K^{3\gamma}) - T_o^4 F(K_\gamma^0 K^{0\gamma}), \quad (20)$$

where clearly the first term can be regarded, in the notation of the previous section, as the equation of state defined by B_+ and the second term as the equation of state defined by B_- . In this form, the Lagrangian is just two doubled Lagrangians for two fluids, not talking to each other.

Additional terms are, however, possible. In [27] the bulk viscosity term was constructed to be

$$\mathcal{L}_{\text{CTP}}^{(1)} = T_o^4 \sum_{i,j,k} z_{ijk} (K^{l\gamma} K_\gamma^m) K^{i\mu} K^{j\nu} \partial_\mu K_\nu^k, \quad (21)$$

which contains the same symmetries of ideal hydrodynamics. Small Latin indices (symbolizing where we are in the doubled Lagrangian) are always summed over $\{0, 3\}$. The l, m is also a summation term, but, unlike non-dissipative terms, it mixes 0 and 3, because $l \neq m$ and i, j, k is summed over (for additional details on this notation see [27] Sec. IV).

The eight coefficients z_{ijk} reduce to four $\bar{z}_{ijk} \equiv z_{ijk}|_{\phi^{+K}=\phi^{-K}}$ due to CTP symmetry as well as positivity (ensuring the system is dissipative rather than antidissipative, where gradients *grow*); see Eq. (A1). These terms specify the dependence of the shear and bulk viscosity on entropy $B^{1/2}$ by contractions of $(K_\gamma^l K^{m\gamma} = B)$ in the argument of coefficient z_{ijk} .

As correctly noted in [27], the construction of the shear viscosity term is complicated by the fact that it breaks the volume preserving diffeomorphism symmetry, and hence cannot be just a function of K . Noting that B_{IJ} is the leading term allowed by all but the volume preserving symmetries, and any thermodynamic quantity can be represented as a function of B only, and using

$$u_\gamma \partial_\mu (\Delta^{\gamma\nu}) = \partial_\mu u_\nu = -u^\lambda B_{IJ}^{-1} \partial_\mu \partial_\gamma \phi^I \partial_\nu \phi^J \quad (22)$$

[easily proven by taking the hydrodynamic derivative of Eq. (28) of [24]], we arrive at

$$\mathcal{L}_{\text{CTP}}^{(1)} = T_o^4 \sum_{i,j,k} z'_{ijk} (K^{l\gamma} K_\gamma^m) B B_{IJ}^{-1} \partial^\mu \phi^{iI} \partial^\nu \phi^{jJ} \partial_\mu K_\nu^k, \quad (23)$$

which will, when converted to $\Delta T_{\mu\nu}$ via Eq. (4), produce the usual first order Navier-Stokes equation shear viscosity term η and bulk viscosity ζ that represent most general possible corrections in first order with the symmetry,

$$\sigma^{\mu\nu} \equiv \eta \Delta^{\mu\alpha} \Delta^{\nu\beta} \left(\partial_\alpha u_\beta + \partial_\beta u_\alpha - \frac{2}{3} \eta_{\alpha\beta} \partial_\lambda u^\lambda \right) + \zeta \Delta_{\mu\nu} \partial_\alpha u^\alpha. \quad (24)$$

A Lagrangian similar to Eq. (23) was recently derived in [30] (Sec. VII) using laboratory coordinates.

Summarizing the shear viscosity appears when we introduce “transverse stress” d.o.f.s to break rotational diffeomorphism symmetry of the Lagrangian, $B_{IJ}^{-1} \partial^\mu \phi^I \partial^\nu \phi^J$, where it does not volume preserve diffeomorphisms by a transformation $\det(\partial \xi^{+I} / \partial \phi^{+I}) = 1$. The bulk viscosity, on the other hand, can be formulated by a projection parallel to K^μ . As a result, the Noether current for diffeomorphism invariance, vorticity [24], is explicitly broken by Eq. (23), something we know well since the presence of shear viscosity dissipates vorticity. Bulk viscosity also violates vorticity conservation, but it does so via the “source term” of Noether’s theorem for dissipative theories [28].

The relation between the viscosity as usually defined and the matrix coefficients as well as the instantaneous entropy B is² (note the mixing between shear and bulk viscosity terms and z)

$$\begin{aligned} \zeta = & -B^{3/2}(\bar{z}'_{003} + \bar{z}'_{303} + 2\bar{z}'_{333} + 2\bar{z}'_{033} + \bar{z}_{333} + \bar{z}_{300} \\ & - \bar{z}_{303} + 3\bar{z}_{330}) + B^{5/2}(\bar{z}'_{003,03} + \bar{z}'_{303,03} + \bar{z}'_{333,03} \\ & + \bar{z}'_{033,03} - 2\bar{z}_{333,03} - 2\bar{z}_{303,03} + 2\bar{z}_{330,03} + 2\bar{z}_{300,03}) \\ & - 4B^{5/2}(\bar{z}_{333,00} + z_{303,00}) + 4B^{5/2}(\bar{z}'_{003,33} + \bar{z}'_{303,33} \\ & + \bar{z}'_{333,33} + \bar{z}'_{033,33} + \bar{z}_{330,33} + \bar{z}_{300,33}), \end{aligned} \quad (25)$$

$$\eta = B^{3/2}(\bar{z}_{003} + \bar{z}_{033} + \bar{z}_{303} + \bar{z}_{333}), \quad (26)$$

where $z_{ijk,lm} \equiv \partial z / \partial (K_\nu^l K^{m\nu})$. Equation (23) is very strange since a term B_{IJ} , independent from K^μ and B , is present at linear order. This term represents the dynamics of energy-momentum components perpendicular to flow and cannot be put in terms of DoFs invariant under volume-preserving diffeomorphisms. The shear viscosity term also breaks volume-preserving invariance, something understandable since this kind of dissipation necessarily requires degrees of freedom moving from IR to UV “macroscopic” to “microscopic” across a cutoff $\sim \frac{1}{T_o}$, and the microscopic scale is expected to be immune to deformation. The doubled degrees of freedom make it possible that these first order terms are physical rather than redundancy terms (as first order terms usually are [25,32]).

This means, however, that the doubled Lagrangian does not have a minimum but at most a saddle point (Fig. 1 top panel). This means that while equations of motion can be constructed independent of B_{IJ} , these will be unstable against perturbations in the B_{IJ} direction. This, in fact, explains, in terms of the Lagrangian, the linear-order results of [6–8] about the instability of Navier-Stokes

²During a time dt , entropy should increase from B to $B + dB$, where dB/dt is a function of the gradient. Viscosity in this context should be a function of B only, and this can generate ambiguity in the definition of viscosity. See the discussion in [27] around Eqs. (85), (98), and (99). This issue is also discussed in the conclusion section of this work.

hydrodynamics and makes it apparent nonlinearities cannot cure the instabilities encountered in these works, at least at the classical level.

In reality, this condition exists implicitly for bulk viscosity as well, for while $K_\mu K^\mu$ is positive definite, $K_\mu K_\nu \partial^\nu K^\mu$ is unbounded above or below (it actually generically follows shear viscosity in the sense that both B_{IJ} and $K_\mu K_\nu \partial^\nu K^\mu$ can become large and arbitrarily positive/negative when gradients do not follow the direction of entropy flow). Hence, Eq. (21) is *also* unbounded below, as expected from the fact that bulk and shear viscosity instabilities arise in a very similar way [7]. The way to stabilize the Lagrangian is clearly to add higher order well behaved (even-power) terms, something that requires a few subtleties, as explained in the next section.

IV. ISRAEL-STEWART HYDRODYNAMICS

The Navier-Stokes (NS) shows unphysical behavior for a short wavelength, where a causality problem is most clearly seen by considering linearized perturbations. The equations of motion for a Lagrangian perturbed from the hydrostatic limit

$$\phi^I = x^I + \delta\pi^I(x^\mu), \quad B \rightarrow B_0 + \delta B(x^\mu)$$

will, when linearized in δB and Fourier transformed, yield a dispersion relation for sound waves of frequency w and wave number k

$$w - \left(\frac{\partial P}{\partial \rho}\right)^{1/2} k + i \left(\frac{4\eta}{3sT}\right) k^2 = 0. \quad (27)$$

It is clear that, for the high wave number diffusive mode, the speed of diffusion

$$v = \frac{w}{k} \sim k.$$

Therefore, for $k \frac{4\eta}{3sT} \gg 1$ we go to the limit where modes of propagation can travel faster than light, and then the principle of causality will be violated. As has long been known [6], such a lack of causality implies a lack of stability. The Lagrangian treatment in the previous section, with a demonstration that the Lagrangian is unbound, confirms the lack of stability is not an artifact of leading-order approximations but a fundamental feature of the theory.

That higher-order NS appears neither stable nor causal is not surprising, since the two concepts correlated in relativistic systems, as noncausality generally implies the absence of a “vacuum” (either quantum or thermal), which in turn generically leads to instabilities in the effective theory. The most widely accepted way to solve this issue [3] is to *promote* $\Pi_{\mu\nu}$ to independent degrees of freedom at

second order. This means to consider the energy-momentum tensor to be

$$T^{\mu\nu} = T_0^{\mu\nu} + \Pi^{\mu\nu}, \quad (28)$$

where $T_0^{\mu\nu}$ is given by Eq. (7) and $\Pi^{\mu\nu}$ is arbitrary beyond the constraints of symmetry and transversality

$$\Pi_{\mu\nu} = \Pi_{\nu\mu}, \quad u_\mu \Pi^{\mu\nu} = 0.$$

The equation of motion is engineered to keep $\Pi^{\mu\nu}$ symmetric and to have the Navier-Stokes as the asymptotic value,

$$\tau_\pi^I \Delta^{\kappa\mu} \Delta^{\zeta\nu} u^\alpha \partial_\alpha \pi_{\kappa\zeta} + \pi^{\mu\nu} = \sigma_\eta^{\mu\nu} + \mathcal{O}((\partial u)^2), \quad (29)$$

$$\tau_\pi^\zeta u^\alpha \partial_\alpha \Pi + \Pi = \sigma_\zeta + \mathcal{O}((\partial u)^2), \quad (30)$$

where $\sigma_{\eta,\zeta}^{\mu\nu}$ are, respectively, the Navier-Stokes terms for shear and bulk viscosity [Eq. (24)]. $\Pi^{\mu\nu} = \pi^{\mu\nu} + \Delta^{\mu\nu} \Pi$ where $\pi^{\mu\nu}$ is symmetric and transverse and has 5 DoFs [4,17] (the two Δ^{\dots} projects make sure $\pi^{\mu\nu}$ remains orthogonal to velocity provided initial conditions are so), while $\Pi \equiv \Pi_\mu^\mu/3$ $\Pi = \Pi_\mu^\mu$ is one number representing the trace.

To understand Eq. (29) from the EFT Lagrangian approach, we have to remember that $\pi_{\mu\nu}$ gets promoted to independent degrees of freedom, subject to the constraint of symmetry and transversality with velocity. This degree of freedom is *not* a Noether current [and hence cannot be obtained from an equation such as Eq. (4)] or a conserved quantity. Hence, the way to write this down in our formalism is to use

$$\pi_{\mu\nu} = X_{IJ} \bar{A}_{\mu\nu}^{IJ}, \quad \Pi = X_{IJ} \frac{1}{3} B^{IJ}, \quad (31)$$

where X_{IJ} is a new symmetric matrix of degrees of freedom, one which is not necessarily isotropic but still homogeneous, and $\bar{A}_{\mu\nu}^{IJ}$ are traceless and traced parts of the most general rank 2 tensor transversal to flow projected onto the comoving frame, the scalar-tensor decomposition of Eq. (6),

$$A_{\mu\nu}^{IJ} = \frac{1}{3} \delta_{\mu\nu} \partial_\lambda \phi^I \partial^\lambda \phi^J + \frac{1}{2} (\partial_\mu \phi^I \partial_\nu \phi^J + \partial_\nu \phi^I \partial_\mu \phi^J - \frac{2}{3} \delta_{\mu\nu} \partial_\lambda \phi^I \partial^\lambda \phi^J). \quad (32)$$

The shear part therefore is

$$\pi_{\mu\nu} = X_{IJ} \frac{1}{2} \left(\partial_\mu \phi^I \partial_\nu \phi^J + \partial_\nu \phi^I \partial_\mu \phi^J - \frac{2}{3} \delta_{\mu\nu} \partial_\lambda \phi^I \partial^\lambda \phi^J \right), \quad (33)$$

and the bulk part is

$$\Pi = X_{IJ} \frac{1}{3} \partial_\lambda \phi^I \partial^\lambda \phi^J. \quad (34)$$

Each of these new degrees of freedom can be doubled, as were equilibrium degrees of freedom in the previous section, to model dissipative dynamics. The doubled degrees of freedom are denoted by X_\pm , Π_\pm . We can see the need for $A_{\mu\nu}^{IJ}$ by applying Eq. (22). It has the same role as Eq. (23), but its coefficient is an independent degree of freedom and not fixed by shear viscosity.

The necessity of new degrees of freedom at second order, somewhat arbitrary in other approaches, becomes clear here from symmetry and causality arguments. Since ϕ_I are already fixed by the initial conditions [up to the volume-preserving and $SO(3)$ diffeomorphism invariance of hydrodynamics], second-order terms in the Lagrangian in terms of just ϕ_I would be either nondissipative or noncausal, or lead to violations of conservation laws: Ostrogradski's theorem [37,38] (see Appendix A) prevents us from employing second order derivatives of ϕ as degrees of freedom³ (as would have been the natural continuation in a gradient expansion). A $\pi_{\mu\nu}$ dependent on the first derivatives of ϕ_I , translated into Eq. (24) can only become of the form

$$\pi_{\mu\nu} = f(\partial_\alpha u_\beta).$$

As shown in Eq. (22), such a term projected perpendicular to u_μ will generally contain a pathologically linear B_{IJ}^{-1} term. At the Lagrangian level, this is the realization that, after linearization, it will give a dispersion relation as a complex polynomial

$$w(k) = A_n k^n,$$

and without extreme fine-tuning, such a dispersion relation will inevitably be noncausal.

We note that, provided the Lagrangian contains square terms of $\pi_{\mu\nu}$, Eq. (31) will contain terms $\sim B_{IJ}^2$ and hence, provided $\Pi_{\mu\nu}$'s normalization is positive definite, should be stable even if X_{IJ} are arbitrary. Thus, a bounded Lagrangian stable with respect to Ostrogradski's conditions should contain terms at least up to $\sim \Pi_{\mu\nu} \Pi^{\mu\nu}$ where $\Pi_{\mu\nu}$ depends on X_{IJ} . The leading-order dependence compatible with Lorentz symmetries is Eqs. (33) and (34).

³Note that the Ostrogradski instability is very different [37] from the instability due to the Lagrangian having saddle points which plagues the Navier-Stokes theory (Fig. 1 top panel). In the Ostrogradski case dynamics is still well-defined, but energy is not positive definite. For an isolated system this does not necessarily produce instabilities, but coupled to another system such a system cannot reach equilibrium. For an unbounded *Lagrangian* the instability happens in an isolated system too.

The introduction of these new degrees of freedom in Eq. (31) and the absence of additional conserved currents means Eq. (29) cannot be obtained from a Noether current equation of the form of $\partial_\mu J^\mu = R$, and J^μ, R are derivable from the symmetrized coordinates [Eqs. (4) and (12) are of this form] but must be obtained from the full Lagrangian equation of motion

$$\partial_\mu \frac{\partial \mathcal{L}}{\partial(\partial_\mu Z)} = \frac{\partial \mathcal{L}}{\partial Z}, \quad (35)$$

where $Z = \Pi_{\mu\nu}(X_{IJ}, \phi_I)$. The right-hand side of this equation is fixed by the necessity of the asymptotic theory to relax to Navier-Stokes by symmetry; since $\Pi_{\mu\nu}$ is perpendicular to u_μ , the new DoFs have to have the same number of elements as $A_{\mu\nu}^{IJ}, B_{IJ}$, hence the necessity for the new matrix.

Using $\Pi_{\mu\nu}$ as variables for the Lagrangian allows us to more readily make contact with standard Israel-Stewart (IS) equations, but obscures the role of symmetries of the X and A terms. In particular, note that the projected traceless part of $\frac{\partial \mathcal{L}}{\partial(\partial_\alpha A_{\mu\nu}^{IJ})} \partial_\beta A_{\mu\nu}^{IJ} \sim \Pi_{\alpha\beta} \partial_\gamma u^\gamma$ is the residual violation of conformal symmetry within volume preserving diffeomorphism invariance for $\Pi_{\mu\nu}$ [the third term of Eq. (3.12) of [5]]. A conformal transformation on the Lagrangian would generate such a term in the energy momentum tensor, and hence this term must appear with the opposite sign if conformal invariance was enforced at the IS level. A consistent development of conformally invariant hydrodynamics is, however, left for a different work, since, as can be seen from these equations, the relationship between $X_{IJ}, \Pi_{\mu\nu}$ and A are complex enough to require some work for conformal symmetry to be fully implemented (there is much more to a conformal fluid than the absence of bulk viscosity).

The second law of thermodynamics prevents X_{IJ} from having nondissipative terms and requires, for long distances, that $\Pi_{\mu\nu}$ relaxes to its Navier-Stokes value. The simplest Lagrangian of this form is (note that the projection of $\Pi_{\mu\nu}$ perpendicular to u_μ is taken when $\Pi_{\mu\nu}$ is defined)

$$\mathcal{L} = \mathcal{L}_{\text{ideal}}(B_\pm) + \mathcal{L}_{\text{IS-shear}} + \mathcal{L}_{\text{IS-bulk}} + \mathcal{L}_2((\partial\phi_\pm)^2), \quad (36)$$

$$\begin{aligned} \mathcal{L}_{\text{IS-shear}} = & \frac{1}{2} \tau_\pi^\eta (\pi^{\mu\nu} u_+^\alpha \partial_\alpha \pi_{\mu\nu+} - \pi^{\mu\nu} u_-^\alpha \partial_\alpha \pi_{\mu\nu-}) \\ & + \frac{1}{2} \pi_\pm^{\mu\nu} \pi_{\mu\nu\pm} + \underbrace{[(A^\circ)_{\mu\nu}^{IJ} \partial^\mu K^\nu]_\pm}_{\sim \sigma_\mu^\eta}, \end{aligned}$$

$$\begin{aligned} \mathcal{L}_{\text{IS-bulk}} = & \frac{1}{2} \tau_\pi^\zeta (\Pi_- u_+^\alpha \partial_\alpha \Pi_+ - \Pi_+ u_-^\alpha \partial_\alpha \Pi_-) \\ & + \frac{1}{2} \Pi_\pm^2 + \underbrace{[K_\mu \partial^\mu B]_\pm}_{\sim \sigma^\zeta}, \end{aligned}$$

where $(A^\circ)_{\mu\nu}^{IJ} \equiv A_{\mu\nu}^{IJ}/B_{IJ}$ and the first term is the ideal one [Eq. (3)], the next two terms give the dissipative dynamics of $\Pi_{\mu\nu}$, and the last one gives the Navier-Stokes source Eq. (24) (note the explicit Lagrangian dependence of Sec. III disappears, as its presence would give rise to unstable modes). \mathcal{L}_2 contains nondissipative ‘‘hydrodynamic’’ terms to second order in gradient enumerated in works such as [39]. It will contain shear and bulk-mixing terms, as well as further restrictions due to, for example, conformal symmetry. Its construction, as in all EFTs, is based on enumerating all second order terms compatible with Lorentz and homogeneity symmetries.

It is easy to see that Eq. (29) arises as an equation of motion with respect to X and a

$$T^{\mu\nu} = T_0^{\mu\nu}(B, u^\mu) + \Pi^{\mu\nu}(X_{IJ}, A^{\mu\nu}),$$

where $T_0^{\mu\nu}$ is given by the ideal tensor Eq. (4) and $\Pi^{\mu\nu}$ is perpendicular to u_μ . It is also clear that this Lagrangian is stable [the action is bounded, with one minimum, in the near-hydrostatic ($\phi_I \approx \vec{x}$) limit, as shown in Fig. 1 bottom panel] against both the ‘‘old’’ DoFs ϕ_I , and the new one X_{IJ} : $\Pi_{\mu\nu} \Pi^{\mu\nu}$ is positive definite. As long as τ_π is large enough to guarantee slower than light diffusion propagation, the kinetic term will not contain ghost modes. Beyond this restriction, $\tau_\pi^{\eta,\zeta}$ can have an arbitrary dependence on the equilibrium DoF B .

V. DISCUSSION

Our results provide a general method to extend the EFT which completes the insights of [7,8,11]. For stability the theory in its Lagrangian description has to contain strictly positive powers of B_{IJ} and its derivatives, which means even powers with positive combinations of gradients and traces at the Lagrangian level. An odd power will generally mean an unstable equation of motion, of the type found in [7,8].

Beyond these constraints, all the allowed combinations of B, B_{IJ}, X_{IJ} and their gradients can go into the Lagrangian, with terms suppressed in powers of the gradient by the Knudsen number. Naively, terms with X_{IJ} are ‘‘one higher order in gradient’’ with respect to B_{IJ}, B . This is what one expects when the theory is close to equilibrium and the viscosity η , relaxation time τ_π , temperature T , and entropy s are related by $\tau_\pi T \sim \eta/s$. This relation, however, is *not* universal. In situations of critical slowing down it manifestly fails [40], since shear viscosity is at a minimum while X_{IJ} never equilibrate.

More generally, since X_{IJ} are independent degrees of freedom, their equilibration time in a classical theory depends on initial conditions, a dependence that, at least in examples with reduced dimension, has been shown to be highly nontrivial [9,10]. This is why the proposal of [12] to treat such terms as independent of the gradient expansion

appears justified. That said, the fact that the leading order dynamics of such terms is only dissipative does provide an explanation for the applicability of the EFT expansion in a regime where there is scope for it failing [41]. After all, hydrodynamic behavior appears universal in nature.

These extra degrees of freedom provide a conceptual framework for unifying Israel-Stewart hydrodynamics with anisotropic hydrodynamics, recently developed as a successful phenomenological theory [42,43]. There is, in fact, no distinction between usual Israel-Stewart and anisotropic hydrodynamics in principle, since the appearance of DoFs corresponding to anisotropies is inevitable in the former. The phenomenological success of [42,43] might be due to the fact that the latter keeps track, within the gradient expansion, the fact that anisotropies in the gradient are very different in the transverse and longitudinal directions. Hence, the number of terms considered should vary between these directions.

It should be remembered that the dissipative terms generally violate conservation laws [28], but, for an EFT expansion of a highly symmetric theory, this violation typically goes as a higher order than the Lagrangian [27]. The Lagrangians examined here are no exception, since the violation of energy conservation examined in Sec. III is $\sim (l_{mfp} \nabla)^2$ [27] while that in Sec. IV should be, from [28] Eq. (2.63),

$$\begin{aligned} \Delta T^{0i} &\sim \dot{X} \frac{\partial \mathcal{L}_{\text{diss}}}{\partial X} + \ddot{X} \frac{\partial \mathcal{L}_{\text{diss}}}{\partial \dot{X}} + (l_{mfp} \nabla)^2 (\nabla X) \\ &\sim (l_{mfp} \nabla) (\nabla X)^2 + (l_{mfp} \nabla)^2 (\nabla X). \end{aligned}$$

However, as the convergence of the IS expansion is unclear in the general case, this issue will need to be examined on a case-by-case basis.

The introduction of X_{IJ} at second order raises the question of whether additional degrees of freedom of this sort are required at higher order. To answer this question, one must remember that Ostrogradski's theorem can be applied sequentially. Once second order derivatives of X_{IJ} are taken into account, new degrees of freedom are required to ensure thermodynamic stability of the theory. These terms cannot be rank two tensors, since by the Coleman-Mandula [44] theorem the only conserved quantity is $T_{\mu\nu}$, and hence a hypothetical X_2^{IJ} can be always absorbed into a redefinition of the nonconserved X_{IJ} . Hence, new terms will come as contractions of higher rank tensors, for example, $X_2^{JKL} X_{IJ} X_{KL}$, with new higher rank terms again being nonconserved. Within the Boltzmann equation [12] one can consider these extra terms as related to moments of the Boltzmann equation, but our theory is “bottom-up” so, beyond these terms encoding microscopic correlations of some sort [45], we can say nothing about them except their symmetry properties.

A topic which we did not elaborate is the role of the entropy in this dynamics. The conservation of the entropy

current arises as an equation of motion if the nondissipative Lagrangian in Sec. II is analyzed in terms of its equations of motion rather than the energy-momentum tensor. To investigate the entropy current systematically in terms of the Lagrangian, we would need a quantitative relation between action and entropy. In the adiabatic limit (microscopic DoFs are parametrically faster than macroscopic ones) we can use Matsubara's prescription [46]

$$t \rightarrow \frac{i}{T}, \quad S_{\text{quantum}} \rightarrow \frac{F}{T} \quad (37)$$

(where S_{quantum} is the action of the quantum theory, F is the free energy, and T is the temperature) together with the semiclassical limit ($T_0 \rightarrow \infty$). [Note that expansion beyond this limit is uncorrelated from the gradient expansion [19,23]. It generally goes as $T_0 \sim g^{-1}$, so $\sim N_c^{-2}$ in $SU(N_c)$ Gauge theories.]

$$F = T \ln Z, \quad Z \simeq \exp(T_0^4 S_{\text{minimum}}). \quad (38)$$

From the definition of the CTP formalism [27] of Eq. (A3) it is clear that the macroscopic entropy of a fluid at temperature T will be

$$s = \frac{1}{T} \int_0^T dT' \int_0^{2\pi} \mathcal{L}(\phi_{\pm}(x, t = e^{i\theta/T'}) d\theta d^d x. \quad (39)$$

These relations ensure that there is a one-to-one correspondence between the Lagrangian terms in the effective theory and the entropy current, which needs to be investigated term by term.

In the ideal limit, where the mixing term in Eq. (A1) vanishes, this entropy is simply equal to $T_0^3 B^{1/2}$ and is conserved, but, as elucidated in [28], dissipative terms generally introduce “violations” of Noether's theorem via sources in the unobserved part of the system. Entropy conservation is, of course, the most well known of such violations. For $T \ll T_0$ we should recover the entropy formulas in [27]. Hence, the formulas argued for in [4],

$$\partial_{\mu}(su^{\mu}) = \partial_{\mu}(\sqrt{B}u^{\mu}) \sim 0|_{i=0} + \Pi_{\mu\nu}\Pi^{\mu\nu}|_{i \geq 1}, \quad (40)$$

where i corresponds to gradient order, can be justified from the Lagrangian description. Higher order terms in the effective Lagrangian with couplings between X_{IJ} and gradients of B will therefore also enter in the entropy current. In a sense, the nondecrease of entropy in this formulation is equivalent to the Lagrangian being bound from below, which reinforces the connection between our work and [7,8].

This “semiclassical” limit, though, is likely to severely underestimate entropy formation at *low* viscosity, for the first of the terms in the inequality required for hydrodynamics to hold [18,19,23],

$$\frac{1}{T_0} \ll \frac{\eta}{Ts} \ll \frac{1}{\partial u}, \quad (41)$$

will inevitably break down as $\eta \rightarrow 0$. In this case Eq. (38) will also break down, and one will have to do the full functional integral, with T_0 as the coupling constant, i.e., replace in Eq. (38)

$$e^{S_{\text{minimum}}(B,X)} \rightarrow \int \mathcal{D}[B, X] e^{T_0^4 \int \mathcal{L}(B,X) d^4x}.$$

Relatively elementary considerations, such as the fact that vortices, which require no energy to form, do not propagate, suggest the expansion around T_0 is highly non-perturbative, possibly necessitating numerical methods to be properly taken into account. Physically, this means that excitations of macroscopic degrees of freedom ϕ_I and X , and the coupling of these to microscopic degrees of freedom, give a non-negligible description of the entropy. The most likely appearance of such degrees of freedom is within the variables $A_{IJ}^{\mu\nu}$ of Eq. (32), classically forbidden within the ideal hydrodynamic limit, as shown by the first efforts to simulate this system numerically [23].

Such effects might be crucial in the low viscosity high flow limit, where the phenomenon of turbulence [36] occurs in the classical limit. In our picture, turbulence can be understood as the occurrence of multiple irregularly distributed minima and saddle points in the action as a function of field configurations (Fig. 2). In this limit deviations from the semiclassical approximations are likely to dominate even for “small gradients,” precisely because $T_0 \sim \langle \partial u \rangle$, and the EFT expansion likely breaks down [41,45].

Such dynamics might have a role in clarifying the mysteries the phenomenon of turbulence still yields. Since T_0 in Eq. (41) is proportional to the distance scale of *microscopic* DoFs, $\mathcal{O}(1000(100 \text{ fm}^3)^{-1})$ in a heavy ion collision (or $10^4/m^3$ in a cold atom system), such corrections, as yet completely unexplored, could become crucial to connect our EFT to phenomenology. Naively, the fluctuation-driven mixing of turbulent and microscopic

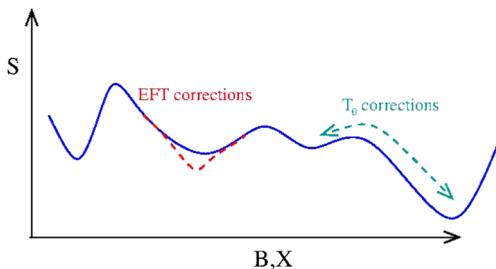


FIG. 2. The profile of the action in a “turbulent” system (small viscosity and well away from the hydrostatic limit) and a qualitative sketch of the role of corrections of gradient and T_0 terms.

degrees of freedom will shorten microscopic thermalization, invalidating “hydrodynamicization” scenarios such as [47], at least beyond the planar limit. Effective field theories emerge from renormalization group flow of microscopic theories. Hydrodynamics is ultimately *not* different, except for the fact that the effective Lagrangian must be nonunitary to take into account entropy exchanges between the microscopic and macroscopic scales [45]. Furthermore, this exchange assumes the existence of a microscopic scale which is not invariant under macroscopic transformations, requiring terms noninvariant under rescaling even in a theory which macroscopically is invariant under such transformations. This is manifest at first order already, since viscosity, ultimately due to a “physical” microscopic scale, is represented by terms that violate rescaling diffeomorphisms. Given these considerations, any strongly coupled relativistic microscopic field theory should in principle coarse grain to something like Eq. (2) provided coarse graining is done within the CTP formalism, as suggested in [48].

In conclusion, we have shown that the Lagrangian formalism incorporates naturally both the Navier-Stokes and the Israel-Stewart terms of hydrodynamics, and it naturally explains the appearance and scaling of these terms in a way that is somewhat model dependent and *ad hoc* in other approaches. We await to see to what extent this proof can be generalized to arbitrary order.

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APPENDIX A: A LAGRANGIAN DESCRIPTION OF CONSERVATIVE SYSTEMS

1. Introduction

In this short review we use the notation of [27]. The Lagrangian formulation is a very powerful technique for formulating both classical and quantum problems. There is a demand for a systematic procedure to incorporate general dissipative features in a variational principle. The best way to establish this change is by theoretically modifying the formulation of the principle of least action [32–34]. The main point is that the variational principle needs *boundary conditions* and temporal invariance. As a result, Liouville’s theorem implies time symmetry, something easy to derive by considering Green’s functions [28].

To go beyond this limitation we will use closed-time path (CTP) [27] in the description of a closed system. For each field $\psi(x)$, we double to a set of variables $\psi \rightarrow (\psi^+, \psi^-)$

with the same initial conditions. Physically, the context of Lagrangian mechanics shows each variable represents an equation of motion where one “absorbs” and another “loses” energy,

$$S_{\text{CTP}}[\hat{\psi}] = \int_{t_f}^{t_i} d^{d+1}x \{ \mathcal{L}_s[\psi^+] - \mathcal{L}_s^*[\psi^-] \}. \quad (\text{A1})$$

In the context of this work, the two systems can be considered to be the infrared (macroscopic) and ultraviolet (microscopic) degrees of freedom.

To reproduce dissipative dynamics via a Lagrangian, each DoF has to ensure the *equality conditions* (sometimes called “physical limit”). In other words, $\psi^+(t_f, \mathbf{x}) = \psi^-(t_f, \mathbf{x})$ and $\partial_t^n \psi^+(t_i, \mathbf{x}) = \partial_t^n \psi^-(t_i, \mathbf{x})$, with ψ^\pm an function of class n . *Initial conditions* maintain a causality in a nonconservative system while generating a difference between advanced and retarded Green’s functions.

The CTP has a degeneracy associated with $\psi^+ \leftrightarrow \psi^-$; that is, both axes obey the same equation of motion, due to the double DoFs that imply in the action (A1),

$$S_{\text{CTP}}[\psi^+, \psi^-] = -S_{\text{CTP}}^*[\psi^-, \psi^+]. \quad (\text{A2})$$

The degeneracy introduced in ψ disappears in p.l., $\psi^+(x) = \psi^-(x)$, only the variable ψ^+ has a physical meaning and another vanishes [27]. The effective Lagrangian is therefore of the form (in our case $\psi = \phi$, introduced in Sec. II and X in Sec. IV)

$$S_{\text{eff}}[\hat{\psi}] = S_s[\hat{\psi}^+] - S_s^*[\hat{\psi}^-] + S_i[\hat{\psi}^+, \hat{\psi}^-], \quad (\text{A3})$$

where the nonaccessible DoFs $S_i(\hat{\psi})$ are microscopic or “high energy,” called internal energy and assumed to be a perturbation close to the ideal limit. The subtraction is equivalent [27,34] to integrating out unseen degrees of freedom.

The variational principle of S_s is defined by the Hessian matrix $\delta^2 S_i / \delta \phi^+ \delta \phi^-$. The first and second terms are responsible to conserved current of energy momentum. The S_i is a small perturbation, which contains all terms due to integration out more dissipative forces. To ensure Liouville’s theorem (unitarity in the quantum theory), we would need to compute all terms of action including the ones we do not keep track of. Care needs to be taken to translate standard Lagrangian mechanics results into the doubled coordinate formalism. For instance, as discussed in [28] dissipative terms $S_i(\psi_+, \psi_-)$ generally “break” conservation laws inferred from Noether’s theorem (friction is an everyday example). Nevertheless, it is possible to extend such theorems into the dissipative domain and gauge their applicability on a case-by-case basis. In the next section we will consider the case of Ostrogradski’s theorem, necessary for the derivation in Sec. IV.

Note that the approach described here is not unique. For instance, one can integrate out the unseen degrees of freedom explicitly, as was done in [35]. We think the method used here has more potential for a systematic gradient expansion, since, as shown in [27], violations of nonentropy conservation laws (energy, charge, etc.) can be systematically organized as “higher order gradient” terms, by ensuring the correct gradient power counting for S_i with respect to S_s . In a direct integrating out procedure, all conservation law violations are parametrically similar (essentially the “violation” is contained in the DoFs one integrates out), and because of this the approximate invariance under conservation laws in [35] depends on linearization as well as the EFT expansion.

2. Ostrogradski’s theorem

Ostrogradski’s theorem [37,38] limits “well-behaved” theories to Lagrangians with two derivatives. Higher derivative terms, even with a well-defined Lagrangian minimum, will have an unstable mode in the *Hamiltonian* (essentially, negative energy “states”). This makes local thermalization for such systems *and any systems coupled to them* obviously problematic. In particular, the EFT expansion generally breaks down because the system has a vacuum instability.

To check that Ostrogradski’s theorem applies to dissipative Lagrangians consider a doubled field Lagrangian density with field coordinate $\phi(x^\mu)$,

$$\Lambda(\phi^\pm, \phi_\mu^\pm, \dots, \phi_{\mu_1 \dots \mu_n}^\pm) = \mathcal{L}_o(\phi^+, \phi_\mu^+, \dots, \phi_{\mu_1 \dots \mu_n}^+) + \mathcal{K}(\phi^\pm, \phi_\mu^\pm, \dots, \phi_{\mu_1 \dots \mu_n}^\pm), \quad (\text{A4})$$

where $\phi_{\mu_1 \dots \mu_n}^\pm \equiv \partial_{\mu_1} \dots \partial_{\mu_n} \phi^\pm$. We will use $(\phi^\pm, \phi_\mu^\pm, \dots, \phi_{\mu_1 \dots \mu_n}^\pm) \equiv (\phi_{\alpha_n}^\pm)$, α is a set formed by $\{\mu, \dots, \mu_1 \dots \mu_n\}$, with $0 \leq n \leq m$, and m is a degree of Lagrangian. Assuming *nondegeneracy* we can invert the highest derivative function as $\phi_{\alpha_m}^\pm = (\phi_{\alpha_1}^\pm; \pi^{\pm \alpha_m})$ with $0 \leq l \leq m-1$.

The canonical momentum is defined as $\pi^{\pm \alpha_n} \equiv \frac{L}{\partial \phi^{\pm \alpha_n}}$ when applying p.l., just as $\pi^{+\alpha_n} \equiv \frac{L}{\partial \phi^{+\alpha_n}}$ generalizing momentum is straightforward. The Hamiltonian is

$$\mathcal{H}(\phi_{\alpha_n}^\pm) = \phi_{\alpha_n}^{i_1} \pi^{j_1 \alpha_n} + \dots + \phi_{\alpha_{n-1}}^{i_{n-1}} \pi^{j_{n-1} \alpha_{n-1}} + \bar{\phi}_{\alpha_n}^{i_n} \pi^{j_n \alpha_n} - \Lambda(\phi_{\alpha_n}^\pm). \quad (\text{A5})$$

The set $(i_n, j_n) = \{(+, -); (-, +)\}$, $0 \leq n \leq m$. CTP is carried over a new poison bracket where f and g are functions of coordinate and momentum,

$$\{\{f, g\}\} = \left\{ \frac{\partial f}{\partial \phi_{\alpha_{n-1}}^+} \frac{\partial g}{\partial \pi_{\alpha_n}^-} - \frac{\partial f}{\partial \phi_{\alpha_{n-1}}^-} \frac{\partial g}{\partial \pi_{\alpha_n}^+} \right\} + \left\{ \frac{\partial f}{\partial \phi_{\alpha_{n-1}}^-} \frac{\partial g}{\partial \pi_{\alpha_n}^+} - \frac{\partial f}{\partial \phi_{\alpha_{n-1}}^+} \frac{\partial g}{\partial \pi_{\alpha_n}^-} \right\}. \quad (\text{A6})$$

It is straightforward to show the new equation of motion to this Hamiltonian is

$$\begin{aligned}\partial_\nu \phi_{\alpha_{n-1}} &= \frac{\partial \mathcal{H}}{\partial \pi^{\nu \alpha_{n-1}}} - \left[\frac{\partial \mathcal{K}}{\partial \pi^{\nu \alpha_{n-1}}} \right]_{\text{P.I.}} \\ &= \{ \phi_{\alpha_{n-1}}, \mathcal{H} \} - \{ \{ \phi_{\alpha_{n-1}}, \mathcal{K}_{\text{P.I.}} \} \}_{\text{P.I.}},\end{aligned}\quad (\text{A7})$$

$$\begin{aligned}\partial_\nu \pi^{\nu \alpha_{n-1}} &= - \frac{\partial \mathcal{H}}{\partial \phi_{\alpha_{n-1}}} + \left[\frac{\partial \mathcal{K}}{\partial \phi_{\alpha_{n-1}}} \right]_{\text{P.I.}} \\ &= \{ \pi^{\alpha_n}, \mathcal{H} \} - \{ \{ \pi^{\alpha_n}, \mathcal{K} \} \}_{\text{P.I.}}.\end{aligned}\quad (\text{A8})$$

One can see that the first term on the left-hand side is **A5** and the second represents the coupling between the two

doubled degrees of freedom (ϕ^+ , ϕ^-) which corresponds to a holonomic force, between system and environment. Provided the new Hessian matrix is invertible

$$\frac{\delta \mathcal{L}}{\delta \phi^+ \delta \phi^-} \neq 0, \quad (\text{A9})$$

the instability described in [37,38], and all the problems inherent to coupling this system to other systems, will also appear in the dissipative Lagrangian,

$$\left[\frac{d}{dt} \frac{\partial \Lambda}{\partial \dot{q}_-} - \frac{\partial \Lambda}{\partial q_-} \right]_{\text{f.l.}} = 0. \quad (\text{A10})$$

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