

Weak lensing by the large scale structure in a spatially anisotropic universe: Theory and predictions

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This article details the computation of the two-point correlators of the convergence, E and B modes of the cosmic shear induced by the weak lensing by large scale structure assuming that the background spacetime is spatially homogeneous and anisotropic. After detailing the perturbation equations and the general theory of weak lensing in an anisotropic universe, it develops a weak shear approximation scheme in which one can compute analytically the evolution of the Jacobi matrix. It allows one to compute the angular power spectrum of the E and B modes. In the linear regime, the existence of B modes is a direct tracer of a late-time anisotropy and their angular power spectrum scales as the square of the shear. It is then demonstrated that there must also exist off-diagonal correlations between the E modes, B modes and convergence that are linear in the geometrical shear and allow one to reconstruct the eigendirections of expansion. These spectra can be measured in future large scale surveys, such as Euclid and Square Kilometre Array, and offer a new tool to test the isotropy of the expansion of the universe at low redshift.

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I. INTRODUCTION

A. Motivations

The standard model of cosmology describes our Universe with a very simple solution of general relativity describing a spatially homogeneous and isotropic spacetime, known as the Friedmann-Lemaître solution. It is assumed to describe the geometry of our Universe smoothed on large scales. Besides, the use of the perturbation theory allows one to understand the properties of the large scale structure, as well as its growth from initial conditions set by inflation and constrained by the observations of the cosmic microwave background (CMB). It is a very successful model and allows one to deal with all existing observations in a consistent way with only six free parameters [1] from primordial nucleosynthesis to today, involving mostly general relativity, electromagnetism and nuclear physics, that is, physics

below 100 MeV and well under control experimentally (see, e.g., Refs. [2–4] for standard textbooks).

The construction of the cosmological model depends on our knowledge of microphysics but also on *a priori* hypotheses on the geometry of the spacetime describing our Universe. It relies on four main hypotheses (see Ref. [5] for a detailed description): (H1) a theory of gravity, (H2) a description of the matter and the nongravitational interactions, (H3) a symmetry hypothesis, and (H4) an hypothesis on the global structure, i.e., the topology, of the Universe. The hypotheses H1 and H2, that refer to the physical theories, are not sufficient to solve the field equations and we need an assumption on the symmetries (H3) of the solutions describing our Universe on large scales.

Among the generic conclusions of this standard model is the need of a dark sector, including dark matter and dark energy, which emphasizes the need for extra degrees of freedom, either physical (new fundamental fields or interactions) or geometrical (e.g., a cosmological solution with lower symmetry). This has driven a lot of activity to test the hypotheses of the cosmological model. In that debate, weak lensing is a key observation to test general relativity on

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cosmological scales [6] and to constrain the scale on which the fluid limit holds [7]. It complements tests of the other hypotheses such as the equivalence principle [8] and the Copernican principle [9]. Our *first motivation* is thus to provide a new test on the isotropy of the expansion at late time, hence providing a new test of the standard cosmological assumption. Any detection of a violation of a symmetry of the background spacetime would have important implications in terms of model building and on the understanding of the dark sector.

While in the standard Λ CDM model the cosmological constant Λ is the source of the acceleration of the Universe, many models have been proposed to explain the acceleration of the cosmic expansion. The property of the dark sector is often modeled as a fluid with an equation of state, $P_{\text{de}} = w\rho_{\text{de}}$, relating its pressure to its energy density. Such a phenomenological parameterization allows one to characterize the ability of different surveys to actually demonstrate that $w = -1$, as expected for a cosmological constant. Among the plethora of dark energy models, many enjoy an anisotropic pressure Π_j^i and thus may trigger a phase of anisotropic expansion at late time when dark energy starts influencing the dynamics of the Universe. This is for instance the case of magnetized dark energy [10,11], solid dark matter [12,13] induced by a network of frustrated topological defects, bigravity models [14], anisotropic dark energy [15,16] and in models in which the backreaction [17] of the large scale structure on the background evolution is the source of the acceleration. This has led to the development of a phenomenological parameterization of the anisotropic pressure in terms of an anisotropic equation of state as $\Pi_j^i = \Delta w_j^i \rho_{\text{de}}$ [18–21]. Our *second motivation* is thus to propose new observational tests on the anisotropic pressure of the dark energy sector, hence constraining another phenomenological deviation from a pure cosmological constant.

When concerned by anisotropic expansion, we can distinguish between two classes of models, that allow one to divide the different methods to constrain anisotropy. Recall that any perturbed quantity, X say, such as the gravitational potential, the density contrast, etc., can be split, in Fourier space, as the product of an initial configuration and a transfer function as $X(t, \mathbf{k}) = T_X(t, \mathbf{k})X_i(\mathbf{k})$. First, early anisotropic models (such as anisotropic inflation) have anisotropic initial conditions [in the sense that the correlation functions of the initial perturbed quantities are such that $\langle X_i(\mathbf{k})X_i^*(\mathbf{k}') \rangle \neq P_X(k)\delta(\mathbf{k} - \mathbf{k}')$] while the transfer functions are independent of direction [i.e., $T_X(t, \mathbf{k}) = T_X(t, k)$] because the geometry has isotropized at later times. Second, late-time anisotropic models have been isotropic during most of the history of the Universe [hence enjoying isotropic correlation functions, e.g., $\langle X_i(\mathbf{k})X_i^*(\mathbf{k}') \rangle = P_X(k)\delta(\mathbf{k} - \mathbf{k}')$] while their transfer function at late time is anisotropic, i.e., $T_X(t, \mathbf{k}) \neq T_X(t, k)$. These two types of models have a huge difference in the

way one attacks observational constraints. In particular the propagation of light is only affected in the second class of models.

Without any source during inflation, any primordial anisotropy is washed out [22,23] by the expansion. It was however demonstrated that it affects the construction of the Bunch-Davies state [22] so that it lets very specific signatures on the primordial power spectrum [24–26] and affects the onset of inflation [27]. Such deviation from isotropy can be constrained by CMB observations [28–35]. An early, postinflationary, anisotropy also affects the synthesis of light elements during primordial nucleosynthesis [36] (mostly because it affects the expansion rate).

Tests of a late-time anisotropy have mostly focused on the Hubble diagram from type Ia supernovae [21,37–46]. An anisotropic expansion will influence the transfer function so that it can also be constrained by the study of the large scale structure [15,47–54] and of the CMB [55–58]. It was argued that supernovae data lead to $\Delta w < 2.1 \times 10^{-4}$ [41] and that next-generation galaxy surveys are capable of constraining anisotropies at the 5% level [21] in terms of the anisotropic equation of state.

In this article, we follow our former analysis [59] on the imprint of a late-time anisotropy on weak lensing. According to the standard lore [60], in a homogeneous and isotropic background spacetime, weak lensing by the large scale structure of the Universe induces a shear field which, to leading order, only contains E modes. It was demonstrated in Ref. [59] that, even in the linear regime, anisotropic expansion will reflect itself in the existence of nonvanishing B modes. The level of B modes is used as an important sanity check during the data processing. On small scales, B modes arise from nonlinear effects [61], intrinsic alignments [62], Born correction, lens-lens coupling [63], and gravitational lensing due to the redshift clustering of source galaxies [64]. On large angular scales in which the linear regime holds, it was demonstrated [59] that nonvanishing B modes would be a signature of a deviation from the isotropy of the expansion, these modes being generated by the coupling of the background Weyl tensor to the E modes.

While light propagation in strictly homogeneous Bianchi universes has been widely investigated [65,66], the analytic computation of the Jacobi matrix was only determined recently [67] (see also Ref. [68]). This article focuses on the computation of the Jacobi matrix taking into account cosmological perturbations at linear order in a spatially homogeneous anisotropic Euclidean spacetime of the Bianchi I family. We provide all the technical tools (perturbation theory, light propagation, expression of the observables). The application of our formalism is exposed in our companion paper [69] in which we compute the expected signals for the Euclid [70] and Square Kilometre Array (SKA) [71] observations.

Among our main results, we emphasize that, as soon as local isotropy does not hold at the background level, there

exist a series of weak-lensing observables that allow one to fully reconstruct the background shear and thus test spatial isotropy. More precisely, as a consequence of the non-vanishing of the B modes, it can be demonstrated that

- (1) the angular correlation function of the B modes, C_ℓ^{BB} , is nonvanishing [59] and scales as the square of the ratio of the geometric shear to the Hubble expansion rate, σ^2/\mathcal{H}^2 ;
- (2) the B modes correlate with both the E modes and the convergence κ leading to the off-diagonal cross-correlations $\langle B_{\ell m} E_{\ell \pm 1 m - M}^* \rangle$ and $\langle B_{\ell m} \kappa_{\ell \pm 1 m - M}^* \rangle$ in which $E_{\ell m}$ and $B_{\ell m}$ are the components of the decomposition of the E and B modes of the cosmic shear in (spin-2) spherical harmonics and $\kappa_{\ell m}$ the components of the decomposition of the convergence in spherical harmonics. These two correlators scale as σ/\mathcal{H} ;
- (3) the deviation from isotropy also generates off-diagonal correlations among κ and E modes, $\langle E_{\ell m} E_{\ell \pm 2 m - M}^* \rangle$, $\langle \kappa_{\ell m} \kappa_{\ell \pm 2 m - M}^* \rangle$, and $\langle E_{\ell m} \kappa_{\ell \pm 2 m - M}^* \rangle$. These three correlators scale as σ/\mathcal{H} ;
- (4) for each type of correlator, there are five values of M so that in principle they can be used to reconstruct the five components of the geometric shear σ_{ij} .

This last point is very important since it exhibits a rigidity between independent observables that can be used to control systematic effects.

B. Structure of the article

Section II summarizes the description of the spacetime at the background level (Sec. II A) and for linear perturbations (Sec. II B). For the sake of clarity, the theory of gauge-invariant perturbations is detailed in Appendix A. It also introduces the parameterization of an anisotropic dark energy sector. The main variables required to describe the evolution of the background spacetime are summarized in Table I.

Section III describes the propagation of a light bundle (Sec. III A) and presents in Sec. III B the central equation for our analysis, namely the Sachs equation

$$\frac{d^2}{dv^2} \mathcal{D}_b^a = \mathcal{R}_c^a \mathcal{D}_b^c,$$

for the 2×2 Jacobi matrix \mathcal{D}_{ab} , the decomposition of which is presented in Sec. III C. It concludes by specifying these general results to the case of a Bianchi I spacetime (Sec. III D), focusing on the technical but useful use of a conformal transformation. The main variables required to describe the evolution of a geodesic bundle are summarized in Tables II and III.

Since the geometric shear is obviously small, we develop in Sec. IV an approximation scheme referred to as *small shear limit* in which σ/\mathcal{H} is considered as a small parameter. We then use a two-parameter expansion scheme

TABLE I. Table of most used quantities describing the background spacetime.

Symbol	Meaning	Appears at Eq.
μ, ν, \dots	Formal spacetime indices	...
i, j, \dots	Cartesian spatial indices	...
\hat{i}, \hat{j}, \dots	Spatial tetrad indices	(2.11)
$\underline{0}$	Time tetrad index	(2.13)
a	Average scale factor	(2.1)
H	Cosmic time Hubble expansion rate	(2.18a)
β_i	Log of directional scale factors	(2.2)
$\hat{\sigma}_{ij}$	Geometrical (cosmic time) shear	(2.4)
σ_{ij}	Geometrical (conformal time) shear	(2.5)
ϑ_0^ν	Timelike vector of background tetrad	(2.12)
ϑ_i^ν	Spacelike vector of background tetrad	(2.11)
Θ_0^ν	Timelike vector of perturbed tetrad	(4.6)
Θ_i^ν	Spacelike vector of perturbed tetrad	(4.6)
Δw_i^j	Equation of state of dark energy anisotropic stress	(2.16)
β_{ij}	Homogeneous perturbation of the Euclidean metric.	(4.5)

in which both σ/\mathcal{H} and the perturbations of the metric, say Φ , are small. Thus, a given order $\{n, p\}$ corresponds to term of order $(\sigma/\mathcal{H})^n \Phi^p$. In this approximation, the structure of our computation is the following. We start from the fact that the Sachs equation can be rewritten as [see Eq. (4.34)]

TABLE II. Table of most used quantities describing the propagation of a geodesic bundle.

Symbol	Meaning	Appears at Eq.
k^μ	Null geodesic tangent vector	(3.1)
\tilde{k}^μ	Conformally null geodesic tangent vector	(3.33)
z	Redshift	(3.4)
\mathbf{n}_o	Initial observed direction	(3.5)
\mathbf{n}_a	Sachs basis	(3.8)
\mathbf{n}_\pm	Helicity basis	(3.11)
η_a	Components of the connecting vector in the Sachs basis	(3.13)
\mathcal{R}_{ab}	Optical tidal matrix	(3.13)
\mathcal{D}_{ab}	Jacobi matrix	(3.14)
$\tilde{\mathcal{D}}_{ab}$	Conformal Jacobi matrix	(3.37)
\tilde{D}_A	Background angular diameter distance	(3.17)
D_A	Angular diameter distance	(3.19)
κ	Convergence	(3.17)
γ_{ab}	Cosmic shear	(3.17)
V	Rotation	(3.17)
$\kappa_{\ell m}$	Multipolar coefficients of the convergence	(3.23)
$V_{\ell m}$	Multipolar coefficients of the rotation	(3.23)
$E_{\ell m}$	Multipolar coefficients of the cosmic shear E modes	(3.25)
$B_{\ell m}$	Multipolar coefficients of the cosmic shear B modes	(3.25)

TABLE III. Table of most used quantities describing the propagation of a geodesic bundle.

Symbol	Meaning	Appears at Eq.
Σ	Scalar shear on the sphere	(4.15)
Σ_a	Vector shear on the sphere	(4.16)
Σ_{ab}	Tensor shear on the sphere	(4.16)
D_a	Covariant derivative on the sphere	(4.17)
\eth, \eth	Spin-raising and -lowering operators	(4.21)
Σ_{2m}	Multipole of the scalar shear	(4.25)
Σ_{\pm}	First derivative of the scalar shear in the helicity basis	(4.27)
m_o^s	Spin- s polarization basis	(5.1)
S^{X_s}	Source of the field X_s	(5.4)
$T_{\ell m}^{X_s}$	Anisotropic transfer function of the field X^s	(5.13)
$X_s T_{\ell m}^{LM}$	Multipoles of the anisotropic transfer function	(5.15)
$E_{\ell m}^{X_s}, B_{\ell m}^{X_s}$	Multipoles of the E and B modes of the field X^s	(5.17)
C_{ℓ}^{EE}	Angular power spectrum of the E modes	(5.21)
C_{ℓ}^{BB}	Angular power spectrum of the B modes	(5.21)
B	Scalar perturbation of the spatial metric	(6.5)
α^a	Deflection angle	(6.13)
ϖ^a	Perturbation of propagating direction	(6.17)
φ	Deflection potential	(6.27)
$\mathcal{N}(\chi)$	Source distribution	(6.43)
$P(k)$	Primordial power spectrum	(5.14)

$$\frac{d^2 \mathcal{D}_{ab}}{d\chi^2} + \frac{1}{k^0} \frac{dk^0}{d\chi} \frac{d\mathcal{D}_{ab}}{d\chi} = \frac{1}{(k^0)^2} \mathcal{R}_{ac} \mathcal{D}_{cb},$$

where χ is the coordinate along the light cone in the background Friedmann-Lemaître spacetime (see Sec. IV D). At order $\{0, 0\}$, $\mathcal{R}_{ab}^{\{0,0\}} = 0$ and $k^{\{0,0\}} = -1$ so that the equation takes the form

$$\frac{d^2 \mathcal{D}_{ab}^{\{0,0\}}}{d\chi^2} = 0$$

and can be integrated trivially (see Sec. VI B). We then expand this equation order by order so that it formally takes the form (since $k_{\{0,0\}}^0 = -1$)

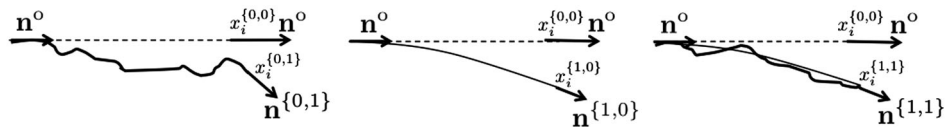


FIG. 1. Comparison of the geodesic in the approximation at order $\{n, p\}$. In order to adopt an observer-based point of view, we need to relate the local direction of propagation $\mathbf{n}^{\{n,p\}}$ to \mathbf{n}^o . The transports for the 3 orders of perturbations are, respectively, detailed in Eqs. (6.12) and (6.37) that determine $x^{i\{n,p\}}(\chi, \mathbf{n}^o)$ that can be further split in a radial component $\delta r^{\{n,p\}}(\chi, \mathbf{n}^o)$ and an orthoradial contribution that defines the deflection angle $\alpha^{a\{n,p\}}(\chi, \mathbf{n}^o)$.

$$\frac{d^2 \mathcal{D}_{ab}^{\{n,p\}}}{d\chi^2} = S^{\{n,p\}}$$

in which the source term contains a contribution from \mathcal{R}_{ab} and k^0 up to order $\{n, p\}$ and from \mathcal{D}_{ab} at lower order. The effects to be taken into account are then

- (1) the tensor and vector contributions to \mathcal{R}_{ab} , which starts at order $\{1, 1\}$ and the contribution of the scalar modes at the relevant order;
- (2) the evolution of all the perturbative modes, that is of the transfer functions, which is decomposed as

$$T_X(\mathbf{k}, t) = T_X^{\{0,1\}}(k, t) + T_X^{\{1,1\}}(\mathbf{k}, t)$$

since the orders $\{0, 0\}$ and $\{1, 0\}$ correspond to homogeneous solutions. This requires one to solve the equations of Appendix A.

- (3) In order to determine k^0 , we also need to solve perturbatively the geodesic equation.
- (4) A source observed in direction \mathbf{n}^o at distance χ is located at a spacetime point $P_{\{n,p\}}$ and its contribution depends on the local direction of the tangent vector to the geodesic in $\mathbf{n}_{\{n,p\}}$, which determines the local Sachs basis in $P_{\{n,p\}}$. We shall thus proceed with two operations:
 - (a) transport $P_{\{n,p\}}$ to $P_{\{0,0\}}$ (see Fig. 1) and
 - (b) transport $\mathbf{n}_{\{n,p\}}$ and the local Sachs basis (see Fig. 2).

This is what we call the *central geodesic approximation* and the possibility to go beyond this approximation is sketched in Appendix C. We however stick to this approximation, which is sufficient in the small shear approximation. At lowest order, it corresponds to the usual Born approximation but at higher order there are post-Born corrections to include.

Section V describes the computation of the angular correlation. Our philosophy is to adopt an observer point of view, that is, to compute all quantities on the celestial sphere of the observer. Given the previous perturbative expansion scheme, any observable X^s of spin s can then be formally expressed as [see Eq. (5.4)]

$$X^s(\chi_S, \mathbf{n}_o) m_o^s = \int_0^{\chi_S} S^{X^s}(\chi_S, \chi, \mathbf{n}_o) m_o^s d\chi.$$

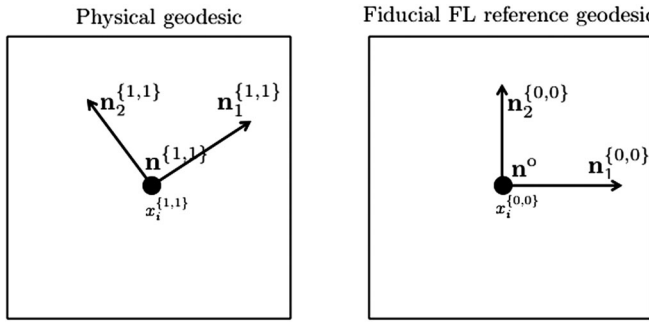


FIG. 2. The local Sachs basis at a point $P_{\{n,p\}}$ on the geodesic has to be transported to the point $P_{\{0,0\}}$ on the fiducial null geodesic of the background Friedmann-Lemaître spacetime. This implies to perform a transport on the tangent space at the same time that the point of observation is transported in real space. The transports for the 3 orders of perturbations are, respectively, detailed in Eqs. (6.15), (6.34) and (6.54) for \mathbf{n} and in Eqs. (6.17), (6.35) and (6.54) for the Sachs basis.

for a source S^{X^s} located at χ_S and observed in direction \mathbf{n}^o . According to the spin s of the quantity we can expand in the proper spherical harmonics with respect to \mathbf{n}^o . This allows one to define the expansion of all the quantities in term of spherical harmonics. As a by-product, we demonstrate in Sec. V C that the five off-diagonal correlators $\langle B_{\ell m} E_{\ell \pm 1 m - M}^* \rangle$, $\langle B_{\ell m} \kappa_{\ell \pm 1 m - M}^* \rangle$, $\langle E_{\ell m} E_{\ell \pm 2 m - M}^* \rangle$, $\langle \kappa_{\ell m} \kappa_{\ell \pm 2 m - M}^* \rangle$, and $\langle E_{\ell m} \kappa_{\ell \pm 2 m - M}^* \rangle$ are nonvanishing.

Equipped with all these tools, we compute these correlators and the angular power spectra of the E and B modes in Sec. VI order by order. Order $\{1, 0\}$ recovers the nonperturbative analysis of Ref. [67] while order $\{0, 1\}$ recovers the standard case of lensing by large scale structure in the linear regime; Sec. VI E gives all the details of the computation at order $\{1, 1\}$. This allows us to discuss the dominant contribution in Sec. VII. In particular, we argue that the dominant term for the cosmic shear is given by

$$\gamma_{ab} = -\alpha^c D_c D_{\langle a} D_{b \rangle} \varphi,$$

where α^c is the deflection angle at order $\{1, 0\}$, φ the deflection potential, and D_a the covariant derivative on the celestial sphere.

Many technicalities are gathered in the Appendixes: linear perturbation theory (Appendix A), the expressions of the geometric quantities at first order in perturbation that are need to compute the source term of the Sachs equation (Appendix B), details on the lensing method (Appendix C) and a catalog of useful mathematical identities (Appendix D). Throughout this work we adopt units in which $c = 1$.

II. SPACETIME STRUCTURES

A. Background spacetime

1. Geometry

At the background level, the Universe is described by a spatially Euclidean, homogeneous, and locally anisotropic solution of the Einstein equation filled with a perfect fluid. Its metric takes the general form (see Refs. [72–76] for general references on Bianchi spacetimes)

$$ds^2 = -dt^2 + \sum_{i=1}^3 X_i^2(t) (dx^i)^2, \quad (2.1a)$$

$$= -dt^2 + a^2(t) \gamma_{ij}(t) dx^i dx^j, \quad (2.1b)$$

where $a(t) \equiv \sqrt{X_1(t)X_2(t)X_3(t)}$ is the volume averaged scale factor and t the cosmic time. We define the tangent vector to the fundamental comoving observer by $u_\mu dx^\mu \equiv dt$. It is normalized such that $u_\mu u^\mu = -1$. The spatial metric γ_{ij} and its inverse γ^{ij} can be decomposed as

$$\gamma_{ij}(t) = \exp[2\beta_i(t)] \delta_{ij}, \quad \gamma^{ij}(t) = \exp[-2\beta_i(t)] \delta^{ij}, \quad (2.2)$$

with the constraint

$$\sum_{i=1}^3 \beta_i = 0 \quad (2.3)$$

that ensures that the comoving volume remains constant (i.e., $\dot{\gamma} = \gamma^{ij} \dot{\gamma}_{ij} = 0$). Note that, as a consequence of Eq. (2.2), some spatial directions should contract while others grow [24]. Note also that there is no sum on i in the definition of γ_{ij} and Latin indices $\{i, j, k, \dots\}$ are raised with γ^{ij} and lowered with γ_{ij} .

The geometrical shear is defined as

$$\hat{\sigma}_{ij} \equiv \frac{1}{2} \dot{\gamma}_{ij}, \quad (2.4)$$

where a dot refers to a derivative with respect to cosmic time. We shall also use the conformal time η defined by $a(\eta)d\eta = dt$ and denote derivatives with respect to it by a prime. Thus, the conformal shear is defined as

$$\sigma_{ij} \equiv \frac{1}{2} \gamma'_{ij} = a \hat{\sigma}_{ij}. \quad (2.5)$$

The amplitude of the shear is defined by

$$\hat{\sigma}^2 \equiv \hat{\sigma}_{ij} \hat{\sigma}^{ij} = \sum_{i=1}^3 \hat{\beta}_i^2 \quad \text{and} \quad \sigma^2 \equiv \sigma_{ij} \sigma^{ij} = a^2 \sum_{i=1}^3 \beta_i'^2 = \sum_{i=1}^3 \beta_i'^2. \quad (2.6)$$

2. Decomposition of the geometric shear

The shear, being a symmetric and traceless spatial tensor ($\sigma_i^i = 0$), has 5 degrees of freedom, three of which correspond to the Euler angles necessary to express the shear in a general basis. By choosing the Cartesian basis (2.2), we have set these three angles to zero so that we are left with only 2 degrees of freedom, namely the three β_i with the constraint (2.3). The components of the shear can thus be expressed as

$$\begin{aligned}\hat{\sigma}_{ij}(t) &= \dot{\beta}_i \exp[2\beta_i(t)]\delta_{ij}, & \hat{\sigma}^{ij}(t) &= \dot{\beta}_i \exp[-2\beta_i(t)]\delta^{ij}, \\ \hat{\sigma}_i^i(t) &= \dot{\beta}_i \delta_i^i.\end{aligned}\quad (2.7)$$

These two independent degrees of freedom can also be decomposed as a magnitude and an angle φ . The first is related to the scalar shear while the choice of the angle defines which of the spatial directions are initially expanding. These variables can be obtained by performing the decomposition

$$\beta_i(t) \equiv C_i W(t), \quad (2.8)$$

with the three constants C_i given by

$$C_i = \sqrt{\frac{2}{3}} \mathcal{S} \sin\left(\varphi + \frac{2\pi}{3} i\right), \quad i \in \{1, 2, 3\} \quad (2.9)$$

and where \mathcal{S} is constant. This parameterization obviously satisfies the required constraints

$$\sum_i C_i = 0, \quad \sum_i C_i^2 = \mathcal{S}^2. \quad (2.10)$$

Therefore, once the Cartesian basis is chosen, we can choose the two constants (φ, \mathcal{S}) to describe the two degrees of freedom of the shear since $\hat{\sigma}^2 = (\mathcal{S}\dot{W})^2$.

3. Spatial triad

It is convenient to introduce a spatial triad—a set of three orthonormal vectors and covectors; the normalization being defined from γ_{ij} and γ^{ij} —related directly to the Cartesian coordinates x^i . Their components in the coordinates basis read

$$\vartheta_i^j = \exp[-\beta_i(t)]\delta_i^j, \quad \vartheta_j^i = \exp[\beta_i(t)]\delta_j^i. \quad (2.11)$$

In such a triad basis, the shear components take the simple form

$$\hat{\sigma}_{\underline{i}\underline{j}} = \hat{\sigma}^{\underline{i}\underline{j}} = \dot{\beta}_i \delta_{ij}, \quad \hat{\sigma}^{\underline{i}\underline{j}} = \sigma^{\underline{i}\underline{j}} = \beta_i' \delta_{ij}. \quad (2.12)$$

Thus, this triad can easily be extended to a tetrad by using the observer's 4-velocity as the normalized timelike vector

$$\vartheta_{\underline{0}}^\mu = \delta_{\underline{0}}^\mu = u^\mu, \quad \vartheta_\mu^{\underline{0}} = \delta_\mu^{\underline{0}} = -u_\mu. \quad (2.13)$$

4. Description of matter and field equations

Concerning the matter sector, we assume it is composed of a pressureless matter fluid and a dark energy component. The dark sector is then described by a fluid whose energy-momentum tensor enjoys a nonvanishing anisotropic stress:

$$T_\nu^\mu = (\rho + P)u^\mu u_\nu + P\delta_\nu^\mu + \Pi_\nu^\mu. \quad (2.14)$$

The anisotropic stress tensor is symmetric ($\Pi_{\mu\nu} = \Pi_{\nu\mu}$), traceless ($\Pi_\mu^\mu = 0$) and transverse ($u_\mu \Pi_\nu^\mu = 0$) which means that it has only 5 degrees of freedom encoded in its spatial part Π_{ij} . Unless we define a microscopic model, we need to use an equation of state for Π_j^i . We decompose it as

$$\Pi_j^i \equiv \rho_{\text{de}} \Delta w_j^i, \quad (2.15)$$

so that the pressure tensor takes the general form

$$P_j^i = \rho_{\text{de}}(w\delta_j^i + \Delta w_j^i), \quad (2.16)$$

where w is the equation of state relating the isotropic pressure to the energy density and Δw_j^i is an equation of state for the anisotropic pressure. From a phenomenological point of view, this corresponds to an extension of the dark energy sector, similar to the ansatz (1) of Ref. [41], which will allow us to address the question of the deviation from the standard cosmological constant reference (i.e., $w = -1$ and $\Delta w_j^i = 0$).

Defining the Hubble expansion rate by

$$H = \dot{a}/a, \quad (2.17)$$

the background equations [22] take the form

$$3H^2 = \kappa(\rho_{\text{m}} + \rho_{\text{de}}) + \frac{1}{2}\hat{\sigma}^2, \quad (2.18a)$$

$$(\hat{\sigma}_j^i)^\cdot = -3H\hat{\sigma}_j^i + \kappa\Pi_j^i. \quad (2.18b)$$

$$\dot{\rho}_{\text{m}} = -3H\rho_{\text{m}}, \quad (2.18c)$$

$$\dot{\rho}_{\text{de}} = -3H(1+w)\rho_{\text{de}} - \hat{\sigma}_{ij}\Pi^{ij}. \quad (2.18d)$$

The first equation is the analogous of the Friedmann equation in the presence of a spatial shear; the second is obtained from the traceless and transverse part of the Einstein equation and dictates the evolution of the shear. The last two equations are the continuity equations for the

dark matter ($P = \Pi_j^i = 0$) and dark energy sector. We have set¹ $\kappa = 8\pi G \equiv M_P^{-2}$.

5. Dynamics

The set of equations (2.18) can be formally integrated. As usual, the dark matter energy density scales as

$$\rho_m = \rho_{m0} \left(\frac{a_0}{a} \right)^3. \quad (2.19)$$

Equation (2.18b) has a first integral given by

$$\hat{\sigma}_j^i = \left(\frac{a_0}{a} \right)^3 \left[C_j^i + \kappa \int \Pi_j^i \left(\frac{a}{a_0} \right)^2 \frac{d(a/a_0)}{H} \right], \quad (2.20)$$

where C_j^i is a constant tensor representing the decaying mode of the shear. Note that if the term proportional to C_j^i is not negligible, then the shear is not proportional to the anisotropic stress so that σ_{ij} and Π_{ij} cannot be diagonalized in the same basis. Integrating Eq. (2.18d) leads to

$$\rho_{de} = \left(\frac{a}{a_0} \right)^{-3(1+w)} \left[\rho_{de0} - \int \hat{\sigma}_i^j \Pi_j^i \left(\frac{a}{a_0} \right)^{2+3w} \frac{d(a/a_0)}{H} \right] \quad (2.21)$$

or, if one uses the decomposition (2.15), as

$$\rho_{de} = \rho_{de0} \left(\frac{a}{a_0} \right)^{-3(1+w)} \exp \left[- \int \hat{\sigma}_i^j \Delta w_j^i \frac{da}{aH} \right]. \quad (2.22)$$

In the particular case where $w = -1$, this latter equation teaches us that the dark energy density does not remain constant.

B. Linear perturbations

Cosmological perturbation theory around a Bianchi I background spacetime, in the Bardeen formalism, was first investigated in Refs. [22,24]. The perturbed spacetime has a metric of the form

$$ds^2 = a^2 [-(1 + 2A)d\eta^2 + 2B_i dx^i d\eta + (\gamma_{ij} + h_{ij}) dx^i dx^j], \quad (2.23)$$

where A is a free scalar function, $B_i \equiv \partial_i B + \bar{B}_i$ and $h_{ij} \equiv 2C(\gamma_{ij} + \frac{\sigma_{ij}}{H}) + 2\partial_i \partial_j E + 2\partial_{(i} E_{j)} + 2E_{ij}$ defined together with the usual transversality and trace-free conditions $\partial_i \bar{B}^i = 0 = \partial_i E^i$, $E_i^i = 0 = \partial_i E^{ij}$.

¹In order to easily check the homogeneity of the equations, we recall that

$$[H] \sim M_P, \quad [\rho] \sim M_P^4, \quad [\kappa] \sim M_P^{-2}, \quad [\sigma] \sim M_P, \quad [\Pi] \sim M_P^4.$$

As summarized in Sec. A 2, one can define 2 scalar (Φ and Ψ), 2 vector (Φ_i) and 2 tensor (E_{ij}) degrees of freedom, which are gauge invariant; see Eq. (A25). Similarly, one can define gauge-invariant variables for the matter sector, leading to four scalar variables ($\delta\hat{\rho}$, $\delta\hat{P}$, \hat{v} and $\hat{\pi}^S$, respectively, for the density, pressure, velocity and anisotropic stress), four vector variables (\hat{v}^i and $\hat{\pi}_i^V$) and two tensor variables ($\hat{\pi}_{ij}^T$) the expressions of which are gathered in Eqs. (A33) and (A35).

Appendix A summarizes all the techniques and results needed to study the perturbations, including the definition of the Fourier transform (Sec. A 1), and the construction of the gauge-invariant variables (Sec. A 2). It then derives the full set of Einstein equations (Sec. A 3) and the conservation equations (Sec. A 4).

Among the important features that differ from the standard perturbation theory around a Friedmann-Lemaître spacetime, let us mention

- (i) the fact that only the components k_i of the wave (co) vector are constant so that both k^i and k are time dependent—see e.g., Eq. (A2);
- (ii) the fact that the scalar-vector-tensor modes do not decouple;
- (iii) the fact that, even at late time, the two Bardeen potentials are not equal because of the anisotropic stress.

III. WEAK LENSING IN A GENERAL SPACETIME

This section provides the definitions and equations describing the propagation of a geodesic bundle (geodesic equation and Sachs equation) in a general spacetime and in the particular case of a Bianchi I universe.

A. Geodesic bundle

Weak lensing is concerned with the deformation of an infinitesimal bundle of light rays propagating in curved spacetimes. It is thus related to the geodesic deviation equation.

1. Geodesic equation

The central quantity in the geodesic equation, obtained as the eikonal limit of Maxwell's equations, is the wave vector of an electromagnetic wave, $k^\mu(v) \equiv dx^\mu/dv$, where v is an affine parameter of a given geodesic $x^\mu(v)$ and defined such that it is zero at the observer and increases towards the source. We shall be working in the eikonal approximation where k^μ is a null vector satisfying the geodesic equation

$$k^\nu \nabla_\nu k^\mu = 0. \quad (3.1)$$

If we parameterize the bundle of null geodesics by $x^\mu(v, s)$, where s is a continuous parameter labeling each ray of the bundle, then each ray has a wave vector given by

$k^\mu(v, s) = \partial x^\mu / \partial v$, whereas the vector $\eta^\mu = \partial x^\mu / \partial s$ gives the infinitesimal separation between two neighboring geodesics of the bundle. The photon wave vector can always be decomposed in components, respectively, parallel and orthogonal to u^μ as

$$\hat{k}^\mu \equiv U^{-1} k^\mu = -u^\mu + n^\mu, \quad (3.2)$$

where n^μ are the components of the local directional vector \mathbf{n} , defined such that

$$u^\mu n_\mu = 0, \quad n_\mu n^\mu = 1. \quad (3.3)$$

Once the geodesic equation is solved, any comoving observer with 4-velocity u^μ , normalized such that $u^\mu u_\mu = -1$, defines the redshift of a source by

$$1 + z(v, \mathbf{n}_o) \equiv \frac{(k_\mu u^\mu)_v}{(k_\mu u^\mu)_o}, \quad (3.4)$$

where v is the affine parameter that specifies the position of the source down the light cone and

$$\mathbf{n}_o \equiv \mathbf{n}(v = 0) \quad (3.5)$$

is the direction of observation. The energy of a photon at a given redshift is

$$U(v, \mathbf{n}_o) = U_o [1 + z(v, \mathbf{n}_o)], \quad U_o = (k^\mu u_\mu)_o. \quad (3.6)$$

By definition, the local spacelike vector \mathbf{n} is a function of the affine parameter v and of the direction of observation observer \mathbf{n}_o , that is, the spacelike vector pointing along the line of sight.

2. Geodesic deviation equation

A (narrow) light beam is a collection of neighboring light rays. The behavior of any such geodesic, with respect to an arbitrary reference one, is described by the separation (or connecting) vector η^μ . Assuming that all the rays converge at a given event O (the location of the observer), $\eta^\mu(0) = 0$. The evolution of $\eta^\mu(v)$ along the beam is governed by the geodesic deviation equation

$$\frac{d^2 \eta^\mu}{dv^2} = R^\mu{}_{\nu\alpha\beta} k^\nu k^\alpha \eta^\beta, \quad (3.7)$$

where $R^\mu{}_{\nu\alpha\beta}$ is the Riemann tensor.

3. Sachs basis and screen space

For any observer whose worldline intersects the light beam at an event different from O , the beam has a nonzero extension, since *a priori* $\eta^\mu \neq 0$. The observer can thus project it on a *screen* to characterize its size and shape. This screen is by essence a two-dimensional spacelike

hypersurface and chosen to be orthogonal to the local line of sight n^μ . Two such spatial vectors required to construct a basis for the tangent space, \mathbf{n}_a with $a = \{1, 2\}$, are defined by the requirement that

$$n_a^\mu n_{b\mu} = \delta_{ab}, \quad n_a^\mu u_\mu = n_a^\mu n_\mu = 0. \quad (3.8)$$

With these definitions we can construct a tensor which projects any geometrical quantity on the two-dimensional surface orthogonal to \mathbf{n} :

$$S_{\mu\nu} \equiv g_{\mu\nu} + u_\mu u_\nu - n_\mu n_\nu. \quad (3.9)$$

Then, with the help of the orthogonality relations (3.8), this two-dimensional screen basis can be parallel propagated along null geodesics as [77]

$$S_{\mu\sigma} k^\nu \nabla_\nu n_a^\sigma = 0. \quad (3.10)$$

A basis satisfying the condition (3.8) and propagated according to Eq. (3.10) is called a *Sachs basis*. It is important to note that the basis formed by the vectors \mathbf{n}_a is defined up to an overall rotation around \mathbf{n}_o . We can fix this freedom by introducing a spherical basis at the observer (i.e., at $v = 0$) by demanding that $\{\mathbf{n}^o, \mathbf{n}_1^o, \mathbf{n}_2^o\} = \{\mathbf{n}_r^o, \mathbf{n}_\theta^o, \mathbf{n}_\varphi^o\}$. With this choice, the integration of Eq. (3.10) allows us to define a unique three-dimensional basis $\{\mathbf{n}_r, \mathbf{n}_\theta, \mathbf{n}_\varphi\}(\mathbf{n}^o, \hat{v})$ at each point along the geodesics; see Ref. [59]. Furthermore, it will be convenient to define a helicity basis as

$$\mathbf{n}_\pm \equiv \frac{1}{\sqrt{2}} (\mathbf{n}_\theta \mp i \mathbf{n}_\varphi) = \frac{1}{\sqrt{2}} (\mathbf{n}_1 \mp i \mathbf{n}_2), \quad (3.11)$$

whose components in the \mathbf{n}_a basis read

$$n_\pm^a = \mathbf{n}_\pm \cdot \mathbf{n}_a = \frac{1}{\sqrt{2}} (\delta_1^a \mp i \delta_2^a) \quad (3.12)$$

and are, by construction, constant.

B. Sachs equation

The screen projection of the connecting vector, $\eta_a \equiv n_a^\mu \eta_\mu$, represents the relative position on the screen of the two light spots associated with two rays separated by η^μ . Similarly, and if we set by convention $U_o = 1$, $\theta_a \equiv (d\eta_a/dv)_o$ represents the angular separation of those rays, as observed from O .

The geodesic equation can be recast as [2] an equation for η_a as

$$\frac{d^2 \eta_a}{dv^2} = \mathcal{R}_{ab} \eta^b, \quad \mathcal{R}_{ab} \equiv R_{\mu\nu\alpha\beta} k^\nu k^\alpha n_a^\mu n_b^\beta. \quad (3.13)$$

\mathcal{R}_{ab} is the screen projected Riemann tensor which can be split into its symmetric traceless part $\mathcal{R}_{(ab)}$ and its trace part

$\mathcal{R} \equiv \mathcal{R}_{ab}\delta^{ab}/2$. It is also referred to as the *optical tidal matrix*. Furthermore, thanks to the linearity of Eq. (3.13), one can decompose the connection vector on the geodesic to its initial derivative as

$$\eta^a(v) = \mathcal{D}_b^a(v) \left(\frac{d\eta^b}{dv} \right)_{v=0}. \quad (3.14)$$

This defines the *Jacobi map* \mathcal{D}_{ab} that satisfies the Sachs equation [2,78]

$$\frac{d^2}{dv^2} \mathcal{D}_b^a = \mathcal{R}_c^a \mathcal{D}_b^c, \quad (3.15)$$

subject to the following initial conditions:

$$\mathcal{D}_b^a(0) = 0, \quad \frac{d\mathcal{D}_b^a}{dv}(0) = \delta_b^a. \quad (3.16)$$

C. Decomposition of the Jacobi matrix and observables

The Jacobi matrix entering the Sachs equation (3.15) encodes all the information about the deformation of a light beam when propagating through a curved spacetime. This 2×2 matrix can be decomposed in different ways.

The usual decomposition is described in terms of a convergence κ , a rotation V , and a shear γ_{ab} as

$$\mathcal{D}_{ab}(v) \equiv \bar{D}_A(v) [(1 + \kappa)I_{ab} + V\epsilon_{ab} + \gamma_{ab}] \quad (3.17)$$

with

$$\epsilon_{ab} = 2in_{[a}^- n_{b]}^+, \quad \gamma_a^a = 0, \quad (3.18)$$

and where screen-basis indices a and b are manipulated with $I_{ab} \equiv S_{\mu\nu} n_a^\mu n_b^\nu = \delta_{ab}$, that is, with a two-dimensional Euclidian metric.

A canonical decomposition was introduced in Ref. [67] as

$$\mathcal{D}_{ab}(v) \equiv D_A(v) \underbrace{\begin{bmatrix} \cos \psi & \sin \psi \\ -\sin \psi & \cos \psi \end{bmatrix}}_{\text{rotation}} \underbrace{\exp \begin{bmatrix} -\Gamma_1 & \Gamma_2 \\ \Gamma_2 & \Gamma_1 \end{bmatrix}}_{\text{cosmic shear}}. \quad (3.19)$$

According to this decomposition, the real size and shape of the light source are obtained from the image by performing the following transformations: (i) an area-preserving shear (Γ_1, Γ_2) , (ii) a global rotation ψ , and (iii) a global scaling. The latter defines the angular distance as

$$D_A(v) \equiv \sqrt{\det \mathcal{D}_{ab}(v)}, \quad (3.20)$$

which does not assume any background spacetime and perturbative expansion. On the other hand, the definition

(3.17) introduces the background angular distances \bar{D}_A . Both are related by

$$D_A(v) \simeq \bar{D}_A(v) [1 + \kappa(v)]. \quad (3.21)$$

As for the deformation of the source shape, it is given by the reduced shear

$$\frac{\mathcal{D}_{\langle ab \rangle}}{\sqrt{\det \mathcal{D}_{ab}}} \simeq \frac{\gamma_{ab}}{(1 - \kappa)}. \quad (3.22)$$

Each one of the above observables are defined on our past light cone, and, as such, they are functions of \mathbf{n}_0 and v . The convergence and the rotation are scalar functions and therefore can be expanded in terms of scalar spherical harmonics as

$$\kappa(\mathbf{n}^0, v) = \sum_{\ell, m} \kappa_{\ell m}(v) Y_{\ell m}(\mathbf{n}^0), \quad (3.23a)$$

$$V(\mathbf{n}^0, v) = \sum_{\ell, m} V_{\ell m}(v) Y_{\ell m}(\mathbf{n}^0). \quad (3.23b)$$

The cosmic shear, on the other hand, being a spin-2 quantity, can be expanded in terms of the polarization basis as

$$\gamma_{ab}(\mathbf{n}^0, v) \equiv \sum_{\lambda=\pm} \gamma^\lambda(\mathbf{n}^0, v) n_a^\lambda n_b^\lambda. \quad (3.24)$$

The coefficients γ^\pm can be further expanded in terms of E and B modes on a basis of spin-2 spherical harmonics as

$$\gamma^\pm(\mathbf{n}^0, v) = \sum_{\ell, m} [E_{\ell m}(v) \pm iB_{\ell m}(v)] Y_{\ell m}^{\pm 2}(\mathbf{n}^0). \quad (3.25)$$

It should be stressed that we adopt an observer-based point of view. This means that all quantities are expressed in terms of (\mathbf{n}^0, \hat{v}) . In general, $\mathbf{n}(\mathbf{n}^0, \hat{v}) \neq \mathbf{n}^0$, with the obvious exception of, e.g., Friedmann-Lemaître spacetimes and spacetimes with a local spherical symmetry for an observer located at the center of symmetry. Therefore, one of the difficulties in obtaining cosmological observables as a function of v , or equivalently as a function of the redshift z , lies in the determination of these coefficients.

D. Particular case of a Bianchi I spacetime

1. Geodesic equation

The Bianchi I spacetime enjoys three Killing vectors ∂_i that allow one to construct three conserved quantities $g(\partial_i, k) = k_i$ along any geodesic. It implies that

$$k_i = \text{cst} \quad (3.26)$$

on each geodesic so that

$$k^i = \frac{\gamma^{ij} k_j}{a^2}. \quad (3.27)$$

k being a null vector, one concludes that $\omega^2 \equiv (k^i)^2 = g^{ij} k_i k_j$ with

$$\omega \equiv \frac{1}{a} \sqrt{\sum_{i=1}^3 (e^{-\beta_i} k_i)^2}. \quad (3.28)$$

It follows that the components of the direction of observation vector n^μ are given by

$$n_i = k_i/\omega, \quad n^i = k^i/\omega. \quad (3.29)$$

The constants of motion k_i are then directly related to the direction in which the observer in O needs to look to detect the light signal, i.e., the direction of the source n_o^μ . The redshift of a source is then given by

$$1 + z(\mathbf{n}_o, t_S) \equiv \frac{\omega_S}{\omega_o} = \frac{a_o}{a(t_S)} \sqrt{\frac{\sum_{i=1}^3 [e^{-\beta_i(t_S)} k_i]^2}{\sum_{i=1}^3 [e^{-\beta_i(t_o)} k_i]^2}}. \quad (3.30)$$

It is always possible to choose the normalization such that $a_o = 1$ and $\beta_i(t_o) = 0$, but we do not make that choice here.

2. Jacobi matrix

The study of the Sachs equation is simplified after performing a conformal transformation of the metric by a scale factor a :

$$g_{\mu\nu} = a^2 \tilde{g}_{\mu\nu}. \quad (3.31)$$

It can be checked that any null geodesic for $g_{\mu\nu}$, affinely parametrized by v , is also a null geodesic for $\tilde{g}_{\mu\nu}$, affinely parametrized by \tilde{v} with $dv = a^2 d\tilde{v}$. The associated wave four-vectors then read $\tilde{k}^\mu = a^2 k^\mu$. Since the 4-velocities of the comoving observers for both geometries are, respectively, $u = \partial_t$ and $\tilde{u} = \partial_{\tilde{t}}$, so that $\tilde{u}^\mu = a u^\mu$, we deduce that

$$\omega \equiv g_{\mu\nu} u^\mu k^\nu = a^{-1} \tilde{g}_{\mu\nu} \tilde{u}^\mu \tilde{k}^\nu \equiv a^{-1} \tilde{\omega}. \quad (3.32)$$

The 3 + 1 decomposition of \tilde{k}^μ is therefore

$$\tilde{k}^\mu = \tilde{\omega}(-\tilde{u}^\mu + \tilde{n}^\mu) \quad (3.33)$$

with $\tilde{n}^\mu \equiv a n^\mu$ implying $\tilde{n}_\mu = n_\mu/a$ and

$$\tilde{n}_i = \frac{\tilde{k}_i}{\tilde{\omega}}. \quad (3.34)$$

The Sachs basis (\tilde{n}_a^μ) for the conformal geometry is then related to the original one (3.8) by

$$\tilde{n}_a^\mu = a n_a^\mu, \quad \tilde{n}_\mu^a = a^{-1} n_\mu^a. \quad (3.35)$$

One can indeed check that the orthonormality (3.8) and the parallel transport conditions (3.10) are preserved by the conformal transformation with the use of the projection matrix $\tilde{S}_{\mu\nu} = a^{-2} S_{\mu\nu}$, instead of Eq. (3.9).

The separation four-vector η^μ is defined by comparing events only, independently from any metric. It is therefore invariant under conformal transformations. However, its projection over the Sachs basis changes (since the Sachs basis itself changes), indeed

$$\eta^a \equiv n_\mu^a \eta^\mu = a \tilde{n}_\mu^a \tilde{\eta}^\mu = a \tilde{\eta}^a. \quad (3.36)$$

This implies that the Jacobi matrix transform as [61,67]

$$\mathcal{D}_{ab} = a \tilde{\mathcal{D}}_{ab}. \quad (3.37)$$

Hence, the angular distance D_A in the Universe described by a metric $g_{\mu\nu}$ is just $a \tilde{D}_A$, where \tilde{D}_A is the angular distance in the Universe described by the metric $\tilde{g}_{\mu\nu}$. At lowest order in perturbations, κ is the relative perturbation of angular diameter distance whatever is the metric used. As for the reduced shear, it remains unaffected by the conformal transformation. In the remainder of this article, we will thus discard the effect of an overall scale factor, in order to simplify the computation. However it should be recalled that, as shown by Eq. (3.32), a conformal transformation has an effect on the energetic aspects of light propagation, that is, on the relation between the redshift and the affine parameter $U(v)$.

3. General solution

Using such a conformal transformation, it was shown in Ref. [67] that the Sachs equation can be solved analytically in a Bianchi I universe. This solution relies on the fact that the Sachs equation can be rewritten as

$$\frac{d^2 \tilde{\mathcal{D}}_{ab}}{d\tilde{v}^2} = \tilde{\mathcal{R}}_{ac} \tilde{\mathcal{D}}_{cb}, \quad (3.38)$$

with the rescaled optical matrix given by

$$\tilde{\mathcal{R}}_{ab} = \tilde{\omega}^2 \left[(\sigma_{ab})' + \sigma_{ac} \sigma_{cb} + \frac{\tilde{\omega}'}{\tilde{\omega}} \sigma_{ab} \right]. \quad (3.39)$$

The explicit solution of this equation is given in Secs. VIIA and B of Ref. [67].

IV. SMALL SHEAR LIMIT

A. Definition

The current observational status of the Λ CDM model shows that if the expansion is anisotropic, σ/\mathcal{H} has to be small. Moreover, since any primordial anisotropy is washed

out by the expansion of the Universe, the term \mathcal{C}_j^i in the evolution of the background shear is negligible compared to the integral term in Eq. (2.20).

As discussed in the introduction, a late-time anisotropy may be generated during the acceleration of the Universe, but the effect we are looking for needs to have an amplitude small enough to be below the detection threshold of ongoing observational surveys.

In full generality a linear and gauge-invariant perturbative expansion around an anisotropic background should be performed. It was developed in Refs. [22,24] in the context of inflation and Appendix A derives the full perturbation theory for a postinflationary era. While a numerical integration of these equations can be performed, it is clear from the previous arguments that an analytical insight in the regime $\sigma/\mathcal{H} \ll 1$ is sufficient.

We shall thus work in the *small shear limit* in which the background shear induced at late time by the anisotropic stress-energy tensor of the dark component is small, that is, in the limit $\sigma/\mathcal{H} \ll 1$. More precisely, we assume that $\gamma_{ij} - \delta_{ij} \simeq 2\beta_i\delta_{ij}$ is a small dimensionless perturbation and σ_{ij}/\mathcal{H} is of the same order as this homogeneous perturbation. We shall thus consider the Bianchi I spacetime as a homogeneous perturbation around an isotropic Friedmann-Lemaître spacetime, hence ignoring nonlinear corrections in the background shear as well. In order to implement this approximation scheme, we introduce a two-parameter perturbation scheme (see e.g., Ref. [79]) in which, besides the usual scalar-vector-tensor (SVT) perturbations over a flat Friedmann-Lemaître background, the geometrical shear is considered as an extra perturbative degree. We refer to Ref. [80] for a detailed description of general Bianchi spaces in this approach.

B. Spacetime description

1. Metric

We shall thus adopt the metric

$$ds^2 = a^2[-(1 + 2\Phi)d\eta^2 + 2\bar{B}_i dx^i d\eta + (\gamma_{ij} + h_{ij})dx^i dx^j], \quad (4.1)$$

where h_{ij} is defined as [see Eqs. (A19) and (A36)]

$$h_{ij} = -2\left(\gamma_{ij} + \frac{\sigma_{ij}}{\mathcal{H}}\right)\Psi + 2E_{ij} \quad (4.2)$$

and γ_{ij} is here understood as the Euclidian metric plus a small perturbation

$$\gamma_{ij} \simeq \delta_{ij} + 2\int_0^a \frac{\sigma_{ij}}{\mathcal{H}} \frac{da'}{a'}, \quad \frac{\sigma_{ij}}{\mathcal{H}} \ll 1. \quad (4.3)$$

In order to simplify the notation, we also define the matrix

$$\beta_{ij} \equiv \text{diag}(\beta_i) \quad (4.4)$$

such that

$$\gamma_{ij} = \exp[2\beta]_{ij} \simeq \delta_{ij} + 2\beta_{ij}, \quad \sigma_{\underline{ij}} = \sigma_j^i = \beta_j^i. \quad (4.5)$$

Thus, β_{ij} controls the homogeneous perturbation. Indices are now raised and lowered with the Euclidian metric δ_{ij} and δ^{ij} , and the vector modes B_i and tensor modes E_{ij} satisfy $\partial^i B_i = \partial^i E_{ij} = E_i^i = 0$. But since β_{ij} is homogeneous, everything happens as if we had usual cosmological perturbation, but also an infinite wavelength perturbation $2\beta_{ij}$ to the spatial metric.

To control the perturbative series, we introduce the $\{n, p\}$ notation, where n and p indicate powers in β and SVT variables, respectively. Thus, a term like σ_{ij}/\mathcal{H} is of order $\{1, 0\}$, terms like Ψ and Φ are of order $\{0, 1\}$, while a product like $\sigma_i^j \partial_j \Psi/\mathcal{H}$ is of order $\{1, 1\}$. However, since vector and tensor modes only appear due to the coupling between the shear and scalar modes [22], vector perturbations B_i and tensor perturbations E_{ij} are also of order $\{1, 1\}$. Hence, for any quantity X , one will consider the different quantities:

- (i) $X^{\{0,0\}}(\eta)$.—the Friedmann-Lemaître background value;
- (ii) $X^{\{1,0\}}(\eta)$.—the first-order (homogeneous) scalar perturbed quantity in σ/\mathcal{H} ;
- (iii) $X^{\{0,1\}}(\eta, \mathbf{x})$.—the first-order inhomogeneous perturbed quantity in Ψ, \dots ;
- (iv) $X^{\{1,1\}}(\eta, \mathbf{x})$.—the first-order inhomogeneous perturbed quantity in both σ/\mathcal{H} and Ψ, \dots and vector and tensor perturbations.

Before moving on we should make some general remarks about the adopted perturbative scheme. Indeed, one might be worried that adding σ_{ij}/\mathcal{H} or β_{ij} as a small homogeneous perturbation to the background metric would not have any significant observable effect, since the SVT decomposition was already designed to describe the most general perturbation over a flat Friedmann-Lemaître universe. Note however that SVT modes do not include a zero Fourier mode in their spectrum (i.e., an infinite wavelength perturbation), since these modes will be isotropic by construction and hence merely rescale the background geometry. The tensor β_{ij} , on the other hand, is a homogeneous (i.e., space-independent) field, which by definition corresponds to an anisotropic zero mode. Thus, its effect cannot be absorbed in a simple rescaling of the scale factor. Moreover, this field sources the background dynamics through Einstein's equations.

2. Tetrad basis

Given this expansion scheme, the tetrad basis associated to the perturbed metric up to order $\{1, 1\}$ is explicitly given by

$$\begin{aligned}
 \Theta_{\underline{i}}^j &\simeq (\delta_{\underline{i}}^j - \beta_{ij})(1 + \Psi) + \frac{\beta'_{ij}}{\mathcal{H}}\Psi - E_{\underline{i}}^j, & \Theta_{\underline{i}}^0 &= 0, \\
 \Theta_{\underline{j}}^i &\simeq (\delta_{\underline{j}}^i + \beta_{ij})(1 - \Psi) - \frac{\beta'_{ij}}{\mathcal{H}}\Psi + E_{\underline{j}}^i, & \Theta_0^{\underline{i}} &= \bar{B}^i, \\
 \Theta_0^0 &= 1 - \Phi, & \Theta_0^{\underline{i}} &= -\bar{B}^i, \\
 \Theta_0^{\underline{i}} &= 1 + \Phi, & \Theta_{\underline{i}}^0 &= 0,
 \end{aligned} \tag{4.6}$$

where $\vartheta_{\underline{i}}^j$ refers to the background spatial triad defined in Eq. (2.11). By choosing the observer to coincide with the timelike vector of the tetrad ($u^\mu = \Theta_0^\mu$, $u_\mu = -\Theta_\mu^0$) we obtain in general the components of the direction vector \mathbf{n} in the tetrad basis as

$$k^{\underline{i}} = -k^0 n^{\underline{i}}, \quad n^{\underline{i}} = \Theta_{\underline{\mu}}^{\underline{i}} n^\mu. \tag{4.7}$$

At the position of the observer, the direction of the geodesic in the tetrad basis $n_0^{\underline{i}}$ is also the direction in which the observation is made. Again, we recall that we are interested in the observables related to light propagation as expressed in function of this observed direction $n_0^{\underline{i}}$.

Since we have introduced two types of tetrads ($\{\vartheta\}$ and $\{\Theta\}$), there is an ambiguity whenever a tetrad index \underline{i} appears on a tensorial quantity. First, for the geometric shear tensor, the tetrad index is defined with respect to the triad $\vartheta_{\underline{i}}^\mu$ and we recall that $\sigma_{\underline{i}\underline{j}} = \sigma^{\underline{i}\underline{j}} = \sigma_{\underline{j}}^{\underline{i}} = \text{diag}(\beta_{\underline{i}}^{\underline{i}}) = \beta_{\underline{i}\underline{j}}^{\underline{i}}$; see Eq. (2.12). Second, for partial derivatives the tetrad index corresponds also to the tetrad $\{\vartheta\}$ and we define

$$\partial_{\underline{i}} \equiv \vartheta_{\underline{i}}^j \partial_j \simeq \partial_i - \beta_{\underline{i}}^j \partial_j. \tag{4.8}$$

It makes clear the difference between a derivative in the direction of a tetrad vector $\partial_{\underline{i}}$ and the derivative in the direction of the vectors ∂_i associated with the Cartesian coordinates. Since the vector perturbations B_i and the tensor perturbations E_{ij} are already of order $\{1, 1\}$, there is absolutely no difference between their tetrad components $B_{\underline{i}}$ and $E_{\underline{i}\underline{j}}$ at this order of perturbations and there is no need to be particularly careful. Everywhere else, a tetrad index refers to the tetrad $\{\Theta\}$ defined in Eqs. (4.6).

C. Technical interlude

Since we are interested in computing observables on the celestial sphere, spherical coordinates are much more convenient than Cartesian coordinates. This section describes the use of such spherical coordinates in real space and of the associated derivatives (radial and on the unit sphere). Several definitions of covariant derivatives have to be distinguished. We finish by relating them to each other and to the spin-raising operator of spherical harmonics.

1. Spherical coordinates in real space

Consider a tensor depending on Cartesian coordinates $T_{i_1 \dots i_n}(x^i)$ (with indices raised and lowered, respectively, with δ_{ij} and δ^{ij}); it can always be constructed by considering the tetrad components of a given tensor. In spherical coordinates, one can then define from the partial derivative $\partial_i = \partial/\partial x^i$ a covariant derivative D_i on the unit sphere and a radial derivative ∂_r . To be more precise, this requires the use of the projectors

$$S_{ij} \equiv \delta_{ij} - \hat{x}_i \hat{x}_j, \quad \hat{x}^i \equiv \frac{x^i}{r}, \quad \text{with } r^2 = \sum_{i=1}^3 (x^i)^2. \tag{4.9}$$

Recall that $S^{ij} = \delta^{ip} \delta^{jq} S_{pq}$ and $S_i^j = \delta^{ip} S_{pj}$. The covariant derivative on the unit sphere $S^2|_{\text{space}}$ of the Cartesian coordinates centered on the observer is denoted by $D_i^{\mathbb{R}^3}$ and is defined from the general projection

$$\frac{1}{r} D_i^{\mathbb{R}^3} T_{j_1 \dots j_n} \equiv S_i^k S_{j_1}^{q_1} \dots S_{j_n}^{q_n} \frac{\partial}{\partial x^k} T_{q_1 \dots q_n} \equiv P \left[\frac{\partial}{\partial x^i} T_{j_1 \dots j_n} \right], \tag{4.10}$$

where $P[\dots]$ is to be understood as the projection of all free Cartesian indices with the projector S_i^j . This derivative only makes sense if the tensor itself is a projected tensor, that is, if it satisfies $P[T_{j_1 \dots j_n}] = T_{j_1 \dots j_n}$.

The radial derivative is then obtained simply by

$$\partial_r T_{j_1 \dots j_n} \equiv \hat{x}^i \frac{\partial}{\partial x^i} T_{j_1 \dots j_n}. \tag{4.11}$$

Now, any combination of partial derivatives ∂_i applied to some tensor can be decomposed in terms of radial derivatives ∂_r and covariant derivatives on the sphere $D_i^{\mathbb{R}^3}$. The simplest such decomposition is

$$\partial_i f = \hat{x}^i \partial_r f + \frac{1}{r} D_i^{\mathbb{R}^3} f, \tag{4.12}$$

for any scalar function f . The decompositions for projected tensors of various ranks is detailed in Appendix D 1. For general tensors which are not necessarily projected, it is necessary to split them into their projected components on the sphere and their radial components before decomposing any derivative applying on them. Such decomposition for the vector and tensor modes is given in Eqs. (D5). To finish, it is easy to check that

$$D_i^{\mathbb{R}^3} S_{jk} = 0, \quad D_i^{\mathbb{R}^3} \epsilon_{jk} = 0, \tag{4.13}$$

where the completely antisymmetric tensor on the sphere is

$$\epsilon_{ij} \equiv \epsilon_{ijk} \hat{x}^k. \tag{4.14}$$

2. Covariant derivative on the tangent space

For any spatial tensor constant in space, such as $\sigma_{i\bar{j}}$, one can define scalar, vector and tensor fields on the unit sphere. First, one can define a scalar field on the unit sphere of observing directions, $S^2|_{\text{obs}}$, by contracting all free indices with the direction of observation:

$$\Sigma \equiv \frac{1}{2} \sigma_{i\bar{k}} n_{\bar{0}}^i n_{\bar{0}}^k. \quad (4.15)$$

Indeed, the observing direction can be considered as a point on $S^2|_{\text{obs}}$, whose spherical coordinates are (θ_o, φ_o) , and Σ from the expression (4.15) is thus a function of (θ_o, φ_o) , that is, a scalar field on $S^2|_{\text{obs}}$. Then, to define a vector field on the unit sphere, one needs to contract one index with the observing direction and project the remaining one on the sphere. Furthermore, in order to get a tensor field on the unit sphere, we shall project the two free indices on the sphere. These projections are obtained by contraction with the screen basis vectors \mathbf{n}_a^o at the observer. For instance, the vector and tensor fields on the sphere build from the geometric shear are simply

$$\Sigma_a \equiv n_a^{o\bar{j}} \sigma_{\bar{j}\bar{i}} n_{\bar{0}}^i, \quad \Sigma_{ab} \equiv n_a^{o\bar{i}} n_b^{o\bar{k}} \sigma_{\bar{i}\bar{k}}. \quad (4.16)$$

We remark that Σ_{ab} , which is a symmetric 2×2 matrix, is not traceless. In fact, using the partition of the identity $\delta^{ij} = n^i n^{\bar{j}} + n_1^i n_1^{\bar{j}} + n_2^i n_2^{\bar{j}}$, the trace is given by $\delta^{ab} n_a^{o\bar{i}} n_b^{o\bar{k}} \sigma_{\bar{i}\bar{k}} = -\sigma_{i\bar{k}} n^i n^{\bar{k}} = -2\Sigma$. Alternatively, the vector and tensor fields (4.16) can be obtained by applying successively the covariant derivative on the unit sphere D_a to $\Sigma(\theta_o, \varphi_o)$. Indeed, with this method, we find the relations

$$\begin{aligned} \Sigma_a &= D_a \Sigma, & \Sigma_{ab} &= D_a D_b \Sigma + 2\delta_{ab} \Sigma, \\ D_a D^a \Sigma &= -6\Sigma, & \Sigma_{(ab)} &= D_{(a} D_{b)} \Sigma. \end{aligned} \quad (4.17)$$

Note that the metric and the antisymmetric tensor on the sphere are obtained from

$$\delta_{ab} = 2n_a^{(+)} n_b^{(-)}, \quad \epsilon_{ab} = 2in_a^{[-]} n_b^{[+]} \quad (4.18)$$

and satisfy

$$D_a \delta_{bc} = 0, \quad D_a \epsilon_{bc} = 0. \quad (4.19)$$

3. Background geodesics and identification of covariant derivatives

The covariant derivative D_a , related to the unit sphere in the observer's tangent space, and the derivative $D_i^{\mathbb{R}^3}$, related to the unit sphere of Cartesian coordinates, are fundamentally different. But, they can be related in a simple way. Indeed, the solution to the background geodesic at order

$\{0, 0\}$, that is, the geodesics of the spatially flat Friedmann-Lemaître spacetime, is given by

$$\begin{aligned} n^{\bar{i}} &= n_{\bar{0}}^i, & n_a^{\bar{i}} &= n_a^{o\bar{i}}, \\ \frac{dx^{i\{0,0\}}}{d\chi} &= n_{\bar{0}}^i \Rightarrow x^{i\{0,0\}} &= \chi n_{\bar{0}}^i, \end{aligned} \quad (4.20)$$

where, we remind the reader, $n_{\bar{0}}^i$ is the direction of the geodesic at the position of the observer in the tetrad basis. This is the direction of observation, since we have oriented the geodesic toward the past.

There is thus a straightforward identification between the sphere of the directions of observation, lying in the tangent space at the observer (the set of directions $S^2|_{\text{obs}}$ spanned by $n_{\bar{0}}^i$), and the set of points of \mathbb{R}^3 reached at an affine parameter χ (or η) on the background geodesic. Indeed, the points spanned by the coordinates $x^{i\{0,0\}}$ at a given affine parameter χ are such that

$$\delta_{ij} x^{i\{0,0\}} x^{j\{0,0\}} = r^2(\chi) = \chi^2$$

and form a sphere in the Cartesian coordinates. We can then subsequently identify this sphere of radius χ to the unit sphere $S^2|_{\text{space}}$.

This means that we can identify $n_{\bar{0}}^i$ with \hat{x}^i and then D_a on $S^2|_{\text{obs}}$ with $n_a^{o\bar{i}} D_i^{\mathbb{R}^3}$, the projection onto the screen basis \mathbf{n}_a^o being used only to switch from the extrinsic point of view of the derivative (the projection of the Cartesian derivative onto the sphere) to an intrinsic point of view on the sphere. In the rest of this article we thus replace the notation $D_i^{\mathbb{R}^3}$ by D_i , $n_a^{o\bar{i}} D_i^{\mathbb{R}^3}$ by D_a , and $n_{\pm}^{o\bar{i}} D_i^{\mathbb{R}^3}$ by D_{\pm} .

4. Link with spin-raising operator and spin-weighted spherical harmonics

The covariant derivative on the unit sphere is related to the usual spin-raising and spin-lowering operators. In spherical coordinates, these operators are defined for a spin- s quantity by

$$\partial X^s = -\sin^s \theta \left[\partial_\theta + i \frac{1}{\sin \theta} \partial_\varphi \right] (\sin^{-s} \theta X^s), \quad (4.21a)$$

$$\bar{\partial} X^s = -\sin^{-s} \theta \left[\partial_\theta - i \frac{1}{\sin \theta} \partial_\varphi \right] (\sin^s \theta X^s). \quad (4.21b)$$

They are related to the covariant derivative through

$$\begin{aligned} \partial &= -\sqrt{2} n_-^o{}^a D_a = -\sqrt{2} D_+, \\ \bar{\partial} &= -\sqrt{2} n_+^o{}^a D_a = -\sqrt{2} D_-, \end{aligned} \quad (4.22)$$

the vector \mathbf{n}_{\pm}^o being defined in Eq. (3.11). Hence, for a tensor field of spin $+|s|$ on the sphere, $X^{\nu_1 \dots \nu_s} = X^s n_+^{\nu_1} \dots n_+^{\nu_s}$, and a tensor of spin $-|s|$, $Z^{\nu_1 \dots \nu_s} = Z^{-s} n_-^{\nu_1} \dots n_-^{\nu_s}$, we have

$$-\sqrt{2}\nabla^\mu X^{\nu_1\dots\nu_s} = (\partial X^s)n_+^{\circ\mu}n_+^{\circ\nu_1}\dots n_+^{\circ\nu_s} + (\bar{\partial}X^s)n_-^{\circ\mu}n_+^{\circ\nu_1}\dots n_+^{\circ\nu_s}, \quad (4.23a)$$

$$-\sqrt{2}\nabla^\mu Z^{\nu_1\dots\nu_s} = (\partial Z^{-s})n_+^{\circ\mu}n_-^{\circ\nu_1}\dots n_-^{\circ\nu_s} + (\bar{\partial}Z^{-s})n_-^{\circ\mu}n_-^{\circ\nu_1}\dots n_-^{\circ\nu_s}. \quad (4.23b)$$

Since the spin-weighted spherical harmonics satisfy the property

$$Y_{\ell m}^s = \begin{cases} \sqrt{\frac{(\ell-s)!}{(\ell+s)!}} \partial^s Y_{\ell m} & \text{if } 0 \leq s \leq \ell, \\ (-1)^s \sqrt{\frac{(\ell+s)!}{(\ell-s)!}} \bar{\partial}^{-s} Y_{\ell m} & \text{if } -\ell \leq s \leq 0, \end{cases} \quad (4.24)$$

any number of covariant derivatives applied on a spherical harmonic can be computed using the properties (4.23).

As an application, consider the expansion of the variable Σ in spherical harmonics

$$\Sigma(\chi, n_0^i) = \sum_{m=-2}^{+2} \Sigma_{2m}(\chi) Y_{2m}(n_0^i). \quad (4.25)$$

If we align the azimuthal direction with an eigendirection of the geometric shear, the multipoles coefficients are then given by

$$\begin{aligned} \Sigma_{20}(\chi) &= -\sqrt{\frac{\pi}{5}} [\beta'_1(\chi) + \hat{\beta}'_2(\chi)], \\ \hat{\Sigma}_{2\pm 2}(\chi) &= \sqrt{\frac{\pi}{30}} [\beta'_1(\chi) - \beta'_2(\chi)]. \end{aligned} \quad (4.26)$$

The most useful derivatives are then easily obtained to be

$$\begin{aligned} \Sigma_{\pm}(\chi, n_0^i) &= n_{\mp}^{\circ k} n_0^{\circ j} \sigma_{kj}(\chi) = D_{\pm} \Sigma(\chi, n_0^i) \\ &= \mp \sqrt{3} \sum_m \Sigma_{2m}(\chi) Y_{2m}^{\pm 1}(n_0^i), \end{aligned} \quad (4.27a)$$

$$\begin{aligned} \Sigma_{\pm\pm}(\chi, n_0^i) &= n_{\mp}^{\circ k} n_{\mp}^{\circ j} \sigma_{kj}(\chi) = D_{\pm} D_{\pm} \Sigma(\chi, n_0^i) \\ &= \sqrt{6} \sum_m \Sigma_{2m}(\chi) Y_{2m}^{\pm 2}(n_0^i). \end{aligned} \quad (4.27b)$$

Similarly, if we expand a scalar field $\varphi(\chi, x^i)$ in spherical harmonics

$$\varphi(\chi, x^i) = \sum_{\ell, m} \varphi_{\ell m}(\chi, r) Y_{\ell m}(\hat{x}^i), \quad (4.28)$$

then the most useful derivatives are

$$D_{\pm} \varphi(\chi, x^i) = \mp \sqrt{\frac{\ell(\ell+1)}{2}} \sum_{\ell, m} \varphi_{\ell m}(\chi, r) Y_{\ell m}^{\pm 1}(\hat{x}^i), \quad (4.29a)$$

$$D_{\pm} D_{\pm} \varphi(\chi, x^i) = \frac{1}{2} \sqrt{\frac{(\ell+2)!}{(\ell-2)!}} \sum_{\ell, m} \varphi_{\ell m}(\chi, r) Y_{\ell m}^{\pm 2}(\hat{x}^i), \quad (4.29b)$$

$$\begin{aligned} 2D_{\pm} D_{\mp} \varphi(\chi, x^i) &= D_a D^a \varphi(\chi, x^i) \\ &= -\ell(\ell+1) \sum_{\ell, m} \varphi_{\ell m}(\chi, r) Y_{\ell m}(\hat{x}^i). \end{aligned} \quad (4.29c)$$

D. Geodesics and Sachs equations in term of the Friedmannian coordinates

In the approximation that we are considering, we can solve the perturbation equations and the Sachs equation up to order $\{1, 1\}$. We shall define the distance down to the light cone on the Friedmann-Lemaître background space-time as

$$\chi \equiv \eta_0 - \eta. \quad (4.30)$$

The geodesic equation (3.1) takes the form

$$\frac{dk^\nu}{dv} + \Gamma_{\alpha\beta}^\nu k^\alpha k^\beta = 0, \quad k^0 = -\frac{d\chi}{dv} \quad (4.31)$$

and using (4.7) can be rewritten directly in terms of tetrad components as

$$\frac{dk^i}{dv} = \frac{dk_i}{dv} = (k^0)^2 (\omega_{\underline{k}\underline{j}\underline{i}} n^{\underline{k}} n^{\underline{j}} + \omega_{\underline{0}\underline{0}\underline{i}} - \omega_{\underline{j}\underline{0}\underline{i}} n^{\underline{j}} - \omega_{\underline{0}\underline{j}\underline{i}} n^{\underline{j}}), \quad (4.32a)$$

$$\frac{dk^0}{dv} = -\frac{dk_0}{dv} = (k^0)^2 (-\omega_{\underline{i}\underline{j}\underline{0}} n^{\underline{i}} n^{\underline{j}} + \omega_{\underline{0}\underline{i}\underline{0}} n^{\underline{i}}), \quad (4.32b)$$

where the affine connections are defined in Appendix B 1. Instead of the parameter v we shall use the parameter χ since, once the wave vector is integrated, we have

$$\frac{dx^\mu}{d\chi} = -\frac{k^\mu}{k^0}. \quad (4.33)$$

The position on the geodesic then becomes a function of the parameter χ and the initial direction n_0^i . Finally, the Sachs equation with the parameter χ reads [61]

$$\frac{d^2 \mathcal{D}_{ab}}{d\chi^2} + \frac{1}{k^0} \frac{dk^0}{d\chi} \frac{d\mathcal{D}_{ab}}{d\chi} = \frac{1}{(k^0)^2} \mathcal{R}_{ac} \mathcal{D}_{cb}. \quad (4.34)$$

V. ANGULAR MULTIPOLE CORRELATIONS IN ANISOTROPIC SPACES

As previously explained, we adopt an observer point of view in which all observable quantities are considered as

functions of the direction of observation \mathbf{n}_o and of the affine parameter v or, equivalently, of the redshift z , keeping in mind that the latter also depends on \mathbf{n}_o . All these quantities can be decomposed on a basis of spin-weighted spherical harmonics, $Y_{\ell m}^s$. The goal of this section is to derive a set of formal expressions concerning these expansions and to establish general results of the two-point correlation function valid in Bianchi I geometries.

We consider that the Universe has undergone an early period of isotropic expansion followed by a late-time anisotropic phase. This is in sharp contrast with the approach of Ref. [30], in which the Universe is supposed to have an early inflationary stage followed by an isotropic evolution (so that geodesics are Friedmann-Lemaître geodesics and anisotropy is imprinted only in the source term).

The tools we shall develop are not specific to weak lensing and can be used in other contexts, such as the study of the cosmic microwave background. We first describe, in Sec. VA, the general expansion of spin- s quantities. This will allow us to express their angular power spectrum in Sec. VB. We conclude by demonstrating that, while spatial parity symmetry implies that the EB correlation matrix vanishes, some off-diagonal correlations are necessarily nonvanishing and encode information on the geometrical shear.

A. Multipolar expansions

The spin- s polarization basis is defined as a tensor product of s polarization vectors as

$$\mathbf{m}_o^s \equiv \begin{cases} \mathbf{n}_o^+ \otimes \cdots \otimes \mathbf{n}_o^+ & \text{if } s > 0, \\ \mathbf{n}_o^- \otimes \cdots \otimes \mathbf{n}_o^- & \text{if } s < 0. \end{cases} \quad (5.1)$$

Under the action of an active rotation R , this basis transforms as

$$R[\mathbf{m}_o^s] \equiv R \cdot \mathbf{m}_o^s (R^{-1} \cdot \mathbf{n}_o), \quad (5.2)$$

where \mathbf{n}_o is the vector along the line of sight at the point of observation. Spin-weighted spherical harmonics transform under the same rotation as

$$\begin{aligned} R[Y_{\ell m}^s(\mathbf{n}_o)\mathbf{m}_o^s] &\equiv Y_{\ell m}^s(R^{-1} \cdot \mathbf{n}_o)R[\mathbf{m}_o^s] \\ &= \sum_{m'} Y_{\ell m'}^s(\mathbf{n}_o)\mathbf{m}_o^s D_{m'm}^\ell(R), \end{aligned} \quad (5.3)$$

where $D_{mm'}^\ell(R)$ are the components of the Wigner D matrix. This means that they transform like *normal* spherical harmonics *provided* they are accompanied by the polarization basis to which they are associated.

Now, any cosmological observable X^s of spin s can be expressed in the form

$$X^s(\chi_S, \mathbf{n}_o)\mathbf{m}_o^s = \int_0^{\chi_S} S^{X_s}(\chi_S, \chi, \mathbf{n}_o)\mathbf{m}_o^s d\chi, \quad (5.4)$$

where χ_S refers to the position of the source. Note that we are explicitly making use of the small shear expansion, since the source term is integrated along a geodesic of the Friedmann-Lemaître spacetime. This means that in order to compute X^s at order $\{n, p\}$ one needs to determine the source S^{X_s} at the same order. The source term $S^{X_s}(\chi_S, \chi, \mathbf{n}_o)$ has to be understood as

$$S^{X_s}(\chi_S, \chi, \mathbf{n}_o) = S^{X_s}(\chi_S, \chi, x^i, \mathbf{n}_o)|_{x^i=\chi n_o^i}, \quad (5.5)$$

that is, evaluated on the background geodesic. Moreover, thanks to Eq. (4.30), the parameters χ and χ_S can be thought as time coordinates. The intrinsic angular dependence of S^{X_s} on \mathbf{n}_o is a consequence of the (possible) nonscalar nature of the source. Moving forward, it is convenient to decompose X^s into spherical harmonics as

$$X^s(\chi_S, \mathbf{n}_o)\mathbf{m}_o^s = \sum_{\ell, m} X_{\ell m}^s(\chi_S)Y_{\ell m}^s(\mathbf{n}_o)\mathbf{m}_o^s, \quad (5.6)$$

which will allow us to define multipolar correlations at unequal times of the form $\langle X_{\ell m}^s(\chi_{S1})X_{\ell' m'}^{s*}(\chi_{S2}) \rangle$. In order to compute these angular correlators, we first need to take the Fourier transform of the source (5.4) off the line of sight

$$S^{X_s}(\chi_S, \chi, x^i, \mathbf{n}_o)\mathbf{m}_o^s = \int \frac{d^3\mathbf{k}}{(2\pi)^{3/2}} S^{X_s}(\chi_S, \chi, \mathbf{k}, \mathbf{n}_o)e^{i\mathbf{k}\cdot\mathbf{x}}\mathbf{m}_o^s, \quad (5.7)$$

in the sense that we do not bind x^i to χ by the relation $x^i = \chi n_o^i$ and χ has to be thought as a time coordinate thanks to Eq. (4.30). Then, the intrinsic dependence of the source on \mathbf{n}_o is further expanded in terms of spherical harmonics, with the latter being defined with respect to an axis aligned with the Fourier mode \mathbf{k} . That is,

$$\begin{aligned} S^{X_s}(\chi_S, \chi, \mathbf{k}, \mathbf{n}_o)\mathbf{m}_o^s \\ = \sum_{\ell, m} S_{\ell m}^{X_s}(\chi_S, \chi, \mathbf{k})i^\ell \sqrt{\frac{4\pi}{2\ell+1}} R_{\mathbf{k}}[Y_{\ell m}^s(\mathbf{n}_o)\mathbf{m}_o^s], \end{aligned} \quad (5.8)$$

where $R_{\mathbf{k}}$ is a rotation that transports the azimuthal direction to the direction of the Fourier mode \mathbf{k} (see Appendix C for details about this notation). The terms with $m = 0, 1, 2$ correspond here to scalar, vector and tensor perturbations, respectively. If we now make use of the Rayleigh expansion

$$\begin{aligned}
 e^{i\mathbf{k}\cdot\mathbf{x}} &= 4\pi \sum_{\ell,m} i^\ell j_\ell(kr) Y_{\ell m}^*(\hat{\mathbf{k}}) Y_{\ell m}(\mathbf{n}_o) \\
 &= \sum_{\ell} i^\ell \sqrt{(4\pi)(2\ell+1)} j_\ell(kr) R_{\mathbf{k}}[Y_{\ell 0}(\mathbf{n}_o)], \quad (5.9)
 \end{aligned}$$

with $r = \delta_{ij} x^i x^j$, and insert the decomposition (5.8) into Eq. (5.7), we find, after comparing Eqs. (5.6) and (5.7), that

$$\begin{aligned}
 X_{\ell m}^s(\chi_s) &= \sqrt{\frac{2}{\pi}} \int d^3\mathbf{k} \int_0^{\chi_s} d\chi' \sum_{m'} D_{mm'}^\ell(R_{\mathbf{k}}) i^\ell \\
 &\times \sqrt{\frac{(2\ell+1)}{4\pi}} \sum_{\ell'} j_{\ell'}^{(\ell' m')}(\chi') S_{\ell' m'}^{X_s}(\chi_s, \chi, \mathbf{k}), \quad (5.10)
 \end{aligned}$$

where we have introduced the definitions

$$j_{\ell'}^{(\ell' m')}(x) \equiv \sum_L {}^s C_{\ell L \ell'}^{m' 0 m'} j_L(x) i^{L+\ell'-\ell} \sqrt{\frac{(4\pi)(2L+1)}{(2\ell+1)(2\ell'+1)}} \quad (5.11)$$

and

$${}^s C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} \equiv \int d^2\Omega Y_{\ell_1 m_1}^{s, \star}(\mathbf{n}_o) Y_{\ell_2 m_2}(\mathbf{n}_o) Y_{\ell_3 m_3}^s(\mathbf{n}_o). \quad (5.12)$$

The dynamical evolution and the initial conditions of the source can be split as

$$S_{\ell m}^{X_s}(\chi_s, \chi, \mathbf{k}) = T_{\ell m}^{X_s}(\chi_s, \chi, \mathbf{k}) \Phi_i(\mathbf{k}), \quad (5.13)$$

where $T_{\ell m}^{X_s}$ is the (anisotropic) transfer function and $\Phi_i(\mathbf{k})$ is the primordial gravitational potential. Then, assuming that anisotropies are induced at late-time evolution only, the statistics of the primordial power spectrum must obey

$$\langle \Phi_i(\mathbf{k}) \Phi_i^*(\mathbf{q}) \rangle = P(k) \delta^3(\mathbf{k} - \mathbf{q}), \quad (5.14)$$

with $P(k)$ being the (isotropic) primordial power spectrum. To account for the angular dependence of the transfer functions, we further decompose them as

$$T_{\ell m}^{X_s}(\chi_s, \chi, \mathbf{k}) = \sum_{L,M} X_s T_{\ell m}^{LM}(\chi_s, \chi, k) Y_{LM}(\hat{\mathbf{k}}). \quad (5.15)$$

B. Expression of the two-point angular correlators

These formulas can now be combined [using in particular Eq. (D25) to integrate out all spherical harmonics] to give an expression for the correlation between the multipoles of two different observables X^{s_1} and Z^{s_2} . We find

$$\begin{aligned}
 \langle X_{\ell_1 m_1}^{s_1}(\chi_{S1}) Z_{\ell_2 m_2}^{s_2 \star}(\chi_{S2}) \rangle &= \frac{2}{\pi} (i)^{\ell_1} (-i)^{\ell_2} \int_0^\infty dk k^2 P(k) \int_0^{\chi_{S1}} d\chi_1 \int_0^{\chi_{S2}} d\chi_2 \sum_{\ell, m} \sum_{\ell', m'} \sum_{\substack{\ell_1, M_1 \\ \ell_2, M_2}} (-1)^{m'_1 + m'_2 s_1} j_{\ell_1}^{(\ell' m'_1)} \\
 &\times (k\chi_1)^{s_2} j_{\ell_2}^{(\ell' m'_2) \star} (k\chi_2)^{-m'_1} C_{\ell_1 \ell L_1}^{m_1 M_1 - m'_2} C_{\ell_2 \ell L_2}^{m_2 M_2 X_{s_1}} T_{\ell_1 m_1}^{L_1 M_1}(\chi_{S1}, \chi_1, k) Z_{\ell_2 m_2}^{L_2 M_2 \star}(\chi_{S2}, \chi_2, k). \quad (5.16a)
 \end{aligned}$$

A central quantity in this description is the two-point correlation function of the E and B modes of a given spin-2 observable (as, for instance, the cosmic shear γ). This expression requires the decomposition of $X^{\pm s}$, ${}^{\pm s} j_{\ell}^{(\ell' m')}$ and $S_{\ell m}^{X_s}$ in their even or odd parity pieces as

$$X_{\ell m}^s(\chi) = E_{\ell m}^{X_s}(\chi) + i \operatorname{sgn}(s) B_{\ell m}^{X_s}(\chi), \quad (5.17a)$$

$${}^{\pm s} j_{\ell}^{(\ell' m')}(x) = |s| \epsilon_{\ell}^{(\ell' m')} (x) + i \operatorname{sgn}(s) |s| \beta_{\ell}^{(\ell' m')}(x), \quad (5.17b)$$

$$S_{\ell m}^{X_s}(\chi_s, \chi, \mathbf{k}) = [T_{\ell m}^{E X_s}(\chi_s, \chi, \mathbf{k}) + i \operatorname{sgn}(s) T_{\ell m}^{B X_s}(\chi_s, \chi, \mathbf{k})] \Phi_i(\mathbf{k}). \quad (5.17c)$$

Note that a spin $s = 2$ field will have both E and B modes, while a scalar ($s = 0$) field will only have the E mode, so that ${}^0 \beta_{\ell}^{(\ell' m')} = 0$ and $B_{\ell m}^{X_0} = 0$.

From these expressions and Eq. (5.10), one can verify that

$$E_{\ell m}^{X_s}(\chi_s) = \sqrt{\frac{2}{\pi}} \int d^3\mathbf{k} \int_0^{\chi_s} d\chi \sum_{m'} D_{mm'}^\ell(R_{\mathbf{k}}) i^\ell \sqrt{\frac{(2\ell+1)}{4\pi}} \\ \times \sum_{\ell'} [|\mathbf{s}| \epsilon_m^{(\ell' m')} (k\chi) T_{\ell' m'}^{E^{X_s}}(\chi_s, \chi, \mathbf{k}) - |\mathbf{s}| \beta_m^{(\ell' m')} (k\chi) T_{\ell' m'}^{B^{X_s}}(\chi_s, \chi, \mathbf{k})] \Phi_i(\mathbf{k}), \quad (5.18a)$$

$$B_{\ell m}^{X_s}(\chi_s) = \sqrt{\frac{2}{\pi}} \int d^3\mathbf{k} \int_0^{\chi_s} d\chi \sum_{m'} D_{mm'}^\ell(R_{\mathbf{k}}) i^\ell \sqrt{\frac{(2\ell+1)}{4\pi}} \\ \times \sum_{\ell'} [|\mathbf{s}| \epsilon_m^{(\ell' m')} (k\chi) T_{\ell' m'}^{B^{X_s}}(\chi_s, \chi, \mathbf{k}) + |\mathbf{s}| \beta_m^{(\ell' m')} (k\chi) T_{\ell' m'}^{E^{X_s}}(\chi_s, \chi, \mathbf{k})] \Phi_i(\mathbf{k}). \quad (5.18b)$$

Then, the EE and BB covariance matrices can be computed by simply taking appropriate combinations of $X_{\ell m}^{\pm s}$. In order to simplify the notation we define

$$\mathcal{M}_{\ell_1 m_1 \ell_2 m_2}^{ACA'C'}(\chi_{S1}, \chi_{S2}) \equiv \frac{2}{\pi} (i)^{\ell_1} (-i)^{\ell_2} \int_0^\infty dk k^2 P(k) \int_0^{\chi_{S1}} d\chi_1 \int_0^{\chi_{S2}} d\chi_2 \\ \times \sum_{\ell, m} \sum_{\ell', m'} \sum_{\ell_1, m_1} (-1)^{m_1 + m_2'} j_{\ell_1}^{(\ell' m_1)}(k\chi_1) j_{\ell_2}^{(\ell_2 m_2)'}(k\chi_2)^{-m_1'} C_{\ell_1 \ell L_1}^{m_1 m M_1 - m_2'} C_{\ell_2 \ell L_2}^{m_2 m M_2 A} T_{\ell_1 m_1}^{L_1 M_1} \\ \times (\chi_{S1}, \chi_1, k)^C T_{\ell_2 m_2}^{L_2 M_2, \star}(\chi_{S2}, \chi_2, k) \quad (5.19a)$$

together with the notation

$$A j_{\ell}^{(\ell' m')} = \begin{cases} |\mathbf{s}| \epsilon_{\ell}^{(\ell' m')} & \text{if } A = E^{X_s}, \\ |\mathbf{s}| \beta_{\ell}^{(\ell' m')} & \text{if } A = B^{X_s}. \end{cases}$$

Thus, the EE and BB correlations become

$$\langle E_{\ell_1 m_1}^{X_s} E_{\ell_2 m_2}^{X_s \star} \rangle = \sum_{A,C} \mathcal{M}_{\ell_1 m_1 \ell_2 m_2}^{ACAC} [\delta_A^E \delta_C^E + \delta_A^B \delta_C^B - \delta_A^E \delta_C^B - \delta_A^B \delta_C^E], \quad (5.20a)$$

$$\langle B_{\ell_1 m_1}^{X_s} B_{\ell_2 m_2}^{X_s \star} \rangle = \sum_{A,C} \mathcal{M}_{\ell_1 m_1 \ell_2 m_2}^{ACA\bar{C}} [\delta_A^E \delta_C^E + \delta_A^B \delta_C^B + \delta_A^E \delta_C^B + \delta_A^B \delta_C^E], \quad (5.20b)$$

where, in the last equality, we have introduced the notation according to which \bar{A} equals E^{X_s} (respectively, B^{X_s}) whenever A is equal to B^{X_s} (respectively, E^{X_s}), the same holding for \bar{C} . The EB correlation can be computed using the same method.

The expression (5.20) is quite general. Let us first focus on its diagonal part, which can be characterized by the following estimators of

$$C_{\ell}^{EE}(\chi_{S1}, \chi_{S2}) = \frac{1}{2\ell+1} \sum_m \langle E_{\ell m}^{X_s}(\chi_{S1}) E_{\ell m}^{X_s \star}(\chi_{S2}) \rangle, \quad (5.21a)$$

$$C_{\ell}^{BB}(\chi_{S1}, \chi_{S2}) = \frac{1}{2\ell+1} \sum_m \langle B_{\ell m}^{X_s}(\chi_{S1}) B_{\ell m}^{X_s \star}(\chi_{S2}) \rangle. \quad (5.21b)$$

The angular power spectra are then given by simpler expressions

$$C_{\ell}^{EE}(\chi_{S1}, \chi_{S2}) = \frac{2}{\pi} \int_0^\infty \frac{dk k^2}{4\pi} P(k) \sum_{m, L, M, A, C} [\delta_A^E \delta_C^E + \delta_A^B \delta_C^B - \delta_A^E \delta_C^B - \delta_A^B \delta_C^E] \\ \times \left[\sum_{\ell_1} \int_0^{\chi_{S1}} d\chi_1 {}^A T_{\ell_1 m}^{LM}(\chi_{S1}, \chi_{S2}, k) {}^A j_{\ell}^{(\ell_1 m)}(k\chi_1) \right] \left[\sum_{\ell_2} \int_0^{\chi_{S2}} d\chi_2 {}^C T_{\ell_2 m}^{LM}(\chi_{S1}, \chi_{S2}, k) {}^C j_{\ell}^{(\ell_2 m)}(k\chi_2) \right]^{\star} \quad (5.22a)$$

with, again, a similar expression for the B modes.

The case where the transfer functions are isotropic is easily recovered. To see that, let us consider the simpler situation where $X^{s_1} = Z^{s_2} = \Theta$, with Θ being the CMB temperature fluctuations. Since Θ is a scalar, then it is a pure E mode with no B mode. In the previous formalism, we just need to set ${}^E T_{\ell m}^{LM} = \Theta T_{\ell m}^{LM}$ and ${}^B T_{\ell m}^{LM} = 0$. Then, using $\Theta T_{\ell m}^{LM} = \sqrt{4\pi} T_{\ell m}^{\Theta} \delta^{L0} \delta^{M0}$, we get from Eq. (5.16) the standard result

$$C_{\ell}^{\Theta\Theta} = \frac{2}{\pi} \int_0^{\infty} k^2 dk P(k) \sum_m \left| \int_0^{\infty} d\chi' \sum_{\ell'} T_{\ell' m}^{\Theta}(k, \chi') j_{\ell'}^{(\ell' m)}(k\chi') \right|^2, \quad (5.23)$$

where in this specific case it must be understood that the visibility function is included in the transfer functions $T_{\ell m}^{\Theta}(k, \chi')$. If we consider only scalar sources, then only the $m = 0$ mode contributes. Analogously, if we also have sources with no intrinsic direction (like, for example, no Doppler effect in the CMB), then we have $\ell' = 0$.

C. Implication of spatial parity

We would like to briefly elucidate the relationship between the symmetries of the underlying background spacetime and the cross-correlation functions of different observables. In particular, we want to show that (spatial) parity symmetry implies that the diagonal piece of the EB correlation matrix is zero, while off-diagonal terms may not necessarily be.

We start by noticing that under a parity inversion $\{x, y, z\} \rightarrow \{-x, -y, -z\}$, or, equivalently, $\{\mathbf{n}_o, \mathbf{n}_\theta, \mathbf{n}_\phi\} \rightarrow \{-\mathbf{n}_o, -\mathbf{n}_\theta, \mathbf{n}_\phi\}$, the polarization vectors transform as

$$\mathbf{n}_o^{\pm}(\mathbf{n}_o) \rightarrow -\mathbf{n}_o^{\mp}(\mathbf{n}_o). \quad (5.24)$$

This implies that the polarization basis should transform under parity as

$$\mathbf{m}_o^s(\mathbf{n}_o) \rightarrow (-1)^s \mathbf{m}_o^{-s}(\mathbf{n}_o). \quad (5.25)$$

Moreover, the sources transform as

$$S^{X_s}(\chi_S, \chi, \mathbf{k}, \mathbf{n}_o) \mathbf{m}_o^s(\mathbf{n}_o) \rightarrow (-1)^s S^{X_s}(\chi_S, \chi, -\mathbf{k}, -\mathbf{n}_o) \mathbf{m}_o^{-s}(\mathbf{n}_o). \quad (5.26)$$

We now demand that any physical quantity remains invariant under a full parity inversion. That is, if at the same time we transform $\mathbf{k} \rightarrow -\mathbf{k}$, $\mathbf{n}_o \rightarrow -\mathbf{n}_o$ and $\mathbf{m}_o^s \rightarrow (-1)^s \mathbf{m}_o^{-s}$, the source S^{X_s} of a physical observable X^s should remain invariant, which from Eqs. (5.7) and (5.26) implies the condition

$$S^{X_s}(\chi_S, \chi, \mathbf{k}, \mathbf{n}_o) = (-1)^s S^{X_s}(\chi_S, \chi, -\mathbf{k}, -\mathbf{n}_o). \quad (5.27)$$

If we take into account the parity transformations of the Wigner matrices and of the spherical harmonics—see Eqs. (D9)–(D11)—then a comparison of the previous expression with Eq. (5.8) shows that the parity condition translates to

$$S_{\ell m}^{X_s}(\chi_S, \chi, \mathbf{k}) = (-1)^{m+s} S_{\ell, -m}^{X_s}(\chi_S, \chi, -\mathbf{k}). \quad (5.28)$$

Then, we rewrite Eq. (5.10) as

$$X_{\ell m}^s(\chi_S) = \sqrt{\frac{2}{\pi}} \int d^3 \mathbf{k} X_{\ell m}^s(\chi_S, \mathbf{k}) \Phi_i(\mathbf{k}). \quad (5.29)$$

The above expression should be seen as a definition of $X_{\ell m}^s(\chi_S, \mathbf{k})$ and corresponds to the contribution of each Fourier mode to the observable, but it is not its Fourier component. Its expression can be obtained by plugging Eq. (5.13) into Eq. (5.10) and then comparing with Eq. (5.29). Then, if we impose the symmetry (5.28) to Eq. (5.29), using again the parity transformation of the Wigner matrices, we finally find that

$$X_{\ell m}^s(\chi_S, \mathbf{k}) = (-1)^{\ell+s} X_{\ell m}^{-s}(\chi_S, -\mathbf{k}). \quad (5.30)$$

From this expression, it is straightforward to check that the E and B modes of a spin-2 quantity transform under parity as

$$\begin{aligned} E_{\ell m}^{X_2}(\chi, \mathbf{k}) &= \frac{1}{2} (X_{\ell m}^2(\chi, \mathbf{k}) + X_{\ell m}^{-2}(\chi, \mathbf{k})) \\ &= (-1)^{\ell} E_{\ell m}^{X_2}(\chi, -\mathbf{k}), \end{aligned} \quad (5.31a)$$

$$\begin{aligned} B_{\ell m}^{X_2}(\chi, \mathbf{k}) &= \frac{-i}{2} (X_{\ell m}^2(\chi, \mathbf{k}) - X_{\ell m}^{-2}(\chi, \mathbf{k})) \\ &= (-1)^{\ell+1} B_{\ell m}^{X_2}(\chi, -\mathbf{k}). \end{aligned} \quad (5.31b)$$

We can now establish our main conclusion: given the above symmetry, together with translational invariance of primordial fluctuations [see Eq. (5.14)], it follows that, for the E and B modes of a spin-2 field, we have

$$\begin{aligned} &\langle E_{\ell_1 m_1}^{X_2}(\chi) B_{\ell_2 m_2}^{X_2^*}(\chi) \rangle \\ &= \frac{2}{\pi} \int d^3 \mathbf{k} \langle E_{\ell_1 m_1}^{X_2}(\chi, \mathbf{k}) B_{\ell_2 m_2}^{X_2^*}(\chi, \mathbf{k}) \rangle P(k) \\ &= (-1)^{\ell_1 + \ell_2 + 1} \frac{2}{\pi} \int d^3 \mathbf{k} \langle E_{\ell_1 m_1}^{X_2}(\chi, -\mathbf{k}) B_{\ell_2 m_2}^{X_2^*}(\chi, -\mathbf{k}) \rangle P(k) \\ &= (-1)^{\ell_1 + \ell_2 + 1} \frac{2}{\pi} \int d^3 \mathbf{k} \langle E_{\ell_1 m_1}^{X_2}(\chi, \mathbf{k}) B_{\ell_2 m_2}^{X_2^*}(\chi, \mathbf{k}) \rangle P(k) \\ &= (-1)^{\ell_1 + \ell_2 + 1} \langle E_{\ell_1 m_1}^{X_2}(\chi) B_{\ell_2 m_2}^{X_2^*}(\chi) \rangle, \end{aligned} \quad (5.32)$$

where, from the second to the third line, we have used $\int_{-\infty}^{+\infty} d^3 \mathbf{k} = \int_{+\infty}^{-\infty} d^3(-\mathbf{k})$. Similarly, one can show that the EE and BB covariance matrices obey

$$\langle E_{\ell_1 m_1}^{X_2} E_{\ell_2 m_2}^{X_2*} \rangle = (-1)^{\ell_1 + \ell_2} \langle E_{\ell_1 m_1}^{X_2} E_{\ell_2 m_2}^{X_2*} \rangle, \quad (5.33a)$$

$$\langle B_{\ell_1 m_1}^{X_2} B_{\ell_2 m_2}^{X_2*} \rangle = (-1)^{\ell_1 + \ell_2} \langle B_{\ell_1 m_1}^{X_2} B_{\ell_2 m_2}^{X_2*} \rangle. \quad (5.33b)$$

We have thus proved that correlations between E and B modes will vanish whenever $\ell_1 + \ell_2$ is an even number. In particular, the diagonal part of the EB covariance matrix is always zero in spacetimes that respect parity (but not necessarily isotropy). Evidently, the same holds for the multipolar coefficients of a spin-0 quantity, such as the CMB temperature $a_{\ell m}$'s (see e.g., Ref. [81]).

VI. PERTURBATION SCHEME IN THE SMALL SHEAR LIMIT

A. Expansion scheme

The structure of the computation has been detailed in Sec. IB. Let us recall that order by order, we need to

- (1) solve the geodesic equation perturbatively in order to determine the displacement from the reference Friedmann-Lemaître geodesic $x^{i\{n,p\}}(\chi, \mathbf{n}^o)$ and the local direction of propagation $\mathbf{n}^{\{n,p\}}(\chi, \mathbf{n}^o)$. Note that $x^{i\{n,p\}}(\chi, \mathbf{n}^o)$ is split in a radial component $\delta r^{\{n,p\}}(\chi, \mathbf{n}^o)$ and an orthoradial component which will be related to the deflection angle $\alpha^{a\{n,p\}}(\chi, \mathbf{n}^o)$;
- (2) determine the transport of the Sachs basis, $\mathbf{n}_a^{\{n,p\}}(\chi, \mathbf{n}^o)$;
- (3) expand the Sachs equation and determine the source terms for $\mathcal{D}_{ab}^{\{n,p\}}(\chi, \mathbf{n}^o)$;
- (4) determine the evolution of the perturbations at the required order;
- (5) perform the multipolar expansion in terms of the direction of observation \mathbf{n}^o .

To avoid confusion, we shall use the notation that $X^{\{n,p\}}$ includes all terms up to order $\{n, p\}$ while $\delta X^{\{n,p\}}$ contains only the terms of order $\{n, p\}$.

B. Order $\{0,0\}$

Since on the background (i.e., a Friedmann-Lemaître spacetime) the metric is just the Minkowski metric, thanks to the overall conformal transformation described in Sec. III D 2, the (conformal) Riemann tensor vanishes, so that $\mathcal{R}_{ab}^{\{0,0\}} = 0$. Since the wave vector is decomposed in accordance to Eq. (3.2), in which we can always choose to set $U_o = 1$, one deduces that it is given by

$$k^{0\{0,0\}} = -1, \quad k^{i\{0,0\}} = n_o^i. \quad (6.1)$$

The Sachs equation (4.34) trivially reduces to

$$\frac{d^2 \mathcal{D}_{ab}^{\{0,0\}}}{d\chi^2} = 0, \quad (6.2)$$

so that the Jacobi matrix is given by

$$\mathcal{D}_{ab}^{\{0,0\}} = D_A^{\{0,0\}}(\chi) I_{ab}, \quad D_A^{\{0,0\}}(\chi) = \chi, \quad (6.3)$$

and its components reduce to

$$\kappa^{\{0,0\}} = \gamma_{ab}^{\{0,0\}} = V^{\{0,0\}} = 0. \quad (6.4)$$

This completely specifies the property of the geodesic bundle at the background level.

C. Order $\{1,0\}$

At this order, the spacetime remains homogeneous, but it now has an anisotropic perturbation described by the shear σ_{ij} , from which we can define a scalar field Σ on the 2-sphere by

$$\Sigma(\chi) \equiv \frac{1}{2} \sigma_{ik}(\chi) n_o^i n_o^k. \quad (6.5)$$

We also introduce a new scalar function

$$\mathcal{B}(\chi) \equiv \frac{1}{2} \beta_{ik}(\chi) n_o^i n_o^k, \quad (6.6)$$

where β_{ij} is defined in Eqs. (4.4) and (4.5).

We will now show that all results at this order can be expressed in terms of these two fields on the unit 2-sphere and the covariant derivative D_a defined in Sec. IV C 2. In what follows we shall use the convention $\mathcal{B}_o = \mathcal{B}(\chi = 0)$.

1. Geodesic equation: Tangent vector

At this order, the 4-velocity of a fundamental observer is just $u_\mu = (d\eta)_\mu = \vartheta_\mu^0$, so that

$$U = k^\mu u_\mu = k^0 = k^0. \quad (6.7)$$

From Eq. (4.31), and using the fact that, at first order, the only nonvanishing Christoffel symbols are [22]

$$\delta \Gamma_{ij}^{0\{1,0\}} = \sigma_{ij}, \quad \delta \Gamma_{0j}^{i\{1,0\}} = \sigma^i_j, \quad (6.8)$$

we obtain that

$$\frac{dk^{\underline{0}\{1,0\}}}{d\chi} = \frac{dk^{0\{1,0\}}}{d\chi} = -\sigma_{ik} n_o^i n_o^k. \quad (6.9)$$

It thus follows that

$$k^{\underline{0}\{1,0\}} = k^{0\{1,0\}} = -1 + 2[\mathcal{B}(\chi) - \mathcal{B}_o] \equiv -1 + \delta k^{0\{1,0\}}. \quad (6.10)$$

This result is expected given, that for a Bianchi I spacetime, k_i is a constant [67]; see Sec. III D 1. Alternatively, this result could have been obtained using Eq. (4.32), with the $\{1,0\}$ order of the affine connections given in

Appendix B 1. Its physical interpretation is simple since the factor $2[\mathcal{B}(\chi) - \mathcal{B}_0]$ can be identified to the Einstein effect between the events of emission and reception.

The evolution of the spatial components of the wave vector is easily obtained using the tetrad components first. From Eq. (4.32) we obtain

$$\begin{aligned} k^{i\{1,0\}}(\chi) &= n_0^i + \int_0^\chi \sigma_{ij}^i(\chi') n_0^j d\chi' \\ &= n_0^i + [\beta_j^i(0) - \beta_j^i(\chi)] n_0^j, \end{aligned} \quad (6.11a)$$

$$\begin{aligned} k^{i\{1,0\}}(\chi) &= k^{i\{1,0\}}(\chi) - \beta_j^i(\chi) n_0^j \\ &= n_0^i + [\beta_j^i(0) - 2\beta_j^i(\chi)] n_0^j, \end{aligned} \quad (6.11b)$$

$$k_i^{\{1,0\}}(\chi) = k_i^{\{1,0\}}(\chi) + \beta_{ij}(\chi) n_0^j = n_0^i + \beta_j^i(0) n_0^j. \quad (6.11c)$$

Again, this corresponds to the small shear limit of our previous general result [67], where $k_i = k_i(0)$ is used first.

2. Geodesic equation: Real space

The parametric equation of the geodesic is obtained from the integration of Eq. (4.33) at order $\{1, 0\}$. Separating the difference between the position at order $\{1, 0\}$ and the position of the background geodesic into a radial displacement and an orthoradial displacement according to

$$\begin{aligned} x^{i\{1,0\}}(\chi) &= \chi n_0^i + \delta x^{i\{1,0\}} \quad \text{with} \\ \delta x^{i\{1,0\}} &= n_0^i \delta r^{\{1,0\}} + \chi \alpha^{a\{1,0\}} n_a^i, \end{aligned} \quad (6.12)$$

which defines the deflection angle $\alpha^{a\{1,0\}}$, and where we have used that $x^{i\{0,0\}}(\chi) = \chi n_0^i$, we get

$$\delta r^{\{1,0\}}(\chi) = -2 \int_0^\chi \mathcal{B}(\chi') d\chi', \quad (6.13a)$$

$$\alpha^{a\{1,0\}}(\chi) = D^a \mathcal{B}_0 - \frac{2}{\chi} \int_0^\chi D^a \mathcal{B}(\chi') d\chi', \quad (6.13b)$$

in which $D^a \mathcal{B}_0$ stands for $(D^a \mathcal{B})_{\chi=0}$, and where the last equalities of the equations above made use of an integration by parts. Note that

$$\lim_{\chi \rightarrow 0} \frac{x^{i\{1,0\}}}{\chi} = n_0^i - \beta_{ij}(0) n_0^j. \quad (6.14)$$

This can be interpreted simply, because it means that very close to the observer, everything happens as if β_{ij} is constant and equal to $\beta_{ij}(0)$. Thus a constant change of coordinates $\tilde{x}^i \equiv x^i + \beta_j^i(0) x^j$ transforms the metric from $\gamma_{ij} = \delta_{ij} + 2\beta_{ij}(0)$ to the Euclidian metric δ_{ij} . The geodesic in these new coordinates is simply the Euclidian one, $\tilde{x}^i(\chi) = \chi n_0^i$.

3. Evolution of the direction and screen vectors

The infinitesimal change of a unit vector lies in the plan orthogonal to it. The perturbation of the direction vector is thus of the form

$$n^{i\{1,0\}} = n_0^i + \varpi^{a\{1,0\}} n_a^{oi}. \quad (6.15)$$

From the previous results for k^i and k^0 , we get immediately

$$n^{i\{1,0\}} = n_0^i + \varpi^{a\{1,0\}} n_a^{oi}, \quad \varpi^{a\{1,0\}} = \int_0^\chi D^a \Sigma d\chi'. \quad (6.16)$$

The transport equation for the screen basis is in turn given by

$$n_a^{i\{1,0\}} = n_a^{oi} - n_0^i \varpi_a^{\{1,0\}}, \quad (6.17)$$

and it can be checked that the screen basis (3.10) does remain orthogonal to the direction vector.

4. Sachs equation

At order $\{1, 0\}$, given that $\mathcal{R}_{ab}^{\{1,0\}} = 0$, the right-hand side of Eq. (4.34) reduces to

$$\mathcal{R}_{ab}^{\{1,0\}} \mathcal{D}_{bc}^{\{0,0\}} = \mathcal{R}_{ab}^{\{1,0\}} \chi \delta_{bc} = \chi \mathcal{R}_{ac}^{\{1,0\}},$$

so that the Sachs equation (4.34) reduces to

$$\frac{d^2 \delta \mathcal{D}_{ab}^{\{1,0\}}}{d\chi^2} = \frac{d\delta k^{0\{1,0\}}}{d\chi} \delta_{ab} + \chi \mathcal{R}_{ab}^{\{1,0\}}. \quad (6.18)$$

Its first integral yields

$$\frac{d\delta \mathcal{D}_{ab}^{\{1,0\}}}{d\chi} = \delta_{ab} + \int_0^\chi \left(\frac{d\delta k^{0\{1,0\}}}{d\tilde{\chi}} \delta_{ab} + \tilde{\chi} \mathcal{R}_{ab}^{\{1,0\}} \right) d\tilde{\chi}. \quad (6.19)$$

The first term gives $\delta_{ab}[1 + \delta k^{0\{1,0\}}(\chi)] = \delta_{ab}[2 + k^{0\{1,0\}}(\chi)]$, so that

$$\begin{aligned} \delta \mathcal{D}_{ab}^{\{1,0\}}(\chi, \mathbf{n}^o) &= \delta_{ab} \int_0^\chi [2 + k^{0\{1,0\}}(\tilde{\chi})] d\tilde{\chi} \\ &\quad + \int_0^\chi d\chi' \int_0^{\chi'} \tilde{\chi} \mathcal{R}_{ab}^{\{1,0\}}(\tilde{\chi}, \mathbf{n}^o) d\tilde{\chi}. \end{aligned} \quad (6.20)$$

The double integral on the right-hand side can be performed by means of an integration by parts. This gives

$$\begin{aligned} &\int_0^\chi d\chi' \int_0^{\chi'} \tilde{\chi} \mathcal{R}_{ab}^{\{1,0\}}(\tilde{\chi}, \mathbf{n}^o) d\tilde{\chi} \\ &= \int_0^\chi \tilde{\chi}(\chi - \tilde{\chi}) \mathcal{R}_{ab}^{\{1,0\}}(\tilde{\chi}, \mathbf{n}^o) d\tilde{\chi} \end{aligned}$$

from where we finally conclude that

$$\begin{aligned} \delta\mathcal{D}_{ab}^{\{1,0\}}(\chi, \mathbf{n}^o) &= \int_0^\chi \{[2 + k^0\{1,0\}(\tilde{\chi})]\delta_{ab} + (\chi - \tilde{\chi})\tilde{\chi}\mathcal{R}_{ab}^{\{1,0\}}(\tilde{\chi}, \mathbf{n}^o)\}d\tilde{\chi}. \end{aligned} \quad (6.21)$$

As detailed in Appendix B 2, the source term takes the form

$$\begin{aligned} \mathcal{R}_{ab}^{\{1,0\}}(\chi, \mathbf{n}^o) &= -\frac{1}{2}(\sigma'_{ij}n_o^i n_o^j)\delta_{ab} + n_{(a}^{oi} n_{b)}^{oj}(\sigma_{ij})' \\ &= -\delta_{ab}\Sigma' + D_{(a}D_{b)}\Sigma'. \end{aligned} \quad (6.22)$$

By inserting the above in Eq. (6.21) and using Eq. (6.11), we find the following expressions for the convergence and shear:

$$\kappa^{\{1,0\}}(\chi, \mathbf{n}^o) = -\int_0^\chi \frac{(\chi - \tilde{\chi})}{\chi} [2\Sigma + \tilde{\chi}\Sigma']d\tilde{\chi}, \quad (6.23a)$$

$$\gamma_{ab}^{\{1,0\}}(\chi, \mathbf{n}^o) = \int_0^\chi \frac{(\chi - \tilde{\chi})\tilde{\chi}}{\chi} D_{(a}D_{b)}\Sigma'd\tilde{\chi}, \quad (6.23b)$$

which simplify to

$$\kappa^{\{1,0\}}(\chi, \mathbf{n}^o) = -\mathcal{B}(\chi) - 3\mathcal{B}_o + \frac{4}{\chi}\int_0^\chi \mathcal{B}(\tilde{\chi})d\tilde{\chi}, \quad (6.24a)$$

$$\begin{aligned} \gamma_{ab}^{\{1,0\}}(\chi, \mathbf{n}^o) &= D_{(a}D_{b)}\mathcal{B}_o + D_{(a}D_{b)}\mathcal{B} \\ &\quad - \frac{2}{\chi}\int_0^\chi D_{(a}D_{b)}\mathcal{B}(\tilde{\chi})d\tilde{\chi}. \end{aligned} \quad (6.24b)$$

Note that in the limit $\chi \rightarrow 0$, $\kappa^{\{1,0\}} \rightarrow 0$ and $\gamma_{ab}^{\{1,0\}} \rightarrow 0$ as it should be, given the initial condition (3.16) for the Jacobi matrix. Finally, since the Jacobi matrix (6.20) is symmetric, at this order we have

$$V^{\{1,0\}} = 0. \quad (6.25)$$

We have checked that these results match those found in [67] when expanded in the small shear limit (where the special choice $\mathcal{B}_o = 0$ is made).

We can now perform the expansion of these observable quantities in terms of spin-weighted spherical harmonics. Using the results of Sec. IV C 4, the shear can be projected into the helicity basis so as to transform the covariant derivatives into spin-raising and spin-lowering operators. The spherical harmonics components of the convergence κ and of the cosmic shear γ^\pm are then easily obtained at order $\{1, 0\}$. Both reduce to a quadrupolar contribution, inherited from the quadrupolar contribution of Σ , so that their only nonvanishing coefficients are

$$\kappa_{2m}^{\{1,0\}}(\chi) = -3\mathcal{B}_{2m}^o - \mathcal{B}_{2m} + \frac{4}{\chi}\int_0^\chi \mathcal{B}_{2m}(\tilde{\chi})d\tilde{\chi}, \quad (6.26a)$$

$$\gamma_{2m}^{\pm\{1,0\}}(\chi) = \sqrt{6}\left(\mathcal{B}_{2m}^o + \mathcal{B}_{2m} - \frac{2}{\chi}\int_0^\chi \mathcal{B}_{2m}(\tilde{\chi})d\tilde{\chi}\right). \quad (6.26b)$$

We conclude that $B_{\ell m}^{\gamma\{1,0\}} = 0$ and $E_{2m}^{\gamma\{1,0\}} = \gamma_{2m}^{\pm\{1,0\}}$.

D. Order $\{0, 1\}$

We follow the same method for the order $\{0, 1\}$ as for the order $\{1, 0\}$. This corresponds to the standard approach to weak lensing in the linear regime of cosmological perturbations. Our main goal is to rederive these standard results in our formalism, so as to serve as a basis for the study at order $\{1, 1\}$. Note that, at this order, we only need to include scalar perturbations since, as stressed before, vectors and tensors modes are of order $\{1, 1\}$.

1. Geodesic equation: Tangent vector

Using the definition of the deflecting potential as $\varphi \equiv \Phi + \Psi$, the energy of a photon evolves according to

$$\frac{dk^0\{0,1\}}{d\chi} = -\frac{\partial\varphi}{\partial\chi} + \frac{d\Phi}{d\chi}, \quad \frac{dk^0\{0,1\}}{d\chi} = -\frac{\partial\varphi}{\partial\chi} + 2\frac{d\Phi}{d\chi}, \quad (6.27)$$

the solution of which is

$$\begin{aligned} k^{0\{0,1\}} &= k^0\{0,1\} + \Phi = -1 + 2\Phi - \Phi_o - \int_0^\chi \frac{\partial\varphi}{\partial\tilde{\chi}}d\tilde{\chi} \\ &\equiv -1 + \delta k^{0\{0,1\}}, \end{aligned} \quad (6.28)$$

where it is understood the integrand is evaluated on the background geodesic, i.e., that $x^i = \tilde{\chi}n_o^i$, at a time associated with $\tilde{\chi}$. The notation is intentionally simplified in this section, so, for example, $k^{0\{0,1\}}$ means $k^{0\{0,1\}}(\chi, n_o^i)$, Φ means $\Phi(\chi, x^i)$ with $x^i = \chi n_o^i$, and so on. In other words, it is understood that everything is evaluated on the background geodesic at parameter χ . The only exception is Φ_o , which is the potential Φ evaluated at the observer, that is, at $\chi = 0$. Note that the total derivative $d/d\chi$, i.e., the total derivative along the background geodesic, satisfies

$$\frac{d\varphi}{d\chi} = \frac{\partial\varphi}{\partial\chi} + \varphi_{,r} = -\varphi' + \hat{x}^i\partial_i\varphi, \quad (6.29)$$

since, from Eq. (4.30),

$$\frac{\partial\varphi}{\partial\chi} = -\varphi'. \quad (6.30)$$

2. Evolution of the direction and screen vectors

The spatial component of the vector k^μ evolves according to

$$\frac{dk^{i\{0,1\}}}{d\chi} = -\partial_i\varphi + n_0^i \frac{d\Psi}{d\chi}, \quad \frac{dk^{i\{0,1\}}}{d\chi} = -\partial_i\varphi + 2n_0^i \frac{d\Psi}{d\chi}, \quad (6.31)$$

the solution of which is

$$\begin{aligned} k^{i\{0,1\}} &= k^{i\{0,1\}} + n_0^i \Psi \\ &= n_0^i [1 + 2\Psi(\chi) - \Psi_0] - \int_0^\chi \partial_i\varphi d\tilde{\chi}. \end{aligned} \quad (6.32)$$

Using Eq. (4.7), we then deduce the evolution of the direction vector

$$\frac{dn^{i\{0,1\}}}{d\chi} = -S^{i\ j} \partial_j\varphi, \quad (6.33)$$

the solution of which is

$$\begin{aligned} n^{i\{0,1\}}(\chi, n_0^i) &= n_0^i + \varpi^{a\{0,1\}}(\chi, n_0^i) n_a^i, \\ \varpi^{a\{0,1\}}(\chi, n_0^i) &\equiv - \int_0^\chi D^a\varphi d\tilde{\chi}. \end{aligned} \quad (6.34)$$

Similarly, the evolution of the screen projectors leads to

$$n_a^{i\{0,1\}}(\chi, n_0^i) = n_a^{0i} - \varpi^{a\{0,1\}}(\chi, n_0^i) n_0^i. \quad (6.35)$$

3. Geodesic equation: Real space

We can then determine $x^{i\{0,1\}}$ from Eq. (4.33) using

$$\left(\frac{dx^i}{d\chi}\right)^{\{0,1\}} = -\left(\frac{k^i}{k^0}\right)^{\{0,1\}} = n_0^i(1 + \varphi) - \int_0^\chi S^{i\ j} \partial_j\varphi d\tilde{\chi}, \quad (6.36)$$

and this leads to

$$x^{i\{0,1\}} = \chi n_0^i + n_0^i \int_0^\chi \varphi d\tilde{\chi} - n_a^{0i} \int_0^\chi d\tilde{\chi} \frac{(\chi - \tilde{\chi})}{\tilde{\chi}} D^a\varphi. \quad (6.37)$$

4. Sachs equation

Finally, at order $\{0, 1\}$, the right-hand side of Eq. (4.34) is simply $\mathcal{R}_{ab}^{\{0,1\}} \mathcal{D}_{bc}^{\{0,0\}} = \chi \mathcal{R}_{ac}^{\{1,0\}}$. Thus, the Sachs equation becomes

$$\frac{d^2 \delta \mathcal{D}_{ab}^{\{0,1\}}}{d\chi^2} = \frac{dk^{0\{0,1\}}}{d\chi} \delta_{ab} + \chi \mathcal{R}_{ab}^{\{0,1\}}. \quad (6.38)$$

The solution of the Sachs equation follows formally the same steps as in the case $\{1, 0\}$. That is, it can be integrated twice, and after an integration by parts for the double integral over the Riemann term, we get

$$\begin{aligned} \delta \mathcal{D}_{ab}^{\{0,1\}}(\chi, \mathbf{n}^0) &= \int_0^\chi \{ [2 + k^{0\{0,1\}}(\tilde{\chi})] \delta_{ab} \\ &\quad + (\chi - \tilde{\chi}) \tilde{\chi} \mathcal{R}_{ab}^{\{0,1\}}(\tilde{\chi}, \mathbf{n}^0) \} d\tilde{\chi}. \end{aligned} \quad (6.39)$$

Now, using the perturbed expression for \mathcal{R}_{ab} found in Appendix B 2 (with $\sigma_{ij} = 0$),

$$\begin{aligned} \chi^2 \mathcal{R}_{ab}^{\{0,1\}} &= \chi^2 n_a^{0i} n_b^{0j} [-\partial_i \partial_j \varphi - \delta_{ij} (\Psi'' - 2n^i \partial_i \Psi') \\ &\quad + n^p n^q \partial_p \partial_q \Psi] \end{aligned} \quad (6.40a)$$

$$\begin{aligned} &= -D_{\langle a} D_{b \rangle} \varphi - \delta_{ab} \chi^2 \left[\frac{1}{2} \partial_i \partial^i \varphi + \Psi'' - 2n^i \partial_i \Psi' \right. \\ &\quad \left. + \frac{1}{2} n^p n^q \partial_p \partial_q (\Psi - \Phi) \right] \end{aligned} \quad (6.40b)$$

and the expression $dk^{0\{1,0\}}/d\chi$ given in Eq. (6.28), one obtains the formal solution of the Sachs equation (4.34) as [61]

$$\begin{aligned} \delta \mathcal{D}_{ab}^{\{0,1\}} &= \chi \left[\delta_{ab} \left(1 - \Psi(\chi) - \Phi_0 + \frac{1}{\chi} \int_0^\chi \varphi(\tilde{\chi}) d\tilde{\chi} \right. \right. \\ &\quad \left. \left. - \frac{1}{2} \int_0^\chi \frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} D_c D^c \varphi(\tilde{\chi}) d\tilde{\chi} \right) \right. \\ &\quad \left. - \int_0^\chi \frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} D_{\langle a} D_{b \rangle} \varphi(\tilde{\chi}) d\tilde{\chi} \right], \end{aligned} \quad (6.41)$$

from which κ and γ_{ab} can be read directly from the expression in brackets in the first and second lines, respectively; see our definitions in Eq. (3.17). Note that, since there is no antisymmetric part in $\delta \mathcal{D}_{ab}^{\{0,1\}}$, we conclude that $V^{\{0,1\}} = 0$.

Dropping the (unobservable) monopole correction due to the local potential Φ_0 , we get their multipoles as

$$\begin{aligned} \kappa_{\ell m}^{\{0,1\}} &= -\Psi_{\ell m}(\chi) + \frac{1}{\chi} \int_0^\chi \varphi_{\ell m}(\tilde{\chi}) d\tilde{\chi} \\ &\quad + \frac{\ell(\ell+1)}{2} \int_0^\chi \frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} \varphi_{\ell m}(\tilde{\chi}) d\tilde{\chi}, \end{aligned} \quad (6.42a)$$

$$\gamma_{\ell m}^{\pm\{0,1\}} = -\frac{1}{2} \sqrt{\frac{(\ell+2)!}{(\ell-2)!}} \int_0^\chi \frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} \varphi_{\ell m}(\tilde{\chi}) d\tilde{\chi}, \quad (6.42b)$$

from which we conclude that $B_{\ell m}^{\gamma\{1,0\}} = 0$ and $E_{\ell m}^{\gamma\{1,0\}} = \gamma_{\ell m}^{\pm\{1,0\}}$.

5. Angular power spectra

To determine the angular power spectrum of the convergence κ and of the E modes of the cosmic shear, we follow the procedure described in Sec. V. At the order $\{0, 1\}$, the transfer function is isotropic and there are only scalar sources. Consequently, only E modes are generated. The power spectrum for the E modes is then just given by

$$C_\ell^{EE\{0,1\}} = \frac{2}{\pi} \int_0^\infty k^2 dk P(k) \left| \int_0^\infty d\chi \mathcal{N}(\chi) \int_0^\chi d\tilde{\chi} g_\ell^E(k, \chi, \tilde{\chi}) \right|^2, \quad (6.43)$$

where the function g^E is defined as

$$g_\ell^E(k, \chi, \tilde{\chi}) = -\frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} j_\ell(k\tilde{\chi}) \frac{1}{2} \sqrt{\frac{(\ell+2)!}{(\ell-2)!}} T^\varphi(k, \tilde{\chi}). \quad (6.44)$$

In Eq. (6.43), $\mathcal{N}(\chi)$ represents the distribution of sources as a function of the radial distance χ defined such that $\mathcal{N}(\chi)d\chi$ is the number of sources between χ and $\chi + d\chi$. At order $\{0, 1\}$, it is sufficient to consider the homogeneous source distribution, so that the observed shear and convergence for sources distributed up to χ_+ are then defined by

$$\begin{aligned} \kappa_o(\chi_+, \mathbf{n}_o) &= \int_0^{\chi_+} \mathcal{N}(\chi) \kappa(\chi, \mathbf{n}_o) d\chi, \\ \gamma_o^\pm(\chi_+, \mathbf{n}_o) &= \int_0^{\chi_+} \mathcal{N}(\chi) \gamma^\pm(\chi, \mathbf{n}_o) d\chi. \end{aligned} \quad (6.45)$$

Since here \mathcal{N} depends on χ alone, this integration can be performed after the multipolar decomposition so that we perform the replacement, e.g.,

$$E_{\ell m}(\chi) \rightarrow \int_0^{\chi_+} \mathcal{N}(\tilde{\chi}) E_{\ell m}(\tilde{\chi}) d\tilde{\chi}, \quad (6.46)$$

in order to build the cosmological observables. Let us emphasize that this derivation can actually be performed in a simpler way [2]: since the source term derives from a potential, one could have simply used the Fourier transform directly in Eq. (6.41) and then expanded the exponential according to Eq. (5.9). The present derivation is however more general when used to higher orders $\{n, p\}$.

On small angular scales, that is, in the limit $\ell \gg 1$, it is possible to use the Limber approximation [82]. Such approximation consists in using

$$\int_0^\infty dx f(x) j_\ell(x) \simeq \sqrt{\frac{\pi}{2L}} f(L) \quad (6.47)$$

with $L \equiv \ell + 1/2$. If we commute the time integrals according to

$$\int_0^\infty d\chi \int_0^\chi d\tilde{\chi} f(\chi, \tilde{\chi}) = \int_0^\infty d\tilde{\chi} \int_{\tilde{\chi}}^\infty d\chi f(\chi, \tilde{\chi}), \quad (6.48)$$

we arrive at the simple expression

$$C_\ell^{EE\{0,1\}} \simeq \frac{1}{4} \frac{(\ell+2)!}{(\ell-2)!} \mathcal{P}_\ell, \quad (6.49)$$

with

$$\mathcal{P}_\ell \equiv \int_0^\infty \frac{d\tilde{\chi}}{\tilde{\chi}^2} P\left(\frac{L}{\tilde{\chi}}\right) \left| T^\varphi\left(\frac{L}{\tilde{\chi}}, \tilde{\chi}\right) \int_{\tilde{\chi}}^\infty d\chi \mathcal{N}(\chi) \frac{(\chi - \tilde{\chi})}{\chi \tilde{\chi}} \right|^2. \quad (6.50)$$

The angular power spectrum of the convergence κ is obtained in a similar way. Indeed, if we consider only the dominant contribution of Eq. (6.42a) at small scales, it is sufficient to replace g_ℓ^E by

$$g_\ell^\kappa(k, \chi, \tilde{\chi}) = \frac{\ell(\ell+1)\chi - \tilde{\chi}}{2\chi\tilde{\chi}} j_\ell(k\tilde{\chi}) T^\varphi(k, \tilde{\chi}) \quad (6.51)$$

in the previous expressions to get $C_\ell^{\kappa\kappa\{0,1\}}$. Using the Limber approximation, we then obtain

$$C_\ell^{\kappa\kappa\{0,1\}} \simeq \frac{\ell^2(\ell+1)^2}{4} \mathcal{P}_\ell, \quad (6.52)$$

and we check immediately that for large ℓ , $C_\ell^{\kappa\kappa\{0,1\}} \simeq C_\ell^{EE\{0,1\}}$.

Finally, the angular power spectrum of the cross-correlations between the shear and the convergence is given by

$$\begin{aligned} C_\ell^{\kappa E\{0,1\}} &= \frac{2}{\pi} \int_0^\infty k^2 dk P(k) \left(\int_0^\infty d\chi \mathcal{N}(\chi) \int_0^\chi d\tilde{\chi} g_\ell^E(k, \chi, \tilde{\chi}) \right) \\ &\quad \times \left(\int_0^\infty d\chi \mathcal{N}(\chi) \int_0^\chi d\tilde{\chi} g_\ell^\kappa(k, \chi, \tilde{\chi}) \right) \end{aligned}$$

for which the Limber approximation gives

$$C_\ell^{\kappa E\{0,1\}} \simeq -\frac{\ell(\ell+1)}{4} \sqrt{\frac{(\ell+2)!}{(\ell-2)!}} \mathcal{P}_\ell. \quad (6.53)$$

E. Order $\{1,1\}$

1. Geodesic equation

In principle, we need to determine $k^{0\{1,1\}}$ from the geodesic equation and then $x^{i\{1,1\}}$. As we shall see, these terms are only needed for the expression of the convergence $\kappa^{\{1,1\}}$. We will instead focus on the computation of the cosmic shear $\gamma_{ab}^{\{1,1\}}$ and also the rotation $V^{\{1,1\}}$, since they give the leading order of the B mode and the rotation.

Fortunately, that computation does not require the solution of the geodesic equation up to order $\{1, 1\}$.

2. Sachs basis

In order to get a definite expression involving only covariant and radial derivatives, we need to expand the direction vector n^i around its background value n_0^i , so as to use the definition of Sec. IV C 3, taking into account the contributions of order $\{0, 1\}$ and $\{1, 0\}$, and similarly for the projection vectors n_a^i . We must use

$$n_a^i(\chi, n_0^i) = n_0^i + [\varpi^{a\{0,1\}}(\chi, n_0^i) + \varpi^{a\{1,0\}}(\chi, n_0^i)]n_a^{0i}, \quad (6.54a)$$

$$n_a^i(\chi, n_0^i) = n_a^{0i} - [\varpi_a^{\{0,1\}}(\chi, n_0^i) + \varpi_a^{\{1,0\}}(\chi, n_0^i)]n_0^i. \quad (6.54b)$$

It turns out that only the expression for the projection vectors is needed since the direction vector n^i appears only in terms which are already of order $\{1, 1\}$. Additionally, we must convert the derivative along the tetrads $\partial_{\underline{i}}$ noted by $\partial_{\underline{i}}$ to derivatives along the Cartesian coordinates, and these are related from Eq. (4.8). This correction is only relevant for the term $\partial_{\underline{i}}\partial_{\underline{j}}\varphi$ because the other terms are already of order $\{1, 1\}$. We thus use

$$\partial_{\underline{i}}\partial_{\underline{j}}\varphi = \partial_i\partial_j\varphi - 2\beta_{(i}^k\partial_j)\partial_k\varphi, \quad (6.55a)$$

$$\beta_{ij} = D_i D_j \mathcal{B} + 2\mathcal{B}S_{ij} + 2D_{(i}\mathcal{B}n_{j)}^0 + \mathcal{B}n_{\underline{i}}^0 n_{\underline{j}}^0. \quad (6.55b)$$

3. General form

Since in Eq. (4.34) the two terms $\frac{1}{k^0}\frac{dk^0}{d\chi}\frac{d\mathcal{D}_{ab}}{d\chi}$ and $\frac{1}{(k^0)^2}\mathcal{R}_{ac}\mathcal{D}_{cb}$ do not contain $\mathcal{D}_{ab}^{\{1,1\}}$ (because $dk^0/d\chi$ and \mathcal{R}_{ab} vanish at order $\{0, 0\}$), it can be integrated to give

$$\frac{d\delta\mathcal{D}_{ab}^{\{1,1\}}}{d\chi} = \delta_{ab} + \int_0^\chi \left[-\frac{d\ln k^0}{d\chi}\frac{d\mathcal{D}_{ab}}{d\chi} + \frac{1}{(k^0)^2}\mathcal{R}_{ac}\mathcal{D}_{cb} \right] d\chi'. \quad (6.56)$$

(We remind the reader of our convention, in which we split k^0 and \mathcal{D}_{ab} , respectively, as $k^0 = -1 + \delta k^0$ and $\mathcal{D}_{ab} = \chi\delta_{ab} + \delta\mathcal{D}_{ab}$.) In the first term of the integral, given that $dk^0/d\chi$ is at least of order $\{1, 0\} + \{0, 1\}$, the term \mathcal{D}'_{ab} can be expressed using the formulas found in the two previous sections, that is,

$$\frac{d\delta\mathcal{D}_{ab}^{\{1,0\}/\{0,1\}}}{d\chi} = \int_0^\chi \left(\frac{dk^{0,\{1,0\}/\{0,1\}}}{d\chi}\delta_{ab} + \tilde{\chi}\mathcal{R}_{ab}^{\{1,0\}/\{0,1\}} \right) d\tilde{\chi}. \quad (6.57)$$

Equation (6.56) can then be integrated as

$$\delta\mathcal{D}_{ab}^{\{1,1\}}(\chi) = \int_0^\chi \frac{\chi - \tilde{\chi}}{\tilde{\chi}} S_{ab}^{\{1,1\}}(\tilde{\chi}) d\tilde{\chi}, \quad (6.58)$$

where $S_{ab}^{\{1,1\}}$ contains all source terms of order $\{1, 1\}$. It is explicitly given by

$$S_{ab}^{\{1,1\}}(\chi) = \frac{\chi^2 \mathcal{R}_{ab}}{(k^0)^2} + \chi \mathcal{R}_{ac} \delta\mathcal{D}_{cb} - \frac{d\ln k^0}{d\ln \chi} (2 + k^0) \delta_{ab} + \frac{dk^0}{d\ln \chi} \int_0^\chi d\tilde{\chi} \tilde{\chi} \mathcal{R}_{ab} + \chi^2 \delta x^i \partial_i \mathcal{R}_{ab}, \quad (6.59)$$

evaluated at order $\{1, 1\}$, and where the last term arises from the fact that, at this order, there is a correction to be considered since we have to go beyond the Born approximation. That is, we cannot just integrate on the Friedmann-Lemaître geodesic; instead we integrate on the geodesic $\tilde{x}^i(\chi, \mathbf{n}_0) = \chi n_0^i + \delta x^i(\chi, \mathbf{n}_0)$, so that the source term is

$$S_{ab}(\tilde{x}^i(\chi, \mathbf{n}_0)) = S_{ab}(\chi, n_0^i) + \delta x^i(\chi, \mathbf{n}_0) \partial_j S_{ab}, \quad (6.60)$$

which implies that

$$S_{ab}^{\{1,1\}}(\tilde{x}^i(\chi, \mathbf{n}_0)) = S_{ab}^{\{1,1\}}(\chi, n_0^i) + \delta x^{i,\{1,0\}}(\chi, \mathbf{n}_0) \partial_j S_{ab}^{\{0,1\}}, \quad (6.61)$$

since $\partial_i S_{ab}^{\{0,0\}} = \partial_i S_{ab}^{\{1,0\}} = 0$. It follows that the source term is explicitly given by

$$S_{ab}^{\{1,1\}}(\chi) = \chi^2 \left\{ \frac{\mathcal{R}_{ab}}{(k^0)^2} \right\}^{\{1,1\}} + \chi \frac{d\delta k^{0\{1,1\}}}{d\chi} \delta_{ab} + \chi \left(\mathcal{R}_{ac}^{\{1,0\}} \delta\mathcal{D}_{cb}^{\{0,1\}} + \mathcal{R}_{ac}^{\{0,1\}} \delta\mathcal{D}_{cb}^{\{1,0\}} + \frac{d\delta k^{0\{0,1\}}}{d\chi} \right) \times \int_0^\chi \tilde{\chi} \mathcal{R}_{ab}^{\{1,0\}} d\tilde{\chi} + \frac{d\delta k^{0\{1,0\}}}{d\chi} \int_0^\chi \tilde{\chi} \mathcal{R}_{ab}^{\{0,1\}} d\tilde{\chi} + \chi \delta_{ab} \left[\frac{d(\delta k^{0\{1,0\}} \delta k^{0\{0,1\}})}{d\chi} + \delta k^{0\{1,0\}} \delta k^{0\{0,1\}} \right] + \chi^2 \delta x^{j,\{1,0\}} \partial_j \mathcal{R}_{ab}^{\{0,1\}}. \quad (6.62)$$

We see on this expression that the general source $S_{ab}^{\{1,1\}}(\chi)$ has several contributions. First, it has contributions from the vector and tensor modes \tilde{B}_i and E_{ij} (respectively, noted $S^{\{1,1\}V}$ and $S^{\{1,1\}T}$) which are at least of order $\{1, 1\}$ since they vanish in the pure Friedmann-Lemaître case; they enter the terms $\mathcal{R}_{ab}^{\{1,1\}}$ and $\delta k^{0\{1,1\}}$. Then, all the other contributions are formally products of the scalar perturbations by the geometrical shear; they appear as products of $\{1, 0\} \times \{0, 1\}$ terms. To compute explicitly these terms, we decompose the source term as

$$S_{ab}^{\{1,1\}}(\chi) = S_{ab}^{\{1,1\}V}(\chi) + S_{ab}^{\{1,1\}T}(\chi) + S_{ab}^{\{1,1\}\text{quad}}(\chi). \quad (6.63)$$

Each contribution can be further decomposed into its trace, symmetric traceless and antisymmetric parts as

$$S_{ab} = \delta_{ab}S + S_{(ab)} + S_{[ab]}. \quad (6.64)$$

Since our goal is to compute the effect of an anisotropic phase on the cosmic shear, and not on the convergence, we are mostly interested only in the symmetric traceless part. We shall thus not report the computation of the trace contribution to the trace part, except for the contribution coming from vectors and tensors, so as to be able to compare our results with the standard results in the literature, in the cases where the vector and tensor modes are considered even around a Friedmann-Lemaître background. A full computation may be useful in order to cross-correlate weak lensing with the magnitude of supernovae.

4. Vector and tensor mode contributions

The vector and tensor contributions are easily found from the literature [61,83]. Splitting the vector mode into a radial and orthoradial parts as

$$\bar{B}_i = \tilde{B}_i + \hat{r}_i B_r, \quad E_{ij} = \tilde{E}_{ij} + 2\hat{r}_{(i}\tilde{E}_{j)} + E_r \hat{r}_i \hat{r}_j, \quad (6.65)$$

the expression for the Riemann tensor given in Appendix B 2 for vector and tensor modes gives

$$\mathcal{R}_{ab}^{\{1,1\}T} = n_a^{oi} n_b^{oj} [E''_{ij} - 4n^q \partial_{[q} E'_{ij]} + n^p n^q (\partial_i \partial_j E_{pq} + \partial_p \partial_q E_{ij}) - 2n^p n^q \partial_q \partial_{(i} E_{j)p}], \quad (6.66a)$$

$$\mathcal{R}_{ab}^{\{1,1\}V} = n_a^{oi} n_b^{oj} (-\partial_{(i} \bar{B}'_{j)} + n^q \partial_q \partial_{(i} \bar{B}_{j)} - n^q \partial_i \partial_j \bar{B}_q). \quad (6.66b)$$

Using the projections of partial derivatives into radial and covariant derivatives (see Appendix D 1), we deduce that the vector and tensor contributions to the sources (6.63) are

$$S_{ab}^{\{1,1\}V}(\chi) = \chi \delta_{ab} B_{r,r} + \frac{\delta_{ab}}{2} \left[-D_c D^c B_r + \frac{1}{\chi^2} \frac{d}{d\chi} (\chi^3 D^c \tilde{B}_c) + \frac{2}{\chi} \frac{d}{d\chi} (\chi^2 B_r) \right] + \frac{d}{d\chi} (\chi D_{(a} \tilde{B}_{b)}) - D_{(a} D_{b)} B_r, \quad (6.67a)$$

$$S_{ab}^{\{1,1\}T}(\chi) = \chi \delta_{ab} \frac{\partial E_r}{\partial \chi} + \frac{\delta_{ab}}{2} \left[D^c D_c E_r - \chi^2 \frac{d^2}{d\chi^2} E_r - 6 \frac{d}{d\chi} (\chi E_r) - \frac{2}{\chi} \frac{d}{d\chi} (\chi^2 D^c \tilde{E}_c) \right] + \chi \frac{d^2}{d\chi^2} (\chi \tilde{E}_{(ab)}) + D_{(a} D_{b)} E_r - 2 \frac{d}{d\chi} (\chi D_{(a} \tilde{E}_{b)}), \quad (6.67b)$$

with the notation for the radial derivative $\cdot_r \equiv \hat{x}^i \partial_i$. The first terms of each expression are, respectively, the V and T contribution of the term in $\delta k^{0\{1,1\}}$ in Eq. (6.62). For each of these two expressions, the first line contributes to the trace of the Jacobi matrix, that is, to convergence $\kappa^{\{1,1\}}$. The second line contributes to the cosmic shear $\gamma_{ab}^{\{1,1\}}$, since it is symmetric and traceless. By construction there is no antisymmetric part, so the vectors and tensors do not contribute to the rotation $V^{\{1,1\}}$.

In order to compare and recover the results of Refs. [61,83], we must use the fact that vector modes are transverse and that tensor modes are transverse and traceless. This allows us to get the relations (see also Appendix D 1)

$$0 = D^a \tilde{B}_a + \chi (B_r)_{,r} + 2B_r, \quad (6.68a)$$

$$0 = D^a \tilde{E}_{ab} + 3\tilde{E}_b + \chi (\tilde{E}_b)_{,r}, \quad (6.68b)$$

$$0 = D^a \tilde{E}_a + 3E_r + \chi (E_r)_{,r}. \quad (6.68c)$$

5. Trace-free part of the quadratic contributions

Starting from the general expression (6.62), the only contribution of the terms of order $\{1, 1\}$ to the trace-free part is $\chi^2 \mathcal{R}_{(ab)}^{\{1,1\}}$. Then, the terms $\delta \mathcal{D}_{ab}^{\{1,0\}/\{0,1\}}$ are decomposed as

$$\delta \mathcal{D}_{ab}^{\{1,0\}/\{0,1\}} = \chi \kappa^{\{1,0\}/\{0,1\}} \delta_{ab} + \chi \gamma_{(ab)}^{\{1,0\}/\{0,1\}}, \quad (6.69)$$

since, as we have just seen, there is no rotation at order $\{1, 0\}$ and $\{0, 1\}$. To finish, it is obvious that

$$\frac{d\delta k^{0\{1,0\}/\{0,1\}}}{d\chi} = \left(\frac{dk^0}{d\chi} \right)^{\{1,0\}/\{0,1\}}. \quad (6.70)$$

It follows that the trace-free part of the quadratic contribution of the source term is given by

$$\begin{aligned}
S_{(ab)}^{\{1,1\}\text{quad}}(\chi) &= \chi^2 \left\{ \frac{\mathcal{R}_{ab}}{(k^0)^2} \right\}^{\{1,1\}} + \chi^2 \mathcal{R}_{(ab)}^{\{1,0\}} \kappa^{\{0,1\}} + \chi^2 \mathcal{R}_{(ab)}^{\{0,1\}} \kappa^{\{1,0\}} + \chi^2 \mathcal{R}^{\{1,0\}} \gamma_{(ab)}^{\{0,1\}} + \chi^2 \mathcal{R}^{\{0,1\}} \gamma_{(ab)}^{\{1,0\}} \\
&+ \chi \left(\frac{dk^0}{d\chi} \right)^{\{0,1\}} \int_0^\chi \tilde{\chi} \mathcal{R}_{(ab)}^{\{1,0\}} d\tilde{\chi} + \chi \left(\frac{dk^0}{d\chi} \right)^{\{1,0\}} \int_0^\chi \tilde{\chi} \mathcal{R}_{(ab)}^{\{0,1\}} d\tilde{\chi} + \chi^2 \delta x^{i\{1,0\}} \partial_i \mathcal{R}_{(ab)}^{\{0,1\}}. \quad (6.71)
\end{aligned}$$

All terms, except the first one, involve products of quantities which are $\{0, 1\}$ and $\{1, 0\}$ and have been already computed. Note that the first term is kept in the form $(\mathcal{R}_{(ab)})/(k^0)^2)^{\{1,1\}}$, and its detailed expression must be found using the perturbed Riemann tensor given in Appendix B 2. This is indeed more convenient since we shall express everything in terms of the tetrad basis, and we will just need to use the fact that

$$k^0 = k^{\underline{0}} \Theta_0^0 = (1 - \Phi) k^{\underline{0}}. \quad (6.72)$$

We find for this first term

$$\begin{aligned}
\left(\frac{\mathcal{R}_{(ab)}}{(k^0)^2} \right)^{\{1,1\}} &= n_{(a}^i n_{b)}^j \left[-\sigma_{ij} (\varphi' + 2\varphi_{,r}) + 2\sigma_{k(i} n^k \partial_{j)} \varphi - \partial_i \partial_j \varphi - \left(\frac{\sigma_{ij} \Psi}{\mathcal{H}} \right)'' \right. \\
&\left. - 2 \left(\frac{\sigma_{ij} \Psi_{,r}}{\mathcal{H}} \right)' + 2 \left(\frac{\sigma_{ik} n^k}{\mathcal{H}} \partial_j \Psi \right)' - \frac{\sigma_{ij}}{\mathcal{H}} \Psi_{,rr} - \frac{\sigma_{ki} n^k n^l}{\mathcal{H}} \partial_i \partial_j \Psi + 2 \frac{\sigma_{ik} n^k}{\mathcal{H}} \partial_j \Psi_{,r} \right]. \quad (6.73)
\end{aligned}$$

Then, we can split all partial derivatives into covariant and radial derivatives, using the expressions of Appendix D 1. This term is then given by

$$\begin{aligned}
\left(\frac{\chi^2 \mathcal{R}_{(ab)}}{(k^0)^2} \right)^{\{1,1\}} &= -\chi^2 D_{(a} D_{b)} \Sigma (2\varphi_{,r} + \varphi') + 2\chi D_{(a} \Sigma D_{b)} \varphi + 2\chi^2 D_{(a} \mathcal{B} D_{b)} \left(\frac{\varphi}{r} \right)_{,r} + 2D_c D_{(a} \mathcal{B} D_{b)} D^c \varphi - (1 - 2\mathcal{B}) D_{(a} D_{b)} \varphi \\
&- \chi^2 \left(\frac{\Psi D_{(a} D_{b)} \Sigma}{\mathcal{H}} \right)'' - 2\chi^2 \left(\frac{\Psi_{,r} D_{(a} D_{b)} \Sigma}{\mathcal{H}} \right)' + 2\chi^2 \left(\frac{D_{(a} \Sigma D_{b)} \Psi}{\mathcal{H}} \right)' - \chi^2 \frac{D_{(a} D_{b)} \Sigma}{\mathcal{H}} \Psi_{,rr} \\
&- \frac{\Sigma}{\mathcal{H}} D_{(a} D_{b)} \Psi + \frac{2\chi^2}{\mathcal{H}} D_{(a} \Sigma D_{b)} \left(\frac{\Psi}{r} \right)_{,r} - 2\chi^2 D_{(a} \Sigma' \varpi_{b)}^{\{0,1\}} + 2\chi^2 \varpi_{(a}^{\{1,0\}} D_{b)} \left(\frac{\varphi}{r} \right)_{,r}. \quad (6.74)
\end{aligned}$$

Finally, the last term of Eq. (6.71) needs to be evaluated. It can be read directly from the previous results at order $\{1, 0\}$ and $\{0, 1\}$. We need only to split it into radial and covariant derivatives using the formulas of Appendix D 1. We find that its contribution to the traceless part of the Jacobi matrix is given by

$$\begin{aligned}
\chi^2 \delta x^{i\{1,0\}} \partial_i \mathcal{R}_{(ab)}^{\{0,1\}} &= -\delta r^{(1,0)} D_{(a} D_{b)} \left(\varphi_{,r} - 2 \frac{\varphi}{\chi} \right) \\
&- \alpha^c \{1,0\} D_c D_{(a} D_{b)} \varphi - 2\chi^2 \alpha_{(a}^{\{1,0\}} D_{b)} \left(\frac{\varphi}{r} \right)_{,r}. \quad (6.75)
\end{aligned}$$

Let us emphasize that, when $\alpha^a \neq \varpi^a$, the source is partially seen on its side.

To conclude, the source term (6.62) is obtained by combining the two terms (6.67) for the vector and tensor contribution to the $\{1, 1\}$ part, the term (6.73) for the quadratic scalar contribution and the term (6.75) for the

post-Born approximation, to which we need to add the six terms which are products $\{1, 0\} \times \{0, 1\}$ in (6.71), obtained from the expressions of the former paragraphs. In principle, once all these contributions to the sources of the Sachs equation are identified and decomposed into radial and covariant derivatives, one should apply the formalism detailed in Appendix V and expand each term in spherical harmonics for both the angular dependence and the Fourier dependence.

This procedure is however extremely long and includes a large number of terms. We will not detail it here but instead just identify the dominant contribution and compute its effect on the Jacobi matrix in order to derive the leading contribution to the B modes in the next section. Indeed, once we convert the covariant derivatives into spin-raising and spin-lowering operators, each covariant derivative is clearly associated with a factor ℓ . In the flat sky approximation, that is, in the small angle approximation, the dominant contribution arises from the first term on the second line of Eq. (6.75),

$$\begin{aligned} \delta\gamma_{ab}^{\{1,1\}}(\chi, \mathbf{n}_o) \\ \simeq - \int_0^\chi \frac{\chi - \tilde{\chi}}{\tilde{\chi}} \alpha^{c\{1,0\}}(\tilde{\chi}, \mathbf{n}_o) D_c D_{(a} D_{b)} \varphi(\tilde{\chi}, \mathbf{n}_o) d\tilde{\chi}, \end{aligned} \quad (6.76)$$

as it enjoys three covariant derivatives.

6. Trace part of the quadratic contributions

As discussed in the previous paragraph, the computation of the trace of $\delta\mathcal{D}_{ab}^{\{1,1\}}$ involves a lot of terms such as $k^{0,\{1,1\}}$ and the fourth line of Eq. (6.62). This tedious computation can indeed be performed with all the details given in this article. It will however give only a small correction to κ , the leading order of which is the standard convergence $\kappa^{\{0,1\}}$.

We thus decide not to include this computation here since we are mostly interested by the lowest order dominant effect related to the anisotropic expansion.

7. Rotation quadratic contributions

As we have seen, the rotation vanishes at orders $\{0, 1\}$ and $\{1, 0\}$ so that its leading-order contribution appears at order $\{1, 1\}$. Since $\mathcal{R}_{ab}^{\{1,1\}}$ is symmetric, its contribution arises simply from the two first terms of the second line of Eq. (6.62), that is, from the source term

$$\begin{aligned} S_{[ab]}^{\{1,1\}}(\chi) &= \chi(\mathcal{R}_{[a|c}^{\{1,0\}} \delta\mathcal{D}_{c|b]}^{\{0,1\}} + \mathcal{R}_{[a|c}^{\{0,1\}} \delta\mathcal{D}_{c|b]}^{\{1,0\}}) \\ &\equiv \epsilon_{ab} S_{\text{rot}}^{\{1,1\}}(\chi). \end{aligned} \quad (6.77)$$

Using the expression of the previous sections, it is explicitly given by

$$\begin{aligned} S_{\text{rot}}^{\{1,1\}}(\chi, \mathbf{n}_o) &= -\frac{i}{2} D_+ D_+ \Sigma' \int_0^\chi \frac{\chi(\chi - \tilde{\chi})}{\tilde{\chi}} D_- D_- \varphi(\tilde{\chi}) d\tilde{\chi} \\ &\quad - (-\leftrightarrow+) \\ &\quad -\frac{i}{2} D_+ D_+ \varphi \int_0^\chi \frac{(\chi - \tilde{\chi})\tilde{\chi}}{\chi} D_- D_- \Sigma'(\tilde{\chi}) d\tilde{\chi} \\ &\quad - (-\leftrightarrow+). \end{aligned} \quad (6.78)$$

The general expression for the rotation is then obtained through

$$V^{\{1,1\}}(\chi, \mathbf{n}_o) = \int_0^\chi \frac{\chi - \tilde{\chi}}{\tilde{\chi}} S_{\text{rot}}^{\{1,1\}}(\tilde{\chi}, \mathbf{n}_o) d\tilde{\chi}. \quad (6.79)$$

The rotation is thus sourced by the coupling between the usual cosmic shear of the standard scalar perturbation around a Friedmann-Lemaître spacetime ($D_+ D_+ \varphi$) and the quadrupolar contribution due to the geometric shear ($D_- D_- \mathcal{B}'' = D_- D_- \Sigma'$).

8. Integration over the source distribution

The last point that needs to be discussed before turning to the multipolar decomposition and the computation of the angular power spectra is the source distribution.

The source distribution represents the mean number of object normalized to the mean density observed in a solid angle $d\Omega_o$, that is,

$$\frac{dN}{d\Omega_o d\chi} \rightarrow \mathcal{N}. \quad (6.80)$$

In the Friedmann-Lemaître and Bianchi I background spacetimes, which are both homogeneous, \mathcal{N} is constant on any constant time hypersurface, which means that it depends on χ alone. Thus

$$\mathcal{N}(\chi, \mathbf{n}_o) = \mathcal{N}(\chi) + \mathcal{N}^{\{0,1\}}(\chi, x^i) + \mathcal{N}^{\{1,0\}}(\chi), \quad (6.81)$$

where the second term is the standard fluctuation of the number density due to the large scale cosmological perturbations and for which it is understood that the position x^i is evaluated on the background geodesic, that is, $x^i = \chi n_o^i$.

Note however than when one turns to redshift space, on which the observations are actually performed, one needs to take into account that z is a function of χ and the direction of observation \mathbf{n}_o , so that we should rather use

$$\mathcal{N}(z, \mathbf{n}_o) = \mathcal{N}(z) + \mathcal{N}^{\{0,1\}}(z, x^i) + \mathcal{N}^{\{1,0\}}(z, \mathbf{n}_o), \quad (6.82)$$

where again the position is evaluated on the background geodesic with $x^i = \chi n_o^i$. It follows that, when computing the observed quantities,

$$\begin{aligned} \gamma_{ab}^{\{1,1\}}(\chi, \mathbf{n}_o) &= \int d\chi [\mathcal{N}(\chi) \gamma_{ab}^{\{1,1\}} + \mathcal{N}^{\{0,1\}}(\chi, x^i) \gamma_{ab}^{\{1,0\}} \\ &\quad + \mathcal{N}^{\{1,0\}}(\chi) \gamma_{ab}^{\{0,1\}}]. \end{aligned}$$

The second term is the standard correlation between the fluctuations of the source distribution and the cosmic shear. It inherits a directional dependence from the spatial dependence $\mathcal{N}^{\{0,1\}}(\chi, x^i)$ given that it is evaluated on the background line of sight, that is, with $x^i = \chi n_o^i$. Because of the coupling to the pure E mode $\gamma_{ab}^{\{1,0\}}$ it will induce B modes in the source averaged cosmic shear. This component is expected to be important on large angular scales. The third term is a correction that arises from the fact that the formation of structure differs *a priori* in the presence of a geometrical shear, but it does not contribute the B modes since it does not have a directional dependence. However, it induces a correction for the E modes and for the convergence.

Now, in redshift space, one needs to be more careful since

$$\gamma_{ab}^{\{1,1\}}(z, \mathbf{n}_o) = \int d\tilde{z} [\mathcal{N}(\tilde{z}) \gamma_{ab}^{\{1,1\}} + \mathcal{N}^{\{0,1\}}(\tilde{z}, x^i) \gamma_{ab}^{\{1,0\}} + \mathcal{N}^{\{1,0\}}(\tilde{z}, \mathbf{n}_o) \gamma_{ab}^{\{0,1\}}].$$

Both the second and the third term depend now explicitly on the direction of observation, so that the convolution by the source distribution has to be performed before the decomposition in spherical harmonics, and both terms will generate B modes out of the E modes of $\gamma_{ab}^{\{1,0\}}$ and $\gamma_{ab}^{\{0,1\}}$, respectively. However, these effects should not dominate for small angular scales and we shall thus neglect them.

VII. ORDERS OF MAGNITUDE

The previous sections have provided all the elements needed to compute the contribution of the B modes at order $\{1, 1\}$ and their correlations with the E modes and the cosmic shear. It is obvious that any further computation has to be performed numerically. It is however important to exhibit the dominant contribution.

A. Dominant effects

Once the covariant derivatives are expressed in terms of spin-raising and spin-lowering operators, it is rather straightforward to realize that any covariant derivative is associated with a factor ℓ in multipole space. The dominant terms contributing to the shear are thus the ones with the highest number of covariant derivatives applied to φ .

For instance, at order $\{0, 1\}$, the convergence is dominated by the last term of Eq. (6.42a) on small scales. That is,

$$\kappa_{\ell m}^{\{0,1\}} \sim \frac{\ell(\ell+1)}{2} \int_0^\chi \frac{\chi - \tilde{\chi}}{\chi \tilde{\chi}} \varphi_{\ell m}(\tilde{\chi}) d\tilde{\chi},$$

simply because of the geometrical factor ℓ^2 . It is indeed the term which is usually presented in textbooks. This term dominates over the second one even at small ℓ , i.e., for $\ell > 2-3$, that is for all practical purposes.

When applying this small scale approximation scheme at order $\{1, 1\}$, we realize that there is just one dominant term—the first one on the second line of Eq. (6.75)—which possesses three covariant derivatives, that is,

$$\begin{aligned} \delta\gamma_{ab}^{\{1,1\}}(\chi, \mathbf{n}_o) \\ \simeq - \int_0^\chi \frac{\chi - \tilde{\chi}}{\tilde{\chi}} \alpha^{c\{1,0\}}(\tilde{\chi}, \mathbf{n}_o) D_c D_{\langle a} D_{b\rangle} \varphi(\tilde{\chi}, \mathbf{n}_o) d\tilde{\chi}. \end{aligned}$$

Physically it corresponds to the orthonormal displacement of the central geodesic on which the Sachs equation is evaluated, when compared with the background geodesic.

It is as if the sources of order $\{0, 1\}$ contributing to the Jacobi map had been lensed by the orthonormal displacement of order $\{1, 0\}$, resulting in an order $\{1, 1\}$ effect. This is similar to the lensing of first-order sources of CMB around the last-scattering surface by first-order gravitational potential in the foreground, resulting in a second-order lensing effect in the CMB.

The first consequence of this is that the formalism used to compute the CMB lensing can also be applied to obtain the resulting Jacobi map due to this leading-order term. However, there is a slight difference. Indeed, for the CMB the sources are all located in a background around the last-scattering surface, for which there is a deflection due to the gravitational potential crossed between emission and reception. For the general solution giving the Jacobi map, however, the sources are distributed from the observer up to the maximum redshift of the survey. For each source there is a different deflection angle as it depends on the trajectory between the source and the observer.

Finally, we must recall that the treatment of CMB lensing by a gradient expansion [84] holds only until the deflection angle is comparable to the angle of structures in the CMB. Beyond that scale, this method underestimates the effect of lensing and one has to resort to a full-lensing method as exposed in Refs. [77,85]. Since we are interested in an order of magnitude estimate of the effect of geometrical shear on the cosmic shear, we will present in the next section a gradient expansion method based on Ref. [84], but one should be aware that for any amplitude of the geometric shear, there must exist a scale ℓ_* beyond which this treatment is inaccurate. The method for the full-lensing method is exposed briefly in Appendix C.

B. Lensing of the central geodesic

1. General formalism of the gradient expansion

Any observable at a given affine parameter χ in a given direction \mathbf{n}_o is formally obtained from an integration on the background geodesic over its sources given by Eq. (5.4), that is,

$$X^s(\chi, \mathbf{n}_o) \mathbf{m}_o^s = \int_0^\chi S^X(\chi, \tilde{\chi}, \mathbf{n}_o) \mathbf{m}_o^s d\tilde{\chi}. \quad (7.1)$$

However, and as discussed above, a true observable like the cosmic shear is obtained by averaging over the true normalized profile $\mathcal{N}(\chi)$ of sources as

$$\begin{aligned} X^s(\mathbf{n}_o) \mathbf{m}_o^s &= \int_0^\infty d\chi \mathcal{N}(\chi) X^s(\chi, \mathbf{n}_o) \mathbf{m}_o^s d\chi \\ &= \int_0^\infty \mathcal{N}(\chi) d\chi \int_0^\chi S^X(\chi, \tilde{\chi}, \mathbf{n}_o) \mathbf{m}_o^s d\tilde{\chi}. \end{aligned} \quad (7.2)$$

Note that the integrals can be interchanged using

$$\int_0^\infty d\chi \mathcal{N}(\chi) \int_0^\chi d\tilde{\chi} f(\chi, \tilde{\chi}) = \int_0^\infty d\tilde{\chi} \int_{\tilde{\chi}}^\infty d\chi \mathcal{N}(\chi) f(\chi, \tilde{\chi}). \quad (7.3)$$

We consider only the effect of the dominant term in Eq. (6.75), which corresponds to the lensing of the sources; that is, it transforms the sources according to a parallel transport along the lensing vector α . A lensed observable \tilde{X}^s is then obtained from an integration over the lensed sources. If the lensing effect is small, it is sufficient to use a Taylor expansion of the lensed sources to express them in terms of the unlensed sources, the small parameter being the lensing vector α . Furthermore, if the lensed vector can be written as the gradient of a scalar, as $\alpha_a = D_a \alpha$, then at lowest order in the Taylor expansion, we get for the lensed source

$$\begin{aligned} \tilde{S}^{X^s}(\chi, \tilde{\chi}, \mathbf{n}_o) \mathbf{m}_o^s &= S^{X^s}(\chi, \tilde{\chi}, \mathbf{n}_o) \mathbf{m}_o^s \\ &+ D^a \alpha(\tilde{\chi}, \mathbf{n}_o) D_a [S^{X^s}(\chi, \tilde{\chi}, \mathbf{n}_o) \mathbf{m}_o^s]. \end{aligned} \quad (7.4)$$

Using Eq. (D26), the multipoles are easily extracted as

$$\tilde{S}_{\ell m}^{X^s}(\chi, \tilde{\chi}) = S_{\ell m}^{X^s}(\chi, \tilde{\chi}) + \sum_{m_1, \ell_2, m_2} \alpha_{2m_1}(\tilde{\chi}) S_{\ell_2 m_2}^{X^s}(\chi, \tilde{\chi}) {}_s I_{\ell 2 \ell_2}^{m m_1 m_2}, \quad (7.5)$$

where the $\alpha_{\ell m}$ are the multipoles of the lensing scalar when decomposed into spherical harmonics and the coefficients ${}_s I_{\ell \ell_1 \ell_2}^{m m_1 m_2}$ are defined in Eq. (D28).

2. Multipoles of the lensing vector

The previous expression depends on the multipoles of the lensing scalar, that can actually be obtained very easily. First, following the definitions (6.5) and (6.6) we define a matrix α_{ij} such that

$$\alpha_{\pm}(\mathbf{n}_o, \chi) \equiv D_{\pm} \alpha(\mathbf{n}_o, \chi) = D_{\pm} \left[\frac{1}{2} \alpha_{ij}(\chi) n_o^i n_o^j \right]. \quad (7.6)$$

Given Eqs. (6.13b) and (6.75), the components of $\alpha_{ij}(\chi)$ are just

$$\alpha_{ij}(\chi) = -\beta_{ij}(0) + 2 \int_0^\chi d\chi' \frac{\chi - \chi'}{\chi} \sigma_{ij}(\chi') \quad (7.7a)$$

$$= \beta_{ij}(0) - \frac{2}{\chi} \int_0^\chi d\chi' \beta_{ij}(\chi'). \quad (7.7b)$$

Then, similarly to the computation of the coefficients Σ_{2m} in Eq. (4.26), the multipoles of $\alpha(\mathbf{n}_o, \chi)$ defined by $\alpha = \sum_m \alpha_{2m} Y_{2m}$ reduce to a quadrupole and are explicitly given by

$$\alpha_{20}(\chi) = -\sqrt{\frac{\pi}{5}} [\alpha_{xx}(\chi) + \alpha_{yy}(\chi)],$$

$$\alpha_{2\pm 2}(\chi) = \sqrt{\frac{\pi}{30}} [\alpha_{xx}(\chi) - \alpha_{yy}(\chi)], \quad (7.8)$$

if the coordinates system is adapted to the eigendirections of the geometrical shear.

3. Extracting the spatial shear components from off-diagonal correlations

A by-product of the formalism just developed is that we can extract information about the geometric shear σ_{ij} from cross-correlations between the E - and B -mode multipoles of the cosmic shear, $E_{\ell m}$ and $B_{\ell m}$, and the multipoles $\kappa_{\ell m}$ of the convergence κ , that would otherwise vanish in the pure Friedmann-Lemaître case. Indeed, even if the B modes are not sourced initially, as is the case of a Friedmann-Lemaître background, at the perturbative level there will be a lensed B -mode term sourced by the E modes of the background shear. In order to extract this effect we decompose the (lensed) E and B modes of the source as

$$\tilde{S}_{\ell m}^{E/B}(\chi, \tilde{\chi}) = \tilde{S}_{\ell m}^E(\chi, \tilde{\chi}) \pm i \tilde{S}_{\ell m}^B(\chi, \tilde{\chi}) \quad (7.9)$$

with a similar decomposition for the (unlensed) $S_{\ell m}^X$. Then, using the properties (D28), it follows that

$$\tilde{S}_{\ell m}^B(\chi, \tilde{\chi}) = -i \sum_{\substack{m_1, m_2 \\ \ell_2 = \ell \pm 1}} \alpha_{2m_1}(\tilde{\chi}) S_{\ell_2 m_2}^E(\chi, \tilde{\chi}) {}_{+2} I_{\ell 2 \ell_2}^{m m_1 m_2}, \quad (7.10a)$$

$$\tilde{S}_{\ell m}^E(\chi, \tilde{\chi}) = S_{\ell m}^E(\chi, \tilde{\chi}) + \sum_{\substack{m_1, m_2 \\ \ell_2 = \ell, \ell \pm 2}} \alpha_{2m_1}(\tilde{\chi}) S_{\ell_2 m_2}^E(\chi, \tilde{\chi}) {}_{+2} I_{\ell 2 \ell_2}^{m m_1 m_2}. \quad (7.10b)$$

We recall that there is no tilde on $S_{\ell m}^E$ on the right-hand side of the above equation, since it corresponds to the unlensed sources. Since the convergence is a spin-0 quantity, then from Eq. (7.5), its sources are transformed under lensing as

$$\tilde{S}_{\ell m}^{\kappa}(\chi, \tilde{\chi}) = S_{\ell m}^{\kappa}(\chi, \tilde{\chi}) + \sum_{\substack{m_1, m_2 \\ \ell_2 = \ell, \ell \pm 2}} \alpha_{2m_1}(\tilde{\chi}) S_{\ell_2 m_2}^{\kappa}(\chi, \tilde{\chi}) {}_s I_{\ell 2 \ell_2}^{m m_1 m_2}. \quad (7.11)$$

From these expressions, it is clear that the off-diagonal terms coming from the EB , EE , $\kappa\kappa$, κE , κB cross-correlation matrices allow us to put constraints on α_{2m} and, consequently, on the geometric shear components σ_{ij} by means of Eqs. (7.7). To see how that is possible, we must remember that the sources should be convolved with $\mathcal{N}(\chi)$ by means of Eq. (7.2).

In Sec. VID 5, the EE , $\kappa\kappa$, and κE correlations at order $\{0, 1\}$ (that is, without the effect of lensing by the geometric shear) have been computed and they are of the form

$$C_{\ell}^{XZ} = \int_0^{\infty} d\tilde{\chi}_1 \int_{\tilde{\chi}_1}^{\infty} d\chi_1 \mathcal{N}(\chi_1) \int_0^{\infty} d\tilde{\chi}_2 \int_{\tilde{\chi}_2}^{\infty} d\chi_2 \mathcal{N}(\chi_2) C_{\ell}^{XZ}(\chi_1, \chi_2, \tilde{\chi}_1, \tilde{\chi}_2), \quad (7.12)$$

where the indices X and Z take the values κ, E , and with the source correlations

$$\langle S_{\ell_1 m_1}^X(\chi_1, \tilde{\chi}_1) S_{\ell_2 m_2}^Z(\chi_2, \tilde{\chi}_2) \rangle = \delta_{\ell_1 \ell_2} \delta_{m_1 m_2} C_{\ell_1}^{XZ}(\chi_1, \chi_2, \tilde{\chi}_1, \tilde{\chi}_2), \quad (7.13a)$$

$$C_{\ell}^{XZ}(\chi_1, \chi_2, \tilde{\chi}_1, \tilde{\chi}_2) \equiv \frac{2}{\pi} \int_0^{\infty} k^2 dk P(k) g_{\ell}^X(k, \chi_1, \tilde{\chi}_1) g_{\ell}^Z(k, \chi_2, \tilde{\chi}_2). \quad (7.13b)$$

For the lensed observables, we define similarly

$$\begin{aligned} \mathcal{P}_{\ell M}^{XZ} &\equiv \int_0^{\infty} d\tilde{\chi}_1 \int_{\tilde{\chi}_1}^{\infty} d\chi_1 \mathcal{N}(\chi_1) \int_0^{\infty} d\tilde{\chi}_2 \int_{\tilde{\chi}_2}^{\infty} d\chi_2 \mathcal{N}(\chi_2) \alpha_{2M}(\tilde{\chi}_1) C_{\ell}^{XZ}(\chi_1, \chi_2, \tilde{\chi}_1, \tilde{\chi}_2) \\ &= \frac{2}{\pi} \int_0^{\infty} k^2 dk P(k) \left(\int_0^{\infty} d\tilde{\chi}_1 \int_{\tilde{\chi}_1}^{\infty} d\chi_1 \mathcal{N}(\chi_1) \alpha_{2M}(\tilde{\chi}_1) g_{\ell}^X(k, \chi_1, \tilde{\chi}_1) \right) \\ &\quad \times \left(\int_0^{\infty} d\tilde{\chi}_2 \int_{\tilde{\chi}_2}^{\infty} d\chi_2 \mathcal{N}(\chi_2) g_{\ell}^Z(k, \chi_2, \tilde{\chi}_2) \right), \end{aligned} \quad (7.14a)$$

such that the following nonvanishing correlations are expressed as

$$\langle \tilde{B}_{\ell m}^X E_{\ell \pm 1 m - M}^{X*} \rangle = -i_{+2} I_{\ell 2 \ell \pm 1}^{mM(m-M)} \mathcal{P}_{\ell \pm 1 M}^{EE}, \quad (7.15a)$$

$$\langle \tilde{B}_{\ell m}^X \kappa_{\ell \pm 1 m - M}^{X*} \rangle = -i_{+2} I_{\ell 2 \ell \pm 1}^{mM(m-M)} \mathcal{P}_{\ell \pm 1 M}^{E\kappa}. \quad (7.15b)$$

Not only do we get off-diagonal contributions for B modes with the E modes and the convergence, but we also get off-diagonal correlations between κ and E modes. They read

$$\langle \tilde{E}_{\ell m}^X \tilde{E}_{\ell \pm 2 m - M}^{X*} \rangle = {}_{+2} I_{\ell 2 \ell \pm 2}^{mM(m-M)} (\mathcal{P}_{\ell \pm 2 M}^{EE} + \mathcal{P}_{\ell M}^{EE}), \quad (7.16a)$$

$$\langle \tilde{\kappa}_{\ell m}^X \tilde{\kappa}_{\ell \pm 2 m - M}^{X*} \rangle = I_{\ell 2 \ell \pm 2}^{mM(m-M)} (\mathcal{P}_{\ell \pm 2 M}^{\kappa\kappa} + \mathcal{P}_{\ell M}^{\kappa\kappa}), \quad (7.16b)$$

$$\langle \tilde{E}_{\ell m}^X \tilde{\kappa}_{\ell \pm 2 m - M}^{X*} \rangle = {}_{+2} I_{\ell 2 \ell \pm 2}^{mM(m-M)} \mathcal{P}_{\ell \pm 2 M}^{E\kappa} + I_{\ell 2 \ell \pm 2}^{mM(m-M)} \mathcal{P}_{\ell M}^{\kappa E}. \quad (7.16c)$$

Note that in all these cross-correlators, M ranges from -2 to 2 , thus spanning the 5 degrees of freedom of the lensing potential α_{2M} and consequently of the underlying Bianchi geometrical shear σ_{ij} . These expressions for the correlators are however not ideal to relate the correlations to the lensing potential and thus to the components of σ_{ij} . Instead, we define appropriate combinations of the correlators by resumming them as [86]

$${}^{XZ} \mathcal{A}_{\ell_1 \ell_2}^{2M} \equiv \sum_m \sqrt{5} (-1)^{m+\ell_1+\ell_2} \begin{pmatrix} \ell_1 & 2 & \ell_2 \\ -m & M & m-M \end{pmatrix} \langle \tilde{X}_{\ell_1 m}^X Z_{\ell_2, m-M}^{X*} \rangle. \quad (7.17)$$

For instance, for the EB and EE correlations, we get

$${}^{BE} \mathcal{A}_{\ell \ell \pm 1}^{2M} \equiv \sum_m \sqrt{5} (-1)^{m+1} \begin{pmatrix} \ell & 2 & \ell \pm 1 \\ -m & M & m-M \end{pmatrix} \langle \tilde{B}_{\ell m}^X E_{\ell \pm 1, m-M}^{X*} \rangle, \quad (7.18a)$$

$${}^{EE} \mathcal{A}_{\ell \ell \pm 2}^{2M} \equiv \sum_m \sqrt{5} (-1)^m \begin{pmatrix} \ell & 2 & \ell \pm 2 \\ -m & M & m-M \end{pmatrix} \langle \tilde{E}_{\ell m}^X \tilde{E}_{\ell \pm 2, m-M}^{X*} \rangle. \quad (7.18b)$$

Then, by using the definition of the symbols ${}_{+2} I_{\ell 2 \ell \pm 1}^{mMm'}$ and $I_{\ell 2 \ell \pm 1}^{mMm'}$ and the orthogonality relations of the Wigner $3j$ symbols, we get

$${}^{BE} \mathcal{A}_{\ell\ell\pm 1}^{2M} = i \frac{{}_2F_{\ell 2\ell\pm 1}}{\sqrt{5}} \mathcal{P}_{\ell\pm 1M}^{EE}, \quad (7.19a)$$

$${}^{B\kappa} \mathcal{A}_{\ell\ell\pm 1}^{2M} = i \frac{F_{\ell 2\ell\pm 1}}{\sqrt{5}} \mathcal{P}_{\ell\pm 1M}^{E\kappa}, \quad (7.19b)$$

$${}^{EE} \mathcal{A}_{\ell\ell\pm 2}^{2M} = \frac{{}_2F_{\ell 2\ell\pm 2}}{\sqrt{5}} (\mathcal{P}_{\ell\pm 2M}^{EE} + \mathcal{P}_{\ell M}^{EE}), \quad (7.19c)$$

$${}^{\kappa\kappa} \mathcal{A}_{\ell\ell\pm 2}^{2M} = \frac{F_{\ell 2\ell\pm 2}}{\sqrt{5}} (\mathcal{P}_{\ell\pm 2M}^{\kappa\kappa} + \mathcal{P}_{\ell M}^{\kappa\kappa}), \quad (7.19d)$$

$${}^{E\kappa} \mathcal{A}_{\ell\ell\pm 2}^{2M} = \frac{{}_2F_{\ell 2\ell\pm 2}}{\sqrt{5}} \mathcal{P}_{\ell\pm 2M}^{E\kappa} + \frac{F_{\ell 2\ell\pm 2}}{\sqrt{5}} \mathcal{P}_{\ell M}^{E\kappa}, \quad (7.19e)$$

where the symbols ${}_2F_{\ell\ell_1\ell_2}$ are defined in Appendix D 4.

Approximate expressions of this correlators can be obtained in the Limber approximation (6.47) and read

$$\mathcal{P}_{\ell M}^{\kappa\kappa} \simeq \frac{\ell^2(\ell+1)^2}{4} \mathcal{P}_{\ell M}, \quad (7.20a)$$

$$\mathcal{P}_{\ell M}^{E\kappa} \simeq \mathcal{P}_{\ell M}^{E\kappa} = \frac{\ell(\ell+1)}{4} \sqrt{\frac{(\ell+2)!}{(\ell-2)!}} \mathcal{P}_{\ell M}, \quad (7.20b)$$

$$\mathcal{P}_{\ell M}^{\kappa\kappa} \simeq \frac{1}{4} \frac{(\ell+2)!}{(\ell-2)!} \mathcal{P}_{\ell M}, \quad (7.20c)$$

with the function $\mathcal{P}_{\ell M}$ given by

$$C_{\ell}^{BB\{1,1\}} = \int_0^{\infty} d\chi_1 \int_0^{\infty} d\chi_2 \mathcal{N}(\chi_1) \mathcal{N}(\chi_2) \int_0^{\chi_1} d\chi'_1 \int_0^{\chi_2} d\chi'_2 \sum_{s=\pm 1, m} \frac{\alpha_{2m}(\chi'_1) \alpha_{2m}^*(\chi'_2)}{5} C_{\ell+s}^{EE}(\chi_1, \chi_2, \chi'_1, \chi'_2) \frac{({}_2F_{\ell 2\ell+s})^2}{2\ell+1}. \quad (7.22)$$

If we now factorize the time integrals, we simply get

$$C_{\ell}^{BB\{1,1\}} = \frac{2}{5\pi} \int_0^{\infty} k^2 dk P(k) \sum_{s=\pm 1} \frac{({}_2F_{\ell 2\ell+s})^2}{2\ell+1} \sum_m \left| \int_0^{\infty} d\chi \mathcal{N}(\chi) \int_0^{\chi} d\chi' \alpha_{2m}(\chi') g_{\ell+s}(k, \chi, \chi') \right|^2. \quad (7.23)$$

Note that for large ℓ the F coefficients behave as

$$\lim_{\ell \rightarrow \infty} \frac{({}_2F_{\ell 2\ell+1})^2}{2\ell+1} = \frac{15}{2\pi}, \quad \lim_{\ell \rightarrow \infty} \frac{({}_2F_{\ell 2\ell-1})^2}{2\ell+1} = \frac{15}{2\pi}. \quad (7.24)$$

Apart from the six terms (sum over $m = -2, 0, +2$ and over $s = \pm 1$), this is numerically as fast as computing the correlation C_{ℓ}^{EE} at order $\{0, 1\}$. Then, using the Limber approximation (6.47), with the definitions $L_s = L + s = \ell + 1/2 + s$ and $\ell_s = \ell + s$, it leads to

$$C_{\ell}^{BB\{1,1\}} \simeq \frac{1}{20} \int_0^{\infty} \frac{d\tilde{\chi}}{\tilde{\chi}^2} \sum_{s=\pm 1} \frac{(\ell_s+2)!}{(\ell_s-2)!} P\left(\frac{L_s}{\tilde{\chi}}\right) \frac{({}_2F_{\ell 2\ell+s})^2}{2\ell+1} \times \sum_m \left| T^{\varphi}\left(\frac{L_s}{\tilde{\chi}}, \tilde{\chi}\right) \alpha_{2m}(\tilde{\chi}) \int_{\tilde{\chi}}^{\infty} d\chi \mathcal{N}(\chi) \frac{(\chi - \tilde{\chi})}{\chi \tilde{\chi}} \right|^2. \quad (7.25)$$

$$\mathcal{P}_{\ell M} \equiv \int_0^{\infty} \frac{d\tilde{\chi}}{\tilde{\chi}^2} P\left(\frac{L}{\tilde{\chi}}\right) \alpha_{2M}(\tilde{\chi}) \times \left| T^{\varphi}\left(\frac{L}{\tilde{\chi}}, \tilde{\chi}\right) \int_{\tilde{\chi}}^{\infty} d\chi \mathcal{N}(\chi) \frac{(\chi - \tilde{\chi})}{\chi \tilde{\chi}} \right|^2, \quad (7.21)$$

where we used the notation $L \equiv \ell + 1/2$.

This provides the expressions of the five (off-diagonal) correlators (7.19), each having five components, and all being linear in σ_{ij} . We stress that the measurement of these quantities from further surveys will allow us to get stronger constraints on the spatial isotropy of the Universe, thus pushing forward the ‘‘beyond Λ CDM’’ program.

4. Autocorrelations of B modes from the lensing of the central geodesic

The previous off-diagonal correlators are the most direct consequence of a late-time geometrical shear on weak lensing. However, experiments are mostly designed to measure the diagonal part. In this section we compute the autocorrelation of B modes induced by the dominant lensing term. This angular power spectrum will thus be quadratic in σ_{ij} . Contrary to the previous estimators, it does not allow us to reconstruct the full geometrical shear σ_{ij} but can be used to set constraints on σ^2 .

Using the properties of the Wigner $3j$ symbols given in Appendix D 4 and starting from the lens sources (7.10), we obtain that the B -mode angular power spectrum of weak-lensing cosmic shear generated by the lensing of the central geodesic is

Finally, using (7.8) to get

$$\sum_m |\alpha_{2m}(\chi)|^2 = \frac{2\pi}{15} \alpha_{ij}(\chi) \alpha^{ij}(\chi) \equiv \frac{2\pi}{15} |\alpha(\chi)|^2, \quad (7.26)$$

we obtain a very compact expression, valid only for large ℓ , which is

$$C_\ell^{BB\{1,1\}} \simeq \frac{\ell^4}{10} \int_0^\infty \frac{d\tilde{\chi}}{\tilde{\chi}^2} P\left(\frac{\ell}{\tilde{\chi}}\right) \times \left| T^\psi\left(\frac{\ell}{\tilde{\chi}}, \tilde{\chi}\right) \alpha(\tilde{\chi}) \int_{\tilde{\chi}}^\infty d\chi \mathcal{N}(\chi) \frac{(\chi - \tilde{\chi})}{\chi \tilde{\chi}} \right|^2. \quad (7.27)$$

A numerical analysis of some simple anisotropic phenomenological models, together with observational constraints from Euclid [70] and SKA [71] surveys, will appear in a companion paper [69].

VIII. DISCUSSION

In this article we have derived the observational signature of a late-time anisotropic expansion on the weak-lensing observables. To that purpose, we have provided all the technical tools, including the evolution of the background spacetime, the perturbation theory, the description of the evolution of a geodesic bundle and the manipulation of observables on the celestial sphere.

Our strategy is to adopt an approach based on the observer point of view, in which all observables are expressed in terms of the direction of observation at the observer. Since a full solution to the problem cannot be attained straightforwardly, and given that CMB observations suggest that spatial anisotropy cannot be too large, we have developed a small shear approximation scheme. It allowed us to identify the following contributions compared to the standard Friedmann-Lemaître case:

- (1) the tensor and vector contributions to the source of the Sachs equation, which starts at order $\{1, 1\}$, and the contribution of the scalar modes coupled to the geometrical shear, which is of order $\{1, 1\}$ as well;
- (2) the evolution of all the perturbative modes, that is, of the transfer functions, which are decomposed as $T^{X_s}(\mathbf{k}, t)$, where the dependence with the direction of \mathbf{k} comes from the coupling with the geometrical shear in the Einstein equation (for that, see Appendix A);
- (3) the fact that the geodesic deviates from the Friedmannian form and which leads to post-Born corrections;
- (4) the effect of the source distributions which are affected by the background shear or the scalar perturbations—that are, respectively, at orders $\{1, 0\}$ and $\{0, 1\}$ —and for which we would in principle need a theory of structure formation.

We have then argued that the dominant term is related to the orthoradial displacement of the central geodesic on which the Sachs equation is evaluated, when compared with the background geodesic.

While we have provided all the elements to perform the full computation, we have focused on this dominant term and demonstrated that there exist five off-diagonal correlators between $E_{\ell m}$, $B_{\ell m}$ and $\kappa_{\ell m}$ each of which has five independent components and thus allow one in principle to fully reconstruct the geometrical shear σ_{ij} . All of them are linear in σ/\mathcal{H} and only two of them involve the B modes. We advocate that their measurements in future surveys such as Euclid and SKA, on scales where the linear regime holds, can set strong constraints on the anisotropy. The amplitude for these two surveys is estimated in our companion article [69].

The existence of nonvanishing B modes also reflects itself in the existence of an angular power spectrum that is quadratic in σ/\mathcal{H} . While probably easier to measure, it does not allow one to fully reconstruct the shear σ_{ij} .

This analysis sets the ground for stronger constraints on an anisotropic expansion, and possibly on the anisotropic stress on the dark energy sector. The new estimators that we proposed will also allow the control of systematics and are new in the weak-lensing literature.

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APPENDIX A: PERTURBATION THEORY IN BIANCHI I UNIVERSES

This section summarizes the general framework of linear perturbation theory in Bianchi I universes. Our approach is an extension of the formalism we introduced in Ref. [22], where perturbation theory was developed in the context of an early anisotropic stage. Here, we adapt this formalism for the physics of the late-time universe. Before we introduce the parameterization of the perturbations and the whole machinery of gauge-invariant linear perturbation theory, we summarize some results regarding the appropriate Fourier transform in anisotropic spacetimes and show how they can be used to extract the dynamics of scalar, vector and tensor modes from Einstein’s equations.

We then use these tools to decompose the background shear and anisotropic stress in a general basis adapted to our coordinate system.

1. Mode decomposition

a. Fourier and SVT decomposition

In order to correctly describe the dynamics of perturbative modes one needs a complete set of spatial eigenfunctions adapted to the symmetries of the spacetime one is dealing with. Since Bianchi *I* universes are spatially flat, at each constant time hypersurface these eigenfunctions are standard plane waves. Therefore, any scalar function of the comoving coordinates $\{x^i\}$ and time can be Fourier decomposed as

$$f(x^j, \eta) = \int \frac{d^3 k_i}{(2\pi)^{3/2}} \hat{f}(k_i, \eta) e^{ik_i x^i} \quad (\text{A1})$$

with the obvious inverse transformation. Because of the lack of rotational symmetry, the direction of a wave vector will vary with time. In particular, since k_i is constant, $k^i = \gamma^{ij} k_j$ varies with time—its rate of change being given by

$$(k^i)' = -2\sigma^{ij} k_j. \quad (\text{A2})$$

Note however that $k_i x^i = k^i x_i$ remains constant. From the above expression, one can easily deduce the time evolution of the modulus $k^2 \equiv k^i k_i$ and unit vector $\hat{k}^i \equiv k^i/k$ as

$$\frac{k'}{k} = -\sigma^{ij} \hat{k}_i \hat{k}_j, \quad (\hat{k}^i)' = (\sigma^{jl} \hat{k}_j \hat{k}_l) \hat{k}^i - 2\sigma^{ij} \hat{k}_j. \quad (\text{A3})$$

As we are going to see, these expressions are crucial for extracting different perturbative modes from Einstein equations.

Once equipped with a Fourier transform, we can proceed and decompose any three-dimensional geometrical object in terms of its scalar, vector and tensor pieces. We start by decomposing any (three-dimensional) vector V_i in its longitudinal and transverse pieces as $V_i = \partial_i V + \bar{V}_i$, with $\partial^i \bar{V}_i = 0$. In Fourier space, this decomposition is equivalent to²

$$V_i = \hat{k}_i V + \bar{V}_i, \quad \hat{k}^i \bar{V}_i = 0. \quad (\text{A4})$$

Since \bar{V}_i is orthogonal to \hat{k}^i , it can be further decomposed as

$$\bar{V}_i = \sum_{a=1,2} V_a(\hat{k}^i, \eta) e^a(\hat{k}_i), \quad (\text{A5})$$

where $\{e_i^a\}$ represents a two-dimensional basis defined so that

²Note that we can always reabsorb i factors in the terms of the decomposition.

$$e_i^a k^i = 0, \quad e_i^a e_j^b \gamma^{ij} = \delta^{ab}. \quad (\text{A6})$$

Analogously, any (three-dimensional) symmetric tensor V_{ij} can be decomposed into a trace plus a traceless part as $V_{ij} = T\gamma_{ij} + \Delta_{ij}S + 2\partial_{(i}\bar{V}_{j)} + 2\bar{V}_{ij}$, where $\Delta_{ij} \equiv \partial_i\partial_j - \gamma_{ij}\Delta/3$, \bar{V}_i is transverse and \bar{V}_{ij} is transverse and traceless. In Fourier space, such decomposition becomes

$$V_{ij} = T\gamma_{ij} + \left(\hat{k}_i\hat{k}_j - \frac{\gamma_{ij}}{3}\right)S + 2\hat{k}_{(i}\bar{V}_{j)} + \bar{V}_{ij}, \quad (\text{A7})$$

where \bar{V}_i is given by Eq. (A5). \bar{V}_{ij} is a transverse and traceless tensor decomposed as

$$\bar{V}_{ij} = \sum_{\lambda=+, \times} V_\lambda(\hat{k}^i, \eta) \epsilon_{ij}^\lambda(\hat{k}^i) \quad (\text{A8})$$

with the traceless ($\epsilon_{ij}^\lambda \gamma^{ij} = 0$), transverse ($\epsilon_{ij}^\lambda \hat{k}^i = 0$) and perpendicular ($\epsilon_{ij}^\lambda \epsilon_\mu^{ij} = \delta_\mu^\lambda$) polarization tensor being defined as

$$\epsilon_{ij}^\lambda = \frac{e_i^1 e_j^1 - e_i^2 e_j^2}{\sqrt{2}} \delta_+^\lambda + \frac{e_i^1 e_j^2 + e_i^2 e_j^1}{\sqrt{2}} \delta_\times^\lambda. \quad (\text{A9})$$

Given the above decomposition, the correspondence between SVT components of any geometrical equation can be extracted uniquely. For example, the scalar part of any vectorial equation of the form $V_i = 0$ can be extracted by projecting it along \hat{k}^i , whereas its vector part can be extracted with the help of the projector

$$P_{ij} \equiv \gamma_{ij} - \hat{k}_i \hat{k}_j = e_i^1 e_j^1 + e_i^2 e_j^2. \quad (\text{A10})$$

Likewise, the scalar components of any tensorial equation like $V_{ij} = 0$ can be extracted by projecting it along γ_{ij} and T_{ij} , with the later projector defined as

$$T_{ij} \equiv \hat{k}_i \hat{k}_j - \frac{1}{3}\gamma_{ij}. \quad (\text{A11})$$

The remaining vector and tensor pieces can be extracted with the help of $P_i^j \hat{k}^j$ and Λ_{ij}^{ab} , respectively, where

$$\Lambda_{ij}^{ab} = P_i^a P_j^b - \frac{1}{2}P_{ij}P^{ab}. \quad (\text{A12})$$

In conclusion, the SVT degrees of freedom of any tridimensional vector and tensor are given explicitly by

$$\begin{aligned} V_i &= (\hat{k}^j V_j) \hat{k}_i + P_i^j V_j, \\ V_{ij} &= \left(\frac{1}{3}\gamma^{kl} V_{kl}\right) \gamma_{ij} + \left(\frac{3}{2}T^{kl} V_{kl}\right) T_{ij} \\ &\quad + 2\hat{k}_{(i} [P_{j)}^m \hat{k}^n V_{mn}] + \Lambda_{ij}^{mn} V_{mn}. \end{aligned} \quad (\text{A13})$$

b. Mode evolution

The SVT decomposition introduced above is based on the properties of a tensor according to the rotation symmetries of the background spacetime. As such, in Friedmann-Lemaître spacetimes this decomposition is always possible and will hold during the entire cosmic evolution. In the Bianchi *I* case, on the other hand, this decomposition will hold, strictly speaking, only on a given constant-time hypersurface. Because of the anisotropic evolution of space, SVT modes which are initially decoupled will couple nontrivially as time evolves, implying in a set of coupled dynamical equations already at linear order in perturbations. Therefore, it is important to have expressions for the time evolution of basis vectors and polarization tensors, which will be directly dependent on the spacetime shear. We have already met the time evolution of \hat{k}^i , Eq. (A3). For completeness, we also give the time evolution of the vector e_i^a and polarization tensor e_{ij}^λ [22]:

$$(\hat{k}^i)' = (\sigma^{jl}\hat{k}_j\hat{k}_l)\hat{k}^i - 2\sigma^{ij}\hat{k}_j, \quad (\text{A14a})$$

$$(e_a^i)' = -\sum_b(\sigma_{jl}e_a^j e_b^l)e_b^i, \quad (\text{A14b})$$

$$(e_{ij}^\lambda)' = -(\sigma^{kl}e_{kl}^\lambda)P_{ij} - (\sigma^{kl}P_{kl})e_{ij}^\lambda + 4\sigma_{(i}^k e_{j)k}^\lambda. \quad (\text{A14c})$$

Special care is needed when extracting SVT modes from Einstein equations, for the projections of SVT modes do not commute with time evolution anymore. As an illustration, let us consider the extraction of the scalar component of an equation like $(\bar{V}_i)' + \mathcal{H}\bar{V}_i = 0$, where \bar{V}_i is any transverse tensor. In Friedmann-Lemaître-Robertson-Walker this equation does not have a scalar component, since $\hat{k}^i\bar{V}_i = 0$. However, due to Eq. (A3) we now get

$$\hat{k}^i[(\bar{V}_i)' + \mathcal{H}\bar{V}_i] = (\hat{k}^i\bar{V}_i)' - (\hat{k}^i)'\bar{V}_i = 2\sigma^{ij}\hat{k}_j\bar{V}_i, \quad (\text{A15})$$

which is only zero when $\sigma_{ij} = 0$. Further mode-extracting relations can be easily found in an analogous manner. For a comprehensive list of relations the reader can check Ref. [22].

c. Background shear and anisotropic stress

Both the (background) spatial shear σ_{ij} and spatial anisotropic stress Π_{ij} are transverse and traceless tensors. As such, each of them is described by five independent degrees of freedom, which are best described in the basis $\{\hat{k}_i, e_i^1, e_i^2\}$ adapted to the modes we are considering. In this basis, these two tensors can be written in terms of ten new scalar functions as

$$\sigma_{ij} = \frac{3}{2}\left(\hat{k}_i\hat{k}_j - \frac{1}{3}\gamma_{ij}\right)\sigma_{\parallel} + 2\sum_{a=1,2}\sigma_{\mathcal{V}^a}\hat{k}_{(i}e_{j)}^a + \sum_{\lambda=+, \times}\sigma_{\mathcal{T}^\lambda}e_{ij}^\lambda, \quad (\text{A16a})$$

$$\Pi_{ij} = \frac{3}{2}\left(\hat{k}_i\hat{k}_j - \frac{1}{3}\gamma_{ij}\right)\Pi_{\parallel} + 2\sum_{a=1,2}\Pi_{\mathcal{V}^a}\hat{k}_{(i}e_{j)}^a + \sum_{\lambda=+, \times}\Pi_{\mathcal{T}^\lambda}e_{ij}^\lambda. \quad (\text{A16b})$$

It is important to note that these new functions, which depend of both \hat{k}_i and time, are not the Fourier transform of their respective tensors, which in fact are homogeneous and depend only on time. In other words, the dependence of $(\sigma_{\parallel}, \sigma_{\mathcal{V}^a}, \sigma_{\mathcal{T}^\lambda})$ and $(\Pi_{\parallel}, \Pi_{\mathcal{V}^a}, \Pi_{\mathcal{T}^\lambda})$ with \hat{k}_i arises solely from the local anisotropy of space.

With the help of background Einstein equations (2.18a) and (2.18b) written in conformal time and the mode evolution described by Eqs. (A14a), one can show with a bit of algebra that

$$(\sigma')_{\parallel} \equiv \sigma'_{\parallel} + 2\mathcal{H}\sigma_{\parallel} + 2\sum_a\sigma_{\mathcal{V}^a}^2 = \kappa a^2\Pi_{\parallel}, \quad (\text{A17a})$$

$$(\sigma')_{\mathcal{V}^a} \equiv \sigma'_{\mathcal{V}^a} + 2\mathcal{H}\sigma_{\mathcal{V}^a} - \frac{3}{2}\sigma_{\mathcal{V}^a}\sigma_{\parallel} + \sum_{b,\lambda}\sigma_{\mathcal{V}^b}\sigma_{\mathcal{T}^\lambda}\mathcal{M}_{ab}^\lambda = \kappa a^2\Pi_{\mathcal{V}^a}, \quad (\text{A17b})$$

$$(\sigma')_{\mathcal{T}^\lambda} \equiv \sigma'_{\mathcal{T}^\lambda} + 2\mathcal{H}\sigma_{\mathcal{T}^\lambda} - 2\sum_{a,b}\mathcal{M}_{ab}^\lambda\sigma_{\mathcal{V}^a}\sigma_{\mathcal{V}^b} = \kappa a^2\Pi_{\mathcal{T}^\lambda}, \quad (\text{A17c})$$

where \mathcal{M}_{ab}^λ is defined as [22]

$$\mathcal{M}_{ab}^\lambda = \frac{1}{\sqrt{2}}\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}\delta_+^\lambda + \frac{1}{\sqrt{2}}\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}\delta_\times^\lambda.$$

2. Gauge-invariant variables

a. Geometry

The most general linearly perturbed metric over a Bianchi *I* spacetime can be parameterized as follows:

$$ds^2 = a^2[-(1+2A)d\eta^2 + 2B_id x^i d\eta + (\gamma_{ij} + h_{ij})dx^i dx^j], \quad (\text{A18})$$

where *A* is a free scalar function and

$$B_i \equiv \partial_i B + \bar{B}_i, \quad (\text{A19a})$$

$$h_{ij} \equiv 2C\left(\gamma_{ij} + \frac{\sigma_{ij}}{\mathcal{H}}\right) + 2\partial_i\partial_j E + 2\partial_{(i}E_{j)} + 2E_{ij}, \quad (\text{A19b})$$

defined together with the usual transversality and trace-free conditions:

$$\partial_i \bar{B}^i = 0 = \partial_i E^i, \quad E_i^i = 0 = \partial_i E^{ij}. \quad (\text{A20})$$

Under an active coordinate transformation, the coordinates of any point will change according to

$$x^\mu \rightarrow \tilde{x}^\mu = x^\mu - \xi^\mu(x^\nu), \quad (\text{A21})$$

where the gauge vector ξ^μ is itself decomposed as

$$\xi^0 = T, \quad \xi^i = \partial^i L + L^i \quad (\text{A22})$$

with $\partial_i L^i = 0$. Under the transformation of Eq. (A21), the perturbations of the metric will transform as

$$\delta g_{\mu\nu} \rightarrow \delta g_{\mu\nu} + \mathcal{L}_\xi \bar{g}_{\mu\nu}, \quad (\text{A23})$$

where $\mathcal{L}_\xi \bar{g}_{\mu\nu}$ is the Lie derivative of the background metric along ξ . Using the above parameterization and the mode decomposition introduced in Sec. A 1, it is straightforward to show that the scalar and vector metric potentials transform, respectively, as

$$A \rightarrow A + T' + \mathcal{H}T, \quad (\text{A24a})$$

$$B \rightarrow B - T + \frac{(k^2 L)'}{k^2}, \quad (\text{A24b})$$

$$C \rightarrow C + \mathcal{H}T, \quad (\text{A24c})$$

$$E \rightarrow E + L, \quad (\text{A24d})$$

$$\bar{B}_i \rightarrow \bar{B}_i + \gamma_{ij}(L^j)' - 2ik^j \sigma_{ij} P_i^j L, \quad (\text{A24e})$$

$$E_i \rightarrow E_i + L_i, \quad (\text{A24f})$$

whereas E_{ij} is automatically gauge invariant. Based on these transformations, we can construct the following gauge-invariant variables:

$$\Phi = A + \frac{1}{a} \left\{ a \left[B - \frac{(k^2 E)'}{k^2} \right] \right\}', \quad (\text{A25a})$$

$$\Psi = -C - \mathcal{H} \left[B - \frac{(k^2 E)'}{k^2} \right], \quad (\text{A25b})$$

$$\Phi_i = \bar{B}_i - \gamma_{ij}(E^j)' + 2ik^j \sigma_{ij} P_i^j E. \quad (\text{A25c})$$

It is easily verifiable that whenever $\sigma_{ij} = 0$ the Fourier wave vector k will be constant and the above variables become the standard Bardeen variables for a Friedmann-Lemaître universe.

b. Matter sector

Moving forward, we now parameterize the perturbations of the energy-momentum tensor defined in Eq. (2.14), which can be decomposed as

$$T_\nu^\mu = \bar{T}_\nu^\mu + \delta T_\nu^\mu. \quad (\text{A26})$$

From the normalization condition of the fluid total four velocity we can write

$$\delta u^\mu = \frac{1}{a}(-A, v^i), \quad v^i = \partial^i v + \bar{v}^i \quad (\text{A27})$$

with $\partial_i \bar{v}^i = 0$, as usual. Likewise, the perturbations to the energy density ($\delta\rho$), pressure (δP) and anisotropic stress ($\delta\pi_j^i$) are introduced as follows:

$$\delta T_0^0 = -\delta\rho, \quad (\text{A28a})$$

$$\delta T_i^0 = [\rho(1+w)\gamma_{ij} + \Pi_{ij}](v^j + B^j), \quad (\text{A28b})$$

$$\delta T_0^i = -\rho(1+w)v^i + \gamma^{ij}\delta\pi_{j0}, \quad (\text{A28c})$$

$$\delta T_j^i = \delta P\delta_j^i + \gamma^{il}\delta\pi_{lj} - \Pi_{jk}h^{ki}, \quad (\text{A28d})$$

where B_i and h_{ij} were defined in Eqs. (A19). Special care to the notation is in order here because, as one can check, $\bar{g}^{\mu\lambda}\delta\pi_{\lambda\nu} \neq \delta\pi_\nu^\mu \equiv \bar{g}^{\mu\lambda}\delta\pi_{\lambda\nu} + \Pi_{\lambda\nu}\delta g^{\lambda\mu}$.

We also need to parametrize the perturbed anisotropic stress tensor $\delta\pi_j^i$. From the transversality condition $(u^\mu + \delta u^\mu)(\Pi_{\mu\nu} + \delta\pi_{\mu\nu}) = 0$, we conclude that

$$\delta\pi_{00} = 0, \quad \delta\pi_{0i} = -\Pi_{ij}v^j. \quad (\text{A29})$$

Note however that these conditions do not fix $\delta\pi_{ij}$. We therefore further decompose $\delta\pi_{ij}$ as

$$\delta\pi_{ij} = 2[\pi^T\gamma_{ij} + \partial_i\partial_j\pi^S + \partial_{(i}\pi_{j)}^V + \pi_{ij}^T], \quad (\text{A30})$$

where T in π^T stands for ‘‘trace’’ and where, as usual, we have

$$\partial^i\pi_i^V = 0 = \partial^i\pi_{ij}^T, \quad \pi_i^{Ti} = 0. \quad (\text{A31})$$

Moreover, note that $\bar{g}^{\mu\nu}\delta\pi_{\mu\nu} = -\Pi_{\mu\nu}\delta g^{\mu\nu} \neq 0$, which is why the above decomposition tensor has a trace.

Under the gauge transformation (A21) and using again the appropriate Fourier decomposition, the above variables transform as

$$\delta\rho \rightarrow \delta\rho + \rho'T, \quad (\text{A32a})$$

$$\delta P \rightarrow \delta P + P'T, \quad (\text{A32b})$$

$$v \rightarrow v - \frac{(k^2 L)'}{k^2}, \quad (\text{A32c})$$

$$\bar{v}^i \rightarrow \bar{v}^i - (L^i)' + 2ik^j\sigma_{ij}P^iL. \quad (\text{A32d})$$

These transformations suggest the introduction of the following gauge-invariant variables:

$$\delta\hat{\rho} \equiv \delta\rho + \rho' \left[B - \frac{(k^2 E)'}{k^2} \right], \quad (\text{A33a})$$

$$\delta\hat{P} \equiv \delta P + P' \left[B - \frac{(k^2 E)'}{k^2} \right], \quad (\text{A33b})$$

$$\hat{v} \equiv v + \frac{(k^2 E)'}{k^2}, \quad (\text{A33c})$$

$$\hat{v}^i \equiv \bar{v}^i + \bar{B}^i. \quad (\text{A33d})$$

The perturbed variables in Eq. (A30), on the other hand, do not have simple transformations as above, essentially because there is no simplifying relation between the background tensor $\Pi_{\mu\nu}$ and the wave vector k^i . Using

$$\mathcal{L}_\xi \Pi_{ij} = \Pi'_{ij} T + \Pi_{il} \xi^l_{,j} + \Pi_{jl} \xi^l_{,i},$$

we find that

$$\pi^T \rightarrow \pi^T + \left(-\frac{1}{4} T^{ij} \Pi'_{ij} + \frac{1}{3} \sigma^{ij} \Pi_{ij} \right) T, \quad (\text{A34a})$$

$$\pi^S \rightarrow \pi^S - \frac{3}{4k^2} T^{ij} \Pi'_{ij} T + \Pi_{ij} \hat{k}^i \hat{k}^j L - i \Pi_{ij} \frac{\hat{k}^i}{k} L^j, \quad (\text{A34b})$$

$$\pi_i^V \rightarrow \pi_i^V - \frac{i}{k} P_i^j \hat{k}^l \Pi'_{jl} T + i k P_i^j \Pi_{jl} \hat{k}^l L + P_i^j \Pi_{jl} L^l, \quad (\text{A34c})$$

$$\pi_{ij}^T \rightarrow \pi_{ij}^T + \frac{1}{2} \Lambda_{ij}^{lm} \Pi'_{lm} T, \quad (\text{A34d})$$

where P_{ij} , T_{ij} and Λ_{kl}^{ij} were defined in Eqs. (A10), (A11) and (A12). From the variables above we construct the following new variables:

$$\hat{\pi}^T \equiv \pi^T + \left[-\frac{1}{4} T^{ij} \Pi'_{ij} + \frac{1}{3} \sigma^{ij} \Pi_{ij} \right] \left(B - \frac{(k^2 E)'}{k^2} \right), \quad (\text{A35a})$$

$$\begin{aligned} \hat{\pi}^S \equiv & \pi^S - \frac{3}{4k^2} T^{ij} \Pi'_{ij} \left(B - \frac{(k^2 E)'}{k^2} \right) \\ & - \Pi_{ij} \hat{k}^i \hat{k}^j E + i \Pi_{ij} \frac{\hat{k}^i}{k} E^j, \end{aligned} \quad (\text{A35b})$$

$$\begin{aligned} \hat{\pi}_i^V \equiv & \pi_i^V - \frac{i}{k} P_i^j \hat{k}^l \Pi'_{jl} \left(B - \frac{(k^2 E)'}{k^2} \right) \\ & - i k P_i^j \Pi_{jl} \hat{k}^l E - P_i^j \Pi_{jl} E^l, \end{aligned} \quad (\text{A35c})$$

$$\hat{\pi}_{ij}^T \equiv \pi_{ij}^T + \frac{1}{2} \Lambda_{ij}^{lm} \Pi'_{lm} \left(B - \frac{(k^2 E)'}{k^2} \right), \quad (\text{A35d})$$

which, as one can easily check, are gauge invariant.

c. Gauge choice

From the construction of gauge-invariant variables presented above, it is clear that an enormous simplification will be achieved if we work in a gauge where

$$B = E = 0 = E'. \quad (\text{A36})$$

In this gauge the scalar modes become

$$\begin{aligned} \Phi &= A, & \Psi &= -C, & \delta\hat{\rho} &= \delta\rho, & \delta\hat{P} &= \delta P, \\ \hat{v} &= v, & \hat{\pi}^T &= \pi^T, & \hat{\pi}^S &= \pi^S, \end{aligned} \quad (\text{A37})$$

whereas the vector and tensor variables become

$$\bar{\Phi}_i = \bar{B}_i, \quad \hat{v}_i = \bar{v}_i + \bar{B}_i, \quad \hat{\pi}_i^V = \pi_i^V, \quad \hat{\pi}_{ij}^T = \pi_{ij}^T. \quad (\text{A38})$$

Apart from the spatial velocity \hat{v}_i , in this gauge the gauge-invariant variables coincide with the original potentials. In other words, by working in this gauge the final equations can be trivially (again, apart from \hat{v}_i) replaced with the same equations satisfied by gauge-invariant variables. Note that this choice fixes the gauge completely and is slightly different from the choice made in [22].

3. Perturbed Einstein's equations in Bianchi I

We have now everything needed to obtain the fully mode-projected and gauge-invariant Einstein equations. This is a tedious but straightforward procedure which requires careful computation of time derivatives and the Fourier vectors through the use of Eqs. (A14a)–(A14c). We note that the main difference with the approach followed in Ref. [22] is that the trick below Eq. (3.21) in [22] cannot be used when Π_{ij} is nonzero.

a. Scalar modes

Einstein equations give four equations for the evolution of the scalar modes. The first of them comes from $\delta G_0^0 = \kappa \delta T_0^0$ and is given by

$$\begin{aligned} k^2 \Psi + 3\mathcal{H}(\Psi' + \mathcal{H}\Phi) - \frac{1}{2} \sigma^2 [X - 3\Psi] - \frac{k^2}{2\mathcal{H}} \sigma_{\parallel} \Psi \\ - \frac{1}{2} i k \sum_a \sigma_{V^a} \Phi_a - \frac{1}{4\mathcal{H}} \Psi [(\sigma^2)' + 4\mathcal{H}\sigma^2] \\ + \frac{1}{2} \sum_\lambda \left[E'_\lambda \sigma_{T^\lambda} + 2E_\lambda \sum_{a,b} \sigma_{V^a} \sigma_{V^b} \mathcal{M}_{a,b}^\lambda \right] = -a^2 \frac{\kappa}{2} \delta\rho, \end{aligned} \quad (\text{A39a})$$

where, for simplicity, we have introduced the new variable

$$X \equiv \Psi + \Phi + \left(\frac{\Psi}{\mathcal{H}}\right)'$$

The second scalar equation can be extracted from $\delta G_i^0 = \kappa \delta T_i^0$ by projecting it along the vector \hat{k}^i and is given by $(\sigma')_{\parallel}$

$$\Psi' + \mathcal{H}\Phi - \frac{\sigma_{\parallel}}{2}X + (\sigma^2 - (\sigma')_{\parallel})\frac{\Psi}{2\mathcal{H}} - \frac{1}{2}\sum_{\lambda} E_{\lambda}\sigma_{T^{\lambda}} = -\frac{a^2}{2}\kappa\left[\rho(1+w)v + \Pi_{\parallel}v - \frac{i}{k}\sum_a \Pi_{V^a}v_a\right]. \quad (\text{A40})$$

The third and fourth equations come from trace and traceless parts of $\delta G_j^i = \kappa \delta T_j^i$. They are

$$\begin{aligned} \Psi'' + 2\mathcal{H}\Psi' + \mathcal{H}\Phi' + (2\mathcal{H}' + \mathcal{H}^2)\Phi - \frac{1}{3}k^2(\Phi - \Psi) - \frac{1}{6}\frac{k^2}{\mathcal{H}}\sigma_{\parallel}\Psi + \frac{1}{2}\sigma^2(X - 3\Psi) \\ - \frac{1}{2}\sum_{\lambda}\left(E'_{\lambda}\sigma_{T^{\lambda}} + 2E_{\lambda}\sum_{a,b}\sigma_{V^a}\sigma_{V^b}\mathcal{M}_{ab}^{\lambda}\right) + \frac{1}{2}ik\sum_a\sigma_{V^a}\Phi_a + \frac{\Psi}{4\mathcal{H}}[(\sigma^2)' + 4\mathcal{H}\sigma^2] \\ = a^2\kappa\left[\frac{1}{2}\delta P + \pi^T - \frac{1}{3}k^2\pi^S + \frac{1}{3}\left(\frac{\Psi}{\mathcal{H}}\Pi^{ij}\sigma_{ij} - \sum_{\lambda}E_{\lambda}\Pi_{T^{\lambda}}\right)\right] \end{aligned} \quad (\text{A41a})$$

and

$$\begin{aligned} \frac{2}{3}k^2(\Phi - \Psi) - \sigma_{\parallel}\left[X' - \frac{k^2}{3}\frac{\Psi}{\mathcal{H}}\right] - 2ik\sum_a\sigma_{V^a}\Phi_a - 2X(\sigma')_{\parallel} - \frac{\Psi}{\mathcal{H}}((\sigma')_{\parallel})' + 4\sum_{a,b,\lambda}\sigma_{V^a}\sigma_{V^b}E_{\lambda}\mathcal{M}_{ab}^{\lambda} \\ = a^2\kappa\left[-\frac{4}{3}k^2\pi^S + \frac{\Psi}{\mathcal{H}}\Pi_{\parallel}\sigma_{\parallel} + \frac{8}{3}\frac{\Psi}{\mathcal{H}}\sum_a\Pi_{V^a}\sigma_{V^a} - \frac{2}{3}\frac{\Psi}{\mathcal{H}}\sum_{\lambda}\sigma_{T^{\lambda}}\Pi_{T^{\lambda}} + \frac{2}{3}\sum_{\lambda}E_{\lambda}\Pi_{T^{\lambda}}\right], \end{aligned} \quad (\text{A42a})$$

respectively. Note that, despite the appearance of i factors, these equations are real.

b. Vector modes

The two equations for the vector modes can be obtained through the combinations $e_a^i(\delta G_i^0 - \kappa \delta T_i^0) = 0$ and $\hat{k}_i e_a^j(\delta G_j^i - \kappa \delta T_j^i) = 0$. They are given, respectively, by

$$\Phi_a - \frac{2i}{k}\sigma_{V^a}X + \frac{4i}{k}\sum_{b,\lambda}E_{\lambda}\sigma_{V^b}\mathcal{M}_{ab}^{\lambda} = \frac{-2a^2\kappa}{k^2}\left[\rho(1+w)v_a + ik\Pi_{V^a}v - \frac{1}{2}\Pi_{\parallel}v_a + \sum_{b,\lambda}\mathcal{M}_{ab}^{\lambda}\Pi_{T^{\lambda}}v_b - ik\frac{\Psi}{\mathcal{H}}\Pi_{V^a}\right] \quad (\text{A43a})$$

and

$$\begin{aligned} \Phi'_a + 2\mathcal{H}\Phi_a - \frac{5}{2}\sigma_{\parallel}\Phi_a + \sum_{b,\lambda}\Phi_b\sigma_{T^{\lambda}}\mathcal{M}_{ab}^{\lambda} - \frac{2i}{k}\sigma_{V^a}X' + \frac{2i\Psi}{k\mathcal{H}}\left[3\sigma_{\parallel}(\sigma')_{V^a} - 3\sigma_{V^a}(\sigma')_{\parallel} + 2\sum_{b,\lambda}\mathcal{M}_{ab}^{\lambda}(\sigma_{V^b}(\sigma')_{T^{\lambda}} - \sigma_{T^{\lambda}}(\sigma')_{V^b})\right] \\ + \frac{4i}{k}\sum_{b,\lambda}E_{\lambda}[\mathcal{M}_{ab}^{\lambda}(\sigma')_{V^b} + \mathcal{N}_{ab}\sigma_{V^b}(\sigma_{T^+}\delta_{\lambda}^{\times} - \sigma_{T^{\times}}\delta_{\lambda}^+)] + \frac{4i}{k}\sum_{b,\lambda}E'_{\lambda}\sigma_{V^b}\mathcal{M}_{ab}^{\lambda} \\ - \frac{4i}{k}X(\sigma')_{V^a} - \frac{2i\Psi}{k\mathcal{H}}\left[(\sigma')_{V^a}' - \frac{3\sigma_{\parallel}}{2}(\sigma')_{V^a} - 2\mathcal{H}(\sigma')_{V^a} + \sum_{b,\lambda}\mathcal{M}_{ab}^{\lambda}(\sigma')_{V^b}\right] \\ = \frac{2i}{k}a^2\kappa\left[ik\pi_a^V + 2\Psi\Pi_{V^a} + 2\frac{\Psi}{\mathcal{H}}\left(\sigma_{\parallel}\Pi_{V^a} - \frac{1}{2}\sigma_{V^a}\sigma_{\parallel} + \sum_{b,\lambda}\sigma_{V^b}\Pi_{T^{\lambda}}\mathcal{M}_{ab}^{\lambda}\right)\right]. \end{aligned} \quad (\text{A44a})$$

c. Tensor modes

There is only one dynamical equation for the tensor modes. This equation follows from the projection $\varepsilon_i^{\lambda j}(\delta G_j^i - \kappa \delta T_j^i) = 0$, which gives

$$E_\lambda'' + 2\mathcal{H}E_\lambda' + k^2 E_\lambda - 2E_\lambda \sum_a \sigma_{V^a}^2 - 2E_\lambda \sigma_{T^{(1-\lambda)}}^2 + 2E_{(1-\lambda)} \sigma_{T^+} \sigma_{T^*} - \sigma_{T^\lambda} \left[k^2 \left(\frac{\Psi}{\mathcal{H}} \right) + X' \right] - 2X(\sigma')_{T^\lambda} + 2ik \sum_{a,b} \sigma_{V^b} \Phi_a \mathcal{M}_{ab}^\lambda - \frac{\Psi}{\mathcal{H}} ((\sigma')_{T^\lambda})' = a^2 \kappa \left[2\pi_\lambda^T + \Pi_\parallel E_\lambda - \frac{\Psi}{\mathcal{H}} \left(\sigma_\parallel \Pi_{T^\lambda} + \sigma_{T^\lambda} \Pi_\parallel + \sum_{a,b} \Pi_{V^a} \sigma_{V^b} \mathcal{M}_{ab}^\lambda \right) \right]. \quad (\text{A45a})$$

4. Perturbed fluid equations

The perturbed conservation equation follows from

$$(\delta \nabla_\mu) T_\nu^\mu + \nabla_\mu (\delta T_\nu^\mu) = 0. \quad (\text{A46})$$

Working in the gauge (A36), the time component ($\nu = 0$) of the above expression gives the perturbed continuity equation

$$\begin{aligned} \delta \rho' + \rho(1+w)\nabla^2 v + 3\mathcal{H}(\delta \rho + \delta P) - (\rho + P)3\Psi' \\ = \partial^j \delta \pi_{j0} - \mathcal{H} \gamma^{ij} \delta \pi_{ij} + \mathcal{H} \Pi_{ij} h^{ij} - \sigma_j^i \delta \pi_{il} \gamma^{lj} + \sigma_j^i \Pi_{il} h^{lj} - \frac{1}{2} (h_i^j)' \Pi_j^i, \end{aligned} \quad (\text{A47a})$$

where we recall that h_{ij} was introduced in Eq. (A19). Likewise, the perturbed Euler equation follows from spatial part ($\nu = i$) of Eq. (A46). We find

$$\begin{aligned} \frac{\partial}{\partial \eta} \{ [\rho(1+w)\gamma_{ij} + \Pi_{ij}] v^j \} + \partial_i \delta P + \partial^l \delta \pi_{li} + (1+w)\rho \partial_i \Phi + \Pi_i^j \partial_j \Phi \\ + 4\mathcal{H} \{ [\rho(1+w)\gamma_{ij} + \Pi_{ij}] v^j \} - \Pi_{il} \partial_j h^{lj} + \frac{1}{2} \Pi_i^j \partial_j h_l^i - \frac{1}{2} \Pi^{jk} \partial_i h_{jk} = 0. \end{aligned} \quad (\text{A48a})$$

Despite their generality, the above equations are not very useful since they are implemented in real space. In order to obtain their Fourier counterparts we need to project these equations along the scalar (\hat{k}^i) and vector (e_a^i) modes. This mode extraction procedure is tedious but straightforward and requires special attention to the use of the evolution Eqs. (A14a)–(A14c) of the Fourier wave vectors.

a. Scalar modes

Both continuity and Euler equations lead to conservation equations for the scalar modes. They are given, respectively, by

$$\begin{aligned} \delta' + 3\mathcal{H}[(c_s^2 - w)\delta + \omega\Gamma] - (1+w)(k^2 v + 3\Psi') - \frac{\delta}{\rho} \sigma^{ij} \Pi_{ij} = \frac{1}{\rho} \left\{ \left[\left(\frac{\Psi}{\mathcal{H}} \right)' \sigma_{ij} - \frac{\Psi}{\mathcal{H}} (\sigma_{ij})' \right] \Pi^{ij} \right. \\ \left. + 2a^2 \kappa \frac{\Psi}{\mathcal{H}} \Pi^{ij} \Pi_{ij} - 8\Psi \Pi^{ij} \sigma_{ij} + k^2 \Pi_\parallel v - ik \sum_a \Pi_{V^a} (v_a - \Phi_a) - 6\mathcal{H} \pi^T + 2k^2 \pi^S (\mathcal{H} + \sigma_\parallel) \right. \\ \left. - 2ik \sum_a \sigma_{V^a} \pi_a^V - 2 \sum_\lambda \sigma_{T^\lambda} \pi_\lambda^T - \sum_\lambda E_\lambda (\sigma_{T^\lambda} \Pi_\parallel + \sigma_\parallel \Pi_{T^\lambda}) + \sum_\lambda \Pi_\lambda (2\mathcal{H} E_\lambda - E_\lambda') \right\} \end{aligned} \quad (\text{A49a})$$

and

$$\begin{aligned}
& v' + \mathcal{H}(1 - 3c_s^2)v + \Phi + \frac{1}{1+w} \left[c_s^2 \delta + w\Gamma + \frac{2}{\rho} (\pi^T - k^2 \pi^S) \right] - \frac{2i}{k} \sum_a \sigma_{V^a} v_a - \frac{\sigma^{ij} \Pi_{ij}}{\rho} v \left(\frac{1 + c_s^2}{1+w} \right) \\
&= \frac{-1}{ik(1+w)\rho} \left\{ ik(\Pi_{\parallel} v)' + ik\Pi_{\parallel} \Phi + 4\mathcal{H} \left(ik\Pi_{\parallel} v + \sum_a \Pi_{V^a} v_a \right) + ik\Psi\Pi_{\parallel} \left(\frac{2\sigma_{\parallel}}{\mathcal{H}} - 1 \right) - ik \sum_{\lambda} \Pi_{T^{\lambda}} E_{\lambda} \right. \\
&+ \left(2 \sum_a \Pi_{V^a} \sigma_{V^a} + \Pi^{ij} \sigma_{ij} \right) \frac{ik\Psi}{\mathcal{H}} + \sum_a [(\Pi_{V^a} v_a)' + \sigma_{\parallel} \Pi_{V^a} v_a + 2ik\sigma_{V^a} \Pi_{V^a} v] \\
&\left. - \sum_a \left(\Pi_{\parallel} \sigma_{V^a} v_a + 2 \sum_{b,\lambda} \sigma_{V^a} v_b \mathcal{M}_{ab}^{\lambda} \Pi_{T^{\lambda}} \right) \right\}, \tag{A50a}
\end{aligned}$$

where we have made use of the equation

$$w' = - \left[3\mathcal{H}(1+w) + \frac{\Pi^{ij} \sigma_{ij}}{\rho} \right] (c_s^2 - w) \tag{A51}$$

and of the definition [2]

$$\delta = \frac{\delta\rho}{\rho}, \quad \delta P = c_s^2 \delta\rho + w\rho\Gamma, \tag{A52}$$

where c_s^2 and Γ are the sound speed and the entropy perturbation, respectively.

b. Vector modes

There is only one conservation equation for the vector modes, which follows from the vector projection of Eq. (A50). This equation is given by

$$\begin{aligned}
& v'_a + \mathcal{H}(1 - 3c_s^2)v_a - \frac{k^2 \pi_a^V}{\rho(1+w)} - \frac{\Pi^{ij} \sigma_{ij}}{\rho} \left(\frac{1 + c_s^2}{1+w} \right) v_a - \frac{1}{2} \sigma_{\parallel} v_a + \sum_{b,\lambda} \mathcal{M}_{ab}^{\lambda} \sigma_{T^{\lambda}} v_b \\
&= - \frac{1}{(1+w)\rho} \left[\partial_{\eta} \left(ik\Pi_{V^a} v - \sum_b \mathcal{V}_{ab} v_b \right) - ik \sum_b \mathcal{U}_{ab} \Pi_{V^b} v + \sum_{b,c} \mathcal{U}_{ab} \mathcal{V}_{bc} v_c \right. \\
&\left. + 4\mathcal{H} \left(ik\Pi_{V^a} v - \sum_b \mathcal{V}_{ab} v_b \right) ik\Pi_{V^a} \Phi + ik \left(2 \sum_{\lambda,b} \Pi_{T^{\lambda}} \sigma_{V^b} \mathcal{M}_{ab}^{\lambda} + 2\Pi_{V^a} \sigma_{\parallel} - \Pi_{\parallel} \sigma_{V^a} - \mathcal{H}\Pi_{V^a} \right) \frac{\Psi}{\mathcal{H}} \right], \tag{A53a}
\end{aligned}$$

where we have introduced

$$\mathcal{U}_{ab} \equiv -\sigma_{ij} e_a^i e_b^j, \quad \mathcal{V}_{ab} \equiv -\Pi_{ij} e_a^i e_b^j. \tag{A54}$$

c. Friedmannian limit

It is a straightforward exercise to verify that the above equations have a well-defined Friedman-Lemaître limit. Redefining $\delta\pi_{ij} \rightarrow P\delta\pi_{ij}$ and $\pi^T \rightarrow k^2\pi^S/3$ to compare with Ref. [2], we find immediately that

$$\delta' + 3\mathcal{H}[(c_s^2 - \omega)\delta + \omega\Gamma] = (1+w)(k^2 v + 3\Psi'), \tag{A55a}$$

$$v' + \mathcal{H}(1 - 3c_s^2)v + \Phi = - \frac{c_s^2}{1+w} \delta - \frac{\omega}{1+w} \left[\Gamma - \frac{2}{3} (2k^2 \pi^S) \right], \tag{A55b}$$

$$v'_a + \mathcal{H}(1 - 3c_s^2)v_a = \frac{\omega}{1+w} k^2 \pi_a^V, \tag{A55c}$$

which are the expected equations.

APPENDIX B: PERTURBED GEOMETRIC QUANTITIES

This section gathers the expression of the geometrical quantities at order $\{1, 1\}$, as needed for the computation of this article.

1. Connections

Using the commutators of the tetrad field \underline{c}

$$\gamma^{\underline{c}}_{\underline{a}\underline{b}} \equiv \Theta^{\underline{c}}_{\mu} [\Theta_{\underline{a}}, \Theta_{\underline{b}}]^{\mu}, \quad \gamma_{\underline{c}\underline{a}\underline{b}} \equiv \eta_{\underline{c}\underline{d}} \gamma^{\underline{d}}_{\underline{a}\underline{b}}, \quad (\text{B1})$$

the Ricci rotation coefficients are obtained through

$$\begin{aligned} \omega_{\underline{a}\underline{b}\underline{c}} &\equiv \eta_{\underline{b}\underline{d}} \Theta^{\underline{d}}_{\nu} \Theta_{\underline{a}}^{\mu} \nabla_{\mu} \Theta_{\underline{c}}^{\nu}, \\ \omega_{\underline{a}\underline{b}\underline{c}} &= \frac{1}{2} (\gamma_{\underline{a}\underline{b}\underline{c}} + \gamma_{\underline{c}\underline{b}\underline{a}} - \gamma_{\underline{b}\underline{c}\underline{a}}). \end{aligned} \quad (\text{B2})$$

Up to order $\{1, 1\}$, the commutators are

$$\gamma^0_{\underline{0}\underline{0}} = \gamma^{\underline{i}}_{\underline{0}\underline{0}} = 0, \quad (\text{B3a})$$

$$\gamma^0_{\underline{0}\underline{i}} = -\gamma^{\underline{0}}_{\underline{i}\underline{0}} = \partial_{\underline{i}} \Phi = \partial_{\underline{i}} \Phi - \beta^{\underline{j}}_{\underline{i}} \partial_{\underline{j}} \Phi, \quad (\text{B3b})$$

$$\begin{aligned} \gamma^{\underline{j}}_{\underline{0}\underline{i}} = -\gamma^{\underline{j}}_{\underline{i}\underline{0}} &= -E_{ij}' + \left(\frac{\sigma_{ij}}{\mathcal{H}} \Psi \right)' + \partial_{\underline{i}} \bar{B}_{\underline{j}} \\ &- \sigma_{\underline{i}\underline{j}} (1 - \Phi) + \Psi' \delta_{\underline{i}}^{\underline{j}}, \end{aligned} \quad (\text{B3c})$$

$$\gamma^{\underline{k}}_{\underline{i}\underline{j}} = -2\partial_{[\underline{i}} E_{j]k} + \frac{2}{\mathcal{H}} \partial_{\underline{i}} \Psi \sigma_{\underline{j}k} + 2\partial_{[\underline{i}} \Psi \delta_{\underline{j}]}^{\underline{k}} - 2\beta^{\underline{q}}_{[\underline{i}} \partial_{\underline{q}} \Psi \delta_{\underline{j}]}^{\underline{k}}, \quad (\text{B3d})$$

and the Ricci rotation coefficients are thus

$$\omega_{\underline{0}\underline{0}\underline{i}} = -\omega_{\underline{0}\underline{i}\underline{0}} = -\exp[-\beta]_{ij} \partial_{\underline{j}} \Phi, \quad (\text{B4a})$$

$$\begin{aligned} \omega_{\underline{i}\underline{0}\underline{j}} = -\omega_{\underline{i}\underline{j}\underline{0}} &= \delta_{ij} \Psi' + \left(\frac{\sigma_{ij}}{\mathcal{H}} \Psi \right)' - \sigma_{\underline{i}\underline{j}} (1 - \Phi) \\ &- E'_{ij} + \partial_{\underline{i}} \bar{B}_{\underline{j}}, \end{aligned} \quad (\text{B4b})$$

$$\omega_{\underline{0}\underline{i}\underline{j}} = -\omega_{\underline{0}\underline{j}\underline{i}} = \partial_{\underline{j}} \bar{B}_{\underline{i}}, \quad (\text{B4c})$$

$$\omega_{\underline{i}\underline{j}\underline{k}} = -\omega_{\underline{i}\underline{k}\underline{j}} = 2\delta_{i[k} \partial_{\underline{j}]} \Psi + 2 \frac{\sigma_{i[k} \partial_{\underline{j}]} \Psi}{\mathcal{H}} - 2\partial_{\underline{j}} E_{k]i}. \quad (\text{B4d})$$

2. Riemann and Ricci tensors

We report the Riemann and Ricci tensor components of the metric (4.1), where the overall scale factor a^2 has been removed by a conformal transformation, up to order $\{1, 1\}$. We first give their components in the coordinated basis (with the use of the package xPAND [87]) and then in the tetrad basis $\{\Theta\}$.

In the coordinate basis, the nonvanishing components are given by

$$\begin{aligned} R_{0i0j} &= \gamma_{ij} \Psi'' + \left(\frac{\sigma_{ij}}{\mathcal{H}} \Psi \right)'' + \sigma_{ij} (\Phi' + 2\Psi') - \sigma'_{ij} (1 - 2\Psi) \\ &+ \partial_{\underline{i}} \partial_{\underline{j}} \Phi - E''_{ij} + \partial_{\underline{i}} \bar{B}'_{\underline{j}}, \end{aligned} \quad (\text{B5a})$$

$$\begin{aligned} R_{0ijk} &= 2\gamma_{i[j} \sigma_{k]}^q \partial_{\underline{q}} \Psi - 2\sigma_{i[j} \partial_{\underline{k}]} \varphi - 2 \left[\left(\gamma_{i[j} + \frac{\sigma_{ij}}{\mathcal{H}} \right) \partial_{\underline{k}]} \Psi \right]' \\ &+ \partial_{\underline{i}} \partial_{\underline{j}} \bar{B}_{\underline{k}} + 2\partial_{[\underline{k}} E'_{\underline{j}]}_{\underline{i}}, \end{aligned} \quad (\text{B5b})$$

$$\begin{aligned} R_{ijpq} &= -4\gamma_{[i[p} \sigma_{j]q]} \Psi' + 4 \left(\gamma_{[i[p} + \frac{\sigma_{[ip}}{\mathcal{H}} \right) \partial_{\underline{j}]} \partial_{\underline{q}]} \Psi - \partial_{\underline{q}} \partial_{\underline{j}} E_{ip} \\ &- \partial_{\underline{i}} \partial_{\underline{p}} E_{jq} + \partial_{\underline{p}} \partial_{\underline{j}} E_{iq} + \partial_{\underline{q}} \partial_{\underline{i}} E_{jp}, \end{aligned} \quad (\text{B5c})$$

and

$$R_{00} = 3\Psi'' + \gamma^{ij} \partial_{\underline{j}} \partial_{\underline{i}} \Phi, \quad (\text{B6a})$$

$$R_{0i} = 2\partial_{\underline{i}} \Psi' - \sigma^{\underline{j}}_{\underline{i}} \partial_{\underline{j}} (\Phi + 3\Psi) - \frac{1}{2} \Delta \bar{B}_{\underline{i}} - \left[\frac{\sigma^{\underline{j}}_{\underline{i}} \partial_{\underline{j}} \Psi}{\mathcal{H}} \right]', \quad (\text{B6b})$$

$$\begin{aligned} R_{ij} &= \sigma'_{ij} (1 - 2\Phi - 2\Psi) - \sigma_{ij} (\Phi' + 3\Psi') \\ &+ \gamma_{ij} [\gamma^{kq} \partial_{\underline{q}} \partial_{\underline{k}} \Psi - \Psi''] \\ &+ \partial_{\underline{i}} \partial_{\underline{j}} (\Psi - \Phi) + E''_{ij} - \Delta E_{ij} - \partial_{\underline{i}} \bar{B}'_{\underline{j}} \\ &- \left(\frac{\sigma_{ij} \Psi}{\mathcal{H}} \right)'' + \frac{\sigma_{ij}}{\mathcal{H}} \partial^k \partial_{\underline{k}} \Psi - 2 \frac{\sigma^{\underline{k}}_{\underline{i}}}{\mathcal{H}} \partial_{\underline{j}} \partial_{\underline{k}} \Psi. \end{aligned} \quad (\text{B6c})$$

Projecting using the tetrad (4.6) leads to the components in the tetrad basis

$$\begin{aligned} R_{\underline{0}\underline{i}\underline{0}\underline{j}} &= \delta_{\underline{i}\underline{j}} \Psi'' + \left(\frac{\sigma_{\underline{i}\underline{j}}}{\mathcal{H}} \Psi \right)'' + \sigma_{\underline{i}\underline{j}} (\Phi' + 2\Psi') - \sigma'_{\underline{i}\underline{j}} (1 - 2\Phi) \\ &+ \partial_{\underline{i}} \partial_{\underline{j}} \Phi - E''_{ij} + \partial_{\underline{i}} \bar{B}'_{\underline{j}}, \end{aligned} \quad (\text{B7a})$$

$$\begin{aligned} R_{\underline{0}\underline{i}\underline{j}\underline{k}} &= 2\delta_{\underline{i}[j} \sigma_{\underline{k}]}^q \partial_{\underline{q}} \Psi - 2\sigma_{\underline{i}[j} \partial_{\underline{k}]} \varphi - 2\delta_{\underline{i}[j} \partial_{\underline{k}]} \Psi' \\ &- 2 \left(\frac{\sigma_{\underline{i}[j} \partial_{\underline{k}]} \Psi}{\mathcal{H}} \right)' + \partial_{\underline{i}} \partial_{\underline{j}} \bar{B}_{\underline{k}} + 2\partial_{[\underline{k}} E'_{\underline{j}]}_{\underline{i}}, \end{aligned} \quad (\text{B7b})$$

$$\begin{aligned} R_{\underline{i}\underline{j}\underline{p}\underline{q}} &= -4\delta_{\underline{i}[p} \sigma_{\underline{j]q]} \Psi' + 4(\delta_{\underline{i}[p} + \sigma_{\underline{i}[p} / \mathcal{H}) \partial_{\underline{j}]} \partial_{\underline{q}]} \Psi \\ &- \partial_{\underline{q}} \partial_{\underline{j}} E_{ip} - \partial_{\underline{i}} \partial_{\underline{p}} E_{jq} + \partial_{\underline{p}} \partial_{\underline{j}} E_{iq} + \partial_{\underline{q}} \partial_{\underline{i}} E_{jp}, \end{aligned} \quad (\text{B7c})$$

and

$$R_{\underline{0}\underline{0}} = 3\Psi'' + \partial^{\underline{i}} \partial_{\underline{i}} \Phi, \quad (\text{B8a})$$

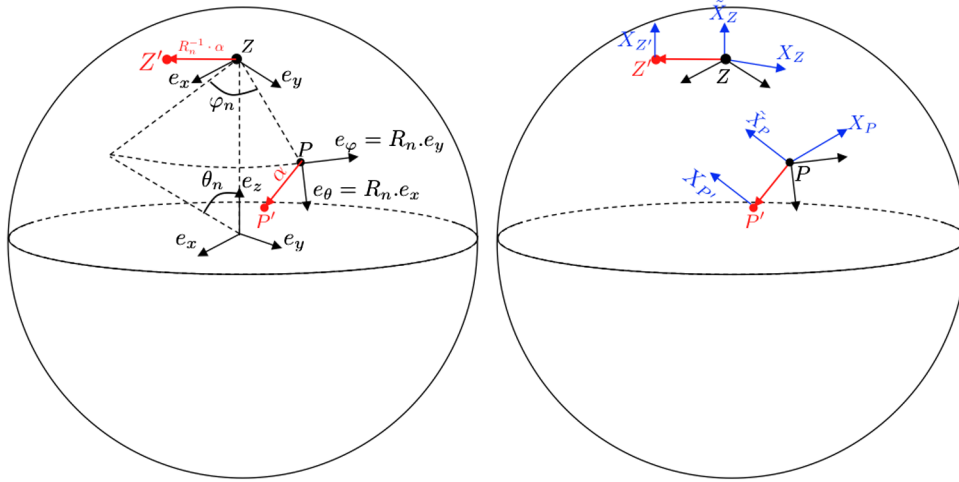


FIG. 3 (color online). The azimuthal point Z is at the azimuthal direction \mathbf{e}_z , while the point P is located in $R_n \cdot \mathbf{e}_z$. Because of lensing the signal observed in P is coming from P' whose location is at $R_{n \times \alpha(n)} \cdot R_n \cdot \mathbf{e}_z$, which corresponds to a covariant transport along α from the point P . As for the point Z' , it is obtained by applying R_n^{-1} on P' meaning that it is located at $R_n^{-1} \cdot R_{n \times \alpha(n)} \cdot R_n \cdot \mathbf{e}_z$. This is equivalent to $R_{\mathbf{e}_z \times [R_n^{-1} \alpha(n)]} \cdot \mathbf{e}_z$ which corresponds to a covariant transport from the point Z , along the vector $R_n^{-1} \alpha(n)$. The lensed field at P (\tilde{X}_P) is obtained by covariantly transporting back along α the unlensed field at P' ($X_{P'}$) by application of $R_{n \times \alpha(n)}^{-1}$, and we get $\tilde{X}_P = (R_{n \times \alpha(n)}^{-1} \cdot X)_{P'}$, and it is in general different from the unlensed field at that point X_P . In order to read the components, everything is transported back into the azimuthal region by application of R_n^{-1} . We get $X_{Z'} \equiv (R_n^{-1} \cdot X)_{Z'}$, $X_Z \equiv (R_n^{-1} \cdot X)_Z$, and $\tilde{X}_Z = (R_n^{-1} \cdot \tilde{X})_Z = (R_n^{-1} \cdot R_{n \times \alpha(n)}^{-1} \cdot X)_Z$. For the latter, there is an alternative expression, which corresponds to covariantly transporting back the field $X_{Z'}$ along $R_n^{-1} \alpha$, and this leads to $\tilde{X}_Z = (R_{\mathbf{e}_z \times [R_n^{-1} \alpha(n)]}^{-1} \cdot R_n^{-1} \cdot X)_Z$, from which the components can be read by projection on the local helicity basis associated with \mathbf{e}_x and \mathbf{e}_y . This is precisely the meaning of Eq. (C8) which is used to compute the components of the lensed field.

$$R_{0\bar{i}} = 2\partial_{\bar{i}}\Psi' - \sigma_{\bar{i}}^j \partial_{\bar{j}}(\Phi + 3\Psi) - \frac{1}{2}\Delta\bar{B}_{\bar{i}} - \left[\frac{\sigma_{\bar{i}}^j \partial_{\bar{j}}\Psi}{\mathcal{H}} \right]', \quad (\text{B8b})$$

$$\begin{aligned} R_{i\bar{j}} &= \sigma'_{i\bar{j}}(1 - 2\Phi) - \sigma_{i\bar{j}}(\Phi' + 3\Psi') + \delta_{i\bar{j}}[\partial^k \partial_{\bar{k}}\Psi - \Psi''] \\ &+ \partial_{\bar{i}}\partial_{\bar{j}}(\Psi - \Phi) + E''_{ij} - \Delta E_{ij} - \partial_{\bar{i}}\bar{B}'_{\bar{j}} \\ &- \left(\frac{\sigma_{i\bar{j}}\Psi}{\mathcal{H}} \right)'' + \frac{\sigma_{i\bar{j}}}{\mathcal{H}}\partial^k \partial_{\bar{k}}\Psi - 2\frac{\sigma_{\bar{i}}^k}{\mathcal{H}}\partial_{\bar{j}}\partial_{\bar{k}}\Psi. \end{aligned} \quad (\text{B8c})$$

APPENDIX C: GLIMPSE ON THE FULL LENSING METHOD

This section details how a tensor field on the sphere X is lensed by a vector field α , the lensing being defined as the result of a parallel transport with respect to this vector field.

First, for any direction on the sphere, there exists a rotation which connects the azimuthal direction with this particular direction \mathbf{n} . If this direction has spherical coordinates (θ, φ) , this is simply

$$\mathbf{n} \equiv R_n \cdot \mathbf{e}_z, \quad R_n = R(\varphi, \theta, 0) = R_z(\varphi) \cdot R_y(\theta) \cdot R_z(0), \quad (\text{C1})$$

where $R(\alpha, \beta, \gamma)$ is a general rotation parameterized by Euler angles. Now, if we want to define the helicity basis at a given direction \mathbf{n} as a result of this rotation applied to the helicity basis at the north pole, we have to face the fact that the helicity basis at the north pole is not well defined, since \mathbf{e}_φ is not defined at this point. We choose that at the north pole $\mathbf{n}^\pm(\mathbf{e}_z) \equiv \frac{1}{\sqrt{2}}(\mathbf{e}_x \mp i\mathbf{e}_y)$, since this ensures that the helicity basis at any point is obtained from the one at the north pole through a rotation, that is,

$$\mathbf{n}^\pm(\mathbf{n}) = R_n \cdot \mathbf{n}^\pm(\mathbf{e}_z). \quad (\text{C2})$$

A spin- s tensor is defined as $X(\mathbf{n}) \equiv X^s(\mathbf{n})\mathbf{m}^s(\mathbf{n}) = [X^s \mathbf{m}^s](\mathbf{n})$. Its components on the polarization basis are simply obtained by projection

$$\begin{aligned} X^s(\mathbf{n}) &= \mathbf{m}^{-s}(\mathbf{n}) \cdot X(\mathbf{n}) = \mathbf{m}^{-s}(\mathbf{e}_z) \cdot [R_n^{-1} \cdot X(\mathbf{n})] \\ &= \mathbf{m}^{-s}(\mathbf{e}_z) \cdot [R_n^{-1} X](\mathbf{e}_z). \end{aligned} \quad (\text{C3})$$

This means that instead of projecting a tensor on the polarization basis at a point \mathbf{n} we can equivalently rotate it so that the point which is initially in \mathbf{n} becomes located on the azimuthal direction. Then we can evaluate its components on the polarization basis at this azimuthal direction.

The azimuthal direction can thus be used as a common reference for all points on the sphere since for each point there is a unique natural rotation to transport from this point to the azimuthal direction.

Let us consider that, due to the lensing vector α , the tensor field we observe in the direction \mathbf{n} is now the result of a parallel transport of the underlying tensor by this vector field α . Such a parallel transport is equivalent to a rotation around the axis $\mathbf{n} \times \alpha$, so that the lensed tensor field is related to the unlensed one by

$$\tilde{X}(\mathbf{n}) \equiv [R_{\mathbf{n} \times \alpha(\mathbf{n})}^{-1} X](\mathbf{n}). \quad (\text{C4})$$

We use the notation $R_{\underline{V}}$ to indicate the rotation defined by the rotation vector \underline{V} . This is the rotation around the axis defined by the vector \underline{V} with an angle obtained from the norm of \underline{V} . It must not be confused with the previous notation $R_{\mathbf{n}}$, which is the rotation that brings the azimuthal direction toward the direction \mathbf{n} . As emphasized previously, the components of the lensed tensor field, as any tensor field, can be obtained by transportation to the azimuthal direction, that is,

$$\tilde{X}^s(\mathbf{n}) = \mathbf{m}^{-s}(\mathbf{n}) \cdot \tilde{X}(\mathbf{n}) = \mathbf{m}^{-s}(\mathbf{e}_z) \cdot [R_{\mathbf{n} \times \alpha(\mathbf{n})}^{-1} R_{\mathbf{n}}^{-1} X](\mathbf{e}_z). \quad (\text{C5})$$

Using the general property of rotations $R_{\mathbf{n}} R_{\underline{V}} R_{\mathbf{n}}^{-1} = R_{\underline{R}_{\mathbf{n}} \cdot \underline{V}}$ leads to

$$R_{\mathbf{n}}^{-1} R_{\mathbf{n} \times \alpha(\mathbf{n})} R_{\mathbf{n}} = R_{\mathbf{e}_z \times [R_{\mathbf{n}}^{-1} \alpha(\mathbf{n})]}, \quad (\text{C6})$$

that is, to

$$R_{\mathbf{n}}^{-1} R_{\mathbf{n} \times \alpha(\mathbf{n})}^{-1} = R_{\mathbf{e}_z \times [R_{\mathbf{n}}^{-1} \alpha(\mathbf{n})]}^{-1} R_{\mathbf{n}}^{-1}, \quad (\text{C7})$$

which can be used to recast Eq. (C5) as

$$\tilde{X}^s(\mathbf{n}) = \mathbf{m}^{-s}(\mathbf{e}_z) \cdot [R_{\mathbf{e}_z \times [R_{\mathbf{n}}^{-1} \alpha(\mathbf{n})]}^{-1} R_{\mathbf{n}}^{-1} X](\mathbf{e}_z). \quad (\text{C8})$$

This can be understood easily once we extract the helicity components of the lensing vector. Indeed, the helicity basis components of the lensing vector field are obtained just like for any vector field as $\alpha^\pm(\mathbf{n}) = \mathbf{n}^\mp(\mathbf{n}) \cdot \alpha(\mathbf{n}) = \frac{1}{\sqrt{2}}(\mathbf{e}_x \mp i\mathbf{e}_y) \cdot [R_{\mathbf{n}}^{-1} \alpha(\mathbf{n})]$. If we define

$$\alpha_x = \frac{1}{\sqrt{2}}(\alpha_+ + \alpha_-), \quad \alpha_y = \frac{i}{\sqrt{2}}(\alpha_+ - \alpha_-), \quad (\text{C9a})$$

$$\alpha_x = \alpha_\theta \cos \alpha_\varphi, \quad \alpha_y = \alpha_\theta \sin \alpha_\varphi, \quad (\text{C9b})$$

where (α_x, α_y) are the components of the lensing field once transported to the azimuthal direction and $(\alpha_\theta, \alpha_\varphi)$ their associated polar components, we obtain that

$$R_{\mathbf{e}_z \times [R_{\mathbf{n}}^{-1} \alpha(\mathbf{n})]} = R(\alpha_\varphi, \alpha_\theta, -\alpha_\varphi). \quad (\text{C10})$$

This means that instead of lensing the tensor field at the point \mathbf{n} and subsequently extracting the component, it is equivalent to transport both the field and the lensing vector at the azimuthal direction with $R_{\mathbf{n}}^{-1}$ and then let the transported lensing vector act on the transported tensor field. This procedure is explained graphically in Fig. 3.

With this crucial result at hand, we just need to compose the rotations of Eq. (C8) in order to obtain the components of the lensed field in terms of the multipole components of the unlensed tensor field. Using the general transformation law (D16), we get

$$\tilde{X}^s(\mathbf{n}) = \sum_{\ell m m'} Y_{\ell m'}^s(\mathbf{e}_z) D_{m' m'}^\ell [R^{-1}(\alpha_\varphi, \alpha_\theta, -\alpha_\varphi)] D_{m' m}^\ell \times [R_{\mathbf{n}}^{-1}] X_{\ell m}^s \quad (\text{C11a})$$

$$= \sum_{\ell m m'} (-1)^s \sqrt{\frac{2\ell+1}{4\pi}} D_{-s m'}^\ell [R^{-1}(\alpha_\varphi, \alpha_\theta, -\alpha_\varphi)] D_{m' m}^\ell \times [R_{\mathbf{n}}^{-1}] X_{\ell m}^s \quad (\text{C11b})$$

$$= \sum_{\ell m m'} e^{is\alpha_\varphi} Y_{\ell m'}^s(\alpha_\theta, \alpha_\varphi) D_{m' m}^\ell [R_{\mathbf{n}}^{-1}] X_{\ell m}^s, \quad (\text{C11c})$$

where it is understood that the components $(\alpha_\theta, \alpha_\varphi)$ correspond to the lensing vector field at the position \mathbf{n} considered, and these should be obtained from the definitions (C9).

From this relation between a tensor acting as a source for an observable and its lensed version due to the geodesic structure between the source and the observer, it is possible in principle to obtain the correlations functions (see e.g., Ref. [77] for the case of CMB lensing). A simplification can be obtained by expanding the spherical harmonics in a small angle approximation. Indeed, very close to the azimuthal direction, the spin-weighted spherical harmonics are approximated by

$$Y_{\ell m}^s(\theta, \varphi) \simeq (-1)^m \sqrt{\frac{2\ell+1}{4\pi}} e^{im\varphi} J_{m+s}[(\ell+1/2)\theta], \quad (\text{C12})$$

and given that $J_{m+s}(x)$ behaves like x^{m+s} when $x \rightarrow 0$ there is a natural way to expand Eq. (C11) in powers of the lensing angle. More details can be found in Ref. [77].

APPENDIX D: MATHEMATICAL TOOLBOX

1. From Cartesian to spherical derivatives

In this section D_i refers to the covariant derivative on the unit sphere in Cartesian coordinates, that is, $D_i^{\mathbb{R}^3}$ defined in Eq. (4.10). The key relation to derive all the

decompositions from Cartesian derivatives ∂_i to radial and covariant spherical derivatives is the simple relation

$$r\partial_i\hat{x}_j = S_{ij}, \quad (\text{D1})$$

which is just the statement that the extrinsic curvature on a unit sphere is equal to the metric on this sphere. For a scalar, a projected vector and a projected tensor, we have

$$\partial_i\varphi = \frac{D_i\varphi}{r} + \varphi_{,r}\hat{x}_i, \quad (\text{D2a})$$

$$\partial_i\tilde{B}_j = \frac{D_i\tilde{B}_j}{r} + (\tilde{B}_j)_{,r}\hat{x}_i - \frac{\hat{x}_j}{r}\tilde{B}_i, \quad (\text{D2b})$$

$$\partial_i\tilde{E}_{jk} = \frac{D_i\tilde{E}_{jk}}{r} + (\tilde{E}_{jk})_{,r}\hat{x}_i - \frac{\hat{x}_j}{r}\tilde{E}_{ik} - \frac{\hat{x}_k}{r}\tilde{E}_{ji}, \quad (\text{D2c})$$

where we use the notation $X_{,r} \equiv \hat{x}^i\partial_i X$ for the radial derivative. Note that this radial derivative and the covariant derivative on the unit sphere D_i commute, as they are just the geometric versions of derivatives in spherical coordinates.

Iterating these relations we obtain for scalar perturbations

$$\partial_i\partial_j\varphi = 2\hat{x}_{(i}D_{j)}\left(\frac{\varphi}{r}\right)_{,r} + \frac{D_iD_j\varphi}{r^2} + \varphi_{,rr}\hat{x}_i\hat{x}_j + S_{ij}\frac{\varphi_{,r}}{r}, \quad (\text{D3a})$$

$$S^{ij}\partial_i\partial_j\varphi = \frac{D_iD^i\varphi}{r^2} + 2\frac{\varphi_{,r}}{r}, \quad (\text{D3b})$$

$$P[\hat{x}^j\partial_i\partial_j\varphi] = D_i\left(\frac{\varphi}{r}\right)_{,r}, \quad (\text{D3c})$$

$$D_i\varphi_{,r} = (D_i\varphi)_{,r}, \quad (\text{D3d})$$

$$S_i^p S_j^q \partial_k \partial_p \partial_q \varphi = \frac{2}{r} S_{k(j} D_{i)} \left(\frac{\varphi}{r}\right)_{,r} + S_{ij} \partial_k \left(\frac{\varphi_{,r}}{r}\right) + \partial_k \left(\frac{D_i D_j \varphi}{r^2}\right), \quad (\text{D3e})$$

$$\hat{x}^k S_i^p S_j^q \partial_k \partial_p \partial_q \varphi = \left(\frac{D_i D_j \varphi}{r^2}\right)_{,r} + S_{ij} \left(\frac{\varphi_{,r}}{r}\right)_{,r}, \quad (\text{D3f})$$

$$S_k^r S_i^p S_j^q \partial_r \partial_p \partial_q \varphi = \frac{2}{r} S_{k(j} D_{i)} \left(\frac{\varphi}{r}\right)_{,r} + S_{ij} D_k \left(\frac{\varphi_{,r}}{r^2}\right) + \left(\frac{D_k D_i D_j \varphi}{r^3}\right). \quad (\text{D3g})$$

As for vectors and tensor, the useful relations are

$$\hat{x}^i \hat{x}^j \partial_k \partial_l E_{ij} = \partial_k \partial_l E_r - \frac{4\partial_{(k}\tilde{E}_{l)}}{r} + \frac{2\tilde{E}_{kl}}{r^2} - \frac{2S_{kl}E_r}{r^2} - 2\tilde{E}_{(k}\hat{x}_{l)}, \quad (\text{D4a})$$

$$\hat{x}^l \partial_i \partial_j B_l = \frac{D_i D^i B_r}{r^2} - \frac{2D^i \tilde{B}_i}{r^2} + (B_r)_{,rr} + 2\frac{(B_r)_{,r}}{r} - \frac{2B_r}{r^2}. \quad (\text{D4b})$$

Finally, using the fact that the vector modes are transverse and that the tensor modes are transverse and traceless, we get

$$B_i \equiv \tilde{B}_i + \hat{x}_i B_r, \quad (\text{D5a})$$

$$D^i \tilde{B}_i = -2B_r - r(B_r)_{,r}, \quad (\text{D5b})$$

$$E_{ij} \equiv \tilde{E}_{ij} + 2\tilde{E}_{(i}\hat{x}_{j)} + E_r \hat{x}_i \hat{x}_j, \quad (\text{D5c})$$

$$S^{ij} \tilde{E}_{ij} = -E_r = 0, \quad (\text{D5d})$$

$$D^i \tilde{E}_i = -3E_r - r(E_r)_{,r}, \quad (\text{D5e})$$

$$D^i \tilde{E}_{ij} = -3\tilde{E}_j - r(\tilde{E}_j)_{,r}. \quad (\text{D5f})$$

2. Spin-weighted spherical harmonics

Spin-weighted spherical harmonics are defined in terms of Wigner D matrices as [88]

$$Y_{\ell m}^s(\alpha, \beta) = \sqrt{\frac{2\ell+1}{4\pi}} (-1)^m e^{is\gamma} D_{-ms}^{\ell}(\alpha, \beta, \gamma) \quad (\text{D6a})$$

$$= \sqrt{\frac{2\ell+1}{4\pi}} (-1)^m D_{-ms}^{\ell}(\alpha, \beta, 0) \quad (\text{D6b})$$

$$= (-1)^{m+s} Y_{\ell, -m}^{-s*}(\alpha, \beta), \quad (\text{D6c})$$

where α, β and γ are the Euler angles. Wigner D matrices are in turn defined in terms of infinitesimal generators of three-dimensional rotations as [89]

$$D_{m_1 m_2}^{\ell} = \langle \ell m_1 | U(R) | \ell m_2 \rangle, \quad \text{where} \\ U(\alpha, \beta, \gamma) = e^{-i\alpha J_z} e^{-i\beta J_y} e^{-i\gamma J_z}. \quad (\text{D7})$$

In the special case in which the direction is aligned with the z axis we have

$$Y_{\ell m}^{-s}(\mathbf{e}_z) = \delta_{ms} (-1)^m \sqrt{\frac{2\ell+1}{4\pi}}. \quad (\text{D8})$$

Under the parity transformation

$$\alpha \rightarrow \alpha + \pi, \quad \beta \rightarrow \pi - \beta, \quad \gamma \rightarrow \gamma + \pi,$$

the spherical harmonics and Wigner D matrices transform as

$$Y_{\ell m}(\alpha, \beta) \rightarrow (-1)^\ell Y_{\ell m}(\alpha, \beta), \quad (\text{D9})$$

$$\begin{aligned} D_{mm'}^\ell(\alpha, \beta, \gamma) &\rightarrow (-1)^{\ell+m} D_{-mm'}^\ell(\alpha, \beta, \gamma) \\ &= (-1)^{\ell+m'} D_{m,-m'}^\ell(\alpha, \beta, \gamma). \end{aligned} \quad (\text{D10})$$

In particular, it follows that under parity transformation the spin-weighted spherical harmonics behaves as

$$Y_{\ell m}^s(\alpha, \beta) \rightarrow (-1)^\ell Y_{\ell m}^{-s}(\alpha, \beta). \quad (\text{D11})$$

3. Rotation of fields on the sphere

The transformation of the spherical harmonics is given by

$$\begin{aligned} [RY_{\ell m}](\mathbf{n}) &\equiv Y_{\ell m}(R^{-1}\mathbf{n}) = \sum_{m'} \langle \mathbf{n} | \ell m' \rangle \langle \ell m' | R | \ell m \rangle \\ &= \sum_{m'} Y_{\ell m'}(\mathbf{n}) D_{m'm}^\ell(R), \end{aligned} \quad (\text{D12})$$

where the first equality is the definition of the transformation of a function on a sphere under a rotation. For a scalar field on the sphere, we can deduce the transformation of its multipolar components of its expansion in spherical harmonics:

$$X(\mathbf{n}) = \sum_{\ell m} X_{\ell m} Y_{\ell m}(\mathbf{n})$$

to be

$$[RX](\mathbf{n}) = X(R^{-1}\mathbf{n}) = \sum_{\ell mm'} Y_{\ell m'}(\mathbf{n}) D_{m'm}^\ell(R) X_{\ell m} \quad (\text{D13})$$

so that

$$[RX]_{\ell m'} = \sum_m D_{m'm}^\ell(R) X_{\ell m}. \quad (\text{D14})$$

The rotation of a tensor field on the sphere is very similar. Once it is broken down into symmetric traceless tensors, then, by using that such tensors are decomposed as $\mathbf{X}(\mathbf{n}) \equiv X^{\pm s}(\mathbf{n}) \mathbf{m}^{\pm s}(\mathbf{n}) = [X^{\pm s} \mathbf{m}^{\pm s}](\mathbf{n})$, it can be expanded in spin-weighted spherical harmonics as

$$\mathbf{X}(\mathbf{n}) = \sum_{\ell m} [X_{\ell m}^{+s} Y_{\ell m}^{+s}(\mathbf{n}) \mathbf{m}^{+s}(\mathbf{n}) + X_{\ell m}^{-s} Y_{\ell m}^{-s}(\mathbf{n}) \mathbf{m}^{-s}(\mathbf{n})]. \quad (\text{D15})$$

Under a rotation, it transforms as (see Appendix A of Ref. [85])

$$\begin{aligned} [RX](\mathbf{n}) &= R \cdot \mathbf{X}(R^{-1}\mathbf{n}) \\ &= \sum_{\ell mm'} Y_{\ell m'}^{\pm s}(\mathbf{n}) D_{m'm}^\ell(R) X_{\ell m}^{\pm s} \mathbf{m}^{\pm s}(\mathbf{n}), \end{aligned} \quad (\text{D16})$$

that is,

$$[RX]_{\ell m'}^{\pm s} = D_{m'm}^\ell(R) X_{\ell m}^{\pm s}. \quad (\text{D17})$$

We remark that it is exactly the same transformation law as for scalar fields because we have transformed the full tensor field $X^{\pm s}(\mathbf{n}) \mathbf{m}^{\pm s}(\mathbf{n})$ and not just its component $X^{\pm s}(\mathbf{n})$ considered as a scalar function, for which the transformation law is more complicated [85].

4. Wigner $3j$ symbols

The $3j$ symbols satisfy the following properties:

$$\begin{aligned} \begin{pmatrix} \ell_1 & \ell_2 & \ell_3 \\ m_1 & m_2 & m_3 \end{pmatrix} &= \begin{pmatrix} \ell_2 & \ell_3 & \ell_1 \\ m_2 & m_3 & m_1 \end{pmatrix} = \begin{pmatrix} \ell_3 & \ell_1 & \ell_2 \\ m_3 & m_1 & m_2 \end{pmatrix} \\ &= (-1)^{\ell_1 + \ell_2 + \ell_3} \begin{pmatrix} \ell_1 & \ell_3 & \ell_2 \\ m_1 & m_3 & m_2 \end{pmatrix} \\ &= (-1)^{\ell_1 + \ell_2 + \ell_2} \begin{pmatrix} \ell_1 & \ell_2 & \ell_3 \\ -m_1 & -m_2 & -m_2 \end{pmatrix}. \end{aligned}$$

Moreover, they are identically zero whenever any of the following conditions are violated:

$$\begin{aligned} m_1 + m_2 + m_3 &= 0, & |\ell_i - \ell_j| &\leq \ell_k \leq \ell_i + \ell_j, \\ \{i, j, k\} &= \{1, 2, 3\}. \end{aligned}$$

They are also orthogonal in the sense that

$$\sum_{m_1, m_2} \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ m_1 & m_2 & m \end{pmatrix} \begin{pmatrix} \ell_1 & \ell_2 & \ell' \\ m_1 & m_2 & m' \end{pmatrix} = \frac{1}{2\ell + 1} \delta_{\ell\ell'} \delta_{mm'} \quad (\text{D18})$$

and that

$$\begin{aligned} \sum_{\ell, m} (2\ell + 1) \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ m_1 & m_2 & m \end{pmatrix} \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ m'_1 & m'_2 & m \end{pmatrix} \\ = \delta_{m_1 m'_1} \delta_{m_2 m'_2}. \end{aligned} \quad (\text{D19})$$

Since Eq. (D19) holds for any set $\{m_1, m'_1, m_2, m'_2\}$, two important cases follow from this expression. First, consider the case where $m_2 = -m_1$ and $m'_2 = -m'_1$. Then, using the selection rule $m_1 + m_2 + m = 0$, it follows that

$$\sum_{\ell} (2\ell + 1) \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ m_1 & -m_1 & 0 \end{pmatrix} \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ m'_1 & -m'_1 & 0 \end{pmatrix} = \delta_{m_1 m'_1}. \quad (\text{D20})$$

Second, note that if we further impose that $m_1 = m'_1 = 0$, then

$$\sum_{\ell} (2\ell + 1) \begin{pmatrix} \ell_1 & \ell_2 & \ell \\ 0 & 0 & 0 \end{pmatrix}^2 = 1. \quad (\text{D21})$$

Another useful expression is

$$\begin{pmatrix} \ell_1 & \ell_2 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \delta_{\ell_1 \ell_2} \frac{1}{\sqrt{2\ell_1 + 1}}. \quad (\text{D22})$$

A recurrent expression when dealing with deviations of isotropy is the integral of three spherical harmonics, also known as the Gaunt integral, and defined as

$$\int d^2\Omega Y_{\ell_1 m_1}^{s_1}(\hat{\mathbf{n}}) Y_{\ell_2 m_2}^{s_2}(\hat{\mathbf{n}}) Y_{\ell_3 m_3}^{s_3}(\hat{\mathbf{n}}) = \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)(2\ell_3 + 1)}{4\pi}} \begin{pmatrix} \ell_1 & \ell_2 & \ell_3 \\ -s_1 & -s_2 & -s_3 \end{pmatrix} \begin{pmatrix} \ell_1 & \ell_2 & \ell_3 \\ m_1 & m_2 & m_3 \end{pmatrix}. \quad (\text{D23})$$

Note that, due to the symmetries of $3j$ symbols and the properties of spin-weighted spherical harmonics under complex conjugation, the coefficients ${}^s C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3}$ defined in Eq. (5.12) satisfy the following properties:

$$-s C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} = (-1)^{\ell_1 + \ell_2 + \ell_3} {}^s C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} = {}^s C_{\ell_1 \ell_2 \ell_3}^{-m_1 -m_2 -m_3}. \quad (\text{D24})$$

From the definitions (D23), (5.12) and the closure relation of spherical harmonics one can also verify that

$$Y_{\ell_2 m_2}(\mathbf{n}) Y_{\ell_3 m_3}^s(\mathbf{n}) = \sum_{\ell_1, m_1} {}^s C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} Y_{\ell_1 m_1}^s(\mathbf{n}), \quad (\text{D25})$$

an identity which is needed in order to derive Eq. (5.16).

Let us also define a useful integral for the gradient expansion approach of lensing by

$${}_{\pm s} I_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} \equiv \int d^2\Omega [D^a Y_{\ell_1 m_1}^{\pm s*}(\hat{\mathbf{n}})] Y_{\ell_2 m_2}(\hat{\mathbf{n}}) [D_a Y_{\ell_3 m_3}^{\pm s}(\hat{\mathbf{n}})], \quad (\text{D26})$$

where the polarization basis is voluntarily omitted for a simpler notation. It has the useful property inherited from Eq. (D24)

$${}_{\pm s} I_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} = (-1)^{\ell_1 + \ell_2 + \ell_3} {}_{\mp s} I_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3}. \quad (\text{D27})$$

Its expression can be found using

$${}_{\pm s} I_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} = \frac{1}{2} [\ell_2(\ell_2 + 1) + \ell_3(\ell_3 + 1) - \ell_1(\ell_1 + 1)] \int d^2\Omega Y_{\ell_1 m_1}^{\pm s*}(\hat{\mathbf{n}}) Y_{\ell_2 m_2}(\hat{\mathbf{n}}) Y_{\ell_3 m_3}^{\pm s}(\hat{\mathbf{n}}) \quad (\text{D28})$$

$$= \frac{1}{2} [\ell_2(\ell_2 + 1) + \ell_3(\ell_3 + 1) - \ell_1(\ell_1 + 1)] {}_{\pm s} C_{\ell_1 \ell_2 \ell_3}^{m_1 m_2 m_3} \quad (\text{D29})$$

$$= {}_{\pm s} F_{\ell_1 \ell_2 \ell_3} \begin{pmatrix} \ell_1 & \ell_2 & \ell_3 \\ -m_1 & m_2 & m_3 \end{pmatrix} (-1)^{m_1 + s}, \quad (\text{D30})$$

where, following Ref. [84], we defined the symbols

$${}_s F_{\ell \ell_1 \ell_2} \equiv \frac{1}{2} [\ell_1(\ell_1 + 1) + \ell_2(\ell_2 + 1) - \ell(\ell + 1)] \sqrt{\frac{(2\ell + 1)(2\ell_1 + 1)(2\ell_2 + 1)}{4\pi}} \begin{pmatrix} \ell & \ell_1 & \ell_2 \\ s & 0 & -s \end{pmatrix}. \quad (\text{D31})$$

In particular we have

$${}_2F_{\ell 2\ell+1} = (\ell + 4) \sqrt{\frac{5(2\ell + 1)(2\ell + 3)}{4\pi}} \begin{pmatrix} \ell & 2 & \ell + 1 \\ 2 & 0 & -2 \end{pmatrix} = (-1)^\ell (\ell + 4) \sqrt{\frac{15}{\pi}} \sqrt{\frac{(\ell + 3)(\ell - 1)}{\ell(\ell + 1)(\ell + 2)}},$$

$${}_2F_{\ell 2\ell-1} = (3 - \ell) \sqrt{\frac{5(2\ell + 1)(2\ell - 1)}{4\pi}} \begin{pmatrix} \ell & 2 & \ell - 1 \\ 2 & 0 & -2 \end{pmatrix} = (-1)^\ell (\ell - 3) \sqrt{\frac{15}{\pi}} \sqrt{\frac{(\ell + 2)(\ell - 2)}{\ell(\ell + 1)(\ell - 1)}}.$$

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