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Membranes with a symmetry of cohomogeneity one

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We study the dynamics of the Nambu-Goto membranes with cohomogeneity one symmetry, i.e., the membranes whose trajectories are foliated by homogeneous surfaces. It is shown that the equation of motion reduces to a geodesic equation on a certain manifold, which is constructed from the original spacetime and Killing vector fields thereon. A general method is presented for classifying the symmetry of cohomogeneity one membranes in a given spacetime. The classification is completely carried out in Minkowski spacetime. We analyze one of the obtained classes in depth and derive an exact solution.

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I. INTRODUCTION

Extended objects came out recently in various areas of physics: topological defects in field theories and in condensed matter physics, and branes in string theories. In cosmology, topological defects such as cosmic strings and domain walls are supposed to have formed in the early universe. In the brane-world universe models, the universe itself is an extended object embedded in a bulk space [1]. Recently, configurations of extended objects in black hole spacetimes are also of growing importance in discussions of the strong coupling regime of gauge theories through gauge/gravity duality [2].

Extended objects, compared with particles, have a wide variety of motion. For example, in Minkowski spacetime, a free particle moves with a constant velocity so that its only possible trajectories are timelike straight lines. On the other hand, the trajectories of a string can be two-dimensional timelike surfaces with various deformations. It is of fundamental importance to clarify the possible motion of extended objects in a given spacetime. However, we do not know much because the equations of motion (EOM) are difficult to solve; the EOM for extended objects are partial differential equations (ODEs) while those for particles are ordinary differential equations (ODEs). Even in the case of strings, where EOM are written as PDEs of two dimensions, we cannot solve EOM except for a few cases such as the Nambu-Goto strings in Minkowski spacetime, where the EOM are reduced to wave equations in two dimensions with constraint equations.

A way to make the EOM tractable is to assume symmetry. The trajectory of an extended object, which we call world volume, is a submanifold embedded in the spacetime manifold \mathcal{M} . Assuming symmetry on the geometry of the world volume, we can simplify the EOM. In particular, in the case when the cohomogeneity one symmetry exists, the EOM are reduced to ODEs. Examples are seen in stationary strings [3–9] and branes [10], and cohomogeneity one strings [11–15].

A cohomogeneity one world volume Σ of m dimensions is foliated by (m-1)-dimensional orbits of a group Gwhich consists of isometries of \mathcal{M} . It is apparent that Σ is homogeneous along the (m-1)-dimensional orbits. For a cohomogeneity one string, its two-dimensional world volume is foliated by one-dimensional orbits of G, so that the group G is one dimensional, and hence there is no variety on the structure of G. For higher dimensional cohomogeneity one objects, the structures of the groups G which act on the homogeneous orbits have a richer variety. For example, in the case of two-dimensional groups, Abelian and non-Abelian groups can act on the orbits.

For cohomogeneity one strings, the Nambu-Goto equation is reduced to the geodesic equations on the orbit space, \mathcal{M}/G . The metric \tilde{h} which appears in the geodesic equations is clearly identified as the one of the form $\tilde{h} = |\boldsymbol{\xi}|h$, where *h* is the metric determined by the requirement that the projection $\mathcal{M} \to \mathcal{M}/G$, which identifies the points on each orbit of *G*, be a Riemannian submersion, and $|\boldsymbol{\xi}|$ is the norm of the Killing vector $\boldsymbol{\xi}$ generating the group

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G [11]. The clarification of the metric structure in relation to G makes it possible to study the integrability of the geodesic equations. The present authors found exact solutions for all of the cohomogeneity one strings in Minkowski spacetime [13].

For higher dimensional cohomogeneity one objects, we may also expect the reduction of the Nambu-Goto equation to the geodesic equations. In the case that G is Abelian, Kubiznak *et al.* showed that the reduction of the equations of motion occurs in the higher dimensional Kerr-NUT-(A) dS spacetime [10]. However, it is not clear that the same reduction occurs in general. The structure of the metric which appears in the geodesic equations is not deeply understood.

In this paper, we study cohomogeneity one membranes, that is, (2+1)-dimensional world volumes embedded in the spacetime, and we give a general formulation of reducing their Nambu-Goto equations to a geodesic problem on the orbit space. We also give a thorough classification of the cohomogeneity one membranes in Minkowski spacetime. A careful treatment is necessary in the classification because different symmetry groups G, which are subgroups of the isometry group of the spacetime \mathcal{M} , could give essentially the same solution to the Nambu-Goto equation. For example, in Minkowski spacetime, a subgroup acting on the x-y plane and another acting on the y-z plane should be identified because the orbits are equivalent geometrically. This identification is achieved by an isometry, a rotation around the y axis, which maps the one plane to the other. Using identification by isometries, we can classify isometry subgroups in a given spacetime. After the classification of the subgroups in Minkowski spacetime, we choose one subgroup for a cohomogeneity one membrane, as an example, and give solutions to the EOM.

In the next section, we show that the Nambu-Goto equations for the cohomogeneity one membranes are reduced to the geodesic equations in the orbit space. The structure of the metric used in the geodesic equations is also clarified. In Sec. III, we discuss the classification of cohomogeneity one symmetry for membranes. As an example, we carry out the classification in Minkowski spacetime in Sec. IV. After the classification, we take a particular cohomogeneity one symmetry and solve the Nambu-Goto equations in Sec. V. Finally, we summarize and discuss the results in Sec. VI.

II. REDUCTION OF EQUATIONS OF MOTION OF COHOMOGENEITY ONE MEMBRANES

We shall give a general formulation for reducing the Nambu-Goto equations of cohomogeneity one membranes. We first give a setup for cohomogeneity one membranes. There exist two cases, where the action of the symmetry group G on the orbits is simply or multiply transitive. Then

we present the method of reducing the equations of motion in each case.

A membrane has a trajectory which is a threedimensional surface embedded in a spacetime manifold \mathcal{M} . Let Isom \mathcal{M} be the isometry group of \mathcal{M} . A membrane is cohomogeneity one if its world volume Σ is foliated by two-dimensional orbits of a subgroup G of Isom \mathcal{M} . We assume that the orbits are non-null. Let π be the projection $\mathcal{M} \to \mathcal{M}/G$ which identifies the points on each orbit of G in \mathcal{M} . By the projection π , the spacetime manifold \mathcal{M} is reduced to the orbit space \mathcal{M}/G , and the world volume Σ of cohomogeneity one membrane is reduced to a curve C in \mathcal{M}/G . Thus the world volume Σ is given as a preimage $\pi^{-1}(\mathcal{C})$ and is completely determined by the curve \mathcal{C} . In the following subsections, we will show that the curve C is a geodesic on \mathcal{M}/G , endowed with an appropriate metric, when the membrane is governed by the Nambu-Goto action.

Before proceeding, let us discuss the dimensionality of *G*. The action of *G* on the orbits may be simply transitive or multiply transitive. In the simply transitive case, the isotropy subgroups are trivial and the dimensionality of *G* is equal to that of the orbits, dim G = 2. In the multiply transitive case, *G* includes a nontrivial isotropy subgroup, so that dim G > 2. On the other hand, the maximal dimensionality of the isometry group acting on a two-dimensional surface is three, then we have dim G = 3, and each orbit is a space of constant curvature.

A. The case dim G = 2

Let (ξ_1, ξ_2) be a pair of Killing vectors which are generators of $G \subset \text{Isom } \mathcal{M}$. The Killing vectors $\xi_I(I = 1, 2)$ are tangent to the orbits and constitute a basis of the Lie algebra \mathfrak{g} of G. It is known that there are only two distinct two-dimensional Lie algebras, commutative and noncommutative. With an appropriate choice of the basis (ξ_1, ξ_2) , the Lie bracket is given by

$$[\boldsymbol{\xi}_1, \boldsymbol{\xi}_2] = \begin{cases} 0 & (\boldsymbol{\mathfrak{g}} \text{ is commutative}) \\ \boldsymbol{\xi}_1 & (\boldsymbol{\mathfrak{g}} \text{ is noncommutative}). \end{cases}$$
(1)

For commutative g's, it was shown that the Nambu-Goto equations in a particular spacetime are reduced to the geodesic equations [10]. It has not been known whether such a reduction is possible for noncommutative g's. In the following, we show that this is also true.

1. Coordinate system in \mathcal{M}

We shall provide \mathcal{M} with a coordinate system by making use of the group action of G on \mathcal{M} . First, we consider a two-dimensional surface S_0 such that each orbit of Gintersects with S_0 once. Introducing a coordinate system (x^1, x^2) on S_0 , we can specify the orbit by the point (x^1, x^2) of intersection with S_0 , which we will denote by $\mathcal{O}_{(x^1, x^2)}$ (see Fig. 1).

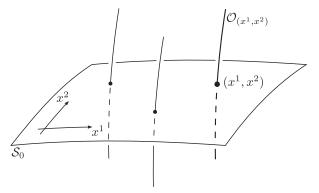


FIG. 1. The surface S_0 and the orbits of *G*. The orbits are depicted as curves though they are actually two dimensional. Each orbit has only one intersection with S_0 .

Next, we consider the action of an element g of G on the points of S_0 . Since G does not admit fixed points, each point on S_0 is necessarily moved along its orbit except in the case that g is the identity element e of G. The moved points form a new surface which does not intersect with S_0 . We denote this surface by S_g and consider a family of the surfaces $\{S_g\} := \{S_g | g \in G\}$ where $S_e = S_0$. It is clear that the surfaces of $\{S_g\}$ fill the spacetime without intersecting with each other.

Let us now choose an orbit, which we denote by \mathcal{O}_0 . All the surfaces of $\{S_g\}$ cross the orbit \mathcal{O}_0 at different points, and hence the surfaces are specified by the intersections on \mathcal{O}_0 . Let (y^1, y^2) be an internal coordinate system of \mathcal{O}_0 . We can denote by $S_{(y^1, y^2)}$ the surface which intersects with \mathcal{O}_0 at (y^1, y^2) (see Fig. 2).

Now that we have two different ways of filling \mathcal{M} —one is with the orbits of $\{\mathcal{O}_{(x^1,x^2)}\}$ and the other is with the surfaces of $\{\mathcal{S}_{(y^1,y^2)}\}$ —we can specify a point of \mathcal{M} by the orbit $\mathcal{O}_{(x^1,x^2)}$ and the surface $\mathcal{S}_{(y^1,y^2)}$ on which the point lies. Using the parameters of the orbit and the surface, we can assign the coordinates (x^1, x^2, y^1, y^2) to the point. This coordinate system is convenient for studying the EOM of cohomogeneity one membranes.

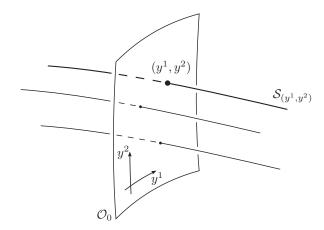


FIG. 2. The orbit \mathcal{O}_0 and the surfaces of $\{S_g\}$. Two-dimensional surfaces are depicted as curves.

2. Metric

To describe the metric, let us introduce an invariant dual basis on each orbit, which is possible when the group action of *G* on the orbits is simply transitive. Let $\{\chi^1, \chi^2\}$ be an invariant dual basis on \mathcal{O}_0 , which satisfies

$$\mathcal{L}_{\xi_I} \chi^J = 0, \qquad (I, J = 1, 2),$$
 (2)

where $\mathcal{L}_{\boldsymbol{\xi}}$ represents the Lie derivative along a vector field $\boldsymbol{\xi}$. With respect to the coordinate system (y^1, y^2) on \mathcal{O}_0, χ^I is written as

$$\chi^I = \chi^I_i(y^1, y^2) dy^i. \tag{3}$$

Considering y^1 and y^2 as the spacetime coordinates, we can extend χ^I to 1-forms in \mathcal{M} satisfying Eq. (2).

Using the invariant dual basis $\{\chi^1, \chi^2\}$, we can write the spacetime metric as

$$ds^2 = g_{pq} dx^p dx^q + 2g_{pI} dx^p \chi^I + g_{IJ} \chi^I \chi^J.$$
 (4)

Here, g_{pq} , g_{pI} and g_{IJ} are functions of x^1 and x^2 only, which is due to the Killing equations

$$\mathcal{L}_{\boldsymbol{\xi}_l} g = 0, \tag{5}$$

and Eq. (2). For later convenience, we write the metric as follows:

$$ds^{2} = h_{pq} dx^{p} dx^{q} + g_{IJ} (\chi^{I} + N^{I}{}_{p} dx^{p}) (\chi^{J} + N^{J}{}_{q} dx^{q}),$$
(6)

where

$$g_{IJ}N^{J}{}_{p} = g_{Ip}, \tag{7}$$

$$h_{pq} = g_{pq} - g_{IJ} N^{I}{}_{p} N^{J}{}_{q}. \tag{8}$$

3. Equations of motion

When we identify the orbits with the points on S_0 , the world volume Σ is reduced to a curve on S_0 . We denote this curve by $C_0(\lambda)$,

$$\mathcal{C}_0: \mathbb{R} \ni \lambda \mapsto (x^1(\lambda), x^2(\lambda)) \in \mathcal{S}_0.$$
(9)

Then we can label the foliating orbits with the parameter λ ,

$$\mathcal{O}_{\lambda} \coloneqq \mathcal{O}_{(x^{1}(\lambda), x^{2}(\lambda))} \tag{10}$$

(see Fig. 3). A point on Σ is specified by the orbit \mathcal{O}_{λ} and the surface $\mathcal{S}_{(y^1,y^2)}$ on which the point lies. Then the set of parameters (λ, y^1, y^2) is considered as a coordinate system on Σ . With this coordinate system, the embedding of Σ into \mathcal{M} is given by

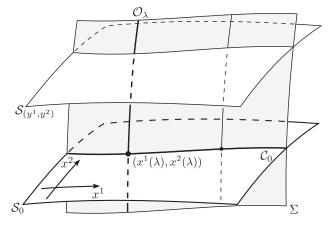


FIG. 3. The curve C_0 on the surface S_0 and the orbits \mathcal{O}_{λ} determine the world volume Σ . The dimension of Σ is three, and of \mathcal{O}_{λ} is two.

$$(\lambda, y^1, y^2) \mapsto (x^1(\lambda), x^2(\lambda), y^1, y^2), \tag{11}$$

and the Nambu-Goto action is given by the three-volume integral

$$S = \int_{\Sigma} \sqrt{|\gamma|} d\lambda dy^1 dy^2 = \int_{\mathcal{C}_0} \left\{ \int_{\mathcal{O}_{\lambda}} \sqrt{|\gamma|} dy^1 dy^2 \right\} d\lambda,$$
(12)

where γ is the determinant of the induced metric on Σ , and hence $\sqrt{|\gamma|}$ is the volume of the parallelepiped spanned by the coordinate basis $(\partial_{\lambda}, \partial_1, \partial_2) := (\partial/\partial \lambda, \partial/\partial y^1, \partial/\partial y^2)$.

The volume of the parallelepiped is given by a product of the area of the base and the height from the base. Considering the parallelogram spanned by ∂_1 and ∂_2 as the base (see Fig. 4), we obtain the area of the base as

$$|\det \chi^{I}{}_{j}|\sqrt{|\det g_{IJ}|}, \qquad (13)$$

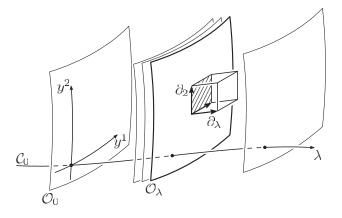


FIG. 4. The parallelepiped spanned by the coordinate basis: $(\partial_{\lambda}, \partial_1, \partial_2)$. The shaded parallelogram is spanned by ∂_1 and ∂_2 . We should note that ∂_{λ} is not necessarily perpendicular to the parallelogram.

and the height of the parallelepiped, which is given by the magnitude of the normal component of $\partial_{\lambda} = \dot{x}^p \partial / \partial x^p$ to the base, as

$$\sqrt{|h_{pq}\dot{\mathbf{x}}^p\dot{\mathbf{x}}^q|},\tag{14}$$

where the dot denotes the derivative with respect to λ . Thereby the volume is written as

$$\sqrt{|\gamma|} = |\det \chi^{I}{}_{j}| \sqrt{|\det g_{IJ}|} \sqrt{|h_{pq} \dot{x}^{p} \dot{x}^{q}|}$$
$$= |\det \chi^{I}{}_{j}| \sqrt{|(\det g_{IJ})h_{pq} \dot{x}^{p} \dot{x}^{q}|}.$$
(15)

Noting that χ^{I}_{j} are functions of y^{1} and y^{2} and that g_{IJ} and h_{pq} are functions of λ , we can write the Nambu-Goto action (12) as

$$S = \int_{\mathcal{C}_0} \left\{ \sqrt{|(\det g_{IJ})h_{pq}\dot{x}^p \dot{x}^q|} \int_{\mathcal{O}_\lambda} |\det \chi^I_j| dy^1 dy^2 \right\} d\lambda$$
(16)

$$= \int_{\mathcal{O}} |\det \chi^{I}{}_{j}| dy^{1} dy^{2} \int_{\mathcal{C}_{0}} \sqrt{|(\det g_{IJ})h_{pq} \dot{x}^{p} \dot{x}^{q}|} d\lambda.$$
(17)

Here, we have used the fact that the integration over the orbit \mathcal{O}_{λ} does not depend on λ . Integrating out the variables y^1 and y^2 , we can reduce the Nambu-Goto action as follows:

$$S \propto \int_{\mathcal{C}_0} \sqrt{|(\det g_{IJ})h_{pq}\dot{x}^p \dot{x}^q|} d\lambda.$$
 (18)

This is identical to the action of a particle moving on the surface S_0 with the metric $(\det g_{IJ})h_{pq}$. The original problem has therefore been reduced to that of finding a geodesic on S_0 .

We have derived the equations of motion on the surface S_0 . It is also possible to do so on other surfaces of $\{S_g\}$. The surfaces can be mapped to each other by the action of g (or g^{-1}) and lead to the same form of (18). The reductions on the surfaces of $\{S_g\}$ are put together by identifying the surfaces with the orbit space \mathcal{M}/G by

$$S_g \ni (x^1, x^2) \leftrightarrow \mathcal{O}_{(x^1, x^2)} \in \mathcal{M}/G.$$
 (19)

We can then conclude that the equations of motion are reduced to the geodesic equations on \mathcal{M}/G . If we consider (x^1, x^2) to be a coordinate system of \mathcal{M}/G , the projection map $\pi: \mathcal{M} \to \mathcal{M}/G$ is explicitly given as

$$\pi: \mathcal{M} \ni (x^1, x^2, y^1, y^2) \mapsto (x^1, x^2) \in \mathcal{M}/G.$$
(20)

Let $(x^1(\lambda), x^2(\lambda))$ be a geodesic in \mathcal{M}/G . The solution of the membrane is given as a preimage: $\pi^{-1}(x^1(\lambda), x^2(\lambda)) = (x^1(\lambda), x^2(\lambda), y^1, y^2)$. By the use of the projection π , we can

naturally induce a metric on \mathcal{M}/G in order that π is a Riemannian submersion. Such an induced metric is given as the symmetric tensor h_{pq} of (8). Weighting h_{pq} with det g_{IJ} , we obtain the metric used in the geodesic action (18) for the cohomogeneity one membrane.

B. The case dim G = 3

In the case dim G = 3, the orbits are two-dimensional spaces of constant curvature. The metric of the orbit with constant curvature K can be written in the form

$$d\sigma^2 = R^2 \{ (dy^1)^2 + \epsilon F^2(y^1) (dy^2)^2 \}$$
(21)

with

$$\epsilon \coloneqq \begin{cases} +1 & (\text{spacelike orbits}) \\ -1 & (\text{timelike orbits}) \end{cases}$$
(22)

and

$$F(y^{1}) \coloneqq \begin{cases} \sin y^{1} & (K > 0) \\ y^{1} & (K = 0) \\ \sinh y^{1} & (K < 0) \end{cases}$$
(23)

where *R* is a constant. By using coordinates x^1 and x^2 which are constant on each orbit, we can write the spacetime metric as [16,17]

$$ds^{2} = e^{2\lambda} (dx^{1})^{2} - \epsilon e^{2\nu} (dx^{2})^{2} + R^{2} \{ (dy^{1})^{2} + \epsilon F^{2} (y^{1}) (dy^{2})^{2} \}, \qquad (24)$$

where λ, ν and *R* are functions of x^1 and x^2 . We can consider (x^1, x^2) as a coordinate system of the orbit space \mathcal{M}/G , and the projection $\pi: \mathcal{M} \to \mathcal{M}/G$ is again given by Eq. (20). We see that

$$ds_{\mathcal{M}/G}^2 \coloneqq e^{2\lambda} (dx^1)^2 - \epsilon e^{2\nu} (dx^2)^2 \tag{25}$$

is the metric on \mathcal{M}/G with π being a Riemannian submersion. Following the same derivation presented in the case dim G = 2, the Nambu-Goto action is separated as

$$S = \int_{\mathcal{O}} |F| dy^1 dy^2 \int_{\mathcal{C}} \sqrt{|R^4 \{ e^{2\lambda} (\dot{x}^1)^2 - \epsilon e^{2\nu} (\dot{x}^2)^2 \}|} d\lambda.$$
(26)

Integrating out the variables y^1 and y^2 , we obtain a reduced action

$$S \propto \int_{\mathcal{C}} \sqrt{|R^4 \{ e^{2\lambda} (\dot{x}^1)^2 - \epsilon e^{2\nu} (\dot{x}^2)^2 \} |} d\lambda.$$
 (27)

Therefore the problem is reduced to solving the geodesic equations on \mathcal{M}/G with the weighted metric

TABLE I. The commutation relations of three Killing vectors $(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2, \boldsymbol{\xi}_3)$ of the two-dimensional spaces of constant curvature.

Spaces of constant curvature	Bianchi type	$[{m \xi}_1, {m \xi}_2]$	$[{\bf \xi}_2, {\bf \xi}_3]$	$[{m \xi}_3, {m \xi}_1]$
Euclid space E^2	VII ₀	0	$-\xi_1$	-ξ ₂
Sphere \hat{S}^2	IX	ξ ₃	$-\boldsymbol{\xi}_1$	$-\xi_{2}$
Hyperbolic space H^2	VIII	ξ 3	$-\boldsymbol{\xi}_1$	- ξ ₂
Minkowski spacetime $E^{1,1}$	VI_0	0	ξ 1	−ξ ₂
de Sitter spacetime dS^2	VIII	ξ 3	$-\xi_1$	-ξ ₂
Anti–de Sitter spacetime AdS ²	VIII	ξ 3	$-\xi_1$	- ξ ₂

$$\tilde{ds}^2_{\mathcal{M}/G} \coloneqq R^4 ds^2_{\mathcal{M}/G} = R^4 \{ e^{2\lambda} (dx^1)^2 - \epsilon e^{2\nu} (dx^2)^2 \}.$$
(28)

We finally note the Lie algebra \mathfrak{g} of G. In the case dim G = 3, the action of G is described by three Killing vector fields, $\xi_I(I = 1, 2, 3)$. The triple (ξ_1, ξ_2, ξ_3) represents a basis of \mathfrak{g} . The commutation relations are those of the two-dimensional spaces of constant curvature, which are listed in Table I in terms of the Bianchi classification of the three-dimensional Lie algebras. As seen in Table I, the Lie algebras of Bianchi VI₀ and VII₀ have two-dimensional commutative subalgebras spanned by ξ_1 and ξ_2 . As for the Bianchi VIII, taking new bases

$$\xi'_1 := \xi_2 - \xi_3, \qquad \xi'_2 := \xi_1,$$
 (29)

which satisfy

$$[\xi_1',\xi_2'] = \xi_1', \tag{30}$$

we find that the Bianchi VIII also has a two-dimensional solvable subalgebra. Since the Lie algebras of Bianchi VI₀, VII₀ and VIII include two-dimensional subalgebras, the groups associated with these Lie algebras include two-dimensional subgroups, whose actions on the orbits are simply transitive. Then, for the groups of Bianchi VI₀, VII₀ and VIII, the reduction of the EOM can be explained in the case dim G = 2.

III. GENERAL CLASSIFICATION METHOD FOR COHOMOGENEITY ONE MEMBRANES

The cohomogeneity one symmetries can be assumed in the spacetimes whose isometry groups admit subgroups Gwith two-dimensional orbits. In a given such spacetime, different G may give the cohomogeneity one membranes which are essentially the same. To discard such redundancy, we shall introduce the notion of geometrical equivalence of world volumes and present the method of classifying cohomogeneity one membranes up to the equivalence.

Let Σ and Σ' be world volumes. We say that they are geometrically equivalent if there is an isometry ϕ on \mathcal{M}

which maps Σ onto Σ' . Suppose further that one of such world volumes, Σ , is of cohomogeneity one with symmetry group G. Then Σ' is of cohomogeneity one with symmetry group $\phi G \phi^{-1}$. To see this, let O_{λ} be the orbits of G which comprise a foliation of Σ . Then for each pair of points p and p' on $\phi(O_{\lambda})$, there exists $g \in G$ such that $g(\phi^{-1}(p)) =$ $\phi^{-1}(p')$ which implies $\phi g \phi^{-1}(p) = p'$. Thus $\phi(O_{\lambda})$ comprise a homogeneous foliation of Σ' with symmetry group $\phi G \phi^{-1}$.

It is natural to introduce an equivalence relation for subgroups G and G' of Isom \mathcal{M} ,

$$G \sim G' \Leftrightarrow \exists \phi \in \operatorname{Isom} \mathcal{M} \quad \text{s.t.} \quad G' = \phi G \phi^{-1}.$$
 (31)

Then subgroups G and G' define geometrically equivalent world volumes if and only if they are equivalent. Our task is to find out the equivalence classes of the relation (31), or the conjugacy class of the subgroups G of Isom \mathcal{M} .

In the actual classification procedure, it is more convenient to work with the Lie algebra \mathfrak{g} of G, which consists of Killing vector fields on \mathcal{M} . Because the conjugation for $g \in G$ by $\phi \in \text{Isom } \mathcal{M}, g \mapsto \phi g \phi^{-1}$, induces the pushforward $\boldsymbol{\xi} \mapsto \phi_* \boldsymbol{\xi}$ for $\boldsymbol{\xi} \in \mathfrak{g}$. The equivalence relation on the symmetry group *G* induces that on the symmetry Lie algebra \mathfrak{g} ,

$$\mathfrak{g} \sim \mathfrak{g}' \Leftrightarrow \exists \phi \in \operatorname{Isom} \mathcal{M} \quad \text{s.t.} \quad \mathfrak{g}' = \phi_* \mathfrak{g}.$$
 (32)

Thus we shall classify the Lie subalgebras \mathfrak{g} of the Lie algebra of Isom \mathcal{M} , up to the equivalence relation (32).

We further would like to derive a basis for each classified symmetry Lie algebra \mathfrak{g} , so that it is convenient in applications. Let $V \coloneqq (\boldsymbol{\xi}_1, \dots, \boldsymbol{\xi}_{\dim G})$ be a basis for a symmetry algebra \mathfrak{g} . The bases V and $V' \coloneqq$ $(\boldsymbol{\xi}'_1, \dots, \boldsymbol{\xi}'_{\dim G})$ give the same \mathfrak{g} when each element of V'is a linear combination of the elements of $V: \boldsymbol{\xi}'_i = A_i{}^j\boldsymbol{\xi}_j$, $A_i{}^j \in \operatorname{GL}(\dim G, \mathbb{R})$. Then the classification of all cohomogeneity one membrane in a given spacetime \mathcal{M} reduces to that of the bases for the symmetry algebras under the equivalence relation

$$V \sim V' \Leftrightarrow {}^{\exists} \phi \in \operatorname{Isom} \mathcal{M}, {}^{\exists} A_i{}^j \in \operatorname{GL}(\dim G, \mathbb{R}) \quad \text{s.t.} \quad \boldsymbol{\xi}_i' = A_i{}^j \phi_* \boldsymbol{\xi}_j.$$
 (33)

A concrete procedure to get a set of class representatives is the following.

Step 1. Choose an abstract Lie algebra **g** of the symmetry group *G*. It must be one of the following six:

 \mathbb{R}^2 , two-dimensional noncommutative algebra,

Bianchi types VI_0 , VII_0 , VIII and IX. (34)

As discussed in Sec. II, the above are the only Lie algebras that allow two-dimensional orbits. Furthermore, as mentioned at the end of Sec. II, one can eliminate Bianchi types VI_0 , VII_0 and VIII from the list (34), because they are the special cases of \mathbb{R}^2 and two-dimensional noncommutative algebra. However, here we retain them so as to include all possible cases that the orbits are spaces of constant curvature and the metric on the orbit space has the simple form (28).

Step 2. Find a general set of Killing vector fields on \mathcal{M} , $V = (\boldsymbol{\xi}_1, \dots, \boldsymbol{\xi}_{\dim G})$, that satisfy one of the commutation relations (1) and those in Table I depending on the Lie algebra chosen in Step 1. Check that the orbit of *V* is two-dimensional.

Step 3-*k* ($k = 1, ..., \dim G$). Canonicalize $\boldsymbol{\xi}_k$. Namely, reduce $\boldsymbol{\xi}_k$ to a certain simple form by using the degrees of freedom of the equivalence relation (33) that preserves $\boldsymbol{\xi}_l$ for l < k. We shall say that such ($\boldsymbol{\xi}_1, ..., \boldsymbol{\xi}_k$) has the canonical form. [We might sometimes rearrange the canonical form ($\boldsymbol{\xi}_1, ..., \boldsymbol{\xi}_k$) by using GL(k, \mathbb{R}) in order to

make it look simpler as a whole.] Finally, with $k = \dim G$, we obtain the canonical form of *V*.

IV. CLASSIFICATION IN MINKOWSKI SPACETIME

We have obtained the general scheme to classify cohomogeneity one membranes in a given spacetime. In this section, we carry out the complete classification in Minkowski spacetime, which admits ten linearly independent Killing vectors,

$$P_{\mu}$$
 ($\mu = t, x, y, z$), Translations;
 K_i ($i = x, y, z$), Lorentz boosts;
 L_i ($i = x, y, z$), Rotations. (35)

Any Killing vector $\boldsymbol{\xi}$ is written as a linear combination of them,

$$\boldsymbol{\xi} = \alpha_{\mu} \boldsymbol{P}_{\mu} + \beta_{i} \boldsymbol{K}_{i} + \gamma_{i} \boldsymbol{L}_{i}, \qquad (36)$$

where α_{μ} , β_i and γ_i are constants.

In Minkowski spacetime, we have an advantage that greatly simplifies the classification scheme because all canonical forms of Killing vector fields are derived [11]. For any g, we can assume that ξ_1 is one of the canonical forms listed in Table II up to scalar multiplication. Thus Step 3-1 is essentially done in advance.

TABLE II. Canonical forms of the Killing vectors in Minkowski spacetime. Any Killing vectors are transformed by isometries to these seven types. Killing vectors in the same canonical form with different pairs of constants (a, b) cannot be transformed to each other.

Туре	Canonical form
Ι	$a\boldsymbol{P}_t + b\boldsymbol{L}_z$
П	$a(\mathbf{P}_t + \mathbf{P}_z) + b\mathbf{L}_z$
III	$a\mathbf{P}_z + b\mathbf{L}_z$
IV	$a P_{z} + b(\tilde{K}_{y} + L_{z})$
V	$a\mathbf{P}_{z} + b\mathbf{K}_{y}$
VI	$a \vec{P_x} + b(\vec{K}_y + L_z)$
VII	$aK_z + bL_z$

A. Classification of two-dimensional Abelian symmetry groups

Let us choose the two-dimensional commutative algebra \mathbb{R}^2 as the symmetry algebra \mathfrak{g} . We would like to derive the equivalence classes of the set of commuting pairs of Killing vector fields,

$$\mathcal{V}_{C} \coloneqq \{(\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}) | [\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}] = 0\}.$$
(37)

As discussed above, Step 3-1 is already carried out and we can take ξ_1 as one of the canonical forms of Table II up to scalar multiplication. We then divide \mathcal{V}_C essentially into seven parts $\mathcal{V}_C^J(J = I, II, ..., VII)$ depending on the canonical form of ξ_1 . For example, \mathcal{V}_C^I is a set of the commuting pairs of Killing vectors (ξ_1, ξ_2) with ξ_1 being in the canonical form of Type I, $\xi_1 = aP_t + bL_z$, and in this case ξ_2 is written as linear combinations of the ten Killing vectors (35) which commute with $aP_t + bL_z$. Next, we reduce the number of the Killing vectors (35) contained in ξ_1 and ξ_2 by using isometries and GL(2, \mathbb{R}) actions on the pair (ξ_1, ξ_2) , so that ξ_1 and ξ_2 contain the smallest possible number of parameters. A detailed calculation for one case is given in the Appendix.

As a result, we obtain simple representatives in each of \mathcal{V}_{C}^{I} . However, we must be aware that two different \mathcal{V}_{C}^{I} 's may lead to equivalent pairs ($\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}$). We eliminate this redundancy and obtain a complete set of canonical forms. The result is shown in Table III. Any element of \mathcal{V}_{C} falls into one of the equivalence classes of these canonical forms.

B. Classification of two-dimensional non-Abelian symmetry groups

Let us choose the two-dimensional noncommutative algebra as the symmetry algebra **g**. This is the classification of $\mathcal{V}_{\rm S} := \{(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) | [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2] = \boldsymbol{\xi}_1\}$. As in the commutative case, we can take $\boldsymbol{\xi}_1$ to be the seven types in Table II, and we reduce the degree of freedom in $\mathcal{V}_{\rm S}$ by using $\boldsymbol{\phi} \in$ Isom \mathcal{M} and $A_i^{\ j} \in \mathrm{GL}(2, \mathbb{R})$ which preserves the

TABLE III. The representatives of the equivalence classes of \mathcal{V}_{C} : a set of commuting pairs of Killing vectors ($\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}$). Those pairs that are connected by a simple rescaling of $\boldsymbol{\xi}_{2}$ are equivalent, though having different (a, b).

ξ 1	$\boldsymbol{\xi}_2$ (<i>a</i> , <i>b</i> : constants)
$\overline{P_t}$	$a\boldsymbol{P}_{z}+b\boldsymbol{L}_{z}$
$\boldsymbol{P}_t + \boldsymbol{P}_z$	$a\mathbf{P}_t + b\mathbf{L}_z, \ a\mathbf{P}_z + b(\mathbf{K}_x - \mathbf{L}_y), \ a\mathbf{P}_y + b(\mathbf{K}_x - \mathbf{L}_y)$
P_z	$a\mathbf{P}_t + b\mathbf{L}_z, \ a\mathbf{P}_x + b\mathbf{K}_y, \ a\mathbf{P}_x + b(\mathbf{K}_y + \mathbf{L}_z)$
L_z	Kz
$K_y + L_z$	$a\boldsymbol{P}_z + b(\boldsymbol{K}_z - \boldsymbol{L}_y)$

TABLE IV. The representatives of the equivalence classes of V_S : a set of noncommuting pairs of Killing vectors $(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2)$.

ξ 1	$\boldsymbol{\xi}_2$ (<i>a</i> : constant)	
$\boldsymbol{P}_t + \boldsymbol{P}_z$	$K_z + aP_x, K_z + aL_z$	
$K_y + L_z$	$-\mathbf{K}_{x}+a\mathbf{P}_{z}$	

commutation relation. The resulting canonical forms are listed in Table IV.

C. Classification of three-dimensional symmetry groups

Let us discuss the case that the symmetry algebra \mathfrak{g} is three dimensional. As was discussed in the previous section, \mathfrak{g} must be one of the Bianchi types VI₀, VII₀, VIII and IX. The classification is for the triples of Killing vector fields (ξ_1, ξ_2, ξ_3) which satisfy either of the commutation relations listed in Table I. The classification procedure for each Bianchi type is described in the subsequent subsections. The result of the canonical forms for all Bianchi types are shown in Table V.

1. Bianchi VI₀

Bianchi type VI₀ algebra has a two-dimensional commutative subalgebra \mathfrak{h} . The subalgebra \mathfrak{h} must be equivalent to one of the Lie algebras defined by the pairs in Table III. Then we should look for the third Killing vector $\boldsymbol{\xi}_3$ which satisfies the commutation relations

$$[\boldsymbol{\xi}_2, \boldsymbol{\xi}_3] = \boldsymbol{\xi}_1, \qquad [\boldsymbol{\xi}_3, \boldsymbol{\xi}_1] = -\boldsymbol{\xi}_2, \qquad (38)$$

where we take a linear combination $\boldsymbol{\xi}_i$ if necessary. Reducing the general expression of $V = (\boldsymbol{\xi}_1, \boldsymbol{\xi}_2, \boldsymbol{\xi}_3)$ by

TABLE V. The representatives of the equivalence classes of triples of Killing vectors $(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2, \boldsymbol{\xi}_3)$ that generate the isometry group that has two-dimensional orbits.

Bianchi type	$\boldsymbol{\xi}_1$	ξ ₂	ξ 3
VI0	\boldsymbol{P}_t	P_{τ}	K_{7}
VII ₀	P_z	$\vec{P_x}$	L_v
	$K_y + L_z$	$K_z - L_y$	L_x
VIII	K_z	K_x	L_{v}
IX	L_z	L_x	L_y

using the equivalence relation (33) leads to the canonical form

$$V = (\boldsymbol{P}_t, \boldsymbol{P}_z, \boldsymbol{K}_z + \alpha_{\mu} \boldsymbol{P}_{\mu} + \gamma \boldsymbol{L}_z), \qquad (39)$$

where α_{μ} and γ are arbitrary constants.

Let us require that the symmetry group G has the twodimensional orbits. The tangent space spanned by V at each point must be two dimensional. The concrete expression of the Killing vector fields,

$$\begin{aligned} \boldsymbol{\xi}_1 &= \partial_t, \qquad \boldsymbol{\xi}_2 = \partial_z, \\ \boldsymbol{\xi}_3 &= z\partial_t + t\partial_z + \alpha_x\partial_x + \alpha_y\partial_y + \gamma(x\partial_y - y\partial_x), \end{aligned} \tag{40}$$

in Cartesian coordinate basis implies that ξ_3 cannot have the terms proportional to ∂_x or ∂_y . Thus, we must have $\alpha_{\mu} = 0$ and $\gamma = 0$ so that

$$V = (\boldsymbol{P}_t, \boldsymbol{P}_z, \boldsymbol{K}_z). \tag{41}$$

The orbits of **g** are obviously the planes parallel to the *t*-*z* plane. We note that the Lie algebra spanned by the basis *V* contains both of the commutative and noncommutative two-dimensional algebras, spanned by (P_t, P_z) in Table III and $(P_t + P_z, K_z)$ in Table IV, respectively. Accordingly, the two-dimensional orbits of (41) can be considered as those generated by (P_t, P_z) or by $(P_t + P_z, K_z)$. The orbit is the two-dimensional Minkowski spacetime.

2. Bianchi VII₀

Let us consider the case of \mathfrak{g} being the Bianchi VII₀ algebra. Then $\boldsymbol{\xi}_1$ and $\boldsymbol{\xi}_2$ in $V = (\boldsymbol{\xi}_1, \boldsymbol{\xi}_2, \boldsymbol{\xi}_3)$ commute. Following the same procedures as in the case of Bianchi VI₀, we obtain two representatives,

$$V = (\boldsymbol{P}_z, \boldsymbol{P}_x, \boldsymbol{L}_y) \quad \text{and} \quad (\boldsymbol{K}_y + \boldsymbol{L}_z, \boldsymbol{K}_z - \boldsymbol{L}_y, \boldsymbol{L}_x). \quad (42)$$

In the first case, which we call type VII₀-1, the orbits are parallels to the *z*-*x* plane and are intrinsically and extrinsically flat. In contrast, in the second case, which we call type VII₀-2, the orbits are flat intrinsically but are embedded in \mathcal{M} in a nontrivial way. Both types of embedding share common features: intrinsic flatness and extrinsic homogeneity and isotropy. The type VII₀-2 with nontrivial embedding of orbits seems worth further analysis. In Sec. V, we will clarify how the orbits of type VII₀-2 are embedded in Minkowski spacetime, and we will explicitly construct a solution of a cohomogeneity one Nambu-Goto membrane.

3. Bianchi VIII

Let the symmetry algebra \mathfrak{g} be the Bianchi VIII algebra. We start with $\boldsymbol{\xi}_1$ of the $V = (\boldsymbol{\xi}_1, \boldsymbol{\xi}_2, \boldsymbol{\xi}_3)$ being one of the canonical forms in Table II (up to rescaling). Next, for the chosen $\boldsymbol{\xi}_1$, we look for $\boldsymbol{\xi}_2$ which satisfies the following relations: PHYSICAL REVIEW D 91, 025007 (2015)

$$[\boldsymbol{\xi}_1, [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2]] = [\boldsymbol{\xi}_1, \boldsymbol{\xi}_3] = \boldsymbol{\xi}_2, \tag{43}$$

$$\boldsymbol{\xi}_{2}, [\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}]] = [\boldsymbol{\xi}_{2}, \boldsymbol{\xi}_{3}] = -\boldsymbol{\xi}_{1}.$$
(44)

The third Killing vector $\boldsymbol{\xi}_3$ is obtained through the commutation relation

.

$$\boldsymbol{\xi}_3 = [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2]. \tag{45}$$

We then have possible V. By using $GL(3, \mathbb{R})$ that preserves the commutation relations, we find that there is only one equivalence class represented by

$$V = (\boldsymbol{K}_x, \boldsymbol{K}_y, \boldsymbol{L}_z). \tag{46}$$

The orbits are two-dimensional hyperboloids or de Sitter spacetimes which are embedded in $E^{2,1}$ with the equation

$$-t^2 + x^2 + y^2 = \text{const.}$$
(47)

As mentioned in Sec. II B, the Lie algebra **g** spanned by V includes a solvable subalgebra spanned by $(\mathbf{K}_y + \mathbf{L}_z, -\mathbf{K}_x)$, which is a special case in Table IV.

4. Bianchi IX

Let g be the Bianchi IX algebra. As in the case of Bianchi VIII, we first consider ξ_1 to be in a canonical form in Table II. We then look for ξ_2 which satisfies

$$[\boldsymbol{\xi}_1, [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2]] = [\boldsymbol{\xi}_1, -\boldsymbol{\xi}_3] = -\boldsymbol{\xi}_2, \tag{48}$$

$$[\boldsymbol{\xi}_2, [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2]] = [\boldsymbol{\xi}_2, -\boldsymbol{\xi}_3] = \boldsymbol{\xi}_1.$$
(49)

The third Killing vector $\boldsymbol{\xi}_3$ is obtained through the commutation relation

$$\boldsymbol{\xi}_3 = [\boldsymbol{\xi}_1, \boldsymbol{\xi}_2]. \tag{50}$$

By using isometries and $GL(3, \mathbb{R})$ actions, we then find that there is only one equivalence class represented by

$$V = (\xi_1, \xi_2, \xi_3) = (L_z, L_x, L_y).$$
(51)

The orbits are spheres centered at the origin.

V. EXACT SOLUTION FOR TYPE VII₀-2 MEMBRANE

Applying the results of Sec. II B, we solve the Nambu-Goto equations for the cohomogeneity one membrane whose world volume has the symmetry of Bianchi type VII₀. The symmetry algebra **g** has two possibilities: one is type VII₀-1 generated by (P_z, P_x, L_y) , and the other is type VII₀-2 generated by $(K_y + L_z, K_z - L_y, L_x)$,

In the case of type VII₀-1, the orbits are the t = const and y = const planes. The weighted metric of the orbit space,

whose geodesics determine the dynamics of the membrane, is flat. Then, the cohomogeneity one membrane of type VII_0 -1 is a static plane or its equivalents.

Hereafter, we concentrate on type VII₀-2. We follow the same conventions as in Sec. II B: the coordinates on the orbits are denoted by (y^1, y^2) , and the orbits are distinguished by (x^1, x^2) .

A. Embbeding of type VII₀-2 orbits

We begin with clarifying the embedding of the VII₀ orbits: $\vec{y} := (y^1, y^2) \mapsto (t, x, y, z)$, generated by the Killing vectors

$$(\boldsymbol{K}_{v} + \boldsymbol{L}_{z}, \boldsymbol{K}_{z} - \boldsymbol{L}_{v}, \boldsymbol{L}_{x}).$$
(52)

Since the Killing vectors $K_y + L_z$ and $K_z - L_y$ commute with each other, we take them as a coordinate basis on the orbit,

$$(\partial_{y^1}, \partial_{y^2}) = (\mathbf{K}_y + \mathbf{L}_z, \mathbf{K}_z - \mathbf{L}_y).$$
(53)

In Cartesian coordinates (t, x, y, z), Eqs. (53) are written as

$$\partial_{y^{1}} = t_{,1}\partial_{t} + x_{,1}\partial_{x} + y_{,1}\partial_{y} + z_{,1}\partial_{z}$$
$$= y(\partial_{t} - \partial_{x}) + (t + x)\partial_{y},$$
(54)

$$\partial_{y^2} = t_{,2}\partial_t + x_{,2}\partial_x + y_{,2}\partial_y + z_{,2}\partial_z$$

= $z(\partial_t - \partial_x) + (t + x)\partial_z$, (55)

where t, x, y and z are considered as embedding functions, namely functions of $y^i (i = 1, 2)$, and the commas denote the differentiation with respect to y^i . Comparing the coefficients of the coordinate basis, we obtain equations of the embedding:

$$\frac{\partial t}{\partial y^{1}} = -\frac{\partial x}{\partial y^{1}} = y, \qquad \frac{\partial t}{\partial y^{2}} = -\frac{\partial x}{\partial y^{2}} = z,$$
$$\frac{\partial y}{\partial y^{1}} = \frac{\partial z}{\partial y^{2}} = (t+x), \qquad \frac{\partial z}{\partial y^{1}} = \frac{\partial y}{\partial y^{2}} = 0.$$
(56)

These equations are readily solved as

$$t = \frac{a}{2}\vec{y} \cdot \vec{y} + \frac{a+b}{2}, \qquad x = -t+a, y = ay^{1}, \qquad z = ay^{2},$$
(57)

where a and b are arbitrary constants. Equations (57) are equivalent to the following implicit equations:

$$-\left(t - \frac{b}{2}\right)^2 + \left(x + \frac{b}{2}\right)^2 + y^2 + z^2 = 0, \quad (58)$$

$$t + x - a = 0. (59)$$

We see that each orbit is the cross section of a light cone (58) and a null plane (59).

With the null coordinates $u \coloneqq t + x$ and $v \coloneqq t - x$, Eqs. (58) and (59) are written as

$$-u(v-b) + y^2 + z^2 = 0,$$
 (60)

$$u - a = 0. \tag{61}$$

Therefore each orbit is a two-dimensional paraboloid

$$-a(v-b) + y^2 + z^2 = 0$$
 (62)

on a null plane u = a. Since the paraboloid is specified by the vertex, located at (u, v, y, z) = (a, b, 0, 0), we identify each such orbit with the point (a, b) in the *u*-*v* plane. Therefore the *u*-*v* plane can be identified with the orbit space. Hereinafter, we use the coordinate system (u, v) of the orbit space as the (x^1, x^2) in Sec. II B.

Combining the coordinate system on the orbit space (u, v) and that on the orbit (y^1, y^2) , we make up a coordinate system (u, v, y^1, y^2) in $E^{3,1}$. By the coordinate transformation between (t, x, y, z) and (u, v, y^1, y^2) given by (57) with a = u and b = v, the metric of $E^{3,1}$ is written as

$$ds^2 = -dudv + u^2 d\vec{y}^2. \tag{63}$$

This form has the same structure of (24); the first term is the metric on \mathcal{M}/G such that the projection is a Riemannian submersion.

B. Solutions for type VII₀-2 membranes

Following the results of Sec. II B, the Nambu-Goto equations for the cohomogeneity one membrane is reduced to the geodesic equations on \mathcal{M}/G with the weighted metric (28) where $R^2 = u^2$,

$$ds^2_{\mathcal{M}/G} = u^4(-dudv). \tag{64}$$

In order to solve the geodesic equations, we start with the action

$$S = \int \left(\frac{\mathcal{L}}{N} - N\right) d\lambda, \qquad \mathcal{L} = -u^4 \dot{u} \, \dot{v}, \qquad (65)$$

where the dots denote the derivative with respect to the parameter λ , and N is a function of λ which determines the parametrization of the geodesic; indeed, variation with N leads

$$-u^4 \dot{u} \, \dot{v} = -N^2. \tag{66}$$

Variations with u and v give two conserved quantities C_u and C_v ,

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$$\frac{\dot{v}}{N} = \sqrt{5}C_u, \qquad \frac{u^4\dot{u}}{N} = C_v. \tag{67}$$

The constraint condition (66) gives $\sqrt{5}C_uC_v = 1$. Then Eqs. (67) are readily integrated as

$$v(\lambda) = C_u^2 u^5(\lambda) + 2D, \tag{68}$$

where D is an arbitrary constant. This curve on the u-v plane describes the trajectory of the vertex of the paraboloid (62).

The embedding of the world volume is implicitly written as

$$-u(v - C_u^2 u^5 - 2D) + y^2 + z^2 = 0, \qquad (69)$$

or, equivalently,

$$-(t-D)^{2} + (x+D)^{2} + y^{2} + z^{2} + C_{u}^{2}(t+x)^{6} = 0.$$
(70)

Though the solution has two free parameters C_u and D, we can set D = 0, i.e.,

$$-t^{2} + x^{2} + y^{2} + z^{2} + C_{u}^{2}(t+x)^{6} = 0, \qquad (71)$$

because the world volume with $D \neq 0$ is identified with the one with D = 0 by using a translation for the null direction. As depicted in Fig. 5, the t = const slices of the world volume are closed; then the solution represents a closed membrane, which shrinks or expands. In contrast, the slices

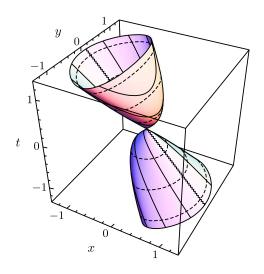


FIG. 5 (color online). The world volume of the membrane with $C_u = 1.1$. The *z* direction is omitted. The lower world volume shrinks to a point at t = x = 0, and the upper expands from there. The dashed lines represent t = const slices. The solid lines represent t + x = const slices, which also represent the foliating orbits of type VII₀-2. The jagged line is a singular orbit of dimension one with u = 0, which corresponds to the "cosmological singularity" of the intrinsic geometry.

with the null planes (61) give the paraboloids of revolution (62) and hence are not closed. Since the paraboloids are the orbits of the Killing vectors (52), the membrane is homogeneous and isotropic, actually flat, on these null slices.

From Eqs. (63), (66) and (67), the metric induced on the world volume is written as

$$ds_{\Sigma}^2 = -d\lambda^2 + u^2 d\vec{y}^2, \qquad u(\lambda) \propto \lambda^{1/3}, \qquad (72)$$

where we have chosen the parametrization of λ so that

$$N(\lambda) = u^2(\lambda). \tag{73}$$

The geometry on the world volume is analogous to the flat Friedmann-Lemaître-Robertson-Walker universe. At the null line u = 0 on the world volume, i.e., t + x = 0, y = z = 0, the scalar curvature of the induced metric (72) diverges. Thus, the cosmological singularity is described by the null line u = 0. The orbits (60) and (61) generated by the Killing vectors (52) are two-dimensional spacelike surfaces, but is a null line at u = 0. Therefore the cosmological singularity is described by the singular orbit. We remark that the orbit is singular at u = 0 but the world volume (71) itself is smooth everywhere except at the origin of Minkowski spacetime. The embedding of the membrane is very similar to that of the brane universe in five-dimensional anti-de Sitter space [18].

VI. SUMMARY AND DISCUSSION

We have investigated the dynamics of cohomogeneity one membranes. The three-dimensional world volume of the cohomogeneity one membrane is foliated by twodimensional orbits of the symmetry group G that is a subgroup of the isometry group, Isom \mathcal{M} , of the spacetime \mathcal{M} . The symmetry suggests that the equations of motion are reduced to ordinary differential equations. We have explicitly shown that the Nambu-Goto equations are reduced to the geodesic equations in the orbit space, or the quotient space \mathcal{M}/G , with a properly defined metric thereon.

In a highly symmetric spacetime, there exists a variety of symmetry groups G that allow two-dimensional orbits. We have proposed a classification of the symmetry groups Gunder the idea that the orbits of G are equivalent if they are connected by an isometry of \mathcal{M} . This leads to the classification of the conjugacy classes of G in Isom \mathcal{M} . The classification is reduced to that of pairs and triples of Killing vectors which form a Lie algebra. We have presented a concrete procedure of the classification.

We have demonstrated the procedure in Minkowski spacetime and have achieved the complete classification of cohomogeneity one membranes (Tables III, IV and V). The symmetry group G must be of two or three dimensions in order to have two-dimensional orbits. In Minkowski spacetime, there are two cases for dim G = 2: the Abelian

group and the non-Abelian group; and four cases for dim G = 3: Bianchi type VI₀, VII₀, VIII and IX. The orbits in the latter four cases are two-dimensional maximally symmetric timelike or spacelike surfaces. In addition, because *G* is a subgroup of Isom \mathcal{M} , the embeddings of the orbits should be homogeneous and isotropic. It is interesting that while Bianchi type VI₀, VIII and IX allow, up to geometric equivalence, a unique foliation by the orbits, Bianchi type VII₀ allows two inequivalent foliations by intrinsically flat orbits. One is the flat embedding (type VII₀-1) and the other is an extrinsically curved one (type VII₀-2).

For the membrane of type VII₀-2, we have constructed an exact solution. The solution describes a (2 + 1)-dimensional analog of the flat Friedman-Lemaître-Robertson-Walker (FLRW) universe embedded in Minkowski spacetime. The cosmological singularity is represented by a null line on the world volume. The embedding is similar to that of the flat FLRW brane universe in the five-dimensional anti–de Sitter spacetime [18].

Our method is general and can be applied to a higherdimensional extended object in an arbitrary spacetime. The equations of motion of an extended object become geodesic equations on the orbit space \mathcal{M}/G . As seen in an example in this article, the solution of the geodesic equations may correspond to a nontrivial configuration of membrane. Therefore the concept of cohomogeneity one objects will be helpful to understand the dynamics of extended objects in spacetime.

It is interesting to classify cohomogeneity one objects in spacetimes of high symmetry such as de Sitter space, antide Sitter space and FLRW spacetimes. It can be carried out in five-dimensional anti-de Sitter space, especially, in the same manner as in the present work, because the canonical forms of Killing vectors are already obtained in [12]. We will consider them in our future work.

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APPENDIX: EQUIVALENCE CLASSES OF \mathcal{V}_{C}^{I}

We give simple representatives of equivalence classes in \mathcal{V}_{C}^{I} , which consists of pairs of commuting Killing vectors $(\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2})$, where $\boldsymbol{\xi}_{1}$ is in the canonical form of Type I, i.e.,

$$\boldsymbol{\xi}_1 = a \boldsymbol{P}_t + b \boldsymbol{L}_z, \quad (a, b: \text{ arbitrary const}). \quad (A1)$$

In the case of $a \neq 0$ and $b \neq 0$, the general form of ξ_2 which commutes with ξ_1 is simply

$$\boldsymbol{\xi}_2 = a' \boldsymbol{P}_t + b' \boldsymbol{L}_z + c' \boldsymbol{P}_z, \qquad (A2)$$

where a', b' and c' are constants. We require

$$ab' - ba' \neq 0 \tag{A3}$$

or

$$c' \neq 0 \tag{A4}$$

so that $\boldsymbol{\xi}_1$ and $\boldsymbol{\xi}_2$ are linearly independent.¹

By virtue of the equivalence under $GL(2, \mathbb{R})$ action, we can reduce the form of $(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2)$ to a simple one. For $\boldsymbol{\xi}_2$ satisfying Eq. (A3), we have

$$(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) = (\boldsymbol{P}_t + c\boldsymbol{P}_z, a'\boldsymbol{P}_t + b'\boldsymbol{L}_z + c'\boldsymbol{P}_z), \quad (A5)$$

where *c* is a constant determined by *a*, *b*, *a'*, *b'* and *c'*. Otherwise, for $\boldsymbol{\xi}_2 = \boldsymbol{P}_z$, we have

$$(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) = (a\boldsymbol{P}_t + b\boldsymbol{L}_z, \boldsymbol{P}_z). \tag{A6}$$

For further reduction of the pair (A5), we take an isometry ϕ generated by K_z , namely Lorentz boost for z direction. The Killing vector $\boldsymbol{\xi}_1 = \boldsymbol{P}_t + c\boldsymbol{P}_z$ is transformed to

$$\phi_* \boldsymbol{\xi}_1 = (\cosh \theta + c \sinh \theta) \boldsymbol{P}_t + (c \cosh \theta + \sinh \theta) \boldsymbol{P}_z.$$
(A7)

Choosing the parameter θ so that

 $c \cosh \theta + \sinh \theta = 0 \quad \text{for } |c| < 1,$ (A8)

$$\cosh \theta + c \sinh \theta = 0 \quad \text{for } |c| > 1,$$
 (A9)

we can reduce the form of the pair (A5) to

$$(\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}) = \begin{cases} (\boldsymbol{P}_{t}, a'' \boldsymbol{P}_{t} + b' \boldsymbol{L}_{z} + c'' \boldsymbol{P}_{z}) & \text{for } |c| < 1, \\ (\boldsymbol{P}_{z}, a'' \boldsymbol{P}_{t} + b' \boldsymbol{L}_{z} + c'' \boldsymbol{P}_{z}) & \text{for } |c| > 1. \end{cases}$$
(A10)

In the case |c| = 1, $\xi_1 (= P_t \pm P_z)$ is invariant under the Lorentz boost ϕ . Using GL(2, \mathbb{R}) action again, we have three kinds of representatives,

$$(\boldsymbol{\xi}_{1}, \boldsymbol{\xi}_{2}) = \begin{cases} (\boldsymbol{P}_{t}, c'' \boldsymbol{P}_{z} + b' \boldsymbol{L}_{z}), \\ (\boldsymbol{P}_{z}, a'' \boldsymbol{P}_{t} + b' \boldsymbol{L}_{z}), \\ (\boldsymbol{P}_{t} + \boldsymbol{P}_{z}, a'' \boldsymbol{P}_{t} + b' \boldsymbol{L}_{z}). \end{cases}$$
(A11)

We should note that the pair (A6) is included in the second case of (A11). Therefore these three kinds are the conclusive representatives of \mathcal{V}_{C}^{I} within the case $a, b \neq 0$. It should also be noted that pairs with different values of constants a'', b' and c'' except for overall scaling of ξ_2 are not equivalent.

¹In the case of a = 0 or b = 0, the general form of ξ_2 is more complicated. For the sake of simplicity, we concentrate on the case $a, b \neq 0$.

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