Black hole hair in generalized scalar-tensor gravity: An explicit example

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In a recent paper we showed that in shift-symmetric Horndeski theory the scalar field is forced to obtain a nontrivial configuration in black hole spacetimes, unless a linear coupling with the Gauss–Bonnet invariant is tuned away. As a result, black holes generically have hair in this theory. In this companion paper, we first review our argument and discuss it in more detail. We then present actual black hole solutions in the simplest case of a theory with the linear scalar-Gauss–Bonnet coupling. We generate exact solutions numerically for a wide range of values of the coupling and also construct analytic solutions perturbatively in the small-coupling limit. Comparison of the two types of solutions indicates that nonlinear effects that are not captured by the perturbative solution lead to a finite area, as opposed to a central, singularity. Remarkably, black holes have a minimum size, controlled by the length scale associated with the scalar-Gauss–Bonnet coupling. We also compute some phenomenological observables for the numerical solution for a wide range of values of the scalar-Gauss–Bonnet coupling. Deviations from the Schwarzschild geometry are generically very small.

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I. INTRODUCTION

In terms of the number of physical parameters one needs to fully characterize them, black holes in gravity theories are rather simple. After the discovery of the uniqueness theorems in general relativity for the Schwarzschild, Reissner–Nordstrom and Kerr solutions [1–[4\],](#page-15-0) it was conjectured that "black holes have no hair" [\[5\]](#page-15-1) other than the mass, angular momentum and electromagnetic charge. Hawking further proved that stationary black holes, which are the endpoint of gravitational collapse, in Einstein– Maxwell theory must be of the Kerr–Newman form [\[6\]](#page-15-2) and later extended this result to Brans–Dicke theory [\[7\]](#page-15-3). Standard scalar-tensor theories have also been shown to fall in the reign of the no-hair theorems [\[8,9\]](#page-15-4). Note that the no-hair theorems concern mostly black hole solutions with flat asymptotics, and hairy black holes with nonflat asymptotics often exist. The no-hair theorems inspired the development of black hole thermodynamics. However, it has been realized that hairy black holes do exist when Yang–Mills fields [\[10](#page-15-5)–12] and noncanonical scalars such as Skyrmions [\[13,14\]](#page-15-6) are included, or when symmetries for nongravitational fields are relaxed [\[15\]](#page-15-7). The possibility of having black holes with quantum hair has been discussed in Ref. [\[16\]](#page-15-8).

Various noncanonical scalar fields (i.e. beyond standard scalar-tensor theory) have been employed to build inflation models in the early Universe and dark energy models in the late Universe. Like Skyrmions, these fields can arise as

effective field theories from some underlying theories. Galileon fields [\[17\]](#page-15-9) are one of this kind and have been extensively investigated recently. The prototype of a Galileon comes from the Dvali–Gabadadze–Porrati braneworld model [\[18\],](#page-15-10) where the brane bending mode roughly plays the role of the Galileon field [\[19\].](#page-15-11) One central feature of Galileon theory is that its Lagrangian terms may contain more than two derivatives, but its equations of motion remain second order, therefore avoiding Ostrogradski ghosts. This delicate construction makes use of the Galileon symmetry $\phi \rightarrow \phi + c + b_u x^{\mu}$ (c, b_u being constant) [\[17\]](#page-15-9) that becomes exact in the flat space limit. Although the Galileon Lagrangian terms can be derived from a braneworld setup [\[20\],](#page-15-12) it is often more convenient to use the four-dimensional covariant effective theories as a proxy (see e.g. Refs. [\[21](#page-15-13)–23]). In generalized Galileon theories, the Galileon symmetry in the flat space limit is abandoned in order to get the most general second-order scalar-tensor theory [\[24\]](#page-16-0). The generalized Galileon has been shown to be equivalent to Horndeski's theory [\[25\]](#page-16-1) in four dimensions [\[26\]](#page-16-2). See Ref. [\[27\]](#page-16-3) for a recent review of Galileon gravity. As they are much more complicated than standard scalar-tensor theory, generalized Galileon theories fall outside the purview of the already known black hole no-hair theorems.

Recently, a no-hair theorem for static, spherically symmetric, asymptotically flat black holes has been proposed for the most general scalar-tensor theory with a shiftsymmetric scalar that leads to second-order equations [\[28\]](#page-16-4). The basic steps of the proof laid out in Ref. [\[28\]](#page-16-4) are the following. Shift symmetry implies that one may write the scalar equation of motion as a current conservation

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equation $\nabla_{\mu}J^{\mu} = 0$, J^{μ} being the associated Noether current. Because of staticity and spherical symmetry, the only nonvanishing component of the current is J^r and is a function of the radial coordinate r only. It is then shown that asymptotic flatness combined with the requirement that the scalar $J^{\mu}J_{\mu}$ be regular on the horizon implies $J^r = 0$ at all r. The last step is to prove that $J^r = 0$ at all r necessarily implies ϕ = const. It is argued that the current takes the form $J^r = g^{rr} \phi^r F(\phi^r; g, g', g'')$ for general shift-symmetric
scalar-tensor theory featuring a canonical kinetic term scalar-tensor theory featuring a canonical kinetic term, where a prime means d/dr , g represents the metric components, and F asymptotes a nonzero constant when ϕ' goes to zero and g^{rr} goes to 1 near spatial infinity. If this is valid, the only solution for J^r to remain zero at all r is that $\phi' = 0$ at all r, which means there is no scalar hair for any spherically symmetric black holes.

In Ref. [\[29\]](#page-16-5) we pointed out that the last step of the proof of Ref. [\[28\]](#page-16-4) discussed above has a loophole. In this paper we will elaborate further on this and also provide a counterexample by constructing an explicit hairy black hole solution in a simple model that falls within generalized Galileon or Horndeski theories.

The rest of the paper is organized as follows. In the next section, we first provide a brief overview of Horndeski theories, and we rigorously identify the most general shiftsymmetric generalized Galileon (SSGG). We then discuss the form of the current associate with shift symmetry, and we carefully analyze the potential loopholes in the proof of Ref. [\[28\].](#page-16-4) We also explain why a generic SSGG would actually not be covered by this no-hair theorem without fine-tuning or additional symmetry assumptions. In Sec. [III](#page-3-0) we present actual black hole solutions for the simplest theory that evades the no-hair theorem. We first generate exact solutions numerically, and we then proceed to construct explicit, analytic solutions perturbatively, in the small-coupling approximation. The structure of these spacetimes is fully analyzed, and a comparison of the two types of solutions identifies the regime in which nonlinear effects are crucial. Finally, we turn our attention to phenomenology and assess how much our solutions deviate from the Schwarzschild solution. Section [IV](#page-11-0) contains our conclusions.

II. BLACK HOLE HAIR IN GALILEON GRAVITY

As mentioned in the Introduction, we will look more carefully at the last step of the proof of Ref. [\[28\]](#page-16-4). In particular, we will examine in detail the functional form of the current associated with shift symmetry and whether it indeed always agrees with what was assumed in Ref. [\[28\]](#page-16-4). Since we are interested in second-order theories (which avoid Ostrogradski instabilities), we can focus on the shiftsymmetric restriction of generalized Galileon theories [\[24\]](#page-16-0) (or Horndeski's theory [\[25\]](#page-16-1)).

A. Shift-symmetry current

First, we need to identify the most general SSGG. This can be done by imposing shift symmetry on the equations of motion of the generalized Galileon. We present a detailed discussion about this in Appendix [A](#page-12-0) and only give the final result here. The Lagrangian is

$$
\mathcal{L} = \mathcal{L}_2 + \mathcal{L}_3 + \mathcal{L}_4 + \mathcal{L}_5, \tag{1}
$$

$$
\mathcal{L}_2 = K(X),\tag{2}
$$

$$
\mathcal{L}_3 = -G_3(X) \Box \phi, \tag{3}
$$

$$
\mathcal{L}_4 = G_4(X)R + G_{4X}[(\Box \phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2], \qquad (4)
$$

$$
\mathcal{L}_5 = G_5(X)G_{\mu\nu}\nabla^{\mu}\nabla^{\nu}\phi - \frac{1}{6}G_{5X}[(\Box\phi)^3
$$

$$
-3\Box\phi(\nabla_{\mu}\nabla_{\nu}\phi)^2 + 2(\nabla_{\mu}\nabla_{\nu}\phi)^3],
$$
(5)

where K , G_3 , G_4 , G_5 are arbitrary functions of $X = -\partial^{\mu}\phi\partial_{\mu}\phi/2$, f_X means $\partial f(X)/\partial X$, $G_{\mu\nu}$ is the Einstein tensor, $(\nabla_{\nu}\nabla_{\nu}\phi)^2 \equiv \nabla_{\nu}\nabla_{\nu}\phi\nabla^{\mu}\phi$, and Einstein tensor, $(\nabla_{\mu} \nabla_{\nu} \phi)^2 \equiv \nabla_{\mu} \nabla_{\nu} \phi \nabla^{\nu} \nabla^{\mu} \phi$, $(\nabla_{\mu}\nabla_{\nu}\phi)^3 = \nabla_{\mu}\nabla_{\nu}\phi\nabla^{\nu}\nabla^{\rho}\phi\nabla_{\rho}\nabla^{\mu}\phi$. The Noether current associated with $\phi \rightarrow \phi + \epsilon$ in SSGG is given by

$$
J^{\mu} = -\partial^{\mu}\phi \left(K_{X} - G_{3X} \Box \phi + G_{4X}R + G_{4XX} [(\Box \phi)^{2} - (\nabla_{\rho} \nabla_{\sigma} \phi)^{2}] + G_{5X} G^{\rho \sigma} \nabla_{\rho} \nabla_{\sigma} \phi \right.\n- \frac{G_{5XX}}{6} [(\Box \phi)^{3} - 3 \Box \phi (\nabla_{\rho} \nabla_{\sigma} \phi)^{2} + 2 (\nabla_{\rho} \nabla_{\sigma} \phi)^{3}] \right)\n- \partial^{\nu} X \left(-\delta^{\mu}_{\nu} G_{3X} + 2 G_{4XX} (\Box \phi \delta^{\mu}_{\nu} - \nabla^{\mu} \nabla_{\nu} \phi) + G_{5X} G^{\mu}_{\nu} - \frac{1}{2} G_{5XX} [\delta^{\mu}_{\nu} (\Box \phi)^{2} - \delta^{\mu}_{\nu} (\nabla_{\rho} \nabla_{\sigma} \phi)^{2} \right.\n- 2 \Box \phi \nabla^{\mu} \nabla_{\nu} \phi + 2 \nabla^{\mu} \nabla_{\rho} \phi \nabla^{\rho} \nabla_{\nu} \phi] \right) + 2 G_{4X} R^{\mu}_{\rho} \nabla^{\rho} \phi + G_{5X} (- \Box \phi R^{\mu}_{\rho} \nabla^{\rho} \phi \right.\n+ R_{\rho \nu}^{\sigma \mu} \nabla^{\rho} \nabla_{\sigma} \phi \nabla^{\nu} \phi + R_{\rho}^{\sigma} \nabla^{\rho} \phi \nabla^{\mu} \nabla_{\sigma} \phi). \tag{6}
$$

We would like to check the explicit form of this current in the spherically symmetric case. To this end, we plug in a general spherically symmetric ansatz,

$$
ds2 = -P(r)dt2 + S(r)dr2 + r2(d\theta2 + sin2\theta d\varphi2), (7)
$$

$$
\phi = \phi(r),
$$
 (8)

which reduces the current to

$$
J^{r} = -\frac{\phi'}{S}K_{X} + \frac{r(\phi')^{2}P' + 4(\phi')^{2}R}{2rPS^{2}}G_{3X} + \frac{2\phi'P - 2\phi'PS + 2r\phi'P'}{r^{2}PS^{2}}G_{4X} - \frac{2(\phi')^{3}P + 2r(\phi')^{3}P'}{r^{2}PS^{3}}G_{4XX} + \frac{(\phi')^{2}SP' - 3(\phi')^{2}P'}{2r^{2}PS^{3}}G_{5X} + \frac{(\phi')^{4}P'}{2r^{2}PS^{4}}G_{5XX}, \quad (9)
$$

where a prime denotes a derivative with respect to the aerial radius coordinate r.

It is worth emphasizing that we are assuming that ϕ respects the symmetries of the metric and, hence, has vanishing Lie derivatives with respect to all Killing vectors. This is the usual assumption in the literature of no-hair theorems and in particular of Ref. [\[28\]](#page-16-4). However, as we have pointed out in Ref. [\[29\]](#page-16-5), one could choose to relax this assumption and require that only the gradient of ϕ has vanishing Lie derivatives. This choice can be justified by the fact that ϕ appears in the field equations only through its gradient, thanks to shift symmetry. Reference [\[30\]](#page-16-6) has discussed this option in more detail. Additionally, no-hair theorems usually concern black holes with flat asymptotics, and hairy black holes with other asymptotics in Horndeski's theory have been found [\[31](#page-16-7)–33].

B. Possible evasions

In Ref. [\[28\],](#page-16-4) it is assumed that the current should be of the form

$$
J^r = \frac{\phi'}{S} F(\phi'; g, g', g''),\tag{10}
$$

where g represents the metric components and F is an unspecified function. Comparing it to Eq. [\(9\),](#page-2-0) this seems to be the case, at least formally, for SSGG. (There actually are no terms with g'' in SSGG.) It is further assumed that F will asymptote to a finite, nonzero constant at spatial infinity, where S, $P \rightarrow 1$ and $\phi' \rightarrow 0$. This is typically valid for a theory featuring a canonical kinetic term in the small field limit, which in turn is a reasonable restriction, as otherwise the scalar will be strongly coupled around the Minkowski vacuum.

We would like to explicitly examine whether these assumptions are always valid. The form of the current in Eq. [\(9\)](#page-2-0) actually leaves room for three different cases. Depending on the exact form of K_X , G_{3X} , G_{4X} , G_{4XX} , G_{5X} , G_{5XX} and performing a Laurent expansion, one has:

(1) Every term in J^r contains positive powers of ϕ' .
This case falls into the reign of the no-h This case falls into the reign of the no-hair theorem [\[28\]](#page-16-4) as one indeed has $F \to -K_X(r \to \infty)$.

(2) J^r contains terms with negative powers of ϕ' .
In this case the current would diverge as ϕ' . In this case the current would diverge as $\phi' \rightarrow 0$. Theories of these types, which correspond to most choices of G_3 , G_4 and G_5 that are nonanalytic as $X \rightarrow 0$, would not admit flat space with a trivial scalar configuration as a solution. Instead, the scalar would be always forced to have a nontrivial configuration, and this would lead to violations of local Lorentz symmetry. If local Lorentz violation would be kept below experimental accuracies these theories could be interesting. However, their study and whether they lead to hairy black hole solutions goes beyond the scope of this paper (and of Ref. [\[28\]\)](#page-16-4).

(3) J^r contains one or more terms with no dependence on ϕ' , but no terms with negative powers of ϕ' .

In this case the current remains finite asymptotically and in flat space, but it is not trivial to determine the asymptotic behavior of F. Hence, this is the case where one could find a loophole to the no-hair theorem.

It is rather easy to guess a choice of functions which would fall under case 3. For example, $G₅$ can be proportional to ln $|X|$, and then the last two terms of Eq. [\(9\)](#page-2-0) will not depend on ϕ' . However, our goal is more ambitious. We would like to identify all of the terms that fall under this category, argue conclusively that they do indeed lead to nontrivial solutions for the scalar in static, spherically symmetric spacetimes, and argue that these terms cannot be excluded from the action without loss of generality or fine-tuning.

If we require the ϕ equation of motion to contain a term independent of ϕ itself, the corresponding term in the Lagrangian should be linear in ϕ , i.e. of the form $\phi A[g]$ up
to a total derivative where $A[g]$ is a diffeomorphism to a total derivative, where $A[g]$ is a diffeomorphism
scalar constructed from the metric and its derivatives scalar constructed from the metric and its derivatives. On the other hand, shift symmetry implies that A itself should be a total derivative. Now, we want the Lagrangian term ϕA in the constant ϕ limit to lead to a contribution to the metric equation of motion that is divergence free and with no more than second-order derivatives. The only choice, by the Lovelock theorem, is then $A = \mathcal{G} \equiv$ $R^{\mu\nu\lambda\kappa}R_{\mu\nu\lambda\kappa} - 4R^{\mu\nu}R_{\mu\nu} + R^2$. Therefore, there is only one term one can have in the Lagrangian that would make a theory fall under case 3 above: ϕ has to have a linear coupling with the Gauss–Bonnet invariant.¹

¹This is the case in four dimensions. In higher dimensions, obviously it should be the highest Lovelock invariant.

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The last statement might seem in contradiction with the example we gave earlier, with $G_5 \propto \ln |X|$. Indeed, the Gauss–Bonnet invariant does not even appear in the generalized Galileon Lagrangian when given in terms of Eqs. (1) – (5) . However, this is just an issue of formalism, and it has been shown in Ref. [\[26\]](#page-16-2) that the term $\alpha\phi\mathcal{G}$ corresponds precisely to the nontrivial choice

$$
K = G_3 = G_4 = 0,
$$
 $G_5 = -4\alpha \ln |X|.$ (11)

 $\ln |X|$ is often written as $\ln X$ in the literature; the later case has to be understood with analytic continuation, as X can be nonpositive.)

One may now check straightforwardly that the present of this term does not allow for a trivial scalar configuration in black hole spacetimes. The current conservation equation $\nabla_{\mu}J^{\mu} = 0$ becomes

$$
\Box \phi + \alpha \mathcal{G} = 0, \tag{12}
$$

if, for example, one makes the choices $K = X$, $G_3 = G_4 = 0$, $G_5 = -4\alpha \ln |X|$. G only vanishes in flat space, which directly implies that ϕ will have to have a nontrivial configuration in any other spacetime, including black hole spacetimes. It is worth stressing that this property will generically persist irrespective of the choices one makes for K , G_3 , G_4 and G_5 , so long as the linear coupling between ϕ and $\mathcal G$ is present.

In summary, the term

$$
\mathcal{L}_{\phi \text{GB}} = \alpha \phi \mathcal{G}
$$

= $\alpha \phi (R^{\mu \nu \rho \sigma} R_{\mu \nu \rho \sigma} - 4R^{\mu \nu} R_{\mu \nu} + R^2)$ (13)

is the only one that falls under the class of shift-symmetric generalized Galileons that does not lead to Lorentz invariance violations and at the same time evades the no-hair theorem of [\[28\]](#page-16-4). When this term is present black holes necessarily have hair.

C. Naturalness

The choice $G_5 = -4\alpha \ln |X|$, or equivalently the term in Eq. [\(13\)](#page-3-1), is certainly special within the full Horndeski theory or generalized Galileons. However, what we have argued above is that any theory that contains it in the action, amongst other terms, will have hairy black holes. Hence, one would need to excise this term in order to get theories in which black holes are the same as those of general relativity. Mathematically this is straightforward. But from an effective field theory's point of view this term has to be present, so long as it is not forbidden by the symmetries of the theory, as it would be generated by quantum corrections even if it were not present at the tree level. In this sense, the evasion of the no-hair theorem is quite generic. One can impose some internal symmetry for the scalar in order to excise the $\phi \mathcal{G}$ term. But the choices are limited as ϕ is real. One possibility is to impose reflection symmetry for the scalar, $\phi \rightarrow -\phi$. This symmetry can indeed do away with the $\phi \mathcal{G}$ term, but it also forbids the \mathcal{L}_3 and \mathcal{L}_5 terms in SSGG, thus significantly reducing the range of validity of the no-hair theorem in theory space.

III. EXPLICIT EXAMPLE: SCALAR-GAUSS– BONNET GRAVITY

In the last section, we showed that the last step of the nohair theorem of Ref. [\[28\]](#page-16-4) does not go through if there is the $\phi \mathcal{G}$ term in the action. Evading the no-hair theorem is certainly essential toward having hairy black holes, but whether they truly exist is another thing. In this section, we will explicitly generate a hairy black hole solution and determine the basic nature of the scalar hair.

We will work on the simplest model with the class of theories that have hairy black holes, that is

$$
S = \frac{m_P^2}{8\pi} \int d^4x \sqrt{-g} \left(\frac{R}{2} - \frac{1}{2} \partial_\mu \phi \partial^\mu \phi + \alpha \phi \mathcal{G}\right), \qquad (14)
$$

where m_P is the Planck mass and α has dimensions of a length squared, to prove the possibility of existence. The Noether current associated with shift symmetry is $J^{\mu} = \sqrt{-g}(\partial^{\mu}\phi + \alpha \tilde{\mathcal{G}}^{\mu})$, where an expression for $\tilde{\mathcal{G}}^{\mu}$ can be found in Appendix B found in Appendix [B.](#page-14-0)

The equations of motion for the metric and the scalar are respectively

$$
G_{\mu\nu} = \mathcal{T}_{\mu\nu},\tag{15}
$$

$$
\Box \phi + \alpha \mathcal{G} = 0, \tag{16}
$$

where the effective energy-momentum tensor is given by

$$
\mathcal{T}_{\mu\nu} = \partial_{\mu}\phi \partial_{\nu}\phi - \frac{1}{2}g_{\mu\nu}(\partial\phi)^{2}
$$

$$
- \alpha(g_{\rho\mu}g_{\delta\nu} + g_{\rho\nu}g_{\delta\mu})\nabla_{\sigma}(\partial_{\gamma}\phi\epsilon^{\gamma\delta\alpha\beta}\epsilon^{\rho\sigma\lambda\eta}R_{\lambda\eta\alpha\beta}). \quad (17)
$$

Some more details of the derivation of the effective energy tensor are given in Appendix [C](#page-14-1). It is worth pointing out that, for a covariant scalar-tensor system, the scalar equation of motion is dynamically redundant, as it is implied by the fact that the energy-momentum tensor is divergence free, which is in turn implied by the contracted Bianchi identity (see e.g. Refs. [\[25,34\]](#page-16-1)). So it is consistent to just solve Eq. [\(15\)](#page-3-2).

Before diving into the details of obtaining black hole solutions, we note that such solutions for theories involving the Gauss–Bonnet term has been discussed before (e.g. Refs. [\[35](#page-16-8)–38]). In fact, black holes with hair have been found in a theory similar to that of [\(14\),](#page-3-3) but with $\phi \mathcal{G}$ replaced with $e^{\phi} \mathcal{G}$ [\[35\]](#page-16-8). The models with $\phi \mathcal{G}$ and $e^{\phi} \mathcal{G}$ are quite distinct in the context of the no-hair proof. The former class enjoys shift symmetry for the scalar, while the latter does not.

A. Spherically symmetric ansatz

We are interested in static, spherically symmetric solutions. The most general ansatz with these symmetries in the Schwarzschild coordinates can be written as

$$
ds^{2} = \eta(-e^{A(r)}dt^{2} + e^{B(r)}dr^{2}) + r^{2}(d\theta^{2} + \sin^{2}\theta d\varphi^{2}),
$$
 (18)

$$
\phi = \phi(r),\tag{19}
$$

where $\eta = 1$ for solutions outside the event horizon and $\eta = -1$ for solutions inside the horizon. Substituting this ansatz into the equations of motion [\(15\)](#page-3-2) and [\(16\)](#page-3-4), the nontrivial components of the modified Einstein equation become

$$
tt:0 = 16\alpha(\eta - e^{-B})\phi'' + 8\alpha(3e^{-B} - \eta)\phi'B'
$$

$$
+ \eta r^2 \phi'^2 - 2\eta rB' - 2e^{B} + 2\eta,
$$
 (20)

$$
rr:0 = (e^{B})^{2} + 12\alpha\phi' A'
$$

$$
- \eta \left(1 + rA' + 4\alpha\phi' A' - \frac{1}{2}r^{2} \phi'^{2}\right) e^{B}, (21)
$$

$$
\theta\theta:0 = 16\eta\alpha(\phi'A'' + \phi''A') - 2re^{B}A'' + 8\eta\alpha(A' - 3B')A'\phi' - 2re^{B}\phi'^{2} - re^{B}(A' - B')A' - 2e^{B}(A' - B'),
$$
 (22)

and the ϕ equation of motion is

$$
\phi: 0 = 8\alpha (\eta e^{-B} - 1)A'' + 2r^2 \phi'' + r^2 (A' - B')\phi' + 4\alpha (1 - 3\eta e^{-B})A'B' + 4\alpha (\eta e^{-B} - 1)A'^2 + 4r\phi'.
$$
 (23)

Explicit expressions for $\Box \phi$, $\mathcal G$ and the nonzero components of $G_{\mu\nu}$, $T_{\mu\nu}$ are given in Appendix [C 1](#page-14-2). We will mainly solve the components of the modified Einstein equation and occasionally make use of the scalar equation of motion. Algebraically solving the rr component, we obtain

$$
e^{B} = \frac{-\Gamma + \xi\sqrt{\Gamma^{2} - 48\alpha\phi' A'}}{2}, \qquad \xi = \pm 1, \qquad (24)
$$

where

$$
\Gamma = -\eta \bigg(1 + rA' + 4\alpha \phi' A' - \frac{1}{2} r^2 \phi'^2 \bigg). \tag{25}
$$

Assuming the usual $1/r$ falloff for the metric and ϕ as $r \to \infty$, as we are interested in asymptotically flat solutions, one gets $\Gamma \rightarrow -1$. This implies that we should select the $\xi = +1$ branch in Eq. [\(24\).](#page-4-0)²

Taking a derivative of the rr component with respect to r, one can obtain an expression for $B'(r)$. Using these
expressions for B and B' we can recast the tt and $\theta\theta$ expressions for B and B', we can recast the tt and $\theta\theta$
components as components as

$$
\phi''(r) = f(r, \phi', A'; \alpha, \eta), \tag{26}
$$

$$
A''(r) = g(r, \phi', A'; \alpha, \eta). \tag{27}
$$

This is a closed dynamical system of ordinary differential equations (ODEs) where $\phi'(r)$ and $A'(r)$ are dynamical
variables and α and n are input constants $f(\phi' | A'(\alpha, n))$ and variables and α and η are input constants. $f(\phi', A'; \alpha, \eta)$ and $g(\phi' | A'; \alpha, \eta)$ can be straightforwardly obtained using a $g(\phi', A'; \alpha, \eta)$ can be straightforwardly obtained using a symbolic computation but we will refrain from displaying symbolic computation, but we will refrain from displaying them here, as they are rather cumbersome.

Obtaining explicit solutions of the ODE system given by [\(26\)](#page-4-1) and [\(27\)](#page-4-2) analytically is a hard task. In what comes next we will follow two routes in parallel. We will seek for exact solutions numerically, and we will also obtain solutions analytically in the limit where α is small compared to the characteristic length scale of the system (smallcoupling limit). But before doing so, we will gain some insight on the basic characteristics of the solutions we should expect to obtain by studying the approximate solutions at spatial infinity and near the horizon.

B. Approximate solutions at spatial infinity

We are interested in asymptotic flat solutions, so as $r \to \infty$ we have $e^A \to 1$, $e^B \to 1$ and $\phi' \to 0$. We can then exploit shift symmetry and set $\phi|_{r\to\infty} \to 0$. To explore the behavior of the solution at spatial infinity, we expand, as a power series in $1/r$,

$$
e^{A(r)} = 1 + \sum_{n=1}^{\infty} c_n^A / r^n,
$$
 (28)

$$
e^{B(r)} = 1 + \sum_{n=1}^{\infty} c_n^B / r^n,
$$
 (29)

$$
\phi(r) = \sum_{n=1}^{\infty} c_n^{\phi} / r^n,
$$
\n(30)

where c_n^A , c_n^B and c_n^{ϕ} are constants to be determined.
Substituting these series into Eqs. (20)–(22) we can Substituting these series into Eqs. (20) – (22) , we can perturbatively solve to get, to order $1/r⁴$,

$$
e^{A}(r) = 1 - \frac{2M}{r} + \frac{MP^{2}}{6r^{3}} + \frac{M^{2}P^{2} + 24\alpha MP}{3r^{4}} + \mathcal{O}\left(\frac{1}{r^{5}}\right),
$$
\n(31)

²A softer falloff would lead to the same result but would require a more convoluted argument.

$$
e^{B(r)} = 1 + \frac{2M}{r} + \frac{8M^2 - P^2}{2r^2} + \frac{16M^3 - 5MP^2}{2r^3} + \frac{192M^4 - 104M^2P^2 - 192\alpha MP + 3P^4}{12r^4} + \mathcal{O}\left(\frac{1}{r^5}\right),
$$
\n(32)

$$
\phi(r) = \frac{P}{r} + \frac{MP}{r^2} + \frac{16M^2P - P^3}{12r^3} + \frac{6M^3P - 12\alpha M^2 - MP^3}{3r^4} + \mathcal{O}\left(\frac{1}{r^5}\right), \quad (33)
$$

where we have used geometrized units with m_P set to 1. As can be defined by usual boundary integrals, here M is the Arnowitt-Deser-Misner (ADM) mass of the potentially existing black hole, and P is the scalar charge, which potentially is the extra scalar "hair." Hence, generically there will be a two-parameter family of solutions. This could have been expected since, thanks to spherical symmetry, Eqs. (26) and (27) can be thought of as an initial value problem with r playing the role of "time." On a given r , one needs to provide 2 pieces of initial data, the values of A' and ϕ' there.

C. Approximate solutions near the horizon

We are interested in black hole solutions, so we will assume that there is an event horizon at $r = r_h$. Thus, we should have $e^A|_{r \to r_h^+} \to 0^+$ outside the horizon $(e^{A}|_{r\to r_h^-} \to 0^-$ inside the horizon), where $r \to r_h^+$ $(r \to r_h^{-1})$ means approaching the horizon from outside
(inside) the horizon That is we have A^{\prime} $\mapsto \pm \infty$ when (inside) the horizon. That is, we have $A'|_{r \to r_h^+} \to +\infty$ when $\eta = 1$ (A'|_{r→r_n} → -∞ when $\eta = -1$).

As $r \to r_h^{\pm}$ and $A'|_{r \to r_h^{\pm}} \to \pm \infty$, we can see from Eq. [\(24\)](#page-4-0) that

$$
e^{B} \rightarrow \frac{1+\text{sign}(r+4\alpha\phi_{h}^{\prime})}{2}(r+4\alpha\phi_{h}^{\prime})\eta A^{\prime}|_{r\rightarrow r_{h}^{\pm}}, \quad (34)
$$

where we have assumed that ϕ' is continuous near the event horizon and thus the limit $\phi'_h \equiv \phi'|_{r \to r_h^{\pm}}$ exists. e^B should diverge near the horizon which implies that diverge near the horizon, which implies that

$$
r_h + 4\alpha \phi'_h > 0. \tag{35}
$$

Then Eq. [\(24\)](#page-4-0) can be expanded near the horizon as

$$
e^{B} = \eta \left[(4\alpha\phi' + r)A' - \left(\frac{r^2\phi'^2}{2} + \frac{8\alpha\phi' - r}{4\alpha\phi' + r} \right) \right] + \mathcal{O}\left(\frac{1}{A'}\right). \tag{36}
$$

Substituting this expression into Eq. [\(26\)](#page-4-1) and [\(27\)](#page-4-2), we have

$$
\phi'' = -\frac{(4\alpha\phi' + r)[r^2\phi'(4\alpha\phi' + r) + 12\alpha]}{r^3(4\alpha\phi' + r) - 96\alpha^2}A' + \mathcal{O}(1),\tag{37}
$$

$$
A'' = -\frac{r^2(4\alpha\phi' + r)^2 - 48\alpha^2}{r^3(4\alpha\phi' + r) - 96\alpha^2}A'^2 + \mathcal{O}(A').
$$
 (38)

For ϕ'' to be finite on the horizon one needs to have $r_h^2 \phi'_h (4\alpha \phi'_h + r_h) + 12\alpha = 0$, which yields

$$
\phi'_h = \frac{-r_h^2 \pm \sqrt{r_h^4 - 192\alpha^2}}{8\alpha r_h}.
$$
 (39)

This equation can be interpreted as a regularity condition for ϕ on the horizon. As discussed previously, one can formulate the problem of generating a solution to Eqs. [\(26\)](#page-4-1) and (27) as an initial value problem, with r playing the role of "time". Then the values of ϕ' and A' on the initial hypersurface would serve as initial data. For a black hole solution it would be most convenient to choose the horizon as the initial hypersurface, as this guarantees that a horizon actually exists. However, Eq. [\(39\)](#page-5-0) fixes the value of ϕ' there. At the same time A' diverges on the horizon by definition, so the only piece of data that is free to choose is r_h , the actual location of the horizon (which will then determine the ADM mass of the black hole). Hence, one expects that there will be a one-parameter family of black hole solutions. This is to be contrasted with the asymptotic behavior of a generic solutions, explored in the previous section, which was found to have two independent charges. We can conclude that regularity on the horizon fixes the scalar charge in terms of the mass of the black hole.

For ϕ'_h to be real, one additionally needs that

$$
r_h > r_h^M \equiv 2\sqrt{2\sqrt{3}|\alpha|}.
$$
 (40)

As we shall see in more detail below, $r_h^M = 2\sqrt{2\sqrt{3}|\alpha|}$ is the minimum size a black hole can have for a given α the minimum size a black hole can have for a given α . Solutions that do not meet this criterion have naked singularities. Note that this condition is consistent with $4\alpha\phi'_h + r_h > 0$, as it should be.

D. Numerical implementation and a fiducial solution

We have already mentioned that the strategy we intend to follow in order to numerically generate a solution will be to start from the horizon and integrate outward and inward. For a given value of the coupling α , different values for the horizon radius would correspond to solutions with a different mass (as we will demonstrate in detail later). One could decide to fix the dimensionless parameter α/r_h^2 and generate the solution for $r_h = 1$. Then, solutions with different horizon radii (and masses) could be simply different horizon radii (and masses) could be simply generated by appropriately rescaling the radial coordinate. It should be stressed that this process generates (after the rescaling) a family of solutions with not only different masses but also different couplings α (as it is α/r_h^2 that is held fixed). However, it allows one to explore a range of held fixed). However, it allows one to explore a range of couplings and masses by scanning only the onedimensional parameter space of α/r_h^2 , instead of the
two-dimensional parameter space of (r, α) two-dimensional parameter space of (r_h, α) .

A numerical issue that one has to face is that the regularity constraint of Eq. [\(39\)](#page-5-0) cannot be imposed numerically with any sensible accuracy. This should be clear from the fact that the first term on the rhs of Eq. [\(37\)](#page-5-1) is seen as an unresolvable $0 \times \infty$ by any finite-accuracy calculator. To circumvent this problem, one can generate a perturbative solution around $r = r_h$. Then one can make use of this perturbative solutions in order to calculate ϕ' and A' at a distance ϵr_h from the horizon, both inward and outward, and start the numeric integration from these radii, r_{+} . This is the method we have followed. We have actually set $\epsilon = 10^{-9}$ and used linear perturbation theory for calculating $A'(r_{\pm})$, whereas we have taken for $\phi'(r_{\pm})$ to be simply the negative-sign root of Eq. (39). Choosing the negative-sign positive-sign root of Eq. [\(39\).](#page-5-0) Choosing the negative-sign root would in principle correspond to a second branch of solutions, but in practice numerics do not generate a sensible solution. Our approximation for $A'(r_{\pm})$ and $A'(r_{\pm})$ might seem to be crude. However, one can use $\phi'(r_{\pm})$ might seem to be crude. However, one can use
the continuity of ϕ'' as one approaches the borizon from the the continuity of ϕ'' as one approaches the horizon from the two sides as an indicator of accuracy for our approximation, and we find the values to match to order 10^{-9} . We use the Maple ODE solver $rk45$ with the error control parameters abserr and relerr set to 10^{-12} and 10^{-10} respectively and the environment viable Digits set to 15.

It is worth noting that action (14) is invariant under the combined operation $\phi \to -\phi$ and $\alpha \to -\alpha$. Therefore, we can choose $\alpha > 0$ without lost of generality, as the solutions with α < 0 can be simply obtained from the corresponding $\alpha > 0$ solutions with ϕ replaced by $-\phi$.

As a preview to our results, we show a few characteristic quantities of a fiducial black hole solution with α/r_h^2 = quantities of a fiducial black hole solution with $\alpha/r_h^2 = 0.001$ $\alpha/r_h^2 = 0.001$ in Fig. 1. The most prominent feature is the presence of a finite surface singularity, which is nevertheless cloaked by the horizon if $r_h > r_h^M \equiv 2\sqrt{2\sqrt{3}|\alpha|}$. Finite surface singularities are not surprising for a theory involving the Gauss–Bonnet term. For example, they have also been observed in Gauss–Bonnet gravity in higher dimensions without coupling to a scalar [\[36,37\]](#page-16-9) or Gauss–Bonnet gravity coupling to a non-shift-symmetric scalar [\[35\]](#page-16-8). We will return to the issue of the finite area singularity in the next section, after deriving first perturbative solutions in the small-coupling limit. This will give us the opportunity to compare these perturbative solutions with the full numerical one and understand the role of nonperturbative effects.

E. Perturbative solutions in the small-coupling limit

We now turn out attention to finding a perturbative solution in the small-coupling limit. We can consider the horizon radius r_h as a characteristic length associated with our solution. Then one can define the dimensionless parameter $\tilde{\alpha} \equiv \alpha/r_h^2$ and attempt to generate a solution perturbative in the limit $\tilde{\alpha} \ll 1$ perturbative in the limit $\tilde{\alpha} \ll 1$.

If $\tilde{\alpha}$ were zero, the theory would reduce to general relativity minimally coupled to a scalar, and we would have the standard Schwarzschild solution. Adding the scalar-Gauss–Bonnet term with a small $\tilde{\alpha}$ induces a perturbatively deformed Schwarzschild solution, which we assume to be

$$
ds^{2} = -\left(1 - \frac{2m}{r}\right)\left(1 + \sum_{n=1} A_{n}(r)\tilde{\alpha}^{n}\right)^{2}dt^{2} + \left(1 - \frac{2m}{r}\right)^{-1}\left(1 + \sum_{n=1} B_{n}(r)\tilde{\alpha}^{n}\right)^{2}dr^{2} + r^{2}(d\theta^{2} + \sin^{2}\theta d\varphi^{2}).
$$
\n(41)

FIG. 1 (color online). A fiducial solution with $\alpha/r_h^2 = 0.001$. r_h is the horizon radius (black, long-dashed vertical line), which is used
as the unit of length. There is a finite radius singularity $(r \approx 0.2689r)$, ind as the unit of length. There is a finite radius singularity ($r \approx 0.2689r_h$), indicated by the red, dotted vertical line. (a): The scalar field $\phi(r)$, normalized to 0 at spatial infinity; (b): The metric component $g_{00} = -\eta e^{A(r)}$ ($\eta = 1$ for $r > r_h$ and $\eta = -1$ for $r < r_h$); (c): The Gauss-Bonnet invariant G.

The scalar is assumed to be

$$
\phi' = \sum_{n=1}^{\infty} \phi'_n(r) \tilde{\alpha}^n.
$$
 (42)

Note that we used m in the metric, rather than M (the mass of the black hole as measured by a far-away observable), because they may be different.

Substituting these Ansätze into the equations of motion Eqs. [\(20\),](#page-4-3) [\(21\)](#page-4-5), [\(22\)](#page-4-4) and [\(23\),](#page-4-6) and solving order by order in $\tilde{\alpha}$, one obtains a perturbative solution. In a slight abuse of notation, in what follows we will set $r_h = 1$ and drop the twiddle, identifying α and $\tilde{\alpha}$. r and m should be then effectively measured in units of r_h , similarly to our numerical solutions.

Note that the approach we follow in the section has been followed in Ref. [\[39\]](#page-16-10) for a more general theory that includes general couplings between the scalar and the Chern–Simons and Gauss–Bonnet invariants. However, a weak field limit approximation was additionally employed, and it was assumed that the coupling functions are dominated by the linear term in this limit. Under these assumptions the Chern–Simons term gives no contribution to second-order in the coupling, and, hence, the solutions we will present below are in full agreement with those of Ref. $[39]$ ³

1. First order

We had stated earlier that one could obtain a consistent solution by solving the modified Einstein equation alone and ignoring the scalar equation. However, in the perturbative treatment it is significantly simpler to solve the scalar equation itself in order to determine ϕ at each order. The first-order equations of motion are

$$
(r - 2m)B'_1 + B_1 = 0, \t(43)
$$

$$
(r - 2m)A'_1 - B_1 = 0, \t(44)
$$

$$
r(r-2m)A_1'' + (r+m)A_1' - (r-m)B_1' = 0,\t(45)
$$

$$
(r-2m)r5\phi''1+2(r-m)r4\phi'1+48m2=0,
$$
 (46)

where Eq. [\(46\)](#page-7-0) is the scalar equation of motion. Imposing the boundary conditions that A_1 , B_1 and ϕ'_1 vanish at spatial
infinity, these equations can be easily solved infinity, these equations can be easily solved,

$$
A_1 = \frac{c_1}{r - 2m},\tag{47}
$$

$$
B_1 = -\frac{c_1}{r - 2m},\tag{48}
$$

$$
\phi_1' = \frac{16m^2 - c_2r^3}{r^4(r - 2m)},\tag{49}
$$

where c_1 and c_2 are undetermined constants. We also have boundary conditions at the horizon and the requirement that the perturbative expansion should remain under control, which leads to

$$
c_1 = 0,
$$
 $c_2 = \frac{2}{m},$ (50)

and so

$$
A_1 = 0, \qquad B_1 = 0, \qquad \phi'_1 = -\frac{2(r^2 + 2mr + 4m^2)}{mr^4}.
$$
\n(51)

Therefore, to leading perturbative order, the metric is not modified by the scalar configuration. This is the solution that is given in Ref. [\[29\].](#page-16-5) By comparing with the asymptotic solution at $r \to +\infty$, the ADM mass and the scalar charge at this order are

$$
M = m, \qquad P = \frac{2\alpha}{M}.
$$
 (52)

As expected, the scalar charge is fixed for a given mass, due to the regularity condition at the horizon. It is remarkable that, as the mass increases, the scalar charge has to decrease for a given coupling α .

Before going further, one should mention that, depending on how action [\(14\)](#page-3-3) arises from a more fundamental theory, it might or it might not make sense to go further in perturbation theory. In particular, suppose α is some order parameter and the action is the product of a truncation to order α . Then clearly one cannot trust solutions beyond that order, as terms of order α^2 have been neglected in the action (and field equations as a consequence). In this case, the numerical solution discussed in the previous section is not particularly useful, as it would anyway be valid only in the range in which it agrees with the perturbative solution just presented. On the other hand, if the action is taken to be exact and not the product of a truncation, then it is worth going to next-to-leading order in perturbation theory in order to obtain a correction to the metric and also be able to compare with the numerical solution (which would then be the full solution).

2. Second order

Proceeding to the next order with the help of the firstorder solutions, the tt and rr components of the modified Einstein equation and the scalar equation of motion can be cast as respectively

 3 In Ref. [\[39\]](#page-16-10), a consistent condition for the perturbative regime to be valid has also been established, which translated to α^2/r_h^4 < $15/1444$ in our formalism. Our consistency condition based on the full solution, i.e. Eq. (40) , is stronger. the full solution, i.e. Eq. [\(40\),](#page-5-2) is stronger.

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$$
4r^{7}(r-2m)^{2}[(r-2m)B'_{2}+B_{2}]-\frac{4}{m^{2}}r^{7} + \frac{8}{m}r^{6}-192r^{5}+768mr^{4}-768m^{2}r^{3} +3072m^{3}r^{2}-12032m^{4}r+11776m^{5}=0,
$$
 (53)

$$
4r^{7}(r-2m)^{2}[(2m-r)A'_{2}+B_{2}]+\frac{4}{m^{2}}r^{7}-\frac{8}{m}r^{6}-64r^{5}+256mr^{4}-256m^{2}r^{3}+512m^{3}r^{2}-2304m^{4}r+2560m^{5}=0,
$$
 (54)

 $r(r-2m)\phi'_2 + 2(r-m)\phi_2 = 0.$ (55)

The equations can be solved to give

$$
A_2 = \frac{r^2}{15m(r-2m)^2} \left(15 \frac{c_3 m}{r} - 30 \frac{c_3 m^2}{r^2} + \frac{5}{r^3} + 120 \frac{m}{r^4} - 194 \frac{m^2}{r^5} - 36 \frac{m^3}{r^6} - 592 \frac{m^4}{r^7} + 800 \frac{m^5}{r^8} \right),
$$
 (56)

$$
B_2 = \frac{-1}{r - 2m} \left(c_3 + \frac{1}{m^2 r} + \frac{1}{mr^2} + \frac{52}{3r^3} + 2\frac{m}{r^4} + \frac{16m^2}{5r^5} - \frac{368m^3}{3r^6} \right),
$$
 (57)

$$
\phi_2 = \frac{c_4}{r(r - 2m)},\tag{58}
$$

where c_3 and c_4 are integration constants. Now, we require A_2 , B_2 and ϕ_2 to be controlled perturbations at $r = 2m$, and this imposes

$$
c_3 = -\frac{49}{40m^3}, \qquad c_4 = 0,\tag{59}
$$

and so

$$
A_2 = -\frac{49}{40m^3r} - \frac{49}{20m^2r^2} - \frac{137}{30mr^3} - \frac{7}{15r^4} + \frac{52m}{15r^5} + \frac{40m^2}{3r^6},
$$
 (60)

$$
B_2 = \frac{49}{40m^3r} + \frac{29}{20m^2r^2} + \frac{19}{10mr^3} - \frac{203}{15r^4} - \frac{436m}{15r^5} - \frac{184m^2}{3r^6},
$$
 (61)

 $\phi_2 = 0.$ (62)

By comparing to the asymptotic solution as $r \to +\infty$, the ADM mass and the scalar charge up to second order are

$$
M = m\left(1 + \frac{49\alpha^2}{40m^4}\right), \qquad P = \frac{2\alpha}{M}.
$$
 (63)

Now, the Ricci scalar and the Gauss–Bonnet invariant can be computed analytically up to $\mathcal{O}(\alpha^2)$:

$$
R = \left(\frac{16}{r^6} - \frac{32m}{r^7} - \frac{64m^2}{r^8} + \frac{4}{r^4m^2} + \frac{8}{r^5m} - \frac{128m^3}{r^9}\right)\alpha^2 + \mathcal{O}(\alpha^3)
$$
(64)

$$
\mathcal{G} = \frac{48m^2}{r^6} + \left(\frac{588}{5m^2r^6} - \frac{64}{mr^7} - \frac{32}{r^8} - \frac{4608m}{r^9} - \frac{448m^2}{r^{10}} - \frac{4096m^3}{5r^{11}} + \frac{53760m^4}{r^{12}}\right)\alpha^2 + \mathcal{O}(\alpha^3). \tag{65}
$$

From Eqs. [\(64\)](#page-8-0) and [\(65\)](#page-8-1), we see that the feature of the finite radius singularity is not captured in the perturbative solution up to $\mathcal{O}(\alpha^2)$, which is the first correction to the Schwarzschild geometry. See Fig. [2](#page-8-2), for example, for a comparison of the Gauss–Bonnet invariant between the numerical full and perturbative solutions for a fiducial α/r_h^2 .

However, since A_2 , B_2 and $\mathcal{G}^{(2)}$ (the α^2 order of \mathcal{G}) tend to infinity as $r \to 0$, the perturbative expansion in α breaks down at some small enough r where either $\alpha^2 A_2$ or $\alpha^2 B_2$ becomes $\mathcal{O}(1)$, or $\mathcal{G}^{(2)}$ becomes $\mathcal{O}(48m^2/r^6)$. It turns out that $\mathcal{G}^{(2)}$ becomes $\mathcal{O}(48m^2/r^6)$ first when r runs to small values for a black hole solution. In Fig. [\(3](#page-9-0)), we have also plotted the radius for which $|G^{(2)}| = 48m^2/r^6$. Presumably, perturbation, theory, actually, breaks, down, before $|G^{(2)}|$ perturbation theory actually breaks down before $|\mathcal{G}^{(2)}|$

FIG. 2 (color online). Comparison of the Gauss–Bonnet invariant between the numerical full solution and the $\mathcal{O}(\alpha^2)$ perturbative solution. α is chosen as $\alpha/r_h^2 = 0.001$, where r_h is the horizon radius (black long-dashed vertical line). The red dotted horizon radius (black, long-dashed vertical line). The red, dotted vertical line ($r \approx 0.2689r_h$) is the finite radius singularity of the full solution.

FIG. 3 (color online). The red, solid line is the radius of the finite singularity surface as a (numerical) function of the Gauss– Bonnet coupling α , computed from the full numerical solution. r_h is the horizon radius (black, long-dashed horizontal line). The green, dot-dashed vertical line is the largest value α/r_h^2 can take
without the solution having a naked singularity. The blue-dotted without the solution having a naked singularity. The blue, dotted line is the radius where the perturbation solution in Sec. [III E](#page-6-1) breaks down, i.e. where the $\mathcal{O}(\alpha^2)$ correction in Eq. [\(65\)](#page-8-1) becomes comparable with the leading order.

reaches $48m^2/r^6$, but we expect the radius at which the two quantities are equal to closely track the finite area singularity radius.

F. Phenomenology

Astronomical observations of black holes and their vicinities have been getting more and more precise and are expected to become an important way to detect possible deviations from general relativity in the near future. In this section we will compute some common observational quantities for the black hole solutions we have generated, and we will compare them to those of the Schwarzschild black hole. These deviations can be used to constrain the linear scalar Gauss–Bonnet coupling $\phi \mathcal{G}$ through confrontation with current and near future experiments. Such constraints can actually be thought of as constraining the possibility of having black holes with scalar hair in SSGG, as we have shown that the linear scalar Gauss–Bonnet coupling is essential for the existence of scalar hair.

Following the lines of Ref. [\[40\]](#page-16-11), we will compute, for different values of α , the innermost stable circular orbit (ISCO) angular frequency, the maximum redshift from the ISCO and the impact parameter of the circular photon orbit. We will provide definitions for these quantities shortly (see e.g. Ref. [\[41\]](#page-16-12) for an discussion on these observables). We will also compute the gravitational radius, defined as

$$
r_g = 2M,\t\t(66)
$$

where M is the ADM mass of the black hole, extracted at spatial infinity as $g_{00} = 1 - r_g/r + \mathcal{O}(1/r^2)$. For the Schwarzschild solution, this is the same as r_h . But r_h and r_g do not generically coincide for black holes that are not solutions of general relativity.

For a massive test particle, there exists the innermost stable circular orbit around a spherical black hole. This orbit occurs when the maximum and the minimum of the effective potential for the radial motion become degenerate. The ISCO radius r_{ISCO} can be determined by the following equation, using the metric [\(18\)](#page-4-7) with $\eta = 1$:

$$
3A' - rA'^2 + rA'' = 0.
$$
 (67)

The ISCO angular frequency is given by

$$
\omega_{\text{ISCO}} = \sqrt{\frac{e^A A'}{2r}}\Big|_{\text{ISCO}}.\tag{68}
$$

A photon emitted by a source at the ISCO is redshifted when observed at infinity. The maximum redshift for a photo emitted from the ISCO is given by

$$
z_M = e^{-\frac{A}{2}} \frac{\sqrt{2} + \sqrt{A'r}}{\sqrt{2 - A'r}} \Big|_{\text{ISCO}} - 1. \tag{69}
$$

A photon can also have a circular orbit, which occurs at

$$
-2 + rA' = 0.
$$
 (70)

The impact parameter for the photon circular orbit is given by

$$
b_{\rm ph} = \frac{r}{\sqrt{e^A}} \Big|_{\rm ph},\tag{71}
$$

and its angular frequency is simply $\omega_{ph} = 1/b_{ph}$.

In Figs. ([4\)](#page-10-0) and [\(5\)](#page-10-1) we show the fractional deviation of the gravitational radius r_q and the ISCO radius from the horizon radius r_h and the general relativity ISCO radius $r = 3r_h$ respectively. Figures [\(6\)](#page-10-2), [\(7\)](#page-10-3) and ([8\)](#page-11-1) are plots of the fractional deviations of a certain quantity from the value it would have for a Schwarzschild black hole for different values of the coupling α . Figure ([6](#page-10-2)) is for the dimensionless quantity $\omega_{\text{ISCO}} r_g$, Fig. [\(7\)](#page-10-3) for z_M and Fig. ([8\)](#page-11-1) for the dimensionless quantity $b_{\rm ph}/r_{\rm g}$. From these plots, one can clearly see that for the spherical black hole solution the deviations from general relativity induced by the scalar Gauss–Bonnet coupling is negligibly small, as long as we impose that the finite radius singularity be cloaked by the horizon. For the extreme case where the finite radius singularity is barely cloaked by the horizon, the deviations from general relativity for $\omega_{\text{ISCO}}r_q$, z_M and b_{ph}/r_q are less than \sim 5%.

FIG. 4 (color online). Comparison between the gravitational radius $r_g = 2M$, where M is the ADM mass of the black hole and the horizon radius r_h . The green, dot-dashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity singularity.

FIG. 6 (color online). Fractional deviation of the ISCO angular frequency times the gravitational radius, $\omega_{\text{ISCO}} r_q$, from the value it would have in general relativity, denoted as (GR). The green, dot-dashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity the solution having a naked singularity.

FIG. 5 (color online). Comparison between the ISCO radius $r_{\rm ISCO}$ and the general relativity ISCO radius $3r_h$. The green, dotdashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity solution having a naked singularity.

It is worth pointing out that in the latter three figures, those for $\omega_{\text{ISCO}}r_g$, z_M and b_{ph}/r_g , we do not consider values of α as low as in the figures for r_g and r_{ISCO} . This is because in order to compute $\omega_{\text{ISCO}}r_g$, z_M and b_{ph}/r_g one needs to numerically solve Eq. [\(67\)](#page-9-1) or Eq. [\(70\)](#page-9-2) as an intermediate step, which intrinsically reduces the numerical accuracy. Going to smaller values of a/r_h^2 would require more accuracy in the numerical implementation, but that seems unnecessary, given that the deviation from general relativity

FIG. 7 (color online). Fractional deviation of the maximum redshift of a photo emitted from the ISCO, z_M , from the value it would have in general relativity, denoted as (GR). The green, dotdashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity solution having a naked singularity.

is already very small for the values of α/r_h^2 computed, and for smaller α/r_h^2 one can safely use the perturbative
solution we have obtained in Sec. III E solution we have obtained in Sec. [III E](#page-6-1).

The exact, numerical solution has been used to produce all of the plots. One may wonder how well the perturbative solution approximates the full numerical one. Figure [2](#page-8-2) already suggests that the $\mathcal{O}(\alpha^2)$ approximation is relatively good sufficiently far from the finite area singularity. The

FIG. 8 (color online). Fractional deviation of the impact parameter of the photon circular orbit over the gravitational radius, b_{ph}/r_q , from the value it would have in general relativity, denoted as (GR). The green, dot-dashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity singularity.

presence of the latter appears to be a highly nonlinear effect, so one expects the perturbative solution to become less and less accurate as the finite radius singularity of the black hole approaches the horizon, i.e., as α approaches $r_h^2/8\sqrt{3}$. In practice, we find that, even when *α* is only slightly less than $r_s^2/8\sqrt{3}$ the $O(\alpha^2)$ perturbative solution slightly less than $r_h^2/8\sqrt{3}$, the $\mathcal{O}(\alpha^2)$ perturbative solution
at most deviates from the full solution by a few percents for at most deviates from the full solution by a few percents for the quantities we consider. See e.g. Fig. [9](#page-11-2) for a comparison between the ISCO radius of the numerical and the perturbative solution. If we were to plot the corresponding

FIG. 9 (color online). r'_{ISCO} and r''_{ISCO} are the ISCO radii for the numerical and perturbative solutions respectively. The green dotnumerical and perturbative solutions respectively. The green, dotdashed vertical line is the largest value α/r_h^2 can take without the solution having a naked singularity solution having a naked singularity.

quantities computed from the perturbative solution in Figs. 4–[8,](#page-10-0) the perturbative solution line would overlap with the full solution line until when α is very close to $r_h^2 / 8\sqrt{3}$.

IV. CONCLUSIONS

We have investigated the existence of hairy black holes in the shift-symmetric generalized Galileon, which is the most general scalar-tensor theory that has shift symmetry for the scalar and of which the equations of motion have up to second-order derivatives. A no-hair theorem for static, spherically symmetric black holes in this theory has been put forward in Ref. [\[28\].](#page-16-4) In Ref. [\[29\]](#page-16-5) we showed that one assumption in the last step of the proof does not generically hold in SSGG. We have elaborated on this point further and argued in detail that there are two cases in which the assumption does not hold: (1) models of SSGG that are Lorentz violating and (2) and theories that are fully Lorentz invariant and where a linear scalar-Gauss–Bonnet coupling $\phi \mathcal{G}$ is present in the Lagrangian. From the effective field theory point of view, it seems unnatural to exclude this scalar-Gauss–Bonnet operator, as it is not forbidden by the underlying symmetries of the theory. So in a sense the existence of hairy black holes seems to be a generic feature of SSGG.

The evasion of the no-hair arguments does not necessarily imply the actual existence of hairy black holes. To show that hairy black holes do indeed exist we have presented here explicit numerical solutions in the theory of [\(14\)](#page-3-3), the simplest in the evading Lagrangian containing the term [\(13\)](#page-3-1). These solutions features a finite surface singularity, which is cloaked by the event horizon if the coupling constant α is sufficiently small. Black holes of this type have a minimum size for a given coupling α . The scalar hair is secondary, according to the terminology of Ref. [\[16\]](#page-15-8), i.e. the scalar charge is not an independent parameter, but it is instead fixed in terms of the mass of the black hole. This last condition is imposed by the requirement that the scalar be regular on the horizon. Note that the fact that the scalar hair is secondary does not necessarily make them any less noteworthy. In our case, since the mass of the black hole and the scalar hair are related, changes in the scalar configuration can affect the black hole mass and vice versa.

We have also constructed analytic solutions perturbatively up to second order in the small α limit. The advantage of these solutions is that they are explicit, and this makes their properties more obvious. Remarkably, at first order in the coupling the spacetime does not deviate from the Schwarzschild solution, and one simply has a nontrivial configuration of the scalar field in this geometry. The scalar charge is already fixed in terms of the mass at this order. This solution might be considered the only solution one can trust if the action is considered a product of some truncation, with α being the expansion parameter, as in this

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case $\mathcal{O}(\alpha^2)$ corrections in the action and field equation would have been anyway neglected. The perturbative solution to $\mathcal{O}(\alpha^2)$ deviates from the Schwarzschild metric. The scalar field profile instead does not receive any $\mathcal{O}(\alpha^2)$ corrections. To this order, the perturbative solution fails to capture the presence of a finite area singularity. In fact, we have shown that the perturbative approximation breaks down in the vicinity of the finite area singularity radius. Hence, one can conclude that nonlinear effects associated with the ϕ G term should be crucial for the formation of this singularity. On the other hand, in the regime where the small coupling perturbative treatment is valid, the perturbative solution seems to be an excellent approximation of the full numerical solution.

Finally, we have investigated the phenomenological properties of the black holes we have generated. We have computed several observables for different values of the coupling α . If we require the finite radius singularity be well within the horizon, the deviations from the Schwarzschild black hole are negligibly small. Hence, it would be rather challenging to detect the presence of a linear scalar-Gauss–Bonnet coupling using black hole observations, even with upcoming astronomical observations. However, any result in this direction should be considered highly preliminary for two reasons. First, astrophysical black holes are rotating, and our black holes do not capture this feature. Certain effects might be much more sensitive to rotation. Additionally, perturbation of these black holes will involve an extra scalar excitation, which could lead to detectable deviation from general relativity. (Examples that support both claims can be found in Refs. [\[42](#page-16-13)–45]).

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APPENDIX A: MOST GENERAL SHIFT-SYMMETRIC GENERALIZED GALILEON

In this section, we will identify the most general shiftsymmetric subset of generalized Galileons [\[24\]](#page-16-0) (or Horndenski's theory [\[25\]\)](#page-16-1). The Lagrangian for generalized Galileons can be written as

$$
\mathcal{L} = \mathcal{L}_2 + \mathcal{L}_3 + \mathcal{L}_4 + \mathcal{L}_5, \tag{A1}
$$

$$
\mathcal{L}_2 = K(\phi, X), \tag{A2}
$$

$$
\mathcal{L}_3 = -G_3(\phi, X) \Box \phi, \tag{A3}
$$

$$
\mathcal{L}_4 = G_4(\phi, X)R + G_{4X}[(\Box \phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2], \quad (A4)
$$

$$
\mathcal{L}_{5} = G_{5}(\phi, X)G_{\mu\nu}\nabla^{\mu}\nabla^{\nu}\phi - \frac{1}{6}G_{5X}[(\Box\phi)^{3} - 3\Box\phi(\nabla_{\mu}\nabla_{\nu}\phi)^{2} + 2(\nabla_{\mu}\nabla_{\nu}\phi)^{3}],
$$
\n(A5)

where K, G_3 , G_4 , G_5 are arbitrary functions of ϕ and X and here f_X stands for $\partial f(\phi, X)/\partial X$. The full equations of motion for this theory have been derived in Ref. [\[26\]](#page-16-2) and independently in Ref. [\[46\]](#page-16-14). They are rather long and cumbersome, so we will not displayed them fully. Our proof does rely on the explicit form of the metric equation of motion, the part that is proportional to $q_{\mu\nu}$ to be precise, as we discuss below.

To get the SSGG, we require the equations of motion be invariant under $\phi \rightarrow \phi + \epsilon$. That is, we require $\delta \mathcal{E}_{\mu\nu} =$ $\epsilon \partial \mathcal{E}_{\mu\nu}/\partial \phi$ to vanish identically, where $\mathcal{E}_{\mu\nu} = 0$ is the field equation for $g_{\mu\nu}$. Note that requiring an expression to vanish identically is different from solving an equation to obtain solutions; we should require the expression to vanish for any field configurations. This means, in our case, terms with the same derivative and curvature tensor structure should cancel exactly, which therefore imposes constraints on the arbitrary functions $G_i(\phi, X)$. (One might be interested in imposing shift symmetry at the level of the Lagrangian and require terms with the same structure to cancel out, but in that case the "same structure" becomes ambiguous, as one is allowed to integrate by parts.)

Let us now focus on the part of $\delta \mathcal{E}_{\mu\nu}$ that is proportional to $g_{\mu\nu}$, which is readily available in Ref. [\[26\]](#page-16-2). First, we notice that there is a term proportional to $-g_{\mu\nu}G_{5X\phi}\nabla^{\beta}\nabla_{\rho}\phi\nabla^{\sigma}\nabla_{\sigma}\phi\nabla^{\lambda}[\nabla_{\lambda}\phi]$, which cannot be canceled by any other term so we have to set celed by any other term, so we have to set

$$
G_{5X\phi} = 0 \tag{A6}
$$

in $\delta \mathcal{E}_{\mu\nu}$. Then, the $g_{\mu\nu}$ part of $\delta \mathcal{E}_{\mu\nu}$ becomes

$$
\delta \mathcal{E}_{\mu\nu}^{(2)} \supset \epsilon g_{\mu\nu} \left(-\frac{1}{2} K_{\phi} \right), \tag{A7}
$$

$$
\delta \mathcal{E}_{\mu\nu}^{(3)} \supset \epsilon g_{\mu\nu} \bigg(G_{3\phi\phi} X + \frac{1}{2} G_{3\phi X} \nabla_{\lambda} \nabla_{\rho} \phi \nabla^{\rho} \phi \nabla^{\lambda} \phi \bigg), \tag{A8}
$$

$$
\delta \mathcal{E}^{(4)}_{\mu\nu} \supset \epsilon g_{\mu\nu} (G_{4\phi\phi} \Box \phi - 2X G_{4\phi\phi\phi} - 2G_{4\phi\phi X} (\nabla_{\rho} \nabla_{\sigma} \phi)^2 - 2G_{4X\phi\phi} X \Box \phi \n- G_{4XX\phi} \nabla_{\lambda} \nabla^{\rho} \phi \nabla^{\lambda} \phi \nabla_{\rho} \phi \Box \phi + G_{4XX\phi} \nabla_{\rho} \nabla_{\lambda} \phi \nabla_{\sigma} \nabla^{\lambda} \phi \nabla^{\rho} \phi \nabla^{\sigma} \phi \n+ G_{4\phi X} \nabla^{\rho} \nabla_{\rho} \phi \nabla^{\sigma} \partial_{\sigma} \phi - G_{4\phi X} R^{\rho \sigma} \nabla_{\rho} \phi \nabla_{\sigma} \phi),
$$
\n(A9)

$$
\delta \mathcal{E}^{(5)}_{\mu\nu}|_{G_{5\phi X}=0} \supset \epsilon g_{\mu\nu} \left(G_{5\phi\phi} R^{\rho\sigma} \nabla_{\rho} \phi \nabla_{\sigma} \phi - G_{5\phi\phi} \nabla^{[\rho} \nabla_{\rho} \phi \nabla^{\sigma]} \nabla_{\sigma} \phi + G_{5\phi\phi\phi} X \Box \phi \right. \\
\left. + \frac{1}{2} G_{5\phi\phi\phi} \nabla_{\rho} \phi \nabla_{\sigma} \phi \nabla^{\rho} \nabla^{\sigma} \phi \right),
$$
\n(A10)

where the superscript (i) refers to the relevant part of the Lagrangian from which the term originates. Requiring terms with the same derivative and curvature structure to cancel, we get the following differential equations for the four arbitrary functions:

$$
G_{4\phi X} - G_{5\phi\phi} = 0, \qquad (A11)
$$

$$
-2G_{4\phi\phi X} + \frac{1}{2}G_{5\phi\phi\phi} = 0, \qquad (A12)
$$

$$
G_{4\phi\phi} - 2G_{4\phi\phi X}X + G_{5\phi\phi\phi}X = 0, \tag{A13}
$$

$$
G_{4\phi XX} = 0, \qquad \text{(A14)}
$$

$$
G_{3\phi X} = 0, \qquad \text{(A15)}
$$

$$
-\frac{1}{2}K_{\phi} + G_{3\phi\phi}X = 0.
$$
 (A16)

The general solution of these equations is

$$
G_5 = c_1 \phi^2 + c_2 \phi + G_5(X), \tag{A17}
$$

$$
G_4 = 2c_1\phi X + G_4(X), \tag{A18}
$$

$$
G_3 = f_3(\phi) + c_3\phi + G_3(X), \tag{A19}
$$

$$
K = 2Xf_{3\phi}(\phi) + K(X),\tag{A20}
$$

where c_1 , c_2 and c_3 are constants, $f_3(\phi)$ is an arbitrary function of ϕ , and we have abused the notation slightly to introduce new arbitrary functions of X . Note that, unlike flat space Galileon theory, the scalar tadpole term in a covariant theory is not shift symmetric, as a shift in the scalar tadpole term simply changes the value of the cosmological constant.

The reason why $c_3\phi$ and $f_3(\phi)$ can be present without compromising shift symmetry is because there is degeneracy between \mathcal{L}_2 and \mathcal{L}_3 in choosing Lagrangian terms that gives rise to the same dynamics. The same is true for c_1 and c_2 in the Lagrangian \mathcal{L}_4 and \mathcal{L}_5 . More specifically, the following identities hold:

$$
f_3(\phi)\Box\phi = 2Xf_{3\phi}(\phi) + \text{total derivative},
$$
 (A21)

$$
XR + (\Box \phi)^2 - (\nabla_{\mu} \nabla_{\nu} \phi)^2
$$

= $-\phi G_{\mu\nu} \nabla^{\mu} \nabla^{\nu} \phi$ + total derivative, (A22)

$$
\phi X R + \phi [(\Box \phi)^2 - (\nabla_\mu \nabla_\nu \phi)^2]
$$

= $-\frac{1}{2} \phi^2 G_{\mu\nu} \nabla^\mu \nabla^\nu \phi$ + total derivative. (A23)

The first two of these relations has been pointed out in Ref. [\[26\].](#page-16-2) Making use of the above relations, after some cancellations, the Lagrangian terms with c_1 and $f_3(\phi)$ are only total derivatives, so they play no role in determining the dynamics of the system, so we can set $c_1 = 0$ and $f_3(\phi) = 0$ without lost of generality. The Lagrangian terms with c_2 and c_3 can be absorbed into redefined $G_4(X)$ and $K(X)$, so we can also set $c_2 = 0$ and $c_3 = 0$. Therefore, only the four arbitrary functions $K(X)$, $G_3(X)$, $G_4(X)$, $G_5(X)$ are left.

Last, we have only consider a fraction of the full equations of motion, but a transformation is a symmetry only if all the equations of motion are invariant under it. However, at this point, if we check the equations of motion or simply the Lagrangian, the theory is already manifestly shift symmetric.

In summary, the most general shift-symmetric generalized Galileon is given by Lagrangian with the four arbitrary functions replaced by

$$
G_5(\phi, X) \to G_5(X), \tag{A24}
$$

$$
G_4(\phi, X) \to G_4(X), \tag{A25}
$$

$$
G_3(\phi, X) \to G_3(X), \tag{A26}
$$

$$
K(\phi, X) \to K(X). \tag{A27}
$$

APPENDIX B: GAUSS–BONNET TERM AS A TOTAL DERIVATIVE

It is most convenient to formulate the Gauss–Bonnet term as a total derivative in the vielbein formalism e^A_μ . First,
note that the curvature form O^A_{B} can be written as note that the curvature form $\Omega^{A}{}_{B}$ can be written as

$$
\Omega^{A}{}_{B} = D\omega^{A}{}_{B} = d\omega^{A}{}_{B} + \omega^{A}{}_{C} \wedge \omega^{C}{}_{B}, \qquad (B1)
$$

where D is the covariant exterior derivative and ω_{B}^{A} is
the spin connection satisfying $d\omega_{B}^{A} + \omega_{B}^{A} + \wedge \omega_{B}^{B} = 0$ and the the spin connection satisfying $de^{A} + \omega^{A}{}_{B} \wedge e^{B} = 0$, and the second Bianchi identity is second Bianchi identity is

$$
D\Omega^{AB} = d\Omega^{AB} + \omega^A{}_C \wedge \Omega^{CB} + \omega^B{}_C \wedge \Omega^{AC} = 0. \quad (B2)
$$

With these relations and the form of the Gauss–Bonnet term in terms of $\Omega^A{}_B$, we have

$$
S = \int d^4x \sqrt{-g} \mathcal{G} = \int d^4x \sqrt{-g} \nabla_{\mu} \tilde{\mathcal{G}}^{\mu}
$$
 (B3)

$$
= \int \Omega^{AB} \wedge \Omega^{CD} \epsilon_{ABCD} \tag{B4}
$$

$$
= \int d(\omega^{A}{}_{B} \wedge \Omega^{C}{}_{D} \epsilon_{A}{}^{B}{}_{C}{}^{D})
$$
 (B5)

$$
= \frac{1}{2} \int \partial_{\mu} (\epsilon_A{}^B c^D \omega_{\nu}^A{}_B R_{\rho \sigma}{}^C{}_{D}) \cdot dx^{\mu} \wedge dx^{\nu} \wedge dx^{\rho} \wedge dx^{\sigma} \quad (B6)
$$

$$
= -\frac{1}{2} \int d^4x \partial_\mu (\sqrt{-g} \epsilon^{\mu\nu\rho\sigma} \epsilon_A{}^B{}_C{}^D \omega^A_{\nu\,B} R_{\rho\sigma}{}^C{}_{D}) \tag{B7}
$$

$$
= \int d^4x \sqrt{-g} \nabla_{\mu} \left(\frac{1}{2} \epsilon^{\mu \nu \rho \sigma} \epsilon_{\alpha \beta}{}^{\lambda \eta} \omega^{\alpha}_{\nu \lambda} R^{\beta}{}_{\eta \rho \sigma} \right), \tag{B8}
$$

where we have defined $\epsilon_{\mu\nu\rho\sigma}|_{\mu\nu\rho\sigma=0123} = \sqrt{-g}$ and $\epsilon_{ABCD}|_{ABCD=0123} = 1$. So the quantity $\tilde{\mathcal{G}}^{\mu}$ introduced in Sec. [III](#page-3-0) is given by

$$
\tilde{\mathcal{G}}^{\mu} = \frac{1}{2} \epsilon^{\mu\nu\rho\sigma} \epsilon_{\alpha\beta}{}^{\lambda\eta} \omega^{\alpha}_{\nu\lambda} R^{\beta}{}_{\eta\rho\sigma}.
$$
 (B9)

APPENDIX C: VARIATION OF THE SCALAR-GAUSS–BONNET TERM

Here we derive the contribution of the action term

$$
S_{\phi GB} = \int d^4x \sqrt{-g} \phi \mathcal{G}
$$

=
$$
\int d^4x \frac{1}{4} \sqrt{-g} \phi \delta^{\mu \rho \sigma}_{\alpha \beta \gamma \delta} R_{\mu \nu}{}^{\alpha \beta} R_{\rho \sigma}{}^{\gamma \delta}, \qquad (C1)
$$

the field equation of the metric, where $\delta^{\mu\nu\rho\sigma}_{\alpha\beta\gamma\delta} = 4! \delta^{\mu}_{[\alpha} \delta^{\nu}_{\beta} \delta^{\sigma}_{\gamma} \delta^{\sigma}_{\delta]} = -\epsilon^{\mu\nu\rho\sigma} \epsilon_{\alpha\beta\gamma\delta}$. $\epsilon^{\mu\nu\rho\sigma}$ is the Levi-Civita tensor. In the field equations for the metric $\delta S_{\phi GB}/\delta g^{\mu\nu}$, there are terms containing $\partial \phi$, as well as terms containing ϕ *a priori*. According to the Gauss– Bonnet theorem, the terms containing ϕ should cancel each other (otherwise the metric equation of motion is not invariant under $\phi \rightarrow \phi + c$, so we only need to keep track of terms containing $\partial \phi$ when varying $S_{\phi GB}$. We will use the equality " \div " when these ϕ terms are dropped. Also, the variation in the following is only with respect to the metric.

Making use of $\delta R^{\rho}{}_{\sigma\mu\nu} = 2\nabla_{[\mu} \delta \Gamma^{\rho}_{\nu]\sigma}$ and $\delta \Gamma^{\rho}_{\mu\nu} = \frac{1}{2} \sigma^{\rho \sigma} [\nabla \delta \sigma + \nabla \delta \sigma - \nabla \delta \sigma]$ we have $\frac{1}{2}g^{\rho\sigma}[\nabla_{\mu}\delta g_{\nu\sigma} + \nabla_{\nu}\delta g_{\mu\sigma} - \nabla_{\sigma}\delta g_{\mu\nu}]$, we have

$$
\delta S_{\phi \text{GB}} = \int d^4 x \frac{1}{2} \sqrt{-g} \phi \delta^{\mu \nu \rho \sigma}_{\alpha \beta \gamma \delta} R_{\mu \nu}{}^{\alpha \beta} \delta R_{\rho \sigma}{}^{\gamma \delta}
$$

$$
= \int d^4 x (\delta \mathcal{T}_1 + \delta \mathcal{T}_2 + \delta \mathcal{T}_3), \tag{C2}
$$

where

$$
\delta \mathcal{T}_1 = \frac{1}{2} \sqrt{-g} \phi \delta^{\mu\nu\rho\sigma}_{\alpha\beta\gamma\delta} R_{\mu\nu}{}^{\alpha\beta} \nabla^\gamma \nabla^\delta \delta g_{\rho\sigma} = 0, \quad (C3)
$$

$$
\delta \mathcal{T}_2 = \frac{1}{2} \sqrt{-g} \phi \delta^{\mu\nu\rho\sigma}_{\alpha\beta\gamma\delta} R_{\mu\nu}{}^{\alpha\beta} \nabla^\gamma \nabla_\sigma (g^{\delta\lambda} \delta g_{\lambda\rho}), \quad (C4)
$$

$$
\delta \mathcal{T}_3 = \delta \mathcal{T}_2
$$

= $-\frac{1}{2} \sqrt{-g} \phi \delta^{\mu\nu\rho\sigma}_{\alpha\beta\gamma\delta} R_{\mu\nu}{}^{\alpha\beta} \nabla^{\gamma} \nabla_{\rho} (g^{\delta\lambda} \delta g_{\lambda\sigma}).$ (C5)

 δT_1 vanishes because ρ and σ are antisymmetrized. So, by partial integrations, we have

$$
\delta S_{\phi GB} \doteq - \int d^4 x \sqrt{-g} \phi \delta^{\mu\nu\rho\sigma}_{\alpha\beta\gamma\delta} R_{\mu\nu}{}^{\alpha\beta} \nabla^{\gamma} \nabla_{\sigma} (g_{\rho\lambda} \delta g^{\delta\lambda}) \qquad (C6)
$$

$$
\doteq \int d^4 x \sqrt{-g} \nabla_{\sigma} (\nabla^{\gamma} \phi \epsilon^{\mu\nu\rho\sigma} \epsilon_{\alpha\beta\gamma\delta} R_{\mu\nu}{}^{\alpha\beta}) g_{\rho\lambda} \delta g^{\delta\lambda} \qquad (C7)
$$

$$
= \int d^4 x \frac{1}{2} \sqrt{-g} (g_{\rho\mu} g_{\delta\nu} + g_{\rho\nu} g_{\delta\mu})
$$

$$
\cdot \nabla_{\sigma} (\partial_{\gamma} \phi \epsilon^{\lambda\eta\rho\sigma} \epsilon^{\alpha\beta\gamma\delta} R_{\lambda\eta\alpha\beta}) \delta g^{\mu\nu} . \qquad (C8)
$$

Note that $\epsilon^{\gamma \delta \alpha \beta} \epsilon^{\rho \sigma \lambda \eta} R_{\lambda \eta \alpha \beta} / 4$ is the double dual Einstein tensor and divergence free.

1. Equations of motion: Spherical symmetry

Here we list the relevant equations of motion terms in spherical symmetry:

$$
G^{t}{}_{t} = -\frac{1}{r^{2}} + \frac{\eta}{r^{2}e^{B}} - \frac{\eta B'}{r e^{B}},
$$
 (C9)

$$
G^{r}{}_{r} = -\frac{1}{r^{2}} + \frac{\eta}{r^{2}e^{B}} + \frac{\eta A'}{r e^{B}},
$$
 (C10)

$$
G^{\theta}_{\theta} = G^{\varphi}_{\phi}
$$

= $\eta \left(\frac{A' - B'}{2re^{B}} + \frac{A'(A' - B')}{4e^{B}} + \frac{A''}{2e^{B}} \right),$ (C11)

$$
\mathcal{T}^{t}_{t} = \frac{4\alpha(\eta e^{B} - 3)\phi' B'}{r^{2} e^{2B}} - \frac{\eta \phi'^{2}}{2e^{B}} - \frac{8\alpha(\eta e^{B} - 1)\phi''}{r^{2} e^{2B}},
$$
\n(C12)

$$
T^{r}{}_{r} = \frac{12\alpha\phi' A'}{r^{2}e^{2B}} - \frac{4\eta\alpha\phi' A'}{r^{2}e^{B}} + \frac{\eta\phi'^{2}}{2e^{B}},
$$
 (C13)

$$
\mathcal{T}^{\theta}_{\theta} = \mathcal{T}^{\varphi}_{\varphi}
$$

=
$$
-\frac{\eta \phi'^2}{2e^B} + \frac{2\alpha (A' - 3B')A'\phi'}{re^{2B}}
$$

+
$$
\frac{4\alpha(\phi'A'' + \phi''A')}{re^{2B}},
$$
 (C14)

$$
\Box \phi = \frac{2\eta \phi'}{re^B} + \frac{\eta (A' - B')\phi'}{2e^B} + \frac{\eta \phi''}{e^B}, \qquad (C15)
$$

$$
G = \frac{2(1 - \eta e^B)A'^2 + 2(\eta e^B - 3)A'B'}{r^2 e^{2B}}
$$

$$
+ \frac{4(1 - \eta e^B)A''}{r^2 e^{2B}}.
$$
(C16)

APPENDIX D: NO-HAIR FOR SLOWLY ROTATING BLACK HOLES

Here we present a short argument which suggests that, for a gravity model containing the metric and a number of

scalars, a no-hair theorem for spherical symmetric black holes can be readily generalized to the slowly rotating black holes. That is, for a multi-scalar-tensor theory, if a static, spherically symmetric black hole does not have scalar hair, then its slowly rotating counterpart will not have hair either. This argument has been already put forth in our paper [\[29\]](#page-16-5).

First, we note that the most general stationary axisymmetric metric to first order in rotation is given by [\[47\]](#page-16-15)

$$
ds^{2} = -H(r)dt^{2} + Q(r)dr^{2} + r^{2}[d\theta^{2} + \sin^{2}\theta d\varphi^{2}]
$$

- 2\epsilon\omega(r, \theta)r^{2}\sin^{2}\theta dt d\varphi + \mathcal{O}(\epsilon^{2}), \qquad (D1)

where $H(r)$ and $Q(r)$ correspond to the static, spherically symmetric seed solution, $\omega(r, \theta)$ parametrizes the correction induces by the rotation, and ϵ is just a bookkeeping parameter for the expansion. On the other hand, the nth scalar field with axisymmetry can be generally expanded as

$$
\phi^{n}(x) = \phi_{0}^{n}(r) + \phi_{1}^{n}(t, r, \theta)\epsilon + \mathcal{O}(\epsilon^{2}).
$$
 (D2)

Now, due to axisymmetry, the system is invariant under the combined operation of $\omega(r, \theta) \rightarrow -\omega(r, \theta)$ and $\varphi \rightarrow -\varphi$. The metric is clearly invariant under this operation. However, $\phi_1^n(t, r, \theta)$ is by definition linear in the rotation,
so it should change sign every time the direction of rotation so it should change sign every time the direction of rotation is reversed. Hence, for the scalar fields ϕ^n to be invariant under $\omega(r, \theta) \rightarrow -\omega(r, \theta)$ and $\varphi \rightarrow -\varphi$, we must have

$$
\phi_1^n(t, r, \theta) = 0 \Rightarrow \phi^n(x) = \phi_0^n(r) + \mathcal{O}(\epsilon^2). \tag{D3}
$$

Thus, the scalar fields $\phi^{n}(x)$ do not acquire a correction at first order in rotation.

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