Choptuik's critical phenomenon in Einstein-Gauss-Bonnet gravity

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We investigate the effects of higher-order curvature corrections to Einstein's gravity on the critical phenomenon near the black hole threshold, namely, the Choptuik phenomenon. We simulate numerically a five-dimensional spherically symmetric gravitational collapse of massless scalar field in Einstein-Gauss-Bonnet gravity towards a black hole formation threshold. When the curvature is sufficiently large, the additional higher-order terms affect the evolution of the whole system. Since high curvature characterizes the region when the critical behavior takes place, this critical behavior is destroyed. Both the selfsimilarity and the mass scaling relation disappear. Instead we find a different behavior near the black hole threshold, which depends on the coupling constant of the higher-order terms. The new features include a change of the sign of the Ricci scalar on the origin which indicates changes in the local geometry of spacetime, and never occurs in classical general relativity collapse, and oscillations with a constant rather than with a diminishing length scale.

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I. INTRODUCTION

Gravity is described by Einstein's theory of general relativity (GR), which predicts the existence of black holes—trapped regions from which nothing can escape. Black holes can form from regular initial data that do not contain a black hole already. Isolated systems in GR can end up in two qualitatively different states: Data that forms a black hole in the evolution and data that does not and in which the mass-energy disperses to infinity. A simplest possible model for such a system is the collapse of a spherically symmetric minimally coupled massless scalar field. The final fate—whether it collapses or not—depends on the ''strength'' of the initial data.

In a pioneering work, Choptuik [\[1](#page-11-0)] explored the transition between the two regimes. He discovered that the black hole threshold shows both surprising structure and surprising simplicity. Universality, power-law scaling of the black hole mass, and scale echoing have given rise to the term ''critical phenomena'' [\[2](#page-11-1),[3](#page-11-2)]. Choptuik [[1](#page-11-0)] considered a one-parameter family of initial data describing a collapsing scalar field (see Fig. [1](#page-1-0) for the structure of space time). He have shown that for each family of initial data parametrized by p (for example, amplitude of the initial pulse), there exists a critical value p_* . For $p > p_*$, we have a supercritical collapse and a black hole forms. For $p < p_*$ the collapse is subcritical and the field disperses to infinity leaving a flat space. Choptuik gave highly convincing numerical evidence that by fine-tuning the parameter p to the threshold value p_* an infinitely small black hole can be created.

The critical solution itself is universal. For a finite time in a finite region of space the spacetime converges to one and the same solution independent of the initial data. The critical solution is discretely self-similar (DSS), namely, it is invariant under rescaling by a particular finite factor, or

its integer powers. Let $Z_*(r, t)$ be the critical solution (collectively for all the parameters—the scalar field and the metric), the critical solution is the same when rescaling space and time by factor e^{Δ}

$$
Z_*(r,t) = Z_*(re^{\Delta}, te^{\Delta}). \tag{1}
$$

The field and metric functions pulsate periodically with ever decreasing temporal and spatial scales, until a black hole forms in supercritical collapse, or the field disperses in subcritical collapse (see Fig. [2\)](#page-2-0). This universal phase ends when the evolution diverges towards a black hole formation or towards dispersion, depending on whether $p > p_*$ or not. In supercritical collapse above p_* , arbitrary small black holes are formed as $p \rightarrow p_*$ and the black hole mass scales as a power law: $M \propto (p - p_*)^{\gamma}$, where γ is universal. It depends on the type of collapsing matter (and on the dimension) but it is independent of the initial data family. Similar critical phenomena were found in many other types of matter coupled to gravity, with spherical symmetry and beyond it (See, e.g., [\[2](#page-11-1)] for a review). The echoing period Δ and critical exponent γ depend on the type of matter and on the dimension, but the phenomenon appears to be generic.

Einstein's equations are derived from the Hilbert action, which is linear in the Ricci scalar- R . It is natural to expect that higher terms in R will appear in a more general theory and it is interesting to explore their possible role. To do so, we have to explore a high curvature regions of space time where such terms are significant. Black hole formation is a natural place to do so, as spacetime becomes highly curved as the matter fields collapse. This behavior usually takes place near the singularity, which is typically hidden inside the black hole. However, they also appear near the threshold for black hole formation when the Choptuik phenomenon take place. Therefore, we explore here the gravitational collapse of a spherically symmetric massless

FIG. 1 (color online). The Penrose diagram in GR of the space time that is expected to form in a gravitational collapse of a shell of in-falling scalar field to a black hole. When the shell is far away from the origin, the self-gravitational effects are small. When it comes closer to the origin, the gravitational field becomes stronger. If the field does not collapses to a black hole, the diagram remains Minkowski-flat, and the event horizon or the singularity do not exist, of course. Light blue lines indicate the numerical domain of integration used in the current work. The initial hypersurface is a null ray. Since the field is massless, it behaves lightlike and it moves along null rays.

scalar field with higher-order corrections to the Hilbert action.

Addition of even the simplest R^2 term induces fourthorder derivatives of the metric in the resulting equations of motion. The original Einstein equations are second order in the metric and the additional generic fourth-order corrections will govern the equations and change completely their character. To overcome this, we consider a special case. Lanczos [[4](#page-11-3)[,5](#page-11-4)] found a generalization of Hilbert's Lagrangian which is quadratic in the Riemann tensor and its contractions, but its variation yields a system of equations that, like Einstein's, is second order in the metric derivatives. This correction to the Lagrangian, called the Lanczos Lagrangian or the Gauss-Bonnet term [[6](#page-12-0)[,7](#page-12-1)], is given by

$$
L_{GB} \equiv R^2 - 4R_{\mu\nu}R^{\mu\nu} + R_{\mu\nu\rho\sigma}R^{\mu\nu\rho\sigma}.
$$
 (2)

The combined theory that includes the Hilbert Lagrangian and the Gauss-Bonnet term is called Einstein-Gauss-Bonnet (EGB) gravity. In four dimensions the Gauss-Bonnet term is a pure divergence, just like Hilbert's Lagrangian in two dimensions, and it does not contribute to the field equations in four dimensions. To overcome this we consider here gravitational collapse in five-dimensional spacetime, which is the simplest system in which the Gauss-Bonnet term contributions can affect the evolution [\[8](#page-12-2)].

We present here the results of a numerical investigation of the influence of higher-order curvature correction, namely, the Gauss-Bonnet term, on the properties of spherically symmetric scalar field collapse in five dimensions. In particular, we focus on the behavior of the Choptuik critical phenomenon. The structure of the paper is as follows: in Sec. [II](#page-1-1) we describe the overall model and the basic equations. In Sec. [III](#page-5-0) we discuss the numerical structure and the numerical difficulties that arise in the calculations. Simulation results and their discussion are presented in Sec. [IV.](#page-6-0)

II. THE MODEL AND THE BASIC EQUATIONS

We consider the collapse of a spherically symmetric massless scalar field, ϕ in five-dimensional space time described by the metric $g_{\alpha\beta}$. We use units in which $G = c = 1.$

A. The metric

The scalar field is massless and it propagates along the light cone. Hence we describe the five-dimensional asymptotically flat spacetime in double null coordinates

$$
ds^{2} = -a^{2}(u, v)dudv + r^{2}(u, v)d\Omega_{3}^{2},
$$
 (3)

where our coordinates are: $(u, v, \varphi, \theta, \gamma)$ and $d\Omega_3^2$ = $\left[\sin^2 \gamma (d\theta^2 + \sin^2 \theta d\varphi^2) + d\gamma^2\right]$ is the metric on a threedimensional unit sphere (see [\[13,](#page-12-3)[14\]](#page-12-4) for an alternative Hamiltonain formulation of this problem). The coordinate u is the retarded time coordinate and a constant u describes an outgoing null trajectory. Similarly v is the advanced time coordinate and surfaces with a constant ν are the ingoing null trajectories. $r \equiv r(u, v)$ is the area coordinate and $r = 0$ is the origin of the spherical symmetry. This definition of the metric is unique only up to a change of variables of the form $v \to \tilde{v}(v)$, $u \to \tilde{u}(u)$. This gauge freedom will be fixed later by the choice of the initial conditions.

B. The scalar field

The Lagrangian density of the field is

$$
L = -\frac{1}{2}\phi_{;\alpha}\phi^{;\alpha},\tag{4}
$$

FIG. 2 (color online). The field function s in classical GR in five dimensions, for a slightly subcritical collapse. The field oscillates with a DSS pattern. The field pulsations decrease in temporal and spatial scales.

and the corresponding equation of motion is

$$
\phi^{;\sigma}_{;\sigma} = 0. \tag{5}
$$

The energy-momentum tensor is given by

$$
T_{\alpha\beta} = \phi_{,\alpha} \phi_{,\beta} - \frac{1}{2} g_{\alpha\beta} \phi_{,\sigma} \phi^{\sigma}
$$

=
$$
\begin{pmatrix} T_{uu} & T_{uv} & 0 & 0 & 0 \\ T_{vu} & T_{vv} & 0 & 0 & 0 \\ 0 & 0 & T_{\varphi\varphi} & 0 & 0 \\ 0 & 0 & 0 & T_{\theta\theta} & 0 \\ 0 & 0 & 0 & 0 & T_{\gamma\gamma} \end{pmatrix}
$$

=
$$
\begin{pmatrix} \phi_{,\mu}^{2} & 0 & 0 & 0 \\ 0 & \phi_{,\nu}^{2} & 0 & 0 \\ 0 & 0 & \sin^{2}\theta T_{\theta\theta} & 0 \\ 0 & \sin^{2}\gamma T_{\gamma\gamma} & 0 & 0 \end{pmatrix}
$$

=
$$
\begin{pmatrix} \phi_{,\mu}^{2} & 0 & 0 & 0 \\ 0 & \phi_{,\nu}^{2} & 0 & 0 \\ 0 & \frac{2r^{2}}{a^{2}} \phi_{,\mu} \phi_{,\nu} \end{pmatrix}
$$

C. The equations of motion

The overall action that includes the Hilbert action and the Gauss-Bonnet term is

$$
S = \int d^n x \sqrt{-g} \left[\frac{1}{16\pi} (R + \alpha L_{GB}) \right] + S_{\text{matter}}, \quad (7)
$$

where α is the coupling constant and it has dimensions of (length)². The value of the coupling constant α is unknown, we assume that $0 < \alpha \ll 1$. We are interested in α values that are significant and that influence the solution.

Therefore, we will look for values that are large enough so that the correction term, which is of order αR^2 , is comparable or larger then the Hilbert term R . Namely, we will be interested in cases where $\alpha R > 1$.

The corresponding gravitational field equations are

$$
G_{\mu\nu} + \alpha H_{\mu\nu} = \kappa_n^2 T_{\mu\nu},\tag{8}
$$

where $G_{\mu\nu}$ is Einstein tensor:

$$
G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}, \tag{9}
$$

 $T_{\mu\nu}$ is the energy-momentum tensor given in [\(6](#page-2-1)), and

$$
H_{\mu\nu} = 2[RR_{\mu\nu} - 2R_{\mu\alpha}R^{\alpha}{}_{\nu} - 2R^{\alpha\beta}R_{\mu\alpha\nu\beta} + R_{\mu}{}^{\alpha\beta\gamma}R_{\nu\alpha\beta\gamma}] - \frac{1}{2}g_{\mu\nu}L_{GB}.
$$
 (10)

We convert the equations to a set of first-order differential equations. To do so we define

$$
s \equiv \sqrt{4\pi G} \phi \tag{11}
$$

$$
z \equiv s_v \tag{12}
$$

$$
w \equiv s_u \tag{13}
$$

$$
d \equiv \frac{a_v}{a} \tag{14}
$$

$$
f \equiv r_u \tag{15}
$$

$$
g \equiv r_v, \tag{16}
$$

where $Z_{\mu} \equiv \frac{\partial Z}{\partial x^{\mu}}$. We obtain, using Eq. ([8\)](#page-2-2), four independent first-order equations:

$$
f_u = 2f\frac{a_u}{a} - \frac{2Gra^2w^2}{3[a^2 + 4\alpha\eta]}; \qquad \underline{uu} \text{ component}; \qquad (17)
$$

$$
g_{\nu} = 2gd - \frac{2Gra^2z^2}{3[a^2 + 4\alpha\eta]}; \qquad \underline{\nu\nu} \text{component}; \qquad (18)
$$

$$
f_v = g_u = -\frac{a^2 r \eta}{2[a^2 + 4\alpha \eta]}; \qquad \underline{uv} \text{ component}; \qquad (19)
$$

and

$$
d_u = \frac{-9a^2\eta[(4\alpha\eta)^2 - 3a^4] + 4a^2Gzw[-9(a^2 + 4\alpha\eta)^2 + 32a^2Gzw\alpha]}{36(a^2 + 4\alpha\eta)^3}; \qquad \frac{a^2}{2r^2}\frac{\gamma\gamma}{1 + uv} \text{ components.} \tag{20}
$$

The scalar field equation derived from ([5\)](#page-2-3) is

$$
w_v = z_u = -\frac{3}{2r}(gw + fz).
$$
 (21)

We have defined here an auxiliary function η

$$
\eta = \frac{a^2 + 4fg}{r^2}.\tag{22}
$$

This is useful to stabilize the numerical solution, as ex-plained later in Sec. [III](#page-5-0). The evolution equation for η is

$$
\eta_v = -\frac{2\eta(g - rd)}{r} - \frac{2a^2(3g\,\eta + 4fz^2)}{3r(a^2 + 4\alpha\,\eta)}.\tag{23}
$$

Equations-[\(17\)](#page-3-0)–([21](#page-3-1)) and [\(23\)](#page-3-2)-together with (12) –[\(16\)](#page-2-5) are a set of 11 coupled first-order differential equations that describe the system. Since there are only nine functions—r, a, s, f, g, z, w, d and η —two equations are redundant and are simply the usual constraint equations. We choose those to be Eqs. ([15\)](#page-2-6) and ([17](#page-3-0)). They are not evolved in the integration, but they are monitored to verify that they are indeed satisfied during the evolution.

The original GR equations are invariant under rescaling. However, the coupling constant α has units of length squared $[L^2]$. Its introduction to the system destroys this scale invariance. Under the rescaling: $r \rightarrow \rho r$ the equations behave as

$$
f_u = 2f\frac{a_u}{a} - \frac{2Gra^2w^2}{3[a^2 + 4\alpha\eta]} \to \frac{1}{\rho}f_u
$$

= $\frac{1}{\rho}2f\frac{a_u}{a} - \frac{1}{\rho}\frac{2Gra^2w^2}{3[a^2 + \frac{4\alpha\eta}{\rho^2}]}$, (24)

$$
g_v = 2gd - \frac{2Gra^2z^2}{3[a^2 + 4\alpha\eta]} \to \frac{1}{\rho}g_v
$$

= $\frac{1}{\rho} 2gd - \frac{1}{\rho} \frac{2Gra^2z^2}{3[a^2 + \frac{4\alpha\eta}{\rho^2}]}$, (25)

$$
f_v = -\frac{a^2 r \eta}{2[a^2 + 4\alpha \eta]} \to \frac{1}{\rho} f_v = -\frac{1}{\rho} \frac{a^2 r \eta}{2[a^2 + \frac{4\alpha \eta}{\rho^2}]}.
$$
 (26)

$$
d_u = \frac{-9a^2\eta[(4\alpha\eta)^2 - 3a^4] + 4a^2Gzw[-9(a^2 + 4\alpha\eta)^2 + 32a^2Gzw\alpha]}{36(a^2 + 4\alpha\eta)^3} \to \frac{1}{\rho^2}d_u
$$

=
$$
\frac{1}{\rho^2} \frac{-9a^2\eta[(\frac{4\alpha\eta}{\rho^2})^2 - 3a^4] + 4a^2Gzw[-9(a^2 + \frac{4\alpha\eta}{\rho^2})^2 + \frac{32a^2Gzw\alpha}{\rho^2}]}{36(a^2 + \frac{4\alpha\eta}{\rho^2})^3}.
$$
 (27)

Obviously, the scale invariance is broken. At smaller scales ($\rho \rightarrow 0$) the noninvariant elements, which rescale as ρ^{-2} , become dominant and govern the equations. This leads to the deviations from the classical GRB behavior that we demonstrate numerically later. In particular the deviations from the GR behavior happen near the critical point where the curvature is large and the non-scaleinvariant Gauss-Bonnet terms are large. These terms eventually destroy the classical Choptuik phenomenon both when black holes form and when they do not. This happens independently of the value of α .

D. The boundary conditions

Regularity and differentiability at the origin $r = 0$ require the following boundary conditions

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$$
g = -f = \frac{a}{2}, \qquad \partial_r s = 0, \qquad \partial_r a = 0. \tag{28}
$$

These conditions imply

$$
a_v = a_u; \t w = z; \n\eta = \frac{a}{12\alpha}(-3a + \sqrt{9a^2 + 48\alpha z^2})
$$
\n(29)

at the origin.

A second set of boundary conditions is set implicitly at infinity. This is trivial in GR, where a Schwarzschild has naturally an asymptotically flat spacetime. However, [\[15\]](#page-12-5) have shown that a Schwarzschild black hole in EGB gravity can have either asymptotically flat or anti-de Sitter structure. Since we consider only a finite region of space time (see Fig. [1](#page-1-0)) we do not examine here to which to the two branches the collapsing black hole will lead.

E. The ricci scalar

The Ricci scalar curvature, R , is given by

$$
R = 8 \frac{-9a^6wz + 432\eta^4\alpha^3 + 72a^2\eta^2(\eta - 2wz)\alpha^2 + a^4(32w^2z^2 - 72wz\eta - 27\eta^2)\alpha}{9a^2(a^2 + 4\alpha\eta)^3}.
$$
 (30)

The Ricci curvature describes the local geometry of the spacetime. The value of the Ricci scalar at the origin is of special interest

$$
R(r=0) = \frac{16z^2}{a\sqrt{9a^2 + 48z^2\alpha}} + \frac{5}{\alpha} \left(\frac{a}{\sqrt{a^2 + \frac{16}{3}z^2\alpha}} - 1\right).
$$
\n(31)

If $\alpha = 0$, the Ricci scalar at the center is always negative: $-\frac{8z^2}{a^2}$. For $\alpha \neq 0$ the situation is more complicated. The Ricci scalar is negative while the following condition is satisfied:

$$
\alpha < \frac{45a^2}{16z^2}.\tag{32}
$$

The simulations show that, along the evolution of the collapsing field system, the metric function $a(u, v)$ approaches zero and $z(u, v)$, the field derivative, is growing to a very big values, the closer we are to the critical amplitude, the larger is the value that ζ approaches. Therefore, the condition of Eq. ([32](#page-4-0)) is violated at some point and the Ricci scalar changes sign. This change of sign heralds the deviation from the classical behavior.

F. The black hole mass

The analysis of mass scaling relation in the critical phenomenon requires a function for a black hole mass. The Arnowitt, Deser, Misner (ADM) mass of a black hole in higher-dimensional GR [[16](#page-12-6)] is

$$
M = \frac{(D-2)A_{D-2}}{16\pi G_D} r_s^{D-3},\tag{33}
$$

when r_s is Schwarzschild radius, D is the dimension, G_D is the D-dimensional Newton constant and A_{D-2} is the area of a unit sphere: $A_{D-2} = \frac{2\pi^{(D-1)/2}}{\Gamma(\frac{D-1}{2})}$ $\frac{\pi^{(D-1)/2}}{\Gamma(\frac{D-1}{2})}$. However, in EGB there is an additional term and for $D = 5$ dimensions the ADM mass is [\[15](#page-12-5)[,17–](#page-12-7)[19\]](#page-12-8)

$$
M = \frac{3\pi}{8G}r_s^2\left(1 + \frac{2\alpha}{r_s^2}\right). \tag{34}
$$

The second term in this equation implies that, as the size of the black hole decreases $(r_s \rightarrow 0)$, its mass in EGB approaches a constant positive value, $M \rightarrow M_0 = 3\pi \alpha/4G$ [\[18](#page-12-9)[,19\]](#page-12-8). This implies that there is a mass gap and all black holes (for $\alpha > 0$) must have an ADM mass larger than M_0 . One can resort to a different definition of the black hole's mass and, instead of using the ADM mass, one can calculate the mass of the apparent (trapping) horizon using an EGB quasilocal mass [\[20,](#page-12-10)[21\]](#page-12-11). Avoiding this problem we will consider, for simplicity, in the following the scaling of the black hole's radius instead of the scaling of the black hole's mass.

We define the critical exponent γ such that $|p - p_*|^{\gamma}$ has a dimension of length. Instead of examining the dependence of the ADM mass on p we will examine the dependence of the black hole's radius, r_s . We expect following the GR case to find $r_s \propto (p - p_*)^{\gamma}$.

G. Initial conditions

We turn to discuss the initial conditions. We consider here the gravitational collapse of a shell of in-falling scalar field. Figure [1](#page-1-0) shows the domain of the current numerical work embedded inside an expected Penrose diagram. The $u-v$ plane is covered by a two-dimensional grid, as de-scribed in Fig. [3.](#page-5-1) The origin $r = 0$ is included in the domain, and it is chosen to be at $u = v$. Therefore the relevant part of u - v space is $v > u$. Our metric is defined up to a coordinate transformation, as was mentioned in Sec. [II A.](#page-1-2) This gauge freedom is fixed by specifying the metric functions on the initial hypersurface, an initial ray with a constant retarded time $u = u_i = 0$. In flat— Minkowski—spacetime, the conventional definition of the null coordinates is $u = t - r$ and $v = t + r$. Since we are dealing with spherical shell, the spacetime is flat in two regions—inside the shell and at asymptotically large radii. The integration starts far away from the event

FIG. 3 (color online). The domain of integration. The calculation employs the two previous lines, L_1 and L_2 , in addition to the line, L_0 , that is currently being solved. The boundary conditions on $r = 0$ involving ∂_r are implemented using the threepoint derivatives along the diagonal line. Smoothing of some functions near $r = 0$ (at a point marked by cross) is done using past light cone points (marked by circles). Figure taken from [[3\]](#page-11-2).

horizon and therefore the metric is nearly flat. Thus we define the area coordinate r along the initial null surface $u = u_i = 0$ as in a flat spacetime $r = \frac{v}{2}$. The fact that the spacetime is only approximately Minkowski is pronounced by the deviation of the other metric function— $a(u, v)$ from its flat-space value ($a = 1$). In addition, we set $a = 1$ at the origin, $r = 0$, at one point $u = v = 0$. From here we can obtain all the other functions on the initial hypersurface by integration from the origin.

The exact shape of the initial scalar field is unimportant, as the Choptuik behavior is universal and independent of this shape. We choose the initial scalar field profile along an outgoing hypersurface $u = u_i = 0$ to be a Gaussian

$$
s(u = 0, v) = p \exp\left[-\left(\frac{v - v_c}{\sigma}\right)^2\right],\tag{35}
$$

where the constants v_c and σ determine the initial position and width of the shell and the constant p is the amplitude of the pulse. p is the strength parameter of the initial data and it is the dynamical parameter that we vary to explore the Choptuik phenomenon.

Having specified the functions r and s on the initial hypersurface, we can derive analytically z and g , which are simply the derivatives $z = s_y$ and $g = r_y = 1/2$. All the other functions on the initial hypersurface—f, a, w, d and η —are obtained by integrating the appropriate equations from the origin.

III. NUMERICAL METHODS

We follow here the methods developed by Sorkin and Oren [[3\]](#page-11-2). However, as discussed later, further steps, including the addition of the variable η , are needed here to stabilize the code near the origin. The problem arises because of the stronger nonlinear behavior of the Gauss-Bonnet terms.

A. The integration scheme

Our domain of integration is an equilateral right triangle in a *u-v* plane: $0 \le u \le u_{\text{max}}$, $0 \le v \le v_{\text{max}}$ and $v \ge u$. $v_{\text{max}} = u_{\text{max}}$ is chosen to cover the interesting relevant region. An illustration of the domain is sketched in Figs. [1](#page-1-0) and [3.](#page-5-1) The simplest computational cell is square with grid spacing $h_u = h_v = h$. Triangular cells near the origin ($u = v$) are treated separately.

The integration begins from the lower line of constant $u = 0$ and propagates to the next line. Once the solution along an outgoing hypersurface with constant u value, $u =$ $U - h$, is known, d and z are propagated to the next line, $u = U$, using Eqs. ([20](#page-3-3)) and [\(21\)](#page-3-1) correspondingly. Then Eqs. ([21](#page-3-1)), [\(19\)](#page-3-4), [\(18\)](#page-3-5), ([12](#page-2-4)), ([16](#page-2-5)), [\(14](#page-2-7)), and ([23](#page-3-2)) are integrated using a fourth-order Runge-Kutta algorithm from the origin outward along ν to obtain the functions w, f, g , s, r, a and η , respectively. The remaining equations are not used directly, but they must be satisfied and are used to test the numerical solution.

The first points near the origin are treated separately. The region near the origin is unstable. The instability arises near the origin where discretization errors are amplified, especially in source terms that involve a division by r. To resolve this problem we take several steps. First we introduce the new variable $\eta = \frac{a^2 + 4fg}{r^2}$. This, unnecessary from the first glance, variable is an algebraic combination of others. It appears in every source function. It includes a division by r^2 which is very sensitive to errors near the origin. The independent evolution of η using Eq. ([23](#page-3-2)) help stabilize the source functions. In addition, we have to take a few more steps: We use at points near the origin a more stable, second-order Runge-Kutta algorithm.

(i) Instead of integrating the function functions f and w along ν , we evaluate these functions using a Taylor expansion, e.g. ,:

$$
f(v) = f(v_0) + dv f_v(v_0) + \frac{(dv)^2}{2} f_{vv}(v_0)
$$

+ $O(dv)^3$, (36)

when v_0 is the v value on the origin and $dv \equiv$ $v - v_0$.

(ii) Additionally we smooth the functions z and d . First we evaluate the function, at some point P , then its value is smoothed with the values of the same function on points on the past light cone of P (see Fig. [3](#page-5-1)). For example, for the function ζ at the point CHOPTUIK's CRITICAL PHENOMENON IN EINSTEIN- ... PHYSICAL REVIEW D 85, 104015 (2012)

marked by cross in Fig. [3,](#page-5-1) the new, smoothed, z is calculated according to

$$
z_{\text{new}} = \left(\omega z_e + \sum_{i=i}^{3} z_i\right) \frac{1}{3+\omega},\tag{37}
$$

where z_e is the value obtained from the evolution equation, z_i are the extrapolated values of z along the three directions of the past light cone: $z_i(u) =$ $2z(u - h) - z(u - 2h)$, and ω is a weight parameter, which is varying for different functions and different code parameters, but typically $\omega \propto 0.1$.

Every one of those actions on its own stabilizes the integration but is insufficient to keep the code completely stable till the end. For the classical GR evolution, with $\alpha =$ 0, η is not needed; however, it is essential for the more general evolution. This combination prevents the code from crashing at least for low enough values of α . However, a strong penalty is paid as the combination and, in particular, the smoothing reduces the convergence rate of the code to a linear order. Using this algorithm, we are able to get a stable and convergent evolution for small values of α . However, the code still becomes unstable for large values of α , usually when the field amplitudes that are close to the critical one.

B. Numerical tests

We performed a series of simulations with step sizes h , $\frac{h}{2}$, and $\frac{h}{4}$ in order to determine the accuracy of the numerical

 0.8

 0.7

method. If the numerical solution converges, the relation between the different numerical solutions and the real one will be

$$
F_{\text{real}} = F^h + O(h^n),\tag{38}
$$

where *n* is the order of convergence and F^h is the numerical solution with step size h . For halved step sizes the error is reduced correspondingly: $F_{\text{real}} = F^{h/2} + O(\frac{h}{2})^n$ and $F_{\text{real}} = F^{h/4} + O\left(\frac{h}{4}\right)^n$. By defining (as in [\[22](#page-12-12)]): $c1 \equiv$ $F^h - F^{h/2}$ and $c2 \equiv F^{h/2} - F^{h/4}$, we find the convergence rate

$$
n = \log_2 \left(\frac{c_1}{c_2}\right). \tag{39}
$$

Figure $4(a)$ depicts *n*. The convergence rate is approximately linear $n \approx 1$ or higher for almost the whole domain. However, n diverges at some points. This arises from crossing of $s =$ const lines, as can be shown in Fig. [4\(b\)](#page-6-1). The upper panel of this figure shows a one-dimensional projection of *n* along constant *u*-ray: $u = 0.4$, and the lower panel shows the corresponding field function $F =$ $s(u, v)$ along the same constant u ray for different grid densities.

IV. RESULTS

The first feature of the collapsing field is the formation, or not, of a black hole. To examine this, we plot a diagram of v vs r , the area coordinate, for different values of u (See Fig. [5\)](#page-7-0). Each line represents an outgoing null ray of a

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FIG. 4 (color online). Convergence for a slightly subcritical run with $\alpha = 10^{-4}$. The convergence rate—n—in panel (a) is derived from the field function $s(u, v)$, with 2^{16} , 2^{17} and 2^{18} grid points in u and v directions [blue, red and green lines, respectively, in s plot on panel (b)]. In panel (b), the divergence of n around $v \sim 0.46$ and $v \sim 0.63$ is caused by s lines crossing, as shown in the zoom window.

constant u, namely, a trajectory of a photon emitted from the origin at u . Rays with u small enough show a flatlike spacetime behavior, for which $v \approx u + 2r$. For small values of u , at early times, the rays do not encounter a strong gravitational field and they escape to infinity. At later times, the gravitational field becomes stronger and the outgoing rays are bent more and more before they eventually manage to escape. Once a black hole forms, these rays are trapped. For subcritical initial configuration, the field disperses and all outgoing null rays reach infinity [see Fig. [5\(a\)\]](#page-7-1). For a supercritical initial configuration, a horizon appears when an outgoing null ray does not escape and does not reach future null infinity but rather remains in the same radius r for all values of v . Later rays that emerge from the origin collapse back to the origin (see Fig. [5\(b\)\)](#page-7-1).

While, as expected, the Gauss-Bonnet terms do not change the overall classical GR behavior, the critical behavior is lost. For classical GR in $D = 5$ dimensions, the black hole radius scales as $R \propto (p - p_{*})^{\gamma}$. Figure [6](#page-7-2) depicts the black hole radius as a function of $|p - p_*|$ for supercritical evolutions with $\alpha = 10^{-4}$. Note that we use here the scaling relation of the Schwarzschild radius instead of the mass (see Sec. [II F\)](#page-4-1). The dependence of the black hole radius on the initial amplitude is monotonic, i.e., for larger values of p the black hole radius is larger. However, in the EGB gravity we do not observe the classical power-law relation. The existence of the scaling relation is related to the self-similar properties of the classical solution [[2](#page-11-1)[,23\]](#page-12-13). Since self-similarity is not preserved in EGB gravity we expect that the scaling relation will also be violated.

In classical GR, the solution is discretely self-similar just below the black hole threshold. The field reaches the

FIG. 5 (color online). Outgoing null rays: v vs r . Both plots have the same parameters except for the initial field amplitude: $\alpha = 10^{-5}$, $v_{\text{max}} = 0.768$, the grid density is 2¹⁵ points in each direction.

FIG. 6 (color online). The black hole's Schwarzschild radius- r_s vs the difference between the amplitude and the critical one- $|p - p_{\ast}|$, for supercritical cases with $\alpha = 10^{-4}$. In the classical GR solution this relation is a power law. Here, in EGB gravity, a power law is not observed.

origin, oscillates, and then disperses or collapses, depending on whether it is subcritical or supercritical. These oscillations do not depend on initial conditions and they decay in a DSS pattern (see Fig. [2\(a\)](#page-2-8)). The addition of the Gauss-Bonnet terms destroys this behavior. With these terms the field still oscillates, but the self-similarity disappears (See Fig. [7](#page-8-0)). The oscillations grow at first as if the additional terms in the Lagrangian amplify the field, prevent it from decaying, and keep the oscillations alive for a longer time. Eventually, the oscillations decay and the field disperses.

In the classical GR solution, we observe more and more self-similar transients when approaching the critical amplitude from both sides. In the EGB solution, while approaching the critical amplitude, more and more oscillations are also observed. However, these oscillations are not self-similar and their scale does not decrease. Figure [7](#page-8-0) depicts the contours of the scalar field s for a set of subcritical solutions [panels (a–d)], with $\alpha = 10^{-5}$, with growing amplitudes approaching the critical one, and a set of supercritical solutions [panels (e–h)] with amplitudes decreasing towards the critical one. An increasing number of oscillations is observed as p approaches p_* . The inserts in the supercritical solution, Figs. $7(e)$ – $7(h)$, depict the $v - r$ diagram, demonstrating black holes formation. A cutoff in field diagram is a sign for a singularity (see the scheme in Fig. [1](#page-1-0)).

Obviously, the self-similarity disappears not only in the field functions, but in all metric functions and their derivatives. Particularly interesting is the behavior of the Ricci scalar [Eq. ([31](#page-4-2))] as seen in Fig. [8](#page-9-0) panels (a3) and (b3), and Fig. [9](#page-10-0) panels (c3) and (d3). This figures show the Ricci scalar at the origin, $R(r = 0)$, as a function of u for different values of α . Purple color indicates negative values and red indicates positive values of the Ricci scalar. Figure [8](#page-9-0) (a3) shows the classical solution, i.e., $\alpha = 0$. In classical

FIG. 7 (color online). Contours of the scalar field function s in EGB gravity with a coupling constant $\alpha = 10^{-5}$, grid density 2^{15} , $v_{\text{max}} = 0.768$, $v_c = 0.22$. The initial field amplitude increases or decreases towards the critical amplitude: $p \rightarrow p_*$. Plots (a-d) subcritical collapse: $p \leq p_*$. Plots (e–h)—supercritical collapse $p > p_*$. The inserts demonstrate the formation of black holes as seen in the $v - r$ diagram. The initial values of the field amplitude are: $p = 0.1654(a)$, 0.16557(b), 0.1657(c), 0.165723(d), 0.1676(e), 0.166 (f) , 0.1658 (g) , 0.16573 (h) .

FIG. 8 (color online). A slightly subcritical collapse with different values of the coupling constant α . Panels (a1–3) correspond to a classical GR solution, $\alpha = 0$. A self-similar behavior can be observed. Panels (b1–4) correspond to EGB gravity with $\alpha = 10^{-6}$. The first row, panels (a1) and (b1), presents contour plots of the field function s. The second row, panels (a2) and (b2), shows the field function s at the origin ($r = 0$) vs u. The third row, panels (a3) and (b3), shows the Ricci scalar on the origin vs u in a logarithmic scale. A red color indicates positive values and a purple color negative values of R. Panel (b4), displays contour plot of $\left|\alpha R\right|$, showing the regions where the higher order terms are significant, i.e., $|\alpha R| > 1$.

FIG. 9 (color online). A continuation of Fig. [8](#page-9-0) with larger values of α in a slightly subcritical collapse. Panels (c1–4) correspond to EGB gravity solution with $\alpha = 10^{-5}$. Panels (d1-4) correspond to EGB gravity solution with $\alpha = 10^{-4}$.

FIG. 10 (color online). The typical wavelength of scalar field oscillations in EGB gravity near the black hole threshold vs the coupling constant α . Red line indicates a linear fit with a slope: $m = 0.54 \pm 0.05$. Namely, the wavelength is proportional to $\sqrt{\alpha}$ as expected from the dimensional analysis.

GR, the condition $\alpha \leq \frac{45a^2}{16z^2}$ [Eq. ([32](#page-4-0))] is always satisfied, thus $R(r = 0)$ is always negative and it never changes sign. On the other hand, for EGB gravity, this condition is inevitably violated for amplitudes close enough to the critical one [see Figs. [8](#page-9-0) (b3), [9](#page-10-0) (c3) and 9 (d3)]. As p approaches p_* , the metric function a tends to zero and the derivative of the field z grows. At some point the condition [\(32\)](#page-4-0) is violated and the Ricci scalar changes sign, indicating a change in the local geometry. This demonstrates that near the black hole threshold for $\alpha > 0$ the local geometry is different from the classical GR geometry.

Figs. [8](#page-9-0) and [9](#page-10-0) compare slightly subcritical solutions with different values of the coupling constant, $\alpha = 0$, 10^{-6} , 10^{-5} , 10^{-4} in each column (columns *a*, *b*, *c* and *d*). The first, upper row of each figure (panels a1, b1, c1 and d1) shows contours of the field function s. The second and the third rows (panels $a2-3$, $b2-3$, $c2-3$ and $d2-3$) show the field function s and the Ricci scalar on the origin ($r = 0$) vs u. The fourth row (panels b4, c4 and $d4$) shows a contour plot of $|\alpha R|$. It indicates the regions where the additional curvature terms are significant, i.e., regions where $|\alpha R| \ge$ 1. Naturally with larger values of α this region grows and $|\alpha R|$ reaches larger values.

The plots of the field function—s—on the origin (b2, c2 and d2) nicely show a ''beat''-like pattern, increasing and then decreasing, in the field pulsation's strength. However, for small values of α , [see Fig. [8](#page-9-0) (b2)], the field behavior on the origin resembles, at least initially, a self-similar behavior in regular GR. This could be explained by the low and insignificant values of the higherorder terms in these regions (see Fig. [8](#page-9-0) (b4)). At the same time, a comparison of the field s and the Ricci scalar at the origin for different values of α [panels $(a2-3)$, $(b2-3)$, $(c2-3)$ and $(d2-3)$] reveals that the new ''beat'' form of the field oscillations appears at the same retarded time u at which Ricci curvature changes sign and becomes positive.

The scalar field oscillations (Figs. [7,](#page-8-0) [7](#page-8-0), and [9\)](#page-10-0) show a typical wavelength, which depends on the value of α (see Fig. [10](#page-11-5)). All the lengths are measured in the simulation length units $[u]$. As expected from a dimensional analysis the typical wavelength of the oscillations is proportional to $\sqrt{\alpha}$.

V. SUMMARY

We have developed a numerical scheme for simulating the dynamical collapse of a spherically symmetric massless scalar field in EGB gravity. This model for gravity includes higher (quadratic)-order curvature corrections to the Hilbert action. These corrections induce changes in Einstein equations, which govern the evolution of the system when the curvature is large.

We find that the addition of higher-order curvature correction destroys the classical Choptuik phenomenon. The introduction of the dimensional coupling constant α , which has a units of length², destroys the scale invariance of the system. As a consequence the self-similar behavior, which is an integral part of the critical phenomena in regular GR, disappears. Instead, the solution shows a different pattern of pulsations with a typical wavelength, which is proportional to $\sqrt{\alpha}$, as expected from a dimensional analysis. The changes in the oscillations pattern are accompanied by changes in the sign of the Ricci scalar at the origin, indicating a change in the local geometry of the spacetime.

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