$N = 8$ supersymmetric mechanics on the sphere S^3

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Starting from quaternionic $N = 8$ supersymmetric mechanics we perform a reduction over a bosonic radial variable, ending up with a nonlinear off-shell supermultiplet with three bosonic end eight fermionic physical degrees of freedom. The geometry of the bosonic sector of the most general sigma-model type action is described by an arbitrary function obeying the three dimensional Laplace equation on the sphere *S*³. Among the bosonic components of this new supermultiplet there is a constant which gives rise to potential terms. After dualization of this constant one may come back to the supermultiplet with four physical bosons. However, this new supermultiplet is highly nonlinear. The geometry of the corresponding sigma-model action is briefly discussed.

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I. INTRODUCTION

Despite the many common structures the mechanics with extended supersymmetries shares with its higher dimensional counterparts (see e.g. [[1\]](#page-5-0)), it also possesses some rather specific features which cannot be even imagined in other dimensions. Among the most impressive examples one may find the one dimensional $N = 4, 8$ supermultiplets without auxiliary components or even without physical bosons [[2](#page-5-1)] as well as plenty of off-shell nonlinear supermultiplets. Just a new $N = 8$ nonlinear supermultiplet and its action are the subject of the present paper.

The idea about the possibility of the existence of the nonlinear supermultiplets in $N = 4$, $d = 1$ supersymmetric theories has been formulated for the first time in [\[3](#page-5-2)]. In a short time, some of the nonlinear $N = 4$ supermultiplets have been explicitly constructed in [\[4](#page-5-3)]. Later on, it has been understood that almost all $N = 4$ supermultiplets, linear and nonlinear ones, can be obtained proceeding from the ''root'' supermultiplet and dualizing the physical bosons into auxiliary components [[5\]](#page-5-4). Alternatively, the superfield procedure for constructing linear and nonlinear supermultiplets starting from the root one has been recently proposed in [\[6](#page-5-5)]. Finally, after some preliminary consideration [\[7](#page-5-6)] it was found that there are infinitely many $N = 4$ nonlinear supermultiplets with a functional freedom in the definition [[8\]](#page-5-7).

When passing to $N = 8$, $d = 1$ supersymmetry, the situation becomes more complicated. Until now only two nonlinear off-shell $N = 8$ supermultiplets are known those with two $[9]$ and four $[10,11]$ $[10,11]$ $[10,11]$ physical bosons were constructed off shell. Other known nonlinear supermultiplets, for example, those discussed in [[12](#page-5-11)], have been constructed with the help of duality transformations and had

been fully described only on shell. One may wonder why we need nonlinear supermultiplets and which additional problems appear in the case of $N = 8$ supersymmetric mechanics. The answer to these questions is that the $N =$ 8 supersymmetry puts a rather strong restriction on the metric of the sigma-model part of the action—for all linear supermultiplets the metric has to be conformally flat, with the conformal factor obeying a proper Laplace equation. Thus, the hyper-Kähler metrics never show up within the models with linear supermultiplets. Moreover, the reduction procedure which perfectly worked in the $N = 4$ case is not so useful for the $N = 8$ case. The explanation is very simple—in order to dualize the physical boson into the auxiliary component one should choose a metric which does not contain this boson. Only with such a condition it is possible to turn this physical boson into the auxiliary component. But in almost all cases this cannot be achieved, because the metrics is subjected to the Laplace equation. Nevertheless, there is one special case where the reduction can be performed. It corresponds to the $N = 8$ supersymmetric mechanics with four physical bosonic components. Only in this case the solution of the four dimensional Laplace equation admits the reduction over radii and results in a three dimensional system with $N = 8$ supersymmetry. Just this case will be analyzed in this paper. We start from the known quaternionic four dimensional $N = 8$ mechanics [\[13\]](#page-5-12) and perform the reduction over the "radii" variable. In such a way we will get the $N = 8$ supersymmetric system on the sphere $S³$ (Sec. II). Then we will write the proper superfield constraint, which follows from the constraints on the four dimensional supermultiplet upon reduction, and construct the most general action (Sec. III). In Sec. IV we consider the potential terms and perform another dualizations of the coupling constant which pushes us back to a new nonlinear four dimensional supermultiplet. For this supermultiplet we find that the geometry of the bosonic sigma-model is neither conformally flat nor of a hyper-Kähler type. In fact, this geometry is just the one

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which was previously found in the $(4, 0)$ heterotic sigma models in $d = 2$ [\[14\]](#page-5-13).

II. $N = 8$ **SUPERSYMMETRIC MECHANICS ON THE SPHERE** *S***³**

As we already mentioned in the Introduction, our idea is to perform the reduction over radii to pass from quaternionic four dimensional $N = 8$ mechanics [[13](#page-5-12)] to three dimensional mechanics with the sphere $S³$ in the bosonic part of the action.

The supermultiplet which has been used to construct the quaternionic mechanics is described by a quartet of $N = 8$ superfields Q^{ia} depending on the coordinates of the $N =$ 8, $d = 1$ superspace $\mathbb{R}^{(1|8)}$. These superfields are subjected to the following constraints [[15\]](#page-5-14):

$$
D_A^{(i} Q^{j)a} = 0, \qquad \nabla_\alpha^{(a} Q^{ib)} = 0. \tag{2.1}
$$

Here *i, a, A,* $\alpha = 1$ *, 2 are doublet indices of four* $SU(2)$ subgroups of the automorphism group of $N = 8$ superspace, and the spinor covariant derivatives are defined to obey the algebra

$$
\{D^{iA}, D^{jB}\} = 2i\epsilon^{ij}\epsilon^{AB}\partial_t, \qquad \{\nabla^{a\alpha}, \nabla^{b\beta}\} = 2i\epsilon^{ab}\epsilon^{\alpha\beta}\partial_t.
$$
\n(2.2)

The component *on-shell* form of the corresponding action with arbitrary metric function *G* depending on four physical bosonic fields is given by

$$
S = \int dt \left[G \left(\dot{q}^{ia} \dot{q}_{ia} + \frac{i}{2} \xi^{i\alpha} \dot{\xi}_{i\alpha} + \frac{i}{2} \psi^{aA} \dot{\psi}_{aA} \right) \right.+ \frac{i}{2} \frac{\partial G}{\partial q^{ia}} (\xi^{ia} \xi^k_{\alpha} \dot{q}^a_{k} + \psi^{aA} \psi^b_{A} \dot{q}^i_{b}) + \frac{1}{8} \left(\frac{\partial^2 G}{\partial q^{ia} \partial q^{kb}} - 2G^{-1} \frac{\partial G}{\partial q^{ia}} \frac{\partial G}{\partial q^{kb}} \right) \xi^{ia} \xi^k_{\alpha} \psi^{aA} \psi^b_{A} \right].
$$
\n(2.3)

The invariance under $N = 8$ supersymmetry imposes the additional constraint on the metric *G* to be harmonic

$$
\frac{\partial^2}{\partial q^{ia}\partial q_{ia}}G = 0.
$$
 (2.4)

It is easy to see that in the special case of the metric function

$$
G = \frac{1}{q^{ia}q_{ia}},\tag{2.5}
$$

the four-fermion term in (2.3) (2.3) (2.3) is canceled. Then, introducing new bosonic and fermionic variables

$$
q^{ia} = \tilde{q}^{ia} e^{u/2}, \qquad \tilde{q}^{ia} \tilde{q}^k_a = \epsilon^{ki}, \qquad \tilde{q}^{ia} \tilde{q}^b_i = \epsilon^{ba},
$$

$$
\tilde{\psi}^{iA} = e^{-u/2} \tilde{q}^i_a \psi^{aA}, \qquad \tilde{\xi}^{a\alpha} = e^{-u/2} \tilde{q}^a_i \xi^{i\alpha},
$$
 (2.6)

one finds that the action (2.3) is reduced to the sum of a bosonic sigma-model type action and the action for free

fermions

$$
S = \frac{1}{2} \int dt \left\{ \frac{1}{2} (\dot{u})^2 + \dot{\tilde{q}}^{ia} \dot{\tilde{q}}_{ia} + \frac{i}{2} \tilde{\xi}^{a\alpha} \dot{\tilde{\xi}}_{a\alpha} + \frac{i}{2} \tilde{\psi}^{iA} \dot{\tilde{\psi}}_{iA} \right\}.
$$
\n(2.7)

If we replace the time derivative of the field *u* by an auxiliary field $A = \dot{u}$ and then exclude *A* by its equation of motion, we will get just $N = 8$ mechanics on the sphere $S³$. What is really interesting is that the $N = 8$ supersymmetrization of this $S³$ is achieved by adding eight free fermions. Let us remind, that just the same phenomenon appears in the case of the $N = 4$ supersymmetrization of the spheres S^2 [[4\]](#page-5-3) and S^3 [\[16,](#page-5-15)[17\]](#page-5-16).

III. THREE DIMENSIONAL MECHANICS: SUPERFIELDS AND COMPONENTS

The example of straightforward reduction presented in the previous section gives only the simplest variant of the three dimensional action. In order to construct the most general sigma-model action one should perform the reduction in terms of superfields. Fortunately, this is rather easy to do. Indeed, let us introduce new $N = 8$ quartet superfields \mathcal{N}^{ia} as follows:

$$
\mathcal{N}^{ia} = \frac{\mathcal{Q}^{ia}}{|\mathcal{Q}|}, \qquad |\mathcal{Q}|^2 = \mathcal{Q}^{ia}\mathcal{Q}_{ia}. \tag{3.1}
$$

Clearly, these new defined superfields \mathcal{N}^{ia} do not include the "radii component" $|Q|^2$ from the supermultiplet Q^{ia} . Moreover, in virtue of (2.1) (2.1) (2.1) , the superfields \mathcal{N}^{ia} obey the closed set of constraints

$$
\mathcal{N}_a^{(k} D_A^i \mathcal{N}^{j)a} = 0, \qquad \mathcal{N}_i^{(a} \nabla_\alpha^b \mathcal{N}^{c)i} = 0,
$$

$$
N^{ia} N_{ia} = 2.
$$
 (3.2)

Thus, the structure of our nonlinear supermultiplet is completely defined by the constraints (3.2) (3.2) (3.2) .

The concise form of the constraints (3.2) (3.2) (3.2) is not practically useful. It is convenient to use instead the following parametrization for them (which solves the last, algebraic constraint in (3.2) :

$$
\mathcal{N}^{ia} = (\mathcal{N}^{11}, \mathcal{N}^{12}, \mathcal{N}^{21}, \mathcal{N}^{22})
$$

$$
= \left(\frac{1}{\sqrt{1+u\bar{u}}}u, \frac{e^{i/2\phi}}{\sqrt{1+u\bar{u}}}, -\frac{e^{-i/2\phi}}{\sqrt{1+u\bar{u}}}, \frac{1}{\sqrt{1+u\bar{u}}}\bar{u}\right).
$$
(3.3)

In this parametrization the constraints (3.2) (3.2) (3.2) read

$$
D^{i}(e^{-(i/2)\phi}u) = 0, \qquad \bar{D}_{i}(e^{(i/2)\phi}\bar{u}) = 0,
$$

\n
$$
\nabla^{a}(e^{(i/2)\phi}u) = 0, \qquad \bar{\nabla}_{a}(e^{-(i/2)\phi}\bar{u}) = 0,
$$

\n
$$
D^{i}(e^{-(i/2)\phi}\bar{u}) = -i\bar{D}^{i}\phi, \qquad \bar{D}_{i}(e^{(i/2)\phi}u) = -iD_{i}\phi,
$$

\n
$$
\nabla^{a}(e^{(i/2)\phi}\bar{u}) = -i\bar{\nabla}^{a}\phi, \qquad \bar{\nabla}_{a}(e^{-(i/2)\phi}u) = -i\bar{\nabla}_{a}\phi.
$$

\n(3.4)

Here, we redefine the covariant derivatives as

$$
D^{i} = \{D^{11}, D^{12}\}, \qquad \bar{D}^{i} = \{D^{21}, D^{22}\},
$$

$$
\nabla^{a} = \{\nabla^{11}, \nabla^{12}\}, \qquad \bar{\nabla}^{a} = \{\bar{\nabla}^{21}, \bar{\nabla}^{22}\},
$$

which now anticommute as follows:

$$
\{D^i, \bar{D}_j\} = -2i\delta^i_j \partial_i, \qquad \{\nabla^a, \bar{\nabla}_b\} = -2i\delta^a_b \partial_i. \quad (3.5)
$$

Besides the superfields $\{\phi, u, \bar{u}\}\$ it is rather convenient to introduce the related sets of superfields $\{\phi, \Lambda, \bar{\Lambda}\}$ and $\{\phi, \lambda, \bar{\lambda}\}$ as

$$
e^{(i/2)\phi}\lambda = u = e^{-(i/2)\phi}\Lambda, \qquad e^{-(i/2)\phi}\bar{\lambda} = \bar{u} = e^{(i/2)\phi}\bar{\Lambda}.
$$
\n(3.6)

Now one may rewrite the constraints (3.4) (3.4) (3.4) in a symmetrical, linear (although disguisedly nonlinear) form

$$
D^i \lambda = 0, \qquad \bar{D}_i \bar{\lambda} = 0,
$$

\n
$$
\nabla^a \Lambda = 0, \qquad \bar{\nabla}_a \bar{\Lambda} = 0,
$$

\n
$$
D^i \bar{\Lambda} = -i \bar{D}^i \phi, \qquad \bar{D}_i \Lambda = -i D_i \phi,
$$

\n
$$
\nabla^a \bar{\lambda} = -i \bar{\nabla}^a \phi, \qquad \bar{\nabla}_a \lambda = -i \nabla_a \phi.
$$

\n(3.7)

Now, it is time to analyze the component structure of our supermultiplet. First of all, let us define the following components of our superfields $¹$:</sup>

$$
\lambda|_{\theta=0} = \lambda(t), \qquad \bar{\lambda}|_{\theta=0} = \bar{\lambda}(t), \qquad \phi|_{\theta=0} = \phi(t),
$$

\n
$$
D^i \bar{\Lambda}|_{\theta=0} = \xi^i(t), \qquad \bar{D}_i \Lambda|_{\theta=0} = \bar{\xi}_i(t),
$$

\n
$$
\nabla^a \bar{\lambda}|_{\theta=0} = \psi^a(t), \qquad \bar{\nabla}_a \lambda|_{\theta=0} = \bar{\psi}_a(t),
$$

\n
$$
D^2 \bar{\Lambda}|_{\theta=0} = iB(t), \qquad \bar{D}^2 \Lambda|_{\theta=0} = i\bar{B}(t),
$$

\n
$$
\nabla^2 \bar{\lambda}|_{\theta=0} = iA(t), \qquad \bar{\nabla}^2 \lambda|_{\theta=0} = i\bar{A}(t),
$$

\n
$$
D^i \nabla^a \bar{\lambda}|_{\theta=0} = Y^{ia}(t), \qquad \bar{D}^i \bar{\nabla}^a \Lambda|_{\theta=0} = -\bar{Y}^{ia}(t).
$$

\n(3.8)

Not all of these components are independent. Indeed, one may check that the constraints [\(3.7\)](#page-2-0) imply the reality of *Yia*

$$
Y^{ia} = \bar{Y}^{ia} \tag{3.9}
$$

and impose the following additional relations between the components *A* and *B*:

$$
A - \bar{A} = -4i\dot{\phi}, \qquad B - \bar{B} = -4i\dot{\phi}, \qquad (3.10)
$$

$$
\dot{A} + \dot{\bar{B}} = 0. \tag{3.11}
$$

Thus, one may see that among the four auxiliary components A , B only one, namely, $(ReA - ReB)$, is independent: the imaginary parts are expressed through $\dot{\phi}$ while the real ones are subjected to the differential constraint following from ([3.11\)](#page-2-1)

$$
\frac{d}{dt}(\text{Re}A + \text{Re}B) = 0 \Rightarrow \text{Re}A + \text{Re}B = m. \tag{3.12}
$$

Therefore, our nonlinear supermultiplet contains eight bosonic components: three physical fields— ϕ , λ , $\overline{\lambda}$ and five auxiliary ones— Y^{ia} , (ReA – ReB), as well as eight fermionic fields— ξ^i , $\bar{\xi}^i$, ψ^a , $\bar{\psi}^a$.

Before going further to construct an invariant superfield action, let us point the attention on the two essential features of our construction. First of all, we defined the components of our nonlinear supermultiplet (3.8) in a rather nonstandard way. Indeed, one may see that the components are defined not only as the spinor derivatives of, say, superfields $\{\phi, \lambda, \lambda\}$, but also through derivatives of another set of superfields $\{\phi, \Lambda, \bar{\Lambda}\}$. Of course, the latter ones are expressed through the former ones. However, proceeding with such a definition, the relations between different auxiliary components in (3.8) acquired the simplest form, as in (3.10) (3.10) , (3.11) (3.11) , and (3.12) . Second, one may see from ([3.12\)](#page-2-4) that the constant *m* appears as a component of our supermultiplet. As we already know from [\[18](#page-5-17)[–20\]](#page-5-18), the presence of this constant is crucial as for generating the potential terms in the action, as well as for the dualization procedure [\[12\]](#page-5-11).

While being a quite reasonable choice for establishing the irreducible constraints for the superfields, the $N = 8$, $d = 1$ superspace is not too suitable for constructing the invariant action. In one dimension, the $N = 4$ superspace provides the best framework for the superfield action. Fortunately enough, for the case at hand the proper $N =$ 4 superspace is almost evident. Indeed, analyzing the con-straints ([3.7](#page-2-0)), one may note that $\{D^2, \overline{D}_2, \nabla^2, \overline{\nabla}_2\}$ derivatives from all superfields and all their combinations are expressed in terms of $\{D^2, \bar{D}_2, \nabla^2, \bar{\nabla}_2\}$ derivatives from another superfield. For example, the spinor components with indices 2 defined in (3.8) can be equivalently expressed as follows:

$$
\xi^2 = -i\bar{D}_1\phi, \qquad \bar{\xi}_2 = iD^1\phi,
$$

$$
\psi^2 = i\bar{\nabla}_1\phi, \qquad \bar{\psi}_2 = i\nabla^1\phi.
$$
 (3.13)

Thus, all independent components present in our $N = 8$ nonlinear superfields appear in the expansion over Grassmann variables with index ''1'' only. Therefore, the proper action reads

$$
S = \int dt d^2\theta^1 d^2\vartheta^1 \mathcal{L} = \int dt D^1 \bar{D}_1 \nabla^1 \bar{\nabla}_1 \mathcal{L}, \qquad (3.14)
$$

where an arbitrary, for the time being, function $\mathcal L$ depends on $\theta^2 = \vartheta^2 = 0$ projections of our superfields ϕ , *u*, \bar{u} (or ϕ , λ , $\bar{\lambda}$ or ϕ , Λ , $\bar{\Lambda}$). Of course, by construction, the action (3.14) (3.14) is invariant only under the manifest $N = 4$ supersymmetry acting on θ^1 , ϑ^1 . The invariance under implicit $N = 4$ supersymmetry imposes the following constraint on the function $L(\phi, u, \bar{u}) = L|_{\theta = \vartheta = 0}$:

¹The higher components in the superfields are easily expressed through the time derivatives of those in (3.8) (3.8) (3.8) .

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$$
\frac{\partial^2 L}{\partial \phi^2} + \frac{1}{4} \left(u \frac{\partial L}{\partial u} + \bar{u} \frac{\partial L}{\partial \bar{u}} \right) + \left(1 + \frac{1}{2} u \bar{u} \right) \frac{\partial^2 L}{\partial u \partial \bar{u}} + \frac{1}{4} \left(u^2 \frac{\partial^2 L}{\partial u^2} + \bar{u}^2 \frac{\partial^2 L}{\partial \bar{u}^2} \right) = 0.
$$
 (3.15)

Of course, it makes no differences which set of superfields is chosen in the superfield Lagrangian density \mathcal{L} . From now on, let us fix this dependence to be on the set $\{\phi, \lambda, \overline{\lambda}\}.$ With this choice the constraint (3.15) acquires the standard form of the three dimensional Laplace equation on the sphere $S³$ in stereographic coordinates

$$
\Delta_3 L = (1 + \lambda \bar{\lambda}) \frac{\partial^2 L}{\partial \lambda \partial \bar{\lambda}} + \frac{\partial^2 L}{\partial \phi^2} + i \bar{\lambda} \frac{\partial^2 L}{\partial \bar{\lambda} \partial \phi} - i \lambda \frac{\partial^2 L}{\partial \lambda \partial \phi} = 0.
$$
\n(3.16)

Thus we conclude that the action (3.14) (3.14) with the function $\mathcal{L}(\phi, \lambda, \overline{\lambda})$ obeying ([3.16](#page-3-1)) is invariant under the entire $N =$ 8 supersymmetry.

For completing this section, let us note that the constraints on the superfields $\{\Lambda, \bar{\Lambda}\}$ in ([3.7](#page-2-0)) may be written as

$$
D^i \Lambda + \Lambda \bar{D}^i \Lambda = 0, \qquad \nabla^a \Lambda = 0. \tag{3.17}
$$

The first part of these constraints coincides with the constraints on the $N = 4$ nonlinear chiral supermultiplet [\[9,](#page-5-8)[20](#page-5-18)[,21\]](#page-5-19), while the second part is just a chirality condition. So, one may wonder whether it is possible to write the superfield action for our supermultiplet in a way similar to the action for the nonlinear chiral supermultiplet, as an integral over the chiral superspace

$$
S_{\text{chir}} \sim \int dt d^2\theta d^2\vartheta \bar{\mathcal{F}}(\bar{\Lambda}) + \int dt d^2\bar{\theta} d^2\bar{\vartheta} \mathcal{F}(\Lambda), \quad (3.18)
$$

where $F(\Lambda)$ is an arbitrary function depending on the superfield Λ only. The simplest consideration shows that the action (3.18) (3.18) (3.18) is perfectly invariant with respect to full $N = 8$ supersymmetry. The natural question is how the action (3.18) is related with the action (3.14) (3.14) which is supposed to be the most general one. In order to clarify this point, let us consider an arbitrary term in the expansion of integrand in (3.18) (3.18) (3.18) over Λ and perform the following transformations:

$$
\begin{split}\n\bar{\nabla}^{2}\bar{D}^{2}\left(\frac{a_{n}}{n!}\Lambda^{n}\right) &\sim \bar{\nabla}^{2}\bar{D}_{1}\bar{D}_{2}\left(\frac{a_{n}}{n!}\Lambda^{n}\right) \\
&= \bar{\nabla}^{2}\bar{D}_{1}\left(\frac{a_{n}}{(n-1)!}\Lambda^{n-1}\bar{D}_{2}\Lambda\right) \\
&= \bar{\nabla}^{2}\bar{D}_{1}\left(-i\frac{a_{n}}{(n-1)!}\Lambda^{n-1}D^{1}\phi\right) \\
&= \bar{\nabla}^{2}\bar{D}_{1}\left(-i\frac{a_{n}}{(n-1)!}\lambda^{n-1}e^{i(n-1)\phi}D^{1}\phi\right) \\
&= \bar{\nabla}^{2}\bar{D}_{1}D^{1}\left(-\frac{a_{n}}{(n-1)(n-1)!}\Lambda^{n-1}\right).\n\end{split} \tag{3.19}
$$

Playing a similar game with $\bar{\nabla}_2$ derivatives we will finally transform the integrand as follows:

$$
\bar{\nabla}^2 \bar{D}^2 \left(\frac{a_n}{n!} \Lambda^n \right) \sim \bar{\nabla}_1 \nabla^1 \bar{D}_1 D^1 (e^{i\phi} (1 + \Lambda \bar{\Lambda}) \Lambda^{n-2}).
$$
\n(3.20)

Therefore, the full action (3.18) (3.18) can be rewritten in the form given in (3.14) with the Lagrangian

$$
\mathcal{L}_{\text{chir}} = \frac{1 + \Lambda \bar{\Lambda}}{\Lambda \bar{\Lambda}} (e^{i\phi} \mathcal{F}' \bar{\Lambda} + e^{-i\phi} \bar{\mathcal{F}}' \Lambda).
$$
 (3.21)

It is a matter of straightforward calculations to check that (3.21) (3.21) obeys the Laplace equation (in the variables ϕ , Λ , $\bar{\Lambda}$

$$
\Delta_3 L = (1 + \Lambda \bar{\Lambda}) \frac{\partial^2 L}{\partial \Lambda \partial \bar{\Lambda}} + \frac{\partial^2 L}{\partial \phi^2} + i \bar{\Lambda} \frac{\partial^2 L}{\partial \bar{\Lambda} \partial \phi} - i \Lambda \frac{\partial^2 L}{\partial \Lambda \partial \phi} = 0,
$$
 (3.22)

as it should be. Thus, the action (3.18) (3.18) is a particular case of the more general action (3.14) (3.14) (3.14) .

IV. BOSONIC SECTOR, POTENTIAL TERMS, AND DUALIZATION

The full component action is rather lengthy, but its pure bosonic core is remarkably simple. Integrating in ([3.14\)](#page-2-5) over Grassmann variables, discarding all fermions, and eliminating the auxiliary fields *Yia*, Im*A*, Im*B* by means of their equations of motion, we get the following action:

$$
S = \int dt \frac{\partial^2 L}{\partial \lambda \partial \overline{\lambda}} \Big[(\text{Re}A) \partial_t (\lambda \overline{\lambda}) + 4 \lambda \overline{\lambda} + 2i \phi (\lambda \overline{\lambda} - \lambda \overline{\lambda})
$$

+ $(1 + \lambda \overline{\lambda}) \Big(\frac{1}{4} (\text{Re}A) (\text{Re}B) + \phi^2 \Big) \Big]$
+ $(\text{Re}A + \text{Re}B) \int dt \Big[\frac{i}{2} \Big(\frac{\partial^2 L}{\partial \phi \partial \lambda} \overline{\lambda} - \frac{\partial^2 L}{\partial \phi \partial \overline{\lambda}} \overline{\lambda} \Big)$
- $\frac{1}{2} \phi \Big(\frac{\partial^2 L}{\partial \phi \partial \lambda} \lambda + \frac{\partial^2 L}{\partial \phi \partial \overline{\lambda}} \overline{\lambda} \Big) \Big].$ (4.1)

Before imposing the last constraint (3.12) (3.12) and eliminating the last auxiliary component, let us introduce the new function $h(\phi, \lambda, \overline{\lambda})$ as follows:

$$
h(\phi, \lambda, \bar{\lambda}) = -\frac{\partial L}{\partial \phi} + i \left(\lambda \frac{\partial L}{\partial \lambda} - \bar{\lambda} \frac{\partial L}{\partial \bar{\lambda}} \right).
$$
 (4.2)

One may check that this function *h* also obeys the three dimensional Laplace equation on the sphere *S*³

$$
(1 + \lambda \bar{\lambda})h_{\lambda \bar{\lambda}} + h_{\phi\phi} - i\lambda h_{\phi\lambda} + i\bar{\lambda}h_{\phi\bar{\lambda}} = 0. \qquad (4.3)
$$

Now, rewriting the action [\(4.1](#page-3-4)) in terms of *h*, taking into account the constraint [\(3.12](#page-2-4)) and eliminating the last auxiliary component, we end up with the bosonic action

$$
S = \int dt \left\{ h_{\phi} \left[\frac{4\lambda \bar{\lambda}}{(1 + \lambda \bar{\lambda})^2} + \left(\dot{\phi} + i \frac{\lambda \bar{\lambda} - \lambda \bar{\lambda}}{1 + \lambda \bar{\lambda}} \right)^2 - \frac{1}{16} m^2 + \frac{m}{2} \frac{\partial_t (\lambda \bar{\lambda})}{1 + \lambda \bar{\lambda}} \right] + i \frac{m}{2} (h_{\bar{\lambda}} \bar{\lambda} - h_{\lambda} \lambda) \right\}.
$$
 (4.4)

The bosonic kinetic terms of the action ([4.4](#page-4-0)) describe just the sphere $S³$ in stereographic coordinates modified by an arbitrary function h_{ϕ} , which is a harmonic function on S^3 . In addition, the action contains potential terms which are completely specified by the same function *h*. One should stress that the action (4.4) (4.4) (4.4) is very similar to the bosonic part of the action describing the $N = 4$ supersymmetric particle on the sphere $S³$ [[4](#page-5-3)[,16](#page-5-15)[,17\]](#page-5-16). The essential difference is that the metrics and the potential terms are defined by the *same* harmonic function *h*, while in the $N = 4$ supersymmetric case the metrics and potential terms are not related. Thus, $N = 8$ supersymmetry puts a rather strong restriction on the possible potential terms. As an impressive example, one may consider the particle on the $S³$ itself. This case corresponds to $h_{\phi} = 1$, and one may immediately check that all potential terms disappear, being either constants or full time derivatives. This is just the result we got in Sec. II, while performing the reduction from quaternionic $N = 8$ supersymmetric mechanics.

The last issue we are going to discuss in this section is a dualization of the coupling constant *m* entering the action [\(4.4\)](#page-4-0) into a fourth physical bosonic field. Following [\[22\]](#page-5-20), we treat the self-evident statement $m =$ const as the additional constraint $\partial_t m = 0$. If we include this constraint into our action ([4.4](#page-4-0)) with a Lagrangian multiplier, it will be possible to express the ''former constant'' *m* in terms of the Lagrange multiplier. So, we have

$$
\hat{S} = S + \frac{1}{2} \int dt m\dot{u}
$$

\n
$$
\Rightarrow -\frac{1}{8} h_{\phi} m + \frac{1}{2} \frac{h_{\phi} \partial_t (\lambda \bar{\lambda})}{1 + \lambda \bar{\lambda}} + i \frac{1}{2} (h_{\bar{\lambda}} \bar{\lambda} - h_{\lambda} \lambda) + \frac{1}{2} \dot{u} = 0.
$$
\n(4.5)

Now we plug this expression for *m* back into the action *S*^. Doing in such a way we get a four dimensional sigmamodel action with the following bosonic part:

 \mathbf{r}

$$
\hat{S} = \int dt \Big\{ h_{\phi} \Big[\frac{4\dot{\lambda}\,\dot{\bar{\lambda}}}{(1 + \lambda\,\bar{\lambda})^2} + \Big(\dot{\phi} + i \frac{\dot{\bar{\lambda}}\lambda - \dot{\lambda}\,\bar{\lambda}}{1 + \lambda\,\bar{\lambda}} \Big)^2 \Big] + \frac{1}{h_{\phi}} \Big[\dot{u} + i(\dot{\bar{\lambda}}h_{\bar{\lambda}} - \dot{\lambda}h_{\lambda}) \Big]^2 \Big\}.
$$
\n(4.6)

The action [\(4.6](#page-4-1)) depends on one arbitrary function $h(\phi, \lambda, \overline{\lambda})$, which obeys the Laplace equation on *S*³. It is interesting to note that the action (4.6) exhibits the same target space geometry which appears in the heterotic (4, 0) sigma-model in $d = 2$ [[14](#page-5-13)].

In the particular case with $h_{\phi} = 1$, $h_{\lambda} = 0$ the action [\(4.6\)](#page-4-1) is reduced to the direct sum of the free actions on *S*³ and on *S*1. Another interesting limit corresponds to a linearized version of the action [\(4.6\)](#page-4-1). In this case it acquires the form of the Gibbons-Hawking ansatz for the hyper-Kähler sigma-model action $[23]$ $[23]$:

$$
\tilde{S} = \int dt \Big\{ h_{\phi} [4\lambda \dot{\lambda} + (\dot{\phi} + i(\dot{\lambda}\lambda - \lambda \dot{\lambda}))^2] + \frac{1}{h_{\phi}} [\dot{u} + i(\dot{\lambda}h_{\lambda} - \dot{\lambda}h_{\lambda})]^2 \Big\},
$$
\n(4.7)

with the function *h* obeying the "flat" three dimensional Laplace equation

$$
h_{\lambda \bar{\lambda}} + h_{\phi \phi} = 0. \tag{4.8}
$$

V. CONCLUSIONS

In this paper, proceeding from quaternionic $N = 8$ supersymmetric mechanics, we performed a reduction over a bosonic radial variable, ending up with a nonlinear off-shell supermultiplet with three bosonic end eight fermionic physical degrees of freedom. The simplest action describes the $N = 8$ supersymmetric mechanics with the sphere $S³$ in the bosonic part of the action. We find the irreducible constraints on the supermultiplet arising upon this reduction and construct the most general superfield action for three dimensional supersymmetric mechanics. The geometry of the bosonic sector of the most general sigma-model type action is described by an arbitrary function obeying the three dimensional Laplace equation on the sphere $S³$. Among the bosonic components of this new supermultiplet there is a constant which gives rise to potential terms. After dualization of this constant one may come back to the supermultiplet with four physical bosons. However, this new supermultiplet is highly nonlinear.

An obvious project for future study is to investigate the same type of radii reductions for other linear $N = 8$ supermultiplets [[15](#page-5-14),[24](#page-5-22)]. One may expect to find new nonlinear supermultiplets which will exhibit a new type of geometry in the bosonic sector. Another related interesting question concerns the superfield description of the supermultiplets depending on the arbitrary function, like our four dimensional nonlinear supermultiplet, which we constructed in the present paper by dualization of the coupling constant. Finally, it would be rather interesting to check the integrability of the constructed system for the simplest choices of the harmonic function h_{ϕ} in a full analogy with the results presented in [[25](#page-5-23)].

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