

Massive Klein-Gordon equation from a Bose-Einstein-condensation-based analogue spacetime

Matt Visser* and Silke Weinfurter†

*School of Mathematics, Statistics, and Computer Science, Victoria University of Wellington,
PO Box 600, Wellington, New Zealand.*

(Received 8 June 2005; published 18 August 2005)

We extend the “analogue spacetime” program by investigating a condensed-matter system that is in principle capable of simulating the massive Klein-Gordon equation in curved spacetime. Since many elementary particles have mass, this is an essential step in building realistic analogue models, and a first step towards simulating quantum gravity phenomenology. Specifically, we consider the class of two-component BECs subject to laser-induced transitions between the components. This system exhibits a complicated spectrum of normal mode excitations, which can be viewed as two interacting phonon modes that exhibit the phenomenon of refraction. We study the conditions required to make these two phonon modes decouple. Once decoupled, the two distinct phonons generically couple to distinct effective spacetimes, representing a bi-metric model, with one of the modes acquiring a mass. In the eikonal limit the massive mode exhibits the dispersion relation of a massive relativistic particle $\omega = \sqrt{\omega_0^2 + c^2 k^2}$, plus curved-space modifications. Furthermore, it is possible to tune the system so that both modes can be arranged to travel at the same speed, in which case the two phonon excitations couple to the same effective metric. From the analogue spacetime perspective this situation corresponds to the Einstein equivalence principle being satisfied.

DOI: [10.1103/PhysRevD.72.044020](https://doi.org/10.1103/PhysRevD.72.044020)

PACS numbers: 04.62.+v, 03.75.Kk, 03.75.Mn

I. INTRODUCTION

Analogue models for gravitation (which should more accurately be referred to as analogue models for curved-space-time) can be used to simulate classical and quantum field theory in curved-space-time [1–18]. The first analogue model for black holes, and for simulating Hawking evaporation, was suggested by Bill Unruh [1] in 1981. He demonstrated that a sound wave propagating through a converging fluid flow exhibits the same kinematics as does light in the presence of a curved-space-time background. Since then several other media—*e.g.* flowing dielectrics [2] and quantum liquids [3]—have been analyzed, and the field has developed tremendously [15–17]. The first approach specifically using Bose-Einstein condensates as an analogue model was made some 19 years after Unruh’s original paper [4]. Since then various configurations of BECs have been studied to simulate different scenarios for gravity [5–9]. Until now it has only been possible to simulate photons, (generally speaking, massless relativistic particles), propagating through a curved-space-time [10–18]. In the present article a two-species BEC is used to extend the class of equations that can be simulated to the full curved-space massive Klein-Gordon equation in $(3 + 1)$ dimensions. (In the language of the BEC community this corresponds to a specific and technologically interesting way of giving a mass to the phonon.) From the viewpoint of the general relativity community, this article provides a route for analogue simulations of curved-space quantum field theory that are more general and realistic

than those considered to date. (A preliminary sketch of these of these ideas appeared in reference [19]. An alternative route to the Klein-Gordon equation via textures in ^3He is described in [20], and the use of “wave guides” to restrict transverse oscillations and implicitly provide an effective $1 + 1$ dimensional mass is described in [6].)

II. TWO-COMPONENT BECS

The class of system we will use in our theoretical analysis is a two-component BEC. More specifically we consider an ultracold two-component BEC atomic gas such as, for example, a two-component condensate of ^{87}Rb atoms in different hyperfine levels, which we label $|A\rangle$ and $|B\rangle$. (Experiments using two different spin states, $|F = 1, m = -1\rangle$ and $|F = 2, m = 2\rangle$, were first performed at *JILA* in 1999 [21].) At very low temperatures nearly all atoms occupy the ground state. For the following calculation the noncondensed atoms are neglected. (In [22–26] finite temperature effects are taken into account.) The quantized field describing the microscopic system can be replaced by a classical mean-field, a macroscopic wavefunction. In this so-called mean-field approximation the number of noncondensed atoms is small. Interactions between the condensed and noncondensed atoms are neglected in the mathematical description, but two-particle collisions between condensed atoms are included. In the case of a two-component system, interactions within each species (U_{AA} , U_{BB}) and between the different species ($U_{AB} = U_{BA}$) take place. In addition the two condensates are coupled by a laser-beam, which drives transitions between the two hyperfine states with a constant rate λ . Without the laser coupling λ , no mass term is generated,

*Electronic address: matt.visser@mcs.vuw.ac.nz

†Electronic address: silke.weinfurter@mcs.vuw.ac.nz

which is consistent with the analysis in reference [9]. (In that article the advantages of using a two-component BEC to simulate cosmological inflation are presented.) Because, for current purposes, the two species are different hyperfine levels of the same atom, the masses of the individual atoms are approximately equal (to about one part in 10^{16}). In the current article we therefore set

$$m_A = m_B = m, \quad (1)$$

though we note that strictly speaking $m_A \neq m_B$. (Indeed in more abstract situations, potentially of relevance in quantum gravity phenomenology, it is worthwhile and instructive to keep this extra mass dependence explicit.)

The resulting coupled two-component time-dependent Gross-Pitaevskii equations are:

$$i\hbar\partial_t\Psi_A = \left[-\frac{\hbar^2}{2m}\nabla^2 + V_A - \mu_A + U_{AA}|\Psi_A|^2 + U_{AB}|\Psi_B|^2 \right] \Psi_A + \lambda\Psi_B, \quad (2)$$

$$i\hbar\partial_t\Psi_B = \left[-\frac{\hbar^2}{2m}\nabla^2 + V_B - \mu_B + U_{BB}|\Psi_B|^2 + U_{AB}|\Psi_A|^2 \right] \Psi_B + \lambda\Psi_A, \quad (3)$$

where $V_{A/B}$ denotes the two external potentials, and $\mu_{A/B}$ the two chemical potentials [27,28]. We note that the parameter λ can be either positive or negative without restriction, while the interaction parameters U_{AA} , U_{AB} , and U_{BB} are typically though not always positive. Adopting the Madelung representation, the two condensate wave-functions Ψ_X can be described in terms of their densities $\{\rho_A, \rho_B\}$ and phases $\{\theta_A, \theta_B\}$:

$$\Psi_X = \sqrt{\rho_X}e^{i\theta_X} \quad \text{for } X = A, B. \quad (4)$$

These four variables in general depend on both time and space.

III. WAVE EQUATION

We study zero sound in the overlap region of the two-component system, produced by exciting density perturbations which are small compared to the density of each condensate cloud. In the first experiment studying localized excitations in a one-component BEC [29], the optical dipole force of a focused laser beam was used to modify the trapping potential, generating a small density modulation. Using phase-contrast imaging it was shown that the resulting perturbation corresponds to a sound wave. The observed speed of sound is

$$c(r) = \sqrt{\frac{4\pi\hbar^2 a \rho_0(r)}{m^2}} = \sqrt{\frac{U\rho_0(r)}{m}}, \quad (5)$$

where $\rho_0(r)$ is the density of the ground state, a is the

scattering length, m is the atomic mass and U is the self-interaction constant. The mathematical equations describing these perturbations lead to the well-known hydrodynamic equations, which are the basis for the most fruitful of the analogies between condensed-matter physics and general relativity [1,4,10,15].

An extension of this method can be used to obtain the kinematic equations for small perturbations propagating in a two-component system. Given that the density modulation is small, the perturbations in the densities and phases can be expanded around their macroscopic states (4) using perturbation theory:

$$\Psi_X = \sqrt{\rho_{X0} + \varepsilon\rho_{X1}}e^{i(\theta_{X0} + \varepsilon\theta_{X1})} \quad \text{for } X = A, B. \quad (6)$$

These states still satisfy the coupled Gross-Pitaevskii equation. When developing a perturbation analysis for the fluctuations we find that unless we set the background phases equal to each other ($\theta_{A0} = \theta_{B0}$) the calculation becomes quite intractable. Specifically, one encounters mixing and damping terms dependent on $\Delta_{AB} = \theta_{A0} - \theta_{B0}$. In the appendix we briefly present the result obtained for arbitrary—even time-dependent—background phases. While these terms and their implications are of interest in their own right, in the following focus will be set on $\Delta_{AB} = 0$ automatically implying, in particular, that the background velocities of the condensates,

$$\vec{v}_{A0} = (\hbar/m)\nabla\theta_{A0} \quad \text{and} \quad \vec{v}_{B0} = (\hbar/m)\nabla\theta_{B0}, \quad (7)$$

are equal:

$$\vec{v}_0 = \vec{v}_{A0} = \vec{v}_{B0}. \quad (8)$$

After a straightforward calculation, the terms of first order in ε include two coupled equations for the perturbation of the phases

$$\begin{aligned} \dot{\theta}_{A1} &= -\vec{v}_0 \cdot \nabla\theta_{A1} - \frac{\tilde{U}_{AA}}{\hbar}\rho_{A1} - \frac{\tilde{U}_{AB}}{\hbar}\rho_{B1}, \\ \dot{\theta}_{B1} &= -\vec{v}_0 \cdot \nabla\theta_{B1} - \frac{\tilde{U}_{BB}}{\hbar}\rho_{B1} - \frac{\tilde{U}_{AB}}{\hbar}\rho_{A1}. \end{aligned} \quad (9)$$

Here

$$\begin{aligned} \tilde{U}_{AA} &= U_{AA} - \frac{\lambda}{2} \frac{\sqrt{\rho_{B0}}}{(\rho_{A0})^{3/2}}, \\ \tilde{U}_{BB} &= U_{BB} - \frac{\lambda}{2} \frac{\sqrt{\rho_{A0}}}{(\rho_{B0})^{3/2}}, \\ \tilde{U}_{AB} &= U_{AB} + \frac{\lambda}{2} \frac{1}{\sqrt{\rho_{A0}\rho_{B0}}}, \end{aligned} \quad (10)$$

are modified interaction potentials for the two coupled condensates. In addition to these two phase equations, there are two coupled equations for the density perturbations

$$\begin{aligned}\dot{\rho}_{A1} &= -\nabla \cdot \left(\frac{\hbar}{m_A} \rho_{A0} \nabla \theta_{A1} + \rho_{A1} \vec{v}_0 \right) \\ &\quad + \frac{2\lambda}{\hbar} \sqrt{\rho_{A0} \rho_{B0}} (\theta_{B1} - \theta_{A1}), \\ \dot{\rho}_{B1} &= -\nabla \cdot \left(\frac{\hbar}{m_B} \rho_{B0} \nabla \theta_{B1} + \rho_{B1} \vec{v}_0 \right) \\ &\quad + \frac{2\lambda}{\hbar} \sqrt{\rho_{A0} \rho_{B0}} (\theta_{A1} - \theta_{B1}).\end{aligned}\quad (11)$$

To adopt a more compact representation of the physics, it is useful to define several matrices and vectors. First, define the coupling matrix

$$\Xi = \frac{1}{\hbar} \begin{bmatrix} \tilde{U}_{AA} & \tilde{U}_{AB} \\ \tilde{U}_{AB} & \tilde{U}_{BB} \end{bmatrix}. \quad (12)$$

A second coupling matrix, defined as

$$\Lambda = \frac{2\lambda \sqrt{\rho_{A0} \rho_{B0}}}{\hbar} \begin{bmatrix} +1 & -1 \\ -1 & +1 \end{bmatrix}, \quad (13)$$

vanishes completely if the laser-coupling λ is switched off. Last but not least, it is also useful to introduce the mass-density matrix D

$$D = \frac{\hbar}{m} \begin{bmatrix} \rho_{A0} & 0 \\ 0 & \rho_{B0} \end{bmatrix}. \quad (14)$$

Now define the two-component column vectors

$$\bar{\theta} = \begin{bmatrix} \theta_{A1} \\ \theta_{B1} \end{bmatrix} \quad \text{and} \quad \bar{\rho} = \begin{bmatrix} \rho_{A1} \\ \rho_{B1} \end{bmatrix} \quad (15)$$

Collecting terms into a 2×2 matrix equation, the equations for the phases (9) and densities (11) become a compact pair of first-order PDEs

$$\dot{\bar{\theta}} = -\Xi \bar{\rho} - \vec{v}_0 \cdot \nabla \bar{\theta}, \quad (16)$$

$$\dot{\bar{\rho}} = -\nabla \cdot (D \nabla \bar{\theta} + \bar{\rho} \vec{v}_0) - \Lambda \bar{\theta}. \quad (17)$$

Equation (16) can be used to eliminate $\bar{\rho}$ and $\dot{\bar{\rho}}$ in Eq. (17), leaving us with a single second-order 2×2 matrix equation for the perturbed phases:

$$\begin{aligned}\partial_t (\Xi^{-1} \dot{\bar{\theta}}) &= -\partial_t (\Xi^{-1} \vec{v}_0 \cdot \nabla \bar{\theta}) - \nabla \cdot (\vec{v}_0 \Xi^{-1} \bar{\theta}) \\ &\quad + \nabla \cdot [(D - \vec{v}_0 \Xi^{-1} \vec{v}_0) \nabla \bar{\theta}] + \Lambda \bar{\theta}.\end{aligned}\quad (18)$$

This equation tells us how a localized collective excitation in a λ -coupled two-component BEC develops in time. It is a special case of the ‘‘normal mode’’ formalism developed in [11–13].

If we adopt a n -dimensional ‘‘spacetime’’ notation by writing $x^a = (t, x^i)$, with $i \in \{1, 2, \dots, n-1\}$ and $a \in \{0, 1, 2, \dots, n-1\}$, then this equation can be very compactly rewritten as [11,12]:

$$\partial_a (f^{ab} \partial_b \bar{\theta}) + \Lambda \bar{\theta} = 0. \quad (19)$$

Here f^{ab} is a n -dimensional rank 2 tensor density, each of

whose components is a 2×2 matrix. Specifically

$$f^{00} = -\Xi^{-1}; \quad f^{0i} = -\Xi^{-1} v_0^i = f^{i0}; \quad (20)$$

and

$$f^{ij} = D \delta_{ij} - \Xi^{-1} v_0^i v_0^j. \quad (21)$$

So far there are no significant restrictions on the background densities (ρ_{A0}, ρ_{B0}), the joint background flow velocity \vec{v}_0 , the interaction constants (U_{AA}, U_{BB}, U_{AB}), and coupling constant, λ . If we do not decouple the two modes, then the most we can say is that the coupled system exhibits ‘‘refringence’’ in the sense of [12,13].

IV. MODE DECOUPLING

The first step in analyzing Eq. (18), or the equivalent (19), is to ask whether it is possible to tune the system so as to completely decouple it into two independent phonon modes. Only if the two modes decouple is it possible to assign individual masses and spacetime geometries to the decoupled modes [11–13]. In the absence of decoupling, one simply has a complicated two-component system with no clear spacetime interpretation. In performing the analysis we have found that decoupling is not possible without introducing several constraints on the background quantities.

The decoupling analysis can be performed in several different ways, all ultimately leading to qualitatively similar physics, with minor technical differences. The major decision to be made is whether one imposes decoupling at the level of physical acoustics (at the level of the wave equation) or at the level of geometrical acoustics (at the level of dispersion relations). The fact that physical acoustics leads to propagation phenomena more subtle than those detectable in the geometric acoustics limit is well known [10,14]. A particularly illustrative example is provided by acoustic propagation in a fluid with nonzero vorticity [30], where the geometric acoustics approximation leads directly to a conformal class of effective spacetime metrics, while the physical acoustic approximation leads to a complicated system of PDEs. If the only thing you can detect experimentally is the dispersion relation, then one should adopt geometrical acoustics and not demand to decouple the wave equation itself. On the other hand, if one has experimental probes that couple directly to the wave itself, then the decoupling should be performed at the level of physical acoustics. We shall do both, and compare results later.

V. PHYSICAL ACOUSTICS

At the level of physical acoustics one treats the wave equation (19) as primary, then decoupling requires that all the (symmetric) matrices f^{ab} , and the (symmetric) matrix Λ , be simultaneously diagonalizable by position-independent orthogonal matrices O . That is, decoupling

requires

$$f^{ab} = O^T f_{\text{diag}}^{ab} O; \quad \Lambda = O^T \Lambda_{\text{diag}} O; \quad \tilde{\theta} = O \bar{\theta}; \quad (22)$$

since then Eq. (19) becomes

$$\partial_a (f_{\text{diag}}^{ab} \partial_b \tilde{\theta}) + \Lambda_{\text{diag}} \tilde{\theta} = 0. \quad (23)$$

Now since

$$\Lambda \propto \begin{bmatrix} +1 & -1 \\ -1 & +1 \end{bmatrix}, \quad (24)$$

the matrix that diagonalizes it is clearly position-independent, and the condition for simultaneous diagonalization reduces to

$$[f^{ab}, f^{cd}] = 0; \quad [f^{ab}, \Lambda] = 0; \quad (25)$$

where the commutators are to be interpreted in the sense of 2×2 matrix multiplication. That is, the matrices Ξ , D , and Λ must all be simultaneously diagonalizable.

We could now proceed by direct calculation of the three commutators

$$[\Xi, D]; \quad [D, \Lambda]; \quad [\Lambda, \Xi]. \quad (26)$$

A perhaps more direct analysis can be performed directly in terms of Eq. (18). Focusing on the last term in Eq. (18), the eigenvectors for nonzero coupling $\lambda \neq 0$ are given by $\{\{1, 1\}^T, [-1, 1]^T\}$. The corresponding eigenvalues are $\{0, 4\lambda\sqrt{\rho_{A0}\rho_{B0}}/\hbar\}$. These eigenvectors (though not the eigenvalues) are fixed, position-independent, and indeed independent of any of the other physical variables. As a result the only way to decouple Eq. (18) into two independent phonon modes, in a position-independent manner, is to demand:

$$\bar{\theta} = \tilde{\theta}_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \tilde{\theta}_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix}. \quad (27)$$

We now analyze Eq. (18) term by term with respect to this particular decomposition.

Firstly, the term on the LHS, and the first two terms on the RHS in Eq. (18), have the same eigenvectors as Eq. (27) *if and only if* $\tilde{U}_{AA} = \tilde{U}_{BB}$. The eigenvalues of Ξ^{-1} corresponding to the eigenvectors $\{\{1, 1\}^T, [-1, 1]^T\}$ are then

$$\left\{ \frac{\hbar}{(\tilde{U}_{AA} + \tilde{U}_{AB})}, \frac{\hbar}{(\tilde{U}_{AA} - \tilde{U}_{AB})} \right\}. \quad (28)$$

This places another constraint on the interaction variables: $\tilde{U}_{AA} \neq \pm \tilde{U}_{AB}$. [Indeed, note what happens if this condition fails and Ξ is singular. Then Eq. (16) cannot be solved for the column vector ρ and we cannot even set up the wave Eqs. (18) or (19).] All in all we must have

$$\Xi = \frac{1}{\hbar} \begin{bmatrix} \tilde{U}_{AA} & \tilde{U}_{AB} \\ \tilde{U}_{AB} & \tilde{U}_{AA} \end{bmatrix}; \quad \det(\Xi) \neq 0. \quad (29)$$

Secondly, we are now left with the penultimate term in Eq. (18). Because the eigenvectors of Ξ^{-1} are already

known, there is only the mass-density matrix D to consider. The final constraint to decouple the equation for the two phase perturbations is now easily seen to be $\rho_{A0} = \rho_{B0}$. We shall simply denote this common density by ρ_0 . That is

$$D = d\mathbf{I} = \frac{\hbar\rho_0}{m} \mathbf{I}. \quad (30)$$

In view of this last constraint the first coupling matrix simplifies considerably (and this was certainly not obvious when we started the analysis). We now have

$$\begin{aligned} \tilde{U}_{AA} &= U_{AA} - \frac{\lambda}{2\rho_0}, \quad \tilde{U}_{BB} = U_{BB} - \frac{\lambda}{2\rho_0}, \\ \tilde{U}_{AB} &= U_{AB} + \frac{\lambda}{2\rho_0}, \end{aligned} \quad (31)$$

and the first mode-decoupling constraint reduces to $U_{AA} = U_{BB}$. In order for the eigenvalues of Ξ^{-1} to be well defined we need both $U_{AA} + U_{AB} \neq 0$ and $\lambda \neq \rho_0(U_{AA} - U_{AB})$, which is a mild easily satisfiable constraint.

VI. BI-METRICITY

Applying all this to Eq. (18) one now sees how mode decoupling is equivalent to bi-metricity: One obtains two [dimension-independent] decoupled equations for the phonon modes described by the eigenstates of Eq. (27):

$$\partial_a (f_I^{ab} \partial_b \tilde{\theta}_I) = -\frac{4\lambda\rho_0}{\hbar} \delta_{2I} \tilde{\theta}_I, \quad \text{for } I = 1, 2, \quad (32)$$

where δ_{2I} is the usual Kronecker delta. Here

$$f_I^{ab} = \frac{d}{c_I^2} \begin{bmatrix} -1 & -v_0^j \\ -v_0^j & c_I^2 \delta^{ij} - v_0^i v_0^j \end{bmatrix}, \quad (33)$$

where the possibly distinct propagation speeds c_I are defined in terms of the eigenvalues Ξ_I of the matrix Ξ by

$$c_I^2 = \Xi_I d = \frac{d(\tilde{U}_{AA} + (-1)^I \tilde{U}_{AB})}{\hbar}, \quad (34)$$

that is

$$c_I^2 = \frac{\rho_0(\tilde{U}_{AA} + (-1)^I \tilde{U}_{AB})}{m}. \quad (35)$$

It is important to note that decoupling by itself does not force the two propagation speeds to be equal—decoupling in this context generically produces a two-metric model [bi-metricity], and the demand that every phonon couple to a single effective metric [monometricity] is an additional independent condition. (In general the phonons arising from a system of N interacting BECs would, if they decoupled in the above manner, lead to an N -metric model.)

Introducing the (dimension-independent) natural oscillation frequency

$$\omega_0^2 = -\frac{4\lambda\rho_0 c_I^2}{\hbar d} = -\frac{4\lambda m c_I^2}{\hbar^2}, \quad (36)$$

we can write

$$\partial_a(f_I^{ab}\partial_b\tilde{\theta}_I) = \frac{d}{c_2^2}\omega_0^2\delta_{2I}\tilde{\theta}_I, \quad \text{for } I = 1, 2, \quad (37)$$

where ω_0 now has the physical interpretation that it is the frequency at which a position-independent (zero-momentum) configuration oscillates.

When converting the contravariant tensor densities f_I^{ab} into covariant spacetime metrics g_{ab} one encounters a number of dimension-dependent factors [10,18], such that naive application of the formalism leads to peculiar dimensionalities for physical quantities. The best way we have found for keeping track of these factors is to introduce space and time-independent *reference constants* c_* and d_* and write

$$\tilde{f}^{ab} = \frac{c_*}{d_*}f^{ab} = \left(\frac{c_*d}{c_I d_*}\right)\frac{1}{c_I}\begin{bmatrix} -1 & -v_0^j \\ -v_0^j & c_I^2\delta^{ij} - v_0^i v_0^j \end{bmatrix}, \quad (38)$$

so that

$$\partial_\mu(\tilde{f}_I^{\mu\nu}\partial_\nu\tilde{\theta}_I) = \frac{c_*d}{c_2 d_*}\frac{\omega_0^2\delta_{2I}}{c_2}\tilde{\theta}_I, \quad \text{for } I = 1, 2. \quad (39)$$

Here c_* and d_* are any convenient but fixed reference values. They might be (for instance) the spatial average values of c_2 and d over the entire condensate, or they might be chosen in terms of the speed of light and other fundamental constants. They are introduced for convenience, and do not ultimately affect the physics we are discussing.

Now introducing a pair of effective ‘‘spacetime metrics’’ by the identifications

$$\sqrt{-g_I}g_I^{ab} = \tilde{f}_I^{ab} \quad \text{and} \quad g_I = \frac{1}{\det[g_I^{ab}]}, \quad (40)$$

we can recast these wave equations equations as a pair of curved-space Klein-Gordon [massive d’Alembertian] equations

$$\frac{1}{\sqrt{-g_I}}\partial_a(\sqrt{-g_I}g_I^{ab}\partial_b\tilde{\theta}_I) = \frac{\mathbf{m}_{\text{phonon}}^2 c_*^2}{\hbar^2}\delta_{2I}\tilde{\theta}_I, \quad (41)$$

where as we shall soon see all quantities carry their standard dimensionality.

After a brief algebraic calculation we find

$$\sqrt{-g_I} = c_I\left(\frac{c_*d}{c_I d_*}\right)^{n/(n-2)} \quad (42)$$

and so

$$g_I^{ab} = \left(\frac{c_*d}{c_I d_*}\right)^{-n/(n-2)}\left\{\frac{1}{c_I^2}\begin{bmatrix} -1 & -v_0^j \\ -v_0^j & c_I^2\delta^{ij} - v_0^i v_0^j \end{bmatrix}\right\}. \quad (43)$$

These quantities depend on the space-time dimension n [10,18] in such a manner that

$$g_{ab}^I = \left(\frac{c_*d}{c_I d_*}\right)^{n/(n-2)}\begin{bmatrix} -(c_I^2 - v_0^2) & -v_0^j \\ -v_0^j & \delta^{ij} \end{bmatrix}. \quad (44)$$

Finally the mass-term is

$$\mathbf{m}_{\text{phonon}}^2 = \frac{\hbar^2\omega_0^2}{c_*^2 c_2^2}\left(\frac{c_*d}{c_2 d_*}\right)^{-2/(n-2)}. \quad (45)$$

We note that this ‘‘mass’’ term can in principle depend on position, so some authors might prefer to refer to it as a ‘‘potential’’ term. There is no universal agreement on terminology regarding this point, but the bulk of the community would be happy to refer to this as a ‘‘position dependent mass’’. Furthermore, if one focuses on the core of the BEC cloud, where all gradients are by definition zero (or small), then this mass term is guaranteed to be approximately constant.

Now the two metrics g_{ab}^I , the inverse metrics g_I^{ab} , and the phonon mass $\mathbf{m}_{\text{phonon}}^2$, all depend on the normalization constants c_* and d_* . This is as it should be, since c_* and d_* were introduced to give canonical dimensions to these quantities. In particular, since c_* and d_* contribute to the overall conformal factor in the analogue spacetime metric, they set the overall scale with respect to which analogue ‘‘masses’’ are to be measured. However, correctly formulated physical questions will depend only on parameters such as ω_0 , c_I , and v_0 which are independent of these normalization constants. For instance, in the eikonal limit the dispersion relation for these two decoupled phonon modes is simply

$$(\omega - \vec{v}_0 \cdot \vec{k})^2 - c_I^2 k^2 = \omega_0^2 \delta_{2I}. \quad (46)$$

(A similar calculation, but restricted to a one-condensate system, where all variables are likewise allowed to be time and space dependent, but no mass term is present, has been presented in [8].)

For the phase vector $\tilde{\theta}_1$, (corresponding to perturbations in the two condensates A and B oscillating ‘‘in phase’’), the mass term is always zero. However, for a laser-coupled system ($\lambda \neq 0$) the mass-term in the equation for $\tilde{\theta}_2$, (corresponding to perturbations in the two condensates A and B oscillating in ‘‘antiphase’’), does not vanish.

VII. MONO-METRICITY

Comparing the definition for the speed of sound (5) in a one-component system, with the two speeds c_I introduced here, we see that the c_I (34) are simply the λ -modified speeds of sound for each decoupled phonon mode. (For instance, consider an idealized situation in which the two condensates decouple completely, $U_{AB} = 0$ and $\lambda = 0$, the two c_I ’s become the independent phonon speeds in each condensate cloud.) This fact leaves us with the possibility of constructing two different types of analogue model. So far we have been dealing with a two-metric structure, which is interesting in itself [12,31]. For instance, in the

absence of laser-coupling, $\lambda = 0$, the presence of two different speed of sounds can be used for tuning effects [9].

If we wish to more accurately simulate the curved space-time of our own universe, another constraint should be placed on the system, to make the two speeds of sound equal $c = c_1 = c_2$. This yields a single sound-cone structure, to match the observed fact that our universe exhibits a single light-cone structure. This condition is fulfilled if we set

$$\tilde{U}_{AB} = 0; \quad \Rightarrow \quad \lambda = -2U_{AB}\rho_0. \quad (47)$$

In this case

$$c^2 = \frac{\rho_0 \tilde{U}_{AA}}{m} = \frac{\rho_0(U_{AA} + U_{AB})}{m}, \quad (48)$$

while we have the dimension-independent result that the natural oscillation frequency becomes

$$\omega_0^2 = 8 \frac{\rho_0^2 U_{AB}(U_{AA} + U_{AB})}{\hbar^2}. \quad (49)$$

In counterpoint

$$\mathbf{m}_{\text{phonon}}^2 = \frac{8U_{AB}\rho_0 m}{c_*^2} \left[\frac{(U_{AA} + U_{AB})d_*^2 m}{\hbar^2 c_*^2 \rho_0} \right]^{1/(n-2)}. \quad (50)$$

We note that in typical situations $U_{AA} \approx U_{BB}$ and U_{AB} are both positive, corresponding to repulsive atomic interactions [28]. This implies that λ is then negative, corresponding to a negative trapping potential, but a positive ω_0^2 and a positive $\mathbf{m}_{\text{phonon}}^2$.

It is also possible to choose systems such that U_{AB} is negative, as long as c^2 is still kept positive, which in turn requires $U_{AA} + U_{AB}$ to be positive, and places a restriction on the relative sizes of the self-interactions and cross-interactions. This implies that λ is positive. Furthermore the natural oscillation frequency ω_0^2 and the phonon mass $\mathbf{m}_{\text{phonon}}^2$ will then be real and negative. That is, attractive atomic interactions, which signal an instability in the condensate, would in our analysis correspond to a tachyonic phonon.

If in contrast we permit c^2 to go negative (that is we permit $U_{AA} + U_{AB}$ to be negative) then we have a ‘‘Euclidean signature regime’’ where phonons do not propagate—this corresponds to the gross instability of the condensate which manifests itself as the ‘‘Bose-Nova’’ phenomenon [32].

In this monometric situation, while the in-phase perturbations will propagate exactly at the speed of sound,

$$\vec{v}_s = \vec{v}_0 + \hat{k}c, \quad (51)$$

the antiphase perturbations will move with a lower group velocity given by:

$$\vec{v}_g = \frac{\partial \omega}{\partial \vec{k}} = \vec{v}_0 + \hat{k} \frac{c^2}{\sqrt{\omega_0^2 + c^2 k^2}}. \quad (52)$$

Here k is the usual wave number. This explicitly demonstrates that the group velocity of the antiphase eigenstate depends on the laser-induced coupling between the condensates.

VIII. SPECIAL CASE: CONSTANT Ξ

There is a special case that is worth considering separately. Suppose that the matrix Ξ is a time and space-independent constant. Then by defining

$$\bar{\theta}_{\text{new}} = \Xi^{-1/2} \bar{\theta}, \quad (53)$$

multiplying Eq. (16) by $\Xi^{+1/2}$, and appropriately commuting Ξ through the space and time derivatives, one can rewrite Eq. (16) as

$$\begin{aligned} \partial_t^2 \bar{\theta}_{\text{new}} = & -\partial_t (\mathbf{I} \vec{v}_0 \cdot \nabla \bar{\theta}_{\text{new}}) - \nabla \cdot (\vec{v}_0 \mathbf{I} \bar{\theta}_{\text{new}}) \\ & + \nabla \cdot [(C^2 - \vec{v}_0 \mathbf{I} \vec{v}_0 \cdot) \nabla \bar{\theta}_{\text{new}}] - M^2 \bar{\theta}_{\text{new}}, \end{aligned} \quad (54)$$

where

$$C^2 = \Xi^{1/2} D \Xi^{1/2}; \quad M^2 = -\Xi^{1/2} \Lambda \Xi^{1/2}. \quad (55)$$

Now the existence of the matrix square root $\Xi^{1/2}$ follows since Ξ itself is real and symmetric. Indeed by the Hamilton-Cayley theorem for 2×2 matrices we know

$$\Xi^{1/2} = a \mathbf{I} + b \Xi, \quad (56)$$

where a and b are functions of the eigenvalues of Ξ . A little matrix algebra yields (for 2×2 matrices only) the explicit formula

$$\Xi^{1/2} = \frac{\sqrt{\det \Xi} \mathbf{I} + \Xi}{\sqrt{2\sqrt{\det \Xi} + \text{tr}(\Xi)}}. \quad (57)$$

It is now clear that both C^2 and M^2 are symmetric matrices, so in this constant- Ξ special case mode decoupling of the wave Eq. (54), that is bi-metricity, requires the simple constraint

$$[C^2, M^2] = 0, \quad (58)$$

which is equivalent to the matrix equation

$$D \Xi \Lambda = \Lambda \Xi D. \quad (59)$$

In terms of the physical parameters we obtain the constraint

$$\rho_{A0} \tilde{U}_{AA} - \rho_{B0} \tilde{U}_{BB} = (\rho_{A0} - \rho_{B0}) \tilde{U}_{AB}. \quad (60)$$

Note that to get to this stage we had to assume Ξ was constant (so \tilde{U}_{AA} , \tilde{U}_{AB} , and \tilde{U}_{BB} are constant), and then from the above we see that decoupling requires that ρ_{A0}/ρ_{B0} must be a position and time-independent constant. We do not however need $\rho_{A0} = \rho_{B0}$; by *restricting* the position and time dependence of Ξ we have permitted other parts of the wave-equation to possess an algebraically more *general* solution to the decoupling constraint (the bi-

metricity constraint). Subject only to the condition (60) the speeds of sound and masses are simply extracted as eigenvalues of the matrices C^2 and M^2 respectively.

Imposing the bi-metricity condition (60) the two eigenvalues of C^2 , the two speeds of sound, are

$$c_{\pm}^2 = \frac{1}{2m} \{ \rho_{A0} \tilde{U}_{AA} + \rho_{B0} \tilde{U}_{BB} \pm (\rho_{A0} + \rho_{B0}) \tilde{U}_{AB} \}. \quad (61)$$

Additionally imposing the monometricity condition requires the two eigenvalues of C^2 to be the same. That is, monometricity enforces $\tilde{U}_{AB} = 0$. Together with the decoupling condition Eq. (60), we now get:

$$\rho_{A0} \tilde{U}_{AA} = \rho_{B0} \tilde{U}_{BB}. \quad (62)$$

That is

$$c^2 = \frac{\rho_{A0} \tilde{U}_{AA}}{m} = \frac{\rho_{B0} \tilde{U}_{BB}}{m}. \quad (63)$$

and

$$\begin{aligned} \omega_0^2 &= \text{tr}[M^2] \\ &= \frac{4\rho_{A0}\rho_{B0}U_{AB}[U_{AA} + U_{BB} + U_{AB}(\frac{\rho_{A0}}{\rho_{B0}} + \frac{\rho_{B0}}{\rho_{A0}})]}{\hbar^2} \end{aligned} \quad (64)$$

The eigenvector corresponding to the massless phonon mode is $\bar{\theta}_{\text{new}} \propto [\sqrt{\tilde{U}_{BB}}, \sqrt{\tilde{U}_{AA}}]^T$, while that for the massive phonon mode is $\bar{\theta}_{\text{new}} \propto [-\sqrt{\tilde{U}_{AA}}, \sqrt{\tilde{U}_{BB}}]^T$. In terms of the original variables $\bar{\theta}$ this corresponds to decoupled eigenmodes $\bar{\theta} \propto [1, 1]^T$ for the massless mode, while that for the massive phonon mode $\bar{\theta} \propto [-\tilde{U}_{AA}, \tilde{U}_{BB}]^T$.

IX. SPECIAL CASE: CONSTANT D

Similarly, consider the case where the matrix D is independent of position and time—this corresponds to a situation where the background densities ρ_{A0} and ρ_{B0} are constant, though they do not need to be equal. In this situation we can define

$$\bar{\theta}_{\text{new}} = D^{+1/2} \bar{\theta}. \quad (65)$$

Then multiplying Eq. (16) by $D^{-1/2}$, and appropriately commuting D through the space and time derivatives, one can rewrite Eq. (16) as

$$\begin{aligned} \partial_t(C^{-2}\partial_t\bar{\theta}_{\text{new}}) &= -\partial_t(C^{-2}\tilde{\mathbf{v}}_0 \cdot \nabla\bar{\theta}_{\text{new}}) - \nabla \cdot (\tilde{\mathbf{v}}_0 C^{-2}\dot{\bar{\theta}}_{\text{new}}) \\ &\quad + \nabla \cdot [(\mathbf{I} - \tilde{\mathbf{v}}_0 C^{-2}\tilde{\mathbf{v}}_0) \nabla\bar{\theta}_{\text{new}}] - \tilde{M}^2\bar{\theta}_{\text{new}}, \end{aligned} \quad (66)$$

where now

$$C^{-2} = D^{-1/2}\Xi^{-1}D^{-1/2}; \quad \tilde{M}^2 = -D^{-1/2}\Lambda D^{-1/2}. \quad (67)$$

The analysis is now similar to the case of constant- Ξ . Decoupling (bi-metricity) requires

$$[C^{-2}, \tilde{M}^2] = 0, \quad (68)$$

that is

$$\Xi^{-1}D^{-1}\Lambda = \Lambda D^{-1}\Xi^{-1}. \quad (69)$$

It is easy to rearrange this equation to yield

$$\Lambda\Xi D = D\Xi\Lambda, \quad (70)$$

which is the *same* matrix equation as encountered in the constant- Ξ case. Consequently, decoupling requires the *same* algebraic condition, Eq. (60) as in the constant- Ξ case. The speeds of sound are now given by the eigenvalues of the matrix

$$C^2 = D^{+1/2}\Xi D^{+1/2}, \quad (71)$$

and explicit computation again yields, after imposing the decoupling constraint (60), the same algebraic result (61). Imposing monometricity again leads to $\tilde{U}_{AB} = 0$ and Eq. (62), which in this case can be read off by inspection from Eq. (71). In short, there is no new physics hiding in the case of constant D ; we again see that by *restricting* the position and time dependence of some of the coefficients in the wave equation (18) we have permitted other parts of the wave-equation to possess a slightly more general solution to the decoupling constraint (the bi-metricity constraint).

X. GEOMETRICAL ACOUSTICS—FRESNEL EQUATION

In geometrical acoustics we adopt the eikonal approximation

$$\bar{\theta} = \mathcal{A} \exp(-i\varphi) \quad (72)$$

with a slowly varying amplitude \mathcal{A} and a rapidly varying phase φ . We also assume that the coefficients in the differential Eq. (18) are slowly varying compared to the phase. This approximation leads, before we apply the decoupling constraints, to the Fresnel equation [11,12]

$$\begin{aligned} \det\{\omega^2\Xi^{-1} - 2\omega(\tilde{\mathbf{v}}_0 \cdot \vec{k})\Xi^{-1} \\ - [Dk^2 - (\tilde{\mathbf{v}}_0 \cdot \vec{k})^2\Xi^{-1}] + \Lambda\} = 0. \end{aligned} \quad (73)$$

In a 2-component BEC the Fresnel equation is in general a quartic dispersion relation for two interacting phonon modes. This approximation makes sense when the period and wavelength of the phonon mode is small compared to the timescale and distance scale over which the background configuration changes.

As was the case in the constant- Ξ physical acoustics analysis, it is convenient to pre-multiply and post-multiply the Fresnel equation by $\Xi^{+1/2}$, thereby rewriting the Fresnel equation as

$$\det\{\omega^2\mathbf{I} - 2\omega(\tilde{\mathbf{v}}_0 \cdot \vec{k})\mathbf{I} - [C^2k^2 - (\tilde{\mathbf{v}}_0 \cdot \vec{k})^2\mathbf{I}] - M^2\} = 0, \quad (74)$$

where again

$$C^2 = \Xi^{1/2} D \Xi^{1/2}; \quad M^2 = -\Xi^{1/2} \Lambda \Xi^{1/2}. \quad (75)$$

Thus by adopting the eikonal approximation implicit in the Fresnel equation one has reduced the number of matrices one needs to deal with to C^2 and M^2 , now without needing to strictly enforce the spatial and temporal constancy of Ξ (or D). The Fresnel equation now becomes

$$\det\{(\omega - \vec{v}_0 \cdot \vec{k})^2 \mathbf{I} - C^2 k^2 - M^2\} = 0. \quad (76)$$

Imposing mode decoupling, which is now equivalent to the Fresnel equation factorizing into two quadratics, forces M^2 and C^2 to be simultaneously diagonalizable. [In which case we recover Eq. (46).] Finally, imposing monometricity enforces $C^2 = c^2 \mathbf{I}$, with M^2 symmetric and singular but otherwise unconstrained.

Thus an analysis in terms of the Fresnel equation leads to the same conclusions as the direct physical acoustics analysis in the special case of constant Ξ , or the special case of constant D — these are the same algebraic constraints as were obtained when analyzing Eqs. (54) and (66), albeit in a slightly different physical regime.

XI. DISCUSSION

In conclusion, the calculation presented in this article is of interest to two separate communities. For the BEC community, it provides a specific example of how to tune an interacting two-BEC condensate in such a manner as to obtain a massive phonon. With the background configurations in phase, but without the fine tuning, it provides an example of two interacting phonon modes whose wave equation is governed by the second-order coupled system of PDEs (18) or equivalently (19), and whose dispersion relation is governed by the quartic Fresnel Eq. (76).

It is important to note that fully decoupling the wave equation in a completely general background is algebraically more restrictive than the problem of decoupling the Fresnel equation in the geometrical acoustics limit. Indeed in the geometrical acoustics limit decoupling places algebraic constraints on the coefficients of the wave equation that are equivalent to physical acoustics in the special case where the matrix Ξ or the matrix D is both position and time independent. This situation is to a good approximation relevant at and near the center of the BEC cloud. The subtleties involved in implementing decoupling into independent modes is surprisingly more complex than one might at first envisage.

If for the sake of discussion we insert specific numbers relevant to a BEC mixture based on hyperfine states in ^{87}Rb , we find $\omega_0 \approx 150$ kHz. For a harmonic magnetic trap this should be compared with a typical trap oscillation frequency of 100 kHz, though note that for nonharmonic traps one can in principle make the trap oscillation frequency arbitrarily small. Similarly we find $\lambda \approx 10^{29}$ J, corresponding to a laser temperature of 800 nK (to be

compared to a BEC condensation temperature of some μK). We also point out that with current single-component BECs, and for the specific experimental configuration described in [33], the excitation spectrum $\omega(k)$ has been measured from 100 Hz to 14 kHz, corresponding to wave-numbers from $k \approx 1/(2\pi R)$ out to $k\xi \approx 4.5$ —the lower limit on wave-number being set by the size of the trap and the upper limit being well into the nonlinear part of the Bogolubov spectrum [33]. There is no sign of any non-linearity at low momenta [33]. A somewhat related experiment, now using tomographic techniques [34], probes the region 250 Hz to 2 kHz, and $k\xi \approx 0.3$ to $k\xi \approx 1$ —again verifying the applicability of the Bogolubov spectrum, and also verifying applicability of the hydrodynamic approximation at low momenta [34]. Thus the mass ω_0 that we have argued we can set up in 2-BEC systems can be arranged to be somewhat larger than the trap oscillation frequency, but lie in a range where $\omega(k)$ is experimentally measurable — the relevant experimental signal would be a specific form of nonlinearity of the phonon spectrum for low momentum.

In short, the effects we have been considering in this article lie at the cutting edge of present day experimental technique. In this regard it is important to realise that multicomponent BECs have already been constructed in the laboratory [35]. The technological issues in actually implementing this approach for generating the massive Klein-Gordon equation amount to keeping the background condensates in phase while decoupling the phonon modes in a simple manner. Doing this may be experimentally challenging, but there appears to be no obstacle in principle to actually implementing the model.

From the general relativity perspective, this article settles an important matter of principle: It provides an example of an analogue system that can be used to mimic a minimally coupled massive scalar field embedded in a curved spacetime. Quantum fields of this type are essential for any realistic application of analogue spacetime ideas to particle physics, and, in particular, are essential for developing condensed-matter simulations of quantum gravity phenomenology.

ACKNOWLEDGMENTS

This research was supported by the Marsden Fund administered by the Royal Society of New Zealand. The authors wish to thank Crispin Gardiner, Piyush Jain, Ashton Bradley, and John Close for their thoughtful comments.

APPENDIX: WAVE EQUATION FOR ARBITRARY INITIAL PHASES

If we start our calculations with a more complex phase relationship between the two condensates then the wave equation (18) gains additional terms.

The result we obtain for two arbitrary initial—possibly even time-dependent—background phases is:

$$\begin{aligned} \partial_t(\Xi^{-1}\dot{\theta}) = & -\partial_t(\Xi^{-1}\vec{V}\nabla\theta) - \nabla(\vec{V}\Xi^{-1}\dot{\theta}) + \nabla((D - \vec{V}\Xi^{-1}\vec{V})\nabla\theta) + \Lambda\dot{\theta} + \{-C_{\text{density}}\Xi^{-1}C_{\text{phase}} + \partial_t(\Xi^{-1}C_{\text{phase}}) \\ & + \nabla(\vec{V}\Xi^{-1}C_{\text{phase}})\}\dot{\theta} + \{\Xi^{-1}C_{\text{phase}} + C_{\text{density}}\Xi^{-1}\}\dot{\theta} + \{\vec{V}\Xi^{-1}C_{\text{phase}} + C_{\text{density}}\Xi^{-1}\vec{V}\}\nabla\theta. \end{aligned} \quad (\text{A1})$$

In addition to those matrices defined in the previous calculations, three new matrices show up.

The matrix \vec{V} simply contains the two background velocities of each condensate,

$$\vec{V} = \begin{bmatrix} \vec{v}_{A0} & 0 \\ 0 & \vec{v}_{B0} \end{bmatrix}, \quad (\text{A2})$$

now with two possibly distinct background velocities,

$$\vec{v}_{A0} = \frac{\hbar}{m}\nabla\theta_{A0}, \quad \vec{v}_{B0} = \frac{\hbar}{m}\nabla\theta_{B0}, \quad (\text{A3})$$

Additionally, we also obtain two completely new matrices, which vanish in the case of identical initial phases

$$\Delta_{AB} := \theta_{A0} - \theta_{B0} = 0. \quad (\text{A4})$$

These new matrices are the coupling-phase matrix,

$$C_{\text{phase}} = \frac{\lambda \sin\Delta_{AB}}{\hbar} \begin{bmatrix} +\sqrt{\frac{\rho_{B0}}{\rho_{A0}}} & -\sqrt{\frac{\rho_{B0}}{\rho_{A0}}} \\ +\sqrt{\frac{\rho_{A0}}{\rho_{B0}}} & -\sqrt{\frac{\rho_{A0}}{\rho_{B0}}} \end{bmatrix}, \quad (\text{A5})$$

and the coupling-density matrix

$$C_{\text{density}} = \frac{\lambda \sin\Delta_{AB}}{\hbar} \begin{bmatrix} -\sqrt{\frac{\rho_{B0}}{\rho_{A0}}} & -\sqrt{\frac{\rho_{A0}}{\rho_{B0}}} \\ +\sqrt{\frac{\rho_{B0}}{\rho_{A0}}} & +\sqrt{\frac{\rho_{A0}}{\rho_{B0}}} \end{bmatrix}. \quad (\text{A6})$$

In the case of identical phases Eq. (A1) simplifies to the wave equation (18) found in the previous calculation. Specifically the first two lines of (A1) are exactly the same as (18), while the next two lines represent a mass-shift, and the last two lines correspond to a damping-term and a smoothing term, respectively.

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