Nonlinear evolutions and non-Gaussianity in generalized gravity

Seoktae Koh^{1,*} and Sang Pyo Kim^{1,2,†}

¹Department of Physics, Kunsan National University, Kunsan 573-701, Korea² *Asia Pacific Center for Theoretical Physics, Pohang 790-784, Korea*

Doo Jong Song‡

Korea Astronomy Observatory, Daejeon 305-348, Korea (Received 26 January 2005; published 9 June 2005)

We use the Hamilton-Jacobi theory to study the nonlinear evolutions of inhomogeneous spacetimes during inflation in generalized gravity. We find the exact solutions to the lowest order Hamilton-Jacobi equation for special scalar potentials and introduce an approximation method for general potentials. The conserved quantity invariant under a change of timelike hypersurfaces proves useful in dealing with gravitational perturbations. In the long-wavelength approximation, we find a conserved quantity related to the new canonical variable that makes the Hamiltonian density vanish, and calculate the non-Gaussianity in generalized gravity. The slow-roll inflation models with a single scalar field in generalized gravity predict too small non-Gaussianity to be detected by future CMB experiments.

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I. INTRODUCTION

Inflation scenario is a successful model to solve the problems of the standard Big Bang theory and explains remarkably the observational data. Quantum fluctuations of a scalar field are adiabatic and Gaussian during the inflation period and provide a seed for density perturbations. The amplitudes of the perturbations freeze out when the perturbations stretch out to the superhorizon scale by an accelerated expansion. Inflation also gives the scale invariant spectrum $(n_s = 1)$ when the perturbation modes cross the horizon. Linear perturbation theory is enough to explain these gravitational perturbations and temperature anisotropy in the early universe.

Recent WMAP observations [1] try to find a signal of the non-Gaussianity in the temperature anisotropy. The non-Gaussian signal in the CMB anisotropy might be generated either from the nonvacuum initial state [2] or from nonlinear gravitational perturbation [3]. Gaussian statistical properties are completely specified by the two-point correlation function. However, the two-point correlation function is not sufficient to describe the statistical properties of the non-Gaussianity, so it is necessary to investigate higher order correlations such as the three-point correlation for nonlinearity of a perturbation field or the four-point correlation for a nonvacuum initial state. Second order perturbation theory has been used to explain the non-Gaussianity in the temperature anisotropy [3]. In addition to second order perturbation theory, the Hamiltonian formalism turned out to useful to deal with nonlinear evolutions in the early universe and was applied to canonical quantum gravity [4] or semiclassical gravity [5,6] for a long time.

Salopek and Bond in Ref. [7] employed the Hamiltonian formalism to study the nonlinear evolutions of gravitational perturbations. It was also applied to Brans-Dicke theory [8] and low energy effective string theory [9]. Especially, the Hamilton-Jacobi theory provides a powerful tool to get solutions of nonlinear evolutions in the early universe through a generating functional which satisfies the momentum constraint equation. Even though it is difficult to get exact solutions of the Hamilton-Jacobi equation for general potentials, the large scale perturbation, which contributes mainly to the large scale structure in the present Universe, could be treated appropriately using the longwavelength approximation. The long-wavelength approximation assumes that the length scale of the spatial variation is much longer than the Hubble radius, so it is a reasonable assumption to deal with superhorizon scale perturbations. It is also known that the gauge invariant conserved quantity exists in nonlinear perturbation theory for a superhorizon scale [7,10,11].

Brans-Dicke type gravity naturally emerges from the fundamental theory of particle physics such as string or M-theory. Although it is not clear how scalar fields couple to gravity, it is necessary to investigate the perturbations in the alternative gravity theory such as $f(\phi)R$ type gravity as well as in Einstein gravity. Recent supernovae observation [12] and WMAP results [13] imply that our universe today is in an accelerated expansion phase and dominated by the dark energy which has the equation of state, $p/\rho < -1/3$. It is also needed to consider nonlinear evolutions of such a matter component to see whether their existence affects the temperature anisotropy.

In this paper, the Hamilton-Jacobi formalism will be used to study the nonlinear evolutions of inhomogeneous spacetimes in generalized gravity theory during the inflation period. The canonical variables will be transformed to new ones that make the new Hamiltonian density vanish

^{*}Electronic address: kohst@ihanyang.ac.kr

[†] Electronic address: sangkim@kunsan.ac.kr

[‡] Electronic address: djsong@kao.re.kr

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and these new variables are constant in time for fixed spacelike hypersurfaces. The gauge invariant quantity, , which is conserved in the large scale limit, is derived from one of new canonical variables. By introducing the nonlinear parameter, f_{NL} , the conserved quantity may be decomposed into a linear Gaussian part, *L*, and a nonlinear part [14]:

$$
\zeta(\mathbf{x}) = \zeta_L(\mathbf{x}) + \frac{3}{5} f_{NL} [\zeta_L^2(\mathbf{x}) - \langle \zeta_L^2(\mathbf{x}) \rangle]. \tag{1.1}
$$

Non-Gaussianity is parameterized through f_{NL} which will be constrained by observations. It is generally expected to be difficult to detect a non-Gaussian signal in CMB experiments for a single field inflation model in Einstein gravity [3]. So the detection of the non-Gaussianity can constrain different inflation models.

This paper is organized as follows. In Sec. II, we derive the Hamilton and momentum constraint equations in generalized gravity. The Hamilton-Jacobi equation will be obtained through a canonical transformation. Assuming a generating functional which satisfies the momentum constraint equation, we get the conserved quantity that is invariant under a change of timelike hypersurfaces in the long-wavelength approximation. In Sec. III, non-Gaussianity will be computed using the generalized curvature perturbation on comoving hypersurfaces. Finally, we discuss the physical implications of the non-Gaussianity in generalized gravity in Sec. IV.

II. HAMILTON-JACOBI FORMALISM IN GENERALIZED GRAVITY

A. Hamilton equations

The generalized gravity action to be studied in this paper is given by

$$
I = \int \sqrt{-g} \left[\frac{1}{2} f(\phi) R - \frac{1}{2} \omega(\phi) g^{\mu \nu} \partial_{\mu} \phi \partial_{\nu} \phi - V(\phi) \right],
$$
\n(2.1)

where $f(\phi)$, $\omega(\phi)$ and $V(\phi)$ are functions of a scalar field ϕ . We shall confine our attention to the slow-roll inflation models that are described by this action. Einstein gravity is recovered when $f(\phi) = 1/8\pi G$ and $\omega(\phi) = 1$. Further, Brans-Dicke theory is prescribed by $f(\phi) =$ $\phi/8\pi$, $\omega(\phi) = \omega/8\pi\phi$ and $V = 0$; the nonminimally coupled scalar field theory corresponds to $f(\phi) =$ $(1 - 8\pi G \xi \phi^2)/8\pi G$ and $\omega(\phi) = 1$; the low energy effective string theory is given by $f(\phi) = e^{-\phi}$ and $\omega(\phi) =$ $e^{-\phi}$. We consider the Arnowitt-Deser-Misner (ADM) metric

$$
ds^{2} = (-N^{2} + N_{i}N^{i})dt^{2} + 2N_{i}dtdx^{i} + \gamma_{ij}dx^{i}dx^{j}, (2.2)
$$

where N and N^i are a lapse function and a shift vector, respectively, and γ_{ij} is a 3-spatial metric. The 4-dimensional Ricci scalar, *R*, can be written in terms of the 3-dimensional Ricci scalar, 3*R*, and the extrinsic curvature, K_{ij} , as [15]

$$
R = {}^{3}R + K_{ij}K^{ij} - K^{2} - \frac{2}{N\gamma^{1/2}} \left[\frac{\partial}{\partial t} (\gamma^{1/2}K) - (\gamma^{1/2}KN^{i} - \gamma^{1/2}\gamma^{ij}N_{,j})_{,i} \right].
$$
\n(2.3)

The terms in the square bracket in the above formula are total derivatives or surface terms so that they can be integrated out in Einstein gravity. They cannot, however, be neglected in generalized gravity. The extrinsic curvature tensor and trace are given by

$$
K_{ij} = \frac{1}{2N} \left(N_{i|j} + N_{j|i} - \frac{\partial \gamma_{ij}}{\partial t} \right), \qquad K = \gamma^{ij} K_{ij} = K_i^i,
$$
\n(2.4)

where the vertical bar is a covariant derivative with respect to γ_{ij} . The *K* is a generalization of the Hubble parameter. By varying action with respect to $\dot{\gamma}_{ij}$ and $\dot{\phi}$, the momenta conjugate to γ_{ij} and ϕ are obtained as

$$
\pi^{ij} = -\frac{1}{2}\gamma^{1/2}f(K^{ij} - K\gamma^{ij}) - \frac{f_{,\phi}}{2N}\gamma^{1/2}\gamma^{ij}(\dot{\phi} - N^k\partial_k\phi),
$$
\n(2.5)

$$
\pi^{\phi} = f_{,\phi} \gamma^{1/2} K + \gamma^{1/2} \frac{\omega}{N} (\dot{\phi} - N^{i} \partial_{i} \phi). \tag{2.6}
$$

From these relations, *K* can be written as

$$
K = \frac{1}{(1+3\Omega)\gamma^{1/2}} \left[\frac{1}{f} \pi^{\gamma} + \frac{3\Omega}{f_{,\phi}} \pi^{\phi} \right],\tag{2.7}
$$

where $\pi^{\gamma} = \gamma^{ij}\pi_{ij}$. Variations of the action with respect to *N* and *Nⁱ* lead to the Hamiltonian and momentum constraint equations, respectively,

$$
\mathcal{H} = \frac{2}{\gamma^{1/2} f} \pi^{ij} \pi^{kl} \bigg[\gamma_{ik} \gamma_{jl} - \frac{1 + 2\Omega}{2(1 + 3\Omega)} \gamma_{ij} \gamma_{kl} \bigg] \n+ \frac{1}{2(1 + 3\Omega)} \frac{1}{\gamma^{1/2} \omega} (\pi^{\phi})^2 - \frac{2\Omega}{1 + 3\Omega} \frac{1}{\gamma^{1/2} f_{,\phi}} \pi^{\gamma} \pi^{\phi} \n- \frac{1}{2} \gamma^{1/2} f^3 R + \frac{1}{2} \gamma^{1/2} (2f_{,\phi\phi} + \omega) \gamma^{ij} \partial_i \phi \partial_j \phi \n+ \gamma^{1/2} V + \gamma^{1/2} f_{,\phi} \Delta \phi = 0, \tag{2.8}
$$

$$
\mathcal{H}_i = -2\partial_j(\gamma_{ik}\pi^{kj}) + \pi^{kl}\partial_i\gamma_{kl} + \pi^{\phi}\partial_i\phi = 0, \quad (2.9)
$$

where

$$
\Omega(\phi) \equiv \frac{f_{,\phi}^2}{2f\omega}, \qquad \Delta\phi = \phi_{|i}^{|i}.
$$
 (2.10)

Then one finds the action of the form

$$
I = \int d^4x [\pi^{ij}\dot{\gamma}_{ij} + \pi^{\phi}\dot{\phi} - N\mathcal{H} - N^i\mathcal{H}_i].
$$
 (2.11)

Here, N and N^i are considered as Lagrange multipliers. The evolution equations for γ_{ij} and ϕ can be obtained by varying the action (2.11) with respect to π^{ij} and π^{ϕ} .

$$
\frac{1}{N}(\dot{\gamma}_{ij} - N_{i|j} - N_{j|i}) = \frac{4}{\gamma^{1/2} f} \left[\pi_{ij} - \frac{1 + 2\Omega}{2(1 + 3\Omega)} \pi^{\gamma} \gamma_{ij} \right] - \frac{2\Omega}{1 + 3\Omega} \frac{1}{\gamma^{1/2} f_{,\phi}} \gamma_{ij} \pi^{\phi},
$$
\n(2.12)

$$
\frac{1}{N}(\dot{\phi} - N^i \partial_i \phi) = \frac{1}{(1 + 3\Omega)\gamma^{1/2}} \left[\frac{1}{\omega} \pi^{\phi} - \frac{2\Omega}{f_{,\phi}} \pi^{\gamma}\right].
$$
\n(2.13)

It should be remarked that though momenta (2.5) and (2.6) seem to depend on the choice of the lapse function *N* and the shift vector N_i , the Hamilton-Jacobi formalism is gauge invariant. The Hamiltonian and momentum constraint Eqs. (2.8) and (2.9) are invariant under general coordinate transformations on three-dimensional hypersurfaces [4]. In fact, each choice of N and N_i corresponds to certain conditions on spacetime coordinates only but does not change physical quantities.

B. Hamilton-Jacobi equation

To solve the Hamiltonian and the momentum constraint equations, (2.8) and (2.9), we use the Hamilton-Jacobi theory. Through an appropriate canonical transformation from γ_{ij} , ϕ , π^{ij} and π^{ϕ} to new ones $\tilde{\gamma}_{ij}$, $\tilde{\phi}$, $\tilde{\pi}^{ij}$ and $\tilde{\pi}^{\phi}$, we can construct a vanishing Hamiltonian

$$
\tilde{H} = H + \frac{\partial S}{\partial t} = 0, \tag{2.14}
$$

where

$$
H = \int d^3x (N \mathcal{H} + N^i \mathcal{H}_i), \tag{2.15}
$$

and the generating functional *S* is a function of ϕ , γ_{ij} , $\ddot{\phi}$ and $\tilde{\gamma}_{ij}$. Then the canonical transformation gives the following relations

$$
\pi^{ij} = \frac{\delta S}{\delta \gamma_{ij}}, \qquad \pi^{\phi} = \frac{\delta S}{\delta \phi}, \qquad \tilde{\pi}^{ij} = -\frac{\delta S}{\delta \tilde{\gamma}_{ij}}, \qquad \tilde{\pi}^{\phi} = -\frac{\delta S}{\delta \tilde{\phi}}.
$$
 (2.16)

Finally, we get the Hamilton-Jacobi equation from the Hamiltonian constraint

$$
\frac{2}{\gamma^{1/2}f} \frac{\delta S}{\delta \gamma_{ij}} \frac{\delta S}{\delta \gamma_{kl}} \bigg[\gamma_{ik} \gamma_{jl} - \frac{1+2\Omega}{2(1+3\Omega)} \gamma_{ij} \gamma_{kl} \bigg] + \frac{1}{2(1+3\Omega)} \frac{1}{\gamma^{1/2} \omega} \bigg(\frac{\delta S}{\delta \phi} \bigg)^2 - \frac{2\Omega}{1+3\Omega} \frac{1}{\gamma^{1/2} f_{,\phi}} \gamma_{ij} \frac{\delta S}{\delta \gamma_{ij}} \frac{\delta S}{\delta \phi} - \frac{1}{2} \gamma^{1/2} f^3 R + \frac{1}{2} \gamma^{1/2} (2f_{,\phi\phi} + \omega) \gamma^{ij} \partial_i \phi \partial_j \phi + \gamma^{1/2} V + \gamma^{1/2} f_{,\phi} \Delta \phi = 0, \quad (2.17)
$$

and the momentum constraint equation

$$
-2\partial_j \left(\gamma_{ik}\frac{\delta S}{\delta \gamma_{kj}}\right) + \frac{\delta S}{\delta \gamma_{kl}}\partial_i \gamma_{kl} + \frac{\delta S}{\delta \phi}\partial_i \phi = 0. \quad (2.18)
$$

The momentum constraint equation implies that the generating functional $S(\phi, \gamma_{ij}, \tilde{\phi}, \tilde{\gamma}_{ij})$ is invariant under spatial coordinate transformations. In general, the momentum constraint equation does not vanish through canonical transformations as long as N^i does not vanish. On the contrary, the Hamiltonian constraint vanishes strongly. It is difficult to solve the Hamilton-Jacobi equation, (2.17), in general, except for special cases such as an exponential potential in Einstein gravity [7].

C. Long-wavelength approximation

To deal with the large scale gravitational perturbations, it is reasonable to use the approximation that temporal variations of fields are much greater than spatial variations. In inflation scenario, the inhomogeneous field, whose physical wavelength is much larger than the horizon size at the end of the inflation period, mostly contributes to formation of the large scale structure in the present universe and large angle CMB anisotropy. The longwavelength approximation assumes that the characteristic scale, λ , of spatial variations is much longer than the Hubble radius, H^{-1} , [7,8]:

$$
\frac{1}{a}\partial_i \gamma_{jk} \ll \dot{\gamma}_{jk} \to \lambda_{ph} = a\lambda \gg H^{-1},\tag{2.19}
$$

where *H* is a Hubble parameter, and λ_{ph} and λ are a physical and a comoving wavelength, respectively. The generating functional can be expanded in a series of spatial gradient terms

$$
S = S^{(0)} + S^{(2)} + S^{(4)} + \cdots
$$
 (2.20)

The lowest order Hamilton-Jacobi equation neglects the terms containing spatial gradients. In this paper we only consider the lowest order Hamilton-Jacobi equation which is sufficient for dealing with the nonlinear evolution of the inhomogeneous gravitational fields. Then the lowest order Hamilton-Jacobi equation is

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$$
\frac{2}{\gamma^{1/2}f} \frac{\delta S^{(0)}}{\delta \gamma_{ij}} \frac{\delta S^{(0)}}{\delta_{kl}} \left[\gamma_{ik} \gamma_{jl} - \frac{1+2\Omega}{2(1+3\Omega)} \gamma_{ij} \gamma_{kl} \right] + \frac{1}{2(1+3\Omega)} \frac{1}{\gamma^{1/2} \omega} \left(\frac{\delta S^{(0)}}{\delta \phi} \right)^2 - \frac{2\Omega}{1+3\Omega} \frac{1}{\gamma^{1/2} f_{,\phi}} \gamma_{ij} \frac{\delta S^{(0)}}{\delta \gamma_{ij}} \frac{\delta S^{(0)}}{\delta \phi} + \gamma^{1/2} V = 0. \quad (2.21)
$$

We assume an ansatz for lowest order generating functional, $S^{(0)}$, such that it satisfies the momentum constraint Eq. (2.18).

$$
S^{(0)}(\phi, \gamma_{ij}, \theta) = 2\beta \int d^3x \gamma^{1/2} f^{3/2}(\phi) W(\phi, \gamma_{ij}, \theta),
$$
\n(2.22)

where θ is a new canonical variable involving $\tilde{\gamma}_{ij}$ and ϕ , and β is a constant which carries a dimension. For Einstein gravity, *W* can be interpreted as a locally defined Hubble gravity, *w* can be interpreted as a R
parameter if we take $\beta = -\sqrt{8\pi G}$.
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7 as a locally defined Hubble
 $\sqrt{8\pi G}$ [7]. This generating functional automatically satisfies the momentum constraint equations if $N^i = 0$, and this will be discussed in the next section.

It is convenient to factor the 3-spatial metric γ_{ij} into a conformal factor and a conformal 3-spatial metric h_{ij} with the unit determinant $\det(h_{ij}) = 1$:

$$
\gamma_{ij}(t, \mathbf{x}) = \gamma^{1/3}(t, \mathbf{x}) h_{ij}(\mathbf{x}). \tag{2.23}
$$

The gravitational waves are related to the h_{ij} . Then, from Eq. (2.16), the conjugate momenta for γ_{ii} and ϕ are

$$
\pi^{ij} = 2\beta f^{3/2} \gamma^{1/2} \left[\frac{1}{2} \gamma^{ij} W + \gamma^{-1/3} \left\{ \frac{\partial W}{\partial h_{ij}} \right. \right.\left. - \frac{1}{3} h^{ij} h_{kl} \frac{\partial W}{\partial h_{kl}} \right],
$$
\n(2.24)

$$
\pi^{\phi} = 2\beta \gamma^{1/2} \left[\frac{3}{2} f^{1/2} \frac{\partial f}{\partial \phi} + f^{3/2} \frac{\partial W}{\partial \phi} \right],
$$
 (2.25)

where we have used [16]

$$
\frac{\partial W}{\partial \gamma_{ij}} = \gamma^{-1/3} \left[\frac{\partial W}{\partial h_{ij}} - \frac{1}{3} h^{ij} h_{kl} \frac{\partial W}{\partial h_{kl}} \right],
$$
 (2.26)

which is traceless, $\gamma_{ij}\partial W/\partial \gamma_{ij} = 0$. If we decompose π^{ij} into the trace π^{γ} and the traceless part $\bar{\pi}^{ij}$, they are given by

$$
\pi^{\gamma} = 3\beta f^{3/2} \gamma^{1/2} W,
$$

$$
\bar{\pi}^{ij} = 2\beta f^{3/2} \gamma^{1/6} \left[\frac{\partial W}{\partial h_{ij}} - \frac{1}{3} h^{ij} h_{kl} \frac{\partial W}{\partial h_{kl}} \right].
$$
 (2.27)

If N^i is set to zero, from Eqs. (2.12) and (2.23) we can write

$$
\bar{\pi}_{ij} = \frac{\gamma^{1/6} f}{4} \frac{1}{N} \dot{h}_{ij}.
$$
 (2.28)

and thus the traceless part of π^{ij} takes part in the gravitational wave. And from Eq. (2.5), $\bar{\pi}^{ij} \propto \bar{K}^{ij}$ where \bar{K}^{ij} is a traceless part of K^{ij} . In the long-wavelength approximation, $\bar{K}^{ij} \propto \gamma^{-1/2}$ [7,17]. \bar{K}^{ij} decays exponentially fast when $\gamma^{-1/2} \propto a^{-3}$ during inflation where *a* is a scale factor. $\bar{\pi}^{ij}$ can thus be set to zero. This implies that the

gravitational wave contribution can be ignored in our present consideration. As long as we do not concern with the gravitational radiations, *W* is assumed to be independent of *hij*. Then the Hamilton-Jacobi equation becomes

$$
W^2 - \frac{2f}{3\omega(1+3\Omega)} \left(\frac{\partial W}{\partial \phi}\right)^2 - \frac{1}{3\beta^2 f^2} V = 0, \qquad (2.29)
$$

and the evolution equations for γ and ϕ are

$$
K \equiv -\frac{1}{2N} \frac{\dot{\gamma}}{\gamma} = \frac{3\beta f^{1/2}}{1 + 3\Omega} \bigg[(1 + 3\Omega)W + \frac{f_{,\phi}}{\omega} \frac{\partial W}{\partial \phi} \bigg],
$$
\n(2.30)

$$
\frac{1}{N}\dot{\phi} = \frac{2\beta f^{3/2}}{\omega(1+3\Omega)}\frac{\partial W}{\partial \phi}.
$$
 (2.31)

D. Solutions of Hamilton-Jacobi equation

Although the Hamilton-Jacobi Eq. (2.29) is difficult to be exactly solved for general potentials, it can be solved for some special cases in generalized gravity.

$$
I. V = 3\beta^2 f^2
$$

If the potential is given by $V(\phi) = 3\beta^2 f^2(\phi)$, then the Hamilton-Jacobi equation takes the form

$$
\left(\frac{\partial W}{\partial \phi}\right)^2 - \alpha^2 W^2 + \alpha^2 = 0, \qquad (2.32)
$$

where

$$
\alpha^2(\phi) = \frac{3\omega(1+3\Omega)}{2f}.
$$
 (2.33)

As $\alpha^2 > 0$, Eq. (2.32) can be exactly integrated to yield [18]

$$
W(\phi) = \cosh\left[\pm \int \alpha(\phi)d\phi + C\right],\tag{2.34}
$$

where *C* is an integration constant. The solution of the form (2.34) is available for a constant potential in Einstein gravity or a massive scalar field potential for the generalized gravity with $f(\phi) \propto \phi$.

2. $V = 0$ *or general potentials*

With the identification of $W = q$ and $\phi = t$, the Hamilton-Jacobi equation may be interpreted as a timedependent inverted oscillator with a unit mass, frequency α , and energy $\alpha^2 \rho$:

$$
\frac{1}{2}\left(\frac{\partial W}{\partial \phi}\right)^2 - \frac{1}{2}\alpha^2 W^2 = -\frac{1}{2}\alpha^2 \rho,\tag{2.35}
$$

where $\rho(\phi) = V/(3\beta^2 f^2)$. In fact, this inverted oscillator has a ϕ -dependent energy and curvature (spring constant) thas a φ -dependent energy and curvature (spring constant)
of potential. The $W = \pm \sqrt{\rho}$ are two fixed or stationary -
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ว points.

First, in the case of $\rho = 0$ corresponding to the Brans-Dicke gravity or low energy effective string theory, the solution can easily be obtained

$$
W_0(\phi) = W_0(\phi_i) \exp\left[\pm \int_{\phi_i}^{\phi} \alpha d\phi\right],
$$
 (2.36)

where $W_0(\phi_i)$ is an initial value at ϕ_i . When α is nonsquare integrable, the solution (2.36) for the upper $(+)$ sign grows to $\pm \infty$ as ϕ goes to ∞ depending on the sign of $W_0(\phi_i)$. This corresponds to the downward motions in Fig. 1. Whereas, for the lower $(-)$ sign, the solution approaches an attractor 0 regardless of $W_0(\phi_i)$ as ϕ goes to ∞ . The solution approaches the attractor 0 regardless of $W_0(\phi_i)$ for the upper sign, but it diverges to $\pm \infty$ for the lower sign depending on the sign of $W_0(\phi_i)$ as ϕ goes to $-\infty$. On the other hand, for a square integrable α , as ϕ goes to $\pm \infty$, the solution (2.36) approaches finite values, $W_0(\phi_i)$ exp $\left[\pm \int_{\phi_i}^{+\infty} \alpha d\phi\right]$, not necessarily attractors, which correspond to the upward motions in Fig. 1.

For general potentials with $\rho \neq 0$, we have a similar picture as shown in Fig. 2. Not only the energy but also the curvature of the potential depend on ϕ . In the analogy of an oscillator, as shown in Fig. 2, the total energy line moves up or down depending on $\alpha^2 \rho$ and the ϕ -dependent curvature α^2 narrows or widens the parabola. As for the $\rho = 0$ case, *W* either approaches to attractors or diverges to $\pm \infty$,

FIG. 1. The inverted oscillator for $\rho = 0: \frac{1}{2}(\frac{\partial W}{\partial \phi})^2 - \frac{1}{2}\alpha^2 W^2 =$ 0.

depending on the sign of $W_0(\phi_i)$ and the behavior of α and ρ , as $|\phi|$ grows. This behavior of *W* for general potentials can be calculated numerically [19].

To find approximately an analytical solution for general potentials, we can write $W(\phi)$ as $W(\phi) = W_0(\phi)Z(\phi)$, where $W_0(\phi)$ is a homogeneous solution (2.36). Then the Hamilton-Jacobi equation reduces to the equation for $Z(\phi)$:

$$
\left(\frac{\partial Z}{\partial \phi}\right)^2 + 2 \frac{\partial \ln W_0}{\partial \phi} Z \frac{\partial Z}{\partial \phi} + \frac{\alpha^2 \rho}{W_0^2} = 0, \tag{2.37}
$$

where we have used Eq. (2.35) for $\rho = 0$. Equation (2.37) is a nonlinear equation for $Z(\phi)$. Assuming that $Z(\phi)$ is a slowly varying function of ϕ , we can introduce a small parameter δ to indicate smallness of the nonlinear terms and rewrite Eq. (2.37) as

$$
2\frac{\partial \ln W_0}{\partial \phi} Z \frac{\partial Z}{\partial \phi} + \delta \left(\frac{\partial Z}{\partial \phi}\right)^2 + \frac{\alpha^2 \rho}{W_0^2} = 0.
$$
 (2.38)

The parameter δ will be set to one in the final result. Now we expand $Z(\phi)$ in a series of δ

$$
Z(\phi) = Z^{(0)} + \delta Z^{(1)} + \delta^2 Z^{(2)} + \cdots.
$$
 (2.39)

Substituting Eq. (2.39) into Eq. (2.38) and comparing terms of the same powers of δ , we obtain the following equations up to first order

(a) δ^0 :

$$
2\frac{\partial \ln W_0}{\partial \phi} Z^{(0)} \frac{\partial Z^{(0)}}{\partial \phi} + \frac{\alpha^2 \rho}{W_0^2} = 0, \qquad (2.40)
$$

(b) δ^1 :

$$
2\frac{\partial \ln W_0}{\partial \phi} \left(Z^{(0)} \frac{\partial Z^{(1)}}{\partial \phi} + Z^{(1)} \frac{Z^{(0)}}{\partial \phi} \right) + \left(\frac{\partial Z^{(0)}}{\partial \phi} \right)^2 = 0.
$$
\n(2.41)

FIG. 2. The inverted oscillator for $\rho \neq 0$: $\frac{1}{2}(\frac{\partial W}{\partial \phi})^2 - \frac{1}{2}\alpha^2 W^2 =$ $-\frac{1}{2}\alpha^2\rho$.

The solutions at each order can easily be found

$$
Z^{(0)} = \pm \left(-\int \frac{\alpha^2 \rho}{W_0^2 \partial \ln W_0 / \partial \phi} d\phi\right)^{1/2},
$$

\n
$$
Z^{(1)} = -\frac{1}{2Z^{(0)}} \int \frac{(\partial Z^{(0)}/\partial \phi)^2}{\partial W_0 / \partial \phi} d\phi.
$$
\n(2.42)

On the other hand, for a rapidly varying function $Z(\phi)$, we can repeat the same analysis and write Eq. (2.37) as

$$
\left(\frac{\partial Z}{\partial \phi}\right)^2 + 2\delta Z \frac{\partial \ln W_0}{\partial \phi} \frac{\partial Z}{\partial \phi} + \frac{\alpha^2 \rho}{W_0^2} = 0 \tag{2.43}
$$

With the series expansion (2.39) for $Z(\phi)$, we obtain the following equations up to first order

(a) δ^0 :

$$
\left(\frac{\partial Z^{(0)}}{\partial \phi}\right)^2 + \frac{\alpha^2 \rho}{W_0^2} = 0
$$
 (2.44)

(b) δ^1 :

$$
\frac{\partial Z^{(1)}}{\partial \phi} + \frac{\partial \ln W_0}{\partial \phi} Z^{(0)} = 0 \tag{2.45}
$$

These equations can be simply integrated to give

$$
Z^{(0)} = \pm \int \sqrt{-\frac{\alpha^2 \rho}{W_0^2}} d\phi, Z^{(1)} = -\int \frac{\partial \ln W_0}{\partial \phi} Z^{(0)} d\phi.
$$
\n(2.46)

The validity of the approximation in Eqs. (2.38) and (2.43) for specific models will be discussed in a future work [19].

E. Conserved quantities

In Eq. (2.22), *W* depends on ϕ , γ_{ij} , and θ , where θ is a new canonical variable that has the conjugate momentum

$$
\pi^{\theta} = -2\beta \gamma^{1/2} f^{3/2}(\phi) \frac{\partial W}{\partial \theta}.
$$
 (2.47)

Then the momentum constraint Eq. (2.9) reduces to [16]

$$
\tilde{\mathcal{H}}_i = \pi^\theta \partial_i \theta. \tag{2.48}
$$

Since the new variable is chosen to make the new Hamiltonian density vanish, the new Hamiltonian contains only a contribution from the momentum constraint

$$
\tilde{H} = \int d^3x N^i \pi^\theta \partial_i \theta. \tag{2.49}
$$

The Hamilton equations for the new variable are

$$
\dot{\theta} - N^i \partial_i \theta = 0, \quad \dot{\pi}^\theta - \partial_i (N^i \pi^\theta) = 0. \quad (2.50)
$$

In general, the new canonical variable needs not to be constant in time, but if the spacelike hypersurfaces are

chosen such that the shift vector, N^i , vanishes, then θ and π^{θ} are constants for fixed spatial coordinates [16].

The spatial gradients of inhomogeneous quantities are gauge invariant because they vanish on a homogeneous background [20]. By taking the spatial gradient of the logarithm of the canonical new variable (2.47), we can obtain the gauge invariant quantity

$$
\partial_i \ln |\pi^{\theta}| = \frac{1}{2} \partial_i \ln \gamma + \partial_i \phi \left[\frac{3}{2} \frac{\partial \ln f}{\partial \phi} + \frac{\partial}{\partial \phi} \ln \frac{\partial W}{\partial \theta} \right].
$$
\n(2.51)

To calculate the last term in the above equation, we differentiated the Hamilton-Jacobi Eq. (2.29) with respect to θ :

$$
\frac{\partial}{\partial \phi} \ln \frac{\partial W}{\partial \theta} = 3\beta f^{1/2} W \frac{N}{\dot{\phi}}.
$$
 (2.52)

With this relation, Eq. (2.51) now becomes

$$
\partial_i \ln |\pi^{\theta}| = \frac{1}{2} \partial_i \ln \gamma + \frac{NK}{\dot{\phi}} \partial_i \phi, \tag{2.53}
$$

where we have used Eqs. (2.30) and (2.31). This quantity is similar to the gauge invariant quantity $\zeta = \Psi$ – $(3H/\dot{\phi})\delta\phi$ in the linear perturbation theory, which is conserved at the superhorizon scale. Here Ψ is a Newtonian gravitational potential. We define the generalized gauge invariant quantity ζ_i in nonlinear theory, which is conserved in the large scale limit

$$
\zeta_i \equiv \frac{1}{3} \partial_i \ln |\pi^{\theta}| = \frac{1}{6} \partial_i \ln \gamma + \frac{NK}{3\dot{\phi}} \partial_i \phi.
$$
 (2.54)

Following Refs. [7,10], we can briefly show that ζ_i is indeed a gauge invariant quantity under the coordinate transformation $(t, x^j) \rightarrow (T(t, x^j), X^j(t, x^j))$ in the longwavelength approximation. For the coordinate transformation

$$
t, x^{j} \rightarrow T(t, x^{j}), X^{j}(t, x^{j}), \qquad (2.55)
$$

by integrating x^j along a line of constant X^j , we obtain [7]

$$
x^{j} = X^{j} + \int \frac{T^{j}}{T_{,0}T^{,0}} dT.
$$
 (2.56)

As x^j and X^j differ only by a first order spatial gradient term, we have, up to the same order,

$$
\frac{\partial x^i}{\partial X^j} \simeq \delta^i_j, \quad \gamma_{kl}(t, x^j) = \delta^{k'}_k \delta^{l'}_l \gamma_{k'l'}(t, X^j). \tag{2.57}
$$

Using these, we can obtain

$$
\partial_i \ln \gamma = \partial_i T \partial_T \ln \tilde{\gamma} + \frac{\partial}{\partial X^i} \ln \tilde{\gamma}
$$
 (2.58)

$$
\partial_i \phi = \partial_i T \partial_T \tilde{\phi} + \frac{\partial}{\partial X^i} \tilde{\phi} \tag{2.59}
$$

where

up to first order spatial gradient. We can thus show that

$$
\zeta_i = \frac{1}{6} \partial_i \ln \gamma + \frac{NK}{3\dot{\phi}} \partial_i \phi
$$

= $\frac{1}{6} \frac{\partial}{\partial X^i} \ln \tilde{\gamma} + \frac{NK}{3\partial_T \phi} \partial_i \tilde{\phi} + \frac{1}{6} \partial_i T \partial_T \ln \tilde{\gamma} + \frac{NK}{3\partial_T \phi} \partial_T \tilde{\phi}.$
(2.61)

From the definition of $K = -\partial_T \ln \gamma / 2N$, the last two terms in the second line in Eq. (2.61) cancel each other. Thus ζ_i is a gauge invariant up to first order spatial gradient. Although ζ_i is defined on the uniform energy density hypersurfaces in general, it coincides with a curvature perturbation \mathcal{R}_i , which is defined on the comoving hypersurfaces in a scalar field dominated universe and also conserved in the large scale limit. ζ_i and \mathcal{R}_i are proved to be conserved in the large scale limit in Refs. [10,11].

III. NON-GAUSSIANITY IN GENERALIZED GRAVITY

Non-Gaussianity in CMB might be generated by a nonvacuum initial state [2] or a nonlinear perturbation [3], even though the initial perturbation is Gaussian. Although the nonvacuum initial state gives the zero three-point correlation function, the relation between the four-point and the two-point correlation functions, which obey the Gaussian statistics,

$$
\left\langle \left(\frac{\delta T}{T}\right)^4 \right\rangle = 3 \left\langle \left(\frac{\delta T}{T}\right)^2 \right\rangle^2, \tag{3.1}
$$

is no longer satisfied [2]. Whereas the nonlinear gravitational perturbation leads to a nonzero three-point correlation function. In this paper we shall focus on the non-Gaussian signal in CMB only from nonlinear perturbations. To show the non-Gaussianity by the nonlinear perturbation, the gravitational potential Φ may be decomposed into a linear part and a nonlinear part with a nonlinear parameter f_{NL} [14]

$$
\Phi(\mathbf{x}) = \Phi_L(\mathbf{x}) + f_{NL}[\Phi_L^2(\mathbf{x}) - \langle \Phi_L^2(\mathbf{x}) \rangle]. \tag{3.2}
$$

Here, $\Phi_L(\mathbf{x})$ is a linear Gaussian perturbation that has the zero expectation value $\langle \Phi_L \rangle = 0$.

With this definition, the nonvanishing component of the $\Phi(\mathbf{k})$ -bispectrum, which is the Fourier transform of the three-point correlation function in the coordinate space, is [14]

$$
\langle \Phi_L(\mathbf{k}_1) \Phi_L(\mathbf{k}_2) \Phi_{NL}(\mathbf{k}_3) \rangle = 2(2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3)
$$

$$
\times f_{NL} P_{\Phi}(\mathbf{k}_1) P_{\Phi}(\mathbf{k}_2), \quad (3.3)
$$

where $P_{\Phi}(\mathbf{k})$ is the linear power spectrum given by

$$
\langle \Phi_L(\mathbf{k}_1)\Phi_L(\mathbf{k}_2)\rangle = (2\pi)^3 P_{\Phi}(\mathbf{k}_1)\delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2), \quad (3.4)
$$

$$
\mathcal{L}^{\mathcal{L}}(\mathcal{L}^{\mathcal{L}}(\mathcal{L}^{\mathcal{L}}))
$$

$$
\Phi_{NL}(\mathbf{k}) = f_{NL} \bigg[\int \frac{d^3 k'}{(2\pi)^3} \Phi_L(\mathbf{k} + \mathbf{k}') \Phi_L^*(\mathbf{k}')
$$

$$
- (2\pi)^3 \delta^{(3)}(\mathbf{k}) \langle \Phi_L^2(\mathbf{x}) \rangle \bigg]. \tag{3.5}
$$

It is known that f_{NL} should be larger than order unity to be detectable by CMB experiment. But the single field inflationary model gives too much small value of $f_{NL} \propto$ $\mathcal{O}(\epsilon, \eta)$ where ϵ and η are slow-roll parameters [3]. Thus, if the non-Gaussianity is detected, it can constrain inflationary models. However, it would be interesting to calculate non-Gaussianity in generalized gravity theories.

We follow the method in Ref. [7] to calculate the nonlinear curvature perturbations on the comoving hypersurfaces. The 3-spatial metric γ_{ij} can be written as

$$
\gamma_{ij}(t, \mathbf{x}) = a^2(t, \mathbf{x}) h_{ij}(\mathbf{x}), \qquad (3.6)
$$

where $a(t, \mathbf{x})$ is a local expansion factor, and the conformal 3-metric, $h_{ij}(\mathbf{x})$, is independent of time and has the unit determinant, $det(h_{ij}) = 1$. Then the local Hubble parameter *H* takes the form

$$
H = \frac{1}{N} \frac{\dot{a}}{a} = -\frac{1}{3} K.
$$
 (3.7)

If we choose ϕ as a time coordinate on the comoving hypersurfaces, we can obtain $ln a(\phi, \mathbf{x})$ from Eq. (2.30)

$$
\ln a(\phi, \mathbf{x}) - \ln a(\phi_0, \mathbf{x}) = -\int_{\phi_0}^{\phi} d\phi N H. \quad (3.8)
$$

We use the notation $(\delta \phi)_{\mathcal{R}} (\ln a_0, \mathbf{x}) \equiv \partial_i \phi (\ln a_0, \mathbf{x}) =$ $\phi(\ln a_0, \mathbf{x}) - \phi(\ln a_0, \mathbf{x}_0)$ for the scalar field fluctuation on the spatially flat hypersurfaces $(\partial_i \ln a = 0)$ and $\mathcal{R}_{\delta\phi}(\phi_0, \mathbf{x}) \equiv \partial_i \ln a(\phi_0, \mathbf{x}) = \ln a(\phi_0, \mathbf{x}) - \ln a(\phi_0, \mathbf{x}_0)$ for the curvature perturbation on the comoving hypersurfaces $(\partial_i \phi = 0)$. The scalar field fluctuations on the spatially flat hypersurfaces are needed to transform to the curvature perturbation on the comoving hypersurface. Then the curvature perturbation on comoving hypersurfaces is given by

$$
\mathcal{R}_{\delta\phi} = -\int_{\phi_0}^{\phi_0 + (\delta\phi)_R} d\phi N H. \tag{3.9}
$$

Using Eqs. (2.30) and (2.31), we get $\mathcal{R}_{\delta\phi}$

$$
\mathcal{R}_{\delta\phi} = \frac{1}{2} \int_{\phi_0}^{\phi_0 + (\delta\phi)_\mathcal{R}} d\phi \bigg[D \bigg(\frac{\partial \ln W}{\partial \phi} \bigg)^{-1} + \frac{\partial \ln f}{\partial \phi} \bigg],\tag{3.10}
$$

where

$$
D(\phi) = \frac{\omega(1+3\Omega)}{f}.
$$
 (3.11)

By expanding the nonlinear relation between $\mathcal{R}_{\delta\phi}$ and $(\delta \phi)_R$ up to second order [21], we obtain a nonlinear

curvature perturbation, $\mathcal{R}_{\delta \phi} = \mathcal{R}_L + \mathcal{R}_{NL}$, where

$$
\mathcal{R}_L = \frac{1}{2} \bigg[D \bigg(\frac{\partial \ln W}{\partial \phi} \bigg)^{-1} + \frac{\partial \ln f}{\partial \phi} \bigg] (\delta \phi)_{\mathcal{R}}, \quad (3.12)
$$

$$
\mathcal{R}_{NL} = \frac{1}{G} \left[\frac{\partial D}{\partial \phi} \frac{\partial \ln W}{\partial \phi} - D \frac{\partial^2 \ln W}{\partial \phi^2} + \left(\frac{\partial W}{\partial \phi} \right)^2 \frac{\partial^2 \ln f}{\partial \phi^2} \right] (\mathcal{R}_L)^2
$$
\n(3.13)

where

$$
G(\phi) = \left(D + \frac{\partial \ln f}{\partial \phi} \frac{\partial \ln W}{\partial \phi}\right)^2. \tag{3.14}
$$

Finally, from Eq. (3.2), we obtain the nonlinear parameter

$$
f_{NL} = \frac{3}{5G} \left[\frac{\partial D}{\partial \phi} \frac{\partial \ln W}{\partial \phi} - D \frac{\partial^2 \ln W}{\partial \phi^2} + \left(\frac{\partial W}{\partial \phi} \right)^2 \frac{\partial^2 \ln f}{\partial \phi^2} \right],
$$
\n(3.15)

where we have used the relation between Φ and \mathcal{R} as Φ = $\frac{3}{5}R$ during the matter dominated era. If we define the slowroll parameters in generalized gravity theories by

$$
\epsilon = \frac{\dot{H}}{NH^2} = \frac{\dot{\phi}}{N}\frac{1}{H^2}\frac{\partial H}{\partial \phi},\tag{3.16}
$$

$$
\eta = \frac{1}{N} \left(\frac{\dot{\phi}}{N} \right) \frac{N}{H \dot{\phi}},\tag{3.17}
$$

using again Eqs. (2.30) and (2.31), we obtain

$$
\epsilon = -\frac{1}{G} \frac{\partial \ln W}{\partial \phi} \left[D \frac{\partial \ln f}{\partial \phi} + 2 \left\{ D + \frac{\partial^2 \ln f}{\partial \phi^2} + \frac{1}{2} \left(\frac{\partial \ln f}{\partial \phi} \right)^2 - \frac{\partial \ln D}{\partial \phi} \frac{\partial \ln f}{\partial \phi} \right\} \frac{\partial \ln W}{\partial \phi} + 2 \frac{\partial \ln f}{\partial \phi} \frac{1}{W} \frac{\partial^2 W}{\partial \phi^2} \right], \quad (3.18)
$$

$$
\eta = -\frac{1}{G} \frac{\partial \ln W}{\partial \phi} \left[D \left(\frac{\partial \ln f}{\partial \phi} - 2 \frac{\partial \ln D}{\partial \phi} \right) + 2D \left(\frac{\partial W}{\partial \phi} \right)^{-1} \frac{\partial^2 W}{\partial \phi^2} + \left\{ \left(\frac{\partial \ln f}{\partial \phi} \right)^2 - 2 \frac{\partial \ln f}{\partial \phi} \frac{\partial \ln D}{\partial \phi} \right\} \frac{\partial \ln W}{\partial \phi} + 2 \frac{\partial \ln f}{\partial \phi} \frac{1}{W} \frac{\partial^2 W}{\partial \phi^2} \right].
$$
\n(3.19)

The nonlinear part of the curvature perturbation can be written in terms of the slow-roll parameters, ϵ and η , as

$$
\mathcal{R}_{NL} = \frac{1}{2} (\eta - \epsilon) (\mathcal{R}_L)^2.
$$
 (3.20)

Hence, the nonlinear parameter, f_{NL} , for generalized gravity theories takes the form

$$
f_{NL} = \frac{1}{2}(\eta - \epsilon). \tag{3.21}
$$

Note that the nonlinear parameter (3.21) in generalized gravities has the same form as in Einstein gravity. The WMAP result gives a constraint on f_{NL} by $-58 < f_{NL}$ 134 at 95% CL [1]. Since the slow-roll inflation implies that $|\epsilon|, |\eta| \ll 1$, non-Gaussianity in the single scalar field inflation model is difficult to be observed by CMB experiments.

IV. CONCLUSION

It is expected that nonlinear perturbations may be responsible for a non-Gaussian signal in CMB experiments. The Hamilton-Jacobi theory can provide a useful and convenient tool to deal with nonlinear perturbations. In this paper we derived the Hamilton-Jacobi equation in generalized gravity theory. Through a canonical transformation, a new set of canonical variables was chosen that could make the new Hamiltonian density vanish. The conserved quantity, $\zeta_i = \partial_i \ln a - (NH/\dot{\phi})\partial_i \phi$, was obtained in the large scale limit by using the fact that the new canonical variable is constant in time on fixed spacelike hypersurfaces. The ζ_i could be regarded as a generalization of the gauge invariant quantity $\zeta = \Psi$ – $(3H/\dot{\phi})\delta\phi$ in the linear perturbation theory. In the longwavelength approximation, we found the exact solutions to the lowest order Hamilton-Jacobi equation for special scalar potentials and introduced an approximation scheme for general potentials.

The non-Gaussianity from nonlinear density perturbations was parameterized with a nonlinear parameter f_{NL} , which is an expansion parameter of the gravitational potential in Eq. (3.2). The nonlinear parameter can be measured by CMB observations. Any detection of the non-Gaussianity of CMB may put a strong constraint on inflation models. Especially, f_{NL} predicted by the single field slow-roll inflation in Einstein gravity is too small to be detected in CMB experiments through a non-Gaussian signal. Nevertheless, it would be interesting to investigate the non-Gaussianity in generalized gravity theory. We have found that even in generalized gravity theory, the nonlinear parameter for the slow-roll inflation takes the same form $f_{NL} = (\eta - \epsilon)/2$ as in Einstein gravity. Hence, the slowroll inflation models based on Brans-Dicke theory, nonminimally coupled scalar field theory, and low energy effective string theory, *et al* as well as Einstein gravity will have the same order of non-Gaussianity for CMB. This has a physical implication that slow-roll inflation models with a single scalar field in such alternative theories of gravity will be ruled out if a signal for non-Gaussianity is observed in future CMB experiments. Therefore, the non-Gaussianity would require multifield inflation models or a different generating mechanism for density perturbations [22] in generalized gravity.

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