Study of relativistic bound states for scalar theories in the Bethe-Salpeter and Dyson-Schwinger formalism

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The Bethe-Salpeter equation for Wick-Cutkosky-like models is solved in the dressed ladder approximation. The bare vertex truncation of the Dyson-Schwinger equations for propagators is combined with the dressed ladder Bethe-Salpeter equation for the scalar *S*-wave bound state amplitudes. With the help of the spectral representation the results are obtained directly in Minkowski space. We give a new analytic formula for the resulting equation simplifying the numerical treatment. The bare ladder approximation of the Bethe-Salpeter equation is compared with the one with dressed ladder. The elastic electromagnetic form factors are calculated within the relativistic impulse approximation.

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I. INTRODUCTION

In quantum field theory the two body bound state is described by the three-point bound state vertex function or, equivalently, by Bethe-Salpeter (BS) amplitudes, both of them are solutions of the corresponding (see Fig. 1) covariant four-dimensional Bethe-Salpeter equations (BSE) [1]. Up to now most of the studies were restricted to the case when irreducible interaction kernel is approximated by (the sum of) single particle exchanges. In this so-called ladder approximation the scattering matrix is given by the sum of the generated ladders. It is known that such an approximation is not sufficient when more realistic models are considered $[2-4]$. To move beyond this approximation one is in practice confined to the use of some phenomenological *Ansätze*. (In hadronic physic, these *Ansätze* are very often made already at the level of two point correlators. For modeling of the gluon propagator in the context of BSE and Dyson-Schwinger equations (DSE) , see for instance $[5]$.)

Here we are considering some simple scalar models. An extensive review of BS studies in scalar theories (with at most cubic and nonderivative interaction) can be found in Refs. $[6,7]$. The various improvements of the simple ladder kernel have been considered, in particular, including the selfenergy effects $[8,9]$ or contributions from crossed box diagrams $[10]$. The study of the influence on the bound state spectrum following from the infinite resummation of certain ladder and crossed-box diagrams can be found in Ref. [11]. Furthermore, there is a number of interesting papers on the solution of Wick-Cutkosky models (with zero mass of the exchanged particle). These solutions employ various effective techniques like the point form of relativistic quantum mechanics $[12]$, variational calculations $[13]$, or the light front dynamics $[14]$.

The standard approach to determine the spectrum and the BS vertex makes use of partial wave decomposition which reduces the four-dimensional integral equation into the twodimensional one. The alternative more recently exploited treatment is based on the $O(4)$ hyperspherical expansion [15]. In this approach the BSE is transformed into an infinite set of one-dimensional integral equations. The notable advantage of this approach is a good numerical convergence and easy identification of excited bound states spectra.

Very often, the ladder BSEs are solved with the help of the so-called Wick rotation $[16]$. However, the backward analytical continuation is quite difficult even for the ladder approximation, while for more complicated cases its proper implementation is unclear or at least highly nontrivial.

In this work we follow the method of solving the BSE directly in Minkowski space $[8,17,18]$, in which the problems associated with Wick rotation do not arise. The method is based on utilization of generalized spectral representation for *n*-point Green functions in quantum field theory $[19]$. In this treatment the BSE written in momentum space is converted into a real integral equation for a real weight function with a number of independent variables dependent on details of the model. We extend the earlier work $\lceil 8 \rceil$ first to the case with unequal masses of constituents. This then allows us to treat the ladder BSE in which all propagators (of constituents and of the exchanged particle) are fully dressed. This is achieved by the implementation of the Lehmann representation of the propagator:

$$
G(p^2) = \int d\omega \tilde{\sigma}(\omega) D(p; \omega),
$$

(1.1)

$$
D(p; \omega) = \frac{1}{p^2 - \omega + i\epsilon}; \quad \tilde{\sigma}(\omega) = R \delta(\omega - m_{\text{pole}}^2) + \sigma(\omega),
$$

where $\sigma(\omega)$, which is a smooth function, nonzero above a threshold, is determined by the Dyson-Schwinger equations (DSE). In the pole term we can take $R=1$, a choice corresponding to the conventional on-shell renormalization

FIG. 1. Diagrammatical representation of the BSE for the bound state vertex function.

scheme (*G* has a unit residuum when momentum approaches a simple pole at physical mass).

To account for the effect of self-energy we transform the momentum BSE to the form suitable for a complementary solution together with the appropriate DSE for propagators. Note here that the perturbative one loop contribution has been already considered in $[8]$ and a certain Euclidian version of this problem has also been investigated $[9]$. In qualitative agreement with $[9]$ we have found that the critical value of coupling gives the domain of applicability of BSE (at least in its ladder approximation). The couplings below the critical one allow only solutions for relatively weakly bound states. It is even more interesting that the effect of the propagator dressing on bound state spectra is rather small. In comparison with the bare ladder approximation the same binding energy is then achieved with the coupling smaller by about several percent, even for values of the coupling close to the critical one.

Clearly, when we take some or even all particle propagators dressed, the number of spectral integrations increases. Note here, that up to the rather exotic case of massless Wick-Cutkosky model the appropriate solution is not known analytically but must be found numerically. Mainly due to this reason we reformulate the equation obtained by Kusaka *et al.* [8] and we offer the solution where the appropriate integral kernel is free of any additional numerical integration (see Appendix of Ref. $[8]$ for the original solution). The elimination of this numerical integration then not only improves numerical accuracy but also reasonably decreases the CPU time.

To see explicitly the effect of radiative corrections we compare the derssed BSE results with its bare ladder approximation. We set the parameters of our model to that used in Refs. $[15]$ and $[17]$ to compare the bare ladder solutions to those obtained before in $[8,15,17]$.

Having solved equations for spectral functions, one can determine the BS amplitudes in an arbitrary reference frame. This makes this technique suitable for calculations of response to a external fields. In Sec. IV we briefly introduce the formulas defining the elastic charge form factor $G(Q^2)$ in relativistic impulse approximation (RIA). Although the elastic form factor represents a simple dynamical observable, its Minkowskian calculation represents a nontrivial task. For this purpose we consider the (massive) Wick-Cutkosky model given by a Lagrangian gauged as follows:

$$
\mathcal{L} = (D^{\mu} \phi_1)^{+} D_{\mu} \phi_1 + \frac{1}{2} \partial_{\mu} \phi_2 \partial^{\mu} \phi_2 + \frac{1}{2} \partial_{\mu} \phi_3 \partial^{\mu} \phi_3
$$

$$
- \frac{1}{4} F_{\mu \nu} F^{\mu \nu} - V(\phi_i),
$$

$$
V(\phi_i) = (m_1^2 + g \phi_3) \phi_1^+ \phi_1 + \left(\frac{m_2^2}{2} + \frac{g}{2} \phi_3\right) \phi_2^2 + \frac{1}{2} m_3^2 \phi_3^2,
$$
 (1.2)

where the covariant derivative is $D_\mu = \partial_\mu - ieA_\mu$. In our form factor calculations the effects of scalar dressing were not taken into account since it would significantly increase the computational complexity of the problem. Furthermore, it is assumed that $e \ll g$ which implies that the interaction of the charged particle field ϕ_1 with the electromagnetic field can be treated perturbatively. As in Ref. $[9]$, we have chosen the same coupling constant for interaction of the field ϕ_3 with the fields ϕ_1 and ϕ_2 . The form factors were calculated for several sets of masses of constituent and exchanged particles.

II. DRESSED LADDER BETHE-SALPETER EQUATION

The BS amplitude for bound state (ϕ_1 , ϕ_2) in momentum space is defined through the Fourier transform of

$$
\langle 0|T\phi_1(x_1)\phi_2(x_2)|P\rangle
$$

= $e^{-iP\cdot X}\langle 0|T\phi_1(\eta_2x)\phi_2(-\eta_1x)|P\rangle$
= $e^{-iP\cdot X}\int \frac{d^4p}{(2\pi)^4}e^{-ip\cdot x}\Phi(p,P),$ (2.1)

where $X = \eta_1 x_1 + \eta_2 x_2$ and $x = x_1 - x_2$, so that $x_1 = X$ $+\eta_2 x$, $x_2 = X - \eta_1 x$. Here $p_{1,2}$ are the four-momenta of particles corresponding to the fields $\phi_{1,2}$ that constitute the bound state (ϕ_1, ϕ_2) . The total and relative momenta are then given as $P=p_1+p_2$ and $p=(\eta_2p_1-\eta_1p_2)$, respectively, and $P^2 = M^2$, where *M* is the mass of the bound state. Finally, $P \cdot X + p \cdot x = p_1 \cdot x_1 + p_2 \cdot x_2$. From now on we will put $\eta_1 = \eta_2 = 1/2$, which corresponds to the usual separation of center of mass motion for equal mass case, but can be also employed for unequal masses (although X is then not the coordinate of the center of mass).

Introducing the BS vertex function $\Gamma = iG_1^{-1}G_2^{-1}\Phi$, the homogeneous BSE for a *S*-wave bound state reads

$$
\Gamma(p, P) = i \int \frac{d^4k}{(2\pi)^4} V(p, k; P) G_1(k + P/2)
$$

× G₂(-k+P/2) $\Gamma(k, P)$. (2.2)

The bound states appear as poles of the scattering matrix. The normalization condition for the BS vertex function follows from the requirement that the pole appropriate to a given bound state is a simple one:

$$
2iP^{\mu} = \int \frac{d^4p}{(2\pi)^4} \int \frac{d^4k}{(2\pi)^4} \overline{\Gamma}(k, P) \Big[(2\pi)^4 \delta^4(p - k) \times \Big(\frac{\partial}{\partial P_{\mu}} G_1(p_1) G_2(p_2) \Big) + i G_1(p'_1) G_2(p'_2) \times \Big(\frac{\partial}{\partial P_{\mu}} V(p, k; P) \Big) G_1(p_1) G_2(p_2) \Big] \Gamma(p, P), \quad (2.3)
$$

where $\overline{\Gamma}(p, P)$ is the conjugate of $\Gamma(p, P)$ and $p_{1,2} = \pm p$ $+P/2, p'_1, z = \pm k + P/2$ (for the details see, e.g., Ref. [6]).

In this work we do not solve the BSE with the most general irreducible scattering kernel V (the most general structure of the kernel *V* written in terms of its perturbation theory integral representation $(PTIR)$ can be found in Ref. $[8]$ or [19]). Here we restrict ourselves to the case of dressed ladder approximation with ϕ_3 -exchange, in which $V(p, k; P)$ $= g^2 G_3(t)$, where *t* denotes the usual Mandelstam variable $t=(p-k)^2$. Note that for the bound state of particles (ϕ_1, ϕ_2) only the *t*-channel interaction above is effective, whereas for the bound state of (ϕ_i, ϕ_i) , *i*=1,2 one has to consider also possible *u* and *s* channel diagrams. In the present work we study the case (ϕ_1, ϕ_2) due to its simplicity and leave the other cases for discussion elsewhere. Let us also recall that in the (dressed) ladder approximation, defined by the exchange of chargeless scalar ϕ_3 , the photon coupling to ϕ_1 alone (one particle current, or in other words RIA) is by itself gauge invariant, when taken between the corresponding solutions of BSE. The normalization condition (2.3) in this approximation reduces to the condition $G(Q^2)$ $=$ 1. We will solve the BSE for massive constituents ($m_{1,2}$) >0) and $m_3 \ge 0$, the invariant mass of the bound state satisfies $0 \le P^2 < (m_1 + m_2)^2$.

Taking the dressed kernel and the full propagators of constituent particles into account, the right-hand side (rhs) of BSE (2.2) can be written as

$$
i g^{2} \prod_{i=1}^{3} \int d\alpha_{i} \tilde{\sigma}(\alpha_{i}) \int \frac{d^{4}k}{(2\pi)^{4}} \times D(k + P/2; \alpha_{1}) D(-k + P/2; \alpha_{2}) D(k - p; \alpha_{3}) \Gamma(k, P).
$$
\n(2.4)

The interesting unequal-mass ladder case of Ref. $[20]$ is also described by Eq. (2.4), although $\eta_1 = \eta_2 = 1/2$ and *p* and *k* are not relative momenta. Since the dependence on momenta in Eq. (2.4) is explicit, one might always rescale $\Gamma(p, P)$ to proper relative momentum.

The integral representation for the BS vertex function may be written as $[19]$

$$
\Gamma(p,P) = \int_{-1}^{1} dz \int_{\alpha_{min}(z)}^{\infty} d\alpha \frac{\rho^{[n]}(\alpha,z)}{\left[\alpha - (p^2 + zp \cdot P + P^2/4) - i\epsilon\right]^n}.
$$
\n(2.5)

The positive integer *n* represents a free parameter without clear physical meaning. One can take advantage of this freedom of choice to pick up *n* so that the numerical solutions of integral equations for spectral functions are made more stable. The spectral functions $\rho^{[n]}(\alpha, z)$ for different *n* can be related by integration over α by parts. Kusaka *et al.* [8] choose $n=2$ for their numerical solution of the BSE, we adopt the same value in this paper.

The bare (symmetric) Wick-Cutkosky model corresponds to the choice: $\alpha_1 = \alpha_2 = m^2$, the exchanged boson is massless $(\alpha_3=0)$, and no radiative corrections are considered. This model is particularly interesting because it is the only example of the nontrivial BSE which is solvable exactly $[16]$. For this model, there is no freedom in choice of *n* and (for the *S*-wave bound state) the expression (2.5) reduces to the one-dimensional PTIR:

$$
\Gamma(p, P) = \int_{-1}^{1} dz \frac{\rho(z)}{m^2 - (p^2 + zp \cdot P + P^2/4) - i\epsilon}.
$$
 (2.6)

Using a technique similar to the one used in Ref. $\vert 8 \vert$, the BSE can be converted to the following real integral equation for the real spectral function:

$$
\rho^{[n]}(\alpha',z') = \lambda \int_{-1}^{1} dz \int_{\alpha_{min}(z)}^{\infty} d\alpha V^{[n]}(\alpha',z';\alpha,z) \rho^{[n]}(\alpha,z),
$$
\n(2.7)

where we denoted $\lambda = g^2/(4\pi)^2$. The derivation is presented in Appendix A, where the explicit expressions for particular choices $n=1,2$ are given. The central results of this work are expressions obtained for $V^{[n]}$, which are simpler that the ones presented in Ref. [8]. No additional integration is required which decreases the computer time necessary for numerical calculation. Besides, our formulas also hold for unequal masses of the constituents. The extension (together with above-mentioned simplification) to the case of a more complicated scattering kernel is not so straightforward, but we believe that it is possible. Note also, that due to the property of solid harmonic with respect to the integration over the momentum the presented procedure can easily be generalized for the bound state with nonzero spin (here, the total orbital momentum) $[8]$.

A bound state with equal composite masses is described by the vertex function Γ which is symmetric under the transformation $P \cdot p \rightarrow P \cdot p$. In terms of the weight function this symmetry reads $\rho(\alpha, z) = \rho(\alpha, -z)$. However, there are solutions that do not respect this symmetry even in the case of equal masses. These are usually called ghost solutions and the appropriate amplitudes have a negative norm. Such solutions are often considered to be nonphysical and it is supposed that they point at inner inconsistency in the description of relativistic bound states within the BS formalism, at least in the ladder approximation. Here, it is important to mention that the Lagrangian (1.2) describes the models that are a subset of theories with potentials unbounded from below and in a very strict sense they are discarded due to the vacuum instability. On the other hand one can assume, at least for sufficiently small couplings, the existence of local minima of the potentials is sufficient to support of the existence of ground state of the theory. While in the large coupling regime, say for $g/m \ge 1$ no reasonable physics can be learned from the perturbation theory and/or from an equationlike ladder BS by itself. To conclude, we note that such ideas are supported by at least two facts. The ghost BS solutions do appear only for a large value of λ . Furthermore, from the Dyson-Schwinger study we know that the scalar theory studied here makes sense only up to a certain critical coupling, see e.g., $[9,21]$.

The important question arises, what is the validity of the full theory when renormalization is properly taken into account. Although the quantitative answer lies beyond the approximations used in this paper and requires more careful investigation, we make a simple attempt to find the domain in which self-consistent solutions of the BSE and Dyson-Schwinger equations (within the framework of reasonable approximations) exist. Furthermore, we inquire an influence of scalar propagator dressing on the solution of the BSE for the bound states.

III. DRESSING PROPAGATORS BY THE DYSON-SCHWINGER EQUATIONS

The solution of the DSE for the scalar models with the help of spectral decomposition will be discussed in detail in our forthcoming paper [21]. Here we give only a brief presentation of the DSE in bare vertex approximation, their renormalization, rearrangement in terms of the spectral function, and some properties of solutions, important for our further discussion of the BSE. In this section we assume m_3 $\leq m_1 + m_2$, so that the propagator of the exchanged particle Φ_3 has an isolated physical pole.

By dressing of the scalar propagators in our study of BSE we mean only the dressing due to the ''strong'' interaction between scalars, the coupling to the electromagnetic field is neglected. Let us now write the strong interaction part of our Lagrangian (1.2) in terms of bare, unrenormalized quantities (fields and coupling constants), labeled by subscript "0:"

$$
\mathcal{L}_{\text{strong}} = -g_{01}\phi_{01}^+ \phi_{01} \phi_{03} - \frac{g_{02}}{2} \phi_{02}^2 \phi_{03}. \tag{3.1}
$$

In the previous section we have chosen the strength of both couplings to be the same. Here, we distinguish the bare couplings, anticipating that they are renormalized by different amounts (see below).

The kinetic terms are parametrized by the unrenormalized masses m_{0i} . These masses undergo the *infinite* mass renormalization

$$
m_{0i}^2 = m_i^2 - \delta m_i^2, \quad i = 1, 2, 3. \tag{3.2}
$$

To rescale the residuum of the full propagators to unity, we will complement the infinite mass renormalization by the *finite* (since the model is superrenormalizable) renormalization of the fields and coupling constants

$$
\phi_{0i} = \sqrt{Z_i} \phi_i
$$
, $i = 1, 2, 3$, $g_{0i} = \frac{1}{Z_i \sqrt{Z_3}} g_i$, $i = 1, 2$. (3.3)

That is, we will employ below the on shell renormalization scheme in which the propagators have unit residua when momentum approaches its mass shell value $p^2 \rightarrow m^2$.

In this paper we consider the Dyson-Schwinger equations in the simplest approximation in which the proper vertices are replaced by the bare ones $\Gamma_{oi} = g_{oi}$. Then, the DSE in their unrenormalized form read

$$
G_{0i}^{-1}(p) = p^2 - m_{0i}^2 - \Pi_{0i}(p^2), \quad i = 1, 2, 3,
$$

$$
\Pi_{0i}(p^2) = ig_{0i}^2 \int \frac{d^4q}{(2\pi)^4} G_{03}(p-q) G_{0i}(q), \quad i = 1, 2, \quad (3.4)
$$

$$
\Pi_{03}(p^2) = i \int \frac{d^4q}{(2\pi)^4} \sum_{i=1,2} g_{0i}^2 G_{0i}(p-q) G_{0i}(q),
$$

where $G_0(p)$ is the Fourier transform of the full unrenormalized propagator $G_{0i}(x-y) = \langle 0 | T\phi_{0i}(x)\phi_{0i}(y)|0\rangle$ and Π_{0i} is the corresponding self-energy.

Under the field strength renormalization the propagators scale like $G_{0i} = Z_i G_i$. Multiplying the equations for G_{0i}^{-1} in Eq. (3.4), defining $\Pi_i = Z_i \Pi_{0i}$, and making use of Eq. (3.3), one gets the rescaled DSE:

$$
G_i^{-1}(p^2) = Z_i(p^2 - m_{0i}^2) - \Pi_i(p^2),
$$

\n
$$
\Pi_i(p^2) = ig_i^2 \int \frac{d^4q}{(2\pi)^4} G_3(p-q) G_i(q), \quad i = 1, 2, \quad (3.5)
$$

\n
$$
\Pi_3(p^2) = ig^2 \int \frac{d^4q}{(2\pi)^4} \sum_{i=1,2} G_i(p-q) G_i(q).
$$

The renormalization of proper self-energies proceeds by double subtraction:

$$
\Pi_{iR}(p^{2}) = \Pi_{i}(p^{2}) - \Pi_{i}(m^{2}) - (p^{2} - m_{i}^{2}) \frac{d\Pi_{i}(p^{2})}{dp^{2}} \bigg|_{p^{2} = m_{i}^{2}}
$$
\n(3.6)

Identifying the appropriate renormalization constants [Eqs. (3.2) , (3.3)

$$
\delta m_i^2 = \Pi_i(m_i^2)/Z_i, \quad Z_i = 1 + \frac{d\Pi_i(p^2)}{dp^2}\bigg|_{p^2 = m_i^2}, \quad (3.7)
$$

we can immediately write the full propagator in terms of finite physical quantities

$$
G_i^{-1}(p) = p^2 - m_i^2 - \Pi_{iR}(p^2), \quad i = 1, 2, 3. \tag{3.8}
$$

The DSE for the renormalized self-energies are given by Eq. (3.5) and subtraction [Eq. (3.6)].

For the purpose of our BS calculation, we now fix the renormalized couplings and masses as follows:

$$
g_1 = g_2 \equiv g;
$$
 $m_1 = m_2 \equiv m;$ $m_3 = \frac{m}{2}$ (3.9)

where g is the coupling constant from Eq. (1.2) . That is, we will compare the solutions of the BSE for the bare and dressed ladder kernel taken for the same numerical value of unrenormalized and renormalized coupling constant, respectively. The masses are fixed to allow comparison with some of the results of Refs. $[8,15,17]$.

Now, it is a straightforward task to evaluate the spectral representation of the renormalized self-energy. Lehmann representation (with unit residuum) for G_i reads:

$$
G_i(p^2) = \int_0^\infty ds \frac{\tilde{\sigma}(s)}{p^2 - s + i\epsilon}, \quad \tilde{\sigma}(s) = \delta(m_i^2 - s) + \sigma(s),
$$
\n(3.10)

Notice that functions σ_i , *i*=1,2, have the thresholds at $m_{i,th} = (m_i + m_3)^2 = 2.25m^2$, whereas the function σ_3 has the threshold at $m_{3,th}=(m_1+m_2)^2=4m^2$. Analogously, for the self-energies:

$$
\Pi_{iR}(p^2) = \int_{m_{i,th}}^{\infty} d\alpha \frac{\rho_{\pi i}(\alpha)}{p^2 - \alpha + i\epsilon} \frac{(p^2 - m^2)^2}{(\alpha - m^2)^2}.
$$
 (3.11)

The spectral representation for Π_R explicitly satisfies $\Pi_R(m^2) = \Pi'_R(m^2) = 0$ following from Eq. (3.6). Rewriting now the relation between *G* and Π in the form $G = D$ $+D\Pi G(D)$ being the free propagator with the physical mass) and taking its imaginary part, we arrive at the first relation between the spectral functions σ and ρ :

$$
\sigma_i(\omega) = \frac{\rho_{\pi_i}(\omega)}{(\omega - m_i^2)^2} + (\omega - m_i^2) P \int \frac{d\alpha}{\omega - \alpha} \left[\frac{\sigma_i(\omega) \rho_{\pi_i}(\alpha)}{(\alpha - m_i^2)^2} + \frac{\sigma_i(\alpha) \rho_{\pi_i}(\omega)}{(\omega - m_i^2)^2} \right], \quad i = 1, 2, 3, \tag{3.12}
$$

where $P\int$ stands for principal value integration. All the functions in Eq. (3.12) are positive and regular above the perturbative thresholds and identically equal to zero elsewhere.

Substituting the spectral representations (3.10) into the DSEs (3.5) , making the subtraction as in Eq. (3.6) , and comparing to the left-hand side (lhs) in the form of Eq. (3.11) , one gets after lengthy algebra:

$$
\rho_{\pi_i}(\omega) = \lambda \int d\alpha d\beta B(\alpha, \beta; \omega) \tilde{\sigma}_3(\alpha) \tilde{\sigma}_i(\beta), \quad i = 1, 2,
$$

\n
$$
\rho_{\pi_3}(\omega) = \lambda \sum_{i=1,2} \int d\alpha d\beta B(\alpha, \beta; \omega) \tilde{\sigma}_i(\alpha) \tilde{\sigma}_i(\beta),
$$
\n(3.13)

where $\lambda = g^2/(4\pi)^2$ and the function $B(\alpha,\beta;\omega)$ is related to the Källen function λ as follows:

$$
B(\alpha, \beta, \omega) = \frac{\sqrt{\lambda(\alpha, \beta, \omega)}}{\omega} \Theta(\omega - (\sqrt{\alpha} + \sqrt{\beta})^2),
$$
\n
$$
\lambda(\alpha, \beta, \omega) = \alpha^2 + \beta^2 + \omega^2 - 2\alpha\beta - 2\alpha\omega - 2\beta\omega.
$$
\n(3.14)

Before the numerical treatment the explicit integrationseparating the δ -function parts of Lehmann weights $\tilde{\sigma}$ -has to be performed.

Equations $(3.12),(3.13)$ constitute the closed system of integral equations for spectral functions which can be solved numerically by iterations without any additional approximation. So obtained dressed propagators have been used when solving the Bethe-Salpeter equation. The results are discussed in the Sec. V. Before leaving this section we review some important features of our solutions of DSE.

The behavior of the imaginary parts of propagators—the Lehmann functions $\sigma_i(\alpha)$ —for fields $\Phi_{1,2,3}$ is shown in Fig. 2.

FIG. 2. The imaginary part of the renormalized propagators for different values of coupling $\tilde{\lambda}$, calculated from the DSE in bare vertex approximation. Upper curves are for particles $\Phi_{1,2}$ (which have identical self-energies), lower ones for particle Φ_3 .

The renormalization constant Z_i is calculated from the relation

$$
Z_i = 1 - \int d\alpha \frac{\rho_i(\alpha)}{(\alpha - m_i^2)^2}.
$$
 (3.15)

From Fig. 3 we can see that the field renormalization constant $Z_{1,2}$ changes sign from positive to negative at some critical point $\overline{\lambda}_{\text{crit}} = g_{\text{crit}}^2/(4 \pi m)^2 \approx 1.5 \pm 0.1$, where the error reflects the difficulty of making the numerical estimate of the value for which the solution cannot be found and the dimensionless coupling is defined as $\tilde{\lambda} = \lambda/m^2$. We did not find any numerical solutions of DSE for couplings larger than

FIG. 3. The dependence of field strength renormalization constants on the coupling $\tilde{\lambda}$.

FIG. 4. Diagrammatic representation of the electromagnetic current bound state matrix element.

 $\tilde{\lambda}_{\text{crit}}$. It is reasonable to suppose that the quanta associated with the fields $\phi_{1,2}$ do not describe physical particles when $\widetilde{\lambda} > \widetilde{\lambda}_{\rm crit}$.

IV. ELASTIC ELECTROMAGNETIC FORM FACTOR

The electromagnetic form factors parametrize the response of bound systems to external electromagnetic field. The calculation of these observables within the BS framework proceeds along the Mandelstam's formalism $[22]$. For the elastic scattering on the *S*-wave bound state, $(P_i^2 = P_f^2)$ $=$ *M*²) the current conservation implies the parametrization of the current matrix element G^{μ} in terms of the single real form factor $G(Q^2)$,

$$
G^{\mu}(P_f, P_i) = G(Q^2)(P_i + P_f)^{\mu}.
$$
 (4.1)

The elastic electromagnetic form factor $G(Q^2)$ depends only on the square of photon incoming momentum *q* and we use the usual SLAC convention $Q^2 = -q^2$, so that Q^2 is positive for elastic kinematics.

The matrix element of the current in relativistic impulse approximation (RIA) is diagrammatically depicted in Fig. 4. In this paper we are not taking into account the dressing of the scalar propagators when calculating the charge form factor. Then, the matrix element is given in terms of the BS vertex functions as

$$
G^{\mu}(P+q, P) = i \int \frac{d^4k}{(2\pi)^4} \overline{\Gamma} \left(k + \frac{q}{2}, P+q \right)
$$

×[$D(p_f; m_1^2) j_1^{\mu}(p_f, p_i) D(p_i; m_1^2)$
× $D(-k + P/2; m_2^2)]\Gamma(k, P),$ (4.2)

where we denote $P = P_i$ and j_1^{μ} represents one-body current for particle ϕ_1 , which for the bare particle reads $j_1^{\mu}(p_f, p_i)$ $=p_f^{\mu}+p_i^{\mu}$, where p_i , p_f is initial and final momentum of the charged particle inside the loop in Fig. 4, i.e., $p_i = k$ $+P/2, p_f = q + k + P/2.$

We have already mentioned in the previous section that if the vertex functions Γ are a solution of the BSE with a kernel corresponding to the exchange of single chargeless particle, the RIA defined above is by itself gauge invariant and the normalization condition for the BS amplitudes is equivalent to the normalization $G(0) = 1$.

TABLE I. Dimensionless coupling $\tilde{\lambda} = g^2/(4 \pi m)^2$ as a function of fraction of binding $\eta = \sqrt{P^2/2m}$ for two cases of exchanged mass m_3 . The case $m_3/m=0$ is the Wick-Cutkosky model. The second case $m_3/m=0.5$ is compared with the result obtained by Kusaka *et al.* $[8]$.

m_3/m	$n=0$	$n = 0.2$	$n = 0.5$	$n = 0.8$	$n = 0.999$
Ω	1.9998	1.954	1.592	0.9067	0.03322
0.5	2.5663	2.498	2.142	1.421	0.3873
Ref. [8]	2.5662	2.4988		1.4056	0.3853

The main result of this paper, as far as charge form factor is concerned, is the rewriting of the rhs of Eq. (4.2) directly in terms of the spectral weights of the bound state vertex function. It allows the evaluation of the form factor by calculating the integral of nonsingular expression, without having to reconstruct the vertex functions $\Gamma(p, P)$ from their spectral representation. The derivation of this integral involves some lengthy algebra and is relegated to Appendix B.

V. NUMERICAL RESULTS

A. Bare ladder BSE

We have solved the bare ladder BSE for symmetric (m_1) $=m_2=m$) scalar theory with bare ladder kernel

$$
V(p,k,P) = V(p-k) = \frac{g^2}{(p-k)^2 - m_2^3},
$$
\n(5.1)

and bare constituent propagators $G_i(p_i)=D_i(p_i,m_i)$ by iterations of the integral equation for spectral functions. The standard procedure was followed: after fixing the bound state mass (P^2) we looked for the solution by iterating spectral function for fixed dimensionless "coupling strength" $\tilde{\lambda}$ $\equiv g^2/[(4\pi)^2m^2]$. If the iterations failed—measure being both the difference of the rhs and lhs of the integral equation and deviation of the auxiliary normalization integral from a predefined value—we were changing $\tilde{\lambda}$ (halving intervals of successive guesses) until the solution was found.

In the case of the Wick-Cutkosky model the onedimensional integral equation (wcmsolve) was solved. Although the solution of this one-dimensional integral equation could be found by the inversion of its discretized form, we have tested the iteration procedure (used later also for massive exchange). The equation was discretized by numerical Gauss integration, it appears that it is sufficient to take 40 Gauss points (though the numbers cited in Table I are obtained with 98 points). It is known [6] that $P^2=0$ corresponds to $\tilde{\lambda} = 2$ from which our result slightly deviates in the fifth digit. We have also reproduced (up to four published digits) all results for the Wick-Cutkosky model from [15]. In Fig. 5 the weight functions are plotted against spectral variable *z* for several fractions of binding $\eta = \sqrt{P^2/2m}$.

For the massive scalar exchange the two-dimensional integral equations $(A31)$, $(A35)$ were solved. We have found (in agreement with $[8]$) that numerical errors are about one order

FIG. 5. The spectral function $\rho(z)$ of the bound-state vertex in the Wick-Cutkosky model for several values of $\eta = \sqrt{P^2/2m}$.

of magnitude bigger for $n=1$, hence $n=2$ is preferable and only the results with this choice are discussed below.

For numerical solution we discretize integration variables α and *z* using Gauss-Legendre quadratures (with tangent mapping from $\langle -1,+1\rangle \rightarrow \langle \alpha_{min},\infty \rangle$ for α). Equation (A35) is solved on the net of $N = N_z^* N_\alpha$ points which are spread on the rectangle $(-1,1)^*(\alpha_{min},\infty)$. The value α_{min} is given by the support of the spectral function (see Appendix A). We have not optimized the grid during the iteration procedure as it was done in the study $[8]$. Instead, we have solved the equation for several different numbers of grid points while keeping fixed the ratio of N_{α}/N_{z} and then extrapolated the results to the "ideal" case with $N_a = N_z = \infty$. Examples of numerical convergence for some cases of bound states are presented in Table II. In Table I we compare our results for $m_3 = m/2$ with those of Ref. [8].

Below we show the dependence of charge form factor on the parameters of the model: on the range of interaction characterized by the inverse mass of exchanged meson m_3 and on the strength of forces which bind the particles together. To calculate the form factors we first have to solve the BSE for chosen sets of parameters. We vary the parameters as follows:

 (1) First we solve the BSE for several bound state masses P^2 keeping the ratio m_3/m fixed; (2) then we vary the mass of the exchanged meson, keeping the masses of all studied

TABLE II. The coupling $\tilde{\lambda} = g^2/(4 \pi m)^2$ for bare ladder BSE as a function of the number of mesh-points.

$N_{z} \times N_{\alpha}$:	16×16	32×32 64 \times 64		96×96	∞
$\eta = 0.999; m_3 = 0.50$	0.3782	0.3754	0.3794	0.3816	0.3874
$\eta = 0.950; m_3 = 1.00$	1.310	1.341	1.355	1.360	1.371
$\eta = 0.950; m_3 = 0.50$	0.752	0.761	0.777	0.783	0.804
$\eta = 0.950; m_3 = 0.10$	0.306	0.350	0.375	0.385	0.409
$\eta = 0.000; m_3 = 1.00$	3.143	3.273	3.342	3.366	3.416
$\eta = 0.000; m_3 = 0.50$	2.207	2.343	2.445	2.483	2.566

TABLE III. Dimensionless coupling $\tilde{\lambda} = g^2/(4 \pi m)^2$ for several selections of $m_3/m =$ and fraction of binding $\eta = \sqrt{P^2}/2m$, compared to the results of Ref. $[15]$.

$\boldsymbol{\eta}$			0.0 0.4 0.5 0.5 0.5 0.95 0.95	
m_3/m 1.0 0.25 1.0 2.0 4.0 0.1 1.0				
λ			3.416 1.77 2.928 4.911 9.997 0.409 1.371	
Ref. [15] 3.419 na 2.940 na na 0.416 1.371				

bound states fixed [our choice is $\eta = \sqrt{P^2/(2m)} = 0.5$] and determining the corresponding coupling strengths $\tilde{\lambda}$.

Where the independent numbers were available $[15]$, they agree with our results (see Table III). If the mass of the exchanged particle becomes small (but nonzero) the convergence of our numerical procedure becomes somewhat poorer and more sensitive to the initial guess. For illustration the weight function $\tilde{\rho}^{[2]}$ is plotted in Figs. 6 and 7 for two different values of exchanged mass.

B. Dressed ladder BSE

In this section we finally discuss numerical solutions of the BSE including the dressing of the propagators. We introduce the dressing by two steps, switching it on first only for the exchanged particle and in the second step also for constituents. We should point out that since the solution of the DSEs in the bare vertex approximation (by which we dress the propagators) breaks down for coupling constants larger that $\tilde{\lambda}_{\text{crit}} = 1.5$ we can consider to only rather weakly bound states: for the bare BSE $\tilde{\lambda} = 1.5$ corresponds to η $=\sqrt{P^2/(2m)} \approx 0.78.$

The propagator dressing of the exchanged particle in the one loop approximation was already considered in Ref. [8]. We go beyond the one loop approximation and determine the continuum part of Lehmann weight σ_3 from the DSE (3.12) with the same value of the coupling constant. That is, we

FIG. 6. The rescaled weight function $\tilde{\rho}(\alpha, z)$ of the bound-state vertex for $\eta=0.95$ calculated in bare ladder approximation. The mass of the exchanged boson $m_3 = 0.5m$.

FIG. 7. The same as in Fig. 6, but for $m_3 = 0.1m$ and η FIG. 8. The eigenvalues λ

insert into Eq. (2.7) the dressed kernel

$$
G_3(p-q) = \int_0^\infty d\omega \frac{\tilde{\sigma}_3(\omega)}{(p-q)^2 - \omega + i\epsilon} \tag{5.2}
$$

with the pole situated at $m_3 = m/2$. As noted above, the constituent propagators are at this stage left undressed in the BSE, although all self-energies have been taken fully into account in DSEs. The integration over ω (5.2) in the BSE kernel was performed using Gaussian quadrature with 16 points. Including the kernel self energy slightly decreases (by at most a few percent) the mass of the bound state, even for $\widetilde{\lambda} \simeq \widetilde{\lambda}_{\rm crit}$.

Let us point out that the kernel of Eq. (2.7) in the dressed ladder kernel approximation is free of any singularities. The accuracy of the numerical solution is comparable to the bare ladder case. For example, $\tilde{\lambda} = 0.734$ for $\eta = 0.95$ for the grid of 32×32 points and $\lambda=0.749(0.752)$ for the grid of $64\times64(96\times96)$, the convergence is similar to the case of bare ladder (see Table I). The extrapolated (to very large grid) values of λ 's for fractional binding η $= 0.999, 0.99, 0.97, 0.95$ are showen in Fig. 8.

In the next step we have included the self-energies of the constituents. As we shall see the effect is relatively small for $\tilde{\lambda} \ll \tilde{\lambda}_{\text{crit}}$, but increases rapidly as $\tilde{\lambda} \rightarrow 1$. As in the previous case the Lehmann weights have been calculated from the DSEs solved for the same value of the coupling. As the first guess we have used the solution of the BSE linearized in $\tilde{\sigma}(\alpha)$, i.e., with only one propagator dressed. This guess is rather close to the exact solution for $\eta \le 0.9$.

The constituent particles in a weakly bound system (η) \approx 1) live near their mass shell. Therefore, one can naively assume that the values of coupling for such a weakly bound state should not be strongly affected by dressing of constituent propagators. For deeper bound states we have found that the effect of the dressing of constituents is much larger than that due to the dressing of the kernel (exchanged particle), Fig. 8. The couplings for fully dressed BSE are not deter-

FIG. 8. The eigenvalues $\tilde{\lambda}$ calculated for the bare BSE, with dressed kernel *V* and for dressed ladder BSE. Beyond the critical value of coupling $\tilde{\lambda}_{\text{crit}}=1.5$ only the bare solution is available.

mined with the same high accuracy as those for the bare ladder BSE, since the grids are not optimalized for very different ratios of α 's which appear in the kernel of the BSE.

C. Charge form factor

Various form factors are extensively studied in scalar theories like the Wick-Cutkosky model (see, for example, [23]). In these studies the dependence of the form factor on the binding and on the range of the ''strong'' interaction has been considered, therefore we perform a similar calculation in our formalism.

In the approach adopted in this paper (employing the spectral representations in the Minkowski space), the bound states masses and corresponding vertex functions can be obtained with good accuracy and in reasonable CPU time. Unfortunately, the calculation of the scalar form factor as outlined in Appendix B leads to more complicated results $(B11), (B12)$. Even if one would be able to perform analytically all additional Feynman integrations, the formula $(B12)$ still involves the four-dimensional integration over the spectral variables. We are taking also the integrals over four Feynman variables numerically with the help of Gauss-Legendre quadrature, taking the number of points for each of them equal to the one for spectral variable *z*. Since a relatively small number of integration points (from 16 to 40) was taken for each integration, the presented results have to be viewed rather as an estimate of form factor behavior. One can always refine the grids at the expense of longer CPU time.

We have also compared our results to those obtained in the Gross (spectator) formalism, choosing the "scalar deuteron" parameters (see $[24]$). In analogy with the real deuteron, the parameters are chosen as: $m_3 / m = 138/938.9, \eta$ $=$ (2×938.9 - 2.3)/2×938.9 \approx 0.9988. The bound state vertex functions were found by solution of the Gross and BS equations. All phenomenological form factors introduced in

FIG. 9. The behavior of the elastic electromagnetic form factors for various bound states characterized by η . The mass of exchanged particle is fixed to be $m_3 = 0.5m$, except for the scalar deuteron case (D.), which is calculated for comparison using two different grids.

[24] have been "switched off" (the limit Λ 's $\rightarrow \infty$ are taken in the "strong" form factors) when calculating the Gross wave function and the bound state current. The electromagnetic form factors were calculated in the spectator RIA and are described in Appendix B (using the grid $32⁸$), respectively.

The form factors for several bound states listed in the Tables I and III are presented in Figs. 9 and 10, respectively. In Fig. 9 the ratio of the exchanged and constituent mass is kept constant $m_3/m=0.5$ and the mass of the bound state $M = \sqrt{P^2}$ is varied. In agreement with physical expectations one sees that as the bound state becomes more tight the elastic form factor increases. (For the infinitely bound point system it should be equal to unity, even our deepest bound states

FIG. 10. Variation of the elastic electromagnetic form factors with the mass of the exchanged particle while $\eta=0.5$ is fixed. The cases $\eta=0.4$, $m_3=0.25m$, and the scalar deuteron are included for comparison.

are of course still only approaching this value.) We put into the same plot for comparison also the scalar deuteron result. How the form factor changes with the mass of the exchanged particle is shown in Fig. 10. We included several states for which $M = m$, bound by the one-boson-exchange potential of the range $r = 1/m_3$, which is varied. Two other systems, first with $\eta=0.4; m_3=0.25$ and the scalar deuteron, are added for comparison. From both figures we can conclude that the behavior of the form factor is determined by the strength of the interaction and its range rather differently for various *M*. The range of the interaction is more significant for the weaker ones. This agrees with the conclusions of Ref. $[10]$, which have also compared our results for small exchanged mass $\eta=0.8, m_3=0.15m$ with the Wick-Cutkosky model prediction for $\eta=0.784$, $m_3=0$ (Tables 2 and 1 of [10], respectively), and found only a slight difference in the range Q^2 $= (0,100m^2)$.

VI. CONCLUDING REMARKS

The spectral representation was employed for solving the Bethe-Salpeter equation in $(3+1)$ Minkowski space. The new analytical formula for the integral equation kernel has been derived.

The method is efficient solving both the bare and dressed ladder BSE. Solving Dyson-Schwinger equations for propagators leads to the appearance of a critical value of the coupling constant, beyond which the solution collapses. This restricts substantially the region in which the effects of dressing can be studied. Since the coupling is rather weak, the dressing leads only to a moderate decrease of the bound state masses: even close to the critical value of the coupling the fractional binding of the bound state of the dressed BSE is smaller than the corresponding one for the bare BSE by at most 15 percent. As an example of application of the obtained vertex functions, we calculated the elastic electromagnetic form factor.

To further develop the method, it would be interesting to extend it to a more complicated BS kernel: trying to include the cross boxed contributions, *s* and *u* channel interactions, etc. It is already known that the ''spectral'' approach used here is suitable even for more complicated systems, for scalar QED see Ref. $[18]$. One of our future goals is to manage the complication due to fermionic degrees of freedom.

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APPENDIX A: KERNEL FUNCTIONS

In this appendix the real integral equation for the BS vertex weight is derived in detail. The PTIR form for a scalar bound-state vertex reads

$$
\Gamma(p, P) = \int_{-1}^{1} dz \int_{\alpha_{min}(z)}^{\infty} d\alpha \frac{\rho^{[n]}(\alpha, z)}{\left[F(\alpha, z; p, P)\right]^{n}}, \quad \text{(A1)}
$$

where $\rho^{[n]}(\alpha, z)$ is the real PTIR weight function for the bound state vertex function, and *n* is a dummy parameter. The function F is given by [19]

$$
F(\alpha, z; p, P) = \alpha - (p^2 + zp \cdot P + P^2/4) - i\epsilon
$$

= $\alpha - f(p, P, z) - i\epsilon$. (A2)

The support of $\rho^{[n]}(\alpha, z)$ can be determined in general (see [19]) for arbitrary interaction. In our case of one-bosonexchange interaction kernel one gets a bit higher α_{min} [8]. We discuss our treatment of the lower bounds below.

The following procedure is straightforward but a bit exhaustive. The rhs of the BSE (2.2) with the kernel given by the exchange of the single (dressed) particle Φ_3 has to be rewritten in the form allowing one to extract the integral equation for the spectral function $\rho^{[n]}(\alpha, z)$. The integrand contains the two ''constituent'' propagators, the denominator $F(\alpha, z, k, P)$ from the spectral representation of $\Gamma(k, P)$ and the propagator of the exchanged particle (all other factors will be skipped for a while for the sake of briefness).

Using the Feynman parametrization technique we first write

$$
D(\kappa + P/2; \alpha_1)D(-\kappa + P/2; \alpha_2)
$$

= $\frac{1}{2} \int_{-1}^{1} \frac{d\eta}{[M^2 - f(k, P, \eta) - i\epsilon]^2},$

$$
M^2(\eta) = \frac{\alpha_1 + \alpha_2}{2} + \frac{\alpha_1 - \alpha_2}{2} \eta.
$$
 (A3)

Next the denominator of Eq. $(A1)$ is added:

 $D(T + P)Q = \sum_{i=1}^{n} P(i)$

$$
\frac{D(k+P/2; \alpha_1)D(-k+P/2; \alpha_2)}{[F(\alpha, z; k, P)]^n}
$$

=
$$
\frac{\Gamma(n+2)}{2\Gamma(n)} \int_{-1}^{1} d\eta \int_{0}^{1} dt \frac{(1-t)t^{n-1}}{[R-f(k, P, z') - i\epsilon]^{n+2}},
$$

$$
R = \alpha t + (1-t)M^2,
$$
 (A4)

where $z' = tz + (1-t)\eta$. Now, we include the propagator of the exchanged particle, the integral over d^4k and factors ig^2 , defining:

$$
I_{DDDF} = ig^2 \int \frac{d^4k}{(2\pi)^4} \frac{D(k+P/2; \alpha_1)D(-k+P/2; \alpha_2)D(p-k; \alpha_3)}{[F(\alpha, z, p, P)]^n}
$$

\n
$$
= -ig^2 \frac{\Gamma(n+3)}{2\Gamma(n)} \int_{-1}^1 d\eta \int_0^1 dt (1-t)t^{n-1} \int_0^1 dx x^{n+1} I_k,
$$

\n
$$
I_k = \int \frac{d^4k}{(2\pi)^4} \Biggl[-k^2 + 2k \cdot Q - (1-x)p^2 - \frac{x}{4}P^2 + (1-x)\alpha_3 + xR - i\epsilon \Biggr]^{-(n+3)}
$$

\n
$$
= \frac{i}{(4\pi)^2} \frac{\Gamma(n+1)}{\Gamma(n+3)} \frac{1}{x^{n+1}(1-x)^{n+1}} \frac{1}{[A - f(k, P, z') - i\epsilon]^{n+1}},
$$

\n
$$
A = \frac{R}{1-x} + \frac{\alpha_3}{x} - \frac{x}{(1-x)}S,
$$

\n(A6)

where $Q = (1-x)p - xz'P/2$ and $S = (1-z')/4P^2$. Since *z'* lies in the interval $\langle -1,+1 \rangle$, $0 \leq S \leq (m_1+m_2)^2/4$. Interchanging the integrals over η and *t* with the help of:

$$
\int_{-1}^{1} d\eta \int_{0}^{1} dt = \int_{-1}^{1} dz' \left[\int_{0}^{T_{+}} \frac{dt}{1 - t} \Theta(z - z') \right] + \int_{0}^{T_{-}} \frac{dt}{1 - t} \Theta(z' - z) \Bigg],
$$
 (A7)

$$
T_{\pm} = \frac{1 \pm z'}{1 \pm z}
$$
 and $z' = tz + (1 - t) \eta$,

and introducing $\lambda = g^2/(4\pi)^2$ we get

$$
I_{DDDF} = \lambda \frac{n}{2} \int_{-1}^{1} dz' \int_{0}^{1} \frac{dx}{(1-x)^{n+1}} \sum_{s=\pm} \Theta[s(z-z')] \times \int_{0}^{T_s} \frac{dt^{n-1}}{[F(A,z',p,P)]^{n+1}}.
$$
 (A8)

Let us separate the *t* dependence of $F(A, z'; p, P)$. First we substitute for η into the definition of M^2 , which yields

$$
(1-t)M2 = -t\left(\frac{\alpha_1 + \alpha_2}{2} + \frac{\alpha_1 - \alpha_2}{2}z\right) + \frac{\alpha_1 + \alpha_2}{2}
$$

$$
+ \frac{\alpha_1 - \alpha_2}{2}z'.
$$
 (A9)

Next, we introduce the notation (indicating explicitly the *t*-dependence of *A* and *R*):

$$
A(t) \equiv \frac{R(t)}{1-x} + \frac{\alpha_3}{x} - \frac{x}{1-x}S = \frac{R(t)-S}{1-x} + \frac{\alpha_3}{x} + S, \quad (A10)
$$

$$
R(t) = \alpha t + (1 - t)M^{2} = J(\alpha, z)t + \frac{\alpha_{1} + \alpha_{2}}{2} + \frac{\alpha_{1} - \alpha_{2}}{2}z',
$$
\n(A11)

$$
J(\alpha, z) \equiv \alpha - \frac{\alpha_1 + \alpha_2}{2} - \frac{\alpha_1 - \alpha_2}{2} z,
$$
 (A12)

in which the *t*-dependence of $F[A(t), z', p, P]$ reads

$$
F[A(t), z'; p, P] = \frac{J(\alpha, z)}{1 - x} t + F[A(0), z'; p, P].
$$
 (A13)

Since *t*-dependence of $F[A(t), z'; p, P]$ is linear, the integral over *t* can be taken:

$$
\int \frac{dt^{n-1}}{F[A(t), z'; p, P]^{n+1}} = \frac{t^n}{nF[A(0), z'; p, P]\{F[A(t), z'; p, P]\}^n}
$$
 (A14)

and hence

$$
I_{DDDF} = \frac{\lambda}{2} \int_{-1}^{1} dz' \int_{0}^{1} \frac{dx}{(1-x)^{n+1}}
$$

$$
\times \sum_{s=\pm} \frac{\Theta[s(z-z')]T_{s}^{n}}{F[A(0),z';p,P]\{F[A(T_{s}),z';p,P]\}^{n}}.
$$

(A15)

Using this result, the BSE can be written as follows:

$$
\int_{-1}^{1} dz' \int_{\alpha_{min}(z')}^{\infty} d\alpha' \frac{\rho^{[n]}(\alpha',z')}{[F(\alpha',z',p,P)]^n}
$$

$$
= \left[\int \sigma \right]^3 \int d\alpha \int dz \rho^{[n]}(\alpha,z) I_{DDDF}. \tag{A16}
$$

$$
\left[\int \sigma\right]^3 \equiv \int_{\alpha_{1,min}}^{\infty} d\alpha_1 \tilde{\sigma}_1(\alpha_1) \int_{\alpha_{2,min}}^{\infty} d\alpha_2 \tilde{\sigma}_2(\alpha_2)
$$

$$
\times \int_{\alpha_{3,min}}^{\infty} d\alpha_3 \tilde{\sigma}_3(\alpha_3), \tag{A17}
$$

where $\tilde{\sigma}(\alpha_i)$ are the Lehmann functions of the dressed propagators, reducing to the δ function if the dressing is neglected. Obviously, the rhs is still not quite in the desired form, both $F[A(0), z', p, P]$ and $F[A(T_s), z', p, P]^n$ are functions of momenta *p* and *P*.

Below we rewrite the kernel as a sum of several fractions, which after substitution $\alpha' = A(T), T = 0, T_{+}$ would allow to use the uniqueness theorem $[19]$ and extract the BSE in the spectral form. This is possible only if the integrals over α' on both right- and left-hand sides of Eq. $(A17)$ are taken over the same intervals. To show this it is first necessary to prove that $R(T) - S > 0$, for $T=0, T_+$, since the functions $A(T)$ $\rightarrow +\infty$ for $x \rightarrow 0$ and $x \rightarrow 1$ they have on for $0 \le x \le 1$ the minimum equal to

$$
A_{min}(T) = (\sqrt{R(T) - S} + m_3)^2 + S
$$

= R(T) + m_3^2 + 2m_3 \sqrt{R(T) - S}. (A18)

Next, one has to show that these lower bounds are not in conflict with the lower bound for α' (and the same lower bound for α). It is simple for the undressed equal mass case, when the condition above taken for $T=0$ actually defines the lower bound for α in the following form:

$$
\alpha \ge (\sqrt{m^2 - S(z')} + m_3)^2 + S(z'), \tag{A19}
$$

and the same for $\alpha, z \rightarrow \alpha', z'$. Since $R(T_{\pm})$ depend also on α and *z* and since for the equal mass case $R(T_+) \ge R(0)$, the next two constrains clearly conform with the lower bound for α' and one can extract from them the upper bound for the integration over α :

$$
\alpha \le m^2 + \frac{1}{T_{\pm}} \left[\left(\sqrt{\alpha' - S(z')} - m_3 \right)^2 + S(z') - m^2 \right] \tag{A20}
$$

[compare to Eq. $(A6)$ of [8], where one bracket seems to be misplaced. For the unequal mass case or for the dressed propagators this analysis is much more complicated, mostly due to the fact that now for some combination of parameters it can occur $R(T+). The necessary condition $R(T)$$ $-S>0$ can again be proven in this case (though after much longer algebra), ensuring that the common lower bound for α 's exists. But we could not resolve the conditions (A18) analytically, they are treated numerically.

Now, let us go back to Eq. $(A17)$ and proceed by considering first the simple case of the symmetric Wick-Cutkosky model.

1. The Wick-Cutkosky model

In this model the constituents have the same masses m_1 $=m_2 = m$ and the mass of the exchanged particle is zero (all propagator dressings are neglected). Then for the S-wave ground state vertex function, the spectral function depends only on variable *z* and the denominator enters with power $n=1$ [Eq. (2.6)]:

$$
\rho^{[n]}(\alpha, z) \to \delta(\alpha - m^2)\rho(z), \tag{A21}
$$

and in I_{DDDF} we replace

$$
n \to 1, \quad M^2 \to m^2, \quad R(t) \to m^2, \quad J(\alpha, z) \to 0,
$$

$$
A(t) \to A = \frac{m^2}{1 - x} - \frac{x}{1 - x} S,
$$

$$
I_{DDDF} \to \frac{\lambda}{2} \int_{-1}^{1} dz' \sum_{s = \pm} \Theta[s(z - z')] T_s
$$

$$
\times \int_{0}^{1} \frac{dx}{[m^2 - xS - (1 - x)f(p, P, z') - i\epsilon]^2}.
$$

Taking the integral over x we find (recall that for equal masses $0 \leq S \leq m^2$:

$$
I_{DDDF} \to \frac{\lambda}{2} \int_{-1}^{1} dz' \sum_{s=\pm} \frac{\Theta[s(z-z')]T_s}{m^2 - S}
$$

$$
\times \frac{1}{m^2 + f(p, P, z') - i\epsilon}.
$$
(A22)

Comparing both sides of the BSE and using the uniqueness theorem $\lceil 19 \rceil$, we get the well-known (see, e.g., $\lceil 6 \rceil$) integral equation for $\rho^{[1]}(z)$:

$$
\rho(z') = \lambda \int_{-1}^{1} dz V^{[1]}(z', z) \rho(z), \tag{A23}
$$

$$
V^{[1]}(z',z) = \sum_{s=\pm} \frac{\Theta[s(z-z')]T_s}{2(m^2-S)}.
$$

Although its solution is known analytically even for exited states, the energy spectrum still has to be found numerically (up to the $P^2=0$ corresponding to $\lambda=2$). For the purpose of numerical treatment, this equation is usually rewritten in the form:

$$
\frac{\rho(z')}{\lambda} = V_0(z') - \int_{-1}^1 dz \rho(z) V_{\pm}(z', z),
$$

$$
V_0(z') = \frac{1}{2(m^2 - S)};
$$

$$
V_{\pm}(z', z) = \frac{\frac{z' - z}{1 - z} \Theta(z' - z) + \frac{z - z'}{1 + z} \Theta(z - z')}{2(m^2 - S)},
$$

where the temporary auxiliary normalization condition $\int dz \rho(z) = 1$ was imposed [i.e., if used in a further application, the vertex function would have to be renormalized in accordance to Eq. (2.3)].

2. The BSE for $n = 1$

We will now bring Eqs. $(A15)$, $(A17)$ to the desired form for the particular choice $n=1$. For the numerical solution this value is not the most suitable one. But since the formal manipulations are in this case the simplest, we treat it first for methodical reasons.

For $n=1$ the integrand of Eq. (A15) can be decomposed into the sum of simpler fractions with the help of

$$
\sum_{s=\pm} \frac{\Theta[s(z-z')]T_s}{F[A(0),z';p,P]F[A(T_s),z';p,P]}
$$

$$
=\frac{1-x}{J(\alpha,z)}\sum_{T} \frac{1}{F[A(T),z';p,P]}, \qquad (A24)
$$

where we have introduced a shorthand notation

$$
\sum_{T} f(T) = f(0) - \theta(z - z')f(T_{+}) - \theta(z' - z)f(T_{-}).
$$
\n(A25)

Notice that the lhs of Eq. (A24) is nonsingular for $J(\alpha, z)$ $=0$, so when this happens the rhs behaves like 0/0, which calls for some caution in the numerics. So, the integral *I_{DDDF}* now reads

$$
I_{DDDF}(n=1) = \frac{\lambda}{2J(\alpha, z)} \sum_{T} \int_{0}^{1} \frac{dx}{(1-x)F[A(T), z'; p, P]}.
$$
\n(A26)

In the last step we introduce the spectral variable α' $=$ *A*(*T*) and use the dependence of *A*(*T*) on *x* to convert the integration over *x* into the integral over α' . Picking up explicitly the *x*-dependence of $A(T)$ we can write:

$$
g(x) = A(T) = \frac{R(T) - S}{1 - x} + \frac{\alpha_3}{x} + S,
$$

\n
$$
g'(x) = \frac{R(T) - S}{(1 - x)^2} - \frac{\alpha_3}{x^2} = \frac{1}{1 - x} \left(A - \frac{\alpha_3}{x^2} - S \right),
$$

\n
$$
\delta[\alpha' - g(x)] = \sum_{i = \pm} \frac{1}{|g'(x_i)|} \delta(x - x_i), \quad g(x_{\pm}) = \alpha',
$$

\n
$$
x_{\pm}(T) = \frac{\alpha' - \alpha_3 - R(T) \pm \sqrt{D}}{2(\alpha'_s)},
$$

\n
$$
D = [R(T) - \alpha' + \alpha_3]^2 - 4\alpha_3[R(T) - S].
$$

\n
$$
g'(x_{\pm}) = \left(g(x_{\pm}) - \frac{\alpha_3}{x_{\pm}^2} - S \right) \frac{1}{1 - x_{\pm}} = \frac{E(x_{\pm}, S, \alpha')}{1 - x_{\pm}},
$$

$$
E(x_{\pm}, S, \alpha') = \alpha' - \frac{\alpha_3}{x_{\pm}^2} - S.
$$

With the help of these relations we get

$$
\sum_{T} \int_{0}^{1} \frac{dx}{(1-x)F[A(T), z'; p, P]}
$$

$$
= \int_{\alpha_{min}^{\infty}} \frac{d\alpha'}{F(\alpha', z'; p, P)}
$$

$$
\times \sum_{T} \sum_{i=\pm} \frac{\theta[x_i(T)]\theta[1-x_i(T)]\theta(D)}{|E[x_i(T), S, \alpha']|}.
$$

Using this result in Eq. $(A17)$, one gets from the uniqueness theorem the integral equation for the BSE structure function:

$$
\rho^{[1]}(\alpha', z')
$$

=\lambda \left[\int \sigma \right]^3 \int dz \int d\alpha V^{(1)}(\alpha, z, \alpha', z') \rho^{[1]}(\alpha, z), (A28)

$$
V^{(1)}(\alpha, z, \alpha', z')
$$

= $\frac{1}{2J(\alpha, z)} \sum_{T} \sum_{i=\pm} \frac{\theta[x_i(T)] \theta[1 - x_i(T)] \theta(D)}{|E[x_{\pm}(T), S, \alpha']|}.$ (A29)

Notice that $x_{\pm}(T)$ depend on α', z' (which are fixed from the lhs), $\alpha_1, \alpha_2, \alpha_3$ (which are fixed when the dressing is neglected), P^2 in *S* (which is given by the binding energy of the system) and for $T \neq 0$ also on α ,*z* [through *J*(α ,*z*) in $R(T₊)$]. This allows one to recast the integral equation into the form more convenient for numerical treatment.

BSE without propagator dressing (for $n=1$ *). If the propa*gator dressing is omitted, $\alpha_i \rightarrow m_i^2$ and the corresponding BSE for the spectral function reads

$$
\rho^{[1]}(\alpha',z') = \lambda \int dz \int d\alpha V^{[1]}(\alpha',z',\alpha,z)\rho^{[1]}(\alpha,z),
$$

$$
V^{[1]}(\alpha', z', \alpha, z)
$$

=
$$
\frac{1}{2J(\alpha, z)} \sum_{T} \sum_{i=\pm} \frac{\theta[x_i(T)] \theta[1 - x_i(T)] \theta(D)}{|E[x_i(T), S, \alpha']|}.
$$

As mentioned above, for $T=0$ the kernel depends on α and *z* only through $J(\alpha, z)$, hence it is convenient to pick up this case from the sum over *T* and rescaling

$$
V^{[1]}(\alpha',z',\alpha,z) = \frac{J(\alpha',z')}{J(\alpha,z)} \widetilde{V}^{[1]}(\alpha',z',\alpha,z),
$$

and imposing the auxiliary normalization

$$
\int dz \int \alpha \tilde{\rho}^{[1]}(\alpha, z) = 1,
$$
 (A30)

rewrite the BSE in the nonhomogenous form:

$$
\tilde{\rho}^{[1]}(\alpha', z') = \lambda \tilde{V}_0^{[1]}(\alpha', z')
$$

$$
-\lambda \int dz \int \alpha \sum_{s=\pm} \tilde{V}_s^{[1]}(\alpha', z', \alpha, z) \tilde{\rho}^{[1]}(\alpha, z),
$$
\n(A31)

$$
\widetilde{V}_0^{[1]}(\alpha',z') = \frac{1}{2J(\alpha',z')}
$$

$$
\times \sum_{i=\pm} \left[\frac{\theta[x_i(T)]\theta[1-x_i(T)]\theta(D)}{|E[x_{\pm}(T),S,\alpha']|}\right]_{T=0},
$$

$$
\begin{aligned} \frac{[1]}{s} & (\alpha', z', \alpha, z) \\ & = \frac{\theta[s(z-z')]}{2J(\alpha', z')} \\ & \times \sum_{i=\pm} \left[\frac{\theta[x_i(T)]\theta[1-x_i(T)]\theta(D)}{|E[x_{\pm}(T), S, \alpha']|} \right]_{T=T_s} \end{aligned}
$$

The θ functions in the kernel impose the proper bounds on α and ensure that the rhs contributes only for α' from the support of $\tilde{\rho}^{[1]}(\alpha',z')$.

.

3. BSE for $n=2$

Now, we would first describe the necessary modifications for the choice $n=2$ which was used in actual numerical calculations in this paper. Going back to Eq. $(A15)$ we can for this case write

$$
\sum_{s=\pm} \frac{\Theta[s(z-z')]T_s^2}{F[A(0), z', p, P]F[A(T_s), z', p, P]^2}
$$

$$
= \frac{1-x}{J(\alpha, z)} \sum_{T} \left[\frac{T}{\{F[A(T), z'; p, P]\}^2} + \frac{1-x}{J(\alpha, z)} \frac{1}{F[A(T), z'; p, P]}\right].
$$

$$
\rho^{[1]}(\alpha,z) = J(\alpha,z)\tilde{\rho}^{[1]}(\alpha,z),
$$

Then, the integral I_{DDDF} can be cast into the form

˜ Vs

$$
I_{DFFF} = \frac{\lambda}{2J(\alpha,z)} \int_{-1}^{1} dz' \int_{0}^{1} \frac{dx}{(1-x)^{2}} \sum_{T} \left[\frac{T}{\{F[A(T), z'; p, P]\}^{2}} + \frac{1-x}{J(\alpha,z)} \frac{1}{F[A(T), z'; p, P]}\right]
$$

\n
$$
= \frac{\lambda}{2J(\alpha,z)} \int_{-1}^{1} dz' \sum_{T} \frac{dx}{\{F[A(T), z'; p, P]\}^{2}} \left[\frac{T}{(1-x)^{2}} - \frac{\ln(1-x)}{J(\alpha,z)} \frac{dA(T)}{dx} \right]
$$

\n
$$
= \frac{\lambda}{2J(\alpha,z)} \int_{-1}^{1} dz' \int_{\alpha_{min}}^{\infty} \frac{d\alpha'}{[F(\alpha', z'; p, P)]^{2}} \sum_{T} \sum_{i=\pm} \theta(x_{i}) \theta(1-x_{i}) \theta(D)
$$

\n
$$
\times \left[\frac{T}{(1-x_{i}) | E(x_{i}, S, \alpha')|} - \frac{\text{sgn}[E(x_{i}, S, \alpha')]\ln(1-x_{i})}{J(\alpha, z)} \right],
$$

where we have first integrated the second term of the sum over *T* by parts (to increase the power of $F[A(T), z'; p, P]$, the boundary term vanishes when $x \rightarrow 0,1$) and then introduced the integration over α' as in the previous section.

Now, we can use the uniqueness theorem of PTIR $[19]$ and identify the BS weight function on the right-hand side of BSE:

$$
\rho^{[2]}(\alpha', z') = \lambda \int_{-1}^{1} dz \int_{-\infty}^{\infty} d\alpha V^{[2]}(\alpha', z'; \alpha, z) \rho^{[2]}(\alpha, z),
$$
\n(A32)

$$
V^{[2]}(\alpha', z'; \alpha, z)
$$

\n
$$
= \left[\int \sigma \right]^3 \sum_{T} \sum_{i = \pm} \frac{\theta(x_i) \theta(1 - x_i) \theta(D)}{2J(\alpha, z)^2}
$$

\n
$$
\times \left\{ \frac{TJ(\alpha, z)}{(1 - x_i)|E(x_i, S, \alpha')|} - \text{sgn}[E(x_i, S, \alpha')] \ln(1 - x_i) \right\}.
$$
 (A33)

Before treating the general case with a fully dressed propagator we consider in the next subsection the pure ladder BSE.

a. BSE without propagator dressing (for $n=2$ *).* In this case we can proceed in a way very similar to the undressed BSE for $n=1$, only with a different rescaling factor,

$$
\rho^{[2]}(\alpha, z) = J(\alpha, z)^2 \tilde{\rho}^{[2]}(\alpha, z),
$$

$$
V^{[2]}(\alpha', z', \alpha, z) = \frac{J(\alpha', z')^2}{J(\alpha, z)^2} \tilde{V}^{[2]}(\alpha', z', \alpha, z).
$$

Imposing the auxiliary normalization

$$
\int dz \int \alpha \tilde{\rho}^{[2]}(\alpha, z) = 1,
$$
 (A34)

$$
\tilde{\rho}^{[2]}(\alpha', z') = \lambda \tilde{V}_0^{[2]}(\alpha', z')
$$

$$
-\lambda \int dz \int \alpha \sum_{s=\pm} \tilde{V}_s^{[2]}(\alpha', z', \alpha, z) \tilde{\rho}^{[2]}(\alpha, z),
$$
\n(A35)

$$
\tilde{V}_0^{[2]}(\alpha', z') = -\sum_{i = \pm} \frac{\theta(x_i) \theta(1 - x_i) \theta(D)}{2J(\alpha', z')^2} \times \text{sgn}[E(x_i, S, \alpha')] \ln(1 - x_i)|_{x_i = x_i(T = 0)},
$$

$$
\tilde{V}_s^{[2]}(\alpha', z', \alpha, z)
$$
\n
$$
= \frac{\theta[s(z-z')]}{2J(\alpha', z')^2} \sum_{i=\pm} \theta(x_i) \theta(1-x_i) \theta(D)
$$
\n
$$
\times \left\{ \frac{T_s J(\alpha, z)}{(1-x_i)|E(x_i, S, \alpha')|} -\text{sgn}[E(x_i, S, \alpha')]\ln(1-x_i) \right\}_{x_i=x_i(T_s)}.
$$

b. Dressed ladder BSE for $n=2$ *. When all the self*energies are taken into account the function $J(\alpha, z)$ does not factorize and the numerically convenient redefinition (redef) cannot be used. Nevertheless, we can still separate from the integral over spectral variables α_i and the sum over *T* the term which depends on α and *z* only through $J(\alpha, z)$, namely the part for which $\tilde{\sigma}_i \rightarrow \delta(\alpha_i - m_i^2)$ and $T = 0$. Explicitly, using the notation

$$
\mathcal{V}(\alpha', z', \alpha, z, T, \alpha_1, \alpha_2, \alpha_3)
$$
\n
$$
= \sum_{i=\pm} \frac{\theta(x_i) \theta(1-x_i) \theta(D)}{2J(\alpha, z)^2} \left\{ \frac{TJ(\alpha, z)}{(1-x_i) | E(x_i, S, \alpha')|} - \text{sgn}[E(x_i, S, \alpha')] \ln(1-x_i) \right\}_{x_i=x_i(T)},
$$

and imposing the normalization condition

we can write

$$
1 = \int_{-1}^{1} dz \int_{-\infty}^{\infty} d\alpha \frac{\rho^{[2]}(\alpha, z)}{J(\alpha, z)^2},
$$
 (A36)

the BSE can be rewritten as

$$
\rho^{[2]}(\alpha', z') = \lambda V_0^{[2]}(\alpha', z')
$$

+ $\lambda \int dz \int d\alpha \sum_T V_T^{[2]}(\alpha', z', \alpha, z) \rho^{[2]}(\alpha, z),$

$$
V_0^{[2]}(\alpha', z') = -\frac{1}{2} \int d\alpha_3 \tilde{\sigma}(\alpha_3)
$$

$$
\times \sum_{s=\pm} \sum_{i=\pm} \theta(x_i) \theta(1 - x_i) \theta(D)
$$

$$
\times \text{sgn}[E(x_i, S, \alpha')] \ln(1 - x_i),
$$

$$
V_T^{[2]}(\alpha', z', \alpha, z)
$$

= $\int d\alpha_3 \tilde{\sigma}(\alpha_3) \int d\alpha_1 d\alpha_2$

$$
\times [\delta_1 \delta_2 (1 - \delta_{T,0}) + \delta_1 \sigma_2 + \sigma_1 \delta_2 + \sigma_1 \sigma_2]
$$

$$
\times V(\alpha', z', \alpha, z, T, \alpha_1, \alpha_2, \alpha_3),
$$

where in $V_0^{[2]}(\alpha', z')$ we take $x_i = x_i(T=0)$, $\alpha_1 = m_1^2$, α_2 $=m_2^2$ and in the last term $\delta_i = \delta(\alpha_i - m_i^2)$ and $\sigma_i = \sigma(\alpha_i)$ $-m_i^{\bar{2}}$, *i* = 1,2.

APPENDIX B: ELASTIC ELECTROMAGNETIC FORM FACTOR

In this appendix we derive the expression for the elastic electromagnetic form factor $G(Q^2)$. The relevant matrix element is diagrammatically depicted in Fig. 4 and the starting equation for the electromagnetic matrix element is given by Eq. (4.2) . The labeling of momenta corresponds to Fig. 4: *q* is a virtual photon incoming momentum and we put Q^2 = $-q^2$ >0, and $P_i = P$ and $P_f = P + q$ are the total momenta of bound state in in- and out-state, respectively. For simplicity, we will consider the equal mass case: $m_1^2 = m_2^2 = m^2$.

The form factor $G(Q^2)$ can easily be extracted from its definition (4.1). After multiplying by $P_i + P_f$ we get

$$
G(Q^{2}) = \frac{G_{\mu}(P+q, P)(2P+q)^{\mu}}{e(2P+q)^{2}}.
$$
 (B1)

The matrix element is evaluated between on-shell states of appropriate composite scalar, i.e., $P^2 = (P+q)^2 = M^2$ which implies

$$
2P \cdot q + q^2 = 0. \tag{B2}
$$

The one body current j_{μ} reads

$$
j^{\mu}(p_f, p_i) = (P + 2k + q)^{\mu}.
$$
 (B3)

Using Eq. $(B2)$ one can simplify

$$
(2P+q)^2 = 4M^2 + Q^2,
$$

$$
(2P+q)\cdot(2k+q+P)=2k\cdot(2P+q)+2M^2+\frac{Q^2}{2},
$$

$$
\frac{(2P+q)\cdot(2k+q+P)}{(2P+q)^2} = \frac{1}{2}\left(1 + \frac{4k\cdot(2P+q)}{4M^2+Q^2}\right).
$$

Taking this into account we can write

$$
G(Q^{2}) = \frac{i}{2} \int \frac{d^{4}k}{(2\pi)^{4}2} \left(\prod_{i=1}^{3} D_{i} \right) (\overline{\Gamma}\Gamma) \left[1 + \frac{4k \cdot (2P + q)}{4M^{2} + Q^{2}} \right],
$$
\n(B4)

$$
\prod_{i=1}^{3} D_{i} = D\left(k + \frac{P}{2}; m^{2}\right)D\left(-k + \frac{P}{2}; m^{2}\right) \times D\left(k + q + \frac{P}{2}; m^{2}\right),
$$
\n(B5)

$$
\overline{\Gamma}\Gamma = \overline{\Gamma}\left(k + \frac{q}{2}, P + q\right)\Gamma(k, P). \tag{B6}
$$

Now, we will express $G(Q^2)$ in terms of spectral functions of the bound state vertex functions Γ , rewriting first the product of the propagators with the help of the Feynman parametrization.

For the product of the propagators one gets:

$$
\prod_{i=1}^{3} D_{i} = D \left(k + q + \frac{P}{2} \right) \frac{1}{2} \int_{-1}^{1} d\eta
$$
\n
$$
\times \frac{1}{\left[k^{2} + \eta k \cdot P + \frac{P^{2}}{4} - m^{2} + i\epsilon \right]^{2}}
$$
\n
$$
= \int_{0}^{1} ds \int_{2s-1}^{1} dy
$$
\n
$$
\times \frac{1}{\left[k^{2} + \frac{M^{2}}{4} - m^{2} - \frac{s}{2} Q^{2} + 2sk \cdot q + yk \cdot P + i\epsilon \right]^{3}},
$$
\n(B7)

where the substitution $y=s+(1-s)\eta$ was applied and relations $P \cdot q = Q^2/2$ and $P^2 = M^2$ were used.

In the next step we combine PTIR (for $n=2$) of the product of the bound state vertex functions.

$$
\int_0^{\infty} d\alpha_1 d\alpha_2 \int_{-1}^{1} dz_1 dz_2 \rho^{[2]}(\alpha_1, z_1) \rho^{[2]}(\alpha_2, z_2)
$$

$$
\times \left\{ \int_0^1 dx \frac{\Gamma(4)}{\Gamma(2)\Gamma(2)} \frac{x(1-x)}{G^4} \right\},
$$

$$
G = k^2 + \frac{M^2}{4} + [z_1 + x(z_2 - z_1)]k \cdot P + x(1 + z_2)k \cdot q
$$

$$
-x(1 + z_2) \frac{Q^2}{4} - (1 - x)\alpha_1 - x\alpha_2 + i\epsilon.
$$
 (B8)

Making use of the Feynman variable t for matching Eq. $(B7)$ with the term in large brackets of Eq. $(B8)$, the relation for the form factor $(B4)$ can be rewritten as

$$
I(Q^{2}) = -\frac{i}{2} \frac{\Gamma(7)}{\Gamma(3)} \int_{0}^{1} ds \int_{2s-1}^{1} dy \int_{0}^{1} dx x(1-x) \int_{0}^{1} dt t^{3}
$$

\n
$$
\times (1-t)^{2} \int \frac{d^{4}k}{(2\pi)^{4}} \frac{\left[1+4\frac{(2P+q)\cdot k}{(2P+q)^{2}}\right]}{(2\pi)^{4} \left[c-k^{2}-k\cdot (aP+bq)-i\epsilon\right]^{7}},
$$

\n
$$
a = t[z_{1}+x(z_{2}-z_{1})]+(1-t)y,
$$

\n
$$
b = tx(1+z_{2})t+2s(1-t),
$$

\n
$$
c = b\frac{Q^{2}}{4} - \frac{M^{2}}{4} + (1-t)m^{2} + t(1-x)\alpha_{1} + tx\alpha_{2},
$$

\n(B9)

where we have omitted the vertex weight functions and the α ,*z*'s integrals [exactly the pre-factor in front of the large bracket in Eq. $(B8)$]. Integration over the momentum k with the shift $k+(aP+bq)/2 \rightarrow k$] then yields

$$
-\frac{i}{2}\frac{\Gamma(7)}{\Gamma(3)}\int \frac{d^4k}{(2\pi)^4} \frac{1+\frac{2k\cdot(2P+q)}{4M^2+Q^2}}{[c-k^2-k\cdot(aP+bq)-i\epsilon]^7}
$$

$$
=\frac{\Gamma(5)}{4(4\pi)^2} \frac{1-\frac{4(Pa+qb)\cdot(2P+q)}{4M^2+Q^2}}{[c+\frac{1}{4}(Pa+qb)^2]^5}.
$$
(B10)

This relation can be further simplified using Eq. $(B2)$ in both the numerator and the denominator,

$$
I(Q^{2}) = \frac{\Gamma(4)}{(4\pi)^{2}} \int_{0}^{1} dt \int_{0}^{1} dx \int_{0}^{1} dy \int_{0}^{(1+y)/2} ds
$$

\n
$$
\times \frac{x(1-x)t^{3}(1-t)^{2}(1-a)}{\left[\frac{Q^{2}}{4}b(b-a-1)-r\right]^{5}}, \qquad (B11)
$$

\n
$$
r = -(1-a^{2})\frac{M^{2}}{4} + (1-t)m^{2} + t(1-x)\alpha_{1} + tx\alpha_{2},
$$

\n
$$
a = t[z_{1} + x(z_{2} - z_{1})] + (1-t)y,
$$

\n
$$
b = tx(1+z_{2})t + 2s(1-t).
$$

It can be shown that for $Q^2 \ge 0$ the denominator is nonzero. The function $I(Q^2)$ can be easily calculated numerically. Including the missing prefactors the elastic electromagnetic form factor is given by

$$
(Q2)
$$

= $\int_0^{\infty} d\alpha_1 d\alpha_2 \int_{-1}^1 dz_1 dz_2 \rho^{[2]}(\alpha_1, z_1) \rho^{[2]}(\alpha_2, z_2) I(Q^2).$
(B12)

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G~*Q*2!

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