Soliton decay in a coupled system of scalar fields

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A system of coupled scalar fields is introduced which possesses a spectrum of massive single-soliton solutions. Some of these solutions are unstable and decay into lower mass stable solitons. Some properties of the solutions are obtained using general principles including conservation of energy and topological charges. Rest energies are calculated via a variational scheme, and the dynamics of the coupled fields are obtained by solving the field equations numerically.

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I. INTRODUCTION

Relativistic solitons, including those of the conventional sine-Gordon (SG) equation, exhibit remarkable similarities with classical particles. They exert short range forces on each other and collide, without losing their identities $[1]$. They are localized objects and do not disperse while propagating in the medium. Because of their wave nature, they do tunnel a barrier in certain cases, although this tunneling is different from the well-known quantum version [2]. Topological solitons are stable, due to the boundary conditions at spatial infinity. Their existence, therefore, is essentially dependent on the presence of degenerate vacua $[3]$.

Topology provides an elegant way of classifying solitons in various sectors according to the mappings between the degenerate vacua of the field and the points at spatial infinity. For the sine-Gordon system in $1+1$ dimensions, these mappings are between $\phi=2n\pi$, $n\in\mathbb{Z}$, and $x=\pm\infty$, which correspond to kinks and antikinks of the SG system. More complicated mappings occur in solitons in higher dimensions. For example, in cosmic strings, the vacuum is $S¹$ and topological sectors correspond to distinct mappings between this *S*¹ and a large circle around the string. This leads to the homotopy group $\pi^1(S^1) = \mathbb{Z}$.

Coupled systems of scalar fields have been investigated by many authors $[4-6]$. Bazeia *et al.* [4] considered a system of two coupled real scalar fields with a particular selfinteraction potential such that the static solutions are derivable from first order coupled differential equations. Riazi *et al.* [5] employed the same method to investigate the stability of the single-soliton solutions of a particular system of this type. Inspired by the well-known properties of the sine-Gordon equation, we introduce a coupled system of two real scalar fields which shows a considerably richer structure and dynamics. The present system is not of the form investigated in $[4]$ and $[5]$ and static solutions are not derivable from first order differential equations.

In our proposed system, a spectrum of solitons with dif-

ferent rest energies exists which are stable, unstable, or metastable, depending on their energies and boundary conditions. Some of the more massive solitons decay spontaneously into stable ones which subsequently leave the interaction area. Note that the term ''soliton'' is used throughout this paper for localized solutions. The problem of integrability of the model is not addressed here. Such nondispersive solutions are called "lumps" by Coleman $[7]$ to avoid confusion with true solitons of integrable models. However, it has now become popular to use the term soliton in its general sense.

Pogosian [8] investigated kink solutions in bidimensional $SU(N) \times Z_2$ models. He found that heavier kinks tend to break up into lighter ones. Comparing our results with those reported by Pogosian, it is interesting to note that fairly similar phenomena are observed in quite different systems. In an earlier paper, Pogosian and Vachaspati [9] reported (*N*) $+1/2$ distinct classes of kink solutions in an SU(*N*) $\times Z_2$ field theory.

The organization of the paper is as follows. In Sec. II, we introduce the Lagrangian density, dynamical equations, and conserved currents of the proposed model. In Sec. III, some exact solutions together with the corresponding charges and energies are derived. The necessary nomenclature and general behavior of the solutions due to the boundary conditions are also introduced in this section. Numerical solutions corresponding to different boundary conditions are presented, and properties of these solutions like their charges, masses, and stability status are addressed in this section. In order to investigate the stability of the numerical solutions, their evolution is worked out numerically. The dynamical evolution of the unstable solutions is investigated further in Sec. IV. Our final conclusion and a summary of the results is given in the last section.

II. DYNAMICAL EQUATIONS AND CONSERVED CURRENTS

Our choice of the Lagrangian density reads

$$
\mathcal{L} = \frac{1}{2} \partial^{\mu} \phi_1 \partial_{\mu} \phi_1 - \alpha_1 (\phi_2^2 + \epsilon_1)(1 - \cos \phi_1)
$$

$$
+ \frac{1}{2} \partial^{\mu} \phi_2 \partial_{\mu} \phi_2 - \alpha_2 (\phi_1^2 + \epsilon_2)(1 - \cos \phi_2)
$$
(1)

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FIG. 1. The self-interaction potential is shown as a height diagram over the (ϕ_1, ϕ_2) plane.

in which
$$
\alpha_{1,2}
$$
 and $\epsilon_{1,2}$ are positive constants, and $\phi_{1,2}$ are two
real scalar fields. The background space-time is assumed to
have the metric $g_{\mu\nu}$ =diag(1,-1) in 1+1 dimensions and
 $c=1$ has been used throughout this paper. Recall that the
sine-Gordon Lagrangian density

$$
\mathcal{L} = \frac{1}{2} \partial^{\mu} \phi \partial_{\mu} \phi - \alpha (1 - \cos \phi) \tag{2}
$$

leads to single-soliton solutions

$$
\phi = 2n\pi \pm 4 \tan^{-1} e^{\sqrt{\alpha}x} \tag{3}
$$

all having rest energies $8\sqrt{\alpha}$. Our proposed Lagrangian density (1) comes from the idea of mixing two scalar fields in such a way that the discrete vacua at $\phi_1 = 2n\pi$, ϕ_2 $=2m\pi$ (*m*,*n* $\in \mathbb{Z}$) survive, while the rest energies of solitons for each field (say ϕ_1) are affected by the value of the other (ϕ_2) , and vice versa. It will be seen later that this idea leads to the appearance of nondegenerate solitons with distinct topological charges.

The corresponding equations of motion are easily obtained by applying the variational principle $\delta(\int \mathcal{L}d^2x)=0$ to the Lagrangian density (1) :

$$
\Box \phi_1 = \alpha_1 (\phi_2^2 + \epsilon_1) \sin \phi_1 + 2 \alpha_2 \phi_1 (1 - \cos \phi_2)
$$
 (4)

and

$$
\Box \phi_2 = \alpha_2 (\phi_1^2 + \epsilon_2) \sin \phi_2 + 2 \alpha_1 \phi_2 (1 - \cos \phi_1). \tag{5}
$$

Since the Lagrangian density (1) is Lorentz invariant, the corresponding energy-momentum tensor $[10]$

$$
T^{\mu\nu} = \partial^{\mu}\phi_1 \partial^{\nu}\phi_1 + \partial^{\mu}\phi_2 \partial^{\nu}\phi_2 - g^{\mu\nu}\mathcal{L}
$$
 (6)

satisfies the conservation law

$$
\partial_{\mu}T^{\mu\nu} = 0. \tag{7}
$$

The Hamiltonian density is obtained from Eq. (6) according to

$$
\mathcal{H} = T_0^0 = \frac{1}{2}\dot{\phi}_1^2 + \frac{1}{2}\dot{\phi}_2^2 + \frac{1}{2}\phi_1'^2
$$

+
$$
\frac{1}{2}\phi_2'^2 + V(\phi_1, \phi_2),
$$
 (8)

where the overdot and prime denote time and space derivatives, respectively. It is seen from Eq. (1) that the potential is

$$
V(\phi_1, \phi_2) = \alpha_1(\phi_2^2 + \epsilon_1)(1 - \cos \phi_1)
$$

+
$$
\alpha_2(\phi_1^2 + \epsilon_2)(1 - \cos \phi_2).
$$
 (9)

This potential is shown in Fig. 1, as a height diagram over the (ϕ_1, ϕ_2) plane. In this figure and any numerical calculation throughout this paper, we fix the parameters as α_1 =0.3, α_2 =1, ϵ_1 =0.5, and ϵ_2 =0.07 for the sake of being definite. The classical vacua consist of points in the (ϕ_1, ϕ_2) plane at which the condition $V(\phi_1, \phi_2)=0$ holds. Since the potential consists of two non-negative terms, it vanishes if and only if the two terms vanish simultaneously. This leads to the vacuum set of points in the (ϕ_1, ϕ_2) space:

$$
V = \{ (\phi_1, \phi_2) | \phi_1 = 2m\pi \text{ and } \phi_2 = 2n\pi; m, n \in \mathbb{Z} \}. \tag{10}
$$

It can be shown that the following topological currents can be defined, which are conserved independently, and lead to quantized charges:

$$
J_{mH}^{\mu} = \delta_{mp} \epsilon^{\mu \nu} \partial_{\nu} \phi_1 / 2\pi
$$

$$
J_{mV}^{\mu} = \delta_{mq} \epsilon^{\mu \nu} \partial_{\nu} \phi_2 / 2\pi.
$$
 (11)

In these equations, *m* is an integer, and the integers *p* and *q* are defined according to

> *p*= integer part of $(\phi_1/2\pi) + 1$, *q* = integer part of $(\phi_2/2\pi)$ + 1.

FIG. 2. Nomenclature of horizontal (H) and vertical (V) solutions according to boundary conditions. The three lightest solutions H_1^0 , V_0^1 , and H_1^1 are stable, while V_1^1 and V_2^1 are unstable. The corresponding rest energies and charges are shown in Table I for our choice of parameters.

The subscripts *V* and *H* denote ''vertical'' and ''horizontal'' which will be explained later. The currents $J_{mH_V}^{\mu}$ are conserved, independent of each other:

$$
\partial_{\mu}J_{mH}^{\mu} = 0,
$$

\n
$$
\partial_{\mu}J_{mV}^{\mu} = 0.
$$
 (12)

The corresponding topological charges are given by

$$
Q_{mH} = \int_{-\infty}^{\infty} J_{mH}^{0} dx = \delta_{mp} [\phi_1(+\infty) - \phi_1(-\infty)]/2 \pi,
$$

$$
Q_{mV} = \int_{-\infty}^{\infty} J_{mV}^{0} dx = \delta_{mq} [\phi_2(+\infty) - \phi_2(-\infty)]/2 \pi.
$$
 (13)

These charges quantify the mappings between the vacua $\phi_{1,2}(\pm\infty) \in \mathcal{V}$ and the points at spatial infinity.

III. SINGLE-SOLITON SOLUTIONS

Static solutions which correspond to transitions between adjacent vacua are symbolically shown in Fig. 2. Accordingly, we call the static solutions H (horizontal) and V (vertical) types. We have called them "horizontal" and "vertical'' simply because of their orientation in the (ϕ_1, ϕ_2) plane. Initial guesses for these solutions are obtained using the known properties of the conventional sine-Gordon equation $[6]$. Note that the exact solutions are not strictly horizontal or vertical lines in the (ϕ_1, ϕ_2) plane. Rather, they are bent curves joining two neighboring vacuum points due to the coupling between the two scalar fields. Any finite energy solution should start and end at one of the vacuum points belonging to V [Eq. (10)]. Equations (4) and (5) possess the following exact single-soliton solutions:

$$
H_{p+1}^{0}: \quad \phi_1 = 4 \tan^{-1} \exp[\pm a(x - x_0)] + 2p \pi
$$

and
$$
\phi_2 = 0
$$
 (14)

with

and

$$
V_0^{q+1}: \quad \phi_2 = 4 \tan^{-1} \exp[\pm b(x - x_0)] + 2q \pi
$$

and $\phi_1 = 0,$ (15)

with

$$
Q_{mH} = 0, \quad Q_{mV} = \delta_{mq},
$$

 $Q_{mH} = \delta_{mp}$, $Q_{mV} = 0$,

where p and q are integers. Note that Eqs. (14) and (15) satisfy Eqs. (4) and (5) in the static ($\partial/\partial t=0$) case. In these equations, $a=\sqrt{\alpha_1\epsilon_1}$, $b=\sqrt{\alpha_2\epsilon_2}$, and x_0 is the kink position. Apart from these exact solutions, we will introduce other static solutions which are obtained numerically later. Despite the similarity of the special solutions (14) and (15) to those of the sine-Gordon equation, there are profound differences between the general static solutions of the present system and of the SG equation, including nondegenerate soliton masses and instability of some of the static solutions. The rest energies of the *H*- and *V*-type solitons are obtained by integrating the corresponding Hamiltonian densities (with $\dot{\phi}_1 = \dot{\phi}_2 = 0$) over the *x* space. The rest energies are approximately given by

$$
H \text{ type:} \quad M_H \approx 8\sqrt{\alpha_1(4\pi^2 n^2 + \epsilon_1)},\tag{16}
$$

and

V type:
$$
M_V \approx 8\sqrt{\alpha_2(4\pi^2 n^2 + \epsilon_2)},
$$
 (17)

where *n* is an integer. We have written programs in the MAT-LAB environment that calculate static solutions and dynamical evolutions from prespecified initial conditions. The static solutions are obtained by minimizing the energy functional

$$
E = \int \mathcal{H} dx \tag{18}
$$

where $H=T_0^0$ is the energy (Hamiltonian) density, using a variational procedure. The program is asked to terminate as soon as the energy converges up to a 10^{-6} accuracy. Inspired by the exact solutions (14) and (15) , the initial guesses were taken to be of the form of sine-Gordon solitons. These initial guesses were deformed toward the lowest energy solutions by the variational calculation. This deformation is caused by the slope of the potential function as depicted in Fig. 1. Sample solutions are shown in Fig. 3. Static solutions V_0^1 , H_1^0 , H_1^1 , and V_1^1 as projected on the (ϕ_1, ϕ_2) plane are shown in Fig. 4. A sample classification is shown in Table I for a particular choice of the parameters. Antisolitons exist

FIG. 3. Examples of static solutions.

with the same masses (rest energies) as solitons but with opposite charges. The antisoliton solutions are obtained by simply exchanging the boundary conditions at $x = +\infty$ into those at $x = -\infty$. For example,

$$
H_1^0: \begin{cases} \phi_1(-\infty) = 0, & \phi_1(+\infty) = 2\pi, \\ \phi_2(-\infty) = 0, & \phi_2(+\infty) = 0, \end{cases}
$$
 (19)

while

$$
\bar{H}_1^0: \begin{cases} \phi_1(-\infty) = 2\pi, & \phi_1(+\infty) = 0, \\ \phi_2(-\infty) = 0, & \phi_2(+\infty) = 0. \end{cases}
$$
 (20)

It is clear from the definition of topological charges (11) that solitons and antisolitons have opposite charges. The approximate formulas (16) and (17) may be compared with the numerical results depicted in Table I. It can be seen that the

FIG. 4. The static solutions V_0^1 , H_1^0 , H_1^1 , and V_1^1 as projected on the (ϕ_1, ϕ_2) plane.

masses of the *H*-type solitons are better approximated by Eq. (16) than those given by Eq. (17) . This difference can be attributed to the fact that the horizontal solitons deviate less from the sine-Gordon solitons (see Fig. 4).

IV. SOLITON DECAY

The time-dependent solutions of the dynamical equations (4) and (5) were obtained numerically, by transforming these partial differential equations (PDEs) into finite difference equations, and calculating the fields $\phi_1(x,t)$ and $\phi_2(x,t)$ in successive time steps. Most of the static solutions obtained did not undergo appreciable variations when inserted into our dynamical program as initial conditions. This is a numerical indication of the stability of the corresponding static solutions. However, not all the static solutions obtained by the variational method explained in the last section were found to be stable. For the given choice of parameters, V_1^1 , for example, is unstable and decays spontaneously via $[see Figs.$ $5(a)$ and $5(b)$]

$$
V_1^1 \to \overline{H}_1^0 + V_0^1 + H_1^1. \tag{21}
$$

Here, \bar{H}_1^0 is the antisoliton of H_1^0 . Figure 5(a) shows the ϕ_1 and ϕ_2 fields after several time steps. The decay product solitons can be identified at positions where the fields jump from one vacuum to an adjacent vacuum. Figure 3 helps in recognizing these decay products. Figure 4 shows the stable solutions H_1^1 , V_0^1 , and H_1^0 and the unstable solution V_1^1 on the (ϕ_1, ϕ_2) plane. Numerical calculations show that the decay of V_1^1 starts with the trajectory shown for this solution and evolves gradually to the \overline{H}_1^0 (H_1^0 in the reverse direction), V_0^1 , and H_1^1 trajectories in this figure. Figure 5(b) shows the

Symbol	Mass	Q_{1H}	Q_{1V}	Q_{2H}	Q_{2V}	Q_{3H}	Stability
\boldsymbol{V}^1_0	2.09	$\overline{0}$	$+1$	$\overline{0}$	$\overline{0}$	θ	stable
V_0^2	2.09	Ω	Ω	Ω	$+1$	0	stable
H_1^0	3.09	$+1$	Ω	Ω	Ω	θ	stable
H_2^0	3.09	Ω	Ω	$+1$	Ω	Ω	stable
H_3^0	3.09	Ω	Ω	Ω	Ω	$+1$	stable
H_1^1	26.7	$+1$	Ω	θ	Ω	$\overline{0}$	stable
H_2^1	27.5	Ω	Ω	$+1$	$\overline{0}$	θ	stable
H_3^1	27.6	Ω	Ω	Ω	Ω	$+1$	stable
V_1^1	42.9	$\overline{0}$	$+1$	θ	$\overline{0}$	θ	$V_1^1 \rightarrow \bar{H}_1^0 V_0^1 H_1^1$
V_1^2	48.4	Ω	Ω	Ω	$+1$	Ω	stable
H_1^2	53.6	$+1$	Ω	Ω	Ω	Ω	stable
H_2^2	54.6	Ω	Ω	$+1$	Ω	θ	stable
V_2^1	89.6	$\overline{0}$	$+1$	$\overline{0}$	$\overline{0}$	$\overline{0}$	$V_2^1 \rightarrow \bar{H}^0_2 \bar{H}^0_1 V_0^1 H_1^1 H_2^1$
${\cal V}_2^2$	95.5	Ω	Ω	Ω	$+1$	$\overline{0}$	stable
V_3^1	129	$\overline{0}$	$+1$	$\overline{0}$	$\overline{0}$	$\overline{0}$	metastable

TABLE I. A sample classification of the lowest energy solitons for $\alpha_1=0.3$, $\alpha_2=1$, $\epsilon_1=0.5$, ϵ_2 $=0.07.$

corresponding energy density for various time steps. Individual solitons as decay products are more apparent in this figure.

The balance of *H* and *V* charges is of course respected in the decay (21) , which can be easily demonstrated by computing Q_{mV} and Q_{mH} for V_1^1 , \bar{H}_1^0 , V_0^1 , and H_1^1 . From the conservation of energy point of view, $M(V_1^1) = 42.9$, while $M(\bar{H}_1^0) + M(V_0^1) + M(H_1^1) = 31.88$, which shows that the decay is allowed, and the excess energy is transferred to the kinetic energies of the solitons. As Fig. $5(b)$ shows, no appreciable energy is radiated away as small amplitude wavelets.

Numerical results show that V_2^1 is also unstable and decays via

$$
V_2^1 \rightarrow \overline{H}_2^0 + \overline{H}_1^0 + V_0^1 + H_1^1 + H_2^1. \tag{22}
$$

Figure 6 illustrates the decay of V_2^1 . It can be seen from Fig. 6(b) that an $\overline{H}_1^0 V_0^1 H_1^1$ compound (i.e., V_1^1) is produced first. This compound subsequently decays into its components in a short time. Note that $M(V_2^1) = 89.6$ and the sum of the rest

energies of the decay products is $\Sigma_{\text{product}}M=62.47$. The difference goes to the kinetic energies of the decay products. The total energy and all topological charges are conserved. In order to demonstrate the conservation of topological charges, let us write down the charges of individual solitons:

$$
V_2^1
$$
: $Q_{1V} = +1$, \overline{H}_2^0 : $Q_{2H} = -1$, \overline{H}_1^0 : $Q_{1H} = -1$,
 V_0^1 : $Q_{1V} = +1$, H_1^1 : $Q_{1H} = +1$, H_2^1 : $Q_{2H} = +1$,

all other charges being zero. We thus have Q_{1V} (LHS)= $+1$ and Q_{1V} (RHS) = $+1$, and all other charges are equal to zero for both sides.

Surprisingly enough, although the decay of V_3^1 via

$$
V_3^1 \rightarrow \bar{H}_3^0 + \bar{H}_2^0 + \bar{H}_1^0 + V_0^1 + H_1^1 + H_2^1 + H_3^1 \tag{23}
$$

FIG. 5. The decay of V_1^1 . (a) ϕ_1 and ϕ_2 as a function of *x* after the decay of V_1^1 . (b) The energy density as a function of *x* for various time steps. The dotted line for V_0^1 is added in order to clarify the trajectory of this decay product.

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is allowed by conservation of energy and charge, such a decay is not observed. We thus conclude that V_3^1 is a metastable soliton, and its fission needs some external trigger.

V. CONCLUSION

Although the sine-Gordon equation is an integrable system, even minor modifications of the equation usually exploit its integrability. We described in this paper and elsewhere $[2,11]$ interesting and rich behavior that may result from suitable modifications of the sine-Gordon equation irrespective of whether it is integrable or not. Removal of mass degeneracy, soliton confinement, and soliton decay are among such properties.

For the system introduced in this paper, we presented a class of exact, single-soliton solutions in the particular case where the system reduced to the sine-Gordon equation (ϕ_1) $=0$ or $\phi_2=0$). Other classes of static solutions were computed numerically using a variational algorithm. These static solutions were then fed into a numerical program which computed the dynamical evolution of the solution. We found that most of the static solutions were stable, while a few underwent decay into lower energy solitons. Topological charges where conserved throughout these dynamical processes, in addition to the conservation of energy and linear momentum which results from the invariance of Lagrangian under space and time translation. In the particular decay (22) , two interesting effects were observed: First, the decay did not start promptly. Rather, V_2^1 decayed into $\overline{H}_2^0 V_1^1 H_2^1$ first, and V_1^1 decayed via Eq. (21) in a later stage. Second, the $(\bar{H}_1^0, \bar{H}_2^0)$ pair apparently remained as a bound system in the decay of V_2^1 . In order to check whether \overline{H}_1^0 and \overline{H}_2^0 do form a bound system, we did numerical calculations (both variational and dynamical) for this system. It turned out that the system split into \overline{H}_1^0 and \overline{H}_2^0 which moved away from each other. We conclude that $\overline{H}_1^0 \overline{H}_2^0$ do not form a bound system.

Finally, let us discuss briefly the kinematics of solitons in the decay process. Since our system is relativistic, principles of conservation of energy and momentum should be applicable in their relativistic form. Ignoring the energy and momentum radiated away in the form of small amplitude wavelets, we may write

FIG. 6. The decay of V_2^1 . (a) ϕ_1 and ϕ_2 as a function of *x* after the decay of V_2^1 . (b) The energy density as a function of *x* for various time steps.

$$
Mc^{2} = \sum_{i=1}^{n} \gamma_{i} m_{i} c^{2}
$$
 (24)

and

$$
\sum_{i=1}^{n} \gamma_i m_i v_i = 0 \tag{25}
$$

for the decay

$$
S \rightarrow s_1 + s_2 + \cdots + s_n. \tag{26}
$$

In Eqs. (24) and (25) , *M* is the mass of the *S* soliton, m_i are the masses of the s_i solitons, v_i are the corresponding velocities, and $\gamma_i = (1 - v_i^2)^{-1/2}$. The system of equations (24) and (25) has a unique solution for v_i , if $n=2$. For $n>2$, we have only two equations for *n* unknowns and the equations do not have a unique solution. However, the decay pattern and the distribution of velocities among the decay products seem to be predetermined in our numerical results (compare the decay pattern of V_1^1 in Figs. 5 and 6). If we note that the decay to the daughter solitons does not happen in a single stage, but rather proceeds in successive stages, it becomes clear why the distribution of velocities among the decay products follow a unique pattern. In each stage, an unstable soliton decays into *two* decay products, which is actually observed numerically. The velocities of the two decay products are unique, according to Eqs. (24) and (25) . One of the decay products, in turn, decays into two solitons in a later stage, and so on.

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