

Phenomenology of the Gowdy universe on $T^3 \times R$

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Numerical studies of the plane symmetric, vacuum Gowdy universe on $T^3 \times R$ yield strong support for the conjectured asymptotically velocity term dominated (AVTD) behavior of its evolution toward the singularity except, perhaps, at isolated spatial points. A generic solution is characterized by spiky features and apparent “discontinuities” in the wave amplitudes. It is shown that the nonlinear terms in the wave equations drive the system generically to the “small velocity” AVTD regime and that the spiky features are caused by the absence of these terms at isolated spatial points. [S0556-2821(98)03808-9]

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I. INTRODUCTION

Spatially inhomogeneous cosmologies constitute almost a “terra incognita” for general relativity. In particular, the nature of the singularity in generic cosmologies is unknown although Belinskii, Khalatnikov, and Lifshitz (BKL) have conjectured that it is locally mixmasterlike [1]. Spatially homogeneous universes’ approach to the singularity can be either asymptotically velocity term dominated (AVTD) [2,3] or mixmasterlike [1,4]. In general, AVTD singularities occur when the influence of spatial derivatives can be neglected. This means that the solution to the full Einstein equations eventually comes arbitrarily close to the solution to the truncated equations one obtains by eliminating the terms containing spatial derivatives [3]. In spatially homogeneous models, spatial derivatives in the metric create the spatial scalar curvature which appears as a potential in minisuperspace [4,5]. An AVTD homogeneous cosmology eventually evolves toward the singularity as a Kasner solution. (The Kasner universe is an exact solution of the vacuum Einstein equations characterized by different expansion rates in different directions with flat spacelike hypersurfaces [6].) Mixmaster dynamics describes the evolution (of nonflat spacelike hypersurfaces) toward the singularity as an infinite sequence of (approximately) Kasner epochs. The Kasner indices (which determine the anisotropic expansion rates) change whenever the influence of the spatial scalar curvature reappears. Its recurring influence means that the mixmaster singularity is not AVTD. BKL claimed to prove that the generic singularity in Einstein’s equations and, in particular, in spatially inhomogeneous cosmologies is mixmasterlike. While this result remains controversial [7], it provides a conjecture which can be tested by evolving spatially inhomogeneous collapsing universes numerically.

As part of such a study of this issue [8–10], we have considered the Gowdy universes on $T^3 \times R$ as a test case. These models are one of the classes discovered by Gowdy [11–13] as a reinterpretation of Einstein-Rosen waves [14]. While their plane symmetry precludes local mixmaster behavior, their nonlinear gravitational wave interactions lead to

an interesting phenomenology which forms the subject of this paper. The Gowdy singularity has been conjectured to be asymptotically velocity term dominated (AVTD) [15] and has been shown rigorously to be so for the polarized case [3]. In addition, it has been shown that for the polarized case, cosmic censorship holds: There exists a natural foliation labeled by $0 \leq \tau < \infty$ such that regular initial data evolve without singularity for all $\tau < \infty$ where (in the collapse direction) a curvature singularity occurs at $\tau = \infty$ [16]. Here we shall use numerical studies to provide support for the extension of the polarized Gowdy results to generic Gowdy models.

Gowdy cosmologies represent the simplest spatially inhomogeneous cosmological solutions to Einstein’s equations. The vacuum case may be interpreted as the two polarizations of gravitational waves propagating in an inhomogeneous background spacetime [8,12]. The model is plane symmetric with the propagation direction of the waves orthogonal to the symmetry plane. Near the singularity, the metric may be rewritten as locally Kasner with spatially dependent Kasner indices [12]. (This is a nonrigorous statement of AVTD behavior.) Matter fields compatible with the Gowdy metric have been discussed by Carmeli, Charach, and Malin [17,18], and Ryan [19]. Here we shall consider only vacuum solutions.

The main phenomena of interest in the Gowdy universe are the growth of small scale spatial structure and the approach to the AVTD regime. We shall demonstrate that both result from the nonlinear terms in the wave equation for P , the + polarization of the gravitational waves. These act as space and time dependent potentials whose effect is to drive the system to velocity dominance. As the AVTD regime is reached, the potentials approach zero. Their spatial dependence means that wave amplitudes grow at some spatial points and decrease at others, eventually producing small scale spatial dependence in the wave forms. Nongeneric behavior occurs at points where the coefficients of the potentials (separately) vanish identically. We note that this analysis in terms of potentials explains the observed episodic evolution of the system to the AVTD regime and the fact that the conditions for AVTD are reached at some spatial points before others. This should be considered together with the asymptotic expansion developed by Grubišić and Moncrief (GM) [15] which displays an exponential decay to the AVTD limit, applicable in the last episode.

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The primary advantage of the Gowdy models as a test case for the study of inhomogeneous cosmologies is the existence of variables in which the dynamical equations for the wave amplitudes decouple from the constraints. Initial data for the wave equations may be freely specified (restricted only in that the total momentum along the direction of propagation must vanish) while the constraints appear as prescriptions for the construction of the background metric from the known solution to the dynamical equations. Thus the two principal difficulties of numerical relativity—solving the initial value problem and preserving the constraints during the evolution—become trivial. This decoupling between dynamical and constraint equations disappears in more complicated inhomogeneous models. However, studies of U(1) symmetric cosmologies (with only one Killing field) indicate that many features of the Gowdy phenomenology such as spiky small scale spatial structure persist in these more complicated models [8,20,10] and, presumably, would be important in the dynamics of generic cosmologies.

In Sec. II, the Gowdy model on $T^3 \times R$ will be reviewed. Section III will contain a brief description of the numerical method. In Sec. IV, the phenomenology will be described. Section V will contain a unified explanation for the phenomenology. Discussion will be given in Sec. VI.

II. THE MODEL

The Gowdy model on $T^3 \times R$ is described by the metric [11,8]

$$ds^2 = e^{-\lambda/2} e^{\tau/2} (-e^{-2\tau} d\tau^2 + d\theta^2) + e^{-\tau} [e^P d\sigma^2 + 2e^P Q d\sigma d\delta + (e^P Q^2 + e^{-P}) d\delta^2], \quad (1)$$

where λ, P, Q are functions of θ, τ . The sign of λ differs from that in [8] as required for consistency with the form given there for the equations for λ . The arguments in [8] did not depend on this error. We impose T^3 spatial topology by requiring $0 \leq \theta, \sigma, \delta \leq 2\pi$ and the metric functions to be periodic in θ . If we assume P and Q to be small, we find them to be, respectively, the amplitudes of the $+$ and \times polarizations of the gravitational waves with λ describing the background in which they propagate. The time variable τ measures the area in the symmetry plane with $\tau = \infty$ a curvature singularity. Einstein's equations split into two groups. The first is nonlinearly coupled wave equations for P and Q (where ${}_{,a} = \partial/\partial a$):

$$P_{,\tau\tau} - e^{-2\tau} P_{,\theta\theta} - e^{2P} (Q_{,\tau}^2 - e^{-2\tau} Q_{,\theta}^2) = 0, \quad (2)$$

$$Q_{,\tau\tau} - e^{-2\tau} Q_{,\theta\theta} + 2(P_{,\tau} Q_{,\tau} - e^{-2\tau} P_{,\theta} Q_{,\theta}) = 0. \quad (3)$$

The second contains the Hamiltonian and θ -momentum constraints which can be expressed as first order equations for λ in terms of P and Q :

$$\lambda_{,\tau} - [P_{,\tau}^2 + e^{-2\tau} P_{,\theta}^2 + e^{2P} (Q_{,\tau}^2 + e^{-2\tau} Q_{,\theta}^2)] = 0, \quad (4)$$

$$\lambda_{,\theta} - 2(P_{,\theta} P_{,\tau} + e^{2P} Q_{,\theta} Q_{,\tau}) = 0. \quad (5)$$

This split into dynamical and constraint equations removes two of the most problematical areas of numerical relativity from this model. (1) The normally difficult initial value prob-

lem becomes trivial since P, Q and their first time derivatives may be specified arbitrarily. The only restriction, that the total θ momentum in the waves vanishes, is a consequence of the requirement that metric variables be periodic in θ . (2) The constraints, while guaranteed to be preserved in an analytic evolution by the Bianchi identities, are not automatically preserved in a numerical evolution with Einstein's equations in differenced form. However, in the Gowdy model, the constraints are trivial since λ may be constructed from the numerically determined P and Q . For the special case of the polarized Gowdy model ($Q=0$), P satisfies a linear wave equation whose exact solution is well known [12]. For this case, it has been proven that the approach to the singularity is AVTD [3]. This has also been conjectured to be true for generic Gowdy models [15]. We shall show in Sec. V how a numerical study of this model provides strong support for this conjecture.

The wave equations (2) and (3) can be obtained by variation of the Hamiltonian [13]

$$H = \frac{1}{2} \int_0^{2\pi} d\theta [\pi_P^2 + e^{-2P} \pi_Q^2] + \frac{1}{2} \int_0^{2\pi} d\theta [e^{-2\tau} (P_{,\theta}^2 + e^{2P} Q_{,\theta}^2)] = H_K + H_V. \quad (6)$$

The variation of the kinetic energy term H_K yields equations of motion for the AVTD solution which arises when spatial derivatives are neglected. These equations are exactly solvable with the solution

$$\begin{aligned} P &= P_0 + \ln[\cosh v\tau + \cos\psi \sinh v\tau] \rightarrow v\tau \quad \text{as } \tau \rightarrow \infty, \\ Q &= Q_0 + \frac{e^{-P_0} \sin\psi \tanh v\tau}{1 + \cos\psi \tanh v\tau} \rightarrow Q_\infty \quad \text{as } \tau \rightarrow \infty, \\ \pi_P &= v \frac{\tanh v\tau + \cos\psi}{1 + \cos\psi \tanh v\tau} \rightarrow v \quad \text{as } \tau \rightarrow \infty, \\ \pi_Q &= e^{P_0} v \sin\psi \equiv \pi_Q^0 \end{aligned} \quad (7)$$

given in terms of four functions of θ : $\psi, v \geq 0, P_0$, and Q_0 . Here $Q_\infty \equiv Q_0 + e^{-P_0} \sin\psi / (1 + \cos\psi)$. The large τ limits given above are for $\cos\psi \neq -1$. The special case $\cos\psi = -1$ will be discussed later. While Eq. (7) may be solved for all these functions, it is convenient to note that [15]

$$v = \sqrt{\pi_P^2 + \pi_Q^2} e^{-2P} \quad (8)$$

is the geodesic velocity in the target space (with metric $ds^2 = dP^2 + e^{2P} dQ^2$) of the wave map [13,15,8]. If, as the singularity is approached, the behavior is AVTD, the true solution will approach the AVTD one. The exponential prefactor $e^{-2\tau}$ in H_V of Eq. (6) makes plausible the conjectured AVTD singularity. However, $P \rightarrow v\tau$ (for $v > 0$) as $\tau \rightarrow \infty$. If $v > 1$, the term $V_2 = e^{-2\tau} e^{2P} Q_{,\theta}^2$ in H_V can grow rather than decay as $\tau \rightarrow \infty$. In fact, if one assumes the AVTD behavior as $\tau \rightarrow \infty$ in Eq. (7), the wave equations become [15]

$$\begin{aligned} P_{,\tau\tau} &= -e^{-2[1-v]\tau} [Q_\infty']^2 + e^{-2\tau} v'' \tau + \pi_Q^2 e^{-2v\tau}, \\ \pi_{Q,\tau} &= e^{-2[1-v]\tau} [Q_\infty'' + 2v' Q_\infty' \tau], \end{aligned} \quad (9)$$

where $' = d/d\theta$. These equations are inconsistent if $v > 1$ unless $Q'_\infty = 0 = Q''_\infty$, which does not occur in a generic (unpolarized) Gowdy model. However, in generic Gowdy models, one also expects isolated points (a set of measure zero) with $Q'_\infty = 0$ but $Q''_\infty \neq 0$. In Sec. V, we shall see that $v > 1$ can persist at such isolated values of θ where the AVTD conditions may not be satisfied. GM thus conjecture that the AVTD limit as $\tau \rightarrow \infty$ requires $0 \leq v < 1$ everywhere except, perhaps, at a set of measure zero (isolated values of θ) [15]. We note that the polarized Gowdy model ($Q = \pi_Q = 0$) has the AVTD solution $P = P_0 + \alpha\tau$, $\pi_p = \alpha$ with $\alpha(\theta)$ unrestricted in sign or magnitude [12,3]. The fact that this behavior is not a limit of the generic AVTD solution (7) illustrates further the qualitative distinction between the polarized case and $Q \neq 0$ but arbitrarily small.

III. NUMERICAL METHODS

The numerical method is discussed in detail elsewhere [8]. However, we shall summarize it here. The work reported here was performed by using a symplectic partial differential equation (PDE) solver [21,22]. Consider a system with one degree of freedom described by $q(t)$ and its canonically conjugate momentum $p(t)$ with a Hamiltonian

$$H = \frac{p^2}{2m} + V(q) = H_K + H_V. \quad (10)$$

Note that the sub-Hamiltonians H_K and H_V separately yield equations of motion which are exactly solvable no matter the form of V . Variation of H_K yields $\dot{q} = p/m$, $\dot{p} = 0$ with the solution

$$p(t + \Delta t) = p(t), \quad q(t + \Delta t) = q(t) + \frac{p(t)}{m} \Delta t. \quad (11)$$

Variation of H_V yields $\dot{q} = 0$, $\dot{p} = -dV/dq$ with solution

$$q(t + \Delta t) = q(t), \quad p(t + \Delta t) = p(t) - \left. \frac{dV}{dq} \right|_t \Delta t. \quad (12)$$

Note that the absence of momenta in H_V makes Eq. (12) exact for any $V(q)$. One can then demonstrate that to evolve from t to $t + \Delta t$ an evolution operator $\mathcal{U}_{(2)}(\Delta t)$ can be constructed from the evolution suboperators $\mathcal{U}_K(\Delta t)$ and $\mathcal{U}_V(\Delta t)$ obtained from Eqs. (11) and (12). One can show that [21]

$$\mathcal{U}_{(2)}(\Delta t) = \mathcal{U}_K(\Delta t/2) \mathcal{U}_V(\Delta t) \mathcal{U}_K(\Delta t/2) \quad (13)$$

reproduces the true evolution operator through order $(\Delta t)^2$. Suzuki has developed a prescription to represent the full evolution operator to arbitrary order [23]. For example,

$$\mathcal{U}_{(4)}(\Delta t) = \mathcal{U}_{(2)}(s\Delta t) \mathcal{U}_{(2)}[(1-2s)\Delta t] \mathcal{U}_{(2)}(s\Delta t), \quad (14)$$

where $s = 1/(2 - 2^{1/3})$. The advantage of Suzuki's approach is that one only needs to construct $\mathcal{U}_{(2)}$ explicitly. $\mathcal{U}_{(2n)}$ is then constructed from appropriate combinations of $\mathcal{U}_{(2n-2)}$.

The generalization of this method to N degrees of freedom and to fields is straightforward. In the latter case, $V[\vec{q}(t)] \rightarrow V[\vec{q}(\vec{x}, t)]$ so that dV/dq becomes the functional

derivative $\delta V/\delta q$. On the computational spatial lattice, the derivatives that are obtained in the expression for the functional derivative must be represented in differenced form. We note that, to preserve n th order accuracy in time, n th order accurate spatial differencing is required. Some discussion of this has been given elsewhere [8].

Convergence studies have been performed to test the algorithm. We have already shown [8] that at any fixed value of τ , there exists a spatial resolution at which every spiky feature is resolved. Any finer resolution will yield identical results. However, as we shall see, generic spiky features grow narrower as the singularity is approached. This means (see [8]) that a spatial resolution which was adequate at some τ_0 will fail to resolve all features at some $\tau_1 > \tau_0$. This type of "resolution dependence" is well understood to be a consequence of the physical behavior of the model. If the physical system has features which become arbitrarily narrow as $\tau \rightarrow \infty$, no resolution will be adequate everywhere for all time.

IV. GOWDY PHENOMENOLOGY

Here we report the results of a numerical study of the evolution of generic Gowdy models toward the singularity ($\tau \rightarrow \infty$). Rather than perform simulations for hundreds of Gowdy models, we consider a single class of models and argue that the observed behavior is generic. For the most part, we shall use the initial data $P = 0$, $\pi_p = v_0 \cos\theta$, $Q = \cos\theta$, and $\pi_Q = 0$. This model is actually generic for the following reasons: The $\cos\theta$ dependence is the smoothest nontrivial possibility. Since we shall discuss the growth of small scale spatial structure, we expect the cleanest effects to arise from the smoothest initial data. A more complicated initial state will not yield any qualitatively new phenomena. For example, choosing $\cos n\theta$ instead yields the same solution repeated n times on the grid thus yielding the same result with poorer resolution. In addition, the amplitude of Q is irrelevant since the Hamiltonian (6) is invariant under $Q \rightarrow \rho Q$, $P \rightarrow P - \ln\rho$ for any constant ρ . This also means that any unpolarized model is qualitatively different from a polarized ($Q = 0$) one no matter how small Q . Traveling waves (subject to $\int d\theta \varphi_\theta = 0$ where φ_θ is the total θ momentum) yield qualitatively similar behavior [24]. We are interested in the spatial structure that can develop from smooth initial data. For this reason, we have used $\cos\theta$ spatial dependence. Starting with a more complicated wave form will yield an eventually more complicated spatial structure but nothing qualitatively different will appear. Similarly, since rescaling Q does not change the solution qualitatively, the amplitude of Q is kept fixed. In this discussion, we shall consider only P and Q and construct λ later if desired.

From the chosen class of initial data, with high spatial resolution, one obtains after some time ($\tau \approx 12$) the profiles for P and Q shown in Fig. 1. The numbered features are typical for any generic solution. The peaks labeled No. 1, No. 2, and No. 3 arise from the same features of the nonlinear interactions. On a finer spatial scale in Fig. 2, we notice that (a) the peak in P is associated with an extremum of Q (which may be a maximum or minimum) and (b) $|\pi_Q|$ becomes large with $\pi_Q < (> 0)$ for a maximum (minimum) in Q . The apparent discontinuity in Q (labeled No. 4 in Fig. 1)

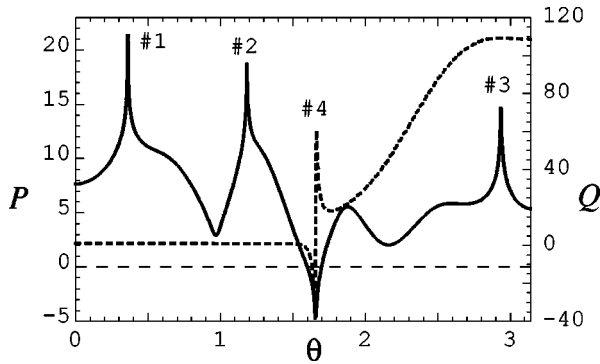


FIG. 1. P (solid line) and Q (dashed line) vs θ at $\tau=12.4$ for the standard initial data set, $P=0$, $\pi_P=v_0 \cos\theta$, $Q=\cos\theta$, $\pi_Q=0$, with $v_0=5$ for $0\leq\theta\leq\pi$. The simulation was run with 20 000 spatial grid points in the interval $0\leq\theta\leq 2\pi$. The numbers on the graph refer to the most interesting features. Peak Nos. 1, 2, and 3 in P are essentially the same in that they occur at extrema (in θ) of Q . (Q has a maximum at the locations of peaks Nos. 1 and 3 and a minimum at No. 2.) Structure No. 4 is qualitatively different in that there appears to be a discontinuity in Q . This occurs where $P<0$ ($P=0$ is shown as a dashed line) and $\pi_Q\approx 0$.

is shown on a finer scale in Fig. 3. We see that this feature occurs as π_Q goes through zero where $P<0$. In Fig. 4, the same features No. 1 and No. 4 are shown at $\tau\approx 18$. We see that the ‘‘spikes’’ have narrowed in θ .

The evolution of P and Q is shown in Fig. 5 (see also [8]) where it is clearly seen that ever shorter wavelength modes develop until the point at which the AVTD behavior sets in. Figure 6 shows an interesting self-similarity in the early evolution. The parameter v_0 in the initial data is varied in a sequence of simulations. In each case, the number of peaks in P is counted after each time step. We find

$$\frac{1}{\tau_N} = a_N(v_0 - \bar{v}_0), \tag{15}$$

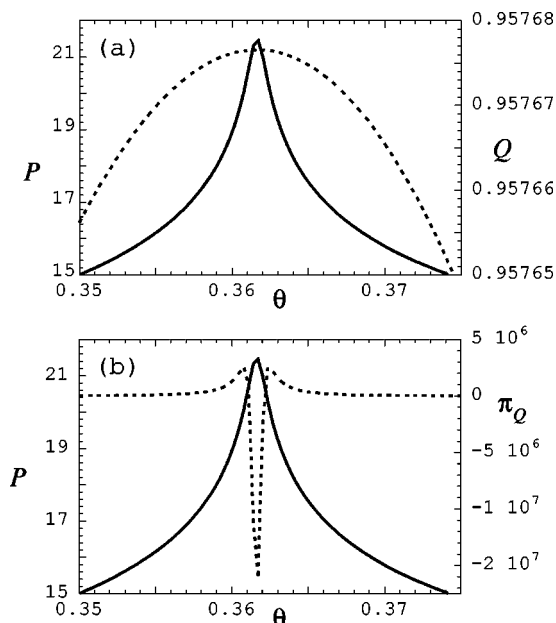


FIG. 2. Details of feature No. 1 in Fig. 1. (a) P (solid line) and Q (dashed line) vs θ near the peak. Note the scales in Q and θ . (b) P (solid line) and π_Q (dashed line) vs θ near the peak.

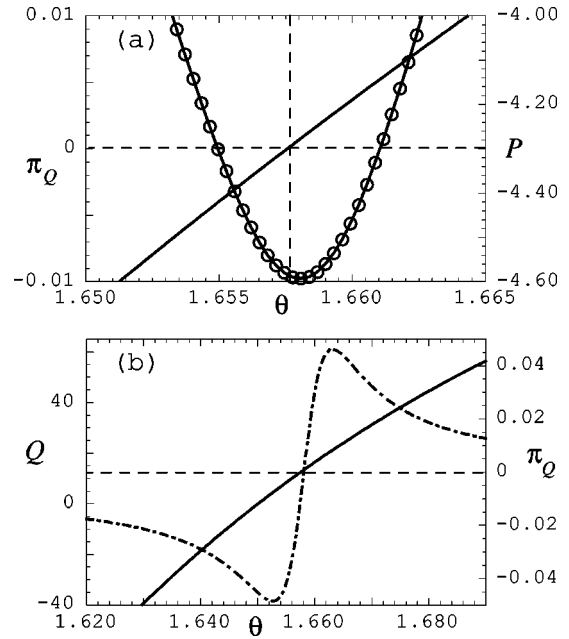


FIG. 3. Details of feature No. 4 in Fig. 1: (a) P (circles) and π_Q (solid line) vs θ . The horizontal dashed line indicates $\pi_Q=0$ while the vertical dashed line marks the θ value at which the π_Q goes through zero. Note the offset between the minimum in P and the zero of π_Q . (b) π_Q (solid line) and Q (dot-dashed line) vs θ near the feature.

where τ_N is the time at which N peaks are first present in the wave form and a_N is a constant. From Eq. (15), \bar{v}_0 denotes the value of v_0 such that the N th peak appears only at $\tau = \infty$. The scaling shown in Fig. 6 is for $N=5$. Similar (but less accurate) straight line fits are found for N equal 3 and 7.

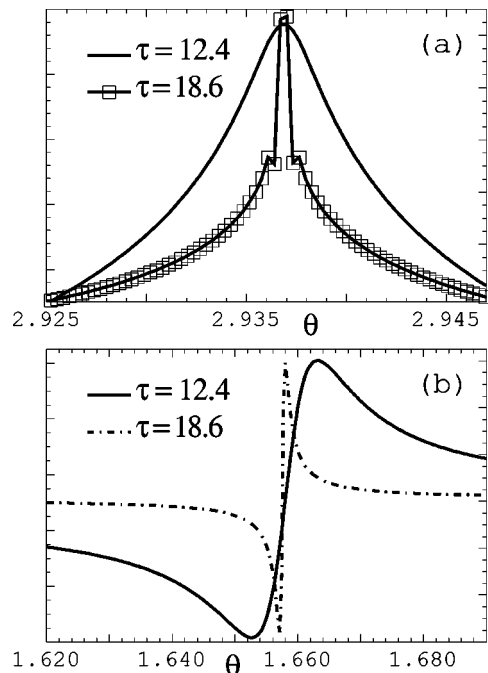


FIG. 4. Evidence for the narrowing of spiky features with increasing τ . (a) P as shown in Fig. 2 is plotted at two different times. (b) Q as shown in Fig. 3 is plotted at two different times. The amplitudes of P and Q have been rescaled for clarity.

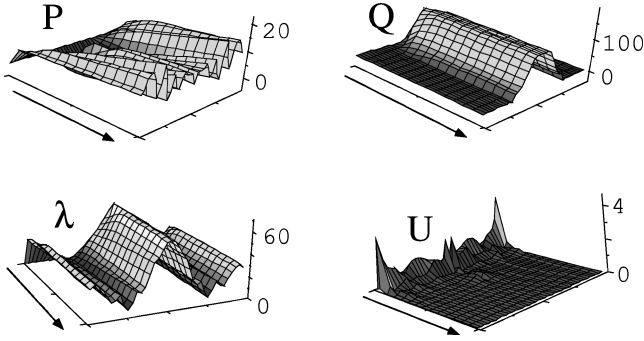


FIG. 5. P , Q , λ , and $U = e^{-2\tau}(P_{,\theta}^2 + e^{2P}Q_{,\theta}^2)$ are shown in the θ - τ plane. The arrow is in the direction of increasing τ .

(The wave equations are even in θ as are the initial data so that P and Q remain even functions of θ . Thus, except for a central peak, other peaks will form two at a time.)

Thus, one may summarize that spatial structure forms more rapidly and evolves a more complicated form, the greater the initial ‘‘energy’’ in the waves as denoted by, e.g., v^2 from Eq. (8). Eventually, the wave forms of P and Q ‘‘freeze’’ to the AVTD behavior of P increasing linearly and Q constant in τ . As has been emphasized by Hern and Stuart (HS) [25], the duration in τ of the observed non-AVTD regime depends on the spatial resolution of the simulation.

In Fig. 7, the maximum value over the spatial grid v_{\max} of the AVTD parameter v is shown as a function of time τ for two simulations with different spatial resolutions. The steps in v_{\max} occur when the location of the spatial point with the maximum value of v changes. Note that, for the lower resolution simulation, v_{\max} eventually falls below unity in support of the GM conjecture [15]. We also see that the higher resolution simulation starts to diverge from the lower resolution one, signaling the presence of narrow features that are unresolved by the coarser resolution. (The former was not run longer primarily because the Courant condition requires small time steps for high resolution studies.) This suggests (as confirmed by HS) that the higher spatial resolution simulation will take longer before it becomes AVTD everywhere. This is shown explicitly in Fig. 8 where $\pi_P > 1$ vs τ is plot-

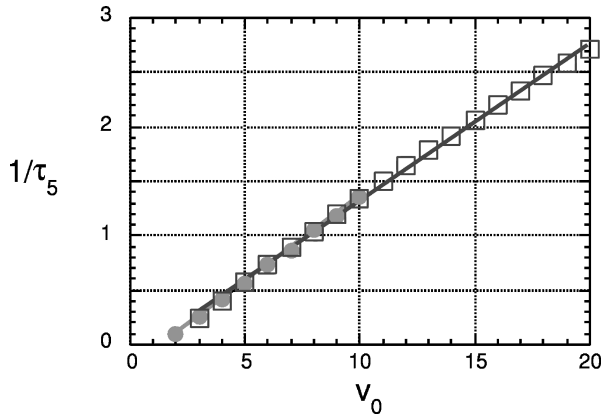


FIG. 6. Scaling in the Gowdy model. Plot of $1/\tau_5$, the inverse of the time at which the fifth peak appears in P vs v_0 . Two cases are shown for initial data $P=0$, $Q=\cos\theta$: (1) $\pi_P = 1/\sqrt{2} v_0 \cos\theta$, $\pi_Q = 1/\sqrt{2} v_0 \cos\theta$ is indicated by filled circles; (2) $\pi_P = v_0 \cos\theta$, $\pi_Q = 0$ is indicated by open squares. The solid line is a linear best fit.

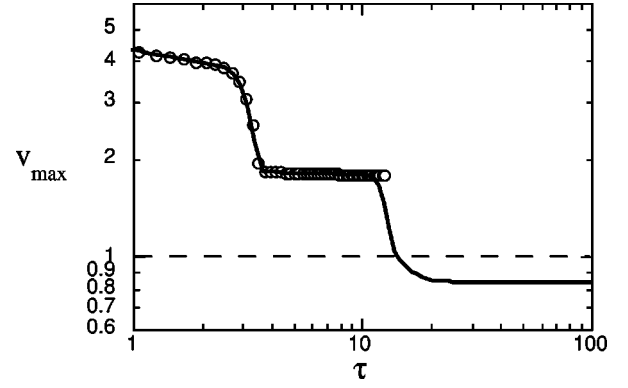


FIG. 7. v_{\max} vs τ for the Gowdy model with $v_0=5$. The solid curve is from a simulation with 3200 spatial grid points while the open circles represent one with 20 000 spatial grid points. The horizontal line is $v_0=1$. The difference near the end of the higher resolution simulation is due to the influence of the nongeneric point where $Q_{,\theta}=0$.

ted for three different spatial resolutions. Note that for two of the spikes, $P_{,\tau}$ is larger for the finest resolution. In Fig. 9, the difference between P/τ and v is plotted vs τ . Since $P \rightarrow v\tau$ as $\tau \rightarrow \infty$, we see the influence of the next (constant in τ) term $P_0 + \ln[(1 + \cos\psi)/2]$, in the AVTD solution for P , Eq. (7).

V. STRUCTURE IN THE GOWDY MODEL

To understand the Gowdy phenomenology of Sec. IV, we must explore the structure of the wave equations for P and Q . Let us consider Eq. (3) first. The equation for Q may be rewritten in first order form as

$$Q_{,\tau} = e^{-2P} \pi_Q,$$

$$\pi_{Q,\tau} = e^{-2\tau}(e^{2P}Q_{,\theta})_{,\theta}. \quad (16)$$

This immediately provides the explanation for both the large central peak which quickly forms in Q and for the apparent discontinuity in Q seen in Figs. 1 and 3. From Eq. (16), Q will grow rapidly where P is negative. Since, early in the evolution, $P \approx v_0 \tau \cos\theta$, one expects a large peak (as is observed in Figs. 1 and 5) where $\cos\theta < 0$. We shall see later that P is driven to positive values eventually stopping the

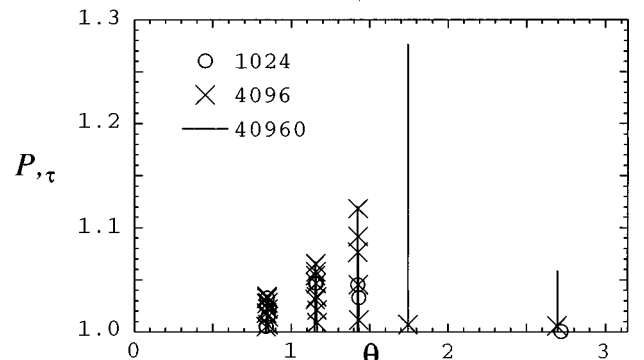


FIG. 8. $P_{,\tau} > 1$ vs θ at $\tau=24.79$ with standard initial data with $v_0=10$ for three spatial resolutions. For the coarser resolutions, all simulation spatial points are shown.

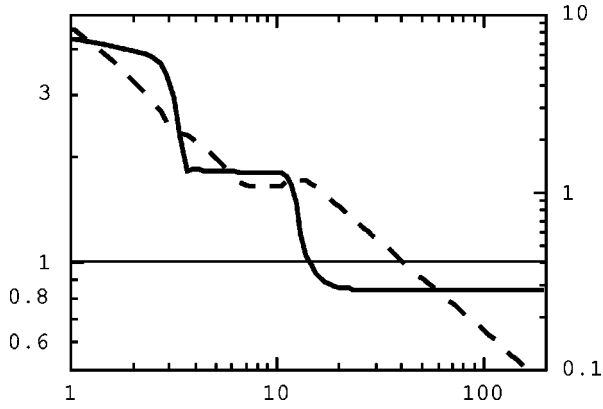


FIG. 9. The same as Fig. 7 with the maximum value of $P/\tau - v$ over the spatial grid also plotted (dashed line) vs τ . The observed behavior is due to the form $P \rightarrow v\tau + \ln[(1 + \cos\psi)/2]$ in the AVTD limit as $\tau \rightarrow \infty$.

growth of Q . However, we shall also see that if $\pi_Q \approx 0$, P can remain negative longer. Say $P \approx -P_0$ for $P_0 > 0$ at a value of $\theta = \theta_1$ where $\pi_Q \approx \pi_Q^0(\theta - \theta_1)$. Thus we find that

$$Q_{,\tau} \approx \pi_Q^0(\theta - \theta_1)e^{2P_0} \quad (17)$$

so that $|Q_{,\tau}|$ is large and Q increases (decreases) exponentially depending (say for $\pi_Q^0 > 0$) on whether $\theta > (<) \theta_1$. Note that we assume $\pi_Q \approx 0$. However, Eq. (16) implies this for P large and negative.

More interesting is the equation for P . Consider two approximate forms of Eq. (2) depending on which nonlinear term dominates. Since the nonlinear terms depend exponentially on P , they will dominate the linear spatial derivative term when the exponential is large.

For example, if P is large and negative,

$$P_{,\tau\tau} - \pi_Q^2 e^{-2P} \approx 0 \quad (18)$$

which has the first integral

$$P_{,\tau}^2 + \pi_Q^2 e^{-2P} = \kappa_1^2. \quad (19)$$

This allows one to define an effective potential

$$V_1 = \pi_Q^2 e^{-2P} \quad (20)$$

which is important when $P_{,\tau} < 0$ and (especially if) $P < 0$. This allows immediate explanation of the following phenomena. (a) In the AVTD regime, $P > 0$ and its asymptotic time derivative $v > 0$ since if $P_{,\tau} < 0$, a bounce off V_1 will occur at which $P_{,\tau} \rightarrow -P_{,\tau}$ so that P will eventually reach positive values. (b) However, if $\pi_Q \approx 0$, $V_1 \approx 0$ so that both P and $P_{,\tau}$ can remain negative for a long time. Nongeneric behavior occurs at the isolated point $\theta = \theta_1$ where V_1 vanishes since P and $P_{,\tau}$ will never be driven to positive values there.

On the other hand, if (a) P is large and positive and (b) $P_{,\tau} > 1$, the wave equation for P is given by

$$P_{,\tau\tau} + e^{2(P-\tau)} Q_{,\theta}^2 \approx 0 \quad (21)$$

which is easy to integrate (for $Z = P - \tau$) as

$$Z_{,\tau}^2 + Q_{,\theta}^2 e^{2Z} = \kappa_2^2. \quad (22)$$

Thus if $P_{,\tau} > 1$, the dynamics of P is dominated by an effective potential

$$V_2 = Q_{,\theta}^2 e^{2(P-\tau)}. \quad (23)$$

Again, from Eq. (16), our implicit assumption that $Q_{,\tau} \approx 0$ is consistent. One sees immediately, that if $P_{,\tau} > 1$ a bounce off V_2 will occur with the result that $Z_{,\tau} \rightarrow -Z_{,\tau}$ or

$$P_{,\tau} \rightarrow -(P_{,\tau} - 2). \quad (24)$$

Thus the existence of V_2 provides a mechanism to drive $P_{,\tau}$ and thus asymptotically v to values below unity. In the actual simulation, the asymptotic regions for the scattering are not reached so that Eq. (24) cannot be used to compute the numerical value of the change in $P_{,\tau}$ with τ . Again one sees that nongeneric behavior can arise, in this case, at $\theta = \theta_2$ where $Q_{,\theta} = 0$. At θ_2 the mechanism to drive v below unity is absent so that larger values of v are allowed. If V_2 is nonvanishing but small, it will take a long time for the bounce to occur so that the AVTD limit will take a long time to arise. This also explains the peaks in P seen in Fig. 1. Where $Q_{,\theta} \approx 0$, V_2 is small so that P can increase without hindrance with a large positive value of $P_{,\tau}$.

For a more quantitative understanding of the small scale spatial structure, note that both Eqs. (18) and (21) have closed form solutions. Equation (18) holds in the AVTD regime, where the solution is given in Eq. (7). The exceptional point θ_1 is the point where $\cos\psi = -1$. Near this point we have $\cos\psi \approx -1 + (\psi')^2(\theta - \theta_1)^2/2$ where $\psi' \equiv \psi_{,\theta}(\theta_1)$. It then follows that, for large τ ,

$$P \approx P_0 - v\tau + \ln[1 + (\psi')^2 e^{2v\tau}(\theta - \theta_1)^2/4],$$

$$Q \approx Q_0 - \frac{e^{-P_0} \psi'(\theta - \theta_1)}{2e^{-2v\tau} + (\psi')^2(\theta - \theta_1)^2/2}. \quad (25)$$

Thus there is a spiky feature in both P and Q at $\theta = \theta_1$ as is shown in Fig. 10. Furthermore, these features steepen exponentially with time. Because of this steepening, the spatial derivatives of P and Q become large at late times. However, the AVTD equations are formed by dropping spatial derivatives from the exact Eqs. (2) and (3). Therefore, one might worry that the terms that have been neglected are not actually negligible near the peaks. However, using Eq. (9) one can show that near $\theta = \theta_1$ the neglected terms go as $e^{2(v-1)\tau}$ and are therefore exponentially damped for $v < 1$.

The solution of Eq. (21) is

$$P = P_0 + \tau - \ln[\cosh w\tau - \cos\phi \sinh w\tau]. \quad (26)$$

Here, $P_0, w \geq 0$, and ϕ are functions of θ , and $Q_{,\theta} = e^{-P_0} w \sin\phi$. Note that $P \rightarrow (1-w)\tau$ for large τ where $\cos\phi \neq 1$. The exceptional point θ_2 is the point where $\cos\phi = 1$. Near this point we have $\cos\phi \approx 1 - (\phi')^2(\theta - \theta_2)^2/2$ where $\phi' \equiv \phi_{,\theta}(\theta_2)$. It then follows that, for large τ ,

$$P \approx P_0 + (1+w)\tau - \ln[1 + (\phi')^2 e^{2w\tau}(\theta - \theta_2)^2/4]. \quad (27)$$

Thus the feature in P narrows exponentially with time as can be seen in Fig. 10. The spatial derivatives of P become very large. However, the neglected terms in the equations go as

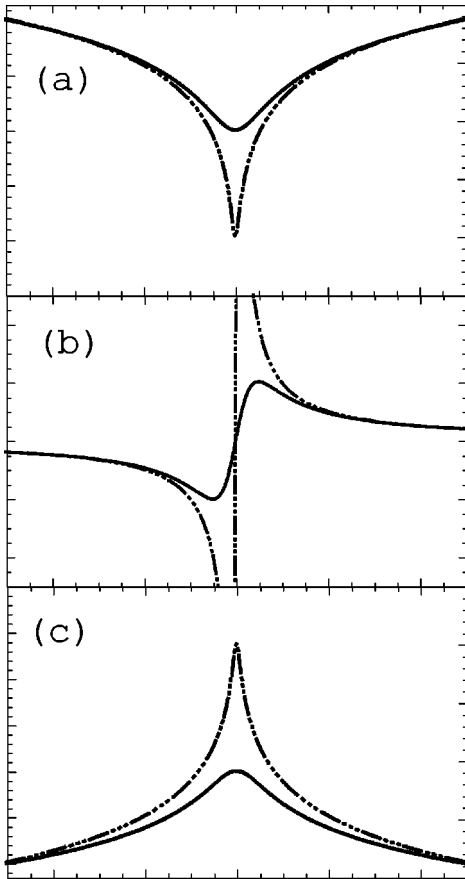


FIG. 10. Sketches of the analytic approximations to the peaks in P and Q . The larger τ value is indicated by the broken line. (a) P from Eq. (25). (b) Q from Eq. (25). (c) P from Eq. (27).

$e^{2(w-1)\tau}$. Since $w-1 < 0$ for $P_{,\tau} > 0$ asymptotically, it follows that these terms become negligible after the last bounce.

The differences in Figs. 7 and 8 seen by increasing the spatial resolution are also understood in terms of our analysis of structure growth. At higher spatial resolution it is more likely that a spatial grid point of the numerical simulation will be very close to a nongeneric point where $Q_{,\theta} = 0$. Thus the nongeneric behavior will become more apparent and the time to reach the AVTD limit characterized by $v < 1$ everywhere will be longer. Clearly, the observed resolution dependence may be interpreted to be evidence for the existence of nongeneric points. The apparent discontinuity in Q seen in Figs. 1 and 3 is evidence for the nongeneric point in θ where $\pi_Q = 0$. Its effect may be seen as a resolution dependence of the shape of this feature. It becomes steeper and narrower with increasing spatial resolution for sufficiently large τ [see Fig. 11(b)] or for increasing τ with fixed spatial resolution [see Fig. 4(b)]. As in Fig. 2, we note that the spikes in Fig. 8 where $v > 1$ are associated with extrema in Q . This is shown in Fig. 12. Note that the alignment is not perfect between the peak in $P_{,\tau}$ and the extremum in Q where the spike is well resolved [see also Fig. 3(a)]. This is understood as evidence that the AVTD regime has not yet been reached. In particular, the site of the extremum may be distorted by a nearby larger feature in Q . Running the simulation twice as long (Fig. 13) shows much closer alignment and is evidence that the predicted nongeneric behavior will eventually dominate the spikes.

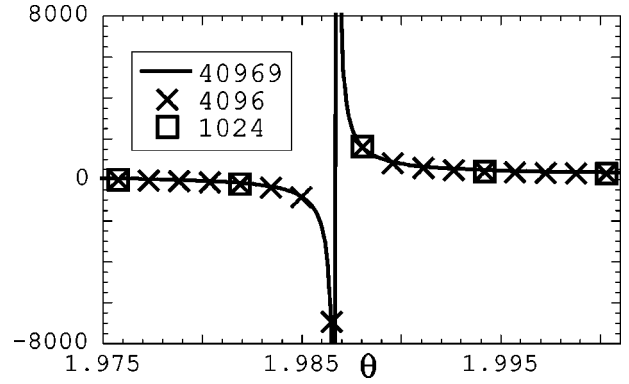


FIG. 11. Q vs θ for $\tau = 24.79$ with $v_0 = 10$ at the site of the apparent discontinuity for three spatial resolutions. At this value of τ , the feature is not resolved even at the finest resolution used.

The effective potentials V_1 and V_2 are displayed in Fig. 14. We see that the approach to the AVTD regime is characterized by repeated alternate interactions of P with the two potentials. This is displayed explicitly for a typical value of θ in Fig. 15 where P , V_1 , and V_2 are shown as functions of τ . After each interaction with V_2 , the quantity $P_{,\tau-1}$ changes sign. If this yields $0 \leq P_{,\tau} < 1$, no further bounces occur. If $P_{,\tau} < 0$, there will be an interaction with V_1 . Eventually, $|P_{,\tau}|$ falls below unity so that V_2 permanently disappears. P then continues to increase for all subsequent τ with constant slope $0 \leq v < 1$ as is characteristic of the AVTD limit. (Note that V_1 will also decrease exponentially as P increases even though it is part of the AVTD solution.) Examination of Eq. (16) shows that, when $|P_{,\tau}|$ falls below unity and $\tau \rightarrow \infty$, $\pi_{Q,\tau} \rightarrow 0$ as required by the AVTD limit. Once π_Q becomes constant, as P increases, $Q_{,\tau} \rightarrow 0$, again as required. The development of Q with time is shown in Fig. 16 for the same value of θ as in the previous figure. Here we see clearly how Q grows fastest when V_1 dominates. This becomes even more dramatic in Fig. 17 which is the same graph for $\theta \approx \theta_1$, the site of the apparent discontinuity in Q .

It is important to emphasize that the magnitude and time evolution of V_1 and V_2 as well as the initial values of the wave amplitude time derivatives are different at different values of θ . This explains the development of complicated small scale spatial structure. From Eqs. (19) or (22), one computes the time to the first bounce off V_1 or V_2 as

$$\Delta\tau = \int_0^{-\ln(\sqrt{V_J^0/\kappa_J})} \frac{d\chi_J}{\kappa_J \sqrt{1 - V_J/\kappa_J^2}}, \quad (28)$$

where $J=1$ or 2 and $V_J^0 = V_J$ at $\tau=0$. Here $\chi_1 = -P$ and $\chi_2 = Z$. Evaluation of Eqs. (19) and (22) at $\tau=0$ yields an approximate inverse scaling with v_0 seen in Fig. 6. The central peak appears first and is easy to understand. Since, initially, $P_{,\tau} = v_0 \cos\theta$, the highest negative velocity occurs at $\theta = \pi$ causing the bounce off V_1 to occur there first. P then begins to increase at $\theta = \pi$ both earlier and faster than at neighboring values of θ . More complicated is the next pair of peaks which occur near $\theta = \pi/4, 7\pi/4$. Initially, the profile of P vs θ steepens. However, bounces off V_2 will begin to occur. This causes the tangent to P vs θ to evolve from negative (positive) to positive (negative) slope for

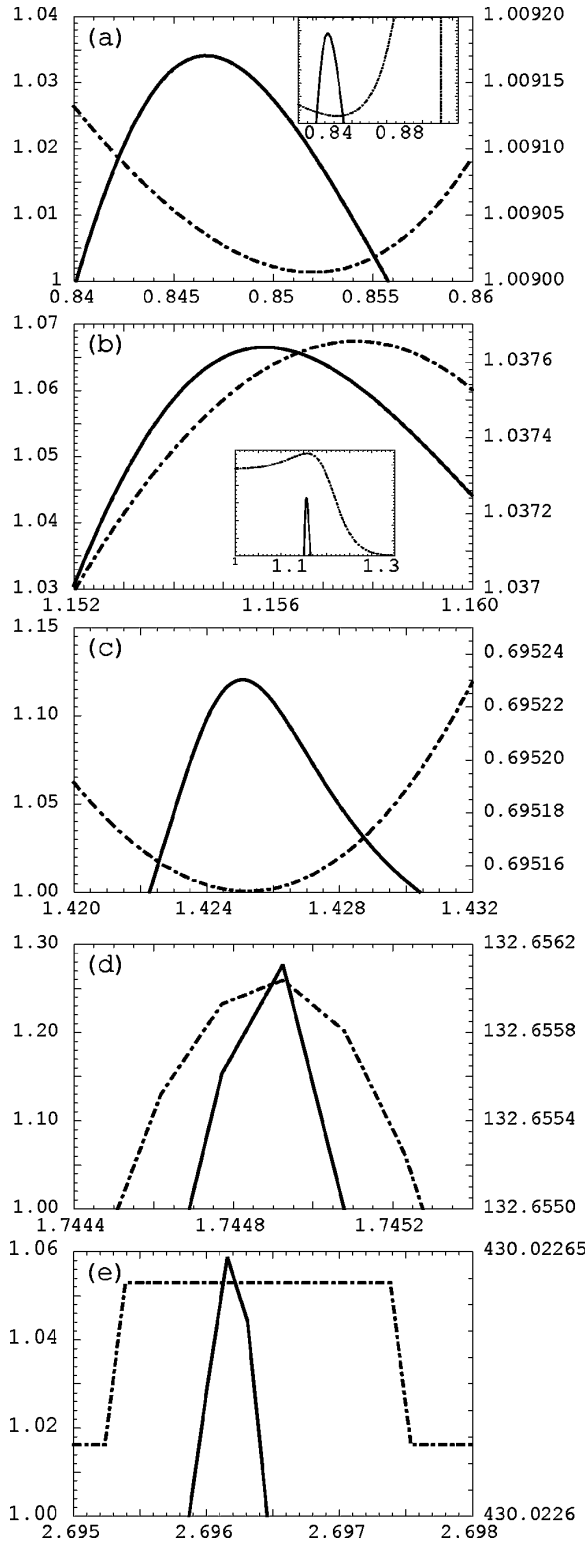


FIG. 12. Details of P (solid line, left axis scale) vs Q (dot-dashed line, right axis scale) for the spikes in Fig. 8. (a) Note that the spike is completely resolved and that there is an offset of the extrema. The inset shows that this peak is part of a larger feature in Q . (b) Again the offset can be related to a larger feature in Q . (c) The extrema are much more closely aligned. (d) The features are not completely resolved. The extrema are aligned to within the resolution. (e) Again the features are not well resolved. The change in the value of Q is the smallest that can be seen in single precision. The simulations were done in double precision but the data was reported in single precision.

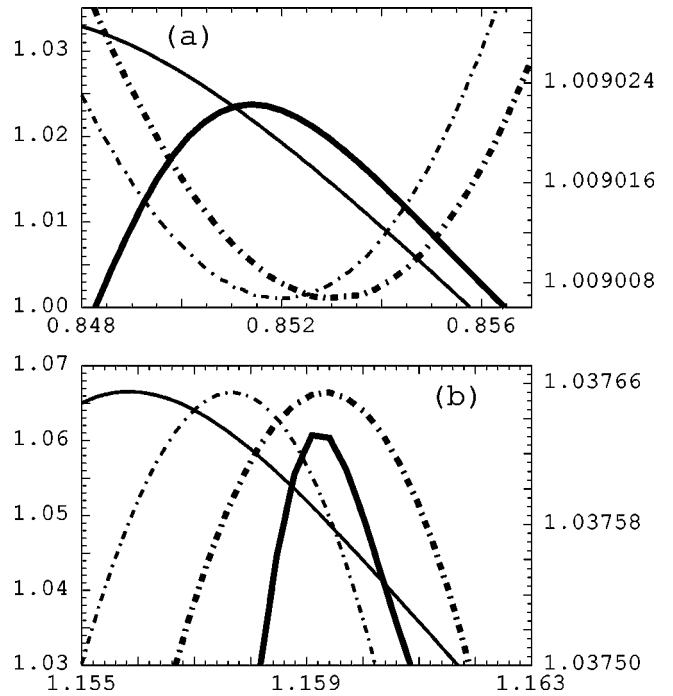


FIG. 13. Spiky features (a) and (b) of P (solid lines, left axis scale) with the associated Q (dot-dashed lines, right axis scale) in Fig. 12 at $\tau=49.5$. Part of the previous figure (at $\tau=24.8$) is shown with finer lines. Note the improvement in alignment and the narrowing of the spike in P .

$0 \leq \theta \leq \pi/2$ ($3\pi/2 \leq \theta \leq 2\pi$) eventually creating a pair of peaks. The higher the original value of v_0 , the greater will be the number of bounces before V_2 disappears for good. Ever finer small scale structures are created at θ values where many bounces occur since P will increase for some spatial regions and decrease for others in a manner that changes with time. As v falls below unity, at a given θ , the bounces, and thus structure formation, will cease there but structure formation will continue in the ever smaller spatial regions where v continues to exceed unity.

VI. DISCUSSION AND CONCLUSIONS

We see that both potentials V_1 and V_2 drive the cosmology toward the AVTD regime characterized by Eq. (7) as $\tau \rightarrow \infty$ with $0 \leq P_{,\tau} \rightarrow v < 1$. This is because V_1 appears and influences the dynamics only when and where $P_{,\tau} < 0$ while V_2 does so only for $P_{,\tau} > 1$. In the AVTD regime, with $0 \leq v < 1$, both corresponding terms in the wave equation for P are exponentially small. We note that the wave equations

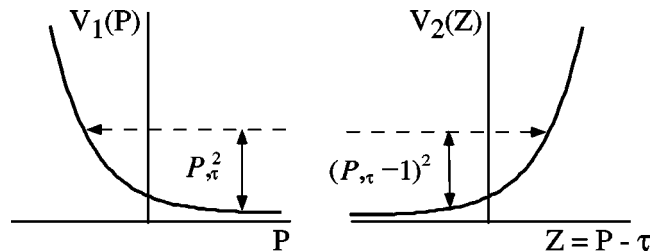


FIG. 14. V_1 vs P and V_2 vs $P - \tau$ shown as solid lines. The horizontal dashed arrows denote the constants κ_1 and κ_2 .

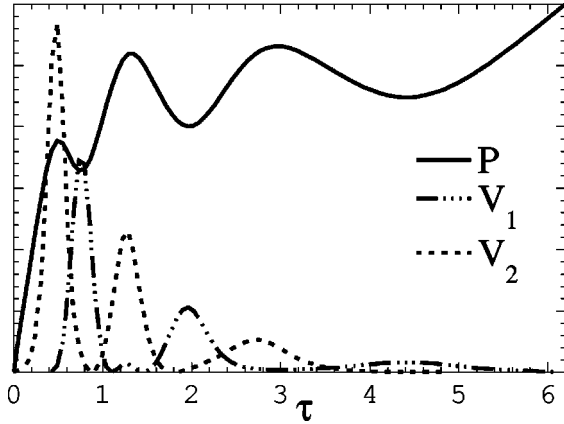


FIG. 15. P (solid curve), V_1 (dash-dotted curve), and V_2 (dashed curve) vs τ at a fixed value of θ .

(2) and (3) provide no other mechanism to drive $P_{,\tau}$ into the required range if it is not there initially. Recall that the polarized Gowdy model can have any value for $P_{,\tau}$. Thus we argue that at isolated points (a set of measure zero in θ) where either π_Q or $Q_{,\theta}$ is precisely zero, $P_{,\tau}$ could remain outside the allowed range. In the former case (say at $\theta = \theta_1$), the consistency equations (9) are satisfied so that one expects the solution at θ_1 to be similar to an AVTD polarized solution. However, in the latter case (say, at $\theta = \theta_2$), the consistency conditions require $Q_{,\theta\theta} = 0$ as well as $Q_{,\theta} = 0$ —something one does not expect generically. If $Q_{,\theta\theta} = 0$ at θ_2 , then the solution is of the AVTD large v type there. If $Q_{,\theta\theta} \neq 0$, the behavior cannot be analyzed either numerically or by these analytic methods. We may therefore conclude that the simulations provide strong support for the conjecture that the Gowdy models have a singularity which is AVTD except, perhaps, at a set of measure zero.

The existence of this set of measure zero of “nongeneric” spatial points can be inferred from the simulations since near them the potentials are very flat. Thus, the closer one is to, e.g., θ_1 or θ_2 defined as above, the longer it will take to drive $P_{,\tau}$ to the range $[0,1)$ there. This manifests itself as a resolution dependence of the simulations of a very specific type. At any value of τ (say $\bar{\tau}$), there is a spatial resolution sufficient to resolve all spiky features. (This was demon-

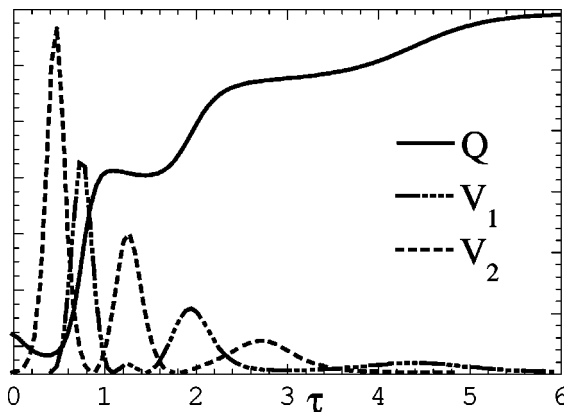


FIG. 16. Q (solid curve), V_1 (dash-dotted curve), and V_2 (dashed curve) vs τ at the same value of θ as in Fig. 15.

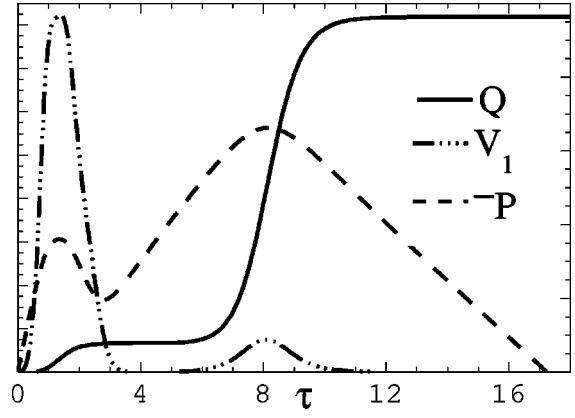


FIG. 17. Q (solid curve), V_1 (dash-dotted curve), and $-P$ (dashed curve) vs τ at the site of feature No. 4 in Fig. 1.

strated in [8].) But the “center” of each spiky feature is the site of a nongeneric point. As one moves away from this point in either direction in θ , the coefficient of the potential will be larger. Thus the interaction with the potential will occur first at regions away from the center of the feature and move closer to the center as τ increases. Since the effect of the interaction is to change the sign of either $P_{,\tau}$ or $P_{,\tau} - 1$, the interactions will tend to eliminate the outer part of the spiky feature. Thus the spiky feature gets narrower in time until for some $\tau > \bar{\tau}$, the original resolution is no longer adequate. Although, in a peak near $Q_{,\theta} = 0$, $P_{,\tau}$ should be > 1 , inadequate resolution may act as an effective averaging to give a measured smaller value of $P_{,\tau}$. Thus the peak in v appears to decrease in amplitude only because, at most θ values, the interaction with V_2 has already occurred. We note that this effective averaging will give $0 \leq v < 1$ everywhere for some τ_F for any fixed spatial resolution. As the spatial resolution is increased, τ_F will also increase since accurate resolution of spiky features can be maintained farther into the simulation and the effective averaging will take longer to come into play. Thus the apparent resolution dependence is consistent with the behavior of the potentials V_1 and V_2 expected near the nongeneric points.

Several examples are shown in Figs. 18–21. In Fig. 18, a spiky feature in $P_{,\tau}$ is shown for three different spatial resolutions at $\tau = 24.79$. While the coarsest resolution shows

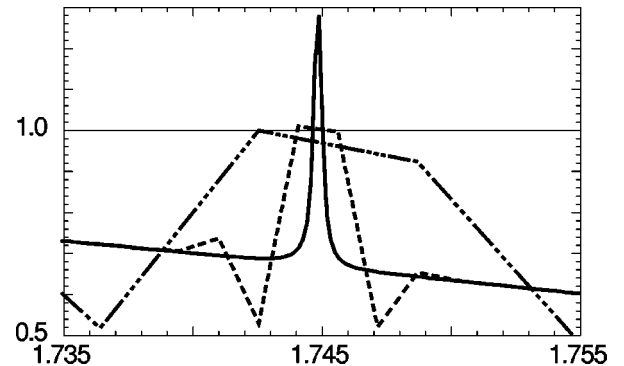


FIG. 18. The same spiky feature in $P_{,\tau}$ vs θ is shown at the same τ for resolutions of 1024 (dash-dotted line), 4096 (dashed line), and 40 960 (solid line) spatial grid points. The horizontal line marks $v = 1$.

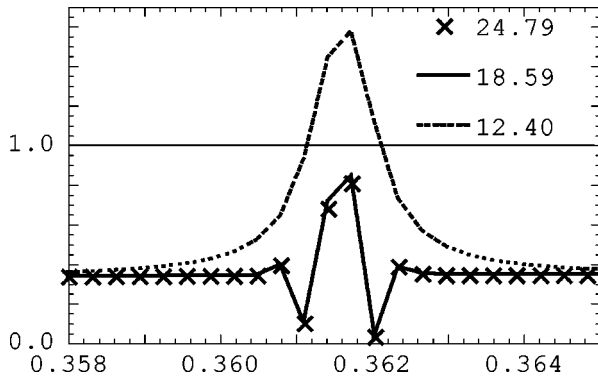


FIG. 19. For a fixed resolution of 20 224 spatial grid points, a spiky feature in P, τ is shown vs θ for three different values of τ .

$v < 1$, it also clearly fails to resolve the spiky feature. The highest resolution both resolves the spiky feature and shows that it has a core where $v > 1$ as expected. A similar spiky feature in P, τ is shown in Fig. 19 for three different times for the same spatial resolution. One expects that the clearly resolved spike observed early in the simulation will narrow as τ increases remaining always > 1 at the center of the peak. This is not observed (rather one sees the constant P, τ behav-

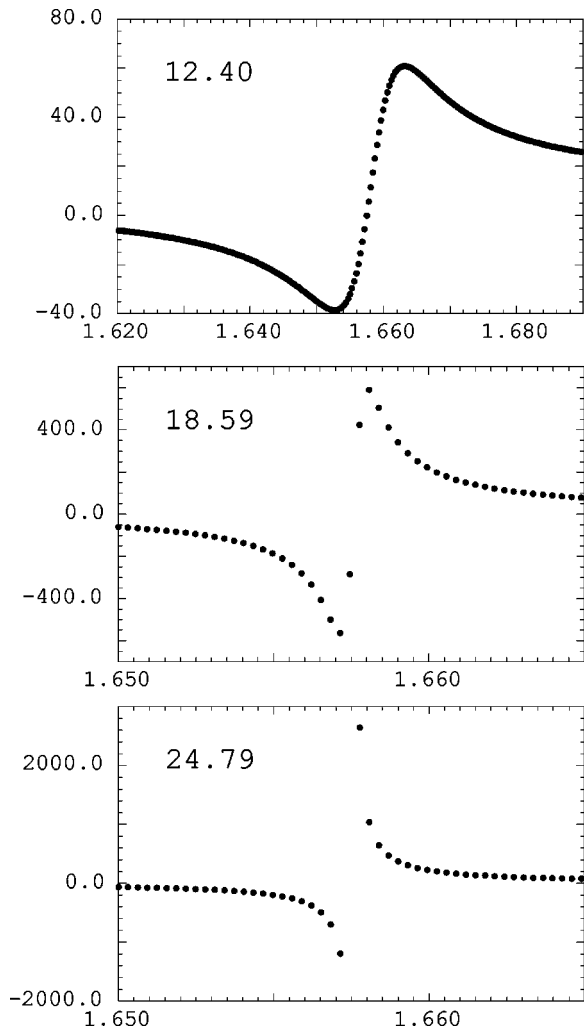


FIG. 20. The apparent discontinuity in Q vs θ at three values of τ with 20 224 spatial grid points.

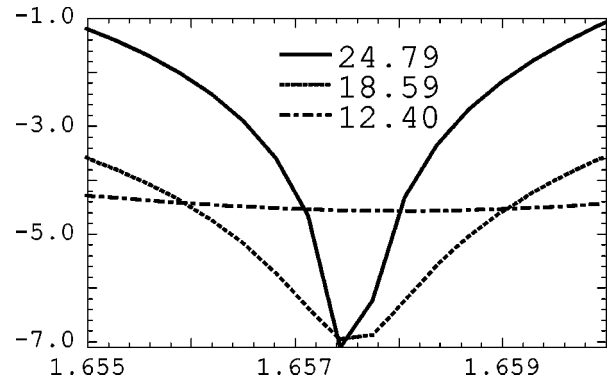


FIG. 21. Part of the region where $P < 0$ vs θ at three values of τ for 20 224 spatial grid points.

ior expected in the AVTD limit). However, one again sees clearly that the spatial resolution which was adequate at $\tau = 12.4$ has become inadequate at later times and that the properties of the spike are not correctly represented. Figure 20 shows that the apparent discontinuity in Q becomes narrower and steeper with time and eventually is not adequately resolved at a given spatial resolution. One expects P to be increasingly negative at the center of this feature since $P, \tau < 0$ is maintained at that nongeneric point. At fixed spatial resolution, we see in Fig. 21 that the negative region of P both narrows and deepens as τ increases from 12.4 to 18.6 as expected. However, at $\tau = 24.8$, the expected behavior is not seen since the depth of the negative region fails to increase. However, we also see that the spatial resolution has become inadequate. Presumably, adequate spatial resolution would show the narrowness and depth of the negative region suggested by the curvature of P vs θ in the region just outside the core.

In conclusion, the behavior of generic Gowdy cosmologies on $T^3 \times R$ can be completely understood in terms of the nonlinear interactions between the two polarizations of the gravitational waves. These act as effective potentials which drive the system to the predicted AVTD behavior and then cease to play a role. At the set of measure zero where the potentials are absent, P, τ may lie outside its allowed AVTD range of $[0, 1)$ for all τ if it does so at any time since the mechanism to correct its value is absent. The existence of this set of measure zero is inferred from the details of the shape and time dependence of the spiky features and from the inability to resolve them with a given spatial resolution beyond a certain time.

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