

Polar gyroscopic tests of general relativity

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Gyroscopic precession at the terrestrial poles is treated using the original Kerr metric in Cartesian coordinates and an isometry method for treating accelerating observers. The results corroborate predictions for gyroscopic precession obtained by gravitomagnetic methods and reinforce recent suggestions that ground-based precession experiments may be viable.

Gyroscopic precession as a test of general relativity (GR) has been an active theoretical topic for a number of years.¹⁻⁴ The well-known results¹ of weak-field GR predict that "geodetic precession" would be modified by the rotation of the Earth, giving a small "motional precession," a gravitomagnetic effect due to "frame dragging."

Since satellite gyro experiments will soon be attempted,⁴ these GR tests are of substantial current interest. Very recently, several authors⁵⁻⁷ have renewed the discussion of ground-based gravitomagnetic experiments, some suggesting terrestrial gyro⁶ and Foucault pendulum⁷ tests of GR. The frame-dragging effects in such environments are predicted to be a half an order of magnitude larger than in orbital experiments, which suggests that ground-based experiments be considered in spite of their extreme technical difficulty.⁵

Here we report precession results obtained using an exact isometry method⁸ for accelerating observers. The Cartesian Kerr⁹ metric avoids coordinate singularities at the poles. Applied to Earth's exterior geometry, the Kerr solution is accurate to first order in $\hat{a} = |\mathbf{J}|/mc$. Higher multipoles make negligible contributions in this precession problem. We calculate exact precession frequencies at the poles for the Kerr portion of Earth's exterior geometry which are in excellent agreement with gravitomagnetic treatments of gyroscopic⁶ and Foucault⁷ precession.

The isometry method⁸ uses an orthonormal (ON) tetrad field rather than a local ON tetrad¹⁰ Fermi-Walker transported along an observer world line $x(\tau)$. This permits simple computations of connection coefficients and "boosted" values for relevant tensors (a^μ , v^μ , and S^μ) for the accelerating observer. The ON tetrad field $K_b^\mu(x)$, and its dual one-form field $K^{-1\mu}_b(x)$, play the role of local rest frames along the observer path $x(\tau)$ for the construction of boost Jacobians for tensors. One first obtains the tetrad components $u_b = K_b^\mu(x)v_\mu$ of the covariant velocity and then uses the spatial components of u_b to form a Lorentz boost matrix $\Lambda^c_d(u)$. The tangent-space boost Jacobians are then formed by similarity transforming into and out of the local ON tetrad (Lorentz) frame, that is, by constructing the inverse Jacobian,

$$J^{-1\mu}_\alpha(x) = K_c^\mu(x)\Lambda^c_d(u)K^{-1,d}_\alpha(x) ,$$

with Λ^{-1} replacing Λ in J . These maps are isometric because $J^T g J = g$ due to the orthonormality relation $K^T g K = \eta = (+ - - -)$ and the O(3,1) isometry $\Lambda^T \eta \Lambda = \eta$. Tensors are then boosted on their contravariant/covariant indices using J^{-1}/J . No change has been made in local coordinate charts but rather a Lorentz-frame change expressed in local coordinate bases.⁸ The boost is easily

shown to be independent of the choice of tetrad field. The Levi-Civita coefficients transform, as does any affine connection, via

$$\bar{\Gamma}^\mu_{\alpha\beta} = J^{-1\mu}_\theta J^\lambda_\alpha J^\sigma_\beta \Gamma^\theta_{\lambda\sigma} + J^{-1\mu}_\theta J^\lambda_\alpha \partial_\lambda J^\theta_\beta .$$

For the polar gyroscope problem, we chose Kerr's original right-handed Cartesian metric⁹ with \mathbf{J} along the $+z$ axis, thus avoiding the coordinate singularities in Boyer-Lindquist¹¹ and isotropic coordinates.¹² At the poles, $|z| = +\rho$ (Boyer-Lindquist) = $+r_0$ (polar radius). A gyro fixed at either pole has covariant velocity

$$v^\mu = (c(\rho^2 + \hat{a}^2)^{1/2}/(\rho^2 + \hat{a}^2 - 2m^*\rho)^{1/2}, 0, 0, 0)$$

with

$$\frac{dt}{d\tau} = (\rho^2 + \hat{a}^2)^{1/2}/(\rho^2 + \hat{a}^2 - 2m^*\rho)^{1/2} ,$$

$m^* = Gm/c^2$, and $\hat{a} = |\mathbf{J}|/mc$.

Polar observers have covariant acceleration

$$\begin{aligned} a^\mu &= (0, 0, 0, \Gamma^3_{00}v^0v^0) \\ &= (0, 0, 0, m^*(\rho^2 - \hat{a}^2)c^2/(\rho^2 + \hat{a}^2)^2) \end{aligned}$$

because $\Gamma^0_{00} = \Gamma^1_{00} = \Gamma^2_{00} = 0$. Note too that $\rho \gg \hat{a} = 329$ cm gives $a^3 \simeq Gm/\rho^2$ as the correct Newtonian limit.

Choosing the timelike tetrad vector as $K^0_\mu = v^\mu/c$ at either pole yields $g(K_b, v) = u_b = 0$ for $b = 1, 2, 3$. Thus the boost is parametrized by $\mathbf{u} = 0$ giving $J = J^{-1} = I$ for any coordinate charts at the poles. Thus tensors are trivially boosted by the identity and the Γ coefficients are unaltered.

The gyroscope spin S^μ satisfies $g(S, v) = 0$ and the Fermi transport law $\nabla S/\partial\tau = dS/d\tau + \Gamma(v, S) = -g(S, a)v/c^2$ in the absence of torques. With $S^0 = 0$ and only $v^0 \neq 0$ we have $dS^1/d\tau + \Gamma^1_{0j}v^0S^j = 0$ along with

$$\nabla S^0/\partial\tau = \Gamma^0_{0j}v^0S^j = -(v^0/c^2)(S^3a_3) . \quad (1)$$

The pertinent Γ coefficients which are nonzero at the poles are

$$\Gamma^0_{03} = m^*(\rho^2 + \hat{a}^2 + 2m^*\rho)(\rho^2 - \hat{a}^2)/(\rho^2 + \hat{a}^2)^3$$

and

$$\Gamma^2_{01} = -\Gamma^2_{02} = 2m^*\rho\hat{a}/(\rho^2 + \hat{a}^2)^2 . \quad (2)$$

Equation (1) holds since $\Gamma^0_{03} = -a^3g_{33}/c^2$ and $g_{33} = -(\rho^2 + \hat{a}^2 + 2m^*\rho)/(\rho^2 + \hat{a}^2)$ at the poles. We also have $dS^3/d\tau = 0$ as expected from axial symmetry since all $\Gamma^3_{0j} = 0$. From Eq. (2) the precession equations for S^1 and S^2 are $dS^1/d\tau = +\Gamma^2_{01}v^0S^2$ and $dS^2/d\tau = -\Gamma^2_{01}v^0S^1$, which

yield the proper-time precession frequency

$$\omega_p = 2m^* \rho \hat{a} c / (\rho^2 + \hat{a}^2)^{3/2} (\rho^2 + \hat{a}^2 - 2m^* \rho)^{1/2}$$

relative to the global right-handed (x^0, x, y, z) coordinate chart (the "fixed stars"). In vector form, with $\rho = |z| \gg \hat{a} \gg m^*$, we have $d\mathbf{S}/d\tau = 2G(\mathbf{S} \times \mathbf{J})/c^2 \rho^3$, which reproduces the "motional precession" result of Schiff.¹ Relative to rotating Cartesian Earth axes (right-handed) at the poles, the proper-time precession frequency is $\tilde{\omega}_p = \omega_p - \omega_E$, where the proper-time rotation frequency ω_E of Earth could be determined astrometrically at the south polar station.⁷

It has been suggested recently^{6,7} that ω_p may be large enough to be measurable, given certain technological im-

provements. We echo this optimism because, upon numerical evaluation of ω_p using $|\mathbf{J}| = 5.9 \times 10^{40}$, $m = 5.98 \times 10^{27}$, and $r_0 = 6.37 \times 10^8$ in cgs units, we obtain the value $\omega_p = 0.22''/\text{yr}$, in excellent agreement with the gravitomagnetic value (0.20''/yr) of Ref. 6 and the Foucault pendulum result (0.218''/yr) of Ref. 7.

While the difficulties⁵ of the terrestrial gyroscopic and Foucault experiments are clearly formidable (if not prohibitive) at present, the terrestrial south polar gravitomagnetic effects are five times larger than expected orbital effects with no competing geodetic effects. Thus serious consideration should be given to the future viability of these delicate and exacting experiments using present and expected technological advances.

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