## Antisymmetric galaxy cross-correlations in and beyond ΛCDM

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Many different techniques to analyze galaxy clustering data and obtain cosmological constraints have been proposed, tested, and used. Given the large amount of data that will be available soon, it is worth investigating new observables and ways to extract information from such datasets. In this paper, we focus on antisymmetric correlations that arise in the cross-correlation of different galaxy populations when the small-scale power spectrum is modulated by a long-wavelength field. In Λ cold dark matter this happens because of nonlinear clustering of sources that trace the underlying matter distribution in different ways. Beyond the standard model, this observable is sourced naturally in various new physics scenarios. We derive, for the first time, its complete expression up to second order in redshift space and show that this improves detectability compared to previous evaluations at first order in real space. Moreover, we explore a few potential applications to use this observable to detect models with vector modes, or where different types of sources respond in different ways to the underlying modulating long mode, and anisotropic models with privileged directions in the sky. This shows how antisymmetric correlations can be a useful tool for testing exotic cosmological models.

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## I. INTRODUCTION

Current and future galaxy surveys are expected to map the large-scale structure (LSS) of the Universe with unprecedented detail, providing us with catalogs of different tracers of the underlying dark matter field. Observing different types of sources will allow for the use of the multitracer approach, which promises to be a winning strategy to beat down cosmic variance [[1](#page-18-0)–[6](#page-18-1)].

Recently, there have been many efforts to improve the available statistical tools for analyzing the LSS, through a more accurate modeling of, e.g., observational, smallscale, and general-relativistic corrections. However, it is also worth investigating completely new avenues, which may both complement existing observables and be better suited to test specific cosmological models. A recently developed observable [[7](#page-18-2)] searches for imprints on the twopoint statistics from primordial fossil fields. These fields could be either scalar, vector, or tensor modes, and they would induce local departures from an otherwise statistically isotropic two-point function.

An extension to this observable has been proposed in [\[8\]](#page-18-3) to exploit the benefits of the multitracer technique: the antisymmetric part of the galaxy cross-correlation, which will be nonvanishing in the presence of two different tracers. If one considers two galaxies drawn from the same population, separated by a distance  $r$ , the two-point autocorrelation function is symmetric under the inversion  $r \mapsto -r$ . But if the two galaxies belong to different populations, with different biasing and evolution properties, then their cross-correlation function may not be symmetric under this exchange. Such an antisymmetric term is generated in standard Λ cold dark matter (ΛCDM), as shown in [[8](#page-18-3)], because of biased nonlinear clustering: it arises from the fact that the two populations trace the dark matter field in different ways, i.e., they have different bias parameters.

An antisymmetric contribution can also arise from exotic new physics, e.g., the presence of vector fields that leave an imprint on the galaxy clustering. This work, starting from the idea sketched in [\[8](#page-18-3)], derives a more complete expression for the antisymmetric part of galaxy correlations, including redshift-space distortions, a more detailed modeling for the galaxy bias, and the effect of primordial non-Gaussianity. Then, for the first time, it investigates the detectability of such an observable by future galaxy surveys. Furthermore, it explores a few possible exotic physics models that could be tested using this new observable.

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### II. ANTISYMMETRIC GALAXY CORRELATION

The two-point correlation function is one of the most widely used summary statistics in large-scale structure surveys. In this context, it is convenient to work in Fourier space (see, e.g., [\[9](#page-18-4)]), where modes are independent and the covariance matrix is diagonal.<sup>1</sup> Alternative approaches are, e.g., the two-point function in configuration space (see, e.g., [\[13](#page-18-5)–[16](#page-18-6)]), spherical-Fourier Bessel decomposition [\[17](#page-18-7)–[20](#page-18-8)], the angular power spectrum [\[21](#page-18-9)–[27](#page-18-10)], and the frequency-angular power spectrum [[10](#page-18-11)–[12\]](#page-18-12).

The two-point autocorrelation function is usually assumed to inherit the properties of statistical homogeneity and isotropy of the Friedmann-Lemaître-Robertson-Walker universe. However, it was pointed out in [[7\]](#page-18-2) that, in principle, the two-point function may depend on the orientation of the two points being correlated and/or on their position in space. Such a signature can be decomposed into scalar, vector, and tensor components, and it can be parametrized as

<span id="page-1-1"></span>
$$
\langle \delta(\mathbf{k}_1)\delta(\mathbf{k}_2)\rangle_h = (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2) P(k_1) + \int \frac{d^3 \mathbf{k}_3}{(2\pi)^3} \sum_p f_p(k_1, k_2, \mathbf{k}_1 \cdot \mathbf{k}_2) h_p^*(\mathbf{k}_3) \epsilon_{ij}^p(\mathbf{k}_3) k_1^i k_2^j (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3). \tag{1}
$$

The second term above is a correlation induced by a perturbation  $h$  with polarization  $p$  and wave vector  $k_3$ , where  $k_3$  is a long-wavelength mode that is modulating the two-point function and  $k_1$ ,  $k_2$  are two short-wavelength modes. The sum on  $p$  runs over the six possible basis tensors for a symmetric tensor. Intuitively, this represents a power spectrum sitting on top of a longwavelength mode, and it is related to the squeezed bispectrum as  $\lim_{k_3 \ll k_1} B_p(k_1, k_2, k_3) = P_p(k_3) f_p(k_1, k_2, k_1)$  $\langle k_2 \rangle \epsilon_{ij}^p(k_3) k_1^i k_2^j$  [\[28](#page-18-13)]. In [[29,](#page-18-14)[30\]](#page-18-15) this formalism has been<br>enplied to study the imprint of primarial fossil fields applied to study the imprint of primordial fossil fields from inflation on the large-scale structure.

In [[8\]](#page-18-3) this parametrization has been generalized to the case of the two-point cross-correlation function, by including the three additional degrees of freedom that are related to the antisymmetric part and, in principle, arise for different tracers

<span id="page-1-0"></span>
$$
\langle \delta_A(\mathbf{k}_1) \delta_B(\mathbf{k}_2) \rangle_h = \int \frac{d^3 \mathbf{k}_3}{(2\pi)^3} \sum_p f_p(k_1, k_2, \mathbf{k}_1 \cdot \mathbf{k}_2) h_p^*(\mathbf{k}_3) \hat{\epsilon}_p
$$

$$
\cdot (\mathbf{k}_1 - \mathbf{k}_2) (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3), \quad (2)
$$

where the sum on  $p$  runs over the three polarizations  $p = L$ , x, y, that is, a longitudinal mode and two vector modes. Choosing  $\hat{\epsilon}_L(k_3) = \hat{k}_3$ , then  $\hat{\epsilon}_{x,y}(k_3)$  are two other unit vectors, orthogonal to  $\hat{k}_3$  and to each other.

No assumption has been made so far on the nature of the long mode that modulates the power spectrum. It could be generated by new physics, and some of these exotic scenarios will be explored in Sec. [V.](#page-10-0) But an antisymmetric contribution to the two-point cross-correlation arises even in pure ΛCDM, due to the nonlinear clustering of biased tracers.

In order to appreciate the underlying physics, it is useful to briefly recall the framework studied in [[8](#page-18-3)]. The abundance of tracers is, in general, a nonlinear function of the local mass density: for simplicity, let  $\delta_X(\mathbf{x}) = b_X \delta(\mathbf{x}) + b_X \delta(\mathbf{x})$  $c_X[\delta(\mathbf{x})]^2 + \dots$  with  $b_X$  the linear bias parameter and  $c_X$  the nonlinear bias parameter [\[31\]](#page-18-16). Such a nonlinear relation implies a nonvanishing three-point function

$$
\langle \delta_A(\mathbf{k}_1) \delta_B(\mathbf{k}_2) \delta(\mathbf{k}_3) \rangle = 2P(k_3)[b_A c_B P(k_1) + b_B c_A P(k_2)]
$$
  
 
$$
\times (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3). \tag{3}
$$

After antisymmetrization in  $k_1 \leftrightarrow k_2$ , and after taking the squeezed limit  $k_1, k_2 \gg k_3$ ,

$$
\frac{B^{A}(k_{1},k_{3})}{P(k_{3})} = (b_{B}c_{A} - b_{A}c_{B})\frac{\partial P(k_{1})}{\partial k_{1}}\frac{k_{1} \cdot k_{3}}{k_{1}}.
$$
 (4)

This sources the antisymmetric part of the modulation of the two-point function due to nonlinear biased clustering as

$$
\frac{\langle \delta_A(\mathbf{k}_1) \delta_B(\mathbf{k}_2) \rangle - \langle \delta_B(\mathbf{k}_1) \delta_A(\mathbf{k}_2) \rangle}{2}
$$
  
= 
$$
\int \frac{d^3 \mathbf{k}_3}{(2\pi)^3} \left( \frac{B^{\mathcal{A}}(\mathbf{k}_1, \mathbf{k}_3)}{P(\mathbf{k}_3)} \right) \delta^*(\mathbf{k}_3) (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3).
$$
 (5)

<span id="page-1-2"></span>Comparing to the general parametrization of the two-point function, [\(2\)](#page-1-0) allows one to recognize the presence of a longitudinal mode  $p = L$ , with

$$
f_L = \frac{1}{2} (b_B c_A - b_A c_B) \frac{\partial P(k_1)}{\partial k_1} \frac{k_3}{k_1}.
$$
 (6)

Physically, this signal describes the small-scale clustering of tracers in the presence of a low-pass-filtered density field. In other words, it is related to the power spectrum of the two tracers on top of a long underlying mode,  $k_3$ .

To estimate the impact of this signal compared to the symmetric one, consider the ratio of the antisymmetric part,

<sup>&</sup>lt;sup>1</sup>Assuming certain approximations, namely, the plane-parallel and equal time; for a detailed analysis of this, see recent discussions in [\[10](#page-18-11)–[12\]](#page-18-12).

$$
P^{A} = (b_{B}c_{A} - b_{A}c_{B}) \frac{\partial P(k_{1})}{\partial k_{1}} \delta^{*}(k_{3}) \frac{k_{1} \cdot k_{3}}{k_{1}}, \qquad (7)
$$

to the symmetric part in the squeezed configuration

$$
P^{S} = (b_{B}c_{A} + b_{A}c_{B})\delta^{*}(k_{3})[P(k_{1}) + P(k_{2})]
$$
  
\n
$$
\simeq (b_{B}c_{A} + b_{A}c_{B})2\delta^{*}(k_{3})P(k_{1})
$$
  
\n
$$
\times \left(1 + \frac{1}{2P(k_{1})}\frac{\partial P(k_{1})}{\partial k_{1}}\frac{k_{1} \cdot k_{3}}{k_{1}}\right),
$$
\n(8)

which gives

$$
\frac{P^A}{P^S} = \frac{(b_B c_A - b_A c_B)}{(b_B c_A + b_A c_B)} \frac{1}{2P(k_1)} \frac{\partial P(k_1)}{\partial k_1} \frac{k_1 \cdot k_3}{k_1} + \mathcal{O}(k_3^2). \tag{9}
$$

Since  $k_1$  are small-scale modes,  $P(k_1)$  can be taken to be a power law  $P(k_1) \propto k_1^n$  with  $n \simeq -3$ . Then, an approximate estimate will be estimate will be

$$
\frac{P^{A}}{P^{S}} = \frac{(b_{B}c_{A} - b_{A}c_{B})}{(b_{B}c_{A} + b_{A}c_{B})} \frac{n k_{3}}{2 k_{1}}.
$$
 (10)

The ratio is therefore suppressed as  $k_3/k_1$ ; however, it could be that, for a particular combination of the bias parameters, the bias-dependent prefactor boosts the signal.

An improved, more detailed modeling of the signal must include the full second-order kernels, containing the physics of gravitational evolution and nonlinear clustering, as well as a more accurate modeling of the bias, with the full basis of bias operators beyond the local-in-matter density expansion up to second order [\[31\]](#page-18-16). The rest of the paper derives such an expression and argues that not only will it be more correct, but it will also improve its detectability.

#### A. Redshift-space distortions

<span id="page-2-0"></span>Observations do not happen in real space, but in the socalled "observed" space, where one has to account for all the light cone and perturbation effects; this is commonly called redshift space when accounting for the (generally) dominant redshift-space distortions (RSDs) caused by peculiar velocities. In this case, the clustering pattern of objects is modified by peculiar velocities [[32](#page-18-17),[33\]](#page-18-18). Since they are sensitive to the line-of-sight component of peculiar velocities, RSDs are a radial effect, and for the case of interest, there is no transverse vector perturbation that can feed the  $p = x, y$  polarizations. Therefore, the expression for the antisymmetric cross-correlation will still contain the L polarization only, but it will be enriched by additional contributions.

Up to second order in fluctuations, one can write the density contrast of the Xth tracer as

$$
\delta_X(\mathbf{k}) = Z_1^X(\mathbf{k})\delta(\mathbf{k}) + \int \frac{d^3\mathbf{p} d^3\mathbf{q}}{(2\pi)^3} \delta^{(3)}(\mathbf{k} - \mathbf{p} - \mathbf{q}) Z_2^X(\mathbf{p}, \mathbf{q}) \delta(\mathbf{p}) \delta(\mathbf{q}), \quad (11)
$$

where  $Z_{1,2}$  are the first- and second-order kernels.

The observable of interest here will require the calculation of both the two- (power spectrum) and three-point (bispectrum) statistics. The bispectrum is

$$
\langle \delta_{s,A}(\mathbf{k}_1) \delta_{s,B}(\mathbf{k}_2) \delta_s(\mathbf{k}_3) \rangle = 2 \{ P(k_1) P(k_2) Z_1^A(\mathbf{k}_1) Z_1^B(\mathbf{k}_2) Z_2(-\mathbf{k}_1, -\mathbf{k}_2) + P(k_2) P(k_3) Z_2^A(-\mathbf{k}_2, -\mathbf{k}_3) Z_1^B(\mathbf{k}_2) Z_1(\mathbf{k}_3) + P(k_1) P(k_3) Z_1^A(\mathbf{k}_1) Z_2^B(-\mathbf{k}_1, -\mathbf{k}_3) Z_1(\mathbf{k}_3) \} (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3). \tag{12}
$$

In order to calculate the expression for the RSD operator, connecting real- to redshift-space observables, one has to compute the Jacobian of the transformation. The calculation can be found in literature (see, e.g., [[13](#page-18-5),[33](#page-18-18),[34](#page-18-19)]) and it reads

$$
1 + \delta_s(\mathbf{s}) = [1 + \delta(\mathbf{r})] \left(1 + \frac{\partial v_r}{\partial r}\right)^{-1} \left(1 + \frac{v_r}{r}\right)^{-2} \frac{\bar{n}(\mathbf{r})}{\bar{n}(\mathbf{r} + v_r(\mathbf{r})\hat{\mathbf{r}})}.
$$
(13)

<span id="page-2-2"></span><span id="page-2-1"></span>The relation between redshift space and real space is  $s = r + v_r(r)\hat{r}$ , with  $v_r = v \cdot \hat{r}/(aH)$ , and  $\bar{n}$  is the average number density of tracers. Keeping all terms, one obtains, to second order,

$$
\delta_s \simeq \delta - \frac{1}{\mathcal{H}} \partial_r v - \frac{\alpha v}{\mathcal{H}r} + \frac{1}{2\mathcal{H}^2} \partial_r^2 v^2 - \frac{1}{\mathcal{H}} \partial_r (\delta v) - \frac{\alpha \delta v}{\mathcal{H}r} + \frac{(\alpha(\alpha - 2) - \gamma)v^2}{\mathcal{H}^2 r^2} + \frac{1}{\mathcal{H}^2} \partial_r \left(\frac{\alpha v^2}{r}\right),\tag{14}
$$

$$
\alpha = \frac{r}{\bar{n}} \frac{\partial \bar{n}}{\partial r} + 2, \qquad \gamma \equiv \frac{r^2}{2\bar{n}} \nabla^2 \bar{n} - 3.
$$
\n(15)

Neglecting the Doppler term  $v/r$  and selection effects,<sup>2</sup> the relation between redshift- and real-space density perturbation becomes

 $2^2$ For the results in this work, the effects of the Doppler term are neglected, as it generally dominates only on large scales, while the antisymmetric correlation has most of its signal on small scales. A more detailed investigation of the impact of Doppler and other terms on the antisymmetric correlation is undergoing. The complete kernel expressions are reported in Appendix [A](#page-14-0).

$$
\delta_s \simeq \delta - \frac{1}{\mathcal{H}} \partial_r v + \frac{1}{2\mathcal{H}^2} \partial_r^2 v^2 - \frac{1}{\mathcal{H}} \partial_r (\delta v). \tag{16}
$$

The objects being correlated are biased tracers of the underlying dark matter distribution. The relation between the two can be described through the bias expansion [\[35\]](#page-18-20)

$$
\delta_g = b_1 \delta + \frac{b_2}{2} \delta^2 + b_{K^2} K^2, \qquad K_{ij} = \left(\frac{\partial_i \partial_j}{\nabla^2} - \frac{1}{3} \delta_{ij}\right) \delta. \tag{17}
$$

The second-order gravitational evolution kernels  $F_2$  and  $G_2$  in an Einstein–de Sitter cosmology are

$$
F_2(\boldsymbol{p}, \boldsymbol{q}) = \frac{5}{7} + \frac{2}{7} \frac{(\boldsymbol{p} \cdot \boldsymbol{q})^2}{p^2 q^2} + \frac{\boldsymbol{p} \cdot \boldsymbol{q}}{2pq} \left(\frac{p}{q} + \frac{q}{p}\right), \quad (18)
$$

$$
G_2(p,q) = \frac{3}{7} + \frac{4}{7} \frac{(p \cdot q)^2}{p^2 q^2} + \frac{p \cdot q}{2pq} \left(\frac{p}{q} + \frac{q}{p}\right).
$$
 (19)

The first- and second-order redshift-space kernels for biased tracers are, in Fourier space,

$$
Z_1(k) = b_1 + f\mu^2, \tag{20}
$$

$$
Z_2(\boldsymbol{p}, \boldsymbol{q}) = \frac{b_2}{2} + b_1 F_2(\boldsymbol{p}, \boldsymbol{q}) + b_{K^2} \left(\mu_{pq}^2 - \frac{1}{3}\right) + f \mu^2 G_2(\boldsymbol{p}, \boldsymbol{q}) + \frac{k \mu f}{2} \left(\frac{\mu_p}{p} (b_1 + f \mu_q^2) + \frac{\mu_q}{q} (b_1 + f \mu_p^2)\right). \tag{21}
$$

The Dirac delta in the convolution enforces that  $k = p + q$ . The cosines of the angles between wave vectors and the line of sight are  $\mu = \mathbf{k} \cdot \hat{\mathbf{n}}/k$ , and the cosine of the angle between the two wave vectors is  $\mu_{pq} = \mathbf{p} \cdot \mathbf{q}/(pq)$ .

<span id="page-3-0"></span>Following the same procedure as above, the antisymmetric part of the cross-power spectrum will be sourced by the antisymmetrized bispectrum in the squeezed regime because the *n*-point function gets modulated by the  $(n + 1)$ point function with a soft momentum as in Eq. [\(1\),](#page-1-1)

$$
\frac{B^{A}(k_{1},k_{3})}{(1+f\mu_{3}^{2})P(k_{3})} = \frac{1}{42} \left(\frac{k_{3}}{k_{1}}\right) \left\{ 3(b_{1}^{A} - b_{1}^{B})f\mu_{1} \left[ k_{1} \frac{\partial P(k_{1})}{\partial k_{1}} \mu_{13} (7f\mu_{1}^{3} - 14\mu_{13}\mu_{3} + \mu_{1}(4 + 10\mu_{13}^{2} - 7f\mu_{3}^{2})) \right] \n+ 2P(k_{1}) \left( -14f\mu_{1}^{3}\mu_{13} + 7f\mu_{1}^{2}\mu_{3} + 3(3 + 4\mu_{13}^{2})\mu_{3} + \mu_{1}\mu_{13} (-13 - 8\mu_{13}^{2} + 7f\mu_{3}^{2})) \right] \n+ 21(b_{2}^{A} - b_{2}^{B})f\mu_{1} \left( k_{1} \frac{\partial P(k_{1})}{\partial k_{1}} \mu_{1}\mu_{13} + 2P(k_{1}) \left( -\mu_{1}\mu_{13} + \mu_{3} \right) \right) \n+ 14(b_{K^{2}}^{A} - b_{K^{2}}^{B})f\mu_{1} \left( k_{1} \frac{\partial P(k_{1})}{\partial k_{1}} \mu_{1}\mu_{13} (3\mu_{13}^{2} - 1) - 2P(k_{1}) \left( -4\mu_{1}\mu_{13} + 6\mu_{1}\mu_{13}^{3} + \mu_{3} - 3\mu_{13}^{2}\mu_{3} \right) \right) \n- 21(b_{1}^{A}b_{2}^{B} - b_{1}^{B}b_{2}^{A})k_{1} \frac{\partial P(k_{1})}{\partial k_{1}} \mu_{13} \n+ 14(b_{1}^{A}b_{K^{2}}^{B} - b_{1}^{B}b_{K^{2}}^{A})\mu_{13} \left( 6P(k_{1}) (\mu_{13}^{2} - 1) + k_{1} \frac{\partial P(k_{1})}{\partial k_{1}} (1 - 3\mu_{13}^{2}) \right) \right\}.
$$
\n(22)

This is related to the antisymmetric component of the two-point function  $B^{A}(k_1, k_2, k_3) = P(k_3)f^{A}_{p}(k_1, k_3)\hat{\epsilon}_p$ <br>  $(k_1 - k_2)$  with the long mode power spectrum  $P(k_2)$  $\cdot$ ( $k_1 - k_2$ ), with the long mode power spectrum  $P(k_3) =$  $(1+f\mu_3^2)P(k_3).$  Comparing w

Comparing with the general parametrization of Eq. [\(2\)](#page-1-0), only the longitudinal vector mode is present  $\hat{\epsilon}_L(k_3) = \hat{k}_3$ ,<br>as expected Indeed, as RSDs are a radial effect, there is no as expected. Indeed, as RSDs are a radial effect, there is no physics that can excite the transverse vector modes.

Notice that, when including RSDs, the signal is nonvanishing even in the case of purely linear bias. In particular, keeping RSDs and linear bias only, the surviving signal from Eq. [\(22\)](#page-3-0) would be

<span id="page-3-1"></span>
$$
\frac{1}{2}\left(\frac{k_3}{k_1}\right)(b_1^A - b_1^B)P(k_1)f^2\mu_1^2 \left[2(-2\mu_1^2\mu_{13} + \mu_1\mu_3 + \mu_{13}\mu_3^2) + \mu_{13}(\mu_1^2 - \mu_3^2)\frac{\partial \log P(k_1)}{\partial \log k_1}\right].
$$
\n(23)

This surviving contribution can be read as follows. The terms from RSDs that are only sensitive to gravity cancel out because of the equivalence principle, but mixed contributions that also contain the bias parameters do survive in the multitracer approach.

The antisymmetric cross-correlation is sensitive to the separation of scales between long- and short-wavelength modes; this is transparent in Eq. [\(6\),](#page-1-2) where the signal is directly proportional to the squeezing factor  $k_3/k_1$ . In the simple case of not modeling higher-order effects that enter when the squeezing factor is reduced, this is unavoidably an arbitrary choice that depends on the details of the analysis and on the specifications of the survey. An attempt to reduce this issue and model the full signal including the case of squeezing factor reduction is currently under development. For now, as a benchmark, the rest of the work uses a squeezing factor of at least 10 between long and short modes; more details on this issue, and how the signal depends on it, will be addressed later.

### B. Primordial non-Gaussianity

Given the nature of antisymmetric correlations and the fact that it is effectively a squeezed bispectrum, it is natural to include the effect of primordial non-Gaussianity (PnG) in its expression. Information about PnG is encoded within higher-order correlations beyond the two-point function, pinpointing interactions of the inflaton with itself or with other fields and thus effectively acting as a particle detector for inflation [[36](#page-18-21)–[38\]](#page-18-22). Single-field models generate negligible non-Gaussianity, whereas multifield inflationary scenarios provide, in general, larger values; for this reason, a measurement of  $f_{\text{NL}} > 1$  would rule out most single-field inflation models [[39](#page-18-23)–[41](#page-18-24)]. The first statistics that is sensitive to deviations from Gaussianity is the bispectrum: its shape dependence is determined by the physical mechanisms at work during inflation, the most common templates being the local shape that peaks on squeezed triangles  $k_3 \ll k_1, k_2$ , the equilateral shape  $k_1 \sim k_2 \sim k_3$ , and the folded shape  $k_1 \sim k_2 \sim k_3/2$  [[42](#page-18-25)].

Cosmic microwave background (CMB) measurements from the *Planck* satellite constrain  $f_{\text{NL}}^{\text{local}} = -0.9 \pm 5.1$ ,<br>  $f_{\text{equil}}^{\text{equil}} = 26 + 47$ , corthoro $-38 + 24$ , of 690% CL 5421.  $f_{\text{NL}}^{\text{equil}} = -26 \pm 47$ ,  $f_{\text{NL}}^{\text{ortho}} = -38 \pm 24$  at 68% CL [[43](#page-18-26)], and improvements are generally expected from large-scale structure measurements. For a review on methodologies and constraints on non-Gaussianity using power-spectrum and bispectrum measurements, see [\[44](#page-19-0)–[46](#page-19-1)] and [[47\]](#page-19-2), respectively, and references therein. More recently, [\[48](#page-19-3)] established  $f_{\text{NL}}^{\text{local}} = -33 \pm 28$  at 68% CL from the BOSS data, a constraint that is expected to improve significantly as future constraint that is expected to improve significantly as future surveys such as SPHEREx [[49](#page-19-4)], which will access larger cosmological volumes. See also [[50](#page-19-5),[51](#page-19-6)] for a discussion on the optimization of surveys to measure PnG.

It is worth noticing that, even with just linear bias, non-Gaussianity can source an antisymmetric signal [\[8\]](#page-18-3). If  $\langle \delta_A(\mathbf{k}_1)\delta_B(\mathbf{k}_2)\delta(\mathbf{k}_3)\rangle = b_1^A(k_1)b_1^B(k_2)B_{\text{grav}}(\mathbf{k}_1,\mathbf{k}_2,\mathbf{k}_3)$ , then

$$
f_L^{A,f_{\rm NL}} \simeq f_{\rm NL} (b_1^A - b_1^B) \frac{3 \delta_{\rm cr} \Omega_{\rm m,0} H_0^2 k_3}{2D_{\rm md}(z) T(k_1) k_1^4} \frac{B_{\rm grav}(k_1, k_2, k_3)}{P(k_3)}.
$$
\n(24)

The bulk of the information for this signal is in the longwavelength modes, then the amplitude decreases for smaller scales, faster than the biased clustering one.

As an indicative example of what could happen for other shapes and early Universe models, alternative scaledependent bias behaviors are presented that are taken to roughly model what would happen for other shapes of PnG. A scale-dependent modification of the bias  $\propto \Delta b_1 k^n$ , with  $n = \{-2, -1, 0\}$  could mimic local, orthogonal, and equilateral shapes, respectively [\[52\]](#page-19-7). In general, if  $b_1^X(k) = b_1^X + f_{\text{NL}} \Delta b_1^X k^n$ , then

$$
f_L^{A,f_{\rm NL}} \simeq \frac{1}{2} f_{\rm NL} (b_1^A \Delta b_1^B - b_1^B \Delta b_1^A) \frac{nk_1^n k_3 B_{\rm grav}(k_1, k_2, k_3)}{2k_1^2}.
$$
\n(25)

The local PnG expression  $n = -2$  is recovered for  $\Delta b_{1}^{X}k^{n} = 3\delta_{\text{cr}}(b_{1}^{X} - 1)\Omega_{\text{m},0}H_{0}^{2}/[D_{\text{md}}(z)T(k)k^{2}].$ <br>An equilateral shape would leave no signature.

An equilateral shape would leave no signature.

This estimate for  $f_L^{A,f_{NL}}$  is obtained by approximating the bispectrum as being simply proportional to the gravitational contribution, via the two linear bias parameters,  $\langle \delta_A(\mathbf{k}_1) \delta_B(\mathbf{k}_2) \delta(\mathbf{k}_3) \rangle = b_1^A(k_1) b_1^B(k_2) B_{\text{grav}}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3)$ . However, this does not capture all the ingredients: the signal needs to be modeled using the full second-order kernels.

In the presence of local-type PnG, the Eulerian basis of operators in the bias expansion is modified by additional terms [[31](#page-18-16)], which at linear level give rise to the well-known scale-dependent bias [[44](#page-19-0)[,53](#page-19-8)–[57\]](#page-19-9). Let  $\phi$  be the Bardeen gravitational potential, related to the primordial curvature perturbation by  $\phi = (3/5)\mathcal{R}$  and to the linear density field by

$$
\delta(\mathbf{k}, \tau) = \mathcal{M}(k, \tau) \phi(\mathbf{k}), \qquad \mathcal{M}(k, \tau) = \frac{2}{3} \frac{k^2 T(k) D_{\text{md}}(z)}{\Omega_{\text{m},0} H_0^2},\tag{26}
$$

where  $D_{\text{md}}(z)$  is the linear growth factor normalized to a during matter domination.

The new operators are  $f_{NL}\phi(q)$  at first order and  $f_{\text{NL}}\delta(x)\phi(q)$  at second order. The Bardeen potential is evaluated at the Lagrangian position  $q$ , since the coupling between non-Gaussianity of primordial fluctuations and matter fluctuations is imprinted in the initial conditions and not induced by evolution. Therefore, these operators get contributions from the (linear-order) displacement field s, given by

$$
x = q + s(q, \tau), \qquad s(q, \tau) = -\frac{\nabla}{\nabla^2} \delta(q, \tau). \tag{27}
$$

The contributions from PnG are

$$
\delta_g(\mathbf{x})|_{f_{\text{NL}}} = f_{\text{NL}} b_{\phi} \phi(\mathbf{q}) + f_{\text{NL}} b_{\phi \delta} \phi(\mathbf{q}) \delta(\mathbf{x}). \quad (28)
$$

When adding RSD, the new terms arise from  $\delta$  and  $\partial_r(\delta v)$ : any effect of  $f_{\text{NL}}$  on velocities can be neglected, because it would be of the same order as higher derivative operators of the form  $\partial^2 \phi$  [[58](#page-19-10)]. Including PnG, thus, the new contributions to the redshift-space kernels in Fourier space are

$$
Z_{1,f_{\rm NL}}(\boldsymbol{k}) = f_{\rm NL} b_{\phi} \mathcal{M}^{-1}(k),\tag{29}
$$

$$
Z_{2,f_{\rm NL}}(\pmb{p},\pmb{q}) = f_{\rm NL} b_{\phi} \frac{\pmb{p} \cdot \pmb{q}}{2} \left( \frac{1}{p^2} \mathcal{M}^{-1}(q) + \frac{1}{q^2} \mathcal{M}^{-1}(p) \right) + f_{\rm NL} b_{\phi \delta} \frac{1}{2} (\mathcal{M}^{-1}(p) + \mathcal{M}^{-1}(q)) + f_{\rm NL} b_{\phi} \frac{k \mu f}{2} \left( \frac{\mu_q}{q} \mathcal{M}^{-1}(p) + \frac{\mu_p}{p} \mathcal{M}^{-1}(q) \right).
$$
(30)

Working at linear order in  $f_{NL}$ , the additional contribution to  $\langle \delta_A(\mathbf{k}_1)\delta_B(\mathbf{k}_2)\delta(\mathbf{k}_3)\rangle$  coming from primordial non-Gaussianity is

$$
2f_{\text{NL}}\{P(k_1)P(k_2)(Z_{1,f_{\text{NL}}}^A(k_1)Z_1^B(k_2)Z_2(-k_1,-k_2)+Z_1^A(k_1)Z_{1,f_{\text{NL}}}^B(k_2)Z_2(-k_1,-k_2)+Z_1^A(k_1)Z_1^B(k_2)Z_{2,f_{\text{NL}}}(-k_1,-k_2))+P(k_1)P(k_3)(Z_{1,f_{\text{NL}}}^A(k_1)Z_2^B(-k_1,-k_3)Z_1(k_3)+Z_1^A(k_1)Z_2^B(-k_1,-k_3)Z_{1,f_{\text{NL}}}(k_3)+Z_1^A(k_1)Z_{2,f_{\text{NL}}}^B(-k_1,-k_3)Z_1(k_3))+P(k_2)P(k_3)(Z_2^A(-k_1,-k_3)Z_{1,f_{\text{NL}}}(k_2)Z_1(k_3)+Z_2^A(-k_2,-k_3)Z_1^B(k_2)Z_{1,f_{\text{NL}}}(k_3)+Z_{2,f_{\text{NL}}}^A(-k_2,-k_3)Z_1^B(k_2)Z_1(k_3))\}. (31)
$$

Antisymmetrizing and taking the squeezed limit, the contributions from non-Gaussianity effects are of order  $(k_3/k_1)^{-1}$ ,  $(k_3/k_1)^0$ ,  $(k_3/k_1)^1$ , and higher order. In the squeezed configuration, the first contribution is expected to be the dominant one,

$$
\frac{B^{A,f_{NL}}(\boldsymbol{k}_{1},\boldsymbol{k}_{3})}{P(k_{3})(1+f\mu_{3}^{2})} = \frac{3f_{NL}H_{0}^{2}\Omega_{m,0}}{4k_{1}k_{3}D_{md}(z)}P(k_{1})\left\{ (b_{\phi}^{A}-b_{\phi}^{B})f\mu_{1}^{2}\left[-2(\mu_{13}+2f\mu_{1}^{2}\mu_{13}-f\mu_{1}\mu_{3})+f\mu_{1}^{2}\mu_{13}\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right] + (b_{\phi\delta}^{A}-b_{\phi\delta}^{B})f\mu_{1}\left[-2(\mu_{1}\mu_{13}-\mu_{3})+\mu_{1}\mu_{13}\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right] + (b_{1}^{A}b_{\phi}^{B}-b_{1}^{B}b_{\phi}^{A})\mu_{13}\left[2(1+f\mu_{3}^{2})-f\mu_{1}^{2}\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right] - (b_{1}^{A}b_{\phi\delta}^{B}-b_{1}^{B}b_{\phi\delta}^{A})\mu_{13}\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right].
$$
\n(32)

This is the leading  $f_{NL}$  contribution to the antisymmetric signal from nonlinear biased clustering. The signal, integrated over long modes and over angles, is shown in Fig. [1.](#page-5-0)

<span id="page-5-0"></span>

FIG. 1. Integral over long modes of  $(P^A)^2$ , with biases  $b_1^A = 3$ ,  $b^B - 1$  1. The signal is modeled using full kernels and local-type  $b_1^B = 1.1$ . The signal is modeled using full kernels and local-type<br>PnG as in Eq. (36). This assumes a survey with volume PnG, as in Eq. [\(36\).](#page-6-0) This assumes a survey with volume  $V_s = 100 \text{ (Gpc/h)}^3$ , centered at  $z = 1$ , and galaxy number<br>densities  $v = 10^{-3} \text{ (h/Mpc)}^3$  and  $v = 2v$ densities  $n_{g,A} = 10^{-3} (h/\text{Mpc})^3$  and  $n_{g,B} = 2n_{g,A}$ .

Going beyond local PnG requires the introduction of an additional bias operator [\[31\]](#page-18-16)

$$
\psi(q) = \int \frac{d^3k}{(2\pi)^3} k^\alpha \phi(k) e^{ikq}, \qquad (33)
$$

again evaluated at the Lagrangian position  $q$ . The resulting contributions to the redshift-space kernels in Fourier space are

$$
Z_{1,\text{PhG}}(k) = a_0 b_{\psi} k^{\alpha} \mathcal{M}^{-1}(k),\tag{34}
$$

$$
Z_{2,PhG}(\boldsymbol{p}, \boldsymbol{q}) = a_0 b_{\psi} \frac{\boldsymbol{p} \cdot \boldsymbol{q}}{2} \left( \frac{1}{p^2} q^{\alpha} \mathcal{M}^{-1}(q) + \frac{1}{q^2} p^{\alpha} \mathcal{M}^{-1}(p) \right) + a_0 b_{\psi} \delta \frac{1}{2} (p^{\alpha} \mathcal{M}^{-1}(p) + q^{\alpha} \mathcal{M}^{-1}(q)) + a_0 b_{\psi} \frac{k \mu f}{2} \left( \frac{\mu_q}{q} p^{\alpha} \mathcal{M}^{-1}(p) + \frac{\mu_p}{p} q^{\alpha} \mathcal{M}^{-1}(q) \right).
$$
\n(35)

The local PnG case discussed above is recovered by setting  $\alpha = 0$ ,  $a_0b_\psi = f_{\text{NL}}b_\phi$ , and more details on the PnG bias parameters can be found in Appendix [C.](#page-16-0) Detectability prospects for the local PnG case will be discussed in Sec. [IV B](#page-8-0). A more detailed analysis of the antisymmetric signal and of the detectability prospects for the orthogonal and folded shapes of PnG is of great interest and left for a future work.

## III. ANTISYMMETRIC GALAXY CORRELATION IN REDSHIFT SPACE, INCLUDING PRIMORDIAL NON-GAUSSIANITY

<span id="page-6-0"></span>The full expression, calculated for the first time, for the antisymmetric correlation in redshift space, including second-order bias and primordial non-Gaussianity is given as follows:

$$
\frac{B^{A}(k_{1},k_{3})}{P(k_{3})(1+f\mu_{3}^{2})} = \frac{1}{42} \left(\frac{k_{3}}{k_{1}}\right) P(k_{1}) \left\{ 3(b_{1}^{A} - b_{1}^{B}) f\mu_{1} \left[\frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{13} (7f\mu_{1}^{3} - 14\mu_{13}\mu_{3} + \mu_{1} (4 + 10\mu_{13}^{2} - 7f\mu_{3}^{2})) \right] \n+ 2(-14f\mu_{1}^{3}\mu_{13} + 7f\mu_{1}^{2}\mu_{3} + 3(3 + 4\mu_{13}^{2})\mu_{3} + \mu_{1}\mu_{13} (-13 - 8\mu_{13}^{2} + 7f\mu_{3}^{2})) \right] \n+ 21(b_{2}^{A} - b_{2}^{B}) f\mu_{1} \left(\frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{1}\mu_{13} + 2(-\mu_{1}\mu_{13} + \mu_{3})\right) \n+ 14(b_{K^{2}}^{A} - b_{K^{2}}^{B}) f\mu_{1} \left(\frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{1}\mu_{13} (3\mu_{13}^{2} - 1) - 2(-4\mu_{1}\mu_{13} + 6\mu_{1}\mu_{13}^{3} + \mu_{3} - 3\mu_{13}^{2}\mu_{3})\right) \n- 21(b_{1}^{A}b_{2}^{B} - b_{1}^{B}b_{2}^{A}) \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{13} + 14(b_{1}^{A}b_{K^{2}}^{B} - b_{1}^{B}b_{K^{2}}^{A}) \mu_{13} \left(6(\mu_{13}^{2} - 1) + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} (1 - 3\mu_{13}^{2})\right) \right) \n+ \frac{3f_{NL}H_{0}^{2}\Omega_{m,0}}{4D_{m}(z)k_{1}^{2}T(k_{1})} \frac{1}{42} P(k_{1}) \left\{ (b_{\phi}^{A} - b_{\phi}^{B}) \left[\left(\frac{k_{3}}{k_{
$$

Г

The  $\mathcal{F}(k_1, k_3)$  functions are reported in Appendix [B](#page-15-0). They depend on the angles between long and short modes, and the angles with the line of sight, on derivatives of the power spectrum, and of the transfer functions.

In the remainder of this work, the second-order bias parameters will be obtained from the linear-order ones by means of fitting formulas [[31](#page-18-16)[,59,](#page-19-11)[60\]](#page-19-12), as reported in Appendix [C.](#page-16-0)

### IV. DETECTABILITY

In [[7](#page-18-2)[,8\]](#page-18-3), an estimator was built in order to extract information on the amplitude of the modulating longwavelength field. The procedure aimed to find the minimum detectable amplitude of the power spectrum of the underlying field, in the spirit of seeking for fossil imprints from primordial exotic physics. In principle, this could be generalized to the case of nonlinear biased clustering as well, and the calculation is reported in Appendix [D](#page-17-0). However, for practical purposes, one can take a different approach and build a signal-to-noise ratio estimator, in the same fashion as in [[61](#page-19-13)].

Let  $k_1$ ,  $k_3$  be the short and long mode, respectively. Defining the antisymmetric signal as

$$
P^{\mathcal{A}}(\boldsymbol{k}, \boldsymbol{K}) \equiv \frac{1}{2} [\delta_{A}(\boldsymbol{k}) \delta_{B}(\boldsymbol{K} - \boldsymbol{k}) - \delta_{A}(\boldsymbol{K} - \boldsymbol{k}) \delta_{B}(\boldsymbol{k})], \qquad (37)
$$

at fixed long mode  $K$ , the covariance in the null hypothesis is

$$
Cov(k, k')_K = \frac{1}{2} [P_{AA}(k)P_{BB}(k) - P_{AB}(k)P_{AB}(k)]
$$
  
 
$$
\times [\delta_{k+k'}^D - \delta_{k-k'}^D].
$$
 (38)

This matrix is not invertible; however, following the same steps as [\[62\]](#page-19-14), one can notice that  $P^{A}(-k) = -P^{A}(k)$  and therefore consider only one hemisphere in  $k$  space and combine the contribution from both  $k$  and  $-k$  modes,

$$
[\langle P^{\mathcal{A}}(\boldsymbol{k})^2 \rangle - \langle P^{\mathcal{A}}(\boldsymbol{k}) \rangle^2] - [\langle P^{\mathcal{A}}(\boldsymbol{k}) P^{\mathcal{A}}(-\boldsymbol{k}) \rangle - \langle P^{\mathcal{A}}(\boldsymbol{k}) \rangle \langle P^{\mathcal{A}}(-\boldsymbol{k}) \rangle]. \tag{39}
$$

<span id="page-7-2"></span>The covariance on the emisphere is

Cov<sup>emi</sup>(**k**, **K**) = 
$$
\frac{1}{2}
$$
 [ $P_{AA}(k)P_{BB}(|K - k|)$   
+  $P_{AA}(|K - k|)$ ) $P_{BB}(k)$ ]  
-  $P_{AB}(k)P_{AB}(|K - k|)$ . (40)

The signal depends on the short mode  $k$ , the long mode  $K$ , and the angle between them. First, one has to integrate over the long modes: in this work, the long modes and short modes are chosen in such a way that they are separated by at least an order of magnitude, that is, the minimum squeezing factor is set to 10, so that there is a hierarchy  $K < K_{\text{max}} \ll k_{\text{min}} < k$ . As anticipated in Sec. [II](#page-2-0) [A,](#page-2-0) the SNR unavoidably depends on the arbitrary choice of squeezing factor. $3$  Of course, the smaller the squeezing factor, the more triangular configurations will enter in the integral, and the larger the SNR; however, on the other hand, the formal derivation has been made in the  $K \ll k$ limit, therefore one should be careful in including configurations that are not "squeezed enough." There has been recently a study in the context of intensity mapping reconstruction [[64](#page-19-15)] that investigates how to deal with this issue by keeping higher-order terms. While that approach will be useful when trying to extract the full signal in the antisymmetric case, for the current purposes here a simpler procedure will be adopted, adding by hand a squeezing factor.

Each pair of short modes  $k_1$ ,  $k_2$  is sensitive to the modulation induced by a long mode  $K = k_1 + k_2$ , therefore the minimum accessible long mode  $K_{\text{min}}$  is taken to be of the order the fundamental wave number of the survey  $k_f = 2\pi/V_s^{1/3}$ . In order to restrict to squeezed configurations only, for a given short mode  $k$  the corresponding maximum long mode is  $K_{\text{max}} = k/10$ . The short modes will span from  $k_{\text{min}} \gtrsim 10k_f$  to some  $k_{\text{max}}$ .

The angles between the line-of-sight direction and the short-wavelength wave vector  $k_1$  are described by  $\mu_1 = \cos \theta_1$  and  $\phi_1$ , while the ones describing the longwavelength wave vector **K** are  $\mu = \cos \theta$  and  $\phi$ .

The signal is  $P^{A}(k, K) = (B^{A}(k, K)/P(K))\delta(K)$ . When including RSD, the long mode power spectrum is  $P(K) = (1 + f\mu_3^2)P(K)$ . The SNR(k) is obtained integrat-<br>ing the signal squared  $S^2 - (P^A)^2$  over the noise ing the signal squared  $S^2 = (P^A)^2$  over the noise  $N^2 = \text{Cov}^{\text{emi}}$ , on the corresponding range of long modes for each  $k_1$ , that is,

<span id="page-7-0"></span>
$$
\left(\frac{S}{N}\right)_k^2 = \int_{k_f}^{k_1/10} \frac{K^2 dK}{(2\pi)^3} \int_{-1}^{+1} d\mu \int_0^{2\pi} d\phi \frac{1}{\text{Cov}^{\text{emi}}(\boldsymbol{k}, \boldsymbol{K})} \times \left(\frac{B^{\text{A}}(\boldsymbol{k}, \boldsymbol{K})}{P(\boldsymbol{K})}\right)^2 P(\boldsymbol{K}).
$$
\n(41)

<span id="page-7-1"></span>Then, integrating over short modes as well,

$$
\left(\frac{S}{N}\right)^{2} = \frac{V_{s}}{(2\pi)^{3}} \int_{k_{f}}^{k_{\max}} k^{2} dk \int_{0}^{2\pi} d\phi_{1} \int_{0}^{1} d\mu_{1}
$$
\n
$$
\times \left\{ \int_{k_{f}}^{k_{1}/10} \frac{k^{2} dK}{(2\pi)^{3}} \int_{-1}^{+1} d\mu \right\}
$$
\n
$$
\times \int_{0}^{2\pi} d\phi \frac{1}{\text{Cov}^{\text{emi}}(\mathbf{k}, \mathbf{K})} \left(\frac{B^{A}(\mathbf{k}, \mathbf{K})}{P(\mathbf{K})}\right)^{2} P(\mathbf{K}) \right\},\tag{42}
$$

where now  $k_{\min} = k_f$  is set by the volume of the survey and  $k_{\text{max}}$  is the minimum scale for the analysis. Notice that the integration over angles covers only the emisphere in  $k$  space.

Figure [2](#page-8-1) shows the SNR for nonlinear biased clustering. It is shown both as a function of  $k_1$  after integrating over the long modes K and as a function of the maximum  $k_{\text{max}}$  of the analysis after integrating over  $k$  as well. Two cases are reported: the minimal kernel framework as in [\[8\]](#page-18-3) and the full kernel one as described in this work. The minimal kernel assumption slightly underestimates the SNR with respect to the more accurate modeling.

A clever choice of the tracers can significantly boost the signal. For example, in the case of a 50  $(Gpc/h)^3$  survey, centered at  $z = 1$ , for a choice of linear biases  $(b_1^A = 2,$ <br> $b_1^B = 1.5$ ) an SNR of order (2(10) is achieved at  $b_1^B = 1.5$ ) an SNR of order  $\mathcal{O}(10)$  is achieved at  $b_1 = \infty$  0.6 h/Mpc. However, when targeting e.g. two  $k_{\text{max}} \sim 0.6 \ h/\text{Mpc}$ . However, when targeting, e.g., two populations with  $(b_1^A = 3, b_1^B = 1.1)$  the SNR is  $\mathcal{O}(10)$ <br>at  $k \approx 0.3 h/Mpc$  which is within the reach of current at  $k_{\text{max}} \sim 0.3 \ h/\text{Mpc}$ , which is within the reach of current analyses [[65](#page-19-16)–[67](#page-19-17)]. This can be used as a guidance for setting the required source targeting, the exact situation being different for specific surveys.

The purely linear bias case is also shown: in the presence of RSD, there is a nonvanishing signal, which is harder to detect unless reaching higher  $k_{\text{max}}$ . The signal comes from the fact that in multitracer analyses there will be a mixed bias-RSD term that carries information on the velocitydensity spectrum, in a similar fashion as unequal time correlations [[10](#page-18-11)].

 $3$ Compare, e.g., to the situation described in [[63](#page-19-18)], where the bulk of the information is contained in the most squeezed configurations, and therefore the analysis can be pushed to  $K_{\text{max}} = k_{\text{min}}$ , including triangles that are technically not squeezed at all.

<span id="page-8-1"></span>

FIG. 2. SNR for nonlinear biased clustering, sourced by the squeezed bispectrum between two tracers and an underlying dark matter long mode, antisymmetrized with respect to the two tracers. Left: the SNR is plotted as a function of the short mode  $k$  after integrating over long modes, Eq. [\(41\).](#page-7-0) Right: the SNR has been integrated over short modes as well, Eq. [\(42\),](#page-7-1) and it is plotted as a function of the maximum wave number of the analysis,  $k_{\text{max}}$ . The various lines represent calculations with minimal kernels as in [[8](#page-18-3)] (MK, dashed) and full kernels as computed in Sec. [II A](#page-2-0) (FK, solid). The case for full kernels with linear bias only is also shown (dot-dashed). The plots show results for two example cases  $(b_1^A = 3, b_1^B = 1.1)$  in black and  $(b_1^A = 2, b_1^B = 1.5)$  in gray. The survey volume is taken to be<br>50  $(\text{Cno}/h)^3$  centered at  $z = 1$  with tracer density  $n = 10^{-3}$  ( $h/\text{Mno}^3$   $n = 2n$ 50  $(Gpc/h)^3$ , centered at  $z = 1$ , with tracer density  $n_{g,A} = 10^{-3}$   $(h/Mpc)^3$ ,  $n_{g,B} = 2n_{g,A}$ .

### A. Constraints on the bias

It comes natural to investigate if the antisymmetric correlation, as it is depending on combinations of the bias parameters that are different from the standard case, can constrain them (or a combination of) in a meaningful way.

In the minimal kernels case, the signal is proportional to the antisymmetrized combination of bias parameters  $P^{\rm A}$  ∝ ( $b_B c_A - b_A c_B$ ) ≡ **2**. Using this simplified case for an estimate of the precision reachable in measuring ב, then  $\sigma$ <sub>2</sub>  $\sim$  1/SNR (68% CL). When including RSD, gravitational evolution, and the other second-order bias parameters, the scaling becomes much more complex and the constraining power cannot be summarized in such a straightforward way.

As mentioned in the previous section, the linear bias parameters  ${b_A^A, b_I^B}$  will be connected to the higher-order<br>ones by means of fitting formulas [31,68] and reported in ones by means of fitting formulas [\[31](#page-18-16)[,68\]](#page-19-19) and reported in Appendix [C.](#page-16-0)

If one were to consider the entire set of parameters, the main limiting factor for the constraining power on the bias parameters would be degeneracies (as expected and, as it happens, for standard observables including loops), especially when accounting for all terms included in this work. As can be immediately seen from Eq. [\(36\),](#page-6-0) the biases  $\{b_1^A, b_1^B, b_2^A, b_2^B, b_{K^2}^A, b_{K^2}^B\}$  combine in the final signal in a way that makes it difficult to disentangle the single contributions. There is virtually no constraining power on the full set of bias parameters, and even pushing the analysis to a more aggressive  $k_{\text{max}} \sim 0.6 \ h/\text{Mpc}$ , the constraints are not competitive with other available observables.

Figure [3](#page-9-0) shows the dependence of the constraining power on  $k_{\text{max}}$  (where of course one would need to model nonlinearities), for two choices of fiducial biases  $(b_1^A = 3, b_1^B = 1, 1)$ , and  $(b_1^A = 2, b_1^B = 1, 5)$ . Constraints, of  $b_1^B = 1.1$ ) and  $(b_1^A = 2, b_1^B = 1.5)$ . Constraints of  $\mathcal{O}(10\% - 30\%)$  on the linear bias parameters are achieved  $\mathcal{O}(10\% - 30\%)$  on the linear bias parameters are achieved when reaching  $k_{\text{max}} \sim 0.3 \ h/\text{Mpc}$ . This is not competitive with expected constraints from future galaxy surveys, but the analysis performed here is a very rough estimate: a more detailed procedure, including several redshift bins and their correlation and pushing the analysis to higher redshifts and smaller scales, may significantly improve the constraints.

#### B. Primordial non-Gaussianity

<span id="page-8-0"></span>This section investigates the constraining power of the antisymmetric galaxy cross-correlation on local PnG. The signal is modeled using the full kernels, as in Eq. [\(36\),](#page-6-0) and assuming a fiducial  $f_{\text{NL}} = 1$  and  $\{b_1^A = 3, b_1^B = 1.1\}$ . Only<br>the  $\alpha k^{-2}$  scale dependent bias associated with local-type the  $\propto k^{-2}$  scale-dependent bias associated with local-type PnG is investigated here. As a first rough estimate of the constraining power, the results on  $\sigma_{f_{NL}}$  are obtained via a Fisher forecast on  $f_{NL}$  alone, with

<span id="page-9-0"></span>

FIG. 3. Forecasts on  $\{b_1^A, b_1^B\}$ , with second-order biases being linked to the linear ones by the fitting formulas. The plot shows the dependence on  $k$  of the  $1\sigma$  constraints on  $b^X$ . The survey volume is 100 (G dependence on  $k_{\text{max}}$  of the  $1\sigma$  constraints on  $b_1^X$ . The survey volume is 100  $(\text{Gpc}/h)^3$  centered at  $z = 1$ , with tracers  $p_1 = 10^{-3}$  ( $h/\text{Mpc}$ )<sup>3</sup>  $p_1 = 2p_1$ . The fiducial bigges are set to  $(h^A - 3, h^B - 1, 1)$  $n_{g,A} = 10^{-3}$   $(h/\text{Mpc})^3$ ,  $n_{g,B} = 2n_{g,A}$ . The fiducial biases are set to  $(b_1^A = 3, b_1^B = 1.1)$  on the left panel and to  $(b_1^A = 2, b_1^B = 1.5)$ on the right panel.

$$
\sigma_{f_{NL}}^{-2} \simeq \frac{V_s}{(2\pi)^3} \int_{k_f}^{k_{\text{max}}} k^2 dk \int_0^{2\pi} d\phi_1 \int_0^1 d\mu_1 \left\{ \int_{k_f}^{k/10} \frac{K^2 dK}{(2\pi)^3} \int_{-1}^{+1} d\mu \int_0^{2\pi} d\phi \frac{1}{\text{Cov}^{\text{emi}}(\boldsymbol{k}, \boldsymbol{K})} \left( \frac{\partial P^{\text{A}}(\boldsymbol{k}, \boldsymbol{K})}{\partial f_{NL}} \right)^2 \right\}.
$$
 (43)

ſ

A more complete analysis, including degeneracies especially with the linear bias parameters  $b_1^A$  and  $b_1^B$ —and extending to orthogonal and folded shapes, is left for a future work.

Figure [4](#page-9-1) investigates what would be the requirements for a survey to set stringent bounds on local  $f_{\text{NL}}$  using this observable. Two directions are explored: a larger survey volume and a larger number density. Both are beneficial, but the improvement given by a larger survey volume tends to saturate: this is because, given the need to keep a hierarchy between long and short modes, the integration over short modes can never be pushed down to  $k_{\text{min}} = 2\pi/V_s^{1/3}$ .

The results fall in the same order of magnitude as recent constraints on  $f_{\text{NL}}$  using the scale-dependent bias, obtained from the power spectrum of quasar samples in the eBOSS survey [[48](#page-19-3),[69](#page-19-20),[70](#page-19-21)], giving  $1\sigma_{f_{NL}} \sim \mathcal{O}(20)$ , as well as the forecasted constraining power for DESI and Euclid using the power spectrum only [[71](#page-19-22)], which will give similar

<span id="page-9-1"></span>

FIG. 4. Value of  $\sigma_{f_{NL}}$  when varying some survey specifications.

results to the Planck ones  $1\sigma_{f_{NL}} \sim \mathcal{O}(10)$ . However, they are not competitive with a combined analysis of power spectrum and bispectrum, and with future radio [[72](#page-19-23),[73](#page-19-24)] and galaxy surveys such as SPHEREx [[49](#page-19-4)] and the proposed SIRMOS [[74](#page-19-25)], that forecast  $\sigma_{f_{NL}} < 1$ .

# V. TESTS OF ALTERNATIVE COSMOLOGICAL MODELS

<span id="page-10-0"></span>The antisymmetric galaxy cross-correlation is not just a new observable, but it presents the advantage of being sensitive to some exotic fundamental physics models that would otherwise not be tested when using more standard statistics; roughly, it can be thought of as something similar to tests performed with cosmic fossils [\[29,](#page-18-14)[75\]](#page-19-26), but being sensitive to odd moments. The antisymmetric crosscorrelation can be sensitive to models that include a preferred direction or where underlying long modes affect different populations in specific ways.

This section investigates a few examples of beyond ΛCDM models that can imprint signatures that can be tested by the antisymmetric cross-correlation of two tracers. Where not otherwise specified, the survey specifications are as in the previous section.

### A. Vector modes

In the presence of primordial vector fields from inflation [\[76](#page-19-27)–[78\]](#page-19-28)—for instance, in axion inflation [[79](#page-19-29)[,80\]](#page-19-30), where the inflaton is coupled to a  $U(1)$  gauge field, or due to primordial magnetic fields [[81](#page-19-31),[82](#page-19-32)]—a vector polarization can arise in the presence of some preferred direction, to which the two tracers would respond in different ways and therefore give a nonvanishing antisymmetric signal.

<span id="page-10-2"></span>The generic parametrization of the antisymmetric component as in [[8\]](#page-18-3) is

$$
P^{\mathcal{A}}(\boldsymbol{k}_1,\boldsymbol{k}_3) = \sum_{p} f^{\mathcal{A}}_{p}(\boldsymbol{k}_1,\boldsymbol{k}_3) h^{\ast}_{p}(\boldsymbol{k}_3) \hat{\boldsymbol{\epsilon}}_{p} \cdot (2\boldsymbol{k}_1\mu_{13} + \boldsymbol{k}_3), \quad (44)
$$

with  $p = L, x, y$ . Taking the longitudinal polarization  $\epsilon_L$ along the long mode direction,  $\hat{k}_3 \equiv \hat{K}$ , a complete orthonormal basis is given by

$$
\hat{\mathbf{K}} = (\cos \theta_3 \cos \phi_3, \cos \theta_3 \sin \phi_3, \sin \theta_3),
$$
  
\n
$$
\hat{\mathbf{X}} = (\sin \phi_3, -\cos \phi_3, 0),
$$
  
\n
$$
\hat{\mathbf{Y}} = \hat{\mathbf{K}} \times \hat{\mathbf{X}} = (\sin \theta_3 \cos \phi_3, \sin \theta_3 \sin \phi_3, -\cos \theta_3).
$$
 (45)

Figure [5](#page-10-1) shows the SNR for a signal as in Eq. [\(44\)](#page-10-2), taking an amplitude [[7](#page-18-2)]  $f_{\text{A,y}}^{\text{A}} = -\frac{3}{2} Z_1^{\text{dm}}(k_1, z) P(k_1)/k_1$ , where the dark matter kernel is  $Z_1^{\text{dm}}(\vec{k}_1, z) = (1 + f\mu_1^2)$ , and a scale-<br>invariant, nower, spectrum,  $B(k_1) = E(2\pi^2 \Lambda / k^3)$ , with invariant power spectrum  $P(k_3) = F(2\pi^2 A_s/k_3^3)$ , with some amplitude *F* which can be constrained some amplitude  $F$ , which can be constrained.

<span id="page-10-1"></span>

FIG. 5. SNR for the two vector polarizations  $p = x, y$ , plotted as a function of  $k_{\text{max}}$ , after integrating over both long and short modes. The long mode  $h_p^*(k_3)$  is a vector field of primordial<br>origin where the power spectrum is taken to be a scale-invariant origin, where the power spectrum is taken to be a scale-invariant  $F(2\pi^2 A_s/k_3^3)$ ; the SNR is shown for different amplitudes F.

The covariance is obtained assuming that there is no cross-correlation in the absence of the long mode, i.e.,  $2P_A^{\text{tot}}(k_1)P_B^{\text{tot}}(k_2)$ , as in [[8\]](#page-18-3).

#### B. Two-component dark matter

There has recently been interest in models where the dark sector is not made by one single particle but it is extended and there are different particles in the dark sector, with particular focus on direct detection searches [[83](#page-19-33)–[88](#page-19-34)]. However, clustering properties of different biased tracers may provide an alternative detection method: it was proposed in [\[8\]](#page-18-3) that a two-component dark matter model may leave an antisymmetric imprint if the two tracers cluster in different ways.

As an example, one can imagine that the dark matter components are affected by a relative modulation that imprints a preferred direction: for simplicity, let us associate it with the second tracer,  $\delta_B(\mathbf{k}) = b_1^B \delta(\mathbf{k}) (1 + A\hat{\mathbf{k}} \cdot \hat{\mathbf{p}})$ ,<br>with  $\hat{\mathbf{n}}$  the preferred direction and A controlling the strength with  $\hat{\boldsymbol{p}}$  the preferred direction and A controlling the strength of the modulation. Then

$$
\langle \delta_A(\mathbf{k}_1) \delta_B(\mathbf{k}_2) \delta(\mathbf{k}_3) \rangle = b_1^A b_1^B (1 + A \hat{\mathbf{k}}_2 \cdot \hat{\boldsymbol{p}}) \langle \delta(\mathbf{k}_1) \delta(\mathbf{k}_2) \delta(\mathbf{k}_3) \rangle, \tag{46}
$$

so that, after antisymmetrization, one is left with a signal  $\propto b_1^A b_1^B B_{\text{grav}}(k_1, k_2, k_3) A(\hat{k}_2 - \hat{k}_1) \cdot \hat{p}$  with  $\hat{\epsilon} = \hat{p}$ . Adding RSD, in the case of generic kernels, the antisymmetrized bispectrum between the two tracers is

$$
B^{\mathcal{A}}(\boldsymbol{k}_{1},\boldsymbol{k}_{2},\boldsymbol{k}_{3}) = \frac{1}{2} \left[ (1 + A\hat{\boldsymbol{k}}_{2} \cdot \hat{\boldsymbol{p}}) \langle \delta_{s,A}(\boldsymbol{k}_{1}) \delta_{s,B}(\boldsymbol{k}_{2}) \delta_{s}(\boldsymbol{k}_{3}) \rangle - (1 + A\hat{\boldsymbol{k}}_{1} \cdot \hat{\boldsymbol{p}}) \langle \delta_{s,B}(\boldsymbol{k}_{1}) \delta_{s,A}(\boldsymbol{k}_{2}) \delta_{s}(\boldsymbol{k}_{3}) \rangle \right].
$$
\n(47)

<span id="page-11-0"></span>

FIG. 6. SNR for the amplitude of the two-component dark matter model, with amplitude A and preferred direction either aligned with the line of sight  $\hat{\mathbf{p}} = (0, 0, 1)$  or orthogonal to it, as an example  $\hat{\boldsymbol{p}} = (1, 0, 0)$ . A linear bias relation is assumed. The solid and dot-dashed lines include both RSD and gravitational evolution, while the dashed line shows the signal without RSD.

This sources a signal

$$
P^{\mathcal{A}}(\boldsymbol{k}_1,\boldsymbol{k}_3) = \frac{B^{\mathcal{A}}(\boldsymbol{k}_1,\boldsymbol{k}_2,\boldsymbol{k}_3)}{P(\boldsymbol{k}_3)}\bigg|_{\boldsymbol{k}_1+\boldsymbol{k}_2+\boldsymbol{k}_3=0} \delta^*(\boldsymbol{k}_3). \qquad (48)
$$

Notice that, since RSDs leave a nonvanishing signature even with linear bias only, this signal will get contributions that come from Eq. [\(23\)](#page-3-1) and are not due to the new ingredient  $\propto A$ .

The (emisphere) covariance will also get modified with respect to Eq. [\(40\)](#page-7-2) as

$$
Cov^{emi}(\boldsymbol{k}_1, \boldsymbol{k}_2, \boldsymbol{k}_3) = \frac{1}{2} [(1 + A\hat{\boldsymbol{k}}_2 \cdot \hat{\boldsymbol{p}})^2 P_{AA}(k_1) P_{BB}(k_2) + (1 + A\hat{\boldsymbol{k}}_1 \cdot \hat{\boldsymbol{p}})^2 P_{AA}(k_2) P_{BB}(k_1)] - (1 + A\hat{\boldsymbol{k}}_1 \cdot \hat{\boldsymbol{p}})(1 + A\hat{\boldsymbol{k}}_2 \cdot \hat{\boldsymbol{p}}) \times P_{AB}(k_1) P_{AB}(k_2).
$$
 (49)

Figure [6](#page-11-0) shows the SNR for the signal above. The procedure of exchanging the two tracers is actually sensitive to the projection of the relative displacement between tracers onto the Fourier plane embedding the three wave vectors. Those wave vectors that happen to lie orthogonally to the preferred direction will give no contribution to the signal.

#### C. Anisotropies from inflation

Statistical isotropy and/or homogeneity may be slightly violated, due to some physical process of primordial origin. In the presence of a dipolar or quadrupolar (or higher) modulation of the primordial curvature power spectrum, the matter power spectrum inherits a new factor so that antisymmetric correlations could test such a model. In this case, the power spectrum can be written as [\[89,](#page-19-35)[90](#page-19-36)]

$$
\langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \rangle = (2\pi)^3 \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2) P_{\zeta}(k_1) [1 + \Phi(\mathbf{k}_1)],
$$
\n(50)

where, for a generic distortion multipole  $L$ ,

 $\sim$   $\sim$ 

$$
\mathcal{P}(\mathbf{k}_1) = \sum_{M} g_{LM} f(k_1) Y_{LM}(\hat{\mathbf{k}}_1).
$$
 (51)

with  $g_{LM}$  being the amplitudes of the modulation and  $f(k)$ carrying the scale dependence. Notice that this case is different from the previous examples: here, the two tracers respond in the same way to the primordial modulation that is imprinted in the initial conditions. In this sense, the antisymmetric signal is still the one that was calculated for the nonlinear biased clustering, but the SNR is modified by the additional anisotropic factor that comes from the primordial curvature power spectrum. In fact, the extra factor can be interpreted as an effective scale-dependent bias,  $b_1(k) = b_1(1 + \Phi(k))$ ; however, the scale dependence is the same for every tracer, and in the case of purely linear bias and no RSD, the antisymmetric signal would vanish, the same way it would for nonlinear clustering.

Figure [7](#page-12-0) shows the signal squared  $(P^A(k_1, k_3))^2$  as a function of the short mode, both for the dipolar and the quadrupolar modulation. The amplitude of the new term has been set to order  $\mathcal{O}(1)$ .

It can be seen how, for the dipolar modulation (and the modeling considered here), there is a scale-dependent change, which modifies the amplitude especially at large scales. For the quadrupolar, on the other hand, the change varies depending on the power of the  $f(k)$  considered, making different parts of the analysis more sensitive to different models.

### 1. Dipolar distortion  $L = 1$

In [[91](#page-19-37),[92](#page-19-38)] the dipolar asymmetry was found to be  $~\sim 6\% - 7\%$  on angular scales  $\ell \lesssim 64$ . A dipolar distortion  $L = 1$  in the CMB can be described by a multiplicative modulation  $T(\hat{\boldsymbol{n}}) = T_{iso}(\hat{\boldsymbol{n}})(1 + A\hat{\boldsymbol{n}} \cdot \hat{\boldsymbol{p}})$  with  $\hat{\boldsymbol{p}}$  the preferred direction of the modulation, and  $A \sim 0.07$  [[93](#page-19-39)]. The power spectrum acquires the extra contribution

$$
\Psi(\mathbf{k}) = \sum_{M} g_{1M} f(k) Y_{1M}(\hat{\mathbf{k}}) = A f(k) \frac{1}{2} \sqrt{\frac{3}{\pi}} \left( \cos \theta - \sqrt{2} \sin \theta \cos \phi \right), \tag{52}
$$

<span id="page-12-0"></span>

FIG. 7. Signal  $(P^{A}(k_1, k_3))^2$  integrated over angles and over long modes, for a correlation sourced by nonlinear biased clustering in the presence of an anisotropic modulation of the power spectrum, with  $L = 1$  (left) and  $L = 2$  (right). The amplitudes of the anisotropic contribution have been set to a larger value of 1, to visually appreciate the effect with respect to the purely isotropic case.

using  $g_{1,-M} = (-1)^M g_{1M}^*$  and assuming for simplicity<br> $g_{1,2} = g_{1,1} = A$ . The following cases will be studied:  $g_{10} = g_{11} = A$ . The following cases will be studied:

$$
f(k) = 1 - \frac{k}{k_A}, \qquad \left(1 - \frac{k}{k_A}\right)^2.
$$
 (53)

These parametrizations were introduced in [\[90\]](#page-19-36) as a heuristic model to capture the main qualitative features emerging from CMB and quasar abundance observations, i.e., a large-scale dipolar asymmetry that rapidly decays and vanishes at  $k \sim k_A = 1$  Mpc<sup>-1</sup>.

Figure [8](#page-12-1) shows the signal squared and the SNR in the presence of dipolar anisotropies, having set the amplitude of the anisotropic contribution to the maximum value currently allowed by Planck constraints,  $A_{1M} = 0.07$  [[94](#page-19-40)].

As it can be seen, the effect is small. The right panel shows the ratio between the SNR for the anisotropic (dipolar) model and the isotropic signal from biased

<span id="page-12-1"></span>

FIG. 8. Left: signal  $(P^A(k, K))^2$  integrated over angles and over long modes, for a correlation sourced by nonlinear biased clustering in the presence of an anisotropic modulation of the power spectrum, with  $L = 1$ . Right: ratio of the anisotropic SNR to the isotropic case. The amplitudes are the maximum ones allowed by Planck constraints,  $A_{1M} = 0.07$  [\[94\]](#page-19-40). As before, the survey volume is 100  $(Gpc/h)^3$ centered at  $z = 1$ , with tracers  $n_{g,A} = 10^{-3} (h/\text{Mpc})^3$ ,  $n_{g,B} = 2n_{g,A}$  and biases  $(b_1^A = 3, b_1^B = 1.1)$ . The dipolar modulation results in an order few percent enhancement of the SNR, depending on the maximum scale k order few percent enhancement of the SNR, depending on the maximum scale  $k_{\text{max}}$  used in the analysis.

<span id="page-13-0"></span>

FIG. 9. Left: signal  $(P^{A}(k, K))^{2}$  integrated over angles and over long modes, for a correlation sourced by nonlinear biased clustering in the presence of an anisotropic modulation of the power spectrum, with  $L = 2$ . Right: ratio of the anisotropic SNR to the isotropic case. The amplitudes are the maximum ones allowed by Planck constraints,  $g_{2,-2} = -10^{-4}$  and  $g_{2M} = 10^{-2}$  ( $M = -1, 0, 1, 2$ ) [\[94\]](#page-19-40). As before, the survey volume is 100  $(\text{Gpc}/h)^3$  centered at  $z = 1$ , with tracers  $n_{g,A} = 10^{-3} (h/\text{Mpc})^3$ ,  $n_{g,B} = 2n_{g,A}$  and biases  $(b_1^A = 3, b_2^B = 1, 1)$ . The quadrupolar modulation oscaptibly does not change the SNP wit  $b_1^B = 1.1$ ). The quadrupolar modulation essentially does not change the SNR with respect to the fully isotropic case, when within the current Planck limits current Planck limits.

clustering. It can be seen that the SNR gets enhanced with respect to the purely isotropic case. Depending on the significance of the isotropic case, there is, in principle, the opportunity to detect such a signal and therefore be competitive with existing constraints from Planck. A more detailed analysis is needed, including a study on the tradeoff between going to larger values of  $k_{\text{max}}$  and having more general constraining power, but having a less relevant contribution from the dipolar modulation, which is most important on the largest scales. For this reason, the ratio to the isotropic SNR case approaches 1 on small scales, and there is not significant gain in pushing the analysis to very high  $k_{\text{max}}$ .

A possible direction to explore to detect anisotropic imprints within this framework can rely on a characterization of the scale dependence of the SNR, either as a function of the survey's short modes  $k$  or as a function of  $k_{\text{max}}$ —provided nonlinear scales can be accurately modeled.

### 2. Quadrupolar distortion  $L = 2$

A quadrupolar distortion  $L = 2$  arises, for example, in models of inflation where the inflaton is coupled to a vector field with a nonvanishing vacuum expectation value [\[77](#page-19-41)[,95\]](#page-19-42). The term encoding the anisotropy is

$$
\Phi(\mathbf{k}) = \sum_{M} g_{2M} f(k) Y_{2M}(\hat{\mathbf{k}}) = g_{2M} f(k) \frac{1}{4} \sqrt{\frac{5}{\pi}} \left[ 3 \cos^2 \theta - 1 + \sqrt{6} \sin^2 \theta \cos(2\phi) - \sqrt{6} \sin(2\theta) \cos \phi \right],
$$
 (54)

with  $g_{2,-M} = (-1)^M g_{2M}^*$  [\[94\]](#page-19-40) and for simplicity  $g_{20} = g_{22} - g_{22}$ . Both the amplitudes and the function  $g_{21} = g_{22} = g_{2M}$ . Both the amplitudes and the function  $f(k)$  are strongly dependent on the underlying inflationary model. In a model-agnostic approach, the following cases will be studied:

$$
f(k) = 1, \qquad \left(\frac{k}{k_{\rm g}}\right)^{\pm 1}, \qquad \left(\frac{k}{k_{\rm g}}\right)^{\pm 2}, \qquad (55)
$$

with  $k_g = 0.05$  Mpc<sup>-1</sup> the pivot scale adopted in the Planck Collaboration. Planck upper bounds give  $|g_{2M}| \lesssim 10^{-2}$  for all these cases, except for  $(k/k<sub>g</sub>)^{-2}$  for which the bound is stronger  $g_{2,-2} \sim -10^{-4}$  [[94](#page-19-40)].

Figure [9](#page-13-0) shows the signal squared and the SNR in the presence of quadrupolar anisotropies, having set the amplitude of the anisotropic contribution to the maximum value allowed by Planck constraints [[94](#page-19-40)]. As it can be seen,

the modifications induced by such a level of quadrupolar anisotropy, on the scales of interest, are very small.

Therefore, it appears clear that Planck already constrains the amplitudes of the quadrupolar modulation to a level that will not realistically be reached by antisymmetric galaxy correlations. The right panel of the figure shows how the SNR from this modulation is virtually unchanged.

#### VI. CONCLUSIONS

This paper investigates one of the recently proposed observables for galaxy clustering, the antisymmetric galaxy cross-correlation. The antisymmetric component of the two-point galaxy cross-correlation function arises when the small-scale power is modulated by a long-wavelength field. Such a signal is sourced by the squeezed bispectrum of the two objects being correlated and the long mode, underlying field. This signal can be decomposed into longitudinal and transverse components, sourced by different physical mechanisms.

The first expression for this observable was given in [[8\]](#page-18-3); this work provides a more accurate modeling by adding redshift-space distortions, nonlinear gravitational evolution, second-order bias expansion, and primordial non-Gaussianity. Moreover, for the first time, the detectability of this signal is investigated from a quantitative point of view by building a recipe for calculating the SNR and applying it to various examples.

In the standard ΛCDM scenario, an antisymmetric crosscorrelation arises between different tracers of the underlying dark matter field because of nonlinear biased clustering.

Beyond ΛCDM, the antisymmetric cross-correlation can pick up the signature of some exotic beyond the standard model scenarios. In particular, this can happen for models where the two objects being correlated respond in a different way to the underlying field and for models with anisotropic features inducing a privileged direction in the sky.

For these reasons, this observable can be a powerful tool to search for hints of new physics. This work investigates the signature of some of these models. A particularly interesting case is the imprint of vector modes [\[8\]](#page-18-3) that arise, e.g., due to primordial magnetic fields [[81](#page-19-31),[82](#page-19-32)] or in models of axion inflation [\[79](#page-19-29)[,80\]](#page-19-30). Other signatures of these fields are related to, e.g., compensated isocurvature perturbations [\[96\]](#page-19-43). Other examples are a two-component dark matter model as suggested in [\[8](#page-18-3)[,83](#page-19-33)–[88](#page-19-34)] and the extra signature coming from primordial anisotropies imprinted in the power spectrum after inflation [[90](#page-19-36)].

These are just few examples that are meant to demonstrate the potential of this new observable in testing both early and late Universe physics. Its full potential for specific models for realistic surveys will be investigated in a future work.

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## <span id="page-14-0"></span>APPENDIX A: FOURIER-SPACE KERNELS

Keeping the full relation between redshift- and realspace overdensity, Eqs. [\(14\)](#page-2-1) and [\(15\)](#page-2-2), including the Doppler term [[34](#page-18-19)] and selection effects, the first- and second-order redshift-space kernels for biased tracers are, in Fourier space,

$$
Z_1(k) = b_1 + f\mu^2 - \frac{i\mu f\alpha}{kr}, \qquad (A1)
$$

$$
Z_{2}(\mathbf{p}, \mathbf{q}) = \frac{b_{2}}{2} + b_{1}F_{2}(\mathbf{p}, \mathbf{q}) + b_{K^{2}} \left(\mu_{pq}^{2} - \frac{1}{3}\right) + f\mu^{2}G_{2}(\mathbf{p}, \mathbf{q})
$$
  

$$
- \frac{i\mu f\alpha}{kr}G_{2}(\mathbf{p}, \mathbf{q}) + \frac{k\mu f}{2} \left(\frac{\mu_{p}}{p}(b_{1} + f\mu_{q}^{2}) + \frac{\mu_{q}}{q}(b_{1} + f\mu_{p}^{2})\right)
$$
  

$$
- \frac{i f\alpha}{r} \left[\frac{\mu_{p}}{p}\left(\frac{b_{1}}{2} + f\mu_{q}^{2}\right) + \frac{\mu_{q}}{q}\left(\frac{b_{1}}{2} + f\mu_{p}^{2}\right)\right] - f^{2} \frac{\mu_{p}\mu_{q}}{pqr^{2}}(\alpha(\alpha - 2) - \gamma),
$$
 (A2)

with  $k = p + q$ , and

$$
\alpha \equiv \frac{r}{\bar{n}} \frac{\partial \bar{n}}{\partial r} + 2, \qquad \gamma \equiv \frac{r^2}{2\bar{n}} \nabla^2 \bar{n} - 3. \tag{A3}
$$

# APPENDIX B: FULL EXPRESSIONS OF THE  $\mathcal F$  FUNCTIONS

<span id="page-15-0"></span>The full expressions of the  $\mathcal{F}(k_1, k_3)$  functions that appear in Eq. [\(36\)](#page-6-0) are as follows [the superscripts refer to the corresponding order in the expansion in powers of the long mode over the short mode,  $(k_3/k_1)$ ]:

$$
\mathcal{F}_{\phi}^{(-1)}(\boldsymbol{k}_{1},\boldsymbol{k}_{3})=42T(k_{1})f\mu_{1}^{2}\bigg\{\bigg[-2+\bigg(-4+\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\bigg)f\mu_{1}^{2}\bigg]\mu_{13}+2f\mu_{1}\mu_{3}\bigg\},\tag{B1}
$$

$$
\mathcal{F}_{\phi}^{(0)}(\mathbf{k}_{1},\mathbf{k}_{3}) = -21T(k_{1})f\mu_{1}\left\{-f\mu_{1}^{3}\left[-4+\frac{\partial\log P(k_{1})}{\partial\log k_{1}}+\left(24+\frac{k_{1}^{2}}{P(k_{1})}\frac{\partial^{2}P(k_{1})}{\partial k_{1}^{2}}\right)\mu_{13}^{2}-9\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\mu_{13}^{2}\right] + 4\mu_{13}\mu_{3} - 6\left(-4+\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right)f\mu_{1}^{2}\mu_{13}\mu_{3} + 2\mu_{1}\left[1+\left(-4+\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right)\mu_{13}^{2}-3f\mu_{3}^{2}\right]\right\},
$$
\n(B2)

$$
\mathcal{F}_{\phi}^{(1)}(\mathbf{k}_{1},\mathbf{k}_{3}) = -6f\mu_{1} \left\{ 2\mu_{3} \left[ 1 + \left( -22 + 7 \frac{\partial \log P(k_{1})}{\partial \log k_{1}} - 7 \frac{\partial \log T(k_{1})}{\partial \log k_{1}} \right) \mu_{13}^{2} \right] + \mu_{3}\mu_{13} \left[ \frac{\partial \log T(k_{1})}{\partial \log k_{1}} \left( -6 + 6\mu_{13}^{2} - 7f\mu_{3}^{2} \right) + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \left( 6 - 6\mu_{13}^{2} + 7f\mu_{3}^{2} \right) - 4(3 - 3\mu_{13}^{2} + 7f\mu_{3}^{2}) \right] \right\} + 7fT(k_{1}) \left\{ -6\mu_{13}\mu_{3}^{2} + 6\mu_{1}\mu_{3} \left[ -2 - 2\left( -4 + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \right) \mu_{13}^{2} + f\mu_{3}^{2} \right] + 9f\mu_{1}^{3}\mu_{3} \left[ -4 + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} - 9 \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{13}^{2} + \left( 24 + \frac{k_{1}^{2}}{P(k_{1})} \frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}} \right) \mu_{13}^{2} \right] + f\mu_{1}^{4}\mu_{13} \left[ 72 - 192\mu_{13}^{2} + \frac{k_{1}^{3}}{P(k_{1})} \frac{\partial^{3} P(k_{1})}{\partial k_{1}^{3}} \mu_{13}^{2} + \frac{k_{1}^{2}}{P(k_{1})} \frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}} \left( 3 - 15\mu_{13}^{2} \right) + 3 \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \left( -9 + 29\mu_{13}^{2} \right) \right] - 3\mu_{1}^{2}\mu_{13} \left[ -12 + \left( 24 + \frac{k_{1}^{2}}{P(k_{1})} \frac{\partial^{2} P(k_{1})}{\partial
$$

$$
\mathcal{F}_{\phi\delta}^{(-1)}(\mathbf{k}_1, \mathbf{k}_3) = 42T(k_1)f\mu_1 \left[ \left( -2 + \frac{\partial \log P(k_1)}{\partial \log k_1} \right) \mu_1 \mu_{13} + 2\mu_3 \right],
$$
\n(B4)

$$
\mathcal{F}_{\phi\delta}^{(0)}(\mathbf{k}_1, \mathbf{k}_3) = 21T(k_1)f \bigg\{ \mu_1^2 \bigg[ -2 + \frac{\partial \log P(k_1)}{\partial \log k_1} + \bigg( 8 + \frac{k_1^2}{P(k_1)} \frac{\partial^2 P(k_1)}{\partial k_1^2} \bigg) \mu_{13}^2 - 5 \frac{\partial \log P(k_1)}{\partial \log k_1} \mu_{13}^2 \bigg] + 4\mu_1\mu_3\mu_{13} \bigg( -2 + \frac{\partial \log P(k_1)}{\partial \log k_1} \bigg) + 2\mu_3^2 \bigg\},
$$
\n(B5)

$$
\mathcal{F}_{\phi\delta}^{(1)}(\mathbf{k}_{1},\mathbf{k}_{3}) = 7f \Big\{ 6\mu_{1} \Big[ 2\mu_{3} - \Big( 4 - \frac{\partial \log P(k_{1})}{\partial \log k_{1}} + \frac{\partial \log T(k_{1})}{\partial \log k_{1}} \Big) \mu_{1} \mu_{13} \Big] \n+ T(k_{1}) \Big[ \mu_{1}^{2} \mu_{13} \Big( 24 - 48\mu_{13}^{2} + \frac{k_{1}^{3}}{P(k_{1})} \frac{\partial^{3} P(k_{1})}{\partial k_{1}^{3}} \mu_{13}^{2} + \frac{k_{1}^{2}}{P(k_{1})} \frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}} (3 - 9\mu_{13}^{2}) + 3 \frac{\partial \log P(k_{1})}{\partial \log k_{1}} (-5 + 11\mu_{13}^{2}) \Big) \n+ 6\mu_{1} \Big( -2 + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} - 5 \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \mu_{13}^{2} + \Big( 8 + \frac{k_{1}^{2}}{P(k_{1})} \frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}} \Big) \mu_{13}^{2} \Big) \mu_{3} + 6 \Big( -2 + \frac{\partial \log P(k_{1})}{\partial \log k_{1}} \Big) \mu_{13} \mu_{3}^{2} \Big] \Big\},
$$
\n(B6)

$$
\mathcal{F}_{1,\phi}^{(-1)}(\mathbf{k}_1,\mathbf{k}_3) = -42T(k_1)\mu_{13} \left[ -2 + \left( -2 + \frac{\partial \log P(k_1)}{\partial \log k_1} \right) f \mu_1^2 \right],\tag{B7}
$$

$$
\mathcal{F}_{1,\phi}^{(0)}(\mathbf{k}_{1},\mathbf{k}_{3}) = 21T(k_{1})\left\{2 + 2\mu_{13}^{2}\left(-2 + \frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right)\right.\n+ f\mu_{1}\left[\mu_{1}\left(2 - \frac{\partial\log P(k_{1})}{\partial\log k_{1}} - \left(8 + \frac{k_{1}^{2}}{P(k_{1})}\frac{\partial^{2}P(k_{1})}{\partial k_{1}^{2}}\right)\mu_{13}^{2} + 5\frac{\partial\log P(k_{1})}{\partial\log k_{1}}\mu_{13}^{2}\right) \right.\n+ 2\mu_{13}\mu_{3}\left(2 - \frac{\partial\log P(k_{1})}{\partial\log k_{1}}\right)\right\},
$$
\n(B8)

$$
\mathcal{F}_{1,\phi}^{(1)}(\mathbf{k}_{1},\mathbf{k}_{3}) = -6\mu_{13} \left[ 26 + 28f\mu_{1}^{2} + 16\mu_{13}^{2} - \frac{\partial \log P(k_{1})}{\partial \log k_{1}} (10 + 7f\mu_{1}^{2} + 4\mu_{13}^{2}) + \frac{\partial \log T(k_{1})}{\partial \log k_{1}} (10 + 7f\mu_{1}^{2} + 4\mu_{13}^{2}) \right]
$$
  
- 7T(k\_{1}) \left\{ 3\mu\_{13} \left[ 6 + \left( 8 + \frac{k\_{1}^{2}}{P(k\_{1})} \frac{\partial^{2} P(k\_{1})}{\partial k\_{1}^{2}} \right) f\mu\_{1}^{2} - \frac{\partial \log P(k\_{1})}{\partial \log k\_{1}} (3 + 5f\mu\_{1}^{2}) \right] \right.  
+ \mu\_{13}^{3} \left( -24 - 48f\mu\_{1}^{2} + \frac{k\_{1}^{3}}{P(k\_{1})} \frac{\partial^{3} P(k\_{1})}{\partial k\_{1}^{3}} f\mu\_{1}^{2} - 3 \frac{k\_{1}^{2}}{P(k\_{1})} \frac{\partial^{2} P(k\_{1})}{\partial k\_{1}^{2}} (1 + 3f\mu\_{1}^{2}) + 3 \frac{\partial \log P(k\_{1})}{\partial \log k\_{1}} (5 + 11f\mu\_{1}^{2}) \right) \right.  
+ 3f\mu\_{1}\mu\_{3} \left( -2 + \frac{\partial \log P(k\_{1})}{\partial \log k\_{1}} \right) + 3f\mu\_{1}\mu\_{3}\mu\_{13}^{2} \left( 8 - 5 \frac{\partial \log P(k\_{1})}{\partial \log k\_{1}} + \frac{k\_{1}^{2}}{P(k\_{1})} \frac{\partial^{2} P(k\_{1})}{\partial k\_{1}^{2}} \right) \right\}, \tag{B9}

$$
\mathcal{F}_{1,\phi\delta}^{(-1)}(\mathbf{k}_1,\mathbf{k}_3) = -42T(k_1)\frac{\partial \log P(k_1)}{\partial \log k_1}\mu_{13},\tag{B10}
$$

$$
\mathcal{F}_{1,\phi\delta}^{(0)}(\mathbf{k}_1,\mathbf{k}_3) = -7T(k_1)\left(3\frac{k_1^2}{P(k_1)}\frac{\partial^2 P(k_1)}{\partial k_1^2}\mu_{13}^2 - 3\frac{\partial \log P(k_1)}{\partial \log k_1}(-1+\mu_{13}^2)\right),\tag{B11}
$$

$$
\mathcal{F}_{1,\phi\delta}^{(1)}(\boldsymbol{k}_{1},\boldsymbol{k}_{3}) = 7\mu_{13} \bigg[ 6\bigg(2 - \frac{\partial \log P(k_{1})}{\partial \log k_{1}} + \frac{\partial \log T(k_{1})}{\partial \log k_{1}}\bigg) - T(k_{1})\bigg(3\frac{k_{1}^{2}}{P(k_{1})}\frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}} - 3\frac{k_{1}^{2}}{P(k_{1})}\frac{\partial^{2} P(k_{1})}{\partial k_{1}^{2}}\mu_{13}^{2} + \frac{k_{1}^{3}}{P(k_{1})}\frac{\partial^{3} P(k_{1})}{\partial k_{1}^{3}}\mu_{13}^{2} + 3\frac{\partial \log P(k_{1})}{\partial \log k_{1}}(-1 + \mu_{13}^{2})\bigg) \bigg], \quad (B12)
$$

$$
\mathcal{F}_{\phi,2}^{(1)}(\mathbf{k}_1,\mathbf{k}_3) = -42\mu_{13} \left( -2 + \frac{\partial \log P(k_1)}{\partial \log k_1} - \frac{\partial \log T(k_1)}{\partial \log k_1} \right),\tag{B13}
$$

$$
\mathcal{F}_{\phi,K^2}^{(1)}(\mathbf{k}_1,\mathbf{k}_3) = -28\mu_{13} \left( 8 + \frac{\partial \log T(\mathbf{k}_1)}{\partial \log \mathbf{k}_1} - 12\mu_{13}^2 - 3\frac{\partial \log T(\mathbf{k}_1)}{\partial \log \mathbf{k}_1} \mu_{13}^2 + \frac{\partial \log P(\mathbf{k}_1)}{\partial \log \mathbf{k}_1} (-1 + 3\mu_{13}^2) \right). \tag{B14}
$$

## APPENDIX C: BIAS PARAMETERS

<span id="page-16-0"></span>In this paper, the second-order biases have been linked to the linear-order one by means of the fitting formula and the local-in-matter-density relation, respectively [[31](#page-18-16),[68](#page-19-19)],

$$
b_2(b_1) = 0.412 - 2.143b1 + 0.929b1^2 + 0.008b1^3, (C1)
$$

$$
b_{K^2}(b_1) = -\frac{2}{7}(b_1 - 1),
$$
 (C2)

and the universal mass function relations

$$
b_{\phi} = 2\delta_{\rm cr}(b_1 - 1),\tag{C3}
$$

$$
b_{\phi\delta} = -b_{1,L} + \delta_{cr} b_{2,L} + b_{\phi}
$$
  
= 1 - b<sub>1</sub> + b<sub>\phi</sub> +  $\left(\frac{8}{21}(1 - b_1) + b_2\right)\delta_{cr}$ , (C4)

with  $\delta_{cr} = 1.686$ , and the Lagrangian biases being connected to the Eulerian ones as [\[35](#page-18-20)[,97,](#page-19-44)[98\]](#page-19-45)

$$
b_{1,L} = b_1 - 1,\t\t(C5)
$$

$$
b_{2,L} = b_2 - \frac{8}{21}(b_1 - 1).
$$
 (C6)

For generic type PnG, one needs to take a step back to the definition of the bias parameters as encoding the response of the galaxy overdensity to a change in the initial conditions, e.g., if one parametrizes this change as a rescaling of the initial density perturbation by  $(1 + 2\epsilon k^{-\alpha})$ , then

$$
b_{\psi\delta^N}^L = \frac{1}{N!} \frac{1}{\bar{n}_g} \frac{\partial^{N+1} \bar{n}_g}{\partial \Delta^N \partial \epsilon} \bigg|_{\Delta=0, \epsilon=0}, \tag{C7}
$$

where  $\Delta$  is the long-wavelength component of the over-density field [\[31,](#page-18-16)[99,](#page-19-46)[100](#page-19-47)]. The Eulerian bias parameters  $b_w$ and  $b_{\psi\delta}$  are obtained as [\[47](#page-19-2)[,101](#page-19-48)]

$$
b_{\psi} = \left[ b_{\phi} + 4 \left( \frac{\partial \ln \sigma_{-\alpha/2}^2}{\partial \ln \sigma^2} - 1 \right) \right] \frac{\sigma_{-\alpha/2}^2}{\sigma^2}, \qquad \text{(C8)}
$$

and

$$
b_{\psi\delta} = A \left[ \delta_{\rm cr} b_2 + \frac{17}{21} 2 \delta_{\rm cr} (b_1 - 1) + (b_1 + 1) \times \left( 2 \frac{\partial \ln \sigma_{-\alpha/2}^2}{\partial \ln \sigma^2} - 3 \right) + 2 \right] \frac{\sigma_{-\alpha/2}^2}{\sigma^2},
$$
 (C9)

with  $\alpha = 0$ ,  $A = 1$  for the local case and  $\alpha = 1$ ,  $A = -3$  for

the orthogonal case, and

$$
\sigma_n^2 = \int \frac{d^3k}{(2\pi)^3} k^n P(k) |W(k)|^2.
$$
 (C10)

### APPENDIX D: ESTIMATOR

<span id="page-17-0"></span>An estimator for the amplitude of the long mode was first proposed in [\[7\]](#page-18-2) and then applied in [[8\]](#page-18-3) to the antisymmetric case, in the null hypothesis where  $\langle \delta_1(\mathbf{k}_1)\delta_2(\mathbf{k}_2)\rangle$  is vanishing in the absence of the modulating field. In the case of biased clustering, however, the situation is different, and the procedure outlined there needs to be generalized.

To single out the antisymmetric part of the signal, the quantity of interest is, in discretized form [\[62\]](#page-19-14),

$$
\frac{1}{2} [\delta_1(\mathbf{k}_1)\delta_2(\mathbf{k}_2) - \delta_1(\mathbf{k}_2)\delta_2(\mathbf{k}_1)]
$$
  
=  $V_s \delta_{\mathbf{k}_1,\mathbf{k}_2,\mathbf{K}} \delta^*(\mathbf{K}) f_L^{\Delta}(\mathbf{k}_1,\mathbf{k}_2) \hat{\mathbf{K}} \cdot (\mathbf{k}_1 - \mathbf{k}_2),$  (D1)

where  $V_s \delta_{k_1,k_2,K} \stackrel{V \to \infty}{\longrightarrow} (2\pi)^3 \delta^{(3)}(k_1 + k_2 + K)$ .<br>Each pair  $k_1$ ,  $k_2$  provides an estimator (changing sign

of  $K$ )

$$
\widehat{\delta(\mathbf{K})} = \frac{1}{2} [\delta_1(\mathbf{k}_1) \delta_2(\mathbf{k}_2) - \delta_1(\mathbf{k}_2) \delta_2(\mathbf{k}_1)] [f_L^{\mathbf{A}}(\mathbf{k}_1, \mathbf{k}_2) \hat{\mathbf{K}} \cdot (\mathbf{k}_1 - \mathbf{k}_2)]^{-1}.
$$
 (D2)

The variance of the antisymmetrized combination of density fluctuations is

$$
\frac{1}{4} \langle (\delta_1(\mathbf{k}_1)\delta_2(\mathbf{k}_2) - \delta_1(\mathbf{k}_2)\delta_2(\mathbf{k}_1)) (\delta_1(\mathbf{k}'_1)\delta_2(\mathbf{k}'_2) - \delta_1(\mathbf{k}'_2)\delta_2(\mathbf{k}'_1)) \rangle + \n- \langle \delta_1(\mathbf{k}_1)\delta_2(\mathbf{k}_2) - \delta_1(\mathbf{k}_2)\delta_2(\mathbf{k}_1) \rangle \langle \delta_1(\mathbf{k}'_1)\delta_2(\mathbf{k}'_2) - \delta_1(\mathbf{k}'_2)\delta_2(\mathbf{k}'_1) \rangle \n= \frac{1}{4} [P_1(k_1)P_2(k_2) + P_1(k_2)P_2(k_1) - 2P_{12}(k_1)P_{12}(k_2)] (\delta_{k_1 + k'_1}^D \delta_{k_1 + k'_2}^D - \delta_{k_1 + k'_2}^D \delta_{k'_1 + k_2}^D),
$$
\n(D3)

where  $k_2 = K - k_1$  and  $k_2' = K - k_1'$ . The term  $[f_L^A(k_1', k_2')\hat{K} \cdot (k_1' - k_2')]^{-1}$  picks up a negative sign from the second combination of Dirac delta's so that the overall variance gets a factor 2 and becomes combination of Dirac delta's, so that the overall variance gets a factor 2 and becomes

$$
\frac{V_s}{2} [f_L^A(\mathbf{k}_1, \mathbf{k}_2) \hat{\mathbf{K}} \cdot (\mathbf{k}_1 - \mathbf{k}_2)]^{-2} (P_1(k_1) P_2(k_2) + P_1(k_2) P_2(k_1) - 2P_{12}(k_1) P_{12}(k_2)).
$$
\n(D4)

The optimal estimator is obtained by summing over all modes with inverse variance weightings

$$
\widehat{\delta(\mathbf{K})} = P_n(\mathbf{K}) \sum_{\mathbf{k}} \frac{[f_L^{\mathbf{A}}(\mathbf{k}_1, \mathbf{k}_2) \hat{\mathbf{K}} \cdot (\mathbf{k}_1 - \mathbf{k}_2)]}{\frac{V_s}{2} (P_1(\mathbf{k}_1) P_2(\mathbf{k}_2) + P_1(\mathbf{k}_2) P_2(\mathbf{k}_1) - 2 P_{12}(\mathbf{k}_1) P_{12}(\mathbf{k}_2))} \frac{1}{2} [\delta_1(\mathbf{k}_1) \delta_2(\mathbf{k}_2) - \delta_1(\mathbf{k}_2) \delta_2(\mathbf{k}_1)],
$$
\n
$$
P_n(\mathbf{K}) = \left[ \sum_{\mathbf{k}} \frac{[f_L^{\mathbf{A}}(\mathbf{k}_1, \mathbf{k}_2) \hat{\mathbf{K}} \cdot (\mathbf{k}_1 - \mathbf{k}_2)]^2}{\frac{V_s}{2} (P_1(\mathbf{k}_1) P_2(\mathbf{k}_2) + P_1(\mathbf{k}_2) P_2(\mathbf{k}_1) - 2 P_{12}(\mathbf{k}_1) P_{12}(\mathbf{k}_2))} \right]^{-1}.
$$
\n(D5)

Since  $\langle |\widehat{\delta(K)}|^2 \rangle = V_s(P(K) + P_n(K))$ , if one parametrizes  $P(K) = AP_f(K)$  with a fiducial power spectrum  $P_f(K)$ , each provides an estimator for the amplitude  $K$  provides an estimator for the amplitude

$$
\hat{A}_K = P_f(K)^{-1} \left( V_s^{-1} |\widehat{\delta(K)}|^2 - P_n(K) \right),\tag{D6}
$$

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so the optimal estimator is

$$
\hat{A} = \sigma^2 \sum_{K} \frac{P_f(K)}{2(P_n(K))^2} (V_s^{-1} |\widehat{\delta(K)}|^2 - P_n(K)), \quad (D7)
$$

$$
\sigma^{-2} = \sum_{K} \frac{(P_f(K))^2}{2(P_n(K))^2}.
$$
 (D8)

The quantity  $\sigma$  roughly represents the sensitivity to the amplitude of the underlying long mode power spectrum and therefore can be used to get an estimate of the detection threshold of the modulation effect.

The sum over Fourier modes becomes  $\sum_k \mapsto$ The sum over Fourier modes becomes  $\sum_k \mapsto$ <br> $V/(2\pi)^3 \int d^3k$ . For the short modes,  $V = V_s$  the survey volume. In order to restrict to squeezed configurations only, at a given long mode  $k_3$ , the lower integration limit is set to  $k_{\text{min}} = 10K$ , where 10 is the (arbitrarily chosen) minimum squeezing factor. As for the long modes, the sum over modes should account for all the large scales that, in principle, can modulate the two-point function on the scales  $k_1$ ,  $k_2$ . Modes that are much larger than the survey will be degenerate with the background, therefore  $V \simeq V_s$ as well, and the lower integration limit can be taken to be of order the fundamental wave vector of the survey,  $K_{\min} \simeq 2\pi/V_s^{1/3}$ . Both integrations run up to  $k_{\max}$ . In practice, given the squeezing requirement, the integration over long modes stops at  $K_{\text{max}}=k_{\text{max}}/10$ .

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