

Quantum flux operators in higher spin theories

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We construct Carrollian higher spin field theories by reducing the bosonic Fronsdal theories in flat spacetime to future null infinity. We extend the Poincaré fluxes to quantum flux operators, which generate Carrollian diffeomorphism, namely supertranslation and superrotation. These flux operators form a closed symmetry algebra once including a helicity flux operator, which follows from higher spin superduality transformation. The superduality transformation is an angle-dependent transformation at future null infinity, which generalizes the usual electromagnetic duality transformation. The results agree with the lower spin cases when restricted to $s = 0, 1, 2$.

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I. INTRODUCTION

Recently, Carrollian manifolds [1,2] have received much attention due to their relations to null geometries. It has been shown that various physically interesting symmetries could be embedded into the geometric symmetry of Carrollian manifold [3–5], including the BMS groups [6–12], Newman-Unti group, etc. Moreover, the Carrollian diffeomorphism, which preserves the null structure of Carrollian manifolds, is nontrivial [13–15] since one can construct corresponding quantum flux operators at future null infinity for lower spin ($s = 0, 1, 2$) theories. The quantum flux operators are obtained by analyzing the Poincaré flux densities, which are radiated to future null infinity. They form a faithful representation of Carrollian diffeomorphism for scalar field theory up to an anomalous term, which is the intrinsic central charge of the theory. For massless theories with nonzero helicity, the superrotation calls for superduality transformation, and one should also consider the corresponding helicity flux operators. The results can also be extended to various null hypersurfaces in general dimensions [16].

In this paper, we will study the quantum flux operators associated with Carrollian diffeomorphism for higher spin (HS) theories ($s > 2$) in four dimensions. Although there is no nontrivial S matrix for flat space massless HS

theories [17–21], it is still valuable to study the HS theories on null hypersurfaces. At first, while there exist extensions of HS supertranslation and superrotation in the literature [22–25], it would be nice to show that the symmetry algebra found in the previous paper [15] still remains valid for general spin theories. Indeed, we find a similar helicity flux operator in the HS theory, which corresponds to superduality transformation at the null boundary. Actually, the electromagnetic duality, originating from the exploration of magnetic monopole by Dirac [26], has been extended to various vector theories [27–30], p -form gauge theories [31–33], gravitational theories [34–41], supersymmetric theories [42–45], and HS theories [46–53]. The superduality transformation is an angle-dependent generalization of the usual duality transformation. Secondly, there are consistent interacting HS gauge theories in AdS (dS) spacetime [54–57], and the result in this paper is expected to be valid for more general null hypersurfaces. Third, interacting HS theories in flat spacetime indeed exist [58–66], and this work may provide insight on the analysis of these theories at future null infinity. Finally, the construction of Carrollian HS theories is an interesting topic in its own right.

The structure of the paper is as follows. In Sec. II, we will introduce the basic ingredients of the Carrollian manifold and review the coordinate systems we adopt in this article. In Sec. III, we will introduce minimal background on the Fronsdal theory in the flat spacetime. In Sec. IV, we will reduce the bulk HS theories to future null infinity and find the boundary equation of motion as well as the symplectic form. We will construct quantum flux operators and compute the Lie algebra they generate in the following section. The helicity flux operator is discussed in Sec. VI. We will conclude in Sec. VII, and technical details are relegated to several appendices.

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II. CARROLLIAN MANIFOLD AND COORDINATE SYSTEMS

In this work, we will use the Greek alphabet $\mu, \nu, \rho, \sigma, \lambda, \kappa$ to denote tensor components in Cartesian coordinates. For example, the Minkowski spacetime $\mathbb{R}^{1,3}$ can be described in Cartesian coordinates $x^\mu = (t, x^i)$

$$ds^2 = -dt^2 + dx^i dx^i = \eta_{\mu\nu} dx^\mu dx^\nu, \quad (2.1)$$

where $\mu = 0, 1, 2, 3$ denotes the spacetime components, and $i = 1, 2, 3$ labels the spatial directions. We will also use the Greek alphabet $\alpha, \beta, \gamma, \delta$ to represent components in retarded coordinates. As an illustration, the metric of the Minkowski spacetime in retarded coordinates $x^\alpha = (u, r, \theta, \phi)$ is

$$ds^2 = -du^2 - 2dudr + r^2 \gamma_{AB} d\theta^A d\theta^B, \quad A, B = 1, 2. \quad (2.2)$$

The capital Latin alphabet A, B, \dots will be used to represent the components of tensors on S^2 in spherical coordinates. The future null infinity \mathcal{I}^+ is a three-dimensional Carrollian manifold

$$\mathcal{I}^+ = \mathbb{R} \times S^2, \quad (2.3)$$

with a degenerate metric

$$ds_{\mathcal{I}^+}^2 \equiv \gamma = \gamma_{AB} d\theta^A d\theta^B, \quad (2.4)$$

which could be obtained by choosing a cutoff $r = R$, using a Weyl scaling to remove the conformal factor in the induced metric and taking the limit $R \rightarrow \infty$ with the retarded time u fixed. The spherical coordinates $\theta^A = (\theta, \phi)$ are used to describe the unit sphere whose metric reads explicitly as

$$\gamma_{AB} = \begin{pmatrix} 1 & 0 \\ 0 & \sin^2 \theta \end{pmatrix}. \quad (2.5)$$

We will also use the notation $\Omega = (\theta, \phi)$ to denote the spherical coordinates in the context. The covariant derivative ∇_A is adapted to the metric γ_{AB} , while ∇_μ adapts to the Minkowski metric in Cartesian frame. The integral measure on \mathcal{I}^+ is abbreviated as

$$\int dud\Omega \equiv \int_{-\infty}^{\infty} du \int_{S^2} d\Omega, \quad (2.6)$$

where the integral measure on S^2 is

$$\int d\Omega \equiv \int_{S^2} d\Omega = \int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\phi. \quad (2.7)$$

The Levi-Civita tensor on S^2 is denoted as $\epsilon = \frac{1}{2} \epsilon_{AB} d\theta^A \wedge d\theta^B$, with

$$\epsilon_{\theta\phi} = -\epsilon_{\phi\theta} = \sin \theta, \quad \epsilon_{\theta\theta} = \epsilon_{\phi\phi} = 0. \quad (2.8)$$

The Dirac delta function on S^2 is

$$\delta(\Omega - \Omega') = \sin^{-1} \theta \delta(\theta - \theta') \delta(\phi - \phi'). \quad (2.9)$$

Besides the metric (2.4), there is also a distinguished null vector

$$\chi = \partial_u, \quad (2.10)$$

which generates the retarded time direction. The Carrollian diffeomorphism is generated by the vector field

$$\xi_{f,Y} = f(u, \Omega) \partial_u + Y^A(\Omega) \partial_A, \quad (2.11)$$

where $f = f(u, \Omega)$ is any smooth function of \mathcal{I}^+ , while $Y^A = Y^A(\Omega)$ is time independent and only a smooth vector field on S^2 . The Carrollian diffeomorphism generated by $\xi_f = f(u, \Omega) \partial_u$ is called general supertranslation (GST), while the one generated by $\xi_Y = Y^A(\Omega) \partial_A$ is referred to special superrotation (SSR).

In the following, we may also use stereographic project coordinates on S^2 , which are defined by

$$z = \cot \frac{\theta}{2} e^{i\phi}, \quad \bar{z} = \cot \frac{\theta}{2} e^{-i\phi}, \quad (2.12)$$

and the metric of S^2 becomes

$$\gamma = 2\gamma dz d\bar{z}, \quad \gamma = \frac{2}{(1 + z\bar{z})^2}. \quad (2.13)$$

The volume form reads

$$d^2z \equiv -i\gamma dz \wedge d\bar{z}, \quad (2.14)$$

with the Levi-Civita tensor being

$$\epsilon_{z\bar{z}} = -\epsilon_{\bar{z}z} = -i\gamma, \quad \epsilon_{zz} = \epsilon_{\bar{z}\bar{z}} = 0. \quad (2.15)$$

The Dirac delta function is defined by

$$\delta^{(2)}(z - z') = i\gamma^{-1} \delta(z - z') \delta(\bar{z} - \bar{z}'). \quad (2.16)$$

In this coordinate system, any rank s symmetric traceless tensor $T_{A(s)}$ can only have two nonvanishing components

$$T_{z(s)}, \quad T_{\bar{z}(s)}. \quad (2.17)$$

Here, we use the short notation

$$T_{A(s)} = T_{(A_1 \dots A_s)} = \frac{1}{s!} \sum_{\pi \in S_s} T_{A_{\pi(1)} A_{\pi(2)} \dots A_{\pi(s)}}, \quad (2.18)$$

to represent a rank s symmetric tensor when it causes no confusion. The element of the permutation group S_s is denoted as π in the above equation. The round brackets (\dots) represent complete symmetrization for the indices inside them. Similarly, the square brackets $[\dots]$ imply complete antisymmetrization; e.g.,

$$T_{[AB]} = \frac{1}{2}(T_{AB} - T_{BA}). \quad (2.19)$$

We will also use the abbreviation

$$\nabla_A T_{A(s-1)} \equiv \frac{1}{s} \sum_{i=1}^s \nabla_{A_i} T_{A_1 \dots A_{i-1} A_{i+1} \dots A_s} = \nabla_{(A_1} T_{A_2 \dots A_s)}, \quad (2.20)$$

which is a slight abuse of notation. Here, the same lower (or upper) indices A_s are totally symmetrized automatically. One should not be confused with the Einstein summation convention where lower and upper indices are denoted by the same letter.

III. METRICLIKE FORMULATION

In this section, we shall review the metriclike formulation of free massless fields of arbitrary spin s . We shall mainly concentrate, however, only on bosonic fields [67] in flat spacetime, while leaving the fermionic HS fields [68] and HS fields in AdS or dS [69] spacetime for future study [70]. As a generalization of the electromagnetism and linearized Einstein gravity, a spin s HS gauge theory ($s > 2$) is described by a totally symmetric and doubly traceless Fronsdal field $f_{\mu(s)}$

$$f_{\mu(s)} = f_{\mu_1 \dots \mu_s} = f_{(\mu_1 \dots \mu_s)}, \quad f''_{\mu(s-4)} = 0, \quad (3.1)$$

where we use a prime to denote the trace of the HS field

$$f'_{\mu(s-2)} = \eta^{\mu(2)} f_{\mu(s)}. \quad (3.2)$$

Therefore, a double prime $f''_{\mu(s-4)}$ is the double trace of the HS field

$$f''_{\mu(s-4)} = \eta^{\mu(2)} \eta^{\mu(2)} f_{\mu(s)}. \quad (3.3)$$

A totally symmetric rank s field has¹

$$C_{s+d-1}^{d-1} = \frac{(s+d-1)!}{s!(d-1)!} \quad (3.4)$$

independent components in general d dimensions. Therefore, the number of independent components of a spin s field is

$$C_{s+d-1}^{d-1} - C_{s+d-5}^{d-1}. \quad (3.5)$$

In four dimensions, this number reduces to $2(1+s^2)$. The spin s field satisfies the Fronsdal equation

$$\mathcal{F}_{\mu(s)} \equiv \square f_{\mu(s)} - s \partial^\nu \partial_\nu f_{\mu(s-1)\nu} + \frac{1}{2} s(s-1) \partial_\mu \partial_\nu f'_{\mu(s-2)} = 0, \quad (3.6)$$

which is invariant under the linearized gauge transformation

$$\delta f_{\mu(s)} = s \partial_\mu \xi_{\mu(s-1)}, \quad (3.7)$$

where the rank $s-1$ tensor $\xi_{\mu(s-1)}$ is totally symmetric and traceless

$$\xi_{\mu(s-1)} = \xi_{(\mu_1 \dots \mu_{s-1})}, \quad \xi'_{\mu(s-3)} = 0. \quad (3.8)$$

The corresponding action is

$$S[f] = \int d^4x \mathcal{L}[f], \quad (3.9)$$

where the Lagrangian density is

$$\begin{aligned} \mathcal{L}[f] = & -\frac{1}{2} (\partial_\rho f_{\mu(s)})^2 + \frac{1}{2} s \partial_\alpha f_{\beta\mu(s-1)} \partial^\beta f^{\alpha\mu(s-1)} - \frac{1}{2} s(s-1) \partial_\nu f'_{\mu(s-2)} \partial_\rho f^{\nu\rho\mu(s-2)} \\ & + \frac{1}{4} s(s-1) (\partial_\rho f'_{\mu(s-2)})^2 + \frac{1}{8} s(s-1)(s-2) (\partial^\nu f'_{\mu(s-3)\nu})^2. \end{aligned} \quad (3.10)$$

The action reduces to the Pauli-Fierz action for $s=2$ and the Maxwell action for $s=1$. The Lagrangian density may be expressed as a compact quadratic form

$$\mathcal{L}[f] = L^{\rho\mu(s)\sigma\nu(s)} \partial_\rho f_{\mu(s)} \partial_\sigma f_{\nu(s)}, \quad (3.11)$$

where the rank $2s+2$ tensor $L^{\rho\mu(s)\sigma\nu(s)}$ is symmetric in the index sets $\mu(s)$ and $\nu(s)$ separately. It is also doubly traceless with respect to these two sets of indices

¹In Appendix A, we review this result in detail.

$$L''\rho\mu^{(s-4)\sigma\nu(s)} = 0, \quad L''\rho\mu^{(s)\sigma\nu(s-4)} = 0. \quad (3.12)$$

It may be obtained by taking the symmetric and doubly traceless part of the following rank $2s + 2$ tensor

$$\begin{aligned} \tilde{L}^{\mu_1 \dots \mu_s \nu_1 \dots \nu_s} &= -\frac{1}{2} \eta^{\mu\nu} \eta^{\mu_1 \nu_1} \dots \eta^{\mu_s \nu_s} + \frac{1}{2} s \eta^{\mu\nu_1} \eta^{\nu_1 \mu_1} \eta^{\mu_2 \nu_2} \dots \eta^{\mu_s \nu_s} \\ &+ \frac{1}{4} s(s-1) (-\eta^{\mu\mu_1} \eta^{\nu\mu_2} \eta^{\nu_1 \nu_2} - \eta^{\mu\nu_1} \eta^{\nu\nu_2} \eta^{\mu_1 \mu_2} + \eta^{\mu\nu} \eta^{\mu_1 \mu_2} \eta^{\nu_1 \nu_2}) \eta^{\mu_3 \nu_3} \dots \eta^{\mu_s \nu_s} \\ &+ \frac{1}{16} s(s-1)(s-2) (\eta^{\mu\mu_1} \eta^{\nu\nu_1} + \eta^{\mu\nu_1} \eta^{\nu\mu_1}) \eta^{\mu_2 \mu_3} \eta^{\nu_2 \nu_3} \eta^{\mu_4 \nu_4} \dots \eta^{\mu_s \nu_s}, \end{aligned} \quad (3.13)$$

with respect to two sets of indices $\mu(s)$ and $\nu(s)$ separately.

Gauge fixing condition. We may choose the following gauge fixing condition

$$\mathcal{G}_{\mu(s-1)} \equiv \partial^\nu f_{\mu(s-1)\nu} - \frac{s-1}{2} \partial_\mu f'_{\mu(s-1)} = 0, \quad (3.14)$$

to reduce the Fronsdal equation to

$$\partial^2 f_{\mu(s)} = 0. \quad (3.15)$$

The gauge fixing condition (3.14) is always possible. More explicitly, we may start from a general field configuration with $\mathcal{G}_{\mu(s-1)} \neq 0$ and choose the gauge parameter $\xi_{\mu(s-1)}$ such that

$$\mathcal{G}_{\mu(s-1)} + \partial^\nu \delta f_{\mu(s-1)\nu} - \frac{s-1}{2} \partial_\mu \delta f'_{\mu(s-2)} = 0. \quad (3.16)$$

This is equivalent to the equation

$$\partial^2 \xi_{\mu(s-1)} = -\mathcal{G}_{\mu(s-1)}, \quad (3.17)$$

whose solution always exists after imposing appropriate initial and boundary conditions. The residue gauge parameter should satisfy the equation

$$\partial^2 \xi_{\mu(s-1)} = 0, \quad (3.18)$$

which could be used to set the Fronsdal field to be traceless

$$f'_{\mu(s-2)} = 0. \quad (3.19)$$

This is always possible since the solution of (3.15) and (3.18) is

$$f_{\mu(s)} = \varepsilon_{\mu(s)}(\mathbf{k}) e^{ik \cdot x}, \quad \xi_{\mu(s-1)} = \kappa_{\mu(s-1)}(\mathbf{k}) e^{ik \cdot x}, \quad k^2 = 0, \quad (3.20)$$

in terms of plane waves. There is no more constraint on the polarization tensors $\varepsilon_{\mu(s)}$ and $\kappa_{\mu(s-1)}$ except that $\kappa_{\mu(s-1)}$ is traceless and $\varepsilon_{\mu(s)}$ is doubly traceless

$$\kappa'_{\mu(s-3)} = 0, \quad \varepsilon''_{\mu(s-4)} = 0. \quad (3.21)$$

Considering a solution $f_{\mu(s)}$, which is not traceless

$$\varepsilon'_{\mu(s-2)} \neq 0, \quad (3.22)$$

we may always find a tensor $\kappa_{\mu(s-1)}$ such that

$$k^\nu \kappa_{\nu\mu(s-2)} = -\frac{1}{2} \varepsilon'_{\mu(s-2)}. \quad (3.23)$$

Therefore, we can always set the HS field to be transverse and traceless. The remaining number of degrees of freedom for the polarization tensor $\varepsilon_{\mu(s)}$ is

$$(C_{s+d-1}^{d-1} - C_{s+d-3}^{d-1}) - (C_{s+d-2}^{d-1} - C_{s+d-4}^{d-1}) = 2s + 1, \quad \text{for } d=4. \quad (3.24)$$

Similarly, the remaining number of degrees of freedom for the polarization tensor $\kappa_{\mu(s)}$ is $2s - 1$. We may impose a further condition

$$n^\nu f_{\nu\mu(s-1)} = 0, \quad (3.25)$$

to reduce the number of degrees of freedom to 2. This is the number of propagating degrees of freedom in four dimensions. When we reduce the theory to future null infinity, the fundamental field $F_{A(s)}$ that encodes the radiation information has exactly two independent components (see the next section). The condition (3.25) in retarded coordinates becomes

$$f_{r\alpha(s-1)} = 0. \quad (3.26)$$

Such a condition requires

$$\varepsilon_{r\alpha(s-1)} + s k_{(r} \kappa_{\alpha(s-1))} = 0, \quad (3.27)$$

which has $2s - 1$ components and will exhaust the degrees of freedom of $\kappa_{\alpha(s-1)}$.

IV. ASYMPTOTIC EQUATION OF MOTION AND SYMLECTIC FORM

Near \mathcal{I}^+ , we may impose the falloff condition

$$f_{\mu(s)} = \sum_{k=1}^{\infty} \frac{F_{\mu(s)}^{(k)}}{r^k} \quad (4.1)$$

for the HS field in Cartesian coordinates. We will abbreviate the leading coefficient as

$$F_{\mu(s)} = F_{\mu(s)}^{(1)}. \quad (4.2)$$

The transformations between retarded and Cartesian coordinates are

$$J^\alpha_{\ \mu} \equiv \frac{\partial x^\alpha}{\partial x^\mu} = -n_\mu \delta_u^\alpha + m_\mu \delta_r^\alpha - \frac{1}{r} Y^\alpha_A \delta_A^\alpha, \quad (4.3a)$$

$$\bar{J}^\mu_{\ \alpha} \equiv \frac{\partial x^\mu}{\partial x^\alpha} = \bar{m}^\mu \delta_\alpha^u + n^\mu \delta_\alpha^r - r Y^\mu_A \delta_\alpha^A, \quad (4.3b)$$

where these newly appearing vectors can be found in Appendix B. The components of the HS field in retarded coordinates can be expressed as

$$f_{\alpha(s)} = \bar{J}^{\mu(s)}_{\ \alpha(s)} f_{\mu(s)}, \quad (4.4)$$

where we have used the notation

$$\bar{J}^{\mu(s)}_{\ \alpha(s)} = \bar{J}^{\mu_1}_{\ \alpha_1} \cdots \bar{J}^{\mu_s}_{\ \alpha_s}. \quad (4.5)$$

By introducing the symbols

$$N^\alpha_{\ \mu} = -n_\mu \delta_u^\alpha + m_\mu \delta_r^\alpha - Y^\alpha_A \delta_A^\alpha, \quad (4.6a)$$

$$\bar{N}^\mu_{\ \alpha} = \bar{m}^\mu \delta_\alpha^u + n^\mu \delta_\alpha^r - Y^\mu_A \delta_\alpha^A, \quad (4.6b)$$

we may define an infinite tower of fields $F_{\alpha(s)}^{(k)}$ on \mathcal{I}^+ through the relation

$$f_{\mu(s)} = \sum_{k=1}^{\infty} r^{-k} N^{\alpha(s)}_{\ \mu(s)} F_{\alpha(s)}^{(k)}, \quad (4.7)$$

where $N^{\alpha(s)}_{\ \mu(s)}$ used the same convention as (4.5). Similar to (4.2), we will always denote

$$F_{\alpha(s)} = F_{\alpha(s)}^{(1)}. \quad (4.8)$$

Combining (4.4) with (4.7), we find

$$f_{\alpha(s)} = \bar{J}^{\mu(s)}_{\ \alpha(s)} N^{\beta(s)}_{\ \mu(s)} \sum_{k=1}^{\infty} r^{-k} F_{\beta(s)}^{(k)}. \quad (4.9)$$

Using the identities in Appendix B, the falloff conditions (4.1) are transformed to

$$\begin{aligned} f_{A(m)\hat{\alpha}(s-m)} &= r^m \sum_{k=1}^{\infty} \frac{F_{A(m)\hat{\alpha}(s-m)}^{(k)}}{r^k} \\ &= r^{m-1} F_{A(m)\hat{\alpha}(s-m)} + \mathcal{O}(r^{m-2}), \quad m=0,1,\dots,s \end{aligned} \quad (4.10)$$

where the indices $\hat{\alpha}$ may be chosen as u or r . Note that when $m=s$, the falloff condition for the totally angular components is

$$f_{A(s)} = r^{s-1} F_{A(s)} + \cdots, \quad (4.11)$$

which agrees with the lower spin cases ($s=0,1,2$).

A. Asymptotic expansions of gauge conditions and EOM

As has been mentioned, we may impose the following gauge conditions:

$$\partial^\nu f_{\nu\mu(s-1)} = 0, \quad f'_{\mu(s-2)} = 0, \quad n^\nu f_{\nu\mu(s-1)} = 0, \quad (4.12)$$

for free HS gauge theory without sources. In retarded coordinates, the third condition leads to

$$F_{r\alpha(s-1)}^{(k)} = 0, \quad k=1,2,\dots. \quad (4.13)$$

Moreover, the traceless condition (3.19) becomes

$$-2f_{u\alpha(s-2)} + f_{r\alpha(s-2)} + r^{-2} \gamma^{AB} f_{AB\alpha(s-2)} = 0, \quad (4.14)$$

and it follows that

$$\gamma^{AB} f_{AB\alpha(s-2)} = 0. \quad (4.15)$$

This is the traceless condition on the sphere S^2 , which is equivalent to

$$\gamma^{AB} \sum_{k=1}^{\infty} r^{-k} F_{ABC(s-2)}^{(k)} = 0 \Rightarrow \gamma^{AB} F_{ABC(s-2)}^{(k)} = 0, \quad k=1,2,\dots. \quad (4.16)$$

The transverse condition (3.25) is

$$\begin{aligned} 0 &= \partial^\nu f_{\nu\mu(s-1)} = \left(-n^\nu \partial_u + m^\nu \partial_r - \frac{1}{r} Y^\nu_A \nabla^A \right) \\ &\quad \times \left[N^{\alpha(s)}_{\ \mu(s-1)\nu} \sum_{k=1}^{\infty} r^{-k} F_{\alpha(s)}^{(k)} \right], \end{aligned} \quad (4.17)$$

where

$$N^{\alpha(s)}_{\mu(s-1)\nu} = N^{\alpha(s-1)}_{\mu(s-1)} N^{\alpha s}_{\nu}. \quad (4.18)$$

Using the identities which are shown in Appendix B, we find

$$(k-2)N^{\alpha(s-1)}_{\mu(s-1)} F_{u\alpha(s-1)}^{(k)} + \nabla^A [N^{\alpha(s-1)}_{\mu(s-1)} F_{A\alpha(s-1)}^{(k)}] = 0, \quad k=1, 2, \dots \quad (4.19)$$

By multiplying the inverse tensor $\bar{N}^{\mu(s-1)}_{\beta(s-1)}$, the above equation becomes

$$(k-2)F_{u\beta(s-1)}^{(k)} - (s-1)\delta_{\beta}^A F_{\beta(s-2)Au}^{(k)} + \nabla^C F_{C\beta(s-1)}^{(k)} = 0. \quad (4.20)$$

(1) For $\beta(s-1) = u(s-1)$, we find

$$(k-2)F_{u(s)}^{(k)} = -\nabla^C F_{Cu(s-1)}^{(k)}. \quad (4.21)$$

The components $F_{u(s)}^{(k)}$ are completely fixed by

$$F_{u(s)}^{(k)} = -\frac{1}{k-2} \nabla^C F_{Cu(s-1)}^{(k)}, \quad (4.22)$$

except for $k=2$. When $k=2$, we have

$$\nabla^C F_{Cu(s-1)}^{(2)} = 0, \quad (4.23)$$

and $F_{u(s)}^{(2)}$ is free.

(2) In general, $\beta(s-1) = A(m)u(s-1-m)$, the equation (4.20) leads to

$$F_{A(m)u(s-m)}^{(k)} = -\frac{1}{k-2-m} \nabla^C F_{CA(m)u(s-1-m)}^{(k)}, \quad m=1, 2, \dots, s-1 \quad (4.24)$$

except for $k=2+m$.

Therefore, at least for $k=1$, all the components like $F_{u\alpha(s-1)}$ are either zero or determined by the symmetric and traceless one $F_{A(s)}$.

Asymptotic equation of motion. We still need to solve the EOM (3.15). From the identity

$$\partial^2 = -2\partial_u \partial_r - \frac{2}{r} \partial_u + \partial_r^2 + \frac{2}{r} \partial_r + \frac{1}{r^2} \nabla_A \nabla^A, \quad (4.25)$$

we find

$$\begin{aligned} \partial^2 f_{\mu(s)} &= \left[-2\partial_u \partial_r - \frac{2}{r} \partial_u + \partial_r^2 + \frac{2}{r} \partial_r + \frac{1}{r^2} \nabla_A \nabla^A \right] \left(N^{\alpha(s)}_{\mu(s)} \sum_{k=1}^{\infty} r^{-k} F_{\alpha(s)}^{(k)} \right) \\ &= \sum_{k \geq 1} r^{-k-1} \left[2(k-1)N^{\alpha(s)}_{\mu(s)} \dot{F}_{\alpha(s)}^{(k)} + (k-1)(k-2)N^{\alpha(s)}_{\mu(s)} F_{\alpha(s)}^{(k-1)} + \nabla^A \nabla_A (N^{\alpha(s)}_{\mu(s)} F_{\alpha(s)}^{(k-1)}) \right]. \end{aligned} \quad (4.26)$$

This leads to an infinite tower of equations for the boundary fields

$$2(k-1)\dot{F}_{\beta(s)}^{(k)} + (k-1)(k-2)F_{\beta(s)}^{(k-1)} + \bar{N}_{\beta(s)}^{\mu(s)} \nabla^A \nabla_A (N^{\alpha(s)}_{\mu(s)} F_{\alpha(s)}^{(k-1)}) = 0. \quad (4.27)$$

It is obvious that there is no dynamical equation for the mode with $k=1$, while all the descendants with $k \geq 2$ are determined through the boundary equations after imposing suitable initial conditions.

B. Symplectic form

We can find the presymplectic form from the variation principle

$$\delta S = \int \text{EOM} + \int (d^3x)_{\mu} \Theta^{\mu}, \quad (4.28)$$

where

$$\Theta^{\rho} = 2L^{\rho\mu(s)\sigma\nu(s)} \delta f_{\mu(s)} \partial_{\sigma} f_{\nu(s)}. \quad (4.29)$$

The symplectic form can be obtained by a further variation

$$\Omega^{\mathfrak{H}}(\delta f; \delta f; f) = 2 \int_{\mathfrak{H}} (d^3x)_{\rho} L^{\rho\mu(s)\sigma\nu(s)} \delta f_{\mu(s)} \wedge \partial_{\sigma} \delta f_{\nu(s)}, \quad (4.30)$$

where we have chosen a hypersurface \mathfrak{H} to evaluate the symplectic form. The symplectic form at \mathcal{I}^+ is the limit

$$\begin{aligned} \Omega(\delta F; \delta F; F) &= \lim_{r \rightarrow \infty, u \text{ fixed}} \Omega^{\mathfrak{H}_r}(\delta f; \delta f; f) \\ &= 2 \int dud\Omega_{\rho} L^{\rho\mu(s)\sigma\nu(s)} \delta F_{\mu(s)} \wedge (-n_{\sigma}) \delta \dot{F}_{\nu(s)} \\ &= \int dud\Omega \delta F_{A(s)} \wedge \delta \dot{F}^{A(s)}, \end{aligned} \quad (4.31)$$

where \mathfrak{H}_r is the constant r slice. It follows that the fundamental commutators are

$$[F_{A(s)}(u, \Omega), F_{B(s)}(u', \Omega')] = \frac{i}{2} X_{A(s)B(s)} \alpha(u - u') \delta(\Omega - \Omega'), \quad (4.32a)$$

$$[F_{A(s)}(u, \Omega), \dot{F}_{B(s)}(u', \Omega')] = \frac{i}{2} X_{A(s)B(s)} \delta(u - u') \delta(\Omega - \Omega'), \quad (4.32b)$$

$$[\dot{F}_{A(s)}(u, \Omega), \dot{F}_{B(s)}(u', \Omega')] = \frac{i}{2} X_{A(s)B(s)} \delta'(u - u') \delta(\Omega - \Omega'), \quad (4.32c)$$

where the function $\alpha(u - u')$ is

$$\alpha(u - u') = \frac{1}{2} [\theta(u' - u) - \theta(u - u')], \quad (4.33)$$

and the rank $2s$ tensor $X_{A(s)B(s)}$ is constructed by

$$X_{A(s)B(s)} = \frac{1}{s!} \sum_{\pi \in S_s} \tilde{X}_{A_1 \dots A_s B_{\pi(1)} \dots B_{\pi(s)}} - \text{traces}, \quad (4.34)$$

where

$$\tilde{X}_{A_1 \dots A_s B_1 \dots B_s} = \gamma_{A_1 B_1} \dots \gamma_{A_s B_s}. \quad (4.35)$$

It should be symmetric and traceless among the indices of the same letter²

$$\begin{aligned} X_{A(s)B(s)} &= X_{(A_1 \dots A_s)(B_1 \dots B_s)}, \\ \gamma^{A_1 A_2} X_{A(s)B(s)} &= \gamma^{B_1 B_2} X_{A(s)B(s)} = 0. \end{aligned} \quad (4.36)$$

The explicit form of $X^{A(s)B(s)}$ is³

$$\begin{aligned} X^{A(s)B(s)} &= \sum_{p, q=0}^{\lfloor s/2 \rfloor} a(p, q; s) \gamma^{A_1 A_2 \dots A_{2p}} \gamma^{A_{2p+1} \dots A_s} \\ &\quad \times \tilde{X}_{p, q}^{A_{2p+1} \dots A_s (B_{2q+1} \dots B_s \gamma^{B_1 B_2} \dots \gamma^{B_{2q-1} B_{2q}})}, \end{aligned} \quad (4.37)$$

with the coefficients $a(p, q; s)$ being

$$\begin{aligned} a(p, q; s) &= (-1)^{p+q} \frac{s! [2s - 2p - 2]!!}{2^p p! (s - 2p)! (2s - 2)!!} \\ &\quad \times \frac{s! [2s - 2q - 2]!!}{2^q q! (s - 2q)! (2s - 2)!!}. \end{aligned} \quad (4.38)$$

The commutators (4.32) can also be derived from canonical quantization, which we have checked in Appendix E.

²This property will be referred to as doubly symmetric traceless (concerning two sets of indices). We hope it will not cause confusion with the symmetric and doubly traceless Fronsdal field $f_{\mu(s)}$.

³We have derived this formula in Appendix D.

After defining the vacuum $|0\rangle$ through the annihilation operator in the boundary theory, we obtain the correlation functions

$$\langle 0 | F_{A(s)}(u, \Omega) F_{B(s)}(u', \Omega') | 0 \rangle = X_{A(s)B(s)} \beta(u - u') \delta(\Omega - \Omega'), \quad (4.39a)$$

$$\langle 0 | F_{A(s)}(u, \Omega) \dot{F}_{B(s)}(u', \Omega') | 0 \rangle = X_{A(s)B(s)} \frac{\delta(\Omega - \Omega')}{4\pi(u - u' - i\epsilon)}, \quad (4.39b)$$

$$\langle 0 | \dot{F}_{A(s)}(u, \Omega) F_{B(s)}(u', \Omega') | 0 \rangle = -X_{A(s)B(s)} \frac{\delta(\Omega - \Omega')}{4\pi(u - u' - i\epsilon)}, \quad (4.39c)$$

$$\langle 0 | \dot{F}_{A(s)}(u, \Omega) \dot{F}_{B(s)}(u', \Omega') | 0 \rangle = -X_{A(s)B(s)} \frac{\delta(\Omega - \Omega')}{4\pi(u - u' - i\epsilon)^2}, \quad (4.39d)$$

where the function $\beta(u - u')$ is defined by

$$\beta(u - u') = \int_0^\infty \frac{d\omega}{4\pi\omega} e^{-i\omega(u - u' - i\epsilon)}. \quad (4.40)$$

V. QUANTUM FLUX OPERATORS

For any conserved current j^μ , one may construct the corresponding flux across a hypersurface \mathfrak{H} through the formula

$$\mathcal{F}[j] = \int_{\mathfrak{H}} (d^3x)_\mu j^\mu. \quad (5.1)$$

To find the Poincaré fluxes, the conserved current should be chosen as

$$j_\xi^\mu = T^\mu{}_\nu \xi^\nu, \quad (5.2)$$

where $T^{\mu\nu}$ is the stress tensor of the theory, and ξ is the Killing vectors of Minkowski spacetime. To discuss the fluxes radiated to \mathcal{I}^+ , we may choose constant r slices \mathfrak{H}_r in retarded coordinates and then take the limit $r \rightarrow \infty$ while keeping the retarded time u finite

$$\lim_+ = \lim_{r \rightarrow \infty, u \text{ finite}}. \quad (5.3)$$

It follows that the Poincaré fluxes at \mathcal{I}^+ are

$$\mathcal{F}_\xi = \lim_+ \int_{\mathfrak{H}_r} (d^3x)_\mu T^\mu{}_\nu \xi^\nu. \quad (5.4)$$

We may read out the flux density operators from the fluxes arrived at \mathcal{I}^+ per unit time and per unit solid angle. The

quantum flux operators are the (generalized) Fourier transformation of the normal-ordered flux density operators. However, the definition of the stress tensor in HS theories is rather subtle. The conserved gauge invariant Bel-Robinson tensor [71,72], a direct generalization of the canonical stress tensor, is not the quantity we sought for $s \geq 2$ since it has $2s$ derivatives. Though there are various discussions on the gauge invariant conserved currents in the literature [73–77], it is believed [78] that there is no gauge invariant stress tensor for $s \geq 2$ due to the no-go theorem of Weinberg and Witten [20]. However, there are gauge noninvariant conserved currents, akin to the Landau-Lifshitz pseudotensor [79] in general relativity, which give rise to the gauge invariant conserved charges [80]. Nevertheless, we will treat the HS fields as ordinary matter and use the formula

$$T_{\rho\sigma} = \frac{-2}{\sqrt{-g}} \frac{\delta S}{\delta g^{\rho\sigma}}, \quad (5.5)$$

to obtain the “stress tensor”. It turns out that this “stress tensor” leads to reasonable flux operators at \mathcal{I}^+ .

A. Fluxes

Substituting the Fronsdal action into (5.5), we find

$$\begin{aligned} T_{\rho\sigma} &= \frac{-2}{\sqrt{-g}} \frac{\delta S}{\delta g^{\rho\sigma}} \Big|_{g \rightarrow \eta} \\ &= \eta_{\rho\sigma} \mathcal{L}[f] - 2 \frac{\partial L^{\lambda\mu(s)\kappa\nu(s)}}{\partial g^{\rho\sigma}} \partial_\lambda f_{\mu(s)} \partial_\kappa f_{\nu(s)} \Big|_{g \rightarrow \eta}. \end{aligned} \quad (5.6)$$

With the conditions (3.14) and (3.19), only the first two terms in the Lagrangian density contribute to the stress tensor

$$\begin{aligned} T_{\rho\sigma} &= -\frac{1}{2} \eta_{\rho\sigma} \partial_\nu f_{\mu(s)} \partial^\nu f^{\mu(s)} + \frac{s}{2} \eta_{\rho\sigma} \partial_{\nu_1} f_{\nu_2 \mu(s-1)} \partial^{\nu_2} f^{\nu_1 \mu(s-1)} + \partial_\rho f_{\mu(s)} \partial_\sigma f^{\mu(s)} \\ &\quad + s \partial_\nu f_{\rho\mu(s-1)} \partial^\nu f_\sigma^{\mu(s-1)} - s [\partial_\rho f_{\mu(s-1)} \partial_\nu f_\sigma^{\mu(s-1)} + (\rho \leftrightarrow \sigma)] \\ &\quad - s(s-1) \partial_{\nu_1} f_{\rho\mu(s-2)}^{\nu_2} \partial_{\nu_2} f_\sigma^{\nu_1 \mu(s-2)}. \end{aligned} \quad (5.7)$$

The stress tensor can be expanded asymptotically near \mathcal{I}^+

$$T_{\rho\sigma} = \sum_{k=2}^{\infty} \frac{t_{\rho\sigma}^{(k)}}{r^k}, \quad (5.8)$$

where the first few orders are

$$t_{\rho\sigma}^{(2)} = n_\rho n_\sigma \dot{F}_{A(s)} \dot{F}^{A(s)}, \quad (5.9a)$$

$$t_{\rho\sigma}^{(3)} = n_\rho n_\sigma X_1 + n_{(\rho} Y_{\sigma)}^C X_C + Y_{(\rho}^B Y_{\sigma)}^C X_{BC} + \frac{d}{du} X_{\rho\sigma}, \quad (5.9b)$$

where

$$\begin{aligned} X_C &= 2\dot{F}_{A(s)} \nabla_C F^{A(s)} + 2(F_{CA(s-1)} \nabla_D \dot{F}^{DA(s-1)} - \dot{F}_{CA(s-1)} \nabla_D F^{DA(s-1)}) \\ &\quad - 2s(s\dot{F}_{uA(s-1)} F_C^{A(s-1)} + \dot{F}_{A(s)} \nabla^A F_C^{A(s-1)} + \dot{F}_{uA(s-1)} F_C^{A(s-1)} - F_{uA(s-1)} \dot{F}_C^{A(s-1)}), \end{aligned} \quad (5.10)$$

and the explicit form of X_1 , $X_{\rho\sigma}$ as well as X_{BC} are not important in this work. For more details on the calculation, we refer to Appendix C. We may compute the Poincaré fluxes generated by Killing vectors ξ

$$\mathcal{F}_\xi = \lim_{+} \int_{\mathfrak{S}_r} (d^3x)_\rho T^{\rho\sigma} \xi_\sigma. \quad (5.11)$$

For the spacetime translation generator labeled by a constant vector c^μ ,

$$\xi_c = c^\mu \partial_\mu, \quad (5.12)$$

we find energy and momentum fluxes

$$\begin{aligned} \mathcal{F}_{\xi_c} &= c^\nu \int dud\Omega m^\mu t_{\mu\nu}^{(2)} \\ &= c^\mu \int dud\Omega n_\mu \dot{F}_{A(s)} \dot{F}^{A(s)}. \end{aligned} \quad (5.13)$$

For the Lorentz transformation generator,

$$\begin{aligned} \xi_\omega &= \omega^{\mu\nu} (x_\mu \partial_\nu - x_\nu \partial_\mu) \Leftrightarrow \\ \xi_\omega^\sigma &= \omega^{\mu\nu} [(rn_\mu + u\tilde{m}_\mu) \delta_\nu^\sigma - (rn_\nu + u\tilde{m}_\nu) \delta_\mu^\sigma], \end{aligned} \quad (5.14)$$

with $\omega^{\mu\nu}$ being a constant antisymmetric tensor; the angular momentum and center-of-mass fluxes are

$$\begin{aligned}
 \mathcal{F}_{\xi_\omega} &= \lim_+ \int_{\mathfrak{S}_r} dud\Omega m^\rho T_{\rho\sigma} \xi_\omega^\sigma \\
 &= \omega^{\mu\nu} \int dud\Omega m^\rho (\bar{m}_\mu \delta_\nu^\sigma - \bar{m}_\nu \delta_\mu^\sigma) t_{\rho\sigma}^{(2)} \\
 &\quad + \omega^{\mu\nu} \int dud\Omega m^\rho (n_\mu \delta_\nu^\sigma - n_\nu \delta_\mu^\sigma) t_{\rho\sigma}^{(3)} \\
 &= \omega^{\mu\nu} \int dud\Omega \frac{u}{2} \nabla_A Y_{\mu\nu}^A \dot{F}_{A(s)} \dot{F}^{A(s)} \\
 &\quad - \frac{1}{2} \omega^{\mu\nu} \int dud\Omega Y_{\mu\nu}^A X_A. \tag{5.15}
 \end{aligned}$$

At the second line, we decompose $t_{\rho\sigma}^{(3)}$ as (5.9b). The total derivative term containing X_2 has no contribution after integration by parts. The terms proportional to $n_\rho n_\sigma$ or $Y_{(\rho}^B Y_{\sigma)}^C$ are also vanishing due to the identities

$$m^\rho (n_\mu \delta_\nu^\sigma - n_\nu \delta_\mu^\sigma) n_\rho n_\sigma = 0, \tag{5.16a}$$

$$m^\rho Y_\rho^A = 0. \tag{5.16b}$$

Using the relation,

$$F_{uA(s-1)} = \frac{1}{s} \nabla^C F_{CA(s-1)}, \tag{5.17}$$

the angular momentum and center-of-mass fluxes become

$$\begin{aligned}
 \mathcal{F}_{\xi_\omega} &= \omega^{\mu\nu} \int dud\Omega \frac{u}{2} \nabla_C Y_{\mu\nu}^C \dot{F}_{A(s)} \dot{F}^{A(s)} \\
 &\quad - \omega^{\mu\nu} \int dud\Omega Y_{\mu\nu}^D [\dot{F}_{A(s)} \nabla_D F^{A(s)} \\
 &\quad - s (\dot{F}_{CA(s-1)} \nabla^C F_D^{A(s-1)} - \dot{F}_D^{A(s-1)} \nabla^C F_{CA(s-1)})]. \tag{5.18}
 \end{aligned}$$

From the Poincaré fluxes, we find the following two flux density operators:

$$T(u, \Omega) = : \dot{F}_{A(s)} \dot{F}^{A(s)} : , \tag{5.19a}$$

$$M_A(u, \Omega) = \frac{1}{2} P_{AB(s)CD(s)} (: \dot{F}^{B(s)} \nabla^C F^{D(s)} - F^{B(s)} \nabla^C \dot{F}^{D(s)} :). \tag{5.19b}$$

The tensor $P_{AB(s)CD(s)}$ is doubly symmetric traceless

$$P_{AB(s)CD(s)} = P_{A(B_1 \dots B_s) C D_1 \dots D_s} = P_{AB_1 \dots B_s C(D_1 \dots D_s)}, \tag{5.20a}$$

$$P_{AB(s)CD(s)} \gamma^{B(2)} = P_{AB(s)CD(s)} \gamma^{D(2)} = 0, \tag{5.20b}$$

and can be obtained from the following tensor:

$$\begin{aligned}
 \tilde{P}_{AB_1 \dots B_s CD_1 \dots D_s} \\
 = (\gamma_{AC} \gamma_{B_1 D_1} + s \gamma_{AB_1} \gamma_{CD_1} - s \gamma_{AD_1} \gamma_{CB_1}) \gamma_{B_2 D_2} \dots \gamma_{B_s D_s}. \tag{5.21}
 \end{aligned}$$

We have discussed this tensor extensively in Appendix D. We have added the normal ordering symbol $:\dots:$ to remove the annihilation operators to the right-hand side of the creation operators. Similar to the lower spin cases, two smeared quantum flux operators can be defined as

$$\mathcal{T}_f = \int dud\Omega f(u, \Omega) T(u, \Omega), \tag{5.22a}$$

$$\mathcal{M}_Y = \int dud\Omega Y^A(u, \Omega) M_A(u, \Omega), \tag{5.22b}$$

where the function f and vector Y^A can be time and angle dependent.

B. Supertranslations and superrotations

The commutators between the quantum flux operators (5.22) and the fundamental field $F_{A(s)}$ are

$$[\mathcal{T}_f, F_{A(s)}(u, \Omega)] = -if(u, \Omega) \dot{F}_{A(s)}(u, \Omega), \tag{5.23a}$$

$$\begin{aligned}
 [\mathcal{M}_Y, F_{A(s)}(u, \Omega)] &= -i \Delta_{A(s)}(Y; F; u, \Omega) \\
 &\quad + \frac{i}{2} \int du' \alpha(u' - u) \Delta_{A(s)}(\dot{Y}; F; u', \Omega), \tag{5.23b}
 \end{aligned}$$

where

$$\begin{aligned}
 \Delta_{A(s)}(Y; F; u, \Omega) &= Y^D \nabla^C F^{B(s)} \rho_{DB(s)CA(s)} \\
 &\quad + \frac{1}{2} \nabla^C Y^D F^{B(s)} P_{DB(s)CA(s)}. \tag{5.24}
 \end{aligned}$$

The rank $2s + 2$ tensor $\rho_{AB(s)CD(s)}$ is

$$\rho_{AB(s)CD(s)} = \frac{1}{2} (P_{AB(s)CD(s)} + P_{AD(s)CB(s)}) = \gamma_{AC} X_{B(s)D(s)}. \tag{5.25}$$

After integration by part, the quantum flux operator \mathcal{M}_Y can be rewritten as

$$\mathcal{M}_Y = \int dud\Omega : \dot{F}^{A(s)}(u, \Omega) \Delta_{A(s)}(Y; F; u, \Omega) :. \tag{5.26}$$

When the test functions f and Y^A are time independent, the quantum flux operators can be interpreted as supertranslation and superrotation generators. In the literature, the supertranslation and superrotation vectors $\xi_{f,Y}$ are expanded as

$$\xi_f = f\partial_u + \frac{1}{2}\nabla_A\nabla^A f\partial_r - \frac{\nabla^A f}{r}\partial_A + \dots, \quad (5.27a)$$

$$\begin{aligned} \xi_Y = & \frac{1}{2}u\nabla_A Y^A\partial_u - \frac{1}{2}r\nabla_A Y^A\partial_r + \frac{u}{4}\nabla_C\nabla^C\nabla \cdot Y\partial_r \\ & + \left(Y^A - \frac{u}{2r}\nabla^A\nabla_B Y^B\right)\partial_A + \dots, \end{aligned} \quad (5.27b)$$

in asymptotically flat spacetime. The Lie derivative of the spin s field along the direction of $\xi_{f,Y}$ is

$$\mathcal{L}_{\xi}f_{\mu(s)} = \xi^\rho\partial_\rho f_{\mu(s)} + s\partial_\mu\xi^\rho f_{\mu(s-1)\rho}. \quad (5.28)$$

We can read out the variations of the fundamental field under supertranslation and superrotation from the leading order of the components $f_{A(s)}$ as

$$\delta_f F_{A(s)} = f\dot{F}_{A(s)}, \quad (5.29a)$$

$$\begin{aligned} \delta_Y F_{A(s)} = & \frac{1}{2}u\nabla_B Y^B\dot{F}_{A(s)} - \frac{1}{2}(s-1)\nabla_B Y^B F_{A(s)} \\ & + Y^B\nabla_B F_{A(s)} + sF_{A(s-1)C}\nabla_A Y^C. \end{aligned} \quad (5.29b)$$

For the supertranslation of the field $F_{A(s)}$, we find

$$\delta_f F_{A(s)} = i[\mathcal{T}_f, F_{A(s)}]. \quad (5.30)$$

We conclude that the quantum flux operator $i\mathcal{T}_f$ is the generator of supertranslation for f being time independent. For the superrotation of the field $F_{A(s)}$, we should replace the variation (5.29b) induced by Lie derivative with the covariant variation [14,15]

$$\delta_Y F_{B(s)} = \delta_Y F_{B(s)} - s\Gamma^A_B(Y)F_{AB(s-1)}, \quad (5.31)$$

where the connection is a symmetric traceless tensor

$$\Gamma_{AB}(Y) = \frac{1}{2}\Theta_{AB}(Y) = \frac{1}{2}(\nabla_A Y_B + \nabla_B Y_A - \gamma_{AB}\nabla_C Y^C). \quad (5.32)$$

After some algebra, we find

$$\delta_Y F_{A(s)} = i[\mathcal{M}_Y, F_{A(s)}] + i[\mathcal{T}_{f=\frac{1}{2}u\nabla_C Y^C}, F_{A(s)}], \quad (5.33)$$

for Y^A being time independent. In this case, after subtracting a term related to supertranslation, the quantum flux operator $i\mathcal{M}_Y$ should be regarded as the generator of superrotation. As a consistency check, one can show that \mathcal{T}_f and \mathcal{M}_Y may also be derived from the Hamilton equation $\delta H_\xi = i_\xi\Omega$ using the above variations.

In [13–15], the supertranslation and superrotation generators have been extended through quantum flux operators by including the time dependencies for the functions f and vectors Y . However, closing the algebra requires $\dot{Y} = 0$, and then we realize the Carrollian diffeomorphism (intertwined with superduality transformation), which will be shown in the next subsection for the higher spin theory. It has also been extended in general dimensions and general null hypersurfaces in [16].

C. The algebra among flux operators

Now it is straightforward to compute the commutators for the quantum flux operators

$$[\mathcal{T}_{f_1}, \mathcal{T}_{f_2}] = C_T(f_1, f_2) + i\mathcal{T}_{f_1\dot{f}_2 - f_2\dot{f}_1}, \quad (5.34a)$$

$$\begin{aligned} [\mathcal{T}_f, \mathcal{M}_Y] = & -i\mathcal{T}_{Y^A\nabla_A f} + i\mathcal{M}_{f\dot{Y}} + \frac{i}{2}s\mathcal{O}_{\dot{Y}^A\nabla^B f\epsilon_{BA}} \\ & + \frac{i}{4}\mathcal{Q}_{\frac{d}{du}(\dot{Y}^A\nabla_A f)}, \end{aligned} \quad (5.34b)$$

$$[\mathcal{M}_Y, \mathcal{M}_Z] = C_M(Y, Z) + i\mathcal{M}_{[Y,Z]} + is\mathcal{O}_{o(Y,Z)} + N_M(Y, Z), \quad (5.34c)$$

$$[\mathcal{T}_f, \mathcal{O}_g] = i\mathcal{O}_{fg}, \quad (5.34d)$$

$$[\mathcal{M}_Y, \mathcal{O}_g] = C_{MO}(Y, g) + i\mathcal{O}_{Y^A\nabla_A g} + N_{MO}(Y, g), \quad (5.34e)$$

$$[\mathcal{O}_{g_1}, \mathcal{O}_{g_2}] = C_O(g_1, g_2) + N_O(g_1, g_2). \quad (5.34f)$$

The results are quite similar to the lower spin cases. We will discuss these commutators term by term.

(1) New local operators. The operator \mathcal{O}_g is

$$\begin{aligned} \mathcal{O}_g = & \int dud\Omega g(u, \Omega): \dot{F}^{DB(s-1)}F_{B(s-1)}^E: \epsilon_{ED} \\ = & \int dud\Omega g(u, \Omega): \dot{F}^{DA(s-1)}F^{EB(s-1)}: \epsilon_{ED}\gamma_{A_1 B_1} \cdots \gamma_{A_s B_s}, \\ \equiv & \int dud\Omega g(u, \Omega): \dot{F}^{A(s)}F^{B(s)}: \mathcal{Q}_{A(s)B(s)}, \end{aligned} \quad (5.35)$$

where the rank $2s$ tensor $\mathcal{Q}_{A(s)B(s)}$ is doubly symmetric traceless

$$\begin{aligned}\mathcal{Q}_{A(s)B(s)} &= \mathcal{Q}_{(A_1 \dots A_s)(B_1 \dots B_s)}, \\ \gamma^{A(2)} \mathcal{Q}_{A(s)B(s)} &= \gamma^{B(2)} \mathcal{Q}_{A(s)B(s)} = 0.\end{aligned}\quad (5.36)$$

It can be obtained from the tensor $\epsilon_{B_1 A_1} \gamma_{A_2 B_2} \dots \gamma_{A_s B_s}$ using the formula in Appendix D. This operator is the helicity flux operator associated with HS duality transformation, which will be discussed in the next section. The other new operator \mathcal{Q}_h is defined as

$$\mathcal{Q}_h = \int dud\Omega h(u, \Omega) : F^{A(s)} F_{A(s)} : . \quad (5.37)$$

Its commutator with the fundamental field $F_{A(s)}$ is non-local, and we do not find a physical interpretation for this operator. Therefore, we will not pay more attention to it in the following.

- (2) The central terms come from two-point functions for the quantum flux operators

$$\mathcal{C}_T(f_1, f_2) = -\frac{i\delta^{(2)}(0)}{24\pi} \mathcal{I}_{f_1 f_2 - f_2 f_1}, \quad (5.38a)$$

$$\begin{aligned}\mathcal{C}_M(Y, Z) &= \int dud u' d\Omega d\Omega' Y^A(u, \Omega) Z^{B'}(u', \Omega') \\ &\times \Lambda_{AB'}^{(s)}(\Omega - \Omega') \eta(u - u'),\end{aligned}\quad (5.38b)$$

$$\begin{aligned}\mathcal{C}_{MO}(Y, g) &= -2s\delta^{(2)}(0) \int dud u' d\Omega Y^A(u, \Omega) \\ &\times \nabla^B g(u', \Omega) \epsilon_{AB} \eta(u - u'),\end{aligned}\quad (5.38c)$$

$$\begin{aligned}\mathcal{C}_O(g_1, g_2) &= 4\delta^{(2)}(0) \int dud u' d\Omega \eta(u - u') \\ &\times g_1(u, \Omega) g_2(u', \Omega),\end{aligned}\quad (5.38d)$$

where

$$\eta(u - u') = -\frac{\beta(u - u') - \frac{1}{4\pi}}{8\pi(u - u' - i\epsilon)^2} + \frac{\beta(u' - u) - \frac{1}{4\pi}}{8\pi(u' - u - i\epsilon)^2}, \quad (5.39)$$

and

$$\begin{aligned}\Lambda_{AE'}^{(s)} &= P_{AB(s)CD(s)} P_{E'F'(s)G'H'(s)} [X^{B(s)F'(s)} \delta(\Omega - \Omega') \nabla^C \nabla^{G'} (X^{D(s)H'(s)} \delta(\Omega - \Omega')) \\ &\quad - \nabla^C (X^{D(s)F'(s)} \delta(\Omega - \Omega')) \nabla^{G'} (X^{B(s)H'(s)} \delta(\Omega - \Omega'))].\end{aligned}\quad (5.40)$$

The identity operator \mathcal{I}_f is defined by

$$\mathcal{I}_f = \int dud\Omega f(u, \Omega). \quad (5.41)$$

The divergence of the Dirac delta function $\delta^{(2)}(0)$ has been regularized to $\frac{1}{12\pi}$ using the Riemann zeta function or heat kernel method [16].

- (3) Nonlocal terms. The nonlocal terms are

$$\begin{aligned}\mathcal{N}_M(Y, Z) &= \frac{i}{2} \int dud u' d\Omega \alpha(u' - u) \Delta_{A(s)}(\dot{Y}; F; u') \\ &\times \Delta^{A(s)}(\dot{Z}; F; u),\end{aligned}\quad (5.42a)$$

$$\begin{aligned}\mathcal{N}_{MO}(Y, g) &= \frac{i}{2} \int dud u' d\Omega \alpha(u' - u) \Delta_{A(s)}(\dot{g}; F; u) \\ &\times \Delta^{A(s)}(\dot{Y}; F; u'),\end{aligned}\quad (5.42b)$$

$$\begin{aligned}\mathcal{N}_O(g_1, g_2) &= \frac{i}{2} \int dud u' d\Omega \alpha(u' - u) \Delta_{A(s)}(\dot{g}_1; F; u') \\ &\times \Delta^{A(s)}(\dot{g}_2; F; u).\end{aligned}\quad (5.42c)$$

Here, the tensor $\Delta_{A(s)}(g; F; u)$ is a shorthand of $\Delta_{A(s)}(g; F; u, \Omega)$, and one should distinguish it from $\Delta_{A(s)}(Y; F; u, \Omega)$, which is the superrotation variation of the fundamental field $F_{A(s)}$. Actually, it is defined as

$$\Delta_{A(s)}(g; F; u, \Omega) = g(u, \Omega) \mathcal{Q}_{A(s)B(s)} F^{B(s)}, \quad (5.43)$$

which relates to the commutator

$$\begin{aligned}[\mathcal{O}_g, F_{A(s)}(u, \Omega)] &= -i\Delta_{A(s)}(g; F; u, \Omega) \\ &\quad + \frac{i}{2} \int du' \alpha(u' - u) \\ &\quad \times \Delta_{A(s)}(\dot{g}; F; u', \Omega).\end{aligned}\quad (5.44)$$

- (4) There is a closed algebra for $\dot{Y} = \dot{g} = 0$, which is similar to the intertwined algebra in the lower spin cases

$$[\mathcal{T}_{f_1}, \mathcal{T}_{f_2}] = \mathcal{C}_T(f_1, f_2) + i\mathcal{T}_{f_1 f_2 - f_2 f_1}, \quad (5.45a)$$

$$[\mathcal{T}_f, \mathcal{M}_Y] = -i\mathcal{T}_{Y^A \nabla_A f}, \quad (5.45b)$$

$$[\mathcal{M}_Y, \mathcal{M}_Z] = i\mathcal{M}_{[Y,Z]} + is\mathcal{O}_{o(Y,Z)}, \quad (5.45c)$$

$$[\mathcal{T}_f, \mathcal{O}_g] = 0, \quad (5.45d)$$

$$[\mathcal{M}_Y, \mathcal{O}_g] = i\mathcal{O}_{Y^A \nabla_{Ag}}, \quad (5.45e)$$

$$[\mathcal{O}_{g_1}, \mathcal{O}_{g_2}] = 0. \quad (5.45f)$$

This algebra is one of the main results of this paper. The spin s on the right-hand side of (5.45c) can be absorbed into the definition of \mathcal{O}_g , and the resulting algebra is isomorphic to each other for $s \neq 0$.

VI. DUALITY TRANSFORMATION

In this section, we will confirm that the operator \mathcal{O}_g is the helicity flux operator associated with special superduality transformation.

Curvature tensor. For a HS field $f_{\mu(s)}$, we may define a curvature tensor [52]

$$R_{\mu_1\nu_1\mu_2\nu_2\cdots\mu_s\nu_s} = -2\delta_{\mu_1\nu_1}^{\rho_1\sigma_1} \cdots \delta_{\mu_s\nu_s}^{\rho_s\sigma_s} \partial_{\rho(s)} f_{\sigma(s)}, \quad (6.1)$$

where the tensor $\delta_{\mu\nu}^{\alpha\beta}$ is

$$\delta_{\mu\nu}^{\alpha\beta} = \delta_\mu^\alpha \delta_\nu^\beta - \delta_\nu^\alpha \delta_\mu^\beta, \quad (6.2)$$

and

$$\partial_{\rho(s)} = \partial_{\rho_1} \cdots \partial_{\rho_s}. \quad (6.3)$$

Due to the antisymmetric property of $\delta_{\mu\nu}^{\alpha\beta}$

$$\delta_{\mu\nu}^{\alpha\beta} = -\delta_{\nu\mu}^{\beta\alpha} = -\delta_{\nu\mu}^{\alpha\beta} = \delta_{\nu\mu}^{\beta\alpha}, \quad (6.4)$$

the curvature tensor is antisymmetric under the exchange of indices μ_i and ν_i

$$R_{\mu_1\nu_1\cdots\mu_i\nu_i\cdots\mu_s\nu_s} = -R_{\mu_1\nu_1\cdots\nu_i\mu_i\cdots\mu_s\nu_s}, \quad i = 1, 2, \cdots, s. \quad (6.5)$$

It is also invariant under the exchange of any pair of indices $(\mu_i\nu_i)$ and $(\mu_j\nu_j)$

$$R_{\cdots\mu_i\nu_i\cdots\mu_j\nu_j\cdots} = R_{\cdots\mu_j\nu_j\cdots\mu_i\nu_i\cdots}, \quad i, j = 1, 2, \cdots, s. \quad (6.6)$$

The cyclic identity

$$R_{[\mu_1\nu_1\mu_2]\nu_2\cdots} = 0, \quad (6.7)$$

and the Bianchi identity

$$\partial_{[\rho} R_{\mu_1\nu_1]\mu_2\nu_2\cdots} = 0, \quad (6.8)$$

are also satisfied similar to the Riemann tensor. The Fronsdl equation is equivalent to the vanishing of the ‘‘Ricci’’ tensor

$$R_{\mu_1\nu_1\mu_2\nu_2\cdots\mu_s\nu_s} \eta^{\nu_1\nu_2} = 0. \quad (6.9)$$

The dual of the curvature tensor is defined through the Levi-Civita tensor

$$\tilde{R}_{\mu_1\nu_1\mu_2\nu_2\cdots\mu_s\nu_s} = -\frac{1}{2} \epsilon_{\mu_1\nu_1\rho\sigma} R^{\rho\sigma}{}_{\mu_2\nu_2\cdots\mu_s\nu_s}, \quad (6.10)$$

and has the same symmetry as the curvature tensor. It also obeys the Bianchi identity

$$\partial_{[\rho} \tilde{R}_{\mu_1\nu_1]\mu_2\nu_2\cdots\mu_s\nu_s} = 0, \quad (6.11)$$

and satisfies the equation of motion

$$\tilde{R}_{\mu_1\nu_1\mu_2\nu_2\cdots\mu_s\nu_s} \eta^{\nu_1\nu_2} = 0. \quad (6.12)$$

Duality transformation and the corresponding flux. The duality transformation is a rotation between the curvature tensor and its dual

$$R_{\mu_1\nu_1\cdots\mu_s\nu_s} \rightarrow R_{\mu_1\nu_1\cdots\mu_s\nu_s} \cos \varphi + \tilde{R}_{\mu_1\nu_1\cdots\mu_s\nu_s} \sin \varphi, \quad (6.13a)$$

$$\tilde{R}_{\mu_1\nu_1\cdots\mu_s\nu_s} \rightarrow -R_{\mu_1\nu_1\cdots\mu_s\nu_s} \sin \varphi + \tilde{R}_{\mu_1\nu_1\cdots\mu_s\nu_s} \cos \varphi, \quad (6.13b)$$

with φ a constant angle. We may introduce a dual Fronsdl field $\tilde{f}_{\mu(s)}$, which has the same symmetry as the Fronsdl field and relate it to the dual curvature tensor

$$\tilde{R}_{\mu_1\nu_1\mu_2\nu_2\cdots\mu_s\nu_s} = -2\delta_{\mu_1\nu_1}^{\rho_1\sigma_1} \cdots \delta_{\mu_s\nu_s}^{\rho_s\sigma_s} \partial_{\rho(s)} \tilde{f}_{\sigma(s)}. \quad (6.14)$$

Thus, the duality transformation may be induced by rotating the fields f and \tilde{f}

$$f'_{\mu(s)} = f_{\mu(s)} \cos \varphi + \tilde{f}_{\mu(s)} \sin \varphi, \quad (6.15a)$$

$$\tilde{f}'_{\mu(s)} = -f_{\mu(s)} \sin \varphi + \tilde{f}_{\mu(s)} \cos \varphi, \quad (6.15b)$$

whose infinitesimal transformations are

$$\delta_\epsilon f_{\mu(s)} = \epsilon \tilde{f}_{\mu(s)}, \quad \delta_\epsilon \tilde{f}_{\mu(s)} = -\epsilon f_{\mu(s)}, \quad (6.16)$$

with ϵ a small positive parameter.

Similar to the vector and gravitational cases, we introduce a symmetric Fronsdl action

$$S[f, \tilde{f}] = \frac{1}{2} (S[f] + S[\tilde{f}]). \quad (6.17)$$

There is a parallel dual gauge transformation generated by a symmetric traceless tensor $\tilde{\xi}_{\mu(s-1)}$

$$\delta\tilde{f}_{\mu(s)} = s\partial_{(\mu_1}\tilde{\xi}_{\mu_2\cdots\mu_s)}. \quad (6.18)$$

From Noether's theorem, we can find a conserved current associated with the global duality transformation

$$\begin{aligned} j_{\text{duality}}^\rho &= \frac{1}{2}\frac{\partial\mathcal{L}[f]}{\partial\partial_\rho f_{\mu(s)}}\delta_\epsilon f_{\mu(s)} + \frac{1}{2}\frac{\partial\mathcal{L}[\tilde{f}]}{\partial\partial_\rho\tilde{f}_{\mu(s)}}\delta_\epsilon\tilde{f}_{\mu(s)} \\ &= L^{\rho\nu(s)\sigma\mu(s)}(\tilde{f}_{\nu(s)}\partial_\sigma f_{\mu(s)} - f_{\nu(s)}\partial_\sigma\tilde{f}_{\mu(s)}). \end{aligned} \quad (6.19)$$

In the last step, we have omitted the constant parameter ϵ . We may expand the dual Fronsdal field as

$$\tilde{f}_{\mu(s)} = \sum_{k=1}^{\infty} r^{-k} N^{\alpha(s)}{}_{\mu(s)} \tilde{F}_{\alpha(s)}^{(k)} \quad (6.20)$$

near \mathcal{I}^+ and impose the gauge fixing conditions

$$\partial^\nu\tilde{f}_{\nu\mu(s-1)} = 0, \quad \tilde{f}'_{\mu(s-2)} = 0, \quad n^\nu\tilde{f}_{\nu\mu(s-1)} = 0. \quad (6.21)$$

Then the helicity flux which radiates to \mathcal{I}^+ is

$$\begin{aligned} \lim_+ \int_{\mathfrak{H}_r} (d^3x)_\mu j_{\text{duality}}^\mu &= \int dud\Omega \tilde{F}_{A(s)} \tilde{F}^{A(s)} \\ &= \int dud\Omega \tilde{F}^{A(s)} Q_{A(s)B(s)} F^{B(s)}. \end{aligned} \quad (6.22)$$

We can read out the helicity density operator

$$O(u, \Omega) =: \tilde{F}^{A(s)} Q_{A(s)B(s)} F^{B(s)}:, \quad (6.23)$$

and construct the helicity flux operator

$$\mathcal{O}_g = \int dud\Omega g(u, \Omega) O(u, \Omega). \quad (6.24)$$

This operator is exactly the same as (5.35). According to the terminology of [15], it becomes the generator of duality transformation for $g = \text{const}$ and generates special super-duality transformation when $g = g(\Omega)$.

Why helicity flux? Now let us show why we call \mathcal{O}_g helicity flux operator by substituting the mode expansion of the fundamental field in Appendix E into \mathcal{O}_g . We focus on the special case $g = 1$

$$\begin{aligned} \mathcal{O}_{g=1} &= \int dud\Omega Q^{A(s)A'(s)} \int_0^\infty \frac{d\omega}{\sqrt{4\pi\omega}} \int_0^\infty \frac{d\omega'}{\sqrt{4\pi\omega'}} \sum_{\ell m} \sum_{\ell' m'} \\ &: [-i\omega c_{\mu(s); \omega, \ell, m} Y_{A(s)}^{\mu(s)} Y_{\ell, m} e^{-i\omega u} + \text{h.c.}] [c_{\mu'(s); \omega', \ell', m'} Y_{A'(s)}^{\mu'(s)} Y_{\ell', m'} e^{-i\omega' u} + \text{h.c.}]: \\ &= -i \int d\Omega Q^{\mu(s)\mu'(s)} \int_0^\infty d\omega \sum_{\ell m} \sum_{\ell' m'} c_{\mu'(s); \omega, \ell', m'}^\dagger c_{\mu(s); \omega, \ell, m} Y_{\ell, m} Y_{\ell', m'}^*, \end{aligned} \quad (6.25)$$

where the tensor $Q^{\mu(s)\mu'(s)}$ is the Cartesian version of $Q^{A(s)A'(s)}$

$$Q^{\mu(s)\mu'(s)} = Q^{A(s)A'(s)} Y_{A(s)}^{\mu(s)} Y_{A'(s)}^{\mu'(s)}. \quad (6.26)$$

Equivalently, it is constructed from

$$\gamma_{\mu\nu} = Y_\mu^A Y_\nu^B \gamma_{AB} \quad \text{and} \quad \bar{\epsilon}_{\mu\nu} = Y_\mu^A Y_\nu^B \epsilon_{AB}. \quad (6.27)$$

The next step is using the bulk creation and annihilation operators to express the boundary ones [see (E11)], and we obtain

$$\begin{aligned} \mathcal{O}_{g=1} &= -i \int_0^\infty \frac{d^3\mathbf{k}}{(2\pi)^3} Q^{\mu(s)\mu'(s)}(\Omega_{\mathbf{k}}) \\ &\times \sum_{\alpha\alpha'} \epsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) \epsilon_{\mu'(s)}^{\alpha'}(\mathbf{k}) b_{\alpha', \mathbf{k}}^\dagger b_{\alpha, \mathbf{k}}. \end{aligned} \quad (6.28)$$

We work in a representation where the particles have either right-hand or left-hand helicity. What follows is

$$Q^{\mu(s)\mu'(s)}(\Omega_{\mathbf{k}}) \epsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) \epsilon_{\mu'(s)}^{\alpha'}(\mathbf{k}) = i\sigma_3^{\alpha\alpha'}, \quad \alpha = \text{R, L}, \quad (6.29)$$

where σ_3 is the third Pauli matrix. Therefore, we find

$$\begin{aligned} \mathcal{O}_{g=1} &= \int \frac{d^3\mathbf{k}}{(2\pi)^3} (b_{\text{R}, \mathbf{k}}^\dagger b_{\text{R}, \mathbf{k}} - b_{\text{L}, \mathbf{k}}^\dagger b_{\text{L}, \mathbf{k}}) \\ &= \int \frac{d^3\mathbf{k}}{(2\pi)^3} (n_{\text{R}, \mathbf{k}} - n_{\text{L}, \mathbf{k}}), \end{aligned} \quad (6.30)$$

where $n_{\text{R/L}, \mathbf{k}} = b_{\text{R/L}, \mathbf{k}}^\dagger b_{\text{R/L}, \mathbf{k}}$ is the particle number with right/left-hand helicity. Therefore, $\mathcal{O}_{g=1}$ is the difference between the numbers of particles with right-hand and left-hand helicity.

VII. DISCUSSION AND CONCLUSION

In this paper, we have reduced the bosonic Fronsdal theory in Minkowski spacetime to future null infinity \mathcal{I}^+ . The boundary HS theory is characterized by the fundamental field $F_{A(s)}$ with a nontrivial symplectic form. All the descendants are determined by the fundamental field by the boundary constraint equations up to initial data. This extends the lower spin Carrollian field theories to general spin s . The symmetry algebra (5.45), which is formed by extending Poincaré and helicity flux operators, shows the same structure as the ones in the lower spin theories. All the flux operators are quadratic in the fundamental fields and could be interpreted as generators of supertranslation, superrotation, and superduality transformation, respectively. The superduality transformation is the angle-dependent extension of the HS duality transformation (6.15) at the null boundary. In Table I, we list the correspondences between the bulk global symmetry transformations and the boundary local transformations. These results lead us to the conjecture that each bulk global symmetry transformation may extend to a boundary local symmetry transformation at the null hypersurfaces. These local symmetry transformations are related to the radiative flux operators from bulk to boundary. It would be interesting to check this conjecture in the future. There are still many open questions to explore.

- (i) Further extension of the Carrollian diffeomorphism. There are HS extensions of BMS symmetry in the literature [22,24,81,82] where the supertranslation and superrotation are large HS gauge transformations. The HS BMS algebra has been extended further for Carrollian conformal scalar theory [25], which is expected to be dual to a nontrivial interacting HS theory in the bulk [66]. On the other hand, we work out the quantum flux operators following from Carrollian diffeomorphism, which relates to spacetime geometry and differs from the ones concerning HS gauge fields. It would be interesting to see whether it is consistent to combine HS supertranslation and superrotation with Carrollian diffeomorphism.
- (ii) General null hypersurfaces. The symmetry algebra found in this work should be valid for general null hypersurface, as has been shown in [16] for scalar theory. The general null hypersurface is intriguing since one may consider massive or nonflat spacetime HS theories.

TABLE I. Bulk global transformations are extended to boundary local transformations.

Bulk global transformations	Boundary local transformations
Translation	Supertranslation
Lorentz rotation	Superrotation
Duality transformation	Superduality transformation

- (iii) Superduality transformation. As has been mentioned in the introduction, duality transformations are found in various gravitational and gauge theories. It would be better to discuss their associated superduality transformations on null boundaries. Besides, it is rather interesting to discuss the physical origin of superduality transformation and its various consequences.

ACKNOWLEDGMENTS

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APPENDIX A: NUMBER OF INDEPENDENT COMPONENTS

In this appendix, we will review the number of independent components for a symmetric tensor in d dimensions. The results can be found in any book on the representation of Lie groups, and we use the review reference [83]. For a d -dimensional vector space V , the symmetric tensors of rank s form a vector space $\text{Sym}^s V$. The number of independent degrees of freedom is equal to the dimension of the space $\dim(\text{Sym}^s V)$. The symmetric tensor forms an irreducible representation of the general linear group $GL(d, \mathbb{R})$ and corresponds to the Young diagram with one row of length s as shown in Fig. 1.

The dimension of any irreducible representation V_λ of $GL(d, \mathbb{R})$ associated with Young diagram $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_r)$ is given by the formula

$$\dim(V_\lambda) = \prod_{(i,j)} \frac{d - i + j}{\text{hook length}}, \tag{A1}$$

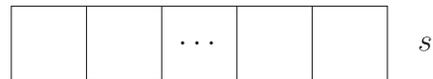


FIG. 1. Young diagram for a rank s symmetric tensor.

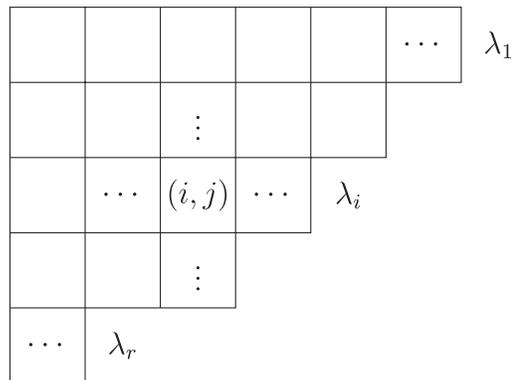


FIG. 2. Young diagram of type $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_r)$.

where (i, j) denotes the box in the i th row and j th column in the Young diagram, as shown in Fig. 2. The product is over all boxes in the diagram, and the hook length is the number of squares directly below or to the right of the square (i, j) , counting itself only once. For the symmetric representation $\text{Sym}^s V$, there is only one row with s boxes. Therefore, the dimension $\dim(\text{Sym}^s V)$ is

$$\dim(\text{Sym}^s V) = \frac{d(d+1) \cdots (d+s-1)}{s(s-1) \cdots 1} = C_{d+s-1}^s. \quad (\text{A2})$$

APPENDIX B: IDENTITIES INVOLVING COORDINATE TRANSFORMATION

In the context, we defined the four vectors in Minkowski spacetime as follows:

$$n^\mu = (1, n^i), \quad \bar{n}^\mu = (-1, n^i), \quad m^\mu = (0, n^i), \quad \bar{m}^\mu = (1, 0), \quad (\text{B1})$$

where n^i is the normal vector of the unit sphere S^2 . The vectors Y_μ^A are related to the first three vectors by

$$Y_\mu^A = -\nabla^A n_\mu = -\nabla^A \bar{n}_\mu = -\nabla^A m_\mu. \quad (\text{B2})$$

These vectors satisfy various identities that are collected in [16]. In this appendix, we can derive more identities associated with N^α_μ and \bar{N}^μ_α in the following:

$$Y_\mu^A N^\alpha_\mu = -\delta_\mu^A, \quad Y_\mu^A \bar{N}^\mu_\alpha = -\delta_\alpha^A, \quad (\text{B3a})$$

$$n^\mu N^\alpha_\mu = \delta_r^\alpha, \quad n_\mu \bar{N}^\mu_\alpha = -\delta_\alpha^u, \quad (\text{B3b})$$

$$m^\mu N^\alpha_\mu = \delta_r^\alpha - \delta_u^\alpha, \quad m_\mu \bar{N}^\mu_\alpha = \delta_\alpha^r, \quad (\text{B3c})$$

$$\bar{n}^\mu N^\alpha_\mu = \delta_r^\alpha - 2\delta_u^\alpha, \quad \bar{n}_\mu \bar{N}^\mu_\alpha = \delta_\alpha^u + 2\delta_\alpha^r, \quad (\text{B3d})$$

$$\bar{m}^\mu N^\alpha_\mu = \delta_u^\alpha, \quad \bar{m}_\mu \bar{N}^\mu_\alpha = -\delta_\alpha^r - \delta_\alpha^u, \quad (\text{B3e})$$

and

$$\begin{aligned} \nabla_A N^\alpha_\mu &= Y_{\mu A} (\delta_u^\alpha - \delta_r^\alpha) - m_\mu \delta_\alpha^A, \\ \nabla_A \bar{N}^\mu_\alpha &= -Y_A^\mu \delta_\alpha^r - \gamma_{AB} m^\mu \delta_\alpha^B, \end{aligned} \quad (\text{B4a})$$

$$\begin{aligned} Y_B^\mu \nabla^A N^\alpha_\mu &= \delta_B^A (\delta_u^\alpha - \delta_r^\alpha), \\ Y_\mu^B \nabla_A \bar{N}^\mu_\alpha &= -\delta_A^B \delta_\alpha^r, \quad n^\mu \nabla_A N^\alpha_\mu = -\delta_A^\alpha, \end{aligned} \quad (\text{B4b})$$

as well as

$$\begin{aligned} \bar{J}^\mu_\alpha N^\beta_\mu &= \delta_\alpha^u \delta_u^\beta + \delta_\alpha^r \delta_r^\beta + r \delta_\alpha^A \delta_A^\beta \\ &= \delta_\alpha^\beta + (r-1) \delta_\alpha^A \delta_A^\beta \\ &= r \delta_\alpha^\beta + (1-r) [\delta_\alpha^u \delta_u^\beta + \delta_\alpha^r \delta_r^\beta], \end{aligned} \quad (\text{B5a})$$

$$\begin{aligned} N^\alpha_\mu \bar{N}^\mu_\beta &= \delta_\beta^\alpha, \quad \bar{N}^\mu_\alpha N^\alpha_\nu = \delta_\nu^\mu, \\ N^\alpha_\mu N^{\beta\mu} &= -\delta_\alpha^u \delta_r^\beta - \delta_\alpha^r \delta_r^\beta + \delta_\alpha^A \delta_A^\beta + \gamma^{AB} \delta_\alpha^A \delta_B^\beta, \end{aligned} \quad (\text{B5b})$$

$$\begin{aligned} \bar{N}^\mu_\beta \nabla_A N^\alpha_\mu &= -\delta_\beta^r \delta_A^\alpha + \gamma_{AB} \delta_\beta^B (\delta_r^\alpha - \delta_u^\alpha), \\ N^\alpha_\mu \nabla_A N^{\beta\mu} &= \delta_\alpha^A (\delta_r^\beta - \delta_u^\beta) - \delta_\alpha^B (\delta_r^\alpha - \delta_u^\alpha). \end{aligned} \quad (\text{B5c})$$

APPENDIX C: ASYMPTOTIC EXPANSION OF STRESS TENSOR NEAR \mathcal{I}^+

The partial derivatives of the HS gauge field are

$$\partial_\nu f_{\mu(s)} = \sum_{k=1}^{\infty} r^{-k} [-n_\nu N_{\mu_1}^{\alpha_1} \cdots N_{\mu_s}^{\alpha_s} \dot{F}_{\alpha(s)}^{(k)} - (k-1) m_\nu N_{\mu_1}^{\alpha_1} \cdots N_{\mu_s}^{\alpha_s} F_{\alpha(s)}^{(k-1)} - Y_\nu^A \nabla_A (N_{\mu_1}^{\alpha_1} \cdots N_{\mu_s}^{\alpha_s} F_{\alpha(s)}^{(k-1)})]. \quad (\text{C1})$$

Therefore, we find the following quadratic terms consisting of the stress tensor:

$$\partial_\nu f_{\mu(s)} \partial^\nu f^{\mu(s)} = \frac{2\dot{F}_{A(s)} F^{A(s)}}{r^3} + \cdots, \quad (\text{C2a})$$

$$\begin{aligned} \partial_\rho f_{\mu(s)} \partial_\sigma f^{\mu(s)} &= \frac{n_\rho n_\sigma \dot{F}_{A(s)} \dot{F}^{A(s)}}{r^2} + \frac{1}{r^3} [2n_\rho n_\sigma \dot{F}_{A(s)} \dot{F}^{(2)A(s)} + 2n_{(\rho} m_{\sigma)} \dot{F}_{A(s)} F^{A(s)} \\ &\quad + 2n_{(\rho} Y_{\sigma)}^B \dot{F}_{A(s)} \nabla_B F^{A(s)} + 2sn_{(\rho} Y_{\sigma)}^B (\dot{F}_{uA(s-1)} F_B^{A(s-1)} - \dot{F}_{BA(s-1)} F_u^{A(s-1)})] + \cdots, \end{aligned} \quad (\text{C2b})$$

$$\partial_\nu f_{\rho\mu(s-1)} \partial^\nu f_\sigma^{\mu(s-1)} = \frac{1}{r^3} \left[2n_\rho n_\sigma \dot{F}_{uA(s-1)} F_u^{A(s-1)} + 2n_{(\rho} Y_{\sigma)}^C \frac{d}{du} (F_{uA(s-1)} F_C^{A(s-1)}) + Y_\rho^B Y_\sigma^C \frac{d}{du} (F_{BA(s-1)} F_C^{A(s-1)}) \right] + \cdots, \quad (\text{C2c})$$

$$\partial_\rho f_{\sigma\mu(s-1)} \partial^\sigma f^{\rho\mu(s-1)} = \frac{2\dot{F}_{A(s)} F^{A(s)}}{r^3} + \dots, \quad (\text{C2d})$$

$$\begin{aligned} \partial_\rho f^\nu_{\mu(s-1)} \partial_\nu f^\mu_{\sigma(s-1)} &= \frac{1}{r^3} [n_\rho n_\sigma (s\dot{F}_{uA(s-1)} F_u^{A(s-1)} + \dot{F}_{A(s)} \nabla^{A_1} F_u^{A_2 \dots A_s}) \\ &+ n_\rho Y_\sigma^B (s\dot{F}_{uA(s-1)} F_B^{A(s-1)} - F_{uA(s-1)} \dot{F}_B^{A(s-1)} + \dot{F}_{CA(s-1)} \nabla^C F_B^{A(s-1)}) \\ &+ n_\sigma Y_\rho^B F_{BA(s-1)} \dot{F}_u^{A(s-1)} + n_\rho m_\sigma \dot{F}_{A(s)} F^{A(s)} + Y_\rho^B Y_\sigma^C \dot{F}_{CA(s-1)} F_B^{A(s-1)}] + \dots, \end{aligned} \quad (\text{C2e})$$

$$\partial_\lambda f^\nu_{\rho\mu(s-2)} \partial_\nu f^{\lambda\mu(s-2)} = \frac{1}{r^3} \frac{d}{du} [N^\alpha_\rho F_{\alpha A(s-1)} N^\beta_\sigma F_\beta^{A(s-1)}] + \dots. \quad (\text{C2f})$$

APPENDIX D: DOUBLY SYMMETRIC TRACELESS TENSOR ON S^2

We will study the doubly symmetric traceless tensors $X_{A(s)B(s)}$, $Q_{A(s)B(s)}$ and $P_{AB(s)CD(s)}$ in this appendix.

The trace-free representation of the fully symmetric rank k tensor $T_0^{a(k)}$ is given by the formula [84,85] in three dimensions and [86] in general dimensions

$$\begin{aligned} T^{a(k)} &= T_0^{a(k)} + \sum_{p=1}^{[k/2]} (-1)^p \frac{k![d+2k-2(p+2)]!!}{2^p p!(k-2p)!(d+2k-4)!!} \\ &\times \eta^{(a_1 a_2 \dots a_{2p-1} a_{2p} T_p^{a_{2p+1} \dots a_k})}, \end{aligned} \quad (\text{D1})$$

where $T_p^{a(k-2p)}$ is obtained by taking the trace of $T_0^{a(k)}$ p times

$$T_p^{a_{2p+1} \dots a_k} = \eta_{a_1 a_2} \eta_{a_3 a_4} \dots \eta_{a_{2p-1} a_{2p}} T_0^{a_1 a_2 \dots a_k}, \quad (\text{D2})$$

and $\eta^{a_1 a_2}$ is the metric of the manifold. Note that the formula can be simplified to

$$\begin{aligned} T^{a(k)} &= \sum_{p=0}^{[k/2]} (-1)^p \frac{k![d+2k-2(p+2)]!!}{2^p p!(k-2p)!(d+2k-4)!!} \\ &\times \eta^{(a_1 a_2 \dots a_{2p-1} a_{2p} T_p^{a_{2p+1} \dots a_k})}. \end{aligned} \quad (\text{D3})$$

In our case, i.e., $d=2$, $k=s$, the trace-free part of a fully symmetric, rank s tensor $T_0^{A(s)}$, is

$$T^{A(s)} = \sum_{p=0}^{[s/2]} a(p; s) \gamma^{(A_1 A_2 \dots A_{2p-1} A_{2p} T_p^{A_{2p+1} \dots A_s})}, \quad (\text{D4})$$

where

$$a(p; s) = (-1)^p \frac{s![2s-2p-2]!!}{2^p p!(s-2p)!(2s-2)!!}, \quad p=0, 1, \dots, [s/2]. \quad (\text{D5})$$

For later convenience, we extend the definition of $a(p; s)$ to $p=-1$ with

$$a(-1; s) = 0. \quad (\text{D6})$$

In [86], this is checked up to rank 8 by computer. It may be proved by noticing the identity

$$\begin{aligned} \gamma_{A_1 A_2} \gamma^{(A_1 A_2 \dots A_{2p-1} A_{2p} T_p^{A_{2p+1} \dots A_s})} \\ = b(p; s) \gamma^{(A_3 A_4 \dots A_{2p-1} A_{2p} T_p^{A_{2p+1} \dots A_s})} \\ + c(p+1; s) \gamma^{(A_3 A_4 \dots A_{2p+1} A_{2p+2} T_{p+1}^{A_{2p+3} \dots A_s})}, \end{aligned} \quad (\text{D7})$$

with

$$b(p; s) = \frac{4p(s-p)}{s(s-1)}, \quad (\text{D8a})$$

$$c(p+1; s) = \frac{(s-2p)(s-2p-1)}{s(s-1)}. \quad (\text{D8b})$$

The coefficients $a(p; s)$, $b(p; s)$ and $c(p; s)$ satisfy the identity

$$a(p; s)b(p; s) + a(p-1; s)c(p; s) = 0, \quad p=0, 1, \dots, [s/2]. \quad (\text{D9})$$

Note that we have used $a(-1; s) = 0$ in the above equation. Therefore, the trace vanishes

$$\begin{aligned}
 \gamma_{A_1 A_2} T^{A_1 \dots A_s} &= \sum_{p=0}^{\lfloor s/2 \rfloor} a(p; s) [b(p; s) \gamma^{(A_3 A_4 \dots \gamma^{A_{2p-1} A_{2p}} T_p^{A_{2p+1} \dots A_s})} + c(p+1; s) \gamma^{(A_3 A_4 \dots \gamma^{A_{2p+1} A_{2p+2}} T_{p+1}^{A_{2p+3} \dots A_s})}] \\
 &= \sum_{p=0}^{\lfloor s/2 \rfloor} [a(p; s) b(p; s) + a(p-1; s) c(p; s)] \gamma^{(A_3 A_4 \dots \gamma^{A_{2p-1} A_{2p}} T_p^{A_{2p+1} \dots A_s})} \\
 &= 0.
 \end{aligned} \tag{D10}$$

1. Doubly symmetric tensor $X_{A(s)B(s)}$

Now we will prove the formula (4.37) in the context. Introducing the notation

$$\begin{aligned}
 \tilde{X}_{p,q}^{A_{2p+1} \dots A_s B_{2q+1} \dots B_s} \\
 = \gamma_{A_1 A_2} \dots \gamma_{A_{2p-1} A_{2p}} \gamma_{B_1 B_2} \dots \gamma_{B_{2q-1} B_{2q}} \tilde{X}^{(A_1 \dots A_s)(B_1 \dots B_s)}, \tag{D11}
 \end{aligned}$$

this is obtained by taking traces p and q times for the indices A_s and B_s , respectively. When $p = q = 0$, we have

$$\tilde{X}_{0,0}^{A_1 \dots A_s B_1 \dots B_s} = \tilde{X}^{(A_1 \dots A_s)(B_1 \dots B_s)}. \tag{D12}$$

We use the vielbeins $e_{\hat{a}}^A$ to decompose the metric γ^{AB} as

$$\gamma^{AB} = e_{\hat{a}}^A e^{B\hat{a}}, \tag{D13}$$

and thus,

$$\gamma^{A_1 B_1} \dots \gamma^{A_s B_s} = e_{\hat{a}_1}^{A_1} \dots e_{\hat{a}_s}^{A_s} e^{B_1 \hat{a}_1} \dots e^{B_s \hat{a}_s}. \tag{D14}$$

It follows that

$$\begin{aligned}
 \tilde{X}^{(A_1 \dots A_s)(B_1 \dots B_s)} &= \frac{1}{s!} \sum_{\pi \in \mathcal{S}_s} \gamma^{A_{\pi(1)} B_1} \dots \gamma^{A_{\pi(s)} B_s} \\
 &= \frac{1}{s!} \sum_{\pi \in \mathcal{S}_s} e_{\hat{a}_1}^{A_{\pi(1)}} \dots e_{\hat{a}_s}^{A_{\pi(s)}} e^{B_1 \hat{a}_1} \dots e^{B_s \hat{a}_s} \\
 &= V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s} e^{B_1 \hat{a}_1} \dots e^{B_s \hat{a}_s}. \tag{D15}
 \end{aligned}$$

In the first step, the indices $A_1 \dots A_s$ are symmetrized using the permutation group \mathcal{S}_s . In the second step, we use the formula (D13). In the last step, we define the symmetric tensor

$$V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s} = \frac{1}{s!} \sum_{\pi \in \mathcal{S}_s} e_{\hat{a}_1}^{A_{\pi(1)}} \dots e_{\hat{a}_s}^{A_{\pi(s)}}, \tag{D16}$$

where

$$V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s} = V_{\hat{a}_1 \dots \hat{a}_s}^{(A_1 \dots A_s)} = V_{(\hat{a}_1 \dots \hat{a}_s)}^{A_1 \dots A_s}. \tag{D17}$$

Therefore, the indices $B_1 \dots B_s$ is symmetrized automatically. We may rewrite

$$\tilde{X}^{(A_1 \dots A_s)(B_1 \dots B_s)} = V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s} V^{B_1 \dots B_s \hat{a}_1 \dots \hat{a}_s}. \tag{D18}$$

The p th trace of $V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s}$ is

$$V_{p; \hat{a}_1 \dots \hat{a}_s}^{A_{2p+1} \dots A_s} \equiv \gamma_{A_1 A_2} \dots \gamma_{A_{2p-1} A_{2p}} V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s}. \tag{D19}$$

We could find the following product:

$$\begin{aligned}
 V_{p; \hat{a}_1 \dots \hat{a}_s}^{A_{2p+1} \dots A_s} V_{q; \hat{a}_1 \dots \hat{a}_s}^{B_{2q+1} \dots B_s \hat{a}_1 \dots \hat{a}_s} \\
 = \gamma_{A_1 A_2} \dots \gamma_{A_{2p-1} A_{2p}} V_{\hat{a}_1 \dots \hat{a}_s}^{A_1 \dots A_s} \gamma_{B_1 B_2} \dots \gamma_{B_{2q-1} B_{2q}} V^{B_1 \dots B_s \hat{a}_1 \dots \hat{a}_s} \\
 = \tilde{X}_{p,q}^{A_{2p+1} \dots A_s B_{2q+1} \dots B_s}. \tag{D20}
 \end{aligned}$$

Then the trace-free part of the tensor $\tilde{X}^{(A_1 \dots A_s)(B_1 \dots B_s)}$ with respect to $A(s)$ and $B(s)$ is

$$\begin{aligned}
 X^{A(s)B(s)} &= \sum_{p=0}^{\lfloor s/2 \rfloor} a(p; s) \gamma^{(A_1 A_2 \dots \gamma^{A_{2p-1} A_{2p}} V_{p; \hat{a}_1 \dots \hat{a}_s}^{A_{2p+1} \dots A_s})} \sum_{q=0}^{\lfloor s/2 \rfloor} a(q; s) \gamma^{(B_1 B_2 \dots \gamma^{B_{2q-1} B_{2q}} V_q^{B_{2q+1} \dots B_s} \hat{a}_1 \dots \hat{a}_s)} \\
 &= \sum_{p,q=0}^{\lfloor s/2 \rfloor} a(p; s) a(q; s) \gamma^{(A_1 A_2 \dots \gamma^{A_{2p-1} A_{2p}} V_{p; \hat{a}_1 \dots \hat{a}_s}^{A_{2p+1} \dots A_s})} \gamma^{(B_1 B_2 \dots \gamma^{B_{2q-1} B_{2q}} V_q^{B_{2q+1} \dots B_s} \hat{a}_1 \dots \hat{a}_s)} \\
 &= \sum_{p,q=0}^{\lfloor s/2 \rfloor} a(p, q; s) \gamma^{(A_1 A_2 \dots \gamma^{A_{2p-1} A_{2p}} \tilde{X}_{p,q}^{A_{2p+1} \dots A_s})(B_{2q+1} \dots B_s \gamma_{B_1 B_2} \dots \gamma_{B_{2q-1} B_{2q}})}, \tag{D21}
 \end{aligned}$$

with the coefficients $a(p, q; s)$ being

$$a(p, q; s) = a(p; s)a(q; s) = (-1)^{p+q} \frac{s![2s-2p-2]!!}{2^p p!(s-2p)!(2s-2)!!} \frac{s![2s-2q-2]!!}{2^q q!(s-2q)!(2s-2)!!}. \quad (\text{D22})$$

As a consistency check, we will list the tensors $X^{A(s)B(s)}$ for several cases of lower spin in the following.

(1) $s = 2$. The tensor $\tilde{X}^{(A_1 A_2)(B_1 B_2)}$ is

$$\tilde{X}^{A_1 A_2 B_1 B_2} = \frac{1}{2} (\gamma^{A_1 B_1} \gamma^{A_2 B_2} + \gamma^{A_1 B_2} \gamma^{A_2 B_1}), \quad (\text{D23})$$

whose traces are

$$\tilde{X}_{1,0}^{B_1 B_2} = \gamma^{B_1 B_2}, \quad \tilde{X}_{0,1}^{A_1 A_2} = \gamma^{A_1 A_2}, \quad \tilde{X}_{1,1} = 2. \quad (\text{D24})$$

With the formula (D21), we find

$$X^{A_1 A_2 B_1 B_2} = \frac{1}{2} (\gamma^{A_1 B_1} \gamma^{A_2 B_2} + \gamma^{A_1 B_2} \gamma^{A_2 B_1}) - \frac{1}{2} \gamma^{A_1 A_2} \gamma^{B_1 B_2}. \quad (\text{D25})$$

(2) $s = 3$. The tensor $\tilde{X}^{(A_1 A_2 A_3)(B_1 B_2 B_3)}$ is

$$\begin{aligned} \tilde{X}^{(A_1 A_2 A_3)(B_1 B_2 B_3)} = & \frac{1}{3!} (\gamma^{A_1 B_1} \gamma^{A_2 B_2} \gamma^{A_3 B_3} + \gamma^{A_1 B_1} \gamma^{A_3 B_2} \gamma^{A_2 B_3} + \gamma^{A_2 B_1} \gamma^{A_1 B_2} \gamma^{A_3 B_3} \\ & + \gamma^{A_2 B_1} \gamma^{A_3 B_2} \gamma^{A_1 B_3} + \gamma^{A_3 B_1} \gamma^{A_2 B_2} \gamma^{A_1 B_3} + \gamma^{A_3 B_1} \gamma^{A_1 B_2} \gamma^{A_2 B_3}), \end{aligned} \quad (\text{D26})$$

and its various traces are

$$\tilde{X}_{1,0}^{A_i B_1 B_2 B_3} = \gamma^{A_i(B_1 B_2 B_3)}, \quad \tilde{X}_{0,1}^{(A_1 A_2 A_3) B_i} = \gamma^{(A_1 A_2 A_3) B_i}, \quad i = 1, 2, 3, \quad (\text{D27a})$$

$$\tilde{X}_{1,1}^{A_i B_j} = \frac{4}{3} \gamma^{A_i B_j}, \quad i, j = 1, 2, 3. \quad (\text{D27b})$$

Therefore, the doubly symmetric traceless tensor $X^{A_1 A_2 A_3 B_1 B_2 B_3}$ should be

$$X^{A_1 A_2 A_3 B_1 B_2 B_3} = \tilde{X}^{(A_1 A_2 A_3)(B_1 B_2 B_3)} - \frac{3}{4} \gamma^{(A_1 A_2} \tilde{X}_{1,0}^{A_3)(B_1 B_2 B_3)} - \frac{3}{4} \gamma^{(B_1 B_2} \tilde{X}_{0,1}^{B_3)(A_1 A_2 A_3)} + \frac{9}{16} \gamma^{(A_1 A_2} \tilde{X}_{1,1}^{A_3)(B_1 B_2 B_3)}. \quad (\text{D28})$$

(3) $s = 4$, the symmetric tensor $\tilde{X}^{(A_1 \dots A_4)(B_1 \dots B_4)}$ is

$$\tilde{X}^{(A_1 \dots A_4)(B_1 \dots B_4)} = \frac{1}{4!} (\gamma^{A_1 B_1} \gamma^{A_2 B_2} \gamma^{A_3 B_3} \gamma^{A_4 B_4} + \text{permutations of } A_1 A_2 A_3 A_4), \quad (\text{D29})$$

and its various traces are

$$\begin{aligned} \tilde{X}_{1,0}^{A_j B_1 B_2 B_3 B_4} = & \frac{1}{12} [\gamma^{B_1 B_2} (\gamma^{A_j B_3} \gamma^{A_j B_4} + \gamma^{A_j B_4} \gamma^{A_j B_3}) + \gamma^{B_1 B_3} (\gamma^{A_j B_2} \gamma^{A_j B_4} + \gamma^{A_j B_4} \gamma^{A_j B_2}) \\ & + \gamma^{B_1 B_4} (\gamma^{A_j B_2} \gamma^{A_j B_3} + \gamma^{A_j B_3} \gamma^{A_j B_2}) + \gamma^{B_2 B_3} (\gamma^{A_j B_1} \gamma^{A_j B_4} + \gamma^{A_j B_4} \gamma^{A_j B_1}) \\ & + \gamma^{B_2 B_4} (\gamma^{A_j B_1} \gamma^{A_j B_3} + \gamma^{A_j B_3} \gamma^{A_j B_1}) + \gamma^{B_3 B_4} (\gamma^{A_j B_1} \gamma^{A_j B_2} + \gamma^{A_j B_2} \gamma^{A_j B_1})], \end{aligned} \quad (\text{D30a})$$

$$\tilde{X}_{2,0}^{B_1 B_2 B_3 B_4} = \frac{1}{3} (\gamma^{B_1 B_2} \gamma^{B_3 B_4} + \gamma^{B_1 B_3} \gamma^{B_2 B_4} + \gamma^{B_1 B_4} \gamma^{B_2 B_3}), \quad (\text{D30b})$$

$$\begin{aligned} \tilde{X}_{0,1}^{A_1 A_2 A_3 A_4 B_i B_j} = & \frac{1}{12} [\gamma^{A_1 A_2} (\gamma^{B_i A_3} \gamma^{B_j A_4} + \gamma^{B_i A_4} \gamma^{B_j A_3}) + \gamma^{A_1 A_3} (\gamma^{B_i A_2} \gamma^{B_j A_4} + \gamma^{B_i A_4} \gamma^{B_j A_2}) \\ & + \gamma^{A_1 A_4} (\gamma^{B_i A_2} \gamma^{B_j A_3} + \gamma^{B_i A_3} \gamma^{B_j A_2}) + \gamma^{A_2 A_3} (\gamma^{B_i A_1} \gamma^{B_j A_4} + \gamma^{B_i A_4} \gamma^{B_j A_1}) \\ & + \gamma^{A_2 A_4} (\gamma^{B_i A_1} \gamma^{B_j A_3} + \gamma^{B_i A_3} \gamma^{B_j A_1}) + \gamma^{A_3 A_4} (\gamma^{B_i A_1} \gamma^{B_j A_2} + \gamma^{B_i A_2} \gamma^{B_j A_1})], \end{aligned} \quad (\text{D30c})$$

$$\tilde{X}_{0,2}^{A_1 A_2 A_3 A_4} = \frac{1}{3}(\gamma^{A_1 A_2} \gamma^{A_3 A_4} + \gamma^{A_1 A_3} \gamma^{A_2 A_4} + \gamma^{A_1 A_4} \gamma^{A_2 A_3}), \quad \tilde{X}_{2,1}^{B_i B_j} = \frac{4}{3} \gamma^{B_i B_j}, \quad (\text{D30d})$$

$$\tilde{X}_{1,1}^{A_i A_j B_k B_l} = \frac{1}{6}[\gamma^{A_i A_j} \gamma^{B_k B_l} + 3(\gamma^{A_i B_k} \gamma^{A_j B_l} + \gamma^{A_i B_l} \gamma^{A_j B_k})], \quad \tilde{X}_{2,2} = \frac{8}{3}. \quad (\text{D30e})$$

$$\tilde{X}_{1,2}^{A_i A_j} = \frac{4}{3} \gamma^{A_i A_j}, \quad (\text{D30f})$$

The doubly symmetric traceless tensor $X^{A_1 A_2 A_3 A_4 B_1 B_2 B_3 B_4}$ should be

$$\begin{aligned} X^{A_1 A_2 A_3 A_4 B_1 B_2 B_3 B_4} &= \tilde{X}^{(A_1 A_2 A_3 A_4)(B_1 B_2 B_3 B_4)} - \gamma^{(A_1 A_2} \tilde{X}^{A_3 A_4) B_1 B_2 B_3 B_4} - \tilde{X}_{0,1}^{A_1 A_2 A_3 A_4 (B_3 B_4} \gamma_{B_1 B_2)} \\ &\quad + \gamma^{(A_1 A_2} \tilde{X}_{1,1}^{A_3 A_4)(B_1 B_2} \gamma_{B_3 B_4)} + \frac{1}{8} \gamma^{(A_1 A_2} \gamma^{A_3 A_4)} \tilde{X}_{2,0}^{B_1 B_2 B_3 B_4} + \frac{1}{8} \gamma^{(B_1 B_2} \gamma^{B_3 B_4)} \tilde{X}_{0,2}^{A_1 A_2 A_3 A_4} \\ &\quad - \frac{1}{8} \gamma^{(A_1 A_2} \gamma^{A_3 A_4)} \gamma^{(B_1 B_2} \tilde{X}_{2,1}^{B_3 B_4)} - \frac{1}{8} \gamma^{(B_1 B_2} \gamma^{B_3 B_4)} \gamma^{(A_1 A_2} \tilde{X}_{1,2}^{A_3 A_4)} \\ &\quad + \frac{1}{24} \gamma^{(A_1 A_2} \gamma^{A_3 A_4)} \gamma^{(B_1 B_2} \gamma^{B_3 B_4)}. \end{aligned} \quad (\text{D31})$$

2. Other doubly symmetric traceless tensors and related identities

In (5.20), we also defined a doubly symmetric traceless tensor $P_{AB(s)CD(s)}$. Using the identity

$$\gamma_{AC} \gamma_{BD} + s \gamma_{AB} \gamma_{CD} - s \gamma_{AD} \gamma_{CB} = \gamma_{AC} \gamma_{BD} + s \epsilon_{AC} \epsilon_{BD}, \quad (\text{D32})$$

we find

$$\tilde{P}_{AB_1 \dots B_s CD_1 \dots D_s} = (\gamma_{AC} \gamma_{B_1 D_1} + s \epsilon_{AC} \epsilon_{B_1 D_1}) \gamma_{B_2 D_2} \dots \gamma_{B_s D_s}, \quad (\text{D33})$$

and the doubly symmetric traceless tensor becomes

$$P_{AB(s)CD(s)} = \gamma_{AC} X_{B(s)D(s)} - s \epsilon_{AC} Q_{B(s)D(s)}. \quad (\text{D34})$$

There are various identities associated with the tensor $X_{A(s)B(s)}$, $Q_{A(s)B(s)}$, and $P_{AB(s)CD(s)}$.

(1) To calculate the commutator between \mathcal{T}_f and the fundamental field $F_{A(s)}$, we need the identity

$$X_{A(s)B(s)} F^{B(s)} = F_{A(s)}. \quad (\text{D35})$$

(2) To compute the commutator between \mathcal{M}_Y and the fundamental field $F_{A(s)}$, we need the identity

$$P_{AB(s)CD(s)} X^{B(s)}_{E(s)} = P_{AE(s)CD(s)}. \quad (\text{D36})$$

(3) To calculate the commutator between \mathcal{O}_g and the fundamental field $F_{A(s)}$, we need the identities

$$Q^{B(s)}_{C(s)} X_{B(s)A(s)} = Q_{A(s)C(s)}, \quad (\text{D37a})$$

$$Q_{B(s)A(s)} = -Q_{A(s)B(s)}. \quad (\text{D37b})$$

(4) By exchanging the indices A and C in the tensor $P_{AB(s)CD(s)}$, we find the tensor $\rho_{AB(s)CD(s)}$

$$\begin{aligned} \rho_{AB(s)CD(s)} &= \frac{1}{2} (P_{AB(s)CD(s)} + P_{AD(s)CB(s)}) \\ &= \gamma_{AC} X_{B(s)D(s)}. \end{aligned} \quad (\text{D38})$$

(5) To obtain the commutator $[\mathcal{T}_f, \mathcal{M}_Y]$, we used the following identities:

$$\begin{aligned} \Delta_{A(s)}(fY; F) &= f \Delta_{A(s)}(Y; F) \\ &\quad + \frac{1}{2} Y^D \nabla^C f F^{B(s)} P_{DB(s)CA(s)}, \end{aligned} \quad (\text{D39a})$$

$$\Delta_{A(s)}(Y; fF) = f \Delta_{A(s)}(Y; F) + Y^D \nabla_D f F_{A(s)}, \quad (\text{D39b})$$

$$\rho_{AB(s)CD(s)} \dot{F}^{B(s)} \dot{F}^{D(s)} = \gamma_{AC} \dot{F}^{B(s)} \dot{F}_{B(s)}, \quad (\text{D39c})$$

$$\begin{aligned} P_{AB(s)CD(s)} \dot{F}^{D(s)} F^{B(s)} &= \gamma_{AC} \dot{F}^{B(s)} F_{B(s)} \\ &\quad - s \epsilon_{AC} \epsilon^{DE} \dot{F}_D^{B(s-1)} F_{EB(s-1)}. \end{aligned} \quad (\text{D39d})$$

(6) For the commutator $[\mathcal{M}_Y, \mathcal{O}_g]$, we need the integral identity

$$\begin{aligned} & \int d\Omega \mathcal{Q}_{A(s)B(s)} g F^{B(s)} \Delta^{A(s)}(Y; \dot{F}) \\ &= - \int d\Omega \mathcal{Q}_{A(s)B(s)} \dot{F}^{A(s)} \Delta^{B(s)}(Y; gF), \end{aligned} \quad (\text{D40})$$

which follows from the algebraic identity

$$\begin{aligned} & \mathcal{Q}_{E(s)A(s)} P_{DB(s)C}^{A(s)} + \mathcal{Q}_{A(s)B(s)} P_{DE(s)C}^{A(s)} \\ &= 2\gamma_{CD} \mathcal{Q}_{E(s)B(s)}. \end{aligned} \quad (\text{D41})$$

(7) For the commutator $[\mathcal{M}_Y, \mathcal{M}_Z]$, we need the identity

$$\Delta_{A(s)}(Y; \Delta(Z; F)) - \Delta_{A(s)}(Z; \Delta(Y; F)) - \Delta_{A(s)}([Y, Z]; F) = so(Y, Z) \mathcal{Q}_{B(s)A(s)} F^{B(s)}. \quad (\text{D42})$$

To prove this formula, we may rewrite the left-hand side as

$$\text{LHS} = \text{terms with } F + \text{terms with } \nabla F + \text{terms with } \nabla \nabla F. \quad (\text{D43})$$

The terms with the second derivative of F are

$$\begin{aligned} Z^G Y^D \nabla^C \nabla^H F^{E(s)} \rho_{GE(s)H}^{B(s)} \rho_{DB(s)CA(s)} - (Y \leftrightarrow Z) &= Z^D Y^C [\nabla_C, \nabla_D] F_{A(s)} \\ &= -Z^D Y^C R_{A_1 CD}^E F_{EA_2 \dots A_s} - \dots - Z^D Y^C R_{A_s CD}^E F_{A_1 \dots A_{s-1} E} \\ &= -s Y^C Z^D R_{CDE(A_1} F_{A_2 \dots A_s)}^E. \end{aligned} \quad (\text{D44})$$

The terms with only the first derivative of F are

$$\begin{aligned} & \left[Y^D \nabla^C Z^G \nabla^H F^{E(s)} \rho_{GE(s)H}^{B(s)} \rho_{DB(s)CA(s)} + \frac{1}{2} Y^D \nabla^H Z^G \nabla^C F^{E(s)} P_{GE(s)H}^{B(s)} \rho_{DB(s)CA(s)} \right. \\ & \quad \left. + \frac{1}{2} Z^G \nabla^C Y^D \nabla^H F^{E(s)} P_{DB(s)CA(s)} \rho_{GE(s)H}^{B(s)} \right] - (Y \leftrightarrow Z) - [Y, Z]^D \nabla^C F^{B(s)} \rho_{DB(s)CA(s)} \\ &= 0. \end{aligned} \quad (\text{D45})$$

The terms linear in F are

$$\begin{aligned} & \left[\frac{1}{2} Y^C \nabla_C \nabla^H Z^G F^{E(s)} P_{GE(s)HA(s)} + \frac{1}{4} \nabla^C Y^D \nabla^H Z^G F^{E(s)} P_{GE(s)H}^{B(s)} P_{DB(s)CA(s)} \right] - (Y \leftrightarrow Z) - \frac{1}{2} \nabla^C [Y, Z]^D F^{B(s)} P_{DB(s)CA(s)} \\ &= \text{terms with } \nabla \nabla Y \quad \text{or} \quad \nabla \nabla Z + \text{terms with } \nabla Y \nabla Z, \end{aligned} \quad (\text{D46})$$

where the first part can be turned into commutators

$$\begin{aligned} \text{terms with } \nabla \nabla Y \text{ or } \nabla \nabla Z &= \frac{1}{2} Y^C \nabla_C \nabla^H Z^G F^{B(s)} P_{GB(s)HA(s)} - \frac{1}{2} Z^C \nabla_C \nabla^H Y^G F^{B(s)} P_{GB(s)HA(s)} \\ & \quad - \frac{1}{2} Y^H \nabla^C \nabla_H Z^D F^{B(s)} P_{DB(s)HA(s)} + \frac{1}{2} Z^H \nabla^C \nabla_H Y^D F^{B(s)} P_{DB(s)CA(s)} \\ &= \frac{1}{2} Y^C [\nabla_C, \nabla^H] Z^D F^{B(s)} P_{DB(s)HA(s)} - (Y \leftrightarrow Z) \\ &= \frac{1}{2} Y^C Z^E R_{EC}^D F^{B(s)} P_{DB(s)HA(s)} - (Y \leftrightarrow Z) \\ &= \frac{s}{2} Y^C Z^E (R_{DEC(A_1} + R_{CDE(A_1}) F_{A_2 \dots A_s})^D - (Y \leftrightarrow Z). \end{aligned} \quad (\text{D47})$$

Utilizing the Bianchi identity $R_{A[BCD]} = 0$, we find that the above results are canceled by (D44). With the identity

$$P_{GE(s)H}^{B(s)} P_{DB(s)CA(s)} = P_{DE(s)C}^{B(s)} P_{GB(s)HA(s)}, \quad (\text{D48})$$

the terms with ∇Y and ∇Z are

$$\begin{aligned}
 \text{terms with } \nabla Y \text{ and } \nabla Z &= \frac{1}{2} \nabla^E Y^F \nabla^G Z^I F^{B(s)} (\gamma_{IE} P_{FB(s)GA(s)} - \gamma_{FG} P_{IB(s)EA(s)}) \\
 &= \frac{s}{2} \nabla^E Y^F \nabla^G Z^I F^{B(s)} (\gamma_{FG} \epsilon_{IE} - \gamma_{IE} \epsilon_{FG}) Q_{A(s)B(s)} \\
 &= -\frac{s}{4} \nabla^A Y^B \nabla^C Z^D (\epsilon^{BC} \gamma^{AD} + \epsilon^{AC} \gamma^{BD} + \epsilon^{BD} \gamma^{AC} + \epsilon^{AD} \gamma^{BC}) Q_{A(s)B(s)} F^{B(s)} \\
 &= s o(Y, Z) Q_{B(s)A(s)} F^{B(s)}. \tag{D49}
 \end{aligned}$$

We have used the Fierz identity

$$\gamma_{AB} \epsilon_{CD} + \gamma_{AC} \epsilon_{DB} + \gamma_{AD} \epsilon_{BC} = 0. \tag{D50}$$

Therefore, we finish the proof of the identity (D42).

(8) To compute the central charge in the commutator $[\mathcal{T}_{f_1}, \mathcal{T}_{f_2}]$, we need the square of $X_{A(s)B(s)}$

$$X_{A(s)B(s)} X^{A(s)B(s)} = 2. \tag{D51}$$

(9) To compute the central charge $C_{MO}(Y, g)$, we need the identity

$$P_{AB(s)CD(s)} Q^{B(s)D(s)} = -2s \epsilon_{AC}, \tag{D52}$$

which follows from the identities

$$X_{A(s)B(s)} Q^{A(s)B(s)} = 0, \quad Q_{A(s)B(s)} Q^{A(s)B(s)} = 2. \tag{D53}$$

3. Tensors and identities in stereographic project coordinates

The previous identities may be checked in stereographic project coordinates. The nonvanishing components of the

doubly symmetric traceless tensors in this coordinate system are

$$X_{z(s)\bar{z}(s)} = X_{\bar{z}(s)z(s)} = \gamma^s, \tag{D54a}$$

$$P_{Az(s)C\bar{z}(s)} = \gamma^s (\gamma_{AC} - i s \epsilon_{AC}), \tag{D54b}$$

$$P_{A\bar{z}(s)Cz(s)} = \gamma^s (\gamma_{AC} + i s \epsilon_{AC}), \tag{D54c}$$

$$Q_{z(s)\bar{z}(s)} = -Q_{\bar{z}(s)z(s)} = i \gamma^s, \tag{D54d}$$

$$\rho_{Az(s)C\bar{z}(s)} = \rho_{A\bar{z}(s)Cz(s)} = \gamma_{AC} \gamma^s. \tag{D54e}$$

For example, the square of $X_{A(s)B(s)}$ can be found to be

$$X_{A(s)B(s)} X^{A(s)B(s)} = X_{z(s)\bar{z}(s)} X^{z(s)\bar{z}(s)} + X_{\bar{z}(s)z(s)} X^{\bar{z}(s)z(s)} = 2. \tag{D55}$$

One can also use the coordinate transformation to find the doubly symmetric traceless tensors, e.g.,

$$X_{A(s)B(s)} = \frac{\partial z(s)}{\partial \theta^{A(s)}} \frac{\partial \bar{z}(s)}{\partial \theta^{B(s)}} X_{z(s)\bar{z}(s)} + \frac{\partial \bar{z}(s)}{\partial \theta^{A(s)}} \frac{\partial z(s)}{\partial \theta^{B(s)}} X_{\bar{z}(s)z(s)} = \gamma^s \left(\frac{\partial z(s)}{\partial \theta^{A(s)}} \frac{\partial \bar{z}(s)}{\partial \theta^{B(s)}} + \frac{\partial \bar{z}(s)}{\partial \theta^{A(s)}} \frac{\partial z(s)}{\partial \theta^{B(s)}} \right), \tag{D56a}$$

$$Q_{A(s)B(s)} = \frac{\partial z(s)}{\partial \theta^{A(s)}} \frac{\partial \bar{z}(s)}{\partial \theta^{B(s)}} Q_{z(s)\bar{z}(s)} + \frac{\partial \bar{z}(s)}{\partial \theta^{A(s)}} \frac{\partial z(s)}{\partial \theta^{B(s)}} Q_{\bar{z}(s)z(s)} = i \gamma^s \left(\frac{\partial z(s)}{\partial \theta^{A(s)}} \frac{\partial \bar{z}(s)}{\partial \theta^{B(s)}} - \frac{\partial \bar{z}(s)}{\partial \theta^{A(s)}} \frac{\partial z(s)}{\partial \theta^{B(s)}} \right). \tag{D56b}$$

In terms of the projective stereographic coordinates, the flux density operators are simplified greatly

$$T(u, z, \bar{z}) = 2\gamma^{-s} \dot{F} \bar{\dot{F}}, \tag{D57a}$$

$$M_z(u, z, \bar{z}) = \frac{1}{2} (1-s) \gamma^{-s} (\dot{F} \nabla_z F - \bar{F} \nabla_z \dot{F}) + \frac{1}{2} (1+s) \gamma^{-s} (\dot{F} \nabla_z \bar{F} - F \nabla_z \dot{F}), \tag{D57b}$$

$$M_{\bar{z}}(u, z, \bar{z}) = \frac{1}{2} (1+s) \gamma^{-s} (\dot{F} \nabla_{\bar{z}} F - \bar{F} \nabla_{\bar{z}} \dot{F}) + \frac{1}{2} (1-s) \gamma^{-s} (\dot{F} \nabla_{\bar{z}} \bar{F} - F \nabla_{\bar{z}} \dot{F}), \tag{D57c}$$

$$O(u, z, \bar{z}) = i \gamma^{-s} (\dot{F} F - \bar{F} \dot{F}). \tag{D57d}$$

APPENDIX E: CANONICAL QUANTIZATION

1. Mode expansion

We can also use the mode expansion to quantize the fundamental field. After imposing the De Donder gauge, the EOM becomes a wave equation whose solution can be expanded in terms of plane waves

$$f_{\mu(s)}(t, \mathbf{x}) = \sum_{\alpha} \int \frac{d^3\mathbf{k}}{(2\pi)^3} \frac{1}{\sqrt{2\omega_{\mathbf{k}}}} \times [\varepsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) b_{\alpha, \mathbf{k}} e^{-i\omega t + i\mathbf{k}\cdot\mathbf{x}} + \varepsilon_{\mu(s)}^{\alpha}(\mathbf{k}) b_{\alpha, \mathbf{k}}^{\dagger} e^{i\omega t - i\mathbf{k}\cdot\mathbf{x}}], \quad (\text{E1})$$

where $\varepsilon_{\mu(s)}^{\alpha}(\mathbf{k})$ is the polarization tensor. Here, the creation and annihilation operators satisfy the canonical commutator

$$[b_{\alpha, \mathbf{k}}, b_{\beta, \mathbf{k}'}^{\dagger}] = (2\pi)^3 \delta_{\alpha, \beta} \delta^{(3)}(\mathbf{k} - \mathbf{k}'), \quad (\text{E2})$$

while other commutators vanish. One can choose appropriate polarization tensors such that they obey the following completeness relation

$$\sum_{\alpha, \beta} \varepsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) \delta_{\alpha, \beta} \varepsilon_{\nu(s)}^{\beta}(\mathbf{k}) = X_{\mu(s)\nu(s)}, \quad (\text{E3})$$

where $X_{\mu(s)\nu(s)}$ is the doubly symmetric traceless part of $\tilde{X}_{\mu_1 \dots \mu_s \nu_1 \dots \nu_s}$

$$\tilde{X}_{\mu_1 \dots \mu_s \nu_1 \dots \nu_s} = \gamma_{\mu_1 \nu_1} \dots \gamma_{\mu_s \nu_s}. \quad (\text{E4})$$

Here, $\gamma_{\mu\nu}$ has been defined as

$$\gamma_{\mu\nu} = \eta_{\mu\nu} - \frac{1}{2} [n_{\mu}(\mathbf{k}) \bar{n}_{\nu}(\mathbf{k}) + \bar{n}_{\mu}(\mathbf{k}) n_{\nu}(\mathbf{k})] = \gamma_{AB} Y_{\mu}^A Y_{\nu}^B(\Omega_{\mathbf{k}}), \quad (\text{E5})$$

with

$$n_{\mu}(\mathbf{k}) = (-1, n_i(\mathbf{k})), \quad \bar{n}_{\mu}(\mathbf{k}) = (1, n_i(\mathbf{k})), \quad n_i(\mathbf{k}) = \frac{k_i}{|\mathbf{k}|}. \quad (\text{E6})$$

In the context, our polarization tensor satisfies

$$\varepsilon'_{\mu(s-2)} = 0, \quad k^{\nu} \varepsilon_{\nu\mu(s-1)} = 0, \quad \varepsilon_{r\mu(s-1)} = 0, \quad (\text{E7})$$

which imply the corresponding properties of (E3). The property of being symmetric and traceless is obvious due to the construction of $X_{\mu(s)\nu(s)}$, while the others are satisfied by the definition of $\gamma_{\mu\nu}$, namely $k^{\mu} \gamma_{\mu\nu} = 0$ and

$$Y_r^A = Y_{\mu}^A \partial_r x^{\mu} = Y_{\mu}^A n^{\mu} = 0 \Rightarrow \gamma_{r\nu} = \gamma_{AB} Y_r^A Y_{\nu}^B = 0. \quad (\text{E8})$$

As in the context, we impose the falloff

$$f_{\mu(s)}(t, \mathbf{x}) = \frac{F_{\mu(s)}(u, \Omega)}{r} + \mathcal{O}(r^{-2}), \quad (\text{E9})$$

which leads to

$$F_{\mu(s)}(u, \Omega) = \sum_{\alpha} \sum_{\ell, m} \int_0^{\infty} d\omega d\Omega_{\mathbf{k}} \left[\frac{\sqrt{\omega}}{4\sqrt{2\pi^2}i} \varepsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) b_{\alpha, \mathbf{k}} e^{-i\omega u} Y_{\ell, m}(\Omega) Y_{\ell, m}^*(\Omega_{\mathbf{k}}) + \text{h.c.} \right] \\ = \int_0^{\infty} \frac{d\omega}{\sqrt{4\pi\omega}} \sum_{\ell, m} [c_{\mu(s); \omega, \ell, m} e^{-i\omega u} Y_{\ell, m}(\Omega) + \text{h.c.}], \quad (\text{E10})$$

with

$$c_{\mu(s); \omega, \ell, m} = \frac{\omega}{(2\pi)^{3/2}i} \int d\Omega_{\mathbf{k}} \sum_{\alpha} \varepsilon_{\mu(s)}^{*\alpha}(\mathbf{k}) b_{\alpha, \mathbf{k}} Y_{\ell, m}^*(\Omega_{\mathbf{k}}), \quad (\text{E11a})$$

$$c_{\mu(s); \omega, \ell, m}^{\dagger} = \frac{i\omega}{(2\pi)^{3/2}} \int d\Omega_{\mathbf{k}} \sum_{\alpha} \varepsilon_{\mu(s)}^{\alpha}(\mathbf{k}) b_{\alpha, \mathbf{k}}^{\dagger} Y_{\ell, m}(\Omega_{\mathbf{k}}). \quad (\text{E11b})$$

Converting to retarded frame, we obtain

$$F_{A(s)}(u, \Omega) = F_{\mu(s)}(u, \Omega) (-Y_{A_1}^{\mu_1}) \dots (-Y_{A_s}^{\mu_s}) \\ = \int_0^{\infty} \frac{d\omega}{\sqrt{4\pi\omega}} \sum_{\ell, m} [(-1)^s c_{i(s); \omega, \ell, m} Y_{A(s)}^{i(s)} Y_{\ell, m}(\Omega) e^{-i\omega u} + \text{h.c.}]. \quad (\text{E12})$$

It is straightforward to compute the commutation relation between boundary creation and annihilation operators

$$\begin{aligned} [c_{i(s);\omega,\ell,m}, c_{i'(s);\omega',\ell',m}^\dagger] &= \frac{\omega\omega'}{(2\pi)^3} \int d\Omega_k d\Omega'_k \varepsilon_{i(s)}^{*\alpha}(\mathbf{k}) Y_{\ell,m}^*(\Omega_k) \varepsilon_{i'(s)}^{\alpha'}(\mathbf{k}') Y_{\ell',m'}^*(\Omega'_k) [b_{\alpha,\mathbf{k}}, b_{\alpha',\mathbf{k}'}^\dagger] \\ &= \delta(\omega - \omega') \int d\Omega_k X_{i(s)i'(s)} Y_{\ell,m}^*(\Omega_k) Y_{\ell',m'}(\Omega_k). \end{aligned} \quad (\text{E13})$$

Now we are prepared to calculate the fundamental commutator

$$\begin{aligned} [F_{A(s)}(u, \Omega), F_{B(s)}(u', \Omega')] &= \int_0^\infty \frac{d\omega}{\sqrt{4\pi\omega}} \frac{d\omega'}{\sqrt{4\pi\omega'}} \left[Y_{A(s)}^{i(s)} Y_{B(s)}^{i'(s)} \right. \\ &\quad \times \sum_{\ell m} Y_{\ell,m}(\Omega) e^{-i\omega u} \sum_{\ell' m'} Y_{\ell',m'}^*(\Omega') e^{i\omega' u'} [c_{i(s);\omega,\ell,m}, c_{i'(s);\omega',\ell',m'}^\dagger] + \text{h.c.} \left. \right] \\ &= \frac{i}{2} \alpha(u - u') \delta(\Omega - \Omega') Y_{A(s)}^{i(s)} Y_{B(s)}^{i'(s)} X_{i(s)i'(s)} \\ &= \frac{i}{2} X_{A(s)B(s)} \alpha(u - u') \delta(\Omega - \Omega'), \end{aligned} \quad (\text{E14})$$

which agrees with our previous result from boundary symplectic form.

We can also use the mode expansion to derive the antipodal matching conditions

$$F_{\mu(s)}^+(\omega, \Omega) = -F_{\mu(s)}^-(\omega, \Omega^P), \quad F_{\mu(s)}^{+(2)}(\omega, \Omega) = F_{\mu(s)}^{-(2)}(\omega, \Omega^P), \quad (\text{E15})$$

up to the first 2 orders, where $\Omega^P = (\pi - \theta, \pi + \phi)$ is the antipodal point of $\Omega = (\theta, \phi)$ on the sphere, and $+$ ($-$) denotes fields at \mathcal{I}^+ (\mathcal{I}^-). This result has also been checked using Green's function for retarded and advanced solutions of the wave equation with source.

2. Polarization tensors

In this subsection, we discuss the polarization tensors in HS theory.

Spin one and special momentum. For simplicity, we consider the case of $s = 1$ and take a special momentum $k_\mu = |\mathbf{k}|(1, 0, 0, 1)$, which is followed by

$$\gamma_{\mu\nu} = \begin{pmatrix} 0 & & & \\ & 1 & & \\ & & 1 & \\ & & & 0 \end{pmatrix}, \quad \bar{\varepsilon}_{\mu\nu} = \begin{pmatrix} 0 & & & \\ & 0 & 1 & \\ & & -1 & 0 \\ & & & 0 \end{pmatrix}. \quad (\text{E16})$$

We need the polarization vectors to satisfy the orthogonality and completeness relations

$$\gamma^{\mu\mu'} \varepsilon_\mu^{*\alpha}(\mathbf{k}) \varepsilon_{\mu'}^{\alpha'}(\mathbf{k}) = \delta^{\alpha\alpha'}, \quad (\text{E17})$$

$$\sum_{\alpha,\beta} \varepsilon_\mu^{*\alpha}(\mathbf{k}) \delta_{\alpha,\beta} \varepsilon_\nu^\beta(\mathbf{k}) = \gamma_{\mu\nu}, \quad (\text{E18})$$

and the transverse condition

$$k^\mu \varepsilon_\mu^\alpha(\mathbf{k}) = 0. \quad (\text{E19})$$

A natural choice is

$$\varepsilon_\mu^R = \frac{1}{\sqrt{2}}(0, 1, i, 0), \quad \varepsilon_\mu^L = \frac{1}{\sqrt{2}}(0, 1, -i, 0), \quad (\text{E20})$$

which also satisfy the condition

$$\bar{\varepsilon}^{\nu\mu}(\Omega_k) \varepsilon_\mu^{*\alpha}(\mathbf{k}) \varepsilon_\nu^\beta(\mathbf{k}) = i\sigma_3^{\alpha\beta}, \quad (\text{E21})$$

and thus agree with (6.29).

General momentum. For a general momentum k_μ , the construction of the polarization vectors may be rather complicated. However, we find that the properties that they need to satisfy happen to be the ones of Y_μ^A , namely

$$Y_\mu^A Y_\nu^B \gamma_{AB} = \gamma_{\mu\nu}, \quad (\text{E22})$$

$$\gamma^{\mu\nu} Y_\mu^A Y_\nu^B = \eta^{\mu\nu} Y_\mu^A Y_\nu^B = \gamma^{AB}, \quad (\text{E23})$$

and $n^\mu Y_\mu^A = 0$, except for (E21). Therefore, one can introduce the vielbeins

$$e_1^A = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \sin^{-1} \theta \end{pmatrix}, \quad e_2^A = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -\sin^{-1} \theta \end{pmatrix}, \quad (\text{E24})$$

such that

$$\delta^{\alpha\beta} e_\alpha^A e_\beta^B = \gamma^{AB}. \quad (\text{E25})$$

It follows that the polarization vectors can be expressed as

$$\varepsilon_\mu^A = \varepsilon_\mu^\alpha e_\alpha^A \equiv Y_\mu^A. \quad (\text{E26})$$

One can invert the relation to obtain

$$\varepsilon_\mu^\alpha = Y_\mu^A e_\alpha^A, \quad e_\alpha^A = e_{\beta}^B \gamma_{AB} \delta^{\alpha\beta}. \quad (\text{E27})$$

With the choice (E26), we find

$$\bar{\varepsilon}^{\mu\nu} Y_\mu^A Y_\nu^B = \varepsilon^{CD} Y_C^\mu Y_D^\nu Y_\mu^A Y_\nu^B = \varepsilon^{AB} = -\varepsilon^{\alpha\beta} e_\alpha^A e_\beta^B, \quad (\text{E28})$$

$$\Leftrightarrow \bar{\varepsilon}^{\nu\mu} \varepsilon_\mu^{*\alpha} \varepsilon_\nu^\beta = \varepsilon^{\alpha\beta}, \quad (\text{E29})$$

which is not the last property (E21) superficially. However, one can combine the polarization vectors to get

$$\varepsilon_\mu^R = \frac{1}{\sqrt{2}}(\varepsilon_\mu^1 + i\varepsilon_\mu^2), \quad \varepsilon_\mu^L = \frac{1}{\sqrt{2}}(\varepsilon_\mu^1 - i\varepsilon_\mu^2), \quad (\text{E30})$$

which satisfy

$$\bar{\varepsilon}^{\nu\mu} \varepsilon_\mu^{*\alpha} \varepsilon_\nu^\beta = i\sigma_3^{\alpha\beta}, \quad \alpha, \beta = R, L, \quad (\text{E31})$$

as we want.

General spin. The key point to derive the HS polarization tensors is noting that (E30) can be rewritten as

$$\begin{aligned} \varepsilon_\mu^R &= \frac{1}{2}[(1+i)Y_\mu^\theta + (1-i)\sin\theta Y_\mu^\phi] \\ &= \frac{1}{2}(1+i)(Y_\mu + i\tilde{Y}_\mu)^\theta \equiv \frac{1}{2}(1+i)\mathcal{Y}_\mu, \end{aligned} \quad (\text{E32a})$$

$$\begin{aligned} \varepsilon_\mu^L &= \frac{1}{2}[(1-i)Y_\mu^\theta + (1+i)\sin\theta Y_\mu^\phi] \\ &= \frac{1}{2}(1-i)(Y_\mu - i\tilde{Y}_\mu)^\theta \equiv \frac{1}{2}(1-i)\bar{\mathcal{Y}}_\mu, \end{aligned} \quad (\text{E32b})$$

where we have defined

$$\tilde{Y}_\mu^A = Y_\mu^B \varepsilon_B^A = (0, \tilde{Y}_i^A), \quad (\text{E33})$$

which can also be interpreted as a Hodge dual

$$\tilde{Y}_\mu^A = \tilde{Y}_{0\mu}^A = \left(0, \frac{1}{2}\varepsilon_{ijk} Y_{jk}^A\right), \quad \tilde{Y}_{\mu\nu}^A = \frac{1}{2}\varepsilon_{\mu\nu\rho\sigma} Y^{\rho\sigma A}. \quad (\text{E34})$$

One can easily find

$$\mathcal{Y}_\mu = (Y_\mu + i\tilde{Y}_\mu)^\theta = \begin{pmatrix} 0 \\ -\cos\theta \cos\phi - i\sin\phi \\ -\cos\theta \sin\phi + i\cos\phi \\ \sin\theta \end{pmatrix}, \quad (\text{E35})$$

and its complex conjugate $\bar{\mathcal{Y}}_\mu$, which agree with the expression in the literature, such as [87]. Now we can construct the polarization tensors for the HS theory

$$\varepsilon_{\mu(s)}^R = \varepsilon_{\mu_1}^R \cdots \varepsilon_{\mu_s}^R = \frac{(1+i)^s}{2^s} \mathcal{Y}_{\mu_1} \cdots \mathcal{Y}_{\mu_s} = \frac{(1+i)^s}{2^s} \mathcal{Y}_{\mu(s)}, \quad (\text{E36a})$$

$$\varepsilon_{\mu(s)}^L = \varepsilon_{\mu_1}^L \cdots \varepsilon_{\mu_s}^L = \frac{(1-i)^s}{2^s} \bar{\mathcal{Y}}_{\mu_1} \cdots \bar{\mathcal{Y}}_{\mu_s} = \frac{(1-i)^s}{2^s} \bar{\mathcal{Y}}_{\mu(s)}. \quad (\text{E36b})$$

A nice property is that these expressions are automatically symmetric and traceless, since we have

$$\begin{aligned} \eta^{\mu\nu} (Y_\mu + i\tilde{Y}_\mu)^A (Y_\nu + i\tilde{Y}_\nu)^B \\ = \gamma^{\mu\nu} (Y_\mu + i\tilde{Y}_\mu)^A (Y_\nu + i\tilde{Y}_\nu)^B = 0, \end{aligned} \quad (\text{E37a})$$

$$\begin{aligned} \eta^{\mu\nu} (Y_\mu - i\tilde{Y}_\mu)^A (Y_\nu - i\tilde{Y}_\nu)^B \\ = \gamma^{\mu\nu} (Y_\mu - i\tilde{Y}_\mu)^A (Y_\nu - i\tilde{Y}_\nu)^B = 0, \end{aligned} \quad (\text{E37b})$$

due to the identities $n^\mu Y_\mu^A = n^\mu \tilde{Y}_\mu^A = \bar{n}^\mu Y_\mu^A = \bar{n}^\mu \tilde{Y}_\mu^A = 0$ and

$$Y^A \cdot Y^B = \tilde{Y}^A \cdot \tilde{Y}^B = \gamma^{AB}, \quad Y^A \cdot \tilde{Y}^B = \varepsilon^{AB}. \quad (\text{E38})$$

Now we need to check the orthogonality and completeness relations, as well as (6.29). The orthogonality relation is straightforward

$$X^{\mu(s)\nu(s)} \varepsilon_{\mu(s)}^{*\alpha} \varepsilon_{\nu(s)}^{\alpha'} = \delta^{\alpha\alpha'}, \quad (\text{E39})$$

since we have

$$\gamma^{\mu\nu} \bar{\mathcal{Y}}_\mu \mathcal{Y}_\nu = 2, \quad \gamma^{\mu\nu} \mathcal{Y}_\mu \mathcal{Y}_\nu = \gamma^{\mu\nu} \bar{\mathcal{Y}}_\mu \bar{\mathcal{Y}}_\nu = 0. \quad (\text{E40})$$

The completeness relation reads

$$\begin{aligned} \varepsilon_{\mu(s)}^{*R} \varepsilon_{\nu(s)}^R + \varepsilon_{\mu(s)}^{*L} \varepsilon_{\nu(s)}^L \\ = 2^{-s} [\bar{\mathcal{Y}}_{\mu_1} \cdots \bar{\mathcal{Y}}_{\mu_s} \mathcal{Y}_{\nu_1} \cdots \mathcal{Y}_{\nu_s} + \text{c.c.}] = X_{\mu(s)\nu(s)}, \end{aligned} \quad (\text{E41})$$

which is a bit difficult to prove. For $s = 1$, we know that it is satisfied

$$\bar{\mathcal{Y}}_\mu \mathcal{Y}_\nu + \text{c.c.} = 2\gamma_{\mu\nu}. \quad (\text{E42})$$

For $s = 2$, we find

$$\begin{aligned}
 X_{\mu(2)\nu(2)} &= \frac{1}{2}(\gamma_{\mu_1\nu_1}\gamma_{\mu_2\nu_2} + \gamma_{\mu_1\nu_2}\gamma_{\mu_2\nu_1} - \gamma_{\mu_1\mu_2}\gamma_{\nu_1\nu_2}) \\
 &= \frac{1}{2} \times \frac{1}{4} [(\bar{\mathcal{Y}}_{\mu_1}\mathcal{Y}_{\nu_1} + \text{c.c.})(\bar{\mathcal{Y}}_{\mu_2}\mathcal{Y}_{\nu_2} + \text{c.c.}) + (\bar{\mathcal{Y}}_{\mu_1}\mathcal{Y}_{\nu_2} + \text{c.c.})(\bar{\mathcal{Y}}_{\mu_2}\mathcal{Y}_{\nu_1} + \text{c.c.}) - (\bar{\mathcal{Y}}_{\mu_1}\mathcal{Y}_{\mu_2} + \text{c.c.})(\bar{\mathcal{Y}}_{\nu_1}\mathcal{Y}_{\nu_2} + \text{c.c.})] \\
 &= \frac{1}{4} [\bar{\mathcal{Y}}_{\mu_1}\bar{\mathcal{Y}}_{\mu_2}\mathcal{Y}_{\nu_1}\mathcal{Y}_{\nu_2} + \text{c.c.}].
 \end{aligned} \tag{E43}$$

In general, we find that the right-hand side of the completeness relation is

$$\text{DST}[\gamma_{\mu_1\nu_1} \cdots \gamma_{\mu_s\nu_s}] = 2^{-s} \text{DST}[(\bar{\mathcal{Y}}_{\mu_1}\mathcal{Y}_{\nu_1} + \text{c.c.}) \cdots (\bar{\mathcal{Y}}_{\mu_s}\mathcal{Y}_{\nu_s} + \text{c.c.})], \tag{E44}$$

which contains a same number of $\bar{\mathcal{Y}}$ and \mathcal{Y} . The notation “DST[$\cdot \cdot \cdot$]” represents the doubly symmetric traceless part of the expression inside the square brackets. To be doubly symmetric traceless, we must have

$$\text{DST}[(\bar{\mathcal{Y}}_{\mu_1}\mathcal{Y}_{\nu_1} + \text{c.c.}) \cdots (\bar{\mathcal{Y}}_{\mu_s}\mathcal{Y}_{\nu_s} + \text{c.c.})] \propto \bar{\mathcal{Y}}_{\mu_1} \cdots \bar{\mathcal{Y}}_{\mu_s}\mathcal{Y}_{\nu_1} \cdots \mathcal{Y}_{\nu_s} + \text{c.c.}, \tag{E45}$$

due to the relations (E40). Then the overall coefficient is easily to be determined.

At last, we can check

$$Q^{\mu(s)\mu'(s)} \epsilon_{\mu(s)}^{*\alpha} \epsilon_{\mu'(s)}^{\alpha'} = i\sigma_3^{\alpha\alpha'}, \quad \alpha, \alpha' = \text{R, L}, \tag{E46}$$

where we need to use

$$Y_A^\mu \bar{\mathcal{Y}}_\mu = Y_A^\mu (Y_\mu - i\tilde{Y}_\mu)^\theta = \gamma_A^\theta - i\epsilon_A^\theta, \tag{E47}$$

and thus,

$$\frac{1}{2} \bar{\epsilon}^{\nu\mu} \bar{\mathcal{Y}}_\mu \mathcal{Y}_\nu = \frac{1}{2} \epsilon^{AB} Y_A^\nu Y_B^\mu \bar{\mathcal{Y}}_\mu \mathcal{Y}_\nu = i. \tag{E48}$$

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