# Study of early time attractor with longitudinal forces with Bjorken symmetry

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(Received 28 November 2023; accepted 8 March 2024; published 15 April 2024)

We study the effect of external proper time-dependent longitudinal forces on the evolution of the distribution function using the Boltzmann equation with a relaxation time collision kernel under Bjorken flow. We derive an exact solution and study the early time attractor behavior of different components of energy-momentum tensor under Bjorken symmetry. We show that the arbitrary initial data approaches the attractor solution but is influenced by the external force with slightly broken Bjorken symmetry.

DOI: 10.1103/PhysRevD.109.074020

### I. INTRODUCTION

In the realm of high-energy heavy-ion collisions, two massive nuclei collide at relativistic speeds and create quark-gluon plasma (QGP) [1]. This novel state of matter is composed of deconfined quarks and gluons, almost freely traversing the nuclear volume. Owing to the initial velocity of the two colliding nuclei, initially, the hot and dense fireball expands primarily along the beam direction; the transverse expansion due to the hydrodynamic response of the system takes some time to catch up with the longitudinal expansion [2-5]. Due to this initial asymmetric flow, the momentum anisotropy can be substantial. This may give rise to a situation where the system is far away from local thermal equilibrium. The momentum anisotropy is also supposed to be larger for smaller systems such as p-p, p-Au, d-Au, etc. However, relativistic hydrodynamics seems to work well even for these small systems [6,7].

Hydrodynamics is a valid description of dynamics when a system under scrutiny has attained a state of near local thermal equilibrium (i.e., the ratio of the off-equilibrium part of the energy-momentum tensor to the equilibrium one is much smaller than one). This raises the question of how the hydrodynamics can be a valid description for the QGP evolution at small timescales of ~0.1 to 0.2 fm/c (at LHC) or for smaller systems where it is supposed to be highly anisotropic. Hydrodynamic attractors were proposed [8] as a possible solution to why hydrodynamics effectively describe QGP evolution even for systems far from local thermal equilibrium. For systems with certain symmetries—conformal and Bjorken/Gubser, it was observed that the nonhydrodynamic modes decay exponentially, and the system relaxes to an attractor solution regardless of the initial conditions (near or far away from local thermal equilibrium). It was speculated then that the validity of hydrodynamics could be expanded beyond the limit of small gradients as previously held. Several subsequent studies [9–21], showed that attractor solutions could be observed in less symmetric systems albeit in a more general sense of an attractor. However, more recent nonconformal studies [11,12,22] using exact solutions to the Boltzmann equation pointed out that attractor behavior is not as general as previously thought as it was absent in several hydrodynamic variables when conformal symmetry was broken and nonconformal systems only show an early-time attractor for the case of scaled longitudinal pressure  $P_L/P$ .

Given that a universal attractor is absent in nonconformal systems, one could ask whether attractors still exist when other symmetries are broken. One method to explore this is to introduce an external force. Due to the relativistic speed of the charged protons inside the colliding nuclei, there exists a strong transient electromagnetic field in the initial stage of heavy-ion collisions. These fields are estimated to possess strengths on the order of  $10^{18}$  to  $10^{19}$  G at the apex of RHIC or LHC energies [23-27]. Advancements have recently been made across various fronts, encompassing theoretical [28–32], phenomenological [33,34], and experimental domains [35,36], all in pursuit of detecting the telltale signals of these potent electromagnetic fields. Given that early-time attractors explore the journey toward equilibrium from highly nonequilibrated states, it is both logical and imperative to investigate their behavior in the presence of electromagnetic fields. In this study, we intend to explore the evolution of a far-from-equilibrium system under an external force arising due to the interaction of electrically conducting QGP fluid and the initial strong EM fields.

We use the RTA-Boltzmann equation to study the effects of external forces in a 0 + 1 dimensional setting under approximate Bjorken symmetry. Specifically, we subject the

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system to a longitudinal force and explore how the evolution of the system varies for varying field strengths and initial anisotropies. We check for the presence of attractor behavior in hydrodynamic variables for the nonconformal systems and if they persist in the conformal limit. For our calculations, we will be using natural units,  $\bar{h} = k_B = c = \epsilon_0 =$  $\mu_0 = 1$ , and the metric signature is mostly negative  $g_{\mu\nu} = \text{diag}(+, -, -, -)$ .

Our paper is structured as follows. In Sec. II, we discuss the relativistic Boltzmann equation with the RTA collision kernel. Then, in the next section, Sec. III, we discuss symmetries and the Bjorken flow. In the next section, Sec. IV, we talk about the formal solution of the Boltzmann equation with external forces. We also cover the discussions on the initial distribution function and how to describe these external forces in Sec. V. Finally, we present our findings for different situations involving external forces and summarize our findings in Secs. VI and VII respectively.

### **II. THE BOLTZMANN EQUATION**

The Boltzmann equation describes the evolution of the single-particle phase space distribution function f(x, p) of a statistical system. The expression of the Boltzmann equation in the presence of external forces can be written as [37]

$$p^{\mu}\frac{\partial f}{\partial x^{\mu}} + mK^{\mu}\frac{\partial f}{\partial p^{\mu}} - \Gamma^{\sigma}_{\mu\nu}p^{\mu}p^{\nu}\frac{\partial f}{\partial p^{\sigma}} = C(f), \qquad (1)$$

here  $K^{\mu}$  is a 4-force and  $\Gamma^{\rho}_{\mu\nu}$  is the Christoffel symbol. The momenta  $p^{\mu}$  satisfy the onshell relation  $g_{\mu\nu}p^{\mu}p^{\nu} = m^2$  and the 4-force satisfy  $g_{\mu\nu}p^{\mu}K^{\mu}/p^0 = 0$ . As the general collision kernel is quite complex, we use Anderson-Witting relaxation time approximation (RTA) [37]

$$C(f) = -u \cdot p \frac{(f - f_{eq})}{\tau_R}.$$
 (2)

Here,  $f_{eq} \sim e^{-(u \cdot p)/T}$  represents the local equilibrium distribution function.  $u \cdot p = g_{\mu\nu} u^{\nu} p^{\mu}$  represents the inner product. *T* is the local temperature and  $u^{\mu}$  is the fluid 4-velocity  $(g_{\mu\nu}u^{\mu}u^{\nu} = 1)$ . We consider the relaxation time  $\tau_R$  is a function of temperature but not of momentum.

The energy-momentum tensor  $T^{\mu\nu}(x)$  is obtained from the distribution function by taking its second moment

$$T^{\mu\nu} = \int d\Xi p^{\mu} p^{\nu} f, \qquad (3)$$

where the integration measure is given by  $d\Xi = \frac{\sqrt{-g}d^3p}{(2\pi)^3p^0}$ . The energy-momentum conservation  $\nabla_{\mu}T^{\mu\nu} = 0$  is ensured for the RTA kernel by imposing the Landau matching condition

$$\int d\Xi (u_{\mu}p^{\mu})^2 f = \int d\Xi (u_{\mu}p^{\mu})^2 f_{\rm eq}, \qquad (4)$$

where  $\nabla_{\mu}$  is the covariant derivative. Here the fluid fourvelocity  $u^{\mu}$  is defined as the eigenvector of  $T^{\mu\nu}$  with energy density  $\epsilon$  as the eigenvalue

$$T^{\mu\nu}u_{\nu} = \epsilon u^{\mu}. \tag{5}$$

### **III. SYMMETRIES AND BJORKEN FLOW**

The symmetries of the system set restrictions on the flow profile of the fluid. A Bjorken system is characterized by translation, rotational symmetry in the transverse plane (x - y), boost invariance along the longitudinal direction z, and a reflection symmetry $(z \rightarrow -z)$ . The symmetries completely determine the Bjorken flow profile,

$$u^{\mu} = \left(\frac{t}{\sqrt{t^2 - z^2}}, 0, 0, \frac{z}{\sqrt{t^2 - z^2}}\right).$$
 (6)

We use Milne coordinate system  $(\tau, x, y, \eta)$ , where

$$\tau = \sqrt{t^2 - z^2},\tag{7}$$

$$\eta = \tanh^{-1}\frac{z}{t},\tag{8}$$

where  $\tau$  is the longitudinal proper time,  $\eta$  the space-time rapidity. The Milne metric is given by  $g_{\mu\nu} = \text{diag}(1, -1, -1, -\tau^2)$  with the nonzero Christoffels symbols

$$\Gamma^{\tau}_{\eta\eta} = \frac{1}{\tau}, \qquad \Gamma^{\eta}_{\tau\eta} = \tau.$$
(9)

The flow profile in the Milne coordinate with Bjorken symmetry ( $\eta$  invariance) becomes  $u^{\mu} = (1, 0, 0, 0)$ . Rotational and translational symmetries in the transverse plane imply that the distribution function cannot depend on x and y. The spatial dependence then reduces to only that of the proper time  $\tau$  due to boost invariance and reflection symmetry. We use transverse momentum  $p_T = \sqrt{p_x^2 + p_y^2}$ and  $w \equiv p_{\eta} = \tau p^z = tp^z - zp^t$  in the longitudinal direction. The distribution function is then only dependent on three variables, one space, and two momenta and the Boltzmann Equation in Milne coordinates takes the simple form

$$\frac{\partial f(\tau, p_T, w)}{\partial \tau} = -\frac{(f - f_{eq})}{\tau_R}.$$
 (10)

A formal solution can be found for this equation in [38–41] which is given as:

$$f(\tau, w, p_T) = D(\tau, \tau_0) f_0(w, p_T) + \int_{\tau_0}^{\tau} \frac{d\tau'}{\tau_R(\tau')} D(\tau, \tau') f_{eq}(\tau', w, p_T), \quad (11)$$

where  $D(\tau_2, \tau_1)$  the damping function defined as

$$D(\tau_2, \tau_1) = \exp\left[-\int_{\tau_1}^{\tau_2} \frac{d\tau''}{\tau_R(\tau'')}\right],\tag{12}$$

and  $f_0 = f(\tau = \tau_0, w, p_T)$ .

#### A. RTA Boltzmann equation under longitudinal force

The introduction of an external force is bound to break one of the four symmetries. This means that Bjorken flow could be modified in the presence of force. In order to approximately retain Bjorken flow, the simplest force one can then introduce is one that only depends on the proper time  $\tau$  and is along the z direction. The introduction of this force will break reflection symmetry about  $\eta = 0$ . Considering the force to be weak enough so that the change in fluid velocity ( $\delta u^{\mu}$ ) is small and the new velocity is written as

$$u^{\mu} = u^{\mu}_{B} + \delta u^{\mu}. \tag{13}$$

This approximation is valid as long as the correction to the fluid variables due to the force is smaller than the equilibrium values. Assuming Bjorken flow, the Boltzmann equation with force along z direction can then be written as (see Appendix A for details)

$$\left(\mathcal{F}(\tau)\tau\frac{\partial}{\partial w} + \frac{\partial}{\partial \tau}\right)f = -\frac{(f - f_{eq})}{\tau_R}.$$
 (14)

#### **IV. SOLUTION UNDER EXTERNAL FORCE**

Here we assume  $\mathcal{F}(\tau) \neq 0$  for any value of  $\tau_i < \tau < \tau_f$ (where  $\tau_i$  and  $\tau_f$  are initial and final time).For convenience we introduce a dimensionless function  $F(\tau)$  and express  $\mathcal{F} = \frac{\alpha}{\tau_F} F(\tau)$ . After a change of variables (see Appendix A 1), Eq. (14) takes the following form,

$$\frac{\partial f(r, s, p_T)}{\partial s} = -\frac{\tau_F}{\tau_R} \frac{(f - f_{eq})}{F(\tau(s))\tau(s)}.$$
 (15)

Where we have defined a new variable *s*.

$$s(\tau) = \int_0^\tau F(\tau') \frac{\tau'}{\tau_F} d\tau', \qquad (16)$$

and used the coordinate transformations  $(w, \tau) \rightarrow (r, s)$ ,

$$r = w - \alpha s, \tag{17}$$

$$s = s. \tag{18}$$

Here  $\alpha$  and  $\tau_F$  are constants with dimensions of momentum and time respectively so that  $\alpha/\tau_F$  has dimensions of force. Then we can write a solution

$$f(s, r, p_T) = D(s, s_0) f_0(r, p_T) + \int_{s_0}^s \frac{ds'}{\tau_R(s')} D(s, s') f_{eq}(s', r, p_T), \quad (19)$$

where

$$D(s_1, s_2) = \exp\left[-\int_{s_1}^{s_2} \frac{ds'}{F(\tau(s'))(\tau(s')/\tau_F)\tau_R(s')}\right].$$
 (20)

The above expression for  $D(s_1, s_2)$  gives the impression that it depends explicitly on the force. However, if one were to change the coordinates back from  $s \to \tau$ , we can see that  $D(s_1, s_2)$  takes the form

$$D(\tau_1, \tau_2) = \exp\left[-\int_{\tau_1}^{\tau_2} \frac{d\tau'}{\tau_R(\tau')}\right].$$
 (21)

Therefore dependence of  $D(\tau_1, \tau_2)$  on force is only implicitly through  $\tau_R(\tau')$ .

#### V. INITIAL CONDITIONS

The initial anisotropic distribution is chosen to be that of Romatschke-Strickland and form [42],

$$f_0 = \frac{2}{(2\pi)^3 N_0} \exp\left\{-\frac{\sqrt{p_T^2 + (1 + \xi_0)p_z^2 + m^2}}{\Lambda_0}\right\}.$$
 (22)

The three initial free parameters  $N_0$ ,  $\xi_0$  and  $\Lambda_0$  allow us to specify the initial fluid parameters  $T, P_L$  and  $P_T$ . Here  $\xi_0$ corresponds to the longitudinal anisotropic parameter in momentum space, and  $\Lambda_0$  is an energy scale, and in the limit it reduces to local temperature. The value of  $\Lambda_0$  and  $N_0$  is set such that the energy density matches the energy density of an equilibrium distribution with the initial temperature  $T_0$ . To study the effect of varying  $\frac{m}{\Lambda_0}$  we can change  $N_0$  while ensuring that the initial energy density and  $\xi_0$  remain fixed. For the nonconformal case  $(m/\Lambda_0 \neq 0)$  we use the same set of initial parameters (Table II, Appendix III) as [43] for ease of comparison.

The hydrodynamic variables like energy density  $(\mathcal{E})$ , longitudinal  $P_L$  and transverse pressure  $P_T$  in the presence of external forces can be obtained from Eqs. (3) and (19)

$$\mathcal{E}(s) = D(s, s_0) \frac{\Lambda_0^4}{4\pi N_0} H_{\varepsilon}^F \left[ s_0, s, \xi_0, \frac{\alpha}{\Lambda_0}, \frac{m}{\Lambda_0} \right] + \int_{s_0}^s \frac{ds'}{\tau_R(s')} D(s', s) T^4(s') H_{\varepsilon}^F \left[ s', s, \frac{\alpha}{T}, \frac{m}{T} \right], \quad (23)$$

$$P_{L}(s) = D(s, s_{0}) \frac{\Lambda_{0}^{4}}{4\pi N_{0}} H_{L}^{F} \left[ s_{0}, s, \xi_{0}, \frac{\alpha}{\Lambda_{0}}, \frac{m}{\Lambda_{0}} \right] + \int_{s_{0}}^{s} \frac{ds'}{\tau_{R}(s')} D(s', s) T^{4}(s') H_{L}^{F} \left[ s', s, \frac{\alpha}{T}, \frac{m}{T} \right], \quad (24)$$

$$P_{T}(s) = D(s, s_{0}) \frac{\Lambda_{0}^{4}}{4\pi N_{0}} H_{T}^{F} \left[ s_{0}, s, \xi_{0}, \frac{\alpha}{\Lambda_{0}}, \frac{m}{\Lambda_{0}} \right] + \int_{s_{0}}^{s} \frac{ds'}{\tau_{R}(s')} D(s', s) T^{4}(\tau') H_{T}^{F} \left[ s', s, \frac{\alpha}{T}, \frac{m}{T} \right], \quad (25)$$

by evaluating the corresponding integrals Appendix B. Note that due to the breaking of reflection symmetry, the energymomentum tensor is no longer diagonal. The nondiagonal term  $T^{03}$  can be evaluated as

$$T^{03} = \int_{s_0}^{s} \frac{ds'}{\tau_R(s')} D(s, s') T^4(s') H_{03}^F \left[ s', s, \frac{m}{T} \right].$$
(26)

We can use it to calculate the modified flow velocity  $u^{\mu}$  using the Landau frame definition

$$T^{\mu\nu}u_{\nu} = \epsilon u^{\mu}. \tag{27}$$

 $T^{03}/P_{eq}$  contains the directionality of the force as its sign changes with the force direction. Therefore we can use  $T^{03}/P_{eq}$  and  $\delta u/u \ll 1$  as a measure of self consistency. Here  $P_{eq}$  is the equilibrium isotropic pressure defined by

$$P_{\rm eq} = \int d\Xi \frac{\boldsymbol{p}^2}{3} f_{\rm eq}.$$
 (28)

For the rest of our calculation, we use the conformal relation  $\tau_R(\tau) = 5c/T(\tau)$ , where  $c \propto \frac{\eta_0}{s_0}$  is a dimensionless number which sets the initial viscosity of the system. In this study, we set the initial time to  $\tau_0 = 0.1$  fm and the initial temperature to  $T_0 = 500$  MeV. For the nonconformal computations, we set the mass to m = 200 MeV.

The Eq. (23) can be solved using iterative techniques (A faster algorithm compared to the iterative technique used in previous studies is given in Appendix C) and using the energy density-temperature relation,

$$\mathcal{E}(T) = \frac{3T^4}{\pi^2} \left( \frac{z^2}{2} K_2(z) + \frac{z^3}{6} K_1(z) \right), \tag{29}$$

where z = m/T and  $K_1$ ,  $K_2$  are modified Bessel functions of the second kind. The relations for pressure Eqs. (24)



FIG. 1. Normalized force  $(\max(F) = 1)$  for different timescales.  $\tau_F = 1 \text{ fm/c (dot)}, \tau_F = 2.5 \text{ fm/c (dashed)}, \tau_F = 5 \text{ fm/c (dot-dashed)}.$ 

and (25) can be evaluated once the temperature is obtained using the above procedure.

### A. Parametrized force

#### 1. Force type 1

Motivated by the exponentially decaying fields in highenergy heavy-ion collisions we use the following parametrization of the force

$$F(\tau) = \frac{\tau}{\tau_F} \exp\left\{1 - \frac{\tau}{\tau_F}\right\},\tag{30}$$

where  $\tau_F$  is a decay timescale. The parameter  $\tau_F$  is the proper time at which  $\mathcal{F}$  takes its maximum value  $\frac{\alpha}{\tau_F}$ . Here  $\alpha$  has the dimension of momentum,  $\frac{\alpha}{\tau_F}$  has dimensions of  $p^2$  (Force). By varying the value of  $\alpha$  and  $\tau_F$  we can control the strength and the duration of the force. A plot of the normalized force for various values of decay time is given in Fig. 1.

#### 2. Force type 2

For exploratory purposes, we also try a constant force

$$F(\tau) = 1, \tag{31}$$

where  $\mathcal{F}$  takes the maximum value  $\mathcal{F}_0$ . For ease of comparison, we rewrite  $\mathcal{F}_0 = \frac{\alpha}{\tau_F}$ .

#### VI. EFFECT OF FORCE ON FLUID VARIABLES

### A. Force type 1

The application of an external force should change the particle momenta and therefore could have observable effects on pressure. We explore these effects in Figs. 2–5 for various values of  $m/\Lambda_0$ . The Figs. 2–5 show the proper time evolution of temperature (top left panel), transverse



FIG. 2. Evolution of T,  $\bar{P}_L$ ,  $\bar{P}_T$ , and  $\bar{T}^{03}$  for  $\alpha = [200, 100, 50, 0]$ ,  $\tau_m = 1$ , and for  $\bar{\Pi}_0 = 0$ ,  $\bar{\pi}_0 = -1$ .



FIG. 3. Evolution of T,  $\bar{P}_L$ ,  $\bar{P}_T$ , and  $\bar{T}^{03}$  for  $\alpha = [200, 100, 50, 0]$ ,  $\tau_m = 1$ , and for  $\bar{\Pi}_0 = 0$ ,  $\bar{\pi}_0 = 0.99$ .



FIG. 4. Evolution of T,  $\bar{P}_L$ ,  $\bar{P}_T$ , and  $\bar{T}^{03}$  for  $\alpha = [200, 100, 50, 0]$ ,  $\tau_m = 1$  and for  $\bar{\Pi}_0 = 0.85$ ,  $\bar{\pi}_0 = 0$ .



FIG. 5. Evolution of T,  $\bar{P}_L$ ,  $\bar{P}_T$ , and  $\bar{T}^{03}$  for  $\alpha = [200, 100, 50, 0]$ ,  $\tau_m = 1$  and for  $\bar{\Pi}_0 = 0.25$ ,  $\bar{\pi}_0 = 0$ .

pressure (top right panel), longitudinal pressure (bottom right panel) and the scaled off-diagonal component  $T^{03}/P_{eq}$  (bottom left panel) of the energy-momentum tensor for various values of initial anisotropy. Different lines in these figures correspond to various values of  $\alpha$ . Figure 2 shows the time evolution of temperature for negative  $\xi_0$  values whereas Fig. 3 is for a sharply peaked  $p_z$  distribution. Figures 4 and 5 is for isotropic initial distribution but for varying  $m/\Lambda_0$  values. In each figure showing the temperature evolution, the red line corresponds to ideal hydro evolution, and green, orange, and blue correspond to Boltzmann solution with  $\alpha = 200, 100, 50, 0$  respectively. The same color code is used in  $\bar{P}_L, \bar{P}_T$ , and  $\bar{T}^{\tau z} - \tau$  evolution.

It is seen that for the magnitude of the force considered in this study, there is a marginal impact on the evolution of energy density (temperature). A possible explanation is the following: the expansion cools down the system whereas force, in the presence of dissipation, should increase the temperature of the system. The effect is small because we are assuming the force and the correction to the fluid velocity is small.

It is also seen that  $\bar{P}_L$  increases while  $\bar{P}_T$  correspondingly decreases during the time period in which the force acts.  $P_L$  increases as it is driven by an external force, which in turn drives the transverse pressure down due to the constraint  $\mathcal{E} - 2P_T - P_L = \langle m^2 \rangle$ . We see that the long-term behavior of the evolution is such that the system relaxes back to the zero-force curve, and loses memory of the variations due to force.

From Figs. 2 and 3 we see that the effect of longitudinal force is diminished when there is a large initial shear anisotropy. That means that the predominant factor driving the evolution of the system is the shear force. On the other hand in Figs. 4 and 5 when the shear anisotropy is low, we see that the effect of force is pronounced and the effect of bulk anisotropy is subdominant.

### B. Force type 2

In the case of constant force, the force-to-temperature ratio cannot be kept constant throughout the evolution of the system. So, we use smaller  $\alpha = 2, 5, 10 \text{ (MeV)}$  values to make the corrections small. We see again that the variation in temperature is marginal except for late times when the force is comparatively larger than the effective temperature. The variations in the bulk observables are also only noticeable at late times. The qualitative behavior of the bulk observables remains the same as that for the case of the decaying force. We show the results for a constant force for  $\overline{\Pi}_0 = -0.37$ ,  $\overline{\pi}_0 = -1$  in Fig. 6.

#### C. Attractor behavior: Nonconformal

It was reported that for nonconformal systems a universal attractor was not obtained for fluid variables other than for



FIG. 6. Evolution of  $T, \bar{P}_L, \bar{P}_T$  and  $\bar{T}^{03}$  for  $\alpha = [10, 5, 2, 0], \tau_m = 1$  and for  $\bar{\Pi}_0 = -0.37, \bar{\pi}_0 = -1$ .

scaled longitudinal pressure  $\bar{P}_L = P_L/P$  [43]. The authors also computed the bounds for  $\Pi/P$  (scaled bulk pressure) and  $\pi/P$  (scaled sheer pressure) so that the positivity of the distribution function, the transverse and the longitudinal pressure is maintained. Following their findings we use the same set of initial parameters given in Table II. The corresponding values for  $m/\Lambda_0$ ,  $N_0$  and  $\xi_0$  are reported in Table III. With this, we check how the attractor behavior is modified by an external force. In Fig. 7 the scaled longitudinal pressure  $\bar{P}_L$  is plotted for three different force  $\alpha = 0$  (top panel),  $\alpha = 50$  (middle panel), and  $\alpha = 100$  (bottom panel). In each subplot, the different colored lines represent different anisotropies as given in Table III.



For zero force we reproduce the results in the previous study [43]. However, for finite forces, only a late-time attractor is present.

## D. Attractor behavior: Massless limit

Systems with conformal symmetry were shown to exhibit universal early time attractor behavior for a variety of system configurations and flow profiles [8,9,44–47]. Here we check if early-time attractors can be reproduced for systems under external forces. In Fig. 8 the transverse and longitudinal pressure is plotted for varying initial conditions (given in Table I) in the presence of an external force in the massless limit. We observe that even when the system is subjected to an external force it shows an attractor in  $\bar{P}_L$  and  $\bar{P}_T$  much earlier than the massive case (as compared to Fig. 7). We note however that this is subject to the condition that the force has died out much before equilibration is achieved.

The equilibration rate is mostly determined by the exponentially decaying damping factor  $D(\tau, \tau')$  given in Eq. (21). One can see from Eqs. (23)–(25) that the decay rate is determined by the interplay between the damping



FIG. 7. Evolution of  $\bar{P}_L$  for  $\alpha = [0, 50, 100], \tau_m = 1$  and for various initial conditions.

FIG. 8. Scaled transverse and longitudinal pressure plotted for varying initial conditions (given in Table I) in the presence of an external force  $\alpha = 100$  with m = 0.

factor and the  $H_{\mathcal{E}/P_L/P_T}$  functions. It is observed from the  $\tau - T$  graphs that the force has negligible impact on the temperature evolution and, therefore, does not modify the damping function(as  $\tau_R \sim 1/T$ ). However, it significantly modifies  $H_{P_L/P_T}$  functions. Therefore, the relative change in behavior is due to the higher sensitivity of these functions on mass and force. Within the approximation scheme employed, in the massless limit, the system regains conformal symmetry. A combination of these factors gives rise to the observed behavior.

### VII. SUMMARY AND CONCLUSION

We solve the RTA Boltzmann equation incorporating the external force and study the dynamics of the system far away from local equilibrium under Bjorken flow. We also study the attractor behavior of a system undergoing Bjorken expansion in the presence of external longitudinal force. For this exploratory study, we consider a constant force and time-parameterized force which initially peaks and then exponentially decays afterward. We treat this force as a small perturbation so that the overall flow profile remains unchanged. For a constant force the temperature evolution was observed to vary at late times while for the time-varying force considered here, no significant change was observed for temperature evolution. The longitudinal pressure was observed to increase as it is driven by the external longitudinal force which in turn drove the transverse pressure down due to the constraint  $\mathcal{E} - 2P_T$ - $P_L = \langle m^2 \rangle$ . The force was also observed to have a larger effect for smaller-scaled mass values.

We explored the attractor behavior by considering the time evolution of scaled longitudinal and transverse pressure for various initial anisotropies. For conformal systems an early time attractor was observed for various bulk scaled observables [8]. Whereas in the nonconformal case [43] an early time attractor was observed only for scaled longitudinal pressure. The addition of force however modifies this behavior and an attractor is only found at late times. In the conformal limit, we observed that, within our approximation scheme, the attractor for scaled longitudinal pressure reappears even in the presence of an external force. This behavior is due to the nontrivial interplay between the damping function  $D(\tau, \tau')$  and  $H_{P_t/P_t}$ . The results in this work were obtained by assuming that the system obeys approximate Bjorken symmetry. However, the nondiagonal terms  $T^{03}$  become comparable to  $\mathcal{E}$  and  $\mathcal{P}$  for large values of force. Therefore, a proper quantitative estimate of the evolution of the bulk properties cannot be obtained using the techniques used in this paper.

For future work, one can explore the effect of force on non-Bjorken flows like Gubser and even arbitrary flow profiles. One can consider more realistic electromagnetic forces and a self-consistent solution can be obtained by considering a 1 + 1 dimensional expansion. One can also solve for systems under a magnetic field which would necessarily include transverse dynamics and momentum dependant forces, Further, one can explore the effects of chromoelectric and chromomagnetic fields which would require modifications in the collision kernel.

#### ACKNOWLEDGMENTS

A. P. acknowledges the CSIR-HRDG financial support. R. G. and V. R. acknowledge support from the DAE, Govt. of India. R. G. also acknowledges fruitful discussions with Sunil Jaiswal during the early stages of this work.

### APPENDIX A: RTA BOLTZMANN EQUATION WITH FORCE

Boltzmann equation would then read

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$$\mathcal{F}\tau \frac{\partial f}{\partial w} + \frac{\partial f}{\partial \tau} + \frac{\delta u_z p^z}{u_\tau p^\tau} \frac{\partial f}{\partial z} \tag{A1}$$

$$= -\frac{p^{\tau}}{u_{\tau}p^{\tau}}\frac{(f-f_{\rm eq})}{\tau_R} - \frac{\delta u \cdot p}{u_{\tau}p^{\tau}}\frac{(f-f_{\rm eq})}{\tau_R}.$$
 (A2)

If we now assume that  $\delta u/u_{\tau} \ll 1$ , we can ignore the  $\delta u$  terms from the above equation and get

$$\left(\mathcal{F}(\tau)\tau\frac{\partial}{\partial w} + \frac{\partial}{\partial \tau}\right)f = -\frac{(f - f_{eq})}{\tau_R}.$$
 (A3)

For the consistency of the above approximation, we need to keep the strength of the force sufficiently small so that the background flow is still close to Bjorken.

### 1. Change of variables

For computational convenience we write the force  $\mathcal{F}$  as

$$\mathcal{F} = \frac{\alpha}{\tau_F} F(\tau). \tag{A4}$$

We then rewrite the Boltzmann equation as

$$\left(\frac{\alpha}{\tau_F}F(\tau)\tau\frac{\partial}{\partial w} + \frac{\partial}{\partial \tau}\right)f = -\frac{(f - f_{eq})}{\tau_R}.$$
 (A5)

To convert Eq. (A3) to a simpler form, we divide both sides by  $F(\tau)\tau/\tau_F$  getting

$$\left(\alpha \frac{\partial}{\partial w} + \frac{\tau_F}{F(\tau)\tau} \frac{\partial}{\partial \tau}\right) f = -\frac{\tau_F}{\tau_R} \frac{(f - f_{eq})}{F(\tau)\tau}.$$
 (A6)

We define the variable s

$$s(\tau) = \int_0^\tau F(\tau') \frac{\tau'}{\tau_F} d\tau', \qquad (A7)$$

and rewrite the proper time derivative to get Eq. (14),

$$\left(\alpha \frac{\partial}{\partial w} + \frac{\partial}{\partial s}\right) f = -\frac{\tau_F}{\tau_R} \frac{(f - f_{eq})}{F(\tau)\tau}.$$
 (A8)

We now use the standard technique of characteristics for solving partial differential equations and define new variables  $(w, s) \rightarrow (r, s)$ 

$$r = w - \alpha s, \tag{A9}$$

$$s = s, \tag{A10}$$

and obtain the equation

$$\frac{\partial f(r, s, p_T)}{\partial s} = -\frac{\tau_F}{\tau_R} \frac{(f - f_{eq})}{F(\tau(s))\tau(s)}.$$
 (A11)

## **APPENDIX B: INTEGRALS**

In this section we give the explicit form of the H functions appearing in the equation for  $\mathcal{E}$ , P etc given in Eqs. (23)–(26) We define the integrals,

$$\tilde{H}_{\varepsilon}^{F}[s',s,m,\alpha] = \frac{1}{4\pi^{2}} \int du u^{3} e^{-\sqrt{u^{2}+z^{2}}} H_{\varepsilon}^{F}(u,z,s,s',\alpha),$$
(B1)

$$\tilde{H}_{L}^{F}[s', s, m, \alpha] = \frac{1}{4\pi^{2}} \int du u^{3} e^{-\sqrt{u^{2} + z^{2}}} H_{L}^{F}(u, z, s, s', \alpha),$$
(B2)

Using the above definitions we can write

$$H^{F}(u, z, s, s', \alpha) = -\bar{h}\sqrt{(1-\bar{h}^{2})}N^{2}\left\{\frac{1}{2}\left[\sin^{-1}\frac{G-1}{N} - \sin^{-1}\frac{(G+1)}{N}\right] + \frac{1}{2}\left[-\frac{1+G}{N}\sqrt{1-\left(\frac{1+G}{N}\right)^{2}} + \frac{G-1}{N}\sqrt{1-\left(\frac{G-1}{N}\right)^{2}}\right]\right\},$$
(B10)

$$H_{L}(u, z, s, s', \alpha) = -\frac{\bar{h}^{3}}{\sqrt{1 - \bar{h}^{2}}} \left\{ \left( \frac{N^{2}}{2} + (g + G)^{2} \right) \left[ \sin^{-1} \frac{G - 1}{N} - \sin^{-1} \frac{1 + G}{N} \right] + \frac{N^{2}}{2} \left[ \frac{1 + G}{N} \sqrt{1 - \left(\frac{1 + G}{N}\right)^{2}} - \frac{G - 1}{N} \sqrt{1 - \left(\frac{G - 1}{N}\right)^{2}} \right] - 2N(g + G) \left[ \sqrt{1 - \left(\frac{1 + G}{N}\right)^{2}} - \sqrt{1 - \left(\frac{1 - G}{N}\right)^{2}} \right] \right\},$$
(B11)

$$\tilde{H}_{T}^{F}[s', s, m, \alpha] = \frac{1}{4\pi^{2}} \int du u^{3} e^{-\sqrt{u^{2} + z^{2}}} H_{T}^{F}(u, z, s, s', \alpha),$$
(B3)

$$\tilde{H}_{03}^{F}[s', s, m, \alpha] = \frac{1}{4\pi^2} \int du u^2 e^{-\sqrt{u^2 + z^2}}$$
(B4)

where u = p/T and z = m/T.

The functions inside the integrals can be obtained using analytical techniques. Define

$$h(s) \equiv \tau(s). \tag{B5}$$

For notational simplicity, we define the following variables

$$\frac{h(s')}{h(s)} \equiv \bar{h}(s, s') \equiv \bar{h}, \tag{B6}$$

$$\frac{\alpha \times (s - s')}{h(s')} \equiv g(s, s') \equiv g,$$
(B7)

and

$$N^{2} \equiv \frac{1}{(1-\bar{h}^{2})} \left( \frac{u^{2} + \bar{h}^{2}g^{2} + z^{2}}{u^{2}} + \frac{g^{2}\bar{h}^{4}}{u^{2}(1-\bar{h}^{2})} \right), \quad (B8)$$

$$G \equiv \frac{g\bar{h}^2}{u(1-\bar{h}^2)}.$$
(B9)

(B13)

$$H_{T}(u, z, s, s', \alpha) = -\frac{\bar{h}}{\sqrt{(1-\bar{h}^{2})}} \left\{ \left(1-G^{2}-\frac{N^{2}}{2}\right) \left[\sin^{-1}\frac{G-1}{N}-\sin^{-1}\frac{1+G}{N}\right] -\frac{N^{2}}{2} \left[\frac{1+G}{N}\sqrt{1-\left(\frac{1+G}{N}\right)^{2}}-\frac{G-1}{N}\sqrt{1-\left(\frac{G-1}{N}\right)^{2}}\right] +2NG\left[\sqrt{1-\left(\frac{1+G}{N}\right)^{2}}-\sqrt{1-\left(\frac{1-G}{N}\right)^{2}}\right]\right\}.$$
(B12)

$$H_{03}^F(u, z, s, s', \alpha) = g\bar{h}$$

#### APPENDIX C: ITERATIVE SOLUTION ALGORITHM

Consider the integral equation

$$y(t) = K(t, t_0, y)v(t, t_0)$$
 (C1)

$$+ \int_{t_0}^t dt' K(t, t', y) \frac{H(t, t', y(t'))}{\tau_R(y(t'))} f(y(t'))$$
(C2)

where,

$$K(t, t', y) = \exp\left\{\int_{t'}^{t} g(y(t''))dt''\right\}$$
(C3)

and we are given the initial condition

$$y(t_0) = y_0. \tag{C4}$$

This implies

$$y(t_0) = v(t_0, t_0)$$
 (C5)

as

$$K(t, t, y) = 1 \tag{C6}$$

The usual method for solving this equation is to consider an arbitrary functional form for the solution y(t) and substitute it in the right-hand side (rhs) and get a new solution. This process is continued until the iteration converges to some desired level of accuracy. The drawback of this method is that the speed of convergence depends on the initial guess y(t). Here we take an alternate approach. If the function y(t) is continuous then we approximate at each step  $t_n = t_{n-1} + \Delta t_n$ ,

$$y(t_{n-1} + \Delta t_n) = y(t_{n-1}) + \mathcal{O}(\Delta t_n).$$
(C7)

Therefore with the initial condition  $y(t_0) = v(t_0, t_0)$ , we start with

$$y(t_0 + \Delta t) \sim y(t_0) \tag{C8}$$

and continue this procedure in order for each *n* successively. We show elsewhere that after one iteration this produces an approximation for y(t) accurate up to  $\mathcal{O}(\Delta t^2)$ . This process gets rid of the need for a good initial guess. It not only converges faster but also allows us to estimate order or error for our computation.

### **APPENDIX D: INITIAL CONDITIONS**

For the conformal case, we fix the anisotropy and normalization the same as the nonconformal case but vary the value of  $\Lambda_0$  to match the initial energy density. The initial conditions for the distribution function were chosen to match [43] for comparison and are reproduced in the Table I.

TABLE I. Various values of  $\Lambda_0, N_0$  and  $\xi_0$  corresponding to different initial values of  $(\pi/P)_0$  for m = 0.

No.	0	1	2	3	4	5	6	
$egin{array}{c} \Lambda_0 \ \xi_0 \end{array}$	321.74 -0.832	314 -0.908	275 -0.949	1089 1208.05	198 0.987	500 0	500 0	

TABLE II. Various initial values of $(\Pi/P)_0, (\pi/P)_0$ and their	number code.	
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		. ,					
No.	0	1	2	3	4	5	6
$\frac{(\Pi/P)_0}{(\pi/P)_0}$	0	-0.25	-0.37	0	0 -1.8	0.25	-0.85

TABLE III. Various values of  $m/\Lambda_0$ ,  $N_0$  and  $\xi_0$  corresponding to different initial values of  $(\Pi/P)_0$ ,  $(\pi/P)_0$  given in Table II.

No.	0	1	2	3	4	5	6
$\frac{m/\Lambda_0}{N_0}$	0.016 0.655	$4.808 \\ 4 \times 10^{-5}$	10.89 $2.5 \times 10^{-8}$	0.294 0.078	1.818 0.0632	2.023 $1.06 \times 10^{-3}$	20 1.48 × 10 <sup>-13</sup>
$\xi_0$	-0.832	-0.908	-0.949	1208.05	-0.987	0	0

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