

Impact of scale-height derivative on general relativistic slim disks in tidal disruption events

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We construct a numerical model of steady-state, general relativistic (GR) super-Eddington accretion flows in an optically thick, advection-dominated regime, motivated by tidal disruption events wherein super-Eddington accretion assumes a pivotal role. Our model takes into account the loss of angular momentum due to radiation and the scale-height derivative in the basic equations of the GR slim disk. For comparison purposes, we also provide a new analytical solution for a radiation-pressure-dominant GR slim disk, which neglects the angular momentum loss due to radiation and the scale-height derivative. We find that the radiation pressure enhances by incorporating the scale-height derivative into the basic equations. As a result, the surface density near the disk's inner edge decreases, whereas the disk temperature and scale-height increase, brightening the disk spectrum in the soft x-ray wave band. Notably, an extremely high-mass accretion rate significantly enhances the effect of the scale-height derivative, affecting the entire disk. In contrast, the inclusion of the radiation-driven angular momentum loss only slightly influences the disk surface density and temperature compared with the case of the scale-height derivative inclusion. The x-ray luminosity increases significantly due to scale-height derivative for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$, where \dot{M}_{Edd} is the Eddington accretion rate with 0.1 energy conversion efficiency. In addition, the increment is higher for the nonspinning black hole than the spinning black hole case, resulting in a one order of magnitude difference for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 100$. We conclude that incorporating the scale-height derivative into a GR slim-disk model is crucial as it impacts the disk structure and its resultant spectrum, particularly on a soft x-ray wave band.

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I. INTRODUCTION

A tidal disruption event (TDE) occurs when a star is disrupted by a black hole's tidal gravity that exceeds the star's self-gravity [1,2]. The radius below which tidal disruption happens is the tidal radius given by $r_t \simeq (M/M_\star)^{1/3}R_\star$ [3], where M is the black hole mass, and M_\star and R_\star are the stellar mass and radius respectively. The disrupted debris returns to the pericenter following a Keplerian orbit with a mass fallback rate $\dot{M}_{\text{fb}} \propto t^{-5/3}$, where t is the time. However, the time variation of \dot{M}_{fb} at early times and the magnitude of \dot{M}_{fb} at the peak depends on the stellar density [4], stellar rotation [5], and stellar orbital eccentricity [6]. If the infalling debris loses its angular momentum on a timescale shorter than the orbital time of the fallback debris, the accretion rate can be equivalent to the mass fallback rate. However, the fallback debris interacts between head and tailed parts due to the general relativistic (GR) apsidal motion, and the resultant energy dissipation by

stream-stream collisions results in the formation of an accretion disk [7–9]. The resultant disk can be circular or elliptical depending on the energy dissipation efficiency [10]. The disk viscosity dominates the subsequent evolution of the formed disk. As the viscous timescale is usually much longer than the orbital time, the mass accretion rate is not likely to equal the mass fallback rate [11–13].

As the ratio of the tidal radius to the black hole horizon is inversely proportional to $M^{2/3}$, an increase in the mass of the black hole results in the tidal disruption radius approaching the event horizon. This highlights the importance of considering GR dynamics for TDEs with higher-mass black holes. The innermost stable circular orbit, r_{ISCO} , decreases for a prograde black hole spin [14] so that the impact of the black hole spin on the accretion dynamics, disk spectra, and light curves can be more significant than in the nonspinning black hole case. This motivated Novikov and Thorne [15] to construct a model of a GR steady-state geometrically thin disk with alpha viscosity. Recently, Balbus and Mummery [16] have constructed a GR model of a time-dependent, optically thick, geometrically thin disk in the context of TDEs. Mageshwaran and Bhattacharyya [17] have developed a GR model of

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a time-dependent, optically thick, geometrically thin disk with a mass fallback rate at the constant outer radius in the case of both full and partial stellar disruptions. These models are gas-pressure dominant, so that should be consistent with the standard disk model when the accretion rate is mildly lower than the Eddington rate in the non-relativistic, steady-state limit [18,19]. The radiation pressure becomes significantly remarkable as the accretion rate exceeds the Eddington rate. However, a radiation-pressure dominant, optically thick disk, where the advective energy transport is not properly treated, is known to result in a Lightman-Eardley thermal instability [20]. Therefore, Abramowicz *et al.* [21] has introduced the advection cooling in the energy conservation equation of the optically thick disk at super-Eddington accretion rate and has constructed the optically thick, advection-dominant disk in the nonrelativistic limit, so-called slim-disk model.

A GR steady-state solution of optically thick, advection-dominated accretion flows with alpha viscosity has been formulated in the Kerr spacetime by Lasota [22], Abramowicz *et al.* [23], Gammie and Popham [24], Beloborodov [25], Sadowski [26], and Sadowski *et al.* [27] have revisited them and, especially, Sadowski [26] found a way to solve them efficiently and numerically (hereafter SA09). The SA09 model has been used by Wen *et al.* [28–30] to fit the x-ray spectra of TDEs ASASSN-14li and ASASSN-15oi at different epochs to estimate the black hole mass and spin by using the mass accretion rates as a parameter. In these disk models, the angular momentum loss due to the radiation in the angular-momentum conservation equation and the scale-height derivative in the advection energy flux has been neglected for their simple treatment in the basic equations. However, these two quantities are likely to significantly impact the disk structure. The radiation-driven angular momentum loss augments the radial inflow velocity, thereby exerting influence on both surface density and temperature. Wen *et al.* [29] examined the effect of the angular momentum loss due to the radiation and found that it was somewhat effective for a low-mass accretion rate and also decreases slightly the disk luminosity by reducing viscous stress. However, it is scarcely delineated whether this trend persists at sufficiently elevated mass accretion rates. On the other hand, the scale-height derivative is likely to affect the disk temperature because of changing the disk-energy allocation among viscous heating, radiative cooling, and advective cooling. However, little has been known about how the scale-height derivative has an influence on the disk structure and emission. In any case, either term can produce a difference in the disk emission. Even if this difference is small, it can produce a significant luminosity difference in x-rays emitted from the inner edge radius due to the exponential decay of the thermal x-ray spectrum, as the Wein law suggests.

In this paper, we develop a new stationary GR slim-disk model by including the two terms (i.e., the angular

momentum loss due to the radiation and the scale-height derivative) in the basic equations. Our model adopts the alpha viscosity prescription and the opacity comprising both Thomson electron scattering and Kramer absorption opacity. Based on the model, we especially examine the effect of the newly added scale-height derivative on the disk structure and emission. In Sec. II, we describe the detailed formulation of our GR slim-disk model. For comparison purposes, we present a new analytical solution for GR slim-disk basic equations without the two terms in Sec. II A and provide full numerical solutions for the basic equations in Sec. II B. The impact of the two terms on the disk structure and spectrum is first described in Sec. III A for two significantly different accretion rate cases, and then how the disk structure and emission depend on the mass accretion rate with and without including the term of the scale-height derivative in Sec. III B. Section III C describes the importance of advective cooling in the entire disk region. The differences in black hole spin are also explained in each subsection of Sec. III. We discuss our results in Sec. IV and summarize our conclusions in Sec. V.

II. GENERAL RELATIVISTIC STATIONARY SLIM-DISK MODEL

In this section, we present the relativistic slim disk equations derived in the Kerr space-time metric. We transform the Kerr metric in the Boyer-Lindquist coordinate to cylindrical coordinate $\{t, r, \phi, z\}$ and the metric on the equatorial plane is limited to first order in z/r . We follow the authors [23,31] to get the four velocities (u^i) in the equatorial plane. The Kerr metric in the cylindrical coordinate and the four velocities are given in Appendix A. Following Abramowicz *et al.* [23], the stress-energy tensor is given by

$$T^{\alpha\beta} = \rho u^\alpha u^\beta + p g^{\alpha\beta} + S^{\alpha\beta} + \tau^{\alpha\beta}, \quad (1)$$

where ρ is the density, p is the pressure, $S^{\alpha\beta}$ is the viscous stress tensor, $\tau^{\alpha\beta} = q^\alpha u^\beta + u^\alpha q^\beta$ with radiative energy flux q^α . The mass conservation is given by $(\rho u^i)_{;i} = 0$ and the radial, and angular momentum conservations are given by $T^i{}_{;r} = 0$ and $(T^i{}_{\xi^k})_{;i} = 0$ respectively, where $\xi^k \equiv \delta_\phi^k$ is the azimuthal Killing vector and δ_ϕ^k is the Kronecker delta.

We solve the conservation equations for a stationary $\partial_t = 0$ and axisymmetric $\partial_\phi = 0$ relativistic accretion disk with angular momentum loss due to the radiation. We take the vertical flow to zero in our model and obtain the vertically integrated conservation equations. The derivation of the conservation equations are given in Appendix A, and here, we write them in terms of the dimensionless variables.

In the steady state, the mass-conservation equation results in

$$\dot{M} = -2\pi r_g c \Sigma \Delta_k^{1/2} \frac{V}{\sqrt{1-V^2}}, \quad (2)$$

where Σ is the disk midplane surface density, $r_g = GM/c^2$ is the black hole radius, V is the radial velocity, and $\Delta_k = x^2 - 2x + j^2$ with $x = r/r_g$ and dimensionless black hole spin $j = a/r_g$ (see also Appendix A). The radial momentum conservation equation is given by

$$\frac{V}{(1-V^2)^2} \frac{dV}{dx} + \frac{c_s^2}{c^2} \frac{1}{P} \frac{dP}{dx} = \mathcal{A}_1, \quad (3)$$

where $c_s = \sqrt{p/\rho}$ is the sound speed with the disk pressure p , $P = \int pdz \approx 2pH$ is the vertically integrated pressure with the disk scale-height H , $A_k = x^4 + x^2j^2 + 2xj^2$, and

$$\begin{aligned} \mathcal{A}_1 &= \frac{r_g}{c^2} \frac{\mathcal{A}}{r(1-V^2)} \\ &= \frac{\gamma_L^2 A_k}{x^4 \Delta_k} (x^3 - j^2) (\omega - \omega_K^+) (\omega - \omega_K^-), \end{aligned} \quad (4)$$

$$\omega = \frac{2jx}{A_k} + \frac{x^3 \Delta_k^{1/2}}{A_k^{3/2}} \frac{\ell}{\gamma_L}, \quad (5)$$

$$\omega_K^\pm = \pm \frac{1}{x^{3/2} \pm j}, \quad (6)$$

$$\gamma_L^2 = \frac{1}{1-V^2} + \frac{x^2 \ell^2}{A_k}, \quad (7)$$

where \mathcal{A} is given by Eq. (A28), ω is the angular velocity with respect to the stationary observer, and ω_K^\pm is the angular velocity of a circular orbit in the Kerr metric. The positive and negative signs indicate the prograde and retrograde directions, respectively.

Here, we define the nondimensional parameter $\ell = \mathcal{L}/(r_g c)$ as the disk angular momentum per unit mass (\mathcal{L}) normalized by $r_g c$. The angular momentum conservation equation of the disk is then given by

$$\frac{d(x \bar{S}_\phi^r)}{dx} = \frac{1}{2\pi} \dot{M} c \frac{d\ell}{dx} - \frac{r_g^2}{c} x \ell Q_{\text{rad}}, \quad (8)$$

where $\bar{S}_\phi^r = -c\nu\Sigma(\Delta_k^{1/2} A_k^{3/2} \gamma_L^3/x^5)(d\omega/dx)$ with the turbulent viscosity ν . We assume that radiative energy flow is along the vertical direction and Q_{rad} represents the radiative energy flux. The scale height of the disk using the first order approximation of z/r and the vertical-hydrostatic equilibrium is given by [32]

$$H = \frac{1}{\sqrt{\zeta(x)}} \frac{c_s}{c} r_g, \quad (9)$$

where $\zeta(x) \equiv [\ell^2 - j^2(\epsilon^2 - 1)]/(2x^4)$ and $\epsilon = u_t$.

The total pressure in the disk is given by $p = p_{\text{rad}} + p_{\text{gas}}$, where $p_{\text{rad}} = a_{\text{rad}} T^4/3$ is the radiation pressure with T as

the midplane temperature of the disk and a_{rad} is the radiation constant, and $p_{\text{gas}} = k_B \rho T / (\mu_m m_p)$ is the gas pressure, where $\Sigma = 2\rho H$ is the density, m_p is the mass of a proton, k_B is the Boltzmann constant, and μ_m is the mean molecular weight taken to be the ionized-solar mean molecular weight of 0.65. The viscous stress in the comoving rotating frame is obtained using the orthonormal tetrad basis and is given by $t_{r\phi} = -x^2 \bar{S}_\phi^r / (\gamma_L A_k^{1/2} \Delta_k^{1/2} r_g)$ [22,33]. Assuming an alpha viscosity, $t_{r\phi} = -\alpha P$ such that the viscosity is given by

$$\nu = -2\alpha \frac{r_g H p}{c} \frac{x^3}{\Sigma A_k \gamma_L^2} \left(\frac{d\omega}{dx} \right)^{-1}. \quad (10)$$

The energy conservation is given by $Q_{\text{vis}} = Q_{\text{adv}} + Q_{\text{rad}}$, where Q_{vis} is the viscous heating flux, Q_{adv} is the advection cooling flux, and Q_{rad} is the radiative cooling flux. They are given by [28,31]

$$Q_{\text{vis}} = \nu \Sigma \left(\frac{c}{r_g} \right)^2 \frac{\gamma_L^4 A_k^2}{x^6} \left(\frac{d\omega}{dx} \right)^2, \quad (11)$$

$$Q_{\text{rad}} = \frac{\theta \sigma T^4}{3 \kappa \Sigma}, \quad (12)$$

$$Q_{\text{adv}} = \frac{1}{2\pi} \frac{\dot{M} c_s^2}{r_g^2 x^2} \xi(r), \quad (13)$$

respectively, where $\theta = 64$ in this paper which is same as in Wen *et al.* [28,29] whereas $\theta = 32$ in SA09, σ is the Stefan-Boltzmann constant, $\kappa = \kappa_{\text{es}} + \kappa_{\text{a}}$ with $\kappa_{\text{es}} = 0.34 \text{ cm}^{-2} \text{ g}^{-1}$ and $\kappa_{\text{a}} = 3.2 \times 10^{22} T^{-7/2} \Sigma / H \text{ cm}^{-2} \text{ g}^{-1}$, and $\beta_{\text{gas}} = p_{\text{gas}}/p$ is the ratio of gas to total pressure. In addition, $\xi(r)$ is defined as [23]

$$\begin{aligned} \xi(r) &\equiv -\frac{T}{c_s^2} \frac{\partial s}{\partial \ln(r)} \\ &= -\frac{4 - 3\beta_{\text{gas}}}{\Gamma_3 - 1} \frac{x}{T} \frac{dT}{dx} + (4 - 3\beta_{\text{gas}}) \left\{ \frac{x}{\Sigma} \frac{d\Sigma}{dx} - \frac{x}{H} \frac{dH}{dx} \right\}, \end{aligned} \quad (14)$$

where s is the specific entropy and Γ_3 is the third adiabatic exponent,

$$\Gamma_3 = 1 + \frac{(4 - 3\beta_{\text{gas}})(\gamma_{\text{gas}} - 1)}{\beta_{\text{gas}} + 12(1 - \beta_{\text{gas}})(\gamma_{\text{gas}} - 1)}$$

with the gaseous specific heat ratio, γ_{gas} [34].

Note that the second term on the right-hand side of Eq. (8) and the term including dH/dx of Eq. (14) show the angular momentum loss due to the radiation and the scale-height derivative, respectively. Both terms have been neglected in the past GR slim-disk models

(e.g., Sadowski [26]). In the next subsection, for comparison purposes, we provide an analytic solution for the GR basic equations (2), (3), (8), (9), and (11)–(13), where we adopt radiation pressure only and neglect the angular momentum loss due to radiation and scale-height derivative.

A. Analytical solution for a radiation pressure dominant disk without the angular momentum loss due to radiation and scale-height derivative

Here we derive an analytical solution for the GR disk with radiation pressure only and no angular momentum loss due to the radiation. The angular momentum of the disk is taken to be the circular angular momentum, $\mathcal{L}_K = \ell_K r_g c$, where ℓ_K is given by

$$\ell_K = \pm \frac{x^2 \mp 2j\sqrt{x} + j^2}{x^{3/4}(x^{3/2} - 3\sqrt{x} \pm 2j)^{1/2}} \quad (15)$$

and the positive sign is here for the prograde orbit, and the negative sign is for the retrograde orbit [14]. For a disk with no angular momentum loss due to the radiation, Eq. (8) reduces to be $x\bar{S}'_\phi = \frac{Mc}{2\pi}[\ell_K - \ell_{K,\text{in}}]$, where $\ell_{K,\text{in}}$ is the angular momentum at the inner radius and the viscous stress is assumed to be zero there. Moreover, by setting $\ell = \ell_K$ at Eq. (7) and $\omega = \omega_K^+$, Eq. (11) reduces to

$$Q_{\text{vis}} = \frac{3}{4\pi} \frac{GM\dot{M}}{r^3} f(x, j), \quad (16)$$

where $f(x, j)$ is defined as a boundary correction factor given by

$$f(x, j) = \left[1 - \frac{\ell_{K,\text{in}}}{\ell_K}\right] \left[1 - \frac{2j}{x^{3/2}} + \frac{j^2}{x^2}\right] \times \left[1 - \frac{3}{x} + \frac{2j}{x^{3/2}}\right]^{-1} \left[1 + \frac{j}{x^{3/2}}\right]^{-1}. \quad (17)$$

Furthermore, this equation reduces to $Q_{\text{vis}} = (3/4\pi)(GM\dot{M}/r^3)[1 - \ell_{K,\text{in}}/\ell_K]$ at the nonrelativistic limit, where $\ell_{K,\text{in}}/\ell_K = \sqrt{x_{\text{in}}/x} = \sqrt{r_{\text{in}}/r}$.

We approximate the advective energy in Eq. (13) as $Q_{\text{adv}} = (1/2\pi)(\dot{M}c_s^2/r^2)$, where $\xi(r) \simeq 1$ is assumed [18]. Because $\xi(r)$ is a kind of logarithmic entropy gradient and thus a slowly varying quantity, the logarithmic derivative terms, and the corresponding coefficients are of the order of unity except for near the horizon. Therefore, $\xi(r) \simeq 1$ is a crude but reasonable assumption for deriving the analytical solution. For a radiation-pressure dominant disk with the Thomson opacity ($\kappa = \kappa_{\text{es}}$) and $p = p_{\text{rad}} = a_{\text{rad}}T^4/3$, the hydrostatic equilibrium $c_s^2 = p_{\text{rad}}/\rho = 2p_{\text{rad}}H/\Sigma$ results in $c_s = (8/\theta)(\kappa_{\text{es}}r_g/c^2)(1/\sqrt{\zeta(x)})Q_{\text{rad}}$. The energy conservation equation results in

$$Q_{\text{rad}} = Q_{\text{vis}} \left[\frac{1}{2} + \sqrt{\frac{1}{4} + \frac{384}{\theta^2} \left(\frac{\dot{M}}{\eta\dot{M}_{\text{Edd}}} \right)^2 \frac{f(x, j)}{x^5 \zeta(x)}} \right]^{-1}, \quad (18)$$

where $\dot{M}_{\text{Edd}} = (1/\eta)4\pi GM/(\kappa_{\text{es}}c) \simeq 2.2 \times 10^{-2} M_\odot/\text{yr} \times (\eta/0.1)^{-1} (M/10^6 M_\odot)$ is the Eddington accretion rate with the radiative efficiency, η , and its fiducial value is 0.1. The surface density and the midplane temperature are then given by

$$\Sigma = \frac{1}{128\pi\alpha} \frac{1}{r_g^3 \kappa_{\text{es}}^2} \frac{\dot{M}\theta^2}{Q_{\text{rad}}^2} \frac{x\zeta(x)[\ell_K - \ell_{K,\text{in}}]}{\Delta_k^{1/2} A_k^{1/2} \gamma_L}, \quad (19)$$

$$T = \left(\frac{3\kappa_{\text{es}}\Sigma}{\theta} Q_{\text{rad}} \right)^{1/4}, \quad (20)$$

respectively.

B. Full solutions for the GR disk basic equations

In this section, we derive the complete solution for the GR disk basic equations, including angular momentum loss due to the radiation and the scale-height derivative. After some manipulations, we can rewrite the momentum and energy conservation equations in terms of three differential equations of V , ℓ , and T as follows:

$$\frac{dV}{dx} = V(1 - V^2) \frac{\mathcal{N}}{\mathcal{D}}, \quad (21)$$

$$\frac{1}{T} \frac{dT}{dx} = \frac{1 + \beta_{\text{gas}}}{4 - 3\beta_{\text{gas}}} \left[\frac{a_4 e_3 - a_3 e_4}{a_3 e_2 + a_2 e_3} + \frac{a_3 e_1 - a_1 e_3}{a_3 e_2 + a_2 e_3} \frac{\mathcal{N}}{\mathcal{D}} \right], \quad (22)$$

$$\frac{d\ell}{dx} = \frac{a_4 e_2 + a_2 e_4}{a_3 e_2 + a_2 e_3} - \frac{a_2 e_1 + a_1 e_2}{a_3 e_2 + a_2 e_3} \frac{\mathcal{N}}{\mathcal{D}}, \quad (23)$$

where

$$\frac{\mathcal{N}}{\mathcal{D}} = \frac{r_2(a_3 e_4 - a_4 e_3) + r_3(a_4 e_2 + a_2 e_4) + r_4(a_3 e_2 + a_2 e_3)}{r_1(a_3 e_2 + a_2 e_3) + r_2(a_3 e_1 - a_1 e_3) + r_3(a_2 e_1 + a_1 e_2)} \quad (24)$$

and each component of r_i , a_i and e_i ($i = 1 \sim 4$) are a function of M , x , j , V , ℓ , and T , and their detailed functional forms are described in Appendix B.

For the GR disk with no angular momentum loss due to the radiation, Abramowicz *et al.* [23] have demonstrated that the flow crosses the horizon with the $V^2 > c_s^2$, whereas the flow is subsonic at a point far from the black hole. At some point, therefore, the flow must pass through a sonic point where $V^2 \approx c_s^2$, meaning $\mathcal{N} = 0$ and $\mathcal{D} = 0$. This is the condition that a solution for the basic equations of the GR slim disk should satisfy. The SA09 model has handled ℓ_{in} as a free parameter and found solutions to satisfy the sonic point condition by varying ℓ_{in} . However, we cannot

solve the angular momentum equation analytically because the term for the angular momentum loss due to radiation is included there.

We integrate Eqs. (21)–(23) inwardly starting at the radius r_{out} which represents the size of the accretion disk. We estimate the boundary values assuming $\omega = \omega_{\text{K}}^+$, advection energy flux $Q_{\text{adv}} = 0$, and radiation driven angular momentum loss term, $x\ell Q_{\text{rad}} = 0$ (SA09, [29,30]) that results in $x\bar{S}_{\phi}^r = (1/2\pi)\dot{M}c(\ell - \ell_{\text{in}})$. We find a numerical solution with a sonic point by handling ℓ_{in} as a free parameter. Specifically, we can have the following relations by using $x\bar{S}_{\phi}^i = (1/2\pi)\dot{M}c(\ell - \ell_{\text{in}})$, $Q_{\text{adv}} = 0$, $c_s = \sqrt{p/\rho}$, and $\omega = \omega_{\text{K}}^+$ at the disk outer region:

$$\frac{\theta}{3\kappa_{\text{es}} + \kappa_a} \frac{\sigma T^4}{\Sigma} = \frac{1}{2\pi} \dot{M} \left(\frac{c}{r_g}\right)^2 \frac{\gamma_{\text{L}} A_k^{1/2}}{x^2 \Delta_k^{1/2}} \left(-\frac{\partial \omega_{\text{K}}}{\partial x}\right) (\ell - \ell_{\text{in}}), \quad (25)$$

$$2 \frac{jx}{A_k} + \frac{x^3 \Delta_k^{1/2}}{A_k^{3/2}} \frac{\ell}{\gamma_{\text{L}}} = \omega_{\text{K}}^+, \quad (26)$$

$$\frac{1}{2\pi\alpha} \frac{\dot{M}c}{r_g} \frac{x(\ell - \ell_{\text{in}})}{\Delta_k^{1/2} A_k^{1/2} \gamma_{\text{L}}} = \frac{k_{\text{B}}T}{\mu_{\text{m}}m_{\text{p}}}\Sigma + \frac{2}{3\sqrt{2\pi}} a_{\text{rad}} T^4 \left(\frac{1}{\alpha} \frac{\dot{M}r_g}{\Sigma c}\right)^{1/2} \times \left[\frac{x(\ell - \ell_{\text{in}})}{\zeta(x)\gamma_{\text{L}}\Delta_k^{1/2}A_k^{1/2}}\right]^{1/2}. \quad (27)$$

We solve these equations for given M , j , ℓ_{in} , and \dot{M} to obtain V , ℓ , and T at the considered outer radius. These quantities work as the boundary condition for Eqs. (21)–(23). By varying ℓ_{in} , we find such boundary values as the solution satisfies the sonic point condition. With the given boundary values, we solve Eqs. (21)–(23), which includes angular momentum loss due to the radiation and the scale-height derivative for the disk region smaller than the outer radius, using the implicit Runge-Kutta method iteratively over ℓ_{in} until the sonic-point condition is satisfied and we have a true solution.

C. Disk spectrum calculation

Assuming the black body radiation from the entire disk, the effective temperature is given by $T_{\text{eff}} = (Q_{\text{rad}}/2\sigma)^{1/4}$ through the Stefan-Boltzmann law. The observed spectral flux density is given by

$$F_{\nu, \text{obs}} = \int_{\Omega} I_{\nu}(T_{\text{eff}}, \nu_{\text{obs}}) d\Omega, \quad (28)$$

where I_{ν} is the specific intensity, $d\Omega$ is the differential solid angle subtended by the emission point to the observer and is given by $d\Omega = dS \cos \theta_{\text{los}} / D_{\text{L}}^2$, where S is the area of emission, D_{L} is the luminosity distance of the source to the observer and θ_{los} is the angle between observer line-of-sight

and disk normal vector. In a relativistic formulation, the area of disk in $\{r, \phi\}$ plane is given by $dS = \sqrt{g_{\text{rr}}g_{\phi\phi}} dr d\phi$, and is $dS = r_g^2 \sqrt{A_k/\Delta_k} dx d\phi$, where $A_k = x^4 + x^2 j^2 + 2x j^2$ and $\Delta_k = x^2 - 2x + j^2$. The gravitational redshift effect is included by using the Lorentz invariant I_{ν}/ν^3 [35] in such a way as $I_{\nu}(\nu_{\text{obs}}) = g^3 I_{\nu}(\nu_{\text{em}})$, where ν_{em} is the emitted frequency and g is the redshift factor. The observed flux density is then given by [16]

$$F_{\nu, \text{obs}} = \frac{\cos \theta_{\text{los}}}{D_{\text{L}}^2} \int_{\Omega} g^3 I_{\nu} \left(T_{\text{eff}}, \frac{\nu_{\text{obs}}}{g}\right) dS, \quad (29)$$

where the radial-integral range is taken to be from the inner-disk radius to the circularization radius $r_{\text{c}} = 2r_{\text{t}}$. The spectral luminosity is then calculated to be

$$\begin{aligned} \nu L_{\nu} &= 4\pi D_{\text{L}}^2 \nu_{\text{obs}} F_{\nu, \text{obs}}, \\ &= 8\pi^2 \cos \theta_{\text{los}} r_g^2 \nu_{\text{obs}} \int_{x_{\text{in}}}^{x_{\text{c}}} g^3 I_{\nu} \left(T_{\text{eff}}, \frac{\nu_{\text{obs}}}{g}\right) \sqrt{\frac{A_k}{\Delta_k}} dx, \end{aligned} \quad (30)$$

where $x_{\text{in}} \equiv r_{\text{in}}/r_g$ and $x_{\text{c}} \equiv r_{\text{c}}/r_g$, and we adopt for the specific evaluation that $\theta_{\text{los}} = 0^\circ$ and $g = 1/u^t$, where u^t is the time component of the four-velocity (see Appendix A for details).

D. Model setup and parameters

Our model has free parameters that are the black hole mass M and spin j , the stellar mass M_{\star} and radius R_{\star} , the angular momentum at the inner radius ℓ_{in} , and the mass accretion rate \dot{M} . We adopt the black hole mass as $M = 10^7 M_{\odot}$ with assuming the disruption of a solar-type star, targeting a TDE candidate ASAS-SN 14li [36,37]. The inner- and outer-disk radii that we adopt are given by the ISCO radius (cf. [14]) and $r_{\text{out}} = 2500 r_g$, respectively. For the comparison purpose, we introduce black hole spin parameters and adopt $j = 0$ and 0.998 for them. Regarding \dot{M} , we describe it in the following sections.

Moreover, the four scenarios are examined in our GR solutions. As depicted in Table I, a model that incorporates both the effect of radiation-induced angular momentum loss and the derivative of the scale height (Model I), a model that accounts for radiation-induced angular momentum loss without incorporating the derivative of the scale height (Model II), a model that accounts for the derivative of the scale height without considering radiation-induced angular momentum loss (Model III), and a model that neglects both of these physical effects (Model IV). In the next section, we provide the solutions with the above parameters for the four models represented in Table I.

TABLE I. The four models to consider for our GR solutions. Model I incorporates both radiation-driven angular momentum loss and the derivative of the scale height. Model II incorporates radiation-driven angular momentum loss but does not consider the derivative of the scale height. Model III incorporates the derivative of the scale height but does not consider radiation-driven angular momentum loss. Model IV does not incorporate either physics. For these models, we take $\theta = 64$ in Eq. (12).

Model	Angular momentum loss due to radiation	Scale-height derivative
I	✓	✓
II	✓	✗
III	✗	✓
IV	✗	✗

III. RESULTS

In this section, we first delineate the distinctions between Models I through VI for two extreme \dot{M} scenarios. Subsequently, we elucidate the dependence of the mass accretion rate on the disk structure and emission to scrutinize the influence of the scale-height derivative more comprehensively. Lastly, we expound upon the significance of advective cooling throughout the entire disk region.

We also compare our Model II and Model IV with the earlier works, i.e., SA09 model and models of Wen *et al.* [28,29] for the confirmation purpose of our model validity (see Appendix C for the details).

A. Two distinct mass accretion rate cases

To clarify the differences between the four models, we choose the following two cases: $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ and $600\dot{M}_{\text{Edd}}$. Note that $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ is a best-fit solution at one epoch for TDE ASAS-SN 14li x-ray spectrum by Wen *et al.* [28] and that $\dot{M} = 600\dot{M}_{\text{Edd}}$ is adopted as an extreme end of the mass accretion rate [28]. Such a high-mass accretion rate is considered from the theoretical viewpoint to know how the extreme mass-accretion rate impacts the radiation-driven angular momentum loss and scale-height derivative terms on the disk accretion flow.

Figure 1 depicts the radial dependence of the surface density, scale-height-to-radius ratio, effective temperature, and disk spectrum with $j = 0.998$ and $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ for the four models represented in Table I. From the figure, we find that the effective temperature and H/r increase, whereas the surface density decreases with the inclusion of the scale-height derivative. The scale-height derivative influence strongly on the higher-energy side of the resultant

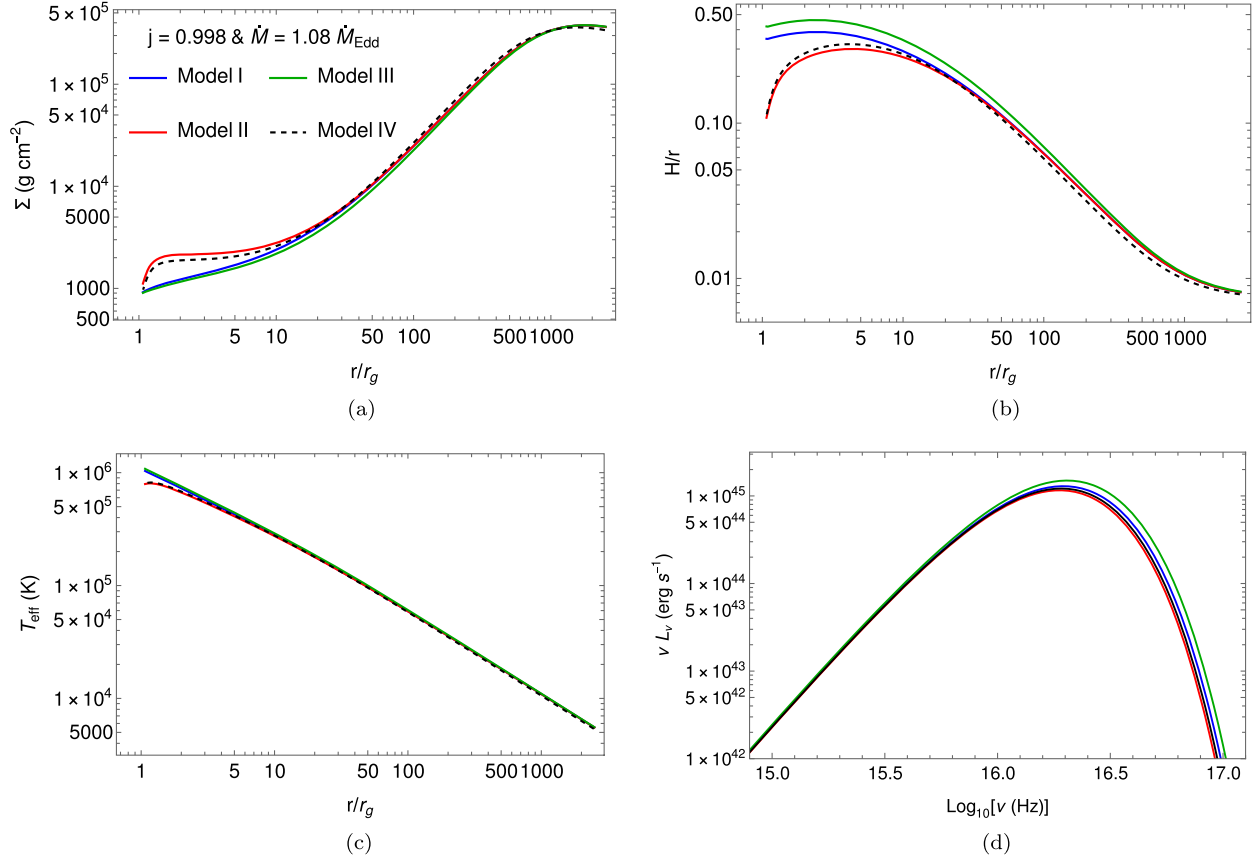


FIG. 1. The radial dependence of the surface density, scale-height-to-radius ratio, effective temperature, and corresponding disk spectrum with $j = 0.998$ and $\dot{M} = 1.08\dot{M}_{\text{Edd}}$. The blue, red, green and black lines correspond to Models I, II, III, and IV respectively.

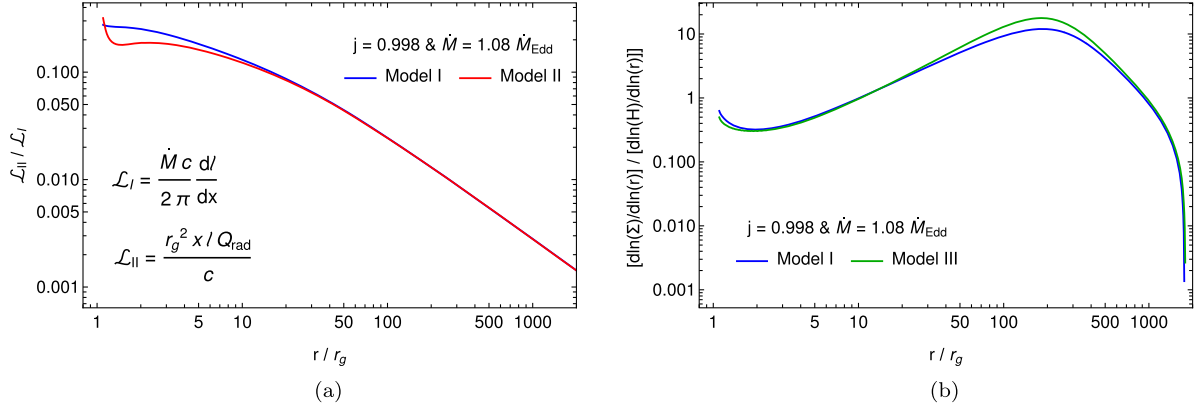


FIG. 2. (a) Radial dependence of the ratio of $\mathcal{L}_{\text{II}} = (r_g^2/c)x\ell Q_{\text{rad}}$ and $\mathcal{L}_{\text{I}} = (1/2\pi)\dot{M}c d\ell/dx$ with $j = 0.998$ and $\dot{M} = 1.08\dot{M}_{\text{Edd}}$. Here \mathcal{L}_{I} and \mathcal{L}_{II} are the first and second terms of the right-hand side of Eq. (8), respectively. The disk properties are depicted in Fig. 1. The blue and red lines correspond to Models I and II, where angular momentum loss due to radiation is included in the model. (b) The radial dependence of the ratio of $d \ln(\Sigma)/d \ln(r)$ to $d \ln(H)/d \ln(r)$, which is seen in the right-hand side of Eq. (13). The blue and green lines correspond to Models I and III, which include the scale-height derivative term in solved basic equations.

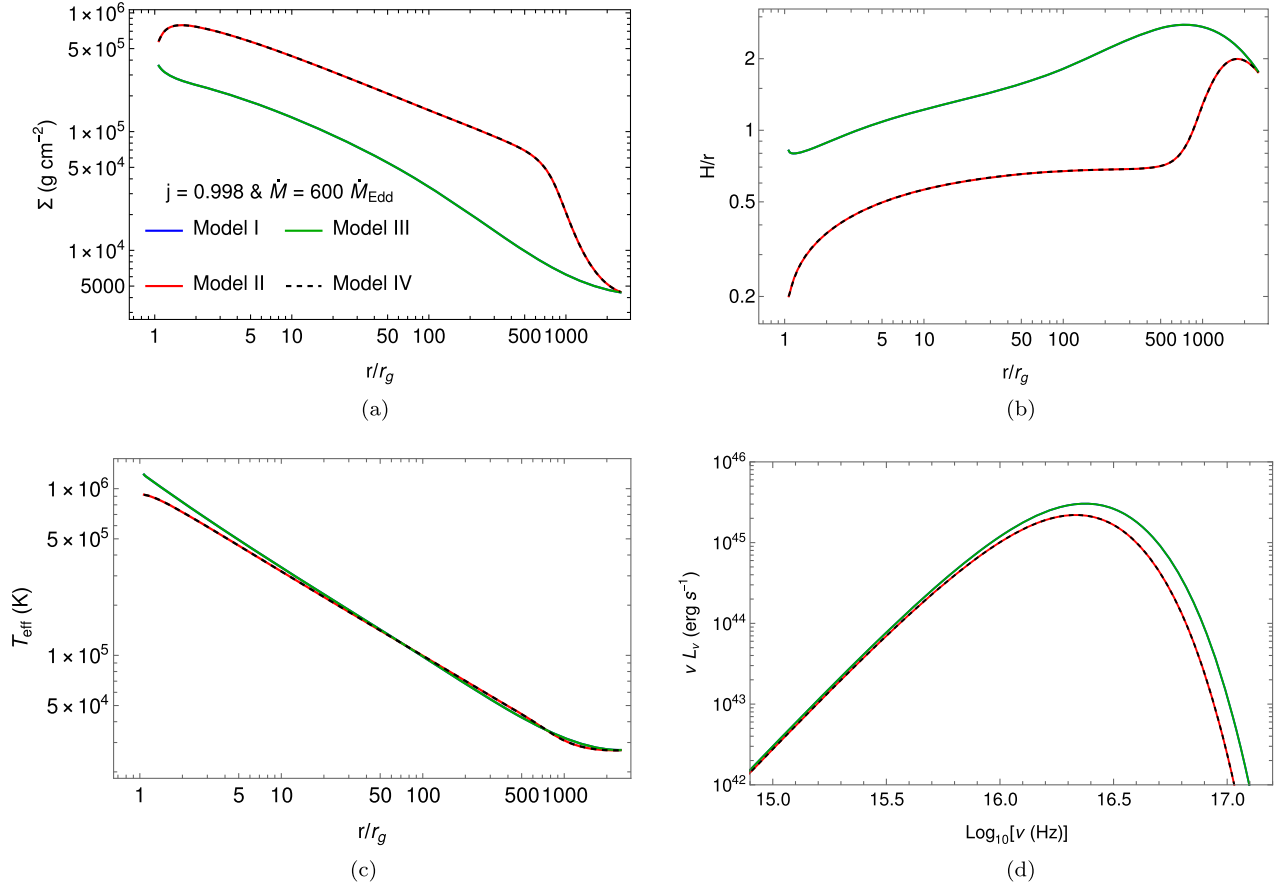
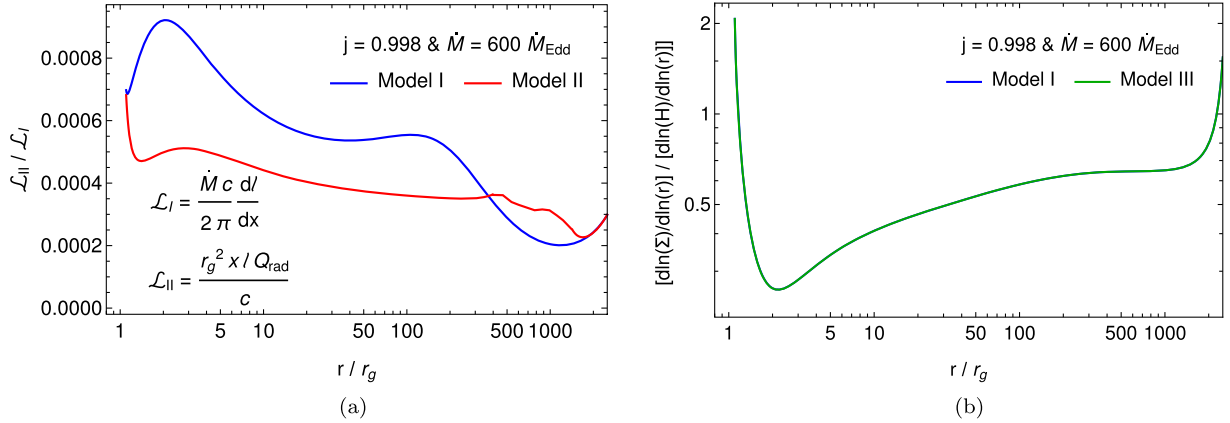
disk spectrum. On the other hand, the radiation-driven angular momentum loss plays the opposite role of the scale-height derivative. In other words, it tends to decrease the effective temperature and H/r and increase the surface density. Overall, both physical terms only affect the inner region of the disk, and the scale-height derivative impacts these physical quantities more significantly than the angular momentum loss due to the radiation.

Panel (a) of Fig. 2 shows the comparison between the angular momentum transfer with and without the radiation-driven angular momentum loss. Here we define $\mathcal{L}_{\text{II}} \equiv (r_g^2/c)x\ell Q_{\text{rad}}$ and $\mathcal{L}_{\text{I}} \equiv (1/2\pi)\dot{M}c d\ell/dx$. These two terms are seen in Eq. (8), which represents the angular momentum conservation. Panel (b) of Fig. 2 depicts the comparison of the radial derivative between the surface density and the scale height, which are appeared on the right-hand side of Eq. (13). Note that we confirm that the radial derivative of the disk temperature is comparable with the other two radial-derivative terms for all the models. From the two panels, we note that both terms are important in the inner part of the disk but insignificant in the outer region of the disk. Specifically, it is clear from panel (a) that the radiation-driven angular momentum loss is less important and the scale-height derivative is more important in the inner region of the disk.

Figures 3 and 4 represent the radial dependence of the same physical quantities as in Figs. 1 and 2, respectively, but for $\dot{M} = 600\dot{M}_{\text{Edd}}$. From the figure, we find that the effect of the scale-height derivative on these quantities is much more remarkable in the entire region of the disk than the $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ case. This suggests the effect of the scale-height derivative is more effective as the mass accretion rate is higher. Panel (a) of Fig. 4 gives a consistent result with this trend. In addition, note that the radiation-driven angular momentum loss more inefficiently works on

the disk structure even if the mass accretion rate significantly increases. This property is seen in panel (b) of Fig. 4 because both lines are completely overlapped there.

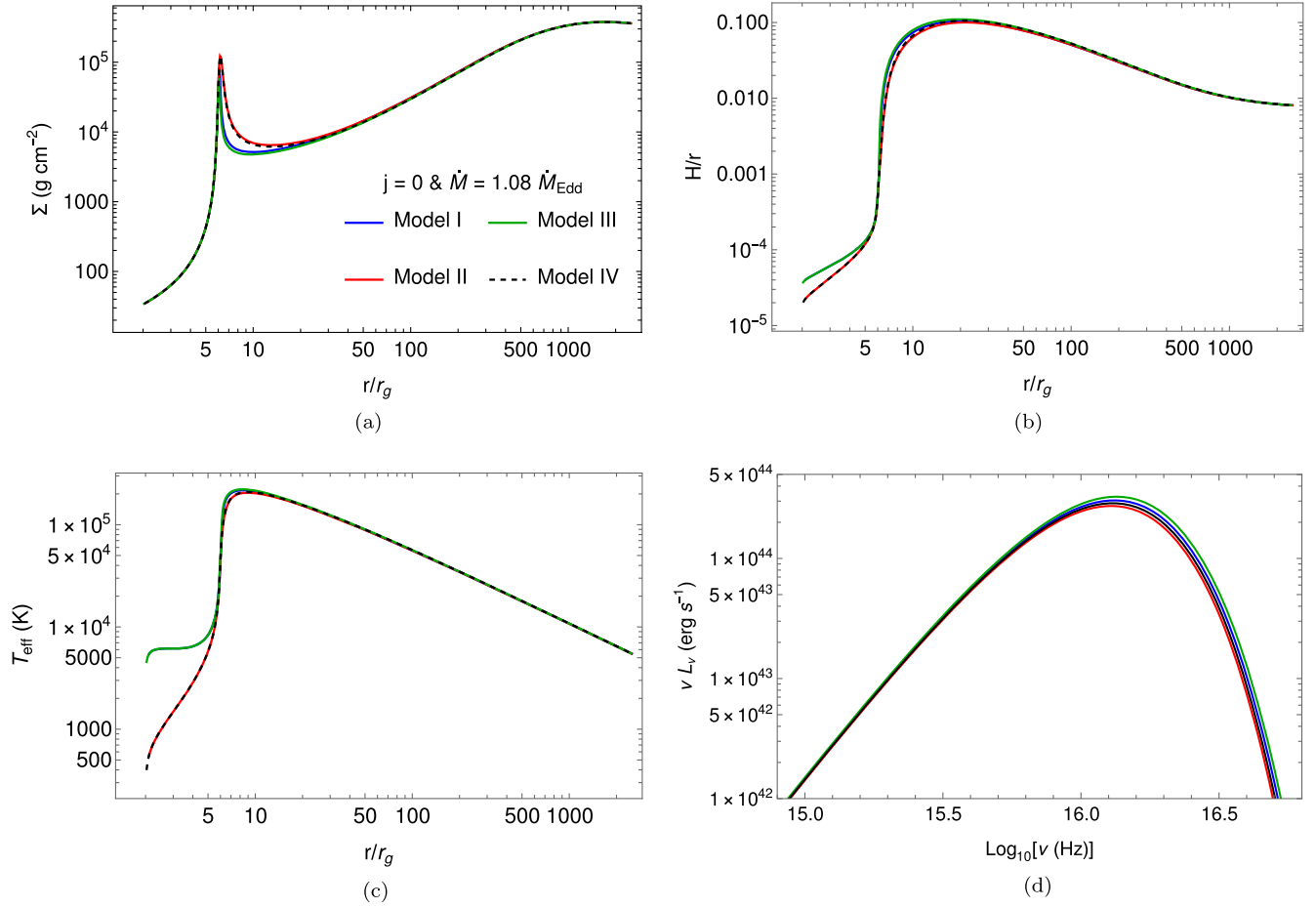
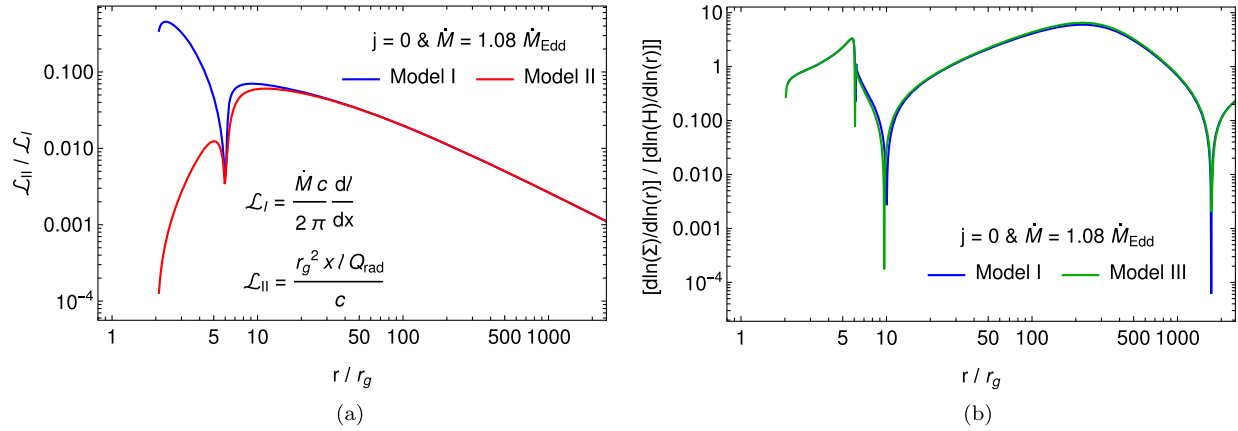
Figure 5 displays the radial dependence of the same physical quantities as in Fig. 1, except that $j = 0$. It is noted from the figure that the surface density profile differs remarkably from the $j = 0.998$ case. Moreover, only this model represents the sharp change near the inner radius in the radial surface density profile. Let us explain the cause in more detail below. We confirm that the radiation pressure dominates the gas pressure near inner radii for all the models, except that $j = 0$ and $\dot{M} = 1.08\dot{M}_{\text{Edd}}$, where the dominant pressure transits from radiation to gas pressure at the inner disk region. Since the analytical solution of the surface density, as seen in Eq. (17), indicates that $\Sigma \propto (\ell - \ell_{\text{in}})/Q_{\text{rad}}^2 \propto 1/(\ell - \ell_{\text{in}})$, the surface density increases rapidly near the inner radius. On the other hand, the Novikov-Thorne solution has shown that the surface density goes to zero at the inner radius for a gas pressure-dominated case [15]. Combining the two solutions suggests that when the disk transit from radiation to gas pressure near the inner disk radius, the surface density changes from the case where it increases to the case where it decreases sharply. This rapid change creates a hump near the inner disk radius. If the disk does not make such a transition, the surface density changes monotonically, as seen in all other models. In addition, the analytical solution of the radiation pressure-dominated disk assumes a zero viscous stress at the inner radius, whereas the full solution has no such assumption, and the boundary condition is set only at the outer radius. Moreover, the analytical solution has no angular momentum loss due to radiation, but our full solution includes it. These two factors can also produce unusual behavior near the inner radius. For example, the $d\Sigma/dr$ is zero at certain points where surface density is

FIG. 3. The same format as Fig. 1 but for $\dot{M} = 600 \dot{M}_{\text{Edd}}$.FIG. 4. The same format as Fig. 2 but for $\dot{M} = 600 \dot{M}_{\text{Edd}}$.

locally flat, causing the ratio of surface density derivative to scale-height derivative near zero at those points. This produces the two sharp droppings as seen in panel (b) of Fig. 6.

Figure 7 depicts the radial dependence of the same physical quantities as in Fig. 3, except that $j = 0$. It is noted from the figure that in comparison with $j = 0$ and $1.08 \dot{M}_{\text{Edd}}$ case, the effective temperature is much higher,

and the resultant peak of the disk spectrum is around 10^{16} Hz. While the surface density decreases due to the scale-height derivative, the H/r and effective temperature is higher. Panels (a) and (b) of Fig. 8 represent quantitatively how important the radiation-driven angular momentum loss and the scale-height derivative terms are to the basic equations. We find that the effect of the angular momentum loss due to radiation is negligibly small for both


 FIG. 5. The same format as Fig. 1 but for $j = 0$.

 FIG. 6. The same format as Fig. 2 but for $j = 0$.

with and without scale-height derivative models as the mass accretion rate increases. Also, the ratio of surface-density derivative $d \ln \Sigma / d \ln r$ and scale-height derivative $d \ln H / d \ln r$ indicates that the scale-height derivative is important over the entire disk. These tendencies are similar to the spinning black hole case that is depicted in Fig. 3.

Overall, the angular momentum loss due to radiation hardly has an influence on the disk structure and tends to be more insignificant with an increase in the mass accretion rate. The disk luminosity decreases by the inclusion of radiation-driven angular momentum loss, and the decrease in luminosity is negligible for a high-mass accretion rate.

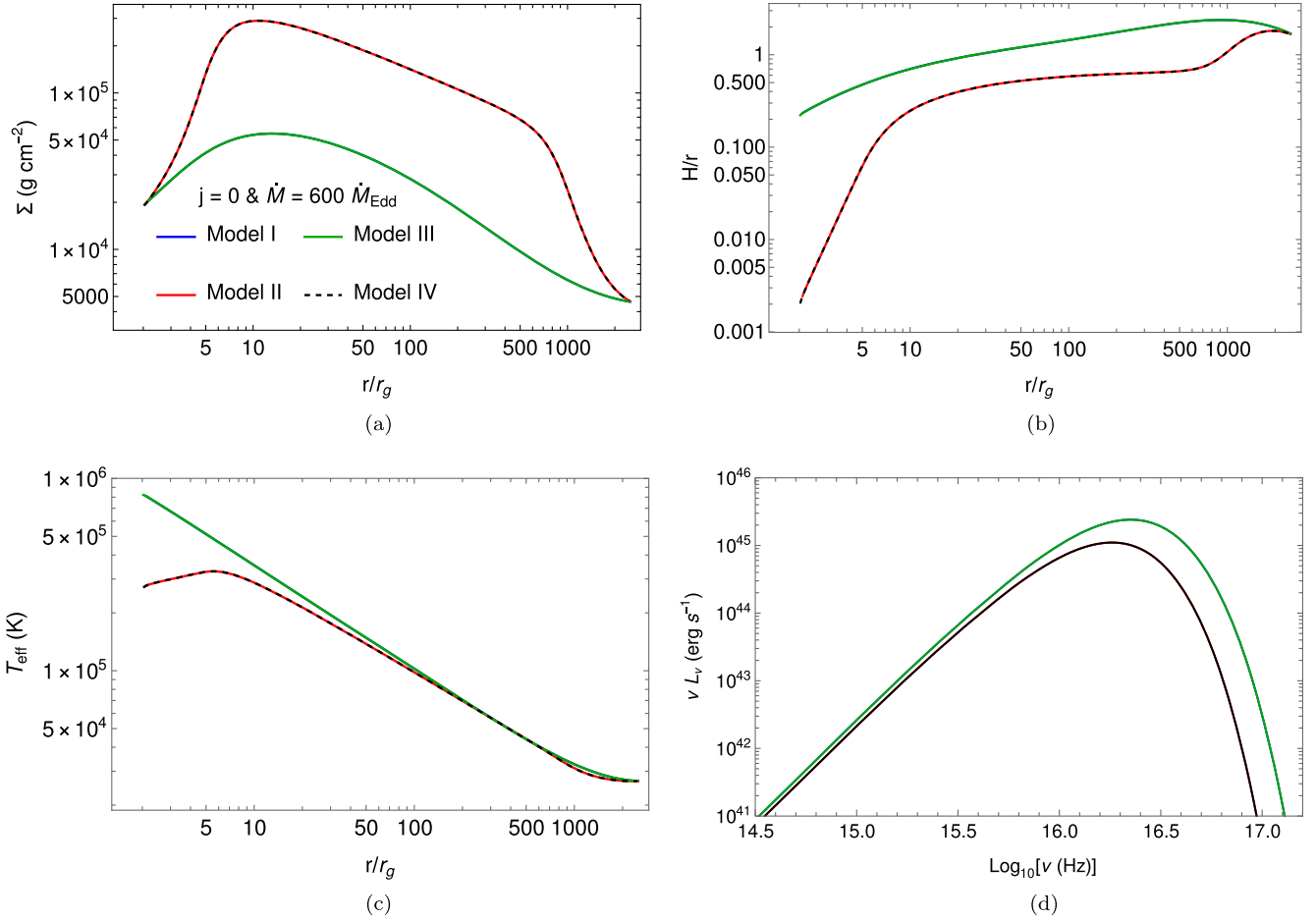


FIG. 7. The same format as Fig. 3 but for $j = 0$.

This result is consistent with Wen *et al.* [29] in that they demonstrated that the effect of the radiation-driven angular momentum loss is significant for a lower-mass accretion rate. In contrast, the scale-height derivative included in the advection energy flux term significantly impacts the disk structure. The effect spreads near the inner edge of the disk

to the entire disk as the mass accretion rate increases. The disk spectrum is more luminous due to the inclusion of the scale-height derivative, and its increment is higher as the mass accretion rate increases. The luminosity difference is more remarkable due to Wein's law exponential decay of the spectrum around the soft x-ray wave band of 10^{16-17} Hz.

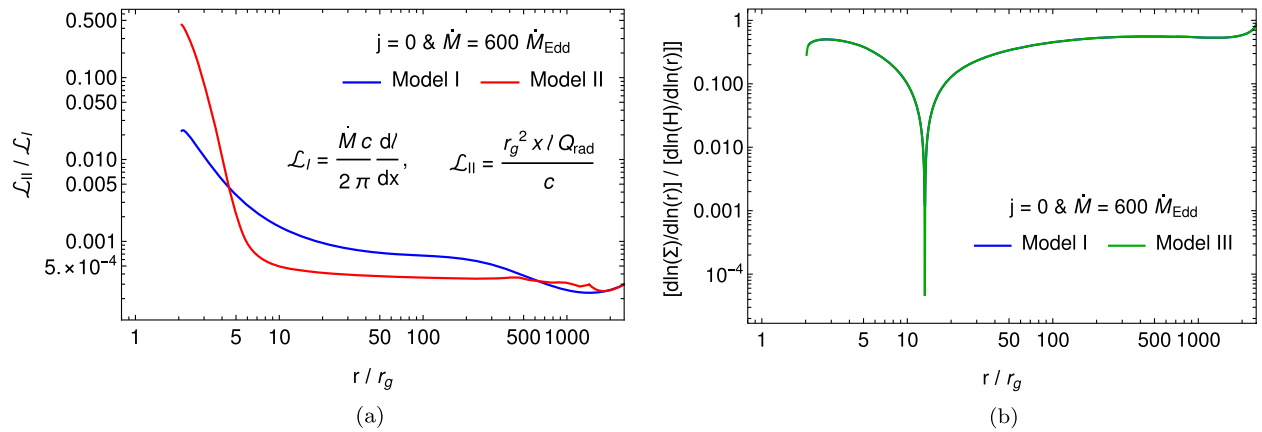


FIG. 8. The same format as Fig. 4 but for $j = 0$.

B. \dot{M} -dependence on the disk structure and emission

In Sec. III A, we investigate the effect of the two terms on the disk structure for two extreme cases of mass-accretion rate. We find there that the radiation-driven angular momentum loss has a weak impact on the disk structure for both low- and high-mass accretion rate cases. In

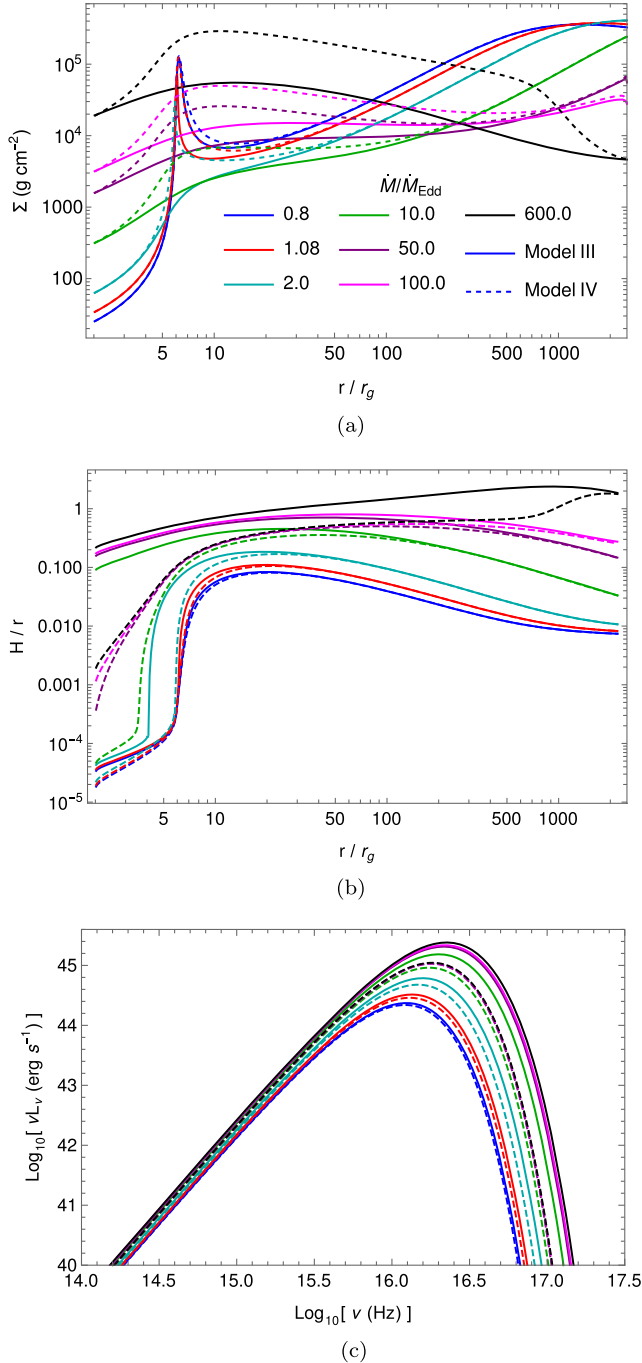


FIG. 9. Radial profiles of the surface density (panel a), the scale-height-to-radius ratio (panel b), and the disk spectrum (panel c) for the $j=0$ case. The different colors represent different mass-accretion rates. The solid and dashed lines denote Models III and IV, respectively.

contrast, the impact on the accretion flow due to scale-height derivative significantly increases with the mass accretion rate. Here, therefore, we examine in more detail how the disk structure and spectral luminosity evolve with mass accretion rate under the effect of scale-height derivative (Model III) and no scale-height derivative (Model IV).

Figure 9 illustrates the radial dependence of the surface density, scale-height-to-radius ratio, and corresponding disk spectrum for the $j=0$ case, while 10 has the same

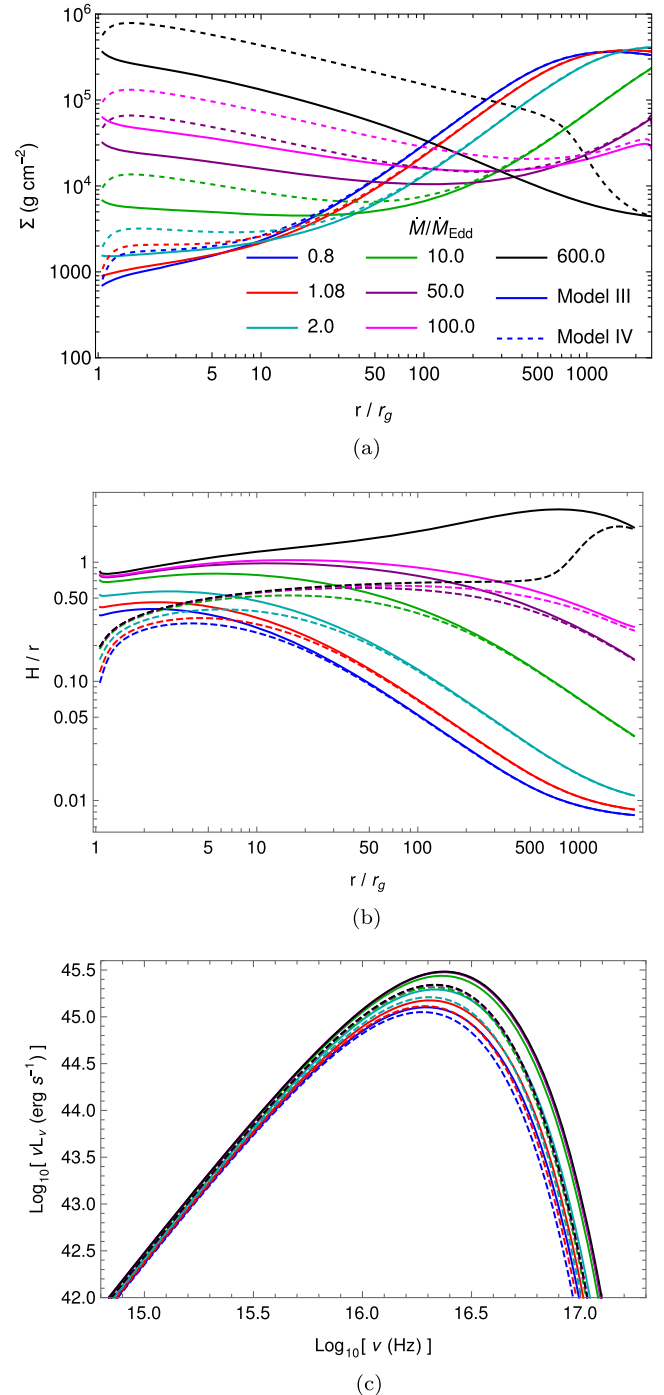


FIG. 10. The same format as Fig. 9 but for the $j=0.998$ case.

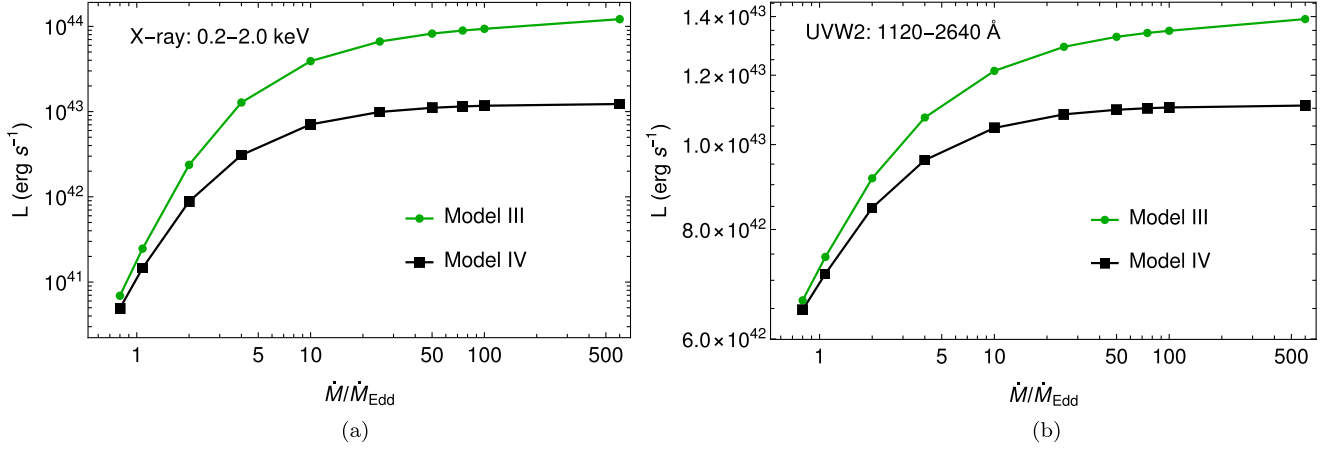


FIG. 11. \dot{M} -dependence of x-ray (0.2–2 keV) and Swift UVW2 (1120–2640 Å) luminosities for the $j = 0$ case. The solid green and black lines represent each luminosity of Model III and Model IV, respectively. Each line is complemented between ten data points of mass-accretion rates.

format but for the $j = 0.998$ case. The scale-height derivative affects the disk structure weakly at a low-mass accretion rate for nonspinning black holes; however, the impact is significant for high-spinning black holes. This suggests that the increase in black hole spin increases the impact of scale-height derivative even at the low-mass accretion rate. The scale-height derivative term affects the disk structure and spectrum crucially at $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$ even for a nonspinning black hole. In the case of a highly spinning black hole, it has a significant influence on the disk structure near the ISCO radius, even for the sub-Eddington accretion rate.

The disk spectrum increases by including the scale-height derivative, and the increment in the spectrum increases with the mass-accretion rate. This results in the brightening of the disk spectrum in the soft x-ray wave band. The observed luminosities in the x-ray (0.2–2.0 keV) and Swift UVW2 (1120–2640 Å) are given by $L = 4\pi D_L^2 \int F_{\nu, \text{obs}} d\nu_{\text{obs}}$, where Eq. (29) gives $F_{\nu, \text{obs}}$. Figures 11 and 12 depict \dot{M} -dependence of x-ray and

UVW2 luminosities for both $j = 0$ and 0.998, respectively. We note the increase in the x-ray luminosity due to the scale-height derivative is much larger than that in the Swift UVW2 luminosity. The increment in the x-ray luminosity is twice or more than for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$. Thus, the scale-height derivative is more important for the soft x-ray observations when $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$. While the luminosity of the $j = 0.998$ case is somewhat larger than that of the $j = 0$ case, the increment of the $j = 0.998$ case is much smaller than that of the $j = 0$ case. Notably, for the nonspinning BH case, the increment in the x-ray luminosity results in a one order of magnitude difference for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 100$.

C. Importance of advective cooling for the entire disk

For a radiation pressure-dominated slim disk, the ratio of advection to radiation cooling rates yields

$$\frac{Q_{\text{adv}}}{Q_{\text{rad}}} = \frac{11}{4} \frac{\dot{M}}{\eta \dot{M}_{\text{Edd}}} \frac{r_g}{r} \frac{H}{r} \xi(r), \quad (31)$$

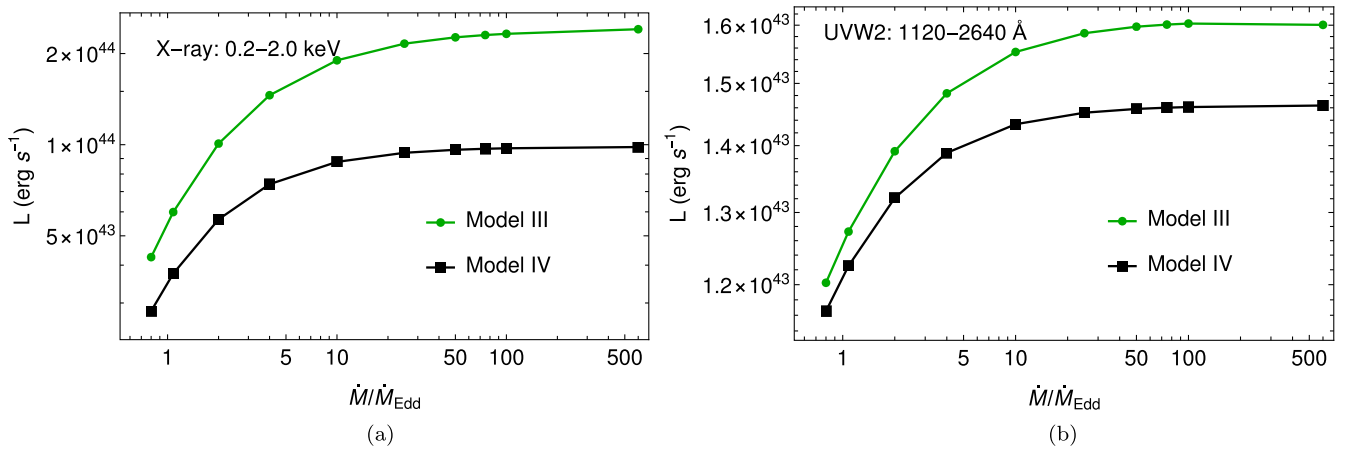


FIG. 12. The same format as Fig. 11 but for the $j = 0.998$ case.

where Eqs. (13) and (18) with $\theta = 64$ are used for the derivation. Assuming that $\xi(r) \sim 1$ for simplicity, Eq. (31) means that the advective cooling rate is lower than the radiative cooling rate if $H/r \ll 1$ at $r \gg r_g$. Moreover, this large/small relationship also holds even if $\dot{M} \gg \dot{M}_{\text{Edd}}$ because $\dot{M}/\dot{M}_{\text{Edd}}$ is comparable to r/r_g . However, if $H/r \sim 1$ and $\dot{M} \gg \dot{M}_{\text{Edd}}$, Q_{adv} is comparable with Q_{rad} even at $r \gg r_g$. To confirm whether this condition is physically satisfied, we calculate H/r , by using Eqs. (9) and (18), to be

$$\begin{aligned} \frac{H}{r} &= \sqrt{2} \frac{c_s}{c} \sqrt{\frac{r}{r_g}} \\ &= \frac{31}{2\eta} \frac{\dot{M}}{\dot{M}_{\text{Edd}}} \frac{r_g}{r} \left[1 + \sqrt{1 + \frac{3}{4} \left(\frac{1}{\eta} \frac{\dot{M}}{\dot{M}_{\text{Edd}}} \frac{r_g}{r} \right)^2} \right]^{-1} \end{aligned} \quad (32)$$

at the Keplerian rotation regime ($r \gg r_g$). This equation indicates that $H/r \gtrsim 1$ at $r = 1000r_g$ for the $\dot{M} = 600\dot{M}_{\text{Edd}}$ case, yielding $Q_{\text{adv}}/Q_{\text{rad}} \sim 1$ from Eq. (31). By substituting Eq. (32) into Eq. (31), $Q_{\text{adv}}/Q_{\text{rad}}$ can be more explicitly written as

$$\begin{aligned} \frac{Q_{\text{adv}}}{Q_{\text{rad}}} &= \frac{3}{8} \xi(r) \left(\frac{1}{\eta} \frac{\dot{M}}{\dot{M}_{\text{Edd}}} \frac{r_g}{r} \right)^2 \\ &\times \left[1 + \sqrt{1 + \frac{3}{4} \left(\frac{1}{\eta} \frac{\dot{M}}{\dot{M}_{\text{Edd}}} \frac{r_g}{r} \right)^2} \right]^{-1}. \end{aligned} \quad (33)$$

Above equation confirms that $Q_{\text{adv}}/Q_{\text{rad}} \gtrsim 1$ for $\eta = 0.1$, $\dot{M} \simeq (r/r_g)\dot{M}_{\text{Edd}}$, and $\xi(r) \sim 1$, demonstrating that the advective cooling is important for the disk structure even at the far outer-disk region if $\dot{M} \gg \dot{M}_{\text{Edd}}$.

This scaling presumption holds even if the $\xi(r) \sim 1$ assumption is relaxed. Figure 13 the radial profile of the ratio of advective to radiative cooling rates. The solid green and dashed black lines represent $|Q_{\text{adv}}|/Q_{\text{rad}}$ of Models III and IV, respectively. The figure illustrates that $Q_{\text{adv}}/Q_{\text{rad}} \sim 1$ at $r \sim 1000r_g$ when $\dot{M} = 600\dot{M}_{\text{Edd}}$, while $Q_{\text{adv}}/Q_{\text{rad}} \ll 1$ at the same radius when $\dot{M} = 1.08\dot{M}_{\text{Edd}}$. Note that the sharp droppings seen in panels (a), (b), and (d) of Fig. 13 are caused by taking the absolute value of Q_{adv} at $Q_{\text{adv}} = 0$ in the logarithmic scale. The zero value of Q_{adv} is due to a change from positive to negative values or vice versa (see also SA09). We confirm that advective cooling is

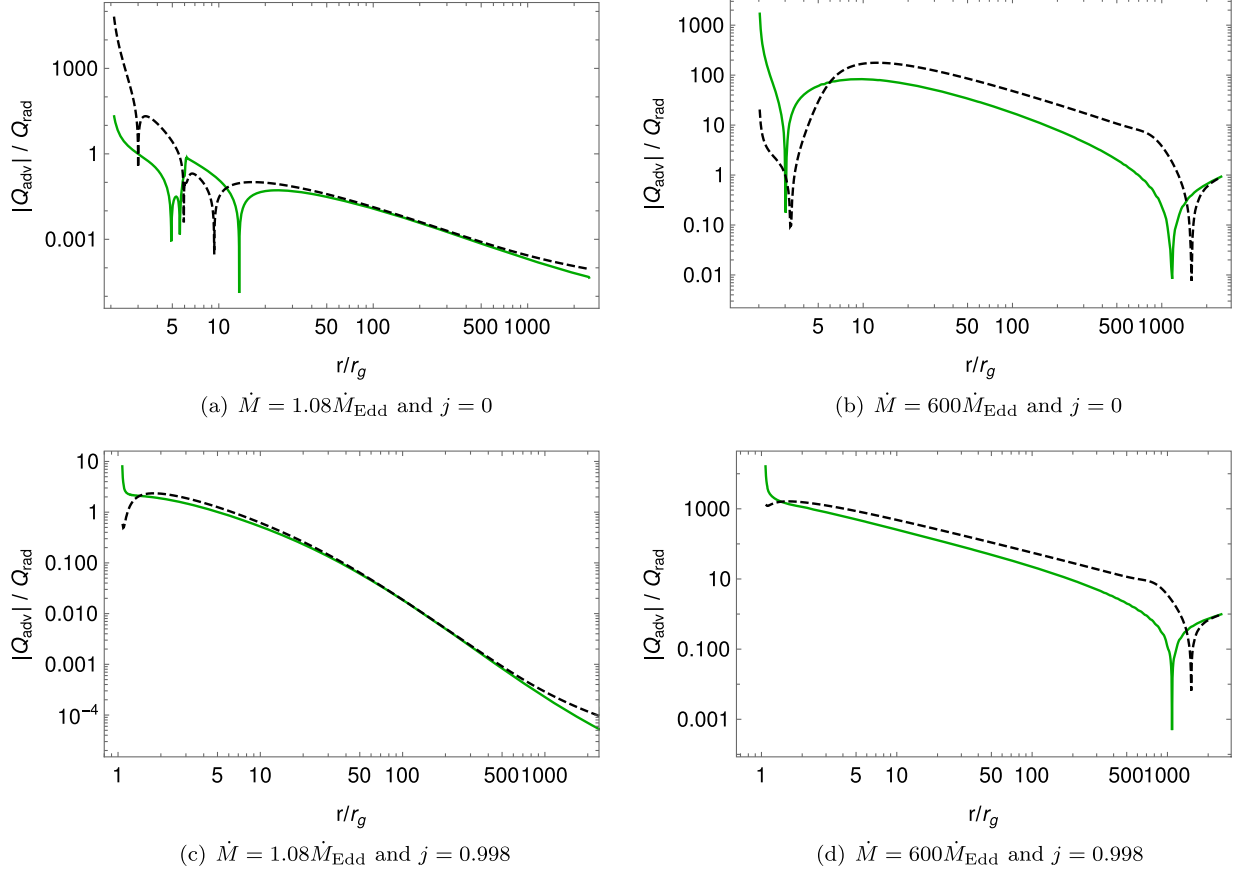


FIG. 13. Radial dependence of the ratio of advective to radiative cooling rates, $|Q_{\text{adv}}|/Q_{\text{rad}}$, for $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ and $600\dot{M}_{\text{Edd}}$. The upper and lower panels depict the $j = 0$ and $j = 0.998$ cases, respectively. The solid green and dashed black lines represent $|Q_{\text{adv}}|/Q_{\text{rad}}$ of Models III and IV, respectively.

crucial even for the disk's outer region if the mass accretion rate is much larger than the Eddington accretion rate.

IV. DISCUSSION

We have studied the impact of the angular momentum loss due to radiation and scale-height derivative on a steady-state GR slim disk. We find that the term of the angular momentum loss due to the radiation $(r_g^2/c)x\ell Q_{\text{rad}}$ is weaker than the term being proportional to the accretion rate $(1/2\pi)\dot{M}cd\ell/dx$ so that becomes significantly less effective for higher-mass accretion rate. In addition, because both the viscous heating and advective fluxes increase with the mass accretion rate, as can be seen from Eqs. (11) and (13), the net radiation flux, which is given by $Q_{\text{rad}} = Q_{\text{vis}} - Q_{\text{adv}}$, little increases with the mass accretion rate, especially in the super-Eddington regime. This also means the effect of the radiation-driven angular momentum loss also does not work effectively for a higher-mass accretion rate.

Next, the impact of the scale-height derivative on the disk structure is prominent in contrast to that of the radiation-driven angular momentum loss. The disk-scale height increases due to the stronger radiation pressure at the more highly super-Eddington regime, resulting in a higher disk temperature. The stronger radiation pressure also decreases the surface density because the ratio of gas to total pressure, β_{gas} , becomes lower. The disk scale-height derivative makes the surface density significantly lower. Note that the lower surface density implies that the radial disk velocity is higher if the mass accretion rate is constant.

The black hole spin also impacts the disk structure mainly at the radius where the GR effects are significant and surely makes the disk structure deviate from the Newtonian one, although the mathematical dependence of the black hole spin on the surface density, disk temperature, and spectrum cannot be written explicitly as they are obtained numerically, unlike the NK solutions [15]. It is noted from Figs. 1 and 5 that for $\dot{M} = 1.08\dot{M}_{\text{Edd}}$, the effective temperature rapidly decreases at the ISCO in the $j = 0$ case. In contrast, it increases with the radius without any significant dropping in the case of $j = 0.998$, extending the disk spectrum to a higher-energy side. This difference is seen in the range of $\nu \gtrsim 10^{16.5}$ of the disk spectrum in Figs. 1(d) and 5(d). It is noted from Figs. 3 and 7 that for $\dot{M} = 600\dot{M}_{\text{Edd}}$, the surface density rapidly decreases around the ISCO in the $j = 0$ case, whereas it increases with radius even beyond $r = 2r_g$ in the $j = 0.998$ case. However, because the effective temperature around the inner edge radius does not change depending on the black hole spin, there is a slight difference in the resultant spectrum. Also, we find that these properties regarding the black hole spin effect on the disk structure show the same tendency between the model comprising the two key terms and the model without them.

Let us discuss how important the inclusion of the scale-height derivative is for identifying parameters such as black hole mass and spins. Indeed, [30] have statistically given a constraint on the black hole mass and spin by comparing the observed x-ray spectra of ASAS-SN 14li with both models of [28,29]. Note that Wen *et al.* [28] applied the GR disk model without including both the angular momentum loss due to radiation and the scale-height derivative to the ASAS-SN 14li x-ray observations, while Wen *et al.* [29] included only the radiation-driven angular momentum loss into the GR slim disk, which is consistent with our solutions for Models I and III. [29] calculated the disk emission by using the photon ray-tracing method. The resultant x-ray spectra yield consistent results with those of Wen *et al.* [28] because the radiation-driven angular momentum loss term has a significantly weak impact on the disk structure. Nonetheless, the model of Wen *et al.* [29] provides a better 1σ contour than that of Wen *et al.* [28]. [30] have demonstrated that, unlike the case of Wen *et al.* [28], the parameters are well constrained within 1σ contour when the radiation-driven angular momentum loss is included, even in spite of the weak impact on the disk structure and emission. As we described in Secs. III A and III B, the scale-height derivative term is much more effective on the disk structure and emission than the radiation-derive angular momentum loss term. Therefore, we will make detailed calculations of the disk spectra by combining our GR model with the GR photon ray tracing code and then compare them with the TDE observations, making it possible to estimate the black hole mass and spin more precisely.

The flux sensitivity of the Swift x-ray telescope (XRT) is $f_{\text{lim}} = 8 \times 10^{-14} \text{ ergs}^{-1} \text{ cm}^{-2}$. The luminosity distance of the ASAS-SN 14li is $D_L = 90 \text{ Mpc}$ [36], such that luminosity detection limit for the ASAS-SN 14li is $L_{\text{lim}} = 4\pi D_L^2 f_{\text{lim}} = 7.75 \times 10^{40} \text{ erg s}^{-1} (D_L/90 \text{ Mpc})^2$. The x-ray luminosity shown in Figs. 11 and 12 is significantly higher than the detection limit of the telescope for both cases with and without scale-height derivative. In addition, the photometric accuracy of Swift XRT is $\sim 10\%$, which implies that the x-ray luminosity of $\gtrsim 10^{41} \text{ erg s}^{-1}$ can be well-measured.

In TDEs, the stellar debris is circularized to form an accretion disk with or without still infalling debris [10]. If the accretion timescale is smaller than the fallback timescale of the infalling debris, we expect the mass accretion rate to follow the mass fallback rate \dot{M}_{fb} . The luminosity will be then $L \propto \dot{M}_{\text{fb}} \propto t^n$, where $n = -5/3$ for full TDEs and $n \simeq -9/4$ [38]. However, the TDE light curves in the soft x-ray wave band have shown different power-law evolution [39] and indicates that the viscous accretion timescale of the TDE disk is usually longer than the fallback timescale. Because the fallback mass is likely to inject into the TDE disk from the outer edge at \dot{M}_{fb} , there is an issue with how the mass accretion rate relates to the mass

fallback rate and also depends on radius and time. In addition, according to the past literature on the non-GR and time-dependent ADAF models [31,40–42], they have demonstrated the limit cycle behavior, which is caused by thermal instability, on the light curves. However, those models are assumed to be in a steady state at the initial time, and then the mass is supplied at the outer radius at a constant rate. This is clearly a different initial condition from that of TDEs. Therefore, there can be another problem with how the initial condition affects the limit cycle behavior. These questions motivate us to construct a time-dependent model of the optically thick ADAF in the TDE context in the near future.

V. CONCLUSIONS

We have constructed a steady-state, optically thick, advection-dominated GR accretion disk with the alpha-viscosity prescription and both gas and radiation pressures by taking account of the angular momentum loss due to the radiation and scale-height derivative. Notably, the scale-height derivative term in the basic equations has hitherto been overlooked in extant literature (e.g., [22–30]).

We have studied the impact of these two physics on the disk structure and emission. Our primary conclusions are summarized as follows:

- (1) For comparison purposes, we have newly derived an analytical solution for a stationary radiation-pressure-dominant GR slim disk with zero viscous stress at the inner radius.
- (2) The angular momentum loss due to radiation only slightly increases the surface density, disk temperature, and resultant spectrum near the disk's inner-edge radius. In addition, these effects become negligibly small as the mass accretion rate increases. This indicates that the radiation-driven angular momentum loss has little impact on the disk surface density, temperature, and spectrum for highly super-Eddington accretion flows.
- (3) In contrast to the radiation-driven angular momentum loss case, the scale-height derivative reduces the disk surface density while it increases the disk temperature and scale height. These effects significantly increase as the mass accretion rate increases, affecting the entire disk region at an extremely high accretion rate.
- (4) The increment in the x-ray (0.2–2.0 keV) luminosity due to scale-height derivative is significant for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$. Moreover, the increment is higher for the nonspinning black hole than the spinning black hole case, resulting in a one order of magnitude difference for $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 100$. These results indicate solving a set of basic equations with the scale-height derivative for a super-Eddington accretion flow with $\dot{M}/\dot{M}_{\text{Edd}} \gtrsim 2$ is crucial, especially for comparing with soft x-ray observations.

ACKNOWLEDGMENTS

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APPENDIX A: BASIC QUANTITIES OF GENERAL RELATIVISTIC DISK EQUATIONS

The Kerr metric in the Boyer-Lindquist coordinate is transformed to a cylindrical coordinate $\{t, r, \phi, z\}$. The space-time metric in the geometrical units ($c = G = 1$) with the signature $(-+++)$, is given by [17]

$$\begin{aligned}
 dS^2 = & - \left[1 - \frac{2M(r^2 + z^2)^{3/2}}{(r^2 + z^2)^2 + a^2 z^2} \right] dt^2 - \frac{4Mar^2 \sqrt{r^2 + z^2}}{(r^2 + z^2)^2 + a^2 z^2} dt d\phi \\
 & + \frac{(r^2 + z^2)^2 + a^2 z^2}{(r^2 + z^2)^2} \left[\frac{r^2}{r^2 + z^2 - 2M\sqrt{r^2 + z^2} + a^2} + \frac{z^2}{r^2 + z^2} \right] dr^2 \\
 & + \frac{(r^2 + z^2)^2 + a^2 z^2}{(r^2 + z^2)^2} \left[\frac{z^2}{r^2 + z^2 - 2M\sqrt{r^2 + z^2} + a^2} + \frac{r^2}{r^2 + z^2} \right] dz^2 \\
 & + \frac{2rz[(r^2 + z^2)^2 + a^2 z^2]}{(r^2 + z^2)^2} \left[\frac{1}{r^2 + z^2 - 2M\sqrt{r^2 + z^2} + a^2} - \frac{1}{r^2 + z^2} \right] dr dz \\
 & + \frac{r^2}{r^2 + z^2} \left[r^2 + z^2 + a^2 + \frac{2Mar^2 \sqrt{r^2 + z^2}}{(r^2 + z^2)^2 + a^2 z^2} \right] d\phi^2.
 \end{aligned} \tag{A1}$$

In the limit of thin disc $z \ll r$, the metric tensors are given by

$$g_{tt} = -1 + \frac{2M}{r} - \frac{M(2a^2 + r^2)z^2}{r^5}, \quad (\text{A2})$$

$$g_{tr} = g_{rt} = 0, \quad (\text{A3})$$

$$g_{t\phi} = g_{\phi t} = -\frac{2Ma}{r} + \frac{M(2a^3 + 3ar^2)z^2}{r^5}, \quad (\text{A4})$$

$$g_{tz} = g_{zt} = 0, \quad (\text{A5})$$

$$g_{rr} = \frac{r^2}{r^2 - 2Mr + a^2} + \frac{[2a^4 + 3a^2(r^2 - 2Mr) + M(4Mr^2 - 3r^3)]z^2}{r^2(r^2 - 2Mr + a^2)^2}, \quad (\text{A6})$$

$$g_{r\phi} = g_{\phi r} = 0, \quad (\text{A7})$$

$$g_{rz} = g_{zr} = 2 \left(-1 + \frac{r^2}{r^2 - 2Mr + a^2} \right) \frac{z}{r}, \quad (\text{A8})$$

$$g_{\phi\phi} = \frac{r^4 + a^2r^2 + 2Ma^2r}{r^2} - \frac{a^2(r^4 + Mr(2a^2 + 5r^2))z^2}{r^6}, \quad (\text{A9})$$

$$g_{\phi z} = g_{z\phi} = 0, \quad (\text{A10})$$

$$g_{zz} = 1 + \left[\frac{a^2 - r^2}{r^2} + \frac{r^2}{r^2 - 2Mr + a^2} \right] \frac{z^2}{r^2}, \quad (\text{A11})$$

which is the same as the metric tensor given in Zhuravlev [43]. At the equatorial plane ($z = 0$), the space-time metric reduces to

$$dS^2 = - \left(\frac{r-2M}{r} \right) dt^2 - \frac{4Ma}{r} dt d\phi + \frac{r^2}{\Delta} dr^2 + \frac{A}{r^2} d\phi^2 + dz^2, \quad (\text{A12})$$

where $\Delta = r^2 - 2Mr + a^2$ and $A = r^4 + a^2r^2 + 2Ma^2r$. In Boyer-Lindquist coordinates using orthonormal tetrad in the local nonrotating frame (LNRF) [14], the contravariant components of four velocities are given by [23,31]

$$u^t = \frac{\gamma_L A^{1/2}}{r \Delta^{1/2}}, \quad (\text{A13})$$

$$u^r = \frac{V}{\sqrt{1-V^2}} \frac{\Delta^{1/2}}{r}, \quad (\text{A14})$$

$$u^\phi = \frac{r^2 \mathcal{L}}{A} + 2Ma \frac{\gamma_L}{A^{1/2} \Delta^{1/2}}, \quad (\text{A15})$$

$$u^z = 0, \quad (\text{A16})$$

where V is the radial velocity in the corotating frame, \mathcal{L} is the angular momentum per unit mass, and γ_L is the Lorentz factor in LNRF near the equatorial plane given by

$$\gamma_L^2 = \frac{1}{1-V^2} + \frac{r^2 \mathcal{L}^2}{A}. \quad (\text{A17})$$

The covariant component of four velocities is given by

$$u_t = -\frac{\gamma_L r \Delta^{1/2}}{A^{1/2}} - \frac{2Mar}{A} \mathcal{L}, \quad (\text{A18})$$

$$u_r = \frac{r}{\Delta^{1/2}} \frac{V}{\sqrt{1-V^2}}, \quad (\text{A19})$$

$$u_\phi = \mathcal{L}, \quad (\text{A20})$$

$$u_z = 0. \quad (\text{A21})$$

The viscous stress tensor is given by $S_\beta^\alpha = -2\eta\sigma_\beta^\alpha$, where $\sigma_\beta^\alpha = g^{\alpha i} \sigma_{i\beta}$, and $\sigma_{i\beta}$ is given by

$$\sigma_{i\beta} = \frac{1}{2} \left[\frac{\partial u_i}{\partial \mathbf{X}^\beta} + \frac{\partial u_\beta}{\partial \mathbf{X}^i} - 2\Gamma_{i\beta}^\lambda u_\lambda + u^\nu (u_i u_\beta)_{;\nu} \right] - \frac{1}{3} u_{;\nu}^\nu [g_{i\beta} + u_i u_\beta], \quad (\text{A22})$$

where Γ is the Christoffel symbol and $\mathbf{X} \equiv \{t, r, \phi, z\}$ represent four coordinates. For a subsonic flow such that angular velocity is smaller than the sound speed $\sim \sqrt{p/\rho}$, the σ_ϕ^r is given by

$$\sigma_\phi^r = \frac{1}{2} \frac{\Delta^{1/2} A^{3/2} \gamma_L^3}{r^5} \frac{d\Omega}{dr}, \quad (\text{A23})$$

where $\Omega = u^\phi / u^t$. The dynamic viscosity $\eta = \nu\rho$, where ν is the kinematic viscosity. The viscous stress is then given by $S_\phi^r = -2\nu\rho\sigma_\phi^r$, and after vertical integration, it is given by

$$\bar{S}_\phi^r = -\nu\Sigma \frac{\Delta^{1/2} A^{3/2} \gamma_L^3}{r^5} \frac{d\Omega}{dr}, \quad (\text{A24})$$

which is the same as the viscous stress obtained by Lasota [22].

The mass-conservation equation is given by $(\rho u^i)_{;i} = 0$, which after vertical integration, results in [31]

$$\frac{\partial}{\partial t}(\Sigma u^t) + \frac{1}{r} \frac{\partial}{\partial r}(r \Sigma u^r) = 0, \quad (\text{A25})$$

where $\Sigma = \int \rho dz = 2H\rho$ and H is the scale height of the disk. For a steady disk, mass accretion rate $\dot{M} = -2\pi r \Sigma u^r$ is a constant and is given by [23]

$$\dot{M} = -2\pi \Sigma \Delta^{1/2} \frac{V}{\sqrt{1-V^2}}. \quad (\text{A26})$$

The radial-conservation equation is given by $T^i{}_{;i} = 0$, which results in [31]

$$\frac{\partial V}{\partial t} = \frac{\Delta \sqrt{1-V^2}}{\gamma_L A^{1/2}} \left[-\frac{V}{1-V^2} \frac{\partial V}{\partial r} + \frac{\mathcal{A}}{r} - \frac{1-V^2}{\rho} \frac{\partial p}{\partial r} \right], \quad (\text{A27})$$

where

$$\mathcal{A} = -\frac{MA}{r^3 \Delta \Omega_K^+ \Omega_K^-} \frac{(\Omega - \Omega_K^+)(\Omega - \Omega_K^-)}{1 - \tilde{\Omega}^2 \tilde{R}^2}, \quad (\text{A28})$$

with $\Omega_K^\pm = \pm M/(r^{3/2} \pm aM^{1/2})$, $\tilde{\Omega} = \Omega - 2Mar/A$, and $\tilde{R} = A/r^2 \Delta^{1/2}$. For the steady case and after the vertical integration, we have

$$\frac{V}{1-V^2} \frac{dV}{dr} = \frac{\mathcal{A}}{r} - \frac{1-V^2}{\Sigma} \frac{dP}{dr}, \quad (\text{A29})$$

where $P = \int p dz = 2Hp$.

The angular momentum conservation equation is given by $(T^i{}_{\phi} \xi^k)_{;i} = 0$ [31], where $\xi^k \equiv \delta_\phi^k$ is the azimuthal Killing vector and δ_ϕ^k is the Kronecker delta. It results in

$$\rho u^t \frac{\partial u_\phi}{\partial t} + \rho u^r \frac{\partial u_\phi}{\partial r} + \frac{1}{r} \frac{\partial (r S_\phi^r)}{\partial r} + \frac{\partial}{\partial z}(u_\phi q^z) = 0, \quad (\text{A30})$$

and performing vertical integration, we get

$$\Sigma u^t \frac{\partial u_\phi}{\partial t} + \Sigma u^r \frac{\partial u_\phi}{\partial r} + \frac{1}{r} \frac{\partial (r \bar{S}_\phi^r)}{\partial r} + u_\phi Q_{\text{rad}} = 0, \quad (\text{A31})$$

where $Q_{\text{rad}} = 2q^z$ is the radiative flux. For a steady case, we get [23]

$$\frac{d(r \bar{S}_\phi^r)}{dr} = \frac{\dot{M}}{2\pi} \frac{d\mathcal{L}}{dr} - r Q_{\text{rad}} \mathcal{L}. \quad (\text{A32})$$

The viscous stress in the comoving rotating frame obtained using the orthonormal tetrad basis is given by

$t_{r\phi} = -r^2 \bar{S}_\phi^r / (\gamma_L A^{1/2} \Delta^{1/2})$ [22,33]. Assuming an alpha viscosity, $t_{r\phi} = -\alpha P$, we have

$$\bar{S}_\phi^r = \alpha P \frac{\gamma_L A^{1/2} \Delta^{1/2}}{r^2}, \quad (\text{A33})$$

$$\begin{aligned} \nu &= -\alpha \frac{P}{\Sigma} \frac{r^3}{\gamma_L^2 A} \left(\frac{d\Omega}{dr} \right)^{-1} \\ &= -2\alpha \frac{HP}{\Sigma} \frac{r^3}{\gamma_L^2 A} \left(\frac{d\Omega}{dr} \right)^{-1}. \end{aligned} \quad (\text{A34})$$

The vertical-hydrostatic equilibrium results in the scale height given by [32]

$$\frac{P}{\Sigma H^2} = \frac{\mathcal{L}^2 - a^2(\epsilon^2 - 1)}{2r^4} \equiv \zeta, \quad (\text{A35})$$

where $\epsilon = u_t$ is the conserved energy for test particle motion.

The energy conservation equation is given by $Q_{\text{vis}} = Q_{\text{rad}} + Q_{\text{adv}}$. Each term are written by [31]

$$Q_{\text{vis}} = \nu \Sigma \frac{\gamma_L^4 A^2}{r^6} \left(\frac{d\Omega}{dr} \right)^2 = -\alpha P \frac{A \gamma_L^2}{r^3} \frac{d\Omega}{dr}, \quad (\text{A36})$$

$$Q_{\text{rad}} = \frac{\theta \sigma T^4}{3 \kappa \Sigma}, \quad (\text{A37})$$

$$Q_{\text{adv}} = \frac{1}{2\pi} \frac{\dot{M} P}{r^2 \Sigma} \xi(r), \quad (\text{A38})$$

where $\theta = 64$ is adopted in our models and in those of Wen *et al.* [28,29], whereas $\theta = 32$ in SA09. In addition, $\xi(r)$ is defined as

$$\begin{aligned} \xi(r) &\equiv -\frac{T}{c_s^2} \frac{\partial s}{\partial \ln(r)} \\ &= -\frac{4 - 3\beta_{\text{gas}}}{\Gamma_3 - 1} \frac{d \ln T}{d \ln r} + (4 - 3\beta_{\text{gas}}) \left(\frac{d \ln \Sigma}{d \ln r} - \frac{d \ln H}{d \ln r} \right), \end{aligned} \quad (\text{A39})$$

where s is the specific entropy, $\beta_{\text{gas}} = p_{\text{gas}}/p$ is the ratio of gas to total pressure, and Γ_3 is the third adiabatic exponent,

$$\Gamma_3 = 1 + \frac{(4 - 3\beta_{\text{gas}})(\gamma_{\text{gas}} - 1)}{\beta_{\text{gas}} + 12(1 - \beta_{\text{gas}})(\gamma_{\text{gas}} - 1)}$$

with the gaseous specific heat ratio, γ_{gas} .

Employing the following dimensionless quantities $x = r/r_g$, $j = a/M$, and $\ell = \mathcal{L}/(r_g c)$, we obtain $A = r_g^4 A_k$, $\Delta = r_g^2 \Delta_k$, $\Omega = (c/r_g) \omega$, and $\gamma_L = \sqrt{1/(1-V^2) + x^2 \ell^2 / A_k}$, where $A_k = x^4 + x^2 j^2 + 2x j^2$, $\Delta_k = x^2 - 2x + j^2$, and $\omega = 2jx/A_k + x^3 \Delta_k^{1/2} \ell / A_k^{3/2}$, respectively. The conservation

equations shown in Sec. II are written in unit of these dimensionless variable.

APPENDIX B: EACH COMPONENT OF a_i , e_i , AND r_i

We present the each component of a_i , e_i , and r_i that appears in the Eqs. (21), (22), and (23) given in Sec. II B to obtain the full GR slim-disk solution.

$$r_1 = \frac{V^2}{1-V^2} - \frac{c_s^2}{c^2} + 2 \frac{c_s^2}{c^2} \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_2, \quad (\text{B1})$$

$$r_2 = 2 \frac{c_s^2}{c^2}, \quad (\text{B2})$$

$$r_3 = 2 \frac{c_s^2}{c^2} \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_3, \quad (\text{B3})$$

$$r_4 = \mathcal{A}_1 + \frac{c_s^2}{c^2} \left[\frac{1}{2\Delta_k} \frac{d\Delta_k}{dx} - 2 \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_4 \right], \quad (\text{B4})$$

$$a_1 = 2\chi_2 \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) - \frac{1}{\gamma_L^2} \left\{ 1 + \frac{x^2 \ell^2}{A_k} \right\}, \quad (\text{B5})$$

$$a_2 = 2, \quad (\text{B6})$$

$$a_3 = \frac{x^2 \ell}{A_k \gamma_L^2} - 2 \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_3 - \begin{cases} \frac{1}{2\pi} \frac{Mc}{x S_\phi^2} & \text{Model: I \& II} \\ \frac{1}{\ell - \ell_{\text{in}}} & \text{Model: III \& IV} \end{cases}, \quad (\text{B7})$$

$$a_4 = -2 \left(\frac{1-\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_4 + \frac{1}{2\gamma_L^2 (1-V^2)} \frac{d}{dx} \left[\log \left(\frac{x^2}{A_k} \right) \right] - \begin{cases} \frac{j_g^2 x \ell Q_{\text{rad}}}{c x S_\phi^2} & \text{Model: I \& II} \\ 0 & \text{Model: III \& IV} \end{cases}, \quad (\text{B8})$$

$$e_1 = \alpha \frac{x^2 \ell V}{\gamma_L A_k^{1/2} \sqrt{1-V^2}} - \begin{cases} 2 \left(\frac{4-3\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_2 x & \text{Model: I \& III} \\ (4-3\beta_{\text{gas}}) x & \text{Model: II \& IV} \end{cases}, \quad (\text{B9})$$

$$e_2 = x \left[\frac{1+\beta_{\text{gas}}}{\Gamma_3 - 1} + \begin{cases} 4-3\beta_{\text{gas}} & \text{Model: I \& III} \\ 0 & \text{Model: II \& IV} \end{cases} \right], \quad (\text{B10})$$

$$e_3 = -\alpha \frac{x^2}{\gamma_L A_k^{1/2} V \sqrt{1-V^2}} + \begin{cases} 2 \left(\frac{4-3\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_3 x & \text{Model: I \& III} \\ 0 & \text{Model: II \& IV} \end{cases}, \quad (\text{B11})$$

$$e_4 = \alpha \frac{\sqrt{1-V^2}}{V} \frac{\gamma_L^2 A_k}{x \Delta_k^{1/2}} \chi_5 - 2\pi \frac{r_g^2 x^2}{M c_s^2} Q_{\text{rad}} + \begin{cases} 2 \left(\frac{4-3\beta_{\text{gas}}}{1+\beta_{\text{gas}}} \right) \chi_4 x & \text{Model: I \& III} \\ (4-3\beta_{\text{gas}}) \frac{x}{2\Delta_k} \frac{d\Delta_k}{dx} & \text{Model: II \& IV} \end{cases}, \quad (\text{B12})$$

$$\chi_1 = \gamma_L \frac{d}{dx} \left[\frac{x \Delta_k^{1/2}}{A_k^{1/2}} \right] + 2j\ell \frac{d}{dx} \left[\frac{x}{A_k} \right] + \frac{1}{2} \frac{\ell^2 x \Delta_k^{1/2}}{\gamma_L A_k^{1/2}} \frac{d}{dx} \left(\frac{x^2}{A_k} \right), \quad (\text{B13})$$

$$\chi_2 = 1 + \frac{1}{2} \frac{j^2 \epsilon}{\zeta(x) x^4} \frac{x \Delta_k^{1/2}}{A_k^{1/2}} \frac{V^2}{\gamma_L (1-V^2)}, \quad (\text{B14})$$

$$\chi_3 = \frac{1}{2} \frac{\ell - j^2 \epsilon \omega}{\zeta(x) x^4}, \quad (\text{B15})$$

$$\chi_4 = \frac{1}{2\Delta_k} \frac{d\Delta_k}{dx} + \frac{1}{2} \frac{j^2 \epsilon \chi_1}{\zeta(x) x^4} + \frac{2}{x}, \quad (\text{B16})$$

$$\chi_5 = 2j \frac{d}{dx} \left(\frac{x}{A_k} \right) + \frac{\ell}{\gamma_L} \frac{d}{dx} \left(\frac{x^3 \Delta_k^{1/2}}{A_k^{3/2}} \right) - \frac{1}{2} \frac{\ell^3 x^3 \Delta_k^{1/2}}{\gamma_L^3 A_k^{3/2}} \frac{d}{dx} \left(\frac{x^2}{A_k} \right). \quad (\text{B17})$$

APPENDIX C: COMPARISON WITH THE EARLIER MODELS

In this section, we compare our models (Model II and Model IV) with the earlier three models (SA09, (Wen *et al.*) [28,29]). The mass conservation equation [Eq. (A26)] is commonly used among all the models. In the radial-momentum conservation equation, SA09, and Wen *et al.* [28,29] neglect the $1-V^2$ term of the right-hand side of Eq. (A29), while our models include it. In the angular momentum conservation equation, Model II and the model of Wen *et al.* [29] include the radiation-driven angular momentum term [i.e., the second term of the right-hand side of Eq. (A32)], while all the other models drop it. Regarding the energy equation, the value of the radiative cooling rate's coefficient, θ , [see Eq. (A37)] is different between SA09 and the other models; $\theta = 64$ is adopted for our models and Wen *et al.* [28,29], whereas $\theta = 32$ for SA09.

Solving these basic equations numerically, we get the radial profiles of the surface density and other disk quantities for respective models. Figure 14 compares the

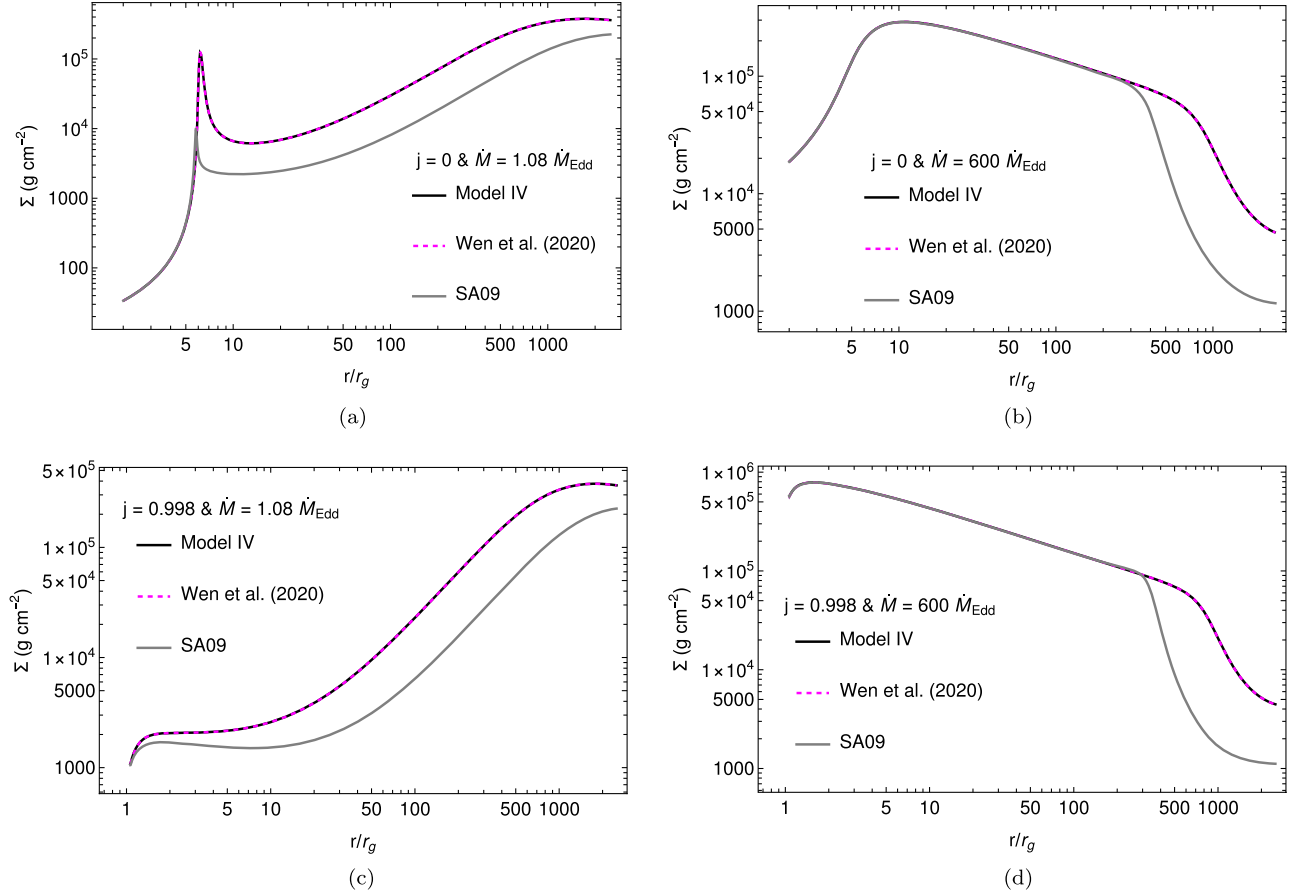


FIG. 14. Comparison of the surface density's radial profiles between Model IV, the model of Wen *et al.* [28], and the SA09 model. Two different mass accretion rates $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ and $\dot{M} = 600\dot{M}_{\text{Edd}}$, and the two different black hole spins $j = 0$ and 0.998 are adopted for each model.

surface density's radial profile of Model IV with those of Wen *et al.* [28] and SA09, whereas Fig. 15 compares the surface density's radial profile of Model II with that of Wen *et al.* [29]. For all the models, we adopt the two different spin parameters $j = 0$ and $j = 0.998$ and the two different mass accretion rates $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ and $600\dot{M}_{\text{Edd}}$. Note again that the three models seen in Fig. 14 include no radiation-driven angular momentum and scale-height derivative terms, whereas the two models appeared in Fig. 15 include only the radiation-driven angular momentum loss.

From Fig. 14, we find that the surface density of Model IV deviates from that of the SA09 model, while Model IV case is overlapped with the surface density profile of Wen *et al.* (2020). These behaviors are independent of the mass accretion rate and black hole spin, and are interpreted by using the simple analytical solutions as follows: Eq. (19) demonstrates that the surface density is proportional to $(\theta/Q_{\text{rad}})^2$, where Q_{rad} is also a function of θ . Adopting $f(x, j) = 1$ and $\zeta(x) = 1/(2x^3)$, corresponding to the nonrelativistic limit, in Eq. (18), Q_{rad} is simply written as

$$Q_{\text{rad}} \approx Q_{\text{vis}} \left[\frac{1}{2} + \sqrt{\frac{1}{4} + \frac{1}{\eta^2} \frac{768}{\theta^2} \left(\frac{\dot{m}}{x}\right)^2} \right]^{-1}, \quad (\text{C1})$$

where $\dot{m} \equiv \dot{M}/\dot{M}_{\text{Edd}}$. This equation shows that Q_{rad} is proportional to θ if $\dot{m}/x \gg 1$, indicating the surface density is independent of θ . This is consistent with the fact that, in the relevant disk region, the radial profiles of the surface density of Model IV is overlapped with those of the SA09 model. However, Q_{rad} is independent of θ if $\dot{m}/x \ll 1$, indicating the surface density is proportional to θ^2 . This produces a significant (roughly factor 4) deviation in the radial profiles of the surface density between Model IV and the SA09 model.

Next, it is found from Fig. 15 that there is no difference in the radial profiles of the surface density between Model II and the model of Wen *et al.* [29], even though there are a few differences in the basic equations between them. This means the $(1 - V^2)$ term of the right-hand side of Eq. (A29) has effectively no impact on the disk structure.

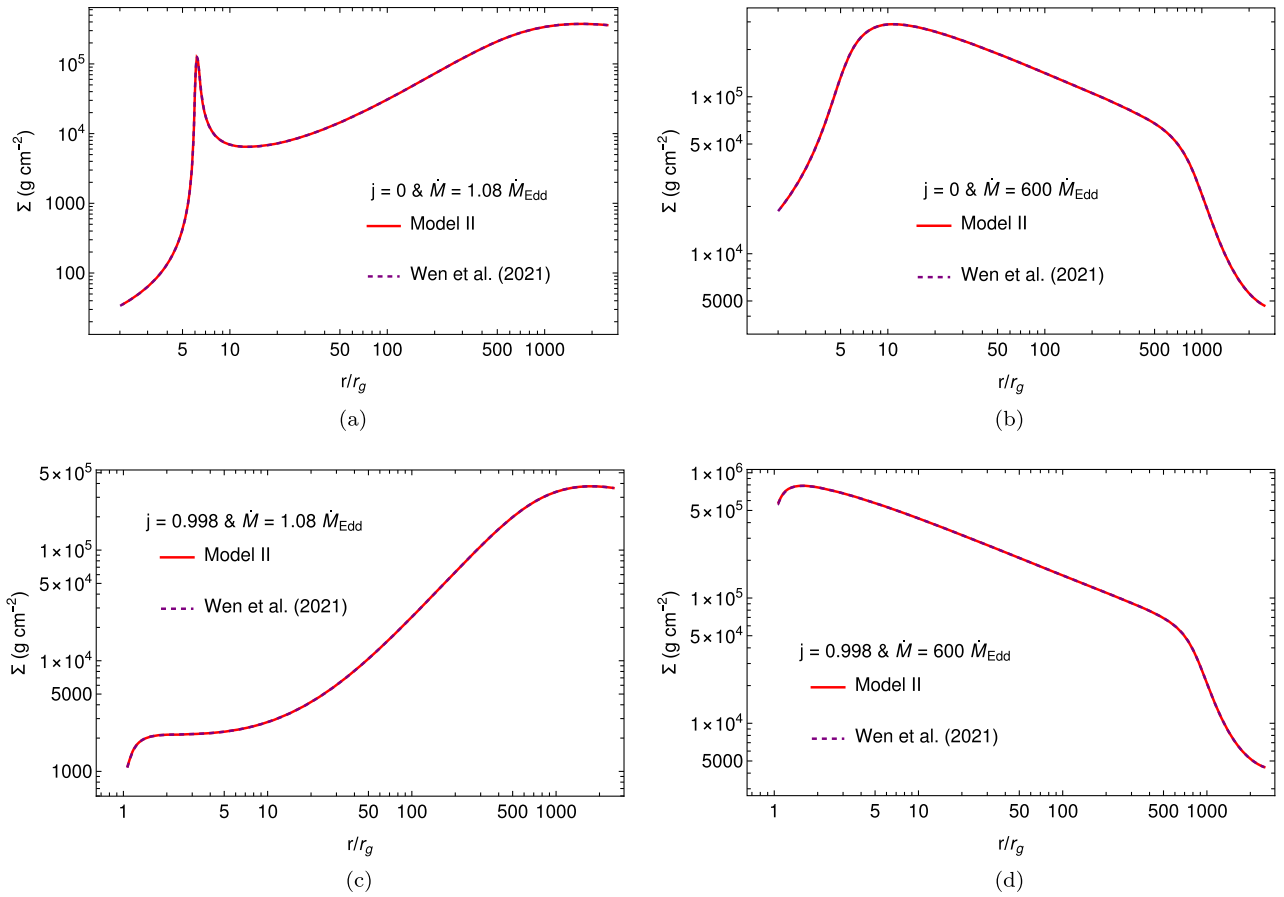


FIG. 15. Comparison of the surface density's radial profiles between Model II and the model of Wen *et al.* [29]. Two different mass accretion rates $\dot{M} = 1.08\dot{M}_{\text{Edd}}$ and $\dot{M} = 600\dot{M}_{\text{Edd}}$, and the two different black hole spins $j = 0$ and 0.998 are adopted for each model.

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