Ghost-free infinite-derivative dilaton gravity in two dimensions

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We present the ghost-free infinite-derivative extensions of the spherically reduced gravity (SRG) and Callan-Giddings-Harvey-Strominger (CGHS) theories in two space-time dimensions. For the case of SRG, we specify the Schwarzschild-type gauge and diagonalize the quadratic action for field perturbations after taking the background fields to be those of the flat-space solution with a linear dilaton. Using the obtained diagonalization, we construct ghost-free infinite-derivative modifications of the SRG theory. In the context of this modified SRG theory we derive a nonlocal modification of the linearized spherically reduced Schwarzschild solution. For the case of CGHS gravity, we work in the conformal gauge and diagonalize the quadratic action associated with this theory for a general background solution. Using these results, we construct the ghost-free infinite-derivative modifications of the CGHS theory and examine nonlocal modifications to the linearized CGHS black-hole solution.

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I. INTRODUCTION

It is well known that the theory of gravity described by the Einstein-Hilbert action together with two-dimensional space-time is topological [1]. This is the result of the fact that, in two dimensions, the space of two-form fields is of dimension one which implies the vanishing of the Einstein tensor [1–3]. Thus, one option to source gravity in two space-time dimensions is to introduce a scalar field, dubbed the dilaton field, coupled to the Ricci scalar. A number of two-dimensional theories involving the dilaton field are then possible (see [4–8] for a review). Among these there is the so-called spherically reduced gravity (SRG) [4,9–18], and Callan-Giddings-Harvey-Strominger (CGHS) gravity [19].

The CGHS theory, which is discussed in the seminal paper [19], has also been studied extensively in [20–35]. The theory admits a black-hole (BH) vacuum solution which was first presented in [36] and subsequently examined further in [37–43]. For discussions on more general dilaton gravity theories, we direct the reader to [4,7,8,44-47].

In the present work, we construct nonlocal modifications to the SRG and CGHS theories of gravity that are ghostfree. One can introduce nonlocality into a given theory by including infinitely many covariant derivatives in the action [48–53]. In particular, one can construct ghost-free infinitederivative modifications of General Relativity; often called infinite derivative gravity (IDG) [54-64]. As discussed in [65,66], there is motivation from *p*-adic string theory for the introduction of nonlocal operators and the first such application of *p*-adic mathematics in string theory appeared when studying scalar tachyon strings. In addition, it was noted in [52,67-71] that certain quantum gravity models are renormalizable through the inclusion of nonlocal operators. The initial-value problem in the context of infinitederivative theories has been studied in [72-77] and the Hamiltonian formulation for nonlocal theories is discussed in [78-83]. Cosmological implications, such as the resolution of cosmological singularities, of IDG are discussed in [50,57,58,84–87]. Studies regarding the resolution of BH singularities through the inclusion of infinitely many derivatives in the action have been conducted in [51,88–90]. In the present work, we shall study the effect of nonlocality in the linearized regime. Linearized solutions in the context of IDG have been studied in [51,53,91–95] and we employ some of these methods in the present work. While we restrict ourselves to the linearized regime, we note that exact

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solutions in the context of IDG have been found in [96–99] whereas in two-dimensional gravity, ghost-free infinitederivative modifications of the Polyakov action have been studied in [100].

This communication is organized as follows: In Sec. II, we begin by considering a generalized dilaton action, defined on a two-dimensional space-time, which generates the SRG and CGHS theories of gravity. There, we shall briefly review this generalized dilaton model and derive the corresponding quadratic action without fixing the gauge. In order to diagonalize such a quadratic action, we shall consider the SRG and CGHS gravity theories separately. Thus, we shall first study the SRG theory in the Schwarzschild-type gauge in Sec. III. Herein, after specifying that gauge, we shall diagonalize the quadratic action in order to construct ghost-free infinite-derivative modifications to the SRG theory. We then construct a source term that can be used to generate the linearized Schwarzschild solution in the context of the local diagonalized theory. Using the same source in the diagonalized nonlocal theory, we obtain a nonlocal modification to the linearized spherically reduced Schwarzschild solution. We will show that the singular nature of the linearized local solution is resolved in the nonlocal theory through the appearance of the error function. This is comparable to the linearized nonlocal Schwarzschild solution of IDG obtained in [51] where the singular nature is also resolved by the error function.

In Sec. IV, we shall turn our attention to the CGHS theory. In this case, we shall resort to the conformal gauge and review the well known CGHS BH solution in this gauge. The corresponding quadratic action is then diagonalized for a general background solution in order to construct ghost-free infinite-derivative modifications to the CGHS theory. Accordingly we shall introduce a source term that generates the CGHS BH solution of the local theory in the linearized regime. Using the aforementioned source term together with the nonlocal theory, we shall examine how the linearized solution is modified as a result of introducing nonlocality. We will show that the singular nature appearing in the linearized local solution is resolved in the nonlocal theory through the appearance of the complementary error function.

We shall end up with Sec. V which encapsulates the conclusions of this investigation.

II. LOCAL TWO-DIMENSIONAL DILATON GRAVITY

A. Action and quadratic action

Let us consider the following dilaton action in twodimensional space-time:

$$S_{\text{local}} := 4 \int d^2 x \sqrt{-g} \left[\frac{R}{4} + k(\partial \phi)^2 + \lambda^2 + \frac{a^2}{2} e^{2\phi} \right] e^{-2\phi}, \quad (2.1)$$

TABLE I. Parameter specifications that, upon substitution into the action (2.2), generate either the SRG or CGHS theories.

	k	λ	а
SRG	1/2	0	а
CGHS	1	λ	0

where $g_{\mu\nu}$ is the metric tensor, *R* is the Ricci scalar, ϕ is the dilaton field, and *k*, λ and *a* are constants [4,7]. We note that both λ and *a* have dimensions of length⁻¹ while *k* is dimensionless. By defining the field $\Phi := e^{-\phi}$, this action (2.1) can be written as

$$S_{\text{local}} = 4 \int d^2 x \sqrt{-g} \left[\frac{\Phi^2 R}{4} + k(\partial \Phi)^2 + \Phi^2 \lambda^2 + \frac{a^2}{2} \right]. \quad (2.2)$$

This generalized action describes a number of dilaton gravity theories. In particular, by setting $\lambda = 0$, k = 1/2 and leaving *a* unspecified, the action (2.2) is that of SRG [4,9–12]. The case where k = 1, a = 0, and leaving λ unspecified corresponds to the vacuum CGHS theory [19]. Table I lists these two theories and their corresponding parameter specifications. Although not examined in this communication, the case where a = 0, k = 0 and leaving λ unspecified is the so-called Jackiw-Teitelboim gravity theory [101,102]. In addition, there are more general dilaton gravity actions which are discussed in [4], however, in this paper the only dilaton gravity models that we consider are the SRG and CGHS theories.

In order to state the definition for the quadratic action, we first perform perturbations of the metric and dilaton field as

$$g_{\mu\nu} = \bar{g}_{\mu\nu} + \delta g_{\mu\nu}, \qquad \Phi = \bar{\Phi} + \delta \Phi, \qquad (2.3)$$

where $(\bar{g}_{\mu\nu}, \bar{\Phi})$ is a solution to the equations of motion and $\delta g_{\mu\nu}$ and $\delta \Phi$ are the perturbed metric and perturbed dilaton field respectively. We also require that the perturbed dilaton field satisfies

$$|\delta\Phi| \ll |\bar{\Phi}|, \tag{2.4}$$

and that the curvature scale of the metric perturbations be much smaller than that of the background metric in order for our approximations to be valid. These conditions placed on the perturbed dilaton are referred to as the smallness conditions. In this paper, we make use of the following definition for the *quadratic action*:

$$\begin{split} \delta^{2}S_{\text{local}} &\coloneqq \int d^{2}x d^{2}x' \left[\delta \Phi(x) \delta \Phi(x') \frac{\delta^{2}S_{\text{local}}}{\delta \Phi(x) \delta \Phi(x')} \right|_{(\bar{g}_{\mu\nu}, \bar{\Phi})} \\ &+ \delta \Phi(x) \delta g^{\mu\nu}(x') \frac{\delta^{2}S_{\text{local}}}{\delta \Phi(x) \delta g^{\mu\nu}(x')} \right|_{(\bar{g}_{\mu\nu}, \bar{\Phi})} \\ &+ \delta g^{\mu\nu}(x) \delta \Phi(x') \frac{\delta^{2}S_{\text{local}}}{\delta g^{\mu\nu}(x) \delta \Phi(x')} \right|_{(\bar{g}_{\mu\nu}, \bar{\Phi})} \\ &+ \delta g^{\mu\nu}(x) \delta g^{\alpha\beta}(x') \frac{\delta^{2}S_{\text{local}}}{\delta g^{\mu\nu}(x) \delta g^{\alpha\beta}(x')} \right|_{(\bar{g}_{\mu\nu}, \bar{\Phi})} \Big], \quad (2.5)$$

whose variation with respect to the fields gives the field equations for the perturbations at first order.

Using the previous definition, we now wish to derive the quadratic action associated with (2.2). Indeed, through the variation of (2.2), one can obtain

$$\delta S_{\text{local}} = -2 \int d^2 x \sqrt{-g} g_{\mu\nu} \delta g^{\mu\nu} \left[\frac{1}{4} \Phi^2 R + k (\partial \Phi)^2 \right] \\ + \Phi^2 \lambda^2 + \frac{a^2}{2} + 4 \int d^2 x \sqrt{-g} \left[\frac{1}{2} \Phi \delta \Phi R \right] \\ + \frac{\Phi^2}{4} (R_{\mu\nu} \delta g^{\mu\nu} - \nabla_\mu \nabla_\nu \delta g^{\mu\nu} + g_{\mu\nu} \Box \delta g^{\mu\nu}) \\ + k \delta g^{\mu\nu} \partial_\mu \Phi \partial_\nu \Phi + 2k \partial^\nu \Phi \partial_\nu \delta \Phi + 2\Phi \delta \Phi \lambda^2 \right]. \quad (2.6)$$

This expression (2.6) would allow us to compute the firstorder functional derivatives of the action. The functional derivative with respect to the dilaton field Φ is

$$\frac{\delta S_{\text{local}}}{\delta \Phi} = 4\sqrt{-g} \left[\frac{1}{2} \Phi R - 2k \Box \Phi + 2\Phi \lambda^2 \right], \quad (2.7)$$

whereas the functional derivative of the action with respect to the inverse metric $g^{\mu\nu}$ is

$$\begin{aligned} \frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}} &= -2\sqrt{-g}g_{\mu\nu} \left[k(\partial\Phi)^2 + \Phi^2\lambda^2 + \frac{a^2}{2} \right] \\ &+ \sqrt{-g}[g_{\mu\nu}\Box\Phi^2 - \nabla_{\mu}\nabla_{\nu}\Phi^2 + 4k\partial_{\mu}\Phi\partial_{\nu}\Phi], \end{aligned}$$
(2.8)

where in the three previous expressions $\Box := g^{\mu\nu} \nabla_{\mu} \nabla_{\nu}$ is the usual space-time covariant d'Alembertian operator and ∇_{μ} is the Levi-Civita covariant derivative. Also note that in obtaining (2.8) we have made use of the fact that the Einstein tensor vanishes identically in two dimensions, i.e., $R_{\mu\nu} = \frac{1}{2} R g_{\mu\nu}$. This results in the Ricci tensor not appearing in (2.8). It is worth mentioning that the trace of (2.8) renders

$$g^{\mu\nu}\frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}} = \sqrt{-g} \left[\Box \Phi^2 - 4\left(\Phi^2 \lambda^2 + \frac{a^2}{2}\right) \right].$$
(2.9)

Thus, the relevant equations of motion are obtained by setting expressions (2.7) and (2.8) equal to zero.

On the other hand, by computing the second-order functional derivatives associated with the action (2.2), we can use the definition (2.5) in order to arrive at the quadratic action

$$\begin{split} \delta^{2}S_{\text{local}} &= \int d^{2}x \sqrt{-\bar{g}} \bigg\{ 8k\delta \Phi \bigg(\frac{\bar{\Box}}{\bar{\Phi}} - \bar{\Box} \bigg) \delta \Phi + 4\delta g^{\mu\nu} \bigg[\frac{1}{2} \bar{R} \bar{g}_{\mu\nu} \bar{\Phi} \delta \Phi + (\bar{g}_{\mu\nu} \bar{\Box} - \bar{\nabla}_{\mu} \bar{\nabla}_{\nu}) (\bar{\Phi} \delta \Phi) \\ &+ 4k\partial_{\mu} \bar{\Phi} \partial_{\nu} \delta \Phi - (1+k) \bar{g}_{\mu\nu} \bar{\nabla}_{\alpha} (\delta \Phi \partial^{\alpha} \bar{\Phi}) + (1-k) \bar{g}_{\mu\nu} \delta \Phi \bar{\Box} \bar{\Phi} \bigg] \\ &+ \delta g^{\mu\nu} \bigg[\bar{g}_{\mu\alpha} (4k\partial_{\beta} \bar{\Phi} \partial_{\nu} \bar{\Phi} - \bar{\nabla}_{\nu} \bar{\nabla}_{\beta} \bar{\Phi}^{2}) + \bar{g}_{\mu\nu} \bar{\nabla}_{\alpha} \bar{\Phi}^{2} \bar{\nabla}_{\beta} - \bar{g}_{\mu[\nu} \bar{g}_{\alpha]\beta} \bar{\nabla}^{\sigma} \bar{\Phi}^{2} \bar{\nabla}_{\sigma} - \bar{g}_{\beta\mu} \bar{\nabla}_{\alpha} \bar{\Phi}^{2} \bar{\nabla}_{\nu} \bigg] \delta g^{\alpha\beta} \bigg\}, \quad (2.10) \end{split}$$

whose derivation can be found in Appendix A where the functional derivatives (2.7) and (2.8) are used.

Equation (2.10) is the quadratic action associated with the general dilaton model (2.2) without any gauge fixing. In addition, this quadratic action is valid for a general background solution $(\bar{g}_{\mu\nu}, \bar{\Phi})$ provided that the smallness conditions stated in (2.4) are satisfied. In Secs. III and IV we shall consider the SRG and CGHS theories independently. For each of those two theories, we shall diagonalize the quadratic action after a gauge fixing. Before proceeding, we wish to make a note on the gauge fixing of the action (2.2). In this work, we will either specify the so-called conformal gauge or the Schwarzschild-type gauge [4] which are defined in later sections. In both cases, the gauge-fixed action contains all the dynamics of the original action (2.2). That is, one obtains the same dynamical equations of motion regardless of whether one fixes the gauge at the level of the action or at the level of the field equations. The constraint equations, on the other hand, appear as a result of specifying a gauge. In Appendixes B 1 and B 2 we show this explicitly for both choices of gauges. For a more elaborate treatment of gauge fixing in the context of two-dimensional dilaton gravity models, the interested reader is directed to [103,104].

B. Symmetries of the dilaton action

Let us briefly examine the redundancies present in the gravitational theories generated by (2.2) (for a detailed discussion, the interested reader is directed to [1,3,105]). The metric tensor and dilaton field contribute three and one degrees of freedom respectively. The action (2.2) admits diffeomorphism invariance contributing two redundancies. Given these two redundancies, after a gauge fixing, one can write the action (2.2) as a functional of two scalar fields: one scalar field describing the dilaton and the other describing the metric. In the case of the SRG theory, i.e., when we set $\lambda = 0$ and k = 1/2, this leaves us with two propagating scalar fields. In the case of the CGHS theory, i.e., when a = 0 and k = 1, there is one additional symmetry described by the following transformation:

$$\delta g^{\mu\nu} = \frac{2\varepsilon g^{\mu\nu}}{\Phi^2}, \qquad \delta \Phi = \frac{\varepsilon}{\Phi}, \qquad (2.11)$$

where $\varepsilon \in \mathbb{R}$ is a constant. We will return to this symmetry in Sec. IV where the CGHS theory is discussed separately.

C. Source action

When studying the SRG and CGHS theories in the linearized regime, we will introduce some source action in addition to the geometric, either local or nonlocal, action. The purpose of introducing such a source action is to generate solutions for the local theories that satisfy the following two properties:

- (i) the local solutions are singular when considering the entire space-time;
- (ii) the local solutions coincide with the BH solution of the relevant theory in the space-time region for which the smallness conditions are satisfied.

Once we have identified a source action accomplishing the two properties above in the local theory, we will make use of the same source action when studying the nonlocal theory. In particular, we shall be interested in examining how the singular nature is resolved as a result of nonlocality as well as how the local BH solutions of the SRG and CGHS theories are modified in the region for which the smallness conditions are satisfied. A similar analysis is done for the case of four-dimensional IDG in [51] where a nonlocal modification to the linearized Schwarzschild solution of GR is obtained.

For our purposes, we consider a source action of the form

$$S_{\text{source}} = 4 \int d^2 x \sqrt{-g} U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi}), \qquad (2.12)$$

where $U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})$ is some function of the dilaton field Φ and the background solution $(\bar{g}_{\mu\nu}, \bar{\Phi})$ to the field equations when U = 0. Thus the total action under consideration would be

$$S_{\text{total}} \coloneqq S_{\text{local}} + S_{\text{source}},$$
 (2.13)

where the local action S_{local} and the source action S_{source} are given by (2.2) and (2.12) respectively. From the definition given in [106], the stress-energy tensor is

$$T_{\mu\nu} \coloneqq \frac{1}{\sqrt{-g}} \frac{\delta S_{\text{total}}}{\delta g^{\mu\nu}}$$
$$= -2g_{\mu\nu} \left[k(\partial \Phi)^2 + \Phi^2 \lambda^2 + \frac{a^2}{2} + U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi}) \right]$$
$$+ g_{\mu\nu} \Box \Phi^2 - \nabla_{\mu} \nabla_{\nu} \Phi^2 + 4k \partial_{\mu} \Phi \partial_{\nu} \Phi, \qquad (2.14)$$

where we made use of Eq. (2.8). In addition, by making use of Eq. (2.7) and varying the source action with respect to Φ one can obtain

$$\frac{\delta S_{\text{total}}}{\delta \Phi} = 4\sqrt{-g} \bigg[\frac{\Phi R}{2} - 2k\Box \Phi + 2\Phi\lambda^2 + \frac{\partial U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})}{\partial \Phi} \bigg].$$
(2.15)

To examine whether the stress-energy tensor (2.14) is conserved, we take the divergence and write

$$\nabla^{\mu}T_{\mu\nu} = -\Box\nabla_{\nu}\Phi^{2} + \nabla_{\nu}\Box\Phi^{2}$$
$$-2\left[2\Phi\lambda^{2} + \frac{\partial U(\Phi,\bar{g}_{\mu\nu},\bar{\Phi})}{\partial\Phi} + 2k\Box\Phi\right]\partial_{\nu}\Phi. \quad (2.16)$$

From the definition of the Riemann tensor, the first two terms on the right-hand side can be written as

$$-\Box \nabla_{\nu} \Phi^2 + \nabla_{\nu} \Box \Phi^2 = -R^{\mu}_{\nu} \nabla_{\mu} \Phi^2. \qquad (2.17)$$

Since the Einstein tensor is identically zero in two spacetime dimensions, i.e., $R_{\mu\nu} = \frac{1}{2}Rg_{\mu\nu}$, we have

$$\nabla^{\mu}T_{\mu\nu} = -2\left[\frac{1}{2}R\Phi + 2\Phi\lambda^{2} + \frac{\partial U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})}{\partial\Phi} - 2k\Box\Phi\right]\partial_{\nu}\Phi. \quad (2.18)$$

The right-hand side of the last expression can be identified with the right-hand side of Eq. (2.15) which implies that the divergence of the stress-energy tensor is

$$\nabla^{\mu}T_{\mu\nu} = -\frac{\partial_{\nu}\Phi}{2\sqrt{-g}}\frac{\delta S_{\text{total}}}{\delta\Phi}.$$
 (2.19)

As mentioned in [106], this implies that the stress-energy tensor is conserved whenever the dilaton equation of motion associated with S_{total} is satisfied. Although additional properties of the stress-energy tensor are studied in [106], we do not discuss the topic further here and

instead direct the interested reader to the aforesaid reference.

In this work, we are interested in considering potentials $U(\Phi, \bar{g}_{uv}, \bar{\Phi})$ of the form

$$U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi}) = -\frac{\Phi^2 \bar{g}^{\mu\nu} A_{\mu\nu}}{2(a\bar{\Phi} - 4\lambda\bar{\Phi}^2)}, \qquad (2.20)$$

where $A_{\mu\nu}$ contains a Dirac delta function. Our motivation for taking the potential $U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})$ to be of the form given in (2.20) is that, for an appropriate choice of $A_{\mu\nu}$, this potential satisfies both properties (i) and (ii) for SRG and CGHS gravity. We will show this explicitly in Secs. III and IV for the SRG and CGHS theories respectively. When generating linearized solutions in these theories, we will be interested in obtaining static solutions perturbed around a flat space-time. To this end, we will take the background metric to be the Minkowski metric in Cartesian coordinates (t, r), i.e., $\bar{g}_{\mu\nu} = \eta_{\mu\nu} := \text{diag}(-1, 1)$. In this context, we will take $A_{\mu\nu}$ to be of the form

$$A_{\mu\nu} = M(\eta_{\mu\nu} + \delta_{\mu\nu})\delta'(r-b), \qquad (2.21)$$

where $\delta_{\mu\nu} := \text{diag}(1, 1), M \in \mathbb{R}$ is a constant of dimension length⁻¹, $b \in \mathbb{R}$ is a constant describing the position of the source and the prime ' denotes differentiation with respect to r. We will show that this choice for $A_{\mu\nu}$ can be used to generate the linearized BH solutions of the local SRG and CGHS theories with the parameter M coinciding with the BH mass.

As a concluding remark about the source action defined here, we wish to examine whether the latter is invariant under the symmetry transformation (2.11). While Eq. (2.12) yields a stress-energy tensor that is conserved when the dilaton equation of motion is satisfied, there is no guarantee that the transformation (2.11), which is a symmetry of the CGHS theory, will leave the source action invariant for a general $U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})$. However, for the specific case where the potential is of the form (2.20), the source action is invariant under the transformation (2.11). This will be shown in Sec. IV when we consider the CGHS theory independently.

Having now stated the source action to be used, we wish to examine the total action (2.13) at quadratic order. By expanding the total action to quadratic order in both $\delta g_{\mu\nu}$ and $\delta \Phi$ around the U = 0 background solution $(\bar{g}_{\mu\nu}, \bar{\Phi})$, one has

$$S_{\text{total}} \approx S_{\text{local}}[\bar{g}_{\mu\nu}, \bar{\Phi}] + S_{\text{source}}[\bar{g}_{\mu\nu}, \bar{\Phi}] + \delta S_{\text{local}}[\bar{g}_{\mu\nu}, \bar{\Phi}] + \delta S_{\text{source}}[\bar{g}_{\mu\nu}, \bar{\Phi}, \delta g^{\mu\nu}, \delta \Phi] + \frac{1}{2} \delta^2 S_{\text{local}}[\bar{g}_{\mu\nu}, \bar{\Phi}, \delta g^{\mu\nu}, \delta \Phi] + \frac{1}{2} \delta^2 S_{\text{source}}[\bar{g}_{\mu\nu}, \bar{\Phi}, \delta g^{\mu\nu}, \delta \Phi].$$
(2.22)

The first two terms on the right-hand side of (2.22) are constant with respect to functional differentiation while the third term is zero since $\bar{g}_{\mu\nu}$ and $\bar{\Phi}$ satisfy the vacuum equations of motion. In addition, the source action is of the order of the perturbations, i.e., $S_{\text{source}} \sim \mathcal{O}(\delta g_{\mu\nu}) + \mathcal{O}(\delta \Phi)$. Therefore, at quadratic order, we can safely ignore the last term on the right-hand side of (2.22). It follows that the quadratic part of the total action is

$$S^{2}S_{\text{total}} \coloneqq \delta S_{\text{source}}[\bar{g}_{\mu\nu}, \bar{\Phi}, \delta g^{\mu\nu}, \delta \Phi] + \frac{1}{2} \delta^{2} S_{\text{local}}[\bar{g}_{\mu\nu}, \bar{\Phi}, \delta g^{\mu\nu}, \delta \Phi]. \quad (2.23)$$

It is important to note that the expansion in (2.22) is valid provided that the smallness condition (2.4) is satisfied.

III. SRG GRAVITY

In this section, we consider the SRG theory which is described by the action (2.2) with k = 1/2, $\lambda = 0$ and *a* left unspecified. As already mentioned, there are two redundancies present in Eq. (2.2) as a result of diffeomorphism invariance. We can remove these two redundancies by specifying the Schwarzschild-type gauge. In this choice of gauge, a generic metric can be written in the form [4]

$$ds^{2} = -f(r,t)dt^{2} + \frac{dr^{2}}{f(r,t)}.$$
 (3.1)

The SRG theory, which is obtained through the spherical reduction of four-dimensional GR, admits the solution described by

$$f = 1 - \frac{2M}{a^2 r},\tag{3.2}$$

whereas the dilaton field is given by

$$\Phi = ar. \tag{3.3}$$

The parameter M in Eq. (3.2) is the ADM mass¹ and has dimensions of length⁻¹. In this note, we refer to this solution as the *spherically reduced Schwarzschild solution* [4]. It is important to note that the flat-space solution, i.e., when M = 0, corresponds to the Minkowski metric with f = 1 while the dilaton remains $\Phi = ar$. The modification of the Schwarzschild solution in the context of IDG is well known and has been obtained in the linearized regime in [51]. Here we construct a ghost-free infinite-derivative modification of SRG and examine how the linearized

¹When performing the spherical reduction of the Einstein-Hilbert action of four-dimensional GR, the resulting action is given by (2.2) with k = 1/2, $\lambda = 0$ and a prefactor proportional to $1/a^2$ which we have dropped. When taking this prefactor into account, the ADM mass is then rescaled to M/a^2 which has dimensions of length and coincides with the mass of the Schwarzschild solution of GR [4].

spherically reduced Schwarzschild solution is modified. In order to construct a ghost-free infinite-derivative modification of SRG, we first have to diagonalize the local quadratic action (2.10).

A. Local SRG gravity

After specifying the Schwarzschild-type gauge (3.1), we can perturb the metric around the Minkowski solution by writing $f = 1 + \delta f$ and expanding the metric to first order in δf . In the perturbation, the background metric is $\bar{g}_{\mu\nu} = \eta_{\mu\nu}$ while the perturbed metric is $\delta g^{\mu\nu} = \delta^{\mu\nu} \delta f$. In addition, we take the background dilaton field to be $\bar{\Phi} = ar$. With these specifications, the quadratic action (2.10) simplifies considerably to

$$\delta^2 S_{\text{local}}^{\text{SRG}} = 4 \int d^2 x (\partial_\mu \delta \Phi \partial^\mu \delta \Phi - \delta^{\mu\nu} \delta f \bar{\Phi} \partial_\mu \partial_\nu \delta \Phi), \quad (3.4)$$

where we lower and raise indices using the Minkowski metric $\eta_{\mu\nu}$. For a derivation of (3.4), the interested reader is directed to Appendix C. While the quadratic action (3.4) contains all the dynamics, we also have the Schwarzschild-type gauge constraint equations

$$f\partial_r^2 \Phi^2 - \frac{1}{f}\partial_t^2 \Phi^2 + f'\partial_r \Phi^2 + \frac{\dot{f}\partial_t \Phi^2}{f^2} - 2a^2 = 0, \quad (3.5)$$

and

$$\partial_t \partial_r \Phi^2 - \frac{f' \partial_t \Phi^2}{2f} + \frac{\dot{f} \partial_r \Phi^2}{2f} - 2\dot{\Phi}\Phi' = 0.$$
(3.6)

For a derivation of these constraint equations, the interested reader is directed to Appendix B 2.

In order to diagonalize the quadratic action (3.4), we can factorize the integrand and obtain

$$\delta^{2} S_{\text{local}}^{\text{SRG}} = 4 \int d^{2}x \left\{ \left[\partial^{\mu} \delta \Phi + \frac{1}{2} \delta^{\mu\nu} \partial_{\nu} (\bar{\Phi} \delta f) \right]^{2} + \frac{1}{4} \bar{\Phi} \delta f \bar{\Box} (\bar{\Phi} \delta f) \right\},$$
(3.7)

where the background d'Alembertian is now $\overline{\Box} = \eta^{\mu\nu} \partial_{\mu} \partial_{\nu}$. Given this form of the quadratic action, it is convenient to carry out a redefinition of fields with

$$\delta N \coloneqq \frac{1}{2} \bar{\Phi} \delta f, \qquad (3.8)$$

and

$$\delta V^{\mu\nu} \coloneqq \eta^{\mu\nu} \delta \Phi + \delta^{\mu\nu} \delta N. \tag{3.9}$$

In terms of these redefined fields, (3.7) can be written as

$$\delta^2 S_{\text{local}}^{\text{SRG}} = 4 \int d^2 x (\delta N \bar{\Box} \delta N - \delta V^{\nu}{}_{\mu} \partial_{\nu} \partial_{\alpha} \delta V^{\mu \alpha}), \quad (3.10)$$

which corresponds to the diagonalized quadratic action associated with SRG in the Schwarzschild-type gauge with the background solution taken to be $(\bar{g}_{\mu\nu}, \bar{\Phi}) = (\eta_{\mu\nu}, ar)$.

Having derived the diagonalized quadratic action for the SRG theory, we turn our attention to solving the linearized theory, provided the source action and $U(\Phi, \bar{g}_{\mu\nu}, \bar{\Phi})$ are given by (2.12) and (2.20), respectively. To accomplish this, let us examine (2.12) in the Schwarzschild-type gauge with $\bar{g}^{\mu\nu} = \eta^{\mu\nu}$. Under such a consideration, expression (2.12) yields

$$S_{\text{source}}^{\text{SRG}} = -2 \int d^2 x \frac{\Phi^2 \eta^{\mu\nu} A_{\mu\nu}}{a\bar{\Phi}}.$$
 (3.11)

We remind the reader that, by definition, we set $\lambda = 0$ in the SRG theory. By varying the source action above and evaluating the result at the background fields we find

$$\delta S_{\text{source}}^{\text{SRG}} = -\frac{4}{a} \int d^2 x \delta \Phi \eta^{\mu\nu} A_{\mu\nu}, \qquad (3.12)$$

which, in terms of the redefined fields δN and $\delta V^{\mu\nu}$, becomes

$$\delta S_{\text{source}}^{\text{SRG}} = -\frac{4}{a} \int d^2 x (\delta V^{\mu\nu} - \delta^{\mu\nu} \delta N) A_{\mu\nu}, \qquad (3.13)$$

where we have made use of the definitions (3.8) and (3.9). Accordingly, we can now write down the total quadratic action by substituting (3.10) and (3.13) into (2.23) which renders

$$\delta^2 S_{\text{total}}^{\text{SRG}} = 2 \int d^2 x \left[\delta N \bar{\Box} \delta N - \delta V^{\nu}{}_{\mu} \partial_{\nu} \partial_{\alpha} \delta V^{\mu \alpha} - \frac{2}{a} (\delta V^{\mu \nu} - \delta^{\mu \nu} \delta N) A_{\mu \nu} \right].$$
(3.14)

Let us now consider the equations of motion for the perturbations $\delta V^{\mu\nu}$ and δN . Variation of the quadratic action (3.14) with respect to δN , gives us

$$\bar{\Box}\delta N = -\frac{1}{a}\delta^{\mu\nu}A_{\mu\nu}.$$
(3.15)

As already mentioned, the purpose of introducing the source action S_{source} is to generate the linearized spherically reduced Schwarzschild solution given by Eqs. (3.2) and (3.3) provided the smallness condition (2.4) is satisfied. We will now show that this choice of a source action allows us to obtain the linearized spherically reduced Schwarzschild solution. In addition, since the linearized spherically reduced Schwarzschild solution is singular at r = 0, we

consider the case where b = 0 in Eq. (2.21). By substituting Eqs. (3.8) and (2.21) into Eq. (3.15) and taking b = 0, we obtain

$$\Delta(\bar{\Phi}\delta f) = -\frac{4M}{a}\delta'(r), \qquad (3.16)$$

where the Laplacian is $\Delta := \partial_r^2$. We now proceed to solve this equation for the perturbed metric δf by resorting to its Fourier transform, \mathcal{F} . Thus,

$$k^{2}\mathcal{F}\{\bar{\Phi}\delta f\} = \frac{4M}{\sqrt{2\pi a^{2}}} \int \mathrm{d}r \mathrm{e}^{-ikr}\delta'(r). \qquad (3.17)$$

Integrating by parts and dividing the resulting expression by k^2 yields the following solution in Fourier space

$$\mathcal{F}\{\bar{\Phi}\delta f\} = \frac{4iM}{ak\sqrt{2\pi}}.$$
(3.18)

Implementing the inverse Fourier transform on the last expressions results in

$$\bar{\Phi}\delta f = -\frac{2M}{\pi i a} \int \mathrm{d}k \frac{\mathrm{e}^{ikr}}{k}.$$
 (3.19)

The integral returns a value of $i\pi$ for r > 0 while returning $-i\pi$ for r < 0. By dividing both sides by $\overline{\Phi} = ar$ we obtain the solution

$$\delta f = -\frac{2M}{a^2|r|}.\tag{3.20}$$

It now remains to compute the perturbed dilaton field. Through the variation of Eq. (3.14) with respect to $\delta V^{\mu\nu}$ one can obtain

$$\partial^{\alpha}\partial_{(\mu}\delta V_{\nu)\alpha} = -\frac{1}{a}A_{\mu\nu}.$$
 (3.21)

Substituting the definition (3.9) into the above gives

$$\partial_{\mu}\partial_{\nu}\delta\Phi + \delta_{\alpha(\mu}\partial_{\nu)}\partial^{\alpha}\delta N = -\frac{1}{a}A_{\mu\nu}.$$
 (3.22)

By seeking static solutions and making use of Eq. (3.15), the last expression reduces to

$$\Delta\delta\Phi = 0, \quad \Rightarrow \quad \delta\Phi = c_1 r + c_2, \qquad (3.23)$$

where c_1 and c_2 are constants of integration. By invoking the constraint Eq. (3.5), we find that $c_2 = 0$. On the other hand, through an appropriate coordinate transformation, one can show that the parameter c_1 simply results in a constant rescaling of the metric. Therefore, without the loss of generality, we can safely set $c_1 = 0$. The perturbed dilaton is then $\delta \Phi = 0$. We also note that the second constraint equation (3.6) is satisfied since the solution is static.

Let us now examine this solution in the space-time region for which the smallness conditions are satisfied. Since $\delta \Phi = 0$, Eq. (2.4) is satisfied and we need only consider the perturbed metric δf . The smallness condition for the perturbed metric is $|\delta f| \ll 1$. For the solution (3.20), the smallness condition is satisfied whenever $|r| \gg 2M/a^2$. Consequently for $r \gg 2M/a^2$, the metric takes the form

$$\mathrm{d}s^2 \approx -\left(1 - \frac{2M}{a^2 r}\right)\mathrm{d}t^2 + \left(1 + \frac{2M}{a^2 r}\right)\mathrm{d}r^2,\qquad(3.24)$$

which is indeed the linearized spherically reduced Schwarzschild solution.

We have thus shown that the source action (3.13) can be used to generate the linearized spherically reduced Schwarzschild solution in the context of the diagonalized theory provided the smallness conditions hold. In the following subsection, we construct a nonlocal modification to the SRG theory and use the same source action to determine if the solution (3.20) is modified.

B. Ghost-free infinite-derivative SRG gravity

The diagonalized quadratic action (3.10) of the local SRG theory implies that its nonlocal modification does not admit any additional degrees of freedom if its quadratic action is of the form

$$\delta^2 S_{\text{nonlocal}}^{\text{SRG}} = 4 \int d^2 x [\delta N a(\bar{\Box}) \bar{\Box} \delta N^{\mu\nu} - \delta V^{\nu}_{\mu} c(\bar{\Box}) \partial_{\nu} \partial_{\alpha} \delta V^{\alpha\mu}], \qquad (3.25)$$

where $a(\overline{\Box})$ and $c(\overline{\Box})$ contain infinitely many derivatives and are analytic with no zeros. It is through these infinitederivative operators that nonlocality is introduced. By making use of this nonlocal quadratic action, we wish to study how the local solution (3.20) would be modified. To study this we consider the case where $a(\overline{\Box}) = c(\overline{\Box}) =$ $e^{-\ell^2 \overline{\Box}}$ and $\ell \ge 0$ is the *length scale of nonlocality*.

The nonlocal analog of Eq. (3.14) can be obtained by replacing the local quadratic action $\delta^2 S_{\text{local}}$ with the non-local quadratic action $\delta^2 S_{\text{nonlocal}}$ given in Eq. (3.25). By making this substitution, we have

$$\delta^2 S_{\text{total}}^{\text{SRG}} = 2 \int d^2 x \left[\delta N a(\bar{\Box}) \bar{\Box} \delta N - \delta V^{\nu}{}_{\mu} c(\bar{\Box}) \partial_{\nu} \partial_{\alpha} \delta V^{\alpha \mu} - \frac{2}{a} (\delta V^{\mu \nu} - \delta^{\mu \nu} \delta N) A_{\mu \nu} \right].$$
(3.26)

Through the variation of this total quadratic action (3.26) with respect to δN , we find the following nonlocal analog to Eq. (3.15)

$$e^{-\ell^2 \bar{\Box}} \bar{\Box} \delta N = -\frac{1}{a} \delta^{\mu\nu} A_{\mu\nu}, \qquad (3.27)$$

after choosing $a(\overline{\Box}) = e^{-\ell^2 \overline{\Box}}$. Upon the substitution of the definitions (3.8) and (2.21) with b = 0 into the last expression, we find

$$e^{-\ell^2 \Delta} \Delta(\bar{\Phi} \delta f) = -\frac{4M}{a} \delta'(r), \qquad (3.28)$$

which holds for static solutions. We can solve this equation of motion by first implementing the Fourier transform, dividing the resulting expression by $k^2 e^{\ell^2 k^2}$ and then applying the inverse Fourier transform. By doing this, we find the nonlocal analog of Eq. (3.19)

$$\bar{\Phi}\delta f = -\frac{2M}{i\pi a} \int \mathrm{d}k \frac{\mathrm{e}^{ikr-\ell^2 k^2}}{k}.$$
 (3.29)

We can write this integral as

$$\bar{\Phi}\delta f = -\frac{2M}{a\pi} \int_{-\infty}^{\infty} dk e^{-\ell^2 k^2} \int_{0}^{r} du e^{iku}$$
$$= -\frac{2M}{a\pi} \int_{0}^{r} du \int_{-\infty}^{\infty} dk e^{-\ell^2 (k - \frac{iu}{2\ell^2})^2 - \frac{u^2}{4\ell^2}}.$$
 (3.30)

Evaluating it over k yields

$$\bar{\Phi}\delta f = -\frac{2M}{a\ell\sqrt{\pi}} \int_0^r \mathrm{d}u \mathrm{e}^{-\frac{u^2}{4\ell^2}}.$$
 (3.31)

Performing the change of variables $v = u/2\ell$ gives us

$$\bar{\Phi}\delta f = -\frac{4M}{a\sqrt{\pi}} \int_0^{r/2\ell} \mathrm{d}v \mathrm{e}^{-v^2}, \qquad (3.32)$$

where the integral above is nothing more than the error function $\frac{\sqrt{\pi}}{2}$ Erf $(r/2\ell)$. Dividing both sides by the background dilaton field $\bar{\Phi} = ar$, we find the nonlocal modification to (3.20),

$$\delta f = -\frac{2M}{a^2 r} \operatorname{Erf}\left(\frac{r}{2\ell}\right). \tag{3.33}$$

It is worth noting that the 1/r nature appearing in the linearized Schwarzschild solution of GR is also resolved by the error function in IDG [51]. As remarked in the aforesaid reference, when $r \to \infty$ the error function returns a value of unity implying that the nonlocal solution has the same asymptotic limit as the local solution. In addition, this is also the case when we send $r \to -\infty$. On the other hand, when we send $r \to 0$, the error function behaves as $\operatorname{Erf}(r/2\ell) \sim r/2\ell$ thus resolving the singularity in the linearized regime. It is also important to note that in the limit $\ell \to 0$ the error function approaches 1 for r > 0 and

-1 for r < 0; recovering the local solution as expected. For the perturbed dilaton, we find that the nonlocal analog of Eq. (3.23) is

$$e^{-\ell^2 \Delta} \Delta \delta \Phi = 0, \qquad (3.34)$$

which once again yields $\delta \Phi = c_1 r + c_2$. We can safely set $c_1 = 0$ using the same argument as for the local case. In addition, by examining the constraint Eq. (3.5) to first order and invoking the smallness conditions, one can show that $c_2 = 0$. The perturbed dilaton therefore takes on the same form as that of the local case, i.e., $\delta \Phi = 0$. The second constraint Eq. (3.6) is satisfied since the solution is static.

In Figs. 1 and 2 we plot the perturbed metric δf and Ricci scalar R respectively for the local case as well as three nonlocal scenarios. The solid blue curves correspond to the local ($\ell = 0$) case whereas the dashed green, dotted orange and dash-dotted red curves correspond to the nonlocal cases with length scale of nonlocality parameters $a\ell = 0.05$, $a\ell = 0.1$ and $a\ell = 0.2$ respectively. Given the perturbed metric δf we compute the Ricci scalar to first order, i.e., by using the expression $R = -\Delta \delta f + O(\delta f^2)$.

IV. CGHS GRAVITY

We now wish to follow a similar procedure to study ghost-free infinite-derivative modifications of the CGHS theory.

A. Conformal gauge

The vacuum CGHS theory is given by the action (2.2) with k = 1, a = 0 and λ left unspecified [19]. While for the case of SRG we worked in the Schwarzschild-type gauge,



FIG. 1. Perturbed metric δf radial dependence for the SRG theory as given by Eqs. (3.20) and (3.33) for the local and nonlocal cases respectively. The solid blue curve shows the local case, i.e., $\ell = 0$. The remaining three curves correspond to nonlocal solutions with the dashed green, dotted orange, and dash-dotted red curves corresponding to $a\ell = 0.05$, $a\ell = 0.1$, and $a\ell = 0.2$ respectively. In producing these plots, we have set a = M = 1.



FIG. 2. Radial dependence of the Ricci scalar R/a^2 for the SRG theory when calculated to first order in δf using $R = -\Delta \delta f + \mathcal{O}(\delta f^2)$. The solid blue curve shows the local case, i.e., $\ell = 0$, which is singular at the origin. The remaining three curves correspond to nonlocal solutions with the dashed green, dotted orange, and dash-dotted red curves corresponding to $a\ell = 0.05$, $a\ell = 0.1$, and $a\ell = 0.2$ respectively. The vertical line through the origin is included to show the distributional character of the Ricci scalar for the local case as well as how it is regularized in the nonlocal cases. In producing these plots, we have set a = M = 1.

for the CGHS theory we shall implement the conformal gauge, i.e., we fix

$$g_{\mu\nu} = \mathrm{e}^{2w} \eta_{\mu\nu}, \qquad (4.1)$$

where $\eta_{\mu\nu}$ is the Minkowski metric in Cartesian coordinates and we refer to *w* as the *conformal scalar*.

In the conformal gauge and starting from Eq. (2.2), we write the CGHS action as

$$S_{\text{local}}^{\text{CGHS}} = 4 \int d^2x \left[\lambda^2 \Phi^2 e^{2w} + (\partial \Phi)^2 - \frac{1}{2} \Phi^2 \Box w \right], \quad (4.2)$$

where we have used the fact that, in this scenario, the Ricci scalar becomes

$$R = -2e^{-2w} \Box w, \tag{4.3}$$

where $\Box := \eta^{\mu\nu} \partial_{\mu} \partial_{\nu}$ is the d'Alembertian operator in Minkowski space-time $\mathbb{R}^{1,1}$. We emphasize that we now raise and lower indices using the Minkowski metric $\eta^{\mu\nu}$. In addition, we have the conformal gauge constraint equations

$$\delta^{\mu\nu}(4\partial_{\mu}\Phi\partial_{\nu}\Phi + 2\partial_{\mu}w\partial_{\nu}\Phi^{2} - \partial_{\mu}\partial_{\nu}\Phi^{2}) = 0, \quad (4.4)$$

and

$$4\partial_{\mu}\Phi\partial_{\nu}\Phi + 2\partial_{(\mu}w\partial_{\nu)}\Phi^{2} - \partial_{\mu}\partial_{\nu}\Phi^{2} = 0, \quad (\mu \neq \nu).$$
(4.5)

Variation of the gauge-fixed action (4.2) yields

$$\delta S_{\text{local}}^{\text{CGHS}} = 4 \int d^2 x \bigg(2\lambda^2 \Phi \delta \Phi e^{2w} + 2\lambda^2 \Phi^2 e^{2w} \delta w + 2\partial_\nu \Phi \partial^\nu \delta \Phi - \Phi \delta \Phi \Box w - \frac{1}{2} \Phi^2 \Box \delta w \bigg).$$
(4.6)

As mentioned in Sec. II B, in addition to the two redundancies appearing as a result of diffeomorphism invariance, there is the additional symmetry described by Eq. (2.11). Let us verify that the CGHS action is indeed left invariant under this transformation. In the conformal gauge, Eq. (2.11) reads

$$\delta w = -\frac{\varepsilon}{\Phi^2}, \qquad \delta \Phi = \frac{\varepsilon}{\Phi}.$$
 (4.7)

Substituting (4.7) into Eq. (4.6) gives us

$$\delta S_{\text{local}}^{\text{CGHS}} = 4\varepsilon \int d^2 x \left[2\partial^{\nu} \Phi \partial_{\nu} \left(\frac{1}{\Phi} \right) + \frac{1}{2} \Phi^2 \Box \left(\frac{1}{\Phi^2} \right) - \Box w \right].$$
(4.8)

The last step required to verify that Eq. (4.7) is a symmetry of the CGHS action is to show that the integrand in the above is a total derivative. To accomplish this, we note that

$$\partial^{\nu} \left(\Phi^2 \partial_{\nu} \frac{1}{\Phi^2} \right) = \Phi^2 \Box \left(\frac{1}{\Phi^2} \right) + 4 \partial^{\nu} \Phi \partial_{\nu} \left(\frac{1}{\Phi} \right).$$
(4.9)

It now follows that Eq. (4.8) reads

$$\delta S_{\text{local}}^{\text{CGHS}} = -4\varepsilon \int d^2 x \partial^{\nu} \left(\frac{\partial_{\nu} \Phi}{\Phi} + \partial_{\nu} w \right), \quad (4.10)$$

showing that the integrand is a total derivative and therefore the CGHS action is invariant under the transformation (4.7).

B. Diagonalization of the quadratic action

We now turn our attention to examining the quadratic CGHS action in the conformal gauge. The functional derivative of the action (4.2) with respect to the dilaton field yields

$$\frac{\delta S_{\text{local}}^{\text{CGHS}}}{\delta \Phi} = 8(\lambda^2 \Phi e^{2w} - \Box \Phi - \Phi \Box w/2), \qquad (4.11)$$

while the functional derivative with respect to the conformal scalar leads to

$$\frac{\delta S_{\text{local}}^{\text{CGHS}}}{\delta w} = 8[\lambda^2 \Phi^2 e^{2w} - (\partial \Phi)^2/2 - \Phi \Box \Phi/2]. \quad (4.12)$$

The corresponding field equations are obtained by setting both Eqs. (4.11) and (4.12) equal to zero. To study the quadratic action for this theory, we perturb the dilaton field

and conformal scalar around some background solution $(\bar{\Phi}, \bar{w})$. That is, we write

$$w = \bar{w} + \delta w, \qquad \Phi = \bar{\Phi} + \delta \Phi, \qquad (4.13)$$

where $(\bar{\Phi}, \bar{w})$ solves the equations of motion and $\delta \Phi$ and δw are the perturbations. In order for the quadratic action to be a valid approximation, we require that the smallness conditions are satisfied. The smallness condition for the dilaton field remains $|\delta \Phi| \ll |\bar{\Phi}|$. To first order in δw the metric tensor is

$$g_{\mu\nu} = e^{2\bar{w}} \eta_{\mu\nu} [1 + 2\delta w + \mathcal{O}(\delta w^2)],$$
 (4.14)

which follows from Eq. (4.1). From this expression, we can extract the smallness condition for the perturbed conformal scalar

$$|\delta w| \ll \frac{1}{2}.\tag{4.15}$$

Provided that these two conditions are satisfied, the quadratic action will be a valid approximation. In Eq. (2.5) we defined the quadratic action for a general background metric $\bar{g}_{\mu\nu}$. In the conformal gauge, Eq. (2.5) becomes

$$\begin{split} \delta^2 S_{\text{local}}^{\text{CGHS}} &\coloneqq \int d^2 x d^2 x' \left[\delta \Phi(x) \delta \Phi(x') \frac{\delta^2 S_{\text{local}}}{\delta \Phi(x) \delta \Phi(x')} \right|_{(\bar{w}, \bar{\Phi})} \\ &+ \delta \Phi(x) \delta w(x') \frac{\delta^2 S_{\text{local}}}{\delta \Phi(x) \delta w(x')} \right|_{(\bar{w}, \bar{\Phi})} \\ &+ \delta w(x) \delta \Phi(x') \frac{\delta^2 S_{\text{local}}}{\delta w(x) \delta \Phi(x')} \right|_{(\bar{w}, \bar{\Phi})} \\ &+ \delta w(x) \delta w(x') \frac{\delta^2 S_{\text{local}}}{\delta w(x) \delta w(x')} \right|_{(\bar{w}, \bar{\Phi})} \end{split}$$
(4.16)

Let us now compute the quadratic action for the CGHS theory in the conformal gauge for a general background solution. The second-order functional derivatives being

$$\frac{\delta^2 S_{\text{local}}^{\text{CGHS}}}{\delta \Phi(x') \delta \Phi(x)} = 8(\lambda^2 e^{2w} - \Box - \Box w/2) \delta^{(2)}(x - x'), \quad (4.17)$$

$$\frac{\delta^2 S_{\text{local}}^{\text{CGHS}}}{\delta w(x') \delta \Phi(x)} = 8 \left(2\lambda^2 e^{2w} \Phi - \frac{1}{2} \Phi \Box \right) \delta^{(2)}(x - x'), \quad (4.18)$$

$$\frac{\delta^2 S_{\text{local}}^{\text{CGHS}}}{\delta \Phi(x') \delta w(x)} = 8 \left(2\lambda^2 \Phi e^{2w} - \partial^\mu \Phi \partial_\mu - \Box \Phi/2 - \frac{1}{2} \Phi \Box \right) \\ \times \delta^{(2)}(x - x'), \tag{4.19}$$

and

$$\frac{\delta^2 S_{\text{local}}^{\text{CGHS}}}{\delta w(x') \delta w(x)} = 16\lambda^2 \Phi^2 e^{2w} \delta^{(2)}(x-x'). \quad (4.20)$$

The substitution of the above second-order functional derivatives when evaluated at the background solution $(\bar{w}, \bar{\Phi})$ renders Eq. (4.16) into

$$\delta^{2} S_{\text{local}}^{\text{CGHS}} = 8 \int d^{2}x \{ \delta \Phi [\lambda^{2} e^{2\bar{w}} - \Box - \Box \bar{w}/2] \delta \Phi + \delta w [2\lambda^{2} e^{2\bar{w}} \bar{\Phi} - \partial^{\mu} \bar{\Phi} \partial_{\mu} - \Box \bar{\Phi}/2 - \bar{\Phi} \Box/2] \delta \Phi + \delta \Phi [2\lambda^{2} \bar{\Phi} e^{2\bar{w}} - \bar{\Phi} \Box/2] \delta w + 2\lambda^{2} \delta w \bar{\Phi}^{2} e^{2\bar{w}} \delta w \},$$

$$(4.21)$$

which can be further simplified by using the equation of motion (4.11) in the first bracket and integrating by parts in the second bracket. Doing this brings the quadratic action to a more tractable form

$$\delta^{2} S_{\text{local}}^{\text{CGHS}} = 8 \int d^{2}x \bigg[2\lambda^{2} \delta w \bar{\Phi}^{2} e^{2\bar{w}} \delta w + \delta \Phi \bigg(\frac{\Box \bar{\Phi}}{\bar{\Phi}} - \Box \bigg) \delta \Phi + \delta \Phi (4\lambda^{2} \bar{\Phi} e^{2\bar{w}} - \bar{\Phi} \Box) \delta w \bigg].$$
(4.22)

From here, we proceed with the diagonalization. First, we define the field

$$\delta \psi \coloneqq \delta w + \frac{\delta \Phi}{\bar{\Phi}}, \qquad (4.23)$$

which is a linear combination of the perturbed metric and dilaton. Substituting this definition for the perturbed conformal scalar δw in the quadratic action (4.22) results in

$$\delta^{2} S_{\text{local}}^{\text{CGHS}} = 8 \int d^{2}x \left\{ 2\lambda^{2} \bar{\Phi}^{2} e^{2\bar{w}} \left[\frac{\delta \Phi^{2}}{\bar{\Phi}^{2}} + \delta \psi^{2} \right] - \delta \Phi \bar{\Phi} \Box \delta \psi \right. \\ \left. + \delta \Phi \left[-4\lambda^{2} \delta \Phi e^{2\bar{w}} + \bar{\Phi} \Box \left(\frac{\delta \Phi}{\bar{\Phi}} \right) \right. \\ \left. + \left(\frac{\Box \bar{\Phi}}{\bar{\Phi}} - \Box \right) \delta \Phi \right] \right\}.$$
(4.24)

At this stage we can make use of the fact that the following combination is a total derivative

$$\Phi \Box \Phi + \frac{\Phi^2 (\partial \bar{\Phi})^2}{\bar{\Phi}^2} - \Phi \bar{\Phi} \Box \left(\frac{\Phi}{\bar{\Phi}}\right) = \partial_{\nu} \left[\frac{\Phi^2 \partial^{\nu} \bar{\Phi}}{\bar{\Phi}}\right], \quad (4.25)$$

so Eq. (4.24) can be rewritten as

$$\delta^{2} S_{\text{local}}^{\text{CGHS}} = 8 \int d^{2}x \left[-2\lambda^{2} \delta \Phi^{2} e^{2\bar{w}} + 2\lambda^{2} \bar{\Phi}^{2} e^{2\bar{w}} \delta \psi^{2} + \frac{\delta \Phi^{2}}{\bar{\Phi}^{2}} \partial_{\nu} (\bar{\Phi} \partial^{\nu} \bar{\Phi}) - \delta \Phi \bar{\Phi} \Box \delta \psi - \partial_{\nu} \left(\frac{\delta \Phi^{2} \partial^{\nu} \bar{\Phi}}{\bar{\Phi}} \right) \right].$$

$$(4.26)$$

The last term in the integrand is a total derivative and therefore has no contribution. Now, since the background solution $(\bar{w}, \bar{\Phi})$ satisfies the equations of motion, we can make use of Eq. (4.12) in the above expression in order to obtain the following, much simpler, form of the quadratic CGHS action

$$\delta^2 S_{\text{local}}^{\text{CGHS}} = 8 \int d^2 x \{ 2\lambda^2 \bar{\Phi}^2 e^{2\bar{w}} \delta \psi^2 - \delta \psi \Box (\bar{\Phi} \delta \Phi) \}.$$
(4.27)

We can further simplify the action if we vary Eq. (4.27) with respect to the perturbation $\delta \psi$ which gives

$$\delta w = -\frac{\delta \Phi}{\bar{\Phi}} + \frac{\Box(\bar{\Phi}\delta\Phi)}{4\lambda^2 \bar{\Phi}^2 e^{2\bar{w}}},\qquad(4.28)$$

after substituting in the definition (4.23) for the original fields. It follows from this last expression that δw is an auxiliary field. By substituting this constraint equation into the quadratic action (4.27) and defining

$$\delta\chi \coloneqq \frac{\Box(\bar{\Phi}\delta\Phi)}{\sqrt{8\lambda\bar{\Phi}e^{\bar{w}}}},\tag{4.29}$$

we can write schematically the diagonalized quadratic CGHS action as

$$\delta^2 S_{\text{local}}^{\text{CGHS}} = -8 \int d^2 x \delta \chi^2, \qquad (4.30)$$

which describes the one propagating off shell degree of freedom. Equation (4.30) is the desired diagonalized quadratic action in terms of the redefined field $\delta\chi$. In Sec. IV E we shall return to the latter expression in order to construct a ghost-free infinite derivative modification of the CGHS quadratic action. Before doing this, let us briefly discuss the CGHS BH solution in the conformal gauge.

C. CGHS BH solution

Let us now study the CGHS BH solution [19] in the conformal gauge. We will first discuss the full local CGHS BH solution in the conformal gauge and then move on to discuss the solution in the linearized regime.

1. General solution

By dividing the equation of motion (4.12) by Φ and then subtracting this from Eq. (4.11), one obtains

$$\Box(w + \ln \Phi) = 0. \tag{4.31}$$

At this point, we can remove the redundancy arising from (2.11) by fixing on shell² the following

$$e^{w}\Phi = e^{\lambda r}, \qquad (4.32)$$

which allows for Eq. (4.31) to be satisfied. With this choice of gauge, the equation of motion (4.12) gives us

$$\Box \Phi^2 = 4\lambda^2 e^{2\lambda r}.$$
 (4.33)

Equation (4.33) is easily solvable to find an expression for the dilaton

$$\Phi^2 = \mathrm{e}^{2\lambda r} + E,\tag{4.34}$$

where $E \in \mathbb{R}$ is a constant. From Eq. (4.31), it now follows that the metric is of the form

$$ds^{2} = \frac{-dt^{2} + dr^{2}}{1 + Ee^{-2\lambda r}},$$
(4.35)

with the conformal scalar written as

$$w = -\frac{1}{2}\ln(1 + Ee^{-2\lambda r}).$$
 (4.36)

As it is done in [4,19], one can show that the constant *E* is related to the ADM mass *M*, which has dimensions of length⁻¹, through $|E| = M/\lambda$. When *E* is positive, the metric (4.35) describes the region exterior to the CGHS BH with $(t, r) \in (-\infty, \infty) \times (-\infty, \infty)$. When $E = -M/\lambda$ the metric describes the interior region of the BH with coordinate range $(t, r) \in (-\infty, \infty) \times (-\infty, \frac{1}{2\lambda} \ln (M/\lambda))$ where $r = \frac{1}{2\lambda} \ln (M/\lambda)$ is the singularity and $r = -\infty$ is the horizon.

2. Linearized local solution

Setting $E = M/\lambda$ in Eq. (4.35) gives the metric that describes the exterior region of the CGHS BH with mass M for $r \in (-\infty, \infty)$ and horizon located at $r = -\infty$. To first order in M/λ , the conformal scalar is

$$w = -\frac{M}{2\lambda} e^{-2\lambda r} + \mathcal{O}\left(\frac{M^2}{\lambda^2}\right), \qquad (4.37)$$

while the dilaton field reads

$$\Phi = e^{\lambda r} + \frac{M}{2\lambda} e^{-\lambda r} + \mathcal{O}\left(\frac{M^2}{\lambda^2}\right).$$
(4.38)

 $^{^{2}}$ Let us note that such a fixing can only be done on shell, because if performed off shell, information about the field dynamics would be lost.

From this expansion, the background fields correspond to the linear dilaton solution

$$\bar{w} = 0$$
, and $\bar{\Phi} = e^{\lambda r}$, (4.39)

while the perturbed fields are

$$\delta w = \frac{M}{2\lambda} e^{-2\lambda r}$$
, and $\delta \Phi = -\frac{M}{2\lambda} e^{-\lambda r}$. (4.40)

It is clear that the smallness conditions are satisfied provided $r \gg \frac{1}{2\lambda} \ln \frac{M}{\lambda}$.

D. Local diagonalized theory with source action

Let us consider the source action (2.12) for the case of the local CGHS theory in the conformal gauge. By setting a = 0 and specifying the conformal gauge, the source action reads

$$S_{\text{source}}^{\text{CGHS}} = \frac{1}{2\lambda} \int d^2x \frac{e^{2w} \Phi^2 \bar{g}^{\mu\nu} A_{\mu\nu}}{\bar{\Phi}^2}, \qquad (4.41)$$

whose variation renders

$$\delta S_{\text{source}}^{\text{CGHS}} = \frac{1}{\lambda} \int d^2 x \frac{e^{2w} \Phi(\Phi \delta w + \delta \Phi) \bar{g}^{\mu\nu} A_{\mu\nu}}{\bar{\Phi}^2}.$$
 (4.42)

At this stage we wish to verify that this source action is invariant under the transformation (4.7). From Eq. (4.7) it is readily seen that $\Phi \delta w + \delta \Phi = 0$ which implies the vanishing of Eq. (4.42). Consequently, the symmetry (2.11) is preserved when introducing the source action (4.41). Moreover, when evaluating the above expression at the background fields $\Phi = \overline{\Phi} = e^{\lambda r}$ and $w = \overline{w} = 0$ we have

$$\delta S_{\text{source}}^{\text{CGHS}} = \frac{1}{\lambda} \int d^2 x \left(\delta w + \frac{\delta \Phi}{\bar{\Phi}} \right) \eta^{\mu\nu} A_{\mu\nu}, \quad (4.43)$$

which in terms of the field $\delta \chi$ as defined in (4.29), renders the last expression into

$$\delta S_{\text{source}}^{\text{CGHS}} = \frac{1}{\sqrt{2}\lambda^2} \int d^2 x \frac{\delta \chi \eta^{\mu\nu} A_{\mu\nu}}{\bar{\Phi}}.$$
 (4.44)

Since the total quadratic action to be considered in the following would be of the form given in (2.23), let us use Eq. (4.30) for $\delta^2 S_{\text{local}}$ as well as Eq. (4.44) for δS_{source} . Thus, the total quadratic action becomes

$$\delta^2 S_{\text{total}}^{\text{CGHS}} = -4 \int d^2 x \left(\delta \chi^2 - \frac{\delta \chi \eta^{\mu\nu} A_{\mu\nu}}{4\sqrt{2}\lambda^2 \bar{\Phi}} \right).$$
(4.45)

Then, the variation of Eq. (4.45) with respect to the perturbation $\delta \chi$ yields the following equation of motion:

$$\delta\chi = \frac{\eta^{\mu\nu}A_{\mu\nu}}{4\sqrt{8}\lambda^2\bar{\Phi}},\tag{4.46}$$

with the tensor field $A_{\mu\nu}$ given in Eq. (2.21). We will now show how this tensor field correctly generates the linearized CGHS BH solution provided the smallness condition is satisfied. Indeed, the substitution of Eqs. (4.29) and (2.21) transforms (4.46) into

$$e^{-\lambda r}\Delta(e^{\lambda r}\delta\Phi) = \frac{Me^{-\lambda r}}{2\lambda}\delta'(r-b), \qquad (4.47)$$

provided we focus on static solutions. We now proceed to solve Eq. (4.47) by performing the Fourier transform, which results in

$$\frac{1}{\sqrt{2\pi}} \int dr e^{-r(ik+\lambda)} \Delta(e^{\lambda r} \delta \Phi)$$
$$= \frac{M}{2\lambda\sqrt{2\pi}} \int dr e^{-r(ik+\lambda)} \delta'(r-b). \qquad (4.48)$$

Integration by parts twice on the left-hand side and once on the right-hand side provides the following solution in Fourier space:

$$\mathcal{F}\{\delta\Phi\} = \frac{M\mathrm{e}^{-b\lambda}}{2\lambda i \sqrt{2\pi}} \frac{\mathrm{e}^{-ikb}}{k - i\lambda},\tag{4.49}$$

whose inverse Fourier transform yields

$$\delta \Phi = \frac{M \mathrm{e}^{-b\lambda}}{4\pi i \lambda} \int \mathrm{d}k \frac{\mathrm{e}^{ik(r-b)}}{k-i\lambda}.$$
 (4.50)

Upon the evaluation of the integral, we obtain the following expression for the perturbed dilaton

$$\delta \Phi = \frac{M \mathrm{e}^{-\lambda r}}{2\lambda} \Theta(r - b), \qquad (4.51)$$

where $\Theta(r-b)$ is the usual Heaviside step function. We now turn our attention to obtaining an expression for the perturbed conformal scalar δw . This can be achieved by substituting Eq. (4.51) into the constraint equation (4.28) in order to find

$$\delta w = -\frac{M \mathrm{e}^{-2\lambda r}}{2\lambda} \Theta(r-b) + \frac{M \mathrm{e}^{-2\lambda r}}{8\lambda^3} \delta'(r-b). \quad (4.52)$$

From Eq. (4.52) we see that the perturbed metric is singular at r = b. In addition, for $b < \frac{1}{2\lambda} \ln \frac{M}{\lambda} \ll r$, Eqs. (4.51) and (4.52) coincide with the linearized CGHS BH solution (4.40). This shows that the solution to the quadratic action (4.45) coincides with the linearized CGHS BH solution provided we consider the space-time region for which the smallness conditions are satisfied. It is straightforward to verify that the conformal gauge constraints (4.4) and (4.5) at first order are satisfied when the smallness conditions are taken into account.

E. Ghost-free infinite-derivative CGHS gravity

We now turn our attention to constructing infinitederivative modifications of the CGHS theory that are ghost-free at the quadratic level. To this end, the local quadratic action (4.30) implies that the nonlocal quadratic action

$$\delta^2 S_{\text{nonlocal}}^{\text{CGHS}} = -8 \int d^2 x \delta \chi a(\Box) \delta \chi \qquad (4.53)$$

admits no additional degrees of freedom provided that $a(\Box)$, which contains infinitely many derivatives, is analytic with no zeros. Thus, this will not add any new degrees of freedom off shell, and hence no ghosts. Replacing the local quadratic action $\delta^2 S_{\text{local}}$ in Eq. (2.23) with the nonlocal quadratic action $\delta^2 S_{\text{nonlocal}}$ given above, and using the same source action as before, we find the nonlocal analog of Eq. (4.45),

$$\delta^2 S_{\text{total}}^{\text{CGHS}} = -4 \int d^2 x \left(\delta \chi a(\Box) \delta \chi - \frac{\delta \chi \eta^{\mu\nu} A_{\mu\nu}}{4\sqrt{2}\lambda^2 \bar{\Phi}} \right).$$
(4.54)

Through the variation of Eq. (4.54) with respect to the perturbation $\delta \chi$ we obtain

$$a(\Box)\delta\chi = \frac{\eta^{\mu\nu}A_{\mu\nu}}{4\sqrt{8}\lambda^2\bar{\Phi}}.$$
(4.55)

By substituting Eqs. (4.29) and (2.21) into the above expression and seeking static solutions we obtain the nonlocal analog of Eq. (4.47),

$$a(\Delta)[\mathrm{e}^{-\lambda r}\Delta(\mathrm{e}^{\lambda r}\delta\Phi)] = -\frac{M\mathrm{e}^{-\lambda r}}{2\lambda}\delta'(r-b). \tag{4.56}$$

Performing the Fourier transform gives us the nonlocal solution in Fourier space,

$$\mathcal{F}\{\delta\Phi\} = \frac{M\mathrm{e}^{-b\lambda}}{2\lambda i \sqrt{2\pi}} \frac{\mathrm{e}^{-ikb}}{a(-k^2)(k-i\lambda)}.$$
 (4.57)

In order to obtain the solution in position space, we first need to specify the form of the operator $a(\Box)$. Here, we use the same choice that was used in the case of SRG and consider $a(\Box) = e^{-\ell^2 \Box}$ where ℓ is the length scale of nonlocality as before. With this choice for the operator $a(\Box)$, the inverse Fourier transform of Eq. (4.57) gives

$$\delta \Phi = \frac{M \mathrm{e}^{-b\lambda}}{4\pi i \lambda} \int \mathrm{d}k \mathrm{e}^{-\ell^2 k^2} \frac{\mathrm{e}^{ik(r-b)}}{k-i\lambda}, \qquad (4.58)$$

which corresponds to the nonlocal analog of expression (4.49). By evaluating the integral on the right-hand side, we obtain the nonlocal solution for the perturbed dilaton field

$$\delta \Phi = \frac{M e^{\ell^2 \lambda^2 - \lambda r}}{4\lambda} \operatorname{Erfc}\left(\lambda \ell + \frac{b - r}{2\ell}\right), \qquad (4.59)$$

where Erfc denotes the complementary error function. The interested reader seeking a derivation of Eq. (4.59) is directed to Appendix D.

Let us now consider the local limit $\ell \to 0$ and verify that we recover the solution (4.51). In this limit, we have $\lim_{\ell \to 0} e^{\ell^2 \lambda^2} = 1$. For the factor containing Erfc, we have

$$\lim_{\ell \to 0} \operatorname{Erfc}\left(\lambda \ell + \frac{b-r}{2\ell}\right) = 2\Theta(r-b).$$
(4.60)

We therefore conclude that Eq. (4.59) reduces to (4.51) in the local limit $\ell \to 0$.

Substituting Eq. (4.59) into the constraint equation (4.28) gives the perturbed conformal scalar

$$\delta w = -\frac{M e^{\ell^2 \lambda^2 - 2\lambda r}}{4\lambda} \operatorname{Erfc}\left(\lambda \ell + \frac{b - r}{2\ell}\right) + \frac{M(\lambda \ell + \frac{b - r}{2\ell})e^{-\lambda(r+b) - \frac{(r-b)^2}{4\ell^2}}}{16\sqrt{\pi}\lambda^3 \ell^2}.$$
(4.61)

In Figs. 3–5 we plot $\delta\Phi$, δw and R/λ^2 respectively with parameter values: b = 0, $\lambda = 35$ and M = 10. We have chosen these parameter values to illustrate the resolution of the singularity at r = b as well as how the nonlocal solutions approach the local solution as the length scale of nonlocality ℓ decreases.

We now wish to examine the effect of nonlocality on the linearized CGHS BH solution by taking into account the smallness condition (2.4). By considering $r \gg b$ and taking *b* to be large and negative in Eqs. (4.59) and (4.61) we obtain

$$\delta \Phi \approx \frac{M \mathrm{e}^{\ell^2 \lambda^2 - \lambda r}}{2\lambda}, \qquad (4.62)$$

and



FIG. 3. Radial dependence of the perturbed dilaton field $\delta \Phi$ for the local and nonlocal CGHS cases. The solid blue curve corresponds to the local case ($\ell = 0$), the dashed green curve corresponds to $\lambda \ell = 0.25$, the dotted orange curve corresponds to $\lambda \ell = 0.4$, and the red dash-dotted curve corresponds to $\lambda \ell = 0.6$. For these plots, we have set M = 10 and $\lambda = 35$.

$$\delta w \approx -\frac{M \mathrm{e}^{\ell^2 \lambda^2 - 2\lambda r}}{2\lambda},\tag{4.63}$$

respectively. For these nonlocal solutions, the smallness conditions are satisfied provided $r \gg \ell^2 \lambda^2 + \frac{1}{2\lambda} \ln \frac{M}{\lambda}$. In summary, from Eqs. (4.62) and (4.63) we have found that, in a nonlocal CGHS theory with $a(\Box) = e^{-\ell^2 \Box}$, the CGHS BH mass *M* is modified by a multiplicative constant factor $e^{\ell^2 \lambda^2}$. This factor, however, can be absorbed through an appropriate coordinate transformation. It is once again straightforward to verify that the conformal gauge constraint Eqs. (4.4) and (4.5) are satisfied at first order when



FIG. 4. Radial dependence of the perturbed conformal scalar δw for both the local and nonlocal CGHS cases. The solid blue curve corresponds to the local case ($\ell = 0$), whereas the dashed green, dotted orange, and red dash-dotted curves correspond to $\lambda \ell = 0.25$, 0.4 and 0.6 respectively. For the local case, the vertical line through the origin is included to illustrate the distributional character of δw as well as how it is regularized in the nonlocal cases. For these plots, we have set M = 10 and $\lambda = 35$.



FIG. 5. Radial dependence of the Ricci scalar *R* for both the local and nonlocal CGHS cases when computed up to first order, i.e., $R = -2\Delta\delta w + O(\delta w^2)$. The solid blue curve corresponds to the local case ($\ell = 0$), whereas the dashed green, dotted orange, and red dash-dotted curves correspond to $\lambda \ell = 0.25$, 0.4, and 0.6 respectively. For the local case, the vertical line through the origin is included to illustrate the distributional character of the Ricci scalar as well as how it is regularized in the nonlocal cases. For these plots, we have set M = 10 and $\lambda = 35$.

the smallness conditions are taken into account since the nonlocal solution differs from the local solution by the aforesaid multiplicative factor in such a case.

V. CONCLUSIONS

In this paper, we constructed ghost-free infinite-derivative modifications for the SRG and CGHS dilaton gravity theories. For the SRG theory, we assumed the Schwarzschild-type gauge and diagonalized the quadratic action which contains two off shell degrees of freedom. We constructed a source action that, upon taking into account the smallness conditions, could be used to generate the linearized spherically reduced Schwarzschild solution of the local theory. Inspired by the diagonalized quadratic action in the local theory, we constructed ghost-free infinite-derivative modifications of the SRG theory. By taking the two operators containing infinitely many derivatives to be the exponential operator $e^{-\ell^2 \Box}$ we were able to obtain a nonlocal modification of the spherically reduced Schwarzschild solution after including the same source action used in the local case. We found that, in the context of this ghost-free infinite-derivative SRG theory, the 1/r factor in the linearized metric is weighted by the error function $\operatorname{Erf}(r/2\ell)$; resolving the singular nature of the local linearized solution at r = 0. In [51], it was found that the 1/rnature in the linearized Schwarzschild solution of GR is also resolved through the error function in four-dimensional IDG.

In the case of the local CGHS theory, we specified the conformal gauge and studied perturbations around a general background solution. We diagonalized the CGHS quadratic action and isolated its one propagating off shell degree of freedom. The ghost-free infinite-derivative modification of the CGHS quadratic action then involved the inclusion of one nonzero analytic differential operator containing infinitely many derivatives. We made use of the source action (4.41) to generate a solution in the local theory which coincides with the linearized CGHS BH solution when taking the smallness conditions into account. The obtained solution is also singular at some given position *b*. Nonetheless, in the nonlocal theory with form factor $e^{-\ell^2 \Box}$, we found that the solution is weighted by the complementary error function $\text{Erfc}(\lambda \ell + (b - r)/2\ell)$ which allowed for the singular nature appearing in the local solution to be resolved.

While we have only considered ghost-free infinitederivative modifications of the SRG and CGHS gravity theories, there is still a multitude of two-dimensional dilaton gravity theories (discussed extensively in [4]) for which similar modifications as the ones presented here can be constructed. One example would be to construct ghostfree infinite-derivative modifications of the dilaton action obtained through the spherical reduction of GR in dimensions other than four. Another example would be to study ghost-free infinite-derivative modifications of the CGHS theory containing additional scalar matter fields such as the model considered in [19]. In this context, one could investigate how solutions generated through so-called *f*-waves are modified as a result of introducing nonlocality. There are also two-dimensional dilaton gravity models that include fermionic matter [8,47] for which one could investigate ghost-free infinite-derivative modifications.

We also note that we were unable to obtain full solutions to these infinite-derivative dilaton gravity theories and were only able to examine how linearized local solutions were modified in the nonlocal theories. Thus, there is still the question of whether one can find full nonlocal solutions to ghost-free infinite-derivative dilaton gravity in two spacetime dimensions.

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APPENDIX A: DERIVATION OF EQ. (2.10)

Here, we provide the main steps to obtaining the quadratic action associated with the general dilaton model (2.2) without any gauge fixing or the specification of a particular background solution. We begin by first obtaining the necessary second-order functional derivatives. To this end, we vary Eq. (2.7) and write

$$\delta \frac{\delta S_{\text{local}}}{\delta \Phi} = -2\sqrt{-g}g_{\mu\nu}\delta g^{\mu\nu} \left[\frac{1}{2}\Phi R - 2k\Box\Phi + 2\Phi\lambda^2\right] + 4\sqrt{-g} \left[\frac{1}{2}R\delta\Phi + \frac{\Phi}{2}(R_{\mu\nu}\delta g^{\mu\nu} - \nabla_{\mu}\nabla_{\nu}\delta g^{\mu\nu} + g_{\mu\nu}\Box\delta g^{\mu\nu}) - 2k\delta(\Box)\Phi - 2k\Box\delta\Phi + 2\delta\Phi\lambda^2\right].$$
(A1)

We can simplify the right-hand side of this expression by using the fact that the Einstein tensor is zero in two spacetime dimensions. In addition, we can evaluate the $\delta(\Box)$ term by using the expression [59]

$$\delta(\Box)\Phi = \delta g^{\mu\nu}\nabla_{\mu}\nabla_{\nu}\Phi + \nabla_{\mu}\Phi\nabla_{\nu}\delta g^{\mu\nu} - \frac{1}{2}g_{\mu\nu}\nabla_{\alpha}\Phi\nabla^{\alpha}\delta g^{\mu\nu},$$
(A2)

which follows directly from

$$\delta(\nabla_{\mu}\nabla_{\nu})\Phi = \partial_{\alpha}\Phi \bigg[g_{\sigma(\nu}\nabla_{\mu)}\delta g^{\alpha\sigma} - \frac{1}{2}g_{\mu\rho}g_{\nu\beta}\nabla^{\alpha}\delta g^{\rho\beta}\bigg]. \quad (A3)$$

We can now write Eq. (A1) as

$$\delta \frac{\delta S_{\text{local}}}{\delta \Phi} = -4\sqrt{-g}g_{\mu\nu}\delta g^{\mu\nu}[\Phi\lambda^2 - k\Box\Phi] + 4\sqrt{-g} \left[\frac{1}{2}R\delta\Phi - \frac{1}{2}\Phi\nabla_{\mu}\nabla_{\nu}\delta g^{\mu\nu} + \frac{1}{2}\Phi g_{\mu\nu}\Box\delta g^{\mu\nu} - 2k\delta g^{\mu\nu}\nabla_{\mu}\nabla_{\nu}\Phi - 2k\nabla_{\mu}\Phi\nabla_{\nu}\delta g^{\mu\nu} + kg_{\mu\nu}\nabla_{\alpha}\Phi\nabla^{\alpha}\delta g^{\mu\nu} - 2k\Box\delta\Phi + 2\delta\Phi\lambda^2\right].$$
(A4)

In this form, we can now use Eq. (A4) to extract the second order functional derivatives

$$\frac{\delta^2 S_{\text{local}}}{\delta \Phi(x') \delta \Phi(x)} = 4\sqrt{-g} \left[\frac{1}{2} R - 2k\Box + 2\lambda^2 \right] \delta^{(2)}(x - x'), \quad (A5)$$

and

$$\frac{\delta^2 S_{\text{local}}}{\delta g^{\mu\nu}(x')\delta\Phi(x)} = 4\sqrt{-g} \left\{ -g_{\mu\nu} [\Phi\lambda^2 - k\Box\Phi] + \frac{1}{2}\Phi g_{\mu\nu}\Box - \frac{1}{2}\Phi\nabla_{\mu}\nabla_{\nu} - 2k\nabla_{\mu}\nabla_{\nu}\Phi - 2k\nabla_{\mu}\Phi\nabla_{\nu} + kg_{\mu\nu}\nabla_{\alpha}\Phi\nabla^{\alpha} \right\} \delta^{(2)}(x-x'), \tag{A6}$$

where $\delta^{(2)}(x - x')$ is the two-dimensional Dirac delta function. It now remains to derive the two remaining second order functional derivatives. Through the variation of Eq. (2.8) one obtains

$$\frac{1}{\sqrt{-g}}\delta\frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}} = \delta g^{\alpha\beta} \left\{ \left[g_{\alpha\beta}g_{\mu\nu} + 2g_{\mu\alpha}g_{\nu\beta} \right] \left[k(\partial\Phi)^2 + \Phi^2\lambda^2 + \frac{a^2}{2} \right] - \frac{1}{2}g_{\alpha\beta}[g_{\mu\nu}\Box\Phi^2 - \nabla_{\mu}\nabla_{\nu}\Phi^2 + 4k\partial_{\mu}\Phi\partial_{\nu}\Phi] + g_{\mu\nu}[\nabla_{\alpha}\nabla_{\beta}\Phi^2 - 2k\partial_{\alpha}\Phi\partial_{\beta}\Phi] - g_{\mu\alpha}g_{\nu\beta}\Box\Phi^2 \right\} + \nabla_{\sigma}\delta g^{\alpha\beta}[g_{\mu\nu}\delta^{\sigma}_{\beta}\nabla_{\alpha}\Phi^2 - g_{\mu[\nu}g_{\alpha]\beta}\nabla^{\sigma}\Phi^2 - g_{\beta[\nu}\delta^{\sigma}_{\mu]}\nabla_{\alpha}\Phi^2] + 2[g_{\mu\nu}\Box(\Phi\delta\Phi) - \nabla_{\mu}\nabla_{\nu}(\Phi\delta\Phi) + 4k\partial_{(\mu}\Phi\partial_{\nu)}\delta\Phi - 2kg_{\mu\nu}\partial_{\alpha}\Phi\partial^{\alpha}\delta\Phi - 2g_{\mu\nu}\Phi\delta\Phi\lambda^2].$$
(A7)

Equation (A7) can be used to extract

$$\frac{\delta^2 S_{\text{local}}}{\delta \Phi(x') \delta g^{\mu\nu}(x)} = 2\sqrt{-g} [(g_{\mu\nu}\Box - \nabla_{\mu}\nabla_{\nu})(\Phi\delta^{(2)}(x-x')) + (4k\partial_{(\mu}\Phi\partial_{\nu)} - 2kg_{\mu\nu}\partial_{\alpha}\Phi\partial^{\alpha} - 2g_{\mu\nu}\Phi\lambda^2)\delta^{(2)}(x-x')], \quad (A8)$$

and

$$\frac{\delta^2 S_{\text{local}}}{\delta g^{\alpha\beta}(x') \delta g^{\mu\nu}(x)} = \sqrt{-g} \left\{ \begin{bmatrix} g_{\mu\nu} g_{\alpha\beta} + 2g_{\mu\alpha} g_{\nu\beta} \end{bmatrix} \begin{bmatrix} k(\partial\Phi)^2 + \Phi^2 \lambda^2 + \frac{a^2}{2} \end{bmatrix} - \frac{1}{2} g_{\alpha\beta} \begin{bmatrix} g_{\mu\nu} \Box \Phi^2 - \nabla_{\mu} \nabla_{\nu} \Phi^2 \\ + 4k \partial_{\mu} \Phi \partial_{\nu} \Phi \end{bmatrix} + g_{\mu\nu} [\nabla_{\alpha} \nabla_{\beta} \Phi^2 - 2k \partial_{\alpha} \Phi \partial_{\beta} \Phi] - g_{\mu\alpha} g_{\nu\beta} \Box \Phi^2 + \begin{bmatrix} g_{\mu\nu} \delta^{\sigma}_{\beta} \nabla_{\alpha} \Phi^2 - g_{\mu[\nu} g_{\alpha]\beta} \nabla^{\sigma} \Phi^2 \\ - g_{\beta(\mu} \delta^{\sigma}_{\nu)} \nabla_{\alpha} \Phi^2 \end{bmatrix} \nabla_{\sigma} \right\} \delta^{(2)}(x - x').$$
(A9)

The desired quadratic action can be found by substituting Eqs. (A5), (A6), (A8), and (A9) into the definition (2.5). In order to obtain this, let us write the quadratic action as

$$\delta^2 S_{\text{local}} = \sum_{i=1}^4 I_i, \qquad (A10)$$

where we define

$$I_{1} \coloneqq \int d^{2}x d^{2}x' \delta \Phi(x) \delta \Phi(x') \frac{\delta^{2} S_{\text{local}}}{\delta \Phi(x) \delta \Phi(x')} \bigg|_{(\bar{g}_{\mu\nu}, \bar{\Phi})}, \quad (A11)$$

$$I_2 \coloneqq \int \mathrm{d}^2 x \mathrm{d}^2 x' \delta \Phi(x) \delta g^{\mu\nu}(x') \frac{\delta^2 S_{\mathrm{local}}}{\delta \Phi(x) \delta g^{\mu\nu}(x')} \bigg|_{(\bar{g}_{\mu\nu}, \bar{\Phi})}, \quad (A12)$$

$$I_{3} \coloneqq \int d^{2}x d^{2}x' \delta g^{\mu\nu}(x) \delta \Phi(x') \frac{\delta^{2} S_{\text{local}}}{\delta g^{\mu\nu}(x) \delta \Phi(x')} \bigg|_{(\bar{g}_{\mu\nu}, \bar{\Phi})}, \quad (A13)$$

Let us now consider each of the I_i individually. Evaluating Eq. (A5) at the background solution $(\bar{g}_{\mu\nu}, \bar{\Phi})$ and substituting this into Eq. (A11) gives

 $I_4 := \int \mathrm{d}^2 x \mathrm{d}^2 x' \delta g^{\mu\nu}(x) \delta g^{\alpha\beta}(x') \frac{\delta^2 S_{\mathrm{local}}}{\delta g^{\mu\nu}(x) \delta g^{\alpha\beta}(x')} \bigg|_{(\bar{g}_{\mu\nu},\bar{\Phi})}.$

$$I_1 = 4 \int d^2 x \sqrt{-\bar{g}} \delta \Phi \left(\frac{1}{2}\bar{R} - 2k\bar{\Box} + 2\lambda^2\right) \delta \Phi, \quad (A15)$$

where \bar{R} and $\bar{\Box} := \bar{g}^{\mu\nu} \bar{\nabla}_{\mu} \bar{\nabla}_{\mu}$ are the background Ricci scalar and d'Alembertian respectively. The equation of motion resulting from (2.7) tells us that

$$\frac{1}{2}\bar{R} + 2\lambda^2 = 2k\frac{\bar{\Box}\,\bar{\Phi}}{\bar{\Phi}},\tag{A16}$$

(A14)

and thus, Eq. (A15) becomes

and

$$I_1 = 8k \int d^2x \sqrt{-\bar{g}} \delta \Phi \left(\frac{\bar{\Box} \bar{\Phi}}{\bar{\Phi}} - \bar{\Box} \right) \delta \Phi. \quad (A17)$$

We now turn our attention to finding I_2 . By evaluating (A6) at the background solution, substituting this into Eq. (A12) and again using the equation of motion (A16), one finds

$$I_{2} = 4 \int d^{2}x \sqrt{-\bar{g}} \delta g^{\mu\nu} \left[\frac{1}{4} \bar{R} \bar{g}_{\mu\nu} \bar{\Phi} \delta \Phi + \frac{1}{2} \bar{g}_{\mu\nu} \bar{\Box} (\bar{\Phi} \delta \Phi) - \frac{1}{2} \bar{\nabla}_{\mu} \bar{\nabla}_{\nu} (\bar{\Phi} \delta \Phi) + 2k \partial_{\mu} \bar{\Phi} \partial_{\nu} \delta \Phi - k \bar{g}_{\mu\nu} \bar{\nabla}_{\alpha} (\delta \Phi \partial^{\alpha} \bar{\Phi}) \right].$$
(A18)

Similarly, by evaluating Eq. (A8) at the background solution and substituting this into (A13) we obtain

$$\begin{split} I_{3} &= 4 \int \mathrm{d}^{2}x \sqrt{-\bar{g}} \delta g^{\mu\nu} \left[\frac{1}{2} (\bar{g}_{\mu\nu} \bar{\Box} - \bar{\nabla}_{\mu} \bar{\nabla}_{\nu}) (\bar{\Phi} \delta \Phi) \right. \\ &+ 2k \partial_{\mu} \bar{\Phi} \partial_{\nu} \delta \Phi - \bar{g}_{\mu\nu} \bar{\nabla}_{\alpha} (\delta \Phi \partial^{\alpha} \bar{\Phi}) + (1-k) \bar{g}_{\mu\nu} \delta \Phi \bar{\Box} \bar{\Phi} \\ &+ \frac{1}{4} \bar{R} \bar{g}_{\mu\nu} \bar{\Phi} \delta \Phi \right], \end{split}$$

$$(A19)$$

where we have once again made use of the equation of motion (A16).

It now remains to compute I_4 . By considering the second order functional derivative (A9) at the classical solution and substituting the result into Eq. (A14) one finds the integral

$$\begin{split} I_4 &= \int \mathrm{d}^2 x \sqrt{-\bar{g}} \delta g^{\mu\nu} \left\{ \bar{g}_{\alpha\beta} \left[\bar{g}_{\mu\nu} \left(k (\partial \bar{\Phi})^2 + \bar{\Phi}^2 \lambda^2 + \frac{a^2}{2} \right) \right. \\ &\left. - \frac{1}{2} \left(\bar{g}_{\mu\nu} \bar{\Box} \bar{\Phi}^2 - \bar{\nabla}_{\mu} \bar{\nabla}_{\nu} \bar{\Phi}^2 + 4 k \partial_{\mu} \bar{\Phi} \partial_{\nu} \bar{\Phi} \right) \right] \\ &\left. + \bar{g}_{\mu\alpha} \left[2 \bar{g}_{\nu\beta} \left(k (\partial \bar{\Phi})^2 + \bar{\Phi}^2 \lambda^2 + \frac{a^2}{2} \right) - \bar{g}_{\nu\beta} \bar{\Box} \bar{\Phi}^2 \right] \right. \\ &\left. + \left[\bar{g}_{\mu\nu} \delta^{\sigma}_{\beta} \bar{\nabla}_{\alpha} \bar{\Phi}^2 - \bar{g}_{\mu[\nu} \bar{g}_{\alpha]\beta} \bar{\nabla}^{\sigma} \bar{\Phi}^2 \right. \\ &\left. - \bar{g}_{\beta\mu} \delta^{\sigma}_{\nu} \bar{\nabla}_{\alpha} \bar{\Phi}^2 \right] \bar{\nabla}_{\sigma} \right\} \delta g^{\alpha\beta}. \end{split}$$

$$(A20)$$

The integral above can be simplified significantly by leveraging the equation of motion obtained by setting (2.8) to zero. More specifically, using this equation of motion, the first square bracket in the integral (A20) vanishes while the second bracket can be simplified. This allows us to write Eq. (A20) as

$$I_{4} = \int d^{2}x \sqrt{-\bar{g}} \delta g^{\mu\nu} \{ \bar{g}_{\mu\alpha} [4k\partial_{\beta}\bar{\Phi}\partial_{\nu}\bar{\Phi} - \bar{\nabla}_{\nu}\bar{\nabla}_{\beta}\bar{\Phi}^{2}]$$

+ $\bar{g}_{\mu\nu}\bar{\nabla}_{\alpha}\bar{\Phi}^{2}\bar{\nabla}_{\beta} - \bar{g}_{\mu[\nu}\bar{g}_{\alpha]\beta}\bar{\nabla}^{\sigma}\bar{\Phi}^{2}\bar{\nabla}_{\sigma}$
- $\bar{g}_{\beta\mu}\bar{\nabla}_{\alpha}\bar{\Phi}^{2}\bar{\nabla}_{\nu} \} \delta g^{\alpha\beta}.$ (A21)

Substituting Eqs. (A17), (A18), (A19), and (A21) into (A10) gives the desired quadratic action (2.10).

APPENDIX B: DILATON GRAVITY IN THE CONFORMAL AND SCHWARZSCHILD-TYPE GAUGES

1. Dilaton gravity in the conformal gauge

In this section, we wish to show that the action

$$S_{\text{local}} = 4 \int d^2 x \left[\Phi^2 e^{2w} \lambda^2 + \frac{a^2}{2} e^{2w} + k \eta^{\mu\nu} \partial_\mu \Phi \partial_\nu \Phi - \frac{1}{2} \Phi^2 \eta^{\mu\nu} \partial_\mu \partial_\nu w \right], \tag{B1}$$

which is obtained by specifying the conformal gauge $g_{\mu\nu} = e^{2w}\eta_{\mu\nu}$ in Eq. (2.2) where $\eta_{\mu\nu} = \text{diag}(-1, 1)$ is the Minkowski metric in Cartesian coordinates contains all the dynamics of the original action (2.2). We wish to show that the same dynamical equations of motion are obtained irrespective of whether we specify the conformal gauge at the level of the action or at the level of the field equations. Such a check is necessary since the two approaches are not equivalent in general.

Let us begin by stating the field equations associated with the gauge-fixed action (B1). Variation with respect to the dilaton field gives

$$\frac{\delta S_{\text{local}}}{\delta \Phi} = 8 \Big[\Phi e^{2w} \lambda^2 - k \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} \Phi - \frac{1}{2} \Phi \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} w \Big], \quad (B2)$$

while variation with respect to the conformal scalar w gives

$$\frac{\delta S_{\text{local}}}{\delta w} = 4 \left[2\Phi^2 e^{2w} \lambda^2 + 2\frac{a^2}{2} e^{2w} - \frac{1}{2} \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} \Phi^2 \right].$$
(B3)

We now turn our attention to specifying the conformal gauge in Eqs. (2.7) and (2.9).

Let us first study the action of the space-time covariant d'Alembertian operator $\Box := \nabla_{\mu} \nabla^{\mu}$ on some smooth test function *h*. Written in terms of the connection coefficients $\Gamma^{\alpha}_{\mu\nu}$ we have

$$\Box h = g^{\mu\nu}\partial_{\mu}\partial_{\nu}h - g^{\mu\nu}\Gamma^{\alpha}_{\mu\nu}\partial_{\alpha}h.$$
 (B4)

In the conformal gauge, we have

$$g^{\mu\nu}\Gamma^{\alpha}_{\mu\nu} = e^{-2w}\eta^{\alpha\sigma}(2-\eta_{\mu\nu}\eta^{\mu\nu})\partial_{\sigma}w = 0.$$
 (B5)

It follows that

$$\Box h = \mathrm{e}^{-2w} \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} h. \tag{B6}$$

By specifying the conformal gauge in Eq. (2.7) one obtains

$$\frac{\delta S_{\text{local}}}{\delta \Phi} = 4e^{2w} [-\Phi e^{-2w} \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} w - 2k e^{-2w} \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} \Phi + 2\Phi \lambda^2], \qquad (B7)$$

where we made use of Eqs. (4.3) and (B6). Upon simplification, it is readily seen that Eq. (B7) is nothing more than Eq. (B2). Fixing the conformal gauge in Eq. (2.9) gives

$$-2g^{\mu\nu}\frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}} = -2e^{2w} \left[e^{-2w} \eta^{\mu\nu} \partial_{\mu} \partial_{\nu} \Phi^2 - 4\left(\Phi^2 \lambda^2 + \frac{a^2}{2}\right) \right].$$
(B8)

Simplifying the last result shows that the right-hand side of Eq. (B8) is nothing more than Eq. (B3).

Finally, notice that in this case the equivalence with the trace of the field equations is sufficient to prove the validity of the gauge-fixing approach, since such equation contains all the dynamics to obtain the solution. On the other hand, the trace-free part of the field equations provides us with the constraint equations

$$\delta^{\mu\nu}(4k\partial_{\mu}\Phi\partial_{\nu}\Phi + 2\partial_{\mu}w\partial_{\nu}\Phi^2 - \partial_{\mu}\partial_{\nu}\Phi^2) = 0, \qquad (B9)$$

and

$$4k\partial_{\mu}\Phi\partial_{\nu}\Phi + 2\partial_{(\mu}w\partial_{\nu)}\Phi^{2} - \partial_{\mu}\partial_{\nu}\Phi^{2} = 0, (\mu \neq \nu), \quad (B10)$$

associated with the imposing of the conformal gauge. We therefore conclude that the consideration of the gauge-fixed action (B1) together with the constraint equations (B9) and (B10) above is equivalent to the consideration of the original action (2.2).

2. Dilaton gravity in the Schwarzschild-type gauge

In this section, we wish to show that the action (2.2) gives the same dynamical equations of motion regardless of whether we specify the Schwarzschild-type gauge at the level of the action or at the level of the field equations. The Schwarzschild-type gauge is stated in Eq. (3.1). Given this form of the metric, the nonvanishing components of the connection coefficients are

$$\Gamma_{tt}^t = -\Gamma_{rt}^r = -f^2 \Gamma_{rr}^t = \frac{\dot{f}}{2f}, \qquad (B11)$$

and

$$\Gamma_{rt}^{t} = -\Gamma_{rr}^{r} = \frac{1}{f^2} \Gamma_{tt}^{r} = \frac{f'}{2f}, \qquad (B12)$$

where f' and \dot{f} denote differentiation with respect to r and t respectively. From the above we can compute the non-vanishing Ricci tensor components

$$R_{tt} = \frac{ff''}{2} + \frac{\ddot{f}}{2f} - \frac{\dot{f}^2}{f^2},$$
 (B13)

and

$$R_{rr} = -\frac{\ddot{f}}{2f^3} + \frac{\dot{f}^2}{f^4} - \frac{f''}{2f}.$$
 (B14)

From the last two expressions it follows that the Ricci scalar is

$$R = -\frac{\ddot{f}}{f^2} - f'' + \frac{2\dot{f}^2}{f^3}.$$
 (B15)

By specifying the Schwarzschild-type gauge in the action (2.2) we have

$$S_{\text{local}} = \int d^2x \Big[R\Phi^2 - \frac{4k}{f} \dot{\Phi}^2 + 4kf \Phi'^2 + 4\Phi^2 \lambda^2 + 2a^2 \Big],$$
(B16)

and it is understood that the Ricci scalar is given by Eq. (B15). The variation of this gauge-fixed action yields

$$\delta S_{\text{local}} = \int d^2 x \left[\delta R \Phi^2 + 2R \Phi \delta \Phi + \frac{4k \delta f}{f^2} \dot{\Phi}^2 + 4k \delta f \Phi'^2 + 8k g^{\mu\nu} \partial_\mu \Phi \partial_\nu \delta \Phi + 8\Phi \delta \Phi \lambda^2 \right].$$
(B17)

Let us turn our attention to the variation of the Ricci scalar δR . From Eq. (B15) we have

$$\delta R = -\partial_t^2 \left(\frac{\delta f}{f^2}\right) - \partial_r^2 \delta f.$$
 (B18)

In terms of the perturbed inverse metric $\delta g^{\mu\nu}$ the last expression is nothing more than

$$\delta R = -\partial_{\mu}\partial_{\nu}\delta g^{\mu\nu}. \tag{B19}$$

We can now write Eq. (B17) as

$$\delta S_{\text{local}} = 2 \int d^2 x \left\{ \delta \Phi (R + 4k\nabla^2 + 4\lambda^2) \Phi + \delta f \right.$$

$$\times \left[\frac{(2k-1)\dot{\Phi}^2}{f^2} + (2k-1)\Phi'^2 - \frac{\Phi \ddot{\Phi}}{f^2} - \Phi \Phi'' \right] \right\}.$$
(B20)

The first functional derivatives of the gauge-fixed action with respect to Φ and f are now found to be

$$\frac{\delta S_{\text{local}}}{\delta \Phi} = 2(R - 4k\nabla^2 + 4\lambda^2)\Phi, \qquad (B21)$$

and

$$\frac{1}{2}\frac{\delta S_{\text{local}}}{\delta f} = \frac{(2k-1)\dot{\Phi}^2}{f^2} + (2k-1)\Phi'^2 - \frac{\Phi\ddot{\Phi}}{f^2} - \Phi\Phi'', \quad (B22)$$

respectively. We now wish to show that these are the same equations of motion that are obtained when gauge fixing at the level of the field equations. It is immediately clear that Eqs. (B21) and (2.7) coincide. We therefore turn our attention to imposing the Schwarzschild-type gauge in Eq. (2.8).

It is worth mentioning that the perturbed metric $\delta g^{\mu\nu}$ is traceless in the Schwarzschild-type gauge, i.e., $g_{\mu\nu}\delta g^{\mu\nu} = 0$. We therefore examine the trace-free part of Eq. (2.8)

$$\left(\frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}}\right)^{\text{TF}} \coloneqq \frac{\delta S_{\text{local}}}{\delta g^{\mu\nu}} - \frac{1}{2}g_{\mu\nu}g^{\alpha\beta}\frac{\delta S_{\text{local}}}{\delta g^{\beta\alpha}}, \qquad (B23)$$

where we have used the superscript TF to denote the tracefree part. From Eq. (2.8) we have the following after imposing the Schwarzschild-type gauge

$$\left(\frac{\delta S_{\text{local}}}{\delta g^{rr}}\right)^{\text{TF}} = 2k\Phi^{\prime 2} + \frac{2k\dot{\Phi}^2}{f^2} - \frac{1}{2f^2}\nabla_t\partial_t\Phi^2 - \frac{1}{2}\nabla_r\partial_r\Phi^2.$$
 (B24)

By replacing the Levi-Civita covariant derivatives in the above with partial derivatives and connection coefficients, we have

$$\begin{pmatrix} \frac{\delta S_{\text{local}}}{\delta g^{rr}} \end{pmatrix}^{\text{TF}} = 2k\Phi'^2 + 2k\frac{\dot{\Phi}^2}{f^2} - \frac{\partial_t^2 \Phi^2}{2f^2} - \frac{1}{2}\partial_r^2 \Phi^2 + \frac{1}{2f^2}\Gamma^{\alpha}_{tt}\partial_{\alpha}\Phi^2 + \frac{1}{2}\Gamma^{\alpha}_{rr}\partial_{\alpha}\Phi^2.$$
 (B25)

From Eqs. (B11) and (B12) we have

$$\Gamma^{\alpha}_{tt} = -f^2 \Gamma^{\alpha}_{rr}.$$
 (B26)

Upon substituting this expression into Eq. (B25), we find that the result is nothing more than the right-hand side of Eq. (B22).

Finally, using a similar argument as in the previous subsection, the equivalence with respect to the trace-free part is enough to motivate the gauge fixing approach since it contains all the dynamics to obtain the solution. While the action (B16) contains all the dynamics, we also have the constraint equations obtained from the trace Eq. (2.9) and the (t, r) component of (2.8) with the former providing us with

$$f\partial_r^2 \Phi^2 - \frac{1}{f}\partial_t^2 \Phi^2 + f'\partial_r \Phi^2 + \frac{\dot{f}\partial_t \Phi^2}{f^2} - 4\Phi^2 \lambda^2 - 2a^2 = 0,$$
 (B27)

and the latter yielding

$$\partial_t \partial_r \Phi^2 - \frac{f' \partial_t \Phi^2}{2f} + \frac{\dot{f} \partial_r \Phi^2}{2f} - 4k \dot{\Phi} \Phi' = 0.$$
 (B28)

APPENDIX C: DERIVATION OF EQ. (3.4)

Here we derive the quadratic action associated with the SRG theory which is given in Eq. (3.4). We will obtain this result by specifying the Schwarzschild-type gauge in Eq. (2.10) for the case of the SRG theory and taking the background fields to be the flat space-time solution with a linear dilaton. We remind the reader that the SRG theory is described by the dilaton model (2.2) for the choice of parameters: $\lambda = 0$, k = 1/2 and *a* left unspecified. We fix the Schwarzschild-type gauge by taking the metric to be of the form given in Eq. (3.1). We take the background metric to be $\bar{g}_{\mu\nu} = \eta_{\mu\nu}$ while taking the background dilaton field to be $\bar{\Phi} = ar$ which corresponds to the flat space-time solution. As already discussed in Sec. III, in the Schwarzschild-type gauge the perturbed metric takes the form $\delta g^{\mu\nu} = \delta^{\mu\nu} \delta f$.

With the specifications mentioned above, we now proceed to derive Eq. (3.4). To accomplish this, we examine the integrals I_i defined in Appendix A that make up the quadratic action. By setting $\overline{\Phi} = ar$ and k = 1/2 in Eq. (A17) and carrying out an integration by parts we obtain

$$I_1^{\text{SRG}} = 4 \int d^2 x \partial^\mu \delta \Phi \partial_\mu \delta \Phi, \qquad (C1)$$

where $\Box := \eta^{\mu\nu}\partial_{\mu}\partial_{\nu}$ is the d'Alembertian in flat space-time. In order to compute the remaining I_i^{SRG} integrals, we substitute in $\delta g^{\mu\nu} = \delta^{\mu\nu} \delta f$. Using the fact that $\delta^{\mu\nu}\eta_{\mu\nu} = 0$, the remaining I_i^{SRG} integrals simplify considerably since the contributions involving contractions $\delta g^{\mu\nu}\eta_{\mu\nu}$ will vanish. For I_2^{SRG} and I_3^{SRG} we find

$$I_2^{\text{SRG}} + I_3^{\text{SRG}} = 4 \int d^2 x \delta^{\mu\nu} \delta f [2\partial_\mu \bar{\Phi} \partial_\nu \delta \Phi - \partial_\mu \partial_\nu (\bar{\Phi} \delta \Phi)].$$
(C2)

Since the background dilaton is $\bar{\Phi} = ar$, we have $\partial_{\mu}\partial_{\nu}\bar{\Phi} = 0$ and thus (C2) becomes

$$I_2^{\text{SRG}} + I_3^{\text{SRG}} = -4 \int d^2 x \delta^{\mu\nu} \delta f \bar{\Phi} \partial_\mu \partial_\nu \delta \Phi. \quad (C3)$$

We now turn our attention to I_4^{SRG} . From Eq. (A21) we have

$$I_{4}^{\text{SRG}} = a^{2} \int d^{2}x \delta f \delta^{\mu\nu} \left\{ \eta_{\mu\alpha} [2\partial_{\beta}r\partial_{\nu}r - \partial_{\nu}\partial_{\beta}r^{2}] + \frac{1}{2} \eta_{\mu\alpha}\eta_{\nu\beta}\partial^{\sigma}r^{2}\partial_{\sigma} - \eta_{\mu\beta}\partial_{\alpha}r^{2}\partial_{\nu} \right\} \delta f \delta^{\alpha\beta}, \qquad (C4)$$

where we have once again used $\delta^{\mu\nu}\eta_{\mu\nu} = 0$. By evaluating the derivatives, the contribution contained in the square brackets vanishes and we are left with

$$I_4^{\text{SRG}} = a^2 \int d^2 x r \delta f(\eta_{\mu\nu} \eta^{\mu\nu} - 2) \partial_r \delta f.$$
 (C5)

It follows that, since the trace of the Minkowski metric in two space-time dimensions is $\eta^{\mu}_{\mu} = 2$, the integral above vanishes and we have

$$I_4^{\text{SRG}} = 0. \tag{C6}$$

Upon the substitution of Eqs. (C1), (C3), and (C6) into (A10) we obtain the desired result (3.4).

APPENDIX D: DERIVATION OF EQ. (4.59)

In this section, we evaluate the integral appearing in Eq. (4.58) and obtain the nonlocal modification to the perturbed dilaton field (4.59). We begin by writing Eq. (4.58) as

$$\delta \Phi = \frac{M \mathrm{e}^{-\lambda r}}{4\pi i \lambda} \int_{-\infty}^{\infty} \mathrm{d}k \mathrm{e}^{-\ell^2 k^2} \\ \times \left[i \int_{0}^{r-b} \mathrm{d}u \mathrm{e}^{iu(k-i\lambda)} + \frac{1}{k-i\lambda} \right].$$
(D1)

We first wish to compute the second term on the right-hand side of the above expression. In order to accomplish this, we need to evaluate the integral

$$L_1 \coloneqq \int \mathrm{d}k \frac{\mathrm{e}^{-\ell^2 k^2}}{k - i\lambda}. \tag{D2}$$

The real part of the integral given above is

$$\operatorname{Re}\{L_1\} = \int \mathrm{d}k \frac{\mathrm{e}^{-\ell^2 k^2} k}{k^2 + \lambda^2} = 0, \qquad (D3)$$

which vanishes since the integrand is an odd function of k. This implies that the integral L_1 is purely imaginary. That is,

$$L_1 = i \text{Im}\{L_1\} = i\lambda \int dk \frac{e^{-\ell^2 k^2}}{k^2 + \lambda^2}.$$
 (D4)

The last expression can be written as

$$L_1 = -i\lambda e^{\ell^2 \lambda^2} \int_{-\infty}^{\infty} \mathrm{d}k \int_{\infty}^{\ell^2} \mathrm{d}u e^{-u(k^2 + \lambda^2)}.$$
 (D5)

By evaluating the integral over k, one finds

$$L_1 = -i\lambda\sqrt{\pi}e^{\ell^2\lambda^2} \int_{\infty}^{\ell^2} du \frac{e^{-u\lambda^2}}{\sqrt{u}}.$$
 (D6)

Performing a change of variables with $u = v^2/\lambda^2$ gives

$$L_1 = 2i e^{\ell^2 \lambda^2} \sqrt{\pi} \int_{\ell\lambda}^{\infty} \mathrm{d}v e^{-v^2}.$$
 (D7)

The integral is nothing more than $\frac{\sqrt{\pi}}{2}$ Erfc($\ell \lambda$) where Erfc is the complementary error function. We therefore have

$$L_1 = i\pi e^{\ell^2 \lambda^2} \operatorname{Erfc}(\ell \lambda).$$
 (D8)

We now wish to compute the first term on the right-hand side of Eq. (D1). We therefore turn our attention to evaluating the integral

$$L_{2} \coloneqq i \int_{-\infty}^{\infty} \mathrm{d}k \int_{0}^{r-b} \mathrm{d}u \mathrm{e}^{-\ell^{2}k^{2} + iku + \lambda u}$$
$$= i \int_{0}^{r-b} \mathrm{d}u \int_{-\infty}^{\infty} \mathrm{d}k \mathrm{e}^{-\ell^{2}(k - \frac{iu}{2\ell^{2}})^{2} - \frac{u^{2}}{4\ell^{2}} + \lambda u}.$$
 (D9)

Evaluating the integral over k gives us

$$L_2 = i \frac{\sqrt{\pi}}{\ell} \int_0^{r-b} du e^{-\frac{1}{4\ell^2}(u-2\lambda\ell^2)^2 + \lambda^2\ell^2}.$$
 (D10)

By performing the change of variables $v = (2\lambda \ell^2 - u)/2\ell$ we obtain

$$L_2 = 2i\sqrt{\pi}\mathrm{e}^{\ell^2\lambda^2} \int_{\lambda\ell' \frac{r-b}{2\ell'}}^{\lambda\ell} \mathrm{d}v\mathrm{e}^{-v^2}. \tag{D11}$$

By adding Eqs. (D7) and (D11) we find

$$L_1 + L_2 = i\pi e^{\ell^2 \lambda^2} \operatorname{Erfc}\left(\ell \lambda - \frac{r-b}{2\ell}\right). \quad (D12)$$

Substituting Eq. (D12) into (D1) gives the desired result (4.59).

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