Modified-gravity theories with nondynamical background fields

Carlos M. Reyes^{1,*} and Marco Schreck^{2,†}

¹Centro de Ciencias Exactas, Universidad del Bío-Bío, Avda. Andrés Bello 720, 3800708 Chillán, Chile ²Departamento de Física, Universidade Federal do Maranhão, Campus Universitário do Bacanga, São Luís, Maranhão 65085-580, Brazil

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We study the dynamics of a modified-gravity theory, which is supplemented by an extended Gibbons-Hawking-York boundary term and incorporates diffeomorphism violation through nondynamical background fields denoted as u and $s^{\mu\nu}$ in the literature. An ADM decomposition allows us to project the modified Einstein equations into purely spacelike hypersurfaces, which implies the field equations for the induced dynamical three-metric. We also obtain the Hamilton-Jacobi equations of motion for the canonical variables of the theory based on its Hamiltonian, which was derived in a previous work. The computations show that the dynamical field equations obtained from the Lagrangian and Hamiltonian approaches are consistent with each other. Connections to Brans-Dicke theory and ghost-free massive gravity are established.

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I. INTRODUCTION

The phenomena of perihelion advance of Mercury [1], light deflection [2], and gravitational redshift [3] compose the three classical tests of General Relativity (GR) and successfully confirm the latter as the correct gravity theory. Further significant validations of GR are the detection of the geodetic and frame-dragging effects by Gravity Probe B [4], the first direct observation of gravitational waves by LIGO [5], and the images of the accretion disks of the supermassive central black holes in the elliptic galaxy M87 and our Milky Way, respectively, which were recently taken by the Event Horizon Telescope [6,7]. Apart from linearized GR exhibiting a propagating massless spin-2 excitation, diffeomorphism invariance is at the heart of Einstein's theory. This symmetry encodes the profound property of GR being invariant under nonlinear, differentiable maps from a spacetime manifold onto itself. The field equations of GR are also covariant under general coordinate transformations, but the latter only operate on the atlas of a manifold as opposed to points, sets, and curves on the manifold proper. The geometry of a curved spacetime manifold is locally equivalent to the pseudo-Euclidean geometry of Minkowski spacetime, whose symmetry group

[°]creyes@ubiobio.cl [†]marco.schreck@ufma.br is the Poincaré group. Our focus is on diffeomorphisms instead of the local symmetry structure of GR.

Any departure from diffeomorphism invariance in a modified-gravity theory is expected to have significant theoretical and observational implications. In particular, the constraint algebra [8] and Dirac observables [9] of GR are likely to be modified. The exact physical consequences of such deviations are challenging to identify and extremely difficult to measure directly, as manipulations of the spacetime manifold are beyond the capabilities of presently conceivable experiments. However, parametrizing explicit diffeomorphism violation via nondynamical background fields, which have nonstandard transformation properties, can provide a window into probing associated phenomena.

In principle, diffeomorphism violation is as old as GR itself. While his theory was still in the making, Einstein required that the determinant of the spacetime metric correspond to unity, which led to vast simplifications of his field equations [10]. This condition is also incorporated in unimodular gravity [11–13], which is not invariant under the full diffeomorphism group of GR, but only under volume-preserving diffeomorphisms. Unimodular gravity corresponds to GR with an arbitrary cosmological constant, although the latter arises as an integration constant instead of a parameter introduced at the level of the action [14,15].

Despite the beauty of Einstein's gravity theory and its astounding achievements, alterations are expected when the latter is to be reconciled with quantum theory. Modifications of the gravitational laws of physics have been found to occur naturally at the Planck scale, where quantum effects are expected to become dominant. Such settings are provided by string theory, branes, and

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supergravity. For example, diffeomorphism violation in gravity can arise from a spontaneous breaking of Lorentz invariance in particular string field theories [16]. The potential mechanism gives rise to problems related to compactified dimensions in the context of inflation, suggesting the generation of mass terms for some metric components [17,18]. Recently, other diffeomorphism-violating gravity models were shown to involve such mass terms [19,20].

Generically, both spontaneous and explicit diffeomorphism symmetry breaking are parametrized within the comprehensive effective-field theory framework known as the gravitational Standard-Model Extension (SME) [21,22]. Searches for diffeomorphism violation—let it be spontaneous or explicit-can constrain SME coefficients. The direct detection of gravitational waves by LIGO [5] ushered in the new era of gravitational-wave astronomy. The latter constitutes one method to probe deviations from GR, which has gained vast prominence and has been providing an ever increasing number of constraints on SME coefficients and parameters in modified-gravity theories [23–30]. The absence of energy losses of particles by gravitational Cherenkov radiation [31,32] provides an alternative possibility of bounding SME coefficients. Some experimental constraints on background field coefficients such as those obtained in, e.g., Refs. [33,34] are interpreted as bounds on explicit diffeomorphism violation. The data tables [35] can be consulted as an extensive compilation of such constraints.

Diffeomorphism invariance is also violated explicitly in particular models of massive gravity. An extension of GR implementing the propagation of a massive spin-2 excitation is known as massive gravity and its construction has received significant attention during the past years. The action initially introduced by Fierz and Pauli [36] is ghostfree at the linearized level, but does not agree with GR in the massless limit. The Vainshtein mechanism [37] solves this problem by taking into account nonlinear effects. Unfortunately, with that settled, another severe issue was revealed by Boulware and Deser; the occurrence of a ghost mode at the nonlinear level at an unacceptably small scale [38].

In 2011, the construction of de Rham, Gabadadze, and Tolley (dRGT) [39] led to a breakthrough, since it avoids the Boulware-Deser (BD) ghost in the decoupling limit to all orders. This realm of research has uncovered many interesting aspects such as its interplay with the physics of diffeomorphism violation [40–42], extra dimensions [43,44], the Stückelberg trick [45–48], linearized [36,49] vs. nonlinear massive gravity [37–39,50–53], the helicity decomposition of the metric perturbation [54], and the Ostrogradsky formalism as well as ghost states [38,55,56]. Note that dRGT theory has even been incorporated into other modified-gravity theories such as f(R) gravity [57]. It is worthwhile to consult the valuable review [58] for this research area.

The motivations for constructing gravity theories beyond GR are multifold. Low-energy extensions of Einstein's gravity are basically motivated by cosmological observations. Understanding the late-time acceleration of the Universe and inflation as well as the search for Dark Matter has inspired various modifications of GR [59–67]. Some alternatives such as Brans-Dicke theory [68] intend to incorporate Mach's principle into the description of gravity. The latter was one of Einstein's motivations for developing his GR, but it seems that he abandoned this goal later on. Hořava-Lifshitz gravity [69,70] is formulated to improve the UV behavior of the graviton propagator, while the theory approaches Einstein's gravity in the IR regime. Another interesting model is cardinal gravity [71,72] that interprets long-range gravitational forces as propagating Nambu-Goldstone modes arising from spontaneous symmetry breaking.

In general, some extensions of GR introduce operators with higher-order derivatives [73–75], others involve functions of the Ricci curvature scalar [59–65] or additional vector and tensor fields coupling to spacetime curvature [76–86]. Stating an exhaustive list of references on extensions or modifications of Einstein's relativity lies beyond our scope. References [87–89] provide elaborate reviews on modified-gravity theories and experimental tests where Ref. [89] focuses on the SME, in particular.

In light of the previously mentioned lines of research, many modified-gravity theories exhibit diffeomorphism violation. While spontaneous symmetry violation such as in Refs. [76–86] is known to be benign [90], the question may arise whether or not explicit diffeomorphism violation implies internal inconsistencies and under which circumstances. This paper intends to answer that question for a particular class of modified-gravity theories. Its action involves coordinate scalars beyond GR being noninvariant under diffeomorphisms. Symmetry violation is parametrized by a nondynamical scalar background field denoted as u and a tensor-valued one called $s^{\mu\nu}$, respectively. The latter settings and extensions thereof are part of the gravitational SME [21,22] mentioned before and have been subject to phenomenological [91-95] as well as theoretical studies [96]. As these alterations of GR are quite generic, relationships to specific modified-gravity theories in the literature are expected. In particular, we will refer to Brans-Dicke theory and dRGT massive gravity.

In the recent work [97], the formalism developed by Arnowitt, Deser, and Misner (ADM) [98–105] was applied to the class of modified-gravity theories characterized by uand $s^{\mu\nu}$. The calculations showed that the background fields imply an altered constraint structure in the Hamiltonian formulation. Incorporating an extension of the Gibbons-Hawking-York (GHY) boundary term [106,107] to eliminate additional second-order time derivatives of the metric, which occur in the Lagrangian and couple to the background fields, was an essential ingredient for constructing the Hamiltonian. Our objective in the present article is to understand the dynamics of this theory better. We will be working both within the covariant and the Hamiltonian formulation. We also note in passing that the authors of Ref. [108] investigate a similar, though not equivalent, theory. Their interest and approach differ from ours in certain aspects.

Our paper is organized as follows. In Sec. II we recapitulate the modified-gravity theory that forms the foundation of Ref. [97] and define the basic variables employed in the ADM decomposition. Furthermore, we emphasize correspondences between the latter setting and Brans-Dicke theory and dRGT massive gravity. In Sec. III, the canonical-momentum variables and the Hamiltonians are compiled from Ref. [97]. Our new investigations start in Sec. IV where the modified Einstein equations are projected into purely spacelike hypersurfaces of the spacetime foliation. Section V is dedicated to the Hamilton-Jacobi equations of motion. Our essential finding here is that the latter correspond to the projected field equations in the covariant formulation. In Sec. VI we continue by studying projections of the modified Einstein equations into subspaces that are partially or completely orthogonal to spacelike hypersurfaces. These projections are demonstrated to be linked to appropriate functional derivatives of the Hamiltonians. Finally, via Sec. VII we would like to motivate further SME-related studies along the same line by demonstrating which SME background fields play a role in linearized dRGT theory and Hořava-Lifshitz gravity. Our findings are concluded on in Sec. VIII. We employ natural units with c = 1 unless otherwise stated. Our metric signature is (-, +, +, +). Greek indices are spacetime indices, whereas Latin indices describe quantities living in purely spacelike hypersurfaces of the ADM decomposition. The *Mathematica* package *xTensor* [109] provides computational support.

II. MODIFIED GRAVITY WITH BACKGROUND FIELDS

We focus on the following modified Einstein-Hilbert (EH) action [21,22] without a cosmological constant,

$$S = \int_{\mathcal{M}} d^4 x \frac{\sqrt{-g}}{2\kappa} [(1-u)^{(4)}R + s^{\mu\nu}{}^{(4)}R_{\mu\nu}], \qquad (1)$$

with $\kappa = 8\pi G_N$, the Ricci tensor ${}^{(4)}R_{\mu\nu}$ and the associated Ricci scalar ${}^{(4)}R := {}^{(4)}R^{\mu}{}_{\mu}$ of the four-dimensional spacetime manifold \mathcal{M} with metric tensor $g_{\mu\nu}$ and $g := \det(g_{\mu\nu})$. Furthermore, u = u(x) and $s^{\mu\nu} = s^{\mu\nu}(x)$ are nondynamical background fields having a generic spacetime dependence. The latter are considered to have zero fluctuations: $\delta u = 0$ and $\delta s^{\mu\nu} = 0$. All fields are defined in the tangent bundle of \mathcal{M} . The modified Einstein equations for Eq. (1) were first obtained in Ref. [91] and can be read from Eqs. (6) and (7) of the latter reference,

$$0 = (1-u)^{(4)}G^{\mu\nu} + \frac{1}{2}(\nabla^{\mu}\nabla^{\nu}u + \nabla^{\nu}\nabla^{\mu}u) - g^{\mu\nu}\Box u$$
$$-\frac{1}{2}(s^{\alpha\beta(4)}R_{\alpha\beta}g^{\mu\nu} + \nabla_{\alpha}\nabla^{\mu}s^{\alpha\nu} + \nabla_{\alpha}\nabla^{\nu}s^{\alpha\mu}$$
$$-\Box s^{\mu\nu} - g^{\mu\nu}\nabla_{\alpha}\nabla_{\beta}s^{\alpha\beta}), \qquad (2)$$

where ${}^{(4)}G^{\mu\nu}$ is the Einstein tensor. Furthermore, ∇_{μ} is the covariant derivative on the spacetime manifold \mathcal{M} and $\Box := \nabla_{\mu} \nabla^{\mu}$ the d'Alembertian. The Bianchi identities of Riemannian geometry imply nontrivial restrictions on the form of the background fields *u* and $s^{\mu\nu}$, which is a well-known feature of this theory that has been indicated in a series of papers such as Refs. [21,22,90], amongst others. We intend to study the consequences of these restrictions in a future paper, but our current focus is on the purely dynamical aspects of Eq. (1).

We use the ADM formalism expressed in terms of the configuration space variables $X := \{N, N^i, q_{ij}\}$. Here, *N* is the lapse function, N^i are the components of the shift vector, and q_{ij} are the components of the induced metric on a spacelike hypersurface Σ_t [98–105]. It then holds that $\sqrt{-g} = N\sqrt{q}$ with $q := \det(q_{ij})$ and

$$g_{00} = -N^2 + q^{ij}N_iN_j, \quad g_{0i} = N_i, \quad g_{ij} = q_{ij}.$$
 (3)

Furthermore, the components of the contravariant metric amount to

$$g^{00} = -\frac{1}{N^2}, \qquad g^{0i} = \frac{N^i}{N^2}, \qquad g^{ij} = q^{ij} - \frac{N^i N^j}{N^2}.$$
 (4)

Since we will have to study projections of the modified Einstein equations into Σ_t , recall also the following decomposition formula for the Ricci tensor and scalar curvature that arise from the Gauss-Codazzi equation,

$$q^{i}{}_{a}q^{j}{}_{\beta}{}^{(4)}R^{\alpha\beta} = R^{ij} + \frac{1}{N}q^{ia}q^{jb}\mathcal{L}_{m}K_{ab} - \frac{1}{N}D^{i}D^{j}N + KK^{ij} - 2K^{ik}K_{k}{}^{j} = \frac{1}{N}q^{ia}q^{jb}\mathcal{L}_{m}K_{ab} - (D^{i}a^{j} + a^{i}a^{j}) + R^{ij} + KK^{ij} - 2K^{ik}K_{k}{}^{j},$$
(5a)

$$^{(4)}R = R + K^2 + K_{ij}K^{ij} - \frac{2}{N}D_iD^iN + \frac{2}{N}\mathcal{L}_mK, \quad (5b)$$

in terms of the extrinsic curvature $K_{ab} \coloneqq D_a n_b$ with $n_{\mu} = (-N, 0, 0, 0)$, the Ricci tensor R_{ij} , and the Ricci scalar R in a spacelike hypersurface Σ_t . Furthermore, \mathcal{L}_m denotes the Lie derivative [110] along the four-vector $m^{\mu} \coloneqq Nn^{\mu}$ with $n^{\mu} = (1/N, -N^i/N)$ and $a_i \coloneqq D_i \ln(N)$ is known as the acceleration. Here, D_i is the covariant derivative in Σ_t , which is compatible with the induced metric q_{ij} .

The background field $s^{\mu\nu}$ is tensor-valued and decomposes into three distinct sectors according to the foliation of the spacetime manifold in terms of the hypersurfaces Σ_t . The following identity is valuable for performing this decomposition,

$$s^{\alpha\beta} = q^{\alpha}{}_{\mu}q^{\beta}{}_{\nu}s^{\mu\nu} - (q^{\alpha}{}_{\nu}n^{\beta} + q^{\beta}{}_{\nu}n^{\alpha})s^{\nu\mathbf{n}} + n^{\alpha}n^{\beta}s^{\mathbf{nn}}, \qquad (6)$$

where $q^{\mu}{}_{\nu}$ projects a tensor or a part of it into Σ_t . Here we define $s^{ij} := q^i{}_{\mu}q^j{}_{\nu}s^{\mu\nu}$ as the purely spacelike sector of $s^{\mu\nu}$ that lives in Σ_t entirely. Furthermore, let $s^{i\mathbf{n}} := q^i{}_{\mu}n_{\nu}s^{\mu\nu}$ be the vector-valued piece and $s^{\mathbf{nn}} := n_{\mu}n_{\nu}s^{\mu\nu}$ the scalar part.

Now, the total ADM-decomposed action based on Eq. (1) reads [97]

$$S = \int_{\mathcal{M}} \mathrm{d}t \mathrm{d}^3 x \mathcal{L}_{\mathrm{ADM}},\tag{7a}$$

$$\mathcal{L}_{\text{ADM}} = \mathcal{L}^{(0)} + \mathcal{L}^{(u)} + \sum_{i=1,2,3} \mathcal{L}_i^{(s)},$$
(7b)

where $\mathcal{L}^{(0)}$ is the ADM-decomposed EH Lagrange density,

$$\mathcal{L}^{(0)} = \frac{N\sqrt{q}}{2\kappa} \left(\frac{2}{N} \mathcal{L}_m K - \frac{2}{N} D_i D^i N + R + K^2 + K_{ij} K^{ij} \right),$$
(7c)

and the modifications are

$$\mathcal{L}^{(u)} = \frac{N\sqrt{q}}{2\kappa} \left[-u(R - K^2 + K_{ij}K^{ij}) + \frac{2}{N}(K\mathcal{L}_m u + uD_iD^iN) \right],$$
(7d)

$$\mathcal{L}_{1}^{(s)} = \frac{N\sqrt{q}}{2\kappa} \left[-\frac{1}{N} (K_{ij}\mathcal{L}_{m}s^{ij} + s^{ij}D_{i}D_{j}N) + s^{ij}(R_{ij} - 2K_{i}^{\ l}K_{lj}) \right],$$
(7e)

$$\mathcal{L}_{2}^{(s)} = \frac{N\sqrt{q}}{2\kappa} \left[s^{\mathbf{nn}} \left(\frac{1}{N} D_{i} D^{i} N - K^{ij} K_{ij} + K^{2} \right) + \frac{1}{N} K \mathcal{L}_{m} s^{\mathbf{nn}} \right],$$
(7f)

$$\mathcal{L}_{3}^{(s)} = \frac{N\sqrt{q}}{2\kappa} [2s^{i\mathbf{n}} (D_{i} K - D_{l} K^{l}_{i})].$$
^(7g)

By defining new shift vector components as $\tilde{N}^i := N^i - Ns^{in}$, the Lagrange density $\mathcal{L}_3^{(s)}$, which involves the vector-valued coefficients s^{in} only, can be reproduced at first order in s^{in} from the ADM decomposition of the EH Lagrange density. This property is a strong argument for s^{in} corresponding to mere gauge degrees of freedom [97]. Thus, they will be completely discarded in the remainder of

the paper. Then, we also take into account an extended GHY boundary term [97] of the form

$$S_{\text{GHY}} = \frac{\varepsilon}{2\kappa} \oint_{\partial \mathcal{M}} \mathrm{d}^3 y \sqrt{q} [2(1-u)K - s^{\mathbf{nn}}K + K_{ij}s^{ij}], \quad (8)$$

where the parameter $\varepsilon = \mp 1$ for a spacelike (timelike) boundary $\partial \mathcal{M}$ of the spacetime manifold \mathcal{M} and the integral runs over the coordinates y^a defined on this boundary. Last but not least, we introduce a second boundary term for u and s^{nn} that is of plainly different nature compared to that of Eq. (8),

$$S_{\partial\Sigma} = -\frac{1}{2\kappa} \oint_{\partial\Sigma_l} d^2 z \sqrt{q} r_l [ND^l (2u + s^{\mathbf{nn}})], \qquad (9)$$

with the coordinates z^a given on the boundary of a spacelike hypersurface Σ_t and a suitably normalized vector r_l orthogonal to the boundary. In earnest, such boundary terms can emerge when integrations by parts are performed over Σ_t while computing the Hamiltonian from the corresponding Lagrangian via a Legendre transformation [97]. The purpose of these boundary contributions will become clear later on.

Any modified-gravity theory that is formulated at the level of an action is expected to have a corresponding background field in the comprehensive parametrization of the gravitational SME recently developed in Ref. [22]. However, it may be challenging to establish such a correspondence for a specific model under consideration. In the following, a number of popular examples are provided, which shall serve as a motivation for developing a better understanding of nondynamical background fields in the gravitational SME.

A. Nondynamical part of Brans-Dicke and f(R) theories

An early motivation for modifying Einstein's GR was to incorporate Mach's principle. One among many possibilities of formulating the latter is via a gravitational "constant" that is promoted to a dynamical field with an explicit dependence on the spacetime coordinates [111]. In the formulation by Brans and Dicke [68] the inverse of the gravitational constant is replaced by a scalar field ϕ , whereupon the modified field equations are based on the variation of a modified action as follows:

$$0 = \delta \int_{\mathcal{M}} \mathrm{d}^4 x \sqrt{-g} \bigg(\phi R + 16\pi L_m - \omega \frac{(\nabla \phi)^2}{\phi} \bigg).$$
(10)

Here, ω is a dimensionless free parameter and L_m contains the matter fields. The action can then be cast into the form

$$S_{\rm BD} = \int_{\mathcal{M}} \mathrm{d}^4 x \sqrt{-g} \left(\frac{G_N}{2\kappa} \phi R + L_m - \frac{\omega G_N}{2\kappa} \frac{(\nabla \phi)^2}{\phi} \right), \quad (11)$$

where $[G_N] = [\kappa] = -2$ and $[\phi] = [R] = 2$. We identify

$$G_N \phi = 1 - u, \tag{12}$$

with the scalar background field u in $\mathcal{L}^{(u)}$ of Eq. (7d). The action of Brans-Dicke theory decomposes into three parts. The first couples the scalar field to spacetime curvature. The second contribution describes matter and the third term gives rise to the dynamics of the theory. The latter is governed by the free parameter ω . A reformulation of the dynamical term in Eq. (11) amounts to

$$S_{\rm BD} \supset \int_{\mathcal{M}} d^4 x \sqrt{-g} \left(-\frac{\omega G_N}{2\kappa} \frac{(\nabla \phi)^2}{\phi} \right)$$
$$= -\int_{\mathcal{M}} d^4 x \frac{\sqrt{-g}}{2\kappa} \omega \frac{(\nabla u)^2}{1-u}. \tag{13}$$

The dynamical part can be switched off by setting $\omega \mapsto 0$, which renders the first term in Eq. (11) nondynamical. Now, the modified field equations [68] following from Eq. (11) read

$$G_{N}\phi G_{\mu\nu} = 8\pi G_{N}T_{\mu\nu} + \frac{\omega}{G_{N}\phi} \left[\nabla_{\mu}(G_{N}\phi)\nabla_{\nu}(G_{N}\phi) - \frac{1}{2}g_{\mu\nu}(\nabla G_{N}\phi)^{2} \right] + \nabla_{\mu}\nabla_{\nu}G_{N}\phi - g_{\mu\nu}\Box G_{N}\phi,$$
(14)

and expressing ϕ in terms of u according to Eq. (12) implies

$$(1-u)G_{\mu\nu} = 8\pi G_N T_{\mu\nu} + \frac{\omega}{1-u} \left[\nabla_{\mu} u \nabla_{\nu} u - \frac{1}{2} g_{\mu\nu} (\nabla u)^2 \right] - \nabla_{\mu} \nabla_{\nu} u + g_{\mu\nu} \Box u.$$
(15)

Dropping the energy-momentum tensor as well as the dynamical contributions in the limit $\omega \mapsto 0$ leads to the modified Einstein equations for the *u* term. They are deduced from Eq. (2) by setting $s^{\mu\nu} = 0$ and will be recalled in Eq. (24) to come. Thus, Brans-Dicke theory without the dynamical term can be identified with the nondynamical *u* sector of the gravitational SME. To the best of our knowledge, this correspondence has not been stated in the literature, so far.

Another observation is that the Lagrange density $\mathcal{L}^{(u)}$ of Eq. (7d) corresponds, in principle, to a particular f(R) theory. The identification requires that a nondynamical background field be incorporated from the beginning such that f(R) = (1 - u)R. It is not difficult to check that the field equations quoted in Eq. (24) are equivalent to Eqs. (1.1), (A4) of Ref. [59] with the energy-momentum tensor $T_{\mu\nu} = 0$.

B. dRGT massive gravity

As GR, massive-gravity theories constructed before the seminal work [39] did not involve canonical momenta associated with the lapse function and the shift vector, which gave rise to four primary first-class constraints. Thus, counting the number of physical degrees of freedom [112] amounts to six, which is one more than expected for a massive graviton. The additional degree of freedom corresponds to the BD ghost mode propagating at energy scales proportional to the minuscule graviton mass, which is unacceptable. dRGT theory emerged in an attempt to conceive a massive-gravity theory that is devoid of the BD ghost. To do so, the EH term is supplemented by a particular potential of the graviton that has a highly peculiar form. The theory is constructed in a manner to provide another primary and an additional secondary constraint [55] on the three-metric components. Thereupon, a counting of the physical degrees of freedom indicates that the ghost mode is eliminated.

The potential of dRGT theory involves traces of coordinate two-tensors $\mathbb{X}^{\mu}{}_{\nu} := \sqrt{g^{\mu\alpha}f_{\alpha\nu}}$ expressed in terms of the dynamical spacetime metric $g_{\mu\nu}$ and a nondynamical reference metric, which is frequently denoted as $f_{\mu\nu}$ [58]. At the level of the pure-gravity action of dRGT theory it is challenging to identify the nondynamical background $f_{\mu\nu}$ or contractions thereof with SME coefficients. After all, the potential is not a simple sum of contributions involving $f_{\mu\nu}$ contracted with dynamical fields or curvature components in a linear fashion. The two-tensor $\mathbb{X}^{\mu}{}_{\nu}$ cannot be evaluated generically, but must be computed based on particular choices of the dynamical metric and the background field.

Finding an appropriate map in the matter sector is plainly simpler. Coupling a particular set of matter fields to the gravity sector via both metrics $g_{\mu\nu}$ and $f_{\mu\nu}$ was demonstrated to reintroduce the BD ghost [113]. A reemergence of the ghost can only be avoided by coupling in a more sophisticated way via an effective metric given by

$$g_{\mu\nu}^{(\text{eff})} = \alpha^2 g_{\mu\nu} + 2\alpha\beta g_{\mu\alpha} \mathbb{X}^a{}_\nu + \beta^2 f_{\mu\nu}, \qquad (16)$$

with arbitrary dimensionless parameters α , β that may be tuned to either couple with the dynamical metric or the reference metric or both. Now, a background vierbein $\bar{v}_{\mu}{}^{a}$ is introduced such that $f_{\mu\nu} = \bar{v}_{\mu}{}^{a}\bar{v}_{\nu}{}^{b}\eta_{ab}$ with the Minkowski metric η_{ab} in a local inertial frame. If the dynamical vierbein $e_{\mu}{}^{a}$ and the background vierbein satisfy $e^{\mu}{}_{a}\bar{v}_{\mu b} = e^{\mu}{}_{b}\bar{v}_{\mu a}$, it holds that $\mathbb{X}^{\mu}{}_{\nu} = e^{\mu}{}_{a}\bar{v}_{\nu}{}^{a} =: \gamma^{\mu}{}_{\nu}$ [114]. In the context of the gravitational SME, a redefinition of the (inverse) metric according to $g^{\mu\nu} \simeq (1+u)\tilde{g}^{\mu\nu} + s^{\mu\nu}$ with a new metric $\tilde{g}_{\mu\nu}$ can be carried out to remove u and $s^{\mu\nu}$ from the pure-gravity sector. Expressing the former metric $g_{\mu\nu}$ in terms of the new metric $\tilde{g}_{\mu\nu}$ in the matter sector, introduces appropriate SME coefficients in the matter sector. By taking $s^{\mu\nu}$ as traceless, for the effective metric of Eq. (16) it is possible to identify [115]

$$u = -\frac{1}{2}\beta\gamma^{\sigma}{}_{\sigma}, \qquad s^{\mu\nu} = -2\beta\left(\gamma^{\mu\nu} - \frac{1}{4}\gamma^{\sigma}{}_{\sigma}g^{\mu\nu}\right).$$
(17)

Thus, the theory of Eq. (7) has a direct link to mattergravity couplings in dRGT massive gravity.

III. CANONICAL MOMENTA AND HAMILTONIANS

We are now interested in understanding the dynamics of the modified-gravity theory based on Eq. (1). Both the dynamical equations of motion and the constraints are encoded in the modified Einstein equations. In principle, each constraint arises from Eq. (2) by performing suitable normal and tangential projections with respect to the hypersurfaces Σ_t defined in the ADM formalism. A wise approach is to explore the scalar *u* as well as the scalar and purely spacelike sectors of $s^{\mu\nu}$ separately.

Let us exemplify the *u* sector. We now consider the set of momenta $\Pi := \{\pi_N, \pi_i, \pi^{ij}\}$ associated with the canonical variables. They are defined as

$$\pi_N \coloneqq \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}^{(u)})}{\partial \dot{N}}, \qquad (18a)$$

$$\pi_i \coloneqq \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}^{(u)})}{\partial \dot{N}^i}, \qquad (18b)$$

$$\pi^{ij} \coloneqq \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}^{(u)})}{\partial \dot{q}_{ij}}, \qquad (18c)$$

where a dot stands for the time derivative. Since the Lagrangian of Eq. (7) does not involve velocities of the gauge variables, \dot{N} and \dot{N}^i , the canonical momentum conjugates to the lapse function and the shift vector, respectively, are found to be weakly equal to zero,

$$\pi_N \approx 0, \qquad \pi_i \approx 0.$$
 (19)

Furthermore, we impose the following fundamental equaltime Poisson brackets between the canonically conjugate variables (see Ref. [116]),

$$\{N(\mathbf{x}), \pi_N(\mathbf{x}')\} = \delta^{(3)}(\mathbf{x} - \mathbf{x}'), \qquad (20a)$$

$$\{N^{j}(\mathbf{x}), \pi_{i}(\mathbf{x}')\} = \delta_{i}^{j} \delta^{(3)}(\mathbf{x} - \mathbf{x}'), \qquad (20b)$$

$$\{q_{kl}(\mathbf{x}), \pi^{ij}(\mathbf{x}')\} = (\delta^{i}_{k}\delta^{j}_{l} - \delta^{i}_{l}\delta^{j}_{k})\delta^{(3)}(\mathbf{x} - \mathbf{x}'), \qquad (20c)$$

where the Poisson bracket is defined as

$$\{Q(\mathbf{x}), P(\mathbf{x}')\} \coloneqq \int_{\Sigma_t} \mathrm{d}^3 \tilde{x} \left[\frac{\delta Q(\mathbf{x})}{\delta X_i(\tilde{\mathbf{x}}, t)} \frac{\delta P(\mathbf{x}')}{\delta \Pi^i(\tilde{\mathbf{x}}, t)} - \frac{\delta Q(\mathbf{x})}{\delta \Pi^i(\tilde{\mathbf{x}}, t)} \frac{\delta P(\mathbf{x}')}{\delta X_i(\tilde{\mathbf{x}}, t)} \right],$$
(21)

with the functional derivatives $\delta/\delta X_i$, $\delta/\delta \Pi^i$ for the canonical variables and momenta, respectively. In an analogous manner, we introduce sets of momenta $\{p_N, p_i, p^{ij}\}$ and $\{P_N, P_i, P^{ij}\}$ associated with the s^{nn} and s^{ij} sector, respectively.

The canonical Hamiltonian that results from the Legendre transformation of the Lagrange density given in Eq. (7) was obtained in Ref. [97]. The canonical momenta for each of these sectors then follow from Eqs. (7c)–(7f),

$$\pi^{ij} \coloneqq \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}^{(u)})}{\partial \dot{q}_{ij}}$$
$$= \frac{\sqrt{q}}{2\kappa} \left[(1 - u)(K^{ij} - q^{ij}K) + \frac{1}{N}q^{ij}\mathcal{L}_m u \right], \qquad (22a)$$

$$p^{ij} \coloneqq \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}_1^{(s)})}{\partial \dot{q}_{ij}}$$
$$= \frac{\sqrt{q}}{2\kappa} \left[(1 - s^{\mathbf{nn}}) (K^{ij} - q^{ij}K) + \frac{1}{2N} q^{ij} \mathcal{L}_m s^{\mathbf{nn}} \right], \quad (22b)$$

$$P^{ij} := \frac{\partial (\mathcal{L}^{(0)} + \mathcal{L}_{2}^{(s)})}{\partial \dot{q}_{ij}} \\ = \frac{\sqrt{q}}{2\kappa} \bigg[K^{ij} - q^{ij} K - (s^{il} K_{l}^{\ j} + s^{jl} K_{l}^{\ i}) - \frac{1}{2N} \mathcal{L}_{m} s^{ij} \bigg]. \quad (22c)$$

For the u, s^{nn} , and s^{ij} sector each, the canonical Hamiltonians have the form

$$H_{u} = \int_{\Sigma_{t}} d^{3}x \left[-\frac{\sqrt{q}}{2\kappa} N((1-u)R + 2D^{i}D_{i}u) + \frac{\mathcal{L}_{m}u}{1-u} \left(\pi - \frac{3\sqrt{q}}{4\kappa N} \mathcal{L}_{m}u \right) + \frac{2\kappa N}{\sqrt{q}(1-u)} \left(\pi^{ij}\pi_{ij} - \frac{\pi^{2}}{2} \right) - 2(D_{i}\pi^{ij})N_{j} \right],$$
(23a)

$$H_1 = \int_{\Sigma_t} \mathrm{d}^3 x \left[-\frac{\sqrt{q}}{2\kappa} N(R + D^i D_i s^{\mathbf{nn}}) + \frac{\mathcal{L}_m s^{\mathbf{nn}}}{2(1 - s^{\mathbf{nn}})} \left(p - \frac{3\sqrt{q}}{8\kappa N} \mathcal{L}_m s^{\mathbf{nn}} \right) + \frac{2\kappa N}{\sqrt{q}(1 - s^{\mathbf{nn}})} \left(p^{ij} p_{ij} - \frac{p^2}{2} \right) - 2(D_i p^{ij}) N_j \right], \quad (23b)$$

$$H_{2} = \int_{\Sigma_{t}} d^{3}x \left[-\frac{\sqrt{q}}{2\kappa} N(R + s^{ij}R_{ij} - D_{j}D_{i}s^{ij}) + \left(P_{ij} - \frac{P}{2}q_{ij}\right) \mathcal{L}_{m}s^{ij} + \frac{2\kappa N}{\sqrt{q}} \left(P^{ij}P_{ij} - (1 - s^{i}_{i})\frac{P^{2}}{2} - 2s^{ij}(P_{ij}P - P_{i}^{k}P_{kj})\right) - 2(D_{i}P^{ij})N_{j} \right] + \mathcal{O}[(s^{ij})^{2}].$$
(23c)

Note that H_2 is valid at first order in the coefficients s^{ij} and derivatives of the latter. Since s^{ij} parametrize a modification of GR, the coefficients are expected to be $\ll 1$ —at least in regions with weak gravitational fields. Furthermore, we assume that these coefficients also vary slowly in spacetime and do not exhibit strong fluctuations, which are reasonable assumptions in the classical regime. Studying contributions to H_2 that are of higher order in s^{ij} and derivatives thereof may be worthwhile, but it is very reasonable to understand the properties of this modification at leading order first.

IV. FIELD EQUATIONS IN THE HYPERSURFACE

Coordinate invariance allows us to work in coordinates with a nontrivial lapse function, $N = N(t, \mathbf{x})$, and a zero shift vector, $N^i = 0$, without a loss of generality. In the following, we will focus on the *u* sector first and set $s^{\mu\nu} = 0$. Later on, we will be studying the complementary $s^{\mu\nu}$ sector with u = 0. Now, the modified Einstein equations for a nonzero *u* read [91]

$$Q^{\mu\nu} \coloneqq (1-u)^{(4)} G^{\mu\nu} + \nabla^{\mu} \nabla^{\nu} u - g^{\mu\nu} \Box u = 0. \quad (24)$$

Their projection into the hypersurface Σ_t is obtained from

$$(1-u)q^{i}_{\ \mu}q^{j}_{\ \nu}{}^{(4)}G^{\mu\nu} + q^{i}_{\ \mu}q^{j}_{\ \nu}\nabla^{\mu}\nabla^{\nu}u - q^{ij}\Box u = 0.$$
(25)

Carrying out the projection of the part proportional to the Einstein tensor is straightforward and the result is readily found to be

$$q^{i}{}_{\mu}q^{j}{}_{\nu}{}^{(4)}G^{\mu\nu} = R^{ij} - \frac{R}{2}q^{ij} + q^{ia}q^{jb}\frac{1}{N}\mathcal{L}_{m}K_{ab}$$
$$-\frac{1}{N}D^{i}D^{j}N + KK^{ij} - 2K^{ik}K_{k}{}^{j}$$
$$-\frac{1}{2}q^{ij}\left(K^{2} + K_{kl}K^{kl} + \frac{2}{N}\mathcal{L}_{m}K - \frac{2}{N}D_{l}D^{l}N\right).$$
(26)

The covariant-derivative pieces are projected in the following way. Consider

$$q^{i}_{\ \mu}q^{j}_{\ \nu}\nabla^{\mu}\nabla^{\nu}u = D^{i}D^{j}u - \frac{1}{N}K^{ij}\mathcal{L}_{m}u, \qquad (27)$$

as well as

$$\Box u = D^2 u - \frac{1}{N} \left[K \mathcal{L}_m u + \mathcal{L}_m \left(\frac{1}{N} \mathcal{L}_m u \right) \right] + a^{\mu} \nabla_{\mu} u.$$
 (28)

We then intend to express the projected field equations in terms of the canonical momentum density π^{ij} that is given by Eq. (22a). Inverting the latter for the extrinsic-curvature tensor K^{ij} gives

$$K^{ij} = \frac{1}{1-u} \left[\frac{2\kappa}{\sqrt{q}} \left(\pi^{ij} - \frac{\pi}{2} q^{ij} \right) + \frac{q^{ij}}{2N} \mathcal{L}_m u \right].$$
(29)

Taking into consideration the previous ingredients, the lefthand side of the modified Einstein equations completely projected into Σ_t reads

$$(\vec{\mathbf{q}}^* \mathbf{Q})^{ij} = \frac{2\kappa}{N\sqrt{q}} \dot{\pi}^{ij} + (1-u) \left(R^{ij} - \frac{R}{2} q^{ij} \right) + \frac{1}{N} (q^{ij} D_k D^k [(1-u)N] - D^i D^j [(1-u)N]) + q^{ij} a^k D_k u - (a^i D^j u + a^j D^i u) + \frac{4\kappa^2}{q(1-u)} \left[2\pi^{ik} \pi_k{}^j - \pi\pi^{ij} - \frac{1}{2} \left(\pi_{kl} \pi^{kl} - \frac{\pi^2}{2} \right) q^{ij} \right] + \frac{\mathcal{L}_m u}{N(1-u)} \left(\frac{2\kappa}{\sqrt{q}} \pi^{ij} - \frac{3}{4N} q^{ij} \mathcal{L}_m u \right),$$
(30a)

with the time derivative of the canonical momentum stated in Eq. (22a),

$$\dot{\pi}^{ij} = \frac{\sqrt{q}}{2\kappa} \left[N(1-u)K(3K^{ij}-q^{ij}K) + (1-u)(\mathcal{L}_m K^{ij}-q^{ij}\mathcal{L}_m K) + (2q^{ij}K-3K^{ij})\mathcal{L}_m u + q^{ij}\mathcal{L}_m \left(\frac{1}{N}\mathcal{L}_m u\right) \right].$$
(30b)

Here, we took over the convenient notation from Refs. [103,105] describing the projection of a generic spacetime tensor into Σ_t ,

$$(\vec{\mathbf{q}}^*\mathbf{T})^{\alpha_1\dots\alpha_s}{}_{\beta_1\dots\beta_t} \coloneqq q^{\alpha_1}{}_{\gamma_1}\dots q^{\alpha_s}{}_{\gamma_s}q^{\delta_1}{}_{\beta_1}\dots q^{\delta_t}{}_{\beta_t}T^{\gamma_1\dots\gamma_s}{}_{\delta_1\dots\delta_t}.$$
(31)

The next step is to consider the modified Einstein equations for the $s^{\mu\nu}$ coefficients [91],

$$J^{\mu\nu} \coloneqq {}^{(4)}G^{\mu\nu} - \frac{1}{2}s^{\alpha\beta}R_{\alpha\beta}g^{\mu\nu} - \frac{1}{2}\nabla_{\alpha}\nabla^{\mu}s^{\alpha\nu} - \frac{1}{2}\nabla_{\alpha}\nabla^{\nu}s^{\alpha\mu} + \frac{1}{2}\Box s^{\mu\nu} + \frac{1}{2}g^{\mu\nu}\nabla_{\alpha}\nabla_{\beta}s^{\alpha\beta} = 0.$$
(32)

The projection of the Einstein tensor is quickly obtained from Eq. (26). As we remarked before, we distinguish

between the different sectors of $s^{\mu\nu}$ mentioned below Eq. (6). Recall that the coefficients s^{in} are pure gauge degrees of freedom, which is why they were discarded right from the start. To compute the projection of Eq. (32) for the purely timelike sector composed of the single scalar coefficient s^{nn} , the following results are indispensable,

$$q^{ij}s^{\mathbf{nn}}R_{\mathbf{nn}} = q^{ij}s^{\mathbf{nn}}\left(-\frac{1}{N}\mathcal{L}_mK + D_la^l + a_la^l - K^{kl}K_{kl}\right),\tag{33a}$$

$$q^{i}{}_{\mu}q^{j}{}_{\nu}\nabla_{\alpha}\nabla^{\mu}(s^{\mathbf{nn}}n^{\alpha}n^{\nu}) = (D^{i}s^{\mathbf{nn}})a^{j} - s^{\mathbf{nn}}a^{i}a^{j} + s^{\mathbf{nn}}(KK^{ij} - K^{ki}K^{j}{}_{k}) + \frac{1}{N}(\mathcal{L}_{m}s^{\mathbf{nn}})K^{ij} + \frac{s^{\mathbf{nn}}}{N}q^{ik}q^{jl}\mathcal{L}_{m}K_{kl},$$
(33b)

$$q^i{}_{\alpha}q^j{}_{\beta}\Box(s^{\mathbf{nn}}n^{\mu}n^{\nu}) = 2s^{\mathbf{nn}}(K^{ik}K^j{}_k - a^ia^j), \tag{33c}$$

$$q^{i}{}_{\mu}q^{j}{}_{\nu}(g^{\mu\nu}\nabla_{\alpha}\nabla_{\beta}s^{\alpha\beta}) = q^{ij} \bigg[\frac{1}{N}\mathcal{L}_{m}\bigg(\frac{1}{N}\mathcal{L}_{m}s^{\mathbf{nn}}\bigg) + a^{k}D_{k}s^{\mathbf{nn}} + \frac{2}{N}(\mathcal{L}_{m}s^{\mathbf{nn}})K + s^{\mathbf{nn}}\bigg(\frac{1}{N}\mathcal{L}_{m}K + K^{2}\bigg) + s^{\mathbf{nn}}(D_{l}a^{l} + a_{l}a^{l})\bigg].$$

$$(33d)$$

Here, the extrinsic curvature expressed in terms of the canonical momentum reads

$$K^{ij} = \frac{1}{1 - s^{\mathbf{nn}}} \left[\frac{2\kappa}{\sqrt{q}} \left(p^{ij} - \frac{p}{2} q^{ij} \right) + \frac{q^{ij}}{4N} \mathcal{L}_m s^{\mathbf{nn}} \right].$$
(34)

The projected field equations are simpler in comparison to those of the *u* sector, as there is no term of the form $s^{\mathbf{nn}}R$ [cf. Eqs. (7d), (7f)]. Now we are in a position to evaluate the left-hand side of Eq. (32) for $s^{i\mathbf{n}} = s^{ij} = 0$ completely projected into Σ_t . It is useful to define $(J_1)^{\mu\nu} := J^{\mu\nu}|_{s^{i\mathbf{n}}=s^{ij}=0}$ with $J^{\mu\nu}$ given in Eq. (32). Then

$$(\vec{\mathbf{q}}^*\mathbf{J}_1)^{ij} = \frac{2\kappa}{N\sqrt{q}}\dot{p}^{ij} + R^{ij} - \frac{R}{2}q^{ij} + \frac{1}{N}(q^{ij}D_kD^kN - D^iD^jN) + \frac{1}{2}[q^{ij}a^kD_ks^{\mathbf{nn}} - (a^iD^js^{\mathbf{nn}} + a^jD^is^{\mathbf{nn}})] \\ + \frac{4\kappa^2}{q(1-s^{\mathbf{nn}})} \left[2p^{ik}p_k{}^j - pp^{ij} - \frac{1}{2}\left(p_{kl}p^{kl} - \frac{p^2}{2}\right)q^{ij}\right] + \frac{\mathcal{L}_ms^{\mathbf{nn}}}{N(1-s^{\mathbf{nn}})}\left(\frac{\kappa}{\sqrt{q}}\pi^{ij} - \frac{3}{16N}q^{ij}\mathcal{L}_ms^{\mathbf{nn}}\right), \quad (35a)$$

with the following time derivative of the canonical momentum of Eq. (22),

$$\dot{p}^{ij} = \frac{\sqrt{q}}{2\kappa} \bigg[N(1-s^{\mathbf{nn}})K(3K^{ij}-q^{ij}K) + (1-s^{\mathbf{nn}})(\mathcal{L}_m K^{ij}-q^{ij}\mathcal{L}_m K) + \left(\frac{3}{2}q^{ij}K-2K^{ij}\right)\mathcal{L}_m s^{\mathbf{nn}} + \frac{q^{ij}}{2}\mathcal{L}_m \left(\frac{1}{N}\mathcal{L}_m s^{\mathbf{nn}}\right) \bigg].$$
(35b)

Finally, we turn to the s^{ij} sector. We need

$$q^{i}{}_{\alpha}q^{j}{}_{\beta}g^{\alpha\beta}s^{\mu\nu}R_{\mu\nu} = q^{ij}s^{kl} \bigg[\frac{1}{N}\mathcal{L}_{m}K_{kl} - (D_{k}a_{l} + a_{k}a_{l}) + R_{kl} + KK_{kl} - 2K_{kn}K^{n}{}_{l} \bigg],$$
(36a)

$$q^{i}{}_{\alpha}q^{j}{}_{\beta}\nabla_{\nu}\nabla^{\alpha}(q^{\nu}{}_{\gamma}q^{\beta}{}_{\delta}s^{\gamma\delta}) = KK^{i}{}_{k}s^{kj} + 2K^{i}{}_{k}K^{k}{}_{l}s^{lj} + D_{k}D^{i}s^{kj} - a^{i}a_{k}s^{kj} + a_{k}D^{i}s^{kj} + \frac{1}{N}(\mathcal{L}_{m}K^{il})q_{lk}s^{kj} + K^{i}{}_{k}s^{kl}K^{l}{}_{l}^{j}, \quad (36b)$$

$$q^{i}{}_{\alpha}q^{j}{}_{\beta}\Box(q^{\alpha}{}_{\gamma}q^{\beta}{}_{\delta}s^{\gamma\delta}) = D_{k}D^{k}s^{ij} - K\left(\frac{1}{N}\mathcal{L}_{m}s^{ij} + s^{ik}K_{k}{}^{j} + s^{jk}K_{k}{}^{i}\right) + K^{i}{}_{k}K^{k}{}_{l}s^{lj} + K^{j}{}_{k}K_{l}{}^{k}s^{il} - \left[\frac{1}{N}\mathcal{L}_{m}\left(\frac{1}{N}\mathcal{L}_{m}s^{ij}\right) + \frac{1}{N}(K_{k}{}^{j}\mathcal{L}_{m}s^{ik} + K^{i}{}_{k}\mathcal{L}_{m}s^{kj}) + \left(\frac{1}{N}\mathcal{L}_{m}s^{ik} + s^{il}K_{l}{}^{k} + s^{kl}K_{l}{}^{i}\right)K_{k}{}^{j} + s^{ik}q_{kl}\left(\frac{1}{N}\mathcal{L}_{m}K^{lj} + 2K^{lm}K_{m}{}^{j}\right) + \left(\frac{1}{N}\mathcal{L}_{m}s^{jk} + s^{jl}K_{l}{}^{k} + s^{kl}K_{l}{}^{j}\right)K_{k}{}^{i} + s^{jk}q_{kl}\left(\frac{1}{N}\mathcal{L}_{m}K^{li} + 2K^{lm}K_{m}{}^{i}\right) - a_{k}D^{k}s^{ij} + a^{i}s^{jk}a_{k} + a^{j}s^{ik}a_{k}\right],$$
(36c)

$$q^{i}{}_{\alpha}q^{j}{}_{\beta}(g^{\alpha\beta}\nabla_{\mu}\nabla_{\nu}s^{\mu\nu}) = q^{ij} \bigg[\frac{1}{N} \mathcal{L}_{m}(K_{kl}s^{kl}) + s^{kl}D_{k}a_{l} + 2a_{k}D_{l}s^{kl} + a_{i}a_{j}s^{ij} + D_{k}D_{l}s^{kl} + KK_{kl}s^{kl} \bigg].$$
(36d)

Furthermore, the extrinsic-curvature tensor is given by

$$K^{ij} = \frac{2\kappa}{\sqrt{q}} \left(P^{ij} - \frac{1}{2} [(1 - s^k_{\ k})P + 2s^{kl}P_{kl}]q^{ij} + s^{ik}P_k^{\ j} + s^{jk}P_k^{\ i} - s^{ij}P \right) + \frac{1}{2N} \left(\mathcal{L}_m s^{ij} - \frac{q^{ij}}{2} q_{kl}\mathcal{L}_m s^{kl} \right) + \mathcal{O}[(s^{ij})^2].$$
(37)

Let $(J_2)^{\mu\nu} := J^{\mu\nu}|_{s^{nn}=s^{in}=0}$ be the left-hand side of the modified Einstein equations of Eq. (32) for the purely spacelike sector composed of the coefficients s^{ij} . Considering their projection into Σ_t and incorporating Eq. (36) as well as expressing the extrinsic curvature in terms of the canonical momentum according to Eq. (22c) results in

$$\begin{aligned} (\vec{\mathbf{q}}^* \mathbf{J}_2)^{ij} &= \frac{2\kappa}{N\sqrt{q}} \dot{P}^{ij} + R^{ij} - \frac{R}{2} q^{ij} + \frac{1}{N} (q^{ij} D_k D^k N - D^i D^j N) + \frac{1}{2} [-q^{ij} (s^{kl} R_{kl} - D_k D_l s^{kl}) - D_k D^i s^{kj} - D_k D^j s^{ki} + D_k D^k s^{ij}] \\ &+ \frac{1}{2} (2q^{ij} [a_k D_l s^{kl} + s^{kl} (D_k a_l + a_k a_l)] - a_k (D^i s^{kj} + D^j s^{ki}) + a_k D^k s^{ij}) + \frac{\kappa^2}{q} ([(1 - s^k_{\ k}) P^2 - 2P^{kl} P_{kl} + 4s^{kl} (PP_{kl} - P_k^m P_{lm})] q^{ij} + 8[P^{ik} P_k^j + s^{ik} P_{kl} P^{lj} + s^{jk} P_{kl} P^{li} - s^{ik} PP_k^j - s^{jk} PP_k^i + s^{kl} (P^i_{\ k} P_l^j - P_{kl} P^{ij})] \\ &+ 2P^2 s^{ij} - 4(1 - s^k_{\ k}) PP^{ij}) + \frac{\kappa}{N\sqrt{q}} [2(P^i_{\ k} \mathcal{L}_m s^{jk} + P^j_{\ k} \mathcal{L}_m s^{ik}) - (P\mathcal{L}_m s^{ij} + P^{ij} q_{kl} \mathcal{L}_m s^{kl})], \end{aligned}$$

$$(38a)$$

where the time derivative of the canonical momentum of Eq. (22b) reads

$$\dot{P}^{ij} = \frac{\sqrt{q}}{2\kappa} \bigg[NK(3K^{ij} - q^{ij}K) - N(s^{il}K_l^{\ j} + s^{jl}K_l^{\ i})K + \mathcal{L}_m K^{ij} - (s^{il}\mathcal{L}_m K_l^{\ j} + s^{jl}\mathcal{L}_m K_l^{\ i}) - q^{ij}\mathcal{L}_m K - \frac{K}{2}\mathcal{L}_m s^{ij} - (\mathcal{L}_m s^{il})K_l^{\ i} - (\mathcal{L}_m s^{jl})K_l^{\ i} - \frac{1}{2}\mathcal{L}_m \bigg(\frac{1}{N}\mathcal{L}_m s^{ij}\bigg) \bigg].$$
(38b)

With the latter result at hand, the modified Einstein equations for the scalar sectors u and s^{nn} as well as the purely spacelike sector s^{ij} have been successfully projected into spacelike hypersurfaces Σ_t .

V. HAMILTON-JACOBI EQUATIONS OF MOTION

With the projected altered Einstein equations of the modified-gravity theory based on Eq. (7) at our disposal, in this section we will be working within the Hamiltonian formalism. The latter is based on the following set of field equations that are of first order in time,

$$\dot{q}_{ij} = \{q_{ij}, H\},$$
 (39a)

$$\dot{\pi}^{ij} = \{\pi^{ij}, H\}. \tag{39b}$$

The first set of equations corresponds to a geometrical identity [8], whereas the second set describes the dynamics of the theory under consideration [116]. In the latter, we employ the canonical Hamiltonians of the u, s^{nn} , and s^{ij} sectors given in Eq. (23). Our goal is to compare the projected Einstein equations stated in Eqs. (30), (35), and (38) to Eq. (39b) evaluated for each of the canonical Hamiltonians of Eq. (23).

The canonical Hamiltonian associated with the u sector is given by Eq. (23a). First of all, we will investigate the first set of Hamilton's equations given by Eq. (39a), i.e.,

$$\dot{q}_{ij} = \{q_{ij}, H_u\}.$$
 (40)

Evaluating the Poisson bracket leads to

$$\dot{q}_{ij} = \left\{ q_{ij}, \int_{\Sigma_i} \mathrm{d}^3 x \frac{1}{1-u} \left[\pi \mathcal{L}_m u + \frac{2\kappa N}{\sqrt{q}} \left(\pi^{kl} \pi_{kl} - \frac{\pi^2}{2} \right) \right] \right\}$$

= 2NK_{ij}, (41)

where we used the extrinsic-curvature tensor of Eq. (29) given as a function of the canonical momentum. After confirming the outcome expected for the Hamiltonian describing the gravitational system, we devote ourselves to the second set of Hamilton's equations in Eq. (39),

$$-\left\{\pi^{ij}, \int_{\Sigma_{i}} d^{3}x \frac{\sqrt{q}}{2\kappa} N(1-u)R\right\}$$

= $-\frac{\sqrt{q}}{2\kappa} (q^{ij} D_{l} D^{l} [(1-u)N] - D^{i} D^{j} [(1-u)N] + N(1-u)G^{ij}),$ (42a)

$$\begin{cases} \pi^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{2\kappa N}{\sqrt{q}(1-u)} \left(\pi^{kl}\pi_{kl} - \frac{\pi^{2}}{2}\right) \\ = -\frac{2\kappa N}{\sqrt{q}(1-u)} \left[2\pi^{ia}\pi^{j}{}_{a} - \pi\pi^{ij} - \frac{1}{2}\left(\pi_{ab}\pi^{ab} - \frac{\pi^{2}}{2}\right)q^{ij}\right], \end{cases}$$
(42b)

$$-\left\{\pi^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{N\sqrt{q}}{\kappa} D^{l} D_{l} u\right\} = -\frac{N\sqrt{q}}{2\kappa} q^{ij} a_{l} D^{l} u, \quad (42c)$$
$$\left\{\pi^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{\mathcal{L}_{m} u}{1-u} \left(\pi - \frac{3}{4} \frac{\sqrt{q}}{\kappa N} \mathcal{L}_{m} u\right)\right\}$$
$$= -\frac{\mathcal{L}_{m} u}{1-u} \left(\pi^{ij} - \frac{3}{8} \frac{\sqrt{q}}{\kappa N} q^{ij} \mathcal{L}_{m} u\right), \quad (42d)$$

with the Einstein tensor G^{ij} in Σ_i . Organizing the individual parts, a multiplication by $2\kappa/(N\sqrt{q})$ reproduces Eq. (30) apart from the last two terms in the third line, which depend on the acceleration. The boundary term of Eq. (9) solves this issue. The part proportional to u is interpreted as an additional contribution to H_u of Eq. (23a) that contains a total derivative,

$$\Delta_{u} \coloneqq -\int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{\sqrt{q}}{\kappa} D_{l}(ND^{l}u)$$
$$= -\int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{N\sqrt{q}}{\kappa} (D_{l}D^{l}u + a_{l}D^{l}u).$$
(43)

Its Poisson bracket with the canonical momentum density reads

$$\{\pi^{ij}, \Delta_u\} = \frac{N\sqrt{q}}{2\kappa} (a^i D^j u + a^j D^i u), \qquad (44)$$

and provides the missing pieces to Eq. (30).

Next, our focus is on the s^{nn} and s^{ij} sectors. A computation reveals that the first set of Hamilton's equations in Eq. (39a) is satisfied for these sectors, too. Thus, for the Hamiltonians H_1 and H_2 of Eq. (23b) and Eq. (23c), respectively, it holds that

$$\dot{q}_{ij} = \{q_{ij}, H_1\}$$

$$= \left\{ q_{ij}, \int_{\Sigma_t} \mathrm{d}^3 x \frac{1}{1 - s^{\mathbf{nn}}} \left[\frac{p}{2} \mathcal{L}_m s^{\mathbf{nn}} + \frac{2\kappa N}{\sqrt{q}} \left(p^{kl} p_{kl} - \frac{p^2}{2} \right) \right] \right\}$$

$$= 2NK_{ij}, \qquad (45a)$$

$$\begin{aligned} \dot{q}_{ij} &= \{q_{ij}, H_2\} \\ &= \left\{ q_{ij}, \int_{\Sigma_t} \mathrm{d}^3 x \left[\frac{2\kappa N}{\sqrt{q}} \left(P^{kl} P_{kl} - (1 - s^k_{\ k}) \frac{P^2}{2} \right. \right. \\ &\left. - 2s^{kl} (P_{kl} P - P_k^{\ n} P_{nl}) \right) + \left(P_{kl} - \frac{P}{2} q_{kl} \right) \mathcal{L}_m s^{kl} \right] \right\} \\ &= 2N K_{ij}, \end{aligned}$$

where the right-hand sides are given by the extrinsic-curvature tensors of Eq. (34) and Eq. (37), respectively. With that settled, we take a look at the second set of Hamilton's equations of Eq. (39b) for the s^{nn} sector. The individual contributions to the Poisson bracket are

$$-\left\{p^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{\sqrt{q}}{2\kappa} NR\right\}$$
$$= -\frac{\sqrt{q}}{2\kappa} (q^{ij} D_{l} D^{l} N - D^{i} D^{j} N + NG^{ij}), \qquad (46a)$$

$$\begin{cases} p^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{2\kappa N}{\sqrt{q}(1-s^{\mathbf{nn}})} \left(p^{kl} p_{kl} - \frac{p^{2}}{2} \right) \end{cases}$$
$$= -\frac{2\kappa N}{\sqrt{q}(1-s^{\mathbf{nn}})} \left[2p^{ia} p^{j}{}_{a} - p p^{ij} - \frac{1}{2} \left(p_{ab} p^{ab} - \frac{p^{2}}{2} \right) q^{ij} \right], \tag{46b}$$

$$-\left\{p^{ij}, \int_{\Sigma_t} \mathrm{d}^3 x \frac{N\sqrt{q}}{2\kappa} D^l D_l s^{\mathbf{nn}}\right\} = -\frac{N\sqrt{q}}{4\kappa} q^{ij} a_l D^l s^{\mathbf{nn}},$$
(46c)

$$\left\{ p^{ij}, \int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{\mathcal{L}_{m} s^{\mathbf{n}\mathbf{n}}}{2(1-s^{\mathbf{n}\mathbf{n}})} \left(p - \frac{3}{8} \frac{\sqrt{q}}{\kappa N} \mathcal{L}_{m} s^{\mathbf{n}\mathbf{n}} \right) \right\} = -\frac{\mathcal{L}_{m} s^{\mathbf{n}\mathbf{n}}}{2(1-s^{\mathbf{n}\mathbf{n}})} \left(p^{ij} - \frac{3}{16} \frac{\sqrt{q}}{\kappa N} q^{ij} \mathcal{L}_{m} s^{\mathbf{n}\mathbf{n}} \right).$$
(46d)

By using these findings and multiplying by $2\kappa/(N\sqrt{q})$, we arrive at Eq. (35) with the exception of the last two terms in the second line depending on the acceleration. Recall that an analogous issue occurred previously in the *u* sector. The boundary term of Eq. (9) again solves this problem. The part proportional to s^{nn} contributes to H_1 of Eq. (23b) with a total derivative,

$$\Delta_{1} \coloneqq -\int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{\sqrt{q}}{2\kappa} D_{l}(ND^{l}s^{\mathbf{nn}})$$
$$= -\int_{\Sigma_{t}} \mathrm{d}^{3}x \frac{N\sqrt{q}}{2\kappa} (D_{l}D^{l}s^{\mathbf{nn}} + a_{l}D^{l}s^{\mathbf{nn}}). \quad (47)$$

Computing the Poisson bracket of the latter contribution with the canonical momentum density results in

$$\{\pi^{ij}, \Delta_1\} = \frac{N\sqrt{q}}{4\kappa} (a^i D^j s^{\mathbf{nn}} + a^j D^i s^{\mathbf{nn}}), \qquad (48)$$

which is related to the missing parts in Eq. (35).

Finally, the most intricate sector of the s^{ij} coefficients is on the menu. Here, we benefit from the results

$$-\left\{P^{ij}, \int_{\Sigma_{i}} \mathrm{d}^{3}x \frac{\sqrt{q}}{2\kappa} NR\right\} = -\frac{\sqrt{q}}{2\kappa} (NG^{ij} + q^{ij}D_{l}D^{l}N - D^{i}D^{j}N), \tag{49a}$$

$$-\left\{P^{ij}, \int_{\Sigma_{t}} d^{3}x \frac{N\sqrt{q}}{2\kappa} (s^{kl}R_{kl} - D_{l}D_{k}s^{kl})\right\} = \frac{N\sqrt{q}}{4\kappa} (-2q^{ij}[a_{k}D_{l}s^{kl} + s^{kl}(D_{k}a_{l} + a_{k}a_{l})] + a_{k}(D^{i}s^{kj} + D^{j}s^{ki}) - a_{k}D^{k}s^{ij} + q^{ij}(s^{kl}R_{kl} - D_{k}D_{l}s^{kl}) + D_{k}D^{i}s^{kj} + D_{k}D^{j}s^{ki} - D_{k}D^{k}s^{ij}),$$
(49b)

$$\left\{P^{ij}, \int_{\Sigma_l} \mathrm{d}^3 x \left(P_{kl} - \frac{P}{2} q_{kl}\right) \mathcal{L}_m s^{kl}\right\} = \frac{1}{2} \left(P^{ij} q_{kl} \mathcal{L}_m s^{kl} + P \mathcal{L}_m s^{ij}\right) - \left(P^i{}_k \mathcal{L}_m s^{kj} + P^j{}_k \mathcal{L}_m s^{ki}\right), \tag{49c}$$

as well as

$$\left\{ P^{ij}, \int_{\Sigma_{i}} d^{3}x \frac{2\kappa N}{\sqrt{q}} \left[P^{kl}P_{kl} - \frac{1}{2}(1 - s^{k}_{k})P^{2} - 2s^{kl}(PP_{kl} - P_{k}^{n}P_{ln}) \right] \right\}$$

$$= -\frac{\kappa N}{2\sqrt{q}} \left(\left[(1 - s^{k}_{k})P^{2} - 2P^{kl}P_{kl} + 4s^{kl}(PP_{kl} - P_{k}^{m}P_{lm}) \right] q^{ij} + 8[P^{ik}P_{k}^{j} + s^{ik}P_{kl}P^{lj} + s^{jk}P_{kl}P^{li} - s^{ik}PP_{k}^{j} - s^{jk}PP_{k}^{i} + s^{kl}(P^{i}_{k}P_{l}^{j} - P_{kl}P^{ij}) \right] + 2P^{2}s^{ij} - 4(1 - s^{k}_{k})PP^{ij}.$$

$$(49d)$$

We employ the latter findings and multiply by $2\kappa/(N\sqrt{q})$, which yields Eq. (38). Hence, our conclusion is that the Lagrangian and Hamiltonian formulation of Eq. (7) lead to the same dynamics. The lengthy computations necessary to demonstrate this outcome corroborate the nontrivial nature of this property.

VI. OTHER PROJECTIONS OF MODIFIED FIELD EQUATIONS

General Relativity is a theory with constraints [100]. The Hamiltonian and momentum constraints of GR are connected to suitable projections of the Einstein equations [105]. Here, we intend to find out whether or not analogous relationships exist for the modified-gravity theory defined by Eq. (7). It is convenient for reasons of brevity to use more of the notation employed in Ref. [105]. Considering a tensor $T^{\mu\nu}$ of rank 2, the complete projection orthogonal to Σ_t and the mixed projection partially orthogonal to Σ_t , respectively, are written as

$$\mathbf{T}(\mathbf{n},\mathbf{n}) \coloneqq n_{\mu}n_{\nu}T^{\mu\nu}, \qquad \mathbf{T}^{\varrho}(\vec{\mathbf{q}}(.),\mathbf{n}) \coloneqq q^{\varrho}{}_{\mu}n_{\nu}T^{\mu\nu}.$$
(50)

Such projections of the modified Einstein equations were already obtained in Ref. [97], but they were expressed in terms of the extrinsic curvature. In the following, we are resorting to Eqs. (29), (34), and (37) to cast these projections into scalar or vector-valued functions depending on the canonical momenta π^{ij} , p^{ij} and P^{ij} , respectively. Then, the purely orthogonal projections for each of the three sectors are given by

$$2\mathbf{Q}(\mathbf{n},\mathbf{n}) = (1-u)R + 2D_i D^i u -\frac{4\kappa^2}{q(1-u)} \left(\pi_{ij}\pi^{ij} - \frac{\pi^2}{2}\right) - \frac{3(\mathcal{L}_m u)^2}{2(1-u)N^2},$$
(51a)

$$2\mathbf{J}_{1}(\mathbf{n},\mathbf{n}) = R + D_{i}D^{i}s^{\mathbf{n}\mathbf{n}} - \frac{4\kappa^{2}}{q(1-s^{\mathbf{n}\mathbf{n}})}\left(p_{ij}p^{ij} - \frac{p^{2}}{2}\right) - \frac{3(\mathcal{L}_{m}s^{\mathbf{n}\mathbf{n}})^{2}}{8(1-s^{\mathbf{n}\mathbf{n}})N^{2}},$$
(51b)

$$2\mathbf{J}_{2}(\mathbf{n}, \mathbf{n}) = R + s^{ij}R_{ij} - D_{i}D_{j}s^{ij} - \frac{4\kappa^{2}}{q} \left[P_{ij}P^{ij} - (1 - s^{k}_{k})\frac{P^{2}}{2} + 2s^{ij}(P_{ik}P_{j}^{k} - P_{ij}P) \right],$$
(51c)

where the latter holds at first order in the background coefficients and their derivatives. Next, the mixed projections can be checked to be

$$2\mathbf{Q}^{k}(\vec{q}(.),\mathbf{n}) = \frac{2\kappa}{\sqrt{q}} \left[2D_{i}\pi^{ik} + \frac{\pi}{1-u}D^{k}u \right] - \frac{3\mathcal{L}_{m}u}{(1-u)N}D^{k}u,$$
(52a)

$$2\mathbf{J}_{\mathbf{1}}{}^{k}(\vec{q}(.),\mathbf{n}) = \frac{2\kappa}{\sqrt{q}} \left[2D_{i}p^{ik} + \frac{p}{2(1-s^{\mathbf{nn}})}D^{k}s^{\mathbf{nn}} \right] -\frac{3\mathcal{L}_{m}s^{\mathbf{nn}}}{4(1-s^{\mathbf{nn}})N}D^{k}s^{\mathbf{nn}}, \qquad (52b)$$

$$2\mathbf{J_2}^{k}(\vec{q}(.),\mathbf{n}) = \frac{2\kappa}{\sqrt{q}} \left[2D_i P^{ik} + 2s^{ij} D_i P_j^{k} - s^{ik} D_i P + 2(D_i s^{ij}) P_j^{k} + (D^k s^{ij}) P_{ij} - \left(D_i s^{ik} + \frac{1}{2} D^k s_i^{i}\right) P \right],$$
(52c)

with the third result again being valid at first order in the diffeomorphism-violating coefficients and derivatives thereof.

Now, turning to the Hamiltonian formulation of GR, on the one hand, the purely orthogonal projection of the Einstein equations is linked to the Poisson bracket of the EH Hamiltonian with the canonical momentum of the lapse function. On the other hand, the mixed projection connects to the Poisson bracket of the EH Hamiltonian with the canonical momentum of the shift vector. In the modifiedgravity theory based on Eq. (7) analogous correspondences are found to hold. To be able to compute variations for the shift vector, we will be working in general coordinates with a lapse function $N = N(t, \mathbf{x})$ and nontrivial shift vector components, $N^i = N^i(t, \mathbf{x})$. Then, for the purely orthogonal projections,

$$\{\pi_N, H_u\} = \frac{\sqrt{q}}{\kappa} \mathbf{Q}(\mathbf{n}, \mathbf{n}),$$
 (53a)

$$\{p_N, H_1\} = \frac{\sqrt{q}}{\kappa} \mathbf{J}_1(\mathbf{n}, \mathbf{n}), \qquad (53b)$$

$$\{P_N, H_2\} = \frac{\sqrt{q}}{\kappa} \mathbf{J}_2(\mathbf{n}, \mathbf{n}).$$
 (53c)

It is not challenging to check these results, as the dependences of H_u , H_1 , and H_2 in Eq. (23) on the lapse function are plainly transparent. Furthermore, after some more involved calculations, we find for the mixed projections

$$\{\pi^k, H_u\} = \frac{\sqrt{q}}{\kappa} \mathbf{Q}^k(\vec{\mathbf{q}}(.), \mathbf{n}), \qquad (54a)$$

$$\{p^k, H_1\} = \frac{\sqrt{q}}{\kappa} \mathbf{J}_1^k(\vec{\mathbf{q}}(.), \mathbf{n}), \qquad (54b)$$

$$\{P^k, H_2\} = \frac{\sqrt{q}}{\kappa} \mathbf{J}_2^k(\vec{\mathbf{q}}(.), \mathbf{n}).$$
(54c)

To verify the latter results, one must take into account that the shift vector components only occur in the last terms of H_u , H_1 , and H_2 in Eq. (23) as well as the Lie derivatives of the background fields. Note that in contrast to what we inferred in Ref. [97], no additional requirements for the background fields arise when the canonical momenta are employed instead of the extrinsic curvature.

With all the previous findings at hand, we are one step away from glimpsing the difficulties that may arise in the constraint analysis of the modified gravity theory under study. Although the complete constraint analysis is beyond the scope of the present work, we can provide a first idea and identify some possible issues that may arise when performing the Dirac procedure. Our focus is on the *u* sector described by the Hamiltonian of Eq. (23a)

$$H_u \coloneqq \int_{\Sigma_t} \mathrm{d}^3 x \mathcal{H}_u, \tag{55a}$$

$$\mathcal{H}_{u} = -\frac{\sqrt{q}}{2\kappa} N[(1-u)R + 2D^{i}D_{i}u] + \frac{\mathcal{L}_{m}u}{1-u} \left(\pi - \frac{3}{4}\frac{\sqrt{q}}{\kappa N}\mathcal{L}_{m}u\right) + \frac{2\kappa N}{\sqrt{q}(1-u)} \left(\pi^{ij}\pi_{ij} - \frac{\pi^{2}}{2}\right) - 2(D_{i}\pi^{ij})N_{j}.$$
 (55b)

We add to this Hamiltonian the primary constraints $\pi_N \approx 0$ and $\pi_i \approx 0$ with Lagrange multipliers λ and λ^i , respectively,

$$H = \int d^3x (\mathcal{H}_u + \lambda \pi_N + \lambda^i \pi_i).$$
 (56)

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We then evolve both constraints and obtain two additional constraints; a modified Hamiltonian constraint

$$\tilde{\mathcal{H}}^{\perp} = \frac{\sqrt{q}}{2\kappa} N[(1-u)R + 2D^i D_i u] - \frac{3\sqrt{q}}{4\kappa(1-u)N^2} (\mathcal{L}_m u)^2 - \frac{2\kappa N}{\sqrt{q}(1-u)} \left(\pi^{ij}\pi_{ij} - \frac{\pi^2}{2}\right),$$
(57a)

and the standard momentum constraint

$$\mathcal{H}_i = 2D_k \pi^k{}_i. \tag{57b}$$

As in GR, the constraints still generate changes in the canonical variables. So by adjoining them, we can write

$$H = \int d^3x \left[-N\tilde{\mathcal{H}}^{\perp} - \frac{3\sqrt{q}}{2\kappa(1-u)N} (\mathcal{L}_m u)^2 - \mathcal{H}_i N^i + \frac{\mathcal{L}_m u}{1-u} \pi + \lambda \pi_N + \lambda^i \pi_i \right].$$
(58)

At this level we can fix the gauge for the variables N and N^i , which will turn these primary constraints, which are first-class constraints, into second-class constraints and impose them strongly to zero. However, when evolving $\tilde{\mathcal{H}}^{\perp}$, the term proportional to 1/N may produce another constraint that is absent in GR. We believe that the latter additional constraint is a reflection of the broken diffeomorphism symmetry in the theory defined by Eq. (23a). A continuation of this critical analysis will be left for a future work.

VII. OUTLOOK: OTHER MODIFIED-GRAVITY THEORIES AND THE SME

After demonstrating the dynamical consistency of Eq. (1), two additional correspondences between modifiedgravity theories and particular sectors of the gravitational SME shall be presented. By doing so, we intend to foster further interest in SME-related physics.

A. Linearized dRGT massive gravity

The recent paper [42] is dedicated to gaining a better theoretical understanding of dRGT theory with an emphasis on the stability of static solutions as well as certain properties of the linearized theory such as gravitationalwave propagation and the gravitational energy between two pointlike masses. To be able to study the propagation of gravitational-wave modes, the linearized field equations are necessary. In momentum space, they are cast into the form

$$\tilde{O}_{\mu\nu}{}^{\alpha\beta}\tilde{h}_{\alpha\beta}=0, \tag{59}$$

where $\tilde{h}_{\alpha\beta}$ corresponds to the Fourier transform of the dynamical-metric perturbation $h_{\mu\nu} \coloneqq g_{\mu\nu} - \eta_{\mu\nu}$ and $\tilde{O}_{\mu\nu}{}^{\alpha\beta}$ is a tensor-valued operator in momentum space given by their Eq. (82). Furthermore, the authors describe the reference metric via a small deviation from the frequently taken Minkowski metric $\eta_{\mu\nu}$, i.e., they define $\delta f^{\mu\nu} := f^{\mu\nu} - \eta^{\mu\nu} \ll 1$. All results are stated at first order in the perturbation $\delta f^{\mu\nu}$.

The modifications of GR are proportional to five dimensionless parameters c_i with $i \in \{1...5\}$. Now, all possible background fields with an arbitrary mass dimension preserving or violating diffeomorphism invariance in linearized gravity are classified in Ref. [117]. Appropriate background fields violating diffeomorphism invariance can be associated with each of these contributions via their symmetry properties and momentum dependences. The only suitable coefficients are those of mass dimension 2 that are totally symmetric and not contracted with additional momenta, $k^{(2,1)\mu\nu\rho\sigma}$. For these SME coefficients we refer to line 11 in Table 1 of Ref. [117]. Then

$$k^{(2,1)\mu\nu\varrho\sigma} = -\frac{m^2}{2} (c_1(\eta^{\varrho(\mu}\eta^{\nu)\sigma} - \eta^{\mu\nu}\eta^{\varrho\sigma}) + c_2\eta^{(\varrho\mu}\eta^{\sigma\nu)} + c_3(\eta^{-1}\delta f)\eta^{\varrho(\mu}\eta^{\nu)\sigma} + c_4[\delta f^{\mu\nu} - \eta^{\mu\nu}(\eta^{-1}\delta f)]\eta^{\varrho\sigma} + c_5\eta^{\mu\nu}\delta f^{\varrho\sigma}),$$
(60)

where m is the graviton mass and indices enclosed by a pair of parentheses indicate that a symmetrization is performed in these indices. The latter coefficients characterize the linear regime of dRGT massive gravity completely.

B. Hořava-Lifshitz gravity

Hořava-Lifshitz gravity [69,70] is a possible UV completion of GR. Its formulation relies on a foliation of spacetime into purely spacelike hypersurfaces via the ADM decomposition, while the leading contributions read [118]

$$S_{\rm HL} = \frac{1}{16\pi G_H} \int_{\mathcal{M}} dt d^3 x N \sqrt{q} (\xi R + K_{ij} K^{ij} - \lambda K^2 + \alpha a_i a^i),$$
(61)

with the extrinsic curvature K_{ij} and the acceleration a_i defined directly under Eq. (5). Furthermore, the action involves dimensionless dynamical parameters ξ , λ , α as well as the dimensionful gravitational constant G_H of this theory. A significant property of Hořava-Lifshitz gravity are different weight factors associated with the contributions $K_{ij}K^{ij}$ and K^2 . As it turns out, it is this property that makes a match to the *u* and $s^{\mu\nu}$ sectors of Eq. (7) presumably impossible. The authors of Ref. [108] also observed this issue, which is why they added further would-be dynamical terms to their action to enable a match. An alternative is to match Eq. (61) with a setting known as Einstein-Aether theory [119–121]. By doing so, the corresponding SMEbased Lagrange density is readily obtained as

$$\mathcal{L}_{\text{gravity}}^{(2)} = \frac{1}{2\kappa} \check{k}^{(2)}, \qquad \check{k}^{(2)} = k_{\kappa\lambda\mu\nu} g^{\kappa\mu} g^{\lambda\nu} + k_{\mu\nu} g^{\mu\nu}, \quad (62a)$$

with the background fields

$$k_{\kappa\lambda\mu\nu} = -\left(1 + \frac{\lambda}{\xi}\right) \nabla_{\kappa} u_{\mu} \nabla_{\lambda} u_{\nu} + \left(1 + \frac{1}{\xi}\right) \nabla_{\kappa} u_{\lambda} \nabla_{\nu} u_{\mu},$$
(62b)

$$k_{\mu\nu} = -\frac{\alpha}{\xi} u^{\kappa} u^{\lambda} \nabla_{\kappa} u_{\mu} \nabla_{\lambda} u_{\nu}, \qquad (62c)$$

where $\xi = G_H/G_N$ and u^{μ} is a unit vector orthogonal to the spacelike hypersurfaces of the spacetime foliation. Here we refer to the second line of Table XVI and Eq. (41) of Ref. [42]. Note that the author of Ref. [121] uses the metric signature (+, -, -, -), which is different from that of Ref. [42].

VIII. CONCLUSIONS

This work was dedicated to a modified-gravity theory incorporating nondynamical background fields that break diffeomorphism invariance explicitly. We focused on two distinct types of background fields: a scalar field denoted as u and a tensor-valued one known as $s^{\mu\nu}$ in the SME literature [21,22]. The latter decomposes into a purely timelike and a purely spacelike sector. The canonical Hamiltonian had already been obtained in the previous article [97] and formed the base of the current paper.

On the one hand, the ADM decomposition allowed us to project the modified Einstein equations into purely spacelike hypersurfaces. On the other hand, the Hamilton-Jacobi equations gave rise to another set of field equations for the theory. We have found that both approaches are consistent with each other. Similarly, projections completely orthogonal to spacelike hypersurfaces as well as partial projections into such hypersurfaces were shown to correspond to functional derivatives of the Hamiltonian for the lapse function and the shift vector componentes, respectively.

These outcomes are highly nontrivial, as nondynamical background fields transform unconventionally under diffeomorphisms. Hence, the structure of such theories is rendered substantially obscure as opposed to GR or extensions thereof with diffeomorphism symmetry either intact or broken spontaneously. Furthermore, having to add the suitable boundary terms of Eqs. (8) and (9) to the action to perform the match between these two approaches emphasizes the importance of our analysis. The latter is the first of its kind in the literature when it comes to the gravitational SME. In principle, the Dirac procedure could imply additional sets of constraints beyond those of GR. However, our findings indicate that the canonical Hamiltonian completely encodes the dynamical properties of the gravitational theory under study. Furthermore, they corroborate the results derived previously in Ref. [97].

The setting investigated is quite generic and links to several popular modified-gravity models proposed in the literature such as Brans-Dicke theory and dRGT massive gravity. Hence, this investigation could also arouse interest of scientists not having had contact to the gravitational SME, so far. Furthermore, with the Hamiltonian of Eq. (23) established and its correctness backed up by the current findings, this article plays a significant role in paving the pathway for phenomenological studies of Eq. (1), e.g., in cosmology or systems of strong gravitational fields such as black holes. Additional explorations of the constraint structure are beyond the scope of this paper and will be pursued in a future work. Gaining a better understanding of the SME sectors identified in Secs. VII A and VII B by utilizing the methodology employed here may be further worthwhile projects.

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