

Detecting and reconstructing gravitational waves from the next galactic core-collapse supernova in the advanced detector era

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We performed a detailed analysis of the detectability of a wide range of gravitational waves derived from core-collapse supernova simulations using gravitational-wave detector noise scaled to the sensitivity of the upcoming fourth and fifth observing runs of the Advanced LIGO, Advanced Virgo, and KAGRA. We use the coherent WaveBurst algorithm, which was used in the previous observing runs to search for gravitational waves from core-collapse supernovae. As coherent WaveBurst makes minimal assumptions on the morphology of a gravitational-wave signal, it can play an important role in the first detection of gravitational waves from an event in the Milky Way. We predict that signals from neutrino-driven explosions could be detected up to an average distance of 10 kpc, and distances of over 100 kpc can be reached for explosions of rapidly-rotating progenitor stars. An estimated minimum signal-to-noise ratio of 10–25 is needed for the signals to be detected. We quantify the accuracy of the waveforms reconstructed with coherent WaveBurst and we determine that the most challenging signals to reconstruct are those produced in long-duration neutrino-driven explosions, and models that form black holes a few seconds after the core bounce.

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I. INTRODUCTION

The discovery of gravitational waves (GWs) from a binary black hole merger [1] marked the beginning of GW astronomy. Similarly, the discovery of a binary neutron star in both GW and electromagnetic spectra [2] began the era of multimessenger astronomy with GWs. While the first, second, and third observing runs (O1, O2, O3) brought a wealth of binary coalescence discoveries [3,4], we expect these numbers to grow with upcoming detector upgrades. Currently, all detected sources are binary systems and we are waiting for a short-duration GW transient (burst). The most prominent source is a core-collapse supernova (CCSN).

Core-collapse supernova explosions (CCSNe) are the violent explosions of massive stars (above $8 M_{\odot}$) and are believed to form most of the black holes (BHs) detected by Advanced LIGO [5] and Advanced Virgo [6]. Despite the growing understanding of stellar collapse, the explosion mechanism is not yet fully understood [7]. All supernovae known to date were detected electromagnetically and low-energy neutrinos were observed from only SN 1987A [8–10]. Unfortunately, the measured light is emitted after the initial collapse, losing most of the detailed information about the explosion mechanism. To understand CCSNe we need to be able to directly probe their inner dynamics. The neutrinos and GWs leave the core around the collapse time and they can be used to directly probe the supernova engine. A future detection of neutrinos will allow us to

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probe mainly the thermodynamic properties of the collapsed core and GWs will allow us to understand the dynamics of moving matter. While neutrinos were already detected from SN 1987A [8–10], GWs from a CCSN have not yet been observed.

CCSNe are stochastic in nature due to the turbulent flow of matter and so are the predicted detailed GW time series. Detecting these bursts is challenging and requires algorithms that operate when the signals cannot be robustly predicted besides the same general constraints in bandwidth and duration. The detection and reconstruction algorithms should be designed for a large range or even unexpected GW morphologies. So far, few algorithms were used to search for GWs from CCSNe. In 2005, a search targeting CCSN bursts was performed using TAMA300 data using an excess-power filter [11]. In 2016, LIGO, Virgo and GEO 600 [12] performed a search [13] using the excess-power coherent WaveBurst (cWB) [14] and X-pipeline [15] search algorithms. In 2020, LIGO-Virgo conducted an analogous search [16] using only cWB. The generic all-sky searches also have the potential to detect CCSN GW bursts. Several searches were conducted prior to the observing runs of the advanced detectors (see e.g., [17–19]). During O1 and O2, LIGO-Virgo performed searches for GW bursts [20,21] using cWB, oLIB [22], and BayesWave [23] as a follow up of the detection candidate events.

Although the predicted signal morphologies are uncertain, some consensus emerged from the multidimensional supernova simulations [24–26]. This knowledge is useful for improving the existing methods for searches, reconstructing waveforms, and inferring physical properties. Being non-deterministic, matched filtering cannot be used and methods should allow for uncertainties in the signal models. Among these methods are principal component analysis [27–30], Bayesian inference [28–32], machine learning [33–37], denoising techniques [38], and others [39–41]. These methods apply the knowledge of CCSN models to different degrees. Given the nondeterministic nature of CCSNe and uncertainties of the models, a detection algorithm should use weak or minimal assumptions.

Detecting GWs from exploding stars is a challenge and the search algorithms should be developed before the next nearby CCSN event happens. The cWB algorithm is used regularly in searching for a variety of GWs (e.g., [16,20,21,42,43]) with minimal assumptions on the signal morphologies. It regularly detects GWs from binary BH mergers [3,4], it was the only search algorithm to detect GW150914 in low latency [44] and recently it observed the first GW detection of an intermediate-mass binary black hole, GW190521 [45,46]. The cWB search was performing low-latency analysis during each observing run of the advanced detectors and during O3 it was the only algorithm capable of detecting GW bursts in low latency. It is therefore a promising tool for the first detection of GWs from the next nearby CCSN.

Prospects for the detection of GWs from CCSNe with the Advanced LIGO and Virgo detectors was previously discussed in Gossan *et al.* [47]. Since then, improvements to the algorithms have resulted in the cWB CCSN search becoming more sensitive [16] than the previous CCSN analyses performed with the X-pipeline algorithm used in Refs. [13,47]. The detectors were upgraded, for example, light squeezing was introduced [48], KAGRA joined the network of GW detectors [49], as well as further upgrades outlined in [49]. The multidimensional CCSN simulations have advanced significantly, including longer-duration three-dimensional simulations that predict the entire GW signal, a better coverage of the CCSN parameter space, and an increase in the number of three-dimensional simulations with respect to [47], and the explosions result in larger GW amplitudes (e.g., [50,51]).

Given all these advances, it is important to understand the feasibility of detecting and reconstructing GWs from the next Galactic or near extra-Galactic CCSN with the planned observations and revisit some of the previous results. In this paper, we perform an extensive analysis of simulated state of the art GW signals and make predictions for the fourth and fifth observing runs (O4 and O5). Using a large set of predicted GW signals we provide basic properties, compare their energy evolution, spectra, and we list the dominant emission processes. While the previous predictions did not discuss the statistical significance and they relied on data from the initial GW detectors that were available at that time [47], we use O2 data rescaled to the projected sensitivities of O4 and O5 in such a way that the features of the noise are preserved. Similar to the LIGO-Virgo searches, we perform a background analysis that allows measuring the statistical significance of the detected events. It is important to stress that the statistical significance of a detection statement is fundamental. Any astrophysical evaluation from the reconstructed GW needs to rely on the significance of an event. For the detection sensitivity studies, a fixed significance level allows comparing the performance of different algorithms on the same data set. The results presented in this paper assume that the events are detected at a high significance level.

Given the uncertainties of the predicted GW signals, we use a wide range of models. We significantly expanded the list of analyzed waveforms in comparison to the previous studies of Refs. [13,16,47]; we include signals that became available at the start of the analysis. The adapted waveform families aim to reflect the landscape of GWs and the richness of physical processes in CCSNe. We describe the challenges of detecting these physical processes. We also quantify the reconstruction accuracy for a wide range of GW morphologies.

The paper structure is as follows. The multidimensional CCSN models and the waveforms used in this paper are described in Sec. II. We highlight the main GW emission

processes and the basic properties of the waveforms, such as their duration, energy, or spectrum. Section III outlines the adopted method that consists of the cWB search pipeline, noise rescaling technique, the background estimation, sensitivity analysis, and the procedure to quantify the accuracy of the cWB reconstruction. Section IV provides the results. Using data from the LIGO detectors, we determine the distance of a CCSN source and how strong the GW signal should be to be detected by cWB. We specify the reconstruction accuracy of the analyzed waveforms and indicate the challenges regarding the reconstruction of certain GW morphologies. The inclusion of the Virgo and KAGRA [52] detectors is also outlined. Finally, Sec. V is a summary of the obtained results.

II. CORE-COLLAPSE SUPERNOVA

During its lifetime a massive star burns its fuel by the means of nuclear fusion. A star's structure becomes an onion shape with an iron core in the center. When a core exceeds the Chandrasekhar mass (around $1.4 M_{\odot}$), the gravitational force is so strong that the core collapses, thus forming a very hot proton-neutron star (PNS). Further evolution may lead to an explosion, the collapse to a BH, or a combination of these fates. While the explosion mechanism is currently not settled (see [7] for a review), it is believed that the massive flux of neutrinos from the PNS plays a crucial role. In this so-called neutrino-driven mechanism, the neutrinos heat up the matter creating a shock that eventually may blow up the star (see [24,53] for a review). When a progenitor star rotates rapidly and has a strong magnetic field, the magnetorotationally-driven (MHD-driven) mechanism is more likely to explain a CCSN explosion. In the latter case, a seed magnetic field is largely magnified by the star's rotation giving a rise to jets moving along the rotational axis that can contribute to destroying the star (e.g., [54–56]). In the quantum chromodynamics phase-transition mechanism, the accreting matter increases PNS density and temperature (e.g., [57,58]). When the PNS collapses, the phase transition to quark matter may occur launching a shock dominating an explosion. In the case when the shock-revival mechanism fails or matter continues accreting (fallback), a star undergoes BH formation (e.g., [59–65]). In the extreme emission models (e.g., [66,67]), the PNS may be highly deformed due to a very rapid rotation of a progenitor star or even fragmented. While the fraction of CCSNe that form BHs is uncertain, it can be up to 20% [68,69]. Around 99% of the explosions are believed to be neutrino-driven and the rest 1% are MHD-driven if the numbers are correlated with the observed neutron stars and gamma-ray bursts [7,70].

For the neutrino-driven mechanism, the CCSN evolution can be divided into a few phases [71–74]. Here, we describe this evolution using three generic stages. During the first phase, the iron core collapses and bounces when it reaches nuclear densities. The supersonic collapse of the iron core

and the infalling external layers launches an initial shock that expands and halts, producing a decrease in frequency prompt-convection GW signal (up to 1 kHz, typically low frequency). This emission is followed by a relatively short quiescent period. The second phase begins around 100 ms with a strong rise of a neutrino outflow from the hot PNS. The neutrinos deposit energy in the turbulent matter between the PNS and the shock wave pushing it outward. This shock revival mechanism is crucial for a star to explode. For a few hundred milliseconds the effect of the neutrino heating on the shock is competing with the accreting matter. This phase can also induce neutrino-driven convection between the shock and the PNS surface. The shock itself can oscillate (in linear and spiral motion) which is referred to as the standing-accretion shock instability (SASI) [75]. These aspherical matter movements produce low-frequency SASI/convection-GW signals in the frequency band where GW detectors are most sensitive (up to around 300 Hz). During this phase, the PNS is stiffening over time because of the residual electron capture and it is excited continuously by the accreting matter. The restoring force for these oscillations can be gravity, surface, or pressure, that results in g -, f -, p -modes that are visible in their GW signals (typically evolving from around 100 Hz to 2 kHz). If the shock expansion is fully revived, the explosion phase occurs, and the accretion continues at a smaller rate and the SASI and convection usually die out—but a weak convection can last for tens of seconds [76–79].

When a progenitor star rotates rapidly, the explosion mechanism is likely to be MHD-driven. In this scenario, rapid rotation flattens the iron core, producing an axisymmetric collapse and a strong linearly polarized GW bounce signal (up to around 1 kHz). The latter stages after bounce are not yet well understood because of insufficient MHD microphysics in the numerical simulations (even if very active research is ongoing [24,25]). Regardless of the progenitor star rotation, if the shock is not revived and the matter continues to fall, the PNS can collapse further to a BH. The BH formation GW signal ends abruptly at the moment of the event horizon creation (it can be up to a few kHz).

A. CCSN models

For more than 50 years various efforts have been made to understand the mechanism of evolution of supernovae [80]. Despite the progress in theoretical and numerical simulations, the dynamics of CCSN explosions are not yet fully understood as extremely complex physics poses many open questions and challenges. For many years, the calculations were performed in one-dimensional and two-dimensional (2D) simulations. Significant progress has been made in recent years with many full three-dimensional (3D) self-consistent simulations. Despite a large number of 3D CCSN simulations, the number of publicly available GW

signals is limited because of the computational cost of extracting them.

Table I summarizes the basic information about numerical methods, types of GW emissions predicted by the simulations, and properties of example waveforms used in this work. We analyzed 82 waveforms from 18 waveform families. We study waveforms from 2D and 3D simulations that were available at the beginning of the analysis. We do not analyze GW signals from older simulations (e.g., [81–85]) and those that became available during our analysis (e.g., [64,86–89]). The set reflects the landscape of available GW signals for a variety of progenitor star

parametrizations, physics approximations, and GW signal properties.

The approximations in the numerical setup of the simulations affect GW production. The axisymmetric 2D models produce by definition linearly polarized signals (h_+ and $h_\times = 0$), while two polarizations (h_+ and h_\times) are available for 3D simulations. The equation of state (EOS) of the dense matter is an important ingredient; they can range from softer to stiffer and they may alter GW signatures. The EOSs mentioned in Table I are: LS, LS180, LS220 [101], Shen [102], DD2, TM1 [103], SFHx, SFHo [104], and others. Various efforts are

TABLE I. Waveforms from multidimensional CCSN simulations described in the text. For each waveform family we provide a reference, dimensionality, a summary of the numerical method (EOS and code name) and observed GW features. Then, we provide details for example waveforms: identifier, progenitor stellar mass M_{star} , initial central angular velocity Ω_c , the frequency f_{peak} at which the GW energy spectrum peaks, the emitted GW energy E_{GW} and approximate signal duration. The superscript symbols: *non-ZAMS, *the simulation was stopped before the full GW signal was developed.

Waveform Family	Numerical Method	GW Features	Waveform Identifier	M_{star} [M_\odot]	Ω_c [rad/s]	f_{peak} [Hz]	E_{GW} [$M_\odot c^2$]	Duration [ms]
Abdikamalov <i>et al.</i> 2014, 2D [90]	LS220, Shen CoCoNuT	Bounce prompt-conv.	A1O01.0	12	1.0	819	9.4×10^{-9}	50*
			A2O01.0	12	1.0	854	1.7×10^{-8}	50*
			A3O01.0	12	1.0	867	7.0×10^{-9}	50*
			A4O01.0	12	1.0	873	4.2×10^{-9}	50*
Andresen <i>et al.</i> 2017, 3D [51]	LS220 CoCoNuT PROMETHEUS	g -modes SASI (spiral) convection	s11	11.2	...	642	1.1×10^{-10}	350*
			s20	20	...	687	7.4×10^{-10}	430*
			s20s	20	...	693	1.4×10^{-9}	530*
			s27	27	...	753	4.4×10^{-10}	570*
Andresen <i>et al.</i> 2019, 3D [91]	LS220 PROMETHEUS	SASI (spiral) g -modes	m15fr	15	0.5	689	2.7×10^{-10}	460*
			m15nr	15	...	820	1.5×10^{-10}	350*
			m15r	15	0.2	801	7.1×10^{-11}	380*
Cerdá-Durán <i>et al.</i> 2013, 2D [59]	LS220 CoCoNuT	BH formation g -modes, SASI/conv.	Fiducial	35	2.0	922	3.3×10^{-7}	1620
			Slow	35	1.0	987	9.4×10^{-7}	1050
Dimmelmeier <i>et al.</i> 2008, 2D [92]	LS, Shen CoCoNuT	Bounce prompt-conv.	s15A2O09-ls	15	4.6	743	2.7×10^{-8}	60*
			s15A3O15-ls	15	13.3	117	5.2×10^{-9}	340*
			s20A3O09-ls	20	9.0	615	2.2×10^{-8}	80*
Kuroda <i>et al.</i> 2016, 3D [93]	SFHx, DD2, TM1 3D-GR	g -modes SASI	SFHx	15	...	718	2.1×10^{-9}	350*
			TM1	15	...	714	1.7×10^{-9}	350*
Kuroda <i>et al.</i> 2017, 3D [94]	SFHx, DD2, TM1 3D-GR	g -modes SASI/convection	s11.2	11.2	...	195	1.3×10^{-10}	190*
			s15.0	15	...	430	3.1×10^{-9}	210*
Mezzacappa <i>et al.</i> 2020, 3D [73]	LS220 CHIMERA	g -, p -modes SASI/convection	c15-3D	15	...	1064	6.4×10^{-9}	420*
Morozova <i>et al.</i> 2018, 2D [95]	LS220, DD2, SFHo FORNAX	f -, g -, p -modes SASI/convection	M10_LS220	10	...	1594	2.4×10^{-9}	1210
			M10_DD2	10	...	1544	1.7×10^{-9}	1700
			M13_SFHo	13	...	976	1.1×10^{-8}	1360
			M19_SFHo	19	...	1851	6.3×10^{-8}	1540
Müller <i>et al.</i> 2012, 3D [71]	JM PROMETHEUS	SASI/convection	L15-3	15	...	144	2.2×10^{-11}	1400
			N20-2	20	...	147	1.1×10^{-11}	1500
			W15-4	15	...	208	2.5×10^{-11}	1300

(Table continued)

TABLE I. (Continued)

Waveform Family	Numerical Method	GW Features	Waveform Identifier	M_{star} [M_{\odot}]	Ω_c [rad/s]	f_{peak} [Hz]	E_{GW} [$M_{\odot}c^2$]	Duration [ms]
O'Connor and Couch 2018, 3D [96]	SFHo FLASH	g -modes SASI/convection	mesa20	20	...	1121	6.3×10^{-10}	500*
			mesa20_LR	20	...	1199	2.2×10^{-9}	650*
			mesa20_pert	20	...	1033	9.5×10^{-10}	530*
			mesa20_v_LR	20	...	887	1.0×10^{-10}	480*
Ott <i>et al.</i> 2013, 3D [97]	LS220 Zelmani	Prompt-conv. g -modes	s27-fheat1.00	27	...	836	4.0×10^{-10}	190*
			s27-fheat1.05	27	...	385	3.4×10^{-10}	190*
			s27-fheat1.10	27	...	340	3.3×10^{-10}	190*
			s27-fheat1.15	27	...	839	3.1×10^{-10}	190*
Powell and Müller 2019, 3D [98]	LS220 CoCoNuT-FMT	g -modes	s3.5_pns	3.5 [†]	...	878	3.6×10^{-9}	700
			s18	18	...	872	1.6×10^{-8}	890
Powell and Müller 2020, 3D [99]	LS220 CoCoNuT-FMT	f -, g -modes SASI prompt-conv.	s18np	18	3.4	742	7.7×10^{-8}	1000
			m39	39	...	674	7.5×10^{-10}	560
			y20	20	...	872	1.0×10^{-8}	980
Radice <i>et al.</i> 2019, 3D [50]	SFHo FORNAX	f -, g -modes SASI/convection prompt-conv.	s9	9	...	727	1.6×10^{-10}	1100
			s13	13	...	1422	5.9×10^{-9}	800*
			s25	25	...	1132	2.8×10^{-8}	600*
Richers <i>et al.</i> 2017, 2D [100]	18 EOSs CoCoNuT	Bounce prompt-conv.	A467_w0.50_SFhx	12	0.5	891	1.6×10^{-8}	60*
			A467_w0.50_LS220	12	0.5	820	5.1×10^{-9}	60*
			A467_w9.50_SFhx	12	9.5	448	4.2×10^{-8}	60*
			A467_w9.50_LS220	12	9.5	863	4.1×10^{-8}	60*
Scheidegger <i>et al.</i> 2010, 3D [54]	LS180 Pen	Bounce prompt-conv. convection	R1E1CA_L	15	0.3	1103	1.2×10^{-10}	90*
			R3E1AC_L	15	6.3	588	2.2×10^{-7}	110*
			R4E1FC_L	15	9.4	683	3.9×10^{-7}	100*
Yakunin <i>et al.</i> 2015, 2D [72]	LS220 CHIMERA	g -modes SASI/convection prompt-conv.	B12	12	...	708	3.4×10^{-9}	1300
			B15	15	...	865	7.9×10^{-9}	1100
			B20	20	...	602	4.2×10^{-9}	900
			B25	25	...	1022	1.4×10^{-8}	1140

conducted for approximating general relativity, neutrino treatment and other physical processes. Some of the approaches used to calculate waveforms we analyze are: CoCoNuT [105], CoCoNuT-FMT [106], PROMETHEUS [107], CHIMERA [108], FLASH [109], Zelmani [110], JM (Janka and Müller [111]), Pen (Pen *et al.* [112]), and 3D-GR [113].

For all waveforms, we provide information about the progenitor star masses M_{star} that range from $3.5 M_{\odot}$ to $60 M_{\odot}$. The $3.5 M_{\odot}$ progenitor is an ultrastripped helium star and all other progenitors have zero-age main-sequence (ZAMS) masses. The rotation of the stars is modeled to be differential and the initial central angular velocity Ω_c is provided. The peak frequency f_{peak} is calculated from the energy spectra and the GW energy E_{GW} is the source angle averaged. The waveform duration is the time from the moment of the collapse until the end of the simulations. Due to a large computational cost, some of the simulations are stopped before the full GW signal develops. This is marked in the table.

Abdikamalov *et al.* 2014 [90] (Abd + 14) study extensively the influence of the angular momentum distribution on the GW signal of rotating collapse, bounce, and the very early postbounce ring-down phase. We analyzed six waveforms: AbdA1O01.0, AbdA2O01.0, AbdA3O01.0, AbdA3O06.0, AbdA4O01.0, and AbdA5O01.0. Abd + 14 do not investigate the postbounce turbulence and its GW production.

Andresen *et al.* 2017 [51] (And + 17) study GW signals from 3D neutrino hydrodynamics simulations of CCSNe. GW emission in the preexplosion phase strongly depends on whether the postshock flow is dominated by SASI and g -mode frequency components in their signals.

Andresen *et al.* 2019 [91] (And + 19) study the impact of moderate progenitor rotation on the GW signals. The stellar evolution calculations include magnetic fields with low angular momentum. GW emission in the preexplosion phase strongly depends on whether the postshock flow is dominated by the SASI with neutrino transport and g -mode frequency components in their signals.

Cerdá-Durán *et al.* 2013 [59] (Cer + 13) analyze GW emission of the BH formation in the collapsar scenario. The model consists of a rapidly-rotating progenitor with LS220. GW emission in the preexplosion phase strongly depends on whether the postshock flow is dominated by the SASI/convection and g -mode frequency components in their signals.

Dimmelmeier *et al.* 2008 [92] (Dim + 08) conduct extensive studies of rotating core collapse and the impact of the rotational profiles, progenitor masses, and EOS. The GW signal is dominated by the core bounce and prompt-convection, depending primarily on the rotation. We analyzed six waveforms: s15a2o05_ls, s15a2o09_ls, s15a3o15_ls, s20a1o05_ls, s20a3o09_ls, and s20a3o13_ls. Similarly to Abd + 10, the postbounce signal is not investigated in this simulation.

Kuroda *et al.* 2016 [93] (Kur + 16) study the impact of the EOSs on the GW signatures using a $15 M_{\odot}$ progenitor star. GW emission in the preexplosion phase strongly depends on whether the postshock flow is dominated by the SASI/convection and g -mode components in their signals. For the TM1 waveform, only one angle orientation was available to analyze.

Kuroda *et al.* 2017 [94] (Kur + 17) is a continuation of Kur + 16 work. Two additional explosions are analyzed, with $11.2 M_{\odot}$ and $40 M_{\odot}$ progenitor stars. Their study suggests a correlation between neutrino fluxes and GWs from the SASI. For both waveforms only one angle orientation was available.

Mezzacappa *et al.* 2020 [73] (Mez + 20) study the details of the GW emission origins and their results replace those of Yakunin *et al.* [114]. The GW signals have two key features: low-frequency emission (<200 Hz) that emanates from the gain layer as a result of neutrino-driven convection, and the SASI and high-frequency emission (>600 Hz) that emanates from the PNS due to convection within it.

Morozova *et al.* 2018 [95] (Mor + 18) explore the impact of progenitor star mass, rotation, EOS, and neutrino microphysics on the GW signatures. Depending on the setup, they find f -, g - and p -modes. We analyzed eight waveforms: M10_LS220, M10_LS220_no_manybody, M10_SFHo, M10_DD2, M13_SFHo, M13_SFHo_multipole, M13_SFHo_rotating, and M19_SFHo.

Müller *et al.* 2012 [71] (Mul + 12) study the neutrino and GW signatures from neutrino-driven explosions. The GW signatures are dominated by the low-frequency (100–500 Hz) convective matter movement.

O'Connor and Couch 2018 [96] (Oco + 18) analyze the impact of the progenitor asphericities, grid resolution and symmetry, dimensionality, and neutrino physics. The GW signals are dominated by the g -mode and the SASI activity is strong. We analyze seven waveforms: mesa20, mesa20_LR, mesa20_pert, mesa20_pert_LR, mesa20_v_LR, mesa20_2D, and mesa20_2D_pert.

Ott *et al.* 2013 [97] (Ott + 13) study the post-core-bounce phase focusing on SASI and neutrino-driven convection development. Shortly after the bounce, the cores are strongly deformed by the prompt-convection that dominates the GW emission.

Powell and Müller 2019 [98] (Pow + 19) analyze models with low and regular CCSN explosion energies, and perform simulations covering all evolution phases. Both GW signals show emissions from g -modes that peak at high frequencies.

Powell and Müller 2020 [99] (Pow + 20) study explosion properties of three progenitor star masses including the impact of rotation in the m39 model. The waveforms from the m39 and y20 models produce very strong GW emissions due to the rapid rotation and very strong neutrino-driven convection, respectively. The s18np model is the same as the s18 model in Pow + 19, but without perturbations, which prevents shock revival and produces strong SASI.

Radice *et al.* 2019 [50] (Rad + 19) explore the dependence of the GW properties on the progenitor star mass, which ranges from $9 M_{\odot}$ to $60 M_{\odot}$. The signals are dominated by f - and g -modes, but some of them also show strong SASI or prompt-convection signatures. We analyzed 10 waveforms: s9, s10, s11, s12, s13, s14, s15, s19, s25, s60.

Richers *et al.* 2017 [100] (Ric + 17) perform an extensive analysis of the bounced signal. They show that the signal is largely independent of the choice of EOS, but it is sensitive to the rotational parameters. We analyzed twelve waveforms: A467w0.50_BHBLP, A467w0.50_GShenFSU2.1, A467w0.50_HSDD2, A467w0.50_LS220, A467w0.50_SFHo, A467w0.50_SFHx, A467w9.50_BHBLP, A467w9.50_GShenFSU2.1, A467w9.50_HSDD2, A467w9.50_LS220, A467w9.50_SFHo, and A467w9.50_SFHx. As for Abd + 14 and Dim + 08, the postbounce phase is not simulated.

Scheidegger *et al.* 2010 [54] (Sch + 10) show a systematic study of GW signatures from neutrino-driven explosions based on 3D MHD simulations. They study the effects of the EOS, initial rotational rate, and the magnetic field. We analyze three waveforms that vary in rotation.

Yakunin *et al.* 2015 [72] (Yak + 15) study the full GW evolution from simulations with four progenitor star masses. These waveforms capture several stages of the explosion. All GW signals show both low (SASI/convection) and high (g -mode) frequency components.

B. Gravitational wave calculations

The quadrupole approximation is commonly used to extract GWs generated by the accelerating matter in CCSNe. The quadrupole radiation is extensively described in the literature (e.g., [115–117]). The metric perturbation \mathbf{h}_{ij}^{TT} in the transverse-traceless (TT) gauge can be expressed as

$$\mathbf{h}_{ij}^{TT}(t, \mathbf{x}) = \frac{1}{D} \frac{2G}{c^4} \ddot{Q}_{ij}^{TT}(t - D/c, \mathbf{x}), \quad (1)$$

where $i, j = \{1, 2, 3\}$ are indices in Cartesian coordinates, c is the speed of light, D is the distance to the source, G is the gravitational constant, and the dots represent the second time derivative. The traceless quadrupole moment Q_{ij}^{TT} is defined as

$$Q_{ij}^{TT}(t, \mathbf{x}) = \int d^3x \rho(t, \mathbf{x}) \left(x_i x_j - \frac{1}{3} \delta_{ij} |\mathbf{x}|^2 \right), \quad (2)$$

where ρ is a mass density and δ_{ij} is the Dirac delta. For practical reasons, usually the traceless \ddot{Q}_{ij}^{TT} is directly extracted from the multidimensional CCSN simulations. However, it is not always the case and in our analysis we unified all the outputs from the CCSN simulations into traceless \ddot{Q}_{ij}^{TT} . For simplicity, we omit TT from \ddot{Q}_{ij}^{TT} .

The metric perturbation can also be written as

$$\mathbf{h}_{ij}^{TT} = h_+ \mathbf{e}_+ + h_\times \mathbf{e}_\times, \quad (3)$$

where \mathbf{e}_+ and \mathbf{e}_\times are unit plus- and cross-polarization tensors. Using a coordinate transformation between Cartesian and spherical coordinates, the GWs radiated in the (θ, ϕ) direction are expressed as [117]

$$h_+ = \frac{1}{D} \frac{2G}{c^4} (\ddot{Q}_{\theta\theta} - \ddot{Q}_{\phi\phi}), \quad (4)$$

$$h_\times = \frac{1}{D} \frac{G}{c^4} \ddot{Q}_{\theta\phi}, \quad (5)$$

where

$$\begin{aligned} \ddot{Q}_{\theta\phi} &= (\ddot{Q}_{22} - \ddot{Q}_{11}) \cos \theta \sin \phi \cos \phi \\ &+ \ddot{Q}_{12} \cos \theta (\cos^2 \phi - \sin^2 \phi) \\ &+ \ddot{Q}_{13} \sin \theta \sin \phi - \ddot{Q}_{23} \sin \theta \cos \phi, \end{aligned} \quad (6)$$

$$\ddot{Q}_{\phi\phi} = \ddot{Q}_{11} \sin^2 \phi + \ddot{Q}_{22} \cos^2 \phi - 2\ddot{Q}_{12} \sin \phi \cos \phi, \quad (7)$$

and

$$\begin{aligned} \ddot{Q}_{\theta\theta} &= (\ddot{Q}_{11} \cos^2 \phi + \ddot{Q}_{22} \sin^2 \phi + 2\ddot{Q}_{12} \sin \phi \cos \phi) \cos^2 \theta \\ &+ \ddot{Q}_{33} \sin^2 \theta - 2(\ddot{Q}_{13} \cos \phi + \ddot{Q}_{23} \sin \phi) \sin \theta \cos \theta. \end{aligned} \quad (8)$$

In the case of axisymmetric 2D simulations, the cross polarization is zero. The Q_{ij} matrix has only diagonal components, $Q_{11} = Q_{22} = -\frac{1}{2}Q_{33}$, and the GW strain h_+ is related to \ddot{Q}_{ij} as [118]

$$h_+ = \frac{1}{D} \frac{G}{c^4} \frac{3 \sin^2 \theta}{2} \ddot{Q}_{33}, \quad (9)$$

where θ is an inclination angle.

We use \ddot{Q}_{ij} to analyze the waveforms and provide basic properties, such as the total energy, energy evolution, energy spectrum, and the characteristic strain. The total energy is calculated as

$$E_{GW} = \int_{-\infty}^{\infty} \frac{dE_{GW}}{dt} dt, \quad (10)$$

where [116,119]

$$\begin{aligned} \frac{dE_{GW}}{dt} &= \frac{G}{5c^5} (\ddot{Q}_{11}^2 + \ddot{Q}_{22}^2 + \ddot{Q}_{33}^2 \\ &+ 2(\ddot{Q}_{12}^2 + \ddot{Q}_{13}^2 + \ddot{Q}_{23}^2)). \end{aligned} \quad (11)$$

The energy spectrum is

$$\begin{aligned} \frac{dE_{GW}}{df} &= \frac{G}{5c^5} (2\pi f)^2 (|\ddot{Q}_{11}|^2 + |\ddot{Q}_{22}|^2 + |\ddot{Q}_{33}|^2 \\ &+ 2(|\ddot{Q}_{12}|^2 + |\ddot{Q}_{13}|^2 + |\ddot{Q}_{23}|^2)), \end{aligned} \quad (12)$$

where \tilde{Q}_{ij} is a Fourier transform of Q_{ij}

$$\tilde{Q}_{ij}(f) = \int Q_{ij}(t) e^{-i2\pi f t} dt. \quad (13)$$

The characteristic strain is defined as [120]

$$h_{char} = \frac{1}{D} \sqrt{\frac{2G}{\pi^2 c^3} \frac{dE_{GW}}{df}}. \quad (14)$$

Before the waveforms can be analyzed with cWB, they need to be prepared to avoid analysis artifacts. The CCSN simulations often create GW components below around 10 Hz that, because of the truncation of the simulations, produce discontinuities at the end of the waveform. This effect is observed to be significant for waveforms from Mor + 18, Mul + 12, Yak + 15, and Pow + 20. This low-frequency component is removed here using a high-pass filter with a cutoff of 10 Hz. All waveforms are resampled to a sampling frequency of 16384 Hz and they are rescaled to a source distance of 10 kpc. For 3D simulations, 100 signals are calculated depending on the source orientation, while 10 inclination angles are chosen for 2D simulations. We note that some of the theoretical properties given in this paper differ from those presented in the papers of the corresponding waveforms. It might be caused by the different processing method. However, these discrepancies have an insignificant effect on our results and conclusions.

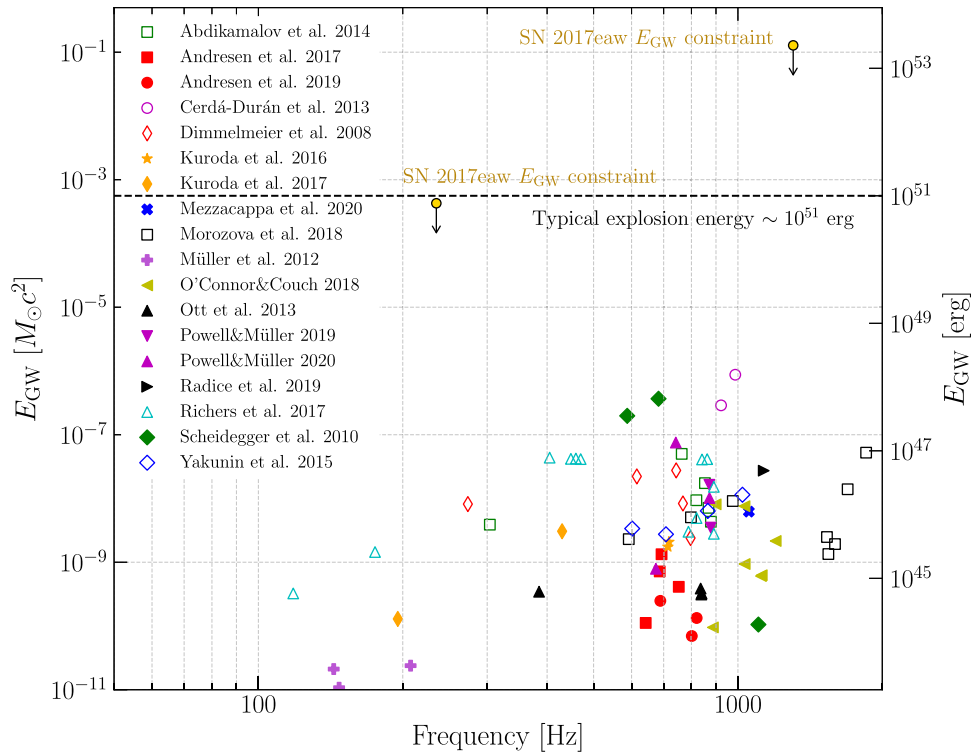


FIG. 1. GW energy as a function of peak frequency (maximum of dE_{GW}/df) for 82 analyzed waveforms. The signals from 2D models are shown with hollow symbols. Spectra of some waveforms are wide band and the peak frequencies could not be accurately determined. For the majority of the signals, the peak frequencies lay between 300 Hz and 1000 Hz that usually corresponds to the proto-neutron star oscillations. The typical energy is in the range from 10^{-10} to $10^{-7} M_{\odot}c^2$ that is smaller than 0.01% of a typical CCSN explosion energy. The current GW energy constraints are $4.27 \times 10^{-4} M_{\odot}c^2$ at 235 Hz and $1.28 \times 10^{-1} M_{\odot}c^2$ at 1304 Hz [16].

C. Energy and spectra of GW signals

The binary BHs are very efficient GW sources, for example, GW150914 radiated around $3 M_{\odot}c^2$ of energy during the merger [1]. On the other side, GW energies from CCSNe are orders of magnitude weaker. Energies of an order of even $10^{-3} M_{\odot}c^2$ can be generated by supernova cores in extreme cases due to the rapid rotation or core fragmentation [66,67]. However, the energies are significantly smaller for the neutrino- and MHD-driven explosions or BH formations (even if a small fraction of the waveforms is currently available for MHD simulations).

Figure 1 shows the source orientation averaged GW energy as a function of the peak frequency f_{peak} (frequency of the $dE_{\text{GW}}(f)/df$ maximum value) for all analyzed waveforms. In the plot, we show the typical explosion energy of a CCSN that is 10^{51} erg (approximately kinetic energy of the ejecta), and the current best GW energy constraint at low frequency is below this limit ($4.27 \times 10^{-4} M_{\odot}c^2$ at 235 Hz [16]). Energies of most of the waveforms are in the 10^{-10} – $10^{-7} M_{\odot}c^2$ range with more energetic emissions involving rapid rotation (Cer + 13, Sch + 10, and Ric + 17). Only less than 0.01% of the explosion energy appears to be converted into GWs. The peak frequencies range from 100 Hz to

above 2 kHz with the majority of the energy emitted around 1 kHz.

Figure 2 shows example curves of the cumulative energy emitted in GWs as a function of time after core bounce. As described earlier, a CCSN explosion can be divided into a few phases that can be observed in the curves. A core

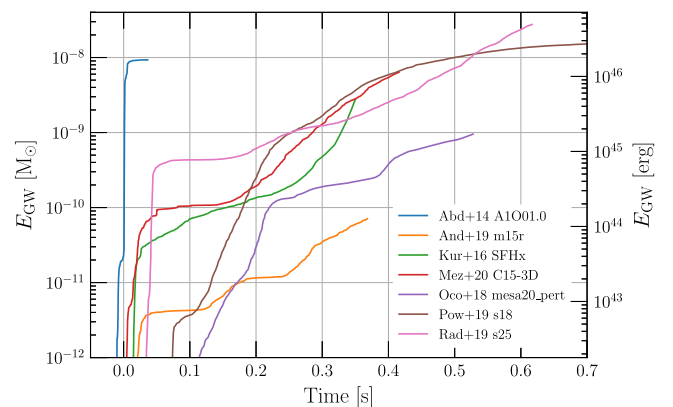


FIG. 2. Examples of the GW energy evolution. The Abd + 14 waveforms are short and energetic core-bounce GW signals. For the neutrino-driven explosions most of the energy is emitted after around 100 ms.

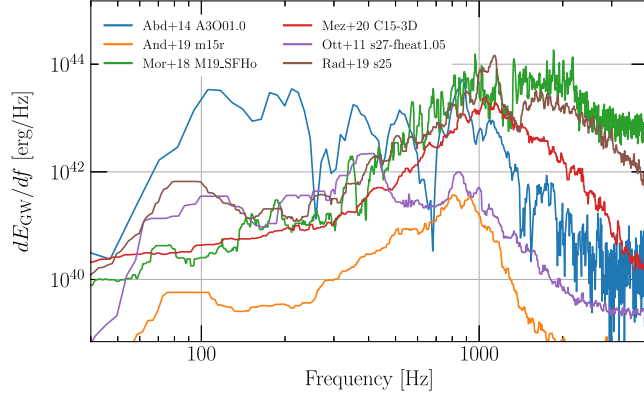


FIG. 3. The GW signals from CCSNe are typically broadband with the majority of the energy at higher frequencies. The peak frequency can be difficult to determine for some waveforms, like for Abd + 14 A3O01.0.

bounce and quiescent phase are followed by a period of accretion and strong GW emission until an explosion phase occurs with typically little accretion and weak GWs. The timescales and the strengths differ between waveforms. Since many simulations are stopped abruptly due to the high computational cost, the GW evolution is stopped before the full signal is evolved. For example, the Abd + 14 waveforms represent the bounce signal of a rapidly rotating core and the later evolution is not yet well understood.

Figure 3 shows the GW energy spectra dE_{GW}/df for a few example waveforms. The GW signals are usually broadband with the majority of the energy at higher frequencies. The dominant GW emission comes typically from the PNS oscillations. In the case of the Ott + 03 model, the explosion is initially very aspherical and the prompt-convection signal around 400 Hz dominates. In some cases, the peak frequencies cannot be determined unambiguously, for example, the Abd + 14 waveforms have multiple peaks in their spectrum.

Figure 4 presents the characteristic strains for example waveforms together with the noise amplitudes of LIGO, Virgo, and KAGRA detectors projected for O4 and O5 [121]. The GW150914 signal is also shown for comparison. The GW detector sensitivities are frequency dependent and it impacts the detectability of GW features. The stronger GW emission from PNS oscillations peaks in a less sensitive area of the detector spectrum. The GWs from lower frequency SASI/convection have the majority of their energy in the frequency range where the detectors are most sensitive.

III. METHODOLOGY

A. Coherent WaveBurst

Coherent WaveBurst is an excess-power search algorithm for detecting and reconstructing GWs [14] using minimal assumptions on the signal morphologies. The

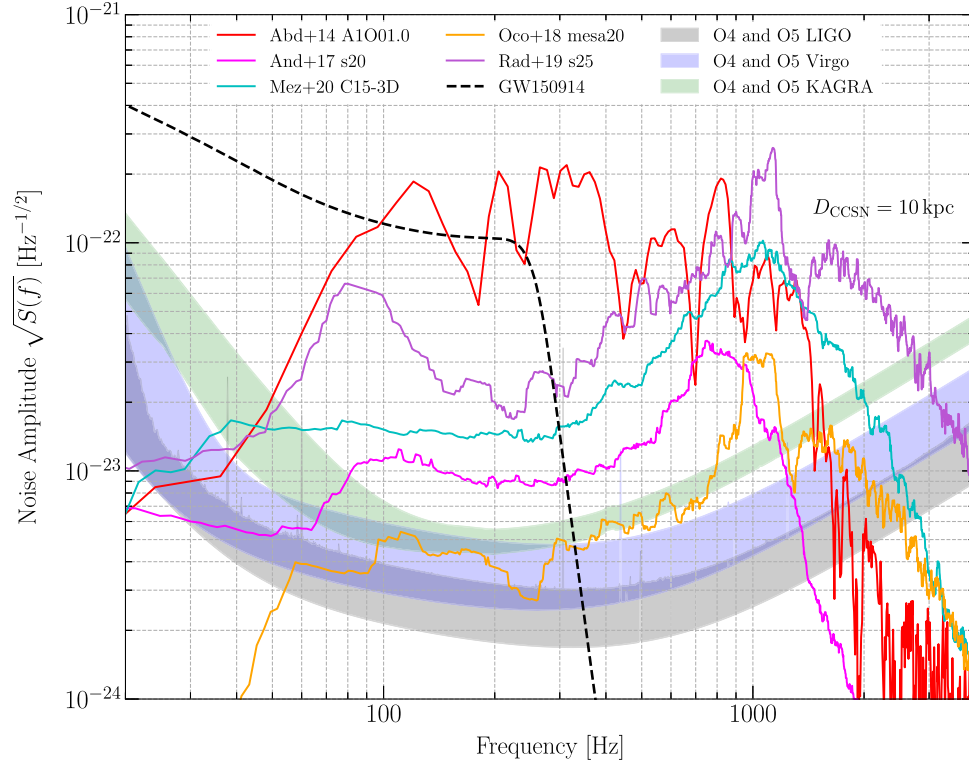


FIG. 4. The projected noise amplitudes of the LIGO, Virgo, and KAGRA detectors for O4 and O5. The characteristic strains are broadband with the majority of the energy in higher frequencies that usually is emitted by PNS oscillations. Abd + 14 represents the core-bounce signal that is strong but broadband. The GW150914 signal is shown for comparison.

cWB search performs a wavelet analysis of GW strain data [122]. It selects wavelets with amplitudes above the fluctuations of the detector noise, groups them into clusters, and identifies coherent events.

The cWB event ranking statistics η_c is based on the coherent network energy E_c obtained by cross-correlating detectors data and η_c is approximately the coherent network signal-to-noise ratio. The events are ranked with $\eta_c = \sqrt{E_c / \max(\chi^2, 1)}$. The value of χ^2 quantifies the agreement of cWB reconstruction and the detector data. It is defined as $\chi^2 = E_n / N_{df}$, where E_n is the residual energy and N_{df} is the number of independent wavelet coefficients used in the reconstruction. E_n is the leftover energy after the reconstructed waveform is subtracted. The events are rejected when $\chi^2 > 2.5$. The further reduction of false alarms due to the nonstationary detector noise is performed using a correlation coefficient $c_c = E_c / (E_c + E_n)$. The events are accepted when $c_c > 0.5$. We set up the internal cWB parameters and selection cuts as in the O1-O2 LIGO-Virgo targeted search for CCSNe [16] with an exception of lowering the c_c threshold from 0.8.

B. Noise rescaling

The GW detectors are impacted by many sources of noise. The data is nonstationary, the amplitudes may fluctuate vastly, and it is corrupted by non-Gaussian noise. Every upgrade of the GW interferometers alters the noise properties. The astrophysical predictions with the projected detector sensitivities should take into account the features of the real detector noise. Therefore, we rescale publicly available O2 data from LIGO Livingston (L1), LIGO Hanford (H1), and Virgo (V1) detectors to the projected sensitivities in O4 and O5 [121]. The data from the KAGRA (K1) detector is not yet available so a Gaussian noise is scaled to projected O4 and O5 sensitivity.

We developed a procedure that allows us to preserve all features of the noise, including the distributions of glitches, fluctuations of the detector spectra, and other noise sources present in the real data. The rescaling procedure uses an average detector noise spectrum from O2, $S_{O2,avg}(f)$ [123,124] and the projected detector sensitivity O5 $S_{O5,proj}(f)$. The algorithm takes time series from O2, calculates the spectrum $S_{O2}(f)$ and rescales it in the frequency domain as

$$S_{O5}(f) = S_{O2}(f) \frac{S_{O5,proj}(f)}{S_{O2,avg}(f)}. \quad (15)$$

The phase is preserved and the rescaled spectra are transformed back to the time domain. The same procedure is performed with O4 data. Figure 5 shows an example of the spectra of the original H1 O2 data that is rescaled to O4 and O5, an average noise in O2, and the projected O4 and O5 sensitivities. In this example, the algorithm preserves the

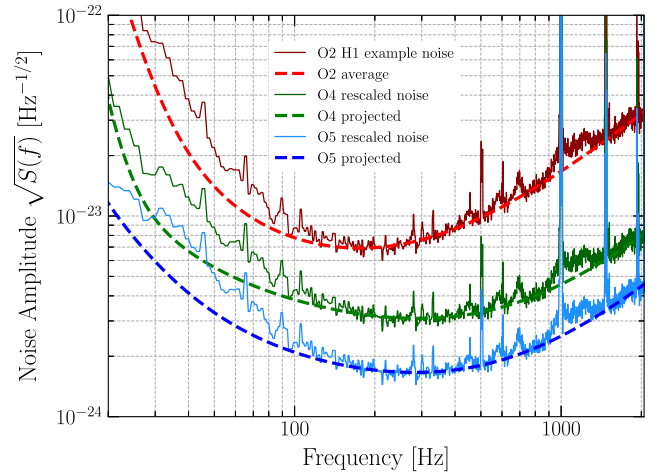


FIG. 5. Example O2 LIGO Hanford detector sensitivity rescaled to O4 and O5 designs. The rescaling procedure preserves all features of the real noise.

lower H1 sensitivity below 100 Hz and a noise excess around 1 kHz.

C. Background estimation

To estimate the background of the noise events we use the same procedure as in [16]. We perform a time-shifting analysis that is widely used in searches for GW bursts. The data from one detector is shifted a multiple of 1 s with respect to the other that is longer than the time delay for GW to pass between detectors. It assures that any event identified by cWB is a noise event. The collection of falsely identified events is used to calculate the false alarm rate (FAR).

To perform background analysis, we use only H1 and L1 data. The V1 and K1 detectors are predicted to be less sensitive bringing the noise to the coherent analysis. The H1 and L1 detector network (HL) is typically used for background estimation and detection statements in the searches for GW bursts, even if V1 data is available [4,21]. The less sensitive detectors may provide crucial data for the detection of a Galactic supernova when data from more sensitive detectors are not available. They may also contribute to localizing the GW sources in the sky, but these considerations are beyond the scope of this paper and most likely an exact sky location will be known [125]. To estimate the background, we use publicly available O2 LIGO data from the GPS time range corresponding to the search period of SN 2017eaw in [16].

Similar to the search procedure in [16], the background events are divided into two mutually exclusive classes. The first class $C1$ contains short-duration transients with up to few cycles, primarily blip glitches [126,127] and the second class $C2$ includes other noise events. The blips are $O(10)$ ms long transients spanning $O(100)$ Hz frequency band with unknown origin. They are present in all

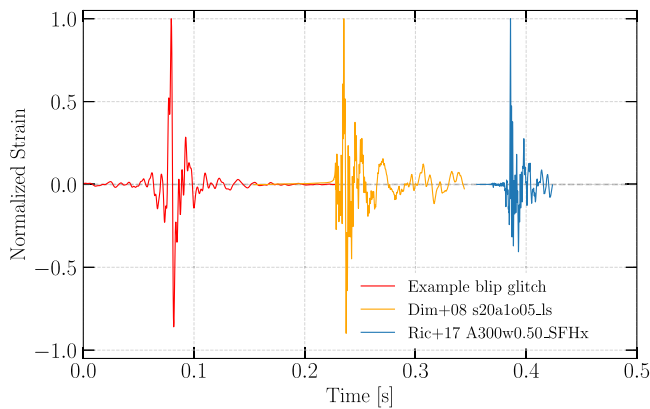


FIG. 6. The comparison between an example blip glitch and core-bounce waveforms for Dim + 08 and Rich + 17.

observing runs of the advanced detectors. Importantly, these glitches are morphologically similar to the CCSN bounce signals. Figure 6 shows examples of a blip together with Dim + 08 and Ric + 18 waveforms.

D. Sensitivity studies

We determine how sensitive the cWB search is to detect and reconstruct CCSN waveforms. The waveforms from different source angle orientations are placed randomly in the sky, added (injected) to the detector noise every 150 s and reconstructed with cWB. This procedure is performed for a range of source distances creating detection efficiency curves. For each waveform, the distance at 50% detection efficiency is referred to as a detection range. A similar procedure is performed with detection efficiency curves as

a function of network signal-to-noise ratio (SNR). The waveforms are placed randomly in the sky and their amplitudes are rescaled to match certain injected SNR (SNR_{inj}). This allows us to determine how strong the GW signal needs to be to be detected by cWB. The minimum detectable SNR is referred to as the SNR at 50% detection efficiency.

In this search sensitivity study, we use ten days of coincident data from O2 rescaled to projected O4 and O5 sensitivities. This extended period of data allows us to average the impact of the detector network angular sensitivity and the effects of the noise. We discard events with FAR larger than one per year. For a GW signal from a nearby CCSN, the Supernova Early Warning System (SNEWS) [128,129] should provide a conservative period of 10 s to identify the GW burst. Assuming that the GW is detected with FAR smaller than one per year, it results in a 5σ detection confidence {see Eq. (1) in [16]}. In case when a neutrino counterpart is not available, the time of the GW burst would have to be estimated from optical observations [16] that will likely be more uncertain than the time from SNEWS therefore decreasing the detection significance.

IV. RESULTS

A. Detection ranges

The detection ranges for the projected sensitivities of the LIGO detectors in O4 and O5 are presented in Fig. 7 and Table II. Top panels of Fig. 7 provide example detection efficiency curves for projected O5 LIGO sensitivities. The bottom panel of Fig. 7 summarizes distances at 10%, 50%, and 90% detection efficiencies for all analyzed waveforms.

TABLE II. The results presenting the sensitivity of cWB to the detection of GWs from a variety of CCSN models. The predicted detection ranges for O4 and O5 are calculated at 10%, 50%, and 90% detection efficiency. The detectable SNR is also calculated at 10%, 50%, and 90% detection efficiency. The waveform overlap (accuracy of cWB reconstruction) is an averaged at injected SNR of 20, 40, and 60.

Waveform Family	Waveform Identifier	O4 det. range [kpc]			O5 det. range [kpc]			O4 Detect. SNR			O4 Wav. Overlap		
		90%	50%	10%	90%	50%	10%	10%	50%	90%	20	40	60
Abdikamalov <i>et al.</i> 2014 [90]	A1O01.0	...	15.9	58.7	...	29.4	109.7	9.7	12.7	...	0.83	0.90	0.93
	A2O01.0	...	19.3	71.0	...	35.2	130.0	10.0	13.1	...	0.88	0.93	0.94
	A3O01.0	...	20.1	84.6	...	37.1	157.4	8.9	12.5	...	0.86	0.92	0.95
	A4O01.0	...	8.4	39.3	...	15.2	72.3	10.2	14	...	0.88	0.91	0.94
Andresen <i>et al.</i> 2017 [51]	s11	0.6	1.4	2.3	1.1	2.6	4.3	13.1	16.5	25.1	0.59	0.82	0.88
	s20	1.4	3.4	5.6	2.5	6.2	10.4	14.2	17.9	24.9	0.50	0.79	0.88
	s20s	1.6	4.1	6.8	2.9	7.5	12.6	19.7	24.0	35.7	0.35	0.71	0.84
	s27	0.8	1.9	3.1	1.4	3.5	5.7	17.6	22.2	33.5	0.71	0.68	0.83
Andresen <i>et al.</i> 2019 [91]	m15fr	1.4	3.2	5.6	2.5	5.8	10.1	11.4	16.1	22.0	0.61	0.77	0.85
	m15nr	0.8	1.8	3.1	1.4	3.3	5.5	13.0	16.3	22.6	0.59	0.82	0.88
	m15r	0.3	0.9	1.5	0.6	1.6	2.8	16.0	20.0	27.6	0.46	0.78	0.86
Cerdá-Durán <i>et al.</i> 2013 [59]	Fiducial	...	15.7	51.5	...	28.2	93.9	31.0	37.8	...	0.52	0.81	0.87
	Slow	...	35.9	154.3	...	66.6	285.7	15.3	19.7	...	0.35	0.63	0.81

(Table continued)

TABLE II. (*Continued*)

Waveform Family	Waveform Identifier	O4 det. range [kpc]			O5 det. range [kpc]			O4 Detect. SNR			O4 Wav. Overlap		
		90%	50%	10%	90%	50%	10%	10%	50%	90%	20	40	60
Dimmelmeier <i>et al.</i> 2008 [92]	s15A2O09-ls	...	14.5	60.1	...	26.1	117.5	10.2	13.2	...	0.86	0.91	0.93
	s15A3O15-ls	...	13.6	59.4	...	24.5	117.1	9.2	12.8	...	0.90	0.94	0.95
	s20A3O09-ls	...	12.5	59.9	...	22.8	125.9	10.3	14.2	...	0.84	0.90	0.92
Kuroda <i>et al.</i> 2016 [93]	SFHx	4.9	11.8	23.8	8.7	21.6	43.3	10.4	14.1	22.1	0.63	0.82	0.88
	TM1	3.7	8.0	13.2	6.5	14.5	24.8	12.7	15.5	19.5	0.61	0.82	0.88
Kuroda <i>et al.</i> 2017 [94]	s11.2	2.5	7.7	15.9	4.8	14.3	29.0	10.0	12.7	21.3	0.82	0.90	0.93
	s15.0	2.7	6.7	11.7	5.0	12.2	20.5	11.2	14.3	19.5	0.75	0.89	0.92
Mezzacappa <i>et al.</i> 2020 [73]	c15-3D	1.8	4.4	7.4	3.0	8.2	14.0	17.0	21.1	33.8	0.42	0.69	0.82
Morozova <i>et al.</i> 2018 [95]	M10_LS220	...	1.3	5.2	...	2.4	9.5	16.2	21.7	...	0.47	0.72	0.81
	M10_DD2	...	1.9	7.4	...	3.4	13.7	15.2	19.6	...	0.57	0.80	0.85
	M13_SFHo	...	2.3	10.2	...	4.5	19.2	15.8	20.9	...	0.49	0.74	0.80
	M19_SFHo	...	3.9	16.7	...	6.9	30.0	18.9	24.4	...	0.37	0.68	0.78
Müller <i>et al.</i> 2012 [131]	L15-3	1.7	4.3	8.0	3.3	8.1	14.1	10.1	12.6	17.6	0.73	0.81	0.84
	N20-2	0.5	1.9	3.6	1.1	3.5	6.5	11.3	14.4	22.1	0.68	0.79	0.84
	W15-4	0.5	1.9	5.2	0.9	3.7	9.7	10.6	14.2	42.2	0.71	0.83	0.88
O'Connor and Couch 2018 [96]	mesa20	0.4	1.1	1.9	0.8	2.0	3.5	16.3	20.7	30.8	0.50	0.70	0.82
	mesa20_LR	0.6	1.4	2.6	1.0	2.5	4.7	18.5	25.0	42.3	0.45	0.67	0.79
	mesa20_pert	0.7	1.6	2.9	1.2	2.9	4.9	16.2	21.0	28.5	0.47	0.75	0.84
	mesa20_v_LR	0.4	1.1	1.9	0.8	2.1	3.5	16.0	20.2	29.6	0.51	0.78	0.87
Ott <i>et al.</i> 2013 [97]	s27-fheat1.00	2.4	5.8	10.5	4.3	10.8	20.2	11.1	14.3	20.1	0.75	0.89	0.92
	s27-fheat1.05	2.0	5.8	10.6	4.1	10.5	18.4	10.9	14.1	19.3	0.74	0.88	0.91
	s27-fheat1.10	2.4	5.8	10.0	4.0	10.0	17.4	11.2	14.2	19.6	0.75	0.88	0.92
	s27-fheat1.15	1.9	5.2	9.0	3.7	9.3	16.0	11.0	14.2	19.5	0.76	0.88	0.92
Powell and Müller 2019 [98]	s3.5_pns	1.8	3.9	6.4	3.2	7.1	11.7	17.0	20.9	30.4	0.44	0.75	0.83
	s18	3.2	7.7	12.7	5.5	14.0	23.0	15.5	19.2	28.0	0.47	0.73	0.81
Powell and Müller 2020 [99]	m39	10.3	30.7	70.2	18.5	56.6	128.8	12.8	18.8	38.2	0.57	0.73	0.81
	s18np	2.3	5.7	12.3	4.1	10.5	22.7	10.6	14.6	21.5	0.67	0.81	0.88
	y20	3.4	8.5	14.6	6.2	15.5	26.8	16.2	19.9	29.4	0.42	0.72	0.82
Radice <i>et al.</i> 2019 [50]	s9	0.0	0.4	0.7	0.2	0.7	1.3	11.1	14.3	23.1	0.73	0.84	0.91
	s13	0.4	1.0	1.8	0.7	1.8	3.1	10.9	14.3	21.1	0.68	0.80	0.87
	s25	2.4	5.6	9.4	4.3	10.3	17.7	22.5	30.6	42.8	0.43	0.65	0.78
Richers <i>et al.</i> 2017 [100]	A467_w0.50_SFHx	...	8.0	32.9	...	15.1	60.6	8.70	13.7	...	0.86	0.91	0.93
	A467_w0.50_LS220	...	10.3	43.0	...	18.1	80.3	10.2	14.2	...	0.85	0.93	0.94
	A467_w9.50_SFHx	...	24.2	105.2	...	47.9	194.2	10.3	14.3	...	0.82	0.91	0.91
	A467_w9.50_LS220	...	22.5	90.5	...	40.8	171.9	10.1	14.1	...	0.82	0.89	0.92
Scheidegger <i>et al.</i> 2010 [54]	R1E1CA_L	0.4	1.3	3.5	0.8	2.4	6.5	9.9	13.1	22.5	0.76	0.86	0.91
	R3E1AC_L	29.9	89.6	171.8	55.5	163.9	313.9	10.6	13.4	17.2	0.76	0.89	0.93
	R4E1FC_L	31.8	98.4	203.4	59.3	180.1	374.6	8.9	11.8	15.7	0.81	0.91	0.94
Yakunin <i>et al.</i> 2015 [72]	B12	...	3.6	13.6	...	6.6	25.2	15.2	19.3	...	0.51	0.80	0.88
	B15	...	4.3	17.9	...	7.7	32.4	17.4	22.1	...	0.44	0.78	0.87
	B20	...	3.0	15.2	...	5.7	28.2	15.8	22.2	...	0.52	0.82	0.89
	B25	...	6.6	26.1	...	12.5	48.2	15.7	20.9	...	0.49	0.76	0.85

In Fig. 7, a detection efficiency curve for a certain waveform can be interpreted as the probability of detecting that waveform as a function of the source distance. The numbers in the brackets are the detection ranges (distances

at 50% detection efficiency). The values vary significantly, from around 1 kpc to over 100 kpc. The maximum values of the detection efficiency curves for waveforms calculated in 3D simulations are above 90% while it is around 70% for

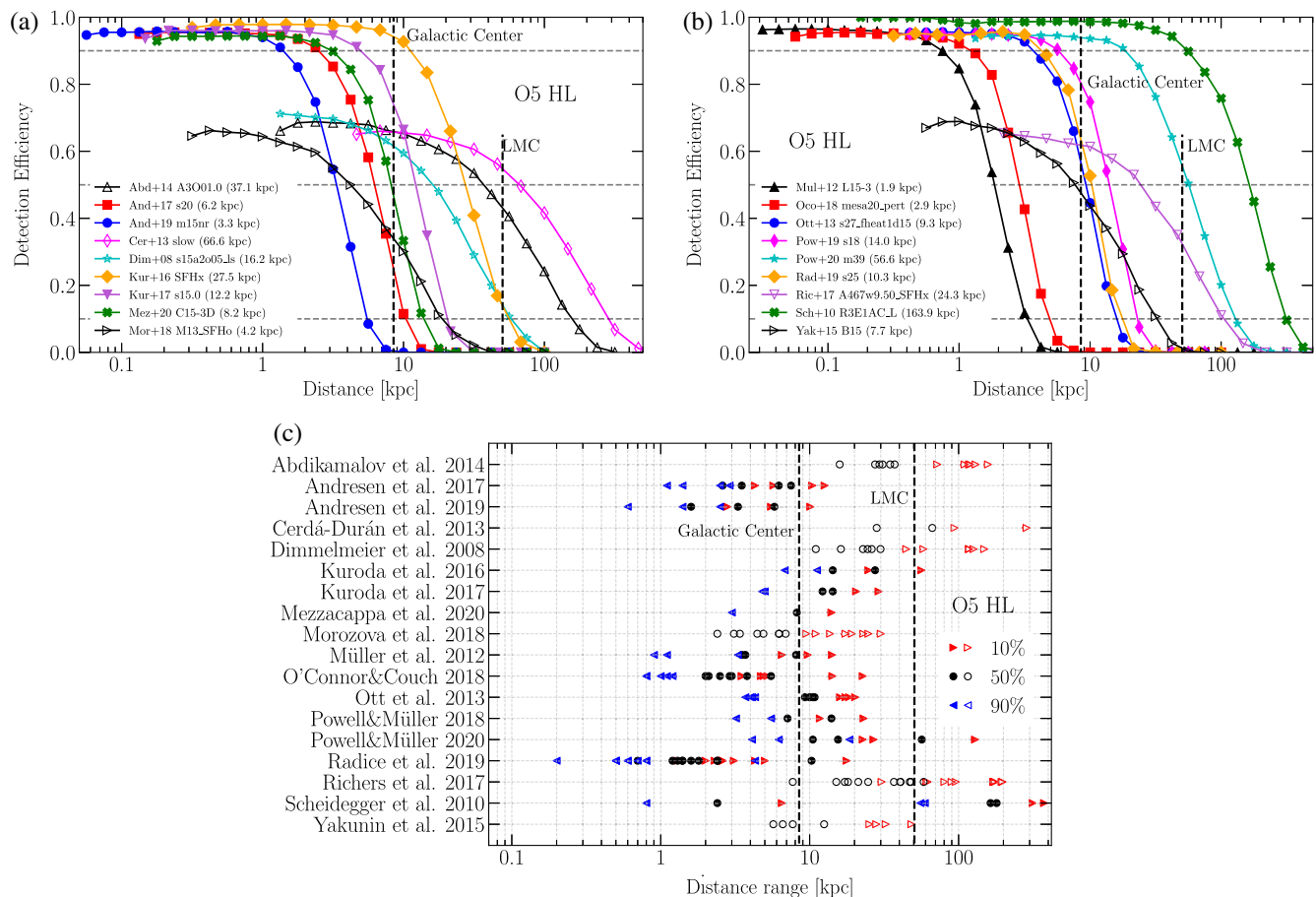


FIG. 7. Detection efficiency curves for example waveforms are presented in panels (a) and (b). The numbers in the brackets are distances at 50% detection efficiencies. Panel (c) shows the distances at 10%, 50%, and 90% detection efficiencies for all waveforms analyzed in this paper. The predicted detection ranges for O5 are typically between 1 kpc and 100 kpc. This range contains the distances to the Galactic center and the Large Magellanic Cloud (LMC) that hosted SN 1987A. The detectability of GW signals coming from 3D simulations can reach almost 100% detection efficiency at close distances, while linearly polarized waveforms (hollow symbols) reach only 70% of the detection efficiency.

linearly-polarized GW signals. The HL network used for this analysis is sensitive effectively to only one polarization (the arms of H1 and L1 detectors are approximately parallel). Depending on the polarization angle a waveform may not be registered at the output of the detectors, even if the amplitude is large compared to the noise level. Notably, the best-studied bounce signal has only one polarization component and with 30% probability, the signal will not be detectable even for a very nearby CCSN.

The bottom panel of Fig. 7 provides a broad overview of how well the GW signals from CCSNe can be detected in O5. Typically, the detection ranges for the waveforms generated in neutrino-driven explosions are up to around 10 kpc and only a few GW signals can be detected up to the edge of the Milky Way. When a star explodes according to the MHD-driven mechanism, the detection ranges may exceed the distance of the Large Magellanic Cloud (49.6 kpc [130]). The largest detection ranges are obtained for Sch + 10 (around 100 kpc for R3E1AC_L and R4E1CA_L) and Pow + 20 (60 kpc for y20). These results

are in a qualitative agreement with previous studies and conclusions from the optically targeted search performed with O1-O2 data [16,47] where the detection ranges for MHD-driven explosions are much larger than for neutrino-driven explosions. It is worth mentioning that the detection ranges for the MHD-driven explosions could increase significantly if the amplitudes of the turbulent phase (not available for Abd + 14, Dim + 08, and Ric + 17) are comparable with the core bounce one.

Table II summarizes the distances at 10%, 50%, and 90% detection efficiencies for waveforms described in Table I. The LIGO detectors will be improved between O4 and O5 consistently in a large frequency range of a factor ~ 1.8 (see Fig. 5) and the detection ranges improve by around the same factor.

B. Minimum detectable SNR

The cWB algorithm is sensitive to a wide range of GW signals but it is not equally sensitive to all morphologies.

In general, waveforms that are short and narrow band are easier to detect than waveforms that are long, broadband, or fragmented in the time-frequency domain. As an illustration, binary BH signals usually have a continuous evolution in the time-frequency domain, in the LIGO band they are typically relatively short and narrow band. On the contrary, the waveforms from CCSNe often have very complex signatures in time and frequency. For example, the peak frequencies of GWs from PNS oscillations evolve from around 100 Hz up to a few kHz during the first second after the collapse. The time-frequency evolution of these oscillations often is not continuous and depends on the amount of accreting matter. Moreover, rapid plumes of infalling matter can cause the generation of a broadband GW signal. Additionally, the GWs from SASI/convection and the PNS oscillations can be disconnected in the time-frequency domain.

The top panels of Fig. 8 present detection efficiency curves as a function of injected SNR for projected O5

sensitivity and an HL network. The numbers in the brackets are the minimum detectable SNR (SNR at 50% detection efficiency). The bottom panel of Fig. 8 summarizes the SNR values at 10%, 50%, and 90% detection efficiency for all analyzed waveforms. The minimum detectable SNR is typically in the range of 10–25. The smallest values are reported for short waveforms (<200 ms) such as Abd + 14, Dim + 08, Kur + 17, Ott + 13, Sch + 10, and Ric + 17, or when they are narrow band, e.g., Mul + 12. The minimum detectable SNR is increasing with the complexity of the waveform morphology and the GW signals from neutrino-driven explosions have higher minimum detectable SNR values, such as for And + 16, Mor + 18, Oco + 18, and Rad + 19. The highest minimum detectable SNR is given for the Cer + 13 fiducial waveform. This signal represents a BH formation after almost 2 s with a broadband spectrum making it challenging to detect. If the star collapses to a BH faster (e.g., Cer + 13 slow or [60–64]) then the corresponding SNR to capture the

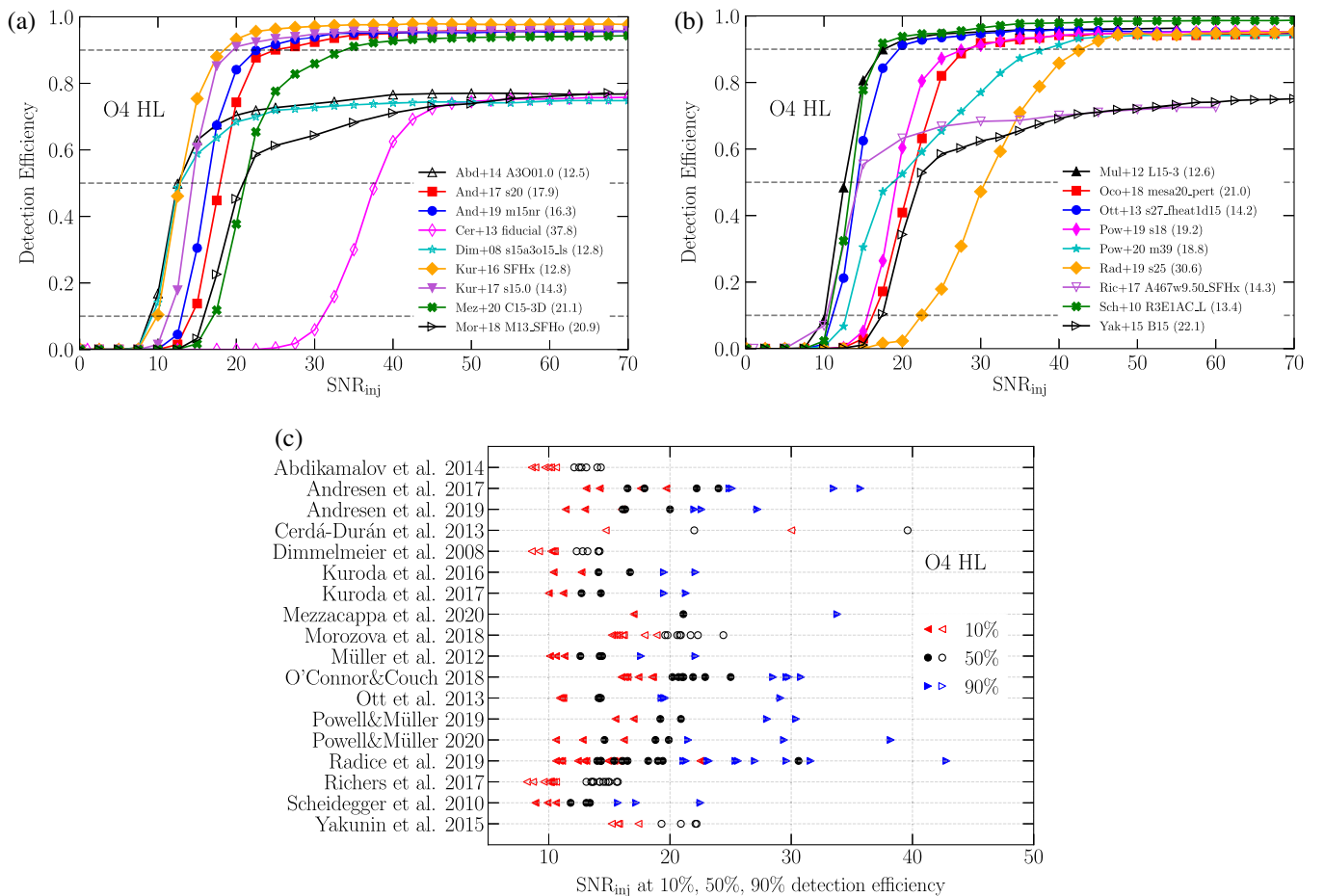


FIG. 8. Detection efficiency curves as a function of injected SNR (SNR_{inj}) for example waveforms are presented in panels (a) and (b). The numbers in the brackets are SNRs at 50% detection efficiencies. Panel (c) shows the SNRs at 10%, 50%, and 90% detection efficiencies for all waveforms analyzed in this paper. The waveforms are typically detectable at SNR of 10–25. The Cer + 13 fiducial waveform is almost 2 s long which makes it challenging to detect. The dominant GW emission periods for Rad + 19 s25 are 0.6 s apart, making it challenging to group them by the algorithm. The linearly-polarized waveforms (hollow symbols) reach only 70% detection efficiency.

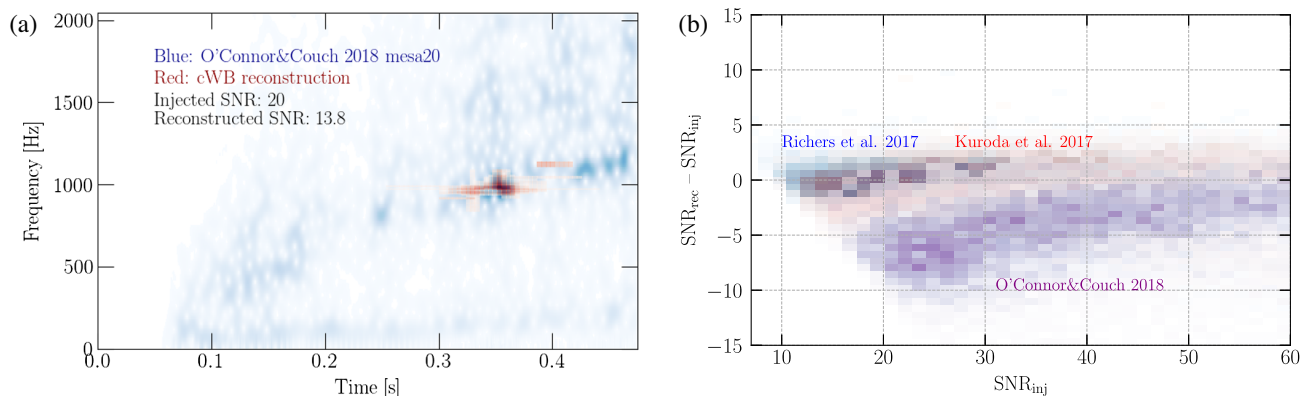


FIG. 9. Panel (a) shows an example Oco + 18 mesa20 waveform with an overlay of the cWB reconstruction. The waveform is relatively long and broadband and for small SNR values the algorithm does not reconstruct a large part of the signal. Panel (b) quantifies the SNR difference as a function of injected SNR. The cWB search reconstructs well the signals that are short in duration and its capabilities decrease with the increasing signal complexity in their time-frequency evolution.

full signal is smaller. Similar to the results obtained in Sec. IV A, the detection efficiency for linearly-polarized waveforms do not exceed around 70% detection efficiency.

Table II provides the SNR values at 10%, 50%, and 90% detection efficiency for the waveforms listed in Table I. Given that the predicted improvement between O4 and O5 is uniform across the LIGO frequency band, the results obtained in both observing runs are practically the same. We provide the results using the O4 sensitivity, as the algorithm improvements are ongoing.

The challenge of detecting and reconstructing GW signals that are long and broadband is illustrated in the left panel of Fig. 9. The plot shows a spectrogram of the Oco + 18 mesa20 waveform and an overlay of a cWB reconstruction. The signal is almost 0.5 s long and its energy spans up to 2 kHz. The waveform has a visible SASI/convection signature and the peak-frequency evolution of the PNS oscillations. The overall energy of the signal is spread rather uniformly in the time-frequency domain. In this particular case, the injected SNR is 20 while the cWB reconstructed SNR is 13.8. The peak frequency is around 1 kHz, and only part of the signal around the peak frequency is reconstructed. This situation is typical for the waveforms from neutrino-driven explosions.

The right panel of Fig. 9 presents the distributions of the difference between the reconstructed and injected SNR as a function of the injected SNR for three waveform families. Ric + 17 simulate the GW bounce signals and the waveforms are only 6 ms long. The minimum detectable SNR is around 10 and the reconstructed SNR matches well the injected SNR. The Kur + 17 waveforms are shorter than 200 ms, they lack emission from the PNS oscillations and the peak frequency is below 400 Hz. In this case, the reconstructed SNR is close to the injected SNR, but the difference is larger than for the Rich + 17 waveforms. The Oco + 18 waveforms have an even more complex time-frequency structure and the reconstructed SNR is significantly underestimated. It is worth mentioning that it is

possible to improve the detectability of long and broadband waveforms by decreasing the cWB internal thresholds. However, it comes with the expense of increasing significantly the number of background events and diminishing the significance of the detected GW signals.

C. Reconstruction accuracy

To quantify the accuracy of the cWB reconstruction, we use the waveform overlap, or a match [45], between a detected $\mathbf{w} = \{w_k(t)\}$ and injected waveform $\mathbf{h} = \{h_k(t)\}$

$$O(\mathbf{w}, \mathbf{h}) = \frac{(\mathbf{w}|\mathbf{h})}{\sqrt{(\mathbf{w}|\mathbf{w})}\sqrt{(\mathbf{h}|\mathbf{h})}}. \quad (16)$$

The scalar product $(\cdot|\cdot)$ is defined in the time domain as

$$(\mathbf{w}|\mathbf{h}) = \sum_k \int_{t_1}^{t_2} w_k(t)h_k(t)dt, \quad (17)$$

where the index k is a detector number and $[t_1, t_2]$ is the time range of the reconstructed event. The waveform overlap ranges from -1 (sign mismatch) to 1 (perfect reconstruction).

The complexity of the GW signals has an impact on the detectable SNR and the corresponding reconstruction accuracy. It is illustrated in Fig. 10 that shows distributions of the waveform overlaps as a function of the injected SNR for three waveform families. The difference between reconstructed and injected SNR for Ric + 17 waveforms is small and they are reconstructed the most accurately, waveform overlaps are around 0.9 even for low SNR signals. The Kur + 17 waveforms are longer and the mismatch is larger than for Ric + 17 waveforms. The SNR for Oco + 17 waveforms is significantly underestimated resulting in relatively low waveform overlap values. The Oco + 17 waveforms require a minimum detectable SNR of around 20 and the corresponding average waveform overlap is

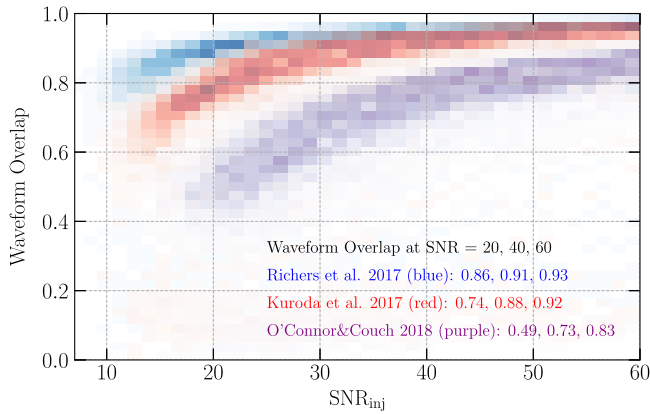


FIG. 10. Waveform overlap as a function of the injected SNR. The waveforms that are short, like Rad + 17 are accurately reconstructed for small SNRs, while waveforms that are long and broadband, like Oco + 18, need to be relatively strong to be reconstructed accurately.

0.49. Even for stronger signals, the waveform overlaps do not reach 0.9 on average.

Table II summarizes the waveform overlap values at injected SNRs of 20, 40, and 60 for the waveforms listed in Table I, and Fig. 11 shows results for all analyzed waveforms. The best reconstruction accuracy is obtained for the signals that are very short (Abd + 14, Dim + 08, and Ric + 17). The reconstruction accuracy decreases with waveform length and their complexities, and it is lowest for the waveforms from the neutrino-driven explosions.

D. Reconstruction of GW features

In the previous section, we quantified how well cWB reconstructs the whole waveforms. Here, we provide a brief

qualitative description of how well particular GW features can be reconstructed. When the GW signals are weak cWB usually detects the signal's components around their peak frequency. However, the frequency-dependent detector noise may alter the f_{peak} of the injected and reconstructed waveforms. For example, the And + 19 m15fr waveform peaks at 689 Hz and contains a very strong low-frequency SASI component in the frequency range where the GW detectors are most sensitive. As a result, at SNR of 20, the peak frequency reconstructed by cWB is usually around 100 Hz. This discrepancy can be explained using Fig. 4. The amplitude ratio between the characteristic strain and O4–O5 detector sensitivities are comparable at low and high frequencies, and the reconstructed peak frequency can be ambiguous. Such discrepancies are rare but they happen when the signal is weak.

The peak frequencies of the GW signals usually correspond to the dominant emission processes, as is illustrated in the reconstruction of the Oco + 18 waveform in the left panel of Fig. 9. When the GW signals are weak, the peak frequency of the dominant GW emission is reconstructed and when the SNR increases, the other parts of the signal get reconstructed as well. For most of the waveforms from the neutrino-driven explosions, the PNS oscillations dominate the waveform amplitudes and the minimum detectable SNR is around 20. The time-frequency path of the increasing peak frequency of the PNS oscillations becomes visible around SNR 30–40. At this SNR level, the SASI/convection becomes reconstructed as well.

The GWs dominated by SASI/convection are relatively narrow band and the minimum detectable SNR is usually smaller for waveforms dominated by PNS oscillations. Examples are Mul + 12 or Pow + 20 s18 waveforms, their minimum detectable SNR is around 15. Similarly, the

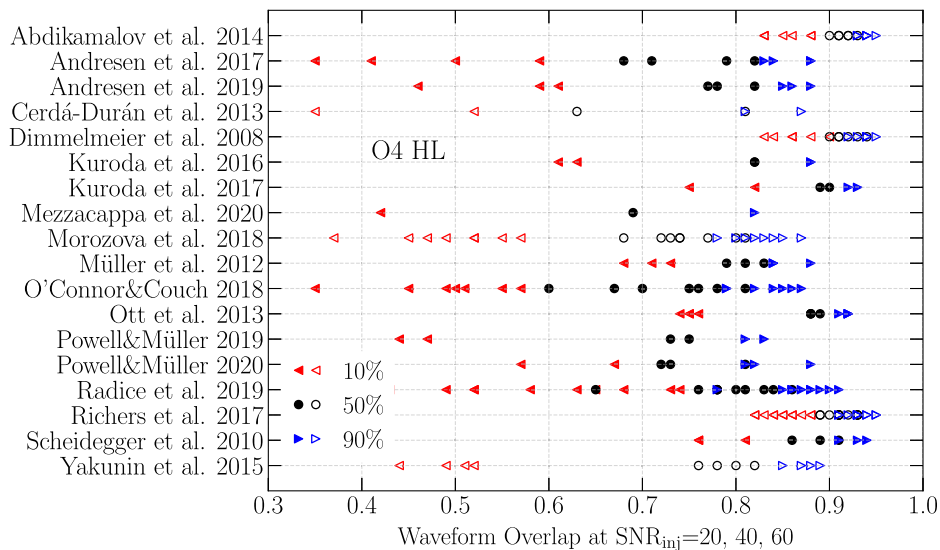


FIG. 11. Waveform overlaps (reconstruction accuracy) for all waveforms analyzed in this paper at injected SNR of 20, 40, and 60. The accuracy of reconstruction is close to unity for short waveforms such as Abd + 14, Dim + 08, and Ric + 17. It decreases with waveform length and its complexity in the time-frequency evolution. The signals from 2D models are shown with hollow symbols.

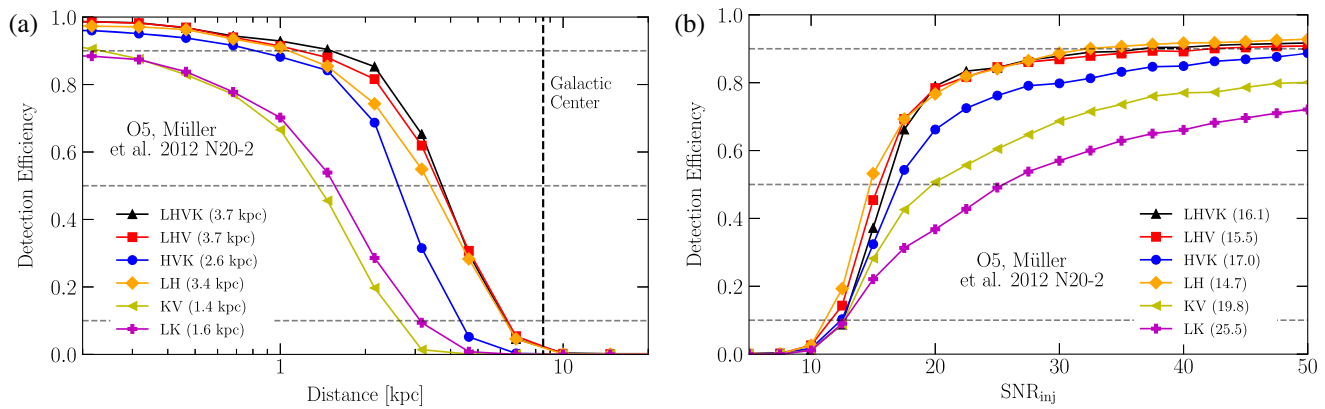


FIG. 12. Detection efficiency curves as a function of (a) distance and (b) injected SNR. The numbers in the brackets show detection range and minimum detectable SNR, respectively. The three- and four-detector networks are significantly less sensitive than for two-detector networks.

prompt-convection signatures are short and they are reconstructed accurately even for small SNR values. For example, Ott + 13 and Kur + 17 s11 waveforms are dominated by a strong prompt-convection and the minimum detectable SNR is around 15. The GWs from rapidly rotating progenitor stars (Abd + 14, Dim + 08, Ric + 17) are dominated by the bounce and prompt-convection, these waveforms are very short and they are detectable in the SNR around 15 or less. The reconstruction of the BH formation signals that may be long is the most challenging. The duration of Cer + 13 fiducial waveform is almost 2 s and for such long signals, an SNR of 50 is needed to capture the full evolution including the final BH formation signal.

E. Inclusion of Virgo and KAGRA

During O4 and O5 the network of GW detectors will consist of four detectors [49]: L1, H1, V1, and K1. They will have different sensitivities which are depicted in Fig. 4. More detectors in the network may be decisive for the detection of Galactic supernova by increasing the time when coherent analysis can be performed, or by increasing the sky coverage. While adding detectors in the network also increases the collected SNR and helps source localization [49], there are certain challenges, especially when some detectors are less sensitive. It includes optimizing the cWB internal thresholds or designing selection cuts but discussing these challenges is beyond the scope of this study. We simplify our method to provide an approximate estimation of the potential of the four detector network in the context of GW signals from CCSNe.

For all detector networks, we do not perform background analysis and no selection cuts are applied besides $\rho > 6$ (in the previous HL analysis it corresponds roughly to the significance of FAR < 1/year). For the sensitivity study, the Mul + 12 N20-2 waveform is used. Four detectors

provide 11 possible network configurations: HLVK, HLV, HVK, LVK, LHK, HL, LV, HV, KV, LK, LK, and HK.

Figure 12 shows the detection efficiency curves as a function of distance and injected SNR for different detector networks. Table III summarizes the detector ranges and minimum detectable SNRs for all detector networks. The networks including H1 and L1 detectors, namely HLVK, HLV, LHK, and HL, have comparable detection ranges in corresponding observing runs and the minimum detectable SNR in O4 will be similar to the one in O5. The detection ranges for the other three-detector networks, HVK and LVK will be slightly shorter while for the other two-detector networks, LV, HV, KV, LK, and HK will be two times smaller than for networks including HL. The minimum detectable SNR for the events detected in two-detector networks will be significantly larger.

TABLE III. Detector ranges and minimum detectable SNRs for projected O4 and O5 sensitivities for 11 possible detector configurations. The analysis is performed on the Mul + 12 N20-2 waveform.

Network	Det. range [kpc]		Min. detect. SNR	
	O4	O5	O4	O5
HLVK	2.1	3.7	15.9	16.1
LHV	1.9	3.7	15.5	15.5
HVK	1.6	2.6	16.4	17.0
LVK	1.5	2.6	16.7	17.3
LHK	2.1	3.7	14.4	14.5
LH	1.8	3.4	14.9	14.7
LV	0.8	1.6	27.0	25.3
HV	0.8	1.7	25.9	24.1
KV	0.8	1.4	19.6	19.8
LK	1.1	1.6	20.7	25.5
HK	1.2	1.6	19.2	25.5

V. SUMMARY

Core-collapse supernovae are one of the most spectacular phenomena known in the Universe. CCSN explosions are multimessenger sources and their emitted GWs are yet to be detected. Although these sources have been modeled for decades, the explosion mechanism and the details of physical processes inside an exploding star are still not fully understood. The detection of these GWs might shed light on rich stochastic dynamics. We analyzed 18 waveform families that represent an extensive set of possible signal morphologies. This wide range of models represents several emission processes, such as prompt convection, PNS oscillations, SASI/convection, core bounce, and BH formation. The typical GW energy range is from around $10^{-10} M_{\odot}$ to $10^{-7} M_{\odot}$ and the peak frequencies range from approximately 100 Hz to 1 kHz.

It is not possible to predict robustly a GW signal emitted by a CCSN, so the search algorithm needs to use weak or minimal assumptions on the signal morphology. Then, using minimal assumptions, we used the coherent WaveBurst algorithm to make predictions on the detectability of the next nearby CCSN event. We predict that in O5, the typical detection range for neutrino-driven explosions will be around 10 kpc. For models involving rapid rotation of the progenitor stars, the detection range can get up to above 100 kpc (and possibly more if a strong turbulent GW production continues after the end of the current simulations).

Our analysis of the minimum detectable SNR indicates that the GWs from CCSNe are detectable in the SNR range of roughly 10–25. The shorter waveforms are detectable with smaller SNR, while the longer and broadband signals require larger SNR to be detected. The latter are more challenging to detect, and their reconstructed SNR is usually underestimated.

We quantified the accuracy of the cWB reconstruction using waveform overlap between injected and reconstructed waveforms. The best accuracy is achieved for the short duration signals, like the core bounce. By considering particular GW emission processes, we find that the signals from PNS oscillations require an SNR of 30–40 to become visible in the time-frequency domain. The GW signatures from SASI/convection and prompt-convection can be detectable at SNR values of 15. To capture the full BH formation evolution of 2 s, in the example considered here, the SNR needs to be around 50.

We analyzed the detectability of GW signals with all possible detector network configurations of LIGO, Virgo, and KAGRA. The distance range and minimum detectable SNR are comparable for four- and three-detector networks

and HL. The detection ranges for two detector networks excluding HL will be around two times smaller.

We conclude that the success of detecting and reconstructing GWs from the next nearby CCSN will depend on several ingredients and in this paper we listed some of the challenges. The algorithms should be prepared before observing the next nearby CCSN and some efforts have already been made. The cWB search may play a significant role in this discovery. One aspect that is not discussed in this paper is the role that the multimessenger observations could have in increasing the detection confidence and feature reconstruction. We leave this aspect for future publications.

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