Gravitational microlensing by dark matter in extended structures

Djuna Croon[®], David McKeen,^{[†](#page-0-1)} and Nirmal Raj^{®[‡](#page-0-2)}

TRIUMF, 4004 Wesbrook Mall, Vancouver, British Columbia V6T 2A3, Canada

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Dark matter may be in the form of nonbaryonic structures such as compact subhalos and boson stars. Structures weighing between asteroid and solar masses may be discovered via gravitational microlensing, an astronomical probe that has in the past helped constrain the population of primordial black holes and baryonic MASSIVE ASTROPHYSICAL COMPACT HALO OBJECTs. We investigate the nontrivial effect of the size of and density distribution within these structures on the microlensing signal and constrain their populations using the EROS-2 and OGLE-IV surveys. Structures larger than a solar radius are generally constrained more weakly than pointlike lenses, but stronger constraints may be obtained for structures with mass distributions that give rise to caustic crossings or produce larger magnifications.

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I. INTRODUCTION

All our evidence for dark matter is gravitational. Its presence is seen in its gravitational pull on stars, gravitational lensing of light from distant galaxies, and gravitational imprints on both the thermal fluctuations of photons from the early Universe and the structure of the Universe on scales galactic and higher. While extensive attempts are at large to produce dark matter at colliders and to detect ambient dark matter directly or, in the remnants of its annihilation, indirectly, an appealing possibility is to unmask its microscopic identity in yet more gravitational phenomena. One such opportunity is provided by the recent inauguration of gravitational wave astronomy [\[1\],](#page-9-0) another by seeking anomalies in pulsar timing arrays [\[2\]](#page-9-1), and yet another by the observation of capture of dark matter sped up by the steep gravitational potentials of compact stars [\[3,4\].](#page-9-2) Astronomical efforts have also been long underway to constrain black holes or faint astronomical objects ("MACHOs") as dark matter candidates via the technique of gravitational microlensing, the observation of temporary, all-wavelength brightening of a background star whose light is deflected by the transiting object. In this paper, we study the microlensing signals of dark matter in macroscopic structures made of nonstandard states, i.e., structures that are not MACHOs.

The key distance scale in microlensing is the Einstein radius, the distance of closest approach of light rays seen by an observer when the source, lens, and observer lie along a line, as the light bends around a lens of mass M. Up to $\mathcal{O}(1)$ factors, the Einstein radius is the geometric mean of the distance to the source star and the Schwarschild radius associated with the lens, $2GM/c^2$. Microlensing surveys are typically sensitive to stars that are 10–1000 kpc away, and to transit times of minutes to years. Thus, for galactic dark matter with speed dispersion $\sim 10^{-3}$ c, microlensing is sensitive to dark matter masses ranging from asteroid to solar masses. Several scenarios predict a large population of dark matter structures in this mass range. Nonstandard cosmologies such as an early period of matter domination or vector boson production during inflation may enhance the growth of small-scale density perturbations, as a result of which most of the dark matter may survive currently in compact subhalos [5–[9\]](#page-9-3). In a similar vein, axion dark matter can form dense "miniclusters" [\[10\].](#page-9-4) The use of weak and strong gravitational lensing to probe such substructure has been already discussed [\[11\]](#page-9-5). Dark matter may also lurk in quantum structures such as boson stars, which are kept from collapsing under self-gravity by kinetic pressure or self-repulsion (e.g., [\[12](#page-9-6)–15]). An observation of the characteristic microlensing signals of any of these structures would have enormous implications for cosmology, star formation, and galaxy evolution.

Gravitational microlensing depends crucially on the spatial extent of the lens. Dark matter structures much smaller than the microlensing Einsten radius imitate pointlike lenses (such as black holes and MACHOs), and those much greater would barely lens the source star due to the diffuse spread of their mass. But for structures with characteristic size comparable to the Einstein radius the signal is nontrivial, and therefore so are the sensitivities of microlensing surveys to the population of dark matter in these structures. The signal also depends sensitively on how the net mass of a lens is distributed within it, as this determines how it bends spacetime and deflects light. Earlier studies have dealt with microlensing by dense primordial hydrogen-helium gas clouds [\[16\]](#page-9-7) and by axion

[^{*}](#page-0-3) dcroon@triumf.ca

[[†]](#page-0-3) mckeen@triumf.ca

[[‡]](#page-0-3) nraj@triumf.ca

FIG. 1. A heuristic estimate of the masses and sizes of dark matter structures that can be probed by the EROS-2 and OGLE-IV microlensing surveys of the Magellanic Clouds and Milky Way Bulge respectively. Here constant detection efficiencies and zero backgrounds are assumed for simplicity. For a fixed mass, the smallest lens size corresponds to the Schwarzschild radius of a black hole with the corresponding mass; the magnification is suppressed for lenses much smaller than the wavelength of light used in a survey. The largest lens size for a given mass that can be probed by the survey in question is approximately the maximum Einstein radius at that mass, above which the lens becomes too diffuse to magnify source stars efficiently. The lowest and highest masses probed by a survey are determined by the observational cadences of the survey. See Sec. [III](#page-3-0) for further details.

miniclusters [\[10,17\].](#page-9-4) In this work we extend these studies to dark matter subhalos with various density profiles, as well as to boson stars, and obtain constraints on their populations from the EROS-2 [\[18\]](#page-9-8) and OGLE-IV [\[19\]](#page-9-9) surveys. In Fig. [1](#page-1-0) we display, in the space of lens size vs lens mass, the best-case sensitivities of these surveys to these extended structures. In Sec. [II](#page-1-1) we explain how to determine these sensitivities. A recent microlensing survey by the Subaru telescope [\[20\]](#page-9-10) also probes our scenario; however, this survey was sensitive to a range of Einstein radii so small that the finite angular extent of source stars affects the signal nontrivially. In forthcoming work [\[21\]](#page-9-11), we investigate the effect of finite-sized sources on microlensing by finite-sized lenses.

This paper is laid out as follows. In Sec. [II](#page-1-1) we review the basics of gravitational microlensing, describing the treatment of extended lenses. In Sec. [III](#page-3-0) we estimate the rate of microlensing events and derive constraints on the fraction of dark matter in nonbaryonic structures. In Sec. [IV](#page-6-0) we outline future avenues of research and conclude. In the appendixes we collect detailed derivations of lens-planeprojected mass profiles of the various structures we consider and provide a method for rapid numerical computations of event rates.

II. MICROLENSING OF EXTENDED OBJECTS

In this section, we review some basics of gravitational microlensing, largely following the treatment in Ref. [\[22\]](#page-9-12).

FIG. 2. The geometry of the microlensing setup for a pointlike lens, seen to produce two images after deflection. From this geometry follows the lensing equation [Eq. [\(1\)\]](#page-1-3) governing the path of light rays, which determines the magnification [Eq. [\(4\)\]](#page-2-0).

Figure [2](#page-1-2) depicts the geometry of the setup. The observerlens, lens-source, and observer-source distances are D_L , $D_{\rm S}$, and $D_{\rm LS}$ respectively; the lens center and the source (an image and the source) subtend an angle β (θ) at the observer: in general, more than one image may be formed. Our calculations simplify as D_L , D_S , and D_{LS} are much larger than all other scales in the problem, resulting in small angular deflections of value $\alpha = \frac{4GM}{c^2 \xi}$ that only occur, in this approximation, when starlight encounters the "lens plane" perpendicular to the observersource axis.

Next we assume that the lens is spherically symmetric¹ with density distribution $\rho(r)$ so that the total mass $M = 4\pi \int_0^{\infty} dr r^2 \rho(r)$. The lensing equation that determines the path of light rays after deflection may then be written as

$$
\beta = \theta - \frac{\theta_{\rm E}^2}{\theta} \frac{M(\theta)}{M},\tag{1}
$$

where

$$
M(\theta) = 2\pi D_{\rm L}^2 \int_0^{\theta} d\theta' \theta' \Sigma(\theta'),
$$

$$
\Sigma(\theta) = \int_{-\infty}^{\infty} dz \rho (\sqrt{D_{\rm L}^2 \theta^2 + z^2}),
$$
 (2)

the latter quantity being the surface mass density projected onto the lens plane. The pointlike Einstein angle $\theta_{\rm E}$ is given by [\[25\]](#page-9-13)

$$
\theta_{\rm E} \equiv \sqrt{\frac{4GM}{c^2} \frac{D_{\rm LS}}{D_{\rm L} D_{\rm S}}},\tag{3}
$$

¹For studies on microlensing by aspherical objects, see, e.g., Refs. [\[23,24\].](#page-9-14)

obtained as the value of θ for a pointlike lens $[M(\theta) \rightarrow M]$ at $\beta = 0$. This in turn defines the pointlike Einstein radius² $r_{\rm E} \equiv D_{\rm L} \theta_{\rm E}$ on the lens plane. The volume contained within circles of radius r_E whose centers are along the line of sight is sometimes known as the "lensing tube". From Eq. [\(3\)](#page-1-4) it may seen that the lensing tube for pointlike lens is an ellipsoid.

Given a lens position β , Eq. [\(1\)](#page-1-3) may be solved to determine the image position(s), θ . While gravitational microlensing does not alter the *luminosity* of the source, the images subtend solid angles that are different from the source, proportionally altering the $flux$ received.³ Thus the magnification induced by an image is the ratio of its angular extent to that of the source,

$$
\mu(\theta(\beta)) = \left| \frac{\theta}{\beta} \frac{d\theta}{d\beta} \right|.
$$
\n(4)

The light curve, or the magnification as a function of time t, for a lens with velocity v and minimum impact parameter ξ_{min} is now determined by setting $\beta r_E = \sqrt{\xi_{\text{min}}^2 + v^2 t^2}$. As
the lens approaches and leaves the vicinity of the observerthe lens approaches and leaves the vicinity of the observersource axis, its image brightens and dims, the hallmark signature of gravitational microlensing. Whether such an occurrence is actually observable depends on the minimum detectable magnification for a given telescope, as well as the range of cadences at the microlensing survey, which sets the transit time scales to which it is sensitive.

For a pointlike lens at some impact parameter (in units of Einstein radius) $u = \xi/r_E = \beta/\theta_E$, we get from Eqs. [\(1\)](#page-1-3) and [\(4\)](#page-2-0) the total magnification,

$$
\mu_{\text{tot}} = \frac{u^2 + 2}{u\sqrt{u^2 + 4}} \xrightarrow{u=1} 1.34. \tag{5}
$$

For a pointlike lens, a microlensing event is defined as a transit across the lensing tube, which acts as the "detector volume". That is, a transit is counted as an event if it produces a total magnification $\mu_{tot} \geq \mu_T$, where it is conventional to take $\mu_T = 1.34$. Following this convention, we will also use this minimum magnification of a transit to define events for extended lenses.

Let us now characterize the *microlensing efficiency of an* extended lens compared to that of a pointlike lens. To do so, we define the quantity $u_{1,34}$ as the impact parameter for a lens such that all smaller impact parameters produce a magnification above the threshold,

$$
\mu_{\text{tot}}(u \le u_{1.34}) \ge 1.34. \tag{6}
$$

For a pointlike lens, $u_{1,34} = 1$. For an extended lens, it is clear from Eqs. [\(1\)](#page-1-3) and [\(4\)](#page-2-0) that $u_{1,34}$ depends on its mass profile, $m(\theta) \equiv M(\theta)/M$. In [A](#page-6-1)ppendix A we derive these mass profiles for all the lens species we consider:

- (i) self-similar subhalos, products of the isolated gravitational collapse of primordial density perturbations [\[26\]](#page-9-15). Their density profiles scale as $-9/4$ powers of the radius,
- (ii) lenses with density profiles that scale as $-3/2$ powers of the radius. These are inspired by the inner profiles of ultracompact minihalos (UCMHs), said to form at redshifts ≥ 1000 in regions where overdensities are very large, $\delta \rho / \rho \gtrsim 10^{-3}$ [\[27\],](#page-9-16)
- (iii) Navarro-Frenk-White (nfw) subhalos, suggested to be the products of hierarchical clustering triggered by, e.g., cold dark matter [\[28\],](#page-9-17)
- (iv) boson stars, gravitationally stable structures composed of scalar fields [\[14\],](#page-9-18)

(v) uniform spheres (of constant density) as a toy model.

In the top panel of Fig. [3](#page-3-1) we plot the various $u_{1,34}$ as a function of $r_{90}/r_E(x)$, where r_{90} is the radius within which 90% of the lens mass is contained, and $x \equiv D_L/D_S$. As expected, $u_{1.34} \to 1$ ($u_{1.34} \to 0$) for $r_{90} \ll r_E$ ($r_{90} \gg r_E$), while the most interesting features arise in the intermediary regime. The spikes in $u_{1,34}$ at $r_{90} \lesssim r_{\rm E}$ for the UCMH-like subhalo, boson star and uniform sphere are caused by the lens crossing a "caustic", an impact parameter at which the number of images changes discontinuously and produces infinite magnification (in reality regulated by the finite extent of the source). For these lens species, regions where $u_{1,34}$ < 1 correspond to there being only one image contributing to μ_{tot} at $u = u_{1.34}$, however even a single image can have large μ_{tot} for $r_{90} \gtrsim r_E$, so that $u_{1,34} > 1$ in this region. For NFW and self-similar subhalos there are no caustics, and $u_{1,34} > 1$ for $r_{90} \gtrsim r_E$. Their mass distributions make them efficient lenses even at very large r_{90} , so that $u_{1,34}$ decreases gradually as $r_{\text{max}}/r_{\text{E}}$ is increased. The above information on microlensing efficiency is key to obtaining microlensing event rates and constraints on lens populations, a task to which we will turn in the next section.

Let us illustrate the above features with concrete exam-ples. In the bottom panel of Fig. [3](#page-3-1) we have plotted $u_{1,34}$ versus D_{L} for NFW subhalos and boson stars of mass 10^{-3} M_{\odot} for various r_{90} : 3 R_{\odot} , 30 R_{\odot} , 300 R_{\odot} , where $R_{\odot} = 6.96 \times 10^9$ is the solar radius. The distance to the source is here assumed to be 50 kpc, corresponding to the distance to the Large Magellanic Cloud. The maximum $r_{\rm E}$ in this setup is 70 R_{\odot} . Lenses much smaller than this have $u_{1,34} \simeq 1$ everywhere, viz., behave like pointlike lenses. The 30 R_{\odot} (300 R_{\odot}) NFW subhalo is slightly more (less) efficient than pointlike lenses everywhere in the lensing tube. Both the 30 R_{\odot} and 300 R_{\odot} boson stars are more efficient than pointlike lenses in the middle of the lensing tube, and less efficient near the source and observer. The 30 R_{\odot} boson star is also seen to spike in efficiency about 5 kpc off the source or observer, which occurs due to it crossing a caustic at these distances.

²In this paper, Einstein angle and radius, $\theta_{\rm E}$ and $r_{\rm E}$, should be understood to refer only to the values corresponding to a pointlike lens of mass M .

One assumes here that the lens is transparent to light (as is true for structures of dark matter) lest it occult the image. We thank Yue Zhao for raising this point on either side of the Pacific.

Threshold impact parameter

FIG. 3. Threshold impact parameter in units of the pointlike Einstein radius, as defined in Eq. [\(6\),](#page-2-1) for various lens species. Top: as a function of the lens radius containing 90% of the total mass r_{90} , in units of the pointlike Einstein radius. *Bottom*: as a function of the distance to the lens D_L for NFW subhalos and boson stars of various sizes with total mass $M = 10^{-3} M_{\odot}$ and distance to the source $D_S = 50$ kpc. In both panels, the spiky features appear for lens sizes and distances corresponding to the lens crossing a caustic, where the magnification formally diverges. The threshold impact parameter defines the cross sectional radius of the "detector volume" at a microlensing survey, transits across which are counted as events. Hence the information in these plots is key to obtaining limits on dark matter populations, as done in Sec. [III.](#page-3-0)

III. EVENT RATES AND CONSTRAINTS

Having defined a microlensing event in Sec. [II](#page-1-1), we now estimate the rate of events collected in microlensing surveys. Here we follow the treatment in Ref. [\[29\],](#page-10-0) which takes into account the distribution of dark matter velocities, assumed to be Maxwell-Boltzmann, as well as the density of dark matter along the line of sight to the source, $\rho_{\text{lens}}(x) = f_{\text{DM}}\rho_{\text{DM}}(x)$, where f_{DM} is the mass fraction of lenses making up the dark matter density ρ_{DM} . For a singe source star and unit exposure time, the differential event rate with respect to x and event time scale $t_{\rm E}$ is then obtained as

$$
\frac{d^2\Gamma}{dx dt_E} = \varepsilon(t_E) \frac{2D_S}{v_0^2 M} f_{\text{DM}} \rho_{\text{DM}}(x) v_E^4(x) e^{-v_E^2(x)/v_0^2}, \quad (7)
$$

where $v_{\rm E}(x) \equiv 2u_{1,34}(x)r_{\rm E}(x)/t_{\rm E}$ with $r_{\rm E}(x)$ given in Eq. [\(3\)](#page-1-4) and $u_{1,34}(x)$ plotted in Fig. [3,](#page-3-1) $v_0 = 220$ km/s is the dark matter circular speed in the Galaxy, and $\varepsilon(t_{\rm E})$ is the efficiency of telescopic detection. Equation [\(7\)](#page-3-2) assumes that the source and the observer are static in the microlensing setup, which yields event rates to within 10% accuracy [\[30\]](#page-10-1). It also assumes that all lenses in a population have a single mass M. Generalizing to other mass distributions is straightforward. The total number of events is then given simply by

$$
N_{\text{events}} = N_{\star} T_{\text{obs}} \int_0^1 dx \int_{t_{\text{E,min}}}^{t_{\text{E,max}}} dt_{\text{E}} \frac{d^2 \Gamma}{dx dt_{\text{E}}}, \qquad (8)
$$

where N_{\star} is the number of source stars used in the survey, T_{obs} is the total observation time, and $t_{E,min}$ ($t_{E,max}$) is the minimum (maximum) time scale of an event in the survey. In Appendix [B](#page-9-19) we briefly describe how to numerically evaluate the above integral rapidly.

The parameters used for EROS-2 and OGLE-IV are given in Table [I.](#page-3-3) For evaluating N_{events} in Eq. [\(8\),](#page-3-4) we use the locations of the source stars and the detection efficiencies provided in Refs. [\[18,30\]](#page-9-8), and assume an isothermal profile for the Milky Way halo,

$$
\rho_{\rm DM}(r) = \frac{\rho_{\rm s}}{1 + (r/r_{\rm s})^2},
$$

$$
r \equiv \sqrt{R_{\rm Sol}^2 - 2xR_{\rm Sol}D_{\rm S}\cos\ell\cos b + x^2D_{\rm S}^2}, \quad (9)
$$

where $R_{Sol} = 8.5$ kpc, $\rho_s = 1.39$ GeV/cm³, and $r_s =$ 4.38 kpc are the galactic radial distance of the Sun, the core density, and core radius respectively [\[31\];](#page-10-2) ℓ and b are the longitude and latitude of the source in galactic coordinates. Picking an isothermal galactic halo, in which v_0 does not vary with distance, simplifies our calculation of the event rate; we have checked that our results are robust against the choice of the halo profile.

TABLE I. Survey parameters used for placing constraints in Sec. [III.](#page-3-0) The third panel provides the location of the source in terms of (distance, longitude, latitude), taken from Ref. [\[32\].](#page-10-3)

Survey	Source field	(D_s, ℓ, b)	N_{+}	$T_{\rm obs}$ (day)	$t_{\rm F}$ range (day)
EROS-2 $[18]$	LMC SMC	$(50 \text{ kpc}, 280.46^{\circ}, -32.89^{\circ})$ $(60 \text{ kpc}, 302.81^{\circ}, -44.33^{\circ})$	5.49×10^{6} 0.86×10^{6}	2500	[1,1000]
OGLE-IV [19,30,33]	MW Bulge	$(8.5 \text{ kpc}, 1.09^{\circ}, -2.39^{\circ})$	4.88×10^{7}	1826	[0.1, 300]

FIG. 4. Left: Differential event detection rates per unit exposure of dark matter in pointlike lenses at the EROS-2 and OGLE-IV microlensing surveys, as obtained from Eq. [\(7\)](#page-3-2) and Table [I.](#page-3-3) The low-t_E (high-t_E) contribution of very light (very heavy) lenses to the event rates are left out due to limitations of the cadences. Right: 90% C.L. limits on the fraction of pointlike lenses making up the dark matter density, as estimated in Sec. [III](#page-3-0). See text for further details.

In Fig. [1](#page-1-0) we show a heuristic estimate of lens sizes and masses probed by the EROS-2 surveys of either Magellanic Cloud and by the OGLE-IV survey of the Milky Way Bulge, assuming zero foreground, and a constant detection efficiency of $\varepsilon(t_{\rm E}) = 0.2$ ($\varepsilon(t_{\rm E}) = 0.05$) and event time scales $\{t_{\text{E,min}}, t_{\text{E,max}}\} = \{1 \text{ d}, 500 \text{ d}\} \quad \{(0.6 \text{ d}, 10 \text{ d}\}) \text{ for EROS-2}$ (OGLE-IV), an approximation that qualitatively characterizes the surveys in Refs. [\[18,30\].](#page-9-8) Lenses cannot be more compact than black holes; hence, their sizes are bounded from below by their Schwarzschild radius $\propto M$. Moreover, the microlensing geometric setup breaks down for lens sizes much smaller than the photonic wavelength spectrum of the telescope, since the effects of wave optics greatly suppress the magnification [\[34\].](#page-10-4) In Fig. [1](#page-1-0) we have indicated this with a horizontal dashed line. As argued in Sec. [II](#page-1-1), lens sizes that can be constrained by microlensing are approximately bounded from above by their pointlike Einstein radius $\propto M^{1/2}$.

At a given microlensing survey, there is a minimum $(t_{\text{E,min}})$ and maximum $(t_{\text{E,max}})$ transit time, set respectively by the maximum and minimum observational cadences. For small M, we have $v_E \gg 1$, and evaluating Eq. [\(8\)](#page-3-4) in this limit, $N_{\text{events}} \propto M/t_{\text{E,min}}^3$. Thus the detection rate is suppressed as we decrease M : these lenses transit too briefly even for the survey's highest cadence. For large M, we have $v_{\rm E} \ll 1$, and in this limit $N_{\rm events} \propto t_{\rm E,max}^3/M^2$. Here the detection rates are suppressed as we increase M : these lenses are too scarce in number and transit too long for the survey's lowest cadence. In Fig. [1,](#page-1-0) $N_{\text{events}} > 1$ for the mass range within the vertical lines corresponding to a survey and $N_{\text{events}} < 1$ outside.

To inspect the above limitations in more detail, in Fig. [4](#page-4-0) left-hand panel we show for pointlike lenses ($u_{1,34} = 1$) the distance-integrated event rates $d\Gamma/dt_E$ at EROS-2 and OGLE-IV. We see that these surveys sample most transits arising from pointlike lenses of masses around $10^{-5} M_{\odot}$. However, low- $t_{\rm E}$ transits of lenses that are much lighter are missed. This is because lighter lenses generate thinner lensing tubes, across which high-velocity transits from the tail of the Maxwell-Boltzmann distribution last for very short times, below the cadence thresholds of the telescope. High- t_E transits of lenses that are very heavy are also missed. This is because these lenses generate very thick lensing tubes, across which low-velocity transits, albeit magnifying some background star, may not alter the source flux appreciably over the maximum timescale of transit to which the telescope is sensitive.

A. Limits on pointlike lenses

The features discussed above result in the 90% C.L. limits plotted in the right-hand panel of Fig. [4,](#page-4-0) on the fraction of dark matter in pointlike lenses as a function of their mass. To obtain the EROS-2 limits, we used Eq. [\(8\)](#page-3-4) and set $N_{\text{events}} = 3.9$, corresponding to the number of events expected at the 90% C.L. for the one event observed, assuming Poisson statistics. Our limits differ somewhat from those estimated by the EROS collaboration, who count events as [\[18\]](#page-9-8)

$$
N_{\text{events}}^{\text{EROS}} = N_{\star} T_{\text{obs}} \frac{2 e(t_{\text{E}})}{\pi \langle t_{\text{E}} \rangle} \tau,
$$
\n(10)

where τ is the "optical depth", the probability of finding a lens in the lensing tube at any given instant,

$$
\tau = D_{\rm S} \int_0^1 dx \frac{f_{\rm DM} \rho_{\rm DM}(x)}{M} \pi r_{\rm E}^2(x). \tag{11}
$$

In the mass range constrained by EROS-2 there are also weak bounds from the MACHO Collaboration, which do not change the limits appreciably when combined with EROS-2 [\[35\]](#page-10-5). Weaker limits also exist from the EROS-1 survey [\[36\]](#page-10-6); these would strengthen our limits at most by 20% for large M, and are completely superseded by OGLE-IV for small M. Finally, the observation of the blue supergiant

FIG. 5. 90% C.L. limits from the microlensing surveys EROS-2 (red curves) and OGLE-IV (blue curves) on the fraction of dark matter in nonbaryonic extended structures, as obtained in Sec. [III](#page-3-0). Structures smaller than 10 R_{\odot} (R_{\odot}) may be approximated as a pointlike lens at EROS-2 (OGLE-IV), resulting in constraints essentially the same as in Fig. [4.](#page-4-0) Larger structures magnify background stars nontrivially depending on their size and internal mass distribution (see Fig. [3](#page-3-1)), resulting in structure-specific constraints.

MACS J1149 LS1 at a distance of 4.3 Gpc, interpreted as a pointlike lens crossing a caustic and producing $\mathcal{O}(10^3)$ magnification, provides a constraint in this mass range [\[37\]](#page-10-7). However, we do not display it here as the astrophysics is relatively uncertain and the EROS-2 limit could almost entirely cover the constrained region (see Fig. 8 of Ref.[\[37\]](#page-10-7)).

To obtain the OGLE-IV limits one must account for $\mathcal{O}(1000)$ events observed in their 5-year data set, which agree at the 1% level with astrophysical models of standard foreground events [\[30\].](#page-10-1) ⁴ There are also six events near $t_{\rm E} \sim 0.1$ days for which there is no satisfactory explanation [\[19,30,39\]](#page-9-9), but here we will adopt the null hypothesis that they constitute the foreground. Using Ref. [\[30\]](#page-10-1)'s binning of events in t_{E} , for every bin i we define N_i^{DM} as the number of dark matter-induced events obtained from Eq. [\(8\)](#page-3-4) and N_i^{FG} as the foreground count. Then defining $N_i^{\text{SIG}} \equiv N_i^{\text{FG}} + N_i^{\text{DM}}$, we use the quantity [\[40\],](#page-10-8)

$$
\kappa = 2 \sum_{i=1}^{N_{\text{bins}}} \left[N_i^{\text{FG}} - N_i^{\text{SIG}} + N_i^{\text{SIG}} \ln \frac{N_i^{\text{SIG}}}{N_i^{\text{FG}}} \right], \qquad (12)
$$

and obtain the 90% C.L. Poissonian limit by locating $(f_{DM},$ M) for which $\kappa = 4.61$. Our resultant limit on the right-hand panel of Fig. [4](#page-4-0) is in good agreement with that obtained in Ref. [\[30\]](#page-10-1).

⁴We note the recent appearance of OGLE-IV's 8-year data set [\[38\]](#page-10-9) containing 5790 observed events as opposed to 2622 in the 5-year data set. As the standard foreground has not been estimated for the new data (a task beyond our scope), we use the 5-year data set for obtaining limits, remarking that we do not expect the limits to improve markedly due to increased foregrounds.

B. Limits on extended lenses: Main results

Next we obtain constraints for extended lenses of various sizes and density profiles by setting $u_{1,34}$ in Eq. [\(7\)](#page-3-2) to the values plotted in Fig. [3](#page-3-1). We display these limits in Fig. [5](#page-5-0), which are the main results of our paper. For $r_{90} \lesssim 10 R_{\odot}$ $(r_{90} \lesssim R_{\odot})$, the EROS-2 (OGLE-IV) limits are the same as that for pointlike lenses seen in Fig. [4](#page-4-0). For r_{90} in these ranges, the lenses are smaller than the smallest r_E to which each survey is sensitive; hence $u_{1,34} \rightarrow 1$ $u_{1,34} \rightarrow 1$ $u_{1,34} \rightarrow 1$ as seen in Fig. 3. As we increase r_{90} , the limits for all lens species generally weaken for small M, where r_E is small so that $u_{1,34} < 1$ for $r_{90}/r_{\rm E} > 1$ as seen in Fig. [3.](#page-3-1) In particular, the OGLE-IV limits for $r_{90} = 30 R_{\odot}$ are $M \lesssim 10^{-6} - 10^{-5} M_{\odot}$, weakening by 1–2 orders of magnitude with respect to pointlike lenses. The limit weakens further by $\mathcal{O}(100)$ for $r_{90} = 300 R_{\odot}$. Similarly, the EROS-2 limit on M weakens by 1–2 orders of magnitude with respect to pointlike lenses for $r_{90} = 300 R_{\odot}$.

For the $r^{-3/2}$ and the boson star profiles, however, we notice additional features: for small M there are two regions where the limits on f_{DM} are weaker than pointlike lenses and two where they are stronger. We can understand this from the behavior of their $u_{1,34}$ in Fig. [3;](#page-3-1) for fixed r_{90} , scanning from left to right on this plot roughly corresponds to scanning from right to left on Fig. [5](#page-5-0). Thus, (1) for large M the lens is pointlike $(u_{1,34} \rightarrow 1)$; (2) as we lower M we enter the region where the lens is efficient (*i.e.*, $u_{1,34} > 1$) due to caustic crossings, giving stronger limits; (3) as we lower M further, the lens is inefficient (*i.e.*, $u_{1,34}$ < 1) due to the contribution of a sole pointlike image to the magnification, giving weaker limits; (4) as we lower M even further, the lens is efficient again (*i.e.*, $u_{1,34} > 1$) due to large magnification from one image, giving stronger limits again; (5) finally, for very small M the lens is too spatially diffuse to magnify the source efficiently (i.e., $u_{1,34} \ll 1$), giving weaker limits again.

We end this section by remarking that we have not used any information about the light curves of events in deriving our constraints. For some lens species, e.g., boson stars, extra features in the light curves that may arise from caustic crossings could be used to better distinguish them from foregrounds, potentially giving improved limits or sensitivity.

IV. DISCUSSION

In this work, we estimated constraints from the gravitational microlensing surveys EROS-2 of the Magellanic Clouds and OGLE-IV of the Galactic Bulge, on the population of dark matter in nonbaryonic structures of selfsimilar subhalos, density profiles that scale like the inner regions of ultracompact minihalos, NFW subhalos, and boson stars. Our main results are summarized in Fig. [5](#page-5-0). In deriving these limits we assumed that the source stars were pointlike, an approximation that breaks down for the high-cadence survey of M31 by Subaru that is sensitive to small Einstein radii [\[20\].](#page-9-10) Computing the magnification of finite-sized stars by finite-sized lenses and estimating the ensuing limits on dark matter populations is the subject of our forthcoming work [\[21\].](#page-9-11)

Our work is applicable to several avenues of research. While we have estimated population limits on four representative extended structures, they may also be estimated for subhalos of other density profiles [\[2,16\]](#page-9-1), ten AU-sized dark stars [\[41\]](#page-10-10), R_{\odot} -sized mirror stars [\[42\],](#page-10-11) primordial dark matter halos [\[43\],](#page-10-12) extended structures formed by mirror dark matter [\[44\],](#page-10-13) and so on. Microlensing surveys of the Galaxy by the space-based WFIRST [\[45\]](#page-10-14) and Euclid [\[46\]](#page-10-15) (the Earth-based LSST [\[47\]](#page-10-16)) would probe sub-Earth mass (stellar mass) dark matter structures. The stellar mass range can also be probed by lensing of type-Ia supernovae [\[48\]](#page-10-17). Using parallax measurements in lensing can probe asteroid to planet masses [\[49,50\]](#page-10-18). Should numerous microlensing events be detected, the data on light curves may help us estimate the subhalo mass function and perform dark matter astrometry, in particular help identify departures from the standard halo model such as the presence of tidal streams, as already constrained by weak lensing in the time domain [\[51,52\]](#page-10-19). Finally, it would be interesting to investigate the effect on our constraints of varying the magnification threshold in Eq. [\(6\).](#page-2-1)

On the whole, microlensing is a promising gravitational probe to discover dark matter structures bred by novel cosmologies and astrophysics.

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APPENDIX A: MASS PROFILES AND LENSING EQUATIONS

In this appendix we give some more information about the mass profiles $M(\theta)/M$ appearing in the lensing equation in Eq. [\(1\)](#page-1-3) for various lens species, discuss features of the resultant solutions to the lensing equation, and obtain expressions for the magnification. These aspects show up as features in the threshold impact parameter $u_{1,34}$ $u_{1,34}$ $u_{1,34}$ (Fig. 3), which are relevant for counting microlensing events and placing constraints.

Let us begin with generalities. Expressing angles in units of the Einstein angle $\theta_{\rm E}$ or, equivalently, distances on the lens plane in units of the Einstein radius $(u = \beta/\theta_E = D_L \beta/r_E, t = \theta/\theta_E = D_L \theta/r_E)$ allows us to rewrite Eqs. [\(1\)](#page-1-3) and [\(2\)](#page-1-5) as

$$
u = t - \frac{m(t)}{t},
$$
 (A1)

where $m(t) \equiv M(\theta_{\rm E}t)/M$ describes the distribution of the lens mass projected onto the lens plane. For a spherically symmetric density profile $\rho(r)$,

$$
m(t) = \frac{\int_0^t d\sigma \sigma \int_0^\infty d\lambda \rho (r_{\rm E} \sqrt{\sigma^2 + \lambda^2})}{\int_0^\infty d\gamma \gamma^2 \rho (r_{\rm E} \gamma)}.
$$
 (A2)

From Eq. [\(4\),](#page-2-0) the magnification can be written as

$$
\mu = \left| \frac{t}{u} \frac{dt}{du} \right| = \left| 1 - \frac{m(t)}{t^2} \right|^{-1} \left| 1 + \frac{m(t)}{t^2} - \frac{1}{t} \frac{dm(t)}{dt} \right|^{-1} . \quad (A3)
$$

From this it is seen that the only way in which the total lens mass M and the distances D_L , D_{LS} , D_S enter the problem is through their contributions to r_E in Eq. [\(3\)](#page-1-4). At a fixed r_{E} , the density profile of the lens $\rho(r)$ turns up as $m(t)$ in Eq. [\(A1\).](#page-7-0) Solving the lensing equation, we can then use Eq. $(A3)$ to determine the magnification of the image (s) as a function of u . We perform this calculation for specific lenses in the following subsections. In what follows, we will make some approximations that illustrate properties of the mass profile $m(t)$ and the resulting solutions of the lensing equation—however, to obtain the limits shown above, we have numerically calculated the $m(t)$ profiles without resorting to any approximate forms.

1. Uniform sphere

As a warm up, we will study a spherical lens of uniform density. This distribution has the virtue of being analytically tractable and shares some qualitative features with other lenses such as the boson star profiles we will find below. The density of such an object can be written as $\rho(r) = \rho_0 \Theta(r_m - r)$ where r_m is the radius of the sphere. From Eq. [\(A2\)](#page-7-1) we obtain

$$
m(t) = \begin{cases} 1 - (1 - t^2/t_m^2)^{3/2}, & |t| < t_m \\ 1, & |t| \ge t_m, \end{cases}
$$
 (A4)

where $t_m \equiv r_m/r_E$. The lensing equation [\(A1\)](#page-7-0) is now quintic in t, and depending on b and t_m , gives either one or three real solutions. In particular, there may be three solutions for $t_m < \sqrt{3/2}$. When $|u| < |t_m - t_m^{-1}|$ two of the solutions located at $|t| > t$ correspond to pointlike lens solutions, located at $|t| > t_{\rm m}$, correspond to pointlike lens solutions,

$$
t_{\pm} = \frac{u}{2} \left(1 \pm \sqrt{1 + \frac{4^2}{u}} \right) \Rightarrow \sum |\mu_{\pm}| = \frac{u^2 + 2}{u\sqrt{u^2 + 4}}.
$$
 (A5)

The third solution is located at $|t| < t_m$ and does not have an analytic form, but we can determine it for $|t| \ll t_{\rm m}$, which corresponds to $u \ll |t_m - t_m^{-1}|$,

$$
t_3 \simeq u \left(1 - \frac{3}{2t_m^2}\right)^{-1},
$$
 (A6)

with magnification,

$$
\mu_3 \simeq \left(1 - \frac{3}{2t_m^2}\right)^{-2} \left[1 - \frac{3u^2}{t_m^2} \left(1 - \frac{3}{2t_m^2}\right)^{-2}\right].
$$
 (A7)

Note that if we take $t_m \rightarrow 0$, the magnification from this image vanishes, $\mu_3 \rightarrow 0$, and the total magnification is just that in [\(A5\)](#page-7-2). In other words, we recover the pointlike magnification in Eq. [\(A5\)](#page-2-2) when we shrink the lens to the pointlike limit.

Now for $t_m < \sqrt{3/2}$ and large u, there is just one solution at $t = t_+$ given in Eq. [\(A5\)](#page-7-2). As one dials u from large to small values, the number of solutions to the lens equation goes from one to three. At the transition, there are two solutions where the magnification formally diverges, since for that solution $du/dt = 0$. In reality, this divergence is regulated by the finite size of the source. The existence of such caustics can, however, have an important effect, causing $u_{1,34} > 1$ for the uniform sphere for some range of $r_{\rm m}/r_{\rm E}$ as seen in Fig. [\(3](#page-3-1)).

For $t_m > \sqrt{3/2}$, there is only one solution to the lensing equation regardless of u. For large u, it is $t \approx u$ with $\mu \approx 1$. For small u, is $t = t_3$ in Eq. [\(A6\)](#page-7-3) with an approximate magnification of

$$
\mu_3 \simeq 1 + \frac{3}{t_{\rm m}^2} (1 - u^2),\tag{A8}
$$

so that to obtain $\mu > 1$ we need $u < 1$; *i.e.*, the lens must be within the pointlike lensing tube.

2. Power-law density profiles

Another profile that will be useful for us is a simple power law, $\rho(r) \propto r^n$. For $n \ge -3$, to avoid a divergent total mass we must cut this profile off at some radius r_m . The mass profile in this case is

$$
m(t) = \frac{\int_0^t d\sigma \sigma \int_0^{\sqrt{t_m^2 - \sigma^2}} d\lambda (\sigma^2 + \lambda^2)^{n/2}}{\int_0^{t_m} d\gamma \gamma^{2+n}}, \quad \text{(A9)}
$$

where, again, $t_m = r_m/r_E$. It is useful to understand the behavior of this at small t . In this regime, we can simplify the expression by taking the upper limit on the λ integral to be ∞ , finding

$$
m(t) \propto \left(\frac{t}{t_{\rm m}}\right)^{3+n}.\tag{A10}
$$

Thus, if $n > -2$, then $m(t)/t \to 0$ as $t \to 0$, giving $u = t = 0$ as a solution to the lensing equation [\(A1\)](#page-7-0). For a density profile that is not too diffuse, i.e., $t_m < 1$, we have $m(t = 1) = 1$, and so $u = 0$, $t = \pm 1$ also satisfies
the lensing equation. This means that if $n > -2$ and $t < 1$ the lensing equation. This means that if $n > -2$ and $t_m < 1$, there is a range of impact parameters u such that there are three solutions to the lensing equation, and therefore there are impact parameters corresponding to caustics where the number of images changes abruptly and formally produces $\mu \rightarrow \infty$. For steeper profiles, $n < -2$, $u = t = 0$ is not a solution of the lensing equation, and one thus finds only two solutions to the lensing equation, with no caustic crossings.

We consider two power-law profiles in this work. The first is the so-called self-similar profile [\[26\],](#page-9-15)

$$
\rho(r) \propto r^{-9/4},
$$

which has been suggested to result from direct gravitational collapse of initial state perturbations within scalar condensates, such as axion miniclusters [\[10\]](#page-9-4). From Sec. [II](#page-1-1) of this appendix, we see that the mass profile $m(t)$ at small t scales as

$$
m(t) \propto t^{3/4}.\tag{A11}
$$

Therefore, we only expect two lensed images, without any caustic crossings. As a result we expect a smooth transition from an inefficient lens, for when the maximum radius of the subhalo is large, to a pointlike lens, for when it is small. This is indeed the behavior we see in the critical impact parameter $u_{1,34}$ for the "self-similar subhalo" in Fig. [3.](#page-3-1)

The second power-law density profile that we study is slightly shallower than the self-similar profile above,

$$
\rho(r) \propto r^{-3/2}.
$$

This form is motivated by studies of the inner region of "ultracompact minihalos" [\[27\]](#page-9-16) as well as halos limited in size by free streaming [\[53\].](#page-10-20) Based on the discussion above, the mass profile at small t scales as

$$
m(t) \propto t^{3/2},\tag{A12}
$$

so that $m(t)/t \to 0$ as $t \to 0$. This means that, when its size is comparable to the pointlike Einstein radius, the $r^{-3/2}$ profile can give rise to caustic crossings and the associated enhancement of the microlensing magnification. We see this exhibited in Fig. [3](#page-3-1) where $u_{1,34} > 1$ for some values of $r_{90}/r_{\rm E}$ for $\rho \propto r^{-3/2}$, similar to the uniform sphere, which can provide a reasonable approximation of this density profile for microlensing.

3. NFW subhalos

The Navarro-Frenk-White (NFW) profile is often a good description of structures that form through hierarchical structure formation. This profile scales as r^{-1} for small radii and as r^{-3} for large radii. The scale factor r_s defines the transition between the two regimes. More concretely, the profile is [\[28\]](#page-9-17)

$$
\rho(r) = \frac{\rho_{\rm s}}{(r/r_{\rm s})(1+r/r_{\rm s})^2}.
$$

The total mass contained within this profile diverges logarithmically, so we must cut it off at some radius r_m . As in Ref. [\[10\]](#page-9-4), we take $r_m = 100 r_s$ for the structures we consider, motivated by numerical studies of axion miniclusters. The mass profile $m(t)$ is obtained numerically, which we use to determine $u_{1,34}$ in Fig. [3.](#page-3-1) Given the large ratio between r_s and r_m , the NFW profile we consider is essentially r^{-3} . Following the discussion above, this means that $|m(t)/t|$ is large near $t = 0$, and therefore multiple images and caustics do not appear as with shallower density profiles. This means that the NFW lens smoothly interpolates between the pointlike and inefficient regimes, as seen in Fig. [3](#page-3-1).

4. Boson stars

Boson stars are Bose-Einstein condensates: gravitationally bound clumps of a scalar field (elementary [\[12\]](#page-9-6) or composite [\[54\]\)](#page-10-21) condensate, kept from collapsing under self-gravity by kinetic pressures and possibly self-repulsive forces. Their occupation numbers in quantum states are typically very high; hence they are described by classical field theory. It is typically sufficient to consider the nonrelativistic limit, δ in which their hydrostatic equilibrium is described by Schrödinger-Poisson equations. In the limit of negligible self-coupling, we solve these equations numerically to compute our mass profile $m(t)$ and the resultant $u_{1,34}$ in Fig. [3.](#page-3-1)

The Schrödinger-Poisson equations are given by [\[12\]](#page-9-6)

$$
i\partial_t \psi = -\frac{1}{2m_\phi} \nabla^2 \psi + m_\phi \Phi \psi,
$$

$$
\nabla^2 \Phi = 4\pi G |\psi|^2,
$$
 (A13)

where ψ is a nonrelativistic decomposition of the scalar field ϕ ,

$$
\phi(r,t) = \frac{1}{\sqrt{2}m_{\phi}} e^{-im_{\phi}t} \psi(r,t) + \text{c.c.},
$$

with m_{ϕ} the mass of the scalar and Φ the self-gravitational potential. The ground state of a boson star is spherically symmetric and can be written as

⁵See, however, Ref. [\[15\]](#page-9-20).

$$
\psi_{\rm gs}(r,t) = \left(\frac{m_\phi}{\sqrt{4\pi G}}\right) \Psi(r) e^{-i\mu t},\tag{A14}
$$

where the dimensionless parameter Ψ parametrizes the radial distribution, and μ is a chemical potential. For the ground state, the first equation in [\(A13\)](#page-8-0) becomes

$$
\mu \Psi = -\frac{1}{2m_{\phi}} \left(\Psi'' + \frac{2}{r} \Psi' \right) + m_{\phi} \Phi \Psi \qquad (A15)
$$

in the absence of self-interactions. We solve these equations numerically, as no closed form solution for $\Psi(r)$ exists generally. As a function of radius, the enclosed mass is then given by

$$
M(r) = \frac{1}{m_{\phi}G} \int_0^{m_{\phi}r} dy y^2 \Psi^2(y), \quad (A16)
$$

from which the projected mass profile $m(t)$ may be computed. Rescalings of Ψ leave Eq. [\(A15\)](#page-9-21) invariant; hence solutions exist for any boson star mass:

$$
\left(\frac{M}{10^{-3} \text{ M}_{\odot}}\right) \sim \lambda \left(\frac{10^{-7} \text{ eV}}{m_{\phi}}\right),\tag{A17}
$$

where λ is the ratio of the gravitational potential energy per scalar constituent to its mass m_{ϕ} [\[55\].](#page-10-22) For the nonrelativistic treatment to be self-consistent, $0 < \lambda \ll 1$.

As seen in Fig. [3](#page-3-1) and mentioned in Sec. [I](#page-0-4), the qualitative features of boson star microlensing signals are captured by the uniform sphere toy model.

APPENDIX B: SPEEDY EVALUATION OF EVENT RATES

We here outline a method to rapidly evaluate the integral in Eq. [\(8\)](#page-3-4) that, to our knowledge, has not been mentioned in the literature before. First we rewrite the integrand as $(A(x)/t_{\rm E}^4)e^{-B(x)/t_{\rm E}^2}$ to separate the $t_{\rm E}$ -dependent and x-
dependent parts. Then we note that the integral over to dependent parts. Then we note that the integral over $t_{\rm E}$ has an analytic form,

$$
A \int dt_{\rm E} \frac{e^{-B/t_{\rm E}^2}}{t_{\rm E}^4} = \frac{A}{2B} \left[\frac{e^{-B/t^2}}{t_{\rm E}} - \sqrt{\pi} \frac{\text{erf}(\sqrt{B}/t_{\rm E})}{\sqrt{B}} \right].
$$

Using this, we can evaluate the integral over x in Eq. [\(8\)](#page-3-4) for narrow bins of t_{E} , taking the efficiency $\varepsilon(t_{\text{E}})$ constant in each bin. Summing over the bins gives N_{events} .

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