Gravitational-wave-driven tidal secular instability in neutron star binaries

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We report the existence of a gravitational-wave-driven secular instability in neutron star binaries, acting on the equilibrium tide. The instability is similar to the classic Chandrasekhar-Friedman-Schutz instability of normal modes and is active when the spin of the primary star exceeds the orbital frequency of the companion. Modeling the neutron star as a Newtonian n = 1 polytrope, we calculate the instability timescale, which can be as low as a few seconds at small orbital separations but still larger than the inspiral timescale. The implications for orbital and spin evolution are also briefly explored, where it is found that the instability slows down the inspiral and decreases the stellar spin.

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I. INTRODUCTION

Finite-size effects have been shown to play an important role during the late stages of a neutron star binary inspiral. Given that current gravitational-wave (GW) detectors rely mainly on searching for theoretically predicted signals in their noisy data stream (matched filtering), the GW signal obtained by modeling the two stars as point particles may not be accurate enough due to phase errors induced by the tidal interaction (e.g., Refs. [1,2]). The significance of tidal effects on the GW signal and the binary evolution is determined by the tidal deformability of the stars, parametrized by the so-called tidal Love number [3], which depends on the neutron star equation of state, namely, the equation of state of cold dense nuclear matter. Hence, the influence of the tidal interaction on the GW signal can be used to place constraints on the neutron star equation of state [4], something that was demonstrated already after the first detection of GWs from a neutron star binary [5–9].

Another promising source of GWs and potential probe of the equation of state of supranuclear matter is neutron star instabilities. As discovered by Chandrasekhar [10] and rigorously proven by Friedman and Schutz [11,12], certain oscillation modes in fast-rotating neutron stars are unstable to the emission of GWs. The instability occurs when a mode which is retrograde in the frame rotating with the star appears as prograde in the inertial frame. Then, the GWs emitted by the deformed star tend to increase the energy of the perturbation, causing the mode to grow on a secular timescale (for a review, see, e.g., Refs. [13,14]). This effect is more pronounced in large-scale perturbations, described by the star's fundamental modes (f modes), which have no radial nodes and emit GWs more efficiently. In addition to polar modes, where density perturbations prevail and fast angular velocities are needed for the instability to develop, axial modes are also prone to the Chandrasekhar-Friedman-Schutz (CFS) instability. These are characterized mainly by perturbations of the fluid's horizontal velocity field and are caused by rotation itself (*r* modes [15]), which makes them CFS-unstable at all rotation rates (in the absence of viscosity) [16,17].

Unstable oscillation modes are suitable for asteroseismology studies, in order to infer the neutron star equation of state, and can, in principle, generate large amounts of GWs [18–22]. Furthermore, the presence of the instability is expected to play a significant role in the evolution of nascent neutron stars and neutron stars in low-mass x-ray binaries (LMXBs), as shown by evolutionary studies [23–27], whereas it has been suggested as a possible explanation for the absence of pulsars spinning close to their break-up (mass-shedding) limit (~1 kHz) [28–30]. So far, Advanced LIGO and Virgo have not detected any evidence for such signals [31–34].

In the present paper, we examine the stability of the tidal perturbation on a rotating star against the emission of GWs. To our knowledge, this problem has not been addressed by previous studies on gravitational radiation from tidally perturbed stars [35–39] (however, see Ref. [40], where the resonant excitation of CFS-unstable modes from the tide is considered).

Assuming that the spin Ω of the primary star is aligned with the orbital angular velocity ω_{orb} of its companion, the tidal perturbation induced on the primary will always be prograde in the inertial frame, but will appear retrograde in the rotating frame if $\Omega > \omega_{orb}$. Using the equilibrium tide approximation, i.e., assuming that the perturbed star is always in hydrostatic equilibrium, we show that GWs generated by the tidally deformed primary drive an instability, which develops on a secular timescale associated with the emission of GWs and has an impact on orbital and spin evolution.

We start by introducing the hydrodynamic equations describing a forced perturbation on the primary star, for which we derive an energy, as well as an energy rate which contains contributions from the varying tidal potential and from the gravitational radiation reaction force (Secs. II A and II B). Subsequently, we approximate the tidal perturbation with the equilibrium tide (Sec. IIC), which is computed analytically for a polytrope with index n = 1in the Appendix. In Sec. III we study the stability of the equilibrium tide against the emission of GWs, where we derive the instability criterion, calculate the instability growth time for a neutron star described by a polytropic equation of state with index n = 1, and compare it to the inspiral timescale. In Sec. IV we explore the implications of this instability for orbital and spin evolution, where we compute the corrections to the inspiral rate and the stellar spin for the same model. Finally, we summarize the main points and results and discuss some caveats and other considerations in Sec. V.

II. THE TIDAL PERTURBATION

A. Equation of motion

We consider a star rotating with an angular velocity Ω (primary), perturbed by the tidal potential U of a companion star. The primary is no longer in hydrostatic equilibrium due to the tidal perturbation. The linearized (with respect to the perturbation) hydrodynamic equations for the primary, in the frame rotating with it, read

$$\frac{\partial \delta \rho}{\partial t} + \nabla \cdot (\rho \delta \boldsymbol{v}) = 0, \qquad (2.1)$$

 $\frac{\partial \delta \boldsymbol{v}}{\partial t} + 2\boldsymbol{\Omega} \times \delta \boldsymbol{v} + \frac{\nabla \delta p}{\rho} - \frac{\nabla p}{\rho^2} \delta \rho + \nabla \delta \Phi + \nabla U = \boldsymbol{0},$ (2.2)

$$\nabla^2 \delta \Phi = 4\pi G \delta \rho, \qquad (2.3)$$

$$\nabla^2 U = 0, \qquad (2.4)$$

$$\frac{\Delta p}{p} = \Gamma_1 \frac{\Delta \rho}{\rho}, \qquad (2.5)$$

which are the (perturbed) continuity equation, Euler equation, Poisson equation, Laplace equation for the tidal potential, and equation of state, respectively. The symbols have their usual meanings: ρ is the density, p is the pressure, Φ is the gravitational potential, v is the velocity, whereas t denotes time and G is the gravitational constant. Eulerian and Lagrangian perturbations are denoted by δ and Δ , respectively, and are related by $\Delta f = \delta f +$ $(\boldsymbol{\xi} \cdot \nabla)f$, where $\boldsymbol{\xi}$ is the displacement vector associated with the perturbation. The adiabatic exponent Γ_1 is defined as

$$\Gamma_1 = \left(\frac{\partial \ln p}{\partial \ln \rho}\right)_{x_p},\tag{2.6}$$

where x_p denotes the proton fraction (i.e., the proton number density over the baryon number density), which generally varies throughout the star, but is considered as "frozen" during an orbital period ($\Delta x_p \approx 0$), due to the slow timescales on which β reactions operate [41].¹

Using the fact that $\delta v = \xi$ (where the dot denotes the time derivative), Eqs. (2.1) and (2.2) are written as

$$\delta \rho + \nabla \cdot (\rho \boldsymbol{\xi}) = 0 \tag{2.7}$$

and

$$\ddot{\boldsymbol{\xi}} + 2\boldsymbol{\Omega} \times \dot{\boldsymbol{\xi}} + \frac{\nabla \delta p}{\rho} - \frac{\nabla p}{\rho^2} \delta \rho + \nabla \delta \Phi + \nabla U = \boldsymbol{0}, \quad (2.8)$$

respectively. Furthermore, using the relation between Lagrangian and Eulerian perturbations, Eq. (2.5) becomes

$$\frac{\delta\rho}{\rho} = \frac{1}{\Gamma_1} \frac{\delta p}{p} - A \cdot \boldsymbol{\xi}, \qquad (2.9)$$

where

$$A = \frac{\nabla \rho}{\rho} - \frac{1}{\Gamma_1} \frac{\nabla p}{p}.$$
 (2.10)

This is the Schwarzschild discriminant, with $|A| \neq 0$ denoting the presence of buoyancy in the star (e.g., Ref. [42]). In a star with no composition gradients $(x_p = \text{const}), |A| = 0$ and perturbed fluid elements adjust instantaneously to the density of their surroundings.² For later convenience, we rewrite the Euler equation (2.8) as

$$\ddot{\boldsymbol{\xi}} + 2\boldsymbol{\Omega} \times \dot{\boldsymbol{\xi}} + \nabla \left(\frac{p\Gamma_1}{\rho} \frac{\delta\rho}{\rho} + \delta\Phi + U \right) + \frac{p\Gamma_1}{\rho} \frac{\delta\rho}{\rho} \boldsymbol{A} + \frac{1}{\rho} \nabla (p\Gamma_1 \boldsymbol{\xi} \cdot \boldsymbol{A}) = \boldsymbol{0}.$$
(2.11)

B. Perturbation energy

The rotating-frame energy associated with the perturbation is [12,44]

$$E = \frac{1}{2} \int \left[|\dot{\boldsymbol{\xi}}|^2 + \boldsymbol{\xi}^* \cdot \boldsymbol{C}(\boldsymbol{\xi}) \right] \rho \mathrm{d}^3 \boldsymbol{r}, \qquad (2.12)$$

¹This assumption may not be valid at large orbital separations, but the current work is not concerned with this regime.

²Entropy gradients can also generate a nonzero buoyancy in a star, but are relevant mostly in newborn neutron stars, where the thermal pressure can be comparable to the degeneracy pressure [43].

where the operator C is given by

$$\boldsymbol{C}(\boldsymbol{\xi}) = \nabla \left(\frac{p\Gamma_1}{\rho} \frac{\delta\rho}{\rho} + \delta\Phi\right) + \frac{p\Gamma_1}{\rho} \frac{\delta\rho}{\rho} \boldsymbol{A} + \frac{1}{\rho} \nabla (p\Gamma_1 \boldsymbol{\xi} \cdot \boldsymbol{A}).$$
(2.13)

Replacing the above in Eq. (2.12) and performing some integrations by parts, we get

$$E = \frac{1}{2} \int \left\{ \rho |\dot{\boldsymbol{\xi}}|^2 + \frac{p\Gamma_1}{\rho} \frac{|\delta\rho|^2}{\rho} - \frac{1}{4\pi G} |\nabla\delta\Phi|^2 - p\Gamma_1 \left[(\boldsymbol{\xi}^* \cdot \boldsymbol{A})(\nabla \cdot \boldsymbol{\xi}) + (\boldsymbol{\xi} \cdot \boldsymbol{A})(\nabla \cdot \boldsymbol{\xi}^*) + \frac{1}{\rho} (\boldsymbol{\xi}^* \cdot \boldsymbol{A})(\boldsymbol{\xi} \cdot \nabla\rho) \right] \right\} d^3\boldsymbol{r}.$$
(2.14)

Because of the presence of the tidal potential, the perturbation energy changes at a rate (e.g., see Ref. [12])

$$\frac{\mathrm{d}E}{\mathrm{d}t} = \mathrm{Re}\left[\int \dot{\boldsymbol{\xi}^*} \cdot (-\nabla U)\rho \mathrm{d}^3 \boldsymbol{r}\right]. \tag{2.15}$$

Equation (2.15) can be further supplemented with dissipation mechanisms, like GWs. In a Newtonian framework, GWs are implemented by introducing a potential that accounts for their emission by the perturbed star [45,46]. Then, the perturbation energy rate due to GW emission is

$$\begin{pmatrix} \frac{\mathrm{d}E}{\mathrm{d}t} \end{pmatrix}_{\mathrm{GW}} = -\frac{1}{2} \sum_{l=2}^{\infty} \sum_{m=-l}^{l} (-1)^{l} N_{l} \\ \times \left[\frac{\mathrm{d}^{2l+1}}{\mathrm{d}t^{2l+1}} (\delta D_{l}^{m} e^{-im\Omega t}) \frac{\mathrm{d}\delta D_{l}^{*m}}{\mathrm{d}t} e^{im\Omega t} + \frac{\mathrm{d}^{2l+1}}{\mathrm{d}t^{2l+1}} (\delta D_{l}^{*m} e^{im\Omega t}) \frac{\mathrm{d}\delta D_{l}^{m}}{\mathrm{d}t} e^{-im\Omega t} \right], \quad (2.16)$$

where

$$N_{l} = \frac{4\pi G}{c^{2l+1}} \frac{(l+1)(l+2)}{l(l-1)[(2l+1)!!]^{2}},$$
 (2.17)

c being the speed of light, and δD_l^m are the mass multipole moments,³ defined as

$$\delta D_l^m = \int r^l \delta \rho Y_l^{*m} \mathrm{d}^3 \boldsymbol{r}, \qquad (2.18)$$

with $Y_l^m(\theta, \phi)$ denoting the spherical harmonic of degree *l* and order *m*, defined in the rotating frame using a spherical coordinate system (r, θ, ϕ) .

The effects of GWs will be treated as secular, i.e., developing on a timescale much longer than the timescale associated with the perturbation. Then, Eq. (2.16) can be evaluated by using the solutions to the inviscid problem, namely, the solutions to Eq. (2.11) [46]. This assumption will be shown to be valid in retrospect.

C. The equilibrium tide

The general solution for the tidal perturbation is often considered to comprise two parts: the *equilibrium* and the *dynamical* tides. The former corresponds to the instantaneous response of the primary to the tidal field of the companion, whereas the latter includes the resonant excitation of the primary's normal modes by the orbiting companion [48,49].

The equilibrium tide is simply obtained by assuming that the tidally perturbed star is in hydrostatic equilibrium, i.e., by setting the time derivatives in Eq. (2.8) to zero. For simplicity, we will neglect the effects of rotation, in which case the eigenfunctions of the equilibrium tide are (e.g., Ref. [50])

$$\delta p = -\rho(\delta \Phi + U), \qquad (2.19)$$

$$\delta\rho = \frac{\mathrm{d}\rho}{\mathrm{d}r}\frac{\delta\Phi + U}{g},\qquad(2.20)$$

$$\xi_r = -\frac{\delta \Phi + U}{g},\tag{2.21}$$

$$\nabla \cdot \boldsymbol{\xi} = 0, \qquad (2.22)$$

and $\delta \Phi$ is given by

$$\nabla^2 \delta \Phi = 4\pi G \frac{\mathrm{d}\rho}{\mathrm{d}r} \frac{\delta \Phi + U}{g}, \qquad (2.23)$$

where $g = d\Phi/dr$ and ξ_r is the radial component of the displacement vector $\boldsymbol{\xi}$.

In order to express the tidal perturbation, we will use an inertial frame centered on the primary, with its z axis parallel to the orbital angular momentum vector (generally not aligned with the primary's spin). Denoting the spherical coordinates of this frame as (r, θ', ϕ') , then the tidal potential is expanded in spherical harmonics as

$$U = -\sum_{l=2}^{\infty} \sum_{m'=-l}^{l} \frac{GM' W_l^{m'} r^l}{D^{l+1}(t)} Y_l^{m'}(\theta', \phi') e^{-im'\Psi(t)}, \qquad (2.24)$$

where M' is the mass of the companion (treated as a point mass), D(t) is the separation between the companion and the primary, $\Psi(t)$ is the orbital phase of the companion, and

³Typically, current multipole moments, accounting for gravitomagnetic effects, must also be included in Eq. (2.16) (see Ref. [47]), but they are ignored here since we only have polar perturbations [see Eq. (2.27)].

$$W_l^{m'} = \frac{4\pi}{2l+1} Y_l^{*m'}(\pi/2,0)$$

= $(-)^{(l+m')/2} \left[\frac{4\pi}{2l+1} (l+m')!(l-m')! \right]^{1/2}$
 $\times \left[2^l \left(\frac{l+m'}{2} \right)! \left(\frac{l-m'}{2} \right)! \right]^{-1},$ (2.25)

where $(-)^k = (-1)^k$, unless k is not an integer, in which case it evaluates to zero [51].

Considering a harmonic (l, m') of the tidal potential and separating the radial, angular, and time dependence of the variables, then Eqs. (2.19)–(2.21) give the radial part of the corresponding eigenfunctions and Eq. (2.23) becomes

$$\frac{1}{r^2}\frac{\mathrm{d}}{\mathrm{d}r}\left(r^2\frac{\mathrm{d}\delta\Phi}{\mathrm{d}r}\right) - \frac{l(l+1)}{r^2}\delta\Phi - 4\pi G\frac{\mathrm{d}\rho}{\mathrm{d}r}\frac{\delta\Phi + U}{g} = 0$$
(2.26)

(henceforth, the tidal potential U and the perturbations will include only their radial dependence, i.e., their angular and time dependence shall be omitted). Replacing the displacement vector for polar perturbations, namely,

$$\boldsymbol{\xi} = \left[\xi_r, \xi_h \frac{\partial}{\partial \theta'}, \frac{\xi_h}{\sin \theta'} \frac{\partial}{\partial \phi'}\right] Y_l^{m'}(\theta', \phi') \qquad (2.27)$$

in Eq. (2.22), we also obtain

$$\xi_h = \frac{1}{l(l+1)r} \frac{d}{dr} (r^2 \xi_r).$$
 (2.28)

For consistency, we will now express the tidal perturbation in the rotating frame used in Sec. II B. Let the rotating frame be described by the axes (x, y, z), with the z axis parallel to the primary's spin, and the inertial frame by (x', y', z'), with the z' axis parallel to the orbital angular momentum. The two frames are related by the three Euler angles (α, β, γ) , which are obtained as follows: rotate the inertial frame about the z' axis by an angle α to obtain the frame $(x'_1, y'_1, z'_1 = z')$; rotate the new frame about the y'_1 axis by an angle β (spin-orbit inclination angle) to obtain the frame $(x'_2, y'_2 = y'_1, z'_2)$ —this is the rotating frame at t = 0, so $z'_2 = z$; finally, rotate the new frame about the z axis by an angle $\gamma = \Omega t$, to obtain the rotating frame (x, y, z).⁴

Then, the spherical harmonics of the inertial frame $Y_l^{m'}(\theta', \phi')$ are related to the spherical harmonics of the rotating frame $Y_l^m(\theta, \phi)$ as

$$Y_{l}^{m'}(\theta',\phi') = \sum_{m=-l}^{l} D_{m'm}^{*(l)}(\alpha,\beta,\gamma) Y_{l}^{m}(\theta,\phi), \qquad (2.29)$$

where the (complex conjugate of the) Wigner D function is given by

$$D_{m'm}^{*(l)} = e^{im'\alpha} d_{m'm}^{(l)}(\beta) e^{im\gamma}, \qquad (2.30)$$

with

$$d_{m'm}^{(l)}(\beta) = [(l+m)!(l-m)!(l+m')!(l-m')!]^{1/2} \\ \times \sum_{k} \frac{(-1)^{k+m'+m}(\cos\frac{\beta}{2})^{2l+m-m'-2k}(\sin\frac{\beta}{2})^{m'-m+2k}}{k!(l-m'-k)!(l+m-k)!(k+m'-m)!}$$
(2.31)

and the summation over k runs over all integer values for which the factorial arguments are non-negative [52].

III. EQUILIBRIUM TIDE STABILITY

According to the classic CFS instability for normal modes in rotating stars, an oscillation on the star becomes unstable to the emission of gravitational radiation when its inertial-frame frequency changes sign [11,12]. For a mode with a harmonic dependence $e^{i(m\phi+\omega t)}$, where ω is its rotating-frame frequency, Eq. (2.16) takes the familiar form [46]

$$\left(\frac{\mathrm{d}E}{\mathrm{d}t}\right)_{\mathrm{GW}} = -\omega(\omega - m\Omega) \sum_{l=l_{\mathrm{min}}}^{\infty} N_l (\omega - m\Omega)^{2l} |\delta D_l^m|^2, \quad (3.1)$$

where $l_{\min} = \max(2, |m|)$. Equation (3.1) shows that $\dot{E}_{\text{GW}} > 0$ if and only if $\omega(\omega - m\Omega) < 0$. Thus, the onset of the instability occurs when the angular velocity of the star is such that the inertial-frame frequency of the mode $\omega_{\text{in}} \equiv \omega - m\Omega$ becomes zero. The instability can only affect retrograde modes (m > 0), i.e., modes propagating against the rotation of the star, which, under the influence of rotation, appear as prograde in the inertial frame.

In the following, we will study the conditions under which the CFS instability affects the equilibrium tide. For simplicity, we will assume that the spin of the primary is aligned with the orbital angular momentum ($\beta = 0$). Then, since $d_{m'm}^{(l)}(0) = \delta_{m'm}$ (where $\delta_{m'm}$ is Kronecker's delta), Eq. (2.29) gives the anticipated result⁵

$$Y_l^m(\theta, \phi') = Y_l^m(\theta, \phi) e^{im\Omega t}.$$
 (3.2)

Hence, the harmonic time dependence of the equilibrium tide in the rotating frame is $e^{im[\Omega t - \Psi(t)]}$.

⁴This is the *z*-*y*-*z* convention, using right-handed frames, with positive angles obtained by the right-handed screw rule [52].

⁵The constant phase difference α between the two frames can be set to zero.

A. Circular orbit

In the simple case of a static circular orbit, we have $\Psi(t) = \omega_{\text{orb}} t$, where ω_{orb} is the orbital angular velocity, and the binary separation D = const. Then, the time dependence of the equilibrium tide in the rotating frame becomes $e^{im(\Omega - \omega_{\text{orb}})t}$ and Eq. (2.16), for a specific harmonic (l, m) of the tide, gives

$$\begin{pmatrix} \frac{\mathrm{d}E}{\mathrm{d}t} \end{pmatrix}_{\mathrm{GW}} = -N_l m^2 \omega_{\mathrm{orb}} (\omega_{\mathrm{orb}} - \Omega) (m\omega_{\mathrm{orb}})^{2l} \\ \times \left[\int_0^R \frac{\mathrm{d}\rho}{\mathrm{d}r} \frac{\delta \Phi + U}{g} r^{l+2} \mathrm{d}r \right]^2.$$
(3.3)

This shows that $\dot{E}_{\rm GW} > 0$ if

$$\Omega > \omega_{\rm orb}, \tag{3.4}$$

or, replacing $\omega_{\rm orb}$ from Kepler's law and normalizing Ω to the Kepler (mass-shedding) limit for spherical stars, $\Omega_K = \sqrt{GM/R^3}$ (where *R* is the primary's radius)⁶ [53], the instability criterion takes the elegant form

$$F(\Omega, D, M') \equiv \left(\frac{\Omega}{\Omega_K}\right) \left(\frac{D}{R}\right)^{3/2} - \left(1 + \frac{M'}{M}\right)^{1/2} > 0.$$
(3.5)

The timescale τ_{GW} associated with damping (or growth) due to GWs is [46]

$$\tau_{\rm GW} = \frac{2E}{\dot{E}_{\rm GW}},\tag{3.6}$$

where the energy of the (l, m) harmonic of the equilibrium tide can be obtained by replacing the eigenfunctions of Sec. II C in Eq. (2.14), which gives

$$E = \frac{1}{2} [m(\Omega - \omega_{\text{orb}})]^2 \int_0^R \left\{ \left(\frac{\delta \Phi + U}{g} \right)^2 + \frac{1}{l(l+1)} \right. \\ \left. \times \left[-\frac{r}{g} \left(\frac{d\delta \Phi}{dr} + \frac{lU}{r} \right) + \frac{\delta \Phi + U}{g} \left(\frac{d\ln g}{d\ln r} - 2 \right) \right]^2 \right\} \rho r^2 dr \\ \left. -\frac{1}{8\pi G} \int_0^\infty \left[\left(r \frac{d\delta \Phi}{dr} \right)^2 + l(l+1)(\delta \Phi)^2 \right] dr \\ \left. + \frac{1}{2} \int_0^R \left(\frac{\delta \Phi + U}{g} \right)^2 \frac{d\ln \rho}{dr} \frac{dp}{dr} r^2 dr.$$
(3.7)

Assuming that the star is described by a polytrope with index n = 1, we can now evaluate the instability timescale τ_{GW} for the l = 2 components of the equilibrium tide, the eigenfunctions of which can be obtained analytically



FIG. 1. Instability growth time τ_{GW} (in sec) as a function of the angular velocity Ω of the primary (normalized to the Kepler limit Ω_K ; *x* axis) and the orbital distance *D* (normalized to the primary's radius *R*; *y* axis). The primary is a neutron star described by an n = 1 polytropic equation of state, with $M = 1.4 M_{\odot}$ and R = 10 km, orbited by an equal mass companion (M' = M). The inspiral timescale τ_{ins} is also shown, as a function of the orbital distance, for comparison.

(as shown in the Appendix). For a neutron star with $M = 1.4 M_{\odot}$ (where M_{\odot} is the solar mass) and R = 10 km, the instability growth time is given by

$$\begin{aligned} \tau_{\rm GW} &= \left[8.5 \times 10^{-4} \left(\frac{D}{R} \right)^9 F^{-1}(\Omega, D, M') \right. \\ &+ 2.3 \times 10^{-3} \left(\frac{D}{R} \right)^6 F(\Omega, D, M') \right] \left(1 + \frac{M'}{M} \right)^{-5/2}. \end{aligned} \tag{3.8}$$

In this model, $\nu_K = \Omega_K / 2\pi \approx 2.2$ kHz. Equation (3.8) is plotted in Fig. 1 for $F(\Omega, D, M') > 0$ (i.e., where the instability is active) and M' = M. For reasonable values of the mass ratio M'/M, the timescale is not significantly affected.

B. Inspiral

The orbital motion of two stars generates GWs, gradually shrinking the binary's orbit and eventually leading to its coalesence. For two pointlike stars in a quasicircular orbit the orbital separation changes due to quadrupole emission of GWs as (e.g., Ref. [54])

$$\frac{\mathrm{d}D}{\mathrm{d}t} = -\frac{64G^3}{5c^5} \frac{MM'(M+M')}{D^3},$$
(3.9)

whereas the orbital phase Ψ evolves according to

⁶A more accurate approximation of the Kepler limit in Newtonian stars can be obtained by using the Roche model and is given by $\Omega_K = (2/3)^{3/2} \sqrt{GM/R^3}$ [53].

$$\frac{\mathrm{d}\Psi}{\mathrm{d}t} = \omega_{\mathrm{orb}} = \sqrt{\frac{G(M+M')}{D^3}},\qquad(3.10)$$

from which we also get

$$\frac{\mathrm{d}\omega_{\mathrm{orb}}}{\mathrm{d}t} = -\frac{3}{2}\frac{\dot{D}}{D}\omega_{\mathrm{orb}}.$$
(3.11)

The orbit is quasicircular in the sense that the inspiral rate $|\dot{D}|/D$ is much smaller than ω_{orb} .

The energy of the tidal perturbation changes due to the orbital shrinking according to Eq. (2.15) which, evaluated for a certain harmonic of the equilibrium tide, gives

$$\left(\frac{\mathrm{d}E}{\mathrm{d}t}\right)_{\mathrm{ins}} = -(l+1)\frac{\dot{D}}{D}\frac{GM'W_l^m}{D^{l+1}}\int_0^R \frac{\mathrm{d}\rho}{\mathrm{d}r}\frac{\delta\Phi+U}{g}r^{l+2}\mathrm{d}r$$
(3.12)

[note that the tidal potential U and the perturbations are now functions not only of r, but also of D(t), which will be henceforth implied]. Using the relation between the mass multipole moments and the tidal Love number k_l (e.g., Ref. [55]), Eq. (3.12) can also be written as

$$\left(\frac{\mathrm{d}E}{\mathrm{d}t}\right)_{\mathrm{ins}} = -2k_l R^{2l+1} \frac{(2l+1)(l+1)}{4\pi G} \frac{\dot{D}}{D} \left(\frac{GM' W_l^m}{D^{l+1}}\right)^2.$$
(3.13)

In a similar manner, the energy rate of the tidal perturbation due to GW emission is obtained from Eq. (2.16) as

$$\begin{pmatrix} \frac{dE}{dt} \end{pmatrix}_{\rm GW} = (-1)^{l+1} N_l \left[\int_0^R \frac{d\rho}{dr} \frac{\delta \Phi + U}{g} r^{l+2} dr \right]^2 \\ \times \operatorname{Re} \left[(f^* - im\Omega) \left(f + \frac{d}{dt} \right)^{2l} f \right],$$
(3.14)

where $f(t) = -(l+1)\dot{D}/D - im\omega_{orb}$. For $l \sim m \neq 0$ we have $|\text{Re}(f)| \ll |\text{Im}(f)|$. From Eq. (3.11) we also see that $\dot{\omega}_{orb} \ll \omega_{orb}^2$, which implies that derivatives of Im(f) can be neglected. Then, we recover Eqs. (3.3) and (3.4), albeit with a time dependence on ω_{orb} and the perturbation variables. This can also be expressed in terms of the Love number as

$$\begin{pmatrix} \frac{dE}{dt} \\ _{\rm GW} \end{pmatrix}_{\rm GW} = -N_l (m\omega_{\rm orb})^{2l+2} \left(1 - \frac{\Omega}{\omega_{\rm orb}}\right) \\ \times \left(2k_l R^{2l+1} \frac{2l+1}{4\pi G} \frac{GM' W_l^m}{D^{l+1}}\right)^2.$$
(3.15)

The significance of the instability can be assessed by comparing the growth time τ_{GW} to the inspiral timescale, given by

$$\tau_{\rm ins} = \frac{D}{|\dot{D}|} = \frac{5c^5}{64G^3} \frac{D^4}{MM'(M+M')}, \qquad (3.16)$$

which, for $M = 1.4 M_{\odot}$ and R = 10 km, evaluates as

$$\tau_{\rm ins} = 2.95 \times 10^{-4} \left(\frac{D}{R}\right)^4 \left[\frac{M'}{M} \left(1 + \frac{M'}{M}\right)\right]^{-1}.$$
 (3.17)

This is also plotted in Fig. 1, alongside the instability growth time. Both from Fig. 1 and from a direct comparison between Eqs. (3.8) and (3.17) it becomes evident that the inspiral timescale is shorter than the time required for the instability to develop for all values of D and Ω .

IV. IMPLICATIONS

Using some simple arguments, we will present the implications of this instability of the equilibrium tide on the orbital and spin evolution, restricting ourselves to the quadrupole components (l = 2). The energy rate of the tidal perturbation, denoted below as \dot{E}_{tide} , is given by Eqs. (3.13) and (3.15) and can be written as

$$\dot{E}_{\text{tide}} = \epsilon \dot{E}_{\text{tide}}^{(1)} + \epsilon^2 \dot{E}_{\text{tide}}^{(2)}, \qquad (4.1)$$

where

$$\epsilon = 2k_2 \left(1 + \frac{M'}{M}\right) \left(\frac{R}{D}\right)^5 \tag{4.2}$$

and $\dot{E}_{tide}^{(1)}, \dot{E}_{tide}^{(2)}$, which will be given below, contain the contributions of the inspiral and of GW emission to the energy rate of the tidal perturbation.

For a binary system in a quasicircular orbit, where the tidal deformation of the primary (but not of the companion) is taken into account, the GW power emitted from the system is [56,57]

$$\dot{E}_{\rm GW} = \dot{E}_{\rm GW}^{(0)} + \epsilon \dot{E}_{\rm GW}^{(1)} + \epsilon^2 \dot{E}_{\rm GW}^{(2)}, \tag{4.3}$$

where

$$\dot{E}_{\rm GW}^{(1)} = 2\dot{E}_{\rm GW}^{(0)},$$
(4.4)

$$\dot{E}_{\rm GW}^{(2)} = \dot{E}_{\rm GW}^{(0)},$$
(4.5)

and

$$\dot{E}_{\rm GW}^{(0)} = -\frac{32G^4(MM')^2(M+M')}{5c^5D^5}, \qquad (4.6)$$

which is the point-mass limit [58]. Note that E_{GW} is not to be confused with the contribution of GW emission to the energy rate of the tidal perturbation [Eqs. (2.16), (3.3), (3.14), and (3.15)], which is here contained in E_{tide} (see below).

Expanding the orbital energy losses in a similar way, we have

$$\dot{E}_{\rm orb} = \dot{E}_{\rm orb}^{(0)} + \epsilon \dot{E}_{\rm orb}^{(1)} + \epsilon^2 \dot{E}_{\rm orb}^{(2)}.$$
 (4.7)

At zeroth order in ϵ , we simply get

$$\dot{E}_{\rm orb}^{(0)} = \dot{E}_{\rm GW}^{(0)},$$
 (4.8)

from which we obtain the orbital decay in the point-mass limit, given by Eq. (3.9). Then, using this in Eq. (3.13), we get

$$\dot{E}_{\text{tide}}^{(1)} = -\frac{6M'}{M+M'} \dot{E}_{\text{GW}}^{(0)}.$$
(4.9)

Hence, the first-order correction to the orbital energy rate is

$$\dot{E}_{\rm orb}^{(1)} = \dot{E}_{\rm GW}^{(1)} - \dot{E}_{\rm tide}^{(1)}$$
 (4.10)

or, replacing Eqs. (4.4) and (4.9),

$$\dot{E}_{\rm orb}^{(1)} = \left(2 + \frac{6M'}{M + M'}\right) \dot{E}_{\rm GW}^{(0)}.$$
(4.11)

This can be used to calculate the first-order correction to the inspiral rate due to the tidal deformation of the primary. If $\dot{D} = \dot{D}^{(0)} + \epsilon \dot{D}^{(1)}$ (where $\dot{D}^{(0)}$ is the point-mass result), we find that

$$\dot{D}^{(1)} = \left(2 + \frac{6M'}{M + M'}\right)\dot{D}^{(0)},$$
 (4.12)

namely, the inspiral is accelerated, as expected [1].

At second order, both the inspiral and GW emission contribute to the tidal perturbation energy rate. The contribution of GW emission, obtained from Eq. (3.15), is

$$\dot{E}_{\text{tide,GW}}^{(2)} = \left(1 - \frac{\Omega}{\omega_{\text{orb}}}\right) \dot{E}_{\text{GW}}^{(0)}.$$
(4.13)

The contribution of the inspiral is found by replacing the first-order correction to the inspiral rate [Eq. (4.12)] back to Eq. (3.13), which gives

$$\dot{E}_{\text{tide,ins}}^{(2)} = -\frac{6M'}{M+M'} \left(2 + \frac{6M'}{M+M'}\right) \dot{E}_{\text{GW}}^{(0)}.$$
 (4.14)

Thus, the second-order correction to the orbital energy rate is

$$\dot{E}_{\rm orb}^{(2)} = \dot{E}_{\rm GW}^{(2)} - \dot{E}_{\rm tide}^{(2)} - \dot{E}_{\rm bg}^{(2)}, \qquad (4.15)$$

where we also added possible changes in the energy of the background (unperturbed) star, $\dot{E}_{\rm bg}^{(2)}$. Replacing Eqs. (4.5), (4.13), and (4.14), we get

$$\dot{E}_{\rm orb}^{(2)} + \dot{E}_{\rm bg}^{(2)} = \left[\frac{\Omega}{\omega_{\rm orb}} + \frac{6M'}{M+M'}\left(2 + \frac{6M'}{M+M'}\right)\right] \dot{E}_{\rm GW}^{(0)}.$$
(4.16)

In order to proceed with Eq. (4.16), we need to also consider the emission of angular momentum from the binary system. For GW emission from the tidal bulge, for which the second order term in Eq. (4.3) is responsible, angular momentum is emitted at a rate $\epsilon^2 \dot{J}_{GW}^{(2)}$, given by [47,59]

$$\dot{J}_{\rm GW}^{(2)} = \frac{\dot{E}_{\rm GW}^{(2)}}{\omega_{\rm orb}}.$$
 (4.17)

Likewise, for the orbit we have

$$\dot{J}_{\rm orb} = \frac{\dot{E}_{\rm orb}}{\omega_{\rm orb}}.$$
(4.18)

The angular momentum rate associated with the tidal perturbation can be obtained by computing the torque applied on the star by the tidal force, as well as by the gravitational radiation reaction force, namely, the force that accounts for GWs (see Ref. [46]). The total torque (along the z axis) is given by [60]

$$T = \int \delta \rho \boldsymbol{e}_z \cdot (\boldsymbol{r} \times \boldsymbol{F}^*) \mathrm{d}^3 \boldsymbol{r}, \qquad (4.19)$$

where F is the corresponding force (e.g., the tidal force is $F = -\nabla U$). Evaluation of Eq. (4.19) shows that $\dot{J}_{\text{tide,ins}}^{(2)} = 0$, which is expected, since we are only considering the equilibrium tide where the tidal bulge is always aligned with the companion.⁷ In addition, we get

$$\dot{J}_{\text{tide,GW}}^{(2)} = \frac{\dot{E}_{\text{tide,GW}}^{(2)}}{\omega_{\text{orb}} - \Omega}.$$
(4.20)

Hence, for the angular momentum emission from the system we have

$$\frac{\dot{E}_{\rm GW}^{(2)}}{\omega_{\rm orb}} = \frac{\dot{E}_{\rm orb}^{(2)}}{\omega_{\rm orb}} + \frac{\dot{E}_{\rm tide,GW}^{(2)}}{\omega_{\rm orb} - \Omega} + \frac{\dot{E}_{\rm bg}^{(2)}}{\Omega}, \qquad (4.21)$$

where we also replaced $\dot{E}_{bg}^{(2)} = \Omega \dot{J}_{bg}^{(2)}$. Using Eqs. (4.5) and (4.13), we finally obtain

⁷Thus, in this case, there is no dynamical tidal lag due to the inspiral (see Ref. [60]). Also, since we ignore viscosity, there is no viscosity-induced tidal lag either [1,2,60].

$$\frac{\dot{E}_{\rm orb}^{(2)}}{\omega_{\rm orb}} = -\frac{\dot{E}_{\rm bg}^{(2)}}{\Omega},\qquad(4.22)$$

which, replaced in Eq. (4.16), gives

$$\dot{E}_{\rm orb}^{(2)} = \frac{\frac{\Omega}{\omega_{\rm orb}} + \frac{6M'}{M+M'} \left(2 + \frac{6M'}{M+M'}\right)}{1 - \frac{\Omega}{\omega_{\rm orb}}} \dot{E}_{\rm GW}^{(0)} \qquad (4.23)$$

and

$$\dot{E}_{bg}^{(2)} = \frac{\frac{\Omega}{\omega_{orb}} + \frac{6M'}{M + M'} \left(2 + \frac{6M'}{M + M'}\right)}{1 - \frac{\omega_{orb}}{\Omega}} \dot{E}_{GW}^{(0)}.$$
 (4.24)

From Eqs. (4.23) and (4.24) we may now obtain the second-order correction to the inspiral rate $\epsilon^2 \dot{D}^{(2)}$ and the background star's spin derivative, respectively, as

$$\dot{D}^{(2)} = -\frac{F(\Omega, D, M') + \left(1 + \frac{M'}{M}\right)^{1/2} + \mathcal{T}(M')}{F(\Omega, D, M')}\dot{D}^{(0)}$$
(4.25)

and

$$\frac{\dot{\Omega}}{\Omega_{K}} = -\frac{F(\Omega, D, M') + \left(1 + \frac{M'}{M}\right)^{1/2} + \mathcal{T}(M')}{F^{2}(\Omega, D, M')} \times \frac{2\tilde{E}_{\text{tide}}(\Omega, D, M')}{\tau_{\text{GW}}(\Omega, D, M')} \left(\frac{D}{R}\right)^{3/2}, \qquad (4.26)$$

where

$$\mathcal{T}(M') = 12\frac{M'}{M} \left(1 + 4\frac{M'}{M}\right) \left(1 + \frac{M'}{M}\right)^{-3/2}$$
(4.27)

and

$$\tilde{E}_{\text{tide}} = \frac{E_{\text{tide}}}{I\Omega_K^2},\tag{4.28}$$

with E_{tide} being the energy of the quadrupole components of the equilibrium tide [see Eq. (3.7)] and *I* being the background star's moment of inertia. For a polytrope with n = 1, $M = 1.4 M_{\odot}$, and R = 10 km, we have

$$\tilde{E}_{\text{tide}} = 2.03 \left(\frac{M'}{M}\right)^2 \left(\frac{D}{R}\right)^{-9} F^2(\Omega, D, M') + 0.75 \left(\frac{M'}{M}\right)^2 \left(\frac{D}{R}\right)^{-6}, \qquad (4.29)$$

whereas $\tau_{\rm GW}$ is given by Eq. (3.8).

Equation (4.25) predicts that, when the instability is active [$F(\Omega, D, M') > 0$], the inspiral is decelerated, which has also been shown to occur during the resonant excitation of CFS-unstable normal modes by the tide [40]. On the other hand, according to Eq. (4.26), the spin of the (unperturbed) primary is decreasing when the instability occurs ($\tau_{GW} > 0$), in accordance with Ref. [59], where the spin evolution equation is derived for unstable *r* modes.

Solving the equations for $\dot{\Omega}$ and $\dot{D} = \dot{D}^{(0)} + \epsilon \dot{D}^{(1)} + \epsilon^2 \dot{D}^{(2)}$, for the same model used above, we find that the change in the spin of the primary is negligible, as shown in Fig. 2. In the same figure, we also plot the second-order contribution to the number of orbital cycles, $\Delta N_{\text{orb}}^{(2)}$, defined as [60]

$$N_{\rm orb} = \int \frac{\omega_{\rm orb}}{2\pi} \frac{\mathrm{d}D}{\dot{D}} = \int \frac{\omega_{\rm orb}}{2\pi} \frac{\mathrm{d}D}{\dot{D}^{(0)} + \epsilon \dot{D}^{(1)}} + \Delta N_{\rm orb}^{(2)}, \quad (4.30)$$



FIG. 2. Change in the primary's spin Ω , relative to its initial value Ω_{in} (left), and second-order contribution to the number of orbital cycles $\Delta N_{orb}^{(2)}$ (right), plotted against the orbital separation D (normalized to the primary's radius R). The primary is a neutron star described by an n = 1 polytropic equation of state, with $M = 1.4 M_{\odot}$ and R = 10 km, orbited by an equal mass companion (M' = M). The evolution is started at an orbital separation $D_{in} = 100R$ and the angular velocity of the primary is set to $\Omega_{in} = 0.3\Omega_K$, where Ω_K is the Kepler limit (for spherical stars). The binary merger is taken to occur at 3R.

with $N_{\rm orb}$ being the total number of orbits at second order. We see that the correction is positive, as expected from the discussion above, and accumulates very close to merger, as is the correction for the spin. However, this too is unimportant, at least for the parameters and the model considered here.

V. SUMMARY AND DISCUSSION

We have shown that the equilibrium tide, namely, the instantaneous hydrostatic response of a star to the tidal field of its companion, is unstable to the emission of gravitational radiation if the spin of the star exceeds the orbital angular velocity of the companion [Eqs. (3.4) and (3.5)]. When this condition is fulfilled, the tidal perturbation, which is always prograde in the inertial frame, becomes retrograde in the frame rotating with the star. Then, the emission of GWs from the tidal bulge tends to increase the energy of the tidal perturbation on a secular timescale. This mechanism shares the same principles with the classic Chandrasekhar-Friedman-Schutz instability for normal modes in rotating stars.

The instability growth time was calculated for a neutron star with $M = 1.4 M_{\odot}$ and R = 10 km, described by a polytropic equation of state with a polytropic index n = 1 [Eq. (3.8)]. For this model, the eigenfunctions of the equilibrium tide can be derived analytically. As seen in Fig. 1, the instability is active in a very large part of the parameter space and the growth time varies by many orders of magnitude throughout the inspiral, depending mainly on the orbital separation and less on the spin of the star. Even though it can become as low as a few seconds very close to coalesence, the instability growth is always slower than the inspiral—at least for the chosen model.

Finally, the implications of the instability for orbital and spin evolution are explored, making use of some basic energy arguments. The corrections to the inspiral rate due to the tidal deformation and the emission of GWs from the tide are found [Eqs. (4.12) and (4.25)], along with the change in the stellar spin [Eq. (4.26)]. It is demonstrated that, when the instability is active, the emission of GWs from the tide slows down the inspiral, which has also been shown to be a consequence of the resonant excitation of CFS-unstable normal modes by the tide [40]. Meanwhile, the angular velocity of the star decreases, evolving in a similar fashion as when under the influence of the classic CFS instability of normal modes [59]. In Fig. 2 it is shown that, for the same model used above, the effects of the instability on orbital and spin evolution start becoming relevant-but still negligible-only very close to merger.

It should be noted that the rotation rates required for the instability to develop are unlikely to occur during the last stages of the binary evolution. However, near coalesence, the inspiral rate becomes too fast (plunge phase) for the quasicircular orbit approximation to be accurate. Moreover, at this stage, the equilibrium tide approximation may also not be valid. If the tidal frequency is larger than the frequency of convective motions in the star (Brunt-Väisälä frequency⁸), then the star responds effectively like a barotrope, in which case the equilibrium tide approximation fails [49,61,62].

Furthermore, an important element which, for simplicity, has been neglected here is viscosity. Even though it makes the orbital evolution more dynamical, by introducing a lag between the orbital motion of the companion and the primary's response, it has been shown not to significantly affect the orbital and spin evolution [1,2]. Nevertheless, it is expected to supress the instability and shrink the parameter space where it is active, as in the case of CFS-unstable modes [46].

From the above, it seems that the instability is purely of conceptual interest. Even so, there are some cases which might be worth considering in the future, like neutron stars described by stiffer equations of state, corresponding to larger deformabilities [3], or systems in which the neutron star has a much more massive companion.

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APPENDIX: EQUILIBRIUM TIDE IN AN n = 1 POLYTROPE

The primary is described by a polytropic equation of state with polytropic index n = 1, namely, $p = K\rho^2$, where K is the polytropic constant. For a star with mass M and radius R, the Lane-Emden equations (e.g., see Ref. [53]) give

$$K = \frac{2GR^2}{\pi},\tag{A1}$$

$$\rho_c = \frac{\pi M}{4R^3},\tag{A2}$$

$$\rho = \rho_c \frac{\sin(\alpha r)}{\alpha r},\tag{A3}$$

$$g = \frac{4\pi G\rho_c}{\alpha^3 r^2} [\sin(\alpha r) - \alpha r \cos(\alpha r)], \qquad (A4)$$

where $\alpha = \pi/R$.

Replacing in Eq. (2.26) and combining with Eq. (2.4) we get

$$\frac{\mathrm{d}}{\mathrm{d}r} \left[r^2 \frac{\mathrm{d}(\delta \Phi + U)}{\mathrm{d}r} \right] + \left[(\alpha r)^2 - l(l+1) \right] (\delta \Phi + U) = 0 \quad (A5)$$

(the tidal potential U and the perturbations include only their radial dependence), the solutions to which are the

⁸The Brunt-Väisälä frequency N is given by $N^2 = -gA$, where g is the local gravitational acceleration and A is the Schwarzschild discriminant [Eq. (2.10)].

spherical Bessel functions $j_l(\alpha r)$ and $y_l(\alpha r)$ (e.g., Ref. [63]). Retaining the solution that is regular at the origin and matching at the surface with the external solution for $\delta \Phi$, we obtain

$$\delta \Phi = \begin{cases} \left[\frac{2l+1}{\pi j_{l-1}(\pi)} j_l(\alpha r) - \left(\frac{r}{R}\right)^l \right] U(R), & r \le R, \\ \frac{j_{l+1}(\pi)}{j_{l-1}(\pi)} \left(\frac{R}{r}\right)^{l+1} U(R), & r > R, \end{cases}$$
(A6)

with j_l given by

$$j_l(z) = z^l \left(-\frac{1}{z} \frac{\mathrm{d}}{\mathrm{d}z} \right)^l \frac{\sin z}{z}.$$
 (A7)

The equations above, together with Eq. (2.24) for the tidal potential, can now be used to obtain the eigenfunctions of the equilibrium tide, as presented in Sec. II C.

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