# Numerical accuracy of mean-field calculations in coordinate space 

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#### Abstract

Background: Mean-field methods based on an energy density functional (EDF) are powerful tools used to describe many properties of nuclei in the entirety of the nuclear chart. The accuracy required of energies for nuclear physics and astrophysics applications is of the order of 500 keV and much effort is undertaken to build EDFs that meet this requirement. Purpose: Mean-field calculations have to be accurate enough to preserve the accuracy of the EDF. We study this numerical accuracy in detail for a specific numerical choice of representation for mean-field equations that can accommodate any kind of symmetry breaking. Method: The method that we use is a particular implementation of three-dimensional mesh calculations. Its numerical accuracy is governed by three main factors: the size of the box in which the nucleus is confined, the way numerical derivatives are calculated, and the distance between the points on the mesh. Results: We examine the dependence of the results on these three factors for spherical doubly magic nuclei, neutron-rich ${ }^{34} \mathrm{Ne}$, the fission barrier of ${ }^{240} \mathrm{Pu}$, and isotopic chains around $Z=50$. Conclusions: Mesh calculations offer the user extensive control over the numerical accuracy of the solution scheme. When appropriate choices for the numerical scheme are made the achievable accuracy is well below the model uncertainties of mean-field methods.


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## I. INTRODUCTION

The self-consistent mean-field approach, based on an energy density functional (EDF), is a tool of choice to study nuclei in any region of the nuclear chart [1]. It allows one to calculate the properties of the ground state but also of alternative configurations, like shape isomers, or to follow the behavior of a nucleus along rotational bands or along fission paths. Often, one is directly interested not in the total binding energy of a specific nucleus but in its evolution along a series of isotopes or isotones, which can signal structural changes for given neutron or proton numbers.

Motivated by the needs of the nuclear physics and astrophysics communities, major efforts are under way to push the predictive power of nuclear mass models well below the $500-\mathrm{keV}$ level. To reach this goal, the protocols used to adjust the EDF parameters have been revisited. In particular, methods are being developed [2-4] to quantify the statistical uncertainty of these parameters. However, besides the errors in observables due to these uncertainties, there is also a numerical error due to the way the self-consistent mean-field equations are solved. One needs to verify that the numerics does not introduce errors that are larger than the maximum error tolerated for mass models. More importantly, these errors should not vary too rapidly from one nucleus to another, to avoid spurious behavior of mass differences.

[^0]The numerical methods used to solve mean-field equations can be classified according to the way the single-particle wave functions are represented: by coordinate-space techniques or by a basis expansion. Coordinate-space techniques represent the single-particle wave functions in a discretized, finite volume. Several discretization techniques exist, utilizing finite-difference (FD) formulas [5], Fourier transformations [6], B splines [7], wavelets [8,9], and the Lagrange-mesh (LM) method [10-12].

The second family of numerical representations involves expanding single-particle wave functions in some chosen (finite) set of basis states. Usually these basis states are harmonic oscillator ( HO ) eigenstates, although the details often vary.

While the origin of numerical errors is quite different for the two families of representations, the type of EDF does not seem to influence the accuracy of the methods very much. The three main families (relativistic EDFs, zero-range Skyrme EDFs, and finite-range EDFs) require similar numbers of basis states to achieve a similar precision (see, e.g., [13-17]). In what follows, we limit ourselves to the study of zero-range Skyrme EDFs.

It is the aim of this paper to study the numerical accuracy of a specific implementation of coordinate-space techniques: representation on a three-dimensional (3D) Cartesian mesh of equidistant points. We focus on two specific techniquesFD formulas and the LM method-which are the ones implemented in our codes. As far as we can infer from the tests published in the literature, the accuracy obtained with the other techniques mentioned above is similar to that obtained
within our LM scheme. Most of the information relative to the tools that we have developed has been presented for the particular implementation made in the Ev8 code [18,19]. More involved implementations have also been used, which differ from Ev8 only in that they impose fewer symmetries on the nucleus. The presence of these symmetries in general allows for a reduction of the dimension of the problem; e.g., in Ev8 it allows for the reduction of the space by a factor of $1 / 8$.

The article is organized as follows: First, we define precisely the quantities that are used to characterize the accuracy of mean-field calculations. Next, we review the basic ingredients needed to define wave functions on a Cartesian mesh and to calculate derivatives and integrals in this representation. We then discuss the main sources of numerical errors: the size of the box in which the nucleus is confined and the step size of the mesh. We discuss the numerical accuracy that can be achieved by comparing energies and radii of doubly magic nuclei with those obtained with a spherical code. Finally, we check the convergence of energies, radii, and multipole moments of deformed nuclei by comparing results obtained with decreasing mesh discretization lengths.

## II. DEFINITION OF USEFUL QUANTITIES

A mean-field configuration is characterized by its energy, its root-mean-square (rms) radius, and multipole moments. In this section we define these quantities, whose dependence on the mesh parameters is studied.

## A. Total energy

For a time-reversal-invariant system as assumed here, the total (tot) energy is composed of the kinetic (kin) energy, the Skyrme energy describing the strong interaction in the particlehole channel, the pairing (pair) energy, the Coulomb (Coul) energy, and a center-of-mass (c.m.) correction [19]:

$$
\begin{equation*}
E_{\text {tot }}=E_{\text {kin }}+E_{\text {Skyrme }}+E_{\text {pair }}+E_{\text {Coul }}+E_{\text {c.m. }} \tag{1}
\end{equation*}
$$

For the parametrizations used throughout this article, the Skyrme EDF takes the form of the sum of various bilinear combinations of the isoscalar $(t=0)$ and isovector $(t=1)$ local densities $\rho_{t}(\mathbf{r})$, kinetic densities $\tau_{t}(\mathbf{r})$, and spin-current densities $J_{t, \mu \nu}(\mathbf{r})$, where $\mu, \nu=x, y, z$,

$$
\begin{align*}
E_{\mathrm{Skyrme}}= & E_{\rho^{2}}+E_{\rho^{2+\alpha}}+E_{\rho \tau}+E_{\rho \Delta \rho}+E_{\rho \nabla J}+E_{J J} \\
= & \sum_{t=0,1} \int d^{3} r\left(C_{t}^{\rho}\left[\rho_{0}\right] \rho_{t}^{2}+C_{t}^{\rho^{\alpha}} \rho_{0}^{\alpha} \rho_{t}^{2}+C_{t}^{\tau} \rho_{t} \tau_{t}\right. \\
& \left.+C_{t}^{\Delta \rho} \rho_{t} \Delta \rho_{t}+C_{t}^{\nabla \cdot J} \rho_{t} \nabla \cdot \mathbf{J}_{t}-C_{t}^{T} \sum_{\mu, v} J_{t, \mu \nu} J_{t, \mu \nu}\right), \tag{2}
\end{align*}
$$

with coupling constants as defined in Ref. [19]. The kinetic energy just depends on the kinetic density

$$
\begin{equation*}
E_{\mathrm{kin}}=\sum_{q=n, p} \int d^{3} r \frac{\hbar^{2}}{2 m_{q}} \tau_{q}(\mathbf{r}) \tag{3}
\end{equation*}
$$

of protons and neutrons. While the Skyrme and kinetic energies are local functionals of the densities, the direct Coulomb energy is a nonlocal functional of the proton density $\rho_{p}(\mathbf{r})$ :

$$
\begin{equation*}
E_{\mathrm{Coul}}^{d}=\frac{e^{2}}{2} \iint d^{3} r d^{3} r^{\prime} \frac{\rho_{p}(\mathbf{r}) \rho_{p}\left(\mathbf{r}^{\prime}\right)}{\left|\mathbf{r}-\mathbf{r}^{\prime}\right|} \tag{4}
\end{equation*}
$$

Compared to the other terms contributing to the total energy, (1), the exact calculation of the Coulomb exchange energy is orders of magnitude more costly, as it is a functional of the complete nonlocal one-body density matrix. As a consequence, the local Slater approximation, whose numerical cost is similar to that of the Skyrme energy, (2), is used instead:

$$
\begin{equation*}
E_{\text {Coul }}^{e}=-\frac{3 e^{2}}{4}\left(\frac{3}{\pi}\right)^{1 / 3} \int d^{3} r \rho_{p}^{4 / 3}(\mathbf{r}) \tag{5}
\end{equation*}
$$

The pairing energy contribution to the energy is

$$
\begin{equation*}
E_{\mathrm{pair}}=\sum_{k, m>0} f_{k} u_{k} v_{k} f_{m} u_{m} v_{m} \bar{v}_{k \bar{k} m \bar{m}}^{\text {pair }}, \tag{6}
\end{equation*}
$$

where the $\bar{v}_{k \bar{k} m \bar{m}}$ are antisymmetrized matrix elements of the pairing interaction and the $f_{i}$ are cutoff factors, both of which are specified in Appendix B.

The expression for the cm correction, which is not relevant for our discussion, can be found in Ref. [19].

## B. Dimensionless multipole moments

As in [19], the dimensionless multipole moments $\beta_{\ell m}$ are related to the matrix elements of the multipole operators $\hat{Q}_{\ell m} \equiv r^{\ell} Y_{\ell m}(\mathbf{r})$ by

$$
\begin{equation*}
\beta_{\ell m}=\frac{4 \pi}{3 R_{0}^{\ell} A}\left\langle\hat{Q}_{\ell m}\right\rangle \tag{7}
\end{equation*}
$$

where $R_{0}=1.2 A^{1 / 3} \mathrm{fm}$. When $m$ is omitted we imply it to be 0 .

## C. Radii

Another set of observables, related to the density profile of the nucleus, is the mean-square ( ms ) radii, rms radii, and isotopic shifts. The ms radius of the proton ( $q=\mathrm{p}$ ), neutron ( $q=\mathrm{n}$ ), and total density distribution is defined as

$$
\begin{align*}
& r_{q}^{2}=\frac{1}{N_{q}} \int d^{3} r \rho_{q}(\mathbf{r}) r^{2}  \tag{8}\\
& r_{t}^{2}=\frac{1}{A} \int d^{3} r\left[\rho_{n}(\mathbf{r})+\rho_{p}(\mathbf{r})\right] r^{2} \tag{9}
\end{align*}
$$

The rms radii are then the square root of the corresponding ms radius.

Similarly, we present results for the isotope shift of charge radii, which are calculated as the difference between the proton ms radius of an isotope with $N$ neutrons and that of a reference isotope with $N_{0}$ neutrons,

$$
\begin{equation*}
\delta r^{2}(N, Z)=r_{p}^{2}(N, Z)-r_{p}^{2}\left(N_{0}, Z\right) \tag{10}
\end{equation*}
$$

without any corrections.

## III. COORDINATE-SPACE REPRESENTATION

Assuming a 3D Cartesian mesh, a function $\Phi(\mathbf{r})=$ $\Phi(x, y, z)$ is represented by the tensor $\Phi_{p q s}$ of its values at the collocation points $\left(x_{p}, y_{q}, z_{s}\right)$ :

$$
\begin{equation*}
\Phi(\mathbf{r})=\left\{\Phi\left(x_{p}, y_{q}, z_{s}\right)\right\}=\left\{\Phi_{p q s}\right\} \tag{11}
\end{equation*}
$$

A mesh can be defined in several ways, depending on the choice of the collocation points. For example, the origin of the coordinate system and the boundaries of the box can be included as collocation points or not. Different choices can also be made for the boundary conditions at the edge of the box.

To set up self-consistent mean-field equations, one has to vary the EDF with respect to $\Phi_{p q s}$. This requires defining the prescriptions to calculate derivatives and integrals from the values of $\Phi_{p q s}$ on the mesh. Several choices for derivatives have been explored over the years.

## A. Derivatives on a mesh

The most straightforward possibility for setting up a coordinate-space representation of self-consistent mean-field equations is provided by the FD method, a widely used tool for solving partial differential equations [20]. In this scheme, the derivatives are calculated with $n$-point FD formulas, and the integrals are obtained by summing up the integrand at the mesh points multiplied by a suitable volume element.

There are three factors that determine the accuracy that can be achieved with the FD method. First is the overall resolution scale provided by the mesh spacing; decreasing the distance between mesh points improves the accuracy. Second, the higher the order of the FD formulas used for a given mesh spacing, the better the accuracy. In both cases, however, a higher accuracy means also an increase in the numerical cost. Third, there are internal inconsistencies introduced by the method itself. For example, taking twice the numerical first-order derivatives of a given function is not equivalent to applying the numerical second-order derivatives. Also, the numerical derivatives are not the inverse of the numerical integrations. Only for very small step sizes, well below 0.1 fm , do these internal inconsistencies become irrelevant. While such small step sizes can be easily handled in spherical 1D codes [21], the required storage is prohibitive in axial 2D and Cartesian 3D codes. In addition, such step sizes are much smaller than what can be expected to be the physically relevant resolution scale; see, for example, the arguments brought forward in Ref. [22].

Several other schemes have been developed in the past with a better consistency between derivation and integration. For instance, derivatives have been defined through a Fourier transformation to momentum space [6,23,24], which is equivalent to the assumption that the functions on the mesh can be developed into a set of plane waves. In this method, the derivatives are quasiexact for a given resolution of the mesh, and first- and second-order derivatives are internally consistent. Similar ideas have been developed in quantum chemistry under the label discrete variable representation
(DVR) [25-27]. A similar formalism that provides an internal consistent scheme for derivatives and integrals is the LM method, which we sketch in the following section.

## B. Lagrange-mesh representation

The idea underlying the LM method is that for each Gauss quadrature one can construct a set of basis functions for which orthogonality and completeness relations are exactly fulfilled when evaluated with the given quadrature [10,28,29]. This additional condition makes the LM method a special case of the slightly less rigorous concept of DVR [26,29].

LMs have been constructed for a multitude of different geometries and used for a wide range of applications (see [29] and references therein). We use here the case of an equidistant 3D Cartesian mesh. Its three directions are separable in the formalism, such that presentation of the principles of the method for one dimension is sufficient.

The underlying basis of a 1D Cartesian equidistant LM is constructed as the set of functions $\varphi_{k}(x)$, whose orthogonality relations are exact when evaluated by a simple $2 N$-point rectangular quadrature rule, sometimes called the midpoint rule [10],

$$
\begin{equation*}
\int_{a}^{b} d x \varphi_{k}^{*}(x) \varphi_{k^{\prime}}(x) \rightarrow d x \sum_{r} \varphi_{k}^{*}\left(x_{r}\right) \varphi_{k^{\prime}}\left(x_{r}\right)=\delta_{k k^{\prime}} \tag{12}
\end{equation*}
$$

where $d x$ is the distance between the collocation points located at

$$
\begin{equation*}
x_{r}=r d x= \pm d x / 2, \pm 3 d x / 2, \ldots, \pm(N-1) d x / 2 \tag{13}
\end{equation*}
$$

and where $a$ and $b$ are the boundaries of the numerical box $[a, b]=[-N d x,+N d x]$. A convenient representation of the $2 N$ basis functions $\varphi_{k}(x)$ are plane waves of the form

$$
\begin{equation*}
\varphi_{k}(x)=\frac{1}{\sqrt{L}} \exp \left(\frac{2 \pi i}{L} k x\right) \tag{14}
\end{equation*}
$$

where $L=2 N d x$ is the length of the numerical box and where $k= \pm \frac{1}{2}, \pm \frac{3}{2}, \ldots, \pm\left(N-\frac{1}{2}\right)$. The real part of the $\varphi_{k}(x)$ is symmetric and has nodes on the boundaries of the box and a maximum at the origin, whereas their imaginary part is skewsymmetric and, consequently, has a node at the origin and maxima on the boundaries of the box. This also implies that $\varphi_{k}^{*}(x)=\varphi_{-k}(x)$.

The $\varphi_{k}\left(x_{r}\right)$ form a complete set of functions to describe any function on the mesh points

$$
\begin{equation*}
d x \sum_{k} \varphi_{k}^{*}\left(x_{r}\right) \varphi_{k}\left(x_{s}\right)=\delta_{r s} \tag{15}
\end{equation*}
$$

Note that the box size $L$ is not a multiple of the wavelength of the basis functions. Instead, twice the box size is an odd multiple of the wavelengths, which take the values $2 L=$ $2 L / 1,2 L / 3,2 L / 5, \ldots, 2 L /(2 N-1)$. Both the real and the imaginary parts of all plane waves in Eq. (14) are nonzero at all mesh points.

As recalled in Ref. [22], in Cartesian DVR and LM coordinate-space methods, where the derivatives are defined
through an expansion in plane waves, the analysis of a calculation's infrared and ultraviolet cutoffs introduced by the basis is straightforward. This has to be contrasted with the much more involved analyses required when working with an HO basis [30-32]. It is also argued in Ref. [22] that a DVR or LM representation of the nuclear many-body problem covers the relevant part of the phase space with a much smaller number of basis states than required by an HO basis. In practice, however, HO bases typically used for self-consistent mean-field calculations are much smaller than the typical number of mesh points used in the same kind of calculation. For a box with 20 points in every direction the number of linearly independent states is 64000 , compared with an HO expansion with 20 shells, which contains 14168 states.

While the basis functions $\varphi_{k}(x)$ in Eq. (14) are useful to discuss the mathematical properties of the LM method, the actual coordinate representation then employs the set of $2 N$

Lagrange interpolation functions $f_{i}(x)$ obtained as $[10,28,29]$

$$
\begin{equation*}
f_{r}(x) \equiv d x \sum_{k} \varphi_{k}^{*}\left(x_{r}\right) \varphi_{k}(x)=\frac{1}{2 N} \frac{\sin \left[\frac{\pi}{d x}(x-r d x)\right]}{\sin \left[\frac{\pi}{d x} \frac{x-r d x}{2 N}\right]} . \tag{16}
\end{equation*}
$$

By construction, the Lagrange interpolation functions have the property of being equal to 1 at the mesh point, $x_{r}=r d x$, and 0 at all others, $f_{r}\left(x_{s}\right)=\delta_{r s}[10,28,29]$. When developed into Lagrange functions, any function $\phi(x)$ on the mesh,

$$
\begin{equation*}
\phi(x)=\sum_{r} \phi\left(x_{r}\right) f_{r}(x)=\sum_{r} \phi_{r} f_{r}(x) \tag{17}
\end{equation*}
$$

is then simply represented by its values $\phi_{r} \equiv \phi\left(x_{r}\right)$ at $2 N$ mesh points.

The Lagrange functions are smooth and infinitely derivable. They can be used to define matrices representing the first and second derivatives of functions discretized through ${ }^{1}$ Eq. (17):

$$
\begin{align*}
&\left.D_{j i}^{(1)} \equiv \frac{d f(x)}{d x}\right|_{x=x_{j}}= \begin{cases}(-1)^{i-j} \frac{\pi}{(2 N) d x} \frac{1}{\sin (\pi(i-j) /(2 N))} & \text { for } \quad i \neq j, \\
0 & \text { for } \quad i=j ;\end{cases}  \tag{18}\\
&\left.D_{j i}^{(2)} \equiv \frac{d^{2} f_{i}(x)}{d x^{2}}\right|_{x=x_{j}}= \begin{cases}(-1)^{i-j+1} 2\left(\frac{\pi}{(2 N) d x}\right)^{2} \frac{\cos [\pi(i-j) /(2 N)]}{\sin ^{2}[\pi(i-j) /(2 N)]} & \text { for } i \neq j, \\
-\frac{\pi^{2}}{3 d x^{2}}\left(1-\frac{1}{(2 N)^{2}}\right) & \text { for } i=j .\end{cases} \tag{19}
\end{align*}
$$

The first derivative of any function $\phi(x)$ on the mesh is obtained by multiplying the $2 N \times 2 N$ matrix $D_{r s}^{(1)}$ by the vector $\phi_{r}$,

$$
\begin{equation*}
\phi_{r}^{\prime}=\phi^{\prime}\left(x_{r}\right)=\sum_{s} D_{r s}^{(1)} \phi_{s}, \tag{20}
\end{equation*}
$$

and similarly for the second derivatives. Note that the derivative matrices have the property $D^{(2)}=D^{(1)} D^{(1)}$ by construction [29], which is not the case for FD formulas. As the derivatives of Eqs. (18) and (19) correspond to full $2 N \times 2 N$ matrices, their application is more time-consuming than that of FD derivatives, which correspond to a sparse band matrix.

The full Cartesian 3D representation of a function $\Phi(\mathbf{r})$ is then provided by

$$
\begin{equation*}
\Phi(\mathbf{r})=\sum_{p q s} \Phi_{p q s} f_{p}(x) f_{q}(y) f_{s}(z) \tag{21}
\end{equation*}
$$

where the number of discretization points does not have to be the same in each direction. In this case, the derivative matrices in Eqs. (18) and (19) have to be set up separately for each direction.

As pointed out in Refs. [26] and [33], a variational calculation using DVR or LM derivatives delivers very precise

[^1]values for the total energy in spite of the individual matrix elements' being much less accurate. In what follows, we illustrate that this property implies very accurate total energies, while separate terms of the Skyrme EDF are less well represented. In addition, we show that using an LM results in a variational calculation.

## IV. NUMERICAL CONSIDERATIONS

## A. Numerical parameters of parameterizations

Unless explicitly stated, we have used the SLy4 parametrization. To explore the dependence of the numerical accuracy on the EDF, we have, in addition, tested a representative set of Skyrme parametrizations, as listed in Appendix A.

In the next two sections, we present calculations for the doubly magic spherical nuclei ${ }^{40} \mathrm{Ca},{ }^{132} \mathrm{Sn}$, and ${ }^{208} \mathrm{~Pb}$; the neutron-rich nucleus ${ }^{34} \mathrm{Ne} ; \mathrm{Cd}, \mathrm{Sn}$, and Te isotope chains; and the fission path of ${ }^{240} \mathrm{Pu}$. It is noteworthy that we only include pairing for the isotopic chains and for ${ }^{240} \mathrm{Pu}$ (see Appendix B for details). In all other cases, pairing has been neglected. In Appendix C we comment on the precise physical constants used during our calculations.

## B. Measuring accuracy

The accuracy of a coordinate-space calculation is limited by the size of the box, the discretization length $d x$, and the way derivatives and integrals are calculated. In order to properly judge these effects we employ two ways of analyzing results.


FIG. 1. (Color online) Comparison between the errors in the total energy of ${ }^{208} \mathrm{~Pb}$ obtained in calculations using different combinations of formulas for the derivatives (see text). Differences are taken with respect to the total energy obtained with LENTEUR [21].

For spherical nuclei we can compare our 3D results with a 1D spherical code that also represents the single-particle wave functions in coordinate space. Because of spherical symmetry, we can use extremely fine discretizations and the results can thus be considered exact to a very high precision. For this purpose we use LENTEUR [21] as a reference.

For deformed nuclei, we no longer have access to such a comparison. Here we have to resort to looking at 3D results as a function of both box size and mesh spacing: we compare results in small boxes with a large mesh spacing to results in very large boxes with a very fine mesh spacing.

## C. Use of derivatives and the variational principle

The numerical cost of using LM derivatives is much higher than that of the FD alternative. To control the computational time, three options have been considered: they differ in the way derivatives are calculated during the mean-field iterations and after convergence. The first option (FD + FD) has been used in the first applications of the codes [5], where derivatives were exclusively calculated by FD. The second one (FD + LM) has been the most used for more than 20 years: FD derivatives are used during the iterations but the energies are recalculated after convergence by LM formulas. Finally, in the last option $(\mathrm{LM}+\mathrm{LM})$, the LM formulas are used during the iterations and after convergence.

In practice, we use a seven-point difference formula for the first-order and a nine-point formula for the second-order derivatives when employing FD formulas. It is shown in Ref. [34] that this provides an efficient compromise in terms of overall speed and precision.

Figure 1 illustrates the accuracy of the total energy obtained using these three options. The LM + LM choice is by far the most accurate. As reported in Table II, the result obtained with a mesh size of 1.0 fm differs by only 25 keV from the LENTEUR result. The FD + LM option is less accurate but already sufficient for most applications, with an error of around 100 keV for $d x=0.8 \mathrm{fm}$. It is better by nearly an order of magnitude than the FD + FD choice. Results presented in the
following were obtained with the FD + LM option, unless otherwise stated.

Both the $\mathrm{FD}+\mathrm{LM}$ and the $\mathrm{LM}+\mathrm{LM}$ calculations underestimate the binding energy, as it should be for a variational calculation. This is due to the fact that the singleparticle wave functions are expanded on a complete and closed basis for a given box size and mesh discretization length [see Eq. (14)]. Increasing the box size and/or decreasing the mesh discretization length enlarges the accessible subspace of the Hilbert space [29] and leads to a monotonous convergence of the energy. In contrast, such a basis cannot be defined for the FD + FD option, for which the calculation systematically overestimates the binding energy of ${ }^{208} \mathrm{~Pb}$.

The same applies to mesh calculations with Fourier derivatives, as can be deduced from the convergence analyses in Refs. [6] and [23]. While for a given $d x$ the overall accuracy of the binding energy found there is very similar to that we find for LM + LM calculations, the energy does not converge monotonically with decreasing $d x$.

While the use of LM derivatives after having used FD ones during the iterations $(\mathrm{FD}+\mathrm{LM})$ is sufficient to obtain an upper bound of the total energy since any wave function discretized on a mesh can be expanded on the LM basis, the errors in the various individual terms of the Skyrme EDF can be very large, as reported in Table I. While the total energy varies by slightly less than 1 MeV when $d x$ is decreased from 1.0 to 0.549 fm , the variation in the kinetic energy is of the order of 40 MeV , counterbalanced by a similar change in the Skyrme energy. The situation for the LM + LM scheme is reported in Table II. It indicates a similar effect, but on a much smaller scale: the total energy varies by 20 keV , while the kinetic energy varies by roughly 150 keV .

When performing symmetry restoration and configuration mixing by the generator coordinate method, a high level of accuracy is required to avoid buildup numerical noise while solving the Hill-Wheeler-Griffin equation. This calls for the use of LM derivatives in these calculations, as done since our first applications [35].


FIG. 2. (Color online) Energy difference between a reference calculation performed with 23 points and calculations performed with $N$ points for the three nuclei ${ }^{40} \mathrm{Ca},{ }^{132} \mathrm{Sn}$, and ${ }^{208} \mathrm{~Pb}$. In all cases, the step size is equal to 1.0 fm .

TABLE I. Decomposition of the total energy between the terms of the Skyrme parametrization SLy4 for ${ }^{208} \mathrm{~Pb}$, using the FD + LM option. All energies are in MeV. See Sec. II A fore definitions of terms. Values obtained with the spherical 1D code LENTEUR are given for comparison.

|  |  | Energy $(\mathrm{MeV})$ |  |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
|  | $d x=1.0 \mathrm{fm}$ | $d x=0.83 \mathrm{fm}$ | $d x=0.71 \mathrm{fm}$ | $d x=0.549 \mathrm{fm}$ | LENTEUR |
|  | 3908.548 | 3880.647 | 3872.035 | 3867.506 | 3866.190 |
| Kinetic + c.m. correction | 831.801 | 829.241 | 828.433 | 828.004 | 827.876 |
| Direct Coulomb | -31.415 | -31.319 | -31.289 | -31.273 | -31.269 |
| Coulomb exchange | -22749.578 | -22510.048 | -22435.391 | -22395.941 | -22384.379 |
| $E_{\rho^{2}}$ | 1368.924 | 1343.506 | 1335.611 | 1331.436 | 1330.206 |
| $E_{\rho \tau}$ | 14812.851 | 14631.848 | 14575.413 | 14545.584 | 14536.832 |
| $E_{\rho^{2+\alpha}}$ | 323.771 | 318.147 | 316.431 | 315.539 | 315.287 |
| $E_{\rho \Delta \rho}$ | -99.730 | -97.595 | -96.917 | -96.554 | -96.445 |
| $E_{\rho \nabla J}$ | -6343.762 | -6314.142 | -6304.854 | -6299.937 | -6298.501 |
| Total Skyrme energy | -1634.828 | -1635.574 | -1635.675 | -1635.700 | -1635.703 |
| Total energy |  |  |  |  |  |

## D. Determining box sizes and mesh spacings

The first requirement for a coordinate-space calculation is that the box in which the nucleus is confined is large enough to avoid any spurious effect due to the truncation of the wave functions. The influence of the box size on the total energy for three spherical nuclei is represented in Fig. 2. The same mesh size, $d x=1.0 \mathrm{fm}$, is used in all calculations while the number of discretization points is varied, thus changing the volume of the box. The calculation in the largest box, using 23 points, is taken as a reference. The errors decrease quickly when the box size is enlarged. If one requires that the error is smaller than 1 keV , we see that taking boxes with half-sides of 11 fm for ${ }^{40} \mathrm{Ca}, 15 \mathrm{fm}$ for ${ }^{132} \mathrm{Sn}$, and 20 fm for ${ }^{208} \mathrm{~Pb}$ is sufficient. Since the numerical effort required for ${ }^{40} \mathrm{Ca}$ is very low we opted to use the slightly larger half-side of 13 fm in order to further increase our accuracy to about 0.1 keV .

Similar analyses have been performed for all nuclei considered in this paper. Since several nuclei in the isotopic chains around $Z=50$ are deformed, we have performed all calculations with the same box size as ${ }^{208} \mathrm{~Pb}$. This choice allows us to calculate all isotopes with the same numerical conditions. The box dimensions are listed in Table III. The columns $C_{x}, C_{y}$, and $C_{z}$ indicate the size of the box in which the Coulomb problem is solved. For every system, the box
size was varied for fixed $d x$ until the energy did not change by more than 0.1 keV , with the exception of ${ }^{240} \mathrm{Pu}$, for which this limit was 1 keV .

A nonambiguous comparison between calculations performed with different mesh discretizations $d x$ can only be achieved when the volume of the box is conserved. This is realized by determining the value of $d x$ in such a way that the box has the same size for each number of mesh points.

## E. Convergence of the iterative procedure

Decreasing the mesh size improves the accuracy. However, this has a price in computing time. First, keeping the same box size requires increasing the number of discretization points. Second, the time step of the imaginary-time-step method [36,37] implemented in the codes [19] has to be decreased with decreasing mesh size, thus increasing the number of iterations necessary to reach convergence and, by consequence, also the computing time. This considerably slows down the convergence. In Fig. 3 we show the evolution of the error in the total energy relative to LENTEUR during the iterations for the ${ }^{40} \mathrm{Ca}$ nucleus for different mesh discretizations $d x$. The most accurate result after 100 iterations is obtained with $d x=1.0 \mathrm{fm}$. Gaining an order of magnitude of accuracy after

TABLE II. Same as Table I, but for the LM + LM option.

|  |  |  | Energy $(\mathrm{MeV})$ |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
|  | $d x=1.0 \mathrm{fm}$ | $d x=0.83 \mathrm{fm}$ | $d x=0.71 \mathrm{fm}$ | $d x=0.549 \mathrm{fm}$ | LENTEUR |
| Kinetic + c.m. correction | 3866.323 | 3866.165 | 3866.182 | 3866.182 | 3866.190 |
| Direct Coulomb | 827.922 | 827.889 | 827.882 | 827.878 | 827.876 |
| Coulomb exchange | -31.269 | -31.268 | -31.268 | -31.268 | -31.269 |
| $E_{\rho^{2}}$ | -22384.936 | -22384.188 | -22384.322 | -22384.320 | -22384.379 |
| $E_{\rho \tau}$ | 1330.300 | 1330.193 | 1330.201 | 1330.200 | 1330.206 |
| $E_{\rho^{2}+\alpha}$ | 14537.174 | 14536.691 | 14536.789 | 14536.787 | 14536.832 |
| $E_{\rho \Delta \rho}$ | 315.238 | 315.275 | 315.284 | 315.284 | 315.287 |
| $E_{\rho \nabla J}$ | -96.430 | -96.444 | -96.445 | -96.445 | -96.445 |
| Total Skyrme energy | -6298.657 | -6298.473 | -6298.493 | -6298.494 | -6298.501 |
| Total energy | -1635.678 | -1635.687 | -1635.696 | -1635.700 | -1635.703 |

TABLE III. Edge lengths (in fm) of boxes used to solve selfconsistent mean-field equations $\left(L_{\mu}\right)$ and to determine the Coulomb potential $\left(C_{\mu}\right)$ for nuclei studied in this paper. Depending on the symmetries imposed on the nucleus, only half of of the length is treated numerically in most cases.

| Nucleus | $L_{x}=L_{y}$ | $L_{z}$ | $C_{x}=C_{y}$ | $C_{z}$ |
| :--- | :---: | :---: | :---: | :---: |
| ${ }^{40} \mathrm{Ca}$ | 26 | 26 | 26 | 26 |
| ${ }^{132} \mathrm{Sn}$ | 30.8 | 30.8 | 46.8 | 46.8 |
| ${ }^{20} 8 \mathrm{~Pb}$ | 40 | 40 | 60 | 60 |
| $Z \approx 50$ | 40 | 40 | 60 | 60 |
| ${ }^{240} \mathrm{Pu}$ | 40 | 60 | 80 | 120 |

convergence requires carrying out roughly 100 more iterations for the step sizes represented in the figure.

## F. Treatment of the long-range Coulomb interaction

The direct Coulomb energy requires a special treatment because of its long range. One of the spatial integrations in Eq. (4) can be eliminated through the calculation of the Coulomb potential of the protons, which satisfies the electrostatic Poisson equation

$$
\begin{equation*}
\Delta U(\mathbf{r})=-4 \pi e^{2} \rho_{p}(\mathbf{r}) \tag{22}
\end{equation*}
$$

where $e^{2}$ is the square of the elementary charge. When solving this equation, boundary conditions need to be imposed at the edge of the box. These can be easily constructed when recalling that at large distances the potential is entirely determined by the multipoles of the nuclear charge distribution $\left\langle\hat{Q}_{\ell m}\right\rangle$. Expanding the Coulomb potential on spherical harmonics and keeping the terms up to $\ell=2$, the Coulomb potential outside the box is approximated by

$$
\begin{equation*}
U(\mathbf{r})=\frac{e^{2} Z}{r}+e^{2} \frac{\left\langle\hat{Q}_{20}\right\rangle Y_{20}(\mathbf{r})+\left\langle\hat{Q}_{22}\right\rangle \operatorname{Re} Y_{22}(\mathbf{r})}{r^{3}} \tag{23}
\end{equation*}
$$



FIG. 3. (Color online) Error in the total energy using the FD + LM option as a function of the number of mean-field iterations for ${ }^{40} \mathrm{Ca}$ for different values of $d x$. Calculations were initialized with Nilsson-model single-particle wave functions. The box length is 26 fm .


FIG. 4. (Color online) Differences between the total energy of ${ }^{208} \mathrm{~Pb}$ calculated on a 3D mesh with different approximations in the calculation of the Coulomb energy and that obtained with LENTEUR. The three lines correspond to the use of three-, five-, and seven-point FD formulas for calculation of the Laplacian in the Poisson equation.
which provides the boundary condition for the numerical solution of Eq. (22). The direct Coulomb energy is then calculated as

$$
\begin{equation*}
E_{\mathrm{Coul}}^{d}=\frac{1}{2} \int d^{3} r U(\mathbf{r}) \rho_{p}(\mathbf{r}) \tag{24}
\end{equation*}
$$

As for the nuclear part of the energy, the accuracy of the electrostatic potential, obtained by solving Eq. (22), is limited by three factors: the size of the box, the mesh discretization length $d x$, and the way derivatives are calculated.

A suitable box size for the Coulomb problem has to be larger than that for the Skyrme EDF. This is a direct consequence of the long range of the Coulomb force. To make negligible the contributions to the boundary conditions of terms higher than $\ell=2$ [see Eq. (23)], one has to calculate the Coulomb potential in a box larger than the one used for the nuclear part of the interaction. Typical values are listed in Table III. For light nuclei such as ${ }^{40} \mathrm{Ca}$, no extra points for Coulomb need to be added, while the box has to be significantly enlarged for heavier systems in the ${ }^{132} \mathrm{Sn}$ and ${ }^{208} \mathrm{~Pb}$ regions. For calculation of the fission barrier of heavy nuclei such as ${ }^{240} \mathrm{Pu}$ up to very large deformations, the Coulomb box size has to be two times larger than the one needed for the Skyrme EDF to obtain the same nuclear accuracy in all the energies.

The Laplacian in Eq. (22) has to be approximated on the mesh in such a way that the accuracy of the Coulomb energy is similar to that of the other terms in the EDF. We show in Fig. 4 the gain in accuracy of the total energy of ${ }^{208} \mathrm{~Pb}$ obtained by going from a three-point to a seven-point FD formula for the Laplacian. Already a five-point formula provides the required accuracy and is used in all other calculations reported here. One can easily understand that a lower-order FD formula than the one used to calculate the kinetic energy is sufficient for the Laplacian in Eq. (22): the typical length scale of the variation of the Coulomb potential is much larger than the scale on which the wave functions vary.


FIG. 5. (Color online) Differences between the total energy calculated with our 3D code and that calculated with the spherical code LENTEUR for ${ }^{40} \mathrm{Ca}(\mathrm{a}),{ }^{132} \mathrm{Sn}(\mathrm{b})$, and ${ }^{208} \mathrm{~Pb}$ (c), as a function of the mesh distance $d x$. Results are plotted for a representative set of Skyrme parametrizations, without pairing. Results for SLy5, T22, and T65 are not shown but are indistinguishable from the SLy4 results at the scale of this graph.

The final factor for the accuracy of the Coulomb solution is the mesh discretization length $d x$. As the effect of the Coulomb term is already incorporated in all of the applications, we do not discuss it separately.

## V. DISCUSSION

## A. Binding energies

Provided that the box size is large enough, the main factor determining the accuracy of our implementation of mesh calculations is the discretization length. In Fig. 5 the energy difference with respect to LENTEUR results is plotted for three doubly magic spherical nuclei, as a function of the mesh discretization $d x$ for a representative set of Skyrme parametrizations. It is remarkable that the interactions are grouped according to their effective mass (see Appendix A for the actual values): interactions with a larger effective mass $m^{*}$ give systematically more accurate results than interactions with a smaller mass. This property is related to the term $E_{\rho \tau}$ term of the Skyrme EDF in Eq. (2), which, in our experience, is the least well represented on a mesh. Since the magnitude of this term increases when the effective mass decreases, the accuracy obtained for a given mesh size deteriorates for a lower effective mass.

One can see that the accuracy obtained with a mesh discretization as large as $d x=1.0 \mathrm{fm}$ is less than 1.0 MeV for ${ }^{208} \mathrm{~Pb}$. The energy difference decreases to a few hundred keV for $d x=0.8 \mathrm{fm}$ and to a few keV for $d x=0.6 \mathrm{fm}$. Note that a similar accuracy for $d x=0.6 \mathrm{fm}$ was found for a 2 D code based on splines [8]. To obtain an agreement between the spherical code LENTEUR and our 3D codes below the $1-\mathrm{keV}$ level would require increasing the box size but also making the codes more similar. For a nucleus with a binding energy higher than 1 GeV , this implies a relative discrepancy of better than $10^{-7}$ and there are several sources of differences in the codes that can play a role, none of which is easy to control.

## B. Deformation energy curves

Let us now study the convergence properties of our numerical scheme for the fission path of ${ }^{240} \mathrm{Pu}$. Our motivation
is twofold: ${ }^{240} \mathrm{Pu}$ is a frequent benchmark for models that describe fission [39-44] but also for numerical algorithms [8,13]. The energy curve of this nucleus presents two minima at prolate deformations, the ground state and a fission isomer. In Fig. 6, we show the variation of the energy with deformation.

The box used for these calculations has the same size for all discretizations, as indicated in Table III. When the left-right symmetry is broken, the number of points along the $z$ direction is doubled. We have performed calculations with four mesh discretizations, $d x=1.0,0.82,0.69$ and 0.60 fm , and tested the convergence as a function of $d x$ by taking the difference with respect to the results obtained with $d x=0.6 \mathrm{fm}$. For each value of $d x$, the energy at each deformation is the energy relative to the prolate ground state.

The energy curve obtained with $d x=0.6 \mathrm{fm}$ is shown in Fig. 6. The topography obtained for other values of $d x$ is the same. Shapes are triaxial in the vicinity of the first barrier, whereas everywhere else they remain axial. At deformations


FIG. 6. (Color online) Energy curve for ${ }^{240} \mathrm{Pu}$ calculated with $d x=0.6 \mathrm{fm}$. Regions where the deformation is axial [(blue) crosses], triaxial [small (green) filled circles], or axial and reflection asymmetric [large (red) filled circles] are indicated.


FIG. 7. (Color online) Energy differences between the results obtained for ${ }^{240} \mathrm{Pu}$ with $d x=1.0,0.82$, and 0.69 fm and those corresponding to $d x=0.6 \mathrm{fm}$.
smaller than the one of the fission isomer the configurations are reflection symmetric, whereas at larger deformations they are increasingly asymmetric.

We use this curve as a reference to determine the accuracy of the calculations carried out for other values of $d x$. For each $d x$, the ground-state energy is taken as the 0 of the energy. The results are shown in Fig. 7. The properties of the minimum are listed in Table IV. The error decreases roughly by an order of magnitude upon going from $d x=1.0$ to $d x=0.82 \mathrm{fm}$ and from $d x=0.82$ to $d x=0.69 \mathrm{fm}$. At $d x=1.0 \mathrm{fm}$ the error is of the order of a few hundred keV , with a rather large oscillation. For a mesh discretization of 0.82 fm , the error becomes lower than 100 keV (except in the vicinity of the spherical configuration, where it reaches 150 keV , but this configuration is very excited) and is quite acceptable for the calculation of energy curves. Decreasing the discretization further, to 0.69 fm , reduces the error to values of a few tens of keV at most.

Some published results allow for a comparison between the accuracy of mesh calculations and that of calculations using


FIG. 8. (Color online) Absolute difference in neutron rms radius for different Skyrme parametrizations for ${ }^{34} \mathrm{Ne}$ at $d x=0.8 \mathrm{fm}$. The reference calculation was performed in a box with $N=20$.
an expansion on an HO basis. Pei et al. [8] have performed calculations on an axial mesh using B splines and on HO bases, either spherical or deformed, with 20 oscillator shells in both cases. The accuracy obtained in [8] on a mesh of $d x=0.65 \mathrm{fm}$ seems very similar to the one we obtain. The use of a spherical HO basis is rather unreliable, with an error larger than 1 MeV already for the excitation energy of the fission isomer and that quickly increases to several MeV at larger deformations. For an axial oscillator basis, the results are similar to those we obtain with a mesh size of 0.82 fm up to the first barrier but the accuracy deteriorates rapidly for larger deformations, being several hundred keV at the deformation corresponding to the fission isomer. Similar results can be found in [46] for ${ }^{194} \mathrm{Hg}$ and in [47] for ${ }^{256} \mathrm{Fm}$.

As a number of shells significantly larger than 20 is numerically prohibitive, either one has to resort to a two-center oscillator basis or one has to construct a suitable subspace within a much larger one-center HO basis by carefully selecting the low-lying single-particle states. The former option is developed in Ref. [48], whereas the latter has been used during the construction of the unedf1 parametrization [49], where the lowest 1771 basis states of a basis of 50 HO shells have been kept. The accuracy obtained in this way for the excitation energy of the fission isomer is of the order of 100 keV . As a comparison, the experimental excitation energies of the fission isomer found in the literature are $2.4 \pm 0.3 \mathrm{MeV}$ [50], approximately 2.8 MeV [51], and $2.25 \pm 0.20 \mathrm{MeV}$ [52]. In the light of these error bars, a numerical accuracy of 100 keV is sufficient for the adjustment of an EDF. However, from the published results of Pei et al. [8], it can be estimated that the numerical error in the fission barrier height is a few times these 100 keV . Similar results have been obtained in the case of the relativistic mean-field method $[13,53]$.

## C. Radial density distribution

The rms radius is intimately linked to the radial density distribution of a nucleus. One can expect that it is particularly sensitive to the box size for nuclei with a large excess of neutrons. Tests have been performed for the very neutron-


FIG. 9. (Color online) Radial density profile of ${ }^{34} \mathrm{Ne}$ in different box sizes with $d x=0.8 \mathrm{fm}$.


FIG. 10. (Color online) Absolute difference between the total rms radii calculated on a 3D mesh with respect to those of LENTEUR as a function of the step size $d x$ for the spherical nuclei ${ }^{40} \mathrm{Ca}(\mathrm{a}),{ }^{132} \mathrm{Sn}(\mathrm{b})$, and ${ }^{208} \mathrm{~Pb}$ (c) and those calculated with the Skyrme parametrizations as indicated.
rich nucleus ${ }^{34} \mathrm{Ne}$ by varying the box size for a fixed mesh discretization $d x=0.8 \mathrm{fm}$. To avoid any ambiguity in the calculation, pairing has been omitted. The results are presented in Fig. 8, where we show the difference in total rms radius as a function of the box size for a representative set of EDF parametrizations. For the size of the box recommended for ${ }^{40} \mathrm{Ca}$ in Table III, the number of points is 16 for a mesh size of 0.8 fm . It leads to an error of the order of $10^{-2} \mathrm{fm}$ for most interactions, the results being slightly less accurate for SV-min. For smaller boxes, the accuracy of radii is lower and depends on the interaction.

In Fig. 9 the radial profile of the total density of ${ }^{34} \mathrm{Ne}$ is plotted as a function of the box size. The distortion of the density in the smallest box is large and demonstrates that half the box size must be larger than 8.0 fm . In all other boxes, the exponential tail of the density distribution is well described, up to the point before the last one. For a box size of around 12 fm , the density is well described up to a decrease in the central density by six orders of magnitude.

The confinement in a volume is less evident in an expansion on a basis than in a mesh calculation, but it is also present. While oscillator basis functions extend to infinity, they are in practice strongly localized by their Gaussian form factor. If one takes its classical turning point as a measure of the extension of an HO state, one obtains, for ${ }^{208} \mathrm{~Pb}$ and 20 oscillator shells, a value for the turning point that varies from 14 fm for $\ell=0$ to 16 fm for $\ell=20 \hbar$. To increase the value of this turning point to 20 fm would require using 28 oscillator shells for $\ell=0$. This effect of confinement by an oscillator basis has been reported in Ref. [54] for the case of ${ }^{112} \mathrm{Zr}$.

For comparison, the experimental uncertainty in rms charge radii for the Ne isotopes (up to $A=28$ ) varies from 0.002 fm close to stability to 0.02 fm for exotic isotopes [55]. It is interesting to note that the numerical accuracy of a mesh meanfield calculation has a similar level (provided the box is large enough) but that the model already introduces uncertainties in the rms radii that are at least one order of magnitude larger [2].

In Fig. 10, we compare the total rms radii calculated with decreasing mesh sizes to those obtained with LENTEUR for three spherical nuclei: ${ }^{40} \mathrm{Ca},{ }^{132} \mathrm{Sn}$, and ${ }^{208} \mathrm{~Pb}$. The agreement is
already very satisfactory for the large mesh size of 1.0 fm , with one order of magnitude gained in accuracy upon decreasing the mesh size to 0.8 fm , which is the usual value of production calculations. An interesting feature that cannot be deduced from Fig. 10 is that all of the parametrizations, with the exception of unedf0, always produce an rms radius that is smaller than the LENTEUR result.

In Fig. 11, we present the isotopic shifts $\delta r^{2}(N, Z)$ for a range of even-even Sn nuclei, the reference being ${ }^{132} \mathrm{Sn}$. All curves almost exactly coincide. This demonstrates that the isotopic shifts are quite reliable even with coarse meshes. Similar results are obtained for $\mathrm{Cd}, \mathrm{Xe}$, and Te isotopes.

## D. Two-neutron separation energies

To put into evidence changes in nuclear structure with nucleon number, one often uses mass filters that are computed by taking specific differences between the binding energies of neighboring nuclei. The simplest filter is the two-nucleon separation energy, which is defined as the energy difference between two isotopes (or isotones) whose nucleon numbers differ by 2 . In Fig. 12, we show the evolution of the


FIG. 11. (Color online) Isotopic shifts $\delta r^{2}(N, Z)$ with respect to ${ }^{132} \mathrm{Sn}$ for different Sn isotopes and different mesh sizes.


FIG. 12. (Color online) Absolute differences of two-neutron separation energies between four mesh discretizations and a calculation with a mesh size of $d x=0.63 \mathrm{fm}$ for Cd (a), Sn (b), and Te (c) isotopes. (d) Plot of the two-neutron separation energies of all of these isotope chains as a reference.


FIG. 13. (Color online) Mass $\beta_{2}$ quadrupole moment as a function of neutron number for a series of Te isotopes.
two-neutron separation energies, $S_{2 n}$, of even-even nuclei for three neighboring isotopic chains when the mesh size $d x$ is decreased. For each discretization $d x$ we have plotted the difference in the $S_{2 n}$ values from the one obtained at $d x=0.63 \mathrm{fm}$. Even with a mesh size as large as $d x=1.0 \mathrm{fm}$, the accuracy of the $S_{2 n}$ is already better than 100 keV , which is small enough for most applications. The mesh size used in most of our published applications, $d x=0.8 \mathrm{fm}$, leads to an accuracy better than 10 keV . In Fig. 12(d), the two-neutron separation energies of the three isotope chains are plotted for four values of $d x$. The curves cannot be distinguished using a scale adapted to the variation of $S_{2 n}$ as a function of the neutron number. This result is in strong contrast with respect to some published calculations using an expansion on an oscillator basis [56], where special algorithms have to be devised to smooth numerical irregularities, which can be of the order of a few hundred keV.

## E. Multipole moments

The dimensionless ground-state quadrupole moments $\beta_{2}$ of even-even Te isotopes are shown in Fig. 13. Differences


FIG. 14. (Color online) Mass octupole moment $\beta_{3}$ along the fission path for ${ }^{240} \mathrm{Pu}$.

TABLE IV. Properties of the ground state of ${ }^{240} \mathrm{Pu}$ as obtained from nonconstrained calculations.

| $d x(\mathrm{fm})$ | $E(\mathrm{MeV})$ | $\beta_{2}$ | $\beta_{4}$ | $\beta_{6}$ | $\beta_{8}$ | $\beta_{10}$ |
| :--- | :---: | :---: | :---: | :---: | ---: | ---: |
| 1.0 | -1801.909 | 0.288 | 0.160 | 0.043 | -0.002 | -0.003 |
| 0.849 | -1802.770 | 0.289 | 0.163 | 0.045 | 0.001 | 0.001 |
| 0.739 | -1802.929 | 0.292 | 0.164 | 0.046 | 0.002 | 0.002 |
| 0.653 | -1802.969 | 0.290 | 0.165 | 0.046 | 0.002 | 0.001 |

between the curves corresponding to different values of $d x$ are tiny and not significant. Similar results were obtained for the Cd and Sn isotopes.

We now examine how the multipole moments of ${ }^{240} \mathrm{Pu}$ along the fission path are affected by the mesh size. In Figs. 14 and 15 we show the octupole and hexadecapole moments, respectively, in the region of the fission path where parity is broken. Similar results obtained for the axial and triaxial cases are not shown. In Tables IV and V we list the multipole moments of the ground state and fission isomer of ${ }^{240} \mathrm{Pu}$ for the different mesh discretizations as obtained by unconstrained calculations.

From Figs. 14 and 15 we see that the overall sequence of shapes along the fission path is robust with respect to the mesh spacing. The fission path is already precisely defined at the coarsest mesh $(d x=1.0 \mathrm{fm})$ we used. A single exception can be seen at the onset of octupole deformation; in the vicinity of this point, however, the energy surface is very flat in the $\beta_{3}$ direction.

On a smaller scale, the multipole moments do vary as a function of the mesh discretization. This is clearly shown in Tables IV and V. Since our method hinges on the variation of the total energy in Eq. (1), there is no guarantee that the values of the multipole moments converge in a predictable way. It is, however, reassuring to see that the typical variation of these moments is of the order of a few percent to, at most, about $10 \%$. The larger variations present themselves in the higher-order $\beta_{6}, \beta_{8}$, and $\beta_{10}$ moments. These are more difficult to resolve on coarse meshes because of the high number of nodes their associated Legendre polynomials have.


FIG. 15. (Color online) Mass hexadecapole moment $\beta_{4}$ for the parity-breaking configurations along part of the fission path for ${ }^{240} \mathrm{Pu}$.

TABLE V. Properties of the superdeformed fission isomer obtained from nonconstrained calculations.

| $d x(\mathrm{fm})$ | $E(\mathrm{MeV})$ | $\beta_{2}$ | $\beta_{4}$ | $\beta_{6}$ | $\beta_{8}$ | $\beta_{10}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 1.0 | -1796.929 | 0.832 | 0.494 | 0.344 | 0.279 | 0.255 |
| 0.849 | -1797.950 | 0.840 | 0.510 | 0.367 | 0.303 | 0.278 |
| 0.739 | -1798.099 | 0.847 | 0.528 | 0.388 | 0.319 | 0.268 |
| 0.653 | -1798.123 | 0.841 | 0.516 | 0.375 | 0.312 | 0.259 |

## F. Single-particle levels

In Fig. 16 we show the evolution of the neutron singleparticle levels within 1.5 MeV of the Fermi energy in the ground state of ${ }^{240} \mathrm{Pu}$ as a function of the mesh spacing $d x$. While slight shifts in the position of the levels are observed as a function of the mesh size, the largest error at $d x=1.0$ fm is of the order of 100 keV . One can also note that the level ordering within the parity subspaces is the same for all values of $d x$. A similar dependence on box parameters is found for the proton states and the lighter nuclei studied here.

## VI. CONCLUSION

The aim of this paper was to study the numerical accuracy of the solution of self-consistent mean-field equations using a discretization on a 3D Cartesian coordinate-space mesh. Three elements permit control of its numerical accuracy. The first one is the method used to calculate derivatives. Using LM derivatives leads to much more accurate results than using FD formulas for derivatives. In addition, a Cartesian LM corresponds to a representation in a closed subspace of the Hilbert space, such that it always provides an upper bound to the binding energy that becomes tighter when adding points outside a given box or when decreasing the distance of mesh points in a given box. Neither is the case for FD derivatives. However, we have shown quantitatively that the accuracy of a calculation that uses FD formulas during the iterations


FIG. 16. (Color online) Eigenvalues of the single-particle Hamiltonian for the ground state of ${ }^{240} \mathrm{Pu}$ as a function of the mesh discretization $d x$. Only neutron single-particle levels within 1.5 MeV of the Fermi energy are shown.
can be significantly improved upon by recalculating the EDF at convergence with LM derivatives. Again, this procedure provides us with an upper bound of the energy, thus restoring the variational character of the calculation. Using Lagrange derivatives during the iterations allows us to improve the accuracy in energies further, but at the cost of at least doubling the computing time.

The second element on which mesh calculations depend is the size of the box in which the nucleus is confined. The examples of doubly magic nuclei and neutron-rich ${ }^{34} \mathrm{Ne}$ illustrate that results for energies and densities are already stable at small box sizes.

The third element is that the quality of the results depends on the mesh size, with errors in energies that are almost independent of the number of neutrons and protons and of the shape of the nucleus. A mesh size $d x=0.8 \mathrm{fm}$ guarantees an accuracy that is, in general, better than 100 keV , which corresponds to a relative accuracy of less than $0.1 \%$, even for lighter nuclei. Decreasing the mesh size to 0.7 fm permits one to gain nearly an order of magnitude and to reach an accuracy that is well below all the uncertainties of the mean-field model.

One can summarize these results by concluding that a mesh technique as implemented in our codes is flexible (it can accommodate any kind of symmetry breaking), is robust (the accuracy can be controlled by an adequate choice of the three elements mentioned above), and can be very accurate if necessary. The positive aspect of our numerical scheme is that using a mesh size of 0.8 fm , as used in most of our past applications, ensures an accuracy of better than 100 keV in energies and reliable shape properties for nuclei of any mass.

Our study has focused on the solution of mean-field equations and we have not touched on the description of pairing correlations. There has already been a study of this problem by Terasaki et al. [57]. It should be revisited to take into account new developments. However, the problem is not related exclusively to the way the mean-field equations are solved. The description of single-particle states well above the Fermi energy is probably very different when using a discretization on a mesh or an expansion on an oscillator basis.

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## APPENDIX A: PARAMETRIZATIONS USED

We make some remarks here on the interactions used throughout the text.

TABLE VI. Value of the isoscalar effective mass in units of the nucleon mass $m^{*} / m$ of the interactions used throughout this paper.

| Parametrization | Ref. No. | $m^{*} / m$ |
| :--- | :---: | :--- |
| SLy4 \& SLy5 | $[58]$ | 0.68 |
| T22 \& T65 | $[59]$ | 0.7 |
| SkI3 | $[60]$ | 0.577 |
| SV-min | $[61]$ | 0.95 |
| unedf0 | $[62]$ | 0.9 |

(i) SLy4 and SLy5 [58]: These parametrizations were used as intended.
(ii) T22 and T65 [59]: These parametrizations were used as intended.
(iii) unedf0 [62]: While this parametrization was adjusted with a nonzero pairing interaction, we used it without any pairing.
(iv) SV-min [61]: This parametrization was adjusted with unequal nucleon masses $m_{n} \neq m_{p}$. LENTEUR does not handle this option, so we used instead the average value $\frac{m_{n}+m_{p}}{2}$ as the nucleon mass.
(v) SkI3 [60]: This parameteriation was adjusted with the inclusion of a perturbative two-body c.m. correction, an option not included in LENTEUR.

The values of their isoscalar effective masses are listed in Table VI.

## APPENDIX B: PAIRING INTERACTION

The density-dependent pairing interaction we used for the isotope chains and the fission path of ${ }^{240} \mathrm{Pu}$ is defined by [45]

$$
\begin{equation*}
\hat{v}^{\text {pair }}\left(\mathbf{r}, \mathbf{r}^{\prime}\right)=-\frac{V_{0}}{2}\left(1-\hat{P}_{\sigma}\right)\left[1-\alpha \frac{\rho_{0}(\mathbf{R})}{\rho_{s}}\right] \delta\left(\mathbf{r}-\mathbf{r}^{\prime}\right) \tag{B1}
\end{equation*}
$$

where $\rho_{0}(\boldsymbol{R})$ is the isoscalar density at $\mathbf{R}=\frac{1}{2}\left(\mathbf{r}+\mathbf{r}^{\prime}\right)$. The parameters take the values $\alpha=1, \rho_{s}=0.16 \mathrm{fm}^{-3}$, and $V_{0}=$ $1250 \mathrm{MeV} \mathrm{fm}^{-3}$. In addition, this interaction was supplemented by two cutoffs, one above and the other below the Fermi energy, in order to eliminate the basis-size dependence of the total energy. They are defined by two Fermi functions,

$$
\begin{equation*}
f_{k}=\left[1+e^{\left(\epsilon_{k}-\lambda q-\Delta \epsilon_{q}\right) / \mu_{q}}\right]^{-1 / 2}\left[1+e^{\left(\epsilon_{k}-\lambda_{q}+\Delta \epsilon_{q}\right) / \mu_{q}}\right]^{-1 / 2} \tag{B2}
\end{equation*}
$$

where $\lambda_{q}$ is the Fermi energy, $\epsilon_{k}$ is the single-particle energy of the single-particle state $k$, and we chose $\mu_{q}=0.5 \mathrm{MeV}$ and $\Delta \epsilon_{q}=5.0 \mathrm{MeV}$ for protons and neutrons.

## APPENDIX C: ROLE OF THE PHYSICAL CONSTANT WHEN USING SKYRME EDFS

By default, the physical constants used in our calculations are the following [38]:

$$
\begin{align*}
e^{2} & =1.43996446 \mathrm{MeV} \mathrm{fm}  \tag{C1}\\
m=\frac{m_{n}+m_{p}}{2} & =938.9187125 \mathrm{MeV} \mathrm{c}^{-2}  \tag{C2}\\
\hbar^{2} /(2 m) & =20.735519104 \mathrm{MeV} \mathrm{fm}^{2} \tag{C3}
\end{align*}
$$



FIG. 17. (Color online) Energy difference for the spherical nuclei ${ }^{40} \mathrm{Ca},{ }^{132} \mathrm{Sn}$, and ${ }^{208} \mathrm{~Pb}$ for calculations with LENTEUR using SLy4 with a modified value of $\hbar^{2} /(2 m)$. The reference calculation is that obtained using the value used during the adjustment of SLy4.

Whenever possible, we have used the value of $\hbar^{2} /(2 m)$ that was used during the adjustment of the parametrization. It might seem superfluous to completely specify the physical constant used, but the results of our calculations depend on the precise values of these constants. In particular, the level of agreement between Ev8 and LENTEUR described in Sec. V A is only attainable when these codes use exactly the same numerical values for the physical constants.

In fact, significant errors can be introduced when the values of the physical constants are changed slightly. The seemingly innocuous value of $\hbar^{2} /(2 m)$ in fact plays a very important role. Figure 17 shows LENTEUR calculations for the spherical nuclei ${ }^{40} \mathrm{Ca},{ }^{132} \mathrm{Sn}$, and ${ }^{208} \mathrm{~Pb}$ with SLy4. Every point was calculated by slightly changing the value of $\hbar^{2} /(2 m)$ from $20.73553 \mathrm{MeV} \mathrm{fm}^{2}$, the SLy4 value. We see that using a value for $\hbar^{2} /(2 m)$ that is not consistent with the value used during the fit of the EDF can lead to an error of several MeV in the total energy. $\hbar^{2} /(2 m)$ is, after all, the proportionality constant of the kinetic energy in Eq. (1). Typical values that have been used over the years vary at least between 20.73 and $20.7363 \mathrm{MeV} \mathrm{fm}^{2}$. If the exact values of the physical constants used during the adjustment of a given parametrization are not available, then one cannot reliably compare the results with experimental data. In this case, one cannot judge the predictive power of this parametrization.


FIG. 18. Difference in the total energy obtained with LENTEUR for ${ }^{40} \mathrm{Ca}$ using a rounded value for the density dependence parameter $\alpha$ in Eq. (2) vs using the full double-precision value $\alpha=1 / 6$ of the SLy4 parametrization.

Similar concerns arise for the parameters of the Skyrme interactions. The energy obtained in our calculations is more sensitive to some Skyrme parameters than to others, but the close agreement observed in Sec. V A is not obtainable without carefully checking that the Skyrme parameters are completely consistent across codes. That this is not trivial can be concluded from examination of Fig. 18. There we plot the relative difference in energy found by LENTEUR between modified versions of the SLy4 functional and the correct SLy4. The interaction parameters are the same for every point, save for the density dependence parameter $\alpha$ in Eq. (2). There are very few parametrizations for which the value of $\alpha$ corresponds to a terminating decimal, for example, SV-min, for which $\alpha=0.255368$. For the large majority of parametrizations the value of $\alpha$ is either $1 / 3$ or, as in the case of SLy $4,1 / 6$. Both of these correspond to a repeating decimal number, whose numerical representation might differ from code to code. Using $\alpha=0.1667$ in a calculation with SLy4 corresponds to a rounding error of $\alpha-1 / 6 \simeq 3.33 \times 10^{-5}$, which introduces an error in the total binding energy of ${ }^{40} \mathrm{Ca}$ of a few tens of keV .

It is clearly shown that a limited representation of $\alpha$ implies a roundoff error that has a visible effect on the energy. This kind of error shows up when comparing LENTEUR and Ev8 results, and for this reason we conclude that relative errors of less than $10^{-5}$ become meaningless. Similar analyses can be made for the other interaction parameters, including the values of physical constants used to fit the interaction.
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[^1]:    ${ }^{1}$ Unfortunately, the corrections of these expressions as given in the corrigendum to Ref. [19] still contain a typographical error: the formula for the second derivative has a superfluous factor of 2 when $i \neq j$.

