# Pion-induced double-charge exchange reactions in the $\Delta$ resonance region

O. Buss,<sup>\*</sup> L. Alvarez-Ruso, A. B. Larionov,<sup>†</sup> and U. Mosel Institut für Theoretische Physik, Universität Giessen, Germany (Received 12 July 2006; published 20 October 2006)

We have applied the Giessen BUU (GiBUU) transport model to the description of the double-charge exchange (DCX) reaction of pions with different nuclear targets at incident kinetic energies of 120–180 MeV. The DCX process is highly sensitive to details of the interactions of pions with the nuclear medium and, therefore, represents a major benchmark for any model of pion scattering off nuclei at low and intermediate energies. The impact of surface effects, such as the neutron skins of heavy nuclei, is investigated. The dependence of the total cross section on the nuclear mass number is also discussed. We achieve a good quantitative agreement with the extensive data set obtained at LAMPF. Furthermore, we compare the solutions of the transport equations obtained in the test-particle ansatz using two different schemes: the full and the parallel ensemble methods.

DOI: 10.1103/PhysRevC.74.044610

PACS number(s): 25.80.Gn, 25.80.Hp, 25.80.Ls

# I. INTRODUCTION AND MOTIVATION

Over the past two decades, the Giessen Boltzmann-Uehling-Uhlenbeck (GiBUU) transport model has been developed to describe heavy-ion collisions and photon-, electron-, pion-, and neutrino-induced reactions within one unified transport framework. A realistic treatment of pion interactions with the nuclear medium is crucial for the interpretation of experiments where pions are produced inside nuclei. Recently, it has been shown using GiBUU [1-3] that pion rescattering in the final-state description of photon-induced double-pion production produces a considerable modification of the  $\pi\pi$ invariant-mass distributions observed by the TAPS Collaboration [4]. Moreover, neutrino-induced pion production, a source of background for neutrino oscillation experiments [5], is very sensitive to pion final-state interactions [6,7]. The propagation of low-energy pions in nuclear matter in the GiBUU framework has already been extensively discussed in Ref. [3] and compared to quantum mechanical calculations.

In this context, pionic double-charge exchange (DCX) is a very interesting reaction. The fact that DCX requires at least two nucleons to take place makes it a very sensitive benchmark for pion rescattering and absorption. This reaction has received considerable attention in the past (see. e.g., Ref. [8] and references therein). The mechanism of two sequential single-charge exchanges has traditionally been able to explain the main features of this reaction [9,10] at low energies, although the contribution of the  $A(\pi, \pi\pi)X$  reaction becomes progressively important as the energy increases [11,12]. At higher ( $\sim$ 1 GeV) energies, the sequential mechanism becomes insufficient to account for the reaction cross section [13,14]. Extensive experimental studies performed at LAMPF obtained high-precision data for doubly differential cross sections on <sup>3</sup>He [15] and heavier nuclei ( $^{16}O$ ,  $^{40}$  Ca, and  $^{208}$ Pb) [16] in the region of  $E_{\rm kin} = 120-270$  MeV.

Hüfner and Thies [17] explored for the first time the applicability of the Boltzmann equation in  $\pi N$  collisions and achieved qualitative agreement with data on singleand double-charge exchange. Their method of solving the Boltzmann equation was based upon an expansion of the pion one-body distribution function in the number of collisions. There, in contrast to our work, the Boltzmann equation is not solved with a test-particle ansatz but by reformulating it into a set of coupled differential equations, which can then be solved in an iterative manner. However, this approach was based on simplifying assumptions of averaged cross sections and averaged potentials. The work by Vicente et al. [11] was based upon the cascade model described in [18]. There, a microscopic model for  $\pi N$  scattering was used as input for the pion reaction rates in the simulation. In that work [11], pion DCX off <sup>16</sup>O and <sup>40</sup>Ca has been explored and fair quantitative agreement with data has been achieved.

In our work, we explore DCX on heavier nuclei, comparing our results with the data measured by Wood et al. [16]. We also address the scaling of the total cross section discussed by Gram et al. [19]. To focus only on single-pion rescattering, we consider incoming pion energies below  $E_{kin} = 180$  MeV; above that energy  $2\pi$  production becomes prominent and the DCX no longer necessarily takes place in a two-step process. Because of the small mean free path of the incoming pions, the process is mostly sensitive to the surface of the nucleus. Therefore, we will discuss and compare two widely used numerical schemes for the solution of the Boltzmann equation: the *parallel ensemble method* employed in the BUU models [20–23] and in the Vlasov-Uehling-Uhlenbeck model [24] and the *full ensemble method* used in the Landau-Vlasov [25], Boltzmann-Nordheim-Vlasov [26,27], and relativistic BUU [28,29] models. Both schemes are based on the test-particle representation of the single-particle phase-space density, but they differ in the locality of the scattering processes (c.f. discussion in [30,31]). In the parallel ensemble method, all test particles are subdivided into groups, or parallel ensembles. The number of test particles in each parallel ensemble is equal to the number of physical particles in the system. Collisions are allowed only between test particles from the same parallel ensemble, and the mean field is averaged over all

<sup>\*</sup>Electronic address: oliver.buss@theo.physik.uni-giessen.de; URL: http://theorie.physik.uni-giessen.de/~oliver

<sup>&</sup>lt;sup>†</sup>On leave from RRC "I.V. Kurchatov Institute", 123182 Moscow, Russia.

parallel ensembles. Without the mean field, then, the parallel ensemble method is equivalent to the intranuclear-cascade simulation [32]. In the *full ensemble method*, collisions between all test particles are allowed. The low-energy ( $E_{lab} = 10$ -50 MeV/nucleon) heavy-ion collisions are better described by the full ensemble method, since this method provides convergence to the exact solution of the original kinetic equation in the limit of large  $N \equiv number of test particles per$ nucleon). However, in codes oriented to particle production in high-energy heavy-ion and hadron-nucleus collisions, the parallel ensemble method is commonly used, since it is simpler and numerically less expensive (see the discussion in Sec. III C). The advantage of the parallel ensemble method is that each parallel ensemble can be considered as a physical event, but this method does not converge to the solution of the kinetic equation in the limit of large N.

This article is structured in the following way. First, we introduce our GiBUU [33] transport model, emphasizing the most relevant issues. Next, we discuss the solution of the Boltzmann equation by using both the full ensemble and the parallel ensemble schemes and check their consistency. Finally, we present our results on DCX in comparison to the data.

# **II. THE GIBUU TRANSPORT MODEL**

Boltzmann-Uehling-Uhlenbeck (BUU) transport models are based on the Boltzmann equation, which was modified by Nordheim, Uehling, and Uhlenbeck to incorporate quantum statistics. A brief description of the formalism is given in the following. For a detailed discussion concerning the physical input for pion-induced reactions we refer the reader to [3] and the references therein. A more general description of the whole GiBUU model will be given in a forthcoming paper [34].

#### A. The BUU equation

The BUU equation actually consists of a series of coupled differential equations, which describe the time evolution of the single-particle phase-space densities  $f_a(\vec{r}, \vec{p}, t)$ . The index  $a = \pi, \omega, N, \Delta, \ldots$  denotes the different particle species in our model. A large number of mesonic and baryonic states is actually included, but at the energies of interest for this study, the relevant ones are  $\pi, N$ , and the  $\Delta(1232)$  resonance.

For a particle of species X, its time evolution is given by

$$\frac{df_X(\vec{r}, \vec{p}, t)}{dt} = \frac{\partial f_X(\vec{r}, \vec{p}, t)}{\partial t} + \frac{\partial H_X}{\partial \vec{p}} \frac{\partial f_X(\vec{r}, \vec{p}, t)}{\partial \vec{r}} - \frac{\partial H_X}{\partial \vec{r}} \frac{\partial f_X(\vec{r}, \vec{p}, t)}{\partial \vec{p}} = I_{\text{coll}}(f_X, f_a, f_b, \dots, )$$
(2.1)

with the one-body Hamilton function

$$H_X(\vec{r}, \vec{p}) = \sqrt{(\vec{p} + \vec{A}_X(\vec{r}, \vec{p}))^2 + m_X^2 + U_X(\vec{r}, \vec{p}) + A_X^0(\vec{r}, \vec{p})}.$$

The scalar potential  $U_X$  and the vector potential  $A_X^{\mu}$  of species X may in principle depend upon the phase-space densities

of all other species. Hence, the differential equations are already coupled through the mean fields. In the limit of  $I_{coll} = 0$ , Eq. (2.1) becomes the well-known Vlasov equation. The collision term  $I_{coll}$  on the right-hand side of Eq. (2.1) incorporates explicitly all scattering processes among the particles. The reaction probabilities used in this collision term are chosen to match the elementary collisions among the particles in vacuum. Within the BUU framework the  $\pi N$  reaction cross section is given by an incoherent sum of resonance contributions and a direct (i.e., pointlike) contribution. Interference effects are therefore neglected.

## **B.** Elementary processes

DCX emerges from the interplay of two elementary mechanisms: pion-nucleon quasi-elastic scattering, with or without charge exchange, and pion absorption inside the nucleus. In our model, the cross section for quasi-elastic scattering is given by an incoherent sum of background  $\sigma^{BG}$  and resonance contributions:

$$\sigma_{\pi N \to \pi N} = \sigma_{\pi N \to R \to \pi N} + \sigma_{\pi N \to \pi N}^{\text{BG}}.$$

The resonance cross sections are obtained from the partial wave analysis of Ref. [35]. The background cross sections denoted by  $\sigma^{BG}$  are chosen in such a manner that the elementary cross-section data in vacuum are reproduced. Background contributions are instantaneous in space-time, whereas the resonances propagate along their classical trajectories until they decay or interact with one or two nucleons in the medium.

As an improvement in the earlier treatment [3,36,37], we now included a more realistic angular distribution for the elastic scattering of the pions. Owing to the *P*-wave nature of the  $\Delta(1232)$  resonance, we assume for  $\pi N \rightarrow \Delta \rightarrow \pi N$ in the resonance rest frame a distribution of the pion scattering angle  $\theta$  according to

$$f^{\Delta}(s,\theta) = [1+3\cos^2(\theta)]g(s,\theta),$$

which is peaked in forward and backward scattering angles. The function  $g(s, \theta)$ , depending on Mandelstam *s*, parametrizes the energy dependence of the  $\pi N$  angular distribution. In a coherent calculation the angular distribution is generated by interference effects, which cannot be accomplished by our transport model. In our ansatz we need to split the cross section in an incoherent way to preserve our semiclassical resonance picture. Therefore we take

$$g(s,\theta) = [\alpha - \cos(\theta)]^{\beta(m_{\Delta} - \sqrt{s})/m_{\Delta}}$$

with the  $\Delta$  pole mass  $m_{\Delta} = 1.232$  GeV. For the background events we assume

$$f^{\mathrm{BG}}(s,\theta) = g(s,\theta).$$

The constants  $\alpha = 1.9$  and  $\beta = 26.5$  are fitted to the angular distributions measured by Crystal Ball [38]; a comparison of our parametrization to these data is shown in Fig. 1.

Concerning pion absorption, the most important mechanisms are a two-step process in which  $\pi N \rightarrow \Delta$  is followed by  $\Delta N \rightarrow NN$  or  $\Delta NN \rightarrow NNN$  and a one-step background process  $\pi NN \rightarrow NN$ .

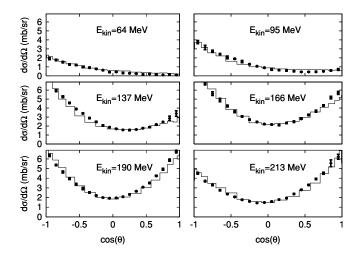


FIG. 1. The angular distributions for the charge exchange process  $\pi^- p \rightarrow \pi^0 n$  in the CM frame of the pion and proton. The plots are labeled by the kinetic energies of the pions in the laboratory frame. The data are taken from Ref. [38].

### C. Medium effects

As medium modifications, we include Pauli blocking and Fermi motion of the nucleons and Coulomb forces and we account as well for the collisional broadening in the  $\Delta$  resonance width. The hadronic potentials included are introduced as timelike components of vector potentials in the local rest frame [39]. For our purposes the most important mean-field potentials are those acting on the nucleon and the  $\Delta$  resonance. The nucleon mean-field potential was parametrized by Welke *et al.* [40] as a sum of a Skyrme term depending only on density and a momentum-dependent contribution (for explicit details and parameters see [39]). Phenomenology tells us that the  $\Delta$  potential has a depth of about -30 MeV at  $\rho_0$  [41,42]. Comparing to a momentumindependent nucleon potential, which is approximately -50 MeV deep, we therefore take the  $\Delta$  potential to be

$$A^{0}_{\Delta}(\vec{p},\vec{r}) = \frac{2}{3}A^{0}_{\text{nucleon}}(\vec{p},\vec{r}).$$

Here we assume the same momentum dependence for the nucleon and the  $\Delta$  potentials. In [3] we discussed the influence of the real part of the pion self-energy on absorption processes in nuclei. Since DCX is mostly sensitive to the surface (see the discussion in Sec. IV), the influence of this real part has turned out to be negligible owing to the low effective density and has not been included in the calculations presented here. For more details see Ref. [3] and the references therein.

### D. Nuclear densities

The nucleons are initialized in a local density approximation. For  ${}^{16}_{80}$ ,  ${}^{40}_{20}$ Ca, and  ${}^{208}_{82}$ Pb we have implemented density profiles  $\rho(r)$  according to the parametrizations collected in Ref. [43], which are of Woods-Saxon type for heavier nuclei (Ca and Pb) and of harmonic-oscillator type for lighter ones (O). The proton densities are based on the compilation of Ref. [44] from electron scattering. The neutron densities are provided by Hartree-Fock calculations. For  ${}^{103}_{-6}$ Rh, we use a

TABLE I. Parameters of the Woods-Saxon parametrizations for  $^{103}_{\rm 45}{\rm Rh}.$ 

$\overline{ ho_p^0}  [\mathrm{fm}^{-3}]$	$\rho_n^0  [{\rm fm}^{-3}]$	$R_p$ [fm]	$R_n$ [fm]	$a_p$ [fm]	<i>a</i> <sub><i>n</i></sub> [fm]
0.0708	0.0835	5.194	5.358	0.4743	0.4780

Woods-Saxon density distribution

$$\rho_n(r) = \frac{\rho_n^0}{1 + \exp[(r - R_n)/a_n]},$$

$$\rho_p(r) = \frac{\rho_p^0}{1 + \exp[(r - R_p)/a_p]},$$
(2.2)

with the parameters given in Table I [45]. The larger neutron radii of heavy nuclei play a relevant role in DCX, as we show in Sec. IV.

## **III. SOLUTION OF THE BOLTZMANN EQUATION**

The fact that the DCX reaction depends considerably on the spatial distributions of protons and neutrons implies that it is also sensitive to the degree of locality of the scattering processes. In the nondiscretized version of the BUU equation, the interactions are strictly local in space-time. By utilizing the test-particle ansatz to solve the problem numerically, this is no longer the case. Therefore, we elaborate in this section on this degree of locality of the scattering processes in our simulation. As a first step, we point out the connection of the underlying BUU equation to the actual numerical implementation. This will lead us to a proper definition of a typical volume in which particles are allowed to interact. Hereafter, we will introduce an approximation to the full solution: the parallel ensemble scheme. In this scheme, computation time is radically decreased by reducing the locality. It is widely employed to solve the BUU equation in particle physics (e.g., Refs. [20-23,36]) since otherwise computations would not be feasible. In Sec. IV, we will discuss a possible problem related with using this scheme and evaluate its applicability to the DCX process.

#### A. The collision term

For the sake of simplicity, let us consider a model with only one fermionic particle species that has no degeneracy, allowing only for binary scattering processes

$$A(\vec{p}_A)B(\vec{p}_B) \longrightarrow a(\vec{p}_a)b(\vec{p}_b).$$

If such a scattering event occurs at point  $\vec{r}$ , then the singleparticle phase-space density decreases in the vicinity of phasespace points  $(\vec{r}, \vec{p_A})$  and  $(\vec{r}, \vec{p_B})$  and increases in the vicinity of  $(\vec{r}, \vec{p_a})$  and  $(\vec{r}, \vec{p_b})$ . Therefore, at each phase-space point, the collision term in Eq. (2.1) consists of a gain term from particles that are scattered into this phase-space point and a loss term from particles that are scattered out:

$$\frac{df(r, p_A, t)}{dt} = I_{\text{gain}}(\vec{r}, \vec{p_A}, t) - I_{\text{loss}}(\vec{r}, \vec{p_A}, t),$$

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with

$$\begin{split} I_{\rm loss}(\vec{r},\,\vec{p_A},t) &= \frac{1}{(2\pi)^3} \int d^3 p_B \int d\Omega_{\rm CM} \\ &\times \frac{d\sigma_{AB \to ab}}{d\Omega_{\rm CM}} v_{AB} f(\vec{r},\,\vec{p_A},t) f(\vec{r},\,\vec{p_B},t) \mathcal{P}_a \mathcal{P}_b, \\ I_{\rm gain}(\vec{r},\,\vec{p_A},t) &= \frac{1}{(2\pi)^3} \int d^3 p_a \frac{1}{(2\pi)^3} \int d^3 p_b (2\pi)^3 \\ &\times \frac{d\sigma_{ab \to AB}}{d^3 p_A} v_{ab} f(\vec{r},\,\vec{p_a},t) f(\vec{r},\,\vec{p_b},t) \mathcal{P}_A \mathcal{P}_B, \end{split}$$

where  $d\sigma_{AB\to ab}/\Omega_{CM}$  and  $d\sigma_{ab\to AB}/d^3 p_A$  are the angular and momentum differential cross sections for the reactions  $AB \to ab$  and  $ab \to AB$ , respectively.  $v_{AB}$  and  $v_{ab}$  are the relative velocities of the collision partners AB and ab. The terms  $\mathcal{P}_X = 1 - f(\vec{r}, \vec{p}_X, t)$  with X = A, B, a, b correspond to the Pauli blocking of the final states. The momenta of the particles in  $I_{\text{loss}}$  and  $I_{\text{gain}}$  satisfy the conditions of energy and momentum conservation.

To point out the connection between our numerical implementation and the underlying BUU equation, we concentrate on the loss term of BUU. We will therefore not elaborate on the gain term  $I_{gain}$ , which describes the production of particles. However, its numerical implementation is analogous to the loss term since both are connected by detailed balance.

The Boltzmann equation can be solved numerically using the so-called test-particle ansatz, where the single-particle density is expressed in terms of  $\delta$  functions:

$$f(\vec{r}, \, \vec{p}, t) = \lim_{N \to \infty} \frac{(2\pi)^3}{N} \sum_{i=1}^{A \times N} \delta[\vec{r} - \vec{r}_i(t)] \delta[\vec{p} - \vec{p}_i(t)]$$

Here  $\mathcal{A}$  denotes the number of physical particles and N is the number of test particles per physical one. So the singleparticle phase-space density is interpreted as a sum of all testparticle densities. The centroids of the  $\delta$  functions,  $\vec{r}_i$  and  $\vec{p}_i$ , obey the classical Hamiltonian equations. The change of the single-particle phase-space density per infinitesimal  $\Delta t$  owing to collisions is given by

$$\Delta f(\vec{r}, \vec{p}, t) = \Delta t (I_{\text{gain}} - I_{\text{loss}}).$$
(3.1)

In terms of the test-particle ansatz the loss term reads

$$\Delta t I_{\text{loss}}(\vec{r}, \vec{p}_A, t) = \lim_{N \to \infty} \frac{(2\pi)^3}{N} \sum_{i=1}^{A \times N} \sum_{j=1, j \neq i}^{A \times N} \delta(\vec{p}_A - \vec{p}_i) \delta(\vec{r} - \vec{r}_i)$$

$$\times \lim_{N \to \infty} \underbrace{\frac{1}{\sigma_{ij}} \int d\Omega_{\text{CM}} \mathcal{P}_a \mathcal{P}_b \frac{d\sigma_{ij \to ab}}{d\Omega_{\text{CM}}}}_{=\overline{\mathcal{P}_a \mathcal{P}_b}}$$

$$\times \underbrace{\sigma_{ij} \Delta t v_{ij} \frac{1}{N}}_{=\Delta V_{ij}} \delta(\vec{r} - \vec{r}_j) \qquad (3.2)$$

$$= \lim_{N \to \infty} \left( \frac{(2\pi)^3}{N} \sum_{i=1}^{\mathcal{A} \times N} \sum_{j=1, j \neq i}^{\mathcal{A} \times N} \delta(\vec{p}_A - \vec{p}_i) \right. \\ \left. \times \, \delta(\vec{r} - \vec{r}_i) \overline{\mathcal{P}_a \mathcal{P}_b} \int_{\Delta V_{ij}} \delta(\vec{r}' - \vec{r}_j) d^3 r' \right),$$

$$(3.3)$$

where  $\sigma_{ij}$  and  $v_{ij}$  are the total interaction cross section and the relative velocity of the test particles i, j;  $\Delta V_{ij} = \sigma_{ij} \Delta t v_{ij}/N$  is an infinitesimal volume in the vicinity of  $\vec{r}_i$ . Note that the latter volume defines the locality of the scattering process of two test particles. The term  $\overline{\mathcal{P}_a \mathcal{P}_b}$  denotes the blocking of the final state averaged over its angular distribution. We excluded self-interactions; therefore a test particle cannot scatter with itself.

### **B.** Numerical implementation

In a real calculation the number of test particles N is chosen to be finite, for our purposes usually of the order of 300–1500. The time step  $\Delta t$  is chosen such that the average distance traveled by the particles during  $\Delta t$  is less than their mean free path. Therefore,  $\Delta V_{ij}$  is small enough such that a particle has no more than one scattering partner at a given time step. The algorithm proceeds as a sequence of the following steps:

- (i) First, we propagate at each time step the test particles according to Hamilton's equations.
- (ii) The loss term is implemented according to Eq. (3.3). Therefore we consider each term in Eq. (3.3) separately. For simplicity let us just consider one summand describing the loss of the *i*th test particle owing to a collision with the *j*th.
  - (a) The term  $\int_{\Delta V_{ij}} \delta(\vec{r}' \vec{r}_j) d^3 r'$  gives 1 or 0 depending on whether *j* is within  $\Delta V_{ij}$ . The volume  $\Delta V_{ij}$  is chosen to be a cylinder of height  $\Delta t v_{ij}$  with a circle basis  $\sigma_{ij}/N$ ; the symmetry axis is chosen along  $\vec{v}_{ij}$  and the basis is centered at  $\vec{r}_i$ . This corresponds to the usual minimum distance concept [32].
  - (b) If the result of the integral is 1, then we evaluate

$$\overline{\mathcal{P}_a \mathcal{P}_b} = \frac{1}{\sigma_{ij}} \int d\Omega_{\rm CM} \ \mathcal{P}_a \mathcal{P}_b \frac{d\sigma_{ij \to ab}}{d\Omega_{\rm CM}}$$

For this we make a Monte Carlo integration with only one integration point, which is a good approximation in the large-*N* limit. This one point  $\Omega^{CM}$  is chosen in the center of mass (CM) frame randomly according to the weight

$$\frac{1}{\sigma_{ij}}\frac{d\sigma_{ij\to ab}}{d\Omega_{\rm CM}}.$$

Since  $\sqrt{s}$  is fixed,  $\Omega^{CM}$  defines the random momentum  $\vec{p}_a^{CM}$ . Furthermore,

$$\vec{p}_b^{\text{CM}} = -\vec{p}_a^{\text{CM}}$$

Finally, by boosting the momenta to the computational frame, we get

$$\overline{\mathcal{P}_a \mathcal{P}_b} = [1 - f(\vec{r}, \vec{p}_a, t)][1 - f(\vec{r}, \vec{p}_b, t)].$$

- (c) Now we interpret  $\overline{\mathcal{P}_a \mathcal{P}_b}$  as a probability that the reaction takes place. So we make a second Monte Carlo decision on whether we accept the reaction or not. This corresponds to substituting  $\overline{\mathcal{P}_a \mathcal{P}_b}$  by a Bernoulli distributed random number with  $p = \overline{\mathcal{P}_a \mathcal{P}_b}$ . With this substitution, the expectation value of the summand is equal to the original summand. In the limit of many ensembles N (i.e., many summands), this yields the right loss term.
- (d) If the reaction is accepted, then we get for this event where *i* is scattering with *j* the loss contribution

$$\delta(\vec{p}_A - \vec{p}_i)\delta(\vec{r} - \vec{r}_i)$$

which corresponds to the destruction of the *i*th test particle. Because of the double sum in Eq. (3.3), we also get the contribution

$$\delta(\vec{p}_A - \vec{p}_j)\delta(\vec{r} - \vec{r}_j).$$

This latter term corresponds to the destruction of the *j*th test particle. Note that we do not evaluate  $\overline{\mathcal{P}_a \mathcal{P}_b}$  for this case but take the same value that leads to the destruction of *i*. This reflects that energy is conserved on an event-by-event basis.

(e) In our simulation, the final states with momenta  $\vec{p}_b^{\text{CM}}$  and  $\vec{p}_a^{\text{CM}}$  contribute to the gain term. New test particles with those momenta are therefore added to the simulation.

A generalization to  $2 \rightarrow 3$  and  $3 \rightarrow 2$  processes and to finite particle species including degeneracies is straightforward.

### C. Full and parallel ensemble methods

The kind of simulation we described in the last section is called a *full ensemble* calculation. There exists a common simplification to this method: the *parallel ensemble method* [22]. In this scheme one sets N = 1, performs  $\tilde{N}$  runs at the same time, and then averages the results over all runs. The densities used in each run are the averaged densities of all  $\tilde{N}$ parallel runs. Therefore the propagation part stays the same, whereas the collision term gets simplified considerably.

Note that the only justification for this simplification is a great gain in computation time. In a full ensemble method, the propagation part scales according to the number of test particles per nucleon N, whereas the collision term scales with  $N^2$ ; therefore the computation time is  $\mathcal{O}(N^2)$ . In a parallel ensemble method  $\tilde{N}$  runs are performed, which results in  $\mathcal{O}(\tilde{N})$  computation time. So there is linear scaling in a parallel ensemble run but a quadratic one in a full ensemble run. In pioneering works, it was shown by Welke *et al.* [30] and Lang *et al.* [31] that the parallel ensemble scheme is a good approximation to the full ensemble scheme under the conditions of high-energy heavy-ion collisions.

### **IV. RESULTS OF THE SIMULATIONS**

# A. Comparison of full and parallel ensemble runs

In the previous section we introduced the concept of the parallel ensemble approximation. For DCX, surface effects are expected to be important; therefore the spatial resolution could be relevant in this context. Indeed, a major problem of the parallel ensemble scheme is that the volume  $\Delta V_{ij}$  can become very large. In the energy regime under consideration, the incoming pions interact strongly with the nucleons so that the total cross section can reach more than 200 mb. For a parallel ensemble run, the typical volume therefore can have a size of 5 fm<sup>3</sup> for a typical  $\Delta t = 0.25$  fm/c. Since it is not obvious that the parallel ensemble scheme should be reliable in this regime, we hence decided to evaluate this approximation scheme by comparison to the full ensemble method.

In Fig. 2, the results for  $d\sigma/d\Omega$  for pions with 180 MeV kinetic energy are presented for both methods. The results obtained are consistent with each other; therefore we used the parallel ensemble method to save CPU time and to reach higher statistics for all further calculations. Note that in the present problem, to obtain a result at a given energy for one specific nucleus, one CPU-day is required in the parallel ensemble scheme. In the full scheme this takes of the order of 30 CPU-days for acceptable statistics, as shown in Fig. 2.

#### B. Influence of the density profile

Because of the low pion mean free path in nuclear matter [3], the DCX is very sensitive to the surface properties of

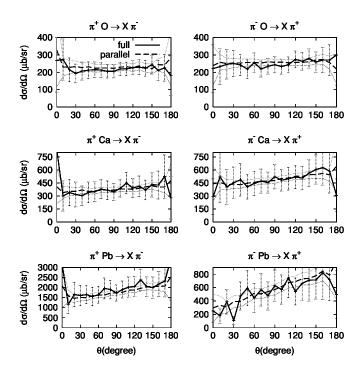


FIG. 2. Comparison of the full and parallel ensemble methods. Angular distributions for the double-charge exchange process  $\pi^{\pm}A \rightarrow \pi^{\mp}X$  at  $E_{\rm kin} = 180$  MeV. The error bars denote the  $1\sigma$ statistical error of each point of the full ensemble run; the thin lines denote the  $1\sigma$  statistical error of the parallel result.

TABLE II. Parameters of the Woods-Saxon parametrizations for  ${}^{208}_{82}$ Pb.

	$ ho_p^0  [\mathrm{fm}^{-3}]$	$\rho_n^0  [{\rm fm}^{-3}]$	$R_p$ [fm]	$R_n$ [fm]	$a_p = a_n$ [fm]
default parameterization [43]	0.0631	0.0859	6.624	6.890	0.549
old parameterization [3]	0.0590	0.0900	6.826	6.826	0.476

the nuclei. Therefore, we compared the results with our present density parametrization for <sup>208</sup>Pb [43], as described in Sec. II D, to the results obtained with the one used in previous publications [1,3,36]. For <sup>208</sup>Pb, both distributions are parametrized according to Eq. (2.2) with the parameters given in Table II. However, neutron skins are very interesting because in those skins only  $\pi^+$  mesons can undergo charge exchange reactions. For the positive pions this causes an enhancement of DCX processes at the surface, so the pions do not need to penetrate deeply for this reaction. Hence, the probability for their absorption is reduced. As can be observed in Fig. 3, the enhancement in the total cross section for  $R_n$  –  $R_p = 0.266$  fm is roughly 35% at 180 MeV. The accurate determination of neutron skins is relevant for different areas of physics such as nuclear structure, neutron star properties, atomic parity violation (PV), and heavy-ion collisions [46–48]. The Parity Radius Experiment (PREX) at JLab [49] will measure the neutron radius with high precision (1%) using PV electron scattering. We have just shown that the DCX cross section is very sensitive to the size of the difference between the proton and the neutron radii of Pb. The effect is especially large (more than a factor of 2) at forward angles, where our model performs very well (see the next section). Indeed, without neutron skin, the strong pion absorption in the bulk nuclear matter leads to a small DCX cross section at forward angles. The presence of a neutron skin favors DCX in peripheral reactions, where the pion propagates in practically pure neutron matter. This naturally enhances the DCX cross section. Hence, a precise measurement of DCX at forward angles, combined with a realistic theoretical analysis, could be a valuable source of information on the neutron skins complementary to the one obtained with PV electron scattering. Note that for the  $\pi^-$  similar arguments lead to a reduction of the cross section.

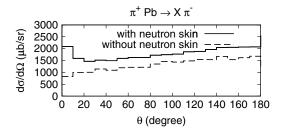


FIG. 3. Influence of the density distribution on the angular distributions for the double-charge exchange process  $\pi^+\text{Pb} \rightarrow \pi^-X$  at  $E_{\text{kin}} = 180$  MeV. The solid line shows the result obtained with our present density distribution [43]; the dashed line was obtained with the previously used one [1,3,36], which contains no neutron skin.

#### C. Comparison to data

Now we proceed to the comparison with the data measured at LAMPF by Wood *et al.* [16]. We discuss first the total cross section. Hereafter, we will explore angular distributions and, finally, address the double differential cross sections as a function of both angles and energies of the outgoing pions.

In Fig. 4 one can see the excellent quantitative agreement to the total cross-section data at 120, 150, and 180 MeV for oxygen and calcium. For the lead nucleus we see some discrepancies. Notice that we reproduce the different *A* dependencies of both  $(\pi^+, \pi^-)$  and  $(\pi^-, \pi^+)$  reactions. These differences arise because, when *A* increases, the number of neutrons increases with respect to the number of protons, and this favors the  $\pi^+$  induced reaction.

In [19], Gram et al. discuss a scaling law of the total cross section. They argue as follows. Since the first collision takes place predominantly at the surface, the cross section should scale with  $A^{2/3}$ . Furthermore, they assume that DCX is mainly a two-step process and that a pion that undergoes an elastic process at the first collision will not contribute. This is reasonable because the incoming pions lose energy in the elastic process, and their cross section for a second charge-exchange reaction is hereafter very much reduced. For a negative pion the first charge-exchange reaction occurs with a probability of Z/N, where Z(N) denotes the number of protons (neutrons). This is the case if the interaction is dominated by the  $\Delta$  resonance, as it should be in this energy region. Finally, the second charge-exchange process then takes place with the probability (Z - 1)/(A - 1) since, in the isospin limit, the  $\pi^0$  interacts equally well with protons and neutrons. Putting these considerations together and extending them to the  $\pi^+$  case, we expect the cross section for DCX to scale according to

$$\sigma_{\rm tot} \sim A^{2/3} \frac{Q}{A-Q} \frac{Q-1}{A-1},$$
 (4.1)

where Q denotes the number of protons in the case of  $\pi^-$ -induced DCX and the number of neutrons in  $\pi^+$ -induced DCX.

Gram *et al.* [19] find good agreement of this scaling law with experimental data. This scaling is also fulfilled in the GiBUU simulation, as can be seen in Fig. 5. Nevertheless, one may wonder why this scaling law works in a process that is so sensitive to the neutron skin on heavy nuclei, as has been shown in Fig. 3. Since the first collision takes place on the surface, a neutron skin causes an enhancement in the  $A(\pi^+, \pi^-)X$  reaction whereas  $A(\pi^-, \pi^+)X$  is suppressed. This effect leads to a deviation from the scaling. However, there are also Coulomb forces, which are not negligible. The Coulomb force enhances  $A(\pi^-, \pi^+)X$  by attracting the

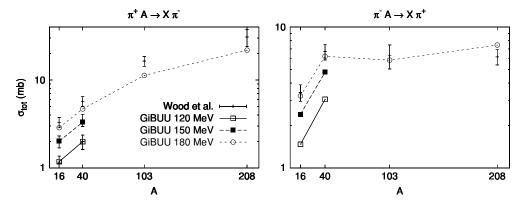


FIG. 4. The inclusive double-charge exchange total cross section as a function of the nuclear target mass at  $E_{kin} = 120$ , 150, and 180 MeV. The lines connecting our results are meant to guide the eye; the data are taken from Ref. [16] (left panel:  $E_{kin} = 120$ , 150, and 180 MeV; right panel: only 180 MeV).

negative projectiles and repelling the positive products, which therefore have a smaller path in the nucleus and undergo less absorption. Similar arguments show that the reaction  $A(\pi^+, \pi^-)X$  is suppressed. We find that this effect counteracts the one from the neutron skin restoring the scaling. In any case, the approximate scaling exhibited by the cross section shows that the reaction is very much surface driven and can be very well understood in terms of a two-step process.

In Fig. 6 we show  $d\sigma/d\Omega$  for DCX at  $E_{\rm kin} = 120$ , 150, and 180 MeV on <sup>16</sup>O,<sup>40</sup> Ca, and <sup>208</sup>Pb as a function of the scattering angle  $\theta$  in the laboratory frame. Our results (bold lines) are shown together with their uncertainties of statistical nature (thin lines). The latter ones are well under control except at very small and very large angles, where the statistics is very poor. Again, there is a very good quantitative agreement for both O and Ca. In the Pb case, the  $(\pi^-, \pi^+)$  reaction is well described, but the  $(\pi^+, \pi^-)$  one is underestimated in spite of the enhancement caused by the neutron skin.

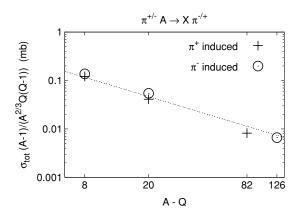


FIG. 5. The scaling of the total charge exchange cross section according to Eq. (4.1) visualized by dividing  $\sigma_{tot}$  by the factor  $A^{2/3}Q(Q-1)/(A-1)$  and plotting it as a function of A - Q. Q denotes the number of protons in the case of  $(\pi^-, \pi^+)$  and the number of neutrons in  $(\pi^+, \pi^-)$ . The points are GiBUU results at pion kinetic energies of 180 MeV; the dashed line denotes a function proportional to 1/(A - Q), corresponding to the exact scaling.

Going into further details of the energy distribution of the produced pions, we show in Figs. 7, 8, and 9 the results for  $d\sigma/(d\Omega dE_{\rm kin})$  at different laboratory angles  $\theta$ , as a function

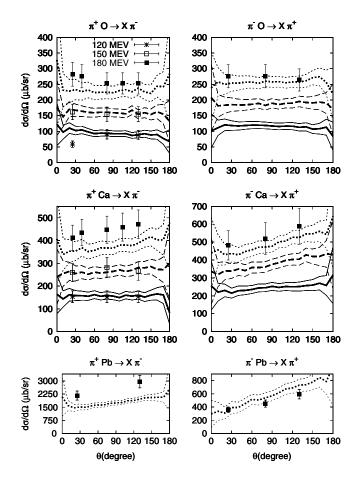


FIG. 6. Angular distributions for the double-charge exchange process  $\pi^{\pm}A \rightarrow \pi^{\mp}X$  at  $E_{\rm kin} = 120$ , 150, and 180 MeV. The data points are taken from [16]; only systematic errors are shown. The solid, dashed, and dotted lines represent the GiBUU results at 120, 150, and 180 MeV, respectively. The bold lines represent the results of the current study; the thin lines represent a 1 $\sigma$  confidence level for each point based upon our statistics.

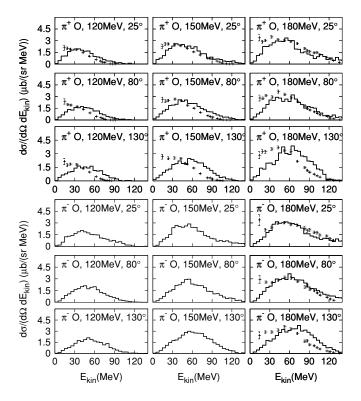


FIG. 7. Double differential cross sections for the DCX process  $\pi^{\pm}O \rightarrow \pi^{\mp}X$  at  $E_{kin} = 120$ , 150, and 180 MeV. The results at different angles are shown as function of the kinetic energies of the produced pions. Data are taken from [16], only statistical errors are shown. The GiBUU results are shown as histograms, where the fluctuations indicate the degree of statistical uncertainty.

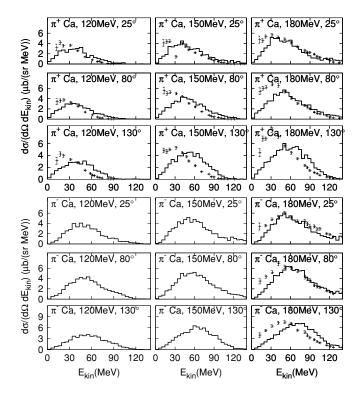


FIG. 8. Same as Fig. 7, but for Ca.

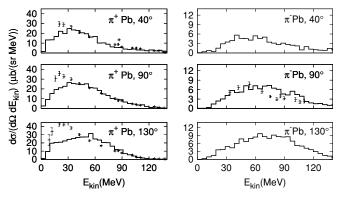


FIG. 9. Same as Fig. 7, but for Pb at  $E_{kin} = 180$  MeV.

of the kinetic energy of the outgoing pion,  $E_{\rm kin}$ . The overall agreement is good, being better at forward and transverse angles than at backward angles. We observe a lack of pions with energies below  $E_{\rm kin} \simeq 30$  MeV. This feature becomes more prominent when going from O to Pb and is present for both incoming  $\pi^+$  and  $\pi^-$ . The same problem also shows up in the work of Vicente *et al.* [11] (see their Fig. 9). A solution to this problem is not clear. Owing to the low-energy nature of those missing pions, one may speculate whether quantum mechanical effects are responsible for the enhancement and therefore cannot be described by a semiclassical transport theory.

### V. SUMMARY

We have studied pionic double-charge exchange on different nuclear targets (<sup>16</sup>O,<sup>40</sup> Ca, and <sup>208</sup>Pb) in the  $\Delta$  region ( $E_{\rm kin} = 120, 150, \text{and } 180 \text{ MeV}$ ) with a semiclassical coupledchannel transport model (GiBUU).

We have established the validity of the parallel ensemble scheme for this reaction, which is very sensitive to local density distributions, by contrasting the results with those obtained in the more precise but time-consuming full ensemble method.

Furthermore, we compared the results of our model with the extensive set of data taken at LAMPF [16], achieving a good agreement, not only for the total cross section but also for angular distributions and double differential cross sections. Still, we miss some strength at backward angles and pion energies below  $E_{\rm kin} \approx 30$  MeV. The scaling of the total cross sections pointed out in [19] could be reproduced. However, we found two important effects that break this scaling: neutron skins and Coulomb forces, which compensate each other. We have shown in Sec. IV B that the DCX cross section is very sensitive to the size of the neutron skin. A precise measurement of DCX at forward angles combined with a theoretical analysis could bring quantitative results on the neutron skins of heavy nuclei.

Finally, we conclude that the implementation of pion rescattering and absorption in the GiBUU transport model successfully passes the demanding test of describing double-charge exchange reactions. Thus the semiclassical approach is well suited to describe pion dynamics in nuclei for pion kinetic energies greater than  $E_{\rm kin} \approx 30$  MeV.

PION-INDUCED DOUBLE-CHARGE EXCHANGE ...

### ACKNOWLEDGMENTS

The authors thank Steven A. Wood for his cooperation by promptly retrieving for us the experimental data. OB is grateful to the rest of the GiBUU group, especially T. Falter,

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K. Gallmeister, T. Leitner, and P. Mühlich for support and providing a good atmosphere, and thanks S. Leupold for fruitful discussions. This work was supported by Deutsche Forschungsgemeinschaft (DFG).

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