

Largest cluster in percolation: Implications for fragmentation studies

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The probability distribution of the largest cluster size is studied within a three-dimensional bond percolation model on small lattices. Cumulants of the distribution exhibit distinct features near the percolation transition (pseudocritical point), providing a method for its identification. The location of the critical point in the continuous limit can be estimated without variation of the system size. This method is remarkably insensitive to finite-size effects and may be applied even for a very small system. The possibility of using various measurable quantities for sorting events makes the procedure useful in studying clusterization phenomena, in particular nuclear multifragmentation. Finite-size scaling and Δ -scaling relations are examined. The role of surface effects is evaluated by a comparison of results for free and periodic boundary conditions.

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I. INTRODUCTION

The main motivation of nuclear multifragmentation studies is probing a liquid-gas coexistence region in the phase diagram of nuclear matter [1–3]. Many works deduce the occurrence of a first- or second-order phase transition [4–14]. Although both transition types can be expected, unambiguous identification is difficult because of strong finite-size effects in systems with a small number of constituents. In such systems, for example, a first-order phase transition may mimic critical behavior [15,16]. On the other hand, nuclear multifragmentation induced by high-energy collisions shows striking similarities to percolation processes that are known to contain a second-order phase transition (critical behavior) [10,17–23]. Percolation-based models also seem to be successful in describing fragmentation of atomic clusters [24,25]. These observations led to the formulation of the hypothesis that percolation could be a universal fragmentation mechanism for simple fluids [23]. For better recognizing critical-like behavior observed in fragmentation processes, the simultaneous application of various complementary methods is necessary. Percolation models are often used to construct or verify procedures that trace critical behavior in fragmenting systems [17–20,26–29]. They provide a simple tool for studying universal aspects of the critical behavior and the role of finite-size effects.

In this work, the largest cluster size distribution is examined in the framework of a percolation model. The size of the largest cluster, as an order parameter in aggregation scenarios of fragment production, is of particular interest in phase-transition studies [28,29]. The limiting forms of the distribution for normal phases are predicted by classical limit theorems for random variables [29–32]. At a second-order phase transition the system is highly correlated with fluctuations occurring on all length scales. Properties of the order parameter close to the critical point can be studied with the renormalization group and finite-size scaling approaches [28–30,32–34]. Recently, it was proposed to identify second-order critical behavior in finite systems by examining universal features of the order parameter

fluctuations with a Δ -scaling method [8,28–30]. The method has been applied to several models and nuclear fragmentation data [8,14,16,28,29,35–38]. Here, Δ -scaling behavior of the largest cluster is investigated in percolation processes.

To compare theoretical predictions with fragmentation data, all experimental conditions should be carefully considered. The bulk behavior of the order parameter can be significantly modified in small fragmenting systems by finite-size and boundary effects. The control parameter is usually not well measured and must be substituted by other measurable quantities in sorting events, leading to additional modifications. The present work evaluates the significance of such effects.

The calculations were performed with a three-dimensional bond percolation model on simple cubic lattices [33]. A Monte Carlo procedure with the Hoshen-Kopelman cluster labeling algorithm was employed to generate events for a distribution of the bond probability p being the control parameter. Lattices of size $N = L^3$ with $L = 3, 4, 5, 6$ correspond to the range of system sizes available in nuclear reactions. Free boundary conditions were applied to account for the presence of a surface in real systems. To evaluate the role and importance of finite-size and boundary effects the calculations were extended to include larger systems and periodic boundary conditions.

We study low-order cumulants (cumulant ratios) as the mean, variance, skewness, and kurtosis of the largest cluster size distribution. These standard statistical measures contain the most significant information, providing a robust identification of the percolation transition. To place our results in a wider context, in the next section some signals of criticality that are frequently tested in fragmentation studies are briefly discussed.

II. PERCOLATION TRANSITION IN SMALL SYSTEMS

In the strictest sense, the phase transition occurs in the continuous limit $N \rightarrow \infty$. Then, below the percolation threshold $p < p_c \simeq 0.2488$, only finite clusters are present. When $p > p_c$ there exists an infinite cluster spanning the whole lattice. The fraction of sites belonging to this cluster is the order parameter. In finite systems the transition is smoothed. The probability that at least one cluster connects the bottom and the top lattice planes changes gradually, as

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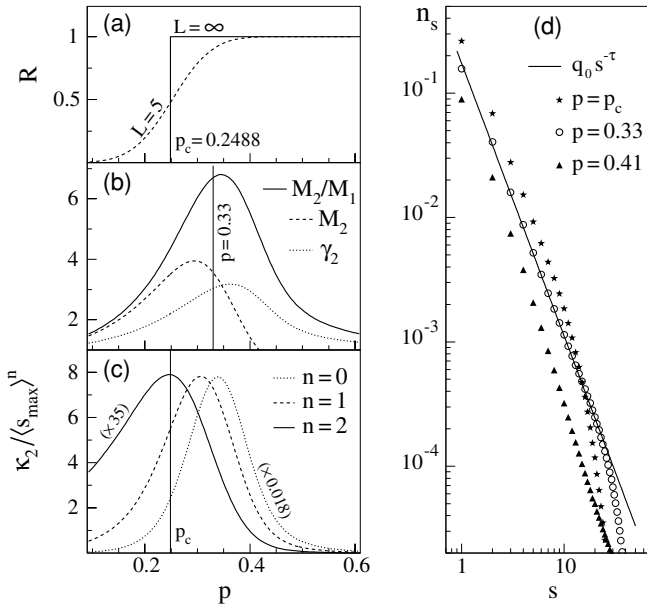


FIG. 1. Bond percolation on a lattice of linear size $L = 5$ with free boundary conditions. Plotted as a function of the bond probability: (a) the probability that a lattice is spanned, (b) moments of the average distribution of cluster sizes, (c) the variance of the largest cluster size distribution with various normalizations. (d) The average distribution of cluster sizes.

illustrated in Fig. 1(a). A natural way to locate the transition is to examine quantities that diverge at the critical point in the continuous limit. For finite systems, the divergence is replaced with a maximum located near p_c . This can be seen in Fig. 1(b) for the second moment of the average distribution of cluster sizes M_2 , the mean cluster size M_2/M_1 , and the reduced variance $\gamma_2 \equiv M_2 M_0 / M_1^2$ [20]. M_k denotes the k th moment of the cluster size distribution, $M_k = \sum_s s^k n_s$, where n_s is the average number of clusters of size s normalized to the system size (the largest cluster excluded). The mean cluster size is the analog of the susceptibility and the location of its maximum value defines the pseudocritical point. Another frequently used method is a power-law fit to the fragment size distribution [4,27]. In our example the best fit is obtained for $p = 0.33$ as shown in Fig. 1(d). The fragment size distribution follows in some range the asymptotic behavior $n_s = q_0 s^{-\tau}$, where the Fisher exponent $\tau = 2.189$ [39]. The normalization constant $q_0 = 1 / \sum_{s=1}^{\infty} s^{(1-\tau)}$ is taken as 0.173 from the summation computed up to $s = 10^9$. Another example is the maximum fluctuation of the largest cluster size. The size of the largest cluster, s_{\max} , plays the role of an extensive order parameter. Its fluctuations are usually measured by the variance κ_2 or the normalized variance $\kappa_2 / \langle s_{\max} \rangle$ of the probability distribution $P(s_{\max})$ [20,23,27,40]. The two quantities are peaked in the transition region, as shown in Fig. 1(c) by the dotted and dashed curves. When the normalization $\kappa_2 / \langle s_{\max} \rangle^2$ is used, the maximum is located remarkably close to the critical point.

The above examples show that various investigated signals appear at different positions, and in most cases they are shifted from the critical point toward the ordered phase region. In small systems the shifts may be significant and should be taken into

account in a criticality analysis. The location of the critical region in nuclear multifragmentation is often deduced from a power-law fit to the fragment size distribution. This location, appearing near the pseudocritical point, would correspond to a temperature T_{pc} distinctly lower than the true critical temperature T_c . For example, converting the bond probability to the temperature with the prescription of Refs. [22,41], one obtains $T_{pc}/T_c = 0.64, 0.73,$ and 0.78 for $N = 27, 64,$ and 125 , respectively.

The location of the true critical point p_c is of particular interest. According to the finite-size scaling, the position of a signal, $p(L)$, is expected to converge to p_c with increasing linear lattice size L as

$$p(L) - p_c \propto L^{-1/\nu}, \quad (1)$$

where ν is the correlation length exponent. The estimation of a critical point by such an extrapolation method seems to be difficult in the case of nuclear multifragmentation. Sizes of fragmenting systems created in nuclear reactions are not well controlled because of the preequilibrium emission and their range is limited. In addition, one may expect large departures from the scaling relation of expression (1) for very small systems. Our observation is that, without relying on the finite-size scaling, the best estimation of the critical point is given by the position of the maximum of $\kappa_2 / \langle s_{\max} \rangle^2$. Behavior of this quantity for different system sizes and various event sortings is investigated in the following sections.

III. DISTRIBUTION OF THE LARGEST CLUSTER SIZE

A. Cumulants and finite-size scaling

The probability distribution of the largest cluster size representative for small lattices with open boundaries is shown in Fig. 2 for various values of p . Far from the transition the distribution is sharply peaked with an extended tail to the right (left) in the disordered (ordered) phase and positioned close to the limiting values. In the transition region the distribution rapidly evolves passing through a broad, flattened, and (nearly) symmetrical distribution. This behavior can be well characterized by use of the skewness K_3 , which measures

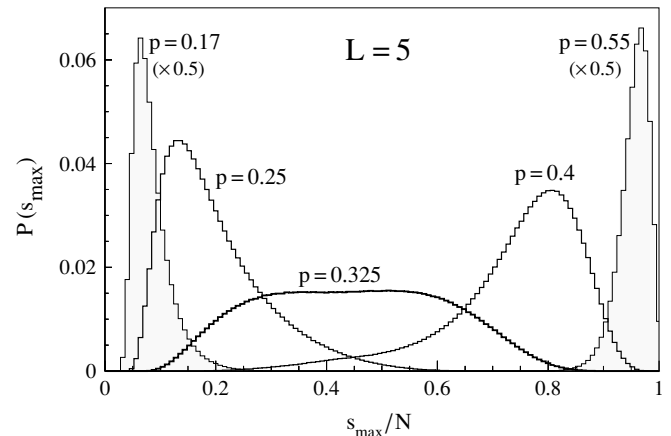


FIG. 2. Probability distributions of the largest cluster size for a lattice of size $N = 125$ with free boundary conditions.

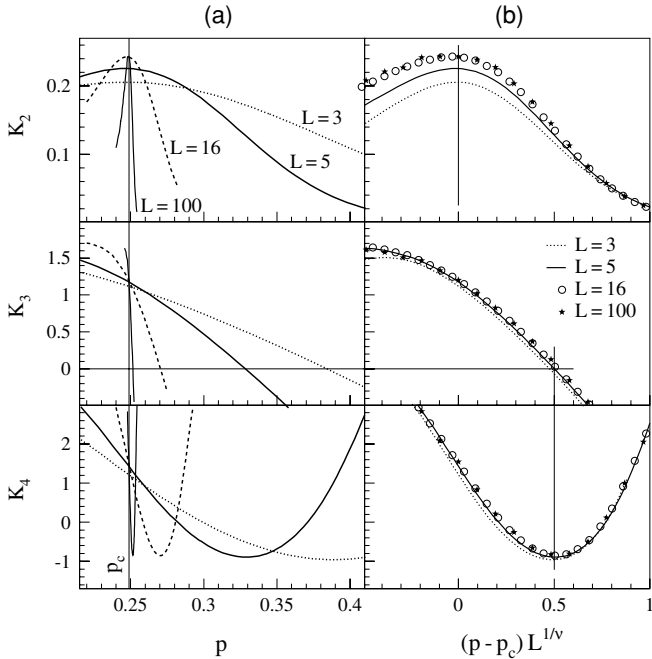


FIG. 3. The cumulant ratios of Eqs. (2) as functions of (a) the bond probability and (b) the scaling variable for systems of different sizes. Calculations are made with free boundary conditions.

the asymmetry of a distribution, and the kurtosis excess K_4 , which quantifies the degree of peakedness. The quantities of interest are defined and expressed in terms of the cumulants as

$$\begin{aligned} K_2 &\equiv \mu_2 / \langle s_{\max} \rangle^2 = \kappa_2 / \kappa_1^2, \\ K_3 &\equiv \mu_3 / \mu_2^{3/2} = \kappa_3 / \kappa_2^{3/2}, \\ K_4 &\equiv \mu_4 / \mu_2^2 - 3 = \kappa_4 / \kappa_2^2, \end{aligned} \quad (2)$$

where $\mu_i = \langle (s_{\max} - \langle s_{\max} \rangle)^i \rangle$ is the i th central moment and κ_i is the i th cumulant of the $P(s_{\max})$ distribution. They are plotted as functions of p for different system sizes in Fig. 3(a). In the vicinity of the critical point and for $L \rightarrow \infty$, one expects for these dimensionless parameters the finite-size scaling relation

$$K_i = f_i[(p - p_c)L^{1/\nu}]. \quad (3)$$

If the scaling holds, values of K_i at p_c are independent of the system size, which is approximately observed in our plots as the crossing of curves for different L near p_c . To verify the scaling in the neighborhood of the critical point the K_i parameters are replotted in Fig. 3(b) against the scaling variable $(p - p_c)L^{1/\nu}$, where $\nu = 7/8$. The collapse of the data shows that the scaling relation with no corrections for finite-size effects is well satisfied even for such small lattices with open boundaries. As can be estimated from Fig. 3(b), the asymptotic values of K_i at p_c are about $K_2 = 0.24$, $K_3 = 1.2$, and $K_4 = 1.5$. For small systems they are somewhat smaller, with largest deviations observed for K_2 . A prominent feature of the K_2 distribution is the maximum located very close to p_c , irrespective of the system size.

Another characteristic point, corresponding to the broad transitional distribution shown in Fig. 2, is where $K_3 = 0$ and simultaneously K_4 reaches its minimum value of about -0.9

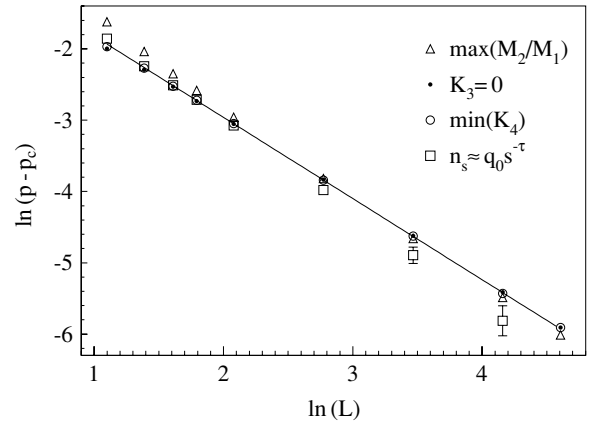


FIG. 4. Finite-size scaling plot for values of the bond probability p at which the conditions indicated on the figure are fulfilled. The line is the best linear fit to the open circles.

whereas $K_2 \simeq 0.135$. This is observed at some distance from the critical point, which depends on the system size as $(p - p_c) \simeq 0.5L^{-1/\nu}$. Such a point approximately coincides with the maximum of the mean cluster size and the power-law behavior of the fragment size distribution (see Fig. 4), and may be used as an estimation of the pseudocritical point. The line in Fig. 4 is a power-law fit of relation (1) to such points giving $\nu = 0.878 \pm 0.005$ in agreement with the expected value $\nu = 0.875$. Corrections to the scaling are not significant in this case. Other variables considered in Fig. 4 show much larger deviations from the asymptotic scaling behavior.

The above characteristics are for free boundary conditions. The behavior of K_i for periodic boundary conditions when surface effects are reduced is shown in Fig. 5. Also in this case the finite-size scaling features are clearly observed. As expected, the scaling functions f_i are compressed now toward lower bond probabilities, which one can see by comparing Fig. 5(b) with Fig. 3(b). The pseudocritical point is positioned very close to the critical point. Thus, the large difference in locations of these points in the case of free boundary conditions may be interpreted as a surface effect.

B. Delta scaling

The behavior of the cumulant moments is of interest in the context of Δ -scaling proposed for studying criticality in finite systems [8,28–30]. Probability distributions $P(s_{\max})$ of the extensive order parameter s_{\max} for different “system sizes” $\langle s_{\max} \rangle$ obey Δ -scaling if they can be converted to a single scaling function $\Phi(z_{(\Delta)})$ by the transformation

$$\langle s_{\max} \rangle^\Delta P(s_{\max}) = \Phi(z_{(\Delta)}) \equiv \Phi\left(\frac{s_{\max} - \langle s_{\max} \rangle}{\langle s_{\max} \rangle^\Delta}\right), \quad (4)$$

where $1/2 \leq \Delta \leq 1$. Concerning a three-dimensional bond percolation model, it was shown that the $\Delta = 1$ scaling is satisfied near the percolation threshold, as predicted for a continuous phase transition point [28,29]. Above the percolation threshold (at $p = 0.35$) one observes the $\Delta = 1/2$ scaling associated with small fluctuations in the ordered phase. These results were presented for systems $N = 14^3 - 32^3$ with periodic boundary conditions. In the following discussion, we examine Δ -scaling

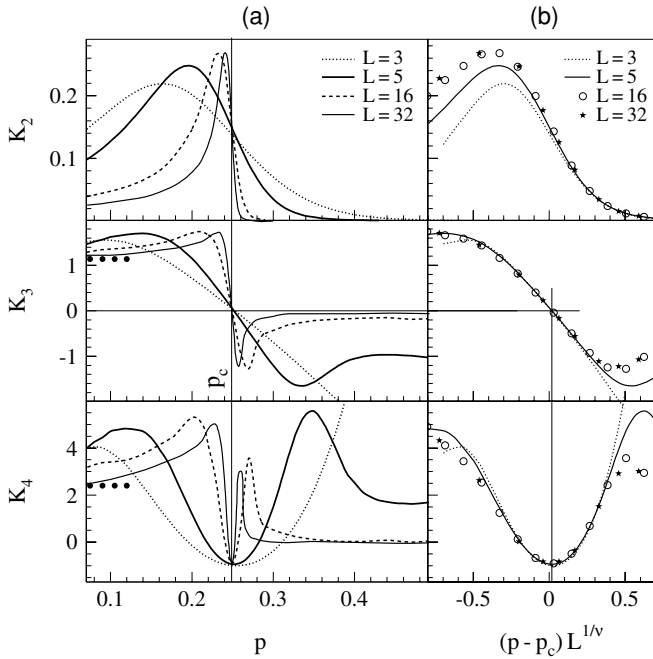


FIG. 5. Same as Fig. 3 but for periodic boundary conditions. The filled circles in (a) indicate the K_3 and K_4 values for the Gumbel distribution (see text).

behavior of $P(s_{\max})$ in a wide range of the control parameter, also for smaller systems with open boundaries.

In the case of Δ -scaling, the normalized cumulants $\kappa_i/\kappa_1^{i\Delta}$ are independent of the “system size” $\kappa_1 \equiv \langle s_{\max} \rangle$. Therefore, for a set of $P(s_{\max})$ distributions, $K_3 = \text{const}$ and $K_4 = \text{const}$ are necessary conditions for a Δ -scaling. Additionally, $K_2 = \text{const}$ for $\Delta = 1$ and $\kappa_2/\kappa_1 = \text{const}$ for $\Delta = 1/2$. The conditions for the $\Delta = 1$ scaling are fulfilled only in the vicinity of the critical point. The crossing points seen in Figs. 3(a) and 5(a) indicate the system size independence of K_i near p_c . The conditions are also satisfied around the critical point when both the system size and the control parameter are varied so that $(p - p_c)L^{1/\nu} = \text{const}$ accordingly to the finite-size scaling. Since the conditions are necessary but not sufficient, we have checked that indeed the scaling relation of Eq. (4) is approximately satisfied. Observing the $\Delta = 1$ scaling requires then a variation of the system size without or with a very specific change of the control parameter. It cannot be observed when the system size is fixed. A similar conclusion has been reached in Ref. [38] for a lattice gas model.

Figure 5(a) shows no evidence for the presence of Δ -scaling in the subcritical region $p < p_c$ (disordered phase). The largest cluster size in subcritical percolation has been extensively studied in Ref. [31]. As predicted by the theory of extremes of independent random variables, $P(s_{\max})$ converges to the Fisher-Tippett (Gumbel) distribution when $N \rightarrow \infty$. The mean grows logarithmically with the system size while the variance is bounded. Such a behavior cannot be described by Δ -scaling. For the Gumbel distribution, $K_3 \simeq 1.14$ and $K_4 = 2.4$, indicated in Fig. 5(a) by the filled circles. As can be seen, the small systems show significant deviations from these asymptotic values even for periodic boundary conditions.

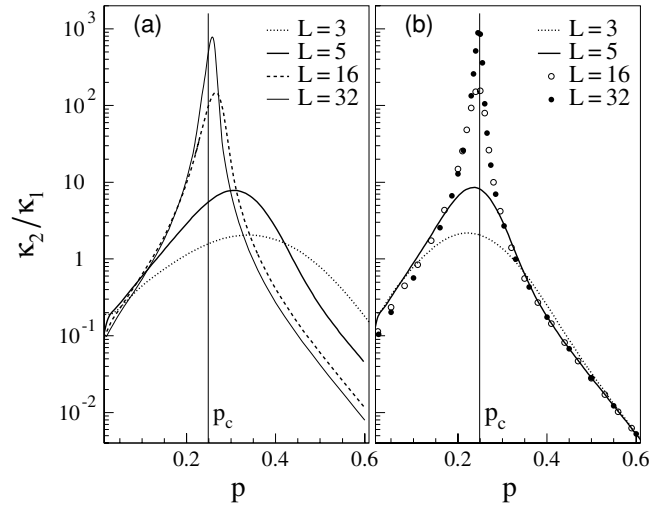


FIG. 6. The normalized variance of $P(s_{\max})$ versus the bond probability for (a) free boundary conditions and (b) periodic boundary conditions.

The limiting behavior of the largest cluster size in the supercritical region $p > p_c$ (ordered phase) is governed by the central limit theorem [29,32]. The asymptotic distribution is Gaussian, $K_3 = K_4 = 0$, with the mean and variance both increasing linearly with the system size, $\kappa_2/\kappa_1 = \text{const}$, satisfying the $\Delta = 1/2$ scaling relation. Such characteristics are seen in Figs. 5(a) and 6(b) away from the critical point for larger systems with periodic boundary conditions. Since the normalized variance κ_2/κ_1 , which is the same for all N , systematically decreases with p , the scaling can be observed only for fixed p and different N . Considering very small systems $L = 3-6$ with free boundary conditions as appropriate for nuclear applications, Fig. 6(a) shows that κ_2/κ_1 at fixed p strongly depends on the system size. This indicates the violation of the scaling as a consequence of surface effects.

Investigations of the largest fragment charge distribution, $P(Z_{\max})$, observed in heavy-ion central collisions at bombarding energies between 25A and 150A MeV, have shown that $\kappa_2/\kappa_1 \simeq \text{const}$ at lower energies while $K_2 \simeq \text{const}$ in a high-energy range [8,35,36]. The two regimes appear on the $\ln(\kappa_2)$ versus $\ln(\kappa_1^2)$ plot along two lines with the slope of $1/2$ and 1 . This observation has been interpreted as the presence of the two limiting Δ -scaling laws corresponding to the ordered and disordered phases (in the case of Δ -scaling, the slope is equal to Δ). Figure 7 shows such a plot when experimental events are sorted according to the estimated source excitation energy. These data, taken from Ref. [35], include quasi-projectiles from Ta + Au collisions which allow us to observe a strong suppression of the fluctuations at lowest energies. Assuming the percolation pattern of the cumulants, interpretation of the high-energy branch in terms of the $\Delta = 1$ scaling would require that for different excitation energies all fragmenting systems are created with nearly the same value of a control parameter close to a critical point. More realistically, the control parameter varies with the excitation energy while changes of the system size are less significant. The dashed and dotted curves in Fig. 7 show percolation results for fixed

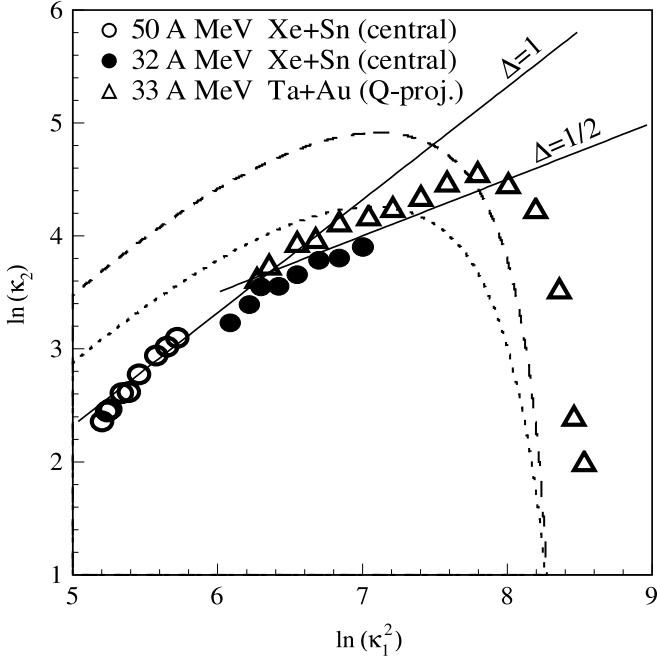


FIG. 7. Log-log plot of the variance versus the squared mean value of the largest fragment size (charge) distribution. The points are experimental data for events sorted according to the excitation energy [35]. The curves are percolation results for $N = 64$ when events are sorted by the bond probability (dashed curve) and by the fraction of open bonds (dotted curve).

$N = 64$ when events are binned by the bond probability and by the fraction of open bonds. Given the mean, the variance depends not only on the system size but also on the choice of binning variable. For a quantitative comparison with the data, one would have to determine appropriate system sizes and a sorting variable equivalent to the excitation energy. Nevertheless, the qualitative behavior of the curves shows similarity to the experimental data. In the model the slope changes continuously and, as shown in Fig. 8, the point with slope of 1 corresponds to the maximum of K_2 (locally $K_2 \simeq \text{const}$), whereas the slope of $1/2$ reflects the maximum of κ_2/κ_1 . These features are not related to Δ -scaling. The rise-and-fall behavior of the correlation in Fig. 7 is a simple consequence of the mass conservation constraint. Some points on this line may have a particular meaning, depending on the assumed model. In the present model, the point of slope 1 approximately corresponds to the critical point. Within the canonical lattice gas model, the point of maximum variance occurs close to the critical point at the critical density. For subcritical densities it is located inside the coexistence region [38].

C. Event sorting effects

The cumulant properties of the largest cluster size distribution presented above are for an ideal situation, which assumes that generated events are sorted according to precisely known values of the control parameter. In experimental studies such a selection is difficult to realize. Usually the sorting parameter is a measurable quantity (e.g., multiplicity, excitation energy per nucleon) that is correlated with the control parameter

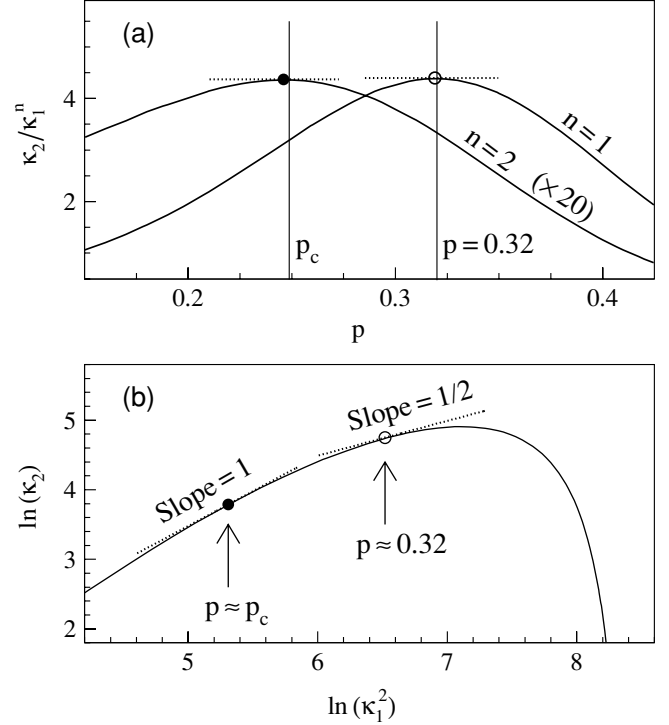


FIG. 8. Percolation lattice of 64 sites with open boundaries: (a) the normalized variance of $P(s_{\max})$ as a function of the bond probability, (b) the variance versus the squared mean in log-log representation for events binned by p .

with a significant dispersion. Even if an attempt is made to estimate a control parameter such as the temperature in nuclear multifragmentation, some dispersion is unavoidable. This can be simulated by use of the fraction of open bonds q for sorting events. On average, the relation between p and q is linear, $q \simeq 1 - p$, for all system sizes. Figure 9 presents K_i as a function of q for small lattices of $L = 3-6$ with open boundaries that are relevant for nuclear multifragmentation studies. The top diagram shows the correspondence between q and $\langle p \rangle$. Comparing $K_i(q)$ with $K_i(p)$ in corresponding intervals shows that absolute values may change significantly; however, some characteristic features are approximately preserved. The $K_2(q)$ distributions exhibit maxima near the “critical” value $q_c \simeq 0.75$, corresponding to p_c . The zeros of $K_3(q)$ coincide with the minima of $K_4(q)$, reflecting the behavior near the pseudo-critical point. However, at the “critical” point q_c , the cumulant values are now much smaller and differ with the lattice size. The crossing points appear shifted from q_c toward the ordered phase. These intersection points are spread out over some range of q and are expected to converge to q_c with increasing N . The relation between p and the number of open bonds is governed by a binomial distribution. This implies that, for a given q , the dispersion of p vanishes as $\sim N^{-1/2}$ with $N \rightarrow \infty$. On the other hand, according to the finite-size scaling, $K_i(p)$ follows the same pattern irrespective of N within a fixed interval of the scaling variable $(p - p_c)L^{1/\nu}$. Thus the corresponding interval of p vanishes with increasing N as $\sim N^{-1/3\nu} \simeq N^{-1/2.625}$. Since the dispersion vanishes faster, the limiting distributions $K_i(q)$ and $K_i(p)$ will be equivalent: $K_i(q) \rightarrow K_i(p = 1 - q)$

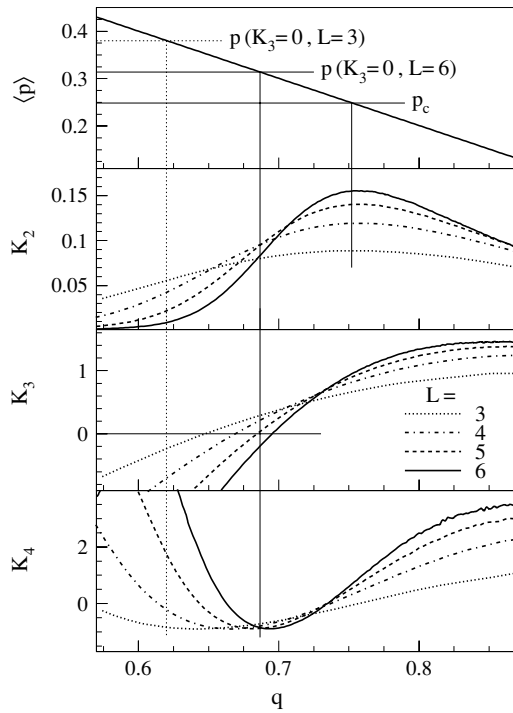


FIG. 9. The cumulant ratios as functions of the fraction of open bonds; top, the correspondence to the mean value of the bond probability.

when $N \rightarrow \infty$. Significant differences between the sortings are observed in small systems.

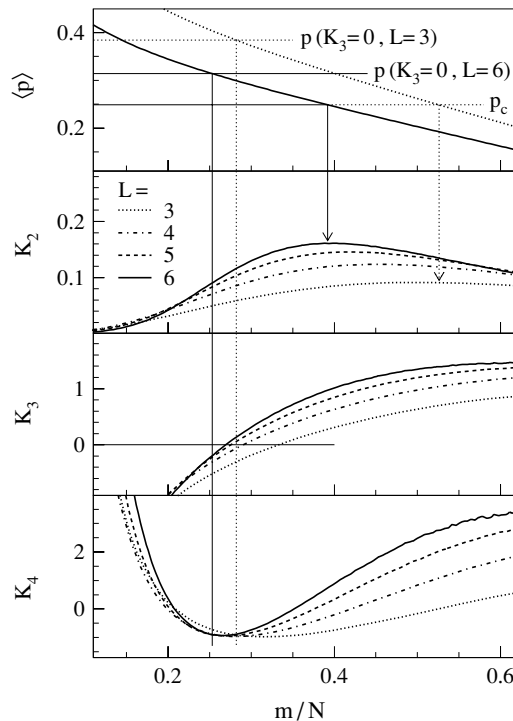


FIG. 10. The cumulant ratios as functions of the normalized multiplicity.

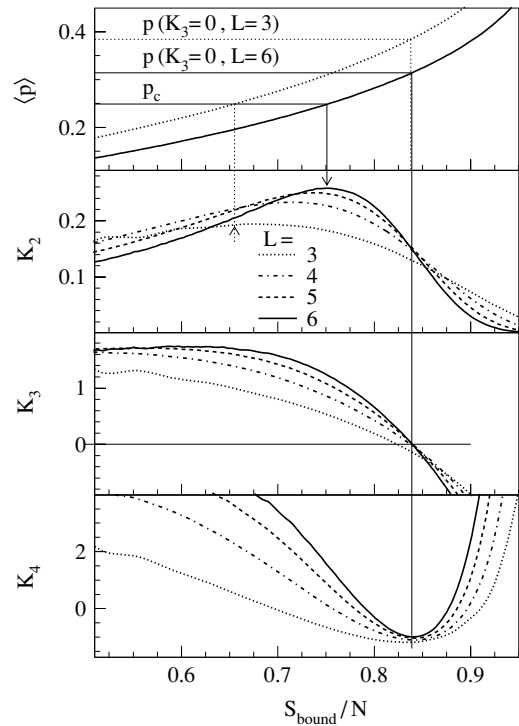


FIG. 11. The cumulant ratios as functions of the normalized total size of complex fragments.

Particularly interesting are event sortings according to directly measurable quantities. We have examined the K_i dependencies on the overall multiplicity m (Fig. 10) and the total size of all clusters of size greater than 1 denoted by S_{bound} (Fig. 11). The parameters are normalized to the system size N . In both cases the average correspondence to the control parameter depends on the system size, which is shown in the top diagrams where the solid line is for $L = 6$ and the dotted one is for $L = 3$. The K_2 distributions exhibit maxima whose positions correspond to the critical value of the control parameter p_c . For such “near-critical” events, values of the sorting variables and the cumulant ratios depend on the system size, as shown in Fig. 12. They all can be well described by the equation

$$X = a - \frac{c}{N + b}, \tag{5}$$

with coefficients a , b , and c listed in Table I. In practice, when the system size is not well known, one can examine K_i as a function of m (and/or S_{bound}). One can find the system size N by solving Eq. (5) with $X = m/N$ for $m = m_c$ at which the maximum of K_2 is observed. Then the values of K_2 , K_3 , and K_4 calculated from Eq. (5) can be verified with those observed at $m = m_c$.

For all the considered sortings, $K_3 = 0$ occurs at the same position as the minimum of K_4 , near the maximum of the mean cluster size and a point where the best power-law fit to the fragment size distribution is observed. Therefore such a point may be used as an alternative or complementary indication of the pseudocritical point. The minimum value

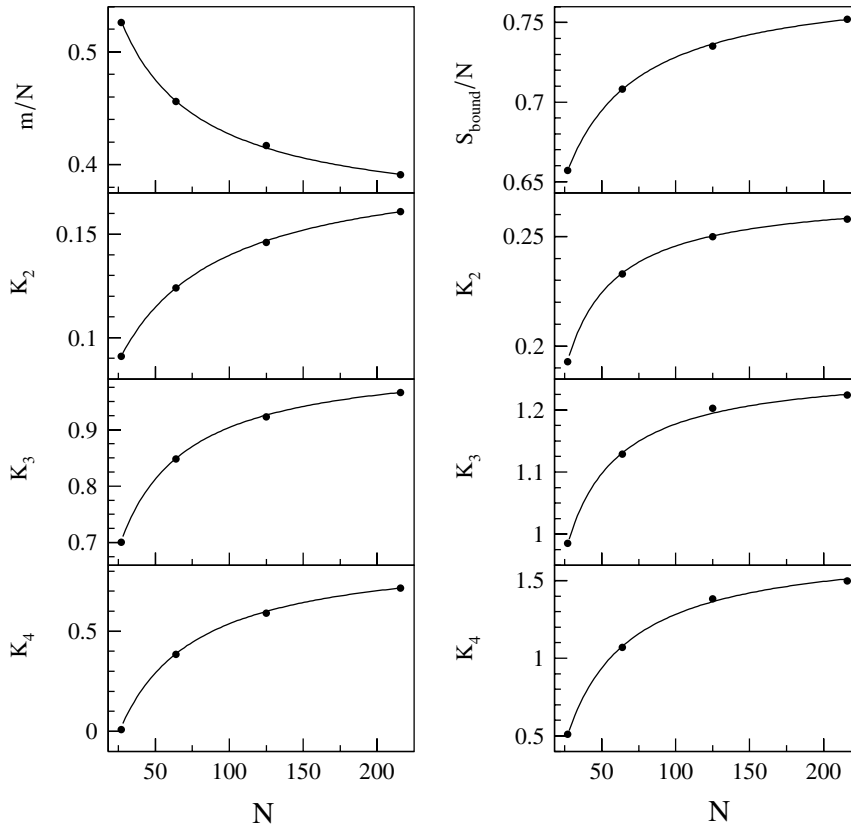


FIG. 12. Parameters of the “critical” point as a function of the system size when events are binned according to the multiplicity (left column) and S_{bound} (right column). The points show percolation values; the curves represent approximations by Eq. (5).

of K_4 is close to -1 for all the sorting parameters and system sizes.

Figures 10 and 11 show that the crossing points, as for the sorting by q , are shifted from the “critical” point corresponding to p_c toward the ordered phase region. For S_{bound}/N they are well localized near the pseudocritical point. In this case the pseudocritical point can be additionally characterized by $K_2 \simeq 0.15$ and the position $S_{\text{bound}}/N \simeq 0.84$.

In our simulations events have been generated for uniformly distributed values of the bond probability p and then grouped in bins of a sorting variable. Using a different distribution of p changes the spectrum of events in a bin. Consequently, quantities such as K_i calculated for events within a bin may also change their values. Calculations performed for a

Gaussian distribution of p that might simulate experimental conditions have shown that this effect is of minor importance.

IV. CONCLUSIONS

The largest cluster size distributions have been examined within a percolation model on small lattices with open boundaries. The dimensionless cumulant ratios as the normalized variance K_2 , the skewness K_3 , and the kurtosis K_4 of the distribution satisfy with a good accuracy the finite-size scaling in the critical region. In particular, K_i are independent of the system size near the critical point (crossing points). This feature has been explored in phase-transition studies as the cumulant crossing method, particularly for the kurtosis in the form of the Binder cumulant [34]. To my knowledge this method has not been applied in analyzing multifragmentation data. However, it would require a wide range of system sizes, which is difficult to realize in nuclear reactions. Moreover, the presence of crossing points has an unambiguous interpretation when events are sorted according to the control parameter. In practice, events are grouped with an inevitable dispersion over the control parameter. This blurs the scaling behavior; the crossing points may appear in a wide range of the sorting parameter away from the “critical” point. These remarks apply also for the $\Delta = 1$ scaling law, since the occurrence of finite-size scaling for the cumulant ratios is a necessary condition for this scaling law. The largest cluster size fluctuations in the disordered phase cannot be described by a Δ -scaling, whereas

TABLE I. The coefficients of Eq. (5) for events grouped in bins of the multiplicity (upper part) and S_{bound} (lower part).

X	a	b	c
m/N	0.352	28.0	-9.6
K_2	0.187	44.0	6.8
K_3	1.03	19.0	15.0
K_4	0.91	26.0	47.0
S_{bound}/N	0.777	23.0	6.0
K_2	0.27	7.0	2.6
K_3	1.27	8.0	10.0
K_4	1.74	16.0	53.0

the limiting $\Delta = 1/2$ scaling in the ordered phase is violated in small systems with open boundaries.

The percolation transition in such systems can be identified by examination of some distinct features of the finite-size scaling functions of K_i , which are not significantly affected by corrections to scaling in small systems and by a dispersion of the control parameter when events are sorted according to various measurable quantities. The maximum of K_2 approximately corresponds to the location of the true critical point. The absolute values of K_i at this point have been determined for sortings by the control parameter, the multiplicity, and S_{bound} , providing complementary characteristics. Coincidentally with the maximum of the mean cluster size (pseudocritical point) and the power-law behavior of the fragment size distribution, one observes $K_3 = 0$ and a minimum value of $K_4 \simeq -1$. If the quantity S_{bound} is used for sorting events, this point can be additionally characterized by $K_2 \simeq 0.15$, and its location is related to the system size as $S_{\text{bound}} \simeq 0.84N$. The analysis does not require the

knowledge or variation of the system size, which is not well controlled in nuclear multifragmentation. It allows us to estimate the system size at the critical and pseudocritical points.

It will be interesting to confront these predictions with multifragmentation data, in particular with the Aladin data, in which the sorting parameter Z_{bound} and the charge of the largest fragment are well determined in a wide range of the excitation energy. It would also be instructive to perform a similar analysis with other models that are known to contain or not contain a phase transition or critical behavior. Using appropriate system sizes, boundary conditions and event sortings in model simulations is an important requirement.

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